

Wilcoxon Research®

# Side exit, 4-20 mA Loop Powered Sensors (LPS®) PC421 series



The 4-20 mA output of the PC421 series is proportional to vibration. The PC series provides continuous trending of overall machine vibration and can help guide maintenance. Dynamic signal output allows spectral vibration measurements using a single sensor. An output of 4 mA indicates a level of 0 ips or no vibration present for velocity output models and 0 g for acceleration output models. A full-scale reading of 20 mA indicates that the maximum range (RMS, equivalent peak or true peak) of the chosen unit, acceleration or velocity, is present.

The dynamic signal output is an optional addition. Any of the base sensor models can also have dynamic signal output. Adding -DA to a model specifies a dynamic acceleration signal output (100 mV/g). Adding -DV to a model specifies a dynamic velocity signal output (100 mV/ips). Choice of output: RMS, equivalent peak, and true peak permits you to choose the sensor that best fits your industrial requirements.

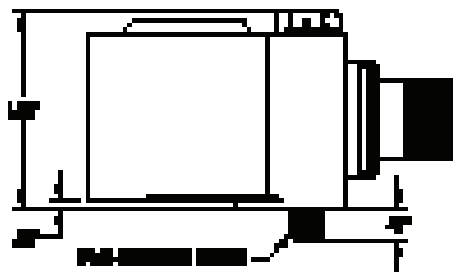
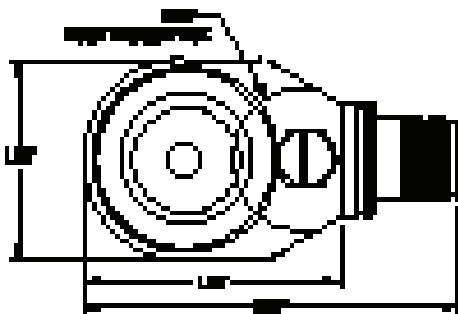
## Key features

- True peak output available on standard versions
- Peak equivalent, true RMS or true peak output available on dynamic signal version
- Optional dynamic signal output
- Case isolated
- Hermetically sealed
- ESD-protected
- EMI/RFI shielded
- Reverse wiring protection
- Manufactured in an approved ISO 9001 and AS9100 facility

## Certifications



Connections		
Function	Connector pin	
	PC421xx-yy	PC421xx-yy-Dz
ground	shell	shell
loop positive (+)	A	A
loop negative (-)	B	B
dynamic signal	NA	C



## Meggitt Sensing Systems

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## PC421 series

### Specifications

<b>Output, 4-20 mA</b>		
<b>Full scale, 20 mA, ±5%</b>	see table 1	
<b>Frequency response</b>	<b>± 10%</b>	10 Hz - 1.0 kHz
	<b>± 3 dB</b>	4.0 Hz - 2.0 kHz
<b>Repeatability</b>	±2%	
<b>Transverse sensitivity, max</b>	5%	
<b>Output, dynamic</b>	PC421xx-yy-DA	PC421xx-yy-DV
<b>Sensitivity, ±10%</b>	100 mV/g	100 mV/ips
<b>Full scale</b>	20 g, peak	1.5 ips at 1 kHz
<b>Frequency response, ±3 dB</b>	2.5 Hz - 10 kHz	2.5 Hz - 2.5 kHz
<b>Amplitude nonlinearity, max</b>	1%	1%
<b>Resonant frequency, mounted, nominal</b>	21 kHz	21 kHz
<b>Transverse sensitivity, max</b>	5%	5%
<b>Power requirements, 2 wire loop power</b>		
<b>Voltage, between pins A and B</b>	10 - 30 VDC	
<b>Loop resistance<sup>1</sup> at 24 VDC, max</b>	700 Ω	
<b>Turn-on time, 4-20 mA loop</b>	30 seconds	
<b>Grounding</b>	case isolated, internally shielded	
<b>Temperature range</b>	-40 to +85° C	
<b>Vibration limit</b>	250 g peak	
<b>Shock limit</b>	2,500 g peak	
<b>Sealing</b>	hermetic	
<b>Sensing element design</b>	PZT, shear	
<b>Weight</b>	320 grams	
<b>Case material</b>	316L stainless steel	
<b>Mounting</b>	1/4-28 captive bolt	
	PC421xx-yy-DA	PC421xx-yy-DV
<b>Output connector</b>	2 pin, MIL-5015 style	3 pin, MIL-5015 style
<b>Mating connector</b>	R6 type	R6G type
<b>Recommended cabling</b>	J9T2A	J9T3A

Notes: <sup>1</sup> Maximum loop resistance (RL) can be calculated by:

$$RL \text{ (max. resistance)} = \frac{V_{DC \text{ power}} - 10 \text{ V}}{20 \text{ mA}}$$

<sup>2</sup> Lower resistance is allowed, greater than 10 Ω recommended

<sup>3</sup> Minimum R<sub>L</sub> wattage determined by: [0.0004 x R<sub>L</sub>]

DC supply voltage	RL (max resistance) <sup>2</sup>	RL (min watt capability) <sup>3</sup>
12 VDC	100 Ω	1/8 Watt
20 VDC	500 Ω	1/4 Watt
24 VDC	700 Ω	1/2 Watt
26 VDC	800 Ω	1/2 Watt
30 VDC	1k Ω	1/2 Watt

Note: Due to continuous process improvement, specifications are subject to change without notice.

This document is cleared for public release.

### Contact

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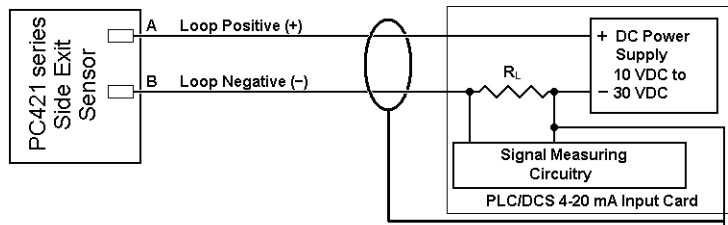
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**Table 1: PC421xx-yy-Dz model selection guide**

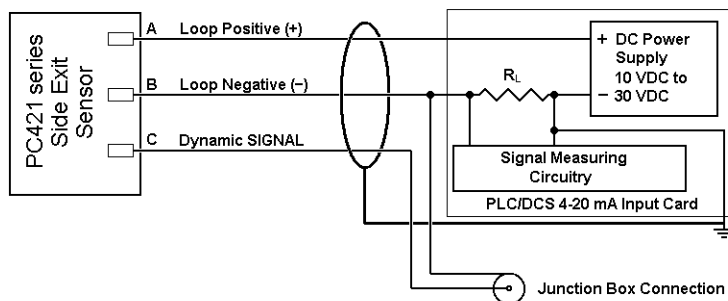
xx (4-20 mA output type)	-yy (full scale)	-Dz (dynamic output) <sup>A</sup>
AR = acceleration, RMS <sup>B</sup> AP = acceleration, equivalent peak <sup>B,C</sup> ATP = acceleration, true peak <sup>D</sup>	-05 = 5 g (49 m/sec <sup>2</sup> ) -10 = 10 g (98 m/sec <sup>2</sup> ) -20 = 20 g (196 m/sec <sup>2</sup> )	-DA = dynamic acceleration 100 mV/g (10.2 mV/m/sec <sup>2</sup> ) -DV = dynamic velocity 100 mV/ips (3.94 mV/mm/sec)
VR = velocity, RMS <sup>B</sup> VP = velocity, equivalent peak <sup>B,C</sup>	-05 = 0.5 ips (12.8 mm/sec) -10 = 1.0 ips (25.4 mm/sec) -20 = 2.0 ips (50.8 mm/sec) -30 = 3.0 ips (76.2 mm/sec) -50 = 5.0 ips (127 mm/sec)	-DA = dynamic acceleration 100 mV/g (10.2 mV/m/sec <sup>2</sup> ) -DV = dynamic velocity 100 mV/ips (3.94 mV/mm/sec)

Notes: <sup>A</sup> Dynamic output is an option on all models. If dynamic output option is not desired, do not add -DA or -DV to the model number.  
<sup>B</sup> RMS and equivalent peak version are available only with dynamic output options. The PCC421 series includes standard RMS and equivalent peak versions with a 105° C maximum operating temperature.  
<sup>C</sup> Equivalent peak output is developed based on the true RMS value of vibration. For a pure sine wave, the equivalent peak output is 1.414 times the RMS value.  
<sup>D</sup> True peak output is based on the actual measured peak value using the time waveform and is not based on the RMS calculation.

## PC421xx-yy wiring diagram



## PC421xx-yy-Dz wiring diagram



All wire and cable used for installation of PC421 series sensors should be shielded. Generally accepted instrumentation wiring practice considers the best way to ground the shield is to connect it at the measurement end of the cable. The shield should not be wired to ground at the sensor end of the cable. Wilcoxon R6W, R6GQAI, R6GQI and R6QI type connectors all leave the shield unconnected at the sensor end of the cable.

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