ADJD-S313-QR999
Miniature Surface-Mount RGB Digital Color Sensor

Avago
T E C H N O L O G I E S

Data Sheet

Description

The ADJD-S313-QR999 is a cost effective, CMOS digital output RGB color sensor in miniature surface-mount package with a mere size of 5x5x0.75mm. The IC comes with integrated RGB filters, an analog-to-digital converter and a digital core for communication and sensitivity control. The output allows direct interface to micro-controller or other logic control for further signal processing without the need of any additional components.

This device is designed to cater for wide dynamic range of illumination level and is ideal for applications like portable or mobile devices which demand higher integration, smaller size and low power consumption. Sensitivity control is performed by the serial interface and can be optimized individually for the different color channel. The sensor can also be used in conjunction with a white LED for reflective color management.

General Specifications

Feature	Value
Interface	100kHz serial interface
Supply	2.6V digital (nominal), 2.6V analog (nominal)

Features

- Fully integrated RGB digital color sensor
- Digital I/O via 2-wire serial interface
- Industry's smallest form factor – QFN 5x5x0.75mm
- Adjustable sensitivity for different levels of illumination
- Uniformly distributed RGB photodiode array
- 7 bit resolution per channel output
- Built in internal oscillator
- Sleep function when not in use
- No external components
- Low supply voltage (V_{DD}) 2.6V
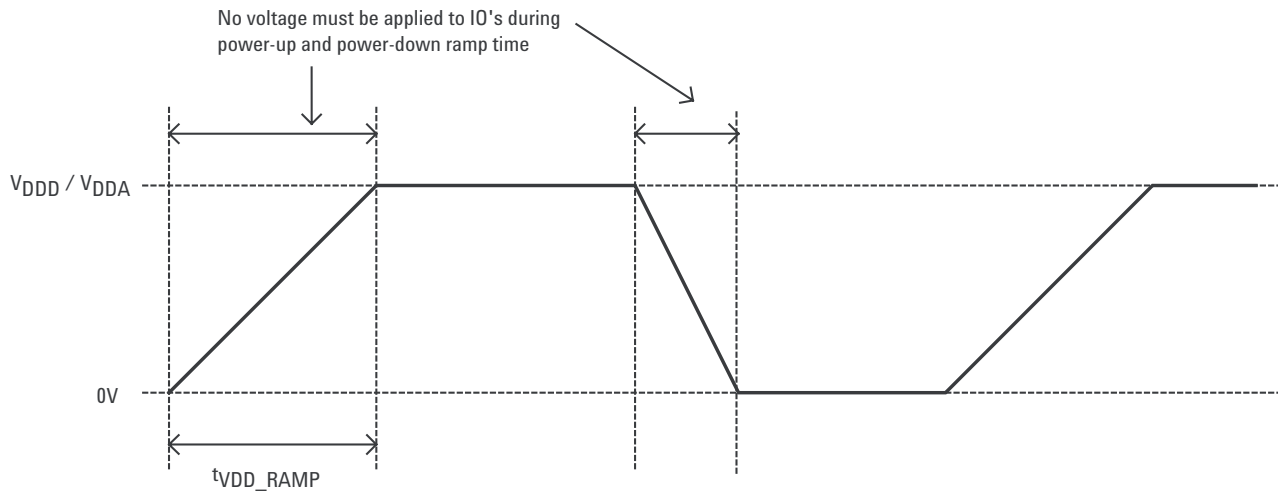- 0°C to 70°C operating temperature
- Lead free package

Applications

- General color detection and measurement
- Mobile appliances such as mobile phones, PDAs, MP3 players,etc.
- Consumer appliances
- Portable medical equipments
- Portable color detector/reader

ESD WARNING: *Standard CMOS handling precautions should be observed to avoid static discharge.*

Powering the Device

No voltage must be applied to IO's during
power-up and power-down ramp time

V_{DDD} / V_{DDA}
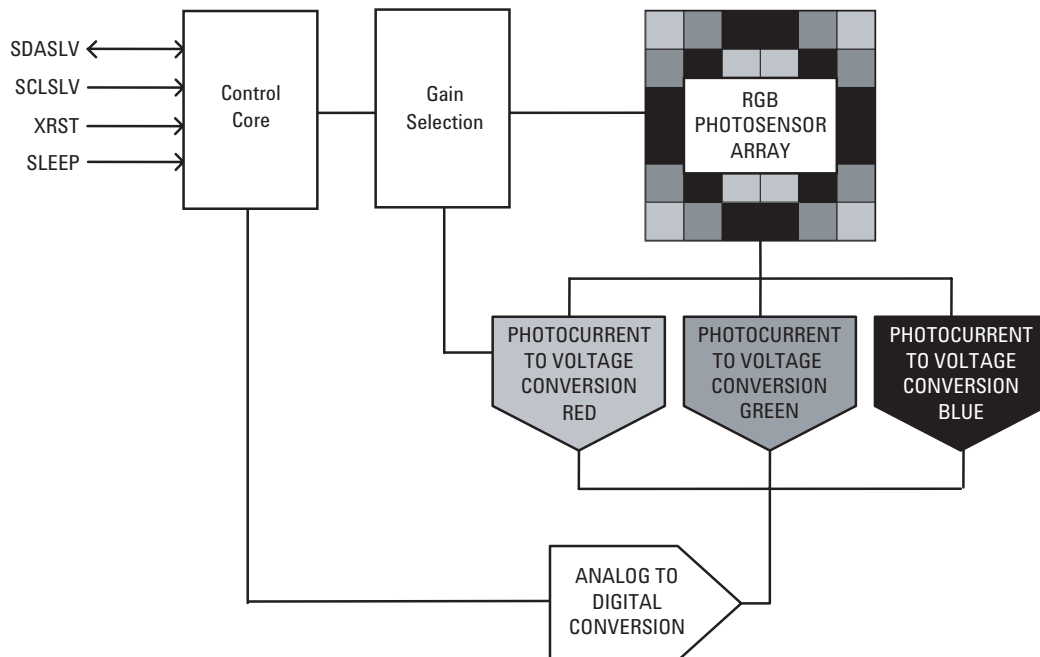
0V

t_{VDD_RAMP}

ESD Protection Diode Turn-On During Power-Up and Power-Down

A particular power-up and power-down sequence must be used to prevent any ESD diode from turning on inadvertently. The figure above describes the sequence. In general, AVDD and DVDD should power-up and powerdown together to prevent ESD diodes from turning on inadvertently. During this period, no voltage should be applied to the IO's for the same reason.

Ground Connection

AGND and DGND must both be set to 0V and preferably star-connected to a central power source as shown in the application diagram. A potential difference between AGND and DGND may cause the ESD diodes to turn on inadvertently.

Block Diagram

SDASLV
SCLSLV
XRST
SLEEP

Control Core

Gain Selection

RGB PHOTOSENSOR ARRAY

PHOTOCURRENT TO VOLTAGE CONVERSION RED

PHOTOCURRENT TO VOLTAGE CONVERSION GREEN

PHOTOCURRENT TO VOLTAGE CONVERSION BLUE

ANALOG TO DIGITAL CONVERSION

Electrical Specifications

Absolute Maximum Ratings (Notes 1 & 2)

Parameter	Symbol	Minimum	Maximum	Units	Notes
Storage temperature	T_{STG_ABS}	-40	85	°C	
Digital supply voltage, DVDD to DVSS	V_{DDD_ABS}	-0.5	3.7	V	
Analog supply voltage, AVDD to AVSS	V_{DDA_ABS}	-0.5	3.7	V	
Input voltage	V_{IN_ABS}	-0.5	V_{DDD}+0.5	V	All I/O pins
Solder Reflow Peak temperature	T_{L_ABS}		235	°C	
Human Body Model ESD rating	ESD_{HBM_ABS}		2	kV	All pins, human body model per JESD22-A114-B

Recommended Operating Conditions

Parameter	Symbol	Minimum	Typical	Maximum	Units
Free air operating temperature	T_A	0	25	70	°C
Digital supply voltage, DVDD to DVSS	V_{DDD}	2.5	2.6	3.6	V
Analog supply voltage, AVDD to AVSS	V_{DDA}	2.5	2.6	3.6	V
Output current load high	I_{OH}			3	mA
Output current load low	I_{OL}			3	mA
Input voltage high level (Note 4)	V_{IH}	0.7 V_{DDD}		V_{DDD}	V
Input voltage low level (Note 4)	V_{IL}	0		0.3 V_{DDD}	V

DC Electrical Specifications

Over Recommended Operating Conditions (unless otherwise specified)

Parameter	Symbol	Conditions	Minimum	Typical (Note 3)	Maximum	Units
Output voltage high level (Note 5)	V_{OH}	I_{OH} = 3mA	V_{DDD}-0.8	V_{DDD}-0.4		V
Output voltage low level (Note 6)	V_{OL}	I_{OL} = 3mA		0.2	0.4	V
Dynamic supply current (Note 7,8)	I_{DD_DYN}	(Note 9)		9.4	14	mA
Static supply current (Note 8)	I_{DD_STATIC}	(Note 9)		2.7		mA
Sleep-mode supply current (Note 8)	I_{DD_SLP}	(Note 9)		0.2	15	uA
Input leakage current	I_{LEAK}		-10		10	uA

AC Electrical Specifications

Parameter	Symbol	Conditions	Minimum	Typical (Note 3)	Maximum	Units
Internal clock frequency	f_{CLK}		16	26	38	MHz

Optical Specification

Parameter	Symbol	Conditions	Minimum	Typical (Note 3)	Maximum	Units
Dark offset*	V_D	Ee = 0		65		LSB

*code is from dark code to (dark code + 128LSB)

Minimum sensitivity

Parameter	Symbol	Conditions		Minimum	Typical (Note 3)	Maximum	Units
Irradiance Responsivity	Re	λ_P = 460 nm Refer Note 10	B		36		LSB / (mW/cm^2)
		λ_P = 542 nm Refer Note 11	G		53		
		λ_P = 645 nm Refer Note 12	R		82		

Maximum sensitivity

Parameter	Symbol	Conditions		Minimum	Typical (Note 3)	Maximum	Units
Irradiance Responsivity	Re	λ_P = 460 nm Refer Note 10	B		1250		LSB / (mW/cm^2)
		λ_P = 542 nm Refer Note 11	G		1750		
		λ_P = 645 nm Refer Note 12	R		2490		

Minimum sensitivity

Parameter	Symbol	Conditions		Minimum	Typical (Note 3)	Maximum	Units
Saturation Irradiance (note 13)		λ_P = 460 nm Refer Note 10	B		4.17		mW/cm^2
		λ_P = 542 nm Refer Note 11	G		2.83		
		λ_P = 645 nm Refer Note 12	R		1.83		

Maximum sensitivity

Parameter	Symbol	Conditions		Minimum	Typical (Note 3)	Maximum	Units
Saturation Irradiance (note 13)		λ_P = 460 nm Refer Note 10	B		0.12		mW/cm^2
		λ_P = 542 nm Refer Note 11	G		0.09		
		λ_P = 645 nm Refer Note 12	R		0.06		

Notes:
1. The "Absolute Maximum Ratings" are those values beyond which damage to the device may occur. The device should not be operated at these limits. The parametric values defined in the "Electrical Specifications" table are not guaranteed at the absolute maximum ratings. The "Recommended Operating Conditions" table will define the conditions for actual device operation.
2. Unless otherwise specified, all voltages are referenced to ground.
3. Specified at room temperature (25°C) and $V_{DDD} = V_{DDA} = 2.6V$.
4. Applies to all DI pins.
5. Applies to all DO pins. SDASLV go tri-state when output logic high. Minimum V_{OH} depends on the pull-up resistor value.
6. Applies to all DO and DIO pins.
7. Dynamic testing is performed with the IC operating in a mode representative of typical operation.
8. Refers to total device current consumption.
9. Output and bidirectional pins are not loaded.
10. Test condition is blue light of peak wavelength (λ_P) 460 nm and spectral half width ($\Delta\lambda\frac{1}{2}$) 25 nm.
11. Test condition is green light of peak wavelength (λ_P) 542 nm and spectral half width ($\Delta\lambda\frac{1}{2}$) 35 nm
12. Test condition is red light of peak wavelength (λ_P) 645 nm and spectral half width ($\Delta\lambda\frac{1}{2}$) 20 nm
13. Saturation irradiance = (MSB)/(Irradiance responsivity)
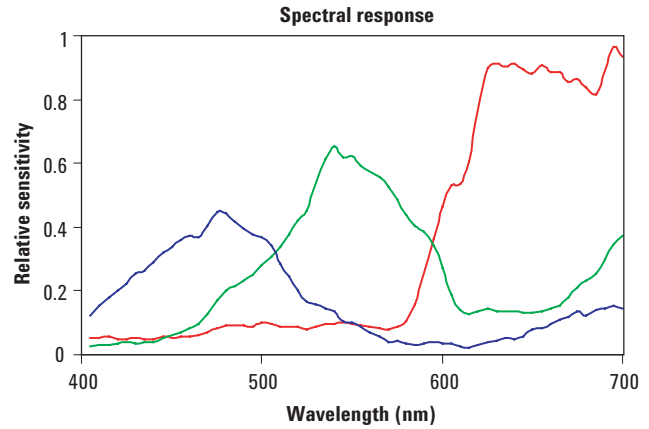
Spectral response

Typical spectral response when the gains for all the color channels are set at equal.

Serial Interface Timing Information

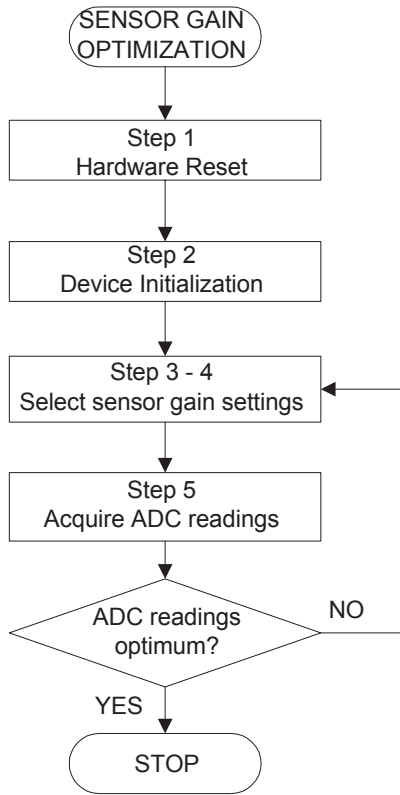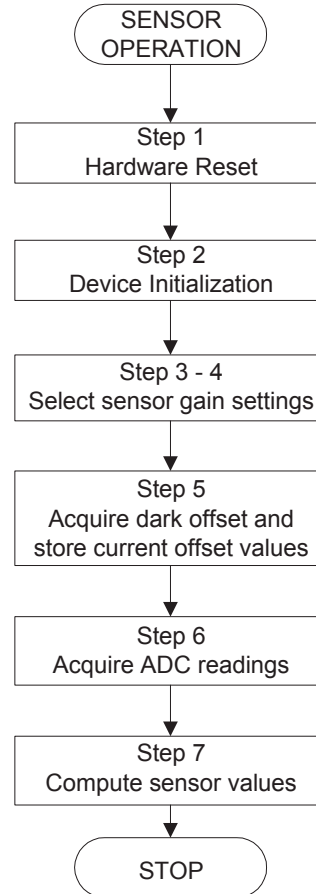| Parameter	Symbol	Minimum	Maximum	Units
SCL clock frequency	f_{scl}	0	100	kHz
(Repeated) START condition hold time	$t_{HD:STA}$	4	-	μs
Data hold time	$t_{HD:DAT}$	0	3.45	μs
SCL clock low period	t_{LOW}	4.7	-	μs
SCL clock high period	t_{HIGH}	4.0	-	μs
Repeated START condition setup time	$t_{SU:STA}$	4.7	-	μs
Data setup time	$t_{SU:DAT}$	250	-	ns
STOP condition setup time	$t_{SU:STO}$	4.0	-	μs
Bus free time between START and STOP conditions	t_{BUF}	4.7	-	μs
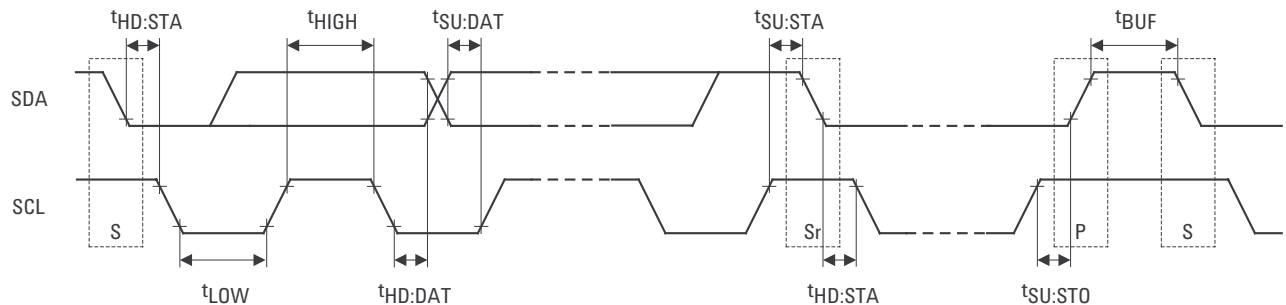
Figure 1. Serial Interface Bus Timing Waveforms

High Level Description

The sensor needs to be configured before it can be used. The gain selection needs to be set for optimum performance depending on light levels. The flowcharts below describe the different procedures required.

```
     ┌─────────────────┐
     │  SENSOR GAIN    │
     │  OPTIMIZATION   │
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │     Step 1      │
     │ Hardware Reset  │
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │     Step 2      │
     │Device Initialization│
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │    Step 3 - 4   │◄──────┐
     │Select sensor gain settings│   │
     └────────┬────────┘       │
              │                │
     ┌────────▼────────┐       │
     │     Step 5      │       │
     │Acquire ADC readings│     │
     └────────┬────────┘       │
              │                │
           ╱──▼──╲         NO  │
          ╱ ADC   ╲────────────┘
          ╲readings╱
          ╱optimum?╲
           ╲──┬──╱
          YES │
     ┌────────▼────────┐
     │      STOP       │
     └─────────────────┘
```

Sensor gain optimization flowchart

```
     ┌─────────────────┐
     │    SENSOR       │
     │   OPERATION     │
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │     Step 1      │
     │ Hardware Reset  │
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │     Step 2      │
     │Device Initialization│
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │    Step 3 - 4   │
     │Select sensor gain settings│
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │     Step 5      │
     │Acquire dark offset and│
     │store current offset values│
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │     Step 6      │
     │Acquire ADC readings│
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │     Step 7      │
     │Compute sensor values│
     └────────┬────────┘
              │
     ┌────────▼────────┐
     │      STOP       │
     └─────────────────┘
```

Sensor operation flowchart

* Please refer to application note for more detailed information.

Detail Description

A hardware reset (by asserting XRST) should be performed before starting any operation.

The user controls and configures the device by programming a set of internal registers through a serial interface. At the start of application, the following setup data must be written to the setup registers:

Address (Hex)	Register	Setup Data (Hex)
03	SETUP0	01
04	SETUP1	01
0C	SETUP2	01
0D	SETUP3	01
0E	SETUP4	01

Sensor Gain Settings

The sensor gain can be adjusted by varying the photodiode size and integration time of the sensor manually through the following registers.

Sensor Sensitivity ~ Photodiode Size x Integration Time Slot

Address (Hex)	Register	Description
0B	PDASR	Red Channel Photodiode Size
0A	PDASG	Green Channel Photodiode Size
09	PDASB	Blue Channel Photodiode Size
11	TINTR	Red Channel Integration Time
10	TINTG	Green Channel Integration Time
0F	TINTB	Blue Channel Integration Time

Setup Value for Photodiode Size

The following value can be written to each of the photodiode size registers to adjust the gain of the sensor. The default value after reset for these registers is 07H.

Value (Hex)	Photodiode Size
01	¼
03	½
07	¾
0F	Full

Setup Value for Integration Time

The following value can be written to each of the integration time registers to adjust the gain of the sensor. The default value after reset for these registers is 07H.

Value (Hex)	Integration Time Slot
00	1
01	2
02	3
03	4
04	5
05	6
06	7
07	8
08	9
09	10
0A	11
0B	12
0C	13
0D	14
0E	15
0F	16

Sensor ADC Output Registers

To obtain sensor ADC value, '02' Hex must be written to ACQ register before reading the Sensor ADC Output Registers.

Address (Hex)	Register	Description
02	ACQ	Acquire sensor analog to digital converter (ADC) values when 02H is written. Reset to 00H when sensor acquisition is completed
44	ADCR	Sensor Red channel ADC value
43	ADCG	Sensor Green channel ADC value
42	ADCB	Sensor Blue channel ADC value

Serial Interface Reference

Description

The programming interface to the ADJD-S313 is a 2-wire serial bus. The bus consists of a serial clock (SCL) and a serial data (SDA) line. The SDA line is bi-directional on ADJD-S313 and must be connected through a pull-up resistor to the positive power supply. When the bus is free, both lines are HIGH.

The 2-wire serial bus on ADJD-S313 requires one device to act as a master while all other devices must be slaves. A master is a device that initiates a data transfer on the bus, generates the clock signal and terminates the data transfer while a device addressed by the master is called a slave. Slaves are identified by unique device addresses.

Both master and slave can act as a transmitter or a receiver but the master controls the direction for data transfer. A transmitter is a device that sends data to the bus and a receiver is a device that receives data from the bus.

The ADJD-S313 serial bus interface always operates as a slave transceiver with a data transfer rate of up to 100kbit/s.

START/STOP Condition

The master initiates and terminates all serial data transfers. To begin a serial data transfer, the master must send a unique signal to the bus called a START condition. This is defined as a HIGH to LOW transition on the SDA line while SCL is HIGH.

The master terminates the serial data transfer by sending another unique signal to the bus called a STOP condition. This is defined as a LOW to HIGH transition on the SDA line while SCL is HIGH.

The bus is considered to be busy after a START (S) condition. It will be considered free a certain time after the STOP (P) condition. The bus stays busy if a repeated START (Sr) is sent instead of a STOP condition.

The START and repeated START conditions are functionally identical.

Data Transfer

The master initiates data transfer after a START condition. Data is transferred in bits with the master generating one clock pulse for each bit sent. For a data bit to be valid, the SDA data line must be stable during the HIGH period of the SCL clock line. Only during the LOW period of the SCL clock line can the SDA data line change state to either HIGH or LOW.
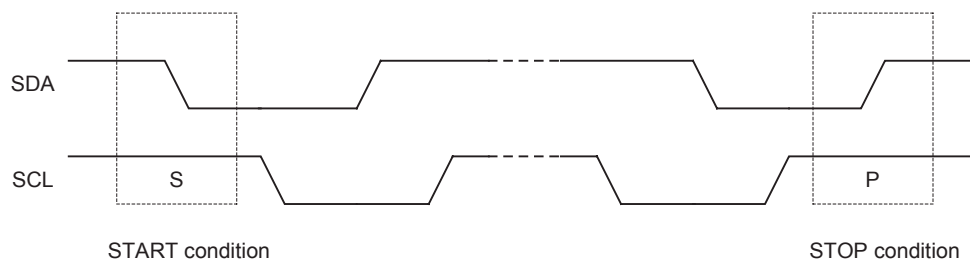
Figure 1. START/STOP Condition
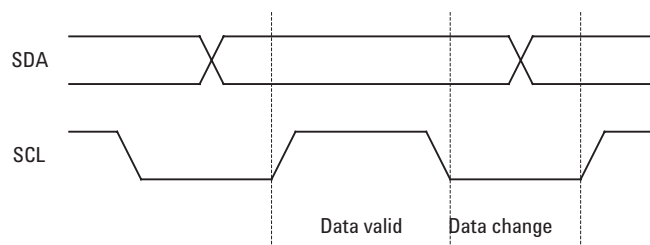
Figure 2. Data Bit Transfer

The SCL clock line synchronizes the serial data transmission on the SDA data line. It is always generated by the master. The frequency of the SCL clock line may vary throughout the transmission as long as it still meets the minimum timing requirements.

The master by default drives the SDA data line. The slave drives the SDA data line only when sending an acknowledge bit after the master writes data to the slave or when the master requests the slave to send data.

The SDA data line driven by the master may be implemented on the negative edge of the SCL clock line. The master may sample data driven by the slave on the positive edge of the SCL clock line. Figure shows an example of a master implementation and how the SCL clock line and SDA data line can be synchronized.

A complete data transfer is 8-bits long or 1-byte. Each byte is sent most significant bit (MSB) first followed by an acknowledge or not acknowledge bit. Each data transfer can send an unlimited number of bytes (depending on the data format).
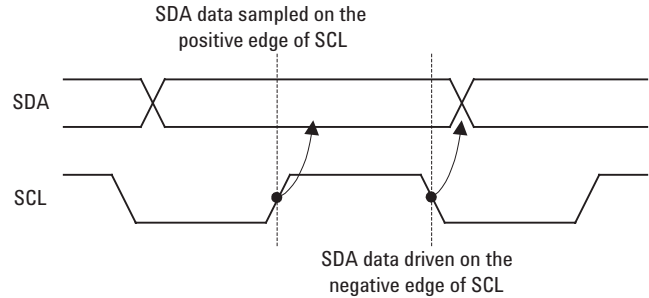
Figure 3. Data Bit Synchronization

Acknowledge/Not acknowledge

The receiver must always acknowledge each byte sent in a data transfer. In the case of the slave-receiver and master-transmitter, if the slave-receiver does not send an acknowledge bit, the master-transmitter can either STOP the transfer or generate a repeated START to start a new transfer.
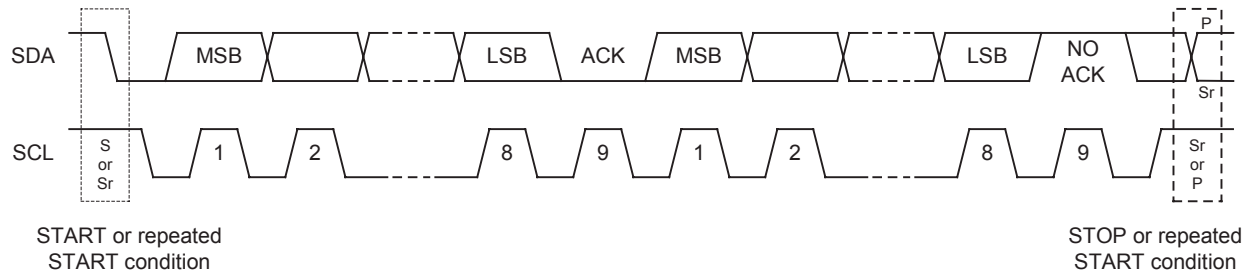
Figure 4. Data Byte Transfer
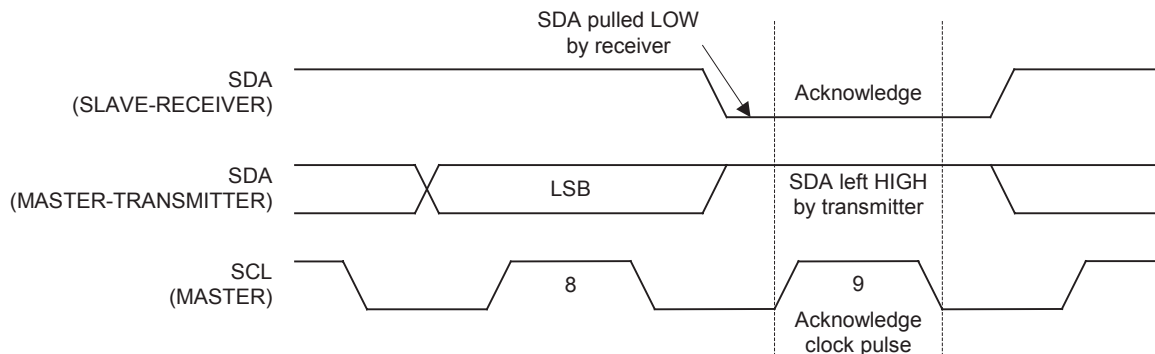
Figure 5. Slave-Receiver Acknowledge

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In the case of the master-receiver and slave-transmitter, the master generates a not acknowledge to signal the end of the data transfer to the slave-transmitter. The master can then send a STOP or repeated START condition to begin a new data transfer.

In all cases, the master generates the acknowledge or not acknowledge SCL clock pulse.

Addressing

Each slave device on the serial bus needs to have a unique address. This is the first byte that is sent by the master-transmitter after the START condition. The address is defined as the first seven bits of the first byte.

The eighth bit or least significant bit (LSB) determines the direction of data transfer. A 'one' in the LSB of the first byte indicates that the master will read data from the addressed slave (master-receiver and slave-transmitter). A 'zero' in this position indicates that the master will write data to the addressed slave (master-transmitter and slave-receiver).

A device whose address matches the address sent by the master will respond with an acknowledge for the first byte and set itself up as a slave-transmitter or slave-receiver depending on the LSB of the first byte.

The slave address on ADJD-S313 is 0x58 (7-bits).
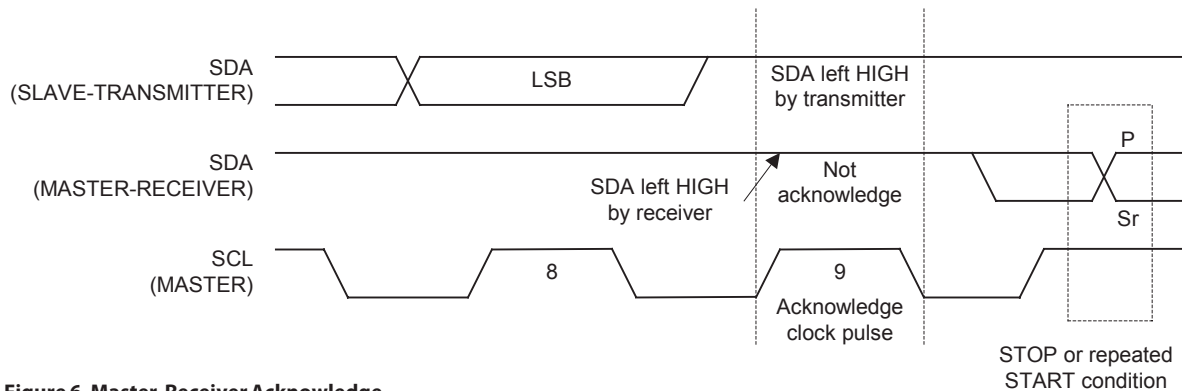
Figure 6. Master-Receiver Acknowledge

Figure 7. Slave Addressing

Data format

ADJD-S313 uses a register-based programming architecture. Each register has a unique address and controls a specific function inside the chip.

To write to a register, the master first generates a START condition. Then it sends the slave address for the device it wants to communicate with. The least significant bit (LSB) of the slave address must indicate that the master wants to write to the slave. The addressed device will then acknowledge the master.

The master writes the register address it wants to access and waits for the slave to acknowledge. The master then writes the new register data. Once the slave acknowledges, the master generates a STOP condition to end the data transfer.

To read from a register, the master first generates a START condition. Then it sends the slave address for the device it wants to communicate with. The least significant bit (LSB) of the slave address must indicate that the master wants to write to the slave. The addressed device will then acknowledge the master.

The master writes the register address it wants to access and waits for the slave to acknowledge. The master then generates a repeated START condition and resends the slave address sent previously. The least significant bit (LSB) of the slave address must indicate that the master wants to read from the slave. The addressed device will then acknowledge the master.

The master reads the register data sent by the slave and sends a no acknowledge signal to stop reading. The master then generates a STOP condition to end the data transfer.
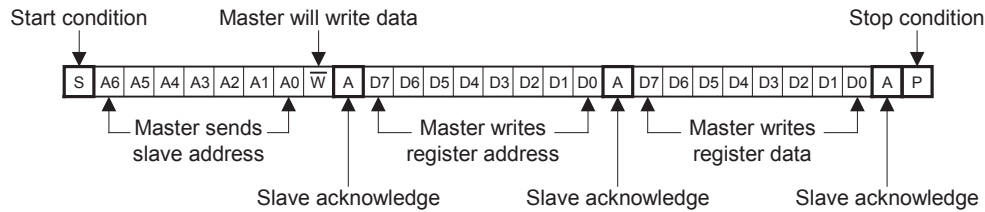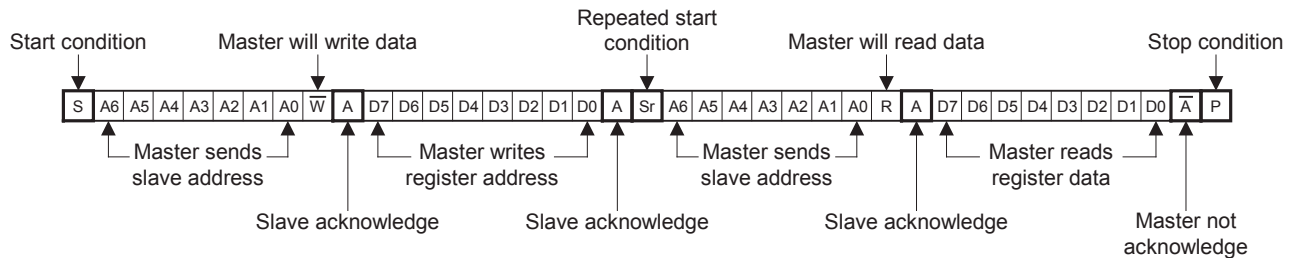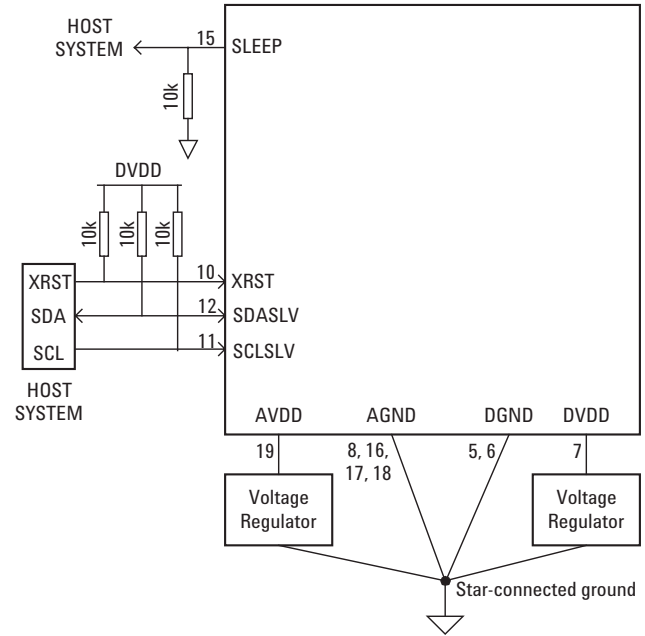

Figure 8. Register Byte Write Protocol

Figure 9. Register Byte Read Protocol

Powering the Device

Ground Connection

AGND and DGND must both be set to 0V and preferably star-connected to a central power source as shown in the application diagram. A potential difference between AGND and DGND may cause the ESD diodes to turn on inadvertently.
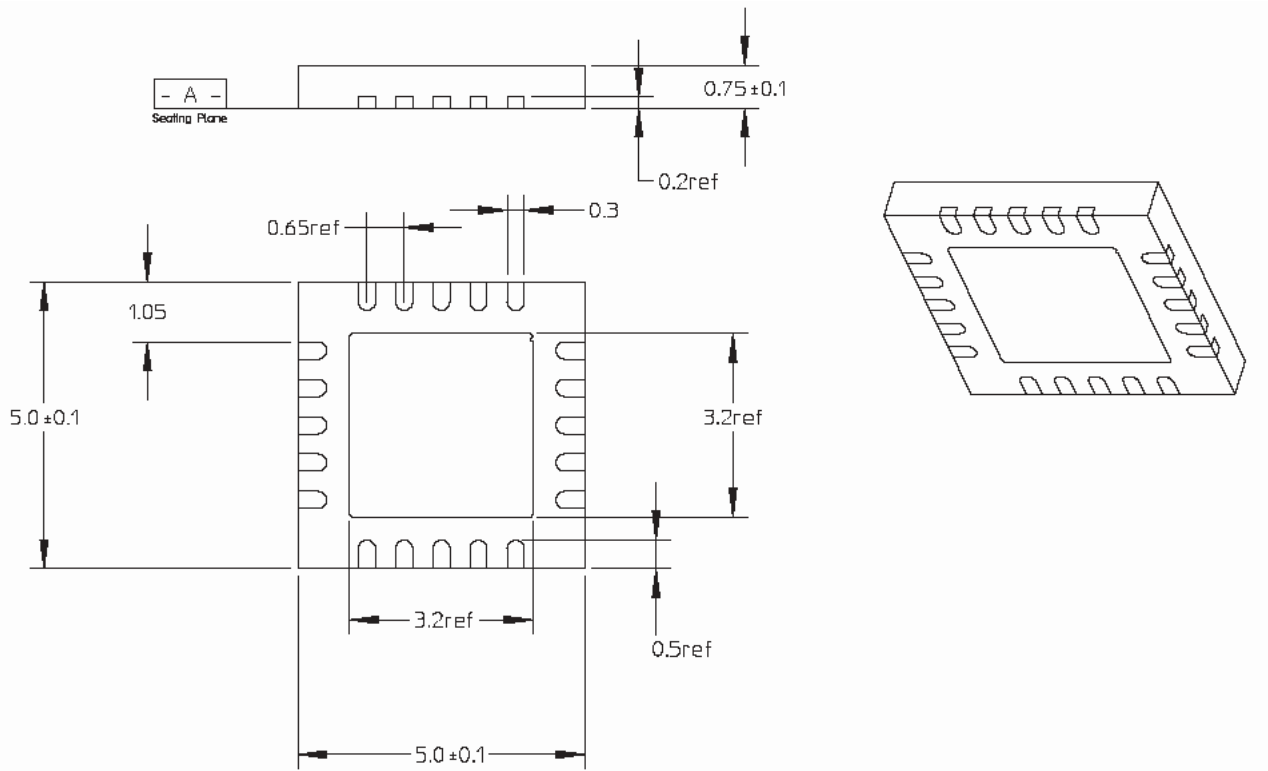
Application Diagrams

Pin Information

PIN	NAME	TYPE	DESCRIPTION
1	NC	No connect	No connect. Leave floating.
2	NC	No connect	No connect. Leave floating.
3	NC	No connect	No connect. Leave floating.
4	NC	No connect	No connect. Leave floating.
5	DGND	Ground	Tie to digital ground.
6	DGND	Ground	Tie to digital ground.
7	DVDD	Power	Digital power pin.
8	AGND	Ground	Tie to analog ground.
9	NC	No connect	No connect. Leave floating.
10	XRST	Input	Global, asynchronous, active-low system reset. When asserted low, XRST resets all registers. Minimum reset pulse low is 10 µs and must be provided by external circuitry.
11	SCLSLV	Input	SDASLV and SCLSLV are the serial interface communications pins. SDASLV is the bidirectional data pin and SCLSLV is the interface clock. A pull-up resistor should be tied to SDASLV because it goes tri-state to output logic 1.
12	SDASLV	Input/Output (tri-state high)	
13	NC	No connect	No connect. Leave floating.
14	NC	No connect	No connect. Leave floating.
15	SLEEP	Input	When SLEEP=1, the device goes into sleep mode. In sleep mode, all analog circuits are powered down and the clock signal is gated away from the core logic resulting in very low current consumption.
16	AGND	Ground	Tie to analog ground.
17	AGND	Ground	Tie to analog ground.
18	AGND	Ground	Tie to analog ground.
19	AVDD	Power	Analog power pin.
20	NC	No connect	No connect. Leave floating.

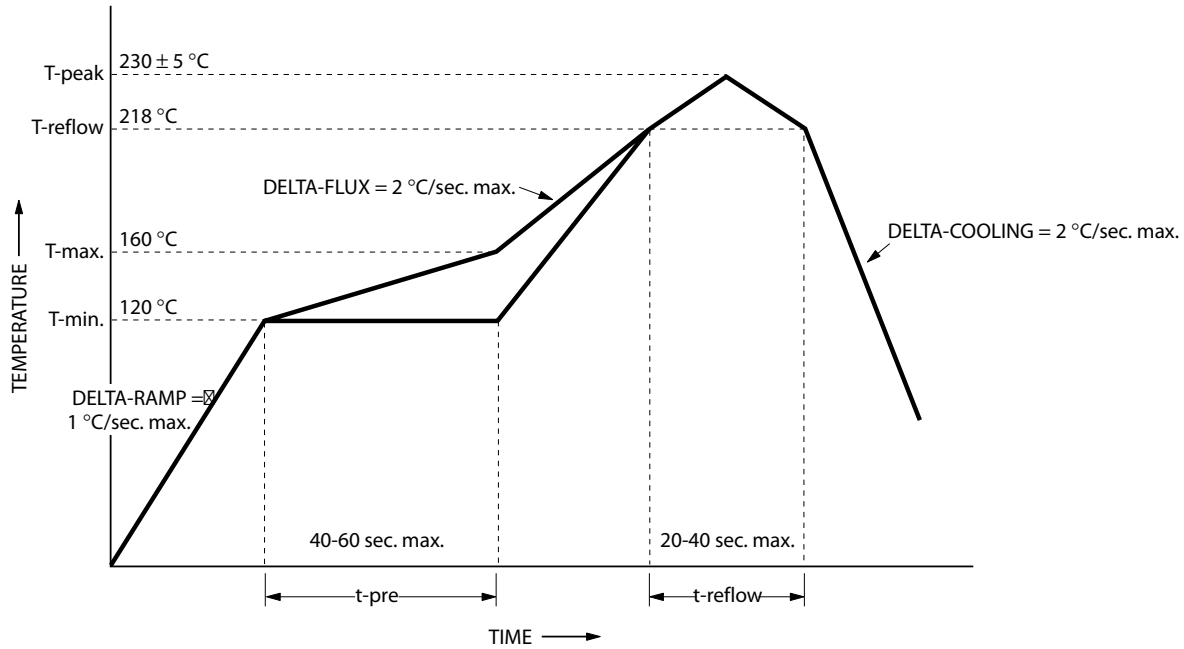## Package Dimensions

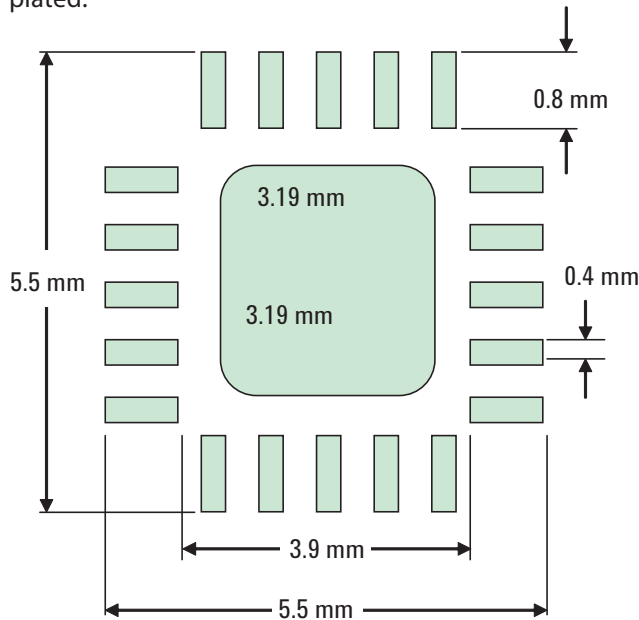## Bottom View
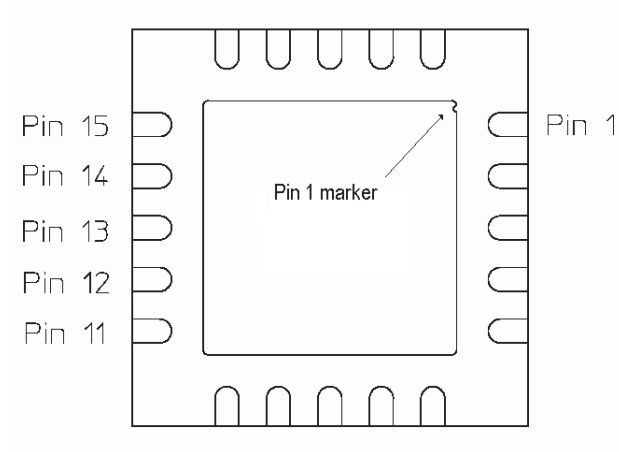
NOTE: DIMENSIONS ARE IN MILIMETERS (MM)

Recommended Reflow Profile

It is recommended that Henkel Pb-free solder paste LF310 be used for soldering ADJD-S313. Below is the recommended soldering profile.
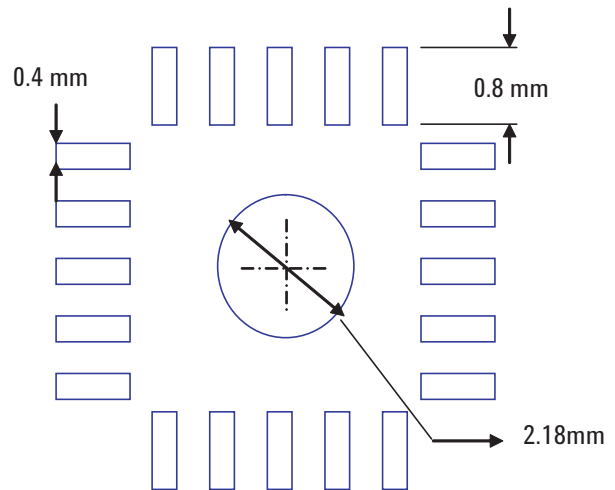

20 Lead QFN Recommended PCB Land Pad Design

IPC-SM-782 is used as the standard for the PCB land pad design. Recommended PCB finishing is gold plated.

20 Lead QFN Recommended Stencil Design

A stencil thickness of 2.18mm (6 mils) for this QFN package is recommended.

Recommendations for Handling and Storage of ADJD-S313

This product is qualified as Moisture Sensitive Level 3 per Jedec J-STD-020. Precautions when handling this moisture sensitive product is important to ensure the reliability of the product. Do refer to Avago Application Note AN5305 Handling Of Moisture Sensitive Surface Mount Devices for details.

A. Storage before use

- Unopened moisture barrier bag (MBB) can be stored at 30°C and 90%RH or less for maximum 1 year

- It is not recommended to open the MBB prior to assembly (e.g. for IQC)

- It should also be sealed with a moisture absorbent material (Silica Gel) and an indicator card (cobalt chloride) to indicate the moisture within the bag

B. Control after opening the MBB

- The humidity indicator card (HIC) shall be read immediately upon opening of MBB

- The components must be kept at <30°C/60%RH at all time and all high temperature related process including soldering, curing or rework need to be completed within 168hrs

C. Control for unfinished reel

- For any unused components, they need to be stored in sealed MBB with desiccant or desiccator at <5%RH

D. Control of assembled boards

- If the PCB soldered with the components is to be subjected to other high temperature processes, the PCB need to be stored in sealed MBB with desiccant or desiccator at <5%RH to ensure no components have exceeded their floor life of 168hrs

E. Baking is required if:

- "10%" or "15%" HIC indicator turns pink

- The components are exposed to condition of >30°C/ 60%RH at any time.

- The components floor life exceeded 168hrs

- Recommended baking condition (in component form): 125°C for 24hrs
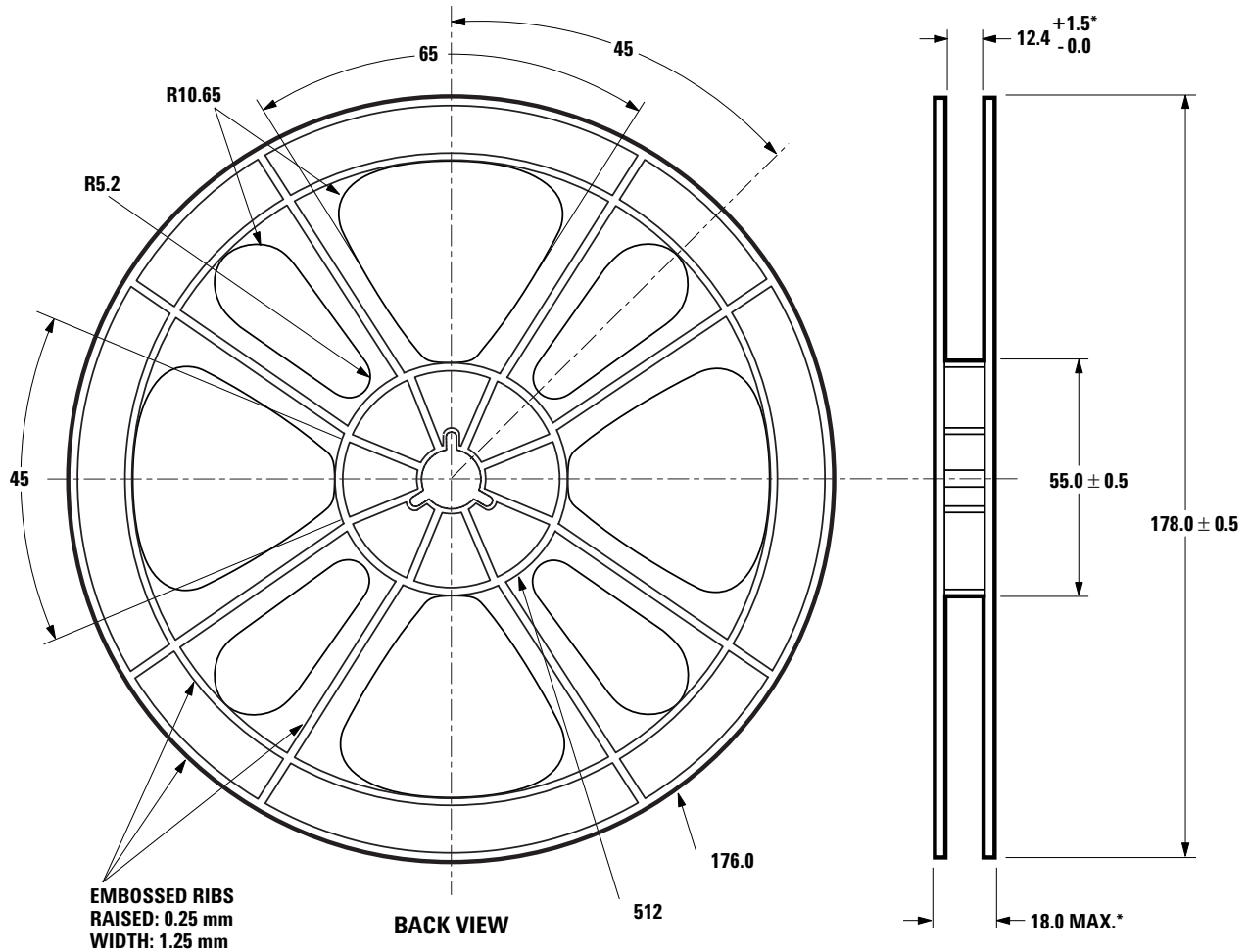
Package Tape and Reel Dimensions

Carrier Tape Dimensions

A_O:	5.30
B_O:	5.30
K_O:	2.20
PITCH:	8.00
WIDTH:	12.00
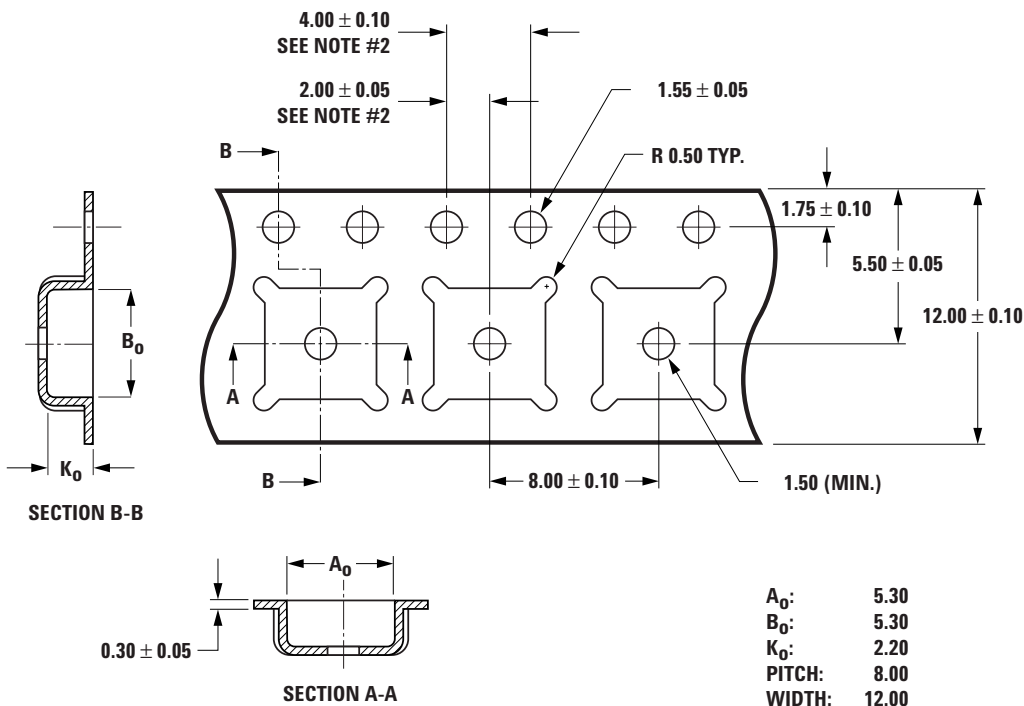
NOTES:

1. A_O AND B_O MEASURED AT 0.3 mm ABOVE BASE OF POCKET.
2. 10 PITCHES CUMULATIVE TOLERANCE IS ± 0.2 mm.
3. DIMENSIONS ARE IN MILLIMETERS (mm).

Reel Dimensions

65

45

R10.65

R5.2

45

176.0

512

BACK VIEW

EMBOSSED RIBS
RAISED: 0.25 mm
WIDTH: 1.25 mm

12.4 $^{+1.5*}_{-0.0}$

55.0 ± 0.5

178.0 ± 0.5

18.0 MAX.*

NOTES:
1. *MEASURED AT HUB AREA.
2. ALL FLANGE EDGES TO BE ROUNDED.

ESD WARNING: *Standard CMOS handling precautions should be observed to avoid static discharge.*

For product information and a complete list of distributors, please go to our web site: **www.avagotech.com**

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