

DESCRIPTION

The TDK 73M1903 Analog Front End (AFE) IC includes fully differential hybrid driver outputs, which connect to the telephone line interface through a transformer-based DAA. The receive pins are also fully differential for maximum flexibility and performance. This arrangement allows for the design of a high performance hybrid circuit to improve signal to noise performance under low receive level conditions, and compatibility with any standard transformer intended for PSTN communications applications.

The device incorporates a programmable sample rate circuit to support soft modem and DSP based implementations of all speeds up to V.92 (56Kbps). The sampling rates supported are from 7.2kHz to 14.4kHz by programming pre-scaler NCO and PLL NCO.

The TDK 73M1903 device incorporates a digital host interface that is compatible with the serial ports found on most commercially available DSPs and processors and exchanges both payload and control information with the host.

Cost saving features of the device include an input reference frequency circuit, which accepts a range of crystals from 9-27MHz. It also accepts external reference clock values between 9-40MHz generated by the host processor. In most applications, this eliminates the need for a dedicated crystal oscillator and reduces the bill of material (BOM).

The 73M1903 also supports two analog loop back and one digital loop back test modes.

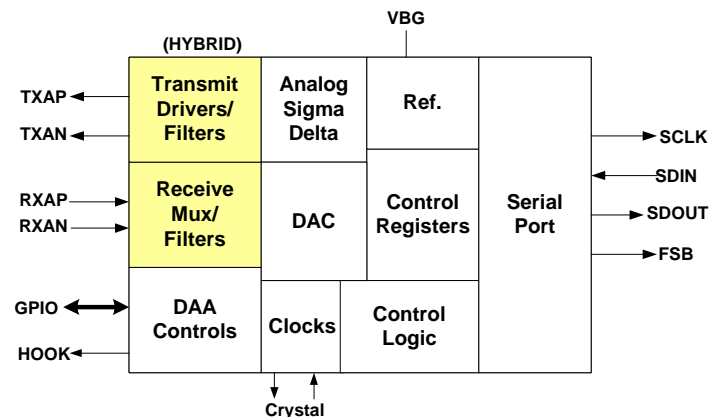
The 73M1903 in 32-TQFP package is footprint compatible with 73M2901CL embedded modem and allows for the same circuit design to accommodate soft modem, V.22bis hard modem, and high speed (V.32bis/V.34/V.92) applications through population of an external data pump device.

FEATURES

- Up to 56Kbps (V.92) performance
- Programmable sample rates (7.2 - 14.4kHz)
- Reference clock range of 9-40MHz
- Crystal frequency range of 9-27MHZ
- Host synchronous serial interface operation
- Pin compatible with 73M2901CL modem
- Low power modes
- On board line interface drivers
- Fully differential receiver and transmitter Drivers for transformer interface
- 3.0V – 3.6V operation
- 5V tolerant I/O
- Industrial temperature range (-40 to +85°C)
- JATE compliant transmit spectrum
- Package options: 32-TQFP and 32-MLF

APPLICATIONS

- Set Top Boxes
- Personal Video Recorders (PVR)
- Multifunction Peripherals (MFP)
- Fax Machines
- Internet Appliances
- Game Consoles
- Point of Sale Terminals
- Automatic Teller Machines
- Speaker Phones
- RF Modems



REVISION HISTORY

Revision Level	Revision Date	Revision Description
2.4	March 13, 2003	Generated Preliminary Datasheet Release
2.5	May 22, 2003	Inconsistent Pin-out tables corrected; Entered limitation on effective divide ≥ 2.0 ; VBG=1.19V; Fs range increased to 14.4kHz; Gain change in ALB mode (Txd code must be reduced by 3dB);SCLK drive strength increased by x5.
3.0	June 2003	Make changes to reflect B01
3.3	August 2003	Make changes to reflect B02
3.4	August 2003	Make changes to delete test comments and pass band ripple
3.5	September 2003	Revised front sheet, added block diagram, IDD current changed.
3.6	September 9, 2003	Add active low fonts, clean up register map, match text to figures, general cleanup
3.7	September 9,2003	Update footer revision on pages 1,2 Removed Pin 21 CLKOUT signal from package drawing.
3.8	October 10, 2003	Update divider tables, RXG[1,0] setting, misc. corrections

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SIGNAL DESCRIPTION

The TDK 73M1903 modem AFE IC is available in a 32 pin TQFP or MLF package with same pin out. The following table describes the function of each pin. There are two pairs of power supply pins, VPA(analog) and VPD(digital). They should be separately decoupled from the supply source in order to isolate digital noise from the analog circuits internal to the chip. Failure to adequately isolate and decouple these supplies will compromise device performance.

PIN NAME	TYPE	PIN #	DESCRIPTION
VND	GND	1,22	Negative Digital Ground
VNA	GND	16	Negative Analog Ground
VPD	PWR	2,25	Positive Digital Supply
VPA	PWR	10	Positive Analog Supply
VPPLL	PWR	20	Positive PLL Supply, shared with VPD
VNPLL	PWR	17	Negative PLL Ground
$\overline{\text{RST}}$	I	9	Master reset. When this pin is a logic 0 all registers are reset to their default states; Weak-pulled high- default
OSCIN	I	19	Crystal oscillator input. When providing an external clock source, drive OSCIN.
OSCOUT	O	18	Crystal oscillator circuit output pin.
GPIO(0-7)	I/O	3, 4, 5, 6, 23, 24,30,31	Software definable digital input/output pins.
VREF	O	13	Reference voltage pin (Reflects Vref)
RXAP	I	15	Receive analog positive input.
RXAN	I	14	Receive analog negative input.
TXAP	O	12	Transmit analog positive output
TXAN	O	11	Transmit analog negative output
SCLK	O	8	Serial interface clock. With SCLK continuous selected, Frequency = 256*Fs (=2.4576MHz for Fs=9.6kHz)
SDOUT	O	32	Serial data output (or input to the host).
SDIN	I	29	Serial data input (or output from the host)
$\overline{\text{FS}}$	O	7	Frame synchronization. (Active Low)
TYPE	I	27	Type of frame sync. Open, weak-pulled high = early (mode1); tied low = late (mode0)
SckMode	I	28	Controls the SCLK behavior after FS. Open, weak-pulled high = SCLK Continuous; tied low = 32 clocks per R/W cycle.

Table 1: -32 TQFP and MLF Pin Description

SERIAL INTERFACE

The serial data port is a bi-directional port that can be supported by most DSPs. Although the 73M1903 is a peripheral to the DSP (host controller), the 73M1903 is the master of the serial port. It generates a serial bit clock, Sclk, from a system clock, Sysclk, which is normally an output from an on-chip PLL that can be programmed by the user. The serial bit clock is always derived by dividing the system clock by 18. The sclk rate, F_{sclk}, is related to the frame synchronization rate, F_s, by the relationship $F_{sclk} = 256 \times F_s$ or $F_s = F_{sclk} / 256 = F_{sys} / 18 / 256 = F_{sys} / 4608$, where F_{sys} is the frequency of Sysclk. F_s is also the rate at which both the transmit and receive data bytes are sent (received) to (by) the Host. Throughout this document two pairs of sample rate, F_s, and crystal frequency, F_{xtal}, will be often cited to facilitate discussions. They are:

1. F_{xtal1} = 27MHz, F_{s1} = 7.2kHz
2. F_{xtal2} = 18.432MHz, F_{s2} = 8kHz.
3. F_{xtal3} = 24.576MHz, F_{s3} = 9.6kHz – chip default.

Upon reset, until a switch to the PLL based clock, Pllclk, occurs, the system clock will be at the crystal frequency, F_{xtal}, and therefore the serial bit clock will be $sclk = F_{sys}/18 = F_{xtal}/18$.

Examples:

1. If F_{xtal1} = 27.000MHz, then $sclk=1.500MHz$ and $F_s=sclk/256 = 5.859375kHz$.
2. If F_{xtal2} = 18.432MHz, then $sclk=1.024MHz$ and $F_s=sclk/256 = 4.00kHz$.
3. If F_{xtal3} = 24.576MHz, then $sclk=1.3653MHz$ and $F_s=sclk/256 = 5.33kHz$.

When 73M1903 is programmed through the serial port to a desired F_s and the PLL has settled out, the system clock will transition to the PLL-based clock in a glitch-less manner.

Examples:

1. If F_{s1} = 7.2kHz, F_{sys} = 4608 * F_s = 33.1776MHz and $sclk = F_{sys} / 18 = 1.8432MHz$.
2. If F_{s2} = 8.0kHz, F_{sys} = 4608 * F_s = 36.8640MHz and $sclk = F_{sys} / 18 = 2.048MHz$.
3. If F_{s3} = 9.6kHz, F_{sys} = 4608 * F_s = 44.2368MHz and $sclk = F_{sys} / 18 = 2.4576MHz$.

This transition is entirely controlled by the host. Upon reset or power down of PLL and/or analog front end, the chip will automatically run off the crystal until the host forces the transition by setting a bit in a designated serial port register – location bit 7, 0Eh. The transition should be forced on or after the second Frame Synch period following the write to a designated PLL programming register (0Dh).

When reprogramming the PLL the host should first transition the system clock to the crystal before reprogramming the PLL so that any transients associated with it will not adversely impact the serial port communication.

Power saving is accomplished by disabling the analog front end by clearing bit 7 of CTRL1 (address 00h), ENFE=0.

During the normal operation, a data \overline{FS} is generated by the 1903 at the rate of F_s. For every data FSB there are 16 bits transmitted and 16 bits received. The frame synchronization (\overline{FS}) signal is pin programmable for type. \overline{FS} can either be early or late determined by the state of the TYPE input pin. When Type pin is left open, an early \overline{FS} is generated in the bit clock prior to the first data bit transmitted or

received. When held low, a late \overline{FS} operates as a chip select; the \overline{FS} signal is active for all bits that are transmitted or received. The TYPE input pin is sampled when the reset pin is active and ignored at all other times. The final state of the TYPE pin as the reset pin is de-asserted determines the frame synchronization mode used.

The bits transmitted on the SDOUT pin are defined as follows:

bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
RX15	RX14	RX13	RX12	RX11	RX10	RX9	RX8	RX7	RX6	RX5	RX4	RX3	RX2	RX1	RX0

If the Hardware Control bit (bit 0 of register 01h) is set to zero, the 16 bits that are received on the SDIN are defined as follows:

bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
TX15	TX14	TX13	TX12	TX11	TX10	TX9	TX8	TX7	TX6	TX5	TX4	TX3	TX2	TX1	CTL

In this case TX0=0 is forced.

If the Hardware Control bit (bit 0 of register 01h) is set to one, the 16 bits that are received on the SDIN input are defined as follows:

bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
TX15	TX14	TX13	TX12	TX11	TX10	TX9	TX8	TX7	TX6	TX5	TX4	TX3	TX2	TX1	TX0

Bit 15 is transmitted/received first. Bits RX15:0 are the receive code word. Bits TX15:0 are the transmit code word. If the hardware control bit is set to one, a control frame is initiated between every pair of data frames. If the hardware control bit is set to zero, CTL is used by software to request a control frame. If CTL is high, a control frame will be initiated before the next data frame. A control frame allows the controller to read or write status and control to the 73M1903.

The control word received on the SDIN pin is defined as follows:

bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
R/W	A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0

The control word transmitted on the SDOUT pin is defined as follows:

bit15	bit14	bit13	bit12	bit11	bit10	bit9	bit8	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
0	0	0	0	0	0	0	0	D7	D6	D5	D4	D3	D2	D1	D0

If the R/\overline{W} bit is set to a 0, the data byte transmitted on the SDOUT pin is all zeros and the data received on the SDIN pin is written to the register pointed to by the received address bits; A6-A0. If the R/\overline{W} bit is set to a 1, there is no write to any register and the data byte transmitted on the SDOUT pin is the data contained in the register pointed to by address bits A6-A0. Only one control frame can occur between any two data frames.

Writes to unimplemented registers are ignored. Reading an unimplemented register returns a value of 0. The position of a control data frame is controlled by the SPOS; bit 1 of register 01h. If SPOS is set to a 0 the control frames occur mid way between data frames, i.e., the time between data frames is equal. If SPOS is set to a 1, the control frame is $\frac{1}{4}$ of the way between consecutive data frames, i.e., the control frame is closer to the first data frame. This is illustrated in Figure 3.

New to TDK 73M1903 modem AFE IC is a feature that shuts off the serial clock (SCLK) after 32 cycles of SCLK following the frame synch (Figure 2). This mode is controlled by the SckMode pin. If this pin is left open the clock will run continuously. If SckMode is low the clock will be gated on for 32 clocks for each \overline{FS} . The SDOOUT and \overline{FS} pins change values following a rising edge of SCLK. The SDIN pin is sampled on the falling edge of SCLK. Figure 4 shows the timing diagrams for the serial port.

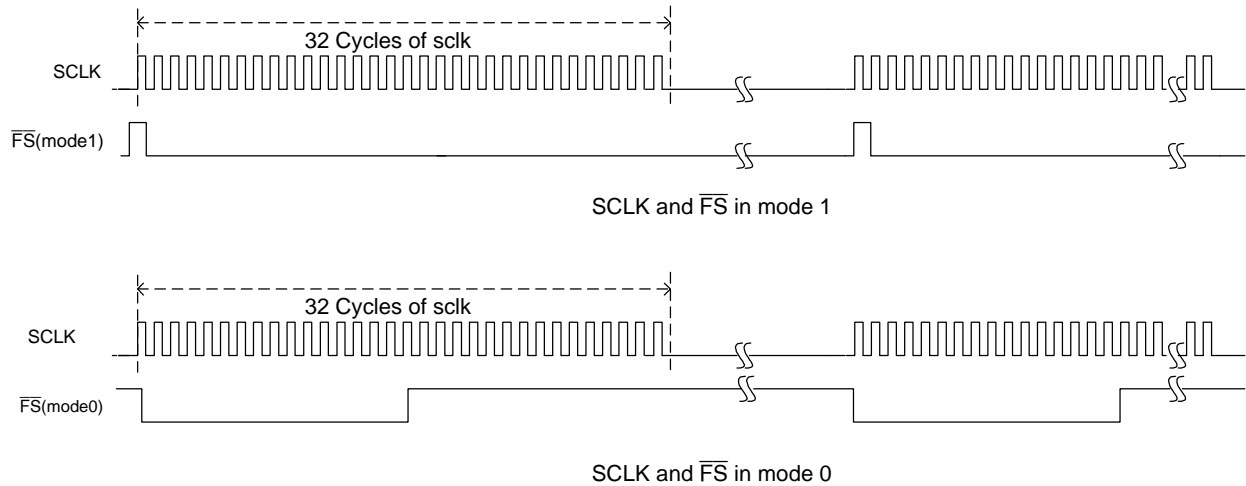


Figure 1 -SCLK and \overline{FS} with SckMode = 0

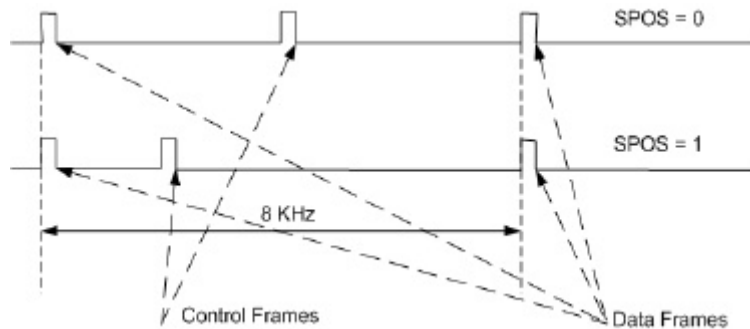


Figure 2 -Control frame position vs. SPOS

PRODUCT DATA SHEET
MEMORY MAP

The following table shows the memory map of addressable registers in the 73M1903. Each register and its bits are described in detail in the following sections.

ADDRESS	Default	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
00	08h	ENFE	unused	DTMFBST	TXBST0	TXDIS	RXG1	RXG0	RXGAIN
01	00h	TMEN	DIGLB	ANALB	INTLB	reserved	RXPULL	SPOS	HC
02	FFh	GPIO7	GPIO 6	GPIO 5	GPIO 4	GPIO 3	GPIO 2	GPIO 1	GPIO 0
03	FFh	DIR7	DIR6	DIR5	DIR4	DIR3	DIR2	DIR1	DIR0
04	00h	reserved	reserved	reserved	reserved	reserved	reserved	reserved	reserved
05	00h	reserved	reserved	reserved	reserved	reserved	reserved	reserved	reserved
06	10h	Rev3	Rev2	Rev1	Rev0	unused	reserved	reserved	reserved
07	00h	unused	reserved	reserved	reserved	reserved	reserved	reserved	reserved
08	00h	Pseq7	Pseq6	Pseq5	Pseq4	Pseq3	Pseq2	Pseq1	Pseq0
09	0Ah	Prst2	Prst1	Prst0	Pdvsr4	Pdvsr3	Pdvsr2	Pdvsr1	Pdvsr0
0A	22h	Ichp3	Ichp2	Ichp1	Ichp0	FL	Kvco2	Kvco1	Kvco0
0B	12h	unused	Ndvsr6	Ndvsr5	Ndvsr4	Ndvsr3	Ndvsr2	Ndvsr1	Ndvsr0
0C	00h	Nseq7	Nseq6	Nseq5	Nseq4	Nseq3	Nseq2	Nseq1	Nseq0
0D	C0h	Xtal1	Xtal0	reserved	reserved	unused	Nrst2	Nrst1	Nrst0
0E	00h	Frcvco	PwdnPLL	reserved	unused	unused	unused	unused	unused
0E-7F		unused	unused	unused	unused	unused	unused	unused	unused

To prevent unintended operation, do not write to reserved or unused locations. These locations are for factory test or future use only and are not intended for customer programming.

Table 2: -Memory Map

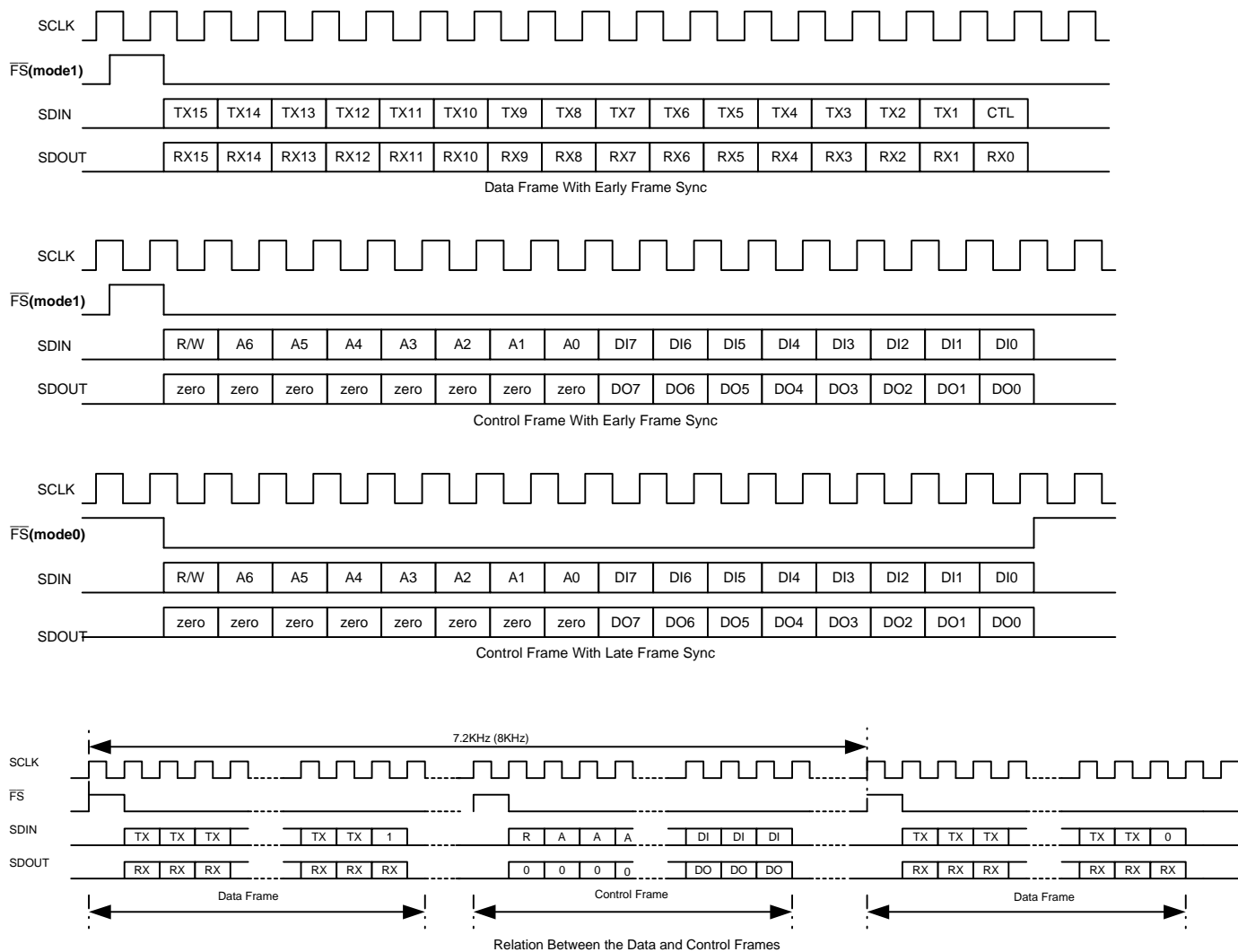


Figure 3 -Serial Port Timing Diagram

GPIO

The TDK 73M1903 modem AFE device provides 8 user defined I/O pins. Each pin is programmed separately as either an input or an output by a bit in a direction register. If the bit in the direction register is set high, the corresponding pin is an input whose value is read from the GPIO data register. If it is low, the pin will be treated as an output whose value is set by the GPIO data register.

To avoid unwanted current contention and consumption in the system from the GPIO port before the GPIO is configured after a reset, the GPIO port I/Os are initialized to a high impedance state. The input structures are protected from floating inputs, and no output levels are driven by any of the GPIO pins. The GPIO pins are configured as inputs or outputs when the host controller (or DSP) writes to the GPIO direction register. The GPIO direction and data registers are initialized to all ones (FFh) upon reset.

GPIO Data (GPIO): Address 02h

Reset State FFh

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
GPIO7	GPIO6	GPIO5	GPIO4	GPIO3	GPIO2	GPIO1	GPIO0

Bits in this register will be asserted on the GPIO(7:0) pins if the corresponding direction register bit is a 0. Reading this address will return data reflecting the values of pins GPIO(7:0).

GPIO Direction (DIR): Address 03h

Reset State FFh

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
DIR7	DIR6	DIR5	DIR4	DIR3	DIR2	DIR1	DIR0

This register is used to designate the GPIO pins as either inputs or outputs. If the register bit is low, the corresponding GPIO pin is programmed as an output. If the register bit is a 1, the corresponding pin will be treated as an input.

ANALOG I/O

Figure 4 on page 12 shows the block diagram of the analog front end. The analog interface circuit uses differential transmit and receive signals to and from the external circuitry.

The hybrid driver in the TDK 73M1903 IC is capable of connecting directly, but not limited to, a transformer-based Direct Access Arrangement (DAA). The hybrid driver is capable of driving the DAA's line coupling transformer, which carries an impedance on the primary side that is typically rated at 600Ω depending on the transformer and matching network. The hybrid drivers can also drive high impedance loads without modification. The class AB behavior of the amplifiers provides load dependent power consumption.

An on-chip band gap voltage is used to provide an internal voltage reference and bias currents for the analog receive and transmit channels. The reference derived from the bandgap, nominally 1.25 Volts, is multiplied to 1.36Volts and output at the VREF pin. Several voltage references, nominally 1.25 Volts, are used in the analog circuits. The band gap and reference circuits are disabled after a chip reset since the ENFE bit is reset to a default state of zero. When ENFE=0, the band gap voltage and the analog bias currents are disabled. In this case all of the analog circuits are powered down and draw less than 5 μ A of current.

A clock generator (CKGN) is used to create all of the non-overlapping phase clocks needed for the time sampled switched-capacitor circuits, ASDM, DAC1, and TLPF. The CKGN input is 2 times the analog/digital interface sample rate or 3.072MHz clock for $F_s=8$ kHz.

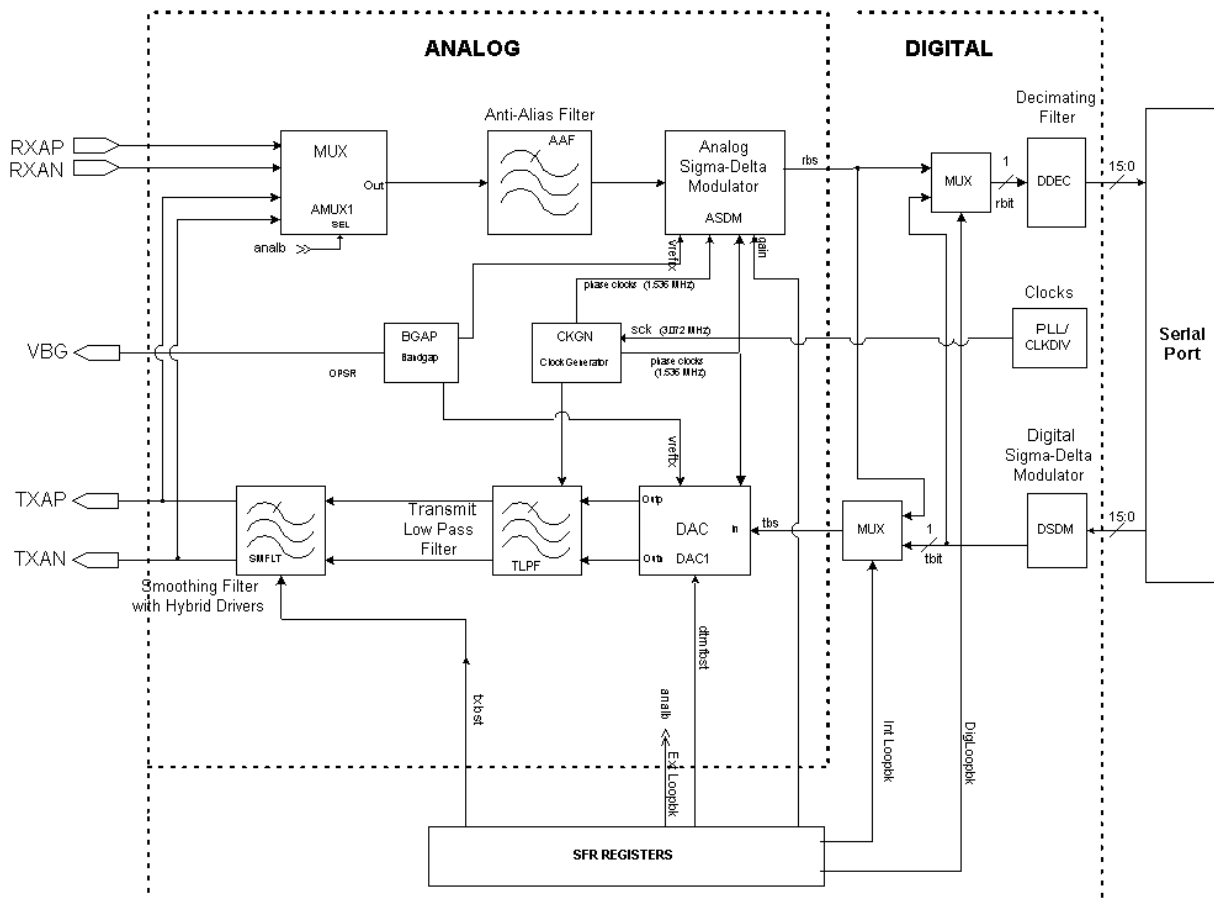


Figure 4 -Analog block diagram

CLOCK GENERATION

Crystal Oscillator and Pre-scaler NCO

The crystal oscillator operates over wide choice of crystals (from 9MHz to 27MHz) and it is first input to an NCO based pre-scaler (divider) prior to being passed onto an on-chip PLL. The intent of the pre-scaler is to convert the crystal oscillator frequency, F_{xtal} , to a convenient frequency to be used as a reference frequency, F_{ref} , for the PLL. The NCO pre-scaler requires a set of three numbers to be entered thru the serial port (Pseq[7:0], Prst[2:0] and Pdvsr[2:0]). The PLL also requires 3 numbers as for programming; Ndvrs[6:0], Nseq[7:0], and Nrst[2:0]. The following is a brief description of the registers that control the NCOs, PLLs, and sample rates for the TDK 73M1903 IC. The tables show some examples of the register settings for different clock and sample rates. A more detailed discussion on how these values are derived can be found in Appendix B.

Control Register (CTRL 8): Address 08h

Reset State 00h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
Pseq7	Pseq6	Pseq5	Pseq4	Pseq3	Pseq2	Pseq1	Pseq0

This corresponds to the sequence of divisor. If Prst[2:0] =0 this register is ignored.

Control Register (CTRL 9): Address 09h

Reset State 0Ah

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
Prst2	Prst1	Prst0	Pdvsr4	Pdvsr3	Pdvsr2	Pdvsr1	Pdvsr0

Prst[2:0] represents the rate at which the sequence register is reset.

Pdvsr[4:0] represents the divisor.

Control Register (CTRL 10): Address 0Ah

Reset State 22h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
lchp3	lchp2	lchp1	lchp0	FL	Kvco2	Kvco1	Kvco0

.Kvco2:0 represents the magnitude of Kvco associated with the VCO within PLL. This indicates the center frequency of the VCO when the control voltage is 1.6 Volts and the slope of the VCO freq vs. control voltage (i.e., Kvco.). FL represents the PLL loop filter settings.

Kvco2	Kvco1	Kvco0	Fvco	Kvco
0	0	0	33 MHz	38MHz/v
0	0	1	36 MHz	38MHz/v
0	1	0	44 MHz	40MHz/v
0	1	1	48 MHz	40MHz/v
1	0	0	57 MHz	63MHz/v
1	0	1	61 MHz	63MHz/v
1	1	0	69 MHz	69MHz/v
1	1	1	73 MHz	69MHz/v

Table 3: Kvco vs. Settings at Vc=1.6V, 25°C

FL	PLLloop Filter settings
0	R1=32kΩ C1=100pF, C2=2.5pF
1	R1=16kΩ C1=100pF, C2=2.5pF

Table 4: PLL Loop Filter Settings
Control Register (CTRL 11): Address 0Bh
Reset State 12h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
	Ndvsr6	Ndvsr5	Ndvsr4	Ndvsr3	Ndvsr2	Ndvsr1	Ndvsr0

Ndvsr[6:0] represents the divisor. If Nrst[2:0] =0 this register is ignored.

Control Register (CTRL 12): Address 0Ch
Reset State 00h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
Nseq7	Nseq6	Nseq5	Nseq4	Nseq3	Nseq2	Nseq1	Nseq0

Nseq[7:0] represents the divisor sequence.

Control Register (CTRL 13): Address 0Dh
Reset State 48h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
Xtal1	Xtal0	reserved	reserved	unused	Nrst2	Nrst1	Nrst0

Xtal[1:0] : 00 = Xtal osc. bias current at 120μA
 01 = Xtal osc. bias current at 180μA
 10 = Xtal osc. bias current at 270μA
 11 = Xtal osc. bias current at 450μA

If OSCIN is used as a Clock input, “00” setting should be used to save power(=167μA at 27.648MHz).

Nrst[3:0] represents the rate at which the NCO sequence register is reset.

The address 0Dh must be the last register to be written to when effecting a change in PLL.

Control Register (CTRL 14): Address 0Eh
Reset State 00h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
Frcvco	PwdnPLL	reserved	unused	unused	unused	unused	unused

Frcvco = 1 forces VCO as system clock. This is reset upon \overline{RST} , PwdnPLL = 1 or Enfe = 0. Both PwdnPLL and Enfe are delayed coming out of digital section to keep PLL alive long enough to transition the system clock to crystal clock when Frcvco is reset by PwdnPLL or Enfe.

PRODUCT DATA SHEET

PwdnPLL = 1 forces Power down of PLL analog section.

Addr. 00h bit 7 Enfe	Addr. 0Eh bit 6 PwdnPLL	PLL
0	X	PLL Power Off
1	0	PLL Power On
1	1	PLL Power Off

Table 5: PLL Power Down

	Fs (kHz)	Nnco1 Dnco1	PsDiv	PsSeq(7:0)	PsRst =Dnco1 -1	Nnco2 Dnco2	PLIDiv	PIISeq(7:0)	PIIRst =Dnco2 -1	Fvco (Mhz)	PPM
Fxtal(Mhz)=27.0	7.2	8/125	15	11011010	7	5/96	19	XXX10000	4	33.177600	0
	8.0	8/125	15	11011010	7	3/64	21	XXXXX100	2	36.864000	0
	2.4*8/7*3 =8.22857142858	8/169	21	10000000	7	3/89	29	XXXXX110	2	37.917160*	-3
	8.4	8/125	15	11011010	7	5/112	22	XXX10100	4	38.707200	0
	9.0	8/125	15	11011010	7	1/24	24	XXXXXXXXXX	0	41.472000	0
	9.6	8/125	15	11011010	7	5/128	25	XXX11010	4	44.236800	0
	2.4*10/7*3 =10.2857142857	8/125	15	11011010	7	7/192	27	X1010110	6	47.396571	0
	2.4*8/7*4 =10.9714285714	7/50	7	X1000000	6	8/107	13	10100100	7	50.557500*	23
	11.2*	7/52	7	X1010100	6	5/71	14	XXX10000	4	51.611538*	38
	12.0	8/125	15	11011010	7	1/32	32	XXXXXXXXXX	0	55.296000	0
	12.8*	8/65	8	10000000	7	4/71	17	XXXXX1110	3	58.984615*	38
	2.4*10/7*4 =13.7142857143	7/80	11	X1010100	6	4/107	26	XXXXX1110	3	63.196875*	23
	14.4	8/125	15	11011010	7	5/192	38	XXX10100	4	66.355200	0
	Fxtal(Mhz)=24.576	7.2	1/10	10	XXXXXXXXXX	0	2/27	13	XXXXXXXXX10	1	33.177600
8.0		1/10	10	XXXXXXXXXX	0	1/15	15	XXXXXXXXXX	0	36.864000	0
2.4*8/7*3 =8.22857142858		4/35	8	XXXXX1110	3	2/27	13	XXXXXXXXX10	1	37.917257...	0
8.4		1/10	10	XXXXXXXXXX	0	4/63	15	XXXXX1110	3	38.707200	0
9.0		1/10	10	XXXXXXXXXX	0	8/135	16	111111110	7	41.472000	0
9.6		1/10	10	XXXXXXXXXX	0	1/18	18	XXXXXXXXXX	0	44.236800	0
2.4*10/7*3 =10.2857142857		3/28	9	XXXXX100	2	1/18	18	XXXXXXXXXX	0	47.3965714..	0
2.4*8/7*4 =10.9714285714		4/35	8	XXXXX1110	3	1/18	18	XXXXXXXXXX	0	50.5563429..	0
11.2		1/10	10	XXXXXXXXXX	0	1/21	21	XXXXXXXXXX	0	51.609600	0
12		1/10	10	XXXXXXXXXX	0	2/45	22	XXXXXXXXX10	1	55.296000	0
12.8		1/10	10	XXXXXXXXXX	0	1/24	24	XXXXXXXXXX	0	58.982400	0
2.4*10/7*4 =13.7142857143		1/7	7	XXXXXXXXXX	0	1/18	18	XXXXXXXXXX	0	63.19542...	0
14.4		1/10	10	XXXXXXXXXX	0	1/27	27	XXXXXXXXXX	0	66.355200	0
Fxtal(Mhz)=9.216		7.2	1/4	4	XXXXXXXXXX	0	5/72	14	XXX10100	4	33.177600
	8.0	1/4	4	XXXXXXXXXX	0	1/16	16	XXXXXXXXXX	0	36.864000	0
	8.4	1/4	4	XXXXXXXXXX	0	5/84	16	XXX11110	4	38.707200	0
	9.0	1/4	4	XXXXXXXXXX	0	1/18	18	XXXXXXXXXX	0	41.472000	0
	9.6	1/4	4	XXXXXXXXXX	0	5/96	19	XXX10000	4	44.236800	0
	2.4*8/7*4 =10.9714285714	2/7	6	XXXXXX10	4	5/96	19	XXX10000	4	50.556343	0
	11.2	1/4	4	XXXXXXXXXX	0	5/112	22	XXX10100	4	51.609600	0
	12	1/4	4	XXXXXXXXXX	0	1/24	24	XXXXXXXXXX	0	55.296000	0
	12.8	1/4	4	XXXXXXXXXX	0	5/128	25	XXX11010	4	58.982400	0
	14.4	1/8	8	XXXXXXXXXX	0	5/288	57	XXX11010	4	66.355200	0

Table 6: -Examples of NCO Settings

Fxtal(MHz)=24.000	7.2	8/125	15	11011010	7	5/108	21	XXX11010	4	33.1776	0
	8.0	2/25	12	XXXXXX10	1	5/96	19	XXX10000	4	36.864	0
	2.4*8/7*3 =8.22857142858	4/73	18	XXXX1000	3	6/173	28	XX111110	5	37.91781*	15
	8.4	8/125	15	11011010	7	5/126	25	XXX10000	4	38.7072	0
	9.0	4/25	6	XXXX1000	3	5/54	10	XXX11110	4	41.472	0
	9.6	8/125	15	11011010	7	5/144	28	XXX11110	4	44.2368	0
	2.4*10/7*3 =10.2857142857	8/125	15	11011010	7	7/216	30	X1111110	6	47.39657	0
	2.4*8/7*4 =10.9714285714	6/59	9	XX111110	5	7/145	20	X1110110	6	50.5569*	12
	11.2	8/125	15	11011010	7	5/168	33	XXX11010	4	51.6096	0
	12.0	4/25	6	XXXX1000	3	5/72	14	XXX10100	4	55.296	0
	12.8	8/125	15	11011010	7	5/192	38	XXX10100	4	58.9824	0
	2.4*10/7*4 =13.7142857143	5/61	12	XXX10000	4	8/257	32	10000000	7	63.19672*	21
	14.4	7/73	10	X1010100	6	6/173	28	XX111110	5	66.35616*	15
	Fxtal(MHz)=25.35	7.2	8/163	20	10010010	7	3/80	26	110	2	33.177914*

Table 6: -Examples of NCO Settings - continued

Reg Address Fs(Khz)	Reg Address							Ichp (uA)	Kvco [2:0]
	8h	9h	Ah	Bh	Ch	Dh*			
7.2	DA	EF	20	13	10	C4	8	0	
8.0	DA	EF	31	15	04	C2	10	1	
2.4*8/7*3 =8.22857142858	80	F5	41	1D	06	C2	12	1	
8.4	DA	EF	31	16	14	C4	10	1	
9.0	DA	EF	31	18	XX	C0	10	1	
9.6	DA	EF	32	19	1A	C4	10	2	
2.4*10/7*3 =10.2857142857	DA	EF	43	1B	54	C6	12	3	
2.4*8/7*4 =10.9714285714*	40	C7	23	0D	A4	C7	8	3	
11.2*	54	C7	23	0E	10	C4	8	3	
12.0	DA	EF	24	20	XX	C0	8	4	
12.8*	80	E8	15	11	0E	C3	6	5	
2.4*10/7*4 =13.7142857143	54	CB	26	1A	0E	C3	8	6	
14.4	DA	EF	46	26	14	C4	12	6	

Table 7: Clock Generation Register Settings for Fxtal = 27MHz

PRODUCT DATA SHEET

Reg Address Fs(Khz)	8h	9h	Ah	Bh	Ch	Dh*	Ichp (uA)	Kvco [2:0]
7.2	XX	0A	10	0D	02	C1	6	0
8.0	XX	0A	11	0F	XX	C0	6	1
$2.4 \cdot 8 / 7^3$ =8.22857142858	0E	68	11	0D	02	C1	6	1
8.4	XX	0A	21	0F	0E	C3	8	1
9.0	XX	0A	21	10	FE	C7	8	1
9.6	XX	0A	22	12	XX	C0	8	2
$2.4 \cdot 10 / 7^3$ =10.2857142857	04	49	23	12	XX	C0	8	3
$2.4 \cdot 8 / 7^4$ =10.9714285714	0E	68	23	12	XX	C0	8	3
11.2	XX	0A	23	15	XX	C0	8	3
12	XX	0A	14	16	02	C1	6	4
12.8	XX	0A	15	18	XX	C0	6	5
$2.4 \cdot 10 / 7^4$ =13.7142857143	XX	07	16	12	XX	C0	6	6
14.4	XX	0A	26	1B	XX	C0	8	6

Table 8: Clock Generation Register Settings for Fxtal = 24.576MHz

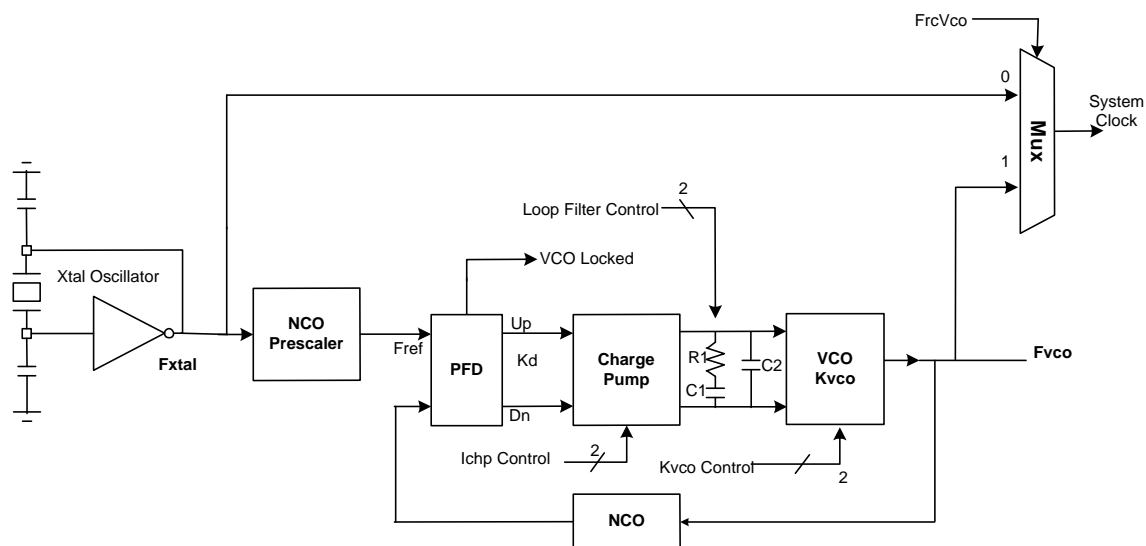
Reg Address Fs(Khz)	8h	9h	Ah	Bh	Ch	Dh*	Ichp (uA)	Kvco [2:0]
7.2	XX	04	20	0E	14	C4	8	0
8.0	XX	04	31	10	XX	C0	10	1
8.4	XX	04	31	10	1E	C4	10	1
9.0	XX	04	31	12	XX	C0	10	1
9.6	XX	04	32	13	10	C4	10	2
$2.4 \cdot 8 / 7^4$ =10.9714285714	02	23	33	13	10	C4	10	3
11.2	XX	04	33	16	14	C4	10	3
12	XX	04	24	18	XX	C0	8	4
12.8	XX	04	35	19	1A	C4	10	5
14.4	XX	08	66	39	1A	C4	16	6

Table 9: Clock Generation Register Settings for Fxtal = 9.216MHz

Reg Address Fs(Khz)	8h	9h	Ah	Bh	Ch	Dh*	Ichp (uA)	Kvco [2:0]
7.2	DA	EF	30	15	1A	C4	10	0
8.0	02	2C	31	13	10	C4	10	1
$2.4 \cdot 8 / 7 \cdot 3$ =8.22857142858	08	72	41	1C	3E	C5	12	1
8.4	DA	EF	41	19	10	C4	12	1
9.0	08	66	11	0A	1E	C4	6	1
9.6	DA	EF	42	1C	1E	C4	12	2
$2.4 \cdot 10 / 7 \cdot 3$ =10.2857142857	DA	EF	43	1E	7E	C6	12	3
$2.4 \cdot 8 / 7 \cdot 4$ =10.9714285714	3E	A9	33	14	76	C6	10	3
11.2	DA	EF	53	21	1A	C4	14	3
12	08	66	14	0E	14	C4	6	4
12.8	DA	EF	45	26	14	C4	12	5
$2.4 \cdot 10 / 7 \cdot 4$ =13.7142857143	10	8C	46	20	80	C7	12	6
14.4	54	CA	46	1C	3E	C5	12	6

Table 10: Clock Generation Register Settings for Fxtal = 24.000MHz

Reg Address Fs(Khz)	8h	9h	Ah	Bh	Ch	Dh*	Ichp (uA)	Kvco [2:0]
7.2	92	F4	50	1A	06	C2	14	0

Table 11: Clock Generation Register Settings for Fxtal = 25.35MHz

Figure 5 - Clock Generation

MODEM RECEIVER

A differential receive signal applied at the RXAP and RXAN pins or the output signal at TXAP and TXAN pass through a multiplexer, which selects the inputs to the ADC. In normal mode, RXAP/RXAN are selected. In analog loopback mode, TXAP/TXAN are selected. The DC bias for the RXAP/RXAN inputs is supplied from TXAP/TXAN thru the external DAA in normal conditions. (See Appendix) It can be supplied internally, in the absence of the external DAA, by setting RXPULL bit in Control Register 2.

The output of the multiplexer goes into a second-order continuous time, Sallen-Key, low-pass filter (AAF) with a 3dB point at approximately 40kHz. The filtered output signal is the input to an analog sigma-delta modulator (ASDM), clocked at an over sampling frequency of 1.536MHz for $F_s = 8\text{kHz}$, which converts the analog signal to a serial bit stream with a pulse density that is proportional to the amplitude of the analog input signal.

There are three gain control bits for the receive path. The RXGAIN bit in control register one results in a +20dB gain of the receive signal when set to a "1". This 20dB of gain compensates for the loss through the DAA while on hook. It is used for Caller ID reception. This gain is realized in the front end of ASDM. The other gain bits in control register 1, RXG1:0, compensate for differences in loss through the receive path.

RXG1	RXG0	Receive Gain Setting
0	0	6dB
0	1	9dB
1	0	12dB
1	1	0dB

Table 10: Receive Gain

The output of ASDM is a serial bit stream that feeds three digital sinc^3 filters. Each filter has a $[\sin(x)/x]^3$ frequency response and provides a 16 bit sample every 288 clock cycles. The filters are synchronized so that there is one sample available after every 96 analog samples or at a rate of 16kHz for $F_s=8\text{kHz}$. The output of the sinc^3 filter is a 17 bit, two's complement number representing the amplitude of the input signal. The sinc^3 filter, by virtue of holding action (for 96 sample period), introduces a droop in the passband that is later corrected for by a 48 tap FIR filter that follows. The maximum digital word that can be output from the filter is 0d800h. The minimum word is 12800h.

The output of the sinc^3 filter is input to another 48 tap digital FIR filter that provides an amplitude correction in the passband to the output of the sinc^3 filter as well as rejecting noise above $F_s/2$ or 4kHz for $F_s=8\text{kHz}$. The output of the this filter is then decimated by a factor of 2; so, the final output is 16 bit, two's complement samples at a rate of 8 kHz.

Figure 6 and Figure 7 depict the sinc^3 filter's frequency response of ASDM along with the 48 tap digital FIR response that compensates for it and the resulting overall response of the receiver.

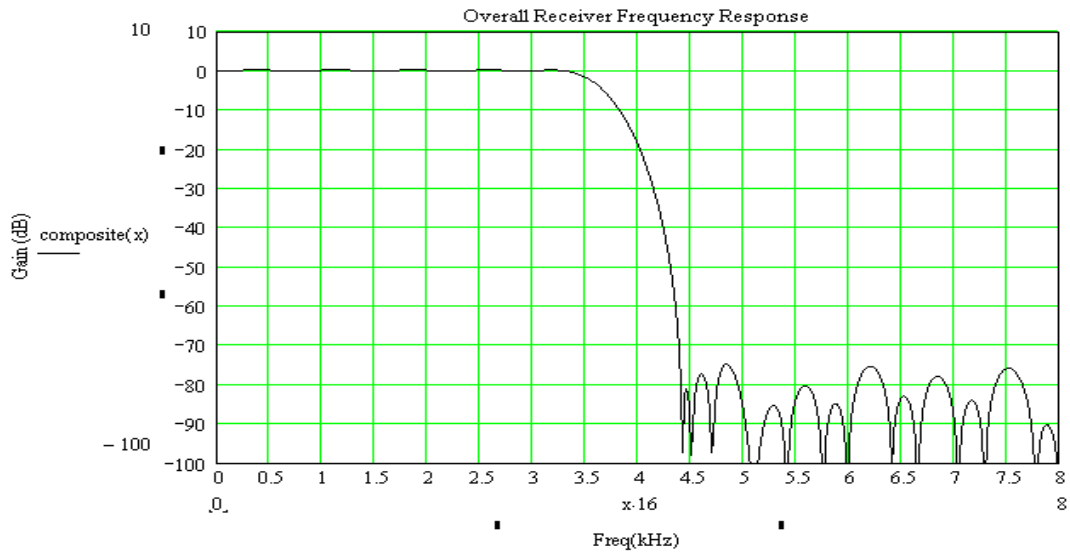


Figure 6 -Overall Receiver Frequency Response

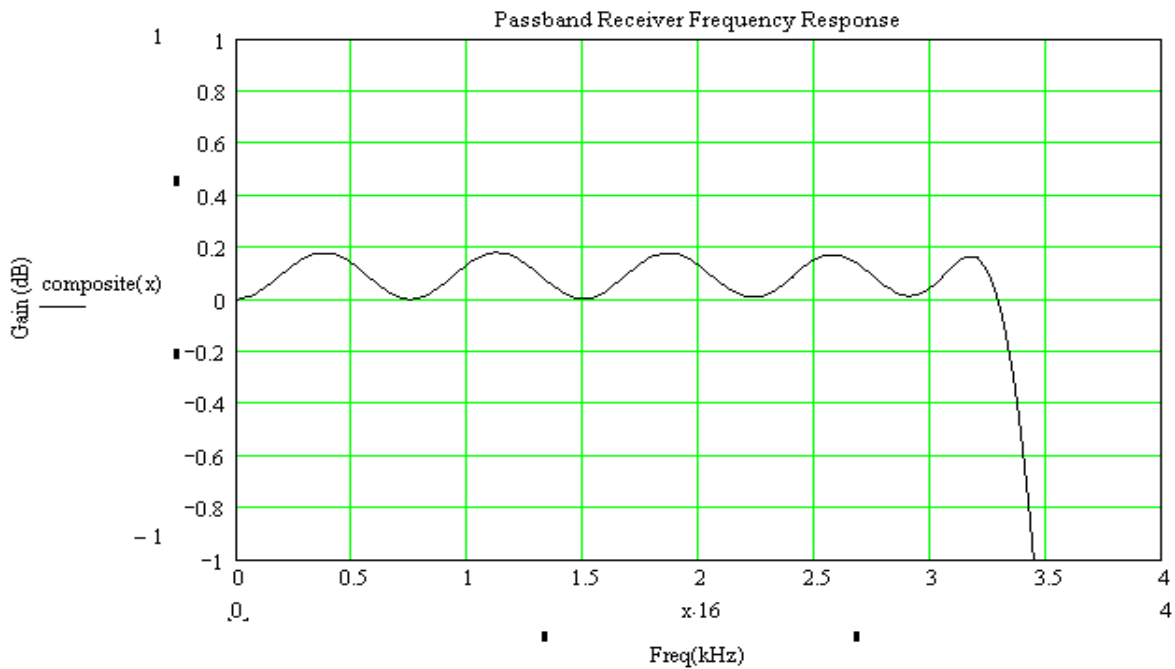


Figure 7 -Rx Path Passband Response

It is important to keep in mind that the receive signal should not exceed 1.16Vpk-diff for proper performance for Rxg=11 (0dB). In particular, if the input level exceeds a value such that one's density of RBS exceeds 99.5%, sinc³ filter output will exceed the maximum input range of the decimation filter and consequently the data will be corrupted. Also for stability reasons, the receive signal should not exceed

1.16Vpk differentially. This value is set at around 65% of the full receive signal of 1.791Vpkdiff at RXAP/RXAN pins that “would” corresponds to ASDM putting out all ones.

Figure 8 and Figure 9 show the spectrum of 1kHz tone received at RXAP/RXAN of 1.16Vpk-diff and 0.5kHz and 1.0kHz tones of 0.6Vpk-diff each, respectively for $F_s=8\text{kHz}$. Note the effect of FIR suppressing the noise above 4kHz but at the same time enhancing (in order to compensate for the passband droop of sinc³ filter) it near the passband edge of 4kHz.

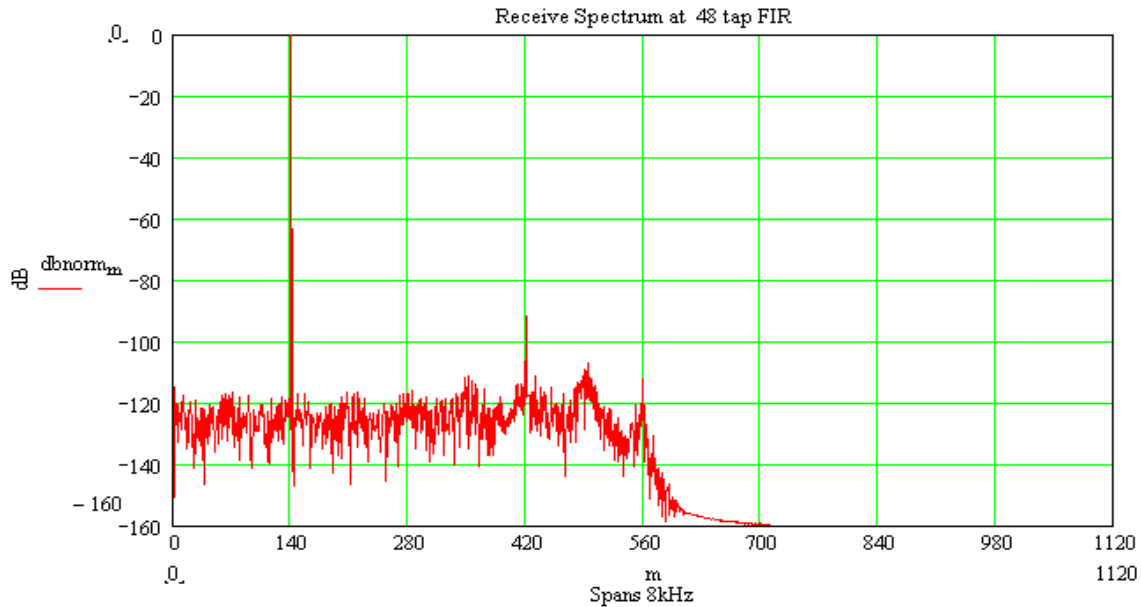


Figure 8 -RXD Spectrum of 1kHz tone

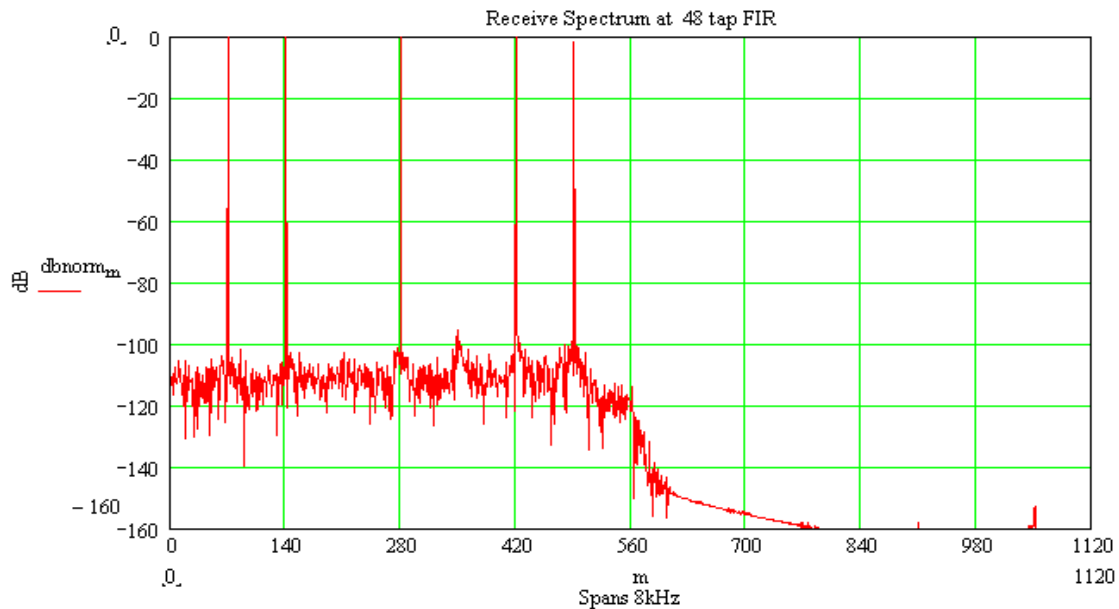


Figure 9 -RXD Spectrum of 0.5kHz, 1kHz, 2kHz, 3kHz and 3.5kHz tones of Equal Amplitudes

MODEM TRANSMITTER

The modem transmitter begins with an 48 tap Transmit Interpolation Filter (TIF) that takes in the 16-bit, two's compliment numbers (TXD) at SDIN pin at $F_s=8\text{kHz}$ rate. It up-samples (interpolates) the data to 16kHz rate rejecting the images at multiples of 8kHz that exist in the original TXD data stream and outputs 16-bit, two's compliment numbers to a digital sigma-delta modulator. The gain of the interpolation filter is 0.640625 (-3.8679dB) at dc.

The digital sigma-delta modulator (DSDM) takes 16-bit, two's compliment numbers as input and generates a 1's bit stream which feeds into a D to A converter (DAC1). The gain through DSDM is 1.0. DSDM takes 16-bit, two's compliment numbers as input and generates a 1's bit stream that feeds into a D to A converter (DAC1).

DAC1 consists of a 5-tap FIR filter and a first order switched capacitor low pass filter both operating at 1.536MHz. It possesses nulls at multiples of 384kHz to allow decimation by the succeeding filter.

DAC1's differential output is fed to a 3rd-order switched-capacitor low pass filter (TLPF). The output of TLPF drives a continuous time smoothing filter. The sampling nature of the transmitter leads to an additional filter response that affects the in-band signals. The response is in the form of $\sin(x)/x$ and can be expressed as $20 \cdot \log \left[\frac{\sin(\pi f/f_s)}{\pi f/f_s} \right]$ where f = signal frequency and f_s = sample frequency = 16 kHz. Figure 10 shows the frequency response of the transmit path from TXD to TXAP/TXAN for a dc to 4kHz in-band signal including the effect of this sampling process plus those of DAC1, TLPF and SMFLT. It is important to note that as TXD is sampled at 8kHz, it is band-limited to 4kHz.

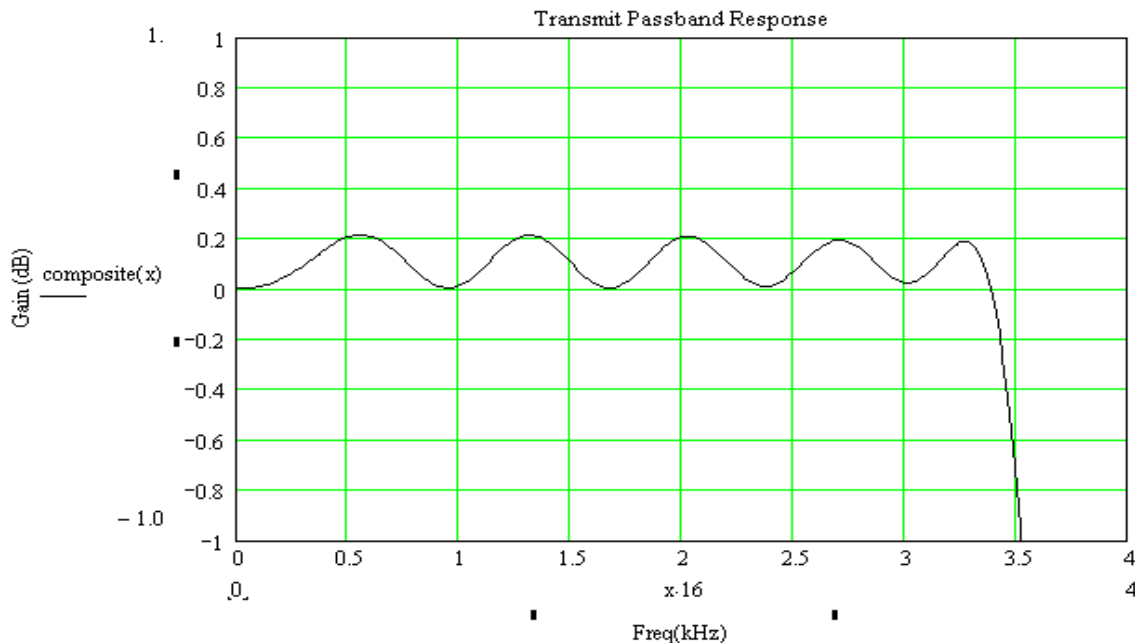


Figure 10 -Frequency Response of TX Path for DC to 4kHz in band Signal

Transmit Levels

The 16-bit transmit code word written by the DSP to the Digital Sigma-Delta Modulator (DSDM) (via TIF) has a linear relationship with the analog output signal. So, decreasing a code word by a factor of 0.5 will result in a 0.5 (-6dB) gain change in the analog output signal.

The following formula describes the relationship between the transmit code word and the output level at the transmit pins (TXAP/TXAN):

$$V_{out} (V) = 2 * \text{code}/32,767 * \text{DSDMgain} * \text{dacGAIN} * V_{ref} * \text{TLPFgain} * \text{SMFLTgain} * \text{FreqFctr}$$

V_{out} is the differential peak voltage at the TXAP and TXAN pins.

$Code$ is the 16-bit, two's complement transmit code word written out by the DSP to the DSDM (via TIF). The code word falls within a range of $\pm 32,767$. For a sinusoidal waveform, the peak code word should be used in the formula to obtain the peak output voltage.

$DSDMgain$ is the scaling factor used on the transmit code word to reduce the possibility of saturating the modulator. This value is set to 0.640625(-3.555821dB) at dc in the 48 tap transmit interpolation filter (TIF) that precedes DSDM.

$dacGAIN$ is the gain of the DAC. The value $dacGAIN$ is calculated based on capacitor values inside DAC1 and $dacGAIN=8/9=0.8889$. The number 32,767 refers to the code word that generates an 82% "1's" pulse density at the output of the DSDM. As one can see from the formula, the D to A conversion is dependent on the level of V_{ref} . Also when DTMFBST bit is set, V_{ref} is increased from 1.36V to 1.586V to allow higher transmit level or 16.6% increase in gain. This bit is intended for enhancing the DTMF transmit level and should not be used in data mode.

TLPFgain is the gain of TLPF and nominally equals to 0.00dB or 1.0.

SMFLTgain is the gain of SMFLT and nominally equal to 1.445 or 3.2dB.

When TXBST0 bit is set, the gain is further increased by 1.65dB (1.21) for the total of 4.85 dB. This is to accommodate greater hybrid insertion loss encountered in some applications.

FreqFctr shows dependency of the entire transmit path on frequency. See Figure 10.

With the transmit code word of +/- 32,767, the nominal differential swing at the transmit pins at dc is:

$$\begin{aligned} V_{out} (V) &= 2 * \text{code}/32,767 * \text{DSDMgain} * \text{dacGAIN} * V_{ref} * \text{TLPFgain} * \text{SMFLTgain} * \text{FreqFctr} \\ &= 2 * 32,767/32,767 * 0.640625 * 0.8889 * 1.36 * 1.0 * 1.4454 * 1.0 = 2.31V_{pk} \text{ diff.} \end{aligned}$$

When DTMFBST bit is set, $V_{out} (V) = 1.166 * 2.31 = 2.693V_{pk} \text{ diff.}$

When TXBST0 bit is set, $V_{out} (V) = 1.21 * 2.31 = 2.795V_{pk} \text{ diff.}^{(1)}$

When both DTMFBST and TXBST0 are set to 1, $V_{out} (V) = 2.795 * 1.166 = 3.259V_{pk} \text{ diff.}$

[1] If not limited by power supply or internal reference.

Transmit Power - dBm

To calculate the analog output power, the peak voltage must be calculated and the peak to rms ratio (crest factor) must be known. The following formula can be used to calculate the output power, in dBm referenced to 600Ω

$$P_{out} \text{ (dBm)} = 10 * \log [(V_{out} \text{ (V)} / cf)^2 / (0.001 * 600)]$$

The following example demonstrates the calculation of the analog output power given a 1.2kHz FSK tone (sine wave) with a peak code word value of 11,878 sent out by the DSP.

The differential output voltage at TXAP-TXAN will be:

With FreqFctr = 1.02, (See Figure 10)

$$V_{out} \text{ (V)} = 2 * (11,878/32,767) * 0.6640625 * 0.8889 * 1.36 * 1.0 * 1.4454 * 1.02 = 0.841V_{pk}$$

The output signal power will be:

$$P_{out} \text{ (dBm)} = 10 * \log [(0.841 / 1.41)^2 / (0.001 * 600)] = - 2.29\text{dBm.}$$

Transmit Type	crest factor	Max line level
V.90	4.0	-12dBm
QAM	2.31	-9dBm
DPSK	1.81	-9dBm
FSK	1.41	-9dBm
DTMF	1.99	-5.7dBm

Table 11: -Peak to RMS ratios for various modulation types

Control Register (CTRL1): Address 00h

Reset State 08h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
ENFE	unused	DTMFBST	TXBST0	TXDIS	RXG1	RXG0	RXGAIN

ENFE 1 = Enable the digital filters and analog front end.
 0 = Disable the analog blocks shut off the clocks to the digital and analog receive/transmit circuits.

DTMFBST 1 = Add a gain of 0.83dB(10%) to the transmitter; also the common mode voltage of the transmit path is increased to 1.375V. This is intended for enhancing DTMF transmit power only and should not be used in data mode.
 0 = No gain is added

TXBST0 1 = A gain of 1.5dB(18.9%) is added to the transmitter
 0 = The gain of the transmitter is nominal

PRODUCT DATA SHEET

- TXDIS 1 = Tri-state the TXAP and TXAN pins, provides a bias of VBG into 80 k Ω for each output pin
- RXG1:0 These bits control the receive gain as indicated in Table 8.
- RXGAIN 1 = Increase the gain of the receiver by 20 dB.

Control Register (CTRL2): Address 01h

Reset State 00h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
TMEN	DIGLB	ANALB	INTLB	CkoutEn	RXPULL	SPOS	HC

- TMEN 1 = Enable test modes.
- DIGLB 1 = Tie the serial bit stream from the digital transmit filter output to the digital receive filter input. DIGITAL LOOPBACK
- ANALB 1 = Tie the analog output of the transmitter to the analog input of the receiver. ANALOG LOOPBACK
- INTLB 1 = Tie the digital serial bit stream from the analog receiver output to the analog transmitter input. INTERNAL LOOPBACK
- CkoutEn 1 = Enable the CLKOUT output; 0 = CLKOUT tri-stated. For test purposes only; do not use in normal operation.
- RXPULL 1 = Pulls DC Bias to RXAP/RXAN pins, thru 100Kohm each, to VREF, to be used in testing Rx path.
0 = No DC Bias to RXAP/RXAN pins
- SPOS 1 = Control frames occur after one quarter of the time between data frames has elapsed.
0 = Control frames occur half way between data frames.
- HC 1 = FSB is under hardware control, bit 0 of data frames on SDIN is bit 0 of the transmit word and control frames happen automatically after every data frame.
0 = FSB is under software control, bit 0 of data frames on SDIN is a control frame request bit and control frames happen only on request.

Revision Register: Address 06h

Reset State 30h

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
Rev3	Rev2	Rev1	Rev0	Unused	reserved	reserved	reserved

Bits 7-4 contain the revision level of the TDK 73M1903 device. The rest of this register is for chip development purposes only and is not intended for customer use. Do not write to shaded locations.

TEST MODES

There are two loop back test modes that affect the configuration of the analog front end. The internal loop back mode connects the serial bit stream generated by the analog receiver to the input of the analog transmitter. This loop back mode is similar to a remote analog loop back mode and can be used to evaluate the operation of the analog circuits. When using this loop back mode, the TXAN/TXAP pins should not be externally coupled to the RXAP/RXAN pins. Set bit 4 (INTLB) in register 1h (CTRL2) to enter this loop back mode.

The second loop back test mode is the external loop back mode, or local analog loop back mode. In this mode, the analog transmitter outputs are fed back into the input of the analog receiver. Set bit 5 (ANALB) in register 1h (CTRL2) to enter this loop back mode. In this mode, TBS must be kept to below a value that corresponds to less than $1.16V/2.31V \times -6dB = 25\%$ of the full scale code of +/- 32768 at TXD in order to ensure that the receiver is not overdriven beyond the maximum of 1.16Vpkpk diff for Rxg=11(0dB) setting. See Table 18 on page 33 for the maximum allowed transmit levels. Check the transmitted data against received data via serial interface. This tests the functionality of essentially all blocks, both digital and analog, of the chip.

There is a third loopback mode that bypasses the analog circuits entirely. Digital loop back forces the transmitter digital serial bit stream (from DSDM) to be routed into the digital receiver's sinc³ filters. Set bit 6 (DIGLB) in register 1h (CTRL2) to enter this loop back mode.

POWER SAVING MODES

The 73M1903 has only one power conservation mode. When the ENFE, bit 7 in register 0h, is zero the clocks to the filters and the analog are turned off. The transmit pins output a nominal 80k Ω impedance. The clock to the serial port is running and the GPIO and other registers can be read or updated.

ELECTRICAL SPECIFICATIONS**ABSOLUTE MAXIMUM RATINGS**

Operation outside these rating limits may cause permanent damage to this device.

PARAMETER	RATING
Supply Voltage	-0.5V to +4.0V
Pin Input Voltage (except OSCIN)	-0.5V to 6.0V
Pin Input Voltage (OSCIN)	-0.5V to VDD + 0.5V

RECOMMENDED OPERATING CONDITIONS

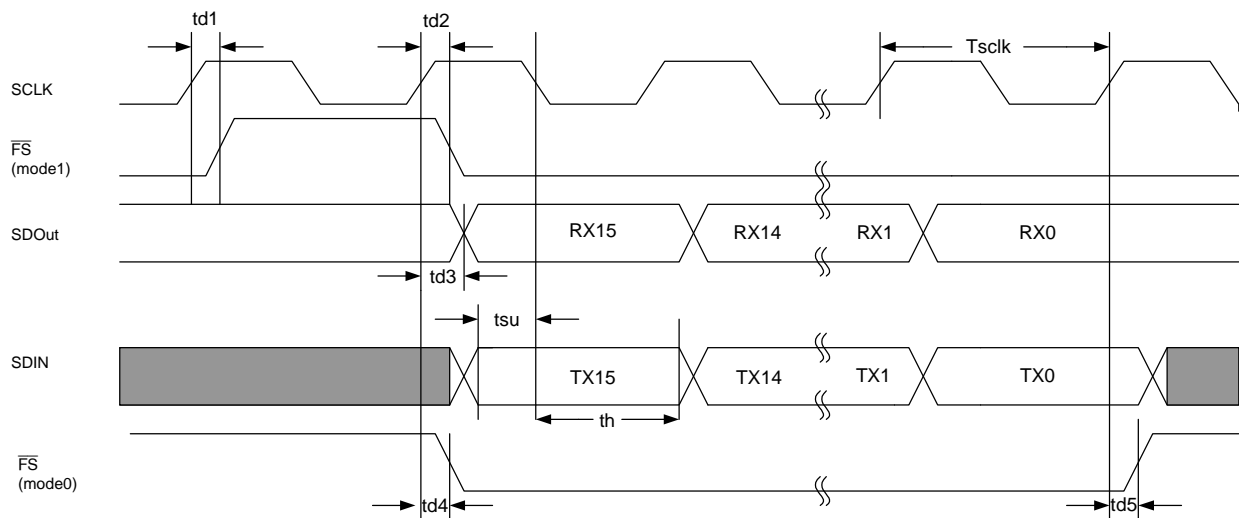
PARAMETER	RATING
Supply Voltage (VDD) with respect to VSS	3.0V to 3.6V
Oscillator Frequency	24.576 MHz \pm 100ppm
Operating Temperature	-40C to +85°C

DIGITAL SPECIFICATIONS
DC CHARACTERISTICS

PARAMETER		Condition	MIN	NOM	MAX	UNIT
Input Low Voltage	VIL		-0.5		0.2 * VDD	V
Input High Voltage (Except OSCIN)	VIH1		0.7 VDD		5.5	V
Input High Voltage OSCIN	VIH2		0.7 VDD		VDD + 0.5	V
Output Low Voltage (Except OSCOUT, \overline{FS} , SCLK, SDOUT)	VOL	IOL = 4mA			0.45	V
Output Low Voltage OSCOUT	VOLOSC	IOL = 3.0mA			0.7	V
Output Low Voltage \overline{FS} ,SCLK,SDOUT	VOL	IOL = 1mA			0.45	V
Output High Voltage (Except OSCOUT, \overline{FS} , SCLK, SDOUT)	VOH	IOH = -4mA	VDD - 0.45			V
Output High Voltage OSCOUT	VOHOSC	IOH = -3.0mA	VDD - 0.9			V
Output High Voltage \overline{FS} ,SCLK,SDOUT	VOH	IOH = -1mA	VDD - 0.45			V
Input Low Leakage Current (Except OSCIN)	IIL1	VSS < Vin < VIL1			1	μ A
Input High Leakage Current (Except OSCIN)	IIH1	VIH1 < Vin < 5.5			1	μ A
Input Leakage Current OSCIN	IIL2	VSS < Vin < VIL2	1		30	μ A
Input High Leakage Current OSCIN	IIH2	VIH2 < Vin < VDD	1		30	μ A
IDD current at 3.0V – 3.6V Nominal at 3.3V						
IDD Total current	IDD	Fs=8hz, Xtal=27Mh		9	12.0	mA
IDD Total current	IDD	Fs=11.2hz, Xtal=27Mh		10.3	13.4	mA
IDD Total current	IDD	Fs=14.4hz, Xtal=27Mh		11.8	14.5	mA
IDD Total current ENFE=0	IDD			2	2.5	mA

AC TIMING

PARAMETER	MIN	NOM	MAX	UNIT
SCLK Period (T _{sclk}) (Fs=8kHz)	-	1/2.048MHz	-	ns
SCLK to FSB Delay (td1) – mode1	-	-	20	ns
SCLK to FSB Delay (td2) – mode1	-	--	20	ns
SCLK to SDOOUT Delay (td3) (With 10pf load)	-	-	20	ns
Setup Time SDIN to SCLK (tsu)	15	-	-	ns
Hold Time SDIN to SCLK (th)	10	-	-	ns
SCLK to FSB Delay (td4) – mode0	-	-	20	ns
SCLK to FSB Delay (td5) – mode0	-	-	20	ns

Table 12: -Serial I/F Timing

Figure 11 -Serial Port Data Timing

ANALOG SPECIFICATIONS
DC SPECIFICATIONS

Vref should be connected to an external bypass capacitor with a minimum value of 0.1uF. This pin is not intended for any other external use.

Parameter	Test Condition	Min	Nom	Max	Units
Vref	VDD= 3.0V - 3.6V.		1.36		V
Vref Noise	300Hz-3.3kHz		-86	-80	dBm ₆₀₀
Vref PSRR	300Hz-30kHz	40*			dB

Table 13: -Reference Voltage Specifications
AC SPECIFICATIONS

The table below shows the maximum transmit levels that the output drivers can deliver before distortion through the DAA starts to become significant. The loss through the DAA transmit path is assumed to be 7 dB. The signals presented at TXAP and TXAN are symmetrical. The transmit levels can be increased by setting either TXBST0 (+1.5dB) or/and DTMFBST (+0.83dB) for the combined total gain of 2.33dB. These can be used where higher-level DTMF tones are required.

MAXIMUM TRANSMIT LEVELS					
Transmit Type	Maximum differential line level (dBm0)	Maximum single-ended level at TXA pins (dBm)	peak to rms ratio	Single-ended rms Voltage at TXA pins (V)	Single-ended Peak Voltage at TXA pins (V)
VPA=2.7V to 3.6V; All rms and peak voltages are relative to Vref					
V.90	-12.0	-11.0	4	0.2175	0.87
QAM	-7.3	-6.3	2.31	0.377	0.87
DPSK	-5.1	-4.1	1.81	0.481	0.87
FSK	-3.0	-2.0	1.41	0.617	0.87
DTMF (high tone)	-7.8	-6.8	1.41	0.354	0.500
DTMF (low tone)	-9.8	-8.8	1.41	0.283	0.400

Table 14: -Maximum Transmit Levels

PERFORMANCE
Receiver

Parameter	Test Conditions	Min	Nom	Max	Units
Input Impedance	Measured at RXAP/N relative to Vref RXPULL=HI		230		k?
	Measured at RXAP/N relative to Vref RXPULL=LO	1.0			M?
Receive Gain Boost	Rxgain = 1; 1kHz; RXAP/N=0.116V _{pk-diff} Gain Measured relative to Rxgain=0				
	Rxgain=1 for Fs=8Khz	17.0	18.5	20.0	dB
	Rxgain=1 for Fs=12Khz	16.2	17.4	18.7	dB
	Rxgain=1 for Fs=14.4Khz	15.7	17.2	18.7	dB
Total Harmonic Distortion (THD)	THD = 2 nd and 3 rd harmonic. Rxgain=1	64	70		
RXG Gain	Gain Measured relative to RXG[1:0]=11 (0dB) @ 1 KHz				
	RXG[1:0]=00	5.8	6	6.2	dB
	RXG[1:0]=01	8.8	9	9.2	dB
	RXG[1:0]=10	11.8	12	12.2	dB
Passband Gain	Input 1.16V _{pk-diff} at RXA. Measure gain at 0.5kHz, and 2KHz. Normalized to 1kHz.				
	Gain at 0.5kHz	-0.29	-0.042	0.21	dB
	Gain at 1kHz (Normalized)		0.000		dB
	Gain at 2.0kHz	-0.067	0.183	0.43	dB
Input offset	Short RXAP to RXAN. Measure input voltage relative to Vref	-30	0	30	mV
Sigma-Delta ADC Modulation gain	Normalized to VBG=1.25V. Includes the effect of AAF(-0.4dB) with Bit1,0 of CTRL2=0,0.		41		μV/bit
Maximum Analog Signal Level at RXAP/RXAN	Peak voltage measured differentially across RXAP/RXAN.			1.16	V _{pk-diff}
Total Harmonic Distortion (THD)	1kHz 1.16V _{pk-diff} at RXA with Rxg=11 THD = 2 nd and 3 rd harmonic.	80	85		dB
Noise	Transmit V.22bis low band; FFT run on ADC samples. Noise in 0 to 4kHz band		-85	-80	dBm
Crosstalk	0dBm 1000Hz sine wave at TXAP; FFT on Rx ADC samples, 1 st four harmonics Reflected back to receiver inputs.		-100		dB

Note: RXG[1:0] and RXGAIN are assumed to have settings of '0' unless they are specified otherwise.

Table 15: -Receiver Performance Specifications

Transmitter

Parameter	Test Condition	Min	Nom	Max	Units
DAC gain (Transmit Path Gain)	Code word of $\pm 32,767$ @1kHz; TXBST0=0; DTMFBST=0		70		$\mu\text{V/bit}$
DC offset –Differential Mode	Across TXAP and TXAN for DAC input = 0	-100		100	mV
DC offset -Common Mode	Average of TXAP and TXAN for DAC input = 0; relative to VREF	-80		80	mV
TXBST0 Gain	Code word of $\pm 32,767$ @1kHz; relative to TXBST0=0; TXBST1=0		1.65		dB
DTMFBST Gain	Code word of $\pm 32,767$ @1kHz; relative to TXBST0=0; TXBST1=0		1.335		dB
Total Harmonic Distortion (THD)	Code word of $\pm 32,767$ @1kHz; relative to TXBST0=0;TXBST1=0 THD = 2 nd and 3 rd harmonic.	-75	-85		dB
1200 Ω Resistor across TNAN/TXAP	Code word of $\pm (32,767 \cdot 0.8)$ @1kHz; relative to TXBST0=0;TXBST1=0 THD = 2 nd and 3 rd harmonic.	-80	-85		dB
	Code word of $\pm (32,767 \cdot 0.9)$ @1kHz; relative to TXBST0=1;TXBST1=1 THD = 2 nd and 3 rd harmonic.	-60	-70		dB
	Code word of $\pm 32,767$ @1kHz; relative to TXBST0=1;DTMFBST=1 THD = 2 nd and 3 rd harmonic		-70		
Intermod Distortion	At output (TXAP-TXAN): DTMF 1.0kHz, 1.2kHz sine waves, summed 2.0V _{pk} (-2dBm tone summed with 0dBm tone) Refer to TBR 21 specifications for description of complete requirements.		70		dB below low tone
Idle Channel Noise	200Hz - 4.0kHz		110		μV
PSRR	-30 dBm signal at VPA 300Hz – 30kHz			40	dB
Passband Ripple	300Hz - 3.2kHz	-0.125		0.125	dB
Transmit Gain Flatness	Code word of $\pm 32,767$ @1kHz. Measure gain at 0.5kHz, and 2KHz relative to 1kHz.				
	Gain at 0.5kHz		0.17		dB
	Gain at 1kHz (Normalized)		0		dB
	Gain at 2.0kHz		0.193		dB
	Gain at 3.3kHz		-0.12		dB

Table 16: -Transmitter Performance Specifications

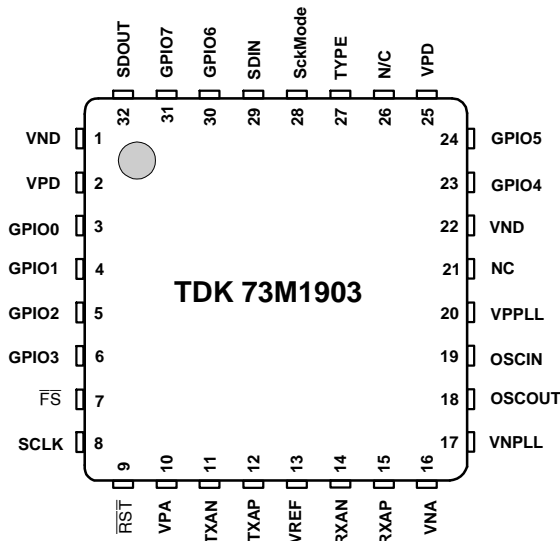
PRODUCT DATA SHEET

Parameter	Test Condition	Min	Nom	Max	Units
Txap/n output impedance differentially (TXDIS=1)	TXDIS =1. Measure impedance differentially between TXAP and TXAN.		160		k?
Txap/n common output offset (TXDIS=1)	TXDIS=1 Short Txap and Txan. Measure the voltage respect to Vbg	-20	0	20	mV
Note: TXBST0 and DTMFBS are assumed have setting 0's unless they are specified otherwise.					

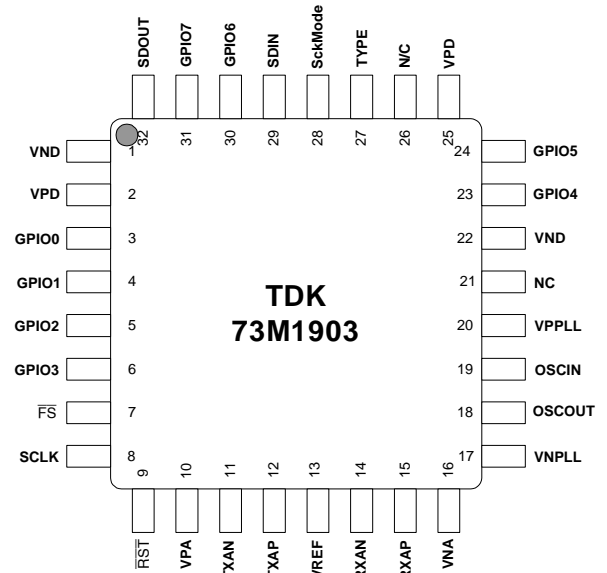
Table 17: -Transmitter Performance Specifications (continued)

PACKAGE OPTIONS

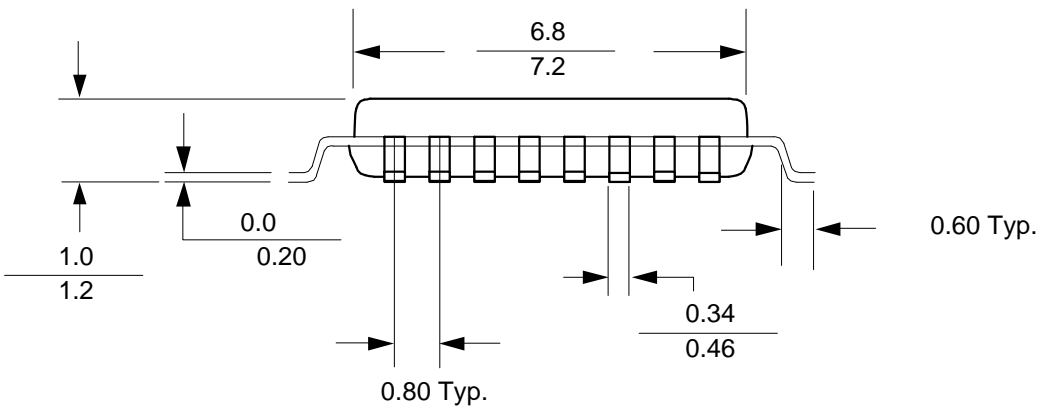
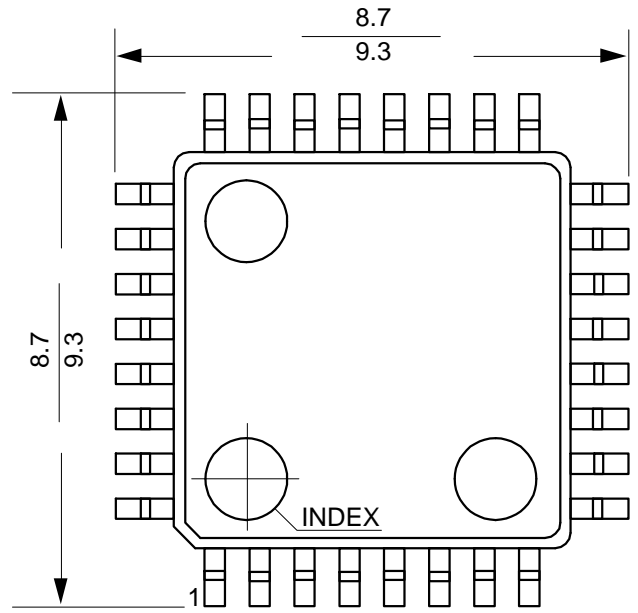
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73M1903 MLF 32



73M1903 TQFP 32

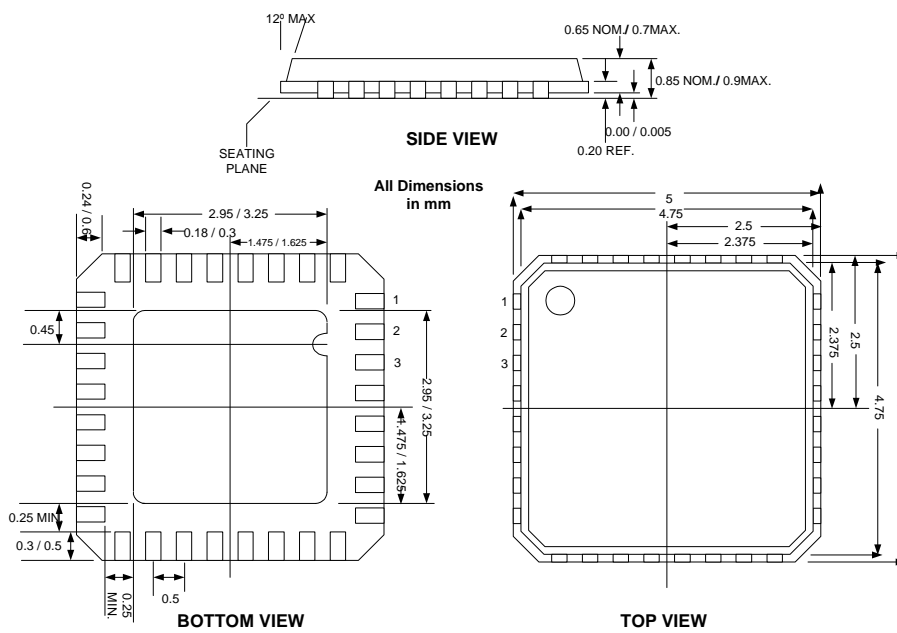


MECHANICAL DRAWINGS

32 lead TQFP

Controlling dimensions in mm

MECHANICAL DRAWINGS cont.

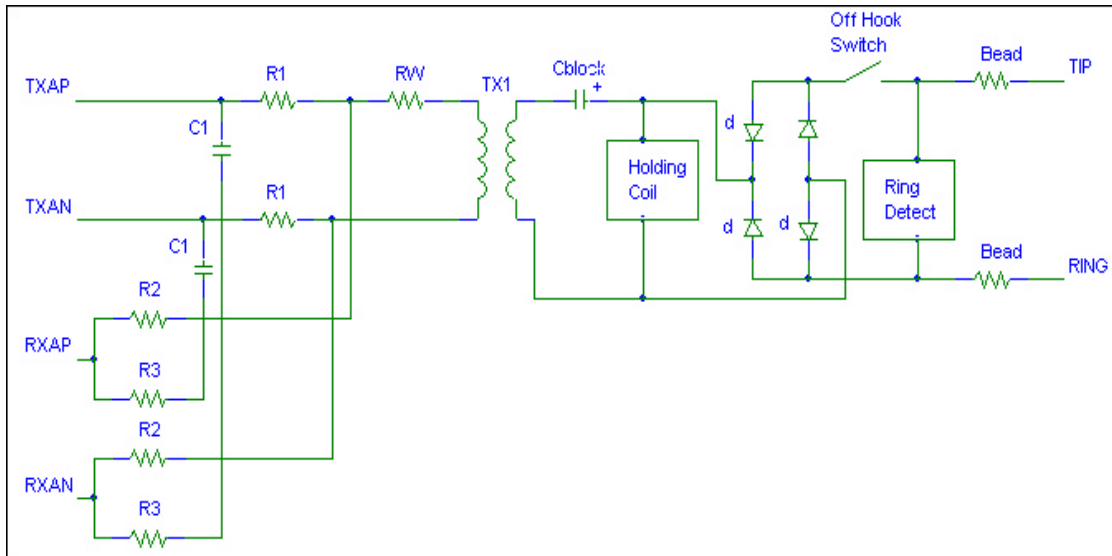


32 lead MLF

Controlling dimensions in mm

APPENDIX A

73M1903 DAA Resistor Calculation Guide



The following procedure can be used to approximate the component values for the DAA. The optimal values will be somewhat different due to the effects of the reactive components in the DAA (this is a DC approximation). Simulations with the reactive components accurately modeled will yield optimal values. The procedures for calculating the component values in the DAA are as follows. First set up R1. The DAA should be designed to reflect 600 Ω when looking in at TIP/RING. If the transformer is 1 to 1, the holding coil and ring detect circuit are high impedance, Cblock is a high value so in the frequency band of interest it is negligible, the sum of R2 and R3 is much greater than R1, and the output impedance of the drivers driving TXAP/TXAN are low then:

$$R_{in} = 2 \cdot R1 + RW + R_{ohswitch} + 2 \cdot R_{bead}$$

RW is the sum of the winding resistance of both sides of the transformer. Measure each side of the transformer with an Ohmmeter and sum them.

Rohswitch is the on resistance of the Off Hook Switch. Mechanical Relay switches can be ignored, but Solid State Relays sometimes have an appreciable on resistance.

Rbead is the DC resistance of whatever series RF blocking devices may be in the design.

For Rin equal to 600 Ω :

$$R1 = \frac{600 - RW - R_{ohswitch} - 2 \cdot R_{bead}}{2}$$

To maximize THL (Trans-Hybrid Loss), or to minimize the amount of transmit signal that shows up back on the Receive pins. The RXAP/RXAN pins get their DC bias from the TXAP/TXAN pins. By capacitively coupling the R3 resistors with the C1 caps, the DC offset can be minimized from the TXAP/TXAN to the

RXAP/RXAN because the DC offset will be divided by the ratio of the R1 resistors to the winding resistance on the one side of the transformer.

Next make the sum of R2 + R3 much higher than 600 Ω. Make sure they are lower than the input impedance of the RXAP/RXAN pins; otherwise they can move the frequency response of the input filter. So let R2 + R3 = 100K.

$$R3 = \frac{100\text{ K}}{1 + \frac{R_{wtot} + 600}{1200}}$$

where

$$R_{wtot} = R_W + R_{ohswitch} + 2 \cdot R_{bead}$$

$$R2 = 100\text{ K} - R3$$

Use 1% resistors for R1, R2, and R3

To select the value for C1, make the zero at around 10Hz.

$$\frac{1}{2 \cdot \pi \cdot 100\text{ K} \cdot C1} = 10$$

$$C1 = \frac{1}{2 \cdot \pi \cdot 100\text{ K} \cdot 10}$$

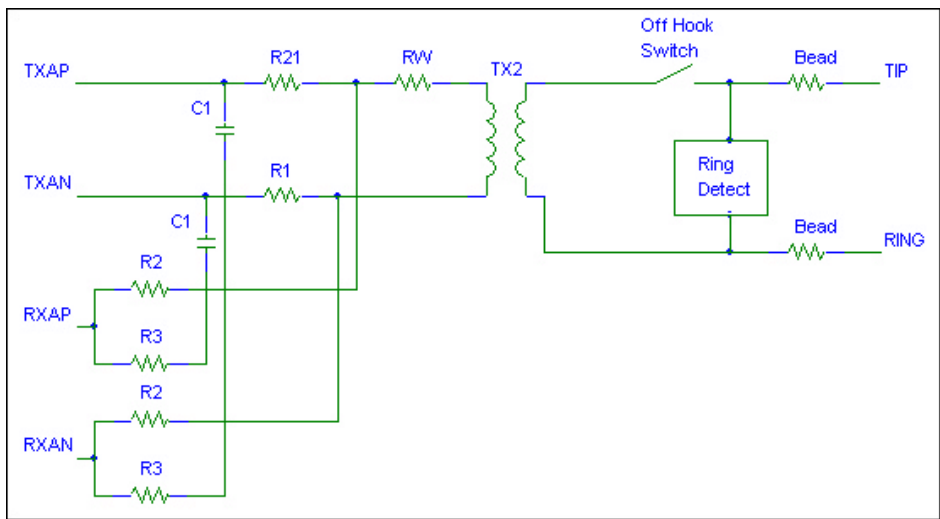
$$C1 = 0.15\text{ }\mu\text{F}$$

The blocking cap Cblock should also have the same frequency response, but due to the low impedance, its value will be much higher, usually requiring a polarized cap. A blocking cap may also be needed on the modem side of the transformer if the DC offset current of the transmit pins will exceed the current rating of the transformer.

$$C_{block} = \frac{1}{2 \cdot \pi \cdot 600 \cdot 10}$$

$$C_{block} = 27\text{ }\mu\text{F}$$

If you are using a Wet transformer design, as in the following figure:



The only difference is that the blocking capacitor, Cblock, it is removed. All other equations still hold true.

Trans-Hybrid Loss (THL)

Trans-Hybrid Loss is by definition the loss of transmit signal from Tip/Ring to the receive inputs on the modem IC. This definition is only valid when driving a specific phone line impedance. In reality, phone line impedances are never perfect, so this definition isn't of much help. Instead, as an alternate definition that helps in analysis for this modem design, THL is the loss from the transmit pins to the receive pins. In this definition the worst-case THL from the transmit pins to the Receive pins is 10.8dB. An insertion loss of 7dB is assumed accounting for losses due to switch, bridge and transformer.

APPENDIX B

Crystal Oscillator

The crystal oscillator is designed to operate over wide choice of crystals (from 9MHz to 27MHz). The crystal oscillator output is input to an NCO based pre-scaler (divider) prior to being passed onto an on-chip PLL. The intent of the pre-scaler is to convert the crystal oscillator frequency, F_{xtal} , to a convenient frequency to be used as a reference frequency, F_{ref} , for the PLL. A set of three numbers— P_{dvsr} (5 bit), $Prst$ (3 bit) and P_{seq} (8 bit) must be entered thru the serial port as follows:

$P_{dvsr} = \text{Integer} [F_{ref}/F_{xtal}]$;

$Prst = \text{Denominator of the ratio } (F_{ref}/F_{xtal}) \text{ minus 1 when it is expressed as a ratio of two smallest integers} = N_{nco1}/D_{nco1}$;

$P_{seq} = \text{Divide Sequence}$

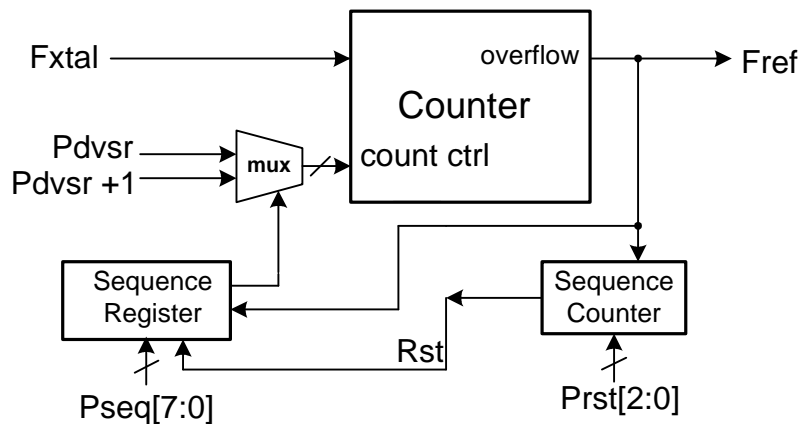


Figure B-1 NCO block diagram

Please note that in all cases, pre-scaler should be designed such that pre-scaler output frequency, F_{ref} , is in the range of 2 ~ 4MHz.

In the first example below, the exact divide ratio required is $F_{xtal}/F_{ref} = 15.625 = 125/8$. If a divide sequence of $\{\div 16, \div 16, \div 15, \div 16, \div 16, \div 15, \div 16, \div 15\}$ is repeated, the effective divide ratio would be exactly 15.625. Consequently, P_{dvsr} of 15, the length of the repeating pattern, $Prst = 8 - 1 = 7$, and the pattern, $\{1, 1, 0, 1, 1, 0, 1, 0\}$, where 0 means P_{dvsr} , or $\div 15$, and 1 means $P_{dvsr} + 1$, or $\div 16$ must be entered as below.

Example 1: $F_{xtal} = 27\text{MHz}$, $F_{ref} = 1.728\text{MHz}$.

$P_{dvsr} = \text{Integer} [F_{xtal}/F_{ref}] = 15 = 0Fh$

$Prst[2:0] = 8 - 1 = 7$ from $F_{xtal}/F_{ref} = 15.625 = 125/8$;

$P_{seq} = \div 16, \div 16, \div 15, \div 16, \div 16, \div 15, \div 16, \div 15 \Rightarrow \{1, 1, 0, 1, 1, 0, 1, 0\} = DAh$.

In the second example, $F_{xtal}/F_{ref} = 4.0$. This is a constant divide by 4. Thus P_{dvsr} is 4, $Prst = 1 - 1 = 0$ and $P_{seq} = \{x, x, x, x, x, x, x, x\}$.

Example 2: $F_{xtal} = 18.432\text{MHz}$, $F_{ref} = 2.304\text{MHz}$.
 $Pdvsr = \text{Integer} [F_{xtal}/F_{ref}] = 8 = 8h$;
 $Prst[2:0] = 1-1 = 0$ from $F_{ref}/F_{xtal} = 18.432/2.304 = 8/1$;
 $Pseq = \{x,x,x,x,x,x,x,x\} = xxh$

Example 3: $F_{xtal} = 24.576\text{MHz}$, $F_{ref} = 2.4576\text{MHz}$.
 $Pdvsr = \text{Integer} [F_{xtal}/F_{ref}] = 10 = Ah$;
 $Prst[2:0] = 1-1 = 0$ from $F_{ref}/F_{xtal} = 24.576/2.4576 = 10/1$;
 $Pseq = \{x,x,x,x,x,x,x,x\} = xxh$

It is also important to note that when F_{xtal}/F_{ref} is an integer the output of the pre-scaler is a straight frequency divider (example 2). As such there will be no jitter generated at F_{ref} . However if F_{xtal}/F_{ref} is a fractional number, F_{ref} , at the output of the pre-scaler NCO would be exact only in an average sense (example 1) and there will be a certain amount of fixed pattern (repeating) jitter associated with F_{ref} which can be filtered out by the PLL that follows by appropriately programming the PLL. It is important to note, however, that the fixed pattern jitter does not degrade the performance of the sigma delta modulators so long as its frequency is $\gg 4\text{kHz}$.

PLL

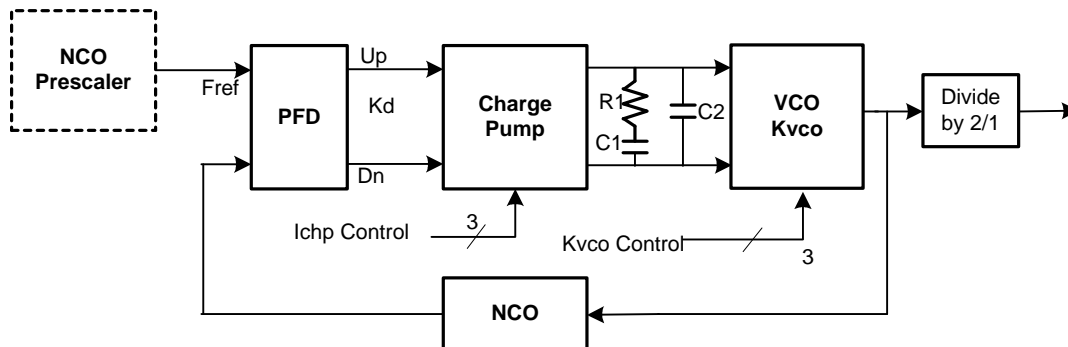


Figure B-2 PLL Block Diagram

1903B has a built in PLL circuit to allow an operation over wide range of F_s . It is of a conventional design with the exception of an NCO based feedback divider. (See Figure B-2: PLL Block Diagram).

The architecture of the 1903B dictates that the PLL output frequency, F_{vco} , be related to the sampling rate, F_s , by $F_{vco} = 2 \times 2304 \times F_s$. The NCO must function as a divider whose divide ratio equals F_{ref}/F_{vco} .

Just as in the NCO pre-scaler, a set of three numbers— $Ndvsr$ (7 bits), $Nrst$ (3 bits) and $Nseq$ (8 bits) must be entered thru a serial port to effect this divide:

$Ndvsr = \text{Integer} [F_{ref}/F_{xtal}]$;
 $Nrst = \text{Denominator of the ratio } (F_{vco}/F_{ref}), D_{nco1}, \text{ minus } 1, \text{ when it is expressed as a ratio of two smallest integers} = N_{nco1}/D_{nco1}$;
 $Nseq = \text{Divide Sequence}$

Example 1: $F_s = 7.2\text{kHz}$ or $F_{vco} = 2 \times 2304 \times 7.2\text{kHz} = 33.1776\text{MHz}$, $F_{ref} = 1.728\text{MHz}$.
 $Ndvsr = \text{Integer} [F_{vco}/F_{ref}] = 19$
 $Nrst = 5 - 1 = 4$ from $F_{vco}/F_{ref} = 19.2 = 96/5$;
 $Nseq = +19, +19, +19, +19, +20 \Rightarrow \{0,0,0,0,1\} = xxx00001 = 01h$.

Example 2: $F_s = 8.0\text{kHz}$ or $F_{vco} = 2 \times 2304 \times 8\text{kHz} = 36.864\text{MHz}$, $F_{ref} = 2.304\text{MHz}$.
 $N_{dvsr} = \text{Integer } [F_{vco}/F_{ref}] = 16 = 10h$;
 $N_{rst} = 1-1 = 0$ from $F_{vco}/F_{ref} = 16/1$;
 $N_{seq} = \{x,x,x,x,x,x,x,x\} = xxh$.

Example 3: $F_s = 9.6\text{kHz}$ or $F_{vco} = 2 \times 2304 \times 9.6\text{kHz} = 44.2368\text{MHz}$, $F_{ref} = 2.4576\text{MHz}$.
 $N_{dvsr} = \text{Integer } [F_{vco}/F_{ref}] = 18 = 16h$;
 $N_{rst} = 1-1 = 0$ from $F_{vco}/F_{ref} = 18/1$;
 $N_{seq} = \{x,x,x,x,x,x,x,x\} = xxh$.

It is important to note that in general the NCO based feedback divider will generate a fixed jitter pattern whose frequency components are at $F_{ref}/\text{Accreset2}$ and its integer multiples. The overall jitter frequency will be a nonlinear combination of jitters from both pre-scaler and PLL NCO. The fundamental frequency component of this jitter is at $F_{ref}/Prst/Nrst$. The PLL parameters should be selected to remove this jitter.

Three separate controls are provided to fine tune the PLL as shown in the following sections.

To ensure quick settling of PLL, a feature was designed into the 73M1903 where $lchp$ is kept at a higher value until $Lokdet$ becomes active or $Frcvco$ bit is set to 1, whichever occurs first. Thus PLL is guaranteed to have the settling time of less than one Frame Synch period after a new set of NCO parameters had been written to the appropriate registers. The serial port register writes for a particular sample rate should be done in sequence starting from register 08h ending in register 0Dh. 0Dh register should be the last one to be written to. This will be followed by a write to the next register in sequence (0Eh) to force the transition of $Sysclk$ from $Xtal$ to $Pllclk$. Upon the system reset, the system clock is reset to $Fxtal/9$. The system clock will remain at $Fxtal/9$ until the Host forces the transition, but no sooner the second Frame Synch period after the write to 0Dh. When this happens, the system clock will transition to $Pllclk$ without any glitches thru a specially designed deglitch MUX.

Examples of NCO settings

Example 1:

Crystal Frequency = 24.576MHz; Desired Sampling Rate, $F_s = 13.714\text{kHz}(=2.4\text{kHz} \times 10/7 \times 4)$

Step 1. First compute the required VCO frequency, F_{vco} , corresponding to
 $F_s = 2.4\text{kHz} \times 10/7 \times 4 = 13.714\text{kHz}$, or
 $F_{vco} = 2 \times 2304 \times F_s = 2 \times 2304 \times 2.4\text{kHz} \times 10/7 \times 4 = 63.19543\text{MHz}$.

Step 2. Express the required VCO frequency divided by the Crystal Frequency as a ratio of two integers. This is initially given by :

$$F_{vco}/F_{xtal} = \frac{2 \cdot 2304 \cdot 2.4\text{kHz} \cdot 10/7 \cdot 4}{24.576\text{MHz}}$$

After a few rounds of simplification this ratio reduces to:

$$\begin{aligned}
 F_{vco} / F_{xtal} &= \frac{18}{7} = \left(\frac{1}{7} \right) \cdot \left(\frac{18}{1} \right) \\
 &= \frac{\frac{N_{nco1}}{D_{nco1}}}{\frac{N_{nco2}}{D_{nco2}}} = \frac{\frac{1}{7}}{\frac{1}{18}}
 \end{aligned}$$

, where Nnco1 and Nnco2 must be < or equal to 8.

The ratio, Nnco1/Dnco1 = 1/7, is used to form a divide ratio for the NCO in prescaler and Nnco2/Dnco2 = 1/18 for the NCO in the PLL.

Prescaler NCO: From Nnco1/Dnco1 = 1/7,

Pdvsr = Integer [Dnco1/Nnco1] = 7;

Prst[2:0] = Nnco1 – 1 = 0; this means NO fractional divide. It always does ÷7. Thus Pseq becomes “don’t care” and is ignored.

Pseq = {x,x,x,x,x,x,x,x} = xxh.

PLL NCO: From Nnco2/Dnco2 = 1/18,

Ndvsr = Integer [Dnco2/Nnco2] = 18;

Nrst[2:0] = Nnco2 – 1 = 0; this means NO fractional divide. It always does ÷18. Thus Pseq becomes “don’t care” and is ignored.

Nseq = {x,x,x,x,x,x,x,x} = xxh.

Example 2:

Crystal Frequency = 24.576MHz; Desired Sampling Rate, Fs = 10.971kHz=2.4kHz x 8/7 x 4

Step 1. First compute the required VCO frequency, Fvco, corresponding to

Fs = 2.4kHz x 8/7 x 4 = 10.971kHz.

Fvco = 2 x 2304 x Fs = 2 x 2304 x 2.4kHz x 8/7 x 4 = 50.55634MHz.

Step 2. Express the required VCO frequency divided by the Crystal Frequency as a ratio of two integers.

This is initially given by :

$$F_{vco} / F_{xtal} = \frac{2 \cdot 2304 \cdot 2.4\text{kHz} \cdot 8/7 \cdot 4}{24.576\text{MHz}}$$

After a few rounds of simplification this ratio reduces to:

$$\begin{aligned}
 F_{vco} / F_{xtal} &= \left(\frac{4}{35} \right) \cdot \left(\frac{18}{1} \right) \\
 &= \frac{\frac{N_{nco1}}{D_{nco1}}}{\frac{N_{nco2}}{D_{nco2}}} = \frac{\frac{4}{35}}{\frac{1}{18}}
 \end{aligned}$$

, where Nnco1 and Nnco2 must be < or equal to 8.

The ratio, Nnco1/Dnco1 = 4/35, is used to form a divide ratio for the NCO in pre-scaler and Nnco2/Dnco2 = 1/18 for the NCO in the PLL.

Pre-scaler NCO: From $Nnco1/Dnco1 = 4/35$,
 $Pdvsr = \text{Integer} [Dnco1/Nnco1] = 8$;
 $Prst[2:0] = Nnco1 - 1 = 3$;
 $Dnco1/Nnco1 = 35/4 = 8.75$ suggests a divide sequence of $\{\div 9, \div 9, \div 9, \div 8\}$, or
 $Pseq = \{x, x, x, x, 1, 1, 1, 0\} = xDh$.

PLL NCO: From $Nnco2/Dnco2 = 1/18$,
 $Ndvsr = \text{Integer} [Dnco2/Nnco2] = 18$;
 $Nrst[2:0] = Nnco2 - 1 = 0$; this means NO fractional divide. It always does $\div 18$. Thus $Pseq$ becomes
 "don't care".
 $Nseq = \{x, x, x, x, x, x, x, x\} = xxh$.

Example3:

Crystal Frequency = 27MHz; Desired Sampling Rate, $F_s = 7.2\text{kHz}$

Step 1. First compute the required VCO frequency, F_{vco} , corresponding to
 $F_s = 2.4\text{kHz} \times 3 = 7.2\text{kHz}$.
 $F_{vco} = 2 \times 2304 \times F_s = 2 \times 2304 \times 2.4\text{kHz} \times 3 = 33.1776\text{MHz}$.

Step 2. Express the required VCO frequency divided by the Crystal Frequency as a ratio of two integers.
 This is initially given by :

$$F_{vco} / F_{xtal} = \frac{2 \cdot 2304 \cdot 2.4\text{kHz} \cdot 3}{27\text{MHz}}$$

After a few rounds of simplification this reduces to:

$$F_{vco} / F_{xtal} = \left(\frac{8}{125} \right) \cdot \left(\frac{96}{5} \right)$$

$$= \frac{\frac{Nnco1}{Dnco1}}{\frac{Nnco2}{Dnco2}} = \frac{\frac{8}{125}}{\frac{5}{96}}$$

The two ratios are not unique and many other possibilities exist. But for this particular application, they are found to be the best set of choices within the constraints of $Prst$ and $Nrst$ allowed. ($Nnco1$, $Nnco2$ must be less than or equal to 8.)

The ratio, $Nnco1/Dnco1 = 8/125$, is used to form a divide ratio for the NCO in prescaler and $Nnco2/Dnco2 = 5/96$ for the NCO in the PLL.

Pre-scaler NCO: From $Nnco1/Dnco1 = 8/125$,
 $Pdvsr = \text{Integer} [Dnco1/Nnco1] = 15$;
 $Prst[2:0] = Nnco1 - 1 = 7$;
 $Dnco1/Nnco1 = 125/8 = 15.625$ suggests a divide sequence of $\{\div 16, \div 16, \div 15, \div 16, \div 16, \div 15, \div 16, \div 15\}$, or
 $Pseq = \{1, 1, 0, 1, 1, 0, 1, 0\} = DAh$.
 PLL NCO: From $Nnco2/Dnco2 = 5/96$,
 $Ndvsr = \text{Integer} [Dnco2/Nnco2] = 19$;
 $Nrst[2:0] = Nnco2 - 1 = 4$;
 $Dnco2/Nnco2 = 19.2$ suggests a divide sequence of $\{\div 19, \div 19, \div 19, \div 19, \div 20\}$, or
 $Nseq = \{x, x, x, 0, 0, 0, 0, 1\} = x1h$.

ORDERING INFORMATION

PART DESCRIPTION	ORDER NUMBER
73M1903 32-Lead MLF Lead Free	73M1903-IM/F
73M1903 32-Lead MLF Standard	73M1903-IM
73M1903 32-Lead Thin Quad Flat Pack Lead Free	73M1903-IGV/F
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