

ADC1010S series

www.DataSheet4U.com

Single 10-bit ADC; 65 Msps, 80 Msps, 105 Msps or 125 Msps;
CMOS or LVDS DDR digital outputs

Rev. 01 — 9 April 2010

Preliminary data sheet

1. General description

The ADC1010S is a single-channel 10-bit Analog-to-Digital Converter (ADC) optimized for high dynamic performances and low power consumption at sample rates up to 125 Msps. Pipelined architecture and output error correction ensure the ADC1010S is accurate enough to guarantee zero missing codes over the entire operating range. Supplied from a single 3 V source, it can handle output logic levels from 1.8 V to 3.3 V in CMOS mode, thanks to a separate digital output supply. It supports the LVDS (Low Voltage Differential Signalling) DDR (Double Data Rate) output standard. An integrated SPI (Serial Peripheral Interface) allows the user to easily configure the ADC. The device also includes a SPI programmable full-scale to allow flexible input voltage range from 1 V to 2 V (peak-to-peak). With excellent dynamic performance from the baseband to input frequencies of 170 MHz or more, the ADC1010S is ideal for use in communications, imaging and medical applications.

2. Features and benefits

- SNR, 62 dBFS; SFDR, 86 dBc
- Sample rate up to 125 Msps
- 10-bit pipelined ADC core
- Clock input divider by 2 for less jitter contribution
- Single 3 V supply
- Flexible input voltage range: 1 V p-p to 2 V p-p
- CMOS or LVDS DDR digital outputs
- Pin compatible with the ADC1410S series and the ADC1210S series
- HVQFN40 package
- Input bandwidth, 600 MHz
- Power dissipation, 430 mW at 80 Msps
- Serial Peripheral Interface (SPI)
- Duty cycle stabilizer
- Fast OuT of Range (OTR) detection
- INL ± 0.07 LSB, DNL ± 0.04 LSB
- Offset binary, two's complement, gray code
- Power-down and Sleep modes

3. Applications

- Wireless and wired broadband communications
- Spectral analysis
- Ultrasound equipment
- Portable instrumentation
- Imaging systems
- Software define radio



www.DataSheet4U.com

4. Ordering information

Table 1. Ordering information

Type number	f _s (MSPs)	Package		Version
		Name	Description	
ADC1010S125HN/C1	125	HVQFN40	plastic thermal enhanced very thin quad flat package; no leads; 40 terminals; body 6 × 6 × 0.85 mm	SOT618-6
ADC1010S105HN/C1	105	HVQFN40	plastic thermal enhanced very thin quad flat package; no leads; 40 terminals; body 6 × 6 × 0.85 mm	SOT618-6
ADC1010S080HN/C1	80	HVQFN40	plastic thermal enhanced very thin quad flat package; no leads; 40 terminals; body 6 × 6 × 0.85 mm	SOT618-6
ADC1010S065HN/C1	65	HVQFN40	plastic thermal enhanced very thin quad flat package; no leads; 40 terminals; body 6 × 6 × 0.85 mm	SOT618-6

5. Block diagram

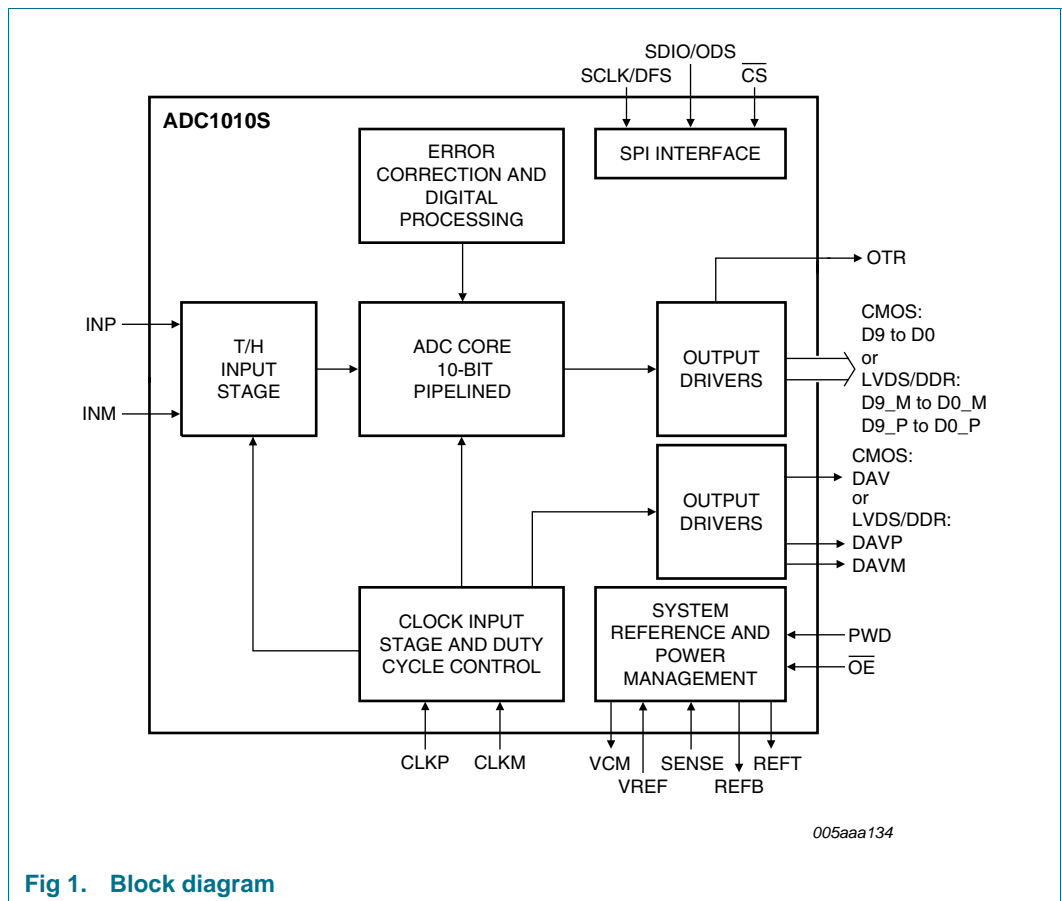
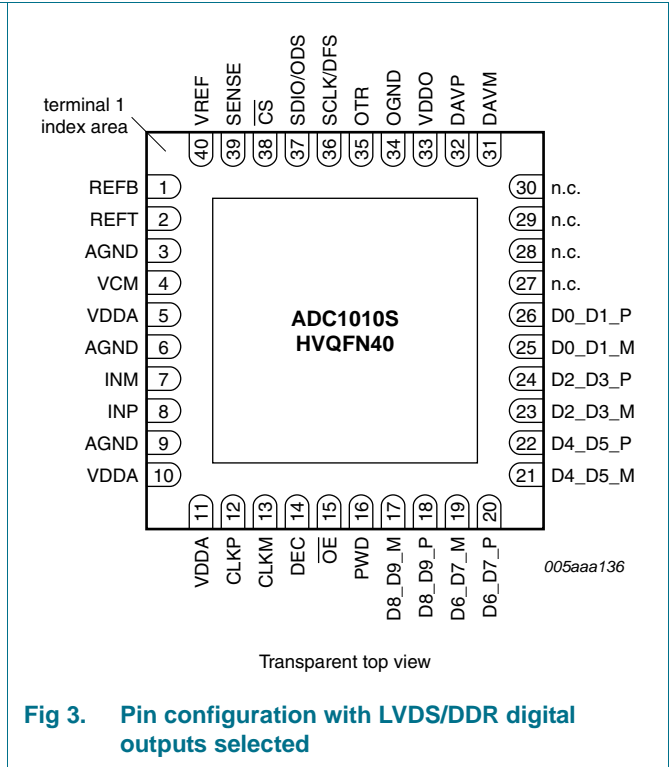
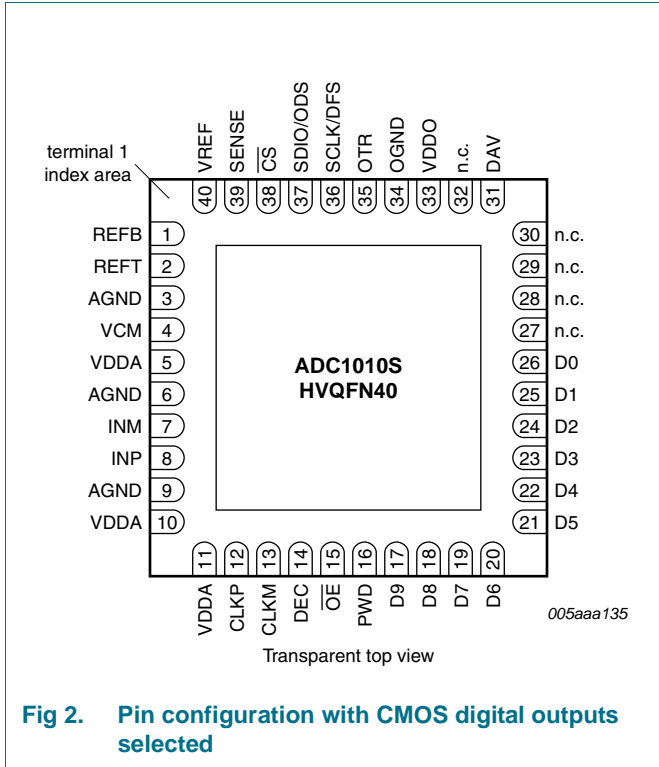


Fig 1. Block diagram

6. Pinning information

6.1 Pinning



6.2 Pin description

Table 2. Pin description (CMOS digital outputs)

Symbol	Pin	Type ^[1]	Description
REFB	1	O	bottom reference
REFT	2	O	top reference
AGND	3	G	analog ground
VCM	4	O	common-mode output voltage
VDDA	5	P	analog power supply
AGND	6	G	analog ground
INM	7	I	complementary analog input
INP	8	I	analog input
AGND	9	G	analog ground
VDDA	10	P	analog power supply
VDDA	11	P	analog power supply
CLKP	12	I	clock input
CLKM	13	I	complementary clock input
DEC	14	O	regulator decoupling node
OE	15	I	output enable, active LOW
PWD	16	I	power down, active HIGH

Table 2. Pin description (CMOS digital outputs) ...continued

Symbol	Pin	Type ^[1]	Description
D9	17	O	data output bit 9 (MSB)
D8	18	O	data output bit 8
D7	19	O	data output bit 7
D6	20	O	data output bit 6
D5	21	O	data output bit 5
D4	22	O	data output bit 4
D3	23	O	data output bit 3
D2	24	O	data output bit 2
D1	25	O	data output bit 1
D0	26	O	data output bit 0 (LSB)
n.c.	27	-	not connected
n.c.	28	-	not connected
n.c.	29	-	not connected
n.c.	30	-	not connected
DAV	31	O	data valid output clock
n.c.	32	-	not connected
VDDO	33	P	output power supply
OGND	34	G	output ground
OTR	35	O	out of range
SCLK/DFS	36	I	SPI clock data format select
SDIO/ODS	37	I/O	SPI data IO output data standard
$\overline{\text{CS}}$	38	I	SPI chip select
SENSE	39	I	reference programming pin
VREF	40	I/O	voltage reference input/output

[1] P: power supply; G: ground; I: input; O: output; I/O: input/output.

Table 3. Pin description (LVDS/DDR) digital outputs)

Symbol	Pin ^[1]	Type ^[2]	Description
D8_D9_M	17	O	differential output data D8 and D9 multiplexed, complement
D8_D9_P	18	O	differential output data D8 and D9 multiplexed, true
D6_D7_M	19	O	differential output data D6 and D7 multiplexed, complement
D6_D7_P	20	O	differential output data D6 and D7 multiplexed, true
D4_D5_M	21	O	differential output data D4 and D5 multiplexed, complement
D4_D5_P	22	O	differential output data D4 and D5 multiplexed, true
D2_D3_M	23	O	differential output data D2 and D3 multiplexed, complement
D2_D3_P	24	O	differential output data D2 and D3 multiplexed, true
D0_D1_M	25	O	differential output data D0 and D1 multiplexed, complement
D0_D1_P	26	O	differential output data D0 and D1 multiplexed, true
n.c.	27	-	not connected
n.c.	28	-	not connected
n.c.	29	-	not connected

Table 3. Pin description (LVDS/DDR) digital outputs) ...continued

Symbol	Pin ^[1]	Type ^[2]	Description
n.c.	30	-	not connected
DAVM	31	O	data valid output clock, complement
DAVP	32	O	data valid output clock, true

[1] Pins 1 to 16 and pins 33 to 40 are the same for both CMOS and LVDS DDR outputs (see [Table 2](#))

[2] P: power supply; G: ground; I: input; O: output; I/O: input/output.

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_O	output voltage	pins D9 to D0 or pins D9P to D0P and D9M to D0M	-0.4	+3.9	V
V_{DDA}	analog supply voltage		-0.4	+3.9	V
V_{DDO}	output supply voltage		-0.4	+3.9	V
T_{stg}	storage temperature		-55	+125	°C
T_{amb}	ambient temperature		-40	+85	°C
T_j	junction temperature		-	125	°C

8. Thermal characteristics

Table 5. Thermal characteristics

Symbol	Parameter	Conditions	Typ	Unit
$R_{th(j-a)}$	thermal resistance from junction to ambient		^[1] 22.5	K/W
$R_{th(j-c)}$	thermal resistance from junction to case		^[1] 11.7	K/W

[1] Value for six layers board in still air with a minimum of 25 thermal vias

9. Static characteristics

Table 6. Static characteristics^[1]

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Supplies						
V_{DDA}	analog supply voltage		2.85	3.0	3.4	V
V_{DDO}	output supply voltage	CMOS mode	1.65	1.8	3.6	V
		LVDS DDR mode	2.85	3.0	3.6	V
I_{DDA}	analog supply current	$f_{clk} = 125$ Msps; $f_i = 70$ MHz	-	210	-	mA
I_{DDO}	output supply current	CMOS mode; $f_{clk} = 125$ Msps; $f_i = 70$ MHz	-	10	-	mA
		LVDS DDR mode: $f_{clk} = 125$ Msps; $f_i = 70$ MHz	-	35	-	mA
P	power dissipation	ADC1010S125; analog supply only	-	630	-	mW
		ADC1010S105; analog supply only	-	550	-	mW
		ADC1010S080; analog supply only	-	430	-	mW
		ADC1010S065; analog supply only	-	380	-	mW
		power-down mode	-	2	-	mW
		sleep mode	-	40	-	mW
Clock inputs: pins CLKP and CLKM						
LVPECL						
$V_{i(ck)dif}$	differential clock input voltage	peak-to-peak	-	± 1.6	-	V
LVDS						
$V_{i(ck)dif}$	differential clock input voltage	peak-to-peak	-	± 0.70	-	V
SINE wave						
$V_{i(ck)dif}$	differential clock input voltage	peak-to-peak	± 0.8	± 3.0	-	V
LVC MOS						
V_{IL}	LOW-level input voltage		-	-	$0.3V_{DDA}$	V
V_{IH}	HIGH-level input voltage		$0.7V_{DDA}$	-	-	V
Logic inputs: pins PWD and OE						
V_{IL}	LOW-level input voltage		0	-	0.8	V
V_{IH}	HIGH-level input voltage		2	-	V_{DDA}	V
I_{IL}	LOW-level input current		<tb>	-	<tb>	μ A
I_{IH}	HIGH-level input current		-10	-	+10	μ A
Serial peripheral interface: pins CS, SDIO/ODS, SCLK/DFS						
V_{IL}	LOW-level input voltage		0	-	$0.3V_{DDA}$	V
V_{IH}	HIGH-level input voltage		$0.7V_{DDA}$	-	V_{DDA}	V
I_{IL}	LOW-level input current		-10	-	+10	μ A
I_{IH}	HIGH-level input current		-50	-	+50	μ A
C_i	input capacitance		-	4	-	pF

Table 6. Static characteristics^[1] ...continued

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Digital outputs, CMOS mode: pins D9 to D0, OTR, DAV						
Output levels, $V_{DDO} = 3\text{ V}$						
V_{OL}	LOW-level output voltage	$I_{OL} = <tbid>$	OGND	-	$0.2V_{DDO}$	V
V_{OH}	HIGH-level output voltage	$I_{OH} = <tbid>$	$0.8V_{DDO}$	-	V_{DDO}	V
I_{OL}	LOW-level output current	3-state; output level = 0 V	-	<tbid>	-	μA
I_{OH}	HIGH-level output current	3-state; output level = V_{DDA}	-	<tbid>	-	μA
C_O	output capacitance	high impedance; $\overline{OE} = \text{HIGH}$	-	3	-	pF
Output levels, $V_{DDO} = 1.8\text{ V}$						
V_{OL}	LOW-level output voltage	$I_{OL} = <tbid>$	OGND	-	$0.2V_{DDO}$	V
V_{OH}	HIGH-level output voltage	$I_{OH} = <tbid>$	$0.8V_{DDO}$	-	V_{DDO}	V
Digital outputs, LVDS mode: pins D9P to D0P, D9M to D0M, DAVP and DAVM						
Output levels, $V_{DDO} = 3\text{ V}$ only, $R_L = 100\ \Omega$						
$V_{O(\text{offset})}$	output offset voltage	output buffer current set to 3.5 mA	-	1.2	-	V
$V_{O(\text{dif})}$	differential output voltage	output buffer current set to 3.5 mA	-	350	-	mV
C_O	output capacitance		-	<tbid>	-	pF
Analog inputs: pins INP and INM						
I_I	input current		-5	-	+5	μA
R_I	input resistance		-	<tbid>	-	Ω
C_I	input capacitance		-	5	-	pF
$V_{I(\text{cm})}$	common-mode input voltage	$V_{INP} = V_{INM}$	0.9	1.5	2	V
B_I	input bandwidth		-	600	-	MHz
$V_{I(\text{dif})}$	differential input voltage	peak-to-peak	1		2	V
Common mode output voltage: pin VCM						
$V_{O(\text{cm})}$	common-mode output voltage		-	$V_{DDA} / 2$	-	V
$I_{O(\text{cm})}$	common-mode output current		-	<tbid>	-	μA
I/O reference voltage: pin VREF						
V_{VREF}	voltage on pin VREF	output	0.5	-	1	V
		input	0.5	-	1	V
Accuracy						
INL	integral non-linearity		-0.4	± 0.07	+0.4	LSB
DNL	differential non-linearity	guaranteed no missing codes	-0.06	± 0.04	+0.06	LSB
E_{offset}	offset error		-	± 2	-	mV
E_G	gain error	full-scale		± 0.5		%
Supply						
PSRR	power supply rejection ratio	100 mV (p-p) on V_{DDA}	-	35	-	dBc

[1] Typical values measured at $V_{DDA} = 3\text{ V}$, $V_{DDO} = 1.8\text{ V}$, $T_{\text{amb}} = 25\text{ }^\circ\text{C}$ and $C_L = 5\text{ pF}$; minimum and maximum values are across the full temperature range $T_{\text{amb}} = -40\text{ }^\circ\text{C}$ to $+85\text{ }^\circ\text{C}$ at $V_{DDA} = 3\text{ V}$, $V_{DDO} = 1.8\text{ V}$; $V_{INP} - V_{INM} = -1\text{ dBFS}$; internal reference mode; applied to CMOS and LVDS interface; unless otherwise specified.

10. Dynamic characteristics

10.1 Dynamic characteristics

Table 7. Dynamic characteristics^[1]

Symbol	Parameter	Conditions	ADC1010S065			ADC1010S080			ADC1010S105			ADC1010S125			Unit
			Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Analog signal processing															
α_{2H}	second harmonic level	$f_i = 3$ MHz	-	87	-	-	87	-	-	86	-	-	88	-	dBc
		$f_i = 30$ MHz	-	86	-	-	86	-	-	86	-	-	87	-	dBc
		$f_i = 70$ MHz	-	85	-	-	85	-	-	84	-	-	85	-	dBc
		$f_i = 170$ MHz	-	82	-	-	82	-	-	81	-	-	83	-	dBc
α_{3H}	third harmonic level	$f_i = 3$ MHz	-	86	-	-	86	-	-	85	-	-	87	-	dBc
		$f_i = 30$ MHz	-	85	-	-	85	-	-	85	-	-	86	-	dBc
		$f_i = 70$ MHz	-	84	-	-	84	-	-	83	-	-	84	-	dBc
		$f_i = 170$ MHz	-	81	-	-	81	-	-	80	-	-	82	-	dBc
THD	total harmonic distortion	$f_i = 3$ MHz	-	85	-	-	85	-	-	84	-	-	86	-	dBc
		$f_i = 30$ MHz	-	84	-	-	84	-	-	84	-	-	85	-	dBc
		$f_i = 70$ MHz	-	83	-	-	83	-	-	82	-	-	83	-	dBc
		$f_i = 170$ MHz	-	80	-	-	80	-	-	79	-	-	81	-	dBc
ENOB	effective number of bits	$f_i = 3$ MHz	-	9.9	-	-	9.9	-	-	9.9	-	-	9.9	-	bits
		$f_i = 30$ MHz	-	9.9	-	-	9.9	-	-	9.9	-	-	9.9	-	bits
		$f_i = 70$ MHz	-	9.9	-	-	9.9	-	-	9.9	-	-	9.9	-	bits
		$f_i = 170$ MHz	-	9.9	-	-	9.9	-	-	9.9	-	-	9.9	-	bits
SNR	signal-to-noise ratio	$f_i = 3$ MHz	-	61.7	-	-	61.7	-	-	61.6	-	-	61.6	-	dBFS
		$f_i = 30$ MHz	-	61.6	-	-	61.6	-	-	61.6	-	-	61.6	-	dBFS
		$f_i = 70$ MHz	-	61.6	-	-	61.6	-	-	61.5	-	-	61.5	-	dBFS
		$f_i = 170$ MHz	-	61.5	-	-	61.5	-	-	61.5	-	-	61.5	-	dBFS
SFDR	spurious-free dynamic range	$f_i = 3$ MHz	-	86	-	-	86	-	-	85	-	-	87	-	dBc
		$f_i = 30$ MHz	-	85	-	-	85	-	-	85	-	-	86	-	dBc
		$f_i = 70$ MHz	-	84	-	-	84	-	-	83	-	-	84	-	dBc
		$f_i = 170$ MHz	-	81	-	-	81	-	-	80	-	-	82	-	dBc

Table 7. Dynamic characteristics^[1] ...continued

Symbol	Parameter	Conditions	ADC1010S065			ADC1010S080			ADC1010S105			ADC1010S125			Unit
			Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
IMD	Intermodulation distortion	$f_i = 3 \text{ MHz}$	-	89	-	-	89	-	-	88	-	-	89	-	dBc
		$f_i = 30 \text{ MHz}$	-	88	-	-	88	-	-	88	-	-	88	-	dBc
		$f_i = 70 \text{ MHz}$	-	87	-	-	87	-	-	86	-	-	86	-	dBc
		$f_i = 170 \text{ MHz}$	-	84	-	-	85	-	-	83	-	-	84	-	dBc

[1] Typical values measured at $V_{DDA} = 3 \text{ V}$, $V_{DDO} = 1.8 \text{ V}$, $T_{amb} = 25 \text{ °C}$ and $C_L = 5 \text{ pF}$; minimum and maximum values are across the full temperature range $T_{amb} = -40 \text{ °C}$ to $+85 \text{ °C}$ at $V_{DDA} = 3 \text{ V}$, $V_{DDO} = 1.8 \text{ V}$; $V_{INP} - V_{INM} = -1 \text{ dBFS}$; internal reference mode; applied to CMOS and LVDS interface; unless otherwise specified.

10.2 Clock and digital output timing

Table 8. Clock and digital output timing characteristics^[1]

Symbol	Parameter	Conditions	ADC1010S065			ADC1010S080			ADC1010S105			ADC1010S125			Unit
			Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Clock timing input: pins CLKP and CLKM															
f _{clk}	clock frequency		20	-	65	60	-	80	75	-	105	100	-	125	MHz
t _{lat(data)}	data latency time	clock cycles	-	14	-	-	14	-	-	14	-	-	14	-	clock cycle
δ _{clk}	clock duty cycle	DCS_EN = 1	30	50	70	30	50	70	30	50	70	30	50	70	%
		DCS_EN = 0	45	50	55	45	50	55	45	50	55	45	50	55	%
t _{d(s)}	sampling delay time		-	0.8	-	-	0.8	-	-	0.8	-	-	0.8	-	ns
t _{wake}	wake-up time		-	<tbd>	-	-	<tbd>	-	-	<tbd>	-	-	<tbd>	-	ns
CMOS mode timing output: pins D9 to D0 and DAV															
t _{PD}	propagation delay	DATA	-	3.9	-	-	3.9	-	-	3.9	-	-	3.9	-	ns
		DAV	-	4.2	-	-	4.2	-	-	4.2	-	-	4.2	-	ns
t _{su}	set-up time		-	7.7	-	-	6.5	-	-	4.7	-	-	4.3	-	ns
t _h	hold time		-	6.7	-	-	5.5	-	-	3.8	-	-	3.5	-	ns
t _r	rise time ^[2]	DATA	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	ns
		DAV	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	ns
t _f	fall time ^[2]	DATA	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	ns
LVDS DDR mode timing output: pins D9P to D0P, D9M to D0M, DAVP and DAVM															
t _{PD}	propagation delay	DATA	-	3.9	-	-	3.9	-	-	3.9	-	-	3.9	-	ns
		DAV	-	4.2	-	-	4.2	-	-	4.2	-	-	4.2	-	ns
t _{su}	set-up time		-	5.1	-	-	3.5	-	-	2.1	-	-	1.4	-	ns
t _h	hold time		-	2.0	-	-	2.0	-	-	2.0	-	-	2.0	-	ns
t _r	rise time ^[3]	DATA	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	ns
		DAV	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	ns
t _f	fall time ^[3]	DATA	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	0.5	-	2.4	ns

[1] Typical values measured at V_{DDA} = 3 V, V_{DDO} = 1.8 V, T_{amb} = 25 °C and C_L = 5 pF; minimum and maximum values are across the full temperature range T_{amb} = -40 °C to +85 °C at V_{DDA} = 3 V, V_{DDO} = 1.8 V; V_{INP} - V_{INM} = -1 dBFS; unless otherwise specified.

[2] Measured between 20 % to 80 % of V_{DDO}.

[3] Rise time measured from -50 mV to +50 mV; fall time measured from +50 mV to -50 mV.

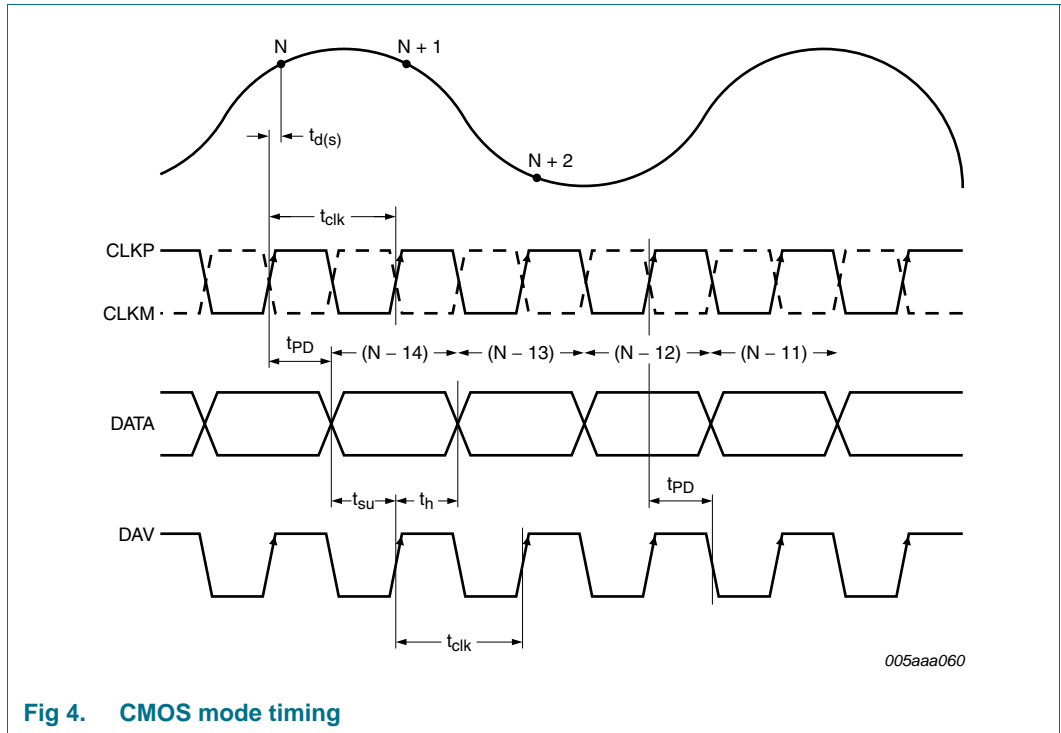


Fig 4. CMOS mode timing

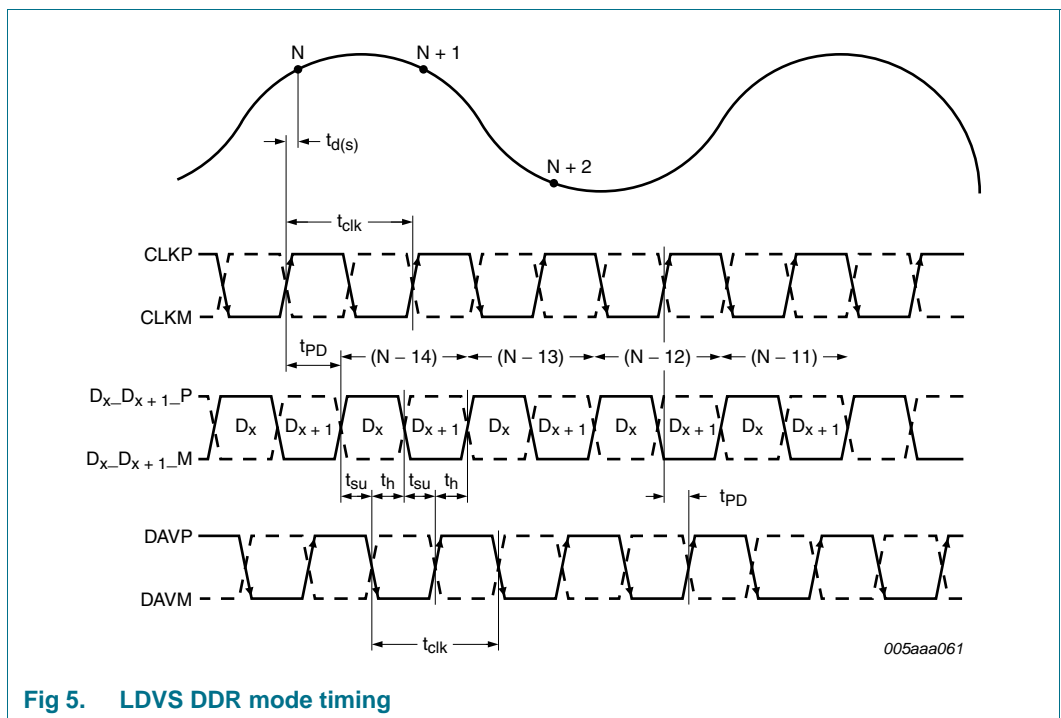


Fig 5. LVDS DDR mode timing

10.3 SPI timings

Table 9. SPI timings characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{w(SCLK)}$	SCLK pulse width		40	-	-	ns
$t_{w(SCLKH)}$	SCLK HIGH pulse width		16	-	-	ns
$t_{w(SCLKL)}$	SCLK LOW pulse width		16	-	-	ns
t_{su}	set-up time	data to SCLK HIGH	5	-	-	ns
		\overline{CS} to SCLK HIGH	5	-	-	ns
t_h	hold time	data to SCLK HIGH	2	-	-	ns
		\overline{CS} to SCLK HIGH	2	-	-	ns
$f_{clk(max)}$	maximum clock frequency		-	-	25	MHz

[1] Typical values measured at $V_{DDA} = 3\text{ V}$, $V_{DDO} = 1.8\text{ V}$, $T_{amb} = 25\text{ }^\circ\text{C}$ and $C_L = 5\text{ pF}$; minimum and maximum values are across the full temperature range $T_{amb} = -40\text{ }^\circ\text{C}$ to $+85\text{ }^\circ\text{C}$ at $V_{DDA} = 3\text{ V}$, $V_{DDO} = 1.8\text{ V}$

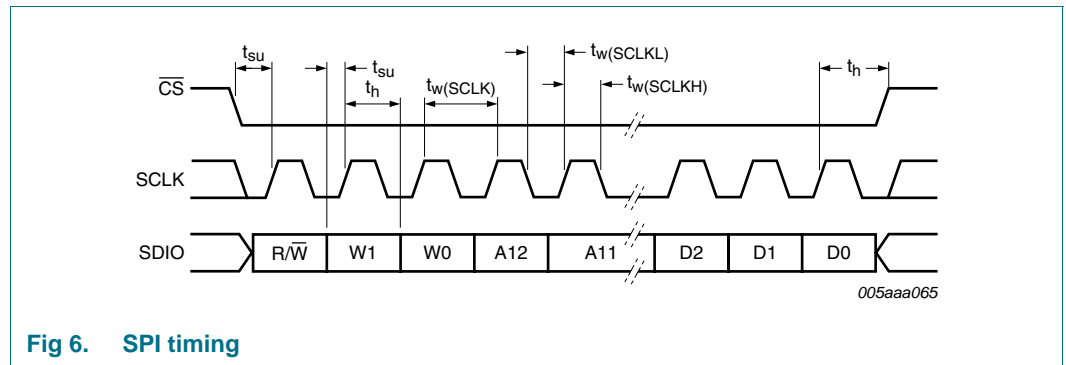


Fig 6. SPI timing

11. Application information

11.1 Device control

The ADC1010S can be controlled via SPI or directly via the I/O pins (PIN control mode).

11.1.1 SPI and Pin control modes

The device enters Pin control mode at power-up, and remains in this mode as long as pin \overline{CS} is held HIGH. In Pin control mode, the SPI pins SDIO, \overline{CS} and SCLK are used as static control pins.

SPI control mode is enabled by forcing pin \overline{CS} LOW. Once SPI control mode has been enabled, the device will remain in this mode. The transition from Pin control mode to SPI control mode is illustrated in [Figure 7](#).

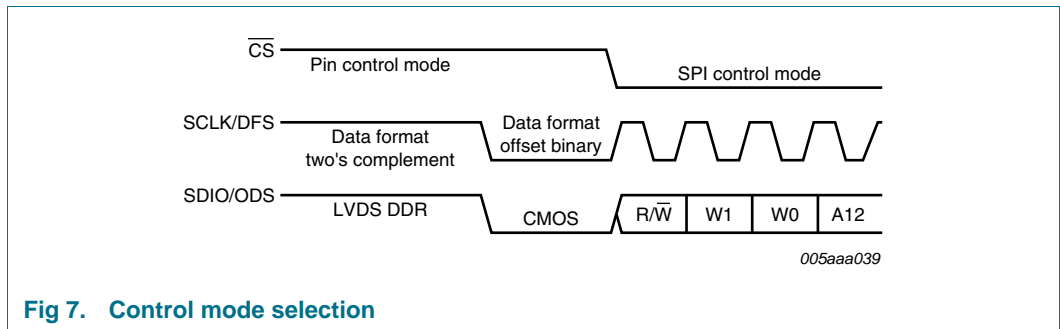


Fig 7. Control mode selection

When the device enters SPI control mode, the output data standard and data format are determined by the level on pin SDIO at the instant a transition is triggered by a falling edge on CS.

11.1.2 Operating mode selection

The active ADC1010S operating mode (Power-up, Power-down or Sleep) can be selected via the SPI interface (see Table 20) or using pins PWD and OE in Pin control mode, as described in Table 10.

Table 10. Operating mode selection via pin PWD and OE

Pin PWD	Pin OE	Operating mode	Output high-Z
0	0	Power-up	no
0	1	Power-up	yes
1	0	Sleep	yes
1	1	Power-down	yes

11.1.3 Selecting the output data standard

The output data standard (CMOS or LVDS DDR) can be selected via the SPI interface (see Table 23) or using pin ODS in Pin control mode. LVDS DDR is selected when ODS is HIGH, otherwise CMOS is selected.

11.1.4 Selecting the output data format

The output data format can be selected via the SPI interface (offset binary, two's complement or gray code; see Table 23) or using pin DFS in Pin control mode (offset binary or two's complement). Offset binary is selected when DFS is LOW. When DFS is HIGH, two's complement is selected.

11.2 Analog inputs

11.2.1 Input stage

The analog input of the ADC1010S supports differential or single-ended input drive. Optimal performance is achieved using differential inputs with the common-mode input voltage ($V_{I(cm)}$) on pins INP and INM set to $0.5V_{DDA}$.

The full-scale analog input voltage range is configurable between 1 V (p-p) and 2 V (p-p) via a programmable internal reference (see Section 11.3 and Table 22 further details).

The equivalent circuit of the sample and hold input stage, including Electrostatic Discharge (ESD) protection and circuit and package parasitics, is shown in Figure 8.

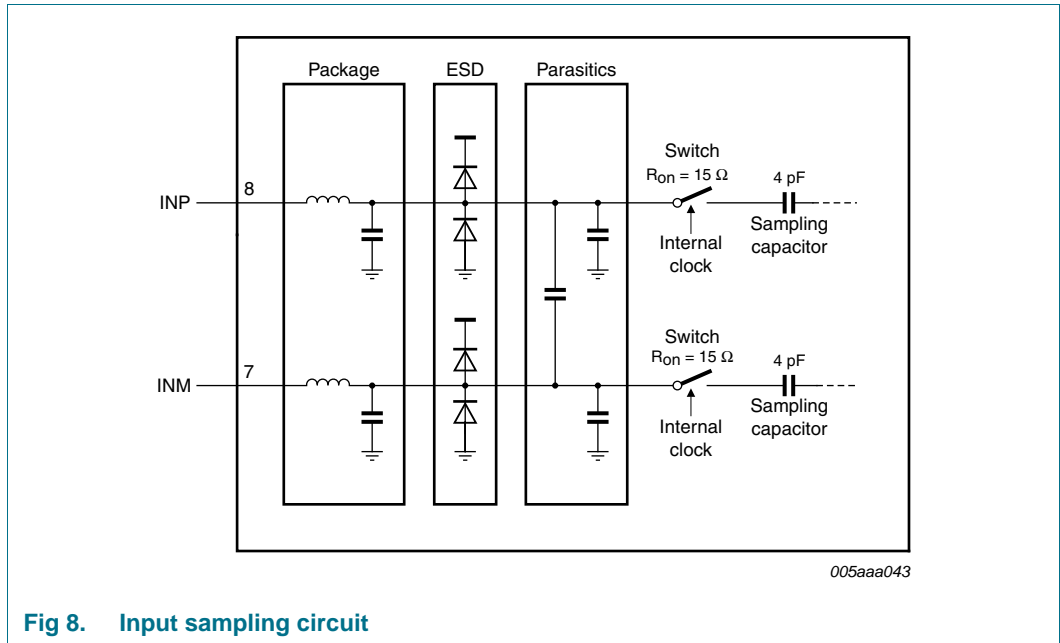


Fig 8. Input sampling circuit

The sample phase occurs when the internal clock (derived from the clock signal on pin CLKP/CLKM) is HIGH. The voltage is then held on the sampling capacitors. When the clock signal goes LOW, the stage enters the hold phase and the voltage information is transmitted to the ADC core.

11.2.2 Anti-kickback circuitry

Anti-kickback circuitry (R-C filter in [Figure 9](#)) is needed to counteract the effects of a charge injection generated by the sampling capacitance.

The RC filter is also used to filter noise from the signal before it reaches the sampling stage. The value of the capacitor should be chosen to maximize noise attenuation without degrading the settling time excessively.

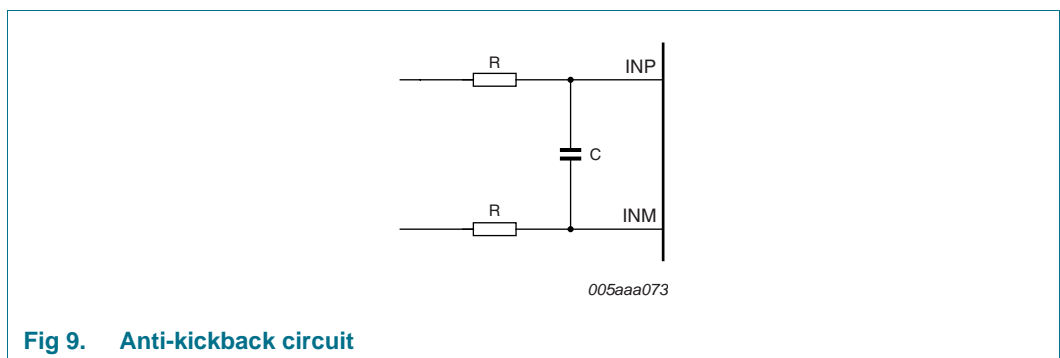


Fig 9. Anti-kickback circuit

The component values are determined by the input frequency and should be selected so as not to affect the input bandwidth.

Table 11. RC coupling versus input frequency - typical values

Input frequency	R	C
3 MHz	25 Ω	12 pF
70 MHz	12 Ω	8 pF
170 MHz	12 Ω	8 pF

11.2.3 Transformer

The configuration of the transformer circuit is determined by the input frequency. The configuration shown in [Figure 10](#) would be suitable for a baseband application.

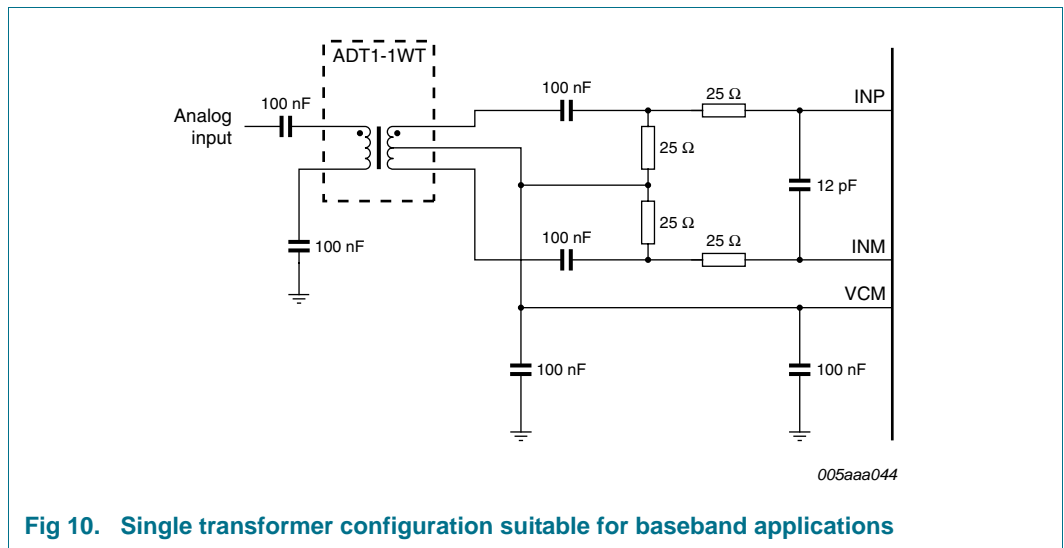


Fig 10. Single transformer configuration suitable for baseband applications

The configuration shown in [Figure 11](#) is recommended for high frequency applications. In both cases, the choice of transformer will be a compromise between cost and performance.

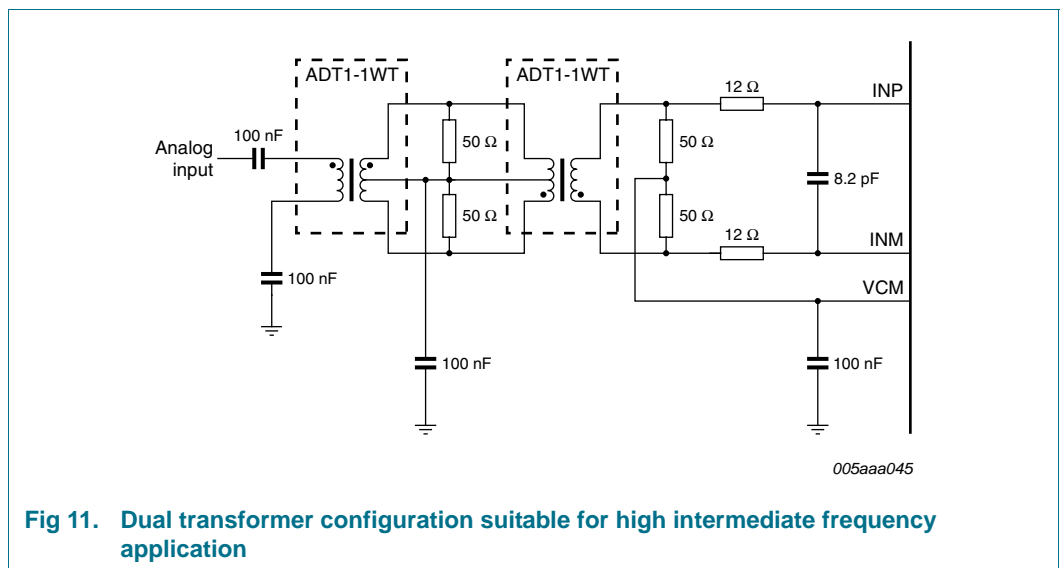


Fig 11. Dual transformer configuration suitable for high intermediate frequency application

11.3 System reference and power management

11.3.1 Internal/external references

The ADC1010S has a stable and accurate built-in internal reference voltage to adjust the ADC full-scale. This reference voltage can be set internally via SPI or with pins VREF and SENSE (programmable in 1 dB steps between 0 dB and -6 dB via control bits INTREF[2:0] when bit INTREF_EN = 1; see Table 22). See Figure 13, Figure 14, Figure 15 and Figure 16. The equivalent reference circuit is shown in Figure 12. External reference is also possible by providing a voltage on pin VREF as described in Figure 15.

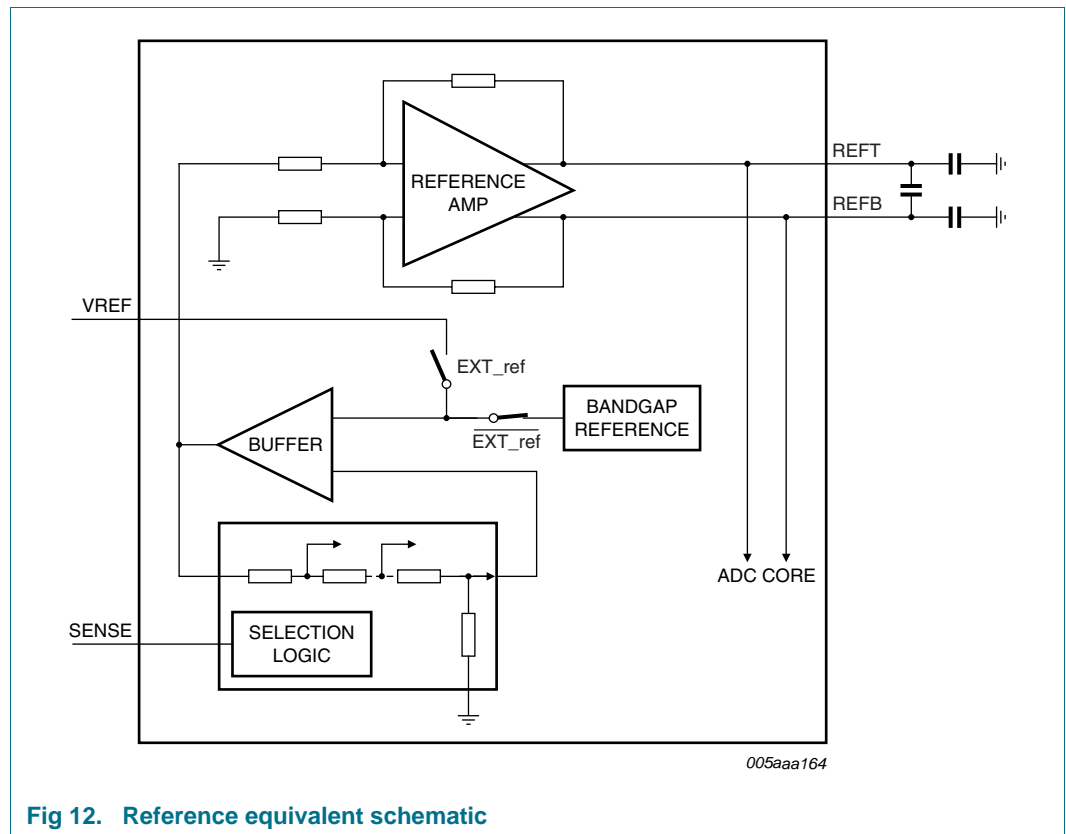


Fig 12. Reference equivalent schematic

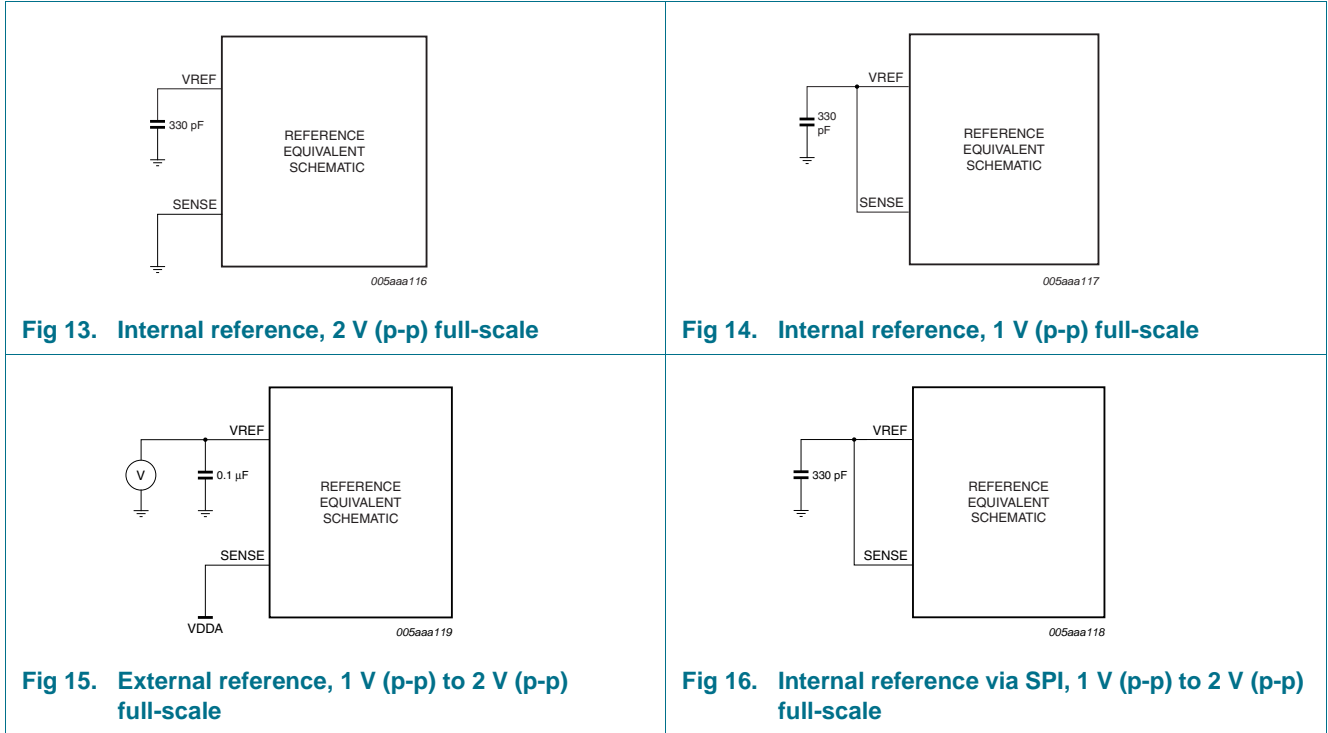
If bit INTREF_EN is set to 0, the reference voltage will be determined either internally or externally as detailed in Table 12.

Table 12. Reference selection

Selection	SPI bit INTREF_EN	SENSE pin	VREF pin	full-scale (p-p)
internal (Figure 13)	0	AGND	330 pF capacitor to AGND	2 V
internal (Figure 14)	0	pin VREF connected to pin SENSE and via a 330 pF capacitor to AGND		1 V
external (Figure 15)	0	V _{DDA}	external voltage between 0.5 V and 1 V ^[1]	1 V to 2 V
internal via SPI (Figure 16)	1	pin VREF connected to pin SENSE and via 330 pF capacitor to AGND		1 V to 2 V

[1] The voltage on pin VREF is doubled internally to generate the internal reference voltage.

Figure 13 to Figure 16 illustrate how to connect the SENSE and VREF pins to select the required reference voltage source.



11.3.2 Reference gain control

The reference gain is programmable between 0 dB to -6 dB in 1 dB steps via the SPI (see Table 22). The corresponding full-scale input voltage range varies between 2 V (p-p) and 1 V (p-p), as shown in Table 13:

Table 13. Reference SPI gain control

INTREF[2:0]	Gain (dB)	Full-scale (V (p-p))
000	0 dB	2 V
001	-1 dB	1.78 V
010	-2 dB	1.59 V
011	-3 dB	1.42 V
100	-4 dB	1.26 V
101	-5 dB	1.12 V
110	-6 dB	1 V
111	reserved	x

11.3.3 Common-mode output voltage ($V_{O(cm)}$)

A 0.1 μ F filter capacitor should be connected between pin VCM and ground to ensure a low-noise common-mode output voltage. When AC-coupled, pin VCM can then be used to set the common-mode reference for the analog inputs, for instance via a transformer middle point.

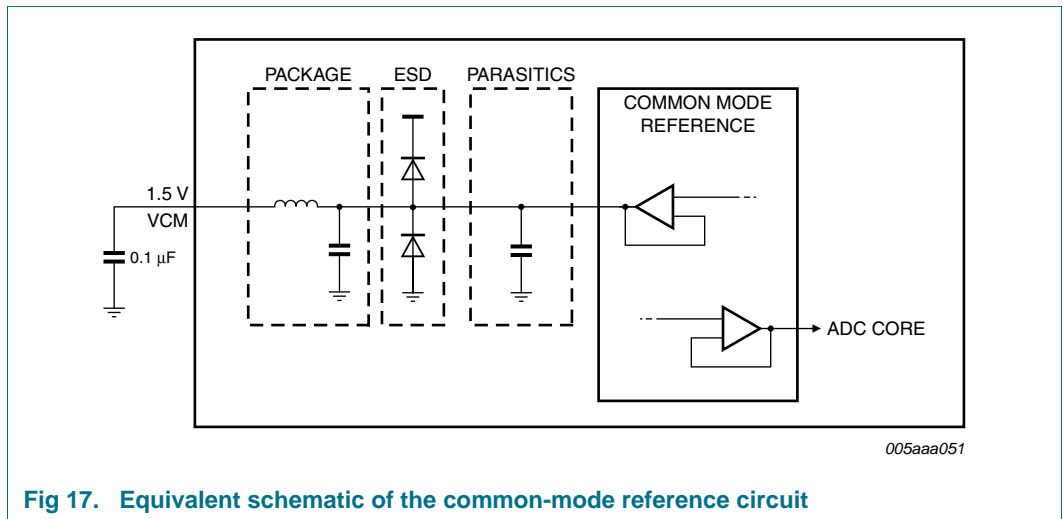


Fig 17. Equivalent schematic of the common-mode reference circuit

11.3.4 Biasing

The common-mode input voltage ($V_{I(cm)}$) on pins INP and INM should be set externally to $0.5V_{DDA}$ for optimal performance and should always be between 0.9 V and 2 V.

11.4 Clock input

11.4.1 Drive modes

The ADC1010S can be driven differentially (SINE, LVPECL or LVDS) with little or no influence on the dynamic performances. It can also be driven by a single-ended LVCMOS signal connected to pin CLKP (CLKM should be connected to ground via a capacitor) or CLKM (CLKP should be connected to ground via a capacitor).

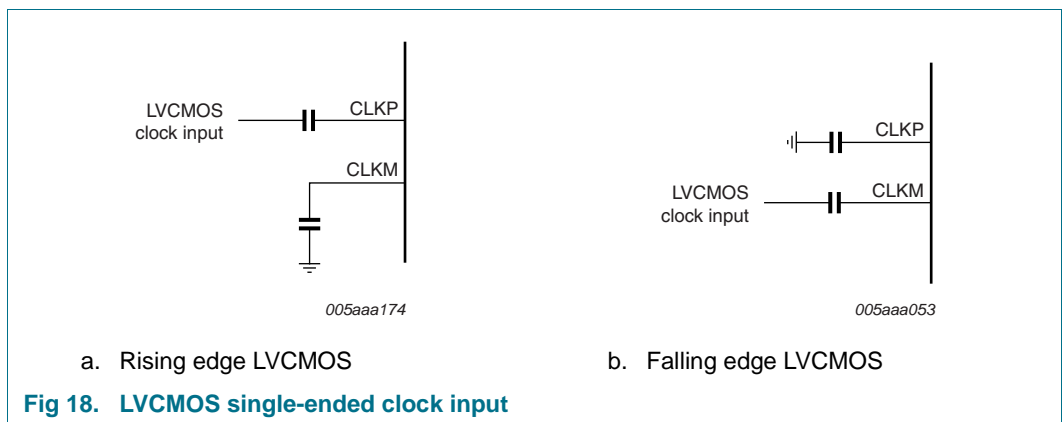
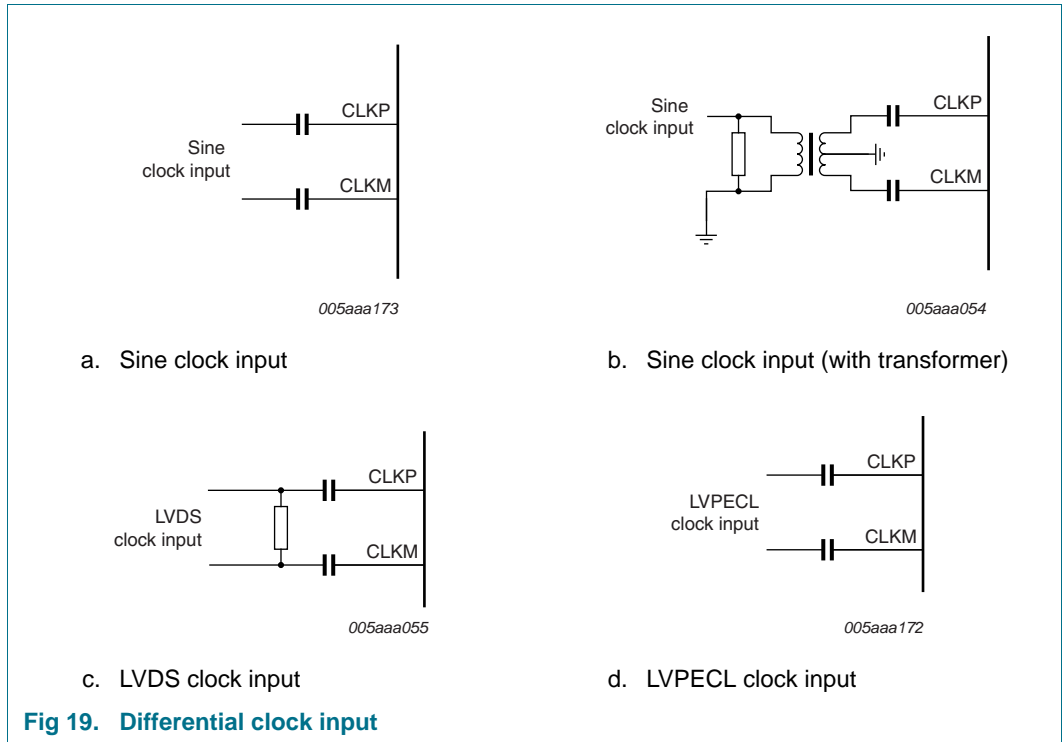
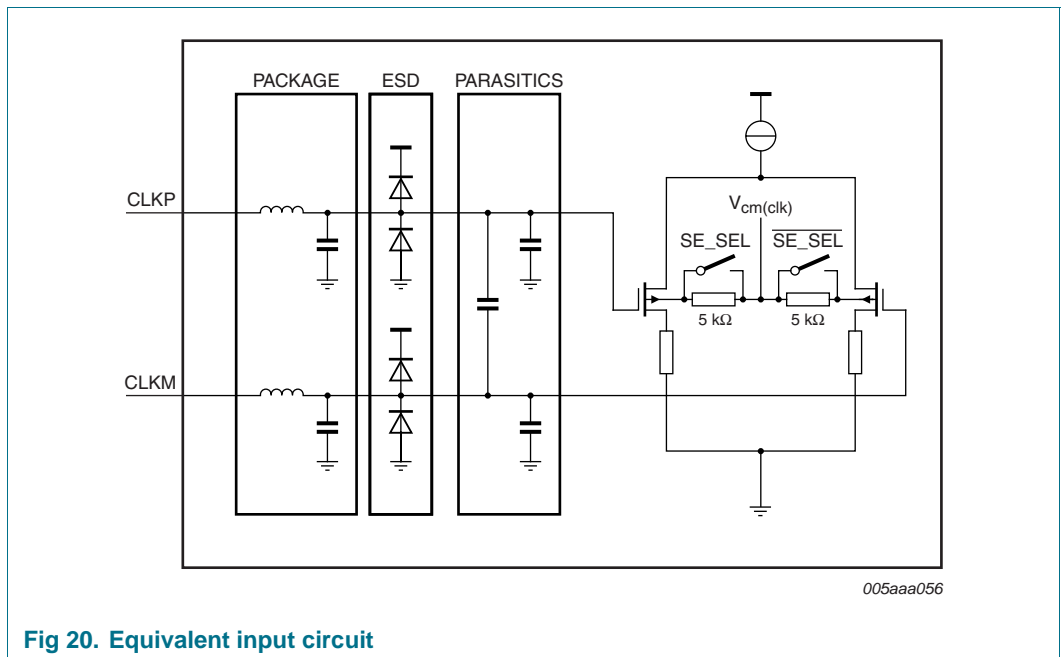


Fig 18. LVCMOS single-ended clock input



11.4.2 Equivalent input circuit

The equivalent circuit of the input clock buffer is shown in [Figure 20](#). The common-mode voltage of the differential input stage is set via internal 5 kΩ resistors.



Single-ended or differential clock inputs can be selected via the SPI interface (see [Table 21](#)). If single-ended is enabled, the input pin (CLKM or CLKP) is selected via control bit SE_SEL.

If single-ended is implemented without setting SE_SEL to the appropriate value, the unused pin should be connected to ground via a capacitor.

11.4.3 Duty cycle stabilizer

The duty cycle stabilizer can improve the overall performances of the ADC by compensating the duty cycle of the input clock signal. When the duty cycle stabilizer is active (bit DCS_EN = 1; see [Table 21](#)), the circuit can handle signals with duty cycles of between 30 % and 70 % (typical). When the duty cycle stabilizer is disabled (DCS_EN = 0), the input clock signal should have a duty cycle of between 45 % and 55 %.

11.4.4 Clock input divider

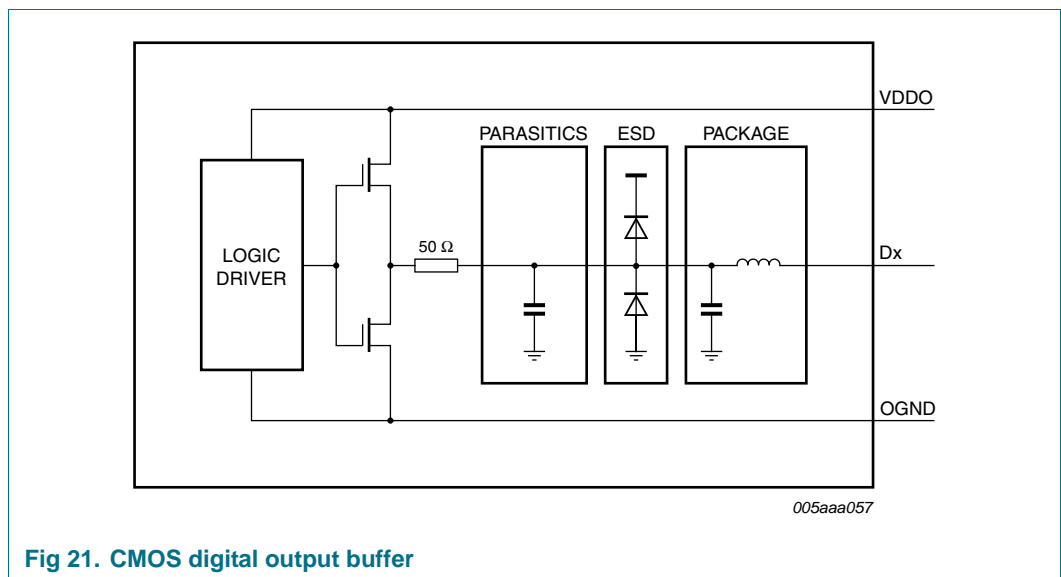
The ADC1010S contains an input clock divider that divides the incoming clock by a factor of 2 (when bit CLKDIV = 1; see [Table 21](#)). This feature allows the user to deliver a higher clock frequency with better jitter performance, leading to a better SNR result once acquisition has been performed.

11.5 Digital outputs

11.5.1 Digital output buffers: CMOS mode

The digital output buffers can be configured as CMOS by setting bit LVDS/CMOS to 0 (see [Table 23](#)).

Each digital output has a dedicated output buffer. The equivalent circuit of the CMOS digital output buffer is shown in [Figure 21](#). The buffer is powered by a separate power supply, pins OGND and V_{DDO}, to ensure 1.8 V to 3.3 V compatibility and is isolated from the ADC core. Each buffer can be loaded by a maximum of 10 pF.



The output resistance is 50 Ω and is the combination of the an internal resistor and the equivalent output resistance of the buffer. There is no need for an external damping resistor. The drive strength of both data and DAV buffers can be programmed via the SPI in order to adjust the rise and fall times of the output digital signals (see [Table 30](#)):

11.5.2 Digital output buffers: LVDS DDR mode

The digital output buffers can be configured as LVDS DDR by setting bit LVDS/CMOS to 1 (see [Table 23](#)).

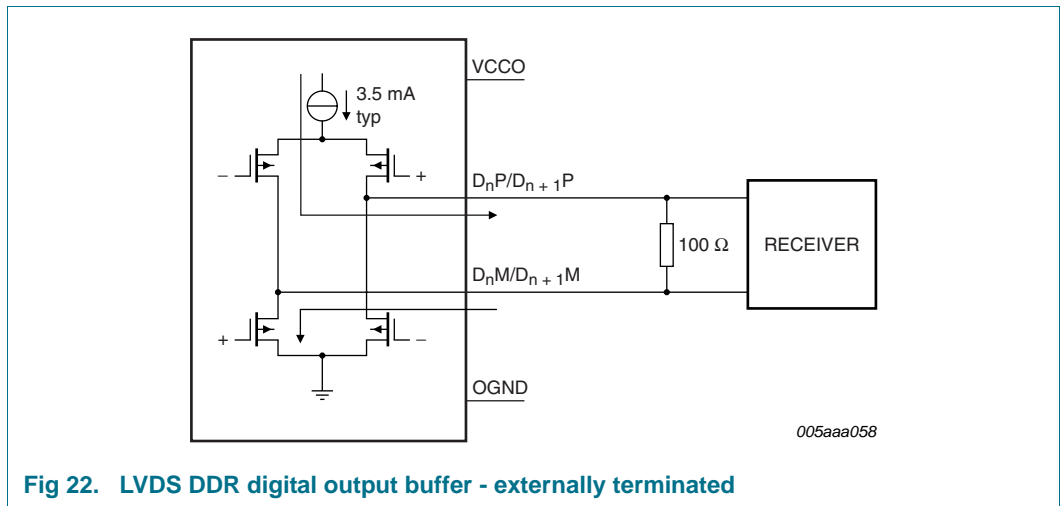


Fig 22. LVDS DDR digital output buffer - externally terminated

Each output should be terminated externally with a 100 Ω resistor (typical) at the receiver side ([Figure 22](#)) or internally via SPI control bits LVDS_INT_TER[2:0] (see [Figure 23](#) and [Table 32](#)).

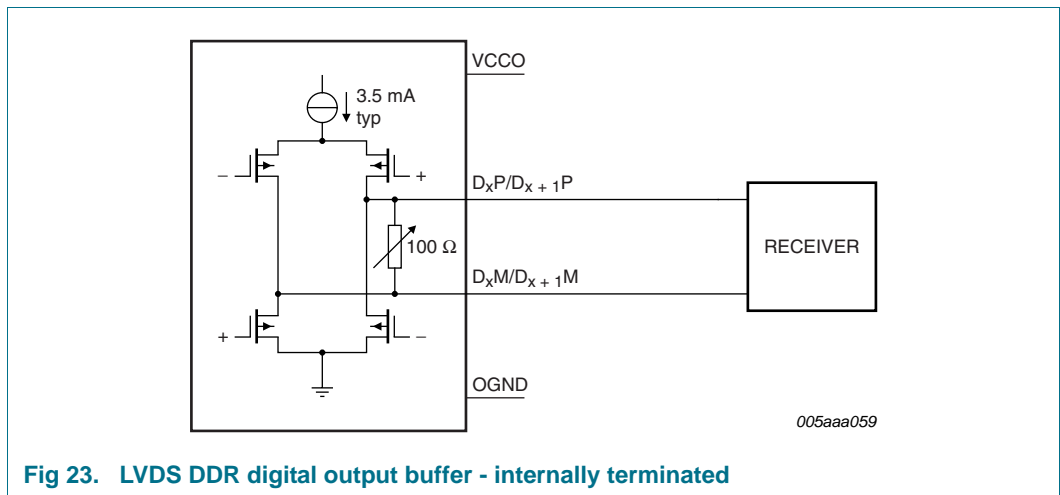


Fig 23. LVDS DDR digital output buffer - internally terminated

The default LVDS DDR output buffer current is set to 3.5 mA. It can be programmed via the SPI (bits DAVI[1:0] and DATA[1:0]; see [Table 31](#)) in order to adjust the output logic voltage levels.

Table 14. LVDS DDR output register 2

LVDS_INT_TER[2:0]	Resistor value (Ω)
000	no internal termination
001	300
010	180
011	110
100	150
101	100
110	81
111	60

11.5.3 Data valid (DAV) output clock

A data valid output clock signal (DAV) can be used to capture the data delivered by the ADC1010S. Detailed timing diagrams for CMOS and LVDS DDR modes are shown in [Figure 4](#) and [Figure 5](#) respectively.

11.5.4 Out-of-Range (OTR)

An out-of-range signal is provided on pin OTR. The latency of OTR is fourteen clock cycles. The OTR response can be speeded up by enabling Fast OTR (bit FASTOTR = 1; see [Table 29](#)). In this mode, the latency of OTR is reduced to only four clock cycles. The Fast OTR detection threshold (below full-scale) can be programmed via bits FASTOTR_DET[2:0].

Table 15. Fast OTR register

FASTOTR_DET[2:0]	Detection level (dB)
000	-20.56
001	-16.12
010	-11.02
011	-7.82
100	-5.49
101	-3.66
110	-2.14
111	-0.86

11.5.5 Digital offset

By default, the ADC1010S delivers output code that corresponds to the analog input. However it is possible to add a digital offset to the output code via the SPI (bits DIG_OFFSET[5:0]; see [Table 25](#)).

11.5.6 Test patterns

For test purposes, the ADC1010S can be configured to transmit one of a number of predefined test patterns (via bits TESTPAT_SEL[2:0]; see [Table 26](#)). A custom test pattern can be defined by the user (TESTPAT_USER; see [Table 27](#) and [Table 28](#)) and is selected when TESTPAT_SEL[2:0] = 101. The selected test pattern will be transmitted regardless of the analog input.

11.5.7 Output codes versus input voltage

Table 16. Output codes

$V_{INP} - V_{INM}$	Offset binary	Two's complement	OTR pin
< -1	00 0000 0000	10 0000 0000	1
-1.0000000	00 0000 0000	10 0000 0000	0
-0.9980469	00 0000 0001	10 0000 0001	0
-0.9960938	00 0000 0010	10 0000 0010	0
-0.9941406	00 0000 0011	10 0000 0011	0
-0.9921875	00 0000 0100	10 0000 0100	0
....	0
-0.0039063	01 1111 1110	11 1111 1110	0
-0.0019531	01 111 1111	11 1111 1111	0
0.0000000	10 0000 0000	00 0000 0000	0
+0.0019531	10 0000 0001	00 0000 0001	0
+0.0039063	10 0000 0010	00 0000 0010	0
....	0
+0.9921875	11 1111 1011	01 1111 1011	0
+0.9941406	11 1111 1100	01 1111 1100	0
+0.9960938	11 1111 1101	01 1111 1101	0
+0.9980469	11 1111 1110	01 1111 1110	0
+1.0000000	11 1111 1111	01 1111 1111	0
> +1	11 1111 1111	01 1111 1111	1

11.6 Serial peripheral interface

11.6.1 Register description

The ADC1010S serial interface is a synchronous serial communications port that allows for easy interfacing with many commonly-used microprocessors. It provides access to the registers that control the operation of the chip.

This interface is configured as a 3-wire type (SDIO as bidirectional pin)

Pin SCLK is the serial clock input and \overline{CS} is the chip select pin.

Each read/write operation is initiated by a LOW level on \overline{CS} . A minimum of three bytes will be transmitted (two instruction bytes and at least one data byte). The number of data bytes is determined by the value of bits W1 and W2 (see [Table 18](#)).

Table 17. Instruction bytes for the SPI

	MSB							LSB
Bit	7	6	5	4	3	2	1	0
Description	R/ \overline{W} [1]	W1[2]	W0[2]	A12	A11	A10	A9	A8
	A7	A6	A5	A4	A3	A2	A1	A0

[1] Bit R/ \overline{W} indicates whether it is a read (1) or a write (0) operation.

[2] Bits W1 and W0 indicate the number of bytes to be transferred after the instruction byte (see [Table 18](#)).

Table 18. Number of data bytes to be transferred after the instruction bytes

W1	W0	Number of bytes transmitted
0	0	1 byte
0	1	2 bytes
1	0	3 bytes
1	1	4 bytes or more

Bits A12 to A0 indicate the address of the register being accessed. In the case of a multiple byte transfer, this address is the first register to be accessed. An address counter is increased to access subsequent addresses.

The steps involved in a data transfer are as follows:

1. A falling edge on \overline{CS} in combination with a rising edge on SCLK determine the start of communications.
2. The first phase is the transfer of the 2-byte instruction.
3. The second phase is the transfer of the data which can vary in length but will always be a multiple of 8 bits. The MSB is always sent first (for instruction and data bytes).
4. A rising edge on \overline{CS} indicates the end on data transmission.

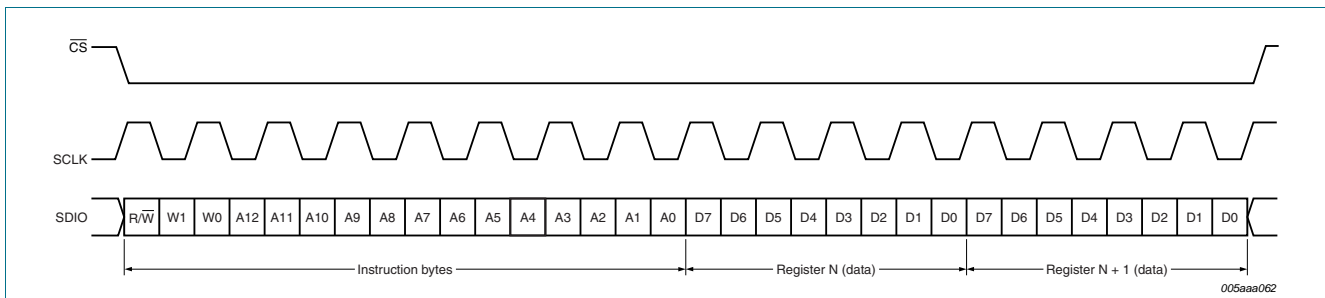


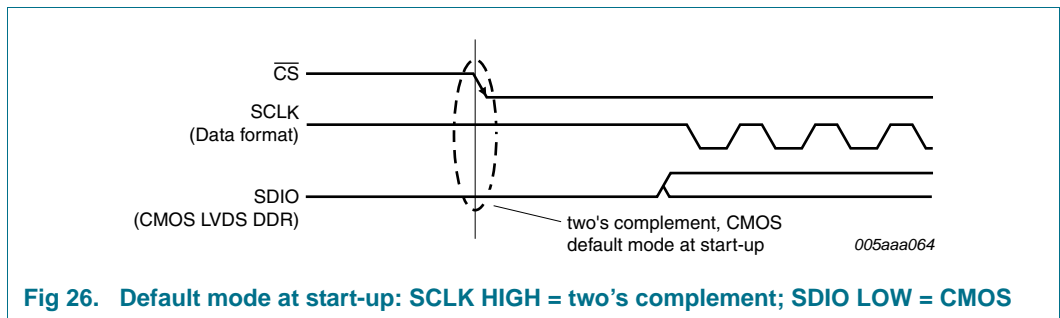
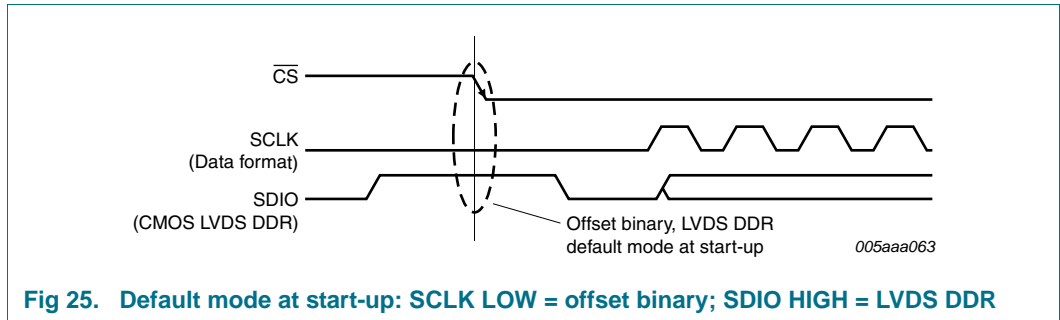
Fig 24. SPI mode timing

11.6.2 Default modes at start-up

During circuit initialization, it does not matter which output data standard has been selected. At power-up, the device enters Pin control mode.

A falling edge on \overline{CS} will trigger a transition to SPI control mode. When the ADC1010S enters SPI control mode, the output data standard (CMOS/LVDS DDR) is determined by the level on pin SDIO (see [Figure 25](#)). Once in SPI control mode, the output data standard can be changed via bit LVDS/CMOS in [Table 23](#).

When the ADC1010S enters SPI control mode, the output data format (two's complement or offset binary) is determined by the level on pin SCLK (gray code can only be selected via the SPI). Once in SPI control mode, the output data format can be changed via bit DATA_FORMAT[1:0] in [Table 23](#).



11.6.3 Register allocation map

Table 19. Register allocation map

AddrHex	Register name	R/W	Bit definition								Default Bin	
			Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
0005	Reset and operating mode	R/W	SW_RST	RESERVED[2:0]			-	-	OP_MODE[1:0]		0000 0000	
0006	Clock	R/W	-	-	-	SE_SEL	DIFF_SE	-	CLKDIV	DCS_EN	0000 0001	
0008	Internal reference	R/W	-	-	-	-	INTREF_EN	INTREF[2:0]			0000 0000	
0011	Output data standard	R/W	-	-	-	LVDS_CMOS	OUTBUF	OUTBUS_SWAP	DATA_FORMAT[1:0]		0000 0000	
0012	Output clock	R/W	-	-	-	-	DAVINV	DAVPHASE[2:0]			0000 1110	
0013	Offset	R/W	-	-	DIG_OFFSET[5:0]						0000 0000	
0014	Test pattern 1	R/W	-	-	-	-	-	TESTPAT_SEL[2:0]			0000 0000	
0015	Test pattern 2	R/W	TESTPAT_USER[9:2]									0000 0000
0016	Test pattern 3	R/W	TESTPAT_USER[1:0]	-	-	-	-	-	-	-	0000 0000	
0017	Fast OTR	R/W	-	-	-	-	FASTOTR	FASTOTR_DET[2:0]			0000 0000	
0020	CMOS output	R/W	-	-	-	-	DAV_DRV[1:0]		DATA_DRV[1:0]		0000 1110	
0021	LVDS DDR O/P 1	R/W	-	-	DAVI_x2_EN	DAVI[1:0]		DATAI_x2_EN	DATAI[1:0]		0000 0000	
0022	LVDS DDR O/P 2	R/W	-	-	-	-	BIT_BYTE_WISE	LVDS_INT_TER[2:0]			0000 0000	

Table 20. Reset and operating mode control register (address 0005h) bit description

Bit	Symbol	Access	Value	Description
7	SW_RST	R/W		reset digital section
			0	no reset
			1	performs a reset on SPI registers
6 to 4	RESERVED[2:0]		000	reserved
3 to 2	-		00	not used
1 to 0	OP_MODE[1:0]	R/W		operating mode
			00	normal (power-up)
			01	power-down
			10	sleep
			11	normal (power-up)

Table 21. Clock control register (address 0006h) bit description

Bit	Symbol	Access	Value	Description
7 to 5	-		000	not used
4	SE_SEL	R/W		single-ended clock input pin select
			0	CLKM
			1	CLKP
3	DIFF_SE	R/W		differential/single ended clock input select
			0	fully differential
			1	single-ended
2	-		0	not used
1	CLKDIV	R/W		clock input divide by 2
			0	disabled
			1	enabled
0	DCS_EN	R/W		duty cycle stabilizer
			0	disabled
			1	enabled

Table 22. Internal reference control register (address 0008h) bit description

Bit	Symbol	Access	Value	Description
7 to 4	-		0000	not used
3	INTREF_EN	R/W		programmable internal reference enable
			0	disable
			1	active
2 to 0	INTREF[2:0]	R/W		programmable internal reference
			000	0 dB (FS = 2 V)
			001	-1 dB (FS = 1.78 V)
			010	-2 dB (FS = 1.59 V)
			011	-3 dB (FS = 1.42 V)
			100	-4 dB (FS = 1.26 V)
			101	-5 dB (FS = 1.12 V)
			110	-6 dB (FS = 1 V)
			111	reserved

Table 23. Output data standard control register (address 0011h) bit description

Bit	Symbol	Access	Value	Description
7 to 5	-		000	not used
4	LVDS_CMOS	R/W		output data standard: LVDS DDR or CMOS
			0	CMOS
			1	LVDS DDR
3	OUTBUF	R/W		output buffers enable
			0	output enabled
			1	output disabled (high Z)
2	OUTBUS_SWAP	R/W		output bus swapping
			0	no swapping
			1	output bus is swapping (MSB becomes LSB and vice versa)
1 to 0	DATA_FORMAT[1:0]	R/W		output data format
			00	offset binary
			01	two's complement
			10	gray code
			11	offset binary

Table 24. Output clock register (address 0012h) bit description

Bit	Symbol	Access	Value	Description
7 to 4	-		0000	not used
3	DAVINV	R/W		output clock data valid (DAV) polarity
			0	normal
			1	inverted
2 to 0	DAVPHASE[2:0]	R/W		DAV phase select
			000	output clock shifted (ahead) by 3 ns
			001	output clock shifted (ahead) by 2.5 ns
			010	output clock shifted (ahead) by 2 ns
			011	output clock shifted (ahead) by 1.5 ns
			100	output clock shifted (ahead) by 1 ns
			101	output clock shifted (ahead) by 0.5 ns
			110	default value as defined in timing section
			111	output clock shifted (delayed) by 0.5 ns

Table 25. Offset register (address 0013h) bit description

Bit	Symbol	Access	Value	Description
7 to 6	-		00	not used
5 to 0	DIG_OFFSET[5:0]	R/W		digital offset adjustment
			011111	+31 LSB
		
			000000	0
		
			100000	-32 LSB

Table 26. Test pattern register 1 (address 0014h) bit description

Bit	Symbol	Access	Value	Description
7 to 3	-		00000	not used
2 to 0	TESTPAT_SEL[2:0]	R/W		digital test pattern select
			000	off
			001	mid scale
			010	-FS
			011	+FS
			100	toggle '1111..1111'/'0000..0000'
			101	custom test pattern
			110	'1010..1010.'
			111	'010..1010'

Table 27. Test pattern register 2 (address 0015h) bit description

Bit	Symbol	Access	Value	Description
7 to 0	TESTPAT_USER[9:2]	R/W	00000000	custom digital test pattern (bits 9 to 2)

Table 28. Test pattern register 3 (address 0016h) bit description

Bit	Symbol	Access	Value	Description
7 to 6	TESTPAT_USER[1:0]	R/W	00	custom digital test pattern (bits 1 to 0)
5 to 0	-		000000	not used

Table 29. Fast OTR register (address 0017h) bit description

Bit	Symbol	Access	Value	Description
7 to 4	-		0000	not used
3	FASTOTR	R/W	0	fast Out-of-Range (OTR) detection
			1	disabled
				enabled
2 to 0	FASTOTR_DET[2:0]	R/W		set fast OTR detect level
			000	-20.56 dB
			001	-16.12 dB
			010	-11.02 dB
			011	-7.82 dB
			100	-5.49 dB
			101	-3.66 dB
			110	-2.14 dB
			111	-0.86 dB

Table 30. CMOS output register (address 0020h) bit description

Bit	Symbol	Access	Value	Description
7 to 4	-		0000	not used
3 to 2	DAV_DRV[1:0]	R/W		drive strength for DAV CMOS output buffer
			00	low
			01	medium
			10	high
			11	very high
1 to 0	DATA_DRV[1:0]	R/W		drive strength for DATA CMOS output buffer
			00	low
			01	medium
			10	high
			11	very high

Table 31. LVDS DDR output register 1 (address 0021h) bit description

Bit	Symbol	Access	Value	Description
7 to 6	-		00	not used
5	DAVI_x2_EN	R/W		double LVDS current for DAV LVDS buffer
			0	disabled
			1	enabled
4 to 3	DAVI[1:0]	R/W		LVDS current for DAV LVDS buffer
			00	3.5 mA
			01	4.5 mA
			10	1.25 mA
			11	2.5 mA
2	DATAI_x2_EN	R/W		double LVDS current for DATA LVDS buffer
			0	disabled
			1	enabled
1 to 0	DATAI[1:0]	R/W		LVDS current for DATA LVDS buffer
			00	3.5 mA
			01	4.5 mA
			10	1.25 mA
			11	2.5 mA

Table 32. LVDS DDR output register 2 (address 0022h) bit description

Bit	Symbol	Access	Value	Description
7 to 4	-		0000	not used
3	BIT_BYTE_WISE	R/W		DDR mode for LVDS output
			0	bit wise (even data bits output on DAV rising edge/odd data bits output on DAV falling edge)
			1	byte wise (MSB data bits output on DAV rising edge/LSB data bits output on DAV falling edge)
2 to 0	LVDS_INTTER[2:0]	R/W		internal termination for LVDS buffer (DAV and DATA)
			000	no internal termination
			001	300 Ω
			010	180 Ω
			011	110 Ω
			100	150 Ω
			101	100 Ω
			110	81 Ω
			111	60 Ω

12. Package outline

HVQFN40: plastic thermal enhanced very thin quad flat package; no leads; 40 terminals; body 6 x 6 x 0.85 mm

SOT618-6

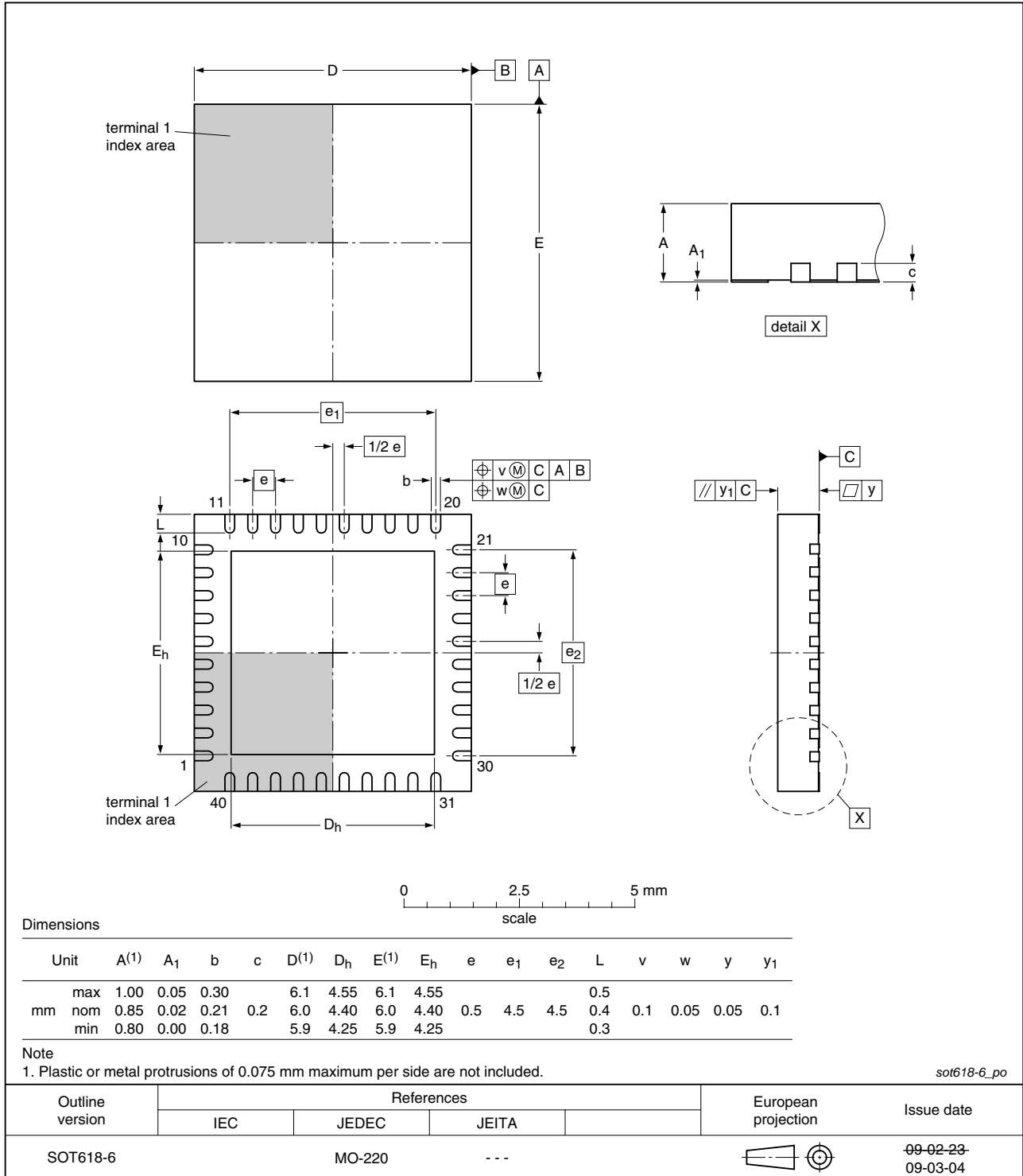


Fig 27. Package outline SOT618-6 (HVQFN40)

13. Revision history

Table 33. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
ADC1010S_SER_1	20100409	Preliminary data sheet	-	-

14. Legal information

14.1 Data sheet status

Document status ^{[1][2]}	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

14.2 Definitions

Draft — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

Product specification — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

14.3 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the *Terms and conditions of commercial sale* of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or

malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors accepts no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

Terms and conditions of commercial sale — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at <http://www.nxp.com/profile/terms>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

No offer to sell or license — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

Export control — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from national authorities.

Non-automotive qualified products — Unless this data sheet expressly states that this specific NXP Semiconductors product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. NXP Semiconductors accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without NXP Semiconductors' warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond

NXP Semiconductors' specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies NXP Semiconductors for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond NXP Semiconductors' standard warranty and NXP Semiconductors' product specifications.

14.4 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

15. Contact information

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: salesaddresses@nxp.com

16. Contents

1	General description	1	11.6.3	Register allocation map	26
2	Features and benefits	1	12	Package outline	32
3	Applications	1	13	Revision history	33
4	Ordering information	2	14	Legal information	34
5	Block diagram	2	14.1	Data sheet status	34
6	Pinning information	3	14.2	Definitions	34
6.1	Pinning	3	14.3	Disclaimers	34
6.2	Pin description	3	14.4	Trademarks	35
7	Limiting values	5	15	Contact information	35
8	Thermal characteristics	5	16	Contents	36
9	Static characteristics	6			
10	Dynamic characteristics	8			
10.1	Dynamic characteristics	8			
10.2	Clock and digital output timing	10			
10.3	SPI timings	12			
11	Application information	12			
11.1	Device control	12			
11.1.1	SPI and Pin control modes	12			
11.1.2	Operating mode selection	13			
11.1.3	Selecting the output data standard	13			
11.1.4	Selecting the output data format	13			
11.2	Analog inputs	13			
11.2.1	Input stage	13			
11.2.2	Anti-kickback circuitry	14			
11.2.3	Transformer	15			
11.3	System reference and power management	16			
11.3.1	Internal/external references	16			
11.3.2	Reference gain control	17			
11.3.3	Common-mode output voltage ($V_{O(cm)}$)	18			
11.3.4	Biasing	18			
11.4	Clock input	18			
11.4.1	Drive modes	18			
11.4.2	Equivalent input circuit	19			
11.4.3	Duty cycle stabilizer	20			
11.4.4	Clock input divider	20			
11.5	Digital outputs	20			
11.5.1	Digital output buffers: CMOS mode	20			
11.5.2	Digital output buffers: LVDS DDR mode	21			
11.5.3	Data valid (DAV) output clock	22			
11.5.4	Out-of-Range (OTR)	22			
11.5.5	Digital offset	22			
11.5.6	Test patterns	22			
11.5.7	Output codes versus input voltage	23			
11.6	Serial peripheral interface	23			
11.6.1	Register description	23			
11.6.2	Default modes at start-up	24			

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP B.V. 2010. All rights reserved.

For more information, please visit: <http://www.nxp.com>
For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 9 April 2010

Document identifier: ADC1010S_SER_1