# ACS8526 LC/P LITE

Line Card Protection Switch for PDH, SONET or SDH Systems

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## Description

The ACS8526 is a highly integrated single-chip solution for protection switching between two SECs (SDH/SONET Equipment Clocks) from Master and Slave SETS clock cards, for line cards in a PDH, SONET or SDH Network Element. The ACS8526 has fast activity monitors on the inputs and will raise a flag on a pin if there is a loss of activity on the currently selected input. The protection switching between the input reference clock sources is controlled by an external pin.

The ACS8526 has two SEC reference clock input ports, configured for expected frequency by setting hardware pins or by writing to registers via the serial interface.

The ACS8526 can perform frequency translation, converting, for example, an 8 kHz SEC input clock from a backplane into a 155.52 MHz clock for local line cards.

The ACS8526 generates two independent SEC clock outputs, one on a PECL/LVDS port and one on a TTL/CMOS port, at spot frequencies configured by hardware pins, or by writing to registers via the serial interface. The hardware selectable spot frequencies range from 1.544 MHz up to 155.52 MHz, with further options for N x E1/DS1 and 311.04 MHz via register selection. The ACS8526 also provides an 8 kHz Frame Sync output and 2 kHz Multi-Frame Sync output, both with programmable pulse width and polarity.

Advanced configuration possibilities are available via the serial port (which can be SPI compatible), however the basic configuration of I/O frequencies and SONET/SDH selection by hardware make the device suitable for standalone operation, i.e., no need for a microprocessor.

## Block Diagram

Figure 1 Block Diagram of the ACS8526 LC/P LITE

#### LOS\_ALARM IP\_FREQ **SEC Outputs** DPI I 1 DPI I 2 01 (LVDS/PECL) MUX 2 x SEC TTL inputs API I 2 02 (TTL) 2 Output Port SEC1 SEC Inputs: Input Digital Feedback equend Programmable SEC Por Selection Frequencies Sync Outputs: Selector E1/DS1 N x 8 kHz SEC2 Synthesis MFrSync 2 kHz (TTL) 1.544 MHz APLL 1 2.048 MHz 1 FrSync 8 kHz (TTL) 6.48 MHz 19 44 MHz Output Frequencies/MHz 25.92 MHz 02 Output: 01 Output: TCK 19.44 1.544 51 84 MHz Chip TDI IEEE SPI Compatible 25.92 2.048 Priority Register Set 77.76 MHz Clock 34.368 (E3) 3.088 TMS L149.1 Serial Interface Table Generator JTAG 38.88 19.44 TRST 44.736 (DS3) 25.92 TDO 51.84 34.368 (E3) 38.88 44.736 (DS3) 155.52 TCXO or OP\_FREQ1 51.84 OP FRE02

## **Features**

- Line card protection switch partners Semtech SETS devices for Stratum 3E/3/4E/4 PDH, SONET or SDH applications
- High performance DPLL/APLL solution
- Output jitter compliant to STM-1
- Two independent SEC inputs ports (TTL)
- Four independent output ports:
  - ◆ Two clock ports: one PECL/LVDS, one TTL
  - ◆ Two Syncs (TTL): 8 kHz FrSync & 2 KHz MFrSync
- ◆ TTL I/O ports: spot frequencies 2 kHz to 77.76 MHz
- ◆ PECL/LVDS port: spot frequencies 2 kHz to 311 MHz
- N x E1/DS1 mode
- Programmable pulse width and polarity on Syncs
- ◆ SONET/SDH frequency translation
- Digital Holdover mode on input failure
- Separate activity monitors and register alarms on each input.
- "Loss of activity" on selected input flagged on dedicated pin
- Source switch under external hardware control
- PLL "Locked" and "Acquisition" bandwidth selectable from 18, 35 or 70 Hz
- Configurable via serial interface or hardware pins
- Output clock phase continuity to GR-1244-CORE<sup>[13]</sup>
- ◆ Single 3.3 V operation, 5 V I/O compatible
- ◆ IEEE 1149.1 JTAG Boundary Scan is supported
- ◆ Operating temperature (ambient) of -40 to +85 °C
- Available in LQFP 64 package
- Lead (Pb)-free version available (ACS8526T), RoHS and WEEE compliant.



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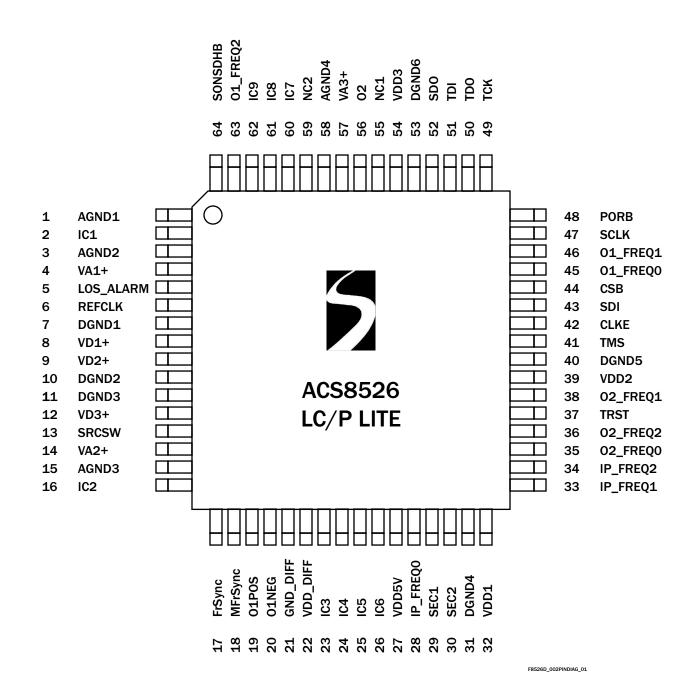


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PinwDiagramet4U.com

Figure 2 ACS8526 Pin Diagram





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## Pin Description com

### Table 1 Power Pins

Pin Number	Symbol	I/O	Туре	Description
8, 9, 12	VD1+, VD2+, VD3+	Р	-	Supply Voltage: Digital supply to gates in analog section, +3.3 Volts ±10%.
22	VDD_DIFF	Р	-	Supply Voltage: Digital supply for differential output pins 19 and 20, +3.3 Volts $\pm 10\%$ .
27	VDD5V	Р	-	Digital Supply for +5 Volts tolerance to input pins. Connect to +5 Volts (±10%) for clamping to +5 Volts. Connect to VDD for clamping to +3.3 Volts. Leave floating for no clamping, input pins tolerant up to +5.5 Volts.
32, 39, 54	VDD1, VDD2, VDD3,	Р	-	Supply Voltage: Digital supply to logic, +3.3 Volts ±10%.
4	VA1+	Р	-	Supply Voltage: Analog supply to clock multiplying PLL, +3.3 Volts ±10%.
14, 57	VA2+, VA3+	Р	-	Supply Voltage: Analog supply to output PLLs APLL2 and APLL1, +3.3 Volts ±10%.
15, 58	AGND3, AGND4		-	Supply Ground: Analog ground for output PLLs APLL2 and APLL1.
7, 10, 11	DGND1, DGND2, DGND3	Р	-	Supply Ground: Digital ground for components in PLLs.
31, 40, 53	DGND4, DGND5, DGND6	Р	-	Supply Ground: Digital ground for logic.
21	GND_DIFF	Р	-	Supply Ground: Digital ground for differential output pins 19 and 20.
1, 3	AGND1, AGND2	Р	-	Supply Ground: Analog grounds.

Note...I = Input, O = Output, P = Power,  $TTL^U = TTL$  input with pull-up resistor,  $TTL_D = TTL$  input with pull-down resistor.

## Table 2 Internally Connected

Pin Number	Symbol	I/O	Туре	Description
2, 16, 23, 24, 25, 26, 60, 61, 62	IC1, IC2, IC3, IC4, IC5, IC6, IC7, IC8 IC9	-	-	Internally Connected: Leave to float.
55, 59	NC1, NC2	-	-	Not Connected: Leave to float.

### Table 3 Other Pins

Pin Number	Symbol	I/O	Туре	Description
5	LOS_ALARM	0	TTL/CMOS	LOS_Alarm: Flag to indicate loss of activity of currently selected reference source.
6	REFCLK	I	TTL	Reference Clock: 12.800 MHz (refer to section headed Local Oscillator Clock).
13	SRCSW	I	TTL <sub>D</sub>	Source Switching: Controls switchover between SEC1 and SEC2 inputs as the selected reference. SRCSW must be held <i>High</i> on power-up or reset, and for a further 251 ms after PORB has gone <i>High</i> . See "Initialization" on page 8.
17	FrSync	0	TTL/CMOS	Output Reference: 8 kHz Frame Sync output.





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Table 3 Other Pins (cont...)

Pin Number	Symbol	I/O	Туре	Description				
18	MFrSync	0	TTL/CMOS	Output Reference: 2 kHz Multi-Frame Sync output.				
19, 20	O1POS, O1NEG	0	LVDS/PECL	Output Reference 1: Differential output., default LVDS.				
28	IP_FREQ0	I	TTL <sub>D</sub>	Input Reference Frequency Select: Frequency select for input SEC1 and SEC2.				
29	SEC1	I	TTL <sub>D</sub>	Input Reference 1: Primary input.				
30	SEC2	I	TTL <sub>D</sub>	Input Reference 2: Secondary input.				
33	IP_FREQ1	I	TTL <sub>D</sub>	Input Reference Frequency Select: Frequency select for input SEC1 and SEC2.				
34	IP_FREQ2	I	TTL <sub>D</sub>	Input Reference Frequency Select: Frequency select for input SEC1 and SEC2.				
35	02_FREQ0	I	TTL <sub>D</sub>	Output 02 Frequency Select: Frequency select for output 02.				
36	02_FREQ2	I	TTL <sub>D</sub>	Output 02 Frequency Select: Frequency select for output 02.				
37	TRST	I	TTL <sub>D</sub>	JTAG Control Reset Input: TRST = 1 to enable JTAG Boundary Scan mode. TRST = 0 for normal device operation (JTAG logic transparent). NC if not us Output O2 Frequency Select: Frequency select for output O2.				
38	02_FREQ1	ı	TTL <sub>D</sub>	Output 02 Frequency Select: Frequency select for output 02.				
41	TMS	I	TTL <sub>D</sub>	JTAG Test Mode Select: Boundary Scan enable. Sampled on rising edge of TCK. NC if not used.				
42	CLKE	I	TTL <sub>D</sub>	SCLK Edge Select: SCLK active edge select, CLKE = 1, selects falling edge of SCLK to be active.				
43	SDI	I	TTL <sub>D</sub>	Interface Address: SPI compatible Serial Data Input.				
44	CSB	I	TTL <sup>U</sup>	Chip Select (Active <i>Low</i> ): This pin is asserted <i>Low</i> by the external device (microprocessor) to enable the Serial interface.				
45	01_FREQ0	I	TTL <sup>U</sup>	Output O1 Frequency Select: Frequency select for output O1.				
46	01_FREQ1	I	TTL <sup>U</sup>	Output O1 Frequency Select: Frequency select for output O1.				
47	SCLK	I	TTL <sub>D</sub>	Serial Data Clock: The <i>Low</i> to <i>High</i> transition on this input latches the data on the SDI input into the internal registers. The active clock edge (defined by CLKE) latches the data out of the internal registers onto the SDO output.				
48	PORB	I	TTL <sup>U</sup>	Power-On Reset: Master reset. If PORB is forced Low, all internal states are reset back to default values.				
49	тск	ı	TTL <sub>D</sub>	JTAG Clock: Boundary Scan clock input.				
50	TDO	0	TTL/CMOS	JTAG Output: Serial test data output. Updated on falling edge of TCK.				
51	TDI	I	TTL <sub>D</sub>	JTAG Input: Serial test data Input. Sampled on rising edge of TCK. NC if not used.				
52	SDO	0	TTL <sub>D</sub>	Interface Address: SPI compatible Serial Data Output.				
56	02	0	TTL/CMOS	Output Reference: Programmable, default 19.44 MHz.				
63	01_FREQ2	ı	TTL <sup>U</sup>	Output O1 Frequency Select: Frequency select for output O1.				
64	SONSDHB	I	πι <sub>D</sub>	SONET or SDH frequency select: Sets the initial power-up state (or state after a PORB) of the SONET/SDH frequency selection registers, Reg. 34, Bit 2 and Reg. 38, Bit 5, Bit 6 and Reg. 64 Bit 4. The register states can be changed after power-up by software. When set <i>Low</i> , SDH rates are selected (2.048 MHz etc.) and when set <i>High</i> , SONET rates are selected (1.544 MHz etc.) The register states can be changed after power-up by software.				



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### Introduction: 4U.com

The ACS8526 is a highly integrated, single-chip solution for protection switching of two SEC inputs from, for example, Master and Slave SETS clock cards sources, for Line Cards in a SONET or SDH Network Element. The ACS8526 has fast activity monitors on the SEC clock inputs.

The ACS8526 can be used as a standalone part without the serial interface where all input and output frequencies are set by external control using the IP\_FREQ and OP\_FREQ pins. These pins determine the default power-up or reset state of internal registers, that in turn determine the I/O frequencies.

If more detailed control is required, then the registers within the device can be re-configured, after an initialization period, by writes through the serial interface. The SRCSW pin is used to select one of the two SEC inputs to lock to. The SRCSW pin must remain *High* for at least 251 ms following power-up or reset (251 ms after the PORB signal has gone *High*). SRCSW *Low* following a power-up or reset is not supported.

The ACS8526 has two SEC inputs from which it can generate independent clocks on outputs 01 and 02 with a total of 53 possible output frequencies. In addition, there are two Sync outputs; 8 kHz Frame Synchronization (FrSync) signal and a 2 kHz Multi-Frame Synchronization (MFrSync) signal.

Initially the ACS8526 generates a stable, low-noise clock signal at a frequency to the same accuracy as the external oscillator, or it can be made more accurate via software calibration to within ±0.02 ppm. The device always attempts to lock to one of its inputs (according to the value on the SRCSW pin). Once locked to a reference the accuracy of the output clock is determined directly by the accuracy of the input reference. In the absence of any input references the device simply maintains its most recent frequency in a Digital Holdover mode. However, as soon as the DPLL detects an input presence, it will attempt to lock to it and will not "qualify" it first. As soon as the DPLL detects a failure on the input, the DPLL freezes its operating frequency and raises the LOS alarm on device pin LOS ALARM.

The overall PLL loop bandwidth, damping, pull-in range and frequency accuracy are all determined by digital parameters that provide a consistent level of performance. An Analog PLL (APLL) takes the signal from the DPLL output and provides a lower jitter output. The

APLL bandwidth is set four orders of magnitude higher than the DPLL bandwidth. This ensures that the overall system performance still maintains the advantage of consistent behavior provided by the digital approach. The DPLLs are clocked by the external oscillator module (TCXO or XO) so that prior to initial lock (with no input reference) or in Digital Holdover, the frequency stability is only determined by the stability of the external oscillator module. This gives the key advantage of confining all temperature critical components to one well defined and pre-calibrated oscillator module, whose performance can be chosen to match the application. All performance parameters of the DPLLs are programmable without the need to understand detailed PLL equations. Bandwidth, damping factor and lock range can all be configured under software control.

The hardware set-up configures a subset of the registers in the register block, with the remainder adopting their default settings. If hardware set-up alone is insufficient for configuring, controlling and monitoring the device for a particular application, then access to the full set of registers for these purposes is provided by an SPI compatible serial interface port.

Each register (8-bit wide data field) is identified by and referred to by its hexadecimal address and name, e.g. Reg. 7D cnfg\_LOS\_alarm. The "Register Map" on page 30 summarizes the content of all of the registers, and each register is individually described in the subsequent Register Tables, organized in order of ascending Address (hexadecimal), in the "Register Descriptions" from page 32 onwards.

An Evaluation board and intuitive GUI-based software package is available for device introduction. This has its own documentation "ACS8526-EVB".

## **General Description**

The following description refers to the Block Diagram (Figure 1 on page 1).

## **Inputs**

The ACS8526 SETS device has two TTL/CMOS compatible SEC input ports. They are 3 V and 5 V compatible (with clamping if required by connecting the VDD5V pin). Refer to the "Electrical Specifications" on page 61 for more information on electrical compatibility.



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Input frequencies supported range from 2 kHz to 155.52 MHz. Common E1, DS1, OC-3 and sub-divisions are supported as spot frequencies that the DPLLs will directly lock to. Any input frequency, up to 100 MHz, that is a multiple of 8 kHz can also be locked to via an inbuilt programmable divider.

In addition to the SEC inputs, there are four configuration pins IP\_FREQ [2:0] and SONSDHB used to configure the input to expect a particular input frequency (same value applies to both inputs), and a control pin SRCSW for switching between SEC1 and SEC2 as the selected input reference to which the device tries to lock.

### **Preconfiguring Inputs - Expected Input Frequency**

The inputs SEC1 and SEC2 must be preconfigured to expect a particular input frequency.

The expected input frequencies can be selected from a range of spot frequencies by either:

- Hardware selection: configuring the hardware pins IP\_FREQ [2:0] and SONSDHB, which are read on reset
- Register programming: writing to the cnfg\_ref\_source\_frequency and cnfg\_input\_mode registers.

### Hardware Selection of Expected I/P Frequency

The combined pin states of IP\_FREQ [2:0] and SONSDHB represent a 4-bit word which addresses a particular frequency value as given in Table 4.

The frequency selected by the hardware configuration is always applied to both inputs on Power-up or Reset, so both will be preconfigured to expect the same frequency. If SEC1 and SEC2 are required to expect different frequencies, then these inputs must be subsequently reconfigured by programming the appropriate registers.

### Register Programming of Expected I/P Frequency

The expected input frequencies can be programmed by writing to the <code>cnfg\_ref\_source\_frequency</code> registers (Reg. 22 and 23) and <code>ip\_sonsdhb</code> (Bit 2 of <code>cnfg\_input\_mode, Reg. 34</code>), via the serial interface. This must not be done until after the end of the initialization period (see "Initialization" on page 8).

Note...Any subsequent reset will cause these registers to be overwritten by values that equate to the single hardware selected frequency on the pins at the time of reset, i.e both inputs will be configured to expect the same input frequency. After a reset and initialization period, any change of state on

IP\_FREQ [2:0] or SONSDHB will have no effect on the device configuration, as these are only read during the reset period.

The register programming approach provides a greater range of frequencies than the hardware selection method: more spot frequencies, plus frequencies derived using DivN Mode up to 100 MHz (TTL technology limit).

Table 4 Hardware Configuration for Selecting Expected Input Frequency on SEC1 and SEC2

I	P_FREQ Pin	S	SONSDHB	Input frequency
2	1	0	Pin	
0	0	0	Х	8 kHz
0	0	1	0	2.048 MHz
		_	1	1.544 MHz
0	1	0	Х	6.48 MHz
0	1	1	Х	19.44 MHz
1	0	0	Х	25.92 MHz
1	0	1	Х	38.88 MHz
1	1	0	Х	51.84 MHz
1	1	1	Х	77.76 MHz

## **Preconfiguring Inputs-SONET/SDH**

The cnfg\_input\_mode register bit ip\_sonsdhb is used to select SDH or SONET mode for the entire device and its setting affects parameters other than just the expected input frequency selection, e.g. output frequency. To set the device for use in a SONET network, set ip\_sonsdhb = 1. For SDH, set ip\_sonsdhb = 0.

## **Input Locking Frequency Modes**

Each input port has to be configured to receive the expected input frequency. To achieve this, three input locking frequency modes are provided: Direct Lock, Lock8K and DivN.

#### **Direct Lock Mode**

In Direct Lock mode, DPLL1 can lock to the selected input at the spot frequency of the input, for example 19.44 MHz performs the DPLL phase comparisons at 19.44 MHz.

In Lock8K and DivN modes an internal divider is used prior to DPLL1 to divide the input frequency before it is used for phase comparisons.



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#### Lock8K Mode

Lock8K mode automatically sets the divider parameters to divide the input frequency down to 8 kHz. Lock8K can only be used on the supported spot frequencies. See divn\_SEC1 and 2 descriptions (Bit 7 of Reg. 22 and 23, cnfg\_ref\_source\_frequency). Lock8k mode is enabled by setting the Lock8k bit (Bit 6) in the appropriate cnfg\_ref\_source\_frequency register. Using lower frequencies for phase comparisons in the DPLL results in a greater tolerance to input jitter. It is possible to choose which edge of the input reference clock to lock to, by setting 8K Edge Polarity, (Bit 2 of Reg. 03, test\_register1).

#### **DivN Mode**

In DivN mode, the divider parameters are set manually by configuration (Bit 7 of the *cnfg\_ref\_source\_frequency* register), but must be set so that the frequency after division is exactly 8 kHz.

The DivN function is defined as:

DivN = "Divide by N+ 1", i.e. it is the dividing factor used for the division of the input frequency, and has a value of (N+1) where N is an integer from 1 to 12499 inclusive.

Therefore, in DivN mode the input frequency can be divided by any integer value between 2 to 12499. Consequently, any input frequency which is a multiple of 8 kHz, between 8 kHz to 125 MHz, can be supported by using DivN mode.

Note...Both reference inputs can be set to use DivN independently of the frequency and configuration of the other input. However only one value of N is allowed, so if both inputs have DivN selected, they must be running at the same frequency.

#### **DivN Examples**

- (a) To lock to 2.000 MHz:
  - (i) Set the cnfg\_ref\_source\_frequency register to 10XX0000 (binary) to enable DivN, and set the frequency to 8 kHz - the frequency required after division. (XX = "Leaky Bucket" ID for this input).
  - (ii) To achieve 8 kHz, the 2 MHz input must be divided by 250. So, if DivN = 250 = (N + 1) then N must be set to 249. This is done by writing F9 hex (249 decimal) to the DivN register pair Reg. 46/47.
- (b) To lock to 10.000 MHz:
  - (i) The cnfg\_ref\_source\_frequency register is set to 10XX0000 (binary) to set the DivN and the

- frequency to 8 kHz, the post-division frequency. (XX = "Leaky Bucket" ID for this input).
- (ii) To achieve 8 kHz, the 10 MHz input must be divided by 1,250. So, if DivN, = 250 = (N+1) then N must be set to 1,249. This is done by writing 4E1 hex (1,249 decimal) to the DivN register pair Reg. 46/47.

## **Selection of Input SECs**

#### Initialization

Switching between inputs SEC1 and SEC2 is triggered directly from a dedicated pin (SRCSW), though for the device to operate properly, the device must first be initialized by holding the pin *High* during reset and for at least a further 251 ms after PORB has gone *High* (250 ms allowance for the internal reset to be removed plus 1 ms allowance for APLLs to start-up and become stable). A simple external circuit to set SCRSW high for the required period is shown in the "Simplified Application Schematic" on page 70. If SCRSW is held *Low* at any time during the 251 ms initialization period, this will result in incorrect device operation.

### **SEC Selection - SRCSW pin**

After the ACS8526 has been initialized (see previous "Initialization" section), then the value of SRCSW pin directly selects either SEC1 (SRCSW *High*) or SEC2 (SRCSW *Low*). The default frequency tolerance of SEC1 and SEC2 is ±80 ppm (Reg. 41 and Reg. 42) with respect to the local (calibrated) oscillator clock. These registers can be subsequently set by external software, if required.

After initialization, the output clocks are stable and the device will operate as a simple switch, with the DPLL trying to lock on to the selected reference source.

# **Output Clock Phase Continuity on Source Switchover**

A phase offset between SEC inputs will be seen as a phase shift on the output on source switchover equal to the input phase offset.

Note... The ACS8526 has no Phase Build-out function to accommodate this. If this function is required, it is available on the AS8525 LC/P device.

The rate of change of phase on the output, during the time between input switchover and the output settling to a steady state, is dependent on factors of: input frequency,



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input phase change, DPLL bandwidth, DPLL frequency limit, and phase detector capture range. The ACS8526 always complies with GR-1244-CORE<sup>[13]</sup> spec for Stratum 3 (max rate of phase change of 81 ns/1.326 ms), for input frequencies at 6.48 MHz or higher, with the default 1UI phase detector capture range.

For inputs at a lower frequency than 6.48 MHz (e.g. 8 kHz) with the DPLL frequency limit set to greater than ±30 ppm (note default is ±80 ppm), then to ensure compliance with GR-1244-CORE<sup>[13]</sup> at DPLL bandwidth settings of 18, 35 or 70 Hz, the input phase difference between the Master and Slave inputs to the line card PLL should be limited to less than 600, 330 ns or 190 ns respectively. Alternatively, the DPLL frequency range should be set <±30 ppm. A well designed system would have Master and Slave clock from the clock sync cards aligned to within a few nanoseconds. In which case a complete system using the Semtech SETS clock card parts (ACS8530, ACS8520 or ACS8510) and this line card part would be fully compliant to GR-1244-CORE<sup>[13]</sup> specifications under all conditions due to the lower frequency range and bandwidth set at the clock card end.

## **Activity Monitors**

Two types of Activity monitors are incorporated in the ACS8526:

- SEC Activity Monitors, which raise flags in Reg. 11, sts\_reference\_sources for each SEC in event of no input activity, as defined by the configuration of Leaky Bucket accumulator.
- Fast Activity Monitor (part of DPLL), which raises LOS alarm on pin LOS\_ALARM in event of two missing cycles of input activity on the selected source.

## **SEC Activity Monitors**

There is a SEC activity monitor assigned to each SEC input. Each has a programmable Leaky Bucket Accumulator which is used to determine at what point the period of inactivity is deemed sufficient to raise or clear an alarm. Each SEC has its own no activity alarm bit in Reg. 11, sts\_reference\_sources,. The monitors operate continuously such that at all times the activity status of each SEC input is known.

#### **Leaky Bucket Accumulator**

Anomalies detected by the Activity Monitor are integrated in a Leaky Bucket Accumulator. There is one Leaky Bucket

Accumulator per SEC input. The accumulators share a set of configuration parameters which can be programmed via Reg. 50 to Reg. 53. They are:

- Bucket size
- Alarm trigger (set threshold)
- Alarm clear (reset threshold)
- Leak rate (decay rate)

There are occasional anomalies that do not cause the Accumulator to cross the alarm setting threshold, but if the Bucket fills faster than it leaks it will eventually cross the alarm setting threshold and the associated SEC Input Activity Alarm bit in Reg. 11, sts\_reference\_sources, will change to 1 (Alarm active).

Each Leaky Bucket Accumulator is a digital circuit which mimics the operation of an analog integrator. If several events occur close together, each event adds to the amplitude and the alarm will be triggered quickly; if events occur over a greater time period but still sufficiently close together to overcome the decay, the alarm will be triggered eventually. If events occur at a rate which is not sufficient to overcome the decay, the alarm will not be triggered. Similarly, if no defect events occur for a sufficient time, the amplitude will decay gradually and the alarm will be cleared when the amplitude falls below the alarm clearing threshold. The ability to decay the amplitude over time allows the importance of defect events to be reduced as time passes by. This means that, in the case of isolated events, the alarm will not be set, whereas, once the alarm becomes set, it will be held on until normal operation has persisted for a suitable time (but if the operation is still erratic, the alarm will remain set). Figure 3 illustrates the behavior of the Leaky Bucket Accumulator.

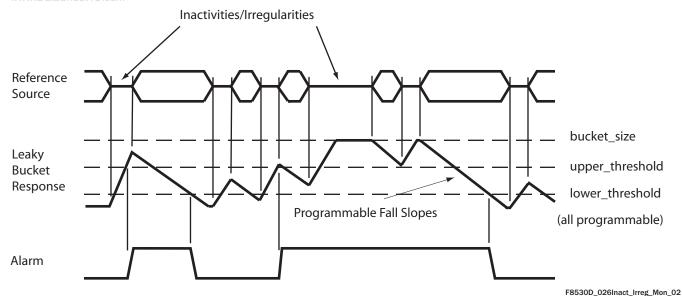
Each SEC input is monitored over a 128 ms period. If, within a 128 ms period, an irregularity occurs that is not deemed to be due to allowable jitter/wander, then the Accumulator is incremented.

The Accumulator continues to increment up to the point that it reaches the programmed Bucket size. The "fill rate" of the Leaky Bucket is, therefore, 8 units/second. The "leak rate" of the Leaky Bucket is programmable to be in multiples of the fill rate (x 1, x 0.5, x 0.25 and x 0.125) to give a programmable leak rate from 8 units/sec down to 1 unit/sec. A conflict between trying to "leak" at the same time as a "fill" is avoided by preventing a leak when a fill event occurs.

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Figure 3 Inactivity and Irregularity Monitoring



### **Leaky Bucket Timing**

The time taken (in seconds) to raise an inactivity alarm on an SEC that has previously been fully active (Leaky Bucket empty) will be:

If an input is intermittently inactive then this time can be longer. The default setting of *cnfg\_upper\_threshold* is 6, therefore the default time is 0.75 s.

The time taken (in seconds) to cancel the activity alarm on a previously completely inactive SEC is calculated, for a particular Leaky Bucket, as:

$$[2^{(a)} \times (b - c)]/8$$

where:

a = cnfg\_decay\_rate

b = cnfg bucket size

c = cnfg\_lower\_threshold

The default setting is shown in the following:

$$[2^{1} \times (8 - 4)] / 8 = 1.0 \text{ secs}$$

## **Fast Activity Monitor**

Anomalies on the selected clock have to be detected as they occur and the PLL must be temporarily isolated until the clock is once again pure. The SEC activity monitor cannot be used for this because the high degree of accuracy required dictates that the process be slow. To achieve the immediacy required, the PLL uses an alternative mechanism. The phase locked loop itself contains an additional fast activity monitor such that

within approximately two missing input clock cycles, a no-activity flag is raised and the DPLL is frozen in Digital Holdover mode. This flag generates LOS (Loss of Signal) alarm on pin LOS ALARM.

With the DPLL in Digital Holdover mode it is isolated from further disturbances. If the input becomes active again then the DPLL will continue to lock to the input, with little disturbance.

## **Phase Locked Loops (PLLs)**

This section is in four parts;

- Overview description of the PLLs
- Architectural description, introducing the sub-blocks and their interconnection options for different frequency selection and jitter filtering
- Description of PLL controls- phase error detector options, Loop bandwidth and damping selection
- DPLL summary feature list.

#### **PLL Overview**

The PLL circuitry comprises the following blocks shown in Figure 1: Two Digital PLLs (DPLL1 and DPLL2), two output multiplying and filtering Analog PLLs (APLL1 and APLL2), output frequency dividers in an Output Port Frequency Selection block, a synthesis block, multiplexers MUX1 and MUX2, and a feedback Analog PLL (APLL3).

These functional blocks, and their interconnections, are highly configurable, via register control, which provides a



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range of output frequencies and levels of jitter performance. However if the device is configured by hardware alone, then the PLLs are configured as shown in Table 7 and 8.

Digital Synthesis is used to generate all required SONET/SDH output frequencies. The digital logic operates at 204.8 MHz that is multiplied up from the external 12.800 MHz oscillator module. Hence the best resolution of the output signals from the DPLLs is one 204.8 MHz cycle or 4.9 ns.

Additional resolution and lower final output jitter is provided by a de-jittering APLL that reduces the 4.9 ns p-p jitter from the digital down to 500 ps p-p and 60 ps RMS as typical final outputs measured broadband (from 10 Hz to 1 GHz). This arrangement combines the advantages of the flexibility and repeatability of a DPLL with the low jitter of an APLL.

The DPLLs in the ACS8526 are programmable for parameters of bandwidth (18, 35 and 70 Hz) and damping factor (from 1.2 to 20). See Sections "DPLL1 Jitter Transfer Characteristic, (Freq. = 1.544 MHz, Jitter = 0.2 UI p-p, Damping Factor = 5)" on page 14, and "Damping Factor Programmability" on page 15.

DPLL1 input frequency is programmable with 12 common SONET/SDH spot frequencies. See <a href="mailto:cnfg\_nominal\_frequency">cnfg\_nominal\_frequency</a> Reg. 3C and Reg. 3D

The DPLL has programmable frequency acceptance and output range (from 0 to 80 ppm) set by the allowable offset between the expected input frequency and the calibrated external frequency, Reg. 41 and Reg. 42).

There is no requirement to understand the loop filter equations or detailed gain parameters since all high level factors such as overall bandwidth can be set directly in registers via the microprocessor interface. No external critical components are required for either the internal DPLLs or APLLs, providing another key advantage over traditional discrete designs.

DPLL1 always produces an output at 77.76 MHz to feed the APLL, regardless of the frequency selected at the output pins or the locking frequency (frequency at the input of the Phase and Frequency Detector- PFD).

DPLL2 can be operated at a number of frequencies. This is to enable the generation of extra output frequencies, which cannot be easily related to 77.76 MHz. If DPLL2 is enabled, it locks to the 8 kHz from DPLL1. This is because all of the frequencies of operation of DPLL2 can be

divided to 8 kHz and this will ensure synchronization of frequencies, from 8kHz upwards, within the two DPLLs.

Both of the DPLLs' outputs can be connected to multiplying and filtering APLLs. The outputs of these APLLs are divided making a number of frequencies simultaneously available for selection at the output clock ports. The various combinations of DPLL, APLL and divider configurations allow for generation of a comprehensive set of frequencies, as listed in Table 9, "Output Frequency Selection," on page 19.

A function is provided to synchronize the lower output frequencies when DPLL1 is locked to a high frequency reference input. The dividers that generate the 2 kHz and 8 kHz outputs are reset such that the output 2/8 kHz clocks are lined up with the input 2 kHz.

The PLL configurations required for particular output frequencies are described in "Output Frequency Selection by Hardware" on page 17, and "Output Frequency Selection by Register Programming" on page 17.

An advanced feature of the device is its ability to control the amount of jitter and wander that is tolerated on the input. This is achieved by the configuration of the Phase and Frequency detectors within the DPLLs, which determines the phase error input to the Digital Loop Filter. For basic operation, the configuration should not be changed from the default settings.

## **PLL Architecture**

Figure 4 shows the PLL arrangement in more detail. Each DPLL comprises a generic Phase and Frequency Detector (PFD) with a Digital Loop filter, together with Forward, Feedback, and Low Frequency (LF) (DPLL1 only) Digital Frequency Synthesis (DFS) blocks. The Forward DFS block represents a Digital Timed Oscillator (DTO).

The DPLL architecture for DPLL1 is more complex than that of DPLL2. See "DPLL Feature Summary" on page 16...

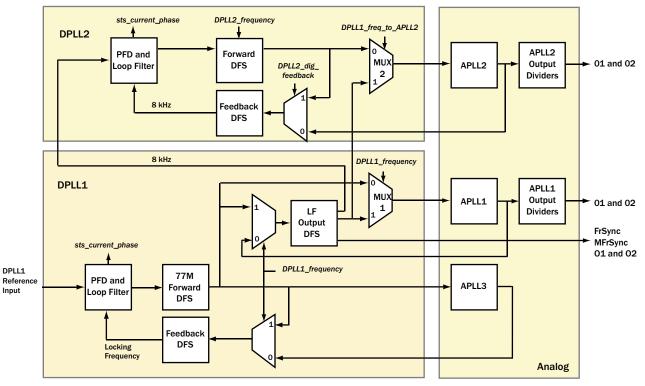
The selected SEC input is always supplied to DPLL1. DPLL1 may use either digital feedback or analog feedback (via APLL3).

DPLL2 always takes its feed from DPLL1 and cannot be used to select a different input to that of DPLL1.

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Figure 4 PLL Block Diagram



F8526D\_017BLOCKDIA\_01

DFS is a technique for generating an output frequency using a higher frequency system clock (204.8 MHz in the case of the 77.76 MHz synthesis). However, the edges of the output clock are not ideally placed in time, since all edges of the output clock will be aligned to the active edge of the system clock. This means that the generated clock will inherently have jitter on it equivalent to one period of the system clock.

#### **DPLL1 and APLLs**

DPLL1 always produces 77.76 MHz. The input reference is either passed directly to the PFD or via a pre-divider (not shown) to produce the reference input. The feedback 77.76 MHz is either divided or synthesized to generate the locking frequency.

The DPLL1 77M Forward DFS block uses DFS clocked by the 204.8 MHz system clock to synthesize the 77.76 MHz and, therefore, has an inherent 4.9 ns of p-p jitter. There is an option to use a feedback APLL (APLL3) to filter out this jitter before the 77.76 MHz is used to generate the feedback locking frequency in the DPLL1 feedback DFS block. This analog feedback option allows a lower jitter (<1 ns) feedback signal to give maximum performance.

The 77.76 MHz is fed to DPLL1 LF Output DFS block and to APLL1. The low frequency DPLL1 LF Output DFS block

is used to produce three frequencies; two of them, Digital1 and Digital2, are available for selection to be produced at outputs O1 and O2, and the third frequency can produce multiple E1/DS1 rates via the filtering APLLs. The input clock to the DPLL1 LF Output DFS block is 77.76 MHz from APLL1 (post jitter filtering) or 77.76 MHz direct from the DPLL1 77M Forward DFS.

Utilizing the clock from APLL1 will result in lower jitter outputs from the DPLL1 LF Output DFS block. However, when the input to the APLL1 is taken from the DPLL1 LF Output DFS block, the input to that block comes directly from the DPLL1 77M Forward DFS block so that a "loop" is not created.

APLL1 is for multiplying and filtering. The input to APLL1 is controlled by MUX 1 (see "Multiplexers" on page 13). The frequency from APLL1 is four times its input frequency i.e. 311.04 MHz when used with a 77.76 MHz input. APLL1 is subsequently divided by 1, 2, 4, 6, 8, 12, 16 and 48 and these are available at the O1 and O2 Outputs.

#### **DPLL2 & APLLs**

DPLL2 is simpler than DPLL1. DPLL2 offers no low frequency output. The DPLL2 input can only be used to lock to DPLL1. Unlike DPLL1, the DPLL2 Forward DFS block does not always generate 77.76 MHz. The possible



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frequencies are listed in Table 12, "APLL2 Frequencies," on page 24. Similarly to DPLL1, the output of the DPLL2 Forward DFS block is generated using DFS clocked by the 204.8 MHz system clock and will have an inherent jitter of 4.9 ns.

The DPLL2 feedback DFS also has the facility to be able to use the post APLL2 (jitter-filtered) clock to generate the feedback locking frequency. Again, this will give the maximum performance by using a low jitter feedback.

APLL2 block is also for multiplying and filtering. The input to APLL2 is controlled by MUX 2 (see "Multiplexers" on page 13) and can come either from the DPLL2 Forward DFS block or from DPLL1.

The frequency generated from the APLL2 is four times its input frequency i.e. 311.04 MHz when used with a 77.76 MHz input. APLL2 is subsequently divided by 2, 4, 8, 12, 16, 48 and 64 and these are available at the O1 and O2 Outputs.

#### "Digital" Frequencies

DFS is also carried out by DPLL1 LF Output DFS block in Figure 4 (E1/DS1 Synthesis block in Figure 1). This block is clocked either by the DPLL1 77M Forward DFS block or via the APLL1, and generates the single frequencies Digital1 and Digital2 (see Table 13 and Table 14). The input clock frequency of the DFS is always 77.76 MHz and as such has a period of approximately 12 ns. The jitter generated on the Digital outputs is relatively high, because they do not pass through an APLL for jitter filtering. The minimum level of jitter is when DPLL1 is in analog feedback mode, when the p-p jitter will be approximately 13 ns (equivalent to a period of the DFS clock). The maximum jitter is generated when in digital feedback mode, when the total is approximately 18 ns.

The E1/DS1 Synthesis block generates the E1/DS1 rates for the APLLs, using the output from DPLL1. It generates 12E1, 16E1, 16DS1 or 24DS1, for selection by MUX1.

#### FrSync, MFrSync, 2 kHz and 8 kHz Clock Outputs

Whilst the FrSync and MFrSync Outputs are always supplied from DPLL1, the 2 kHz and 8 kHz options available from the O1 and O2 Outputs can be supplied from either DPLL1 or DPLL2 (Reg. 7A Bit 7).

### **Multiplexers**

Multiplexers MUX1 and MUX2 are used to select the appropriate inputs to the Analog PLLs. The function they

represent is controlled by *cnfg\_DPLL1\_frequency* Reg. 65.

#### **APLL2 Input Selection using MUX 2**

- DPLL2 selected for input to APLL2 (Reg. 65 Bit 6 = 0)
   The input frequency is selected from the operating frequency of DPLL2 (Reg. 64 Bits [2:0])
- DPLL1 + LF Output DFS selected for Input to APLL2
  - 12E1 (Reg. 65 Bit 6 = 1 and Bits [5:4] set to 00)
  - 16E1 (Reg. 65 Bit 6 = 1 and Bits [5:4] set to 01)
  - 24DS1 (Reg. 65 Bit 6 = 1 and Bits [5:4] set to 10)
  - 16DS1 (Reg. 65 Bit 6 = 1 and Bits [5:4] set to 11)

#### **APLL1 Input Selection using MUX 1**

- DPLL1 (77.76 MHz) output fed to input of APLL1.
   Analog feedback used in DPLL1 (Reg. 65 Bits [2:0] set to 000)
- DPLL1 (77.76 MHz) output fed to input of APLL1.
   Digital feedback used in DPLL1 (Reg. 65 Bits [2:0] set to 001)
- DPLL1 + LF Output DFS selected for input to APLL1
  - 12E1 (Reg. 65 Bits [2:0] set to 010)
  - 16E1 (Reg. 65 Bits [2:0] set to 011)
  - 24DS1 (Reg. 65 Bits [2:0] set to 100)
  - 16DS1 (Reg. 65 Bits [2:0] set to 101)

Notes: (i) DPLL2 output cannot be selected for input to APLL1

(ii) If both multiplexers select LF Output DFS, the same frequency value must be selected in Reg. 65 Bits [2:0] and Reg. 65 Bits [5:4].

#### **APLLs**

There are three main APLLs. APLL1 and APLL2 provide a lower final output jitter reducing the 4.9 ns p-p jitter from the digital down to 500 ps p-p and 60 ps RMS as typical final outputs measured broadband (from 10 Hz to 1 GHz). The feedback APLL (APLL3) is selected by default; it provides improved performance over the digital feedback.

#### **APLL Output Dividers**

Each APLL has its own divider. Each divider simultaneously outputs a series of fixed ratios of its APLL input. Any of these divided outputs may be selected as the output on Outputs O1 or O2 by configuring Reg. 61 and Reg. 62, with the following exceptions: (APLL1)/2 and (APLL1)/1 only available for Output O1 (differential port), and (APLL1)/48 only available for Output O2.



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### PFD and Loop Filters

The PFD compares the input reference with that of the locking frequency (feedback) giving a phase error which is then filtered by a 100Hz low pass filter, to give the average phase error for input into a loop filter. The PFD is quite complex and has several programmable options to determine what phase error value is fed to the loop (See "Phase and Frequency Detectors" on page 15.") depending on the type of jitter/wander expected.

The loop filter bandwidth and damping is programmable to optimize the locking time/ability to track the input. See Figure 5 and "Damping Factor Programmability" on page 15.

## **PLL Operational Controls**

The main factors controlling the operation of the PLL are:

- 1. Input reference and feedback frequency selection See "PLL Architecture" on page 11., and "Input Locking Frequency Modes" on page 7.
- 2. Loop Bandwidth and Damping factor of the DPLLs these determine how fast the device can to lock to the selected input, or how tightly it can track the input.

3. PFD settings - these affect the input phase error to the Loop filter and relate to jitter and wander tolerance - See "Phase/Frequency/Lock Detection" on page 15.

DPLL1 initially tries to lock to the input frequency of the selected input SEC. By default, it uses a wide "acquisition" bandwidth setting until it has achieved frequency lock, then DPLL1 switches to using a narrower "Locked" bandwidth setting as it locks to the phase of the input.

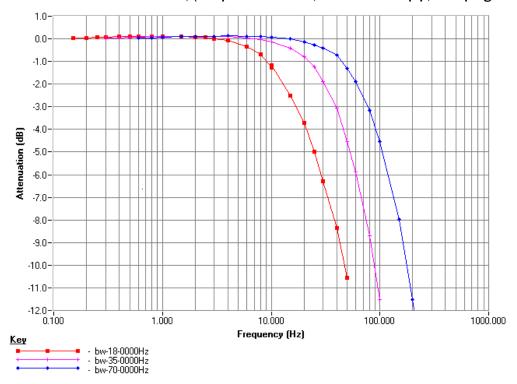
### **Input Acquisition Bandwidth**

DPLL1 has programmable acquisition bandwidth of 18, 35 or 70 Hz. The default is set to 70 Hz.

#### **Input Locked Bandwidth**

The ACS8526 has programmable "Locked" bandwidth of 18, 35 or 70 Hz. These bandwidth settings correspond to the -3 dB jitter attenuation point on the ACS8526's jitter transfer characteristic shown in Figure 5. If the ACS8526 is used with only DPLL1, the highest bandwidth setting is recommended to ensure the closest tracking of the input SEC. If DPLL2 is also to be used, DPLL1 should be set to a lower bandwidth setting than DPLL2. The lowest bandwidth setting will provide the highest jitter attenuation, although this is not the main function of the ACS8526 device.

Figure 5 DPLL1 Jitter Transfer Characteristic, (Freq. = 1.544 MHz, Jitter = 0.2 UI p-p, Damping Factor = 5)





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### Damping Factor Programmability

The DPLL damping factor is set by default to provide a maximum wander gain peak of around 0.1 dB. Many of the specifications (e.g. GR-1244-CORE <sup>[13]</sup>, G.812<sup>[7]</sup> and G.813<sup>[8]</sup>) specify a wander transfer gain of less than 0.2 dB. GR-253<sup>[11]</sup> specifies jitter (not wander) transfer of less than 0.1 dB. To accommodate the required levels of transfer gain, the ACS8526 provides a choice of damping factors, with more choice given as the bandwidth setting increases into the frequency regions classified as jitter. Table 5 shows which damping factors are available for selection at the different bandwidth settings, and the corresponding jitter transfer approximate gain peak.

Table 5 Available Damping Factors for different DPLL Bandwidths, and Associated Gain Peak Values

Bandwidth/Hz	Reg. 6B [2:0]	Damping Factor selected	Gain Peak/dB
18	1	1.2	0.4
	2	2.5	0.2
	3, 4, 5	5	0.1
35	1	1.2	0.4
	2	2.5	0.2
	3	5	0.1
	4, 5	10	0.06
70	1	1.2	0.4
	2	2.5	0.2
	3	5	0.1
	4	10	0.06
	5	20	0.03

#### Phase/Frequency/Lock Detection

Two main types of detector are available in the ACS8526:

- Phase and frequency detectors, and
- Phase Loss/Lock detectors.

#### **Phase and Frequency Detectors**

There are two multi-phase and frequency detectors, one for each DPLL. The multi-phase and frequency detectors are used to compare input and feedback clocks. They operate at input frequencies up to 77.76 MHz (155.52 MHz is internally divided down to 77.76 MHz).

A common arrangement however is to use Lock8k mode (See Bit 6 of Reg. 22 and 23), where all input frequencies are divided down to 8 kHz internally. Marginally better MTIE figures may be possible in direct lock mode due to more regular phase updates. This direct locking capability is one of the unique features of the ACS8526.

A multi-phase detector (patent pending) approach is used in order to give an infinitesimally small input phase resolution combined with large jitter tolerance. A multi-phase detector comprises the following phase detectors:

- Phase and frequency detector (±360°, or ±180° range).
- An Early/Late phase detector for fine resolution.
- A multi-cycle phase detector for large input jitter tolerance (up to 8191 UI), which captures and remembers phase differences of many cycles between input and feedback clocks.

The phase detectors can be configured to be immune to occasional missing input clock pulses by using nearest edge detection ( $\pm 180\,^\circ$  capture) or the normal  $\pm 360\,^\circ$  phase capture range which gives frequency locking. The device will automatically switch to nearest edge locking when the multi-UI phase detector is not enabled, and the other phase detectors have detected that phase lock has been achieved. It is possible to disable the selection of nearest edge locking via Reg. 03 Bit 6 (set to 1). In this setting, frequency locking will always be enabled.

The balance between the first two types of phase detector employed can be adjusted via Reg. 6A to 6D. The default settings should be sufficient for all modes. Adjustment of these settings affects only small signal overshoot and bandwidth.

The multi-cycle phase detector (wide-range) is enabled via Reg. 74, Bit 6 set to 1 and the range is set in exponentially increasing steps from ±1 UI up to 8191 UI via Reg. 74, Bits [3:0].

When this detector is enabled it keeps a track of the correct phase position over many cycles of phase difference to give excellent jitter tolerance. This provides an alternative to switching to Lock8k mode as a method of achieving high jitter tolerance.

An additional control (Reg. 74 Bit 5) enables the multi-phase detector value to be used in the final phase value as part of the DPLL loop. When enabled by setting *High*, the multi cycle phase value will be used in the loop and gives faster pull-in (but more overshoot).



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The characteristics of the loop will be similar to Lock8k mode where again large input phase differences contribute to the loop dynamics. Setting the bit *Low* only uses a max figure of 360° in the loop and will give slower pull-in but gives less overshoot. The final phase position that the loop has to pull in to is still tracked and remembered by the multi-cycle phase detector in either case.

#### **Phase Lock/Loss Detectors**

Phase lock/loss detection is handled in several ways. Phase loss can be triggered from:

- The fine phase lock detector, which measures the phase between input and feedback clock
- The coarse phase lock detector, which monitors whole cycle slips
- Detection that the DPLL is at min. or max. frequency
- Detection of no activity on the input.

Each of these sources of phase loss indication is individually enabled via registers bits (see Reg. 73 and 74). Phase lock or loss is used to determine whether to switch to nearest edge locking and whether to use acquisition or normal bandwidth settings for the DPLL. Acquisition bandwidth is used for faster pull-in from an unlocked state.

The coarse phase lock detector detects phase differences of n cycles between input and feedback clocks, where n is set by Reg. 74, Bits [3:0]; the same register that is used for the coarse phase detector range, since these functions go hand in hand. This detector may be used in the case where it is required that a phase loss indication is not given for reasonable amounts of input jitter and so the fine phase loss detector is disabled and the coarse detector is used instead.

### **DPLL Feature Summary**

(\* = hardware default selection)

#### **DPLL1 Main Features**

- Multiple E1 and DS1 outputs supported
- Low jitter MFrSync (2 kHz) and FrSync (8 kHz) outputs
- Multiple phase loss and multiple phase detectors (see "DPLL1 Advanced Features")
- Direct PLL locking to common SONET/SDH input frequencies or any multiple of 8 kHz
- Fast detection on input failure and entry into Digital Holdover mode (holds at the current frequency value)

- Frequency translation between input and output rates via direct digital synthesis
- High accuracy digital architecture for stable PLL dynamics combined with an APLL for low jitter final output clocks
- Selectable Automatic DPLL bandwidth control (auto\* selects either Locked bandwidth, or Acquisition bandwidth), or Locked DPLL bandwidth (Reg. 3B Bit 7)
- Two programmable bandwidth controls:
  - Locked bandwidth: 18, 35\* or 70 Hz (Reg. 67)
  - Acquisition bandwidth: 18, 35 or 70\* Hz (Reg. 69)
- Programmable damping factor, (For optional faster locking and peaking control) Factors = 1.2, 2.5, 5, 10\* or 20 (Reg. 6B, Bits [2:0])
- Programmable DPLL pull-in frequency range (Reg. 41, Reg. 42).

#### **DPLL1 Advanced Features**

#### **Phase Loss Indicators**

- Phase loss fine limit. on\*/off (Reg. 73 Bit 7) and programmable range 0 to 7 Dec. (Reg. 73 Bits [2:0])
- Multi-cycle phase loss course limit, on\*/off (Reg. 74 Bit 7) and selectable range from ±(1 to 8191) UI in 13 steps (Reg. 74 Bits [3:0]).

#### **Phase Detector Controls**

- Multi-cycle phase detector Course phase detector & capture range on\*/off (Reg. 74 Bit 6) and selectable range from ±(1 to 8191) UI in 13 steps (Reg. 74 Bits [3:0]). If selected, this feature increases jitter and wander tolerance to a maximum of 8192 UI (normally limited to ±0.5 UI)
- Use of coarse phase detector result in DPLL algorithm, on\*/off (Reg. 74 Bit 5) - speeds up phase locking
- Limit DPLL1 Integral when at DPLL frequency limit, on\*/off (Reg. 3B Bit 3) - reduces overshoot
- Anti-noise filter for low frequency inputs, on/off\* (Reg. 76 Bit 7).

#### **Advanced Phase Detector Controls**

 DPLL1 PD2 gain enable, on\*/off (Reg. 6D Bit 7)

If on, this allows automatic gain selection according to the type of feedback to the DPLL (For the digital feedback setting, the gain used for PD2 is given by Reg. 6D Bits [2:0]). If off, PD2 is not used.



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- Adjustable gain settings for PD2 (when enabled), for the following feedback cases:
  - Digital feedback (Reg. 6D Bits [2:0])
  - Analog feedback (all frequencies above 8 kHz) (Reg. 6D Bits [6:4])
  - Analog 8k (or less) feedback (Reg. 6B Bits [2:0]).

#### **DPLL2 Main Features**

- Always locked to DPLL1
- A single programmable bandwidth control: 18\*, 35 or 70 Hz
- Programmable damping factor, (For optional faster locking and peaking control) Factors = 1.2, 2.5, 5\*, 10 or 20.
- Digital feedback, on\*/off (Reg. 35 Bit 6)
- Output frequency selection (Reg. 64)
  - DS3/E3 support (44.736 MHz / 34.368 MHz) independent of rates from DPLL1
  - Low jitter E1/DS1 options independent of rates from DPLL1
  - Frequencies of n x E1/DS1 including 16 and 12 x E1, and 16 and 24 x DS1 supported
  - · Squelched (clock off)
- Can provide the source for the 2 kHz and 8 kHz outputs available at Outputs 01 and 02 (Reg. 7A Bit 7).

#### **DPLL2 Advanced Features**

The advanced features are the same as those for DPLL1, with DPLL2 using the configuration values for DPLL1, with the following exceptions:

#### **Advanced Phase Detector Controls**

- PD2 gain control enable, on\*/off (Reg. 6C Bit 7)
  If on, this allows automatic gain selection according to
  the type of feedback to the DPLL (For the digital
  feedback setting, the gain used for PD2 is given by
  (Reg. 6C Bits [2:0]). If off, PD2 is not used
- Adjustable gain settings for PD2 (with auto switching enabled), for the following feedback cases:
  - Digital feedback (Reg. 6C Bits [2:0])
  - Analog feedback (all frequencies above 8K) (Reg. 6C Bits [6:4])
  - Analog 8k (or less) feedback (Reg. 6A Bits [2:0]).

## **Outputs**

The ACS8526 delivers four output signals on the following ports: Two clocks, one each on Output O1 and O2, and two Sync signals, one each on output ports FrSync and MFrSync. Outputs O1 and O2 are independent of each other and are individually selectable. Output O1 is a differential port (pins O1POS and O1NEG), and can be selected to be PECL or LVDS via Reg. 3A cnfg\_differential\_output. Output O2 (pin O2) and the Sync outputs are TTL/CMOS compatible.

The two Sync outputs, FrSync (8 kHz) and MFrSync (2 kHz), are derived from DPLL1.

The frequencies available on the outputs can be selected from a range of spot frequencies by either:

- Hardware selection: configuring the hardware pins OP\_FREQ1 [2:0], OP\_FREQ2[2:0] and SONSDH, which are read on reset, or
- Register programming: writing to the registers after the end of the initialization period.

## **Output Frequency Selection by Hardware**

Tables 6 and 7 show the hardware settings for selecting particular output frequencies on Outputs 01 and 02. Note that the hardware frequency selection method provides only a subset (11) of the total number of frequencies (55) available when selecting by register programming.

# **Output Frequency Selection by Register Programming**

The output frequencies on O1 and O2 are controlled by a number of interdependent parameters (refer to "PLL Architecture" on page 11). The frequencies of the output clocks are selectable from a range of pre-defined spot frequencies/port technologies, as defined in Table 8.

### **Outputs 01 & 02 Frequency Configuration Steps**

The output frequency selection is performed in the following steps:

- 1. Refer to Table 10, Frequency Divider Look-up, to choose a set of output frequencies.
- 2. Refer to the Table 10 to determine the required APLL frequency to support the frequency set.
- 3. Refer to Table 11, APLL1 Frequencies, and Table 12, APLL2 Frequencies, to determine in what mode DPLL1 and DPLL2 need to be configured, considering the output jitter level.



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4. Refer to Table 13, O1 and O2 Output Frequency Selection, and the column headings in Table 10, Frequency Divider Look-up, to select the appropriate frequency from either of the APLLs on each output as required.

Table 6 Output 01 Frequency Selection by Hardware Configuration

	O1_FREQ		SONSDHB	Output	DPLL Selected	DPLL Mode	Jitter Le	evel (typ)
2	1	0	Pin	Frequency/ MHz			rms (ps)	p-p (ns)
0	0	0	Х	0	-	-	-	-
0	0	1	0	34.368	DPLL2	E3	120	1
	0	Τ	1	44.736	DPLL2	DS3	110	1
0	1	0	Х	19.44	DPLL1	Analog feedback	60	0.6
0	1	1	Х	25.92	DPLL1	Analog feedback	60	0.6
1	0	0	Х	38.88	DPLL1	Analog feedback	60	0.6
1	0	1	Х	51.84	DPLL1	Analog feedback	60	0.6
1	1	0	Х	77.76	DPLL1	Analog feedback	60	0.6
1	1	1	Х	155.52	DPLL1	Analog feedback	60	0.6

Table 7 Output 02 Frequency Selection by Hardware Configuration

	02_FREQ		SONSDHB	O1_FREQ	Output	DPLL Selected	DPLL Mode	Jitter Le	vel (typ)
2	1	0	Pin	"001"	Frequency/ MHz			rms (ps)	p-p (ns)
0	0	0	Х	X	0	-	-	-	-
0	0	1	0	FALSE	2.048	DPLL2	16E1	400	2
			1	TALSE	1.544	DPLL2	16DS1	200	1.2
0	0	1	0	TRUE	2.048	DPLL1	12E1	900	0.45
		_	1	TIVOL	3.088	DPLL1	24DS1	110	0.75
0	1	0	0	Х	34.368	DPLL2	E3	120	1
		, , , , , , , , , , , , , , , , , , ,	1	Х	44.736	DPLL2	DS3	110	1
0	1	1	Х	Х	19.44	DPLL1	Analog feedback	60	0.6
1	0	0	Х	Х	25.92	DPLL1	Analog feedback	60	0.6
1	0	1	Х	Х	38.88	DPLL1	Analog feedback	60	0.6
1	1	0	Х	Х	51.84	DPLL1	Analog feedback	60	0.6
1	1	1	Х	Х	77.76	DPLL1	Analog feedback	60	0.6



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## Table 8 Output Reference Source Selection Table

Port Name	Output Port Technology	Frequencies Supported
Output 01	LVDS/PECL (LVDS default)	Frequency selection as per Table 9 and Table 13
Output 02	TTL/CMOS	Trequency selection as per rable 3 and rable 13
FrSync	TTL/CMOS	FrSync, 8 kHz programmable pulse width and polarity, see Reg. 7A.
MFrSync	TTL/CMOS	MFrSync, 2 kHz programmable pulse width and polarity, see Reg. 7A.

Note...1.544 MHz/2.048 MHz are shown for SONET/SDH respectively. Pin SONSDHB controls default. When High, SONET is default.

### **Table 9 Output Frequency Selection**

Frequency (MHz, unless stated otherwise)		DPLL1 Mode	DPLL2 Mode	APLL2 Input Mux	Jitter Level (typ)		
					rms (ps)	p-p (ns)	
2 kHz		77.76 MHz Analog	-	-	60	0.6	
2 kHz		Any digital feedback mode	-	-	1400	5	
8 kHz		77.76 MHz Analog	-	-	60	0.6	
8 kHz		Any digital feedback mode	-	-	1400	5	
1.536		-	12E1 mode	Select DPLL2	500	2.3	
1.536		-	-	Select DPLL1 12E1	250	1.5	
1.544		-	16DS1 mode	Select DPLL2	200	1.2	
1.544		-	-	Select DPLL1 16DS1	150	1.0	
1.544	via Digital1 or Digital2 (not Output O1)	77.76 MHz Analog	-	-	3800	13	
1.544	via Digital1 or Digital2 (not Output O1)	Any digital feedback mode	-	-	3800	18	
2.048		-	12E1 mode	Select DPLL2	500	2.3	
2.048		-	-	Select DPLL1 12E1	250	1.5	
2.048		-	16E1 mode	Select DPLL2	400	2.0	
2.048		-	-	Select DPLL1 16E1	220	1.2	
2.048	(not Output O1)	12E1 mode	-	-	900	4.5	
2.048	via Digital1 or Digital2 (not Output 01)	77.76 MHz Analog	-	-	3800	13	
2.048	via Digital1 or Digital2 (not Output O1)	Any digital feedback mode	-	-	3800	18	
2.059		-	16DS1 mode	Select DPLL2	200	1.2	
2.059		-	-	Select DPLL1 16DS1	150	1.0	





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Table 9 Output Frequency Selection (cont...)

Frequency (MHz, unless stated otherwise)		DPLL1 Mode	DPLL2 Mode	APLL2 Input Mux	Jitter Level (typ)		
					rms (ps)	p-p (ns)	
2.059	(not Output O1)	16DS1 mode	-	-	760	2.6	
2.316		-	24DS1 mode	Select DPLL2	110	0.75	
2.316		-	-	Select DPLL1 24DS1	110	0.75	
2.731		-	16E1 mode	Select DPLL2	400	1.5	
2.731		-	-	Select DPLL1 16E1	220	1.2	
2.731	(not Output O1)	16E1 mode	-	-	250	1.6	
2.796		-	DS3 mode	Select DPLL2	110	1.0	
3.088		-	24DS1 mode	Select DPLL2	110	0.75	
3.088		-	-	Select DPLL1 24DS1	110	0.75	
3.088	(not Output O1)	24DS1 mode	-	-	110	0.75	
3.088	via Digital1 or Digital2 (not Output 01)	77.76 MHz Analog	-	-	3800	13	
3.088	via Digital1 or Digital2 (not Output 01)	Any digital feedback mode	-	-	3800	18	
3.728		-	DS3 mode	Select DPLL2	110	1.0	
4.096	via Digital1 or Digital2 (not Output 01)	77.76 MHz Analog	-	-	3800	13	
4.096	via Digital1 or Digital2 (not Output 01)	Any digital feedback mode	-	-	3800	18	
4.296		-	E3 mode	Select DPLL2	120	1.0	
4.86		-	77.76 MHz mode	Select DPLL2	60	0.6	
5.728		-	E3 mode	Select DPLL2	120	1.0	
6.144		12E1 mode	-	-	900	4.5	
6.144		-	12E1 mode	Select DPLL2	500	2.3	
6.144		-	-	Select DPLL1 12E1	250	1.5	
6.176		16DS1 mode	-	-	760	2.6	
6.176		-	16DS1 mode	Select DPLL2	200	1.2	
6.176		-	-	Select DPLL1 16DS1	150	1.0	
6.176	via Digital1 or Digital2 (not Output 01)	77.76 MHz Analog	-	-	3800	13	
6.176	via Digital1 or Digital2 (not Output 01)	Any digital feedback mode	-	-	3800	18	
6.48		-	77.76 MHz mode	Select DPLL2	60	0.6	
6.48	(not Output O1)	77.76 MHz analog	-	-	60	0.6	
6.48	(not Output O1)	77.76 MHz digital	-	-	60	0.6	





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Table 9 Output Frequency Selection (cont...)

Frequency (MHz, unless stated otherwise)	DPLL1 Mode	DPLL2 Mode	APLL2 Input Mux	Jitter Level (typ)		
				rms (ps)	p-p (ns)	
8.192	12E1 mode	-	-	900	4.5	
8.192	16E1 mode	-	-	250	1.6	
8.192	-	16E1 mode	Select DPLL2	400	2.0	
8.192	-	-	Select DPLL1 16E1	220	1.2	
8.192 via Digital1 or Digital2 (not Output O1)	77.76 MHz Analog	-	-	3800	13	
8.192 via Digital1 or Digital2 (not Output 01)	Any digital feedback mode	-	-	3800	18	
8.235	16DS1 mode	-	-	760	2.6	
9.264	24DS1 mode	-	-	110	0.75	
9.264	-	24DS1 mode	Select DPLL2	110	0.75	
9.264	-	-	Select DPLL1 24DS1	110	0.75	
10.923	16E1 mode	-	-	250	1.6	
11.184	-	DS3 mode	Select DPLL2	110	1.0	
12.288	12E1 mode	-	-	900	4.5	
12.288	-	12E1 mode	Select DPLL2	500	2.3	
12.288	-	-	Select DPLL1 12E1	250	1.5	
12.352	24DS1 mode	-	-	110	0.75	
12.352	16DS1 mode	-	-	760	2.6	
12.352	-	16DS1 mode	Select DPLL2	200	1.2	
12.352	-	-	Select DPLL1 16DS1	150	1.0	
12.352 via Digital1 or Digital2 (not Output 01)	77.76 MHz Analog	-	-	3800	13	
12.352 via Digital1 or Digital2 (not Output 01)	Any digital feedback mode	-	-	3800	18	
16.384	12E1 mode	-	-	900	4.5	
16.384	16E1 mode	-	-	250	1.6	
16.384	-	16E1 mode	Select DPLL2	400	2.0	
16.384	-	-	Select DPLL1 16E1	220	1.2	
16.384 via Digital1 or Digital2 (not Output 01)	77.76 MHz Analog	-	-	3800	13	
16.384 via Digital1 or Digital2 (not Output 01)	Any digital feedback mode	-	-	3800	18	
16.469	16DS1 mode	-	-	760	2.6	
17.184	-	E3 mode	Select DPLL2	120	1.0	





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Table 9 Output Frequency Selection (cont...)

Frequency (MHz, unless stated otherwise)	DPLL1 Mode	DPLL2 Mode	APLL2 Input Mux	Jitter Level (typ)		
				rms (ps)	p-p (ns)	
18.528	24DS1 mode	-	-	110	0.75	
18.528	-	24DS1 mode	Select DPLL2	110	0.75	
18.528	-	-	Select DPLL1 24DS1	110	0.75	
19.44	77.76 MHz analog	-	-	60	0.6	
19.44	77.76 MHz digital	-	-	60	0.6	
19.44	-	77.76MHz mode	Select DPLL2	60	0.6	
21.845	16E1 mode	-	-	250	1.6	
22.368	-	DS3 mode	Select DPLL2	110	1.0	
24.576	12E1 mode	-	-	900	4.5	
24.576	-	12E1 mode	Select DPLL2	500	2.3	
24.576	-	-	Select DPLL1 12E1	250	1.5	
24.704	24DS1 mode	-	-	110	0.75	
24.704	16DS1 mode	-	-	760	2.6	
24.704	-	16DS1 mode	Select DPLL2	200	1.2	
24.704	-	-	Select DPLL1 16DS1	150	1.0	
25.92	77.76 MHz analog	-	-	60	0.6	
25.92	77.76 MHz digital	-	-	60	0.6	
32.768	16E1 mode	-	-	250	1.6	
32.768	-	16E1 mode	Select DPLL2	400	2.0	
32.768	-	-	Select DPLL1 16E1	220	1.2	
34.368	-	E3 mode	Select DPLL2	120	1.0	
37.056	24DS1 mode	-	-	110	0.75	
37.056	-	24DS1 mode	Select DPLL2	110	0.75	
37.056	-	-	Select DPLL1 24DS1	110	0.75	
38.88	77.76 MHz analog	-	-	60	0.6	
38.88	77.76 MHz digital	-	-	60	0.6	
38.88	-	77.76 MHz mode	Select DPLL2	60	0.6	
44.736	-	DS3 mode	Select DPLL2	110	1.0	
49.152 (Output O1 only)	12E1 mode	-	-	900	4.5	
49.408 (Output 01 only)	16DS1 mode	-	-	760	2.6	
51.84	77.76 MHz analog	-	-	60	0.6	



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Table 9 Output Frequency Selection (cont...)

Frequency (MHz, unless stated otherwise)	DPLL1 Mode	DPLL2 Mode	APLL2 Input Mux	Jitter Level (typ)		
				rms (ps)	p-p (ns)	
51.84	77.76 MHz digital	-	-	60	0.6	
65.536 (Output O1 only)	16E1 mode	-	-	250	1.6	
68.736	-	E3 mode	Select DPLL2	120	1.0	
74.112 (Output 01 only)	24DS1 mode	-	-	110	0.75	
77.76	77.76 MHz analog	-	-	60	0.6	
77.76	77.76 MHz digital	-	-	60	0.6	
77.76	-	77.76 MHz mode	Select DPLL2	60	0.6	
98.304 (Output 01 only)	12E1 mode	-	-	900	4.5	
98.816 (Output O1 only)	16DS1 mode	-	-	760	2.6	
131.07 (Output 01 only)	16E1 mode	-	-	250	1.6	
148.22 (Output O1 only)	24DS1 mode	-	-	110	0.75	
155.52 (Output O1 only)	77.76 MHz analog	-	-	60	0.6	
155.52 (Output O1 only)	77.76 MHz digital	-	-	60	0.6	
311.04 (Output O1 only)	77.76 MHz analog	-	-	60	0.6	
311.04 (Output O1 only)	77.76 MHz digital	-	-	60	0.6	

## Table 10 Frequency Divider Look-up

Transmission Rate	APLL Frequency	APLL/2	APLL/4	APLL/6	APLL/8	APLL/12	APLL/16	APLL/48	APLL/64
OC-N Rates	311.04	155.52	77.76	51.84	38.88	25.92	19.44	6.48	4.86
E3	274.944	137.472	68.376	-	34.368	-	17.184	5.728	4.296
DS3	178.944	89.472	44.736	-	22.368	-	11.184	3.728	2.796
24DS1	148.224	74.112	37.056	24,704	18.528	12.352	9.264	3.088	2.316
16E1	131.072	65.536	32.768	21.84533	16.384	10.92267	8.192	2.730667	2.048
16DS1	98.816	49.408	24.704	16.46933	12.352	8.234667	6.176	2.058667	1.544
12E1	98.304	49.152	24.576	16.384	12.288	8.192	6.144	2.048	1.536

Note...All frequencies in MHz.



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## Table 11 APLL1 Frequencies

APLL1 Frequency	Synthesis/MUX setting for APLL1 input	DPLL1 Frequency Control Reg. 65 Bits[2:0]	Output Jitter Level ns (p-p)
311.04	Normal (digital feedback)	000	<0.5
311.04 MHz	Normal (analog feedback)	001	<0.5
98.304 MHz	12E1 (digital feedback)	010	<2
131.072 MHz	16E1 (digital feedback)	011	<2
148.224 MHz	24DS1 (digital feedback)	100	<2
98.816 MHz	16DS1 (digital feedback)	101	<2
-	Do not use	110	-
-	Do not use	111	-

### Table 12 APLL2 Frequencies

APLL2 Frequency	DPLL Mode	DPLL2 Forward DFS Frequency (MHz)	DPLL2 Freq Control Register Bits Reg. 64 Bits [2:0]	APLL2 Input from DPLL1 or 2. Reg. 65 Bit 6	DPLL1 + Synthesis Freq to APLL2 Register Bits Reg. 65 Bits [5:4]	Output Jitter Level ns (p-p)
311.04 MHz	DPLL2-Squelch ed	77.76	000	0 (DPLL2 selected)	XX	<0.5
311.04 MHz	DPLL2-Normal	77.76	001	0 (DPLL2 selected)	XX	<0.5
98.304 MHz	DPLL2-12E1	24.576	010	0 (DPLL2 selected)	XX	<0.5
131.072 MHz	DPLL2-16E1	32.768	011	0 (DPLL2 selected)	XX	<0.5
148.224 MHz	DPLL2-24DS1	37.056 (2*18.528)	100	0 (DPLL2 selected)	XX	<0.5
98.816 MHz	DPLL2-16DS1	24.704	101	0 (DPLL2 selected)	XX	<0.5
274.944 MHz	DPLL2-E3	68.736 (2*34.368)	110	0 (DPLL2 selected)	XX	<0.5
178.944 MHz	DPLL2-DS3	44.736	111	0 (DPLL2 selected)	XX	<0.5
98.304 MHz	DPLL1-12E1	-	XXX	1 (DPLL1 selected)	00	<2
131.072 MHz	DPLL1-16E1	-	XXX	1 (DPLL1 selected)	01	<2
148.224 MHz	DPLL1-24DS1	-	XXX	1 (DPLL1 selected)	10	<2
98.816 MHz	DPLL1-16DS1	-	XXX	1 (DPLL1 selected)	11	<2

Note...If using Synthesis for inputs to both APLL1 and APLL2, then they must both use the same synthesis settings.



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"Digital" Frequencies

Table 13, "01 and 02 Output Frequency Selection," lists Digital 1 and Digital 2 as available for selection. Digital 1 is a single frequency selected from the range shown in

Table 14. Digital 2 is another single frequency selected from the same range.

Table 13 01 and 02 Output Frequency Selection

	Output Frequency for given "Value in Register" for each Output Port's Cnf_output_frequency Register					
Value in Register	Output O2 Reg. 61 Bits [3:0]	Output O1 Reg. 62 Bits [7:4]				
0000	Off	Off				
0001	2 kHz	2 kHz				
0010	8 kHz	8 kHz				
0011	Digital2	APLL1/2				
0100	Digital1	Digital1				
0101	APLL1/48	APLL1/1				
0110	APLL1/16	APLL1/16				
0111	APLL1/12	APLL1/12				
1000	APLL1/8	APLL1/8				
1001	APLL1/6	APLL1/6				
1010	APLL1/4	APLL1/4				
1011	APLL2/64	APLL2/64				
1100	APLL2/48	APLL2/48				
1101	APLL2/16	APLL2/16				
1110	APLL2/8	APLL2/8				
1111	APLL2/4	APLL2/4				

# Using Output O2 to Control Pulse Width of 2/8 kHz on FrSync, MFrSync and O1 Outputs

It can be seen from Table 13 (01 and 02 Output Frequency Selection) that frequencies listed as 2 kHz and 8 kHz can be selected. Whilst the FrSync and MFrSync outputs are always supplied from DPLL1, the 2 kHz and 8 kHz options available from the 01 and 02 outputs are all supplied via DPLL1 or DPLL2 (Reg. 7A Bit 7).

The outputs can be either clocks (50:50 mark-space) or pulses, and can be inverted. When pulse configuration is used, the pulse width will be one cycle of the rate selected on Output O2 (Output O2 must be configured to generate at least 1,544 kHz to ensure that pulses are generated correctly). Figure 6 shows the various options with the 8 kHz controls in Reg. 7A. There is an identical

arrangement with Reg. 7A Bits [1:0] for the 2 kHz 01 and MFrSync outputs. Outputs FrSync and MFrSync can be disabled via Reg. 63 Bits [7:6].

#### Power-On Reset

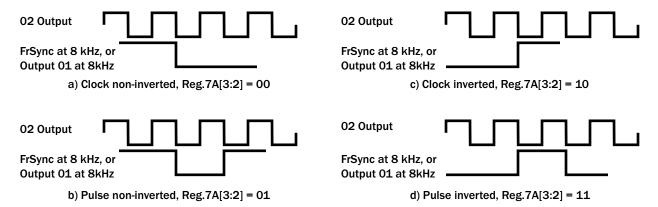
The Power-On Reset (PORB) pin resets the device if forced Low. The reset is asynchronous, the minimum Low pulse width is 5 ns. Reset is needed to initialize all of the register values to their defaults. Reset must be asserted at power on, and may be re-asserted at any time to restore defaults. This is implemented simply using an external capacitor to GND along with the internal pull-up resistor. The ACS8526 is held in a reset state for 250 ms after the PORB pin has been pulled High. In normal operation PORB should be held High.



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Figure 6 Control of 8k Options.



F8525\_016outputoptions8k\_01

Table 14 Digital Frequency Selections

Digital1 Control Reg.39 Bits [5:4]	Digital1 SONET/ SDH Reg. 38 Bit5	Digital1 Freq. (MHz)
00	0	2.048
01	0	4.096
10	0	8.192
11	0	16.384
00	1	1.544
01	1	3.088
10	1	6.176
11	1	12.352

Digital2 Control Reg. 39 Bits[7:6]	Digital2 SONET/SDH Reg.38 Bit6	Digital2 Freq. (MHz)
00	0	2.048
01	0	4.096
10	0	8.192
11	0	16.384
00	1	1.544
01	1	3.088
10	1	6.176
11	1	12.352



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## Local Oscillator Clock

The Master system clock on the ACS8526 should be provided by an external clock oscillator of frequency 12.800 MHz. Wander on the local oscillator clock will not have a significant effect on the output clock whilst in Locked mode. In Free-Run or Holdover mode wander on the crystal is more significant. Variation in crystal temperature or supply voltage both cause drifts in operating frequency, as does ageing. These effects must be limited by careful selection of a suitable component for the local oscillator. Please contact Semtech for information on crystal oscillator suppliers.

### **Crystal Frequency Calibration**

The absolute crystal frequency accuracy is less important than the stability since any frequency offset can be compensated by adjustment of register values in the IC. This allows for calibration and compensation of any crystal frequency variation away from its nominal value. An adjustment of ±50 ppm would be sufficient to cope with most crystals, in fact the range is an order of magnitude larger due to the use of two 8-bit register locations. The setting of the <code>cnfg\_nominal\_frequency</code> register allows for this adjustment. An increase in the register value increases the output frequencies by 0.0196229 ppm for each LSB step.

Note...The default register value (in decimal) = 39321 (9999 hex) = 0 ppm offset. The minimum to maximum offset range of the register is 0 to 65535 (dec), giving an adjustment range of -771 ppm to +514 ppm of the output frequencies, in 0.0196229 ppm steps.

Example: If the crystal was oscillating at 12.800 MHz + 5 ppm, then the calibration value in the register to give a - 5 ppm adjustment in output frequencies to compensate for the crystal inaccuracy, would be:

39321 - (5 / 0.0196229) = 39066 (dec) = 989A (hex).

## **Status Reporting**

### **Loss of Input Signal - LOS Flag**

In the event of loss of SEC input signal, LOS flag is raised on the LOS\_ALARM pin. The LOS alarm is active *low*, and *high impedance* when inactive, i.e. when an LOS alarm exists, the output will be driven *low*; with no LOS alarm, the output will float. This is designed to be able to be connected to a processor together with other interrupt

sources to trigger an interrupt. The output will require a pull-up resistor to pull the voltage up when the alarm is inactive.

#### **Status Information**

Status information can be read from the following Status Registers:

- sts\_current\_DPLL\_frequency (Reg. 0C, 0D, and 07)
- sts\_reference\_sources (Reg. 11).

The registers sts\_current\_DPLL\_frequency report the frequency of DPLL1 or DPLL2 with respect to the external crystal XO frequency (after calibration via Reg. 3C, 3D if used). The selection of DPLL2 or DPLL1 reporting is made via Reg. 4B, Bit 4. The value is a 19-bit signed number with one LSB representing 0.0003068 ppm (range of ±80 ppm). This value is actually the integral path value in the DPLL, and as such corresponds to an averaged measurement of the input frequency, with an averaging time inversely proportional to the DPLL bandwidth setting. Reading this regularly can show how the currently locked source is varying in value e.g. due to frequency wander on its input.

### **Serial Interface**

The ACS8526 device has a serial interface which can be SPI compatible.

The Motorola SPI convention is such that address and data is transmitted and received MSB first. On the ACS8526, device address and data are transmitted and received LSB first. Address, read/write control and data on the SDI pin is latched into the device on the rising edge of the SCLK. During a read operation, serial data output on the SDO pin can be read out of the device on either the rising or falling edge of the SCLK depending on the logic level of CLKE. For standard Motorola SPI compliance, data should be clocked out of the SDO pin on the rising edge of the SCLK so that it may be latched into the microprocessor on the falling edge of the SCLK. Figure 7 and 8 show the timing diagrams of write and read accesses for this interface.

The serial interface clock (SCLK) is not required to run between accesses (i.e., when CSB = 1).



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Figure 7 Write Access Timing for SERIAL Interface

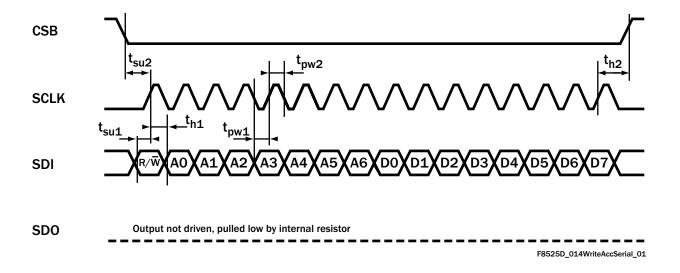


Table 15 Write Access Timing for SERIAL Interface (For use with Figure 7)

Symbol	Parameter	MIN	TYP	MAX
t <sub>SU1</sub>	Setup SDI valid to SCLK <sub>rising edge</sub>	4 ns	-	-
t <sub>SU2</sub>	Setup CSB <sub>falling edge</sub> to SCLK <sub>rising edge</sub>	14 ns	-	-
t <sub>pw1</sub>	SCLK Low time	22 ns	-	-
t <sub>pw2</sub>	SCLK High time	22 ns	-	-
t <sub>h1</sub>	Hold SDI valid after SCLK <sub>rising edge</sub>	6 ns	-	-
t <sub>h2</sub>	Hold CSB Low after SCLK <sub>rising edge</sub>	5 ns	-	-
t <sub>p</sub>	Time between consecutive accesses (CSB <sub>rising edge</sub> to CSB <sub>falling edge</sub> )	10 ns	-	-

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Figure 8 Read Access Timing for SERIAL Interface

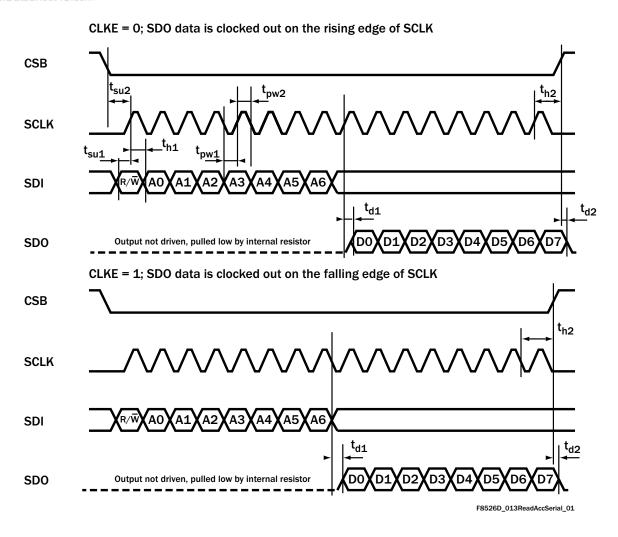


Table 16 Read Access Timing for SERIAL Interface (For use with Figure 8)

Symbol	Parameter	MIN	TYP	MAX
t <sub>su1</sub>	Setup SDI valid to SCLK <sub>rising edge</sub>	4 ns	-	-
t <sub>su2</sub>	Setup CSB <sub>falling edge</sub> to SCLK <sub>rising edge</sub>	14 ns	-	-
t <sub>d1</sub>	Delay SCLK <sub>rising edge</sub> (SCLK <sub>falling edge</sub> for CLKE = 1) to SDO valid	-	-	18 ns
t <sub>d2</sub>	Delay CSB <sub>rising edge</sub> to SDO High-Z	-	-	16 ns
t <sub>pw1</sub>	SCLK Low time	22 ns	-	-
t <sub>pw2</sub>	SCLK High time	22 ns	-	-
t <sub>h1</sub>	Hold SDI valid after SCLK <sub>rising edge</sub>	6 ns	-	-
t <sub>h2</sub>	Hold CSB Low after SCLK <sub>rising edge</sub> , for CLKE = 0 Hold CSB Low after SCLK <sub>falling edge</sub> , for CLKE = 1	5 ns	-	-
t <sub>p</sub>	Time between consecutive accesses (CSB <sub>rising edge</sub> to CSB <sub>falling edge</sub> )	10 ns	-	-



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## Registerta Map Lu.com

Each Register, or register group, is described in the following Register Map (Table 17) and subsequent Register Description Tables.

## **Register Organization**

The ACS8526 LC/P LITE uses a total of 46 eight-bit registers, identified by a Register Name and corresponding hexadecimal Register Address. They are presented here in ascending order of Reg. address and each Register is organized with the most-significant bit positioned in the left-most bit, with bit significance decreasing towards the right-most bit. Some registers carry several individual data fields of various sizes, from single-bit values (e.g. flags) upwards. Several data fields are spread across multiple registers, as shown in the Register Map, Table 17.

Shaded areas in the map are "don't care" and writing either 0 or 1 to them will not affect any function of the device.

Bits labelled "Set to 0" or "Set to 1" must be set as stated during initialization of the device, either following power-up, or after a power-on reset (POR). Failure to correctly set these bits may result in the device operating in an unexpected way.

CAUTION! Do not write to any undefined register addresses as this may cause the device to operate in a test mode. If an undefined register has been inadvertently addressed, the device should be reset to ensure the undefined registers are at default values.

## **Multi-word Registers**

For multi-word registers (e.g. Reg. OC and OD), all the words have to be written to their separate addresses, and without any other access taking place, before their combined value can take effect. If the sequence is interrupted, the sequence of writes will be ignored.

Reading a multi-word address freezes the other address words of a multi-word address so that the bytes all correspond to the same complete word

## **Register Access**

Most registers are either configuration registers or status registers, the exceptions being the *chip\_id* and *chip\_revision* registers. Configuration registers may be written to or read from at any time (the complete 8-bit register must be written, even if only one bit is being modified). All status registers may be read at any time. A description of each register is given in the Register Map, and Register Map Description.

### **Configuration Registers**

Each configuration register reverts to a default value on power-up or following a reset. Most default values are fixed, but some will be pin-settable. All configuration registers can be read out over the serial port.

## **Status Registers**

The Status Registers contain readable registers. They may all be read from outside the chip but are not writeable from outside the chip (except for a clearing operation). All status registers are read via shadow registers to avoid data hits due to dynamic operation. Each individual status register has a unique location.

### **Flags**

In the event of loss of the currently selected input a no-activity flag is raised on pin LOS\_ALARM indicating that the input to DPLL1 has failed. The active state (*High* or *Low*) of the LOS\_ALARM pin is programmable and the pin can either be driven, or set to high impedance when nonactive (Reg 7D refers).

#### **Defaults**

Each Register is given a defined default value at reset and these are listed in the Map and Description Tables. However, some read-only status registers may not necessarily show the same default values after reset as those given in the tables. This is because they reflect the status of the device which may have changed in the time it takes to carry out the read, or through reasons of pin configuration. In the same way, the default values given for shaded areas could also take different values to those stated.



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Table 17 Register Map

Register Name	SS	Ħ <sub>©</sub>				Dat	ta Bit			
RO = Read Only R/W = Read/Write	Address (hex)	Default (hex)	7 (msb)	6	5	4	3	2	1	O (Isb)
chip_id (RO)	00	4E			•	chip_id[7:0], 8	LSBs of Chip ID	•	•	1
	01	21				chip_id[15:8], 8	MSBs of Chip ID	)		
chip_revision (RO)	02	00				chip_rev	vision[7:0]			
test_register1 (R/W)	03	14	Phase_alarm	Disable_180		Resync_	Set to 0	8K Edge	Set to 0	Set to 0
ete aurrent DDII fraguencul7:01	ОС	00	(RO)		Dit	analog	ront DDLL from	Polarity		
sts_current_DPLL_frequency[7:0]	0D	00				s [7:0] of sts_cur [15:8] of sts_cur				
(RO) [15:8]		00			DILS	[15.6] 01 StS_Cu1	rent_DPLL_rrequ		of etc. ourront D	DII fraguanov
sts_reference_sources (RO)	11	22			No Activity			BIIS [10.10]	of sts_current_D  No Activity	T Tequency
Alarm Status on inputs:SEC1 & 2	11	22			SEC2				SEC1	
cnfg_ref_source_frequency SEC1	22	00	divn_SEC1	lock8k_SEC1				reference_sourc	e_frequency_SEC	21
(R/W) SEC2	23	00	divn_SEC2	lock8k_SEC2					e_frequency_SEC	
cnfg_input_mode (R/W)	34	C2	auto_extsync_	_	XO_ edge		1	ip_sonsdhb		
5_ , _ , ,			en					1		
cnfg_DPLL2_path (R/W)	35	40		•				•		
cnfg_dig_outputs_sonsdh (R/W)	38	14		dig2_sonsdh	dig1_sonsdh					
cnfg_digtial_frequencies (R/W)	39	08	digital2_	frequency	digital1_	frequency				
cnfg_differential_output (R/W)	3 <i>A</i>	C2							Output O1	_LVDS_PECL
cnfg_auto_bw_sel	3B	98	auto_BW_sel				DPLL1_lim_int			
cnfg_nominal_frequency [7:0]	3C	99		-	I	Bits[7:0] of cnfg_	nominal_frequen	су		
(R/W) [15:8]	3D	99			В	its[15:8] of cnfg_	_nominal_frequer	псу		
cnfg_DPLL_freq_limit (R/W) [7:0]	41	FF				Bits[7:0] of cnfg	g_DPLL_freq_limi	t		
cnfg_DPLL_freq_limit (R/W) [9:8]	42	03							Bits[9:8] cnfg_	DPLL_freq_lim
cnfg_freq_divn (R/W) [7:0].	46	FF			divn_	value [7:0] (divid	le Input frequenc	y by n)		
[13:8]	47	3F				divn_	value [13:8] (divi	de Input frequen	cy by n)	
cnfg_registers_source_select	4B	00				DPLL1_DPLL2				
(R/W)						_select				
cnfg_freq_lim_ph_loss	4D		freq_lim_ph_							
and was a threshold (D (M)	50	00	loss			Lucius (Activitus	lawa Lasla Dual	.at aat thuashala	<u></u>	
cnfg_upper_threshold (R/W)	50	06						ket - set threshold		
cnfg_lower_threshold (R/W)	51	04						et - reset threshol	a)	
cnfg_bucket_size (R/W)	52	08			bucket_si	ize_value (Activit)	/ alarm, Leaky Bl	icket - size)		
cnfg_decay_rate (R/W)	53	01								_value (Activity Bucket - leak rat
cnfg_output_frequency(R/W) (O2)	61	OA						outnut	_freq_02	dence lear rat
(01)	62	00		outnut	freq_01			- Output	_1104_02	
(MFrSync/FrSync)	63	CO	MFrSync_en	FrSync_en	T					
cnfg_DPLL2_frequency (R/W)	64	00	Wil Toyric_err	TTSyric_en					DPLL2_frequence	01/
cnfg_DPLL1_frequency (R/W)	65	01		APLL2_for_	DDII1 fro	q_to_APLL2	1		DPLL1_frequent	
chig_britti_hequency (N/ W)	03	01		DPLL1_E1/ DS1	DI LLI_Ne	q_to_Ar LL2			DI LLI_Hequent	Jy
cnfg_DPLL2_bw (R/W)	66	00							DPLL2_	bandwidth
cnfg_DPLL1_locked_bw (R/W)	67	10							DPLL1_lock	ed_bandwidth
cnfg_DPLL1_acq_bw (R/W)	69	11							DPLL1_acquis	 sition_bandwidt
cnfg_DPLL2_damping (R/W)	6A	13		DF	PLL2_PD2_gain_a	alog			DPLL2_dampin	g
cnfg_DPLL1_damping (R/W)	6B	14			 L1_PD2_gain_ald				DPLL1_dampin	
cnfg_DPLL2_PD2_gain (R/W)	6C	C2	DPLL2_PD2_ gain_enable			<u></u>		DP	LL2_PD2_gain_c	
cnfg_DPLL1_PD2_gain (R/W)	6D	C2	DPLL1_PD2_ gain_enable	DF	PLL1_PD2_gain_a	alog		DP	LL1_PD2_gain_c	ligital
cnfg_phase_loss_fine_limit (R/W)	73	A2	fine_limit_en	noact_ph_loss	narrow_en			р	hase_loss_fine_l	imit
cnfg_phase_loss_coarse_limit (R/W)	74	E5	coarse_lim_ phaseloss_en	wide_range_ en	multi_ph_resp			phase_loss	_coarse_limit	
cnfg_ip_noise_window (R/W)	76	06	ip_noise_ window_en		l					
cnfg_sync_pulses (R/W)	7A	00	2k_8k_from_ DPLL2				8k_invert	8k_pulse	2k_invert	2k_pulse
cnfg_LOS_alarm (R/W)	7D	02						LOS_GPO_en	LOS_tristate_ en	LOS_ polarity
cnfg_protection (R/W)	7E	85				protecti	ion_value	•	•	•



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## Register Descriptions

## Address (hex): 00

Register Name	chip_id		nip_id <b>Description</b> (RO) 8 lea chip ID.		nificant bits of the	Default Value	0100 1110
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
			chip_id[7:0],	8 LSBs of Chip ID			
Bit No.	Description			Bit Value	Value Descriptio	n	
[7:0]	chip_id Least significant	byte of the 2-by	rte device ID.	4E (hex)			

## Address (hex): 01

Register Name	chip_id		Description	(R0) 8 most sig chip ID.	nificant bits of the	Default Value	0010 0001
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
			chip_id[15:8],	8 MSBs of Chip ID	)		
Bit No.	Description			Bit Value	Value Descriptio	n	
[7:0]	chip_id Most significant l	oyte of the 2-by	te device ID.	21 (hex)			

## Address (hex): 02

Register Name	chip_revision		Description	(RO) Silicon rev	(R0) Silicon revision of the device. <b>Default Value</b>							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0					
	chip_revision[7:0]											
Bit No.	Description			Bit Value	Value Description							
[7:0]	chip_revision Silicon revision of	the device.		00 (hex)								





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Address (hex): 03 s h e

Register Name	test_register1	test_register1			containing various not normally used).	Default Value	00X1 0100
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
phase_alarm	disable_180		resync_analog	Set to 0	8k Edge Polarity	Set to 0	Set to 0
Bit No.	Description			Bit Value	Value Description	n	
7	phase_alarm (ph Instantaneous re			0 1	DPLL1 reporting DPLL1 reporting		
6	disable_180 Normally the DPL	L will try to lock	to the pearest	0	DPLL1 automatic enable.	ally determines	frequency lock
	edge (±180°) for a new reference. that it is phase lo capture range rev to frequency and into frequency lock to	the first 2 secon- If the DPLL does locked after this ti- verts to ±360°, v phase locking. F cking mode may a new reference er, this may caus to 360° when the	ds when locking to a not determine time, then the which corresponds forcing the DPLL reduce the time to be by up to two e an unnecessary ne new and old	1		always frequenc	y and phase lock.
5	Not used.			-	-		
4	The analog outpu synchronization r	ıt dividers includ nechanism to en	e-synchronization) e a sure phase lock at ut and the output.	0	clocks divided do	wer-up. Iways synchroni wn from the API	during first 2 zed.This keeps the LL output, in sync clocks in the DPLL.
					Hence ensuring t	utput clocks, and even though only a	
3	Set to 0 Test Control. Lea	ve unchanged or	r set to 0.	0	-		
2	8k Edge Polarity When Lock8k or current input SEC on either the risin clock.	C, this bit allows	the system to lock	0 1	Lock to falling clo		
1	Set to 0 Test Control. Lea	ve unchanged or	r set to 0.	0	-		
0	Set to 0 Test Control. Lea	ve unchanged or	r set to 0.	0	-		



# ADVANCED COMMUNICATIONS FINAL DATASHEET

Address (hex): 07

Register Name	sts_current_DPL [18:16]	L_frequency	Description	(RO) Bits [18:16] of the current DPLL frequency.		Default Value	0000 0000		
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O		
					Bits [18:16] of sts_current_DPLL_frequency				
Bit No.	Description			Bit Value	Value Descripti	on			
[7:3]	Not used.			-	-				
[2:0]	Bits [18:16] of si When Bit 4 (DPL (onfg_registers_s for DPLL1 is repo When this Bit 4 = reported.	L1_DPLL2_sele source_select) = orted.	ct) of Reg. 4B = 0 the frequency	-	See register de sts_current_DP	scription of PLL_frequency at F	Reg. OD.		

## Address (hex): OC

Register Name	sts_current_DPLL_frequency [7:0]		Description	(R0) Bits [7:0] of frequency.	of the current DPLL	Default Value	0000 0000	
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O	
			Bits [7:0] of sts_cu	rrent_DPLL_frequ	ency			
Bit No.	Description			Bit Value	Value Description	1		
[7:0]	Bits [7:0] of sts_ When Bit 4 (DPLI (cnfg_registers_s for DPLL1 is reported.	L1_DPLL2_sele source_select) = orted.	ct) of Reg. 4B • 0 the frequency	-	See register description of sts_current_DPLL_frequency at Reg. 0D.			



# ADVANCED COMMUNICATIONS FINAL DATASHEET

Address (hex): 0D s h e

Register Name	sts_current_DPL [15:8]	L_frequency	uency <b>Description</b> (RO) Bits DPLL freq		] of the current y.	Default Value	0000 0000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Е	Bits [15:8] of sts_cu	rrent_DPLL_freq	uency		
Bit No.	Description			Bit Value	Value Descript	ion	
[7:0]	in Reg. OC and Refrequency offset When Bit 4 (DPLI	register is comb eg. 07 to repres of the DPLL. L1_DPLL2_sele source_select) = orted.	oined with the value sent the current ct) of Reg. 4B to the frequency		respect to the in Reg. 07, Reg concatenated. signed integer. 0.0003068 de with respect to crystal calibrat cnfg_nominal_value is actual can be viewed rate of change Bit 3 of Reg. 31	• •	complement ed by ue in ppm offset allowing for any performed, via C and 3D. The I path value so it quency, where the PLL bandwidth. If value will freeze if

## Address (hex): 11

Register Name	sts_reference_sources SEC1 & SEC2		Description	(RO except for test when R/W) Reports any alarms active on inputs.		Default Value	0010 0010
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
		No Activity SEC2 Input				No Activity SEC1 Input	
Bit No.	Description			Bit Value	Value Descripti	on	
[7:6]	Not Used			-	-		
5	SEC2 Input Acti Alarm indication	vity Alarm n from the activity	monitors.	0 1	No alarm (input Input has an ac	valid). tive "no activity" a	larm.
[3:2]	Not Used			-	-		
1	SEC1 Input Activity Alarm Alarm indication from the activity monitors.			0 1	No alarm (input Input has an ac	valid). tive "no activity" a	larm.
0	Not Used			-	-		



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Address (hex): 22

Register Name	cnfg_ref_source_ SEC1	frequency	Description	(R/W) Configuration of the frequency and input monitoring for input SEC <n>. For Reg. 22, <n> = 1.</n></n>		<b>Default Value</b> 0000 XXXX  Where XXXX is set by values on Pins IP_FREQ[2:0] and SONSDH See Note in Description [3:0].		
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
divn_SEC <n></n>	lock8k_SEC <n></n>				reference_source	_frequency_SEC<	<n></n>	
Bit No.	Description			Bit Value	Value Descripti	on		
7	divn_SEC <n> This bit selects w divided in the pro being input to the Reg. 46 and Reg.</n>	grammable pre DPLL and freq	e-divider prior to quency monitor- see	0 1	Input SEC <n> fed directly to DPLL and moni Input SEC<n> fed to DPLL and monitor via p divider.</n></n>			
6	to the DPLL. This	eset pre-divider results in the D has been divide	prior to being input PPLL locking to the ed to 8 kHz. This bit	0 1	•	ed directly to DPL ed to DPLL via pre		
[5:4]	Not used.			-	-			
[3:0]	reference_source Programs the free input SEC <n>. If of should be set to 0</n>	quency of the S divn_SEC <n> is</n>		0000 0001 0010 0011	8 kHz. 1544/2048 kH in Reg. 34). 6.48 MHz. 19.44 MHz.	z (dependant on I	Bit 2 (ip_sonsdhb)	
	frequency which, both cnfg_ref_so each the same de register can, after after PORB goes basis by writing to serial interface, he cause these regis whatever value is	mines the defau at power-up/re urce_frequency efault value. Th r the initializati High), be chang o each register nowever any sui sters' values to s on the pins at enfiguring Input	alt expected input eset is written to a registers, giving e values in each on period (251 ms ged on an individual separately via the bsequent reset will be overwritten by the time of the s - Expected Input	0100 0101 0110 0111 1000 1001 1010 1011-1111	25.92 MHz. 38.88 MHz. 51.84 MHz. 77.76 MHz. Not used. 2 kHz. 4 kHz. Not used.			

Address (hex): 23 cnfg\_ref\_source\_frequency SEC2 As Reg. 22, but for SEC2, i.e. <n> = 2 Default = 0000 0000



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Address (hex): 34

Register Name	cnfg_input_mode  Bit 6 Bit 5		Description	(R/W) Register input modes of	controlling various f the device.	Default Value	1100 0010*	
Bit 7			Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
		XO_edge			ip_sonsdhb			
Bit No.	Description			Bit Value	Value Descriptio	n		
[7:6]	Not used.			-	-			
5	XO_edge If the 12.8 MHz	z oscillator module	connected to	0	Device uses the rising edge of the external oscillator.			
	jitter performan	nce reasons, the fa is bit allows either	_	1	Device uses the oscillator.	falling edge of th	e external	
[4:3]	Not used.			-	-			
2	ip_sonsdhb			0	SDH- inputs set t	o 0001 expected	d to be 2048 kHz.	
	SONET or SDH of selections of OC cnfg_ref_source	input frequencies derived. This appli- 001 (bin) in the e_frequency regist v is either 1544 kH	es only to ers when the	1	SONET- inputs se 1544 kHz.	et to 0001 expec	ted to be	
		alue of Bit 2 is take B pin at power-up.						
[1:0]	Not used.			-	-			

Register Name	cnfg_DPLL2_path		Description	(R/W) Register to configure the feedback mode of DPLL2.		Default Value	0100 0000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
	DPLL2_dig_ feedback						
Bit No.	Description			Bit Value	Value Descripti	on	
7	Not used.			-	-		
6	DPLL2_dig_feedb Bit to select digita		de for DPLL2	0 1		g feedback mode. I feedback mode.	
[5:0]	Not used.	Treedback mo	GC 101 D1 LLZ.	-	-	Trocusack mode.	



## ADVANCED COMMUNICATIONS FINAL

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Address (hex): 38

Register Name	cnfg_dig_outputs_sonsdh			Configures <i>Digital1</i> and <i>Digital2</i> output frequencies to be SONET or SDH compatible frequencies.		Default Value	0001 0100
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
	dig2_sonsdh	dig1_sonsdh					
Bit No.	Description			Bit Value	Value Description	on	
7	Not used.			-	-		
6	Digital2 frequer SDH.	r the frequencies g ncy generator are S f this bit is set by th	SONET derived or	1	12,352 kHz.	,	44/3,088/6,176/ 948/4,096/8,192/
5	dig1_sonsdh Selects whether the frequencies generated by the Digital1 frequency generator are SONET derived or SDH. Default value of this bit is set by the SONSDHB pin at power-up.			0	12,352 kHz.		44/3,088/6,176/ 48/4,096/8,192/
[4:0]	Not used.			-	-		

Register Name	cnfg_digtial_freq	uencies	Description	(R/W) Configur frequencies of	0000 1000		
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
digital2_	digital2_frequency digital1_frequency						
Bit No.	Description			Bit Value	Value Descripti	on	
[7:6]	digital2_frequen	су		00 Digital2 set to 1,544 kHz or 2,048			8 kHz.
	Configures the fre	equency of <i>Digita</i>	12. Whether this is	01	Digital2 set to 3	3,088 kHz or 4,09	6 kHz.
	SONET or SDH ba	ased is configure	d by Bit 6	10	Digital2 set to 6	6,176 kHz or 8,19	2 kHz.
	(dig2_sonsdh) of	Reg. 38.		11	Digital2 set to 1	12,353 kHz or 16,	384 kHz.
[5:4]	digital1_frequen	cy		00	Digital1 set to 1	1,544 kHz or 2,04	8 kHz.
	Configures the fre	equency of Digita	<ol><li>Whether this is</li></ol>	01	Digital1 set to 3	3,088 kHz or 4,09	6 kHz.
	SONET or SDH ba	ased is configure	d by Bit 5	10	Digital1 set to 6	6,176 kHz or 8,19	2 kHz.
	(dig1_sonsdh) of	Reg. 38.		11	Digital1 set to 1	12,353 kHz or 16,	384 kHz.
[3:0]	Not used.						



Address (hex): 3A

Register Name	cnfg_differential_output		Description	(R/W) Configures the electrical compatibility of the differential output driver to be 3 V PECL or 3 V LVDS.		Default Value	1100 0010
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
						Output 01	_LVDS_PECL
Bit No.	Description			Bit Value	Value Descripti	on	
[7:2]	Not used.			-	-		
[1:0]	Output O1_LVDS Selection of the e between 3 V PEC	electrical compa	atibility of Output O1 S.	00 01 10 11	•	bled. PECL compatible. LVDS compatible.	

Register Name	cnfg_auto_bw_sel		Description	(R/W) Register to select			1001 1000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
auto_BW_sel				DPLL1_lim_int			
Bit No.	Description			Bit Value	Value Descriptio	n	
7	auto_BW_sel Bit to select locked ba	•	-	1	Automatically sel	propriate.	
	acquisition bandwidth	n (Reg. 69) f	or DPLL1.	0	Always selects locked bandwidth.		
[6:4]	Not used.			-	-		
3	DPLL1_lim_int			1	DPLL value froze	n.	
	When set to 1 the intellimited or frozen wher max. frequency. This subsequent overshood Note that when this befrequency value, via conductive of the conduct	n DPLL1 rea can be used of when the oit is enabled current_DPL	ches either min. or I to minimize DPLL is pulling in. d, the reported	0	DPLL not frozen.		
[2:0]	Not used.			-	-		





Address (hex): 3C

Register Name	Name cnfg_nominal_frequency [7:0]		[7:0] used to ca		used to calibra oscillator used	R/W) Bits [7:0] of the register sed to calibrate the crystal scillator used to clock the evice.		1001 1001
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
			cnfg_nominal_f	requency_value[7:	:0]			
Bit No.	Description			Bit Value	Value Descript	ion		
[7:0]	cnfg_nominal_frequency_value[7:0].		-	•	scription of Reg. 3 _frequency_value[			

Register Name	cnfg_nominal_frequency [15:8]		Description	(R/W) Bits [15:8] of the register used to calibrate the crystal oscillator used to clock the device.		Default Value	1001 1001
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
			cnfg_nominal_fre	equency_value[15	5:8]		
Bit No.	Description			Bit Value	Value Descripti	on	
[7:0]	This register is us (cnfg_nominal_fi offset the freque +514 ppm and - represents 0 ppr		n with Reg. 3C 7:0].) to be able to oscillator by up to efault value 800 MHz.		oscillator frequence Reg. 3D need to unsigned integer 0.0196229 dec calculate the above the calculate th	ram the ppm offse ency, the value in be concatenated er. The value multi c. will give the valu psolute value, the ds to be subtracte	Reg. 3C and d. This value is an plied by ie in ppm. To default 39321



Address (hex): 41

Register Name	cnfg_DPLL_freq_lim [7:0]	it	Description	. , ,	(R/W) Bits [7:0] of the DPLL frequency limit register.		1111 1111
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
			Bits[7:0] of cnf	g_DPLL_freq_limi	it		
Bit No.	Description			Bit Value	Value Descrip	tion	
[7:0]	Bits [7:0] of cnfg_DF. This register defines to which DPLL1 will i.e. it represents the offset of the device offset of the DPLL with external crystal of the oscillator is callibration is automatically and performed by the compared to the trequency.	the extent of track a source pull-in range is determined then compared poscillator cloop or ated using ency Reg. 30 atically takent limits the of	of frequency offset the before limiting- the of the DPLLs. The digital by the frequency and to the offset of the device. If the cand 3D, then this in into account. The freet of the DPLL		Bits [1:0] of Re to be concater and represent	culate the frequences. 42 and Bits [7:0] ated. This value is a limit <i>both</i> positive multiplied by 0.0°	o)] of Reg. 41 need a unsigned integer and negative in

Register Name	e cnfg_DPLL_freq_limit [9:8]		Description	(R/W) Bits [9:8] of the DPLL frequency limit register.		Default Value	0000 0011
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
						Bits [9:8] of cnf	ig_DPLL_freq_limit
Bit No.	Description			Bit Value	Value Descriptio	n	
[7:2]	Not used.			-	-		
[1:0]	Bits [9:8] of cnfg_DI	PLL_freq_limit.		-	See Reg. 41 (cnf	fg_DPLL_freq_lim	it) for details.



Address (hex): 46

Register Name	cnfg_freq_divn [7:0].		Description	. , ,	of the division s using the DivN	Default Value	1111 1111
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
		div	n_value [7:0] (div	vide input frequenc	cy by n)		
Bit No.	Description			Bit Value	Value Descripti	on	
[7:0]	divn_value[7:0].			-	See Reg. 47 (cr	nfg_freq_divn {13:	8]) for details.

## Address (hex): 47

Register Name	cnfg_freq_divn [13:8]		Description	· , , .	8] of the division s using the DivN	Default Value	0011 1111
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
			divr	n_value [13:8] (div	vide input frequenc	cy by n)	
Bit No.	Description			Bit Value	Value Descripti	on	
[7:6]	Not used.			-	-		
[5:0]	divn_value[13:8] This register, in co (cnfg_freq_divn) rowhich to divide inp. The DivN feature s maximum of 100 value that should hex (12499 dec). result in unreliable.	epresents the in outs that use the supports input fr MHz; therefore, be written to thi Use of higher Di	nteger value by e DivN pre-divider. requencies up to a the maximum s register is 30D3	ı	•	ency will be divide s 1. i.e. to divide t	•

Register Name	legister Name cnfg_registers_source_select		Description	(R/W) Register to select the source of many of the registers.		Default Value	0000 0000	
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
			DPLL1_DPLL2_ select					
Bit No.	Description			Bit Value	Value Description	n		
[7:5]	Not used.			-	-			



Address (hex): 4B (cont...)

Register Name	cnfg_registers_s	Description	(R/W) Register to select the source of many of the registers.		Default Value	0000 0000	
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
			DPLL1_DPLL2_ select				
Bit No.	Description			Bit Value	Value Descripti	on	
4	DPLL1_DPLL2_s Bit to select betw associated with I registers.	veen many of the	•	0 1	DPLL1 registers DPLL2 registers		
[3:0]	Not used.			-	-		

Register Name	cnfg_freq_lim_ph_loss			(R/W) Register phase lost indic hits its hard fre	cation when DPLL	Default Value	1000 1110
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
freq_lim_ph_ loss							
Bit No.	Description			Bit Value	Value Descripti	on	
7	freq_lim_ph_loss Bit to enable the phase lost indication when the DPLL hits its hard frequency limit as programmed in Reg. 41 and Reg. 42 (cnfg_DPLL_freq_limit). This results in the DPLL entering the phase lost state any time the DPLL tracks to the extent of its hard limit.			0 1	•	ked determined no ed when DPLL trac	•
[6:0]	Not used.			-	-		



Address (hex): 50

Register Name	cnfg_upper_thre	shold	Description	. , , .	to program the setting limit for the Configuration.	Default Value	0000 0110
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	
		upper_thresho	ld_value (Activity	alarm, Leaky Bucl	ket - set threshold)		
Bit No.	Description			Bit Value	Value Descriptio	n	
[7:0]	by 1, and for eac	et operates on a 1 detects that an independent of the nerratic, then for some of 1, 2, and the nerratic of the nerratic of 1, 2, and the nerratic of the nerra	nput has either reach cycle in or is incremented 4, or 8 cycles, as eay_rate), in which of is the the value hold_value, the		Value at which the inactivity alarm.	ne Leaky Bucket	will raise an

Register Name	cnfg_lower_threshold	Description	activity alarm r	(R/W) Register to program the activity alarm resetting limit for the Leaky Bucket Configuration.		0000 0100
Bit 7	Bit 6	Bit 5 Bit 4	Bit 3	Bit 2	Bit 1	Bit O
	lower_	_threshold_value (Activity a	et - reset threshold)			
Bit No.	Description		Bit Value	Value Descripti	on	
[7:0]	during a cycle, it detects failed or has been errati which this occurs, the a by 1, and for each perio	ates on a 128 ms cycle. If, is that an input has either ic, then for each cycle in ccumulator is incremented of 1, 2, 4, or 8 cycles, as (cnfg_decay_rate), in which accumulator is		Value at which inactivity alarm	the Leaky Bucket	will reset an
	The lower_threshold_va	lue is the value at which than inactivity alarm.	e			



Address (hex): 52

			(R/W) Register to program the maximum size limit for the Leaky Bucket Configuration.		Default Value	0000 1000	
Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O	
		bucket_size_value (Activity alarm, Leaky Bu			Bucket - size)		
escription			Bit Value	Value Description	n		
uring a cycle, it determined or has been ended in this occurs, the y 1, and for each performed in Reg. his does not occur, the ecremented by 1.	ects that an inj ratic, then for e accumulator rriod of 1, 2, 4 53 ( <i>cnfg_deca</i> he accumulat	out has either each cycle in is incremented, or 8 cycles, as by_rate), in which or is	-		•	•	
Lit Ual	escription  ucket_size_value ne Leaky Bucket op uring a cycle, it dete illed or has been en hich this occurs, the v 1, and for each pe rogrammed in Reg. is does not occur, the ceremented by 1.	bucket_s  escription  ucket_size_value  ne Leaky Bucket operates on a 12  uring a cycle, it detects that an inj iled or has been erratic, then for hich this occurs, the accumulator 1, and for each period of 1, 2, 4 rogrammed in Reg. 53 (cnfg_deca is does not occur, the accumulate ecremented by 1.	bucket_size_value (Activite the Leaky Bucket operates on a 128 ms cycle. If, suring a cycle, it detects that an input has either illed or has been erratic, then for each cycle in thich this occurs, the accumulator is incremented of 1, 2, 4, or 8 cycles, as a cogrammed in Reg. 53 (cnfg_decay_rate), in which it is does not occur, the accumulator is ecremented by 1.	bucket_size_value (Activity alarm, Leaky Bucket_size_value  acket_size_value  be Leaky Bucket operates on a 128 ms cycle. If, buring a cycle, it detects that an input has either illed or has been erratic, then for each cycle in blich this occurs, the accumulator is incremented  at 1, and for each period of 1, 2, 4, or 8 cycles, as cogrammed in Reg. 53 (cnfg_decay_rate), in which be discounted by 1.  The number in the Bucket cannot exceed the value	bucket_size_value (Activity alarm, Leaky Bucket - size)  Bit Value Value Description  Ucket_size_value  - Value at which the ne Leaky Bucket operates on a 128 ms cycle. If, urring a cycle, it detects that an input has either illed or has been erratic, then for each cycle in which this occurs, the accumulator is incremented of 1, 2, 4, or 8 cycles, as rogrammed in Reg. 53 (cnfg_decay_rate), in which is does not occur, the accumulator is ecremented by 1.  The number in the Bucket cannot exceed the value	bucket_size_value (Activity alarm, Leaky Bucket - size)  Bit Value Value Description  - Value at which the Leaky Bucket one Leaky Bucket operates on a 128 ms cycle. If, uring a cycle, it detects that an input has either illed or has been erratic, then for each cycle in which this occurs, the accumulator is incremented of 1, 2, 4, or 8 cycles, as a cogrammed in Reg. 53 (cnfg_decay_rate), in which is does not occur, the accumulator is ecremented by 1.  The number in the Bucket cannot exceed the value	

Register Name	cnfg_decay_rate		Description	(R/W) Register "decay" or "lea Leaky Bucket C		Default Value	0000 0001
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
						, , – –	lue (Activity alarm, ket - leak rate)
Bit No.	Description			Bit Value	Value Descript	ion	
[7:2]	Not used.			-	-		
[1:0]	decay_rate_value The Leaky Bucket o during a cycle, it de failed or has been e which this occurs, ti by 1, and for each p programmed in this occur, the accumula The Leaky Bucket c "decay" at the same effectively at one ha the fill rate.	tects that an interratic, then for the accumulato period of 1, 2, 4 register, in whator is decrement an be programe arate as the "f	aput has either reach cycle in r is incremented 1, or 8 cycles, as ich this does not ented by 1.  med to "leak" or ill" cycle, or	00 01 10 11	Bucket decay r Bucket decay r	ate of 1 every 128 ate of 1 every 256 ate of 1 every 512 ate of 1 every 1,02	ms. ms.





Register Name	cnfg_output_freq (Output O2)	uency	Description		to configure and quencies available	Default Value 0000 XXXX  Where XXXX is set by values or Pins 02_FREQ[2:0], SONSDHB and 01_FREQ[2:0]. See Note in [3:0] description.	
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3 Bit 2		Bit 1	Bit O
					output_	_freq_02	
Bit No.	Description			Bit Value	Value Description	on	
[7:4]	Not used.			-	-		
[3:0]	APLL2. These are Reg. 65. See "Ou Register Program NoteThe values SONSDHB and Ocoutput frequency up/reset is writter egister. The valuinitialization periobe changed by whowever any substitution of the change of	of the frequencies of the frequencies of the configured in Responsible to the transfer of the configured in Responsible to the pins O2_1_FREQ[2:0] determined to the configure of (251 ms after priting to it via the sequent reset with the time of the responsible to the configuration of the responsible to the time of the responsible to the configuration of the responsible to the time of the responsible to the time of the responsible to the configuration of th	es available are the APLL1 and the eg. 64 and Selection by 7.  FREQ [2:0], Fremine the default which, at power- tput_frequency can, after the PORB goes High), serial interface, Il cause this by whatever value uset. See "Output	0000 0001 0010 0011 0100 0101 0111 1000 1001 1010 1011 1100 1101 1111		9 cnfg_digital_fre 9 cnfg_digital_fre y/48. y/12. y/8. y/6. y/4. y/48. y/16. y/16.	•



Address (hex): 62

Register Name	cnfg_output_freque (Output O1)	ncy	Description		to configure and juencies available	Where XXXX is set by values on Pins 02_FREQ[2:0] and SONSDHB, See Note in [3:0] description.		
Bit 7	Bit 6 Bit 5		Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
	output_fre	q_01						
Bit No.	Description			Bit Value	Value Description	on		
[7:4]	output_freq_O1 Configuration of the Output O1. Many of dependent on the fr APLL2. These are co Reg. 65. See "Output Register Programmi  NoteThe values or SONSDHB determin for Output O1, which the cnfg_output_free this register can, afr (251 ms after PORE writing to it via the s subsequent reset w be overwritten by we the time of the rese Selection by Hardwa	the frequenci equencies of the prigured in Reput the price of the pric	es available are the APLL1 and the eg. 64 and Selection by .7.  FREQ [2:0] and output frequency / reset is written to er. The value in ation period be changed by e., however any register's value to is on the pins at a Frequency	0000 0001 0010 0011 0100 0101 0111 1000 1001 1010 1011 1100 1101 1110	Output disabled 2 kHz. 8 kHz. APLL1 frequency Digital1 (Reg. 38 APLL1 frequency APLL1 frequency APLL1 frequency APLL1 frequency APLL1 frequency APLL2 frequenc	y/2. 9 cnfg_digital_fre y/16. y/12. y/8. y/6. y/4. y/48. y/16. y/16.	quencies).	
[3:0]	Not used.			-	-			

Register Name	cnfg_output_frequency (MFrSync/FrSync)		Description	enable the free	to configure and juencies available Sync and FrSync.	Default Value	1100 0000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
MFrSync_en	FrSync_en						
Bit No.	Description			Bit Value	Value Description	on	
7	MFrSync_en Register bit to er (MFrSync).	nable the 2 kHz	Sync output	0 1	Output MFrSync Output MFrSync		



Address (hex): 63 (cont...)

Register Name	cnfg_output_frequency (MFrSync/FrSync)		Description	enable the freq	to configure and juencies available Sync and FrSync.	Default Value	1100 0000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
MFrSync_en	FrSync_en						
Bit No.	Description			Bit Value	Value Description	on	
6	FrSync_en Register bit to er	nable the 8 kHz	Sync output	0 1	Output FrSync d Output FrSync e		
[5:0]	(FrSync). Not used.			-	-		

Register Name	cnfg_DPLL2_fred	quency	Description	(R/W) Register DPLL2 Frequer	J	Default Value	0000 0000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
						DPLL2_frequence	су
Bit No.	Description			Bit Value	Value Description	on	
[7:4]	Not used.			-	-		
[2:0]	DPLL2_frequenc	y		000	DPLL2 squelche	ed (clock off).	
	•		cy of operation of	001	77.76 MHz (OC-	**	
	•	•	vill also affect the	2.4.2	•	y = 311.04 MHz.	
	frequency of the			010		equency = 98.304	
	frequencies avail Reg. 61 and Reg	•		011 100	•	equency = 131.07 requency = 148.2	
	-		o run directly from	101		requency = 148.2	
	DPLL1 output, se		orall allectly from	110		ency = 274.944	
	(cnfg_DPLL1_fre	U	equencies are	111	, ,	uency = 178.94	
	`		LL2 should not be		•	,	
	squelched, as the	e APLL2 input is s	squelched and the				
	APLL2 will free ru	ın.					



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Address (hex): 65

Register Name	cnfg_DPLL1_freq	uency	Description	(R/W) Register DPLL1 and MU	to configure X2 parameters.	Default Value	0000 0001
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
	APLL2_for_ DPLL1_E1/DS1	DPLL1_fre	eq_to_APLL2			DPLL1_frequenc	су
Bit No.	Description			Bit Value	Value Descripti	on	
7	Not used.			-	-		
6	APLL2 for DPLL1	1 E1/DS1		0	APLL2 takes its	input from DPLL2	2.
	Register bit to cor the APLL2 takes in DPLL1 is selected by Bits [5:4], DPL	ntrol MUX2 which ts input from DP I then the freque	LL2 or DPLL1. If ncy is controlled			input from DPLL1	
[5:4]	DPLL1_freq_to_A	PLL2		00	12E1, APLL2 fr	equency = 98.304	MHz.
. ,	Register to select		node of DPLL1	01		equency = 131.07	
	which is driven to	the APLL2 when	selected by Bit 6,	10		frequency = 148.2	
	APLL2_for_DPLL1	1_E1/DS1.		11	16DS1, APLL2	frequency = 98.81	L6 MHz.
3	Not used.			-	-		
[2:0]	DPLL1_frequency Register to config		y of operation of	000	77.76 MHz, dig	ital feedback, cy = 311.04 MHz.	
	DPLL1/APLL1. Th available at output	is register affect	s the frequencies	001	77.76 MHz, and	alog feedback, (via cy = 311.04 MHz.	a APLL3)
	Reg. 62.	• = • = , •	00 110g. 0 = a.i.a	010	•	equency = 98.304	MHz.
	5			011		equency = 131.07	
				100	·	frequency = 148.2	
				101		frequency = 98.81	L6 MHz.
				110	Not used.		
				111		e only selection th All other selection	

Register Name cnfg_DPLL2_bw			Description	(R/W) Register bandwidth of D	to configure the PLL2.	Default Value	0000 0000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
						DPLL2_	bandwidth
Bit No.	Description			Bit Value	Value Description	on	
[7:2]	Not used.			-	-		



Address (hex): 66 (cont...)

Register Name	e cnfg_DPLL2_bw		Description	(R/W) Register bandwidth of D	to configure the PLL2.	Default Value	0000 0000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
						DPLL2_	<u>b</u> andwidth
Bit No.	Description			Bit Value	Value Descripti	on	
[1:0]	DPLL2_bandwidth Register to configur	e the bandwi	dth of DPLL2.	00 01 10 11	DPLL2 18 Hz ba DPLL2 35 Hz ba DPLL2 70 Hz ba Not used.	andwidth.	

#### Address (hex): 67

Register Name	cnfg_DPLL1_locked_bw <b>Description</b>			(R/W) Register to configure the bandwidth of DPLL1, when phase locked to an input.		Default Value	0001 0000
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
						DPLL1_lock	ked_bandwidth
Bit No.	Description			Bit Value	Value Descriptio	n	
[7:2]	Not used.			-	-		
[1:0]	DPLL1_locked_k	pandwidth		11	DPLL1, 18 Hz lo	cked bandwidth.	
	Register to confi	gure the bandwi	idth of DPLL1 when	00	DPLL1, 35 Hz loo	cked bandwidth.	
	locked to an inp	ut reference. Re	g. 3B Bit 7 is used	01	DPLL1, 70 Hz lo	cked bandwidth.	
	to control wheth time or automat locked.		th is used all of the o when phase	10	Not used.		

Register Name cnfg_DPLL1_acq_bw		Description	. , ,	to configure the PLL1, when not o an input.	Default Value	0001 0001	
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
						DPLL1_acquisit	tion_bandwidth
Bit No.	Description			Bit Value	Value Description	on	
[7:4]	Not used.			-	-		



Address (hex): 69 (cont...)

Register Name	cnfg_DPLL1_acq	_bw	Description	. , ,	to configure the PPLL1, when not o an input.	Default Value	0001 0001
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
						DPLL1_acquisit	tion_bandwidth
Bit No.	Description			Bit Value	Value Description	on	
[3:0]	DPLL1_acquisitio	n_bandwidth		11	DPLL1, 18 Hz a	cquisition bandwi	dth.
	Register to config	gure the bandwid	dth of DPLL1 when	00	DPLL1, 35 Hz a	cquisition bandwi	dth.
	acquiring phase l	ock on an input	reference. Reg. 3B	01	DPLL1, 70 Hz a	cquisition bandwi	dth.
	Bit 7 is used to conot used or autor phase locked.			10	Not used.		

Register Name	cnfg_DPLL2_damping	g Des	Description	damping factor	to configure the of DPLL2, along f Phase Detector 2 s.	Default Value	0001 0011
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
	DPLL2_	_PD2_gain_alog				DPLL2_dampin	g
Bit No.	Description			Bit Value	Value Description	n	
7	Not used.			-	-		
[6:4]	DPLL2_PD2_gain_alo Register to control the This setting is only use cnfg_DPLL2_PD2_gai	e gain of the Phase ed if Reg. 6C Bit 7		-		e Phase Detector nce in analog feed	2 when locking to lback mode.
3	Not used.			-	-		



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Address (hex): 6A (cont...)

Register Name	cnfg_DPLL2_damping	Description	damping factor	to configure the r of DPLL2, along f Phase Detector 2 S.	Default Value	0001 0011	
Bit 7	Bit 6	Bit 5 Bit 4	Bit 3	Bit 2	Bit 1	Bit O	
	DPLL2_F	PD2_gain_alog			DPLL2_damping		
Bit No.	Description	Bit Value	Value Descriptio	n			
[2:0]	The bit values correspond	ne damping factor of DPLL2.		Damping Factor for Bandwidth of 18 Hz:	Damping Factor for Bandwidth of 35 Hz:	Damping Factor for Bandwidth of 70 Hz:	
	ractors, depending on t	he bandwidth selected.	001	1.2	1.2	1.2	
	The Gain Peak for the Description (right	Damping Factors given in the t) are tabulated below:	010	2.5	2.5	2.5	
			011	5	5	5	
	Damping Factor	Gain Peak	100	5	10	10	
	1.2 2.5 5 10 20	0.4 dB 0.2 dB 0.1 dB 0.06 dB 0.03 dB	101	5	10	20	

Register Name	Bit 6 Bit 5  DPLL1_PD2_gain_alog_		Description	. , , .		Default Value	0001 0100
Bit 7			Bit 4	Bit 3	Bit 2	Bit 1	Bit O
			log_8k		DPLL1_damping		
Bit No.	Description			Bit Value	Value Description	on	
7	Not used.			-	-		
[6:4]	when locking to a analog feedback r	I the gain of th reference of 8 mode. This sett lection is enabl		-		e Phase Detector nce in analog feed	_
3	Not used.			-	-		



Address (hex): 6B (cont...)

Register Name	cnfg_DPLL1_da	mping	Description	(R/W) Register to configure the damping factor of DPLL1, along with the gain of the Phase Detector 2 in some modes.				
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O	
	DPI	LL1_PD2_gain_ald	og_8k			DPLL1_damping		
Bit No.	Description			Bit Value	Value Description			
[2:0]	The bit values co	igure the damping orrespond to diffe	rent damping		Damping Factor for Bandwidth of 18 Hz:	Damping Factor for Bandwidth of 35 Hz:	Damping Factor for Bandwidth of 70 Hz:	
	ractors, depend	ing on the bandwi	ath selected.	001	1.2	1.2	1.2	
		or the Damping Fa on (right) are the s	actors given in the ame as those	010	2.5	2.5	2.5	
	tabulated in the	description for Re	eg. 6A.	011	5	5	5	
				100	5	10	10	
				101	5	10	20	

Register Name	cnfg_DPLL2_PD2	2_gain	Description	(R/W) Register to configure the <b>Default Value</b> 1100 gain of Phase Detector 2 in some modes for DPLL2.			1100 0010
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
DPLL2_PD2_ gain_enable					LL2_PD2_gain_c	ligital	
Bit No.	Description			Bit Value	Value Descriptio	n	
7	DPLL2_PD2_gain_enable			0 1	DPLL2 Phase De DPLL2 Phase De gain determined - digital feedback - analog feedback	tector 2 gain ena according to the mode	bled and choice of
[6:3]	Not used.			-	-		
[2:0]	DPLL2_PD2_gain Register to contr when locking in c is always used if DPLL2_PD2_gain	ol the gain of P digital feedback gain is disabled	mode. This setting	-	Gain value of Pha digital feedback		hen locking in





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Register Name	cnfg_DPLL1_PD2	2_gain	Description		to configure the Detector 2 in some L1.	Default Value	1100 0010
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
DPLL1_PD2_ gain_enable	DF	PLL1_PD2_gain_a	alog		DP	LL1_PD2_gain_o	ligital
Bit No.	Description			Bit Value	Value Descriptio	n	
7	DPLL1_PD2_gair	n_enable		0	DPLL1 Phase De	etector 2 not used	i.
				1		according to the k mode k mode	bled and choice of locking mode:
[6:4]	when locking to a analog feedback	ol the gain of Pha a reference, highe mode. This settir election is disable	er than 8 kHz, in ng is not used if	-		ase Detector 2 w eference in analo	hen locking to a g feedback mode.
3	Not used.			-	-		
[2:0]	when locking to a mode. Automatic (Bit 7, DPLL1_PD	n_digital ol the gain of Pha a reference in dig c gain selection m D2_gain_enable), n_digital to have a	ital feedback ust be enabled for	-		ase Detector 2 w tal feedback mod	hen locking to any e.



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Register Name	cnfg_phase_loss	s_fine_limit	Description		to configure some ers of the DPLL rs.	Default Value	1010 0010
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
fine_limit_en	noact_ph_loss	narrow_en			p	hase_loss_fine_l	imit
Bit No.	Description			Bit Value	Value Descriptio	n	
7	Bits [2:0]. When determined by the	Reg. 74,	lock/loss is	0 1	Phase loss trigge		ed by other means. error exceeds the fine_limit,
6	rapidly. Normally condition, it does and will phase to when a source b giving tolerance indicated, then finstigated (±360)	ock to the nearest ecomes available to missing cycles requency and pha o locking). This bi o indicate phase l	detects this ase lock to be lost edge (±180°) again, hence If phase loss is ase locking is t can be used to	0 1	indication.	ference does not ers phase lost ind	trigger phase lost ication.
5	narrow_en (test Set to 1 (default			0 1	Do not use. Set to 1.		
[4:3]	Not used.			-	-		
[2:0]	the phase limit a lost or locked. The window size of a position of the inthe window limit indicates phase any time then pheror most cases the satisfactory. The to the value, so a lost of the value of the value, so a lost of the value of the value	y Bit 7, this regist which the device the default value of the default value of the default to the DPLL for 1 - 2 seconds lock. If it is outside as loss is immended window size chains a value of 1 (001)	e indicates phase of 2 (010) gives a 80°). The phase has to be within a before the device the window for diately indicated.	000 001 010 011 100 101 110 111	Small phase win Recommended v ) )	cates phase loss of dow for phase loo value. vindow for phase	ck indication.





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DATASHEET

Address (hex): 74 s h e

Register Name	ame cnfg_phase_loss_coarse_limit		Description	(R/W) Register to configure some of the parameters of DPLL phase detectors.		Default Value	1110 0101	
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O	
coarse_lim_ phaseloss_en	wide_range_en	multi_ph_resp			phase_loss_	_coarse_limit		
Bit No.	Description			Bit Value	Value Descriptio	n		
7	coarse_lim_phas Register bit to er	nable the coarse p	ohase detector,	0	Phase loss not tr detector.	riggered by the co	oarse phase lock	
	whose range is d phase_loss_coar sets the limit in that the input ph indicates phase	rse_limit Bits [3:0 he number of inpo ase can move by	ut clock cycles (UI)	Phase loss triggered when phase error exce limit programmed in phase_loss_coarse_lin				
6	of applied jitter a the input frequer range phase dete employed. This b detector. This all and therefore ke	and still do direct ney rate (up to 77 ector and phase I bit enables the widows the device to the track of, drifts. The range of the register used for	.76 MHz), a wide ock detector is de range phase be tolerant to, in input phase of phase detector is	0 1	Wide range phas Wide range phas			
5	multi_ph_resp Enables the phase detector to be us should also be se	sed in the DPLL a	lgorithm. Bit 6	0	DPLL phase detector limited to $\pm 360^{\circ}$ ( $\pm 1$ UI). However it will still remember its original phase position over many thousands of UI if Bit 6 is se			
	coarse phase de over many thous excellent jitter ar enables that pha algorithm, so tha a faster pull-in of the phase measu can give a slower frequencies, but overshoot.  Setting this bit in with a 19.44 MH	tector can measurands of input cycle and wander tolerar use result to be used to a large phase measurement is limited at pull-in rate at his could also be used to direct locking measurement, would give as a 19.44 MHz, where the input	re and keep track les, thus allowing nee. This bit sed in the DPLL easurement gives bit is not set then d to ±360° which gher input ed to give less ode, for example we the same z input used with	1	DPLL phase dete phase detector r ±360° x 8191 UI	esult. It can now	measure up to:	
4	Not used.			-	-			



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Address (hex): 74 (cont...)

Register Name	cnfg_phase_loss_coarse_limit <b>Desc</b>		Description	· / / O	to configure some ers of DPLL phase	Default Value	1110 0101	
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O	
coarse_lim_ phaseloss_en	wide_range_en	multi_ph_resp		phase_loss_coarse_limit				
Bit No.	Description			Bit Value	Value Description	n		
[3:0]	phase_loss_coarse_limit			0000	Input phase error tracked over ±1 UI.			
	•	f the coarse phas	e loss detector	0001	Input phase erro			
	and the coarse p			0010	Input phase error tracked over ±7 UI.			
	_	a high frequency		0011	Input phase error tracked over ±15 UI.			
		r than 0.5 UI is re		0100	Input phase error tracked over ±31 UI.			
		figured to track p		0101	Input phase error tracked over ±63 UI.			
	, .	c periods. This is p	•	0110	Input phase error tracked over ±127 UI.			
	· ·	ndwidths. This reg	_	0111	Input phase error			
	•	er which the input	•	1000	Input phase error tracked over ±511 UI.			
		ets the range of the	•	1001	Input phase error tracked over ±1023 UI.			
	,		vith or without the	1010	Input phase error tracked over ±2047 UI.			
	•	apture range capa	•	1011	Input phase error tracked over ±4095 UI. Input phase error tracked over ±8191 UI.			
	inis register valt	ue is used by Bits	o and 7.	1100-1111	input phase error	r tracked over ±8	3191 UI.	

Register Name	cnfg_ip_noise_window		Description	(R/W) Register to enable the noise rejection function for low frequency inputs.		Default Value	0000 0110
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
ip_noise_ window_en							
Bit No.	Description			Bit Value	Value Descripti	on	
7	feature ensures to outside the 5% w	nable a window lency inputs (2, that any edge chindow where the lered within the se hit when a lo	4 and 8 kHz). This aused by noise ne edge is expected DPLL. This reduces ow-frequency	0 1		all edges for phas	•
[6:0]	Not used.			-	-		





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Register Name	cnfg_sync_pulses		Description	(R/W) Register to configure the Sync outputs available from FrSync and MFrSync and select the source for the 2 kHz and 8 kHz outputs from 01 and 02.		Default Value	0000 0000	
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O	
2k_8k_from_ DPLL2				8k_invert	8k_pulse	2k_invert	2k_pulse	
Bit No.	Description			Bit Value	Value Descript	ion		
7	2k_8k_from_DPLL2 Register to select the the 2 kHz and 8 kHz 02.			0 1		and 02 generated and 02 generated		
[6:4]	Not used.			-	-			
3	8k_invert Register bit to invert the 8 kHz output from FrSync.			0 1	8 kHz FrSync output not inverted. 8 kHz FrSync output inverted.			
2	8k_pulse Register bit to enable the 8 kHz output from FrSync to be either pulsed or 50:50 duty cycle. Output 02 must be enabled to use "pulsed output" mode on the FrSync output, and then the pulse width on the FrSync output will be equal to the period of the output programmed on 02.			0	8 kHz FrSync output not pulsed. 8 kHz FrSync output pulsed.			
1	2k_invert Register bit to invert MFrSync.	the 2 kHz ou	tput from	0 1	2 kHz MFrSync output not inverted. 2 kHz MFrSync output inverted.			
0	2k_pulse Register bit to enabl MFrSync to be either Output 03 must be e mode on the MFrSyn width on the MFrSyn period of the output	r pulsed or 50 enabled to use nc output, and c output will b	2:50 duty cycle.  e "pulsed output"  I then the pulse  be equal to the	0	2 kHz MFrSync 2 kHz MFrSync	output not pulsed output pulsed.		





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Register Name	ne cnfg_LOS_alarm		Description	(R/W) Register to configure LOS (Loss of Signal) Alarm.		Default Value	0000 0010
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit O
					LOS_GPO_en	LOS_tristate_en	LOS_ polarity
Bit No.	Description			Bit Value	Value Description	on	
[7:3]	Not used.			-	-		
2	LOS_GPO_en (General Purpose Output). If the LOS_ALARM output pin is not required, then setting this bit will allow the pin to be used as a general purpose output. The pin will be driven to the state of the polarity control bit, int polarity.				LOS_ALARM output pin used for interrupts. LOS_ALARM output pin used for GPO purpose.		
1	LOS_tristate_en The LOS_ALARM pir connected directly t with other sources.			0 1		always driven whe only driven when a n inactive.	
0	LOS_polarity The LOS_ALARM pir High or Low.	n can be conf	igured to be active	0 1	•	driven Low to indic driven High to indi	





Register Name cnfg_protection			Description	(R/W) Protection register to protect against erroneous software writes.		Default Value	1000 0101
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
			protecti	on_value			
Bit No.	Description			Bit Value	Value Description		
[7:0]	protection_value This register can be software writes a specific control or c			0000 0000 - 1000 0100	Protected mode.		
	before being able to device. Three mode	modify any ot	her register in the	1000 0101	Fully unprotected.		
	(i) protected, (ii) fully unprotected	d,		1000 0110	Single unprotecte	d.	
	(iii) single unprotec			1000 0111 -	Protected mode.		
	When protected, no be written to. When register in the devic unprotected, only o the device automat NoteThis register	fully unproted ce can be writte ne register car ically re-proted	ted, any writeable en to. When single be written before ets itself.	1111 1111			

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#### Electrical Specifications

#### **JTAG**

The JTAG connections on the ACS8526 allow a full boundary scan to be made. The JTAG implementation is fully compliant to IEEE 1149.1<sup>[4]</sup>, with the following minor exceptions, and the user should refer to the standard for further information.

- The output boundary scan cells do not capture data from the core, and so do not support INTEST. However this does not affect board testing.
- In common with some other manufacturers, pin TRST is internally pulled Low to disable JTAG by default. The standard is to pull High. The polarity of TRST is as the standard: TRST High to enable JTAG boundary scan mode, TRST Low for normal operation.

The JTAG timing diagram is shown in Figure 9.

#### **Over-voltage Protection**

The ACS8526 may require Over-voltage Protection on input reference clock ports according to ITU recommendation K.41<sup>[10]</sup>. Semtech protection devices are recommended for this purpose (see separate Semtech data book).

#### **ESD Protection**

Suitable precautions should be taken to protect against electrostatic damage during handling and assembly. This device incorporates ESD protection structures that protect the device against ESD damage at ESD input levels up to at least +/2kV using the Human Body Model (HBD) MIL-STD-883D Method 3015.7, for all pins.

#### **Latchup Protection**

This device is protected against latchup for input current pulses of magnitude up to at least ±100 mA to JEDEC Standard No. 78 August 1997.

Figure 9 JTAG Timing

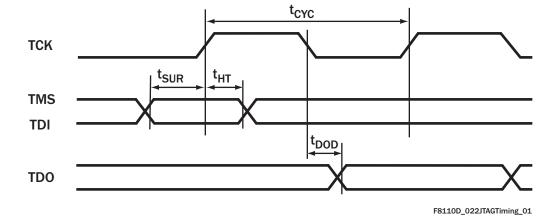


Table 18 JTAG Timing (for use with Figure 9)

Parameter	Symbol	Minimum	Typical	Maximum	Units
Cycle Time	t <sub>CYC</sub>	50	-	-	ns
TMS/TDI to TCK rising edge time	t <sub>SUR</sub>	3	-	-	ns
TCK rising to TMS/TDI hold time	t <sub>HT</sub>	23	-	-	ns
TCK falling to TDO valid	t <sub>DOD</sub>	-	-	5	ns



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## **Maximum Ratings**

Important Note: The Absolute Maximum Ratings, Table 19, are stress ratings only, and functional operation of the device at conditions other than those indicated in the Operating Conditions sections of this specification are not implied. Exposure to the absolute maximum ratings for an extended period may reduce the reliability or useful lifetime of the product.

Table 19 Absolute Maximum Ratings

Parameter	Symbol	Minimum	Maximum	Units
Supply Voltage VDD1, VDD2, VDD3, VD1+,VD2+, VD3+, VA1+, VA2+, VA3+, VDD_DIFF	$V_{DD}$	-0.5	3.6	V
Input Voltage (non-supply pins)	V <sub>IN</sub>	-	5.5	V
Output Voltage (non-supply pins)	V <sub>OUT</sub>	-	5.5	V
Ambient Operating Temperature Range	T <sub>A</sub>	-40	+85	°C
Storage Temperature	T <sub>STOR</sub>	-50	+150	°C

## **Operating Conditions**

#### **Table 20 Operating Conditions**

Parameter	Symbol	Minimum	Typical	Maximum	Units
Power Supply (dc voltage) VDD1, VDD2, VDD3, VD1+,VD2+, VD3+, VA1+, VA2+, VA3+, VDD_DIFF	V <sub>DD</sub>	3.0	3.3	3.6	V
Power Supply (dc voltage) VDD5V	V <sub>DD5V</sub>	3.0	3.3/5.0	5.5	V
Ambient Temperature Range	T <sub>A</sub>	-40	-	+85	οС
Supply Current (Typical - one 19 MHz output)	I <sub>DD</sub>		110	200	mA
Total Power Dissipation	P <sub>TOT</sub>		360	720	mW

#### **DC** Characteristics

#### Table 21 DC Characteristics: TTL Input Port

Across all operating conditions, unless otherwise stated

PARAMETER	Symbol	Minimum	Typical	Maximum	Units
V <sub>IN</sub> High	V <sub>IH</sub>	2	-	-	V
V <sub>IN</sub> Low	V <sub>IL</sub>	-	-	0.8	V
Input Current	I <sub>IN</sub>	-	-	10	μА



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#### Table 22 DC Characteristics: TTL Input Port with Internal Pull-up

Across all operating conditions, unless otherwise stated

Parameter	Symbol	Minimum	Typical	Maximum	Units
V <sub>IN</sub> High	$V_{IH}$	2	-	-	V
V <sub>IN</sub> Low	V <sub>IL</sub>	-	-	0.8	V
Pull-up Resistor	PU	25	-	95	kΩ
Input Current	I <sub>IN</sub>	-	-	120	μΑ

#### Table 23 DC Characteristics: TTL Input Port with Internal Pull-down

Across all operating conditions, unless otherwise stated

Parameter	Symbol	Minimum	Typical	Maximum	Units
V <sub>IN</sub> High	V <sub>IH</sub>	2	-	-	V
V <sub>IN</sub> Low	V <sub>IL</sub>	-	-	0.8	V
Pull-down Resistor (except TCK input)	PD	25	-	95	kΩ
Pull-down Resistor (TCK input only)	PD	12.5	-	47.5	kΩ
Input Current	I <sub>IN</sub>	-	-	120	μΑ

#### Table 24 DC Characteristics: TTL Output Port

Across all operating conditions, unless otherwise stated

Parameter	Symbol	Minimum	Typical	Maximum	Units
$V_{OUT}$ Low ( $I_{OL} = 4$ mA)	V <sub>OL</sub>	0	-	0.4	V
V <sub>OUT</sub> High (I <sub>OH</sub> = 4mA)	V <sub>OH</sub>	2.4	-	-	V
Drive Current	I <sub>D</sub>	-	-	4	mA

#### Table 25 DC Characteristics: PECL Output Port

Across all operating conditions, unless otherwise stated

Parameter	Symbol	Minimum	Typical	Maximum	Units
PECL Output Low Voltage (Note (i))	V <sub>OLPECL</sub>	V <sub>DD</sub> -2.10	-	V <sub>DD</sub> -1.62	V
PECL Output High Voltage (Note (i))	V <sub>OHPECL</sub>	V <sub>DD</sub> -1.25	-	V <sub>DD</sub> -0.88	V
PECL Output Differential Voltage (Note (i))	V <sub>ODPECL</sub>	580	-	900	mV

Note: (i) With 50  $\Omega$  load on each pin to V<sub>DD</sub>-2 V, i.e. 82  $\Omega$  to GND and 130  $\Omega$  to V<sub>DD</sub>.



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Figure 10 Recommended Line Termination for PECL Output Port

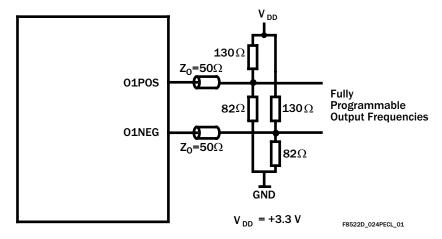


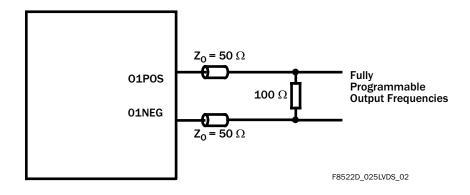
Table 26 DC Characteristics: LVDS Output Port

Across all operating conditions, unless otherwise stated

Parameter	Symbol	Minimum	Typical	Maximum	Units
LVDS Output High Voltage (Note (i))	V <sub>OHLVDS</sub>	-	-	1.585	V
LVDS Output Low Voltage (Note (i))	V <sub>OLLVDS</sub>	0.885	-	-	V
LVDS Differential Output Voltage	V <sub>ODLVDS</sub>	250	-	450	mV
LVDS Change in Magnitude of Differential Output Voltage for complementary States (Note (i))	V <sub>DOSLVDS</sub>	-	-	25	mV
LVDS Output Offset Voltage Temperature = 25°C (Note (i))	V <sub>OSLVDS</sub>	1.125	-	1.275	V

Notes: (i) With 100  $\Omega$  load between the differential outputs.

Figure 11 Recommended Line Termination for LVDS Output Port





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### **Jitter Performance**

Output jitter generation measured over 60 second interval, UI p-p max measured using C-MAC E2747 12.8 MHz TCXO on ICT Flexacom tester.

Table 27 Output Jitter Generation at 35 Hz bandwidth and 8 kHz Input

Test Definition	Jitter Spec	ACS8526 Jitter	
Specification	Filter	UI	UI (TYP)
$G813^{[8]}$ for 155 MHz o/p option 1	65 kHz - 1.3 MHz	0.1 p-p	0.073 р-р
G813 <sup>[8]</sup> & G812 <sup>[7]</sup> for 2.048 MHz option 1	20 Hz - 100 kHz	0.05 p-p	0.012 p-p
G813 <sup>[8]</sup> for 155 MHz o/p option 2	12 kHz - 1.3 MHz	0.1 p-p	0.069 р-р
G812 <sup>[7]</sup> for 1.544 MHz o/p	10 Hz - 40 kHz	0.05 p-p	0.011 p-p
G812 <sup>[7]</sup> for 155 MHz electrical	500 Hz - 1.3 MHz	0.5 p-p	0.083 р-р
G812 <sup>[7]</sup> for 155 MHz electrical	65 kHz - 1.3 MHz	0.075 p-p	0.073р-р
ETS-300-462-3 <sup>[2]</sup> for 2.048 MHz SEC o/p	20 Hz - 100 kHz	0.5 р-р	0.012 p-p
ETS-300-462-3 <sup>[2]</sup> for 2.048 MHz SEC o/p	49 Hz - 100 kHz	0.2 p-p	0.012 р-р
ETS-300-462-3 <sup>[2]</sup> for 2.048 MHz SSU o/p	20 Hz - 100 kHz	0.05 p-p	0.012 р-р
ETS-300-462-5 <sup>[3]</sup> for 155 MHz o/p	500 Hz - 1.3 MHz	0.5 p-p	0.083 р-р
ETS-300-462-5 <sup>[3]</sup> for 155 MHz o/p	65 kHz - 1.3 MHz	0.1 p-p	0.073 р-р
GR-253-CORE <sup>[11]</sup> net i/f, 51.84 MHz o/p	100 Hz - 0.4 MHz	1.5 p-p	0.038 p-p
GR-253-CORE <sup>[11]</sup> net i/f, 51.84 MHz o/p	20 kHz to 0.4 MHz	0.15 p-p	0.019 p-p
GR-253-CORE <sup>[11]</sup> net i/f, 155 MHz o/p	500 Hz - 1.3 MHz	1.5 p-p	0.083 р-р
GR-253-CORE <sup>[11]</sup> net i/f, 155 MHz o/p	65 kHz - 1.3 MHz	0.15 p-p	0.073 р-р
GR-253-CORE <sup>[11]</sup> cat II elect i/f, 155 MHz	12 kHz - 1.3 MHz	0.1 p-p	0.069 р-р
		0.01 rms	0.009 rms
GR-253-CORE <sup>[11]</sup> cat II elect i/f, 51.84 MHz	12 kHz - 400 kHz	0.1 p-p	0.008 р-р
		0.01 rms	0.004 rms
GR-253-CORE <sup>[11]</sup> DS1 i/f, 1.544 MHz	10 Hz - 40 kHz	0.1 p-p	0.001 p-p
		0.01 rms	<0.001 rms
AT&T 62411 <sup>[1]</sup> for 1.544 MHz	10 Hz - 8 kHz	0.02 rms	<0.001 rms
AT&T 62411 <sup>[1]</sup> for 1.544 MHz	8 Hz - 40 kHz	0.025 rms	<0.001 rms
AT&T 62411 <sup>[1]</sup> for 1.544 MHz	10 Hz - 40 kHz	0.025 rms	<0.001 rms
AT&T 62411 <sup>[1]</sup> for 1.544 MHz	Broadband	0.05 rms	<0.001 rms
G-742 <sup>[6]</sup> for 2.048 MHz	DC - 100 kHz	0.25 rms	0.012 rms
G-742 <sup>[6]</sup> for 2.048 MHz	18 kHz - 100 kHz	0.05 p-p	0.012 p-p
G-736 <sup>[5]</sup> for 2.048 MHz	20 Hz - 100 kHz	0.05 p-p	0.012 p-p





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Table 27 Output Jitter Generation at 35 Hz bandwidth and 8 kHz Input (cont...)

Test Definition	Jitter Spec	ACS8526 Jitter	
Specification	Filter	UI	UI (TYP)
GR-499-CORE <sup>[12]</sup> & G824 <sup>[9]</sup> for 1.544 MHz	10 Hz - 40kHz	5.0 р-р	0.001 p-p
GR-499-CORE <sup>[12]</sup> & G824 <sup>[9]</sup> for 1.544 MHz	8 kHz - 40kHz	0.1 p-p	0.001 p-p
GR-1244-CORE <sup>[13]</sup> for 1.544 MHz	> 10 Hz	0.05 p-p	0.001 p-p

Note...This table is only for comparing the ACS8526 output jitter performance against values and quoted in various specifications for given conditions. It should not be used to infer compliance to any other aspects of these specifications.

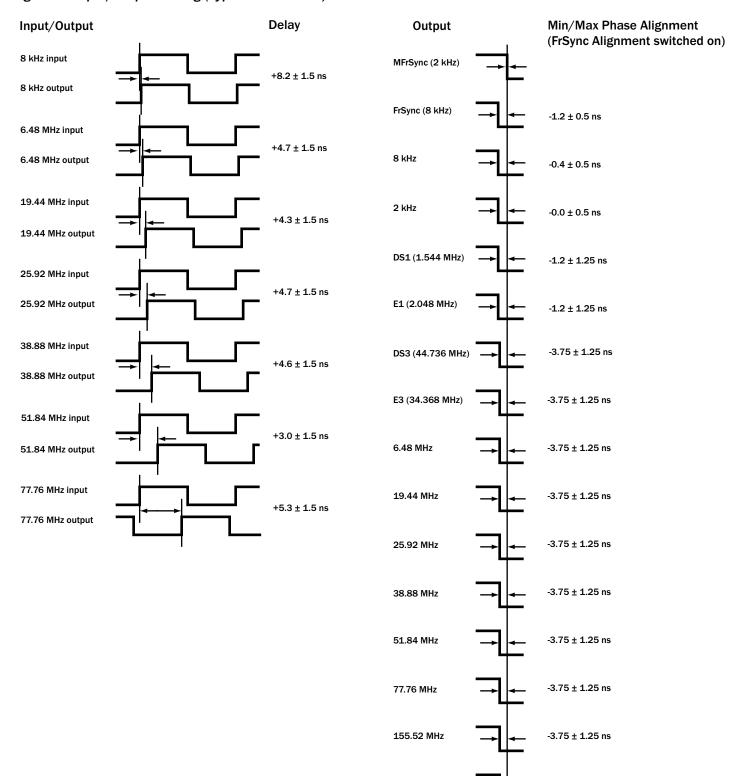


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## Input/Output Timing

Figure 12 Input/Output Timing (Typical Conditions)



F8526D\_021IP\_0PTiming\_03

-3.75 ± 1.25 ns

311.04 MHz

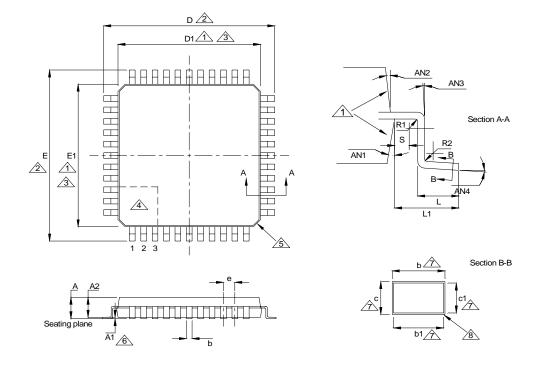


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## Package Information

Figure 13 LQFP Package



#### Notes

 $\stackrel{\frown}{\Lambda}$  The top package body may be smaller than the bottom package body by as much as 0.15 mm.

To be determined at seating plane.

Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is 0.25 mm per side. D1 and E1 are maximum plastic body size dimensions including mold mismatch.

Details of pin 1 identifier are optional but will be located within the zone indicated.

Exact shape of corners can vary.

A1 is defined as the distance from the seating plane to the lowest point of the package body.

These dimensions apply to the flat section of the lead between 0.10 mm and 0.25 mm from the lead tip.

8 Shows plating.

Table 28 64 Pin LQFP Package Dimension Data (for use with Figure 13)

Dimensions in mm	D/E	D1/ E1	A	<b>A1</b>	A2	е	AN1	AN2	AN3	AN4	R1	R2	L	L1	S	b	<b>b1</b>	С	<b>c1</b>
Min.			1.40	0.05	1.35		11º	11º	0°	0°	0.08	0.08	0.45		0.20	0.17	0.17	0.09	0.09
Nom.	12.00	10.00	1.50	0.10	1.40	0.50	12°	12°	-	3.5°	-	-	0.60	1.00 (ref)	-	0.22	0.20	-	-
Max.			1.60	0.15	1.45		13°	13°	-	7°	-	0.20	0.75		-	0.27	0.23	0.20	0.16



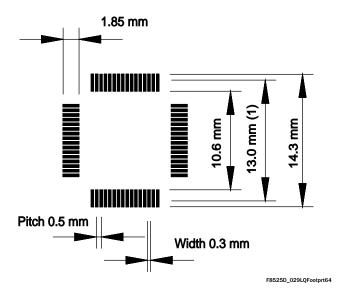
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### **Thermal Conditions**

The device is rated for full temperature range when this package is used with a 4 layer or more PCB. Copper coverage must exceed 50%. All pins must be soldered to the PCB. Maximum operating temperature must be reduced when the device is used with a PCB with less than these requirements.

Figure 14 Typical 64-Pin LQFP Package Landing Pattern



Notes: (i) Solderable to this limit.

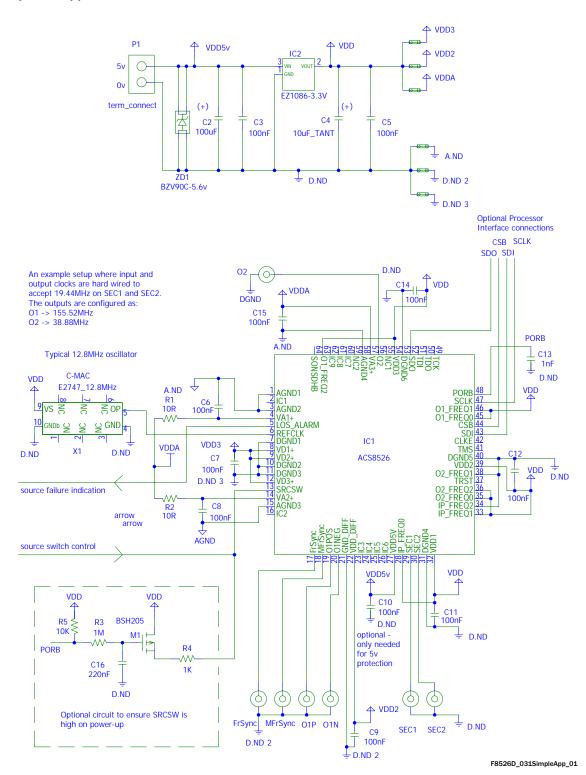
- (ii) Square package dimensions apply in both X and Y directions.
- (iii) Typical example. The User is responsible for ensuring compatibility with PCB manufacturing process, etc.

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#### Application-Information

Figure 15 Simplified Application Schematic





#### Abbreviations U.com References

APLL Analogue Phase Locked Loop
BITS Building Integrated Timing Supply

DFS Digital Frequency Synthesis
DPLL Digital Phase Locked Loop
DS1 1544 kbit/s interface rate

DTO Discrete Time Oscillator
E1 2048 kbit/s interface rate

I/O Input - Output LOS Loss Of Signal

LQFP Low profile Quad Flat Pack
LVDS Low Voltage Differential Signal
MTIE Maximum Time Interval Error

NE Network Element PBO Phase Build-out

PDH Plesiochronous Digital Hierarchy

PD2 Phase Detector 2

PECL Positive Emitter Coupled Logic
PFD Phase and Frequency Detector

PLL Phase Locked Loop
POR Power-On Reset
ppb parts per billion
ppm parts per million
p-p peak-to-peak
R/W Read/Write

rms root-mean-square

RO Read Only

RoHS Restrictive Use of Certain Hazardous

Substances (directive)

SDH Synchronous Digital Hierarchy
SEC SDH/SONET Equipment Clock

SETS Synchronous Equipment Timing source

SONET Synchronous Optical Network
SSU Synchronization Supply Unit
STM Synchronous Transport Module

TDEV Time Deviation

TCXO Temperature Compensated Crystal

Oscillator

UI Unit Interval

WEEE Waste Electrical and Electronic

Equipment (directive)

XO Crystal Oscillator

[1] AT & T 62411 (12/1990)

ACCUNET® T1.5 Service description and Interface

Specification

[2] ETSI ETS 300 462-3, (01/1997)

Transmission and Multiplexing (TM); Generic

requirements for synchronization networks; Part 3: The control of jitter and wander within synchronization

networks

[3] ETSI ETS 300 462-5 (09/1996)

Transmission and Multiplexing (TM); Generic

requirements for synchronization networks; Part 5: Timing characteristics of slave clocks suitable for operation in Synchronous Digital Hierarchy (SDH) equipment

[4] IEEE 1149.1 (1990)

Standard Test Access Port and Boundary-Scan

Architecture

[5] ITU-T G.736 (03/1993)

Characteristics of a synchronous digital multiplex

equipment operating at 2048 kbit/s

[6] ITU-T G.742 (1988)

Second order digital multiplex equipment operating at

8448 kbit/s, and using positive justification

[7] ITU-T G.812 (06/1998)

Timing requirements of slave clocks suitable for use as

node clocks in synchronization networks

[8] ITU-T G.813 (08/1996)

Timing characteristics of SDH equipment slave clocks

(SEC)

[9] ITU-T G.824 (03/2000)

The control of jitter and wander within digital networks

which are based on the 1544 kbit/s hierarchy

[10] ITU-T K.41 (05/1998)

Resistability of internal interfaces of telecommunication

centres to surge overvoltages

[11] Telcordia GR-253-CORE, Issue 3 (09/ 2000)

Synchronous Optical Network (SONET) Transport Systems: Common Generic Criteria

[12] Telcordia GR-499-CORE, Issue 2 (12/1998)

Transport Systems Generic Requirements (TSGR)

Common requirements

[13] Telcordia GR-1244-CORE, Issue 2 (12/2000)

Clocks for the Synchronized Network: Common Generic

Criteria





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### Trademark Acknowledgements

Notes

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**DATASHEET** 

### Revision Status/History

The Revision Status of the datasheet, as shown in the center of the datasheet header bar, may be DRAFT, PRELIMINARY, or FINAL, and refers to the status of the Device (not the datasheet) within the design cycle. DRAFT status is used when the design is being realized but is not yet physically available, and the datasheet content reflects the intention of the design. The datasheet is raised to PRELIMINARY status when initial prototype devices are physically available, and the datasheet content more accurately represents the realization of the design. The datasheet is only raised to FINAL status after

the device has been fully characterized, and the datasheet content updated with measured, rather than simulated parameter values.

This is a FINAL release (Revision 4.01) of the ACS8526 datasheet. Changes made for this document revision are given in Table 29, together with a summary of previous revisions. For specific changes between earlier revisions, refer (where available) to those earlier revisions. Always use the current version of the datasheet.

Table 29 Revision History

Revision	Reference	Description of changes
2.00/ December 2002	All pages	First full release.
3.00/ January 2003	All pages	Updated to FINAL status.
4.00/September 2003	All Pages	Major revision. All pages reformatted. General update of cross-references.
	Reg. 38, 3C, 3D, 41, 6A, and 6B	Register descriptions updated.
	Reg. 4D	New register inserted.
	Table 3 ,Table 13 , Table 15, Table 22, Table 23, Figure 2 and Figure 12	Tables and Figures updated.
	"Crystal Frequency Calibration" on page 27, "Multiplexers" on page 13, "Phase and Frequency Detectors" on page 15, "Register Map" on page 30, "JTAG" on page 61, "Abbreviations" on page 71. "Revision Status/History" on page 73	Sections updated.
	"ESD Protection" on page 61, "Latchup Protection" on page 61	New Sections inserted.
4.01/June 2006	Front and back pages and "Abbreviations" on page 71	Interim update to reflect availability of lead(Pb)-free packaged part and change to Semtech US address.
	"Trademark Acknowledgements" on page 72 and "Revision Status/History" on page 73	Minor non-technical changes.
	Back page	Taiwan address updated.



#### **FINAL**

### **DATASHEET**

#### Ordering Information

#### Table 30 Parts List

Part Number	Description
ACS8526	LC/P LITE Line Card Protection Switch for PDH, SONET or SDH Systems
ACS8526T	Lead (Pb)-free package version of ACS8526; RoHS and WEEE compliant.

#### **Disclaimers**

Life support- This product is not designed or intended for use in life support equipment, devices or systems, or other critical applications. This product is not authorized or warranted by Semtech for such use.

Right to change- Semtech Corporation reserves the right to make changes, without notice, to this product. Customers are advised to obtain the latest version of the relevant information before placing orders.

Compliance to relevant standards- Operation of this device is subject to the User's implementation and design practices. It is the responsibility of the User to ensure equipment using this device is compliant to any relevant standards.

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