# 74AVC16835A

18-bit registered driver with Dynamic Controlled Outputs; 3-state

Rev. 6 — 24 September 2018

**Product data sheet** 

## 1. General description

The 74AVC16835A is an 18-bit universal bus driver. Data flow is controlled by output enable ( $\overline{OE}$ ), latch enable (LE) and clock inputs (CP).

This product is designed to have an extremely fast propagation delay and a minimum amount of power consumption.

To ensure the high-impedance state during power up or power down,  $\overline{OE}$  should be tied to V<sub>CC</sub> through a pullup resistor (Live Insertion).

A Dynamic Controlled Output (DCO) circuitry is implemented to support termination line drive during transient. See Fig. 5 for typical curves.

# 2. Features and benefits

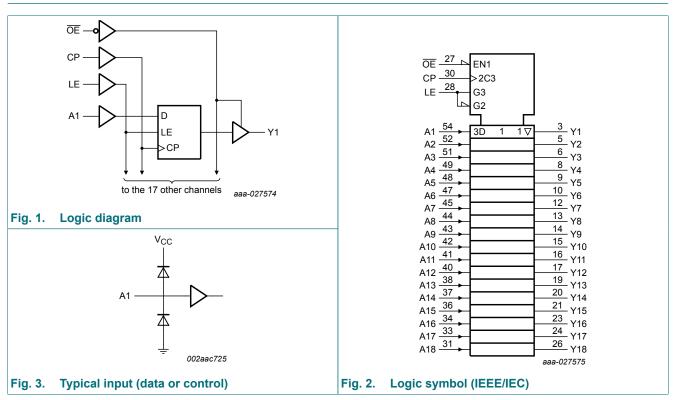
- Wide supply voltage range from 1.2 V to 3.6 V
- Complies with JEDEC standards:
  - JESD8-7 (1.2 V to 1.95 V)
  - JESD8-5 (1.8 V to 2.7 V)
  - JESD8-1A (2.7 V to 3.6 V)
- CMOS low power consumption
- Input/output tolerant up to 3.6 V
- Dynamic Controlled Output (DCO) circuit dynamically changes output impedance, resulting in noise reduction without speed degradation
- Low inductance multiple V<sub>CC</sub> and GND pins to minimize noise and ground bounce
- Power off disables 74AVC16835A outputs, permitting Live Insertion
- Integrated input diodes to minimize input overshoot and undershoot

# 3. Ordering information

Table 1. Ordering information						
Type number	Package					
	Temperature range	Name	Description	Version		
74AVC16835ADGG	-40 °C to + 85 °C	TSSOP56	plastic thin shrink small outline package; 56 leads; body width 6.1 mm	SOT364-1		

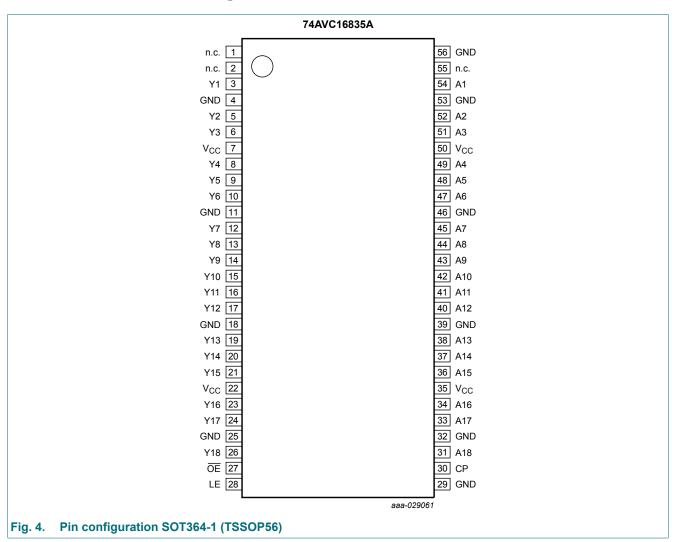
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# 4. Functional diagram



74AVC16835A

# 5. Pinning information



5.1. Pinning

74AVC16835A

Symbol	Pin	Description
A1, A2, A3, A4, A5, A6, A7, A8, A9, A10, A11, A12, A13, A14, A15, A16, A17, A18	54, 52, 51, 49, 48, 47, 45, 44, 43, 42, 41, 40, 38, 37, 36, 34, 33, 31	data inputs
Y1, Y2, Y3, Y4, Y5, Y6, Y7, Y8, Y9, Y10, Y11, Y12, Y13, Y14, Y15, Y16, Y17, Y18	3, 5, 6, 8, 9, 10, 12, 13, 14, 15, 16, 17, 19, 20, 21, 23, 24, 26	data outputs
n.c.	1, 2, 55	not connected
LE	28	latch enable input
ŌĒ	27	output enable input (active LOW)
CP	30	clock input
GND	4, 11, 18, 25, 29, 32, 39, 46, 53, 56	ground (0 V)
V <sub>CC</sub>	7, 22, 35, 50	supply voltage
		1

### 5.2. Pin description

# 6. Functional description

### Table 3. Function selection

H = HIGH voltage level; L = LOW voltage level; X = Don't care; Z = high-impedance OFF-state;

 $\uparrow$  = LOW to HIGH level transition.

Inputs	Outputs			
OE	LE	СР	An	Yn
Н	Х	Х	Х	Z
L	Н	Х	L	L
L	Н	Х	Н	Н
L	L	↑	L	L
L	L	1	Н	Н
L	L	Н	Х	Y <sub>0</sub> [1]
L	L	L	Х	Y <sub>0</sub> [2]

[1] Output level before the indicated steady-state input conditions were established, provided that CP is high before LE goes low.

[2] Output level before the indicated steady-state input conditions were established.

# 7. Limiting values

### Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC</sub>	supply voltage			-0.5	+4.6	V
I <sub>IK</sub>	input clamping current	V <sub>1</sub> < 0 V		-50	-	mA
VI	input voltage		[1]	-0.5	+4.6	V
I <sub>OK</sub>	output clamping current	$V_{\rm O}$ > $V_{\rm CC}$ or $V_{\rm O}$ < 0 V		-	±50	mA
Vo	output voltage	output HIGH or LOW	[1]	-0.5	V <sub>CC</sub> + 0.5	V
		output 3-state	[1]	-0.5	+4.6	V
I <sub>O</sub>	output current	$V_{O}$ = 0 V to $V_{CC}$		-	±50	mA
I <sub>CC</sub>	supply current			-	100	mA
I <sub>GND</sub>	ground current			-100	-	mA
T <sub>stg</sub>	storage temperature			-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40 \text{ °C to } +85 \text{ °C}$	[2]	-	600	mW

The input and output voltage ratings may be exceeded if the input and output current ratings are observed. Above 55 °C the value of  $P_{tot}$  derates linearly with 8 mW/K. [1]

[2]

# 8. Recommended operating conditions

### Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>CC</sub>	supply voltage	for low-voltage applications	1.2	-	3.6	V
		according to JEDEC Low Voltage	1.65	-	1.95	V
		Standards	2.3	-	2.7	V
			3.0	-	3.6	V
VI	input voltage		0	-	3.6	V
Vo	output voltage	output HIGH or LOW	0	-	V <sub>CC</sub>	V
		output 3-state	0	-	3.6	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	V <sub>CC</sub> = 1.65 V to 2.3 V	0	-	30	ns/V
	V <sub>CC</sub> = 2.3 V to 3.0 V	V <sub>CC</sub> = 2.3 V to 3.0 V	0	-	20	ns/V
		V <sub>CC</sub> = 3.0 V to 3.6 V	0	-	10	ns/V

# 9. Static characteristics

### Table 6. Static characteristics

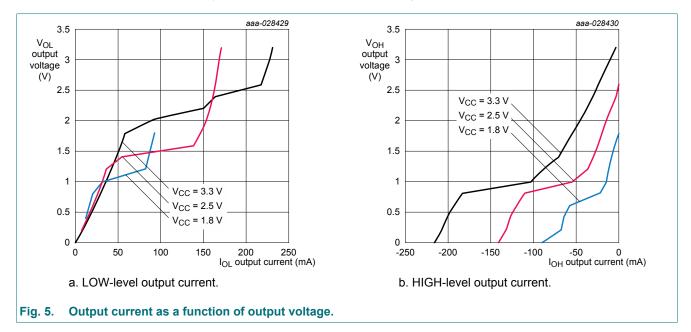
At recommended operating conditions;  $T_{amb} = -40$  °C to +85 °C; Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ[1]	Max	Unit
V <sub>IH</sub>	HIGH-level input	V <sub>CC</sub> = 1.2 V	V <sub>CC</sub>	-	-	V
	voltage	V <sub>CC</sub> = 1.65 V to 1.95 V	0.65 × V <sub>CC</sub>	0.9	-	V
		V <sub>CC</sub> = 2.3 V to 2.7 V	1.7	1.2	-	V
		V <sub>CC</sub> = 3.0 V to 3.6 V	2.0	1.5	-	V
V <sub>IL</sub>	LOW-level input	V <sub>CC</sub> = 1.2 V	-	-	GND	V
	voltage	V <sub>CC</sub> = 1.65 V to 1.95 V	-	0.9	0.35 × V <sub>CC</sub>	V
		V <sub>CC</sub> = 2.3 V to 2.7 V	-	1.2	0.7	V
		V <sub>CC</sub> = 3.0 V to 3.6 V	-	1.5	0.8	V
V <sub>OH</sub>	HIGH-level output	$V_{I} = V_{IH} \text{ or } V_{IL}$				
	voltage	$I_{O}$ = -100 µA; $V_{CC}$ = 1.65 V to 3.6 V	V <sub>CC</sub> - 0.20	V <sub>CC</sub>	-	V
		I <sub>O</sub> = -4 mA; V <sub>CC</sub> = 1.65 V	V <sub>CC</sub> - 0.45	V <sub>CC</sub> - 0.10	-	V
		I <sub>O</sub> = -8 mA; V <sub>CC</sub> = 2.3 V	V <sub>CC</sub> - 0.55	V <sub>CC</sub> - 0.28	-	V
		I <sub>O</sub> = -12 mA; V <sub>CC</sub> = 3.0 V	V <sub>CC</sub> - 0.70	V <sub>CC</sub> - 0.32	-	V
	LOW-level output	$V_{I} = V_{IH} \text{ or } V_{IL}$				
	voltage	$I_{O}$ = 100 µA; $V_{CC}$ = 1.65 V to 3.6 V	-	GND	0.20	V
		I <sub>O</sub> = 4 mA; V <sub>CC</sub> = 1.65 V	-	0.10	0.45	V
		I <sub>O</sub> = 8 mA; V <sub>CC</sub> = 2.3 V	-	0.26	0.55	V
		I <sub>O</sub> = 12 mA; V <sub>CC</sub> = 3.0 V	-	0.36	0.70	V
l <sub>l</sub>	input leakage current	$V_{I}$ = $V_{CC}$ or GND; $V_{CC}$ = 1.65 V to 3.6 V	-	0.1	2.5	μA
I <sub>OFF</sub>	power-off leakage current	$V_{I} \text{ or } V_{O} = 3.6 \text{ V}; V_{CC} = 0 \text{ V}$	-	0.1	±10	μA
I <sub>IHZ</sub> /I <sub>ILZ</sub>	power-off leakage current	$V_{CC}$ = 1.65 V to 3.6 V; $V_{I}$ = $V_{CC}$ or GND	-	0.1	12.5	μA
l <sub>oz</sub>	OFF-state output	$V_{I} = V_{IH} \text{ or } V_{IL}; V_{O} = V_{CC} \text{ or } GND$				
	current	V <sub>CC</sub> = 1.65 V to 2.7 V	-	0.1	5	μA
		V <sub>CC</sub> = 3.0 V to 3.6 V	-	0.1	10	μA
I <sub>CC</sub>	supply current	$V_{I} = V_{CC}$ or GND; $I_{O} = 0$ A				
		$V_{CC}$ = 1.65 V to 2.7 V	-	0.1	20	μA
		V <sub>CC</sub> = 3.0 V to 3.6 V	-	0.2	40	μA
CI	input capacitance		-	3.8	-	pF

[1] All typical values are measured at  $T_{amb}$  = 25 °C.

### 9.1. Dynamic Controlled Output graphs

A Dynamic Controlled Output (DCO) circuit is designed in. During the transition, it initially lowers the output impedance to effectively drive the load and, subsequently, raises the impedance to reduce noise. Fig. 5 show  $V_{OL}$  vs.  $I_{OL}$  and  $V_{OH}$  vs.  $I_{OH}$  curves to illustrate the output impedance and drive capability of the circuit. At the beginning of the signal transition, the DCO circuit provides a maximum dynamic drive that is equivalent to a high drive standard output device.



# **10. Dynamic characteristics**

### Table 7. Dynamic characteristics

Voltages are referenced to GND (ground = 0 V). For test circuit see Fig. 12.

Symbol	Parameter	Conditions		Min	Typ [1]	Max	Unit
t <sub>pd</sub>	propagation delay	An to Yn; see Fig. 6	[2]				
		V <sub>CC</sub> = 1.2 V		-	5.2	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		1.6	3.6	5.1	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		1.3	2.1	4.2	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.0	1.7	3.0	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		0.9	1.5	2.5	ns
		LE to Yn; see <u>Fig. 7</u>	[2]				-
		V <sub>CC</sub> = 1.2 V		-	4.2	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		1.6	2.8	4.6	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		1.3	2.2	4.0	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.1	1.9	3.5	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		0.9	1.6	2.9	ns
		CP to Yn; see Fig. 9	[2]				
		V <sub>CC</sub> = 1.2 V		-	4.3	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		1.6	2.9	4.6	ns
	V <sub>CC</sub> = 1.65 V to 1.95 V		1.5	2.2	3.7	ns	
		$V_{CC}$ = 2.3 V to 2.7 V		1.0	1.8	3.0	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		0.8	1.7	2.7	ns
t <sub>en</sub>	enable time	OE to Yn; see Fig. 11	[2]				
		V <sub>CC</sub> = 1.2 V		-	6.3	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		2.5	4.4	7.6	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		2.2	3.1	5.8	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.5	2.5	4.5	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		1.2	2.1	4.0	ns
t <sub>dis</sub>	disable time	OE to Yn; see Fig. 11	[2]				
		V <sub>CC</sub> = 1.2 V		-	5.5	-	ns
		V <sub>CC</sub> = 1.4 V to 1.6 V		2.2	4.1	7.6	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V		2.0	3.1	5.6	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.2	2.2	4.5	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		1.1	2.6	4.8	ns
tw	pulse width	CP HIGH or LOW; see Fig. 9.					
		V <sub>CC</sub> = 1.65 V to 1.95 V		2.0	-	-	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.2	-	-	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		1.0	-	-	ns
		LE HIGH; see Fig. 7.					
		V <sub>CC</sub> = 1.65 V to 1.95 V		2.0	-	-	ns
		V <sub>CC</sub> = 2.3 V to 2.7 V		1.2	-	-	ns
		V <sub>CC</sub> = 3.0 V to 3.6 V		1.0	-	_	ns

#### Symbol Parameter Conditions Min Typ [1] Max Unit An to CP; see Fig. 10 set-up time t<sub>su</sub> V<sub>CC</sub> = 1.2 V 0.0 ns -- $V_{CC}$ = 1.4 V to 1.6 V 0.2 0.0 ns - $V_{CC}$ = 1.65 V to 1.95 V -0.2 0.0 \_ ns $V_{CC}$ = 2.3 V to 2.7 V 0.0 -0.2 ns - $V_{CC}$ = 3.0 V to 3.6 V 0.0 -0.3 \_ ns An to LE; see Fig. 8 V<sub>CC</sub> = 1.2 V 1.5 ns - $V_{CC}$ = 1.4 V to 1.6 V 1.6 0.9 ns - $V_{CC}$ = 1.65 V to 1.95 V 1.1 0.6 ns \_ $V_{CC}$ = 2.3 V to 2.7 V 0.7 0.3 \_ ns $V_{CC}$ = 3.0 V to 3.6 V 1.0 0.5 ns -An to CP; see Fig. 10 hold time t<sub>h</sub> $V_{CC} = 1.2 V$ 0.1 \_ ns \_ $V_{CC}$ = 1.4 V to 1.6 V 0.7 0.3 ns \_ $V_{CC}$ = 1.65 V to 1.95 V 0.7 0.3 ns - $V_{CC}$ = 2.3 V to 2.7 V 0.7 0.3 ns \_ $V_{CC}$ = 3.0 V to 3.6 V 1.3 0.6 ns -An to LE; see Fig. 8 $V_{CC} = 1.2 V$ -0.7 \_ ns $V_{CC}$ = 1.4 V to 1.6 V 0.0 -0.3 \_ ns $V_{CC}$ = 1.65 V to 1.95 V 0.2 -0.2 ns $V_{CC}$ = 2.3 V to 2.7 V 0.2 0.0 \_ ns $V_{CC}$ = 3.0 V to 3.6 V 0.3 0.8 \_ ns CP; see Fig. 9 f<sub>max</sub> maximum frequency V<sub>CC</sub> = 1.65 V to 1.95 V 250 MHz -- $V_{CC}$ = 2.3 V to 2.7 V 400 \_ \_ MHz $V_{CC}$ = 3.0 V to 3.6 V 500 MHz \_ \_ power dissipation capacitance per buffer; $V_I = GND$ to $V_{CC}$ CPD [3] outputs enabled 25 pF \_ \_ outputs disabled \_ 6 pF \_

### 18-bit registered driver with Dynamic Controlled Outputs; 3-state

Typical values are measured at  $T_{amb}$  = 25 °C and  $V_{CC}$  = 1.5 V, 1.8 V, 2.5 V and 3.3 V respectively. [1] [2]

t<sub>pd</sub> is the same as t<sub>PLH</sub> and t<sub>PHL</sub>.

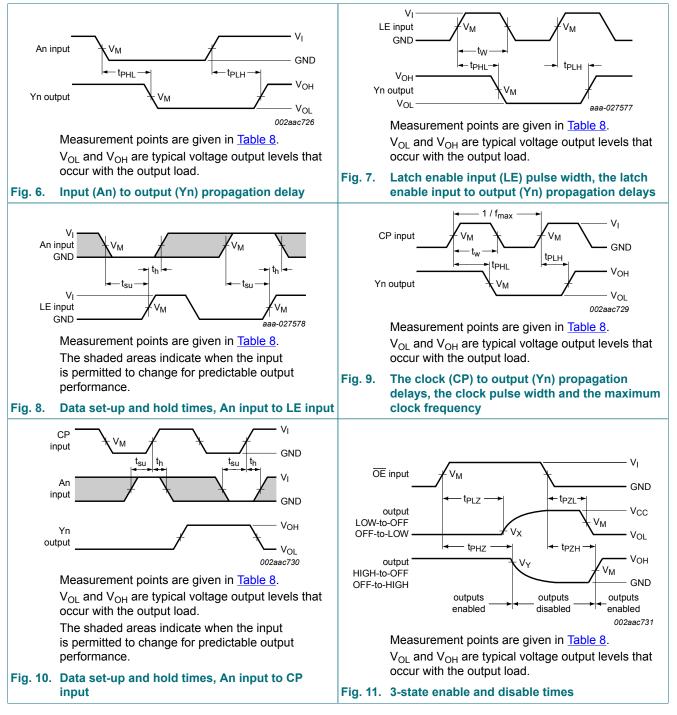
 $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ [3]  $C_{PD}$  is used to determine the dynamic power dissipation (P<sub>D</sub> in  $\mu$ W).  $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where: f<sub>i</sub> = input frequency in MHz; fo = output frequency in MHz CL = output load capacitance in pF V<sub>CC</sub> = supply voltage in Volts

N = number of inputs switching

 $\Sigma(C_L \times V_{CC}^2 \times f_0)$  = sum of the outputs.

## 10.1. Waveforms and test circuit

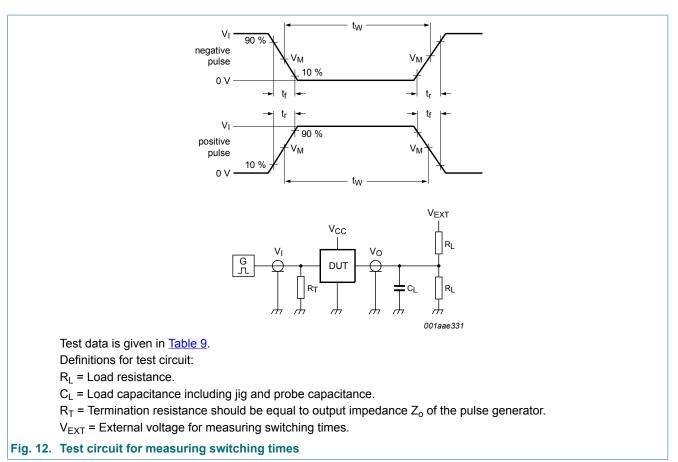


### Table 8. Measurement points

Supply voltage	Input		ly voltage Input Output			
V <sub>cc</sub>	VI	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>	
≤ 2.3 V	V <sub>CC</sub>	0.5 x V <sub>CC</sub>	0.5 x V <sub>CC</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V	
2.3 V to 2.7 V	V <sub>CC</sub>	0.5 x V <sub>CC</sub>	0.5 x V <sub>CC</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V	
3.0 V to 3.6 V	V <sub>CC</sub>	0.5 x V <sub>CC</sub>	0.5 x V <sub>CC</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> - 0.3 V	

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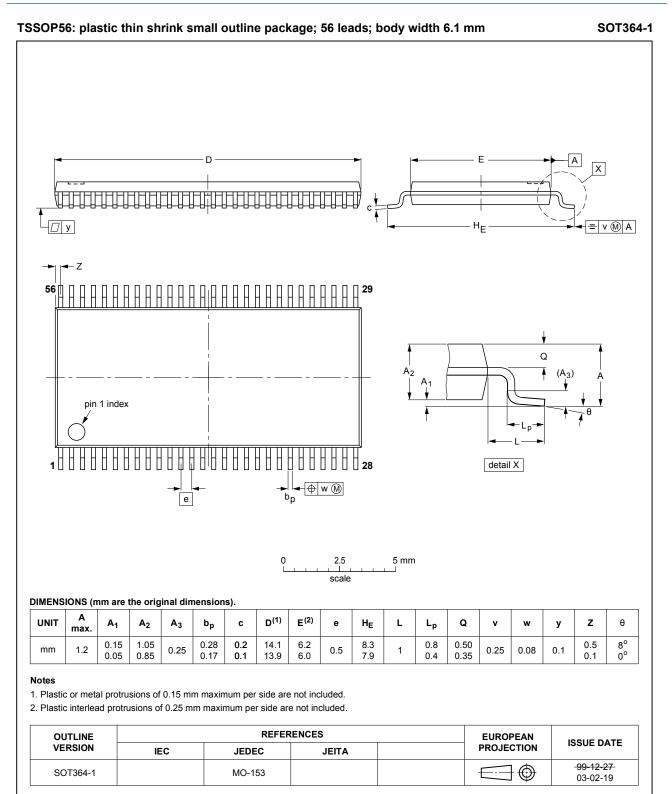
### 18-bit registered driver with Dynamic Controlled Outputs; 3-state



### Table 9. Test data

Supply voltage	Input		Load		V <sub>EXT</sub>	V <sub>EXT</sub>		
V <sub>cc</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL	RL	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PLZ</sub> , t <sub>PZL</sub>	t <sub>PHZ</sub> , t <sub>PZH</sub>	
≤ 2.3 V	V <sub>CC</sub>	≤ 2.0 ns	30 pF	1000 Ω	open	$2 \times V_{CC}$	GND	
2.3 V to 2.7 V	V <sub>CC</sub>	≤ 2.0 ns	30 pF	500 Ω	open	$2 \times V_{CC}$	GND	
3.0 V to 3.6 V	V <sub>CC</sub>	≤ 2.0 ns	30 pF	500 Ω	open	$2 \times V_{CC}$	GND	

# **11. Package outline**



### Fig. 13. Package outline SOT364-1 (TSSOP56)

74AVC16835A

# 12. Abbreviations

Table 10. Abbreviations				
Acronym	ronym Description			
CMOS	Complementary Metal-Oxide Semiconductor			
DCO	Dynamic Controlled Output			
DUT	Device Under Test			

# 13. Revision history

### Table 11. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
74AVC16835A v.6	20180924	Product data sheet	-	74AVC16835A v.5	
Modifications:	<ul> <li>The format of this data sheet has been redesigned to comply with the identity guidelin Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li>Type number 74AVC16835ADGV (SOT481-2) removed.</li> </ul>				
74AVC16835A v.5	20020315	Product data sheet	-	74AVC16835A v.4	
74AVC16835A v.4	20000725	Product specification	-	74AVC16835A v.3	
74AVC16835A v.3	20000502	Preliminary specification	-	74AVC16835 v.2	
74AVC16835 v.2	19990405	Preliminary specification	-	74AVC_AVCH16835 v.1	
74AVC_AVCH16835 v.1	19981207	Objective specification	-	-	

# 14. Legal information

### **Data sheet status**

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

 Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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