## Board mount pressure sensor with digital output (I<sup>2</sup>C)

#### **FEATURES**

- Calibrated and temperature compensated pressure sensor with digital output (I<sup>2</sup>C)
- Differential, relative (gage), bidirectional differential, absolute and barometric versions
- Digital output for pressure and temperature via I<sup>2</sup>C interface
- · High accuracy at RT
- Small overall error within a temperature range of 0 .. 60 °C
- Supply voltage: 3.3 V and 5 V models available
- High long term stability
- Programmable 7 bit I2C-address
- Compact DIL package
- Horizontal and vertical pressure port configurations available
- Ready to use
- RoHS and REACH compliant
- Substitute product for Honeywell's HSC series

#### GENERAL DESCRIPTION

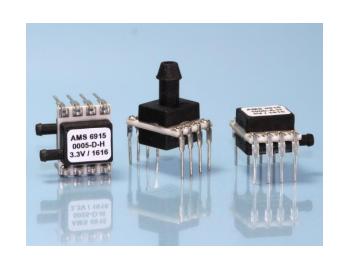
AMS 6915 is a series of high-precision OEM pressure sensors with a digital I<sup>2</sup>C-interface in a compact DIL package for assembly on printed circuit boards (PCBs). The series is especially suitable for low and medium differential pressure measurements in applications, which require a consequent miniaturization.

The sensors in the AMS 6915 series combine a micromachined, high quality piezoresistive measuring cell with a modern, mixed-signal conditioning ASIC on a ceramic substrate. The sensors are calibrated and temperature compensated and have an operating temperature range of -25 .. 85 °C. With their digital I<sup>2</sup>C output and a supply voltage of 3.3 V or 5 V they are ideal for microcontroller applications.

The AMS 6915 series is available for various applications and pressure ranges: differential devices in pressure ranges from 0 .. 5 mbar up to 0 .. 1 bar, relative sensors for 0 .. 25 mbar up to 0 .. 1 bar, an absolute pressure variant for 0 .. 1 bar and a barometric type. Bidirectional differential devices are available in pressure ranges from -2.5 .. +2.5 mbar up to -1 .. +1 bar. Custom specific pressure ranges or further modifications are available on request.

#### TYPICAL APPLICATIONS

- Static and dynamic pressure measurement
- Industrial process control
- Medical instrumentation
- Heating, Ventilation and Air Conditioning (HVAC)
- Barometric pressure measurement
- Vacuum monitoring
- Gas flow measurement





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## Amplified pressure sensor with digital output (I<sup>2</sup>C)

### PRESSURE RANGES AND TYPES

Pressure sensor code	Pressure type	Pressure range in mbar	Burst pressure <sup>1)</sup> in bar	Pressure range in PSI	Burst pressure in PSI
Ultra low pressure					
AMS 6915-0002-D-B	bidirectional differential	-2.5 +2.5	> 0.35	-0.0363 +0.0363	> 5
AMS 6915-0005-D	differential (relative)	0 5	> 0.35	0 0.0725	> 5
AMS 6915-0005-D-B	bidirectional differential	-5 +5	> 0.35	-0.0725 +0.0725	> 5
AMS 6915-0010-D	differential (relative)	0 10	> 0.35	0 0.145	> 5
AMS 6915-0010-D-B	bidirectional differential	-10 +10	> 0.35	-0.145 +0.145	> 5
Low pressure					
AMS 6915-0025-D	differential (relative)	0 25	> 0.5	0 0.363	> 7.5
AMS 6915-0025-D-B	bidirectional differential	-25 +25	> 0.5	-0.363 +0.363	> 7.5
AMS 6915-0050-D	differential (relative)	0 50	> 1	0 0.725	> 15
AMS 6915-0050-D-B	bidirectional differential	-50 +50	> 1	-0.725 +0.725	> 15
AMS 6915-0100-D	differential (relative)	0 100	> 1	0 1.450	> 15
AMS 6915-0100-D-B	bidirectional differential	-100 +100	> 1	-1.450 +1.450	> 15
Standard pressure					
AMS 6915-0200-D	differential (relative)	0 200	> 5	0 2.901	> 72
AMS 6915-0200-G	relative	0 200	> 5	0 2.901	> 72
AMS 6915-0200-D-B	bidirectional differential	-200 +200	> 5	-2.901 +2.901	> 72
AMS 6915-0350-D	differential (relative)	0 350	> 5	0 5.076	> 72
AMS 6915-0350-G	relative	0 350	> 5	0 5.076	> 72
AMS 6915-0350-D-B	bidirectional differential	-350 +350	> 5	-5.076 +5.076	> 72
AMS 6915-1000-D	differential (relative)	0 1000	> 5	0 14.50	> 72
AMS 6915-1000-G	relative	0 1000	> 5	0 14.50	> 72
AMS 6915-1000-D-B	bidirectional differential	-1000 +1000	> 5	-14.50 +14.50	> 72
AMS 6915-1000-A	absolute	0 1000	> 5	0 14.5	> 72
AMS 6915-1200-B	barometric	700 1200	> 5	10.88 17.4	> 72

Table 1: AMS 6915 standard pressure ranges (other ranges on request)

#### **MAXIMUM RATINGS**

Parameter	Minimum	Typical	Maximum	Units
Maximum supply voltage: V <sub>S,max</sub>			6.0	V
Operating temperature: $T_{op}$	-25		85	°C
Storage temperature: T <sub>amb</sub>	-25		85	°C
Common mode pressure $p_{CM}^{\ 2)}$			16	bar

### Table 2: Maximum ratings

#### Notes:

- 1) Burst pressure is defined as the maximum pressure, which may be applied to one pressure port relative to the other port (or while only one pressure port is connected) without causing leaks in the sensor.
- Common mode pressure is defined as the maximum pressure, which can be applied simultaneously on both pressure
  ports of a differential or bidirectional transmitter without causing damages, while no further differential pressure is applied.



# Amplified pressure sensor with digital output (I<sup>2</sup>C)

### **SPECIFICATIONS**

All parameters apply to  $T_{op} = 25$  °C and  $V_S = 3.3$  V (3.3 V models) or  $V_S = 5.0$  V (5 V models), unless otherwise stated.

Parameter	Minimum	Typical	Maximum	Units
Digital output signal (pressure) 1)				
@ specified minimum pressure (see "pressure range") <sup>2)</sup>		1638		counts
@ specified maximum pressure (see "pressure range") <sup>2)</sup>		14745		counts
Full span output (FSO) <sup>3)</sup>		13107		counts
Without pressure (bidirectional differential)		8192		counts
Digital output signal (temperature) <sup>4)</sup>				
@ minimum temperature $T = -25$ °C		256		counts
@ maximum temperature $T = 85  ^{\circ}C$		1382		counts
Accuracy <sup>5)</sup> (pressure measurement) @ $T = 25$ °C				
Ultra low pressure sensors (2.5, 5, 10 mbar)			± 1.5	%FSO
Low pressure sensors (25, 50, 100 mbar)			± 1.0	%FSO
Standard pressure sensors (> 100 mbar)			± 0.5	%FSO
Overall error <sup>6)</sup> (pressure meas.) @ $T = 0 60  ^{\circ}$ C				
Ultra low pressure sensors (2.5, 5, 10 mbar)			± 2.0	%FSO
Low pressure sensors (25, 50, 100 mbar)			± 1.5	%FSO
Standard pressure sensors (> 100 mbar)			± 1.0	%FSO
Error temperature measurement @ T = -25 85 °C				
All types of AMS 6915			± 3.0	%FSO
Long term stability			< 0.5	%FSO/a
Resolution A/D converter		14		bits
Resolution pressure signal		12		bits
Resolution temperature signal			11	bits
Supply voltage range (V <sub>S</sub> ) for 3.3 V model	3.0	3.3	3.6	V
Supply voltage range (V <sub>S</sub> ) for 5 V model	4.75	5.00	5.25	V
Overall ratiometricity error (@ supply voltage range)		± 0.025	± 0.1	%FSO
Current consumption			5	mA
Reaction time (10 % 90 % rise time)		0.5	1	ms
Start up time (Power up to data ready)			10	ms
I <sup>2</sup> C-interface				
Input high level	80		100	% Vs
Input low level	0		20	% Vs
Output low level	0		10	% V <sub>S</sub>
Load capacitance @ SDA			200	pF
Clock frequency SCL		100	400	kHz
Pull-up resistor	500			Ω
Pressure changes	10 <sup>6</sup>			
Compensated temperature range	0		60	°C
Weight		1.5		g
Media compatibility	See "S	Specification not	es" 7) 8)	

Table 3: Specifications



## Amplified pressure sensor with digital output (I<sup>2</sup>C)

#### **SPECIFICATION NOTES**

- 1) The digital pressure output signal is <u>not</u> ratiometric to the supply voltage.
- 2) For pressure ranges see Table 1.
- 3) The Full Span Output (FSO) is the algebraic difference between the output signal at the specified maximum pressure and the output signal at the specified minimum pressure (see "Pressure ranges").
- 4) The digital temperature output signal is <u>not</u> ratiometric to the supply voltage. The digital temperature value is the sensor temperature (including self heating).
- 5) Accuracy is defined as the measurement value's maximum deviation from the ideal characteristic curve at room temperature (RT) in %FSO including the adjustment error (offset and span), nonlinearity, pressure hysteresis and repeatability. Nonlinearity is the measured deviation from the best fit straight line (BFSL) across the entire pressure range. Pressure hysteresis is the maximum deviation of the output value at any pressure within the specified range when the pressure is cycled to and from the minimum or maximum rated pressure. Repeatability is the maximum deviation of the output value at any pressure within the specified range after 10 pressure cycles.
- 6) The overall error is defined as the maximum deviation of the measurement value from the ideal characteristic curve in %FSO across the entire compensated temperature range (0 .. 60 °C).
- 7) Media compatibility of pressure port 1 (for a description of port 1, see *Figure 5*): fluids and gases non-corrosive to LCP, silicon, Pyrex, RTV silicone rubber and epoxy.
- 8) Media compatibility of pressure port 2 (for a description of port 2, see *Figure 5*): clean, dry gases, non-corrosive to LCP, silicon, RTV silicone rubber, epoxy, gold (alkaline or acidic liquids can destroy the sensor).



## Amplified pressure sensor with digital output (I<sup>2</sup>C)

#### FUNCTIONAL DESCRIPTION

The pressure sensors in the AMS 6915 series combine a high quality, piezoresistive silicon sensing element with a modern mixed-signal CMOS ASIC for signal-conditioning on a ceramic substrate. This enables high precision measurements and excellent drift and long-term stability.

The functional principle of the AMS 6915 sensors is explained using Figure 1.

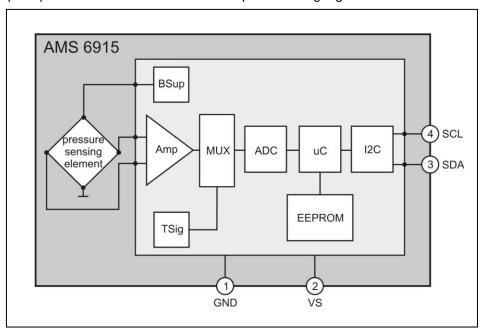


Figure 1: Functional principle

The physical pressure is measured at AMS 6915's piezoresistive pressure sensing element, where the pressure is converted into a differential voltage signal, which is almost proportional to the pressure. This differential voltage signal is corrected and conditioned by the ASIC in multiple steps.

At first the differential voltage signal from the sensing element is pre-amplified by the ASIC's amplifier stage and transmitted to the A/D converter stage (ADC) by the multiplexer stage. The ADC stage converts this voltage signal into digital values with a resolution of 14 bits. The digitized signal is corrected and calibrated in the subsequent ASIC microcontroller block.

During AMS 6915's factory calibration sensor-specific correction coefficients are determined and stored in each sensor's EEPROM. This permits sensor-specific calibration and correction (i.e. temperature compensation and linearization) of the digitized pressure signal. The temperature signal necessary for temperature compensation is generated at the ASIC's temperature reference block and is transmitted by the multiplexer stage to the ADC stage, where it is digitized. The ASIC's microcontroller block runs a cyclic program, which continuously calculates the current standardized and corrected digital pressure value using the current digitized pressure and temperature values as well as the stored correction coefficients. In addition, a standardized current digital temperature value is calculated. These calculated and corrected digital values (14 bit pressure value and 11 bit temperature value) are written to the ASIC's output registers and are continuously updated (typically every 0.5 ms).

The signal readout of the corrected digital pressure and temperature values is done via the I<sup>2</sup>C sensor interface at pin 3 (SDA) and pin 4 (SCL). The digital output values (for pressure and temperature) are not ratiometric to the supply voltage.



## Amplified pressure sensor with digital output (I<sup>2</sup>C)

#### INITIAL OPERATION

AMS 6915 is connected up electrically by mounting them on a PCB<sup>1)</sup>, pins 1 to 4 have to be connected as shown in *Figure 2*.

**Important:** Each  $I^2C$ -bus communication line has to be connected to the positive supply voltage using pull-up resistors (4.7 k $\Omega$  is recommended).

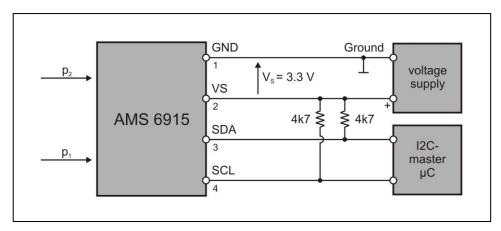


Figure 2: Principle electric circuitry

The pressure connection is established using suitable hoses<sup>2)</sup> attached to AMS 6915's barbed pressure ports. Depending on the type of sensor and measuring pressure one or two of the pressure ports have to be connected up to the measuring media / volumes. For the pressures at port 1 and 2 (for port definition see *Figure 5*) the following requirements have to be fulfilled (according to the definition  $p_1$  = pressure at port 1 and  $p_2$  = pressure at port 2):

for differential pressure types (AMS 6915-XXXX-D-...):  $p_1 > p_2$  for relative / gage pressure types (AMS 6915-XXXX-G-...):  $p_1 > p_2$  or  $p_1 > p_2$  or  $p_1 > p_2$  or  $p_1 < p_2$  possible for absolute pressure types (AMS 6915-XXXX-D-B-...):  $p_2 = p_2$  or  $p_1 < p_2$  possible for absolute pressure types (AMS 6915-XXXX-A-...):  $p_2 = p_2$  measuring pressure types (AMS 6915-XXXX-B-...):  $p_2 = p_2$ 

The guidelines on media compatibility have to be taken into account (see "Specification notes", 7 and 8).

#### Notes:

- 1. ESD precautions are necessary, it is essential to ground machines and personnel properly during assembly and handling of the device
- 2. For horizontal pressure port configuration Analog Microelectronics recommends a silicone hose tubing with inner diameter  $\emptyset = 1.6$  mm, outer diameter  $\emptyset = 3.2$  mm and for vertical pressure port configuration a silicone hose tubing with inner diameter  $\emptyset = 2$  mm, outer diameter  $\emptyset = 6$  mm.



## Amplified pressure sensor with digital output (I<sup>2</sup>C)

### I<sup>2</sup>C-INTERFACE

AMS 6915 pressure sensors have an I<sup>2</sup>C-interface for digital data readout. When connected to a computer or microcontroller via a bidirectional I<sup>2</sup>C-bus, the current digital pressure and temperature measurement values can be read from AMS 6915's output register.

Communication via the I<sup>2</sup>C-bus follows a simple master-slave principle. Data transfer is always initialized by a master (e.g. a microcontroller), which sends a data request to the sensor; the AMS 6915 sensor – which always operates as slave – answers then.

The I<sup>2</sup>C-bus requires only two bus lines: a serial data line (SDA) and a serial clock line (SCL). SDA and SCL are bidirectional lines, which are connected to the positive supply voltage via pull-up resistors.

AMS 6915 communication protocol adheres to a standard I<sup>2</sup>C communication protocol (given in *Figure 3*)<sup>1</sup>.

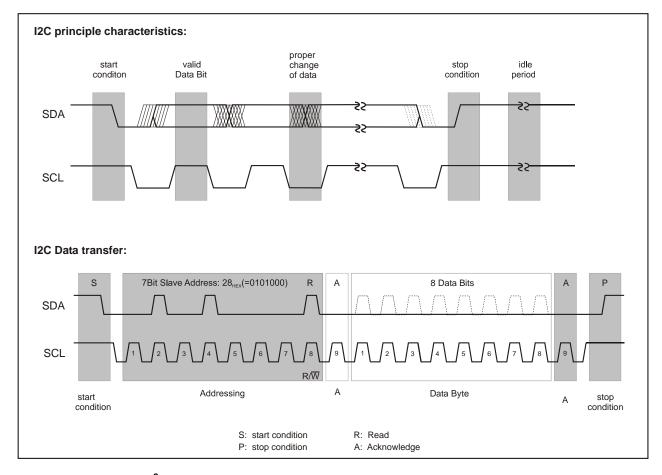


Figure 3: Standard I<sup>2</sup>C protocol

<sup>3.</sup> Between the start condition and the first rising SCL edge no a falling SDA edge is allowed.



<sup>&</sup>lt;sup>1</sup> There are three differences of AMS 6915 communication protocol compared to the original I<sup>2</sup>C communication protocol:

<sup>1.</sup> A stop condition directly after a start condition without clock pulses in between is not allowed. This creates a communication error for the next communication.

<sup>2.</sup> A second start condition (restart) during data transmission, when SCL is still high, is not allowed.

## Amplified pressure sensor with digital output (I<sup>2</sup>C)

The I<sup>2</sup>C communication phases are as follows:

#### **Idle period** (bus is free)

When the bus is free, both I2C-bus lines (SDA and SCL) are pulled up to supply voltage level ("high level").

#### **Start S** (start condition)

Prior to any data transfer on the bus a start condition must be generated. The start condition is always sent by the I<sup>2</sup>C-master. The start condition is defined as a transition from "high level" to "low level" on the SDA line, while the SCL line is still on "high level". The digital data readout from AMS 6915 is always initiated by a start condition.

#### Stop P (stop condition)

The stop condition is always generated by the I<sup>2</sup>C-master after a data transfer has been completed. The stop condition is defined as a transition from "low level" to "high level" on the SDA line while the SCL line is still on "high level". The digital data readout from the AMS 6915 is always terminated by a stop condition.

#### Valid data

Data is transmitted in bytes (8 bits), starting with the most significant bit (MSB). One data bit is transmitted with each clock pulse. After a start condition the transmitted bits are only valid, if the level on the SDA line stays constant as long as the SCL line is on "high level". Changes to the SDA level must be made while the SCL line is on "low level".

#### Acknowledge A

After a byte has been transmitted the respective receiver (master or slave) has to send an acknowledge (additional acknowledge bit) confirming the correct receipt of the data. To this end the master generates an extra acknowledge-related clock pulse. The receiver sends the acknowledge bit by pulling the SDA line down to "low level" during the additional clock pulse.

#### Addressing / Slave address (I2C-address AMS 6915)

After the start condition the master sends an addressing byte (the first byte after the start condition) which determines which slave is selected. The addressing byte contains the individual 7 bit slave address of the selected slave (AMS 6915) and a data direction bit  $(R/\overline{W})$ . An "0" for the  $R/\overline{W}$  bit indicates a transmission from master to slave (W: write; the master wishes to transmit data to the selected slave), a "1" a data request (R: read; the master requests data from the slave).

The pressure sensors in the AMS 6915 series have a standard, factory-programmed 7 bit slave address of  $0x28_{Hex}$  (0101000<sub>bin</sub>).

If more than one AMS 6915 have to be connected to the same I<sup>2</sup>C-bus, each pressure sensor requires an individual slave address. On request each AMS 6915 can be ordered with an individual 7 bit slave address programmed at the factory; 7 bit addressing allows 128 different addresses. Using the AMS 6915's USB starter kit the customer can program the individual slave address himself.



## Amplified pressure sensor with digital output (I<sup>2</sup>C)

### DATA READOUT VIA THE I2C-INTERFACE

The digital output values for pressure (14 bit value) and temperature (11 bit value) are read out from the AMS 6915 output register via AMS 6915 I<sup>2</sup>C-interface. The data readout, which is illustrated in *Figure 4*, is done byte per byte.

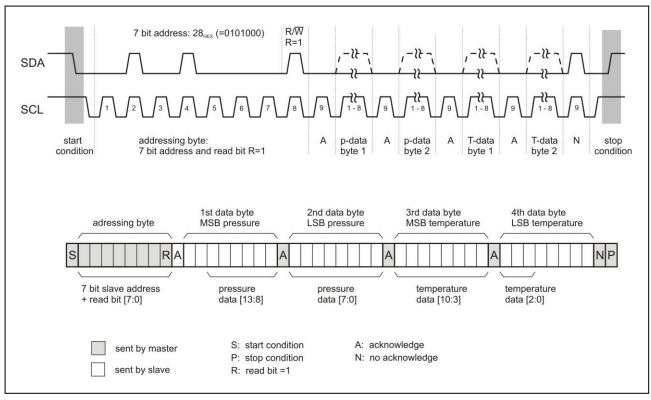


Figure 4: Data readout of the digital pressure and temperature values

Data transfer via the I<sup>2</sup>C-bus is always initialized by a data request from the I<sup>2</sup>C-master. For this purpose the I<sup>2</sup>C-master generates a start condition on the I<sup>2</sup>C-bus lines. Following the start condition the I<sup>2</sup>C-master then sends the addressing byte containing the 7 bit slave address of the AMS 6915 (programmed to  $0x28_{Hex} = 0101000_{bin}$  at the factory) and the data direction bit R = 1 (indicating a data request) leading to the addressing byte  $01010001_{bin}$ . The selected pressure sensor first answers with an acknowledge bit and starts the data transfer from the output register.

For pressure and temperature value readout a total of four data bytes are transmitted from the pressure sensor to the I<sup>2</sup>C-master. The two bytes for the current digital pressure value are sent first, followed by the two bytes for the current digital temperature value, always beginning with the most significant byte. On each transferred data byte the I<sup>2</sup>C-master sends an acknowledge bit confirming the correct receipt of data. After the fourth data byte the receiving master has to generate a no acknowledge bit, leading to the pressure sensor being set to inactive. The I<sup>2</sup>C-master shuts down the data transfer by sending a stop condition.

The 14 bit pressure value is given by the last 6 bits of the first data byte and the 8 bits of the second data byte always beginning with the most significant bit. The 11 bit temperature value is given by the 8 bits of the third data byte and the first 3 bits of the fourth data byte.

For pressure value readout only it is possible to stop the data transfer after two data bytes. In this case the I<sup>2</sup>C-master sends a no acknowledge bit after the second data byte and shuts down the data transfer by sending a stop condition.



## Amplified pressure sensor with digital output (I<sup>2</sup>C)

#### Calculating the current pressure and temperature value

To obtain the desired information on pressure and temperature in physical units the digital output values for pressure and temperature have to be converted.

The current pressure in bar (or PSI) can be calculated from the 14 bit digital pressure value using the following equation:

$$p = \frac{p_{Digout}(p) - p_{min,Digout}}{Sens_p} + p_{min} \quad \text{with} \quad Sens_p = \frac{p_{max,Digout} - p_{min,Digout}}{p_{max} - p_{min}}$$
 (1)

with

p = current pressure in bar (or PSI, kPa)

 $p_{Digout}(p)$  = current digital 14 bit pressure value in counts

 $p_{min.Digout}$  = digital pressure value at minimum specified pressure (typ. 1638 counts)

 $p_{max,Digout}$  = digital pressure value at maximum specified pressure (typ. 14745 counts)

Sens<sub>p</sub> = the pressure sensor's sensitivity in counts/bar (or counts/PSI, counts/kPa)

 $p_{min}$  = the pressure sensor's specified minimum pressure in bar (or PSI, kPa)

 $p_{max}$  = the pressure sensor's specified maximum pressure in bar (or PSI, kPa).

The current sensor temperature T in °C is calculated from the 11 bit digital temperature value  $T_{Digout}(T)$  using the following equation:

$$T = \frac{T_{Digout}(T) \cdot 200}{2048} - 50 \quad \text{in °C}$$
 (2)

#### **Example**

At the digital output of an AMS 6915-0005-D-B (bidirectional differential sensor, range: -5 .. 5 mbar) the following data bytes 1 .. 4 are read:

Byte 1: 00101100

Byte 2: 11001101

Byte 3: 01011100

Byte 4: 11100000

Taking the last 14 bits of byte 1 and byte 2 the current 14 bit digital pressure value is:

$$p_{Digout}(p) = (10110011001101)_{bin}$$
 counts =  $(2CCD)_{Hex}$  counts =  $11469$  counts

and with the first 11 bits of byte 3 and byte 4 the digital temperature value is:

$$T_{Diaout}(T) = (01011100111)_{bin} \text{ counts} = (2E7)_{Hex} \text{ counts} = 743 \text{ counts}$$
.

With  $p_{min} = -5$  mbar,  $p_{max} = 5$  mbar and  $p_{min,Digout} = 1638$  counts,  $p_{max,Digout} = 14745$  counts specified for AMS 6915-0005-D-B the current pressure in mbar is calculated using equation (1) as:

$$p = \frac{(11469-1638) counts}{(13107/10) counts/mbar} + (-5 mbar) = 2.5 mbar$$

Using equation (2), the current sensor temperature in °C is calculated to:

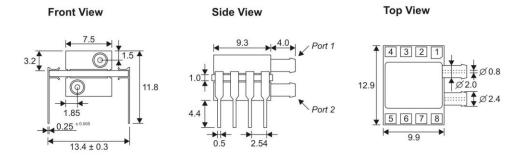
$$T = \frac{(743 \cdot 200) \text{ counts} \cdot {}^{\circ}\text{C}}{2048 \text{ counts}} - 50 \, {}^{\circ}\text{C} = 22.6 \, {}^{\circ}\text{C}$$



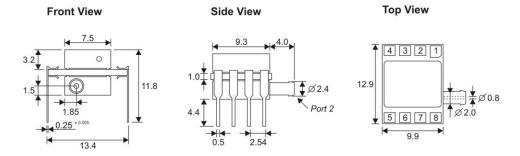
## Amplified pressure sensor with digital output (I<sup>2</sup>C)

### **DIMENSIONS AND PINOUT**

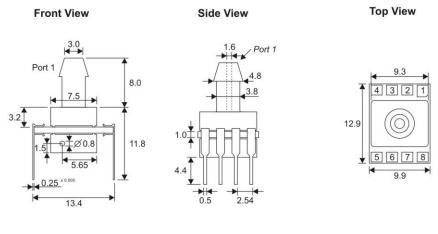
AMS 6915-xxxx-D-H-x-DIL & AMS 6915-xxxx-D-B-H-x-DIL (horizontal pressure port configuration):



AMS 6915-xxxx-A-H-x-DIL & AMS 6915-1200-B-H-x-DIL (horizontal pressure port configuration):



AMS 6915-xxxx-G-V-x-DIL (vertical pressure port configuration):



Pinout:

Pin	Description
1	GND
2	VS
3	SDA
4	SCL
5 - 8	N.C.

All dimensions in mm, tolerances: ±0.1 mm unless otherwise noted

Figure 5: AMS 6915 dimensions and pinout



# Amplified pressure sensor with digital output (I<sup>2</sup>C)

### **ORDERING CODES**

### Horizontal pressure port configuration (DIL package)

With x = 3 for 3.3 V supply voltage models and x = 5 for 5 V supply voltage models.

Ordering Code	mbar	kPa	PSI		
Differential pressure types (-D)					
AMS 6915-0005-D-H-x-DIL	0 5	0 0.5	0 0.0725		
AMS 6915-0010-D-H-x-DIL	0 10	0 1	0 0.145		
AMS 6915-0025-D-H-x-DIL	0 25	0 2.5	0 0.363		
AMS 6915-0050-D-H-x-DIL	0 50	0 5	0 0.725		
AMS 6915-0100-D-H-x-DIL	0 100	0 10	0 1.450		
AMS 6915-0200-D-H-x-DIL	0 200	0 20	0 2.901		
AMS 6915-0350-D-H-x-DIL	0 350	0 35	0 5.076		
AMS 6915-1000-D-H-x-DIL	0 1000	0 100	0 14.50		
Bidirectional differential pressure types (-D-B)					
AMS 6915-0002-D-B-H-x-DIL	-2.5 +2.5	-0.25 +0.25	-0.0363 +0.0363		
AMS 6915-0005-D-B-H-x-DIL	-5 <b>+</b> 5	-0.5 +0.5	-0.0725 +0.0725		
AMS 6915-0010-D-B-H-x-DIL	-10 +10	-1 +1	-0.145 +0.145		
AMS 6915-0025-D-B-H-x-DIL	-25 +25	-2.5 +2.5	-0.363 +0.363		
AMS 6915-0050-D-B-H-x-DIL	-50 +50	-5 <b>+</b> 5	-0.725 +0.725		
AMS 6915-0100-D-B-H-x-DIL	-100 +100	-10 +10	-1.450 +1.450		
AMS 6915-0200-D-B-H-x-DIL	-200 +200	-20 +20	-2.901 +2.901		
AMS 6915-0350-D-B-H-x-DIL	-350 +350	-35 +35	-5.076 +5.076		
AMS 6915-1000-D-B-H-x-DIL	-1000 +1000	-100 +100	-14.50 +14.50		
Absolute pressure types (-A)					
AMS 6915-1000-A-H-x-DIL	0 1000	0 100	0 14.5		
Barometric (absolute) pressure types (-B)					
AMS 6915-1200-B-H-x-DIL	700 1200	70 120	10.88 17.4		

### **Vertical pressure port configuration (DIL package)**

With x = 3 for 3.3 V supply voltage models and x = 5 for 5 V supply voltage models.

Ordering Code	mbar	kPa	PSI		
Relative (Gage) pressure types (-G)					
AMS 6915-0200-G-V-x-DIL	0 200	0 20	0 2.901		
AMS 6915-0350-G-V-x-DIL	0 350	0 35	0 5.076		
AMS 6915-1000-G-V-x-DIL	0 1000	0 100	0 14.50		



# Amplified pressure sensor with digital output (I<sup>2</sup>C)

### **ADDITIONAL EQUIPMENT**

A USB starter kit with software is available for AMS 6915 sensors. This kit permits easy readout of the digital pressure and temperature values using a standard Windows PC. Furthermore, the starter kit can be used to set a permanent individual I<sup>2</sup>C slave address for a particular AMS 6915 sensor, allowing the readout of multiple sensors via the same I<sup>2</sup>C-bus.

Ordering code	Description
USB starter kit AMS 6915	AMS 6915 - starter kit (2 PCBs with software)

#### **NOTES**

Analog Microelectronics GmbH reserves the right to amend any dimensions, technical data or other information contained herein without prior notification.

