

### **DESCRIPTION**

A24C64 provides 65536 bits of serial electrically erasable and programmable read-only memory (EEPROM) organized as 4096 words of 8 bits each.

The A24C64 is optimized for use in many industrial and commercial applications where low-power and low-voltage operations are essential. The A24C64 is accessed via a two-wire serial interface.

The A24C64 is available in SOP8 and TSSOP8 packages.

### **FEATURES**

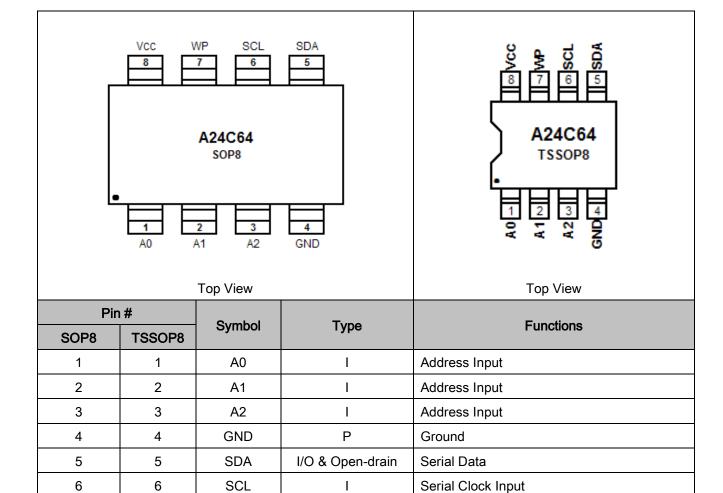
- Two-Wire Serial Interface
- V<sub>CC</sub>=1.8V To 5.5V
- Bi-Directional Data Transfer Protocol
- Internal Organized 8192 x 8 (64K bits)
- 400KHz (1.8V, 2.7V & 5V) Compatibility
- 32-byte Page Write Mode
- Partial Page Writes Allowed
- Self-Timed Write Cycle (5ms Max)
- High-Reliability
- 1 Million Write Cycles guaranteed
- Data Retention > 100 Years
- Operating Temperature: -40°C to +85°C
- Available in SOP8 and TSSOP8 Package

#### ORDERING INFORMATION

Package Type	Part Number			
		A24C64M8R		
6000	N40	A24C64M8U		
SOP8	M8	A24C64M8VR		
		A24C64M8VU		
TSSOP8	TMX8	A24C64TMX8R		
		A24C64TMX8U		
		A24C64TMX8VR		
		A24C64TMX8VU		
	R: Tape & Reel			
Note	U: Tube V: Halogen free Package			
AiT provides all RoHS products				
suffix "V" means Halogen free Package				



## PIN DESCIPTION



I

Ρ

Write ProtectNote1

Power Supply

NOTE 1 Write Protect

7

8

7

8

WP Pin Status	Part of the Array Protected		
At V <sub>CC</sub>	Full (64K) Array		
At GND	Normal Read/Write Operations		

WP

 $\mathsf{V}_{\mathsf{CC}}$ 

TWO-WIRE SERIAL 64K BITS (8192 X 8)

## **ABSOLUTE MAXIMUM RATINGS**

DC Supply Voltage	-0.3V to +6.5V
Input / Output Voltage	GND-0.3V to $V_{CC}$ +0.3V
Operating Ambient Temperature	-40°C to +85°C
Storage Temperature	-65°C to +150°C

Stresses above those listed under" Absolute Maximum Ratings" may cause permanent damage to this device. These are stress ratings only. Functional operation of this device at these or any other condition above those indicated in the operational sections of this specification is not implied or intended. Exposure to the absolute maximum rating conditions for extended periods may affect device reliability.



# **ELECTRICAL CHARACTERISTICS**

Applicable over recommended operating range from: T<sub>A</sub> = -40°C to +85°C, V<sub>CC</sub> = +1.8V to +5.5V, unless otherwise noted

Applicable over recommended operating range from: $T_A = -40^{\circ}\text{C}$ to $+65^{\circ}\text{C}$ , $V_{CC} = +1.87$ to $+5.57$ , unless otherwise note							
Parameter	Symbol Condition		Min.	Тур.	Max.	Unit	
DC ELECTRICAL CHARACTERISTICS							
Supply Voltage	Vcc		1.8	-	5.5	V	
Supply Current V <sub>CC</sub> = 5.0V	I <sub>CC1</sub>	Read at 100KHz	-	0.4	1.0	mA	
Supply Current V <sub>CC</sub> = 5.0V	I <sub>CC2</sub>	Write at 100KHz	-	2.0	3.0	mA	
Standby Current	$I_{SB}$	$V_{IN} = V_{CC}$ or GND	-	-	1.0	μΑ	
Input Leakage Current	Iμ	V <sub>IN</sub> = V <sub>CC</sub> or GND	-	-	3.0	μA	
Output Leakage Current	ILO	Vout = Vcc or GND	-	0.05	3.0	μΑ	
Input Low Level	VIL		-0.6	-	Vcc x 0.3	V	
Input High Level	ViH		Vcc x0.7	-	Vcc+0.5	V	
Output Low Level V <sub>CC</sub> = 5.0V	$V_{OL3}$	$I_{OL} = 3.0 \text{mA}$	-	-	0.4	V	
Output Low Level V <sub>CC</sub> = 3.0V	$V_{OL2}$	I <sub>OL</sub> = 2.1mA	-	-	0.4	V	
Output Low Level V <sub>CC</sub> = 1.8V	V <sub>OL1</sub>	I <sub>OL</sub> = 0.15mA	-	-	0.2	V	

Applicable over recommended operating range from:  $T_A$  = 25°C, f = 1.0MHz,  $V_{CC}$  = +1.8V

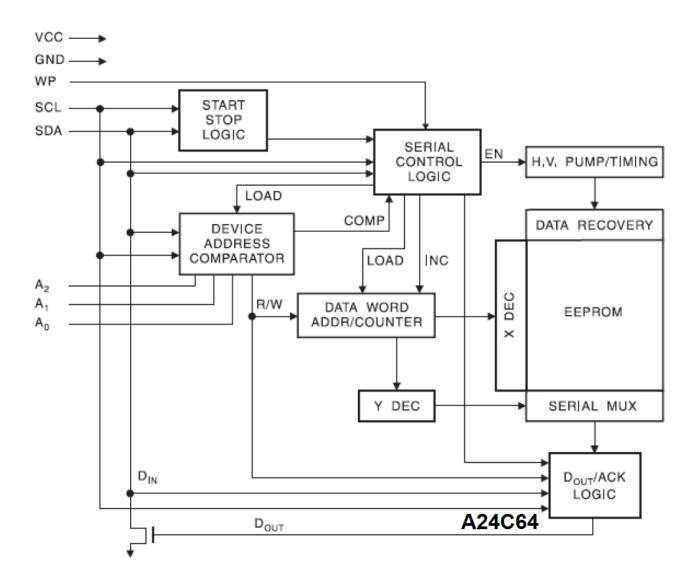
Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit
PIN CAPACITANCE						
Input / Output Capacitance (SDA)	C <sub>I/O</sub>	V <sub>I/O</sub> = 0V	-	-	8	pF
Input Capacitance (A0, A1, A2, SCL)	CIN	$V_{IN} = 0V$	-	-	6	pF

Applicable over recommended operating range from:  $T_A$  = -40°C to +85°C,  $V_{CC}$  = +1.8V to +5.5V,  $C_L$  = 1 TTL Gate and 100pF, unless otherwise noted

Donomotor	Symbol Condition	1.8, 2.7	1 1-:4					
Parameter	Symbol Condition		Min.	Max.	Unit			
AC ELECTRICAL CHARACTERISTI	AC ELECTRICAL CHARACTERISTICS							
Clock Frequency, SCL	f <sub>SCL</sub>		-	400	KHz			
Clock Pulse Width Low	tLOW		1.2	-	μs			
Clock Pulse Width High	tніgн		0.6	-	μs			
Noise Suppression Time	t <sub>i</sub>		-	50	ns			
Clock Low to Data Out Valid	taa		0.1	0.9	μs			
Time the bus must be free before a new transmission can start	t <sub>BUF</sub>		1.2	-	μs			
Start Hold Time	thd.sta		0.6	_	μs			
Start Setup Time	tsu.sta		0.6	_	μs			
Data In Hold Time	thd.dat		0	-	μs			
Data In Setup Time	t <sub>SU.DAT</sub>		100	-	ns			
Inputs Rise Time	t <sub>R</sub>		-	0.3	μs			
Inputs Fall Time	t <sub>F</sub>		-	300	ns			
Stop Setup Time	tsu.sto		0.6	-	μs			
Data Out Hold Time	tон		50	-	ns			
Write Cycle Time	twR	·	-	5	ms			
5.0V, 25°C, Byte Mode	Endurance		1M	-	Write Cycles			



# **BLOCK DIAGRAM**





### **DETAILED INFORMATION**

#### **Memory Organization**

A24C64 64K SERIAL EEPROM: The 64K is internally organized as 256 pages of 32 bytes each. Random word addressing requires a 13-bit data word address.

#### **Device Operation**

Clock and Data Transitions: The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (see Figure 1 on page10). Data changes during SCL high periods will indicate a start or stop condition as defined below.

#### START CONDITION

A high-to-low transition of SDA with SCL high is a start condition which must precede any other command (see Figure 2 on page 10).

#### **STOP CONDITION**

A low-to-high transition of SDA with SCL high is a stop condition. After a read sequence, the stop command will place the EEPROM in a standby power mode (see Figure 2 on page 10).

#### **ACKNOWLEDGE**

All addresses and data words are serially transmitted to and from the EEPROM in 8-bit words. The EEPROM sends a "0" to acknowledge that it has received each word. This happens during the ninth clock cycle.

#### STANDBY MODE

The A24C64 features a low-power standby mode which is enabled: (a) upon power-up and (b) after the receipt of the STOP bit and the completion of any internal operations.

#### **MEMORY RESET**

After an interruption in protocol, power loss or system reset, any two-wire part can be reset by following these steps:

- 1. Clock up to 9 cycles.
- 2. Look for SDA high in each cycle while SCL is high.
- 3. Create a start condition.



#### **Device Addressing**

The 64K EEPROM devices all require an 8-bit device address word following a start condition to enable the chip for a read or write operation (see Figure 4 on page 10).

The device address word consists of a mandatory "1", "0" sequence for the first four most significant bits as shown. This is common to all the Serial EEPROM devices.

The 64K uses the three device address bits A2, A1, A0 to allow as many as eight devices on the same bus. These bits must compare to their corresponding hardwired input pins. The A2, A1, and A0 pins use an internal proprietary circuit that biases them to a logic low condition if the pins are allowed to float.

The eighth bit of the device address is the read/write operation select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low.

Upon a compare of the device address, the EEPROM will output a "0". If a compare is not made, the chip will return to a standby state.

#### **NOISE PROTECTION**

Special internal circuitry placed on the SDA and SCL pins prevent small noise spikes from activating the device.

#### **DATA SECURITY**

The A24C64 has a hardware data protection scheme that allows the user to write protect the entire memory when the WP pin is at  $V_{CC}$ .

#### Write Operations

#### **BYTE WRITE**

A write operation requires an 8-bit data word address following the device address word and acknowledgment. Upon receipt of this address, the EEPROM will again respond with a "0" and then clock in the first 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will output a "0" and the addressing device, such as a microcontroller, must terminate the write sequence with a stop condition. At this time the EEPROM enters an internally timed write cycle, twR, to the nonvolatile memory. All inputs are disabled during this write cycle and the EEPROM will not respond until the write is complete (see Figure 5 on page 11).



#### **PAGE WRITE**

The 64K devices are capable of 32-byte page writes.

A page write is initiated the same as a byte write, but the microcontroller does not send a stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the microcontroller can transmit up to 31 more data words. The EEPROM will respond with a "0" after each data word received. The microcontroller must terminate the page write sequence with a stop condition (see Figure 6 on page11).

The data word address lower five (64K) bits are internally incremented following the receipt of each data word. The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than 32 data words are transmitted to the EEPROM, the data word address will "roll over" and previous data will be overwritten.

#### **ACKNOWLEDGE POLLING**

Once the internally timed write cycle has started and the EEPROM inputs are disabled, acknowledge polling can be initiated. This involves sending a start condition followed by the device address word. The read/write bit is representative of the operation desired. Only if the internal write cycle has completed will the EEPROM respond with a "0", allowing the read or write sequence to continue.

### **Read Operations**

Read operations are initiated the same way as write operations with the exception that the read/write select bit in the device address word is set to "1". There are three read operations: current address read, random address read and sequential read.

#### **CURRENT ADDRESS READ**

The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address "roll over" during read is from the last byte of the last memory page to the first byte of the first page. The address "roll over" during write is from the last byte of the cur- rent page to the first byte of the same page. Once the device address with the read/write select bit set to "1" is clocked in and acknowledged by the EEPROM, the current address data word is serially clocked out. The microcontroller does not respond with an input "0" but does generate a following stop condition (see Figure 7 on page11).



#### **RANDOM READ**

A random read requires a "dummy" byte write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the EEPROM, the microcontroller must generate another start condition. The microcontroller now initiates a current address read by sending a device address with the read/write select bit high. The EEPROM acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a "0" but does generate a following stop condition (see Figure 8 on page 12).

#### **SEQUENTIAL READ**

Sequential reads are initiated by either a current address read or a random address read. After the microcontroller receives a data word, it responds with an acknowledge. As long as the EEPROM receives an acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address limit is reached, the data word address will "roll over" and the sequential read will continue. The sequential read operation is terminated when the microcontroller does not respond with a "0" but does generate a following stop condition (see Figure 9 on page 12)

Figure 1 Data Validity

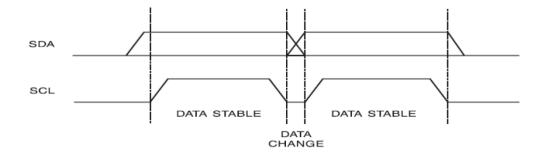


Figure 2 Start and Stop Definition

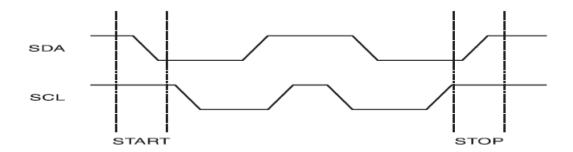


Figure 3 Output Acknowledge

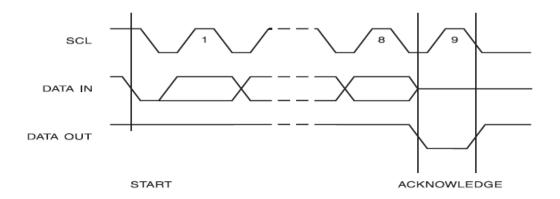


Figure 4 Device Address

1	0	1	0	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	R/W
MSB							LSB



Figure 5 Byte Write

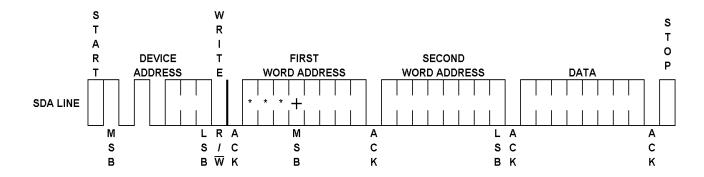


Figure 6 Page Write

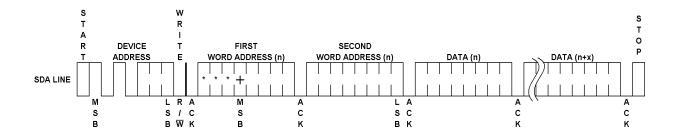


Figure 7 Current Address Read

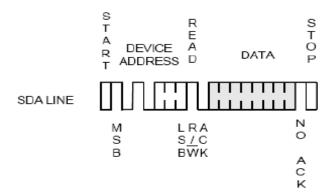


Figure 8 Random Read

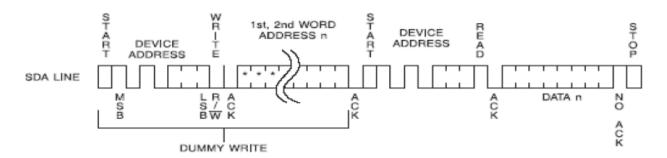
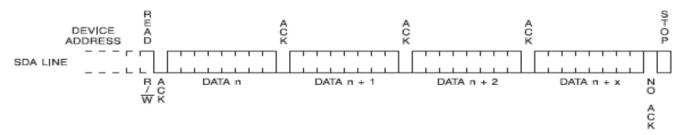
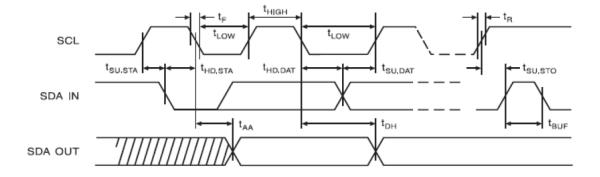


Figure 9 Sequential Read



### **BUS TIMING**

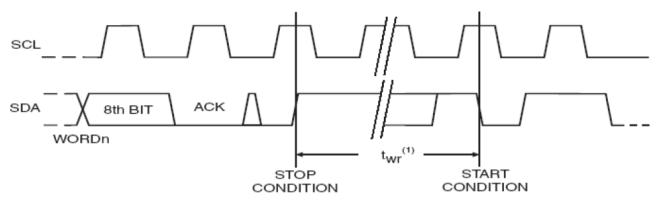
Figure 10 SCL: Serial Clock, SDA: Serial Data I/O



TWO-WIRE SERIAL 64K BITS (8192 X 8)

### WRITE CYCLE TIMING

Figure 11 SCL: Serial Clock, SDA: Serial Data I/O

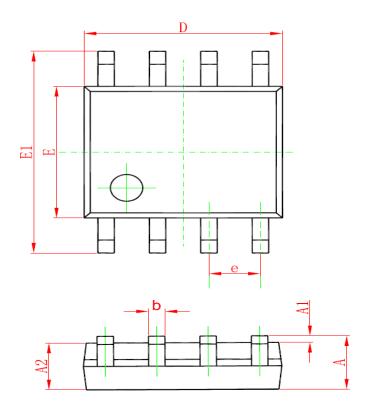


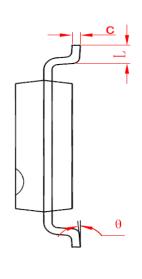
 $NOTE: The \ write \ cycle \ time \ t_{WR} \ is \ the \ time \ from \ a \ valid \ stop \ condition \ of \ a \ write \ sequence \ to \ the \ end \ of \ the \ internal \ clear/write \ cycle.$ 



# PACKAGE INFORMATION

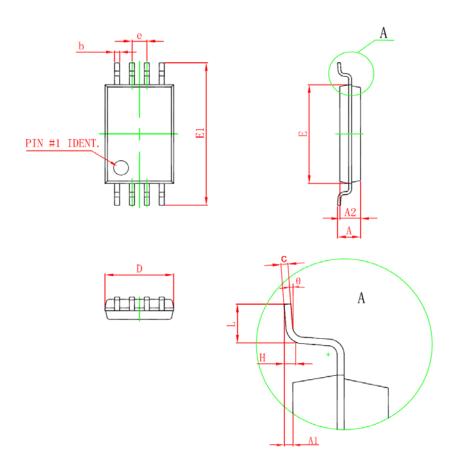
Dimension in SOP8 (Unit: mm)





Symbol	Min	Max	
Α	1.350	1.750	
A1	0.100	0.250	
A2	1.350	1.550	
b	0.330	0.510	
С	0.170	0.250	
D	4.700	5.100	
E	3.800	4.000	
E1	5.800	6.200	
е	1.270(BSC)		
L	0.400	1.270	
θ	0°	8°	

### Dimension in TSSOP8 Package (Unit: mm)



Symbol	Min	Max	
D	2.900	3.100	
Е	4.300	4.500	
b	0.190	0.300	
С	0.090	0.200	
E1	6.250	6.550	
А	-	1.100	
A2	0.800	1.000	
A1	0.020	0.150	
е	0.65 (BSC)		
L	0.500	0.700	
Н	0.25(TYP)		
θ	1°	7°	



### IMPORTANT NOTICE

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