

## AF133/AF134 PCM Transmit/Receive Filters

### General Description

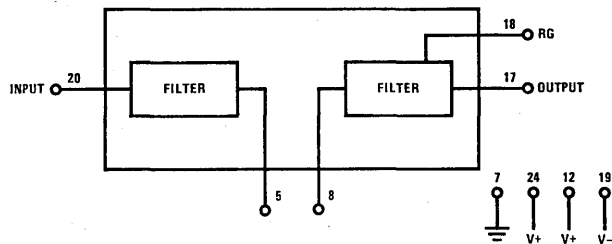
The AF133 and AF134 filter circuits are specifically designed to meet the stringent requirements of the telephone industry. Special attention has been given not only to the electrical filtering requirements of the D3 channel bank, but also to the physical size, environmental, life and cost requirements.

The filters are manufactured using a well understood and dependable thick film technology using laser trimmed resistors and the highest quality components.

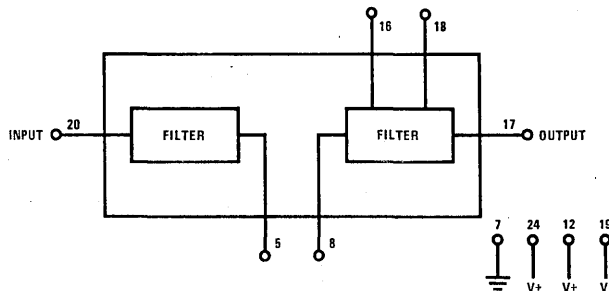
### Features

- No external components required
- Active laser trimmed
- Consistent uniform product
- Insensitive to time and temperature
- Designed for D3 system requirements
- Wide power supply range  $\pm 12V$  to  $\pm 15V$

### Connection Diagram



Ceramic Dual-In-Line Package HY24A  
AF133-1CJ  
AF133-2CJ



Ceramic Dual-In-Line Package HY24A  
AF134-1CJ  
AF134-2CJ

## Absolute Maximum Ratings

|                               |                 |
|-------------------------------|-----------------|
| Supply Voltage                | ±18V            |
| Power Dissipation             | 1W/Package      |
| Input Voltage                 | ±18V            |
| Output Short-Circuit Duration | Continuous      |
| Operating Temperature Range   | 0°C to +70°C    |
| Storage Temperature Range     | -25°C to +100°C |

## Electrical Characteristics

Unless otherwise noted, these specifications apply over the temperature range from 0°C to +70°C and are tested using ±12V supplies, but are guaranteed for any symmetrical supply operation between ±12V to ±15V.

### AF133 Transmit Filter

| SYMBOL                    | PARAMETER                       | CONDITIONS  | AF133-1 |        |      | AF133-2 |        |        | UNITS |
|---------------------------|---------------------------------|---|---------|--------|------|---------|--------|--------|-------|
|                           |                                 |   | MIN     | TYP    | MAX  | MIN     | TYP    | MAX    |       |
| <b>FREQUENCY RESPONSE</b> |                                 |   |         |        |      |         |        |        |       |
| A                         | Voltage Gain                    | (Note 2)<br>f = 3.4 kHz   | -1.5    | -0.6   | 0    | -0.9    | -0.6   | 0      | dB    |
| A                         |                                 | f = 4 kHz   |         | -16    | -14  |         | -16    | -15    | dB    |
| A                         |                                 | f ≥ 4.5 kHz   |         | -33    | -30  |         | -33    | -32    | dB    |
| ΔA                        | Pass Band Ripple                | 300 Hz ≤ f ≤ 3 kHz  |         | ±0.08  | ±0.3 |         | ±0.08  | ±0.125 | dB    |
| Δt                        | Differential Delay              | 1 kHz ≤ f ≤ 2.6 kHz   |         | 60     | 90   |         | 60     | 80     | μs    |
| ΔA <sub>0</sub> /ΔT       | Gain Stability with Temperature | f = kHz, e <sub>IN</sub> = 0.1 Vrms   |         | 0.0015 |      |         | 0.0015 |        | dB/°C |
| ΔA <sub>0</sub> /Δt       | Gain Stability with Time        | f = 1 kHz, e <sub>IN</sub> = 0.1 Vrms   |         | 0.0005 |      |         | 0.0005 |        | dB/Yr |
| THD                       | Distortion                      | f = 1 kHz, e <sub>IN</sub> = 0.1 Vrms   |         | 0.1    | 0.5  |         | 0.1    | 0.5    | %     |
| e <sub>n</sub>            | Output Noise Voltage            | 10 Hz to 50 kHz, e <sub>IN</sub> = 0V,<br>T <sub>A</sub> = 25°C               |         | 150    | 250  |         | 150    | 250    | μVp-p |
| e <sub>o</sub>            | Output Voltage Swing            | V <sub>CC</sub> = ±12V, R <sub>L</sub> = 2k,<br>A = A <sub>0</sub> , (Note 2) | 10      | 15     |      | 10      | 15     |        | Vp-p  |
| V <sub>os</sub>           | Output DC Offset                |   | -150    |        | 150  | -75     |        | 75     | mV    |
| Z <sub>IN</sub>           | Input Impedance                 | DC to 10 kHz, T <sub>A</sub> = 25°C   | 100k    |        |      | 100k    |        |        | Ω     |
| Z <sub>o</sub>            | Output Impedance                | DC to 10 kHz, T <sub>A</sub> = 25°C   |         | 0.5    | 1    |         | 0.5    | 1      | Ω     |
| PSRR                      | Power Supply Rejection          | 120 Hz to 3.4 kHz   |         | 97     |      | 97      |        |        | dB    |
|                           |                                 | 3.4 kHz to 25 kHz   |         | 90     |      | 90      |        |        | dB    |
| P <sub>D</sub>            | Power Dissipation               | V <sub>CC</sub> = ±12V  |         | 135    | 220  |         | 135    | 220    | mW    |
|                           |                                 | V <sub>CC</sub> = ±15V  |         | 190    | 270  |         | 190    | 270    | mW    |

**Note 1:** The voltage gain may be adjusted. Refer to application discussion.

**Note 2:** The AF133 requires an external gain resistor, (R = 133k typ). All gain measurements assume gain at DC set for 0 dB at 1 kHz.

# Electrical Characteristics

## AF134 Receive Filter

| SYMBOL                    | PARAMETER                       | CONDITIONS  | AF134-1 |        |      | AF134-2 |        |       | UNITS |
|---------------------------|---------------------------------|---|---------|--------|------|---------|--------|-------|-------|
|                           |                                 |   | MIN     | TYP    | MAX  | MIN     | TYP    | MAX   |       |
| <b>FREQUENCY RESPONSE</b> |                                 |   |         |        |      |         |        |       |       |
|                           | Voltage Gain                    | (Notes 1 and 2)   |         |        |      |         |        |       |       |
| A <sub>o</sub>            |                                 | f = 1 kHz   | -0.08   | 0.22   | 0.52 | 0.095   | 0.22   | 0.345 | dB    |
| A                         |                                 | f = 3.4 kHz   | -1.2    | -0.6   | 0    | -0.9    | -0.6   | 0     | dB    |
| A                         |                                 | f = 4 kHz   |         | -12    | -10  |         | -12    | -11   | dB    |
| A                         |                                 | f > 4.5 kHz   |         | -25    | -24  |         | -26    | -25   | dB    |
| A                         |                                 | f = 8 kHz   |         | -31    | -30  |         | -31    | -30   | dB    |
| ΔA                        | Pass Band Ripple                | 300 Hz ≤ f ≤ 3 kHz,<br>(Note 2)                                 | -0.3    |        | 0.3  | -0.125  | 0      | 0.125 | dB    |
| Δt                        | Differential Delay              | 1 kHz ≤ f ≤ 2.6 kHz   |         | 80     | 90   |         | 80     | 90    | μs    |
| ΔA <sub>o</sub> /ΔT       | Gain Stability with Temperature | f = 1 kHz, e <sub>IN</sub> = 0.1 Vrms                           |         | 0.0015 |      |         | 0.0015 |       | dB/°C |
| ΔA <sub>o</sub> /Δt       | Gain Stability with Time        | f = 1 kHz, e <sub>IN</sub> = 0.1 Vrms                           |         | 0.0005 |      |         | 0.0005 |       | dB/Yr |
| THD                       | Distortion                      | f = 1 kHz, e <sub>IN</sub> = 0.1 Vrms                           |         | 0.1    | 0.5  |         | 0.1    | 0.5   | %     |
| e <sub>n</sub>            | Output Noise Voltage            | 10 Hz to 50 kHz, e <sub>IN</sub> = 0V,<br>T <sub>A</sub> = 25°C |         | 150    | 250  |         | 150    | 250   | μVp-p |
| e <sub>o</sub>            | Output Voltage Swing            | V <sub>CC</sub> = ±12V, R <sub>L</sub> = 2k                     | 10      | 15     |      | 10      | 15     |       | Vp-p  |
| V <sub>os</sub>           | Output DC Offset                | V <sub>IN</sub> = 0V, T <sub>A</sub> = 25°C                     | -150    |        | 150  | -75     |        | 75    | mV    |
| Z <sub>IN</sub>           | Input Impedance                 | DC to 10 kHz, T <sub>A</sub> = 25°C                             | 100k    |        |      | 100k    |        |       | Ω     |
| Z <sub>o</sub>            | Output Impedance                | DC to 10 kHz, T <sub>A</sub> = 25°C                             |         | 0.5    | 1    |         | 0.5    | 1     | Ω     |
| PSRR                      | Power Supply Rejection          | 120 Hz to 3.4 kHz   |         | 97     |      | 97      |        |       | dB    |
|                           |                                 | 3.4 kHz to 25 kHz   |         | 90     |      | 90      |        |       | dB    |
| P <sub>D</sub>            | Power Dissipation               | V <sub>CC</sub> = ±12V  |         | 135    | 220  |         | 135    | 220   | mW    |
|                           |                                 | V <sub>CC</sub> = ±15V  |         | 190    | 270  |         | 190    | 270   | mW    |

**Note 1:** The voltage gain may be adjusted. Refer to application discussion.

**Note 2:** For the AF134, the pass band ripple specifications do not refer to the AF134 itself. This specification is the deviation from the ideal

band pass response that would result if the  $\left[ \frac{\sin \frac{\pi f}{8000}}{\frac{\pi f}{8000}} \right]$  roll-off characteristic were compensated perfectly, and assumes the inclusion of an ideal sample and hold.

## Applications Information

### GENERAL

The AF133 and AF134 are both fifth order elliptic low pass filters that have been specifically designed for 8 kHz sampled data systems found in telephone PCM communication systems and some military systems, (Figure 1).

The AF133 transmit filter is designed to (a) provide a very flat band pass response from DC to 3.2 kHz, (b) attenuate signals at 4 kHz (1/2 the sampling rate) by at least 16 dB to prevent "aliasing" or "frequency folding" in the sampled data, and (c) attenuate signals above

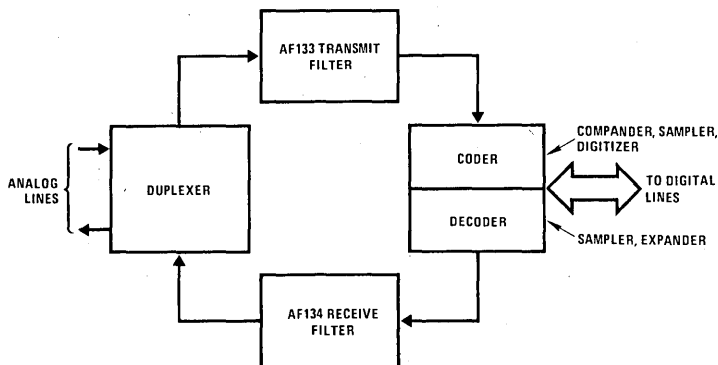


FIGURE 1. PCM Block Diagram

## Applications Information (Continued)

4.5 kHz to prevent these signals from occurring in the sampled data.

The AF134 receive filter is designed to receive the sampled data in order to reconstruct the original analog signal. Because the information has been processed through a sample and hold technique, the amplitude information in the band pass has a characteristic (SIN X)/X response. The purpose of the AF134 filter is to provide the necessary response to compensate for the input signal frequency response and restore the amplitude information to a flat pass band characteristic.

### GAIN ADJUST

The block diagram in *Figure 2* indicates the basic connection of the AF133.

It consists of 2 separate sections which are connected together externally by the user by jumpering pin 5 to pin 8.

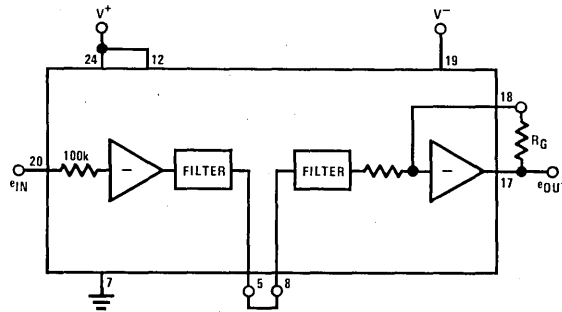
Because it is desirable to have the ability to adjust the voltage gain of the filter, provision has been made to do so by *omitting the gain setting resistor in the feedback path of the output operational amplifier*. For this reason, an external resistor *must* be added between pins 17 and 18 to render the filter operative. The nominal value of the resistor required is 133 k $\Omega$  for a 0 dB voltage gain.

All other pins not shown connected should be left open.

Likewise, provision has been made for the user to adjust the gain of the AF134 receive filter as shown in *Figure 3*.

Although R1 and/or R2 are not required for normal operation, it can be easily seen that the addition of R1 (across the internal 100k resistor) will increase the gain, whereas the addition of R2 (across the internal feedback resistor) will decrease the gain.

Obviously, R1 and R2 can be replaced by a single pot with the wiper arm tied to pin 18.



$R_G = 133 \text{ k}\Omega$  for 0 dB gain (nominal)

FIGURE 2. Functional Diagram of AF133

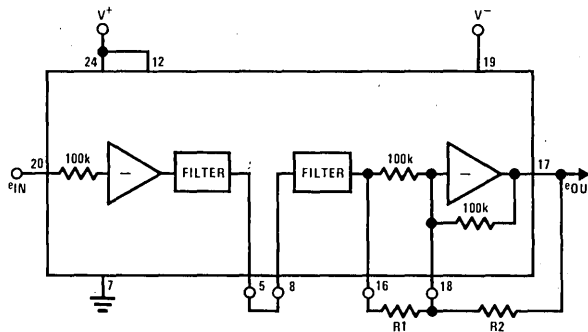


FIGURE 3. AF134 Gain Adjust

### PROVIDING LOW FREQUENCY ROLL-OFF

In some systems, it is necessary to have a low frequency high pass filter in front of the transmit filter to attenuate 60 Hz and 120 Hz. Some attenuation can be achieved by capacitively coupling the input signal, with the proper value of capacitor, C, selected to trade off 60 Hz attenuation with the amount of band pass flatness

near 300 Hz. The capacitor is easily selected since the input impedance (resistive only) is specified. A second, and more desirable solution, is shown in *Figure 4*. This filter makes use of the AF100 as a second order high pass filter. It provides 22 dB of attenuation of 60 Hz, and has less than 0.03 dB effect on the band pass characteristics at 300 Hz.

Applications Information (Continued)

| FREQUENCY | ATTENUATION |
|-----------|-------------|
| 60 Hz     | -22 dB      |
| 120 Hz    | -6 dB       |
| 180 Hz    | -1.5 dB     |
| 300 Hz    | -0.03 dB    |

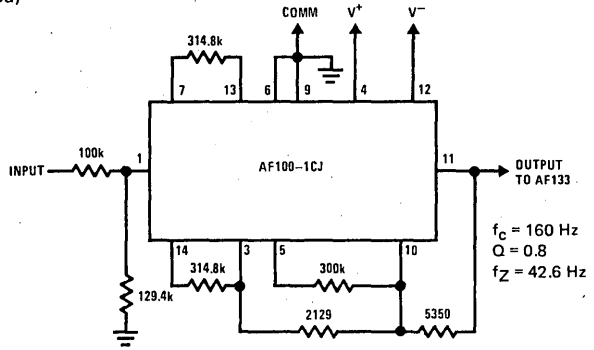


FIGURE 4. Providing 60 Hz Attenuation

TESTING

The circuit shown below is typical of that used by National Semiconductor to test the active filters. In testing and in actual application, the filter must be driven from a low impedance source ( $R_S \leq 50\Omega$ ).

CODEC

National Semiconductor presently manufactures 2 monolithic circuits designed to perform the entire companding coder/decoder function. Before proceeding with your design, please contact National for information about these devices, the MM58100 and the LF2700.

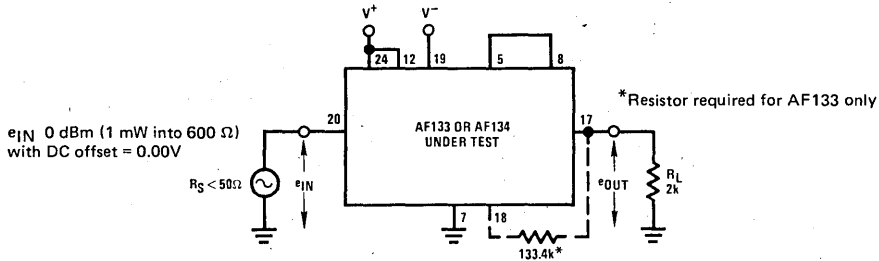


FIGURE 5. Test Circuit

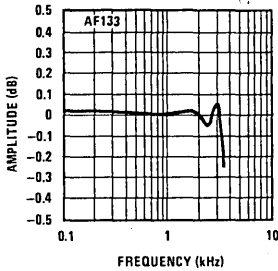


FIGURE 6. AF133 Pass Band Frequency Response

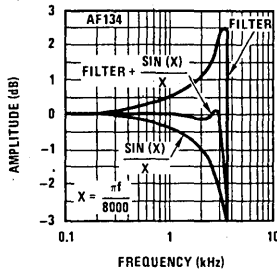


FIGURE 7. AF134 Pass Band Frequency Response

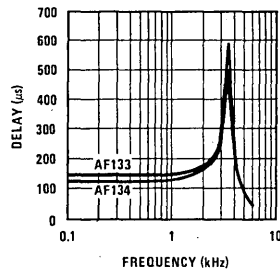


FIGURE 8. Group Delay as a Function of Frequency

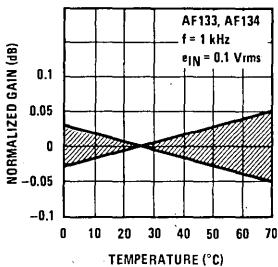


FIGURE 9. Normalized Gain Variation with Temperature

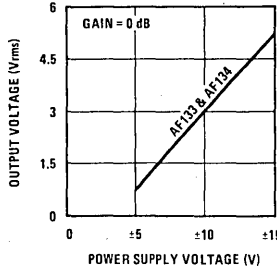


FIGURE 10. Output Voltage Swing vs Power Supply Voltage

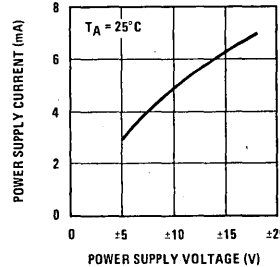


FIGURE 11. Power Supply Current vs Power Supply Voltage