

# 41KP Latched Serial Register

## Benefits

- Combines functions of the LS373 and LS164 devices on a single chip
- Cost and space saving

## Features

- Typical shift frequency of 35 MHz
- Asynchronous master reset
- Non-latched output for synchronous cascaded operation

- Synchronous data transfers
- Useful as input or output port for microprocessors
- TTL and CMOS compatible
- Typical power consumption of 350 mW
- Water soluble flux and total immersion cleaning compatible
- Class II ESD Protection: > 500 V, < 2500 V

## Description

The 41KP Latched Serial Register (LSR) integrated circuit is organized as an internal connection of an 8-bit shift register, an 8-bit level-triggered latch, and an 8-bit, 3-state output driver. The latch, which may be connected to a data bus via the output driver, provides storage for an 8-bit byte within the device. The LSR effectively combines the functions of the LS164 (8-bit serial-in parallel-out shift register) and the LS373 (3-state bus-driving outputs) integrated circuits.

The 41KP LSR is designed to interface output circuits to parallel buses. Typical applications include serial-to-parallel conversion systems, data concentration, scanning and communication subsystems, data communication subsystems, digital trunk subsystems, and reduction of physical interconnection wiring in microprocessor systems. The LSR is compatible with existing parallel-to-serial registers and may be used to form an efficient data serialization system. The devices can be cascaded to produce a register that can handle multiples of 8-bit bytes. The LSR output port can be used to drive discrete circuits, LEDs, relays, logic circuits, or independent buses. The device, fabricated using LSTTL technology, is available in a 16-pin plastic DIP or SOJ package for surface mounting.

## User Information

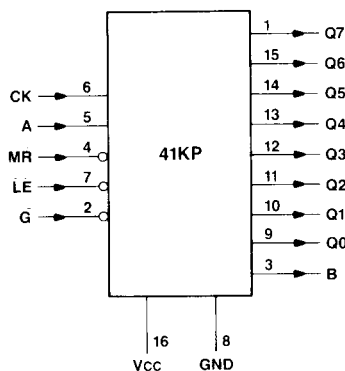


Figure 1. 41KP LSR Logic Symbol

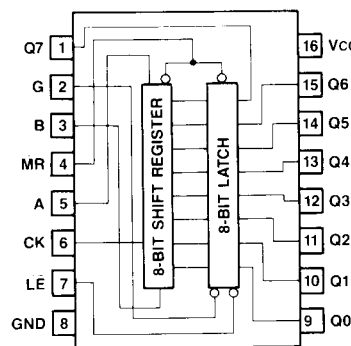


Figure 2. 41KP LSR Pin Function Diagram

## 41KP Latched Serial Register

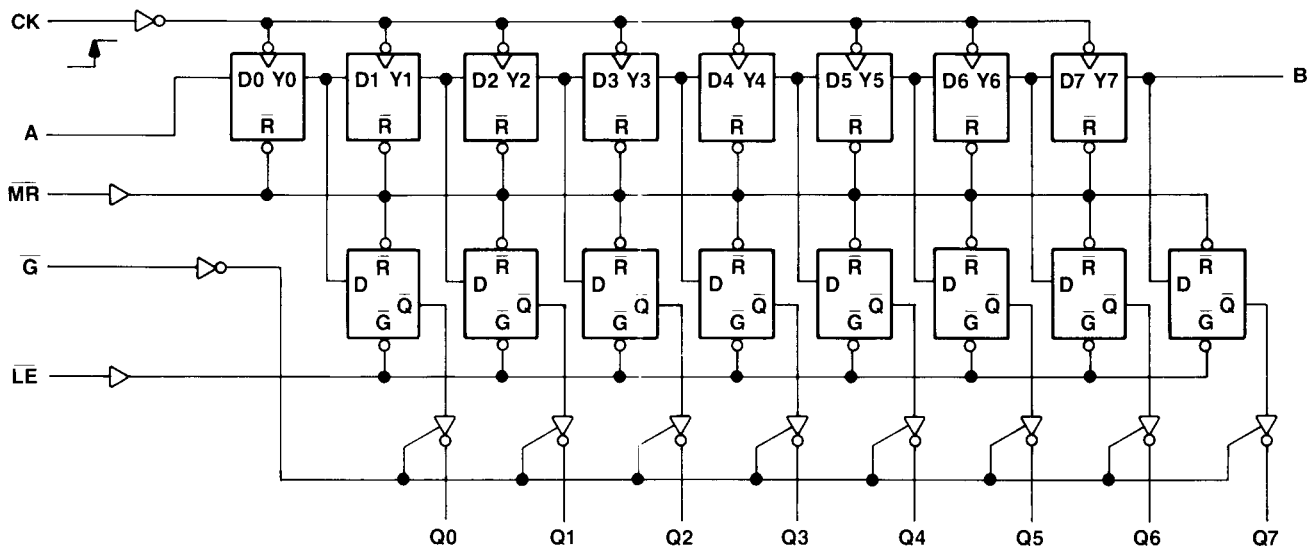


Figure 3. 41KP LSR Logic Diagram

Table 1. 41KP LSR Pin Descriptions

| Pin     | Symbol          | Type | Name/Function   |
|---------|-----------------|------|---|
| 1, 9—15 | Q7, Q0—Q6       | O    | <b>Parallel Data Outputs.</b> 8-bit parallel output port.   |
| 2       | $\overline{G}$  | I    | <b>Output Enable.</b> This input controls the 3-state capability of the output driver. When $\overline{G}$ is low, the output pins of the 41KP LSR are in the active state and reflect the data contents of the storage latch. When $\overline{G}$ is high, the output pins of the LSR are in the high impedance state. |
| 3       | B               | O    | <b>Serial Data Output.</b> This output reflects the data on the output of the last or rightmost flip-flop of the shift register. The output is used to allow cascading of several LSRs in an expanded system.   |
| 4       | $\overline{MR}$ | I    | <b>Master Reset.</b> A low at this input overrides all inputs and asynchronously clears the shift register and the storage latch. A high at this input is required for all other LSR operations.  |
| 5       | A               | I    | <b>Serial Data Input.</b> This input accepts serial data as input to the LSR. Data on this input shifts into the first of the eight flip-flops that make up the shift register on the low-to-high transition of the clock (CK) input.   |
| 6       | CK              | I    | <b>Serial Clock Input.</b> A low-to-high transition on this input causes data stored in the shift register to shift one place to the right.   |

| Pin | Symbol          | Type | Name/Function   |
|-----|-----------------|------|---|
| 7   | $\overline{LE}$ | I    | <b>Latch Enable.</b> A high on this input causes the latch to be transparent. Data on the input to the latch (from the shift register) appears on the latch output if $\overline{LE}$ is high. When $\overline{LE}$ is low, data at the latch output remains constant regardless of the data input to the latch. In this state, the shift register data is latched, allowing a new data byte to be assembled into the shift register. |
| 8   | GND             | —    | <b>Ground.</b> The power and signal ground connection for the LSR.  |
| 16  | Vcc             | —    | <b>+5 V Supply.</b>   |

## Overview

The 41KP LSR effectively combines the features of serial shifting and storage into a single 16-pin, plastic DIP or SOJ. The 8-bit shift register is functionally identical to the LS164 8-bit serial-in parallel-out shift register. Serial data is entered into the shift register synchronously with a low-to-high transition of the shift register clock input. Each transition shifts data one place to the right, entering the data at  $D_N$  into  $Y_N$  just prior to transition.

The 8-bit latch is a transparent D-type. While the latch enable ( $\overline{LE}$ ) control signal is high, the output of the latch follows the input from the shift register. When  $\overline{LE}$  is low, the output of the latch is held at the current level.

The output driver features “totem-pole,” 3-state outputs specifically designed for driving high-capacitive loads. The high-impedance 3-state and increased high-logic-level drive provides the LSR with the capability of being connected directly to bus-organized systems. The output port may be used to drive discrete circuits, LEDs, relays, logic circuits, or independent buses.

The latch and output driver have separate control signals to facilitate interconnection of the device within a system environment. The control signals do not affect the operation of the serial shift register. Old data can be retained while new data is being assembled in the shift register, or new data can be assembled and subsequently transferred to the storage latch while the output is in the off state.

The data that appears on the output pins is true data from the shift register. No inversion takes place from serial input to parallel output.

On power-up, the internal flip-flops of the shift register and storage latch assume a random state. Therefore, the system should assert a master reset for an initial condition.

## 41KP Latched Serial Register

### Characteristics

#### Electrical Characteristics

$T_A = 0\text{ }^{\circ}\text{C}$  to  $85\text{ }^{\circ}\text{C}$ ,  $V_{CC} = 5.0 \pm 0.5\text{ V}$

| Parameter   | Symbol    | Min | Max   | Unit          |
|---|-----------|-----|-------|---------------|
| Input Voltages:   |           |     |       |               |
| Low Level   | $V_{IL}$  | —   | 0.7   | V             |
| High Level  | $V_{IH}$  | 2.0 | 7.5   | V             |
| Input Clamp Diode Voltage ( $V_{CC} = 4.5\text{ V}$ , $I_I = -5\text{ mA}$ )              | $V_{IK}$  | —   | -1.5  | V             |
| Output Voltages (except B output):  |           |     |       |               |
| Low Level ( $V_{CC} = 4.5\text{ V}$ , $V_I = 2.0\text{ V}$ , $I_{CL} = 12\text{ mA}$ )    | $V_{OL}$  | —   | 0.4   | V             |
| Low Level ( $V_{CC} = 4.5\text{ V}$ , $V_I = 2.0\text{ V}$ , $I_{OL} = 24\text{ mA}$ )    | $V_{OL}$  | —   | 0.5   | V             |
| High Level ( $V_{CC} = 4.5\text{ V}$ , $V_I = 0.7\text{ V}$ , $I_{OH} = -3.0\text{ mA}$ ) | $V_{OH}$  | 2.4 | —     | V             |
| Output Voltages (B output):   |           |     |       |               |
| Low Level ( $V_{CC} = 4.5\text{ V}$ , $V_I = 2.0\text{ V}$ , $I_{CL} = 0.4\text{ mA}$ )   | $V_{OL}$  | —   | 0.4   | V             |
| Low Level ( $V_{CC} = 4.5\text{ V}$ , $V_I = 2.0\text{ V}$ , $I_{OL} = 0.8\text{ mA}$ )   | $V_{OL}$  | —   | 0.5   | V             |
| High Level ( $V_{CC} = 4.5\text{ V}$ , $V_I = 0.7\text{ V}$ , $I_{OH} = -0.1\text{ mA}$ ) | $V_{OH}$  | 2.4 | —     | V             |
| DN Off-State Current:   |           |     |       |               |
| Low Level at DN ( $V_{OL} = 0.3\text{ V}$ )   | $I_{OZL}$ | -20 | 20    | $\mu\text{A}$ |
| High Level at DN ( $V_{OH} = 5.5\text{ V}$ )  | $I_{OZH}$ | -20 | 20    | $\mu\text{A}$ |
| Input Currents:   |           |     |       |               |
| Low Level ( $V_{CC} = 5.5\text{ V}$ , $V_I = 0.4\text{ V}$ )                              | $I_{IL}$  | —   | -0.40 | mA            |
| High Level ( $V_{CC} = 5.5\text{ V}$ , $V_I = 2.7\text{ V}$ )                             | $I_{IH}$  | —   | 0.02  | mA            |
| High Level ( $V_{CC} = 5.5\text{ V}$ , $V_I = 7.5\text{ V}$ )                             | $I_I$     | —   | 0.1   | mA            |
| Output Short-Circuit Current ( $V_{CC} = 5.5\text{ V}$ ):                                 |           |     |       |               |
| Except B Output   | $I_{OS}$  | -20 | -100  | mA            |
| B Output  | $I_{OS}$  | -20 | -165  | mA            |
| Power Supply Current ( $V_{CC} = 5.5\text{ V}$ )  | $I_{CC}$  | —   | 85    | mA            |

#### Maximum Ratings

Power Supply Voltage ( $V_{CC}$ ).....7.0 Vdc  
 Operating Temperature Range ( $T_A$ ).....0  $^{\circ}\text{C}$  to 85  $^{\circ}\text{C}$   
 Storage Temperature Range ( $T_{stg}$ ).....-55  $^{\circ}\text{C}$  to +150  $^{\circ}\text{C}$

Maximum Ratings are the limiting conditions that can be applied under all variations of circuit and environmental conditions without the occurrence of permanent damage.

External leads can be bonded or soldered safely at temperatures up to 300  $^{\circ}\text{C}$ .

**Handling Precautions**

Although protection circuitry has been designed into this device, proper precautions should be taken to avoid exposure to electrostatic discharge (ESD) during handling and mounting. AT&T employs a human-body model (HBM) and a charged-device model (CDM) for ESD susceptibility testing and protection design evaluation. ESD voltage thresholds are dependent on the circuit parameters used to define the model. No industry-wide standard has been adopted for the CDM. However, a standard HBM (resistance = 1500  $\Omega$ , capacitance = 100 pF) is widely used and therefore can be used for comparison purposes. The HBM ESD threshold presented here was obtained using these circuit parameters.

| Human-Body Model ESD Threshold |                 |
|--------------------------------|-----------------|
| Device                         | Voltage         |
| 41KP                           | >500 V, <2500 V |

**Timing Characteristics**

T<sub>A</sub> = 25 °C, C<sub>L</sub> = 15 pF, V<sub>CC</sub> = 5.0 V

| Symbol           | Description   | Min | Max | Unit |
|------------------|---|-----|-----|------|
| f <sub>max</sub> | Maximum Clock Frequency                                   | 25  | —   | MHz  |
| t <sub>PCK</sub> | Propagation Delay, Positive Clock to Output               | —   | 59  | ns   |
| t <sub>PMR</sub> | Propagation Delay, Negative $\overline{MR}$ to Output     | —   | 46  | ns   |
| t <sub>PLE</sub> | Propagation Delay, $\overline{LE}$ to Output              | —   | 36  | ns   |
| t <sub>PZH</sub> | Output Enable Time to HIGH Level                          | —   | 28  | ns   |
| t <sub>PZL</sub> | Output Enable Time to LOW Level                           | —   | 36  | ns   |
| t <sub>PLZ</sub> | Output Disable Time from LOW Level                        | —   | 90  | ns   |
| t <sub>PHZ</sub> | Output Disable Time from HIGH Level                       | —   | 40  | ns   |
| t <sub>SD</sub>  | Set-Up Time, A-Input to Positive Clock                    | 15  | —   | ns   |
| t <sub>HD</sub>  | Hold Time, A-Input to Positive Clock                      | 5   | —   | ns   |
| t <sub>WCH</sub> | Clock Pulse Width, HIGH                                   | 20  | —   | ns   |
| t <sub>WCL</sub> | Clock Pulse Width, LOW                                    | 20  | —   | ns   |
| t <sub>WMR</sub> | $\overline{MR}$ Pulse Width                               | 20  | —   | ns   |
| t <sub>REC</sub> | Recovery Time, Positive $\overline{MR}$ to Positive Clock | 30  | —   | ns   |
| t <sub>WLE</sub> | $\overline{LE}$ Pulse Width                               | 15  | —   | ns   |
| t <sub>SLE</sub> | Set-Up Time, $\overline{LE}$ to Clock                     | 32  | —   | ns   |
| t <sub>HLE</sub> | Hold Time, $\overline{LE}$ to Clock                       | 0   | —   | ns   |

# 41KP Latched Serial Register

## Timing Diagrams

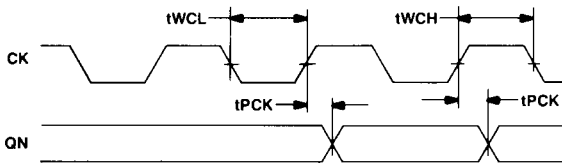


Figure 4. Propagation Delay — Clock to Output

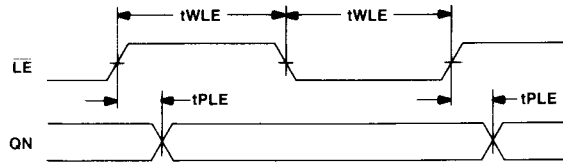


Figure 7. Propagation Delay — Latch Enable to Output

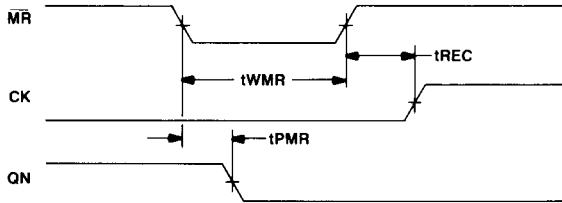


Figure 5. Propagation Delay — Negative Master Reset to Output

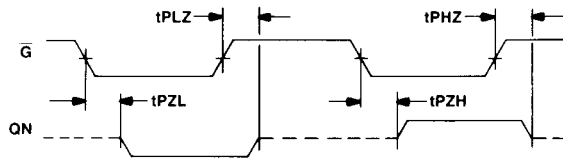


Figure 8. Propagation Delay — Output Enable to Output

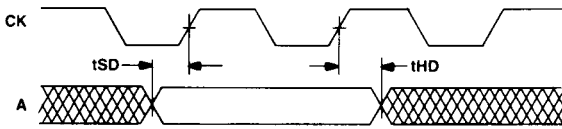


Figure 6. Set-Up and Hold Times — A Input to Positive Clock

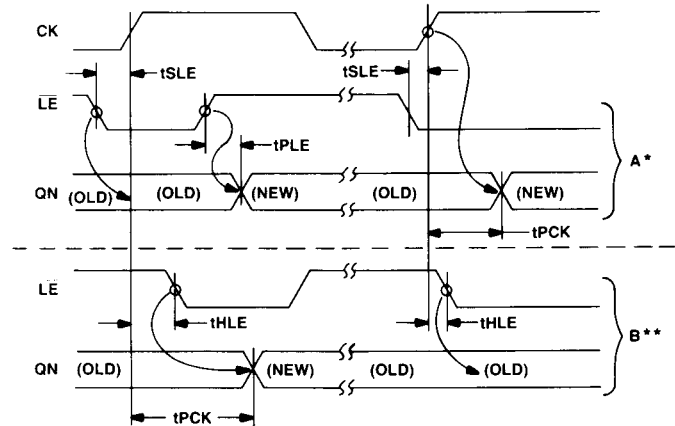


Figure 9. Set-Up Times — Clock to Latch Enable

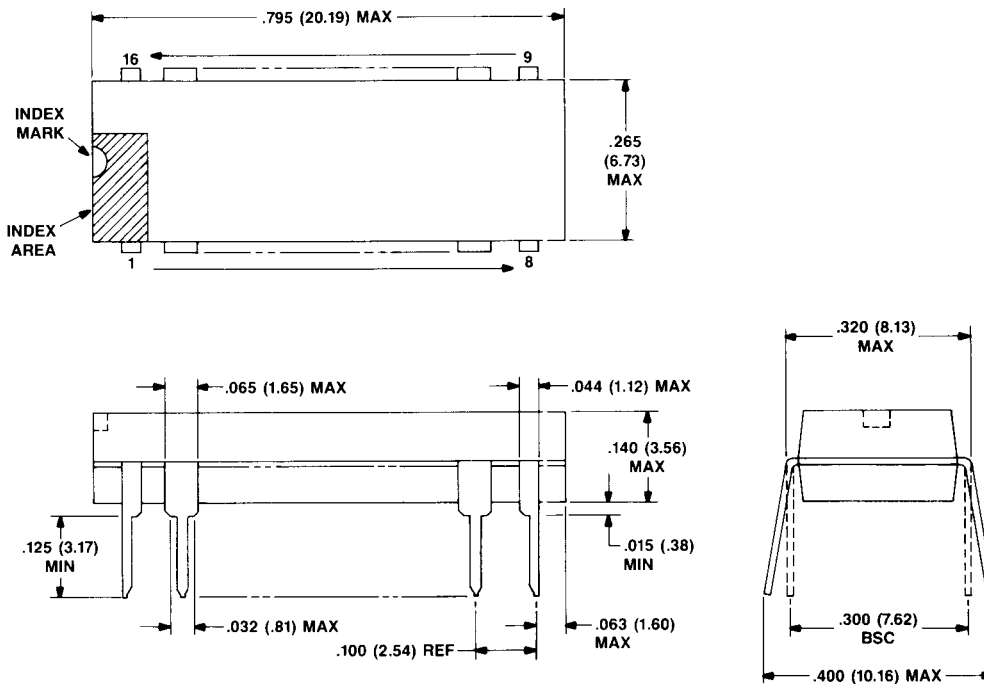
\* Bracket "A" waveforms show when  $\overline{LE}$  must be made low to latch current data ( $t_{SLE}$ ). This must occur prior to new data entry. If  $\overline{LE}$  is made low close to the rising edge of CK, output will change reflecting new data.

\*\* Bracket "B" waveforms show minimum time needed ( $t_{HLE}$ ) before  $\overline{LE}$  may be made low to latch new data. If  $\overline{LE}$  is made low too soon after rising edge of CK, old data is retained rather than entry of new data by rising edge of CK.

**Outline Diagrams**

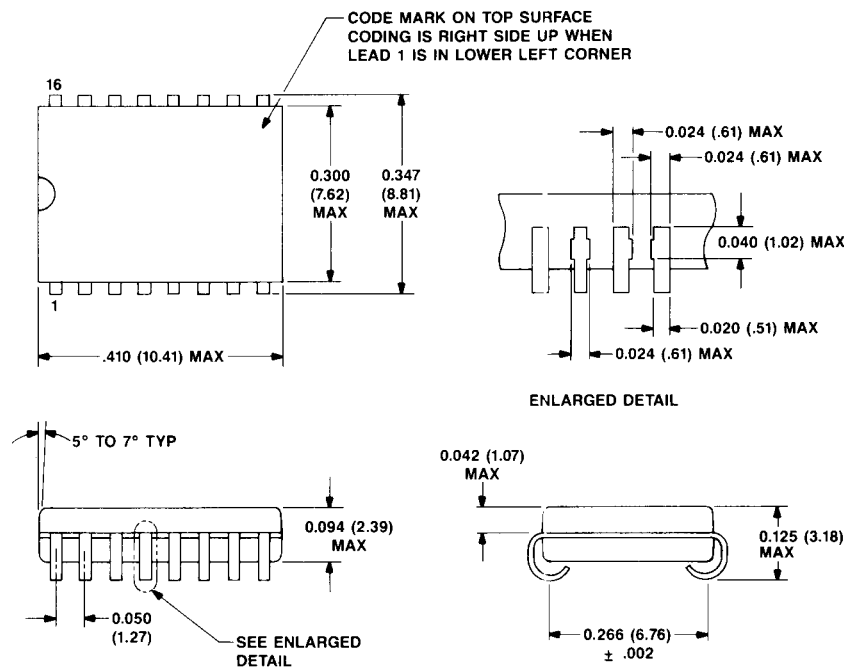
**16-Pin Plastic DIP**

Dimensions are in inches and (millimeters).



**16-Pin Plastic SOJ, Surface Mounting**

Dimensions are in inches and (millimeters).



Note: Pin numbers are shown for reference only.

## 41KP Latched Serial Register

### Ordering Information

| Device Code | Package            | Comcode   |
|-------------|--------------------|-----------|
| 41KP        | 16-Pin Plastic DIP | 103157103 |
| 41KP-B*     | 16-Pin Plastic DIP | 103836771 |

\* "B" denotes burned-in devices.

Note: The 41KP LSR is available in a 16-pin SOJ. The proper code will be provided upon ordering.

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