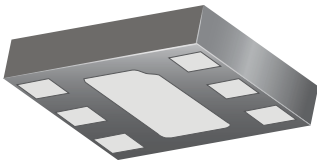# Low Voltage Full Bridge Brushless DC Motor Driver with Hall Commutation and Soft Switching, and Reverse Battery, Short Circuit, and Thermal Shutdown Protection

## Features and Benefits

- Low voltage operation
- Reverse voltage protection on VDD and $\overline{\text{SLEEP}}$ pins
- Output short circuit and thermal shutdown protections
- Soft switching algorithm to reduce audible switching noise and EMI interference
- Unidirectional working mode provides motor rotation in one direction
- Hall chopper stabilization technique for precise signal response over operating range
- Sleep mode pin allowing external logic signal enable/ disable to reduce average power consumption
- Antistall feature guarantees continuous rotation
- Low current consumption sleep mode
- Single-chip solution for high reliability
- Miniature MLP/DFN package

## Package: 6 pin MLP/DFN (suffix EW)

1.5 mm × 2 mm, 0.40 mm maximum overall height

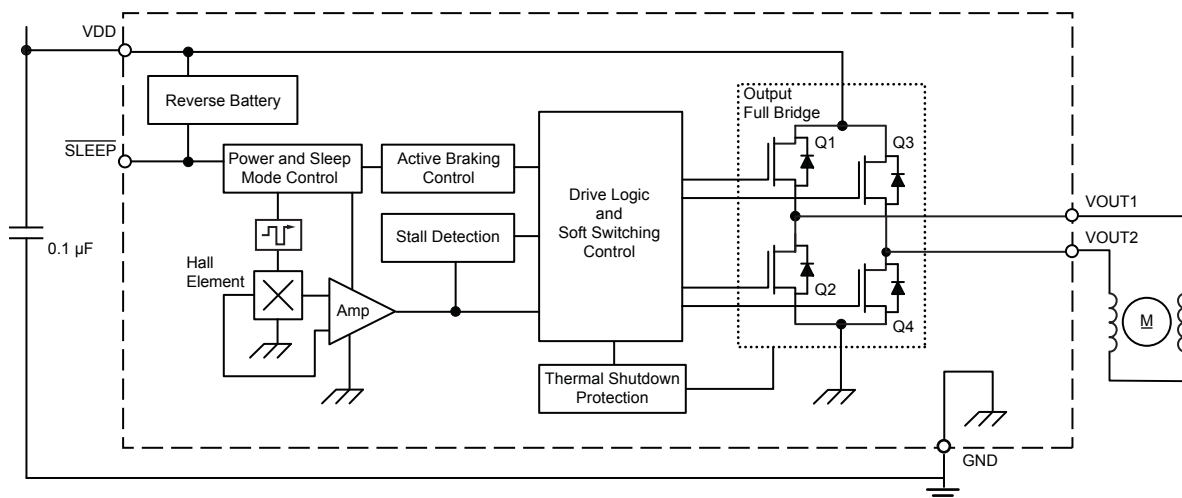*Approximate scale*

## Description

The A1442 is a full-bridge motor driver designed to drive low-voltage, brushless DC motors. Commutation of the motor is achieved by use of a single Hall element to detect the rotational position of an alternating-pole ring magnet. A high-density CMOS semiconductor process allows the integration of all the necessary electronics. This includes the Hall element, the motor control circuitry, and the full output bridge. Low-voltage design techniques have been employed to achieve full device functionality down to low $V_{DD}$ values. This fully integrated single chip solution provides enhanced reliability (including reverse battery protection and output short circuit protection) and eliminates the need for any external support components.

The A1442 employs a soft-switching algorithm to reduce audible switching noise and EMI interference. A micropower sleep mode can be enabled by an external signal, to reduce current consumption for battery management in portable electronic devices. This feature allows the removal of a FET transistor for switching the device on and off.

The A1442 is optimized for vibration motor applications in cellular phones, pagers, electronic toothbrushes, hand-held video game controllers, and low power fan motors.

The small package outline and low profile make this device ideally suited for use in applications where printed circuit board area and component headroom are at a premium. It is available in a lead (Pb) free, 6 pin MLP/DFN microleadframe package, with an exposed pad for enhanced thermal dissipation.

## Functional Block Diagram

**A1442**

*Low Voltage Full Bridge Brushless DC Motor Driver*
*with Hall Commutation and Soft Switching,*
*and Reverse Battery, Short Circuit, and Thermal Shutdown Protection*

## Selection Guide

| Part Number | Package[1] | Packing |
|---|---|---|
| A1442EEWLT-P[2] | MLP/DFN 1.5 mm × 2 mm, 0.4 mm maximum overall height | 3000 pieces / 7 in. reel |

[1]Contact Allegro® for additional packing options.

[2]Allegro products sold in DFN package types are not intended for automotive applications.

## Absolute Maximum Ratings

| Characteristic | Symbol | Notes | Rating | Units |
|---|---|---|---|---|
| Forward Supply Voltage | $V_{DD}$ | | 5.0 | V |
| Reverse Supply Voltage | $V_{RDD}$ | | −5.0 | V |
| Output Voltage | $V_{OUT}$ | $V_{DD} > 0$ V | 0 to $V_{DD} + 0.3$ | V |
| Reverse Output Voltage | $V_{ROUT}$ | $V_{DD} > 0$ V | −0.3 | V |
| $\overline{SLEEP}$ Input Voltage | $V_{IN}$ | | 0 to $V_{DD} + 0.3$ | V |
| Peak Output Current | $I_{OUTpk}$ | < 1 ms | ±400 | mA |
| Operating Ambient Temperature | $T_A$ | Range E | −40 to 85 | ºC |
| Junction Temperature | $T_J(max)$ | | 165 | ºC |
| Storage Temperature | $T_{stg}$ | | −65 to 165 | ºC |

## Pin-out Diagram
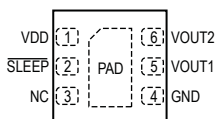


## Terminal List Table

| Pin | Name | Function |
|---|---|---|
| 1 | VDD | Supply voltage |
| 2 | $\overline{SLEEP}$ | Toggle sleep/enabled modes |
| 3 | NC | No connection |
| 4 | GND | Ground |
| 5 | VOUT1 | First output |
| 6 | VOUT2 | Second output |

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**A1442**

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**OPERATING CHARACTERISTICS** valid over the full $V_{DD}$ and $T_A$ range unless otherwise noted

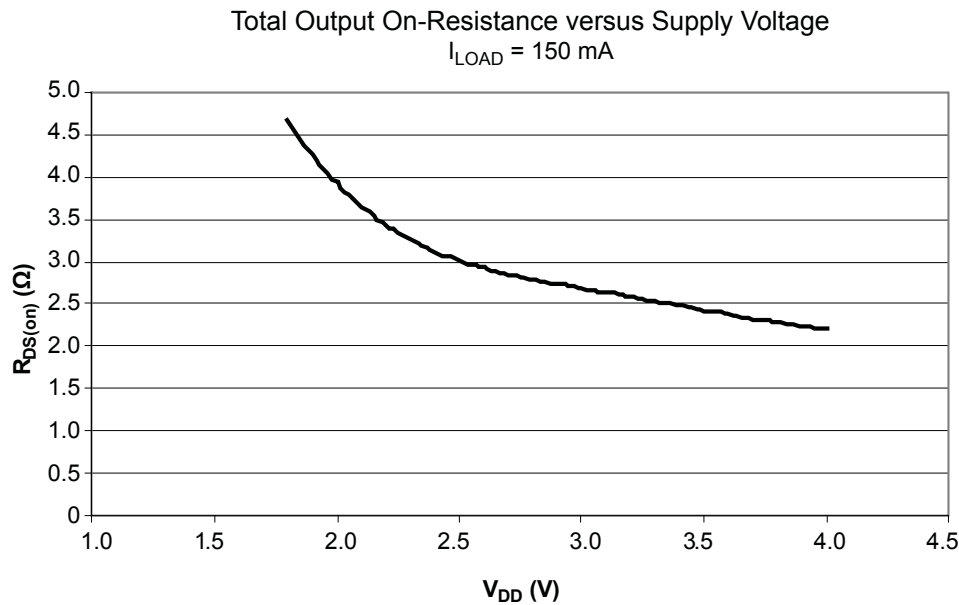| Characteristic | Symbol | Test Conditions | Min. | Typ. | Max. | Units |
|---|---|---|---|---|---|---|
| Supply Voltage[1] | $V_{DD}$ | Operating, $T_J < T_J$(max); $C_{BYP}$ = 0.1 µF | 2.0 | – | 4.2 | V |
| Supply Current | $I_{DD(ON)}$ | $V_{IN} > V_{INHI}$, , $T_A$ = 25°C, no load | – | 4 | 6 | mA |
| | | $V_{IN} < V_{INLO}$ , $T_A$ = 25°C | – | – | 10 | µA |
| Total Output On Resistance[2,3] | $R_{DS(on)}$ | $V_{DD}$ = 2 V, $I_{OUT}$ = 70 mA, $T_A$ = 25°C | – | 3.9 | – | Ω |
| | | $V_{DD}$ = 3 V, $I_{OUT}$ = 70 mA, $T_A$ = 25°C | – | 2.6 | – | Ω |
| | | $V_{DD}$ = 4 V, $I_{OUT}$ = 70 mA, $T_A$ = 25°C | – | 2.2 | – | Ω |
| Reverse Battery Current | $I_{RDD}$ | $V_{RDD}$ = –4.2 V | – | – | –10 | mA |
| Sleep Input Threshold | $V_{INHI}$ | | $0.7 \times V_{DD}$ | – | | V |
| | $V_{INLO}$ | | – | – | $0.2 \times V_{DD}$ | V |
| Sleep Input Current | $I_{IN}$ | $V_{IN}$ = 3.0 V | – | 1.0 | 5 | µA |
| Reverse Sleep Current | $I_{RIN}$ | $V_{RIN}$ = –4.2 V | – | – | –10 | mA |
| Restart Delay[4] | $t_{RS}$ | | – | 120 | – | ms |
| Hall Chopping Settling Time | $t_{S(CHOP)}$ | | – | 80 | – | µs |
| Magnetic Switchpoints[2] | $B_{OP}$ | | – | 35 | 75 | G |
| | $B_{RP}$ | | –75 | -35 | – | G |
| | $B_{HYS}$ | | – | 70 | – | G |
| Output Polarity | $V_{OUT1}$ | $B < B_{RP}$ | – | LOW | – | V |
| | | $B > B_{OP}$ | – | HIGH | – | V |
| | $V_{OUT2}$ | $B < B_{RP}$ | – | HIGH | – | V |
| | | $B > B_{OP}$ | – | LOW | – | V |

[1] A bypass capacitor of 0.1 µF is required between VDD and GND for proper device operation through the full specified voltage range.

[2] Extended $V_{DD}$ range affects $R_{DS(on)}$ and $B_x$.

[3] Total On Resistance equals either $R_{DS(on)}Q1 + R_{DS(on)}Q4$ or $R_{DS(on)}Q2 + R_{DS(on)}Q3$.

[4] The Restart Delay is the time the outputs are on or off when the device is attempting a restart.

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## Characteristic Performance

Total Output On-Resistance versus Supply Voltage
$I_{LOAD}$ = 150 mA



## Functional Description

**Soft Switching** The A1442 device includes a soft-switching algorithm that controls the output switching slew rate for both output pins. As a result the A1442 device is ideal for use in applications requiring low audible switching noise and low EMI interference.

**Sleep Mode** The $\overline{SLEEP}$ pin accepts an external signal that enables sleep mode. In sleep mode, the current consumption is reduced to an extremely low level, conserving battery power in portable electronics.

**Antistall Algorithm** If a stall condition occurs, the device will execute an antistall algorithm.

**Device Start-up** The start-up behavior of the device output is determined by the applied magnetic field, as specified in the Operating Characteristics table.

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## Application Information

Two typical application circuits are shown in figures 4 and 5. The first application circuit shows the device SLEEP pin controlled by the user. Figure 5 illustrates an application circuit where the device VDD and SLEEP pin are connected together.

Note that:

• No external diode is required for reverse battery protection because the protection is fully integrated into the IC.

• Thermal shutdown is integrated also.

A bypass capacitor of 0.1 µF is required between VDD and GND for proper device operation through the full specified supply voltage range.
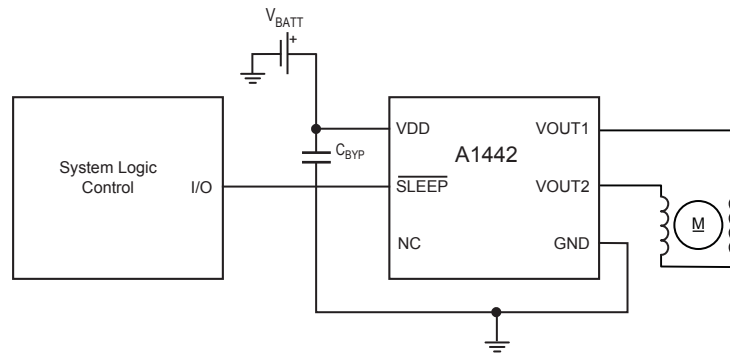


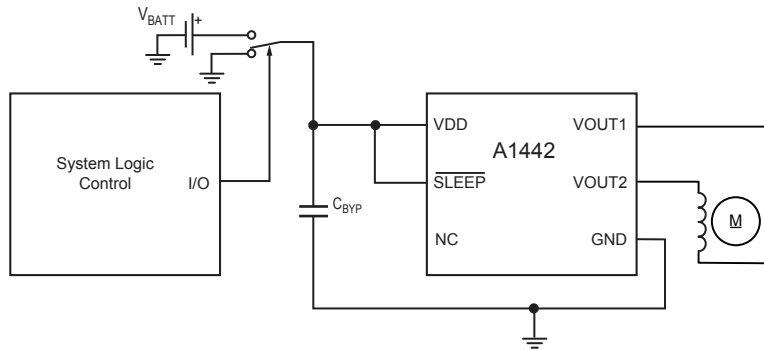Figure 4. Application circuit showing user-controlled sleep/enable mode, while the A1442 remains powered at all times



Figure 4. Application circuit showing simultaneous user control of power supply and sleep mode.

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## Power Derating

The device must be operated below the maximum junction temperature of the device, $T_J(max)$. Under certain combinations of peak conditions, reliable operation may require derating supplied power or improving the heat dissipation properties of the application. This section presents a procedure for correlating factors affecting operating $T_J$. (Thermal data is also available on the Allegro MicroSystems Web site.) The package thermal resistance, $R_{\theta JA}$, is a figure of merit summarizing the ability of the application and the device to dissipate heat from the junction (die), through all paths to the ambient air. Its primary component is the effective thermal conductivity, K, of the printed circuit board, including adjacent devices and traces. Radiation from the die through the device case, $R_{\theta JC}$, is relatively small component of $R_{\theta JA}$. Ambient air temperature, $_{TA}$, and air motion are significant external factors, damped by overmolding. The effect of varying power levels (power dissipation, $P_D$) can be estimated. The following formulas represent the fundamental relationships used to estimate $T_J$ at given levels of $P_D$.

Given:

$$P_D = V_{IN} \times I_{IN} , \tag{1}$$

$$\Delta T = P_D \times R_{\theta JA} \text{ , and} \tag{2}$$

$$T_J = T_A + \Delta T \tag{3}$$

For a load of 30 Ω, given common conditions such as: $T_A = 25°C$, $V_{DD} = 3$ V, $I_{DD} = 83$ mA, $V_L = 2.43$ V, $I_L = 81$ mA and $R_{\theta JA} = 250$ °C/W, then:

$$P_D = V_{DD} \times I_{DD} - V_L I_L$$

$$= 3 \text{ V} \times 83 \text{ mA} - 2.43 \text{ V} \times 81 \text{ mA} = 52.17 \text{ mW} ,$$

$$\Delta T = P_D \times R_{\theta JA}$$

$$= 52.17 \text{ mW} \times 250 \text{ °C/W} = 13°C \text{ , and}$$

$$T_J = T_A + \Delta T = 25°C + 13°C = 38°C$$

A worst-case estimate, $P_D(max)$, represents the maximum allowable power level, without exceeding $T_J(max)$, at a selected $R_{\theta JA}$ and $T_A$.



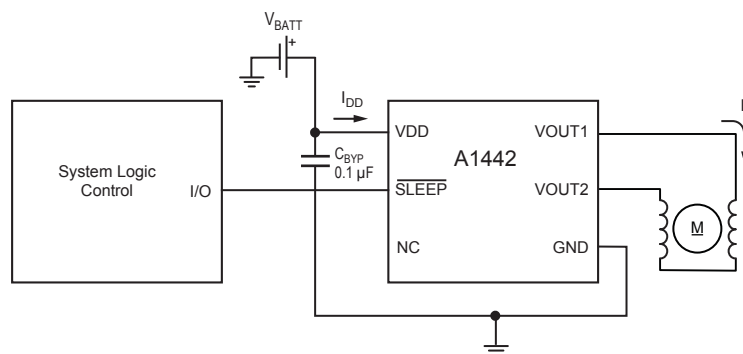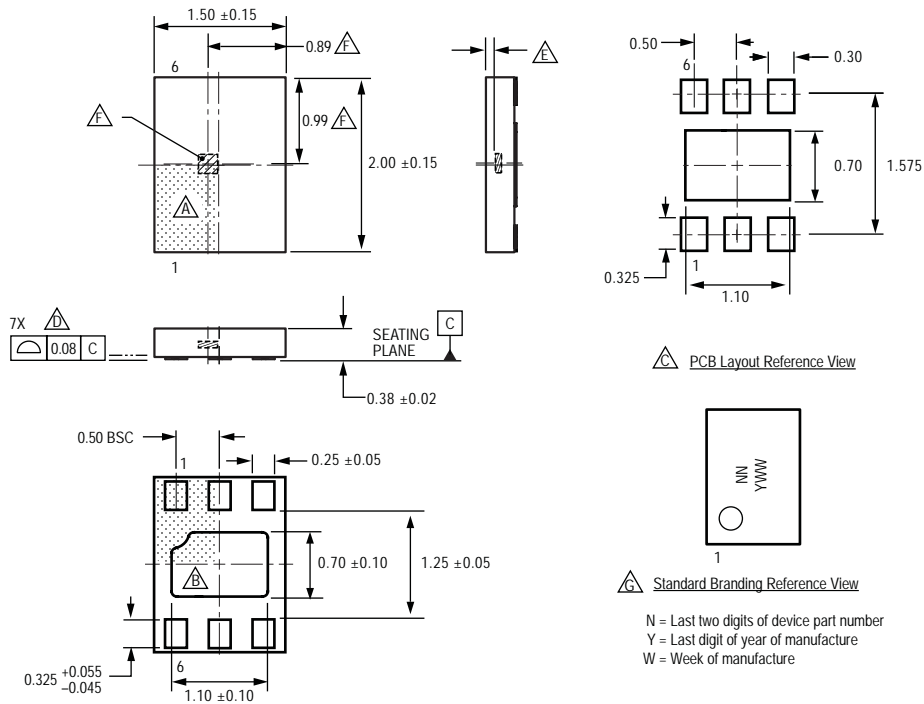Figure 4. Typical application showing current paths

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## Package EW, 6 pin MLP/DFN



For Reference Only, not for tooling use (refernce DWG-2856; similar to JEDEC Type 1, MO-229X2BCD)
Dimensions in millimeters
Exact case and lead configuration at supplier discretion within limits shown

A Terminal #1 mark area

B Exposed thermal pad (reference only, terminal #1 identifier appearance at supplier discretion)

C Reference land pattern layout (reference IPC7351 SON50P200X200X100-9M);
All pads a minimum of 0.20 mm from all adjacent pads; adjust as necessary to meet application process requirements and PCB layout tolerances; when mounting on a multilayer PCB, thermal vias at the exposed thermal pad land can improve thermal dissipation (reference EIA/JEDEC Standard JESD51-5)

D Coplanarity includes exposed thermal pad and terminals

E Active Area Depth 0.15 mm REF

F Hall Element (not to scale)

G Branding scale and appearance at supplier discretion

### PCB Layout Reference View

### Standard Branding Reference View

N = Last two digits of device part number
Y = Last digit of year of manufacture
W = Week of manufacture

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**Revision History**

| Revision | Revision Date | Description of Revision |
|----------|---------------|-------------------------|
| Rev. 2 | October 26, 2011 | Update Selection Guide |
| | | |

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