# 74AVC16334A

# 16-bit registered driver with inverted register enable and Dynamic Controlled Outputs; 3-state

Rev. 3 — 12 September 2018

**Product data sheet** 

## 1. General description

The 74AVC16334A is a 16-bit universal bus driver. Data flow is controlled by output enable  $(\overline{OE})$ , latch enable  $(\overline{LE})$  and clock inputs (CP).

This product is designed to have an extremely fast propagation delay and a minimum amount of power consumption.

To ensure the high-impedance state during power up or power down,  $\overline{\text{OE}}$  should be tied to  $V_{CC}$  through a pullup resistor (Live Insertion).

A Dynamic Controlled Output (DCO) circuitry is implemented to support termination line drive during transient. See <u>Section 9.1</u> for typical curves.

## 2. Features and benefits

- Wide supply voltage range from 1.2 V to 3.6 V
- · Complies with JEDEC standards:
  - JESD8-7 (1.2 V to 1.95 V)
  - JESD8-5 (1.8 V to 2.7 V)
  - JESD8-1A (2.7 V to 3.6 V)
- CMOS low power consumption
- Input/output tolerant up to 3.6 V
- Dynamic Controlled Output (DCO) circuit dynamically changes output impedance, resulting in noise reduction without speed degradation
- · Low inductance multiple V<sub>CC</sub> and GND pins to minimize noise and ground bounce
- Power off disables 74AVC16334A outputs, permitting Live Insertion
- Integrated input diodes to minimize input overshoot and undershoot

# 3. Ordering information

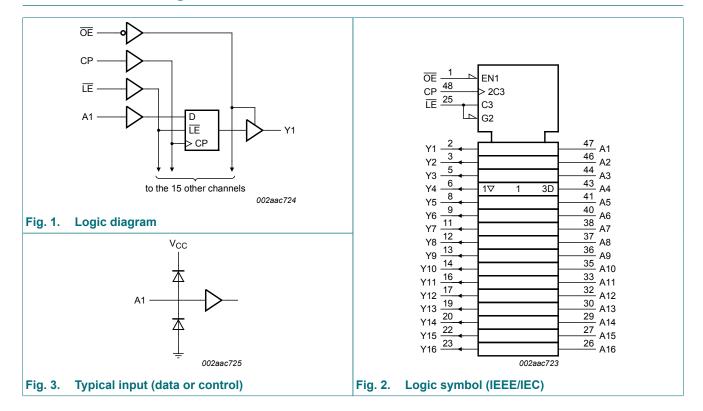
#### **Table 1. Ordering information**

Type number	Package					
	Temperature range	Name	Description	Version		
74AVC16334ADGG	-40 °C to +85 °C		plastic thin shrink small outline package; 48 leads; body width 6.1 mm	SOT362-1		



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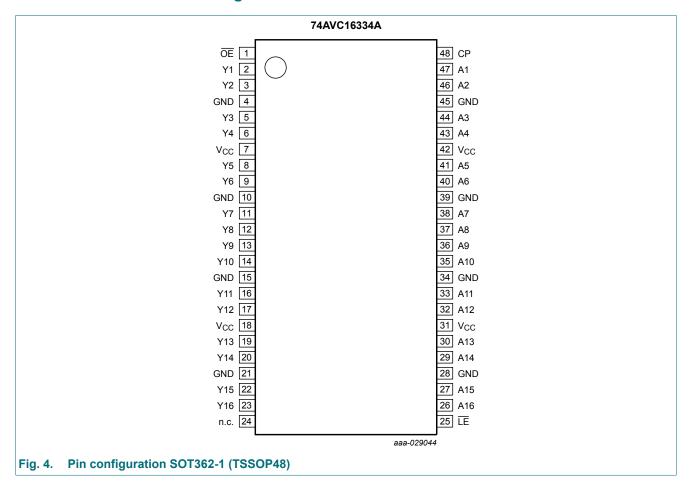
# 4. Functional diagram



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## 5. Pinning information

## 5.1. Pinning



## 5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
ŌE	1	output enable input (active LOW)
Y1, Y2, Y3, Y4, Y5, Y6, Y7, Y8, Y9, Y10, Y11, Y12, Y13, Y14, Y15, Y16	2, 3, 5, 6, 8, 9, 11, 12, 13, 14, 16, 17, 19, 20, 22, 23	data output
GND	4, 10, 15, 21, 28, 34, 39, 45	ground supply (0 V)
V <sub>CC</sub>	7, 18, 31, 42	supply voltage
n.c.	24	not connected
LE	25	latch enable input (active LOW)
A1, A2, A3, A4, A5, A6, A7, A8, A9, A10, A11, A12, A13, A14, A15, A16	47, 46, 44, 43, 41, 40, 38, 37, 36, 35, 33, 32, 30, 29, 27, 26	data input
СР	48	clock input

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# 6. Functional description

Table 3. Function selection [1]

Inputs					
ŌĒ	LE	СР	An	Yn	
Н	Х	Х	Х	Z	
L	L	Х	L	L	
L	L	Х	Н	Н	
L	Н	<b>↑</b>	L	L	
L	Н	<b>↑</b>	Н	Н	
L	Н	H or L	Х	Y <sub>0</sub> [2]	

<sup>[1]</sup> H = HIGH voltage level; L = LOW voltage level; X = Don't care; Z = high-impedance OFF-state; ↑ = LOW to HIGH level transition.

# 7. Limiting values

#### **Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC</sub>	supply voltage		-0.5	+4.6	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < 0 V	-50	-	mA
VI	input voltage	data inputs [1]	-0.5	+4.6	V
I <sub>OK</sub>	output clamping current	$V_O > V_{CC}$ or $V_O < 0$ V	-	±50	mA
Vo	output voltage	output HIGH or LOW [1]	-0.5	V <sub>CC</sub> + 0.5	V
		output 3-state [1]	-0.5	+4.6	V
Io	output current	V <sub>O</sub> = 0 V to V <sub>CC</sub>	-	±50	mA
I <sub>CC</sub>	supply current		-	100	mA
I <sub>GND</sub>	ground current		-100	-	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C to } +85  ^{\circ}\text{C}$ [2]	-	600	mW

<sup>[1]</sup> The input and output voltage ratings may be exceeded if the input and output current ratings are observed.

<sup>[2]</sup> Y<sub>0</sub> = Output level before the indicated steady-state input conditions were established.

<sup>[2]</sup> Above 55 °C the value of Ptot derates linearly with 8 mW/K.

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# 8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>CC</sub>	supply voltage	for low-voltage applications	1.2	-	3.6	V
		according to JEDEC Low Voltage	1.65	-	1.95	V
		Standards	2.3	-	2.7	V
			3.0	-	3.6	V
VI	input voltage		0	-	3.6	V
Vo	output voltage	output HIGH or LOW	0	-	V <sub>CC</sub>	V
		output 3-state	0	-	3.6	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	V <sub>CC</sub> = 1.65 V to 2.3 V	0	-	30	ns/V
		V <sub>CC</sub> = 2.3 V to 3.0 V	0	-	20	ns/V
		V <sub>CC</sub> = 3.0 V to 3.6 V	0	-	10	ns/V

# 9. Static characteristics

#### **Table 6. Static characteristics**

At recommended operating conditions;  $T_{amb}$  = -40 °C to +85 °C; Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ[1]	Max	Unit
V <sub>IH</sub>	HIGH-level input	V <sub>CC</sub> = 1.2 V	V <sub>CC</sub>	-	-	V
	voltage	V <sub>CC</sub> = 1.65 V to 1.95 V	0.65 × V <sub>CC</sub>	0.9	-	V
		V <sub>CC</sub> = 2.3 V to 2.7 V	1.7	1.2	-	V
		V <sub>CC</sub> = 3.0 V to 3.6 V	2.0	1.5	-	V
V <sub>IL</sub>	LOW-level input	V <sub>CC</sub> = 1.2 V	-	-	GND	V
	voltage	V <sub>CC</sub> = 1.65 V to 1.95 V	-	0.9	0.35 × V <sub>CC</sub>	V
		V <sub>CC</sub> = 2.3 V to 2.7 V	-	1.2	0.7	V
		V <sub>CC</sub> = 3.0 V to 3.6 V	-	1.5	0.8	V
V <sub>OH</sub>	HIGH-level output	$V_I = V_{IH}$ or $V_{IL}$				
	voltage	$I_{O}$ = -100 $\mu$ A; $V_{CC}$ = 1.65 V to 3.6 V	V <sub>CC</sub> - 0.20	V <sub>CC</sub>	-	V
		I <sub>O</sub> = -4 mA; V <sub>CC</sub> = 1.65 V	V <sub>CC</sub> - 0.45	V <sub>CC</sub> - 0.10	-	V
		$I_{O}$ = -8 mA; $V_{CC}$ = 2.3 V	V <sub>CC</sub> - 0.55	V <sub>CC</sub> - 0.28	-	V
		$I_{O}$ = -12 mA; $V_{CC}$ = 3.0 V	V <sub>CC</sub> - 0.70	V <sub>CC</sub> - 0.32	-	V
V <sub>OL</sub>	LOW-level output	$V_I = V_{IH}$ or $V_{IL}$				
	voltage	$I_{O}$ = 100 $\mu$ A; $V_{CC}$ = 1.65 V to 3.6 V	-	GND	0.20	V
		I <sub>O</sub> = 4 mA; V <sub>CC</sub> = 1.65 V	-	0.10	0.45	V
		I <sub>O</sub> = 8 mA; V <sub>CC</sub> = 2.3 V	-	0.26	0.55	V
		I <sub>O</sub> = 12 mA; V <sub>CC</sub> = 3.0 V	-	0.36	0.70	V

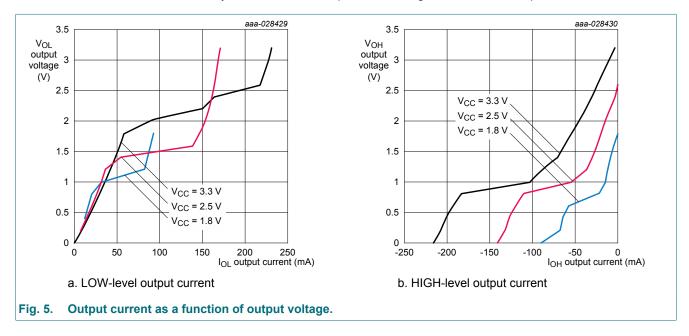
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Symbol	Parameter	Conditions	Min	Typ[1]	Max	Unit
I <sub>I</sub>	input leakage current	$V_I = V_{CC}$ or GND; $V_{CC}$ 3.6 V	-	0.1	2.5	μA
I <sub>OFF</sub>	power-off leakage current	$V_{I}$ or $V_{O} = 3.6 \text{ V}$ ; $V_{CC} = 0 \text{ V}$	-	0.1	±10	μΑ
I <sub>OZ</sub>	OFF-state output	$V_I = V_{IH}$ or $V_{IL}$ ; $V_O = V_{CC}$ or GND				
	current	V <sub>CC</sub> = 1.65 V to 2.7 V	-	0.1	5	μA
		V <sub>CC</sub> = 3.0 V to 3.6 V	-	0.1	10	μA
I <sub>CC</sub>	supply current	$V_I = V_{CC}$ or GND; $I_O = 0$ A				
		V <sub>CC</sub> = 1.65 V to 2.7 V	-	0.1	20	μA
		V <sub>CC</sub> = 3.0 V to 3.6 V	-	0.2	40	μA
C <sub>I</sub>	input capacitance		-	3.8	-	pF

<sup>[1]</sup> All typical values are measured at  $T_{amb}$  = 25 °C.

## 9.1. Dynamic Controlled Output graphs

A Dynamic Controlled Output (DCO) circuit is designed in. During the transition, it initially lowers the output impedance to effectively drive the load and, subsequently, raises the impedance to reduce noise. Fig. 5 shows  $V_{OL}$  vs.  $I_{OL}$  and  $V_{OH}$  vs.  $I_{OH}$  curves to illustrate the output impedance and drive capability of the circuit. At the beginning of the signal transition, the DCO circuit provides a maximum dynamic drive that is equivalent to a high drive standard output device.



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# 10. Dynamic characteristics

**Table 7. Dynamic characteristics** 

Voltages are referenced to GND (ground = 0 V). For test circuit see Fig. 12.

Symbol	Parameter	Conditions		Min	Typ [1]	Max	Unit
t <sub>pd</sub>	propagation delay	An to Yn; see Fig. 6	[2]				
		V <sub>CC</sub> = 1.2 V		-	5.0	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		1.7	-	5.3	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		1.0	2.5	4.4	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		8.0	1.7	3.0	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		0.7	1.5	2.6	ns
		LE to Yn; see Fig. 7	[2]				
		V <sub>CC</sub> = 1.2 V		-	5.3	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		1.7	-	6.0	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		1.2	2.7	4.8	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.0	2.0	3.3	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		0.7	1.6	3.2	ns
		CP to Yn; see Fig. 9	[2]				
		V <sub>CC</sub> = 1.2 V		-	4.1	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		1.4	-	4.6	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		1.0	2.3	3.9	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		8.0	1.7	3.0	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		0.7	1.6	2.8	ns
t <sub>en</sub>	enable time	OE to Yn; see Fig. 11	[2]				
		V <sub>CC</sub> = 1.2 V		-	6.0	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		2.0	-	6.7	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		1.5	3.1	5.3	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.0	2.2	3.8	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		0.7	1.7	3.4	ns
t <sub>dis</sub>	disable time	OE to Yn; see Fig. 11	[2]				
		V <sub>CC</sub> = 1.2 V		-	6.1	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		1.7	-	7.1	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		1.5	3.7	6.5	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		0.9	2.0	3.9	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		1.0	2.1	3.7	ns
t <sub>W</sub>	pulse width	CP HIGH or LOW; see Fig. 9.					
		V <sub>CC</sub> = 1.65 V to 1.95 V		2.0	-	-	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.2	-	-	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		1.0	-	-	ns
		LE LOW; see Fig. 7.					
		V <sub>CC</sub> = 1.65 V to 1.95 V		2.0	-	-	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.2	-	-	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		1.0	-	-	ns

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Symbol	Parameter	Conditions	Min	Typ [1]	Max	Unit
t <sub>su</sub>	set-up time	An to CP; see Fig. 10				
		V <sub>CC</sub> = 1.2 V	-	0.0	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V	0.1	-	-	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V	0.1	-0.1	-	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V	0.1	-0.1	-	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V	0.2	-0.1	-	ns
		An to LE; see Fig. 8				
		V <sub>CC</sub> = 1.2 V	-	1.0	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V	1.2	-	-	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V	0.8	0.3	-	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V	0.5	0.1	-	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V	0.4	0.1	-	ns
t <sub>h</sub> hold t	hold time	An to CP; see Fig. 10				
		V <sub>CC</sub> = 1.2 V	-	0.1	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V	0.6	-	-	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V	0.6	0.2	-	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V	0.6	0.2	-	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V	0.6	0.2	-	ns
		An to LE; see Fig. 8				
		V <sub>CC</sub> = 1.2 V	-	-0.4	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V	0.3	-	-	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V	0.3	0.1	-	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V	0.4	0.1	-	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V	0.4	0.1	-	ns
f <sub>max</sub>	maximum frequency	CP; see Fig. 9				
		V <sub>CC</sub> = 1.65 V to 1.95 V	250	-	-	MHz
		V <sub>CC</sub> = 2.3 V to 2.7 V	400	-	-	MHz
		V <sub>CC</sub> = 3.0 V to 3.6 V	500	-	-	MHz
C <sub>PD</sub>	power dissipation capacitance	per buffer; $V_I = GND$ to $V_{CC}$ [3]				
		outputs enabled	-	25	-	pF
		outputs disabled	-	6	-	pF

Typical values are measured at  $T_{amb}$  = 25 °C and  $V_{CC}$  = 1.2 V, 1.5 V, 1.8 V, 2.5 V and 3.3 V respectively.

 $t_{\text{en}}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}.$ 

 $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ . [3]  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu$ W).  $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_0)$  where:

 $f_i$  = input frequency in MHz;

fo = output frequency in MHz

C<sub>L</sub> = output load capacitance in pF

V<sub>CC</sub> = supply voltage in Volts

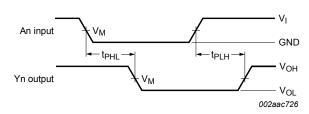
N = number of inputs switching

 $\Sigma(C_L \times V_{CC}^2 \times f_0)$  = sum of the outputs.

t<sub>pd</sub> is the same as t<sub>PLH</sub> and t<sub>PHL</sub>.

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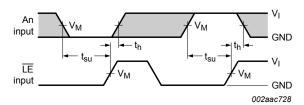
#### 10.1. Waveforms and test circuit



Measurement points are given in Table 8.

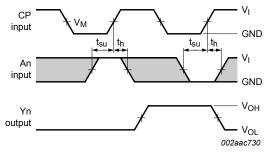
 $V_{OL}$  and  $V_{OH}$  are typical voltage output levels that occur with the output load.

Fig. 6. Input (An) to output (Yn) propagation delay



Measurement points are given in <u>Table 8</u>. The shaded areas indicate when the input is permitted to change for predictable output performance.

Fig. 8. Data set-up and hold times, An input to LE input

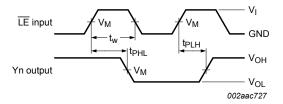


Measurement points are given in Table 8.

The shaded areas indicate when the input is permitted to change for predictable output performance.

 $V_{OL}$  and  $V_{OH}$  are typical voltage output levels that occur with the output load.

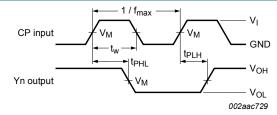
Fig. 10. Data set-up and hold times, An input to CP input



Measurement points are given in Table 8.

 $V_{OL}$  and  $V_{OH}$  are typical voltage output levels that occur with the output load.

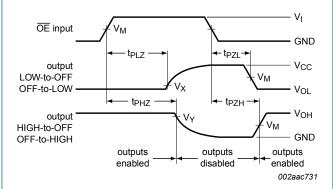
Fig. 7. LE input pulse width, LE input to Yn output propagation delays



Measurement points are given in Table 8.

 $\mbox{V}_{\mbox{OL}}$  and  $\mbox{V}_{\mbox{OH}}$  are typical voltage output levels that occur with the output load.

Fig. 9. CP to Yn propagation delays, clock pulse width, and maximum clock frequency



Measurement points are given in <u>Table 8</u>.

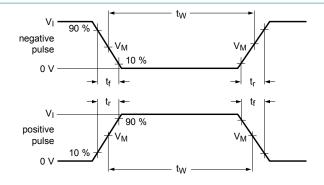
 $V_{OL}$  and  $V_{OH}$  are typical voltage output levels that occur with the output load.

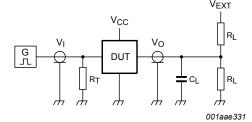
Fig. 11. 3-state enable and disable times

**Table 8. Measurement points** 

Supply voltage	Input		Output			
V <sub>CC</sub>	V <sub>I</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>	
≤ 2.3 V	V <sub>CC</sub>	0.5 x V <sub>CC</sub>	0.5 x V <sub>CC</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V	
2.3 V to 2.7 V	V <sub>CC</sub>	0.5 x V <sub>CC</sub>	0.5 x V <sub>CC</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V	
3.0 V to 3.6 V	V <sub>CC</sub>	0.5 x V <sub>CC</sub>	0.5 x V <sub>CC</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> - 0.3 V	

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Test data is given in Table 9.

Definitions for test circuit:

 $R_L$  = Load resistance.

 $C_L$  = Load capacitance including jig and probe capacitance.

 $R_T$  = Termination resistance should be equal to output impedance  $Z_0$  of the pulse generator.

V<sub>EXT</sub> = External voltage for measuring switching times.

Fig. 12. Test circuit for measuring switching times

Table 9. Test data

Supply voltage	Input		Load V <sub>EXT</sub>			Load		
V <sub>CC</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL	R <sub>L</sub>	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PLZ</sub> , t <sub>PZL</sub>	t <sub>PHZ</sub> , t <sub>PZH</sub>	
≤ 2.3 V	V <sub>CC</sub>	≤ 2.0 ns	30 pF	1000 Ω	open	2 x V <sub>CC</sub>	GND	
2.3 V to 2.7 V	V <sub>CC</sub>	≤ 2.0 ns	30 pF	500 Ω	open	2 x V <sub>CC</sub>	GND	
3.0 V to 3.6 V	V <sub>CC</sub>	≤ 2.0 ns	30 pF	500 Ω	open	2 x V <sub>CC</sub>	GND	

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## 11. Package outline

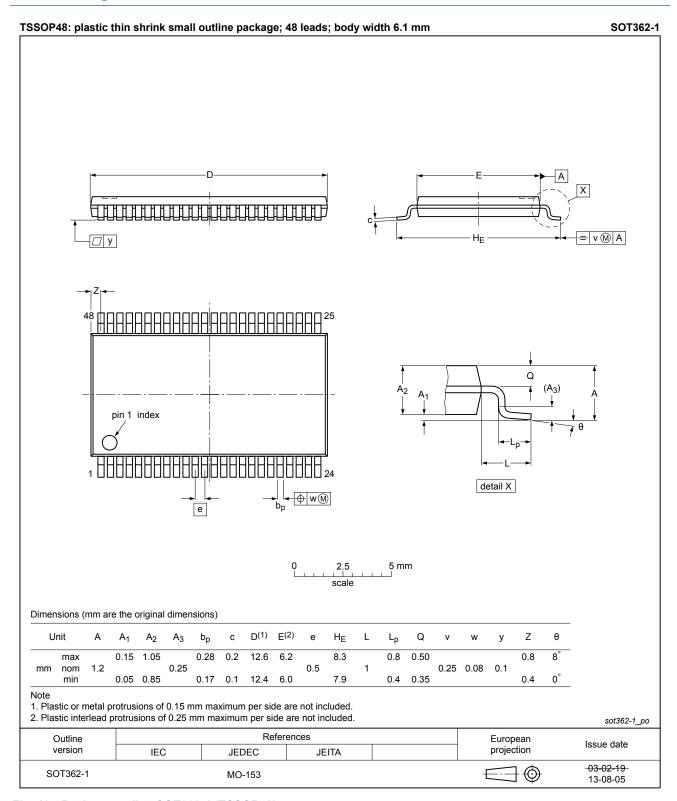


Fig. 13. Package outline SOT362-1 (TSSOP48)

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## 12. Abbreviations

#### **Table 10. Abbreviations**

Acronym	Description	
CMOS	omplementary Metal-Oxide Semiconductor	
DCO	Dynamic Controlled Output	
DUT	Device Under Test	

# 13. Revision history

## Table 11. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74AVC16334A v.3	20180912	Product data sheet	-	74AVC16334A v.2
Modifications:	of Nexperia.	his data sheet has been we been adapted to the ne		oly with the identity guidelines where appropriate.
74AVC16334A v.2	20000803	Product specification	-	74AVC16334A v.1
74AVC16334A v.1	20000502	Product specification	-	-

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## 14. Legal information

#### **Data sheet status**

Document status [1][2]	Product status [3]	Definition
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## 16-bit registered driver with inverted register enable and Dynamic Controlled Outputs; 3-state

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