### DATASHEET

### **General Description**

The 9DMU0131 is a member of IDT's SOC-Friendly 1.5V Ultra-Low-Power (ULP) PCIe Gen1-2-3 family. The output has an OE# pin for optimal system control and power management. The part provides asynchronous or glitch-free switching modes.

### **Recommended Application**

2:1 1.5V PCIe Gen1-2-3 Clock Mux

### **Output Features**

• 1 – Low-Power (LP) HCSL DIF pair

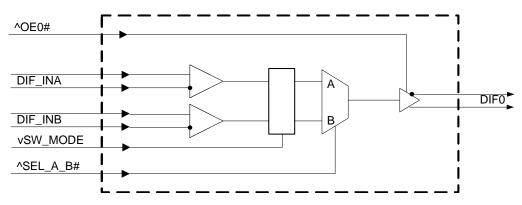
### **Key Specifications**

- DIF additive cycle-to-cycle jitter <5ps
- DIF phase jitter is PCIe Gen1-2-3 compliant
- 125MHz additive phase jitter 535fs rms typical (12kHz to 20MHz)

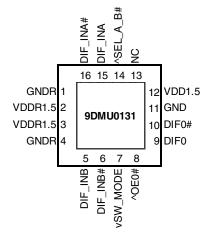
### **Block Diagram**

### Features/Benefits

- LP-HCSL output; saves 2 resistors compared to standard HCSL output
- 1.5V operation; 11mW typical power consumption
- Selectable asynchronous or glitch-free switching; allows the mux to be selected at power up even if both inputs are not running, then transition to glitch-free switching mode
- Spread Spectrum Compatible; supports EMI reduction
- OE# pin; supports DIF power management
- HCSL differential inputs; can be driven by common clock sources
- 1MHz to 167MHz operating frequency
- Space saving 16-pin 3x3mm VFQFPN; minimal board space



### **Pin Configuration**



#### 16-pin VFQFPN, 3x3 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor v prefix indicates internal 120KOhm pull down resistor

Note: Paddle may be connected to ground for thermal purposes. It is not required electrically.

#### **Power Management Table**

OEx# Pin	DIF IN	DIFx			
		True O/P	Comp. O/P		
0	Running	Running	Running		
1	Running	Low	Low		

#### **Power Connections**

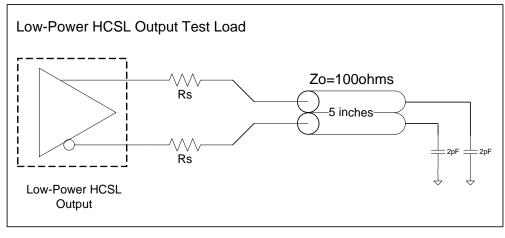
Pin Nu	umber	Description				
VDD	GND	Description				
2	1	Input A receiver analog				
3	4	Input B receiver analog				
12	11	DIF outputs				

Note: Pins 2 and 3 should be decoupled separately to pins 1 and 4 respectively.

### **Pin Descriptions**

Pin#	Pin Name	Туре	Pin Description				
1	GNDR	GND	Analog Ground pin for the differential input (receiver)				
2	VDDR1.5	PWR	1.5V power for differential input clock (receiver). This VDD should be treated as an Analog				
2	VDDR1.5	power rail and filtered appropriately.					
3	VDDR1.5	PWR	1.5V power for differential input clock (receiver). This VDD should be treated as an Analog				
<u> </u>			power rail and filtered appropriately.				
4	GNDR	GND	Analog Ground pin for the differential input (receiver)				
5	DIF_INB	IN	HCSL Differential True input				
6	DIF_INB#	IN	HCSL Differential Complement Input				
			Switch Mode. This pin selects either asynchronous or glitch-free switching of the mux. Use				
			asynchronous mode if 0 or 1 of the input clocks is running. Use glitch-free mode if both input				
7	vSW_MODE IN clocks are running. This pin has an internal pull down resistor of ~120kohms.						
			0 = asynchronous mode				
			1 = glitch-free mode				
8	^OE0#	IN	Active low input for enabling DIF pair 0. This pin has an internal pull-up resistor.				
			1 =disable outputs, 0 = enable outputs				
9	DIF0	OUT	Differential true clock output				
10	DIF0#	OUT	Differential Complementary clock output				
11	GND	GND	Ground pin.				
12	VDD1.5	PWR	Power supply, nominally 1.5V				
13	NC	N/A	No Connection.				
			Input to select differential input clock A or differential input clock B. This input has an internal				
14	^SEL_A_B#	IN	pull-up resistor.				
			0 = Input B selected, 1 = Input A selected.				
15	DIF_INA	IN	HCSL Differential True input				
16	DIF_INA#	IN	HCSL Differential Complement Input				

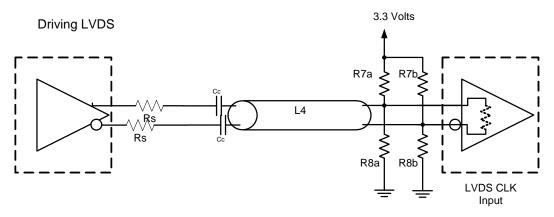
### **Test Loads**



#### Alternate Differential Output Terminations

Rs	Zo	Units
33	100	Ohms
27	85	CHIIIS

# **Driving LVDS**



#### **Driving LVDS inputs**

	, ,	Value		
	Receiver has Receiver does not			
Component	termination	have termination	Note	
R7a, R7b	10K ohm	140 ohm		
R8a, R8b	5.6K ohm	75 ohm		
Cc	0.1 uF	0.1 uF		
Vcm	1.2 volts	1.2 volts		

## **Electrical Characteristics–Absolute Maximum Ratings**

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	МАХ	UNITS	NOTES
Supply Voltage	VDDx		-0.5		2	V	1,2
Input Voltage	V <sub>IN</sub>		-0.5		V <sub>DD</sub> +0.5	V	1,3
Input High Voltage, SMBus	VIHSMB	SMBus clock and data pins			3.3	V	1
Storage Temperature	Ts		-65		150	°C	1
Junction Temperature	Tj				125	°C	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

<sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Operation under these conditions is neither implied nor guaranteed.

<sup>3</sup> Not to exceed 2.0V.

# Electrical Characteristics–Input/Supply/Common Parameters–Normal Operating Conditions

TA = T<sub>AMB</sub>, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

,							
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDx	Supply voltage for core and analog	1.425	1.5	1.575	V	
Ambient Operating Temperature	T <sub>AMB</sub>	Industrial range	-40	25	85	°C	1
Input High Voltage	V <sub>IH</sub>	Single-ended inputs, except SMBus	$0.75 V_{DD}$		$V_{DD} + 0.3$	V	
Input Low Voltage	V <sub>IL</sub>	Single-ended inputs, except SMBus	-0.3		$0.25 V_{DD}$	V	
	I <sub>IN</sub>	Single-ended inputs, $V_{IN} = GND$ , $V_{IN} = VDD$	-5		5	uA	
Input Current	I <sub>INP</sub>	Single-ended inputs $V_{IN} = 0 V$ ; Inputs with internal pull-up resistors $V_{IN} = VDD$ ; Inputs with internal pull-down resistors	-200		200	uA	
Input Frequency	F <sub>in</sub>		1		167	MHz	2
Pin Inductance	L <sub>pin</sub>				7	nH	1
	CIN	Logic Inputs, except DIF_IN	1.5		5	pF	1
Capacitance	C <sub>INDIF_IN</sub>	DIF_IN differential clock inputs	1.5		2.7	pF	1,4
	C <sub>OUT</sub>	Output pin capacitance			6	pF	1
Clk Stabilization	T <sub>STAB</sub>	From V <sub>DD</sub> Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock			1	ms	1,2
Input SS Modulation Frequency PCIe	f <sub>MODINPCIe</sub>	Allowable Frequency for PCIe Applications (Triangular Modulation)	30		33	kHz	
Input SS Modulation Frequency non-PCIe	f <sub>MODIN</sub>	Allowable Frequency for non-PCIe Applications (Triangular Modulation)	0		66	kHz	
OE# Latency	t <sub>LATOE#</sub>	DIF start after OE# assertion DIF stop after OE# deassertion	1		3	clocks	1,3
Tfall	t <sub>F</sub>	Fall time of single-ended control inputs			5	ns	1,2
Trise	t <sub>R</sub>	Rise time of single-ended control inputs			5	ns	1,2

<sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup>Control input must be monotonic from 20% to 80% of input swing.

<sup>3</sup>Time from deassertion until outputs are >200 mV

<sup>4</sup> DIF\_IN input

### **Electrical Characteristics–Clock Input Parameters**

TA = T<sub>AMB</sub>, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage - DIF_IN	V <sub>IHDIF</sub>	Differential inputs (single-ended measurement)	300	750	1150	mV	1
Input Low Voltage - DIF_IN	V <sub>ILDIF</sub>	Differential inputs (single-ended measurement)	V <sub>SS</sub> - 300	0	300	mV	1
Input Common Mode Voltage - DIF_IN	V <sub>COM</sub>	Common Mode Input Voltage	200		725	mV	1
Input Amplitude - DIF_IN	V <sub>SWING</sub>	Peak to Peak value (V <sub>IHDIF</sub> - V <sub>ILDIF</sub> )	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.35		8	V/ns	1,2
Input Leakage Current	I <sub>IN</sub>	$V_{IN} = V_{DD}, V_{IN} = GND$	-5		5	uA	
Input Duty Cycle	d <sub>tin</sub>	Measurement from differential wavefrom	45	50	55	%	1
Input Jitter - Cycle to Cycle	J <sub>DIFIn</sub>	Differential Measurement	0		150	ps	1

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Slew rate measured through +/-75mV window centered around differential zero

### **Electrical Characteristics–DIF Low-Power HCSL Outputs**

TA = T<sub>AMB</sub>, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	dV/dt	Scope averaging on, fast setting	1.3	2.5	3.9	V/ns	1,2,3
Slew rate matching	∆dV/dt	Slew rate matching, Scope averaging on		16	20	%	1,2,4
Voltage High	V <sub>HIGH</sub>	Statistical measurement on single-ended signal using oscilloscope math function. (Scope	550	766	850	mV	
Voltage Low	V <sub>LOW</sub>	averaging on)	-150	22	150		
Max Voltage	Vmax	Measurement on single ended signal using		774	1150	mV	
Min Voltage	Vmin	absolute value. (Scope averaging off)	-300	-33		IIIV	
Vswing	Vswing	Scope averaging off	300	1488		mV	1,2
Crossing Voltage (abs)	Vcross_abs	Scope averaging off	250	382	550	mV	1,5
Crossing Voltage (var)	∆-Vcross	Scope averaging off		11	140	mV	1,6

<sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Measured from differential waveform

<sup>3</sup> Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

<sup>4</sup> Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

<sup>5</sup> Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

<sup>6</sup> The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross\_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

### **Electrical Characteristics–Current Consumption**

TA = T<sub>AMB</sub>, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Operating Supply Current	I <sub>DD</sub>	VDD, All outputs active @100MHz		7	11	mA	1
Powerdown Current	I <sub>DDPD</sub>	VDD, all outputs disabled		1.4	2.5	mA	1, 2

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Input clock stopped.

# Electrical Characteristics–Output Duty Cycle, Jitter, Skew and PLL Characteristics

TA = T<sub>AMB</sub>, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Duty Cycle Distortion	t <sub>DCD</sub>	Measured differentially@100MHz	-1	-0.1	1	%	1,3
Skew, Input to Output	t <sub>pdBYP</sub>	Bypass Mode, V <sub>T</sub> = 50%	2166	2896	3952	ps	1
Skew, Output to Output	t <sub>sk3</sub>	V <sub>T</sub> = 50%		N/A	N/A	ps	1
Jitter, Cycle to cycle	t <sub>jcyc-cyc</sub>	Additive Jitter		0.1	8	ps	1,2

<sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> Measured from differential waveform

<sup>3</sup> Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

### **Electrical Characteristics–Phase Jitter Parameters**

 $TA = T_{AMB}$ , Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	МАХ	INDUSTRY LIMIT	UNITS	Notes
	t <sub>jphPCleG1</sub>	PCIe Gen 1		0.4	5	N/A	ps (p-p)	1,2,3,5
		PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.4	0.55	N/A	ps (rms)	1,2,3,4, 5
	t <sub>jphPCleG2</sub>	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		0.1	0.2	N/A	ps (rms)	1,2,3,4
Additive Phase Jitter, Bypass Mode	t <sub>jphPCleG3</sub>	PCIe Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)		0.05	0.1	N/A	ps (rms)	1,2,3,4
	t <sub>jph125M0</sub>	125MHz, 1.5MHz to 10MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		365	380	N/A	fs (rms)	1,6
	t <sub>jph125M1</sub>	125MHz, 12KHz to 20MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		535	550	N/A	fs (rms)	1,6

<sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>2</sup> See http://www.pcisig.com for complete specs

<sup>3</sup> Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

<sup>4</sup> For RMS figures, additive jitter is calculated by solving the following equation: Additive jitter = SQRT[(total jitter)^2 - (input jitter)^2]

<sup>5</sup> Driven by 9FGU0831 or equivalent

<sup>6</sup> Rohde&Schartz SMA100

### **Marking Diagram**



Notes:

- 1. "XXX" is the last 3 characters of the lot number.
- 2. "YYWW" is the last two digits of the year and week that the part was assembled.
- 3. Line 3: truncated part number
- 4. "I" denotes industrial temperature grade.

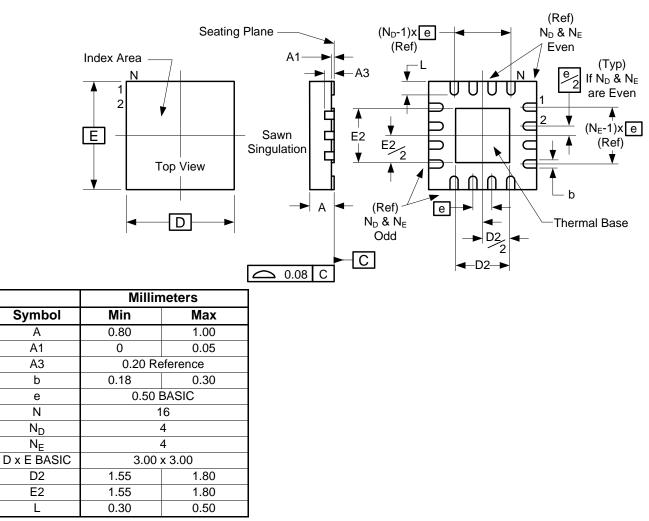
### **Thermal Characteristics**

PARAMETER	SYMBOL	CONDITIONS	PKG	TYP VALUE	UNITS	NOTES
Thermal Resistance	θ <sub>JC</sub>	Junction to Case	NLG16	66	°C/W	1
	$\theta_{Jb}$	Junction to Base		5	°C/W	1
	$\theta_{JA0}$	Junction to Air, still air		63	°C/W	1
	$\theta_{JA1}$	Junction to Air, 1 m/s air flow		56	°C/W	1
	$\theta_{JA3}$	Junction to Air, 3 m/s air flow	51 49		°C/W	1
	$\theta_{JA5}$	Junction to Air, 5 m/s air flow			°C/W	1

<sup>1</sup>ePad soldered to board

# Package Outline and Package Dimensions (NLG16)

Package dimensions are kept current with JEDEC Publication No. 95



### **Ordering Information**

Part / Order Number	Shipping Packaging	Package	Temperature	
9DMU0131AKILF	Trays	16-pin VFQFPN	-40 to +85° C	
9DMU0131AKILFT	Tape and Reel	16-pin VFQFPN	-40 to +85° C	

"LF" to the suffix denotes Pb-Free configuration, RoHS compliant.

"A" is the device revision designator (will not correlate with the datasheet revision).

# **Revision History**

Rev.	Initiator	Issue Date	Description	Page #
			1. Update front page text and electrical tables with char data.	
Α	RDW	9/29/2014	<ol><li>Update pinout diagram with note about package paddle.</li></ol>	Various
			3. Move to final.	



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