S29JL032H 32 Megabit (4 M x 8-Bit/2 M x 16-Bit) CMOS 3.0 Volt-only, Simultaneous Read/Write Flash Memory



Notice to Readers: The Advance Information status indicates that this document contains information on one or more products under development at Spansion LLC. The information is intended to help you evaluate this product. Do not design in this product without contacting the factory. Spansion LLC reserves the right to change or discontinue work on this proposed product without notice.

This page intentionally left blank.

S29JL032H

32 Megabit (4 M x 8-Bit/2 M x 16-Bit) CMOS 3.0 Volt-only, Simultaneous Read/Write Flash Memory



Distinctive Characteristics

Architectural Advantages

- Simultaneous Read/Write operations
 - Data can be continuously read from one bank while executing erase/program functions in another bank.
 - Zero latency between read and write operations
- Multiple Bank architecture
- Four bank architectures available (refer to Table 2).
- Boot Sectors
 - Top and bottom boot sectors in the same device
 Any combination of sectors can be erased
- Manufactured on 0.13 µm process technology
- SecSi[™] (Secured Silicon) Sector: Extra 256 Byte sector
 - Factory locked and identifiable: 16 bytes available for secure, random factory Electronic Serial Number; verifiable as factory locked through autoselect function.
 - Customer lockable: One-time programmable only.
 Once locked, data cannot be changed
- Zero Power Operation
 - Sophisticated power management circuits reduce power consumed during inactive periods to nearly zero.
- Compatible with JEDEC standards
 - Pinout and software compatible with single-powersupply flash standard

Package options

48-pin TSOP

Performance Characteristics

- High performance
 - Access time as fast as 60 ns
 - Program time: 4 $\mu s/word$ typical using accelerated programming function

- Ultra low power consumption (typical values)
 2 mA active read current at 1 MHz
 - 10 mA active read current at 5 MHz
 - 200 nA in standby or automatic sleep mode
- Cycling Endurance: 1 million cycles per sector typical
- Data Retention: 20 years typical

Software Features

- Supports Common Flash Memory Interface (CFI)
- Erase Suspend/Erase Resume
 - Suspends erase operations to read data from, or program data to, a sector that is not being erased, then resumes the erase operation.
- Data# Polling and Toggle Bits
 - Provides a software method of detecting the status of program or erase cycles
- Unlock Bypass Program command
 - Reduces overall programming time when issuing multiple program command sequences

Hardware Features

Ready/Busy# output (RY/BY#)

Hardware method for detecting program or erase cycle completion

- Hardware reset pin (RESET#)
 - Hardware method of resetting the internal state machine to the read mode
- WP#/ACC input pin
 - Write protect (WP#) function protects the two outermost boot sectors regardless of sector protect status
 - Acceleration (ACC) function accelerates program timing

Sector protection

- Hardware method to prevent any program or erase operation within a sector
- Temporary Sector Unprotect allows changing data in protected sectors in-system



Notice On Data Sheet Designations

Spansion LLC issues data sheets with Advance Information or Preliminary designations to advise readers of product information or intended specifications throughout the product life cycle, including development, qualification, initial production, and full production. In all cases, however, readers are encouraged to verify that they have the latest information before finalizing their design. The following descriptions of Spansion data sheet designations are presented here to highlight their presence and definitions.

Advance Information

The Advance Information designation indicates that Spansion LLC is developing one or more specific products, but has not committed any design to production. Information presented in a document with this designation is likely to change, and in some cases, development on the product may discontinue. Spansion LLC therefore places the following conditions upon Advance Information content:

"This document contains information on one or more products under development at Spansion LLC. The information is intended to help you evaluate this product. Do not design in this product without contacting the factory. Spansion LLC reserves the right to change or discontinue work on this proposed product without notice."

Preliminary

The Preliminary designation indicates that the product development has progressed such that a commitment to production has taken place. This designation covers several aspects of the product life cycle, including product qualification, initial production, and the subsequent phases in the manufacturing process that occur before full production is achieved. Changes to the technical specifications presented in a Preliminary document should be expected while keeping these aspects of production under consideration. Spansion places the following conditions upon Preliminary content:

"This document states the current technical specifications regarding the Spansion product(s) described herein. The Preliminary status of this document indicates that product qualification has been completed, and that initial production has begun. Due to the phases of the manufacturing process that require maintaining efficiency and quality, this document may be revised by subsequent versions or modifications due to changes in technical specifications."

Combination

Some data sheets will contain a combination of products with different designations (Advance Information, Preliminary, or Full Production). This type of document will distinguish these products and their designations wherever necessary, typically on the first page, the ordering information page, and pages with DC Characteristics table and AC Erase and Program table (in the table notes). The disclaimer on the first page refers the reader to the notice on this page.

Full Production (No Designation on Document)

When a product has been in production for a period of time such that no changes or only nominal changes are expected, the Preliminary designation is removed from the data sheet. Nominal changes may include those affecting the number of ordering part numbers available, such as the addition or deletion of a speed option, temperature range, package type, or V_{IO} range. Changes may also include those needed to clarify a description or to correct a typographical error or incorrect specification. Spansion LLC applies the following conditions to documents in this category:

"This document states the current technical specifications regarding the Spansion product(s) described herein. Spansion LLC deems the products to have been in sufficient production volume such that subsequent versions of this document are not expected to change. However, typographical or specification corrections, or modifications to the valid combinations offered may occur."

Questions regarding these document designations may be directed to your local AMD or Fujitsu sales office.



General Description

The S29JL032H is a 32 megabit, 3.0 volt-only flash memory device, organized as 2,097,152 words of 16 bits each or 4,194,304 bytes of 8 bits each. Word mode data appears on DQ15–DQ0; byte mode data appears on DQ7–DQ0. The device is designed to be programmed in-system with the standard 3.0 volt V_{CC} supply, and can also be programmed in standard EPROM programmers.

The device is available with an access time of 60, 70, or 90 ns and is offered in a 48-pin TSOP package. Standard control pins—chip enable (CE#), write enable (WE#), and output enable (OE#)—control normal read and write operations, and avoid bus contention issues.

The device requires only a **single 3.0 volt power supply** for both read and write functions. Internally generated and regulated voltages are provided for the program and erase operations.

Simultaneous Read/Write Operations with Zero Latency

The Simultaneous Read/Write architecture provides **simultaneous operation** by dividing the memory space into separate banks (see Table 2). Sector addresses are fixed, system software can be used to form user-defined bank groups.

During an Erase/Program operation, any of the non-busy banks may be read from. Note that only two banks can operate simultaneously. The device can improve overall system performance by allowing a host system to program or erase in one bank, then immediately and simultaneously read from the other bank, with zero latency. This releases the system from waiting for the completion of program or erase operations.

The S29JL032H can be organized as both a top and bottom boot sector configuration.

S29JL032H Features

The **SecSi™** (Secured Silicon) Sector is an extra 256 byte sector capable of being permanently locked by Spansion or customers. The SecSi Customer Indicator Bit (DQ6) is permanently set to 1 if the part has been customer locked, permanently set to 0 if the part has been factory locked, and is 0 if customer lockable. This way, customer lockable parts can never be used to replace a factory locked part.

Factory locked parts provide several options. The SecSi Sector may store a secure, random 16 byte ESN (Electronic Serial Number), customer code (programmed through Spansion programming services), or both. Customer Lockable parts may utilize the SecSi Sector as bonus space, reading and writing like any other flash sector, or may permanently lock their own code there.

DMS (Data Management Software) allows systems to easily take advantage of the advanced architecture of the simultaneous read/write product line by allowing removal of EEPROM devices. DMS will also allow the system software to be simplified, as it will perform all functions necessary to modify data in file structures, as opposed to single-byte modifications. To write or update a particular piece of data (a phone number or configuration data, for example), the user only needs to state which piece of data is to be updated, and where the updated data is located in the system. This is an advantage compared to systems where user-written software must keep track of the old data location, status, logical to physical translation of the data onto the Flash memory device (or memory devices),



and more. Using DMS, user-written software does not need to interface with the Flash memory directly. Instead, the user's software accesses the Flash memory by calling one of only six functions.

The device offers complete compatibility with the **JEDEC 42.4 single-power-supply Flash command set standard**. Commands are written to the command register using standard microprocessor write timings. Reading data out of the device is similar to reading from other Flash or EPROM devices.

The host system can detect whether a program or erase operation is complete by using the device **status bits:** RY/BY# pin, DQ7 (Data# Polling) and DQ6/DQ2 (toggle bits). After a program or erase cycle has been completed, the device automatically returns to the read mode.

The **sector erase architecture** allows memory sectors to be erased and reprogrammed without affecting the data contents of other sectors. The device is fully erased when shipped from the factory.

Hardware data protection measures include a low V_{CC} detector that automatically inhibits write operations during power transitions. The **hardware sector protection** feature disables both program and erase operations in any combination of the sectors of memory. This can be achieved in-system or via programming equipment.

The device offers two power-saving features. When addresses have been stable for a specified amount of time, the device enters the **automatic sleep mode**. The system can also place the device into the **standby mode**. Power consumption is greatly reduced in both modes.



Table Of Contents

| Notice On Data Sheet Designations Advance Information | |
|--|------------|
| Preliminary | 2 |
| Combination | |
| Full Production (No Designation on Document) | |
| Product Selector Guide | |
| Block Diagram | 6 |
| Connection Diagrams | |
| Pin Description | |
| Logic Symbol | |
| Ordering Information | |
| Device Bus Operations | |
| Table 1. S29JL032H Device Bus Operations | .11 |
| Requirements for Reading Array Data | . 12 |
| Writing Commands/Command Sequences | . 12 |
| Accelerated Program Operation | . 13 |
| Autoselect Functions | . 13 |
| Simultaneous Read/Write Operations with Zero Latency | . 13 |
| Automatic Sleep Mode | |
| RESET#: Hardware Reset Pin | |
| Output Disable Mode | |
| Table 2. S29JL032H Bank Architecture | |
| Table 3. S29JL032H Sector Addresses - Top Boot Devices | |
| Table 4. S29JL032H Sector Addresses - Bottom Boot Devices . | |
| Table 5. S29JL032H Autoselect Codes, (High Voltage Method) | |
| Sector/Sector Block Protection and Unprotection | |
| Table 6. S29JL032H Boot Sector/Sector Block Addresses for Pri tection/Unprotection (Top Boot Devices) | 0- |
| Table 7. S29JL032H Sector/Sector Block Addresses for Protection | .21 0n/ |
| Unprotection (Bottom Boot Devices) | |
| Table 8. WP#/ACC Modes | |
| Temporary Sector Unprotect | 23 |
| Figure 1. Temporary Sector Unprotect Operation | |
| Figure 2. In-System Sector Protect/Unprotect Algorithms | 25 |
| SecSi™ (Secured Silicon) Sector | |
| Flash Memory Region | |
| Hardware Data Protection | |
| Low VCC Write Inhibit | |
| Write Pulse "Glitch" Protection | |
| Logical Inhibit | |
| Power-Up Write Inhibit | |
| Common Flash Memory Interface (CFI) | 27 |
| Table 9. CFI Query Identification String | |
| Table 10. System Interface String Table 11. Device Geometry Definition | .28 |
| Table 11. Device Geometry Definition Table 12. Primary Vendor-Specific Extended Query | |
| Command Definitions | |
| Reading Array Data | |
| Reset Command | |
| Autoselect Command Sequence | |
| Enter SecSi™ Sector/Exit SecSi Sector | 52 |
| Command Sequence | າ |
| Byte/Word Program Command Sequence | |
| Unlock Bypass Command Sequence | |
| Figure 3. Program Operation | |
| Chip Erase Command Sequence | |
| | 51 |

| Sector Erase Command Sequence | |
|---|--|
| Figure 4. Erase Operation | |
| Erase Suspend/Erase Resume Commands | |
| Table 13. S29JL032H Command Definitions | |
| Write Operation Status | |
| DQ7: Data# Polling | |
| Figure 5. Data# Polling Algorithm | |
| DQ6: Toggle Bit I | |
| Figure 6. Toggle Bit Algorithm | |
| DQ2: Toggle Bit II | |
| Reading Toggle Bits DQ6/DQ2 | . 43 |
| DQ5: Exceeded Timing Limits | . 43 |
| DQ3: Sector Erase Timer | |
| Table 14. Write Operation Status | |
| Absolute Maximum Ratings | |
| Figure 7. Maximum Negative Overshoot Waveform | 45 |
| Figure 8. Maximum Positive Overshoot Waveform | |
| Operating Ranges | |
| Industrial (I) Devices | |
| V _{CC} Supply Voltages | |
| | |
| CMOS Compatible | |
| Figure 9. I _{CC1} Current vs. Time (Showing Active and | . 40 |
| Automatic Sleep Currents) | 17 |
| Figure 10. Typical I _{CC1} vs. Frequency | 47 |
| | |
| Figure 11. Test Setup | |
| Key To Switching Waveforms | |
| Figure 12. Input Waveforms and Measurement Levels | |
| AC Characteristics | |
| | 49 |
| | |
| Read-Only Operations | . 49 |
| Read-Only Operations Figure 13. Read Operation Timings | . 49 . 49 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) | . 49 . 49 . 50 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings | . 49 . 49 . 50 . 50 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) | . 49 . 49 . 50 . 50 5 1 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations | . 49 . 50 . 50 51 . 52 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations | . 49 . 50 . 50 51 . 52 . 52 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Erase and Program Operations | . 49 . 50 . 50 51 . 52 . 52 . 52 . 53 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operations Figure 17. Program Operation Timings | . 49 . 50 . 50 . 51 . 52 . 52 . 52 . 53 . 54 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Erase and Program Operations | . 49 . 50 . 50 . 51 . 52 . 52 . 53 . 54 . 54 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 18. Accelerated Program Timing Diagram Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings | . 49 . 50 . 50 . 51 . 52 . 52 . 52 . 53 . 54 . 55 . 55 . 56 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operations Figure 17. Program Operation Timings Figure 18. Accelerated Program Timing Diagram Figure 19. Chip/Sector Erase Operation Timings | . 49 . 50 . 50 . 51 . 52 . 52 . 52 . 53 . 54 . 55 . 55 . 56 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 18. Accelerated Program Timing Diagram Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm | . 49 . 50 . 50 . 52 . 52 . 52 . 53 . 54 . 55 . 56 . 56 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 15. BYTE# Timings for Write Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 18. Accelerated Program Timing Diagram Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithms) | . 49 . 50 . 50 . 52 . 52 . 52 . 54 . 55 . 56 . 55 . 56 . 57 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 18. Accelerated Program Timing Diagram Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 22. Toggle Bit Timings (During Embedded Algorithms) Figure 23. DQ2 vs. DQ6 | . 49 . 49 . 50 . 50 . 51 . 52 . 52 . 52 . 52 . 53 . 54 . 55 . 56 . 57 . 57 . 57 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 15. BYTE# Timings for Write Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 18. Accelerated Program Timing Diagram Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithms) Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect | .49 .49 .50 .50 .52 .52 .52 .53 .54 .55 .56 .57 .57 .57 .58 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram | .49 .49 .50 .50 .52 .52 .52 .53 .54 .55 .56 .57 .57 .57 .58 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram Figure 25. Sector/Sector Block Protect and | . 49 . 49 . 50 . 50 . 52 . 52 . 52 . 52 . 53 . 54 . 55 . 56 . 57 . 58 . 58 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 15. BYTE# Timings for Write Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithms) Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram Figure 25. Sector/Sector Block Protect and Unprotect Timing Diagram | . 49 . 49 . 50 . 50 . 52 . 52 . 52 . 52 . 52 . 53 . 54 . 55 . 56 . 57 . 58 . 58 . 59 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram Figure 25. Sector/Sector Block Protect and Unprotect Timing Diagram | . 49 . 49 . 50 . 50 . 52 . 52 . 52 . 52 . 52 . 53 . 54 . 55 . 56 . 57 . 58 . 58 . 59 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram Figure 25. Sector/Sector Block Protect and Unprotect Timing Diagram Alternate CE# Controlled Erase and Program Operations | .49 .50 .50 .52 .52 .52 .52 .53 .54 .55 .56 .57 .57 .58 .58 .59 .60 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram Figure 25. Sector/Sector Block Protect and Unprotect Timing Diagram Alternate CE# Controlled Erase and Program Operations Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings | .49 .50 .50 .52 .52 .52 .52 .52 .55 .55 .56 .57 .57 .58 .58 .59 .60 .61 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 22. Toggle Bit Timings (During Embedded Algorithms) Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram Figure 25. Sector/Sector Block Protect and Unprotect Timing Diagram Alternate CE# Controlled Erase and Program Operations Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings | .49 .50 .50 .52 .52 .52 .52 .52 .55 .55 .55 .55 .55 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm) Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram Figure 25. Sector/Sector Block Protect and Unprotect Timing Diagram Alternate CE# Controlled Erase and Program Operations Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings | .49 .49 .50 .50 .52 .52 .52 .53 .54 .55 .56 .57 .57 .58 .59 .60 .61 .62 .62 |
| Read-Only Operations Figure 13. Read Operation Timings Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 22. Toggle Bit Timings (During Embedded Algorithms) Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 25. Sector/Sector Block Protect and Unprotect Timing Diagram Alternate CE# Controlled Erase and Program Operations Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings Figure 27. Pin Capacitance | .49 .49 .50 .50 .52 .52 .52 .53 .54 .55 .56 .57 .57 .58 .59 .60 .61 .62 .63 |
| Read-Only Operations Figure 13. Read Operation Timings. Hardware Reset (RESET#) Figure 14. Reset Timings Word/Byte Configuration (BYTE#) Figure 15. BYTE# Timings for Read Operations Figure 16. BYTE# Timings for Write Operations Figure 17. Program Operation Timings Figure 19. Chip/Sector Erase Operation Timings Figure 20. Back-to-back Read/Write Cycle Timings Figure 21. Data# Polling Timings (During Embedded Algorithm Figure 22. Toggle Bit Timings (During Embedded Algorithms) Figure 23. DQ2 vs. DQ6 Temporary Sector Unprotect Figure 24. Temporary Sector Unprotect Timing Diagram Figure 25. Sector/Sector Block Protect and Unprotect Timing Diagram Alternate CE# Controlled Erase and Program Operations Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings | .49 .49 .50 .51 .52 .52 .52 .53 .54 .55 .56 .57 .57 .58 .59 .60 .61 .62 .63 .63 |

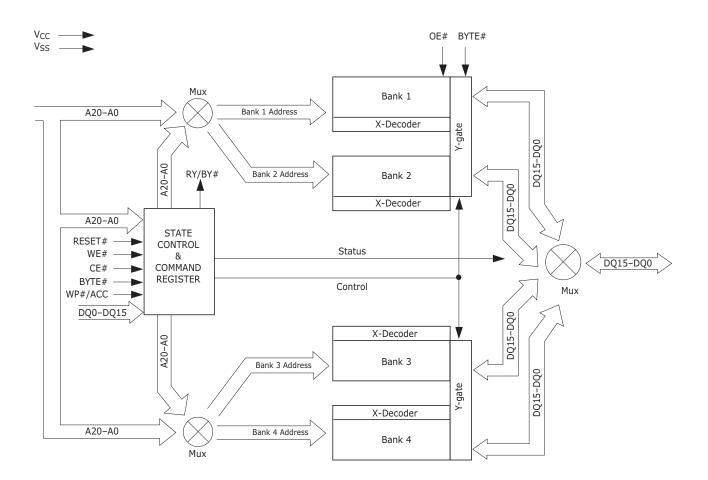


Product Selector Guide

| Part Number | | S29JL032H | | | |
|--------------------------------------|---|-----------|----|----|--|
| Speed Option | Standard Voltage Range: $V_{CC} = 3.0-3.6 V$ | 60 | | | |
| Speed Option | Standard Voltage Range: V _{CC} = 2.7–3.6 V | | 70 | 90 | |
| Max Access Time (ns), t _A | сс | 60 | 70 | 90 | |
| CE# Access (ns), t _{CE} | | 60 | 70 | 90 | |
| OE# Access (ns), t _{OE} | | 25 | 30 | 35 | |

Block Diagram

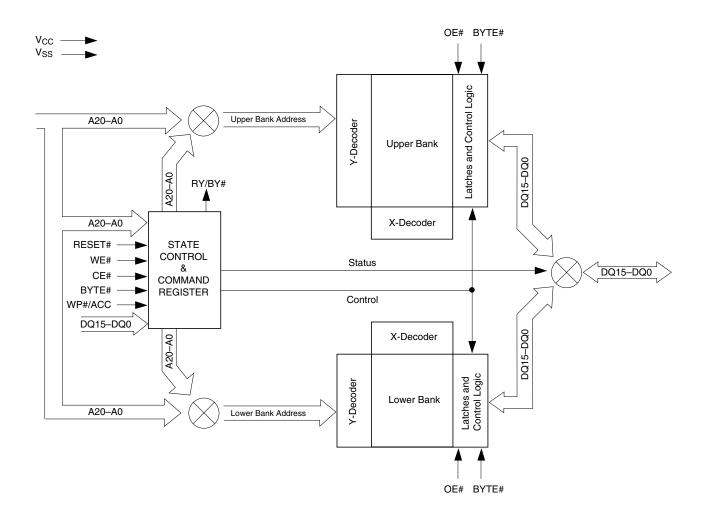
4 Bank Device





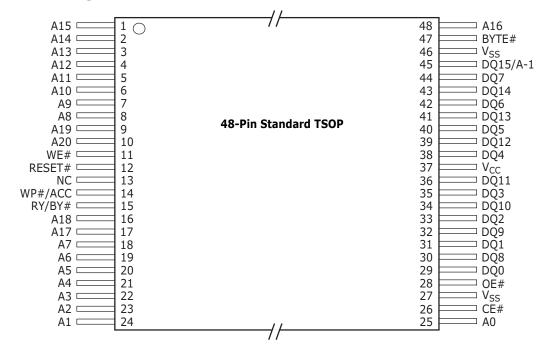
Block Diagram

2 Bank Device





Connection Diagrams

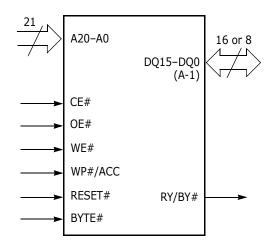




Pin Description

| A20-A0 | = | 21 Addresses |
|-----------------|---|--|
| DQ14-DQ0 | = | 15 Data Inputs/Outputs (x16-only devices) |
| DQ15/A-1 | = | DQ15 (Data Input/Output, word mode), A-1 (LSB Address Input, byte mode) |
| CE# | = | Chip Enable |
| OE# | = | Output Enable |
| WE# | = | Write Enable |
| WP#/ACC | = | Hardware Write Protect/ Acceleration Pin |
| RESET# | = | Hardware Reset Pin, Active Low |
| BYTE# | = | Selects 8-bit or 16-bit mode |
| RY/BY# | = | Ready/Busy Output |
| V _{CC} | = | 3.0 volt-only single power supply (see Product Selector Guide for speed options and voltage supply tolerances) |
| V _{SS} | = | Device Ground |
| NC | = | Pin Not Connected Internally |

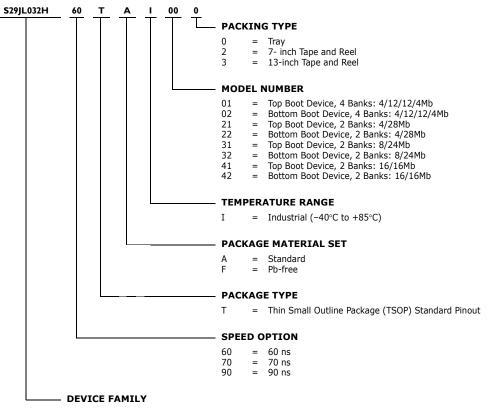
Logic Symbol





Ordering Information

The order number (Valid Combination) is formed by the following:



S29JL032H

3.0 Volt-only, 32 Megabit (2 M x 16-Bit/4 M x 8-Bit) Simultaneous Read/Write Flash Memory Manufactured on 130 nm process technology

| | S29JL032H Valid Combinations | | | | | | | |
|---------------|------------------------------|---|--------------|-------------------------|----------|---------|--|--|
| Device Family | Speed Option | Package, Material, Set and Temperature Range | Model Number | Packing Type | Packag | је Туре | | |
| | | | 01 | | | | | |
| | 60 70 90 (Note 2) | TAI TFI | 02 | 0 2 3 (Note 1) | TS048 TS | | | |
| | | | 21 | | | | | |
| S29JL032H | | | 22 | | | TSOP | | |
| 3295205211 | | | 31 | | | | | |
| | | | 32 | | | | | |
| | | | 41 | | | | | |
| | | | 42 | | | | | |

Note:

- 1. Type 0 is standard. Specify others as required; TSOPs can be packed in Types 0 and 3; BGAs can be packed in Types 0, 2, or 3.
- 2. Operating voltage Vcc varis depending on speed option.

Valid Combinations

Valid Combinations list configurations planned to be supported in volume for this device. Consult your local Spansion sales office to confirm availability of specific valid combinations and to check on newly released combinations.



Device Bus Operations

This section describes the requirements and use of the device bus operations, which are initiated through the internal command register. The command register itself does not occupy any addressable memory location. The register is a latch used to store the commands, along with the address and data information needed to execute the command. The contents of the register serve as inputs to the internal state machine. The state machine outputs dictate the function of the device. Table 1 lists the device bus operations, the inputs and control levels they require, and the resulting output. The following subsections describe each of these operations in further detail.

| | | | | | | | DQ15-DQ8 | | |
|-------------------------------|----------------------------|-----|-----|----------------------------|----------|-------------------------------|----------------------------|-------------------------|------------------|
| Operation | CE# | OE# | WE# | RESET# | WP#/ACC | Addresses (Note 1) | BYTE# = V _{IH} | BYTE# = V _{IL} | DQ7-DQ0 |
| Read | L | L | Н | Н | L/H | A _{IN} | D _{OUT} | DQ14-DQ8 = High- | D _{OUT} |
| Write | L | Н | L | Н | (Note 3) | A _{IN} | D _{IN} | Z, DQ15 = A-1 | D _{IN} |
| Standby | V _{CC} ± 0.3 V | х | х | V _{CC} ± 0.3 V | L/H | х | High-Z | High-Z | High-Z |
| Output Disable | L | н | Н | Н | L/H | Х | High-Z | High-Z | High-Z |
| Reset | Х | Х | Х | L | L/H | Х | High-Z | High-Z | High-Z |
| Sector Protect (Note 2) | L | Н | L | V_{ID} | L/H | SA, A6 = L, A1 = H, A0 = L | х | х | D _{IN} |
| Sector Unprotect (Note 2) | L | Н | L | V_{ID} | (Note 3) | SA, A6 = H, A1 = H, A0 = L | х | х | D _{IN} |
| Temporary Sector Unprotect | Х | Х | х | V_{ID} | (Note 3) | A _{IN} | D_{IN} | High-Z | D _{IN} |

Table 1. S29JL032H Device Bus Operations

Legend: $L = Logic Low = V_{IL}$, $H = Logic High = V_{IH}$, $V_{ID} = 11.5-12.5 V$, $V_{HH} = 9.0 \pm 0.5 V$, X = Don't Care, SA = Sector Address, $A_{IN} = Address In$, $D_{IN} = Data In$, $D_{OUT} = Data Out$

Notes:

- 1. Addresses are A20:A0 in word mode (BYTE# = V_{IH}), A20:A-1 in byte mode (BYTE# = V_{IL}).
- 2. The sector protect and sector unprotect functions may also be implemented via programming equipment. See the "Sector/Sector Block Protection and Unprotection" section.
- 3. If $WP#/ACC = V_{IL}$, the two outermost boot sectors remain protected. If $WP#/ACC = V_{IH}$, protection on the two outermost boot sectors depends on whether they were last protected or unprotected using the method described in "Sector/Sector Block Protection and Unprotection". If $WP#/ACC = V_{HH}$, all sectors will be unprotected.



Word/Byte Configuration

The BYTE# pin controls whether the device data I/O pins operate in the byte or word configuration. If the BYTE# pin is set at logic `1', the device is in word configuration, DQ15–DQ0 are active and controlled by CE# and OE#.

If the BYTE# pin is set at logic '0', the device is in byte configuration, and only data I/O pins DQ7–DQ0 are active and controlled by CE# and OE#. The data I/O pins DQ14–DQ8 are tri-stated, and the DQ15 pin is used as an input for the LSB (A-1) address function.

Requirements for Reading Array Data

To read array data from the outputs, the system must drive the CE# and OE# pins to V_{IL}. CE# is the power control and selects the device. OE# is the output control and gates array data to the output pins. WE# should remain at V_{IH}. The BYTE# pin determines whether the device outputs array data in words or bytes.

The internal state machine is set for reading array data upon device power-up, or after a hardware reset. This ensures that no spurious alteration of the memory content occurs during the power transition. No command is necessary in this mode to obtain array data. Standard microprocessor read cycles that assert valid addresses on the device address inputs produce valid data on the device data outputs. Each bank remains enabled for read access until the command register contents are altered.

Refer to the AC Read-Only Operations table for timing specifications and to Figure 13 for the timing diagram. I_{CC1} in the DC Characteristics table represents the active current specification for reading array data.

Writing Commands/Command Sequences

To write a command or command sequence (which includes programming data to the device and erasing sectors of memory), the system must drive WE# and CE# to V_{IL} , and OE# to V_{IH} .

For program operations, the BYTE# pin determines whether the device accepts program data in bytes or words. Refer to "Word/Byte Configuration" for more information.

The device features an **Unlock Bypass** mode to facilitate faster programming. Once a bank enters the Unlock Bypass mode, only two write cycles are required to program a word or byte, instead of four. The "Byte/Word Program Command Sequence" section has details on programming data to the device using both standard and Unlock Bypass command sequences.

An erase operation can erase one sector, multiple sectors, or the entire device. Tables 3 and 4 indicate the address space that each sector occupies. Similarly, a "sector address" is the address bits required to uniquely select a sector. The "Command Definitions" section has details on erasing a sector or the entire chip, or suspending/resuming the erase operation.

The device address space is divided into four banks. A "bank address" is the address bits required to uniquely select a bank.

 $\rm I_{CC2}$ in the DC Characteristics table represents the active current specification for the write mode. The AC Characteristics section contains timing specification tables and timing diagrams for write operations.



Accelerated Program Operation

The device offers accelerated program operations through the ACC function. This is one of two functions provided by the WP#/ACC pin. This function is primarily intended to allow faster manufacturing throughput at the factory.

If the system asserts V_{HH} on this pin, the device automatically enters the aforementioned Unlock Bypass mode, temporarily unprotects any protected sectors, and uses the higher voltage on the pin to reduce the time required for program operations. The system would use a two-cycle program command sequence as required by the Unlock Bypass mode. Removing V_{HH} from the WP#/ACC pin returns the device to normal operation. Note that V_{HH} must not be asserted on WP#/ACC for operations other than accelerated programming, or device damage may result. In addition, the WP#/ACC pin must not be left floating or unconnected; inconsistent behavior of the device may result. See "Write Protect (WP#)" for related information.

Autoselect Functions

If the system writes the autoselect command sequence, the device enters the autoselect mode. The system can then read autoselect codes from the internal register (which is separate from the memory array) on DQ15–DQ0. Standard read cycle timings apply in this mode. Refer to the Autoselect Mode and Autoselect Command Sequence sections for more information.

Simultaneous Read/Write Operations with Zero Latency

This device is capable of reading data from one bank of memory while programming or erasing in the other bank of memory. An erase operation may also be suspended to read from or program to another location within the same bank (except the sector being erased). Figure 20 shows how read and write cycles may be initiated for simultaneous operation with zero latency. I_{CC6} and I_{CC7} in the DC Characteristics table represent the current specifications for read-while-program and read-while-erase, respectively.





Standby Mode

When the system is not reading or writing to the device, it can place the device in the standby mode. In this mode, current consumption is greatly reduced, and the outputs are placed in the high impedance state, independent of the OE# input.

The device enters the CMOS standby mode when the CE# and RESET# pins are both held at V_{CC} \pm 0.3 V. (Note that this is a more restricted voltage range than V_{IH}.) If CE# and RESET# are held at V_{IH}, but not within V_{CC} \pm 0.3 V, the device will be in the standby mode, but the standby current will be greater. The device requires standard access time (t_{CE}) for read access when the device is in either of these standby modes, before it is ready to read data.

If the device is deselected during erasure or programming, the device draws active current until the operation is completed.

 I_{CC3} in the DC Characteristics table represents the standby current specification.

Automatic Sleep Mode

The automatic sleep mode minimizes Flash device energy consumption. The device automatically enables this mode when addresses remain stable for t_{ACC} + 30 ns. The automatic sleep mode is independent of the CE#, WE#, and OE# control signals. Standard address access timings provide new data when addresses are changed. While in sleep mode, output data is latched and always available to the system. I_{CC5} in the DC Characteristics table represents the automatic sleep mode current specification.

RESET#: Hardware Reset Pin

The RESET# pin provides a hardware method of resetting the device to reading array data. When the RESET# pin is driven low for at least a period of t_{RP} , the device immediately terminates any operation in progress, tristates all output pins, and ignores all read/write commands for the duration of the RESET# pulse. The device also resets the internal state machine to reading array data. The operation that was interrupted should be reinitiated once the device is ready to accept another command sequence, to ensure data integrity.

Current is reduced for the duration of the RESET# pulse. When RESET# is held at $V_{SS}\pm0.3$ V, the device draws CMOS standby current (I_{CC4}). If RESET# is held at V_{IL} but not within $V_{SS}\pm0.3$ V, the standby current will be greater.

The RESET# pin may be tied to the system reset circuitry. A system reset would thus also reset the Flash memory, enabling the system to read the boot-up firmware from the Flash memory.

If RESET# is asserted during a program or erase operation, the RY/BY# pin remains a "0" (busy) until the internal reset operation is complete, which requires a time of t_{READY} (during Embedded Algorithms). The system can thus monitor RY/ BY# to determine whether the reset operation is complete. If RESET# is asserted when a program or erase operation is not executing (RY/BY# pin is "1"), the reset operation is completed within a time of t_{READY} (not during Embedded Algorithms). The system can read data t_{RH} after the RESET# pin returns to V_{IH} .

Refer to the AC Characteristics tables for RESET# parameters and to Figure 14 for the timing diagram.



Output Disable Mode

When the OE# input is at $V_{\rm IH},$ output from the device is disabled. The output pins are placed in the high impedance state.

| Device Model Numbers | Bank 1 | | Bank 2 | | Bank 3 | | Bank 4 | |
|----------------------------|----------|---|----------|--------------------------------------|----------|--------------------------------------|----------|-----------------------------|
| | Megabits | Sector Size | Megabits | Sector Size | Megabits | Sector Size | Megabits | Sector Size |
| 01, 02 | 4 Mbit | Eight 8 Kbyte/ 4 Kword, seven 64 Kbyte/ 32 Kword | 12 Mbit | Twenty-four 64 Kbyte/ 32 Kword | 12 Mbit | Twenty-four 64 Kbyte/ 32 Kword | 4 Mbit | Eight 64 Kbyte/ 32 Kword |

| Table 2. | S29JL032H Bank Architecture |
|----------|-----------------------------|
| 14510 11 | |

| Device | | Bank 1 | Bank 2 | | | |
|------------------|----------|--|----------|----------------------------------|--|--|
| Model Numbers | Megabits | Sector Sizes | Megabits | Sector Sizes | | |
| 21, 22 | 4 Mbit | Eight 8 Kbyte/4 Kword, seven 64 Kbyte/32 Kword | 28 Mbit | Fifty-six 64 Kbyte/32 Kword | | |
| 31, 32 | 8 Mbit | Eight 8 Kbyte/4 Kword, fifteen 64 Kbyte/32 Kword | 24 Mbit | Forty-eight 64 Kbyte/32 Kword | | |
| 41, 42 | 16 Mbit | Eight 8 Kbyte/4 Kword, thirty-one 64 Kbyte/32 Kword | 16 Mbit | Thirty-two 64 Kbyte/32 Kword | | |



| S29JL032H (Model 41) | S29JL032H (Model 31) | S29JL032H (Model 21) | S29JL032H (Model 01) | Sector | Sector Address A20-A12 | Sector Size (Kbytes/ Kwords) | (x8) Address Range | (x16) Address Range |
|----------------------|----------------------|----------------------|----------------------|--------------|---------------------------|------------------------------------|------------------------------------|------------------------------------|
| | | | | SA0 | 000000xxx | 64/32 | 000000h-00FFFFh | 000000h-07FFFh |
| | | | | SA1 | 000001xxx | 64/32 | 010000h-01FFFFh | 008000h-0FFFFh |
| | | | 4 | SA2 | 000010xxx | 64/32 | 020000h-02FFFFh | 010000h-17FFFh |
| | | | | SA3 | 000011xxx | 64/32 | 030000h-03FFFFh | 018000h-01FFFFh |
| | | | Bank | SA4 | 000100xxx | 64/32 | 040000h-04FFFFh | 020000h-027FFFh |
| | | | - | SA5 | 000101xxx | 64/32 | 050000h-05FFFFh | 028000h-02FFFFh |
| | | | | SA6 | 000110xxx | 64/32 | 060000h-06FFFFh | 030000h-037FFFh |
| | | | | SA7 | 000111xxx | 64/32 | 070000h-07FFFFh | 038000h-03FFFFh |
| | | | | SA8 | 001000xxx | 64/32 | 080000h-08FFFFh | 040000h-047FFFh |
| | | | | SA9 | 001001xxx | 64/32 | 090000h-09FFFFh | 048000h-04FFFFh |
| | | | | SA10 | 001010xxx | 64/32 | 0A0000h-0AFFFFh | 050000h-057FFFh |
| | | | | SA11 | 001011xxx | 64/32 | 0B0000h-0BFFFFh | 058000h-05FFFFh |
| | | | | SA12 | 001100xxx | 64/32 | 0C0000h-0CFFFFh | 060000h-067FFh |
| | | | | SA13 | 001101xxx | 64/32 | 0D0000h-0DFFFFh | 068000h-06FFFFh |
| 2 | 2 | 2 | | SA14 | 001110xxx | 64/32 | 0E0000h-0EFFFFh | 070000h-077FFFh |
| Bank | Bank | Bank | | SA15 | 001111xxx | 64/32 | 0F0000h-0FFFFh | 078000h-07FFFh |
| Bai | Bal | Bai | | SA16 | 010000xxx | 64/32 | 100000h-10FFFFh | 080000h-087FFFh |
| | | | | SA17 | 010001xxx | 64/32 | 110000h-11FFFFh | 088000h-08FFFFh |
| | | | m | SA18 | 010010xxx | 64/32 | 120000h-12FFFFh | 090000h-097FFFh |
| | | | ank | SA19 | 010011xxx | 64/32 | 130000h-13FFFFh | 098000h-09FFFFh |
| | | | Ba | SA20 SA21 | 010100xxx | 64/32 | 140000h-14FFFFh | 0A0000h-0A7FFFh |
| | | | | | 010101xxx | 64/32 | 150000h-15FFFFh | 0A8000h-0AFFFh |
| | | | | SA22 SA23 | 010110xxx 010111xxx | 64/32 64/32 | 160000h-16FFFFh 170000h-17FFFFh | 0B0000h-0B7FFFh 0B8000h-0BFFFFh |
| | | | | SA23 | 010111xxx 011000xxx | 64/32 | 180000h-18FFFFh | 0C0000h-0C7FFFh |
| | | | | SA24 SA25 | 011000xxx 011001xxx | 64/32 | 190000h-19FFFFh | 0C8000h-0CFFFFh |
| | | | | SA25 | 011001xxx 011010xxx | 64/32 | 190000h-19FFFh | 0D0000h-0D7FFFh |
| | | | | SA20 | 011010xxx 011011xxx | 64/32 | 1B0000h-1BFFFFh | 0D0000h-0D7FFFh |
| | | | | SA27 | 011100xxx | 64/32 | 1C0000h-1CFFFFh | 0E0000h-0E7FFFh |
| | | | | SA28 | 011100xxx 011101xxx | 64/32 | 1D0000h-1DFFFFh | 0E8000h-0EFFFFh |
| | | | | SA29 SA30 | 011101XXX 011110XXX | 64/32 | 1E0000h-1EFFFFh | 0F0000h-0F7FFFh |
| | | | | SA30 | 011110XXX 011111XXX | 64/32 | 1F0000h-1FFFFFh | 0F8000h-0FFFFFh |
| L | | | | 3431 | 011111/// | 07/32 | 1.00001-1111111 | |



| Table 3. | S29JL032H Sector Addresses - | • Top Boot Devices | (Continued) |
|----------|------------------------------|--------------------|-------------|
|----------|------------------------------|--------------------|-------------|

| | ~ | ~ | | | | | | |
|----------------------|----------------------|----------------------|----------------------|--------|---------------------------|------------------------------------|-----------------------|------------------------|
| S29JL032H (Model 41) | S29JL032H (Model 31) | S29JL032H (Model 21) | S29JL032H (Model 01) | Sector | Sector Address A20–A12 | Sector Size (Kbytes/ Kwords) | (×8) Address Range | (x16) Address Range |
| | | | | SA32 | 100000xxx | 64/32 | 200000h-20FFFFh | 100000h-107FFFh |
| | | | | SA33 | 100001xxx | 64/32 | 210000h-21FFFFh | 108000h-10FFFFh |
| | | | | SA34 | 100010xxx | 64/32 | 220000h-22FFFFh | 110000h-117FFFh |
| | | | | SA35 | 100011xxx | 64/32 | 230000h-23FFFFh | 118000h-11FFFFh |
| | | | | SA36 | 100100xxx | 64/32 | 240000h-24FFFFh | 120000h-127FFFh |
| | (p | | | SA37 | 100101xxx | 64/32 | 250000h-25FFFFh | 128000h-12FFFFh |
| | (cont'd) | | | SA38 | 100110xxx | 64/32 | 260000h-26FFFFh | 130000h-137FFFh |
| | 8 | | | SA39 | 100111xxx | 64/32 | 270000h-27FFFFh | 138000h-13FFFFh |
| | Ν | | | SA40 | 101000xxx | 64/32 | 280000h-28FFFFh | 140000h-147FFFh |
| | Bank | (p | | SA41 | 101001xxx | 64/32 | 290000h-29FFFFh | 148000h-14FFFFh |
| | Ba | (cont' | 8 | SA42 | 101010xxx | 64/32 | 2A0000h-2AFFFFh | 150000h-157FFFh |
| | | 8 | ¥ | SA43 | 101011xxx | 64/32 | 2B0000h-2BFFFFh | 158000h-15FFFFh |
| | | Bank 2 (| Bank | SA44 | 101100xxx | 64/32 | 2C0000h-2CFFFFh | 160000h-167FFFh |
| | | | - | SA45 | 101101xxx | 64/32 | 2D0000h-2DFFFFh | 168000h-16FFFFh |
| | | | | SA46 | 101110xxx | 64/32 | 2E0000h-2EFFFFh | 170000h-177FFFh |
| | | | | SA47 | 101111xxx | 64/32 | 2F0000h-2FFFFFh | 178000h-17FFFFh |
| | | | | SA48 | 110000xxx | 64/32 | 300000h-30FFFFh | 180000h-187FFFh |
| | | | | SA49 | 110001xxx | 64/32 | 310000h-31FFFFh | 188000h-18FFFFh |
| - | | | | SA50 | 110010xxx | 64/32 | 320000h-32FFFFh | 190000h-197FFFh |
| Bank | | | | SA51 | 110011xxx | 64/32 | 330000h-33FFFFh | 198000h-19FFFFh |
| Ba | | | | SA52 | 110100xxx | 64/32 | 340000h-34FFFFh | 1A0000h-1A7FFFh |
| | | | | SA53 | 110101xxx | 64/32 | 350000h-35FFFFh | 1A8000h-1AFFFFh |
| | | | | SA54 | 110110xxx | 64/32 | 360000h-36FFFFh | 1B0000h-1BFFFFh |
| | | | | SA55 | 110111xxx | 64/32 | 370000h-37FFFFh | 1B8000h-1BFFFFh |
| | | | | SA56 | 111000xxx | 64/32 | 380000h-38FFFFh | 1C0000h-1C7FFFh |
| | | | | SA57 | 111001xxx | 64/32 | 390000h-39FFFFh | 1C8000h-1CFFFFh |
| | 1 | | | SA58 | 111010xxx | 64/32 | 3A0000h-3AFFFFh | 1D0000h-1DFFFFh |
| | Bank | | | SA59 | 111011xxx | 64/32 | 3B0000h-3BFFFFh | 1D8000h-1DFFFFh |
| | ä | | | SA60 | 111100xxx | 64/32 | 3C0000h-3CFFFFh | 1E0000h-1E7FFFh |
| | | | | SA61 | 111101xxx | 64/32 | 3D0000h-3DFFFFh | 1E8000h-1EFFFFh |
| | | (1 | | SA62 | 111110xxx | 64/32 | 3E0000h-3EFFFFh | 1F0000h-1F7FFFh |
| | | Bank | Bank | SA63 | 111111000 | 8/4 | 3F0000h-3F1FFFh | 1F8000h-1F8FFFh |
| | | ä | ä | SA64 | 111111001 | 8/4 | 3F2000h-3F3FFFh | 1F9000h-1F9FFFh |
| | | | | SA65 | 111111010 | 8/4 | 3F4000h-3F5FFFh | 1FA000h-1FAFFFh |
| | | | | SA66 | 111111011 | 8/4 | 3F6000h-3F7FFFh | 1FB000h-1FBFFFh |
| | | | | SA67 | 111111100 | 8/4 | 3F8000h-3F9FFFh | 1FC000h-1FCFFFh |
| | | | | SA68 | 111111101 | 8/4 | 3FA000h-3FBFFFh | 1FD000h-1FDFFFh |
| | | | | SA69 | 111111110 | 8/4 | 3FC000h-3FDFFFh | 1FE000h-1FEFFFh |
| | | | | SA70 | 111111111 | 8/4 | 3FE000h-3FFFFFh | 1FF000h-1FFFFh |



| Table 4. | S29JL032H | Sector Addresses | - Bottom | Boot Devices |
|----------|-----------|------------------|----------|---------------------|
|----------|-----------|------------------|----------|---------------------|

| 42) | 32) | 22) | 02) | | | | | |
|--------------------|--------------------|--------------------|--------------------|--|---|--|--|--|
| S29JL032H (Model 4 | S29JL032H (Model 3 | S29JL032H (Model 2 | S29JL032H (Model 0 | Sector | Sector Address A20-A12 | Sector Size (Kbytes/ Kwords) | (x8) Address Range | (x16) Address Range |
| | | | | SA0 | 00000000 | 8/4 | 000000h-001FFFh | 000000h-000FFFh |
| | | | | SA1 | 00000001 | 8/4 | 002000h-003FFFh | 001000h-001FFFh |
| | | | | SA2 | 00000010 | 8/4 | 004000h-005FFFh | 002000h-002FFFh |
| | | | | SA3 | 00000011 | 8/4 | 006000h-007FFFh | 003000h-003FFFh |
| | | | | SA4 | 00000100 | 8/4 | 008000h-009FFFh | 004000h-004FFFh |
| | | | | SA5 | 00000101 | 8/4 | 00A000h-00BFFFh | 005000h-005FFFh |
| | | < 1 | < 1 | SA6 | 00000110 | 8/4 | 00C000h-00DFFFh | 006000h-006FFFh |
| | | Bank | Bank | SA7 | 000000111 | 8/4 | 00E000h-00FFFFh | 007000h-007FFFh |
| | | 8 | 8 | SA8 | 000001xxx 000010xxx | 64/32 | 010000h-01FFFFh 020000h-02FFFFh | 008000h-00FFFFh |
| | | | | SA9 SA10 | 000010xxx 000011xxx | 64/32 64/32 | 020000h-02FFFFh 030000h-03FFFFh | 010000h-017FFFh 018000h-01FFFFh |
| | k 1 | | | SA10 SA11 | 000011xxx 000100xxx | 64/32 | 040000h-04FFFFh | 020000h-027FFFh |
| | Bank | | | SA11 SA12 | 000100xxx 000101xxx | 64/32 | 050000h-05FFFFh | 028000h-02FFFFh |
| | - | | | SA12 SA13 | 000101XXX 000110XXX | 64/32 | 060000h-06FFFFh | 030000h-037FFFh |
| | | | | SA15 | 000111xxx | 64/32 | 070000h-07FFFFh | 038000h-03FFFFh |
| | | | | | | | | |
| | | | | | | | | |
| | | | | SA17 | 001010xxx | | 0A0000h-0AFFFFh | 050000h-057FFFh |
| - | | | | SA18 | 001011xxx | 64/32 | 0B0000h-0BFFFFh | 058000h-05FFFFh |
| hk | | | | SA19 | 001100xxx | 64/32 | 0C0000h-0CFFFFh | 060000h-067FFFh |
| Ba | | | | SA20 | 001101xxx | 64/32 | 0D0000h-0DFFFFh | 068000h-06FFFFh |
| | | | | SA21 | 001110xxx | 64/32 | 0E0000h-0EFFFFh | 070000h-077FFFh |
| | | | | SA22 | 001111xxx | 64/32 | 0F0000h-0FFFFFh | 078000h-07FFFFh |
| | | | | SA23 | 010000xxx | | 100000h-10FFFFh | 080000h-087FFFh |
| | | | | | | • | | |
| | | 2 | 2 | | | | | |
| | | | | | | | | |
| | | Bai | Bai | - | | | | |
| | | | | | | • | | |
| | 2 | | | | | | | |
| | h | | | | | | | |
| | Ba | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| | | | | SA37 | 011110xxx | | 1E0000h-1EFFFFh | 0F0000h-0F7FFFh |
| | | | | SA38 | 011111xxx | 64/32 | 1F0000h-1FFFFFh | 0F8000h-0FFFFFh |
| Bank 1 | ank | Bank 2 | Bank 2 | SA15 SA16 SA17 SA18 SA19 SA20 SA21 SA22 SA23 SA24 SA25 SA26 SA27 SA28 SA29 SA30 SA31 SA32 SA33 SA34 SA35 SA36 SA37 | 001000xxx 001001xxx 001010xxx 001011xxx 001100xxx 001101xxx 001110xxx 001110xxx 001111xxx 010000xxx 010010xxx 010010xxx 010010xxx 010110xxx 010111xxx 011010xxx 011011xxx 011011xxx 011011xxx 011011xxx 011100xxx 011110xxx 011110xxx 011110xxx 011110xxx | 64/32 | 080000h-08FFFFh 090000h-09FFFFh 0A0000h-0AFFFFh 0B0000h-0BFFFFh 0C0000h-0CFFFFh 0E0000h-0EFFFFh 0F0000h-0FFFFFh 100000h-10FFFFh 120000h-10FFFFh 120000h-12FFFFh 130000h-13FFFFh 140000h-13FFFFh 150000h-15FFFFh 160000h-16FFFFh 180000h-18FFFFh 180000h-18FFFFh 1B0000h-1BFFFFh 1C0000h-1CFFFFh 1D0000h-1DFFFFh 1E0000h-1EFFFFh | 040000h-047FFFh 048000h-04FFFFh 050000h-057FFFh 060000h-057FFFh 068000h-067FFFh 070000h-077FFFh 078000h-077FFFh 078000h-077FFFh 088000h-087FFFh 098000h-087FFFh 098000h-097FFFh 098000h-097FFFh 0A0000h-0A7FFFh 0B8000h-0B7FFFh 0B8000h-0B7FFFh 0C0000h-0C7FFFh 0D8000h-0D7FFFh 0D8000h-0D7FFFh 0E8000h-0E7FFFh 0E8000h-0E7FFFh |



| Table 4. | S29JL032H Sector | Addresses - Bottom | Boot Devices | (Continued) |
|----------|------------------|--|--------------|-------------|
|----------|------------------|--|--------------|-------------|

| S29JL032H (Model 42) | S29JL032H (Model 32) | S29JL032H (Model 22) | S29JL032H (Model 02) | Sector | Sector Address A20-A12 | Sector Size (Kbytes/ Kwords) | (x8) Address Range | (x16) Address Range |
|----------------------|----------------------|----------------------|----------------------|--------------|---------------------------|------------------------------------|------------------------------------|------------------------------------|
| | | | | SA39 | 100000xxx | 64/32 | 200000h-20FFFFh | 100000h-107FFFh |
| | | | | SA40 | 100001xxx | 64/32 | 210000h-21FFFFh | 108000h-10FFFFh |
| | | | | SA41 | 100010xxx | 64/32 | 220000h-22FFFFh | 110000h-117FFFh |
| | | | | SA42 | 100011xxx | 64/32 | 230000h-23FFFFh | 118000h-11FFFFh |
| | | | | SA43 | 100100xxx | 64/32 | 240000h-24FFFFh | 120000h-127FFFh |
| | | | | SA44 | 100101xxx | 64/32 | 250000h-25FFFFh | 128000h-12FFFFh |
| | | | | SA45 | 100110xxx | 64/32 | 260000h-26FFFFh | 130000h-137FFFh |
| | | | | SA46 | 100111xxx | 64/32 | 270000h-27FFFFh | 138000h-13FFFFh |
| | | | | SA47 | 101000xxx | 64/32 | 280000h-28FFFFh | 140000h-147FFFh |
| | | | | SA48 | 101001xxx | 64/32 | 290000h-29FFFFh | 148000h-14FFFFh |
| | | | m | SA49 | 101010xxx | 64/32 | 2A0000h-2AFFFFh | 150000h-157FFFh |
| | | | ¥ | SA50 | 101011xxx | 64/32 | 2B0000h-2BFFFFh | 158000h-15FFFFh |
| | | | Bank | SA51 | 101100xxx | 64/32 | 2C0000h-2CFFFFh | 160000h-167FFh |
| | (p | (p) | _ | SA52 | 101101xxx | 64/32 | 2D0000h-2DFFFFh | 168000h-16FFFFh |
| 2 | out | (cont'd) | | SA53 | 101110xxx | 64/32 | 2E0000h-2EFFFFh | 170000h-177FFFh |
| Bank | 2 (cont'd) | Ŭ | | SA54 | 110111xxx | 64/32 | 2F0000h-2FFFFh | 178000h-17FFFFh |
| Bai | 2 | 2 | | SA55 | 111000xxx | 64/32 | 300000h-30FFFFh | 180000h-187FFh |
| | Bank | Bank | | SA56 | 110001xxx | 64/32 | 310000h-31FFFFh | 188000h-18FFFFh |
| | ä | ä | | SA57 | 110010xxx | 64/32 | 320000h-32FFFFh | 190000h-197FFh |
| | | | | SA58 | 110011xxx | 64/32 | 330000h-33FFFFh | 198000h-19FFFh |
| | | | | SA59 | 110100xxx | 64/32 | 340000h-34FFFFh | 1A0000h-1A7FFh |
| | | | | SA60 | 110101xxx | 64/32 | 350000h-35FFFFh | 1A8000h-1AFFFh |
| | | | | SA61 SA62 | 110110xxx 110111xxx | 64/32 64/32 | 360000h-36FFFFh 370000h-37FFFFh | 1B0000h-1B7FFFh 1B8000h-1BFFFFh |
| | | | | SA62 SA63 | 111000xxx | 64/32 | 370000h-37FFFh 380000h-38FFFFh | 1C0000h-1C7FFFh |
| | | | | SA63 | 111000xxx 111001xxx | 64/32 | 390000h-39FFFFh | 1C8000h-1CFFFFh |
| | | | | SA65 | 111001xxx 111010xxx | 64/32 | 3A0000h-3AFFFFh | 1D0000h-1D7FFh |
| | | | 4 | SA65 SA66 | 111010xxx 111011xxx | 64/32 | 3B0000h-3BFFFFh | 1D8000h-1DFFFFh |
| | | | Bank | SA60 | 111011XXX 111100XXX | 64/32 | 3C0000h-3CFFFFh | 1E0000h-1E7FFFh |
| | | | Ba | SA67 | 111100xxx 111101xxx | 64/32 | 3D0000h-3DFFFFh | 1E8000h-1EFFFFh |
| | | | | SA69 | 111101XXX 111110XXX | 64/32 | 3E0000h-3EFFFFh | 1F0000h-1F7FFFh |
| | | | | SA05 | 111110xxx | 64/32 | 3F0000h-3F1FFFh | 1F8000h-1FFFFFh |
| L | | | | 5470 | 111111/// | UT/ JZ | 5100001-5111111 | 11000011-1111111 |



Autoselect Mode

The autoselect mode provides manufacturer and device identification, and sector protection verification, through identifier codes output on DQ7–DQ0. This mode is primarily intended for programming equipment to automatically match a device to be programmed with its corresponding programming algorithm. However, the autoselect codes can also be accessed in-system through the command register.

When using programming equipment, the autoselect mode requires V_{ID} on address pin A9. Address pins must be as shown in Table 5. In addition, when verifying sector protection, the sector address must appear on the appropriate highest order address bits. Table 5 shows the remaining address bits that are don't care. When all necessary bits have been set as required, the programming equipment may then read the corresponding identifier code on DQ7–DQ0. However, the autoselect codes can also be accessed in-system through the command register, for instances when the S29JL032H is erased or programmed in a system without access to high voltage on the A9 pin. The command sequence is illustrated in Table 13. Note that if a Bank Address (BA) on address bits A20, A19 and A18 is asserted during the third write cycle of the autoselect command, the host system can read autoselect data from that bank and then immediately read array data from another bank, without exiting the autoselect mode.

To access the autoselect codes in-system, the host system can issue the autoselect command via the command register, as shown in Table 13. This method does not require $V_{\rm ID}.$ Refer to the Autoselect Command Sequence section for more information.

| | | | | | A20 | A11 | | A 8 | | A5 | | | | | DQ15 | to DQ8 | DQ7 |
|---------------------------------------|-----------------------------|-----|-----|-----|-----------|-----------|-----------------|------------|----|----------|----|----|----|----|----------------------------|----------------------------|--|
| C | Description | CE# | OE# | WE# | to A12 | to A10 | A9 | to A7 | A6 | to A4 | A3 | A2 | A1 | A0 | BYTE# = V _{IH} | BYTE# = V _{IL} | to DQ0 |
| Manufacturer ID: Spansion Products | | L | L | Н | BA | х | V_{ID} | х | L | х | L | L | L | L | х | х | 01h |
| 02) | Read Cycle 1 | | | | | | | | L | | L | L | L | Н | 22h | | 7Eh |
| Device ID odels 01, | Read Cycle 2 | L | L | н | ва | х | V _{ID} | х | L | x | H | H | H | L | 22h | x | 0Ah |
| Device II (Models 01, | Read Cycle 3 | - | - | | DA | Χ | • ID | λ | L | Λ | н | Н | Н | Н | 22h | Λ | 00h (bottom boot) 01h (top boot) |
| | Device ID odels 21, 22) | L | L | Н | BA | х | V_{ID} | х | L | х | х | х | L | н | 22h | х | 56h (bottom boot) 55h (top boot) |
| | Device ID odels 31, 32) | L | L | Н | BA | Х | V_{ID} | х | L | х | х | х | L | н | 22h | х | 53h (bottom boot) 50h (top boot) |
| | Device ID odels 41, 42) | L | L | Н | BA | х | V_{ID} | х | L | х | х | х | L | н | 22h | х | 5Fh (bottom boot) 5Ch (top boot) |
| | or Protection ication | L | L | Н | SA | х | V_{ID} | х | L | х | L | L | Н | L | х | х | 01h (protected), 00h (unprotected) |
| | Si Indicator Bit 5, DQ7) | L | L | Н | ВА | x | V _{ID} | х | L | x | L | L | Н | Н | x | х | 82h (factory locked), 42h (customer locked), 02h (not factory/customer locked) |

Table 5. S29JL032H Autoselect Codes, (High Voltage Method)

Legend: $L = Logic Low = V_{IL}$, $H = Logic High = V_{IH}$, BA = Bank Address, SA = Sector Address, X = Don't care.



Sector/Sector Block Protection and Unprotection

Note: For the following discussion, the term "sector" applies to both sectors and sector blocks. A sector block consists of two or more adjacent sectors that are protected or unprotected at the same time (see Table 6).

The hardware sector protection feature disables both program and erase operations in any sector. The hardware sector unprotection feature re-enables both program and erase operations in previously protected sectors. Sector protection/ unprotection can be implemented via two methods.

Table 6. S29JL032H Boot Sector/Sector Block Addresses for Protection/Unprotection (Top Boot Devices)

| Sector | A20–A12 | Sector/ Sector Block Size |
|-----------|---------------------------------------|------------------------------|
| SA0 | 000000XXX | 64 Kbytes |
| SA1-SA3 | 000001XXX, 000010XXX 000011XXX | 192 (3x64) Kbytes |
| SA4-SA7 | 0001XXXXX | 256 (4x64) Kbytes |
| SA8-SA11 | 0010XXXXX | 256 (4x64) Kbytes |
| SA12-SA15 | 0011XXXXX | 256 (4x64) Kbytes |
| SA16-SA19 | 0100XXXXX | 256 (4x64) Kbytes |
| SA20-SA23 | 0101XXXXX | 256 (4x64) Kbytes |
| SA24-SA27 | 0110XXXXX | 256 (4x64) Kbytes |
| SA28-SA31 | 0111XXXXX | 256 (4x64) Kbytes |
| SA32-SA35 | 1000XXXXX | 256 (4x64) Kbytes |
| SA36-SA39 | 1001XXXXX | 256 (4x64) Kbytes |
| SA40-SA43 | 1010XXXXX | 256 (4x64) Kbytes |
| SA44-SA47 | 1011XXXXX | 256 (4x64) Kbytes |
| SA48-SA51 | 1100XXXXX | 256 (4x64) Kbytes |
| SA52-SA55 | 1101XXXXX | 256 (4x64) Kbytes |
| SA56-SA59 | 1110XXXXX | 256 (4x64) Kbytes |
| SA60-SA62 | 111100XXX, 111101XXX, 111110XXX | 192 (3x64) Kbytes |
| SA63 | 111111000 | 8 Kbytes |
| SA64 | 111111001 | 8 Kbytes |
| SA65 | 111111010 | 8 Kbytes |
| SA66 | 11111011 | 8 Kbytes |
| SA67 | 11111100 | 8 Kbytes |
| SA68 | 11111101 | 8 Kbytes |
| SA69 | 11111110 | 8 Kbytes |
| SA70 | 111111111 | 8 Kbytes |

Table 7. S29JL032H Sector/Sector Block Addresses for Protection/Unprotection (Bottom Boot Devices)

| Sector | A20–A12 | Sector/Sector Block Size |
|-----------|---------------------------------------|-----------------------------|
| SA70 | 111111XXX | 64 Kbytes |
| SA69-SA67 | 111110XXX, 111101XXX, 111100XXX | 192 (3x64) Kbytes |
| SA66-SA63 | 1110XXXXX | 256 (4x64) Kbytes |
| SA62-SA59 | 1101XXXXX | 256 (4x64) Kbytes |
| SA58-SA55 | 1100XXXXX | 256 (4x64) Kbytes |
| SA54-SA51 | 1011XXXXX | 256 (4x64) Kbytes |
| SA50-SA47 | 1010XXXXX | 256 (4x64) Kbytes |
| SA46-SA43 | 1001XXXXX | 256 (4x64) Kbytes |
| SA42-SA39 | 1000XXXXX | 256 (4x64) Kbytes |
| SA38-SA35 | 0111XXXXX | 256 (4x64) Kbytes |
| SA34-SA31 | 0110XXXXX | 256 (4x64) Kbytes |
| SA30-SA27 | 0101XXXXX | 256 (4x64) Kbytes |
| SA26-SA23 | 0100XXXXX | 256 (4x64) Kbytes |
| SA22–SA19 | 0011XXXXX | 256 (4x64) Kbytes |
| SA18-SA15 | 0010XXXXX | 256 (4x64) Kbytes |
| SA14-SA11 | 0001XXXXX | 256 (4x64) Kbytes |
| SA10-SA8 | 000011XXX, 000010XXX, 000001XXX | 192 (3x64) Kbytes |
| SA7 | 000000111 | 8 Kbytes |
| SA6 | 000000110 | 8 Kbytes |
| SA5 | 000000101 | 8 Kbytes |
| SA4 | 000000100 | 8 Kbytes |
| SA3 | 00000011 | 8 Kbytes |
| SA2 | 00000010 | 8 Kbytes |
| SA1 | 00000001 | 8 Kbytes |
| SA0 | 00000000 | 8 Kbytes |

Sector protect/Sector Unprotect requires V_{ID} on the RESET# pin only, and can be implemented either in-system or via programming equipment. Figure 2 shows the algorithms and Figure 25 shows the timing diagram. For sector unprotect, all unprotected sectors must first be protected prior to the first sector unprotect write cycle. Note that the sector unprotect algorithm unprotects all sectors in parallel. All previously protected sectors must be individually re-protected. To change data in protected sectors efficiently, the temporary sector unprotect function is available. See "Temporary Sector Unprotect".

The device is shipped with all sectors unprotected. Optional Spansion programming service enable programming and protecting sectors at the factory prior to shipping the device. Contact your local sales office for details.

It is possible to determine whether a sector is protected or unprotected. See the Autoselect Mode section for details.

22



Write Protect (WP#)

The Write Protect function provides a hardware method of protecting certain boot sectors without using $V_{\rm ID}.$ This function is one of two provided by the WP#/ACC pin.

If the system asserts $V_{\rm IL}$ on the WP#/ACC pin, the device disables program and erase functions in the two outermost 8 Kbyte boot sectors independently of whether those sectors were protected or unprotected using the method described in "Sector/Sector Block Protection and Unprotection". The two outermost 8 Kbyte boot sectors are the two sectors containing the lowest addresses in a bottom-boot-configured device, or the two sectors containing the highest addresses in a top-boot-configured device.

If the system asserts V_{IH} on the WP#/ACC pin, the device reverts to whether the two outermost 8K Byte boot sectors were last set to be protected or unprotected. That is, sector protection or unprotection for these two sectors depends on whether they were last protected or unprotected using the method described in "Sector/Sector Block Protection and Unprotection".

Note that the WP#/ACC pin must not be left floating or unconnected; inconsistent behavior of the device may result.

| | Device |
|-------------------|---|
| WP# Input Voltage | Mode |
| V _{IL} | Disables programming and erasing in the two outermost boot sectors |
| V _{IH} | Enables programming and erasing in the two outermost boot sectors, dependent on whether they were last protected or unprotected |
| V _{HH} | Enables accelerated programming (ACC). See "Accelerated Program Operation" |

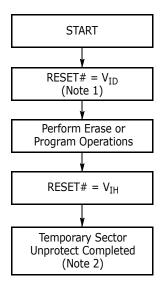
| Table 8 | . WP | #/ACC | Modes |
|---------|------|-------|---------|
| Table 0 | | | i ioucs |

Temporary Sector Unprotect

(Note: For the following discussion, the term "sector" applies to both sectors and sector blocks. A sector block consists of two or more adjacent sectors that are protected or unprotected at the same time (see Table 6 and Table 7).)

This feature allows temporary unprotection of previously protected sectors to change data in-system. The Temporary Sector Unprotect mode is activated by setting the RESET# pin to V_{ID} . During this mode, formerly protected sectors can be programmed or erased by selecting the sector addresses. Once V_{ID} is removed from the RESET# pin, all the previously protected sectors are protected again. Figure 1 shows the algorithm, and Figure 24 shows the timing diagrams, for this feature. If the WP#/ACC pin is at V_{IL} , the two outermost boot sectors will remain protected during the Temporary sector Unprotect mode.





Notes:

- 1. All protected sectors unprotected (If WP#/ACC = V_{IL}, the outermost two boot sectors will remain protected).
- 2. All previously protected sectors are protected once again.

Figure I. Temporary Sector Unprotect Operation



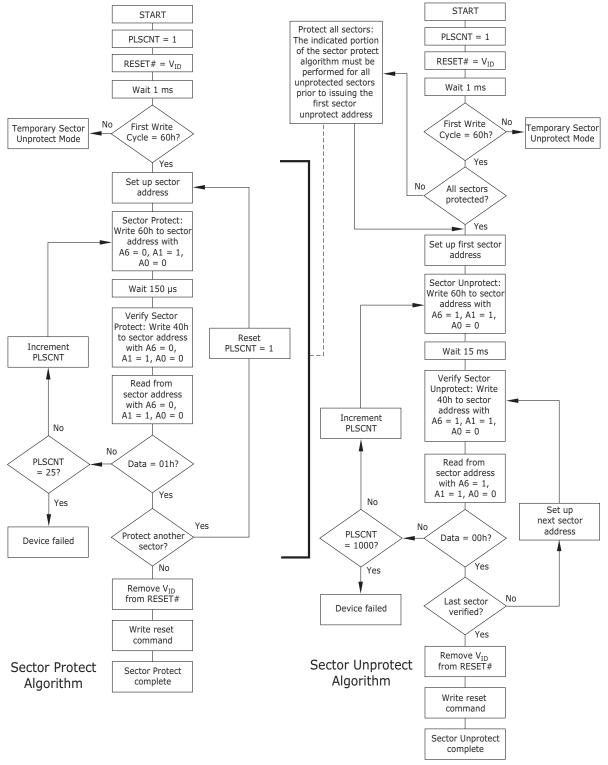


Figure 2. In-System Sector Protect/Unprotect Algorithms



SecSi[™] (Secured Silicon) Sector Flash Memory Region

The SecSi (Secured Silicon) Sector feature provides a Flash memory region that enables permanent part identification through an Electronic Serial Number (ESN). The SecSi Sector is 256 bytes in length, and uses a SecSi Sector Indicator Bit (DQ7) to indicate whether or not the SecSi Sector is locked when shipped from the factory. This bit is permanently set at the factory and cannot be changed, which prevents cloning of a factory locked part. This ensures the security of the ESN once the product is shipped to the field.

The product is available with the SecSi Sector either factory locked or customer lockable. The factory-locked version is always protected when shipped from the factory, and has the SecSi Sector Indicator Bit permanently set to a "1." The customer-lockable version is shipped with the SecSi Sector unprotected, allowing customers to utilize that sector in any manner they choose. The customer-lockable version has the SecSi Sector Indicator Bit permanently set to a "0." Thus, the SecSi Sector Indicator Bit prevents customer-lockable devices from being used to replace devices that are factory locked. The SecSi Customer Indicator Bit (DQ6) is permanently set to 1 if the part has been customer lockable.

The system accesses the SecSi Secure through a command sequence (see "Enter SecSi[™] Sector/Exit SecSi Sector Command Sequence"). After the system has written the Enter SecSi Sector command sequence, it may read the SecSi Sector by using the addresses normally occupied by the boot sectors. This mode of operation continues until the system issues the Exit SecSi Sector command sequence, or until power is removed from the device. On power-up, or following a hardware reset, the device reverts to sending commands to the first 256 bytes of Sector 0. Note that the ACC function and unlock bypass modes are not available when the SecSi Sector is enabled.

Factory Locked: SecSi Sector Programmed and Protected At the Factory

In a factory locked device, the SecSi Sector is protected when the device is shipped from the factory. The SecSi Sector cannot be modified in any way. The device is preprogrammed with both a random number and a secure ESN. The 8-word random number is at addresses 000000h-000007h in word mode (or 000000h-00000Fh in byte mode). The secure ESN is programmed in the next 8 words at addresses 000008h-00000Fh (or 000010h-00001Fh in byte mode). The device is available preprogrammed with one of the following:

- A random, secure ESN only
- Customer code through Spansion programming services
- Both a random, secure ESN and customer code through Spansion programming services

Contact your local sales office for details on using Spansion programming services.

Customer Lockable: SecSi Sector NOT Programmed or Protected At the Factory

If the security feature is not required, the SecSi Sector can be treated as an additional Flash memory space. The SecSi Sector can be read any number of times, but can be programmed and locked only once. *Note that the accelerated programming (ACC) and unlock bypass functions are not available when programming the SecSi Sector.*



The SecSi Sector area can be protected using one of the following procedures:

- Write the three-cycle Enter SecSi Sector Region command sequence, and then follow the in-system sector protect algorithm as shown in Figure 2. This allows in-system protection of the SecSi Sector Region without raising any device pin to a high voltage. Note that this method is only applicable to the SecSi Sector.
- Write the three-cycle Enter SecSi Sector Region command sequence, and then use the alternate method of sector protection described in the "Sector/ Sector Block Protection and Unprotection" section.

Once the SecSi Sector is locked and verified, the system must write the Exit SecSi Sector Region command sequence to return to reading and writing the remainder of the array.

The SecSi Sector lock must be used with caution since, once locked, there is no procedure available for unlocking the SecSi Sector area and none of the bits in the SecSi Sector memory space can be modified in any way.

Hardware Data Protection

The command sequence requirement of unlock cycles for programming or erasing provides data protection against inadvertent writes (refer to Table 13 for command definitions). In addition, the following hardware data protection measures prevent accidental erasure or programming, which might otherwise be caused by spurious system level signals during V_{CC} power-up and power-down transitions, or from system noise.

Low V_{CC} Write Inhibit

When V_{CC} is less than V_{LKO} , the device does not accept any write cycles. This protects data during V_{CC} power-up and power-down. The command register and all internal program/erase circuits are disabled, and the device resets to the read mode. Subsequent writes are ignored until V_{CC} is greater than V_{LKO} . The system must provide the proper signals to the control pins to prevent unintentional writes when V_{CC} is greater than V_{LKO} .

Write Pulse "Glitch" Protection

Noise pulses of less than 5 ns (typical) on OE#, CE# or WE# do not initiate a write cycle.

Logical Inhibit

Write cycles are inhibited by holding any one of OE# = V_{IL} , CE# = V_{IH} or WE# = V_{IH} . To initiate a write cycle, CE# and WE# must be a logical zero while OE# is a logical one.

Power-Up Write Inhibit

If WE# = CE# = V_{IL} and OE# = V_{IH} during power up, the device does not accept commands on the rising edge of WE#. The internal state machine is automatically reset to the read mode on power-up.

Common Flash Memory Interface (CFI)

The Common Flash Interface (CFI) specification outlines device and host system software interrogation handshake, which allows specific vendor-specified software algorithms to be used for entire families of devices. Software support can then be device-independent, JEDEC ID-independent, and forward- and backward-compatible for the specified flash device families. Flash vendors can standardize their existing interfaces for long-term compatibility.



This device enters the CFI Query mode when the system writes the CFI Query command, 98h, to address 55h in word mode (or address AAh in byte mode), any time the device is ready to read array data. The system can read CFI information at the addresses given in Tables 9-12. To terminate reading CFI data, the system must write the reset command. The CFI Query mode is not accessible when the device is executing an Embedded Program or embedded Erase algorithm.

The system can also write the CFI query command when the device is in the autoselect mode. The device enters the CFI query mode, and the system can read CFI data at the addresses given in Tables 9-12. The system must write the reset command to reading array data.

For further information, please refer to the CFI Specification and CFI Publication 100. Contact your local sales office for copies of these documents.

| Addresses (Word Mode) | Addresses (Byte Mode) | Data | Description |
|--------------------------|--------------------------|-------|--|
| 10h | 20h | 0051h | Query Unique ASCII string "QRY" |
| 11h | 22h | 0052h | |
| 12h | 24h | 0059h | |
| 13h | 26h | 0002h | Primary OEM Command Set |
| 14h | 28h | 0000h | |
| 15h | 2Ah | 0040h | Address for Primary Extended Table |
| 16h | 2Ch | 0000h | |
| 17h | 2Eh | 0000h | Alternate OEM Command Set (00h = none exists) |
| 18h | 30h | 0000h | |
| 19h | 32h | 0000h | Address for Alternate OEM Extended Table (00h = none exists) |
| 1Ah | 34h | 0000h | |

Table 9. CFI Query Identification String

| Table I0. | System | Interface | String |
|-----------|--------|-----------|--------|
|-----------|--------|-----------|--------|

| Addresses (Word Mode) | Addresses (Byte Mode) | Data | Description |
|--------------------------|--------------------------|-------|--|
| 1Bh | 36h | 0027h | V _{CC} Min. (write/erase) D7-D4: volt, D3-D0: 100 millivolt |
| 1Ch | 38h | 0036h | V _{CC} Max. (write/erase) D7-D4: volt, D3-D0: 100 millivolt |
| 1Dh | 3Ah | 0000h | V_{PP} Min. voltage (00h = no V_{PP} pin present) |
| 1Eh | 3Ch | 0000h | V_{PP} Max. voltage (00h = no V_{PP} pin present) |
| 1Fh | 3Eh | 0003h | Typical timeout per single byte/word write 2^{N} µs |
| 20h | 40h | 0000h | Typical timeout for Min. size buffer write $2^{N} \mu s$ (00h = not supported) |
| 21h | 42h | 0009h | Typical timeout per individual block erase 2 [№] ms |
| 22h | 44h | 0000h | Typical timeout for full chip erase 2^{N} ms (00h = not supported) |
| 23h | 46h | 0005h | Max. timeout for byte/word write 2 ⁿ times typical |
| 24h | 48h | 0000h | Max. timeout for buffer write 2 ^N times typical |
| 25h | 4Ah | 0004h | Max. timeout per individual block erase 2 ^N times typical |
| 26h | 4Ch | 0000h | Max. timeout for full chip erase 2^{N} times typical (00h = not supported) |



| Addresses (Word Mode) | Addresses (Byte Mode) | Data | Description |
|--------------------------|--------------------------|----------------------------------|---|
| 27h | 4Eh | 0016h | Device Size = 2^{N} byte |
| 28h 29h | 50h 52h | 0002h 0000h | Flash Device Interface description (refer to CFI publication 100) |
| 2Ah 2Bh | 54h 56h | 0000h 0000h | Max. number of byte in multi-byte write = 2^{N} (00h = not supported) |
| 2Ch | 58h | 0002h | Number of Erase Block Regions within device |
| 2Dh 2Eh 2Fh 30h | 5Ah 5Ch 5Eh 60h | 0007h 0000h 0020h 0000h | Erase Block Region 1 Information (refer to the CFI specification or CFI publication 100) |
| 31h 32h 33h 34h | 62h 64h 66h 68h | 003Eh 0000h 0000h 0001h | Erase Block Region 2 Information (refer to the CFI specification or CFI publication 100) |
| 35h 36h 37h 38h | 6Ah 6Ch 6Eh 70h | 0000h 0000h 0000h 0000h | Erase Block Region 3 Information (refer to the CFI specification or CFI publication 100) |
| 39h 3Ah 3Bh 3Ch | 72h 74h 76h 78h | 0000h 0000h 0000h 0000h | Erase Block Region 4 Information (refer to the CFI specification or CFI publication 100) |

| Table II. | Device | Geometry | Definition |
|-----------|--------|----------|------------|
|-----------|--------|----------|------------|

| Table I2. | Primary | Vendor-S | pecific | Extended | Query |
|-----------|---------|----------|---------|----------|-------|

| Addresses (Word Mode) | Addresses (Byte Mode) | Data | Description | |
|--------------------------|--------------------------|-------------------------|---|--|
| 40h 41h 42h | 80h 82h 84h | 0050h 0052h 0049h | Query-unique ASCII string "PRI" | |
| 43h | 86h | 0031h | Major version number, ASCII (reflects modifications to the silicon) | |
| 44h | 88h | 0033h | Minor version number, ASCII (reflects modifications to the CFI table) | |
| 45h | 8Ah | 000Ch | Address Sensitive Unlock (Bits 1-0) 0 = Required, 1 = Not Required Silicon Revision Number (Bits 7-2) | |
| 46h | 8Ch | 0002h | Erase Suspend 0 = Not Supported, 1 = To Read Only, 2 = To Read & Write | |
| 47h | 8Eh | 0001h | Sector Protect 0 = Not Supported, X = Number of sectors in per group | |
| 48h | 90h | 0001h | Sector Temporary Unprotect 00 = Not Supported, 01 = Supported | |
| 49h | 92h | 0004h | Sector Protect/Unprotect scheme $01 = 29F040 \mod 02 = 29F016 \mod 03 = 29F400, 04 = 29LV800 \mod 04$ | |



| Addresses (Word Mode) | Addresses (Byte Mode) | Data | Description (Continued) |
|--------------------------|--------------------------|--------|--|
| 4Ah | | 00XXh | Number of sectors (excluding Bank 1) |
| | 046 | | XX = 38 (models 01, 02, 21, 22) |
| 4411 | 94h | | XX = 30 (models 31, 32) |
| | | | XX = 20 (models 41, 42) |
| 4Bh | 96h | 0000h | Burst Mode Type 00 = Not Supported, 01 = Supported |
| 4Ch | 98h | 0000h | Page Mode Type 00 = Not Supported, 01 = 4 Word Page, 02 = 8 Word Page |
| 4Dh | 9Ah | 0085h | ACC (Acceleration) Supply Minimum |
| 4011 | 9411 | 008511 | 00h = Not Supported, D7-D4: Volt, D3-D0: 100 mV |
| 4Eb | 0.Ch | 00051 | ACC (Acceleration) Supply Maximum |
| 4Eh | 9Ch | 0095h | 00h = Not Supported, D7-D4: Volt, D3-D0: 100 mV |
| 456 | 051 | 000Xh | Top/Bottom Boot Sector Flag |
| 4Fh | 9Eh | | 02h = Bottom Boot Device, 03h = Top Boot Device |
| 501 | A0h | 0001h | Program Suspend |
| 50h | | | 0 = Not supported, 1 = Supported |
| | AEh | 000Xh | Bank Organization |
| EZh | | | 00 = Data at 4Ah is zero |
| 57h | | | X = 4 (4 banks, models 01, 02) |
| | | | X = 2 (2 banks, all other models) |
| | B0h | 00XXh | Bank 1 Region Information - Number of sectors on Bank 1 |
| 58h | | | XX = 0F (models 01, 02, 21, 22) |
| 5011 | | | XX = 17 (models 31, 32) |
| | | | XX = 27 (models 41, 42) |
| | B2h | | Bank 2 Region Information - Number of sectors in Bank 2 |
| | | | XX = 18 (models 01, 02) |
| 59h | | 00XXh | XX = 38 (models 21, 22) |
| | | | XX = 30 (models 31, 32) |
| | | | XX = 20 (models 41, 42) |
| | B4h | 00XXh | Bank 3 Region Information - Number of sectors in Bank 3 |
| 5Ah | | | XX = 18 (models 01, 02) |
| | | | XX = 00 (all other models) |
| | | 00XXh | Bank 4 Region Information - Number of sectors in Bank 4 |
| 5Bh | B6h | | XX = 08 (models 01, 02) |
| | | | XX = 00 (all other models) |



Command Definitions

Writing specific address and data commands or sequences into the command register initiates device operations. Table 13 defines the valid register command sequences. Writing incorrect address and data values or writing them in the improper sequence may place the device in an unknown state. A reset command is then required to return the device to reading array data.

All addresses are latched on the falling edge of WE# or CE#, whichever happens later. All data is latched on the rising edge of WE# or CE#, whichever happens first. Refer to the AC Characteristics section for timing diagrams.

Reading Array Data

The device is automatically set to reading array data after device power-up. No commands are required to retrieve data. Each bank is ready to read array data after completing an Embedded Program or Embedded Erase algorithm.

After the device accepts an Erase Suspend command, the corresponding bank enters the erase-suspend-read mode, after which the system can read data from any non-erase-suspended sector within the same bank. The system can read array data using the standard read timing, except that if it reads at an address within erase-suspended sectors, the device outputs status data. After completing a programming operation in the Erase Suspend mode, the system may once again read array data with the same exception. See the Erase Suspend/Erase Resume Commands section for more information.

The system *must* issue the reset command to return a bank to the read (or erasesuspend-read) mode if DQ5 goes high during an active program or erase operation, or if the bank is in the autoselect mode. See the next section, Reset Command, for more information.

See also Requirements for Reading Array Data in the Device Bus Operations section for more information. The Read-Only Operations table provides the read parameters, and Figure 13 shows the timing diagram.

Reset Command

Writing the reset command resets the banks to the read or erase-suspend-read mode. Address bits are don't cares for this command.

The reset command may be written between the sequence cycles in an erase command sequence before erasing begins. This resets the bank to which the system was writing to the read mode. Once erasure begins, however, the device ignores reset commands until the operation is complete.

The reset command may be written between the sequence cycles in a program command sequence before programming begins. This resets the bank to which the system was writing to the read mode. If the program command sequence is written to a bank that is in the Erase Suspend mode, writing the reset command returns that bank to the erase-suspend-read mode. Once programming begins, however, the device ignores reset commands until the operation is complete.

The reset command may be written between the sequence cycles in an autoselect command sequence. Once in the autoselect mode, the reset command must be written to return to the read mode. If a bank entered the autoselect mode while in the Erase Suspend mode, writing the reset command returns that bank to the erase-suspend-read mode.



If DQ5 goes high during a program or erase operation, writing the reset command returns the banks to the read mode (or erase-suspend-read mode if that bank was in Erase Suspend).

Autoselect Command Sequence

The autoselect command sequence allows the host system to access the manufacturer and device codes, and determine whether or not a sector is protected. The autoselect command sequence may be written to an address within a bank that is either in the read or erase-suspend-read mode. The autoselect command may not be written while the device is actively programming or erasing in another bank.

The autoselect command sequence is initiated by first writing two unlock cycles. This is followed by a third write cycle that contains the bank address and the autoselect command. The bank then enters the autoselect mode. The system may read any number of autoselect codes without reinitiating the command sequence.

Table 13 shows the address and data requirements. To determine sector protection information, the system must write to the appropriate bank address (BA) and sector address (SA). Tables 3 and 4 show the address range and bank number associated with each sector.

The system must write the reset command to return to the read mode (or erasesuspend-read mode if the bank was previously in Erase Suspend).

Enter SecSi[™] Sector/Exit SecSi Sector Command Sequence

The SecSi Sector region provides a secured data area containing a random, sixteen-byte electronic serial number (ESN). The system can access the SecSi Sector region by issuing the three-cycle Enter SecSi Sector command sequence. The device continues to access the SecSi Sector region until the system issues the four-cycle Exit SecSi Sector command sequence. The Exit SecSi Sector command sequence returns the device to normal operation. The SecSi Sector is not accessible when the device is executing an Embedded Program or embedded Erase algorithm. Table 13 shows the address and data requirements for both command sequences. See also "SecSi™ (Secured Silicon) Sector Flash Memory Region" for further information. Note that the ACC function and unlock bypass modes are not available when the SecSi Sector is enabled.

Byte/Word Program Command Sequence

The system may program the device by word or byte, depending on the state of the BYTE# pin. Programming is a four-bus-cycle operation. The program command sequence is initiated by writing two unlock write cycles, followed by the program set-up command. The program address and data are written next, which in turn initiate the Embedded Program algorithm. The system is *not* required to provide further controls or timings. The device automatically provides internally generated program pulses and verifies the programmed cell margin. Table 13 shows the address and data requirements for the byte program command sequence.

When the Embedded Program algorithm is complete, that bank then returns to the read mode and addresses are no longer latched. The system can determine the status of the program operation by using DQ7, DQ6, or RY/BY#. Refer to the Write Operation Status section for information on these status bits.



Any commands written to the device during the Embedded Program Algorithm are ignored. Note that a **hardware reset** immediately terminates the program operation. The program command sequence should be reinitiated once that bank has returned to the read mode, to ensure data integrity. *Note that the SecSi Sector, autoselect, and CFI functions are unavailable when a program operation is in progress.*

Programming is allowed in any sequence and across sector boundaries. A bit cannot be programmed from "0" back to a "1." Attempting to do so may cause that bank to set DQ5 = 1, or cause the DQ7 and DQ6 status bits to indicate the operation was successful. However, a succeeding read will show that the data is still "0." Only erase operations can convert a "0" to a "1."

Unlock Bypass Command Sequence

The unlock bypass feature allows the system to program bytes or words to a bank faster than using the standard program command sequence. The unlock bypass command sequence is initiated by first writing two unlock cycles. This is followed by a third write cycle containing the unlock bypass command, 20h. That bank then enters the unlock bypass mode. A two-cycle unlock bypass program command sequence is all that is required to program in this mode. The first cycle in this sequence contains the unlock bypass program command, A0h; the second cycle contains the program address and data. Additional data is programmed in the same manner. This mode dispenses with the initial two unlock cycles required in the standard program command sequence, resulting in faster total programming time. Table 13 shows the requirements for the command sequence.

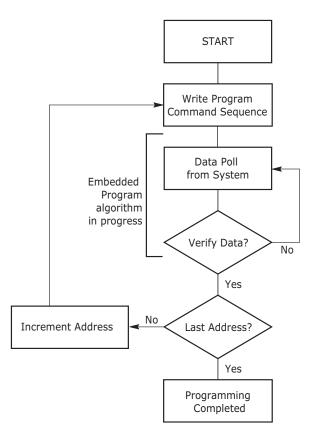
During the unlock bypass mode, only the Unlock Bypass Program and Unlock Bypass Reset commands are valid. To exit the unlock bypass mode, the system must issue the two-cycle unlock bypass reset command sequence. (Table 13).

The device offers accelerated program operations through the WP#/ACC pin. When the system asserts V_{HH} on the WP#/ACC pin, the device automatically enters the Unlock Bypass mode. The system may then write the two-cycle Unlock Bypass program command sequence. The device uses the higher voltage on the WP#/ACC pin to accelerate the operation. Note that the WP#/ACC pin must not be at V_{HH} for any operation other than accelerated programming, or device damage may result. In addition, the WP#/ACC pin must not be left floating or unconnected; inconsistent behavior of the device may result.

Figure 3 illustrates the algorithm for the program operation. Refer to the Erase and Program Operations table in the AC Characteristics section for parameters, and Figure 17 for timing diagrams.







Note: See Table 13 for program command sequence.

Figure 3. Program Operation

Chip Erase Command Sequence

Chip erase is a six bus cycle operation. The chip erase command sequence is initiated by writing two unlock cycles, followed by a set-up command. Two additional unlock write cycles are then followed by the chip erase command, which in turn invokes the Embedded Erase algorithm. The device does *not* require the system to preprogram prior to erase. The Embedded Erase algorithm automatically preprograms and verifies the entire memory for an all zero data pattern prior to electrical erase. The system is not required to provide any controls or timings during these operations. Table 13 shows the address and data requirements for the chip erase command sequence.

When the Embedded Erase algorithm is complete, that bank returns to the read mode and addresses are no longer latched. The system can determine the status of the erase operation by using DQ7, DQ6, DQ2, or RY/BY#. Refer to the Write Operation Status section for information on these status bits.

Any commands written during the chip erase operation are ignored. However, note that a **hardware reset** immediately terminates the erase operation. If that occurs, the chip erase command sequence should be reinitiated once that bank has returned to reading array data, to ensure data integrity. *Note that the SecSi Sector, autoselect, and CFI functions are unavailable when an erase operation is in progress.*



Figure 4 illustrates the algorithm for the erase operation. Refer to the Erase and Program Operations tables in the AC Characteristics section for parameters, and Figure 19 section for timing diagrams.

Sector Erase Command Sequence

Sector erase is a six bus cycle operation. The sector erase command sequence is initiated by writing two unlock cycles, followed by a set-up command. Two additional unlock cycles are written, and are then followed by the address of the sector to be erased, and the sector erase command. Table 13 shows the address and data requirements for the sector erase command sequence.

The device does *not* require the system to preprogram prior to erase. The Embedded Erase algorithm automatically programs and verifies the entire sector for an all zero data pattern prior to electrical erase. The system is not required to provide any controls or timings during these operations.

After the command sequence is written, a sector erase time-out of 80 µs occurs. During the time-out period, additional sector addresses and sector erase commands may be written. Loading the sector erase buffer may be done in any sequence, and the number of sectors may be from one sector to all sectors. The time between these additional cycles must be less than 80 µs, otherwise erasure may begin. Any sector erase address and command following the exceeded time-out may or may not be accepted. It is recommended that processor interrupts be disabled during this time to ensure all commands are accepted. The interrupts can be re-enabled after the last Sector Erase command is written. **Any command other than Sector Erase or Erase Suspend during the time-out period resets that bank to the read mode.** The system must rewrite the command sequence and any additional addresses and commands.

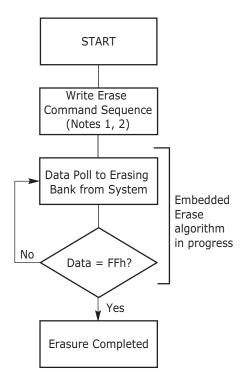
The system can monitor DQ3 to determine if the sector erase timer has timed out (See the section on DQ3: Sector Erase Timer.). The time-out begins from the rising edge of the final WE# or CE# pulse (first rising edge) in the command sequence.

When the Embedded Erase algorithm is complete, the bank returns to reading array data and addresses are no longer latched. Note that while the Embedded Erase operation is in progress, the system can read data from the non-erasing bank. The system can determine the status of the erase operation by reading DQ7, DQ6, DQ2, or RY/BY# in the erasing bank. Refer to the Write Operation Status section for information on these status bits.

Once the sector erase operation has begun, only the Erase Suspend command is valid. All other commands are ignored. However, note that a **hardware reset** immediately terminates the erase operation. If that occurs, the sector erase command sequence should be reinitiated once that bank has returned to reading array data, to ensure data integrity. *Note that the SecSi Sector, autoselect, and CFI functions are unavailable when an erase operation is in progress.*

Figure 4 illustrates the algorithm for the erase operation. Refer to the Erase and Program Operations tables in the AC Characteristics section for parameters, and Figure 19 section for timing diagrams.





Notes:

- 1. See Table 13 for erase command sequence.
- 2. See the section on DQ3 for information on the sector erase timer.

Figure 4. Erase Operation

Erase Suspend/Erase Resume Commands

The Erase Suspend command, B0h, allows the system to interrupt a sector erase operation and then read data from, or program data to, any sector not selected for erasure. The bank address is required when writing this command. This command is valid only during the sector erase operation, including the 80 μ s time-out period during the sector erase command sequence. The Erase Suspend command is ignored if written during the chip erase operation or Embedded Program algorithm. The bank address must contain one of the sectors currently selected for erase.

When the Erase Suspend command is written during the sector erase operation, the device requires a maximum of 20 μs to suspend the erase operation. However, when the Erase Suspend command is written during the sector erase time-out, the device immediately terminates the time-out period and suspends the erase operation.

After the erase operation has been suspended, the bank enters the erase-suspend-read mode. The system can read data from or program data to any sector not selected for erasure. (The device "erase suspends" all sectors selected for erasure.) Reading at any address within erase-suspended sectors produces status information on DQ7–DQ0. The system can use DQ7, or DQ6 and DQ2 together, to determine if a sector is actively erasing or is erase-suspended. Refer to the Write Operation Status section for information on these status bits.



After an erase-suspended program operation is complete, the bank returns to the erase-suspend-read mode. The system can determine the status of the program operation using the DQ7 or DQ6 status bits, just as in the standard Byte Program operation. Refer to the Write Operation Status section for more information.

In the erase-suspend-read mode, the system can also issue the autoselect command sequence. The device allows reading autoselect codes even at addresses within erasing sectors, since the codes are not stored in the memory array. When the device exits the autoselect mode, the device reverts to the Erase Suspend mode, and is ready for another valid operation. Refer to the Autoselect Mode and Autoselect Command Sequence sections for details.

To resume the sector erase operation, the system must write the Erase Resume command. The bank address of the erase-suspended bank is required when writing this command. Further writes of the Resume command are ignored. Another Erase Suspend command can be written after the chip has resumed erasing.

| | Command | | ŝ | | | | | Bu | s Cycle | s (Notes | 2-5) | | | | |
|------------|-----------------------------|-------------------|--------|------------|------|------|------|---------|---------|----------|------------|---------|------------|---------|------------|
| | Sequence | | Cycles | Fir | rst | Sec | ond | Thire | d | Four | th | Fift | ı | Sixt | :h |
| | (Note 1) | | ς Ω | Addr | Data | Addr | Data | Addr | Data | Addr | Data | Addr | Data | Addr | Data |
| Rea | ad (Note 6) | | 1 | RA | RD | | | | | | | | | | |
| Res | set (Note 7) | | 1 | XXX | F0 | | | | | | | | | | |
| | Manufacturer ID | Word | 4 | 555 | AA | 2AA | 55 | (BA)555 | 90 | (BA)X00 | 01 | | | | |
| 8 | | Byte | ۲ | AAA | ~~ | 555 | 55 | (BA)AAA | 50 | (DA)/00 | 01 | | | | |
| ote | | Word | | 555 | | 2AA | | (BA)555 | | (BA)X01 | See | (BA)X0E | See | (BA)X0F | See |
| 2 | Device ID (Note 9) | Byte | 6 | AAA | AA | 555 | 55 | (BA)AAA | 90 | (BA)X02 | Table 5 | (BA)X1C | Table 5 | (BA)X1E | Table 5 |
| ect | SecSi Sector Factory | Word | 4 | 555 | AA | 2AA | 55 | (BA)555 | 90 | (BA)X03 | 82/ | | | | |
| sel | Protect (Note 10) | Byte | 4 | AAA | AA | 555 | 55 | (BA)AAA | 90 | (BA)X06 | 02 | | | | |
| Autoselect | Sector/Sector Block | Word | | 555 | | 2AA | | (BA)555 | | (SA)X02 | 00/ | | | | |
| A | Protect Verify (Note 11) | Byte | 4 | AAA | AA | 555 | 55 | (BA)AAA | 90 | (SA)X04 | 01 | | | | |
| Ent | er SecSi Sector Region | Word | 3 | 555 | AA | 2AA | 55 | 555 | 88 | | | | | | |
| | er secsi sector Region | Byte | 5 | AAA | AA | 555 | - 55 | AAA | 00 | | | | | | |
| Evi | t SecSi Sector Region | Word | 4 | 555 | AA | 2AA | 55 | 555 | 90 | XXX | 00 | | | | |
| | L SECSI SECLOI REGION | Byte | | AAA | ~~ | 555 | 55 | AAA | 50 | ~~~ | 00 | | | | |
| Pro | gram | Word 4 555 AA 2AA | 55 | 555 A0 | PA | PD | | | | | | | | | |
| 110 | gram | Byte | т | AAA | ~~ | 555 | 55 | AAA | AU | | 10 | | | | |
| Un | lock Bypass | Word | 3 | 555 | ΑΑ | 2AA | 55 | 555 | 20 | | | | | | |
| | 21 | Byte | , | AAA | | 555 | | AAA | 20 | | | | | | |
| | lock Bypass Program (No | , | 2 | XXX | A0 | PA | PD | | | | | | | | |
| Un | lock Bypass Reset (Note | | 2 | XXX | 90 | XXX | 00 | | | | | | | | |
| Chi | p Erase | Word | 6 | 6 44 55 80 | 555 | AA | 2AA | 55 | 555 | 10 | | | | | |
| | | Byte | - | AAA | | 555 | | AAA | | AAA | | 555 | | AAA | _ |
| Sec | ctor Erase | Word Byte | 6 | 555 | AA | 2AA | 55 | 555 | 80 | 555 | AA | 2AA | 55 | SA | 30 |
| _ | | | | AAA | | 555 | | AAA | | AAA | | 555 | | | |
| | se Suspend (Note 14) | | 1 | BA | B0 | | | | | | | | | | |
| Era | se Resume (Note 15) | | 1 | BA | 30 | | | | | | | | | | |
| CFI | Query (Note 16) | Word Byte | 1 | 55 AA | 98 | | | | | | | | | | |

Table I3. S29JL032H Command Definitions

Legend:

X = Don't care

- RA = Address of the memory location to be read.
- RD = Data read from location RA during read operation.

PA = Address of the memory location to be programmed. Addresses latch on the falling edge of the WE# or CE# pulse, whichever happens later.

Notes:

- 1. See Table 1 for description of bus operations.
- 2. All values are in hexadecimal.
- Except for the read cycle and the fourth, fifth, and sixth cycle of the autoselect command sequence, all bus cycles are write cycles.
- Data bits DQ15-DQ8 are don't care in command sequences, except for RD and PD.
- 5. Unless otherwise noted, address bits A20–A11 are don't cares for unlock and command cycles, unless SA or PA is required.
- 6. No unlock or command cycles required when bank is reading array data.
- 7. The Reset command is required to return to the read mode (or to the erase-suspend-read mode if previously in Erase Suspend) when a bank is in the autoselect mode, or if DQ5 goes high (while the bank is providing status information).
- 8. The fourth cycle of the autoselect command sequence is a read cycle. The system must provide the bank address to obtain the manufacturer ID, device ID, or Sec5i Sector factory protect information. Data bits DQ15–DQ8 are don't care. While reading the autoselect addresses, the bank address must be the same until a reset command is given. See the Autoselect Command Sequence section for more information.

PD = Data to be programmed at location *PA*. Data latches on the rising edge of *WE*# or *CE*# pulse, whichever happens first.

SA = Address of the sector to be verified (in autoselect mode) or erased. Address bits A20–A12 uniquely select any sector. Refer to tables 3 and 4 for information on sector addresses.

BA = Address of the bank that is being switched to autoselect mode, is in bypass mode, or is being erased. A20–A18 uniquely select a bank.

- 9. For models 01, 02, the device ID must be read across the fourth, fifth, and sixth cycles.
- 10. The data is 82h for factory locked, 42h for customer locked, and 02h for not factory/customer locked.
- 11. The data is 00h for an unprotected sector/sector block and 01h for a protected sector/sector block.
- 12. The Unlock Bypass command is required prior to the Unlock Bypass Program command.
- 13. The Unlock Bypass Reset command is required to return to the read mode when the bank is in the unlock bypass mode.
- 14. The system may read and program in non-erasing sectors, or enter the autoselect mode, when in the Erase Suspend mode. The Erase Suspend command is valid only during a sector erase operation, and requires the bank address.
- 15. The Erase Resume command is valid only during the Erase Suspend mode, and requires the bank address.
- 16. Command is valid when device is ready to read array data or when device is in autoselect mode.



Write Operation Status

The device provides several bits to determine the status of a program or erase operation: DQ2, DQ3, DQ5, DQ6, and DQ7. Table 14 and the following subsections describe the function of these bits. DQ7 and DQ6 each offer a method for determining whether a program or erase operation is complete or in progress. The device also provides a hardware-based output signal, RY/BY#, to determine whether an Embedded Program or Erase operation is in progress or has been completed.

DQ7: Data# Polling

The Data# Polling bit, DQ7, indicates to the host system whether an Embedded Program or Erase algorithm is in progress or completed, or whether a bank is in Erase Suspend. Data# Polling is valid after the rising edge of the final WE# pulse in the command sequence.

During the Embedded Program algorithm, the device outputs on DQ7 the complement of the datum programmed to DQ7. This DQ7 status also applies to programming during Erase Suspend. When the Embedded Program algorithm is complete, the device outputs the datum programmed to DQ7. The system must provide the program address to read valid status information on DQ7. If a program address falls within a protected sector, Data# Polling on DQ7 is active for approximately 1 μ s, then that bank returns to the read mode.

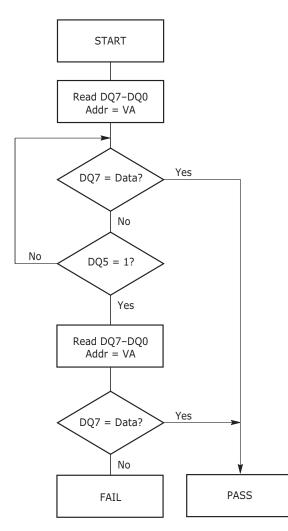
During the Embedded Erase algorithm, Data# Polling produces a "0" on DQ7. When the Embedded Erase algorithm is complete, or if the bank enters the Erase Suspend mode, Data# Polling produces a "1" on DQ7. The system must provide an address within any of the sectors selected for erasure to read valid status information on DQ7.

After an erase command sequence is written, if all sectors selected for erasing are protected, Data# Polling on DQ7 is active for approximately 100 μ s, then the bank returns to the read mode. If not all selected sectors are protected, the Embedded Erase algorithm erases the unprotected sectors, and ignores the selected sectors that are protected. However, if the system reads DQ7 at an address within a protected sector, the status may not be valid.

When the system detects DQ7 has changed from the complement to true data, it can read valid data at DQ15–DQ0 (or DQ7–DQ0 for x8-only device) on the *following* read cycles. Just prior to the completion of an Embedded Program or Erase operation, DQ7 may change asynchronously with DQ15–DQ8 (DQ7–DQ0 for x8-only device) while Output Enable (OE#) is asserted low. That is, the device may change from providing status information to valid data on DQ7. Depending on when the system samples the DQ7 output, it may read the status or valid data. Even if the device has completed the program or erase operation and DQ7 has valid data, the data outputs on DQ15–DQ0 may be still invalid. Valid data on DQ15–DQ0 (or DQ7–DQ0 for x8-only device) will appear on successive read cycles.

Table 14 shows the outputs for Data# Polling on DQ7. Figure 5 shows the Data# Polling algorithm. Figure 21 in the AC Characteristics section shows the Data# Polling timing diagram.





Notes:

- VA = Valid address for programming. During a sector erase operation, a valid address is any sector address within the sector being erased. During chip erase, a valid address is any non-protected sector address.
- 2. DQ7 should be rechecked even if DQ5 = "1" because DQ7 may change simultaneously with DQ5.

Figure 5. Data# Polling Algorithm



RY/BY#: Ready/Busy#

The RY/BY# is a dedicated, open-drain output pin which indicates whether an Embedded Algorithm is in progress or complete. The RY/BY# status is valid after the rising edge of the final WE# pulse in the command sequence. Since RY/BY# is an open-drain output, several RY/BY# pins can be tied together in parallel with a pull-up resistor to V_{CC} .

If the output is low (Busy), the device is actively erasing or programming. (This includes programming in the Erase Suspend mode.) If the output is high (Ready), the device is in the read mode, the standby mode, or one of the banks is in the erase-suspend-read mode.

Table 14 shows the outputs for RY/BY#.

DQ6: Toggle Bit I

Toggle Bit I on DQ6 indicates whether an Embedded Program or Erase algorithm is in progress or complete, or whether the device has entered the Erase Suspend mode. Toggle Bit I may be read at any address, and is valid after the rising edge of the final WE# pulse in the command sequence (prior to the program or erase operation), and during the sector erase time-out.

During an Embedded Program or Erase algorithm operation, successive read cycles to any address cause DQ6 to toggle. The system may use either OE# or CE# to control the read cycles. When the operation is complete, DQ6 stops toggling.

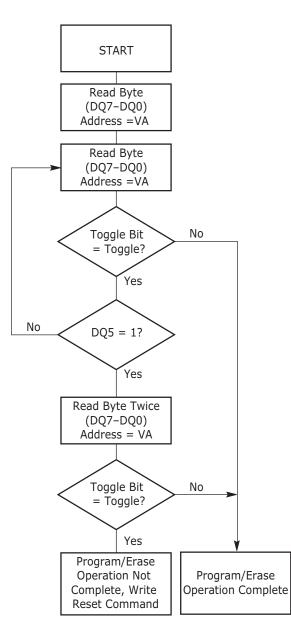
After an erase command sequence is written, if all sectors selected for erasing are protected, DQ6 toggles for approximately 100 μ s, then returns to reading array data. If not all selected sectors are protected, the Embedded Erase algorithm erases the unprotected sectors, and ignores the selected sectors that are protected.

The system can use DQ6 and DQ2 together to determine whether a sector is actively erasing or is erase-suspended. When the device is actively erasing (that is, the Embedded Erase algorithm is in progress), DQ6 toggles. When the device enters the Erase Suspend mode, DQ6 stops toggling. However, the system must also use DQ2 to determine which sectors are erasing or erase-suspended. Alternatively, the system can use DQ7 (see the subsection on DQ7: Data# Polling).

If a program address falls within a protected sector, DQ6 toggles for approximately 1 μ s after the program command sequence is written, then returns to reading array data.

DQ6 also toggles during the erase-suspend-program mode, and stops toggling once the Embedded Program algorithm is complete.





Note: The system should recheck the toggle bit even if DQ5 = "1" because the toggle bit may stop toggling as DQ5 changes to "1." See the subsections on DQ6 and DQ2 for more information.

Figure 6. Toggle Bit Algorithm

DQ2: Toggle Bit II

The "Toggle Bit II" on DQ2, when used with DQ6, indicates whether a particular sector is actively erasing (that is, the Embedded Erase algorithm is in progress), or whether that sector is erase-suspended. Toggle Bit II is valid after the rising edge of the final WE# pulse in the command sequence.



DQ2 toggles when the system reads at addresses within those sectors that have been selected for erasure. (The system may use either OE# or CE# to control the read cycles.) But DQ2 cannot distinguish whether the sector is actively erasing or is erase-suspended. DQ6, by comparison, indicates whether the device is actively erasing, or is in Erase Suspend, but cannot distinguish which sectors are selected for erasure. Thus, both status bits are required for sector and mode information. Refer to Table 14 to compare outputs for DQ2 and DQ6.

Figure 6 shows the toggle bit algorithm in flowchart form, and the section "DQ2: Toggle Bit II" explains the algorithm. See also the DQ6: Toggle Bit I subsection. Figure 22 shows the toggle bit timing diagram. Figure 23 shows the differences between DQ2 and DQ6 in graphical form.

Reading Toggle Bits DQ6/DQ2

Refer to Figure 6 for the following discussion. Whenever the system initially begins reading toggle bit status, it must read DQ15–DQ0 (or DQ7–DQ0 for x8-only device) at least twice in a row to determine whether a toggle bit is toggling. Typically, the system would note and store the value of the toggle bit after the first read. After the second read, the system would compare the new value of the toggle bit with the first. If the toggle bit is not toggling, the device has completed the program or erase operation. The system can read array data on DQ15–DQ0 (or DQ7–DQ0 for x8-only device) on the following read cycle.

However, if after the initial two read cycles, the system determines that the toggle bit is still toggling, the system also should note whether the value of DQ5 is high (see the section on DQ5). If it is, the system should then determine again whether the toggle bit is toggling, since the toggle bit may have stopped toggling just as DQ5 went high. If the toggle bit is no longer toggling, the device has successfully completed the program or erase operation. If it is still toggling, the device did not completed the operation successfully, and the system must write the reset command to return to reading array data.

The remaining scenario is that the system initially determines that the toggle bit is toggling and DQ5 has not gone high. The system may continue to monitor the toggle bit and DQ5 through successive read cycles, determining the status as described in the previous paragraph. Alternatively, it may choose to perform other system tasks. In this case, the system must start at the beginning of the algorithm when it returns to determine the status of the operation (top of Figure 6).

DQ5: Exceeded Timing Limits

DQ5 indicates whether the program or erase time has exceeded a specified internal pulse count limit. Under these conditions DQ5 produces a "1," indicating that the program or erase cycle was not successfully completed.

The device may output a "1" on DQ5 if the system tries to program a "1" to a location that was previously programmed to "0." **Only an erase operation can change a "0" back to a "1."** Under this condition, the device halts the operation, and when the timing limit has been exceeded, DQ5 produces a "1."

Under both these conditions, the system must write the reset command to return to the read mode (or to the erase-suspend-read mode if a bank was previously in the erase-suspend-program mode).

DQ3: Sector Erase Timer

After writing a sector erase command sequence, the system may read DQ3 to determine whether or not erasure has begun. (The sector erase timer does not



apply to the chip erase command.) If additional sectors are selected for erasure, the entire time-out also applies after each additional sector erase command. When the time-out period is complete, DQ3 switches from a "0" to a "1." If the time between additional sector erase commands from the system can be assumed to be less than 50 μ s, the system need not monitor DQ3. See also the Sector Erase Command Sequence section.

After the sector erase command is written, the system should read the status of DQ7 (Data# Polling) or DQ6 (Toggle Bit I) to ensure that the device has accepted the command sequence, and then read DQ3. If DQ3 is "1," the Embedded Erase algorithm has begun; all further commands (except Erase Suspend) are ignored until the erase operation is complete. If DQ3 is "0," the device will accept additional sector erase commands. To ensure the command has been accepted, the system software should check the status of DQ3 prior to and following each subsequent sector erase command. If DQ3 is high on the second status check, the last command might not have been accepted.

Table 14 shows the status of DQ3 relative to the other status bits.

| | | | DQ7 | | DQ5 | | DQ2 | |
|-----------------|------------------|-------------------------------|--------|-----------|------|-----------|--------|---|
| | Status | (Note 2) | DQ6 | (Note 1) | DQ3 | (Note 2) | RY/BY# | |
| Standard | Embedded Program | DQ7# | Toggle | 0 | N/A | No toggle | 0 | |
| Mode | Embedded Erase | 0 | Toggle | 0 | 1 | Toggle | 0 | |
| Erase | Erase-Suspend- | Erase Suspended Sector | 1 | No toggle | 0 | N/A | Toggle | 1 |
| Suspend Mode | Read | Non-Erase Suspended Sector | Data | Data | Data | Data | Data | 1 |
| | Erase-Suspend-P | DQ7# | Toggle | 0 | N/A | N/A | 0 | |

Table I4. Write Operation Status

Notes:

1. DQ5 switches to '1' when an Embedded Program or Embedded Erase operation has exceeded the maximum timing limits. Refer to the section on DQ5 for more information.

2. DQ7 and DQ2 require a valid address when reading status information. Refer to the appropriate subsection for further details.

3. When reading write operation status bits, the system must always provide the bank address where the Embedded Algorithm is in progress. The device outputs array data if the system addresses a non-busy bank.



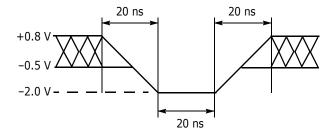
Absolute Maximum Ratings

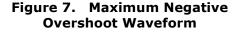
| Storage Temperature Plastic Packages |
|---|
| Ambient Temperature with Power Applied65°C to +125°C |
| Voltage with Respect to Ground |
| V_{CC} (Note 1) |
| A9, OE#, and RESET# |
| (Note 2)0.5 V to +12.5 V |
| WP#/ACC0.5 V to +10.5 V |
| All other pins (Note 1) |
| Output Short Circuit Current (Note 3) 200 mA |
| |

Notes:

- 1. Minimum DC voltage on input or I/O pins is -0.5 V. During voltage transitions, input or I/O pins may overshoot V_{SS} to -2.0 V for periods of up to 20 ns. Maximum DC voltage on input or I/O pins is V_{CC} +0.5 V. See Figure 7. During voltage transitions, input or I/O pins may overshoot to V_{CC} +2.0 V for periods up to 20 ns. See Figure 8.
- Minimum DC input voltage on pins A9, OE#, RESET#, and WP#/ACC is -0.5 V. During voltage transitions, A9, OE#, WP#/ ACC, and RESET# may overshoot V_{SS} to -2.0 V for periods of up to 20 ns. See Figure 7. Maximum DC input voltage on pin A9 is +12.5 V which may overshoot to +14.0 V for periods up to 20 ns. Maximum DC input voltage on WP#/ACC is +9.5 V which may overshoot to +12.0 V for periods up to 20 ns.
- 3. No more than one output may be shorted to ground at a time. Duration of the short circuit should not be greater than one second.

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this data sheet is not implied. Exposure of the device to absolute maximum rating conditions for extended periods may affect device reliability.





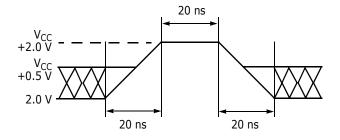


Figure 8. Maximum Positive Overshoot Waveform

Operating Ranges

Industrial (I) Devices

| Ambient Temperature (T _A) $\dots \dots -40^{\circ}$ C to +85°C |
|--|
| V _{CC} Supply Voltages |
| V_{CC} for standard voltage range $\ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots 2.7$ V to 3.6 V or |
| |

Note:Operating voltage Vcc varis depending on speed option.

Operating ranges define those limits between which the functionality of the device is guaranteed.



CMOS Compatible

| Parameter Symbol | Parameter Description | Test Conditio | ns | Min | Тур | Max | Unit |
|---------------------|---|---|--------|------------------------|------|-----------------------|------|
| I_{LI} | Input Load Current | $V_{IN} = V_{SS}$ to V_{CC} , $V_{CC} = V_{CC max}$ | | | | ±1.0 | μA |
| I _{LIT} | A9, OE# and RESET# Input Load Current | $V_{CC} = V_{CC max}, OE\# =$ OE# or RESET# = 12. | | | 35 | μA | |
| I _{LO} | Output Leakage Current | $V_{OUT} = V_{SS}$ to V_{CC} , $V_{CC} = V_{CC max}$, $OE# =$ | | | ±1.0 | μA | |
| I _{LR} | Reset Leakage Current | $V_{CC} = V_{CC max}$; RESE 12.5 V | T# = | | | 35 | μA |
| | | $CE\# = V_{IL}, OE\# = V_{IH},$ | 5 MHz | | 10 | 16 | |
| T | V _{CC} Active Read Current | Byte Mode | 1 MHz | | 2 | 4 | mA |
| I _{CC1} | (Notes 1, 2) | $CE\# = V_{IL}, OE\# =$ | 5 MHz | | 10 | 16 | |
| | | $V_{\mathrm{IH}}\text{,}$ Word Mode | 1 MHz | | 2 | 4 | |
| I _{CC2} | V _{CC} Active Write Current (Notes 2, 3) | $CE\# = V_{IL}, OE\# = V_{IH}, WE\# = V_{IL}$ | | | 15 | 30 | mA |
| I _{CC3} | V _{CC} Standby Current (Note 2) | CE#, RESET# = $V_{CC} \pm$ | 0.3 V | | 0.2 | 10 | μA |
| I _{CC4} | V _{CC} Reset Current (Note 2) | RESET# = $V_{SS} \pm 0.3 V$ | | | 0.2 | 10 | μA |
| I _{CC5} | Automatic Sleep Mode (Notes 2, 4) | $V_{IH} = V_{CC} \pm 0.3 V;$ $V_{IL} = V_{SS} \pm 0.3 V$ | | | 0.2 | 10 | μA |
| | V _{CC} Active Read-While-Program | | Byte | | 21 | 45 | |
| I _{CC6} | Current (Notes 1, 2) | $CE\#=V_{IL},OE\#=V_{IH}$ | Word | | 21 | 45 | mA |
| | V _{CC} Active Read-While-Erase | | Byte | | 21 | 45 | |
| I _{CC7} | Current (Notes 1, 2) | $CE\#=V_{IL},OE\#=V_{IH}$ | Word | | 21 | 45 | mA |
| I _{CC8} | V _{CC} Active Program-While-Erase- Suspended Current (Notes 2, 5) | $CE\# = V_{IL}, OE\# = V_{IH}$ | | | 17 | 35 | mA |
| V _{IL} | Input Low Voltage | | | -0.5 | | 0.8 | V |
| V _{IH} | Input High Voltage | | | 0.7 x V _{CC} | | V _{CC} + 0.3 | V |
| V _{HH} | Voltage for WP#/ACC Sector Protect/Unprotect and Program Acceleration | V _{CC} = 3.0 V ± 10% | | 8.5 | | 9.5 | v |
| V_{ID} | Voltage for Autoselect and Temporary Sector Unprotect | $V_{CC} = 3.0 \text{ V} \pm 10\%$ | | 8.5 | | 12.5 | V |
| V _{OL} | Output Low Voltage | I_{OL} = 2.0 mA, V _{CC} = V | CC min | | | 0.45 | V |
| V _{OH1} | Output High Valtage | I_{OH} = -2.0 mA, V _{CC} = | | 0.85 x V _{CC} | | | V |
| V _{OH2} | Output High Voltage | $I_{OH} = -100 \ \mu A, \ V_{CC} =$ | | V _{CC} -0.4 | | | |
| V _{LKO} | Low V _{CC} Lock-Out Voltage (Note 5) | | - | 2.3 | 2.4 | 2.5 | V |

Notes:

1. The I_{CC} current listed is typically less than 2 mA/MHz, with OE# at V_{IH} .

2. Maximum I_{CC} specifications are tested with $V_{CC} = V_{CC}max$.

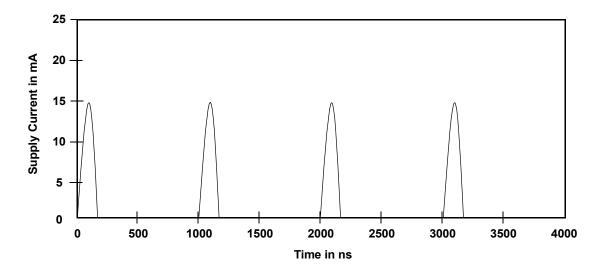
3. I_{CC} active while Embedded Erase or Embedded Program is in progress.

4. Automatic sleep mode enables the low power mode when addresses remain stable for t_{ACC} + 30 ns. Typical sleep mode current is 200 nA.

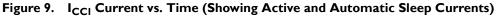
5. Not 100% tested.

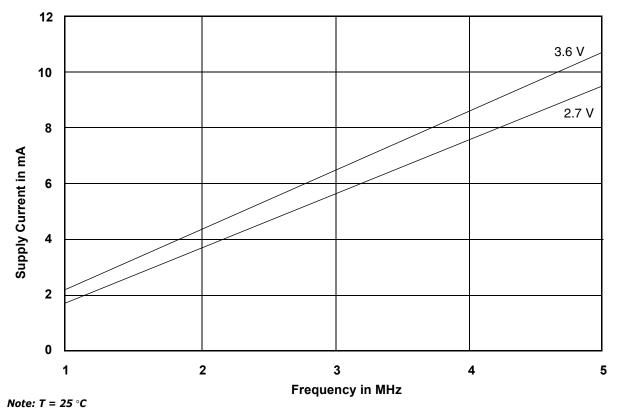


DC Characteristics Zero-Power Flash



Note: Addresses are switching at 1 MHz

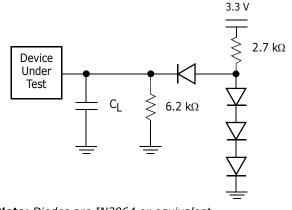








Test Conditions



Note: Diodes are IN3064 or equivalent

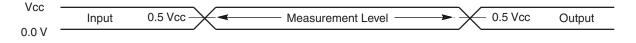
Figure II. Test Setup

 Table 1.
 Test Specifications

| Test Condition | 60 | 70, 90 | Unit | | | | |
|--|-------|------------|------|--|--|--|--|
| Output Load | | 1 TTL gate | | | | | |
| Output Load Capacitance, C _L (including jig capacitance) | 30 | 100 | pF | | | | |
| Input Rise and Fall Times | | 5 | | | | | |
| Input Pulse Levels | 0.0 0 | or Vcc | V | | | | |
| Input timing measurement reference levels | 0.5 | 0.5 Vcc | | | | | |
| Output timing measurement reference levels | 0.5 | 0.5 Vcc | | | | | |

Key To Switching Waveforms

| WAVEFORM | INPUTS | OUTPUTS |
|----------|----------------------------------|--|
| | | Steady |
| | Cha | anging from H to L |
| | Cha | anging from L to H |
| XXXXXX | Don't Care, Any Change Permitted | Changing, State Unknown |
| | Does Not Apply | Center Line is High Impedance State (High Z) |







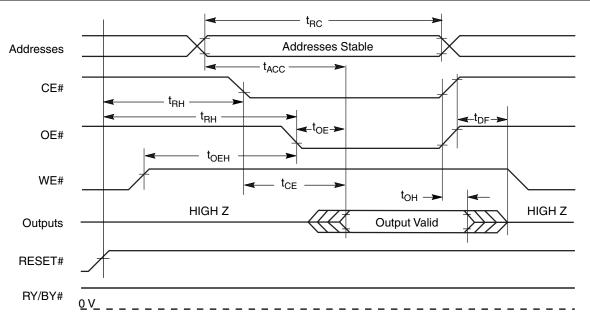
AC Characteristics Read-Only Operations

| Param | neter | | | | | Spe | eed Opti | ons | |
|-------------------|------------------|---|-----------------------------|-------------------------------|-----|----------|----------|-----|------|
| JEDEC | Std. | Description | | Test Setup | | 60 | 70 | 90 | Unit |
| t _{AVAV} | t _{RC} | Read Cycle Time (Note 1) | | Min | 60 | 70 | 90 | ns | |
| t _{AVQV} | t _{ACC} | Address to Output Delay | | CE#, OE# = V _{IL} | Max | 60 | 70 | 90 | ns |
| t _{ELQV} | t _{CE} | Chip Enable to Output Dela | У | $OE\# = V_{IL}$ | Max | 60 70 90 | | | ns |
| t _{GLQV} | t _{OE} | Output Enable to Output De | elay | | Max | 25 30 35 | | | ns |
| t _{EHQZ} | t _{DF} | Chip Enable to Output High | Z (Notes 1, 3) | | Max | 16 | | | ns |
| t _{GHQZ} | t _{DF} | Output Enable to Output Hi | gh Z (Notes 1, 3) | | Max | | 16 | | ns |
| t _{AXQX} | t _{OH} | Output Hold Time From Add OE#, Whichever Occurs Fire | | | Min | | 0 | | ns |
| | | | Read | | Min | | 0 | | ns |
| | t _{OEH} | Output Enable Hold Time (Note 1) | Toggle and Data# Polling | | Min | 5 | 1 | .0 | ns |

Notes:

1. Not 100% tested.

- 2. See Figure 11 and Table 1 for test specifications
- 3. Measurements performed by placing a 50 ohm termination on the data pin with a bias of $V_{CC}/2$. The time from OE# high to the data bus driven to $V_{CC}/2$ is taken as t_{DF}





AC Characteristics Hardware Reset (RESET#)

| Paran | neter | | | | |
|-------|--------------------|--|-------------------|------|----|
| JEDEC | Std | Description | All Speed Options | Unit | |
| | t _{Ready} | RESET# Pin Low (During Embedded Algorithms) to Read Mode (See Note) | Max | 20 | μs |
| | t _{Ready} | RESET# Pin Low (NOT During Embedded Algorithms) to Read Mode (See Note) | Max | 500 | ns |
| | t _{RP} | RESET# Pulse Width | Min | 500 | ns |
| | t _{RH} | Reset High Time Before Read (See Note) | Min | 50 | ns |
| | t _{RPD} | RESET# Low to Standby Mode | Min | 20 | μs |
| | t _{RB} | RY/BY# Recovery Time | Min | 0 | ns |

Note: Not 100% tested.

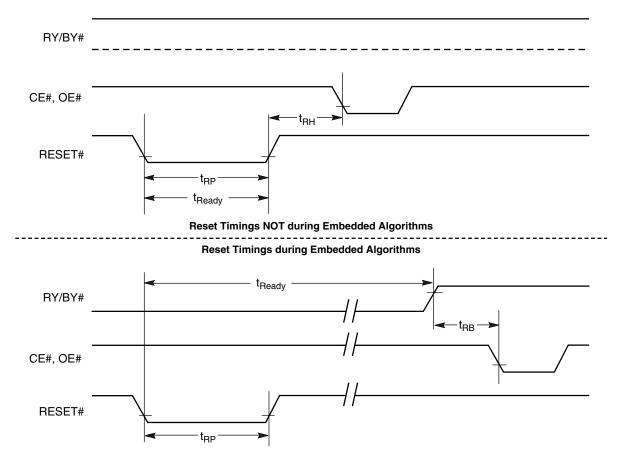


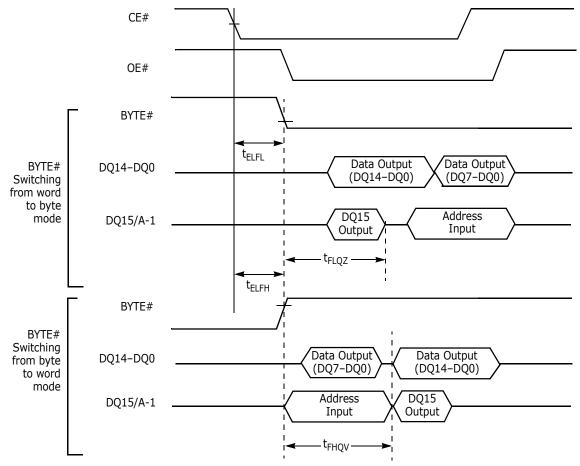
Figure I4. Reset Timings



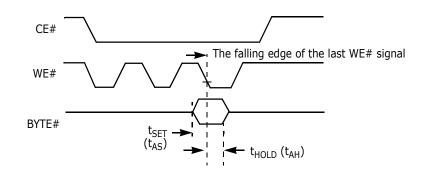
AC Characteristics Word/Byte Configuration (BYTE#)

| Para | Parameter | | | Speed Options | | | |
|-------|--------------------------------------|---------------------------------------|-----|---------------|----|----|------|
| JEDEC | Std. | Description | | 60 | 70 | 90 | Unit |
| | t _{ELFL/} t _{ELFH} | CE# to BYTE# Switching Low or High | Max | | 5 | | ns |
| | t _{FLQZ} | BYTE# Switching Low to Output HIGH Z | Max | | 16 | | ns |
| | t _{FHQV} | BYTE# Switching High to Output Active | Min | 60 | 70 | 90 | ns |









Note: Refer to the Erase/Program Operations table for t_{AS} and t_{AH} specifications.

Figure I6. BYTE# Timings for Write Operations

52



AC Characteristics Erase and Program Operations

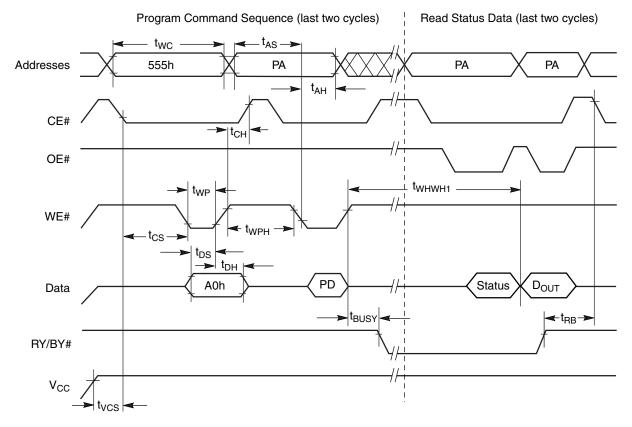
| Para | meter | | | | Sp | eed Optio | ons | | |
|--------------------|--------------------|---|---------|-----|-------|-----------|-----|------|--|
| JEDEC | Std | Description | | | 60 | 70 | 90 | Unit | |
| t _{AVAV} | t _{WC} | Write Cycle Time (Note 1) | | Min | 60 | 70 | 90 | ns | |
| t _{AVWL} | t _{AS} | Address Setup Time | | Min | | 0 | | ns | |
| | t _{ASO} | Address Setup Time to OE# low during tog polling | gle bit | Min | | 12 | | ns | |
| t _{WLAX} | t _{AH} | Address Hold Time | | Min | 35 | 40 | 45 | ns | |
| | t _{AHT} | Address Hold Time From CE# or OE# high during toggle bit polling | | Min | | 0 | | ns | |
| t _{DVWH} | t _{DS} | Data Setup Time | | Min | 35 | 40 | 45 | ns | |
| t _{WHDX} | t _{DH} | Data Hold Time | | Min | | 0 | | ns | |
| | t _{OEPH} | Output Enable High during toggle bit pollin | g | Min | | 20 | | ns | |
| t _{GHWL} | t _{GHWL} | Read Recovery Time Before Write (OE# High to WE# Low) | | Min | 0 | | | ns | |
| t _{ELWL} | t _{CS} | CE# Setup Time | | Min | | 0 | | ns | |
| t _{WHEH} | t _{CH} | CE# Hold Time | | Min | | 0 | | ns | |
| t _{WLWH} | t _{WP} | Write Pulse Width | | Min | 25 | 30 | 35 | ns | |
| t _{WHDL} | t _{WPH} | Write Pulse Width High | | Min | 25 | 30 | 30 | ns | |
| | t _{SR/W} | Latency Between Read and Write Operation | าร | Min | | 0 | | ns | |
| + | + | Programming Operation (Note 2) | Byte | Тур | 4 | | | | |
| t _{WHWH1} | t _{WHWH1} | | Word | Тур | | 6 | | μs | |
| t _{WHWH1} | t _{WHWH1} | Accelerated Programming Operation, Byte or Word (Note 2) | | Тур | Гур 4 | | | μs | |
| t _{WHWH2} | t _{WHWH2} | Sector Erase Operation (Note 2) | | | 0.4 | | | sec | |
| | t _{VCS} | V _{CC} Setup Time (Note 1) | | Min | | 50 | | μs | |
| | t _{RB} | Write Recovery Time from RY/BY# | | Min | | 0 | | ns | |
| | t _{BUSY} | Program/Erase Valid to RY/BY# Delay | | Max | | 90 | | ns | |

Notes:

1. Not 100% tested.

2. See the "Erase And Programming Performance" section for more information.





Notes:

- 1. PA = program address, PD = program data, D_{OUT} is the true data at the program address.
- 2. Illustration shows device in word mode.



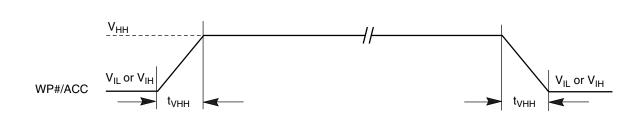
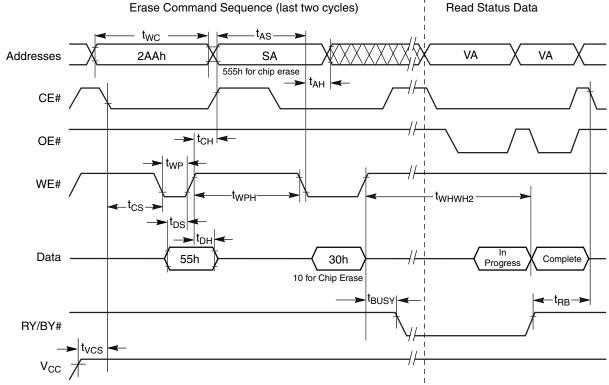


Figure 18. Accelerated Program Timing Diagram



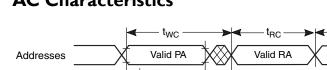


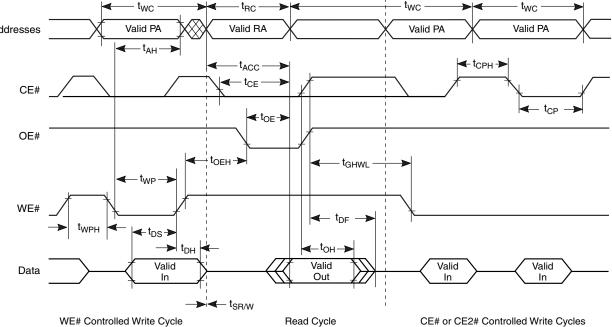
Notes:

- 1. SA = sector address (for Sector Erase), VA = Valid Address for reading status data (see "Write Operation Status".
- 2. These waveforms are for the word mode.

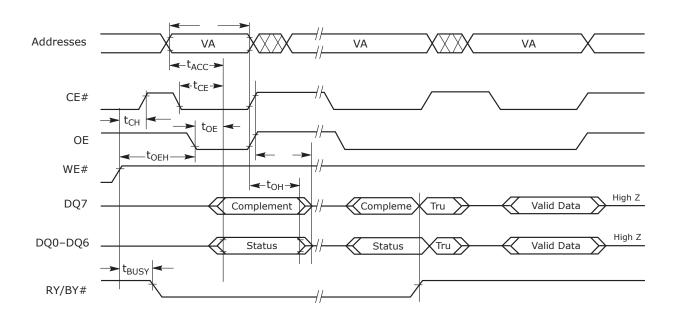
Figure 19. Chip/Sector Erase Operation Timings



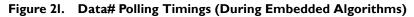




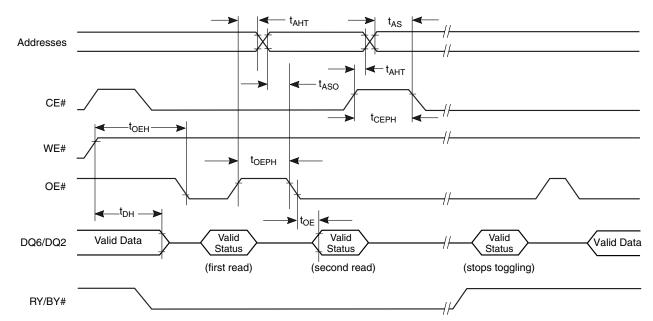
Back-to-back Read/Write Cycle Timings Figure 20.



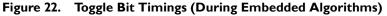
Note: VA = Valid address. Illustration shows first status cycle after command sequence, last status read cycle, and array data read cycle.







Note: VA = Valid address; not required for DQ6. Illustration shows first two status cycle after command sequence, last status read cycle, and array data read cycle



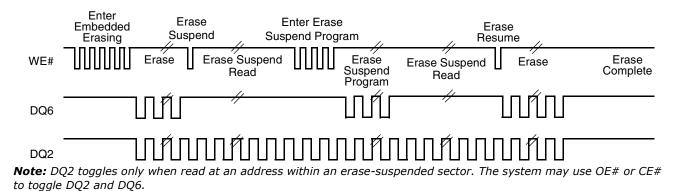


Figure 23. DQ2 vs. DQ6

Temporary Sector Unprotect

| Parameter | | | | | |
|-----------|-------------------|---|-----|-------------------|------|
| JEDEC | Std | Description | | All Speed Options | Unit |
| | t _{VIDR} | V_{ID} Rise and Fall Time (See Note) | Min | 500 | ns |
| | t _{VHH} | V _{HH} Rise and Fall Time (See Note) | Min | 250 | ns |
| | t _{RSP} | RESET# Setup Time for Temporary Sector Unprotect | Min | 4 | μs |
| | t _{RRB} | RESET# Hold Time from RY/BY# High for Temporary Sector Unprotect | Min | 4 | μs |

Note: Not 100% tested.

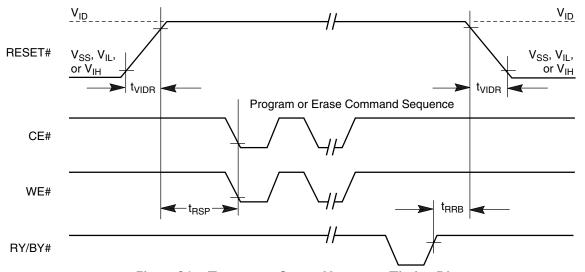
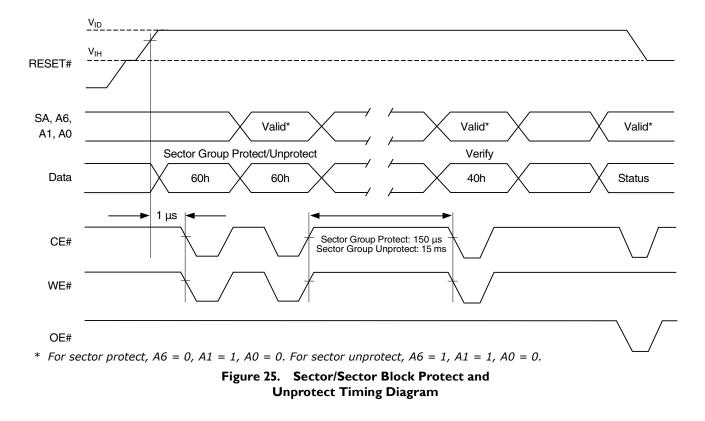


Figure 24. Temporary Sector Unprotect Timing Diagram







AC Characteristics Alternate CE# Controlled Erase and Program Operations

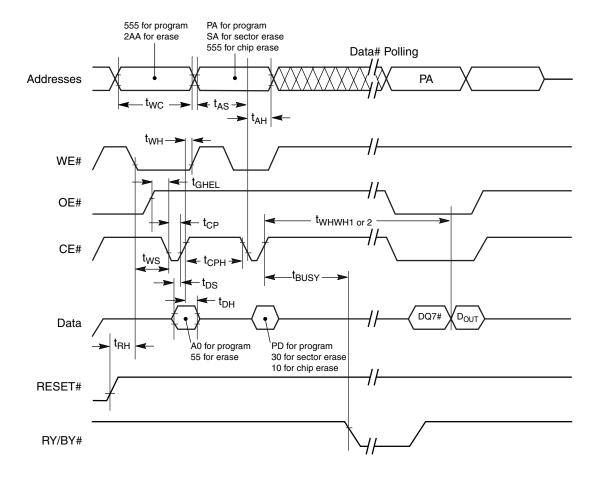
| Parameter | | | | | Speed Options | | | |
|--------------------|--------------------|---|------|-----|---------------|----|-----|------|
| JEDEC | Std. | Description | | | 60 | 70 | 90 | Unit |
| t _{AVAV} | t _{WC} | Write Cycle Time (Note 1) | | Min | 55 | 70 | 90 | ns |
| t _{AVWL} | t _{AS} | Address Setup Time | | Min | 0 | | | ns |
| t _{ELAX} | t _{AH} | Address Hold Time | | Min | 35 | 40 | 45 | ns |
| t _{DVEH} | t _{DS} | Data Setup Time | | Min | 35 | 40 | 45 | ns |
| t _{EHDX} | t _{DH} | Data Hold Time | | Min | 0 | | | ns |
| t _{GHEL} | t _{GHEL} | Read Recovery Time Before Write (OE# High to WE# Low) | | Min | 0 | | | ns |
| t _{WLEL} | t _{WS} | WE# Setup Time | | Min | 0 | | | ns |
| t _{EHWH} | t _{WH} | WE# Hold Time | | Min | 0 | | ns | |
| t _{ELEH} | t _{CP} | CE# Pulse Width | | Min | 25 | 30 | 35 | ns |
| t _{EHEL} | t _{CPH} | CE# Pulse Width High | | Min | 25 | 30 | 30 | ns |
| L | t _{WHWH1} | t _{WHWH1} Programming Operation (Note 2) | Byte | Тур | 4 | | | |
| t _{WHWH1} | | | Word | Тур | | 6 | | μs |
| t _{WHWH1} | t _{WHWH1} | Accelerated Programming Operation, Byte or Word (Note 2) | | Тур | 4 | | μs | |
| t _{WHWH2} | t _{WHWH2} | Sector Erase Operation (Note 2) | | Тур | 0.4 | | sec | |

Notes:

1. Not 100% tested.

2. See the "Erase And Programming Performance" section for more information.





Notes:

- 1. Figure indicates last two bus cycles of a program or erase operation.
- 2. PA = program address, SA = sector address, PD = program data.
- 3. DQ7# is the complement of the data written to the device. D_{OUT} is the data written to the device.
- 4. Waveforms are for the word mode.

Figure 26. Alternate CE# Controlled Write (Erase/Program) Operation Timings



Erase And Programming Performance

| Parameter | | Typ (Note 1) | Max (Note 2) | Unit | Comments |
|------------------------------------|------------------|--------------|--------------|--------------------------|---------------------------|
| Sector Erase Time | 0.4 | 2 | sec | Excludes 00h programming | |
| Chip Erase Time | | 28 | | sec | prior to erasure (Note 4) |
| Byte Program Time | | 4 | 80 | μs | |
| Word Program Time | | 6 | 100 | μs | |
| Accelerated Byte/Word Program Time | | 4 | 70 | μs | Excludes system level |
| | Byte Mode | 12.6 | 50 | | overhead (Note 5) |
| Chip Program Time (Note 3) | Word Mode | 12.0 | 35 | sec | |
| | Accelerated Mode | 10 | 30 | | |

Notes:

- 1. Typical program and erase times assume the following conditions: 25°C, V_{CC} = 3.0 V, 100,000 cycles; checkerboard data pattern.
- 2. Under worst case conditions of 90°C, $V_{CC} = 2.7 V$, 1,000,000 cycles.
- *3.* The typical chip programming time is considerably less than the maximum chip programming time listed, since most bytes program faster than the maximum program times listed.
- 4. In the pre-programming step of the Embedded Erase algorithm, all bytes are programmed to 00h before erasure.
- 5. System-level overhead is the time required to execute the two- or four-bus-cycle sequence for the program command. See Table 13 for further information on command definitions.
- 6. The device has a minimum cycling endurance of 100,000 cycles per sector.

TSOP Pin Capacitance

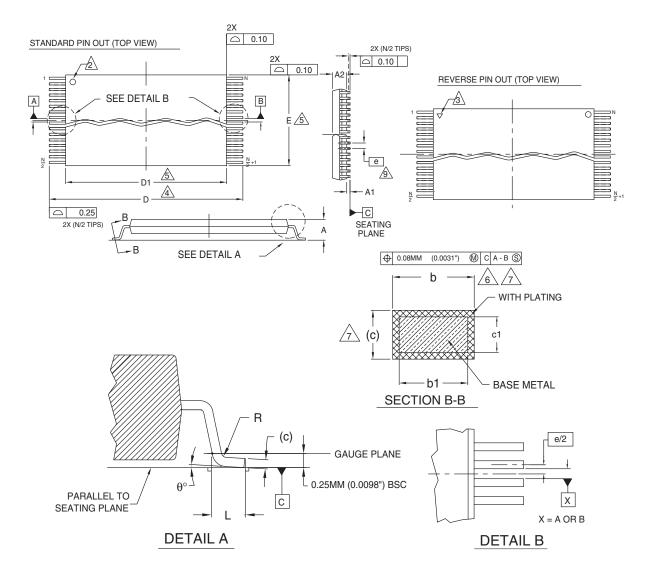
| Parameter Symbol | Parameter Description | Test Setup | | Тур | Max | Unit |
|------------------|-------------------------|---------------|------|-----|-----|------|
| C _{IN} | Input Capacitance | $V_{IN} = 0$ | TSOP | 6 | 7.5 | pF |
| C _{OUT} | Output Capacitance | $V_{OUT} = 0$ | TSOP | 8.5 | 12 | pF |
| C _{IN2} | Control Pin Capacitance | $V_{IN} = 0$ | TSOP | 7.5 | 9 | pF |

Notes:

- 1. Sampled, not 100% tested.
- 2. Test conditions $T_A = 25^{\circ}C$, f = 1.0 MHz.



Physical Dimensions TS 048—48-Pin Standard TSOP



| | - | 0/700.0 | 10 | | | |
|---------|---------------|---------|-------|--|--|--|
| Package | TS/TSR 048 | | | | | |
| Jedec | MO-142 (D) DD | | | | | |
| Symbol | MIN | NOM | MAX | | | |
| A | - | - | 1.20 | | | |
| A1 | 0.05 | - | 0.15 | | | |
| A2 | 0.95 | 1.00 | 1.05 | | | |
| b1 | 0.17 | 0.20 | 0.23 | | | |
| b | 0.17 | 0.22 | 0.27 | | | |
| c1 | 0.10 | - | 0.16 | | | |
| С | 0.10 | - | 0.21 | | | |
| D | 19.80 | 20.00 | 20.20 | | | |
| D1 | 18.30 | 18.40 | 18.50 | | | |
| E | 11.90 | 12.00 | 12.10 | | | |
| е | 0.50 BASIC | | | | | |
| L | 0.50 | 0.60 | 0.70 | | | |
| θ | 0° | - | 8° | | | |
| R | 0.08 | - | 0.20 | | | |
| N | N 48 | | | | | |

NOTES:

- CONTROLLING DIMENSIONS ARE IN MILLIMETERS (mm).
 - (DIMENSIONING AND TOLERANCING CONFORMS TO ANSI Y14.5M-1982)
- PIN 1 IDENTIFIER FOR REVERSE PIN OUT (DIE UP).
- PIN 1 IDENTIFIER FOR REVERSE PIN OUT (DIE DOWN), INK OR LASER MARK.
- TO BE DETERMINED AT THE SEATING PLANE C: THE SEATING PLANE IS DEFINED AS THE PLANE OF CONTACT THAT IS MADE WHEN THE PACKAGE LEADS ARE ALLOWED TO REST FREELY ON A FLAT HORIZONTAL SURFACE.
- DIMENSIONS D1 AND E DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE MOLD PROTUSION IS 0.15mm (.0059") PER SIDE.
- DIMENSION & DOES NOT INCLUDE DAMBAR PROTUSION. ALLOWABLE DAMBAR PROTUSION SHALL BE 0.08 (0.0031") TOTAL IN EXCESS OF & DIMENSION AT MAX. MATERIAL CONDITION. MINIMUM SPACE BETWEEN PROTRUSION AND AN ADJACENT LEAD TO BE 0.07 (0.0028").
- THESE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.10MM (.0039") AND 0.25MM (0.0098") FROM THE LEAD TIP.
 - LEAD COPLANARITY SHALL BE WITHIN 0.10mm (0.004") AS MEASURED FROM THE SEATING PLANE.
 - DIMENSION "e" IS MEASURED AT THE CENTERLINE OF THE LEADS.

3355 \ 16-038.10c



Revision Summary

Revision A (May 2I, 2004)

Initial release.

Revision A+I (August 5, 2004)

SecSi Sector Flash Memory Region

Reworded how the SecSi Sector area can be protected.

Removed SecSi Sector Protect Verify flowchart.

CMOS Compatible

Updated Output Low Voltage.

Erase and Programming Performance

Updated Word and Byte Mode for the Chip Program Time.

Revision A+II (March 10, 2005)

Deleted 55ns speed option

Changed operating voltage(Vcc) range for 60ns option

Changed standby current(Icc3, Icc4, Icc5)

Deleted SecSi sector protection functionality with RESET#=VIH method.

Colophon

The products described in this document are designed, developed and manufactured as contemplated for general use, including without limitation, ordinary industrial use, general office use, personal use, and household use, but are not designed, developed and manufactured as contemplated (I) for any use that includes fatal risks or dangers that, unless extremely high safety is secured, could have a serious effect to the public, and could lead directly to death, personal injury, severe physical damage or other loss (i.e., nuclear reaction control in nuclear facility, aircraft flight control, air traffic control, mass transport control, medical life support system, missile launch control in weapon system), or (2) for any use where chance of failure is intolerable (i.e., submersible repeater and artificial satellite). Please note that Spansion will not be liable to you and/or any third party for any claims or damages arising in connection with above-mentioned uses of the products. Any semiconductor devices have an inherent chance of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions. If any products described in this document represent goods or technologies subject to certain restrictions on export under the Foreign Exchange and Foreign Trade Law of Japan, the US Export Administration Regulations or the applicable laws of any other country, the prior autorization by the respective government entity will be required for export of those products.

Trademarks and Notice

The contents of this document are subject to change without notice. This document may contain information on a Spansion product under development by Spansion LLC. Spansion LLC reserves the right to change or discontinue work on any product without notice. The information in this document is provided as is without warranty or guarantee of any kind as to its accuracy, completeness, operability, fitness for particular purpose, merchantability, non-infringement of third-party rights, or any other warranty, express, implied, or statutory. Spansion LLC assumes no liability for any damages of any kind arising out of the use of the information in this document.

Copyright © 2003-2005 Spansion LLC. All rights reserved. Spansion, the Spansion logo, MirrorBit, combinations thereof, and ExpressFlash are trademarks of Spansion LLC. Other company and product names used in this publication are for identification purposes only and may be trademarks of their respective companies.