

AP4203 15ch 100mA LED Driver IC

1. General Description

The AP4203 is a 15 channel LED Driver that supports 2 types of serial interfaces (SCI serial interface or serial F/F cascade interface) to program LED lighting. The built-in 100mA drivable power MOSFET is used to shut off the LED current, and LEDs are controlled by a PWM method in accordance with the LED gradation data that is programmed into the device. Constant current output and Open drain output are selectable by DRSET setting pin. To reduce wirings in the system, voltage on anode side of LEDs can be communized. A maximum of 32 devices can be connected on a single BUS to a common master device; furthermore, each AP4203 retains its own programmed commands allowing continuous autonomous lighting. The internal UVLO function prevents the LEDs from incorrect operations when the supply voltage is 4V or less. An internal over current protection function and a thermal protection function are also integrated.

2. Features

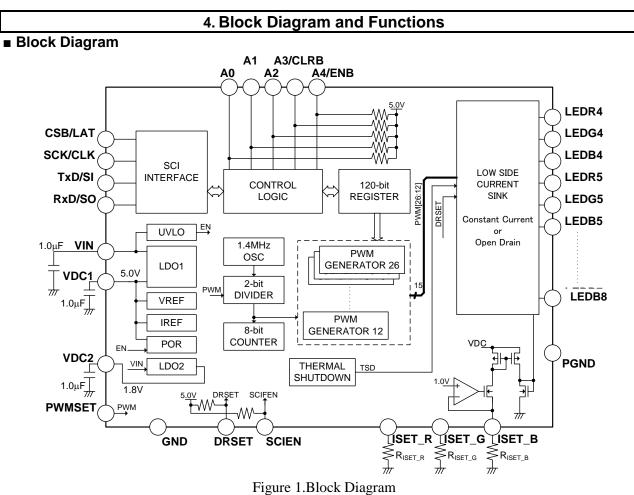
- Power Supply Voltage 8.0V~24.0V
 - 4.5V~5.5V (connect VIN pin and VDC1 pin)
 - Oprating Temperature $0 \sim 70^{\circ}$ C
- Absolute Maximum Voltage 30V (VIN, LEDR4~8, LEDG4~8, LEDB4~8)
- 2 Types of Serial Interface for Setting Lighting Data
 - 4-wire SCI interface (maximum communication clock: 5MHz)
 - Serial-F/F cascade (maximum communication clock: 10MHz)
 - Applicable to both 3.3V and 5.0V input signal (output is fixed to 5.0V)
- LED Current maximum 100mA/ch
- Constant Current Output 50mA/ch
- Open Drain Output 100mA/ch

(Each channel current is less than the value when 15 channels are set simultaneously)

- LED Gradation 8-bit PWM gradation method (256 gradation)
- Built-in PWM Generator, Adjustable PWM Period
- Simultaneous lighting-off function (SCI interface)
- Protection Function
 - Under voltage lock our (UVLO)
 - Over current protection (timer latch recovery type)
 - Thermal shutdown (automatic recovery)
- Package 48-pin LQFP
- Application A LED loading machine for the decoration

3. Table of Contents

1. General Description	1
2. Features	1
3. Table of Contents	2
4. Block Diagram and Functions	3
Block Diagram	
Function	3
5. Ordering Guide	4
6. Pin Configurations and Functions	4
Pin Layout	4
Function	5
7. Absolute Maximum Rating	9
8. Recommended Operating Conditions	9
9. Electrical Characteristics	
■ SCI Interface (AC timing)	11
■ Serial F/F Control (AC timing)	12
10. Functional Descriptions	13
10.1. Operation Outline	13
10.2. SCI Interface Command	13
10.3. Serial F/F Cascade Control	20
10.4. LED Current Setting (fixed current output)	21
10.5. Input Voltage Range (VIN)	
10.6. POR Operation (Power on Reset)	22
10.7. Reset State	23
10.8. Protection Functions	24
11. Recommended External Circuits	25
12. Package	26
■ Package (48 pin LQFP)	26
■ Marking	26
13. Revision History	27
IMPORTANT NOTICE	28



∎ Ft	unction	
No	Block	Function
1	SCI INTERFACE	In case of SCI: hold the setting data of the PWM gradation. In case of serial F/F: hold the PWM gradation data.
2	CONTROL LOGIC	Detect SCI instruction, control the operation mode.
3	"120-bit" REGISTER	Hold the 8-bit PWM gradation data of LEDR4~8, LEDG4~8 and LEDB4~8.
4	PWM	Compare PWM gradation with counter and generate PWM wave.
5	1.4MHz OSC	Generate 1.4MHz clock.
6	"2-bit" DIVIDER	Divide 1.4MHz clcok to 256 gradation clock.
7	"8-bit" COUNTER	Count with the 256 gradation clock within PWM period.
8	UVLO	Generate reset signal for preventing unstable operating when input power voltage
9	LDO1	Generate an internal 5 voltage. It can supply less than 30mA for driving external
10	LDO2	Generate an internal 1.8 voltage. Driving external circuit is forbidden.
11	VREF	Generate a reference voltage.
12	IREF	Generate a reference current.
13	POR	Generate reset signal at power start up.
14	LOW SIDE CURRENT SINK	LED output driver which can set to current source or open drain output. Over current protection circuit is built in.
15	THERMAL SHUTDOWN	Shut down the LED current and set the VDC1,VDC2 pins to 0 voltage when internal temperature is more than setting value.

5. Ordering Guide

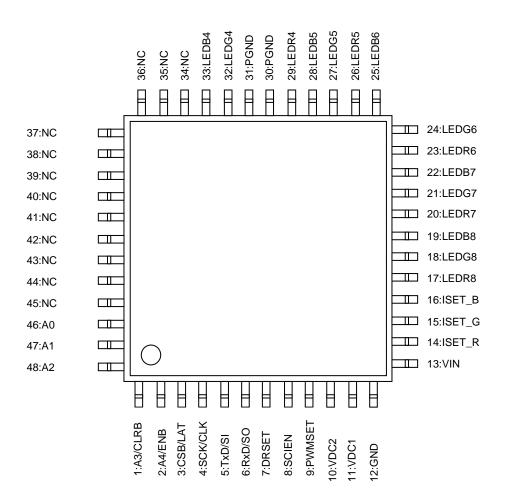
0°C**~**70°C

6. Pin Configurations and Functions

48-pin LQFP

Pin Layout

AP4203



Function

	Nomo	Equivalant airavit	Exploration
No.	Name	Equivalent circuit VDC1 VDC1	Explanation
1	A3/CLRB		IC address input pin 3 (built in 100kohm pull-up resistor). Configure by connecting to GND or open. CLRB input pin used for serial F/F. Data clear pin used for shift register.
2	A4/ENB		IC address input pin 4 (built in 100kohm pull-up resistor). Configure by connecting to GND or open. ENB input pin used for serial F/F. Control the shift resister data which reflect to PWM data or not.
3	CSB/LAT		Strobe signal input pin for SCI. Respective orders are accepted when the CSB terminal goes "L" level. The CSB terminal always needs to be "L" level while commands are entered or data are transferred. If the CSB pin goes "H" level when data are transferred, the commands are disregarded. LAT signal input pin used for serial F/F. Input LAT signal for shift register.
4	SCK/CLK		Clock signal input for SCI. Writing data is entered from the TxD pin at the SCK rising edge, reading data is output to RxD pin at the SCK falling edge. It is not always necessary to supply a clock signal to the SCK pin. CLK signal input pin used for serial F/F. CLK signal for shift register.
5	TxD/SI		Data signal input pin. To input commands, writing data. SI input pin for serial F/F. To input data signal of shift register. Input to F/F which determine LEDB0 lighting data.
6	RxD/SO		Data signal output pin for SCI. To output reading data. Outputs Hi-Z except when data is output. SO output pin for serial F/F. To output data signal of shift register. Output from F/F which determine LEDR8 lighting data.
7	DRSET		Switching pin which can switch to driver output current source or open drain (100kohm pull up) Connect to GND or set to open. If connect to GND, it can work as open drain mode.

No.	Name	Equivalent circuit	Explanation
8	SCIEN		Enable pin for serial interface. (100kohm pull up) Connect to GND or set to open. If connect to GND, it can work as serial F/F control mode. If open this pin, it can work as SCI control mode.
9	PWMSET		PWM period setting pin. (100kohm pull down) Connect to VDC1 pin or set to open. If connect to GND (or open), PWM gradation period= low speed 546µs(typ.) If connect to VDC1 pin, PWM gradation period= high speed 364µs(typ.)
10	VDC2	VIN VIN Internal circuit	Internal 1.8V LDO output pin. Drive external circuit is prohibited. Connect a 1.0µF capacitor between the VDC2 pin and GND.
11	VDC1	VIN VIN Internal circuit	Internal 5V LDO output pin. External current capability is 30mA maximum. Connect a 1.0µF capacitor between the VDC terminal and GND.
12	GND	-	Ground
13	VIN		IC power input pin. Internal 5V LDO's output and 1.8V output. Connect a 1.0µF capacitor between the VDC terminal and GND.
14	ISET_R		Current setting pin for LEDR4~8. Connect an external resistor between this pin and GND.
15	ISET_G	Same as 14-pin	The pin which set the current of LEDG4~8. (same as 14 pin)
16	ISET_B	Same as 14-pin	The pin which set the current of LEDB4~8. (same as 14 pin)
17	LEDR8		R8 pin (connect to LED cathode).Current source/open drain output. Control the internal MONFET to drive LED with lighting setting.

10		Some as 17 min	G8 pin (connect to LED cathode).Current source/open drain
18	LEDG8	Same as 17-pin	output. Control the internal MONFET to drive LED with lighting setting.
			B8 pin (connect to LED cathode).Current source/open drain
19 LEDB8	Same as 17-pin	output.	
17	LLDDO	Same as 17-pm	Control the internal MONFET to drive LED with lighting setting.
			R7 pin (connect to LED cathode).Current source/open drain
20	LEDR7	Same as 17-pin	output.
		1	Control the internal MONFET to drive LED with lighting setting.
			G7 pin (connect to LED cathode).Current source/open drain
21	LEDG7	Same as 17-pin	output.
			Control the internal MONFET to drive LED with lighting setting.
			B7 pin (connect to LED cathode).Current source/open drain
22	LEDB7	Same as 17-pin	output.
			Control the internal MONFET to drive LED with lighting setting.
22		0 17 .	R6 pin (connect to LED cathode).Current source/open drain
23	LEDR6	Same as 17-pin	output.
			Control the internal MONFET to drive LED with lighting setting. G6 pin (connect to LED cathode).Current source/open drain
24	LEDG6	Same as 17-pin	output.
24	LEDGO	Same as 17-pm	Control the internal MONFET to drive LED with lighting setting.
			B6 pin which connect to LED cathode.
25	LEDB6	Same as 17-pin	Current source/open drain output.
			Control the internal MONFET to drive LED with lighting setting.
			R5 pin (connect to LED cathode).Current source/open drain
26	LEDR5	Same as 17-pin	output.
		-	Control the internal MONFET to drive LED with lighting setting.
			G5 pin (connect to LED cathode).Current source/open drain
27	LEDG5	Same as 17-pin	output.
			Control the internal MONFET to drive LED with lighting setting.
20			B5 pin (connect to LED cathode).Current source/open drain
28	LEDB5	Same as 17-pin	output.
			Control the internal MON-FET to drive LED with lighting setting. R4 pin (connect to LED cathode).Current source/open drain
29	LEDR4	Same as 17-pin	output.
2)	LEDR4	Same as 17-pm	Control the internal MONFET to drive LED lighting setting.
30	PGND		Ground pin for LED current.
31	PGND	-	Ground pin for LED current.
51	TOND		G4 pin (connect to LED cathode).Current source/open drain
32	LEDG4	Same as 17-pin	output.
	_	I	Control the internal MONFET to drive LED lighting setting.
22			B4 pin (connect to LED cathode).Current source/open drain
33	LEDB4	Same as 17-pin	output.
			Control the internal MONFET to drive LED with lighting setting.
34	NC	-	NC pin
35	NC	-	NC pin
36	NC	-	NC pin
37	NC	-	NC pin
38	NC	-	NC pin
39	NC	-	NC pin
40	NC	-	NC pin
41	NC	-	NC pin
42	NC	-	NC pin
43	NC NC		NC pin
43	NC NC		NC pin
++	ne	-	no pii

45	NC	NC pin
46	A0	IC address input pin 0 (Built in $100k\Omega$ pull up resistor) Configure by connecting to GND or OPEN.
47	A1	IC address input pin 1 (Built in $100k\Omega$ pull up resistor) Configure by connecting to GND or OPEN.
48	A2	IC address input pin 2 (Built in $100k\Omega$ pull up resistor) Configure by connecting to GND or OPEN.

Note 1. Handling of unused pins. (complementary): Set all unused pins open when the either interface for LED gradation data is selected. There is no need to connect unused pin to GND. Since No. 3~5 pins are always used, the circuit for unused status is not built-in to these pins. It is necessary to control these pins to not become Hi-Z state while the power is supplied.

Note 2. The PGND pin and the GND pin are not connected internally. Therefore these pins must be connected externally.

Note 3. $\dashv \Box$ symbol means high voltage tolerance MOS, the pin with this MOS can tolerate high voltage.

7. Absolute Maximum Rating

Parameter	Symbol	min	max	Unit
VIN voltage	V _{IN}	-0.3	30	V
LEDR4-8, LEDG4-8, LED B4-8 voltage	V _{LED}	-0.3	30	V
CSB/LAT, SCK/CLK, TxD/SI, A0-2, A3/CLRB, A4/ENB, RxD/SO, DRSET Voltage (Note 7)	-	-0.3	$V_{DC1} + 0.3$	V
VDC2 Voltage	-	-0.3	1.98	V
PWMSET, VDC1, ISET_R, ISET_G, ISET_B voltage	-	-0.3	5.5	V
Power Dissipation (Note 5, Note 6)	P _D		1400	mW
Storage Temperature	T _{STG}	-40	150	°C

Note 4. All voltages are with respect to GND pin (GND, PGND) as zero (reference) voltage.

Note 5. P_D is decreased at the rate of 14mW/°C when Ta \geq 25°C. (Mounted on 100 mm × 103 mm t=1.0mm double side FR-4 board.)

Note 6. When calculating thermal design, please include the heat generated by the internal regulator along with the LED pins.

• The case of fixed current output:

IC power consumption

= LED pins power consumption (LED current*LED pin voltage) * LED numbers

+Internal LDO power consumption [(VIN-VDC1) * (VDC1 output current+IC consumption (8.5mA))] +VDC1*IC consumption (8.5mA)

• The case of open drain output:

IC power consumption

= LED pins power consumption (LED current*LED current*LED ON-resistor 9.30hm)*LED numbers

+Internal LDO power consumption [(VIN-VDC1) * (VDC1 output current+IC consumption(2mA))] +VDC1*IC consumption (2mA)

Note 7. The maximum value is limited to 5.5V when the VDC1 exceeds 5.2V.

WARING: Operation at or beyond these limits may result in permanent damage to the device. Normal operation is not guaranteed at these extremes.

8. Recommended Operating Conditions						
Parameter	Symbol	min	typ	max	Unit	Conditions
Input Voltage 1	V _{IN1}	8.0	12.0	24.0	V	Not connect VIN pin and VDC1 pin
Input Voltage 2 (Note 8)	V _{IN2}	4.5	5.0	5.5	V	Connect VIN pin and VDC1 pin
Maximum LDO1 output current	I _{DC}	-	-	30	mA	VIN=12V
Maximum LED pin voltage	V _{LEDOFF}	-	-	24.0	V	LED pin= off setting
Operation Temperature	Та	0	-	70	°C	

Note 8. Input range (VIN pin voltage) = $5.5V \sim 8.0V$ is prohibited.

WARNING: AKM assumes no responsibility for the usage beyond the conditions in this data sheet.

9. Electrical Characteristics

(VIN=12V, GND=PGND=0V, Ta=+25 °C, Capacitor at VIN, VDC1 and VDC2 pins = 1.0μ F.

DRSET=High (fixed current), RISET_R=RISET_G=RISET_B= $33.3k\Omega$; Recommend Parts, unless otherwise specified)

Parameter	Symbol	min	typ	max	Unit	Conditions
	I _{DD1}	-	1.2	2.0		DRSET="L" (open drain) PWM duty= 0%
	I _{DD2}	-	1.3	2.0		DRSET="L" (open drain) PWM duty=50%
Power Consumption	I _{DD3}	-	5.0	8.5	mA	DRSET="H" (fixed current) PWM duty= 0%
	I _{DD4}	-	5.0	8.5		DRSET="L" (fixed current) PWM duty= 50%
VIN Reset Voltage	VIN _{RST}	-	4.0	4.2	V	Activated by decreasing VIN from normal state.
VIN Hysteresis Width	VIN _{HYS}	-	0.2	-	V	Hysteresis between VINrst and VIN set voltage (VINset) (VINset>VINrst)
LDO1 Output Voltage	V _{DC1}	4.75	5.0	5.25	V	V _{IN} =12V, I _{DC1} =-30mA (Note 9)
LDO2 Output Voltage	V _{DC2}	-	1.8	-	V	V_{IN} =12V, I_{DC2} =-0mA
LED Current Capability	I _{LEDO}	-	-	100	mA	DRSET="L" (open drain)
per Channel	I _{LEDC}	-	-	50	mA	DRSET= "H" (fixed current)
LED current switching MOS-FET ON resistance	R _{LED}	-	6	9.3	Ω	DRSET="L" (open drain) LED current= +100mA
LED pin Voltage	D	1.8	-	(Note 10)	V	DRSET="H" (fixed current) LED current= $+50$ mA R _{ISET} = 20 k Ω
(for all 15 channels)	R _{LED}	0.8	-	(Note 10)	V	DRSET="H" (fixed current) LED current= $+15$ mA R _{ISET} = 66.7 k Ω
LED Current Accuracy 1	I _{LEDC1}	28.05	30.0	31.95	mA	DRSET="H" (fixed current)
LED Current Accuracy 2	I _{LEDC2}	13.95	15.0	16.05	mA	DRSET="H" (fixed current) R_{ISET} = 66.7k Ω
LED Current Mismatch	ΔI_{LED}	-4	-	4	%	DRSET="H" (fixed current) (Note 11)
LED pin off-lead Current	I _{LEAK_LED}		-	1.0	μA	LED pin voltage= 24V
PWM Period Accuracy	T _{PWM}	-10	-	+10	%	All setting value
PWM Setting Range	D _{PWM}	0	-	100	%	All setting value
		-	±1	-	LSB	PWMSET="L"
PWM Setting Error		-	±1	-	LSB	PWMSET="H"
Input High-level Voltage	V _{IH}	2.5	-	5.5	V	
Input Low-level Voltage	V _{IL}	-0.2	-	0.5	V	
Output High-level Voltage	V _{OH}	3.7	-	5.3	V	I ₀ =-500μA
Output Low-level Voltage	V _{OL}	0	-	0.8	V	I ₀ =+500μA
Input Leak Current	I _{LI}	-1.0	-	1.0	μA	CSB, SCK, TxD pins
Output Leak Current	I _{LO}	-1.0	-	1.0	μA	

Note 9. I_{DC1}=-30mA means that internal 5V LDO1 (VDC1 pin) can drive external circuit less than 30mA. Note 10. V_{LED} identifies the voltage range. There is a range that cannot be set even less than absolute maximum voltage (30V) because of the maximum power dissipation. Please refer to "10.8 Protection Functions".

Note 11. $\triangle I_{\text{LED}}(\%) = \frac{I_{\text{LEDxxMAX}} - I_{\text{LEDxxMIN}}}{I_{\text{LEDxxMAX}} + I_{\text{LEDxxMIN}}} \times 100$

■ SCI Interface (AC timing)

Table 1. SCI Timing						
Parameter	Symbol	min	typ	max	Unit	Condition
SCK Period	t _{SCKP}	200	-	-	ns	
SCK Pulse Width	t _{SCKW}	60	-	-	ns	
CSB Set-up Time	t _{CSS}	50	-	-	ns	
CSB Hold Time	t _{CSH}	70	-	-	ns	
Data Set-up Time	t _{DIS}	50	-	-	ns	
Data Hold Time	t _{DIH}	70	-	-	ns	
ByD nin Output Dalay Time	+	-	-	80	ns	C _L =100pF
RxD pin Output Delay Time	t _{PD}	-	-	50	ns	C _L =20pF
CSB High-level Minimum Time	t _{CS}	2	-	-	μs	
RxD pin High-impedance Output Delay Time	t _{OZ}	-	-	250	ns	C _L =100pF
SCK, CSB, TxD Raising Time	t _{CSR}	-	-	$t_{SCKW} \times 15\%$	ns	t _{SCKW} <4000ns
		-	-	600	ns	t _{SCKW} ≥4000ns
SCK, CSB, TxD Falling Time	t _{CSF}	-	-	$t_{SCKW} \times 15\%$	ns	t _{SCKW} <4000ns
		-	-	600	ns	t _{SCKW} ≥4000ns

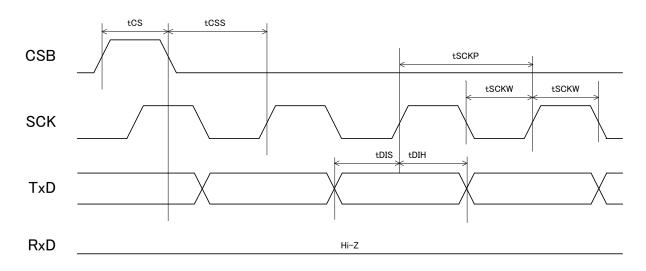


Figure 2. SCI Interface Timing Chart 1

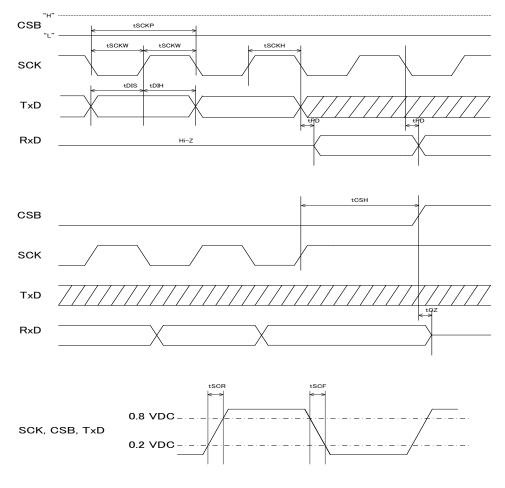


Figure 3. SCI Interface Timing Chart 2

■ Serial F/F Control (AC timing)

Table 2. SCI Serial F/F Control Timing

Parameter	Symbol	min	typ	max	Units	Condition
CLK Period	t _{CLP}	100	-	-	ns	
CLK Pulse Width	t _{CLW}	40	-	-	ns	
Data Set-up Time	t _{DIS}	25	-	-	ns	
Data Hold Time	t _{DIH}	40	-	-	ns	
LAT Pulse Width	t _{LAW}	2	-	-	μs	

The AC timings of CLK (SCK), LAT (CSB), SI (TxD) and SO (RxD) are the same as the SCI interface except data set-up time and data hold time. But the SO (RxD) pin output delay time is the value when $C_L=20$ pF.

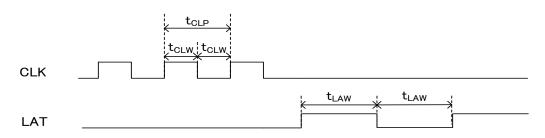


Figure 4. Serial F/F timing

10. Functional Descriptions

10.1. Operation Outline

The AP4203 controls external LED lights using the data that can be configured by two types of interfaces (4-wire SCI control, serial F/F control). Fixed current output or open drain can be selected by the DRSET pin setting. LED lighting is performed by switching the LED current using internal MOSFET controlled by the PWM method. In this case, LED current will be set by an external resistor which is connected to each LED pin when open drain is selected. When fixed current is selected, LED current will be set by an external resistor which is connected to each RGB line, and the all LED pins in the same color are set with the same value. For gradation data setting, the AP4203 writes 8-bit PWM control data into IC registers when SCI control is selected. Two type frequencies can be selected with PWM setting pin, it is effective to optimize the refresh period. The AP4203 has an IC address configured by OPEN/SHORT setting of the A0 to A4 pins, and the LED pin addresses that are determined through the SCI interface. By using this IC address configuration, diversification of the LED lighting across multiple AP4203s in a single BUS can be achieved. By using the OENB pin, all LEDs can be simultaneously turned off regardless of the signal from the SCI interface. However, this is not the lowest power consumption state because the LED gradation data is still being held even while all LEDs are turned off.

ruble 5. Description ruble for Setting rins	Table 3.	Description	Table for	Setting Pins
---	----------	-------------	-----------	--------------

DRSET pin	DRSET setting result	SCIEN pin	SCIEN setting result
Connect to GND ("L")	Open drain output	Connect to GND ("L")	Serial F/F control
OPEN ("H")	Fixed current output	OPEN ("H")	SCI control

PWMSET pin	Dimming PWM frequency[Hz] (same as period[µs]) (typ.)
Connect to GND ("L")	1830Hz (546µs)
Connect to VDC1 ("H")	2745Hz (364µs)

10.2. SCI Interface Command

Table 4. Command Description (Hereinafter initial "16-bit" data transmission is called command part)

Instruction Content	Function	Description
Instruction	Designate instruction contents by initial "4-bit"	-
"A4~A0"	Assign the IC address	Instructions for a different configured address (set by these pins) are ignored. ("H" display)
"RW"	"1"= Write "0"= Read	-
"ALL"	"1"= All LED pins (all RGB sets) "0"= Base on ch3~ch0 setting	Give the priority to the setting of "ch3~ch0"
"RST"	"1"= LED gradation PWM output stop "0"= Normal operation setting value	Set to [1] only in case of PWM output stopped Stopped in case of $\lceil RW \rfloor = \lceil ALL \rfloor = \lceil RST \rfloor = "1"$
"ch3~ch0"	Assign RGB sets in case of ALL= "0"	-

Table 5. LED Line Address

1 4010	Table 5. LED Line Address										
]	LED lin	e addres	S	Channel							
ch3	ch2	ch1	ch0	(LED line)							
0	0	0	0	Setting is prohibited							
0	0	0	1	Setting is prohibited							
0	0	1	0	Setting is prohibited							
0	0	1	1	Setting is prohibited							
0	1	0	0	LEDR4, LEDG4, LEDB4							
0	1	0	1	LEDR5, LEDG5, LEDB5							
0	1	1	0	LEDR6, LEDG6, LEDB6							
0	1	1	1	LEDR7, LEDG7, LEDB7							

1	LED line	e addres	S	Channel
ch3	ch2	ch1	ch0	(LED line)
1	0	0	0	LEDR8, LEDG8, LEDB8
1	0	0	1	LEDR8~LEDR4 write to LEDR pins in order
1	0	1	0	LEDG8~LEDG4 write to LEDG pins in order
1	0	1	1	LEDB8~LEDB4 write to LEDB pins in order
1	1	0	0	LED*8~LED*4 write to LEDR,G,B pins with same data at the same time
1	1	0	1	LED** write to all LED pins with same data
1	1	1	0	Sotting is prohibited
1	1	1	1	Setting is prohibited

Table 6. Command Table

Tuble of Com																	
Command		Instr	uctior	1		IC address			RW	ALL	RST	LED address			Pin		
SCL	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	SCK
Normal	0	0	1	0	A 4	A3	12	A 1	10	RW	ALL	RST	ah2	ahQ	ah 1	ah0	
Unreflected	0	0	0	1	A4	AS	A2	A1	A0	ĸw	ALL	KSI	ch3	ch2	ch1	ch0	TxD
Lach	0	0	0	0						Do	Not Enter	•					

Note 12. Changing setting of the A4~A0 pins is prohibited when the CSB pin= "L" (during command input). Note 13.

- 1. Normal Command: when the CSB pin is set "High" after executing a command, the state of the LED lighting reflects the PWM gradation data configured by the command.
- 2. Unreflected Command: when the CSB pin is set "High" after executing a command, the state of LED lighting does not reflect the PWM gradation data configured by the command. LED lighting is not changed by executing the command.
- 3. Latch Command: Latch Command simultaneously executes the LED lighting based on all the PWM gradation data in the IC when the CSB pin is set "High" after executing the Latch command.
- 4. When the latch command is executed, LEDs that are not set with PWM gradation data are turned off.
- 5. In case of the latch command, the CSB pin can be set "High" after entering the "4-bit" instruction.
- 6. When ALL= "0" is set, the PWM gradation data should be set for 1-RGB (=3 LED lines).
- e.g. In the case of ch3~ch0= "0111", (R7D7~R7D0) (G7D7~G7D0) (B7D7~B7D0) should be set with the same command.
- 7. When ALL= "0" is set, there is a possibility that the AP4203 becomes shipping test status by setting a one LED line address to the "setting prohibited status" twice continuously. (It is necessary to supply the power again to recover from this shipping test status.)

Table 7. IC Address List

IC Address Data [A4~A0]: Command will be executed to the assigned IC address.								
00000 = Address 0	01000 = Address 8	10000 = Address 16	11000 = Address 24					
00001 = Address 1	01001 = Address 9	10001 = Address 17	11001 = Address 25					
00010 = Address 2	01010 = Address 10	10010 = Address 18	11010 = Address 26					
00011 = Address 3	01011 = Address 11	10011 = Address 19	11011 = Address 27					
00100 = Address 4	01100 = Address 12	10100 = Address 20	11100 = Address 28					
00101 = Address 5	01101 = Address 13	10101 = Address 21	11101 = Address 29					
00110 = Address 6	01110 = Address 14	10110 = Address 22	11110 = Address 30					
00111 = Address 7	01111 = Address 15	10111 = Address 23	11111 = Address 31					

Note 14. Set address 0~31 by the A4~A0 pin for IC address setting (connect to GND or OPEN).

Normal Command		Instruction IC Address RW ALL RST LED Line Address					IC Address				ess	Pin					
SCL(times)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	SCK
Case 1	0	0	1	0	A4	A3	A2	A1	A0	1	1	0	-	-	-	-	
Case 2	0	0	1	0	A4	A3	A2	A1	A0	1	0	0	0	1	0	0	
Case 3	0	0	1	0	A4	A3	A2	A1	A0	0	1	0	-	-	-	-	
Case 4	0	0	1	0	A4	A3	A2	A1	A0	0	0	0	0	1	1	0	TxD
Case 5	0	0	1	0	A4	A3	A2	A1	A0	1	1	1	-	-	-	-	
Case 6	0	0	1	0	A4	A3	A2	A1	A0	1	0	0	1	0	0	1	
Case 7	0	0	1	0	A4	A3	A2	A1	A0	1	0	0	1	1	0	0	

Table 8. Normal Command Examples

Note 15. 'Data' described below represents the PWM gradation data for each individual LED channel. The PWM gradation data is set in hexadecimal for the lighting ratio. "8-bit" data "10(H)" generates a light level of 16/255. (All-0= "00(H)"= turns all LEDs off)

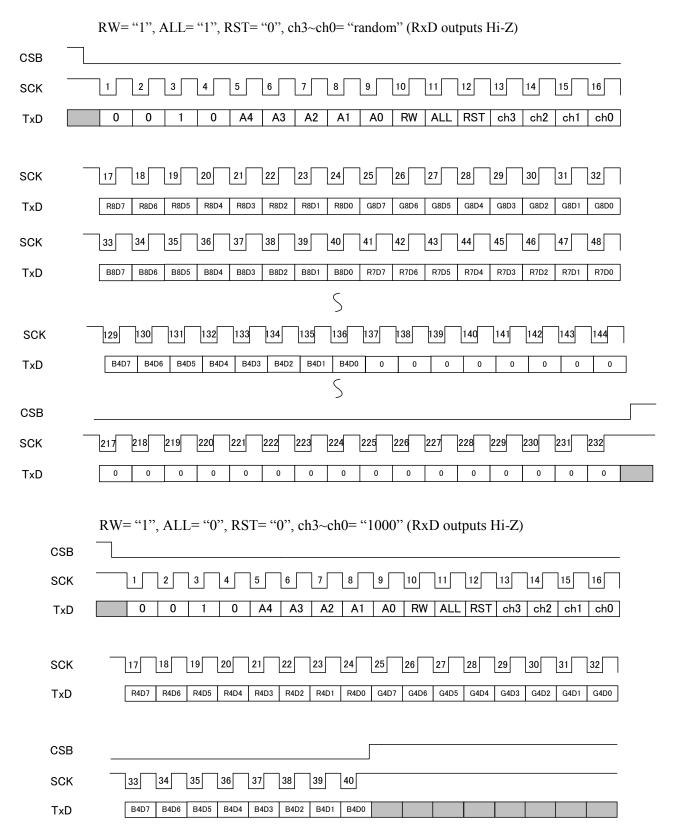
- Case 1: Write LED gradation data using an "8-bit" configuration to the IC assigned by an IC address. In accordance with [ALL] = "1", write data to all the LED lines. In this case, LED line address data are ignored; however, the 4 clock pulses for the LED line addresses are still necessary. Following the initial "16-bit" command, "8-bit" x 15 LED lines = "120-bit" of data input and dummy bit x 12LED lines = 96 bit, total 216-bit data are necessary.
- Case 2: Write LED gradation data using an "8-bit" configuration to the IC assigned by an IC address. In accordance with [ALL] = "0", write data to a specified 3 colors LED line(LEDR8, LEDG8, LEDB8). Following the initial "16-bit" command, "8-bit" x 3 LED lines = "24-bit" of data input are necessary.
- Case 3: Read LED gradation data using an "8-bit" configuration from the IC assigned by an IC address. In accordance with [ALL] = "1", read data from all the LED lines. In this case, LED line address data are ignored; however, the 4 clock pulses for the LED line addresses are still necessary. Following the initial "16-bit" command, CLK pulses for "8-bit" x 15 LED lines = "120-bit" are necessary.
- Case 4: Read LED gradation data using a "8-bit" configuration from the IC assigned by an IC address. In accordance with [ALL] = "0", read data from a specified 3 colors LED lines (LEDR6, LEDG6, LEDB6). In this case, Following the initial "16-bit" command, CLK pulses for "8-bit" x 3 LED lines = "24-bit" are necessary.
- Case 5: This command means [turn off all at once].
 - In accordance with [RW]=[ALL]=[RST]= "1", turn off LEDs of the IC assigned by an IC address. This command is used to turn off all LED lines, the LED gradation data before turning off will be kept continually. Executing a latch command can relight the LEDs with the same gradation data. This command is valid when the instruction= [normal command], [RW]=[ALL]=[RST]= "1" and command length \geq "16-bit" (need "16-bit" CLK pulse input). If [RST]= "1" is input when these conditions are not satisfied, [RST] command will be recognized as "0". (This command is used for LED dynamic and scanning drives.)
- Case 6: Write LED gradation data by an "8-bit" configuration to an IC assigned by the IC address. In accordance with [ALL]= "0" and LED line setting (ch3~ch0), only write [R] data to LED lines in the order as shown below. (R\$D7_R\$D0) (R7D7_R7D0) ••• (R4D7_R4D0) [Total "8 bit"×51 ED lines = "40 bit" (bit

(R8D7~R8D0) (R7D7~R7D0) • • • (R4D7~R4D0) [Total "8-bit"×5LED lines = "40-bit" (bit number of data)] and dummy bit x 4LED lines =32-bit, total 88bit data are necessary.

Case 7. Write LED gradation data using an "8-bit" configuration to an IC assigned the IC address. In accordance with [ALL]= "0" and LED line setting (ch3~ch0), write data to one set of LED lines for three colors in the order as shown below.

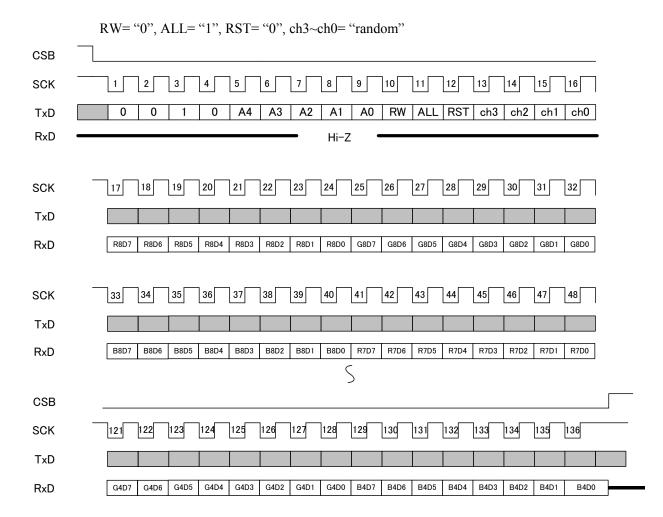
(RxD7~RxD0) (GxD7~GxD0) (BxD7~BxD0) [Total "8-bit"×3LED lines = "24-bit" (bit number of data)]. For this setting, the data of one set of written LED lines for three colors is reflected to all LED lines.

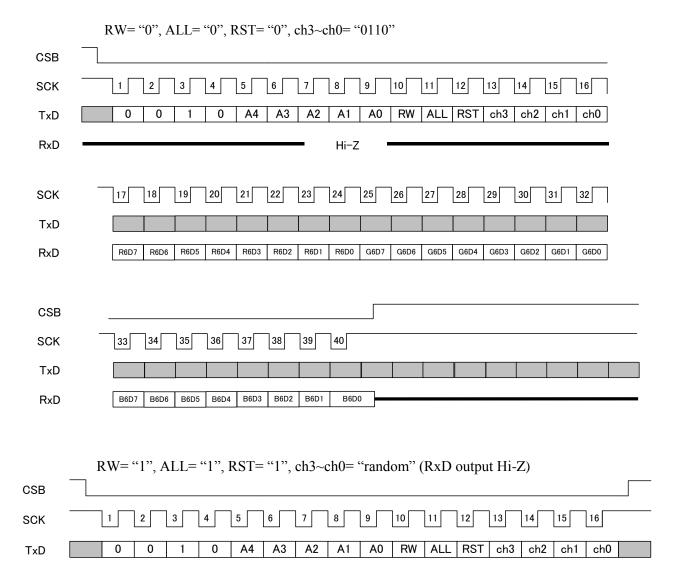
Timing Diagram

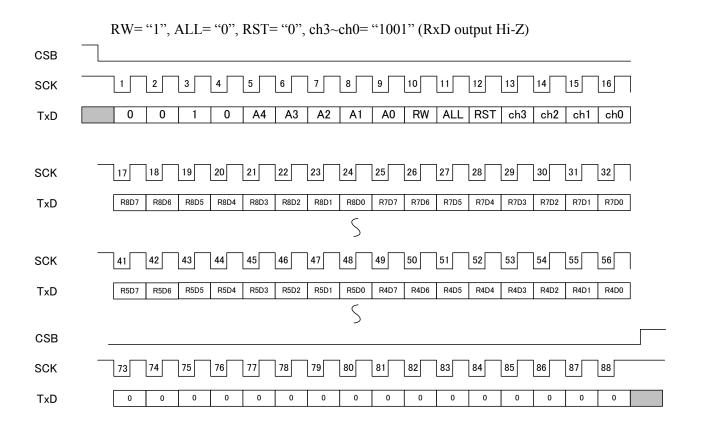


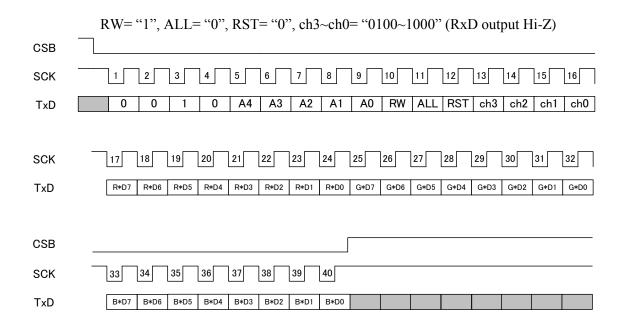
LED line (gradation data): R4, G4, B4

Data write order (MSB-first): R8D7, R8D6, ...R8D1, R8D0, G8D7, G8D6, ...G8D1, G8D0, B8D7, B8D6, ...B8D1, B8D0









10.3. Serial F/F Cascade Control

Input LED gradation data serially (8 bits x 12ch= 96 bits for data justifying and then 8 bits x 15ch= 120 bits) and set PWM data from internal shift register to control LEDs. Multiple AP4203s can be used to control LEDs with shift register by connecting the SO output pin to the next IC's SI pin.

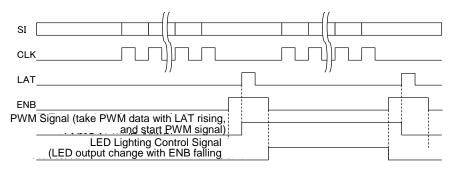
	Inp	out		Shift nagistan	Latch Data	LED air
CLRB	CLK	LAT	ENB	Shift register	Laten Data	LED pin
L	×	×	×	L	L	OFF
Н	Ł	L	Н	Data shift (Note 16) $SI \rightarrow$ data input for 96bits $PWM_B4 \rightarrow$ $PWM_G4 \rightarrow$ $PWM_R4 \rightarrow$ $PWM_B5 \rightarrow$: $PWM_7R \rightarrow$ $PWM_8B \rightarrow PWM_8G \rightarrow$ $PWM_8R \rightarrow SO$	Hold	OFF
Н	Ł	L	L	Data shift (Note 16) $SI \rightarrow data input for 96bits$ $PWM_B4 \rightarrow$ $PWM_G4 \rightarrow$ $PWM_R4 \rightarrow$ $PWM_B5 \rightarrow$: $PWM_7R \rightarrow$ $PWM_8B \rightarrow PWM_8G \rightarrow$ $PWM_8R \rightarrow SO$	Hold	ON at PWM signal = "1" OFF at PWM signal = "0"
Н	L	ſ	Н	Not shift	Transfer	off
Н	L	1	L	Not shift	Transfer	ON at PWM signal = "1" OFF at PWM signal = "0"
Н	×	×	L	_	_	ON at PWM signal = "1" OFF at PWM signal = "0"

Table 9. Serial F/F Cascade Control

Note 16. PWM_Rx, PWM_Gx, PWM_Bx (x=8~4) means shift each channel's PWM gradation data. (same as CSI control, input with MSB order)

e.g.) PWM_B4: "B4D0 \rightarrow B4D1 \rightarrow B4D2 \rightarrow B4D3 \rightarrow B4D4 \rightarrow B4D5 \rightarrow B4D6 \rightarrow B4D7"

(B4D0 is the LSB gradation data of LEDB4, B4D7 is the MSB gradation data of LEDB4)



The SI input shift data can be taken by many chips with LAT rising. Output each chip's LED lighting control signal when ENB= "0" (ENB= "1": all channel= "off")

Figure 5. Serial F/F Cascade Control

10.4. LED Current Setting (fixed current output)

LED current can be adjusted from 5mA to 50mA with an external resistor which is connected between the ISET pin and GND. Since the ISET pin is easily affected by a noise, RISET layout should take a shortest connection to avoid unstableness LED current. The ISET_R pin is used to set LEDR4~8 current, the ISET_G pin used to set LEDG4~8 current and the ISET_B pin used to set LEDB4 ~ 8 current. An approximate formula of ILED, that is LED current, and RISET resistor, which is connected to the ISET pin, and a relationship table between ILED and RISET are shown below. Please confirm actual values on your board when setting.

ILED(mA) =
$$\frac{1000}{R_{ISET}(k\Omega)}$$

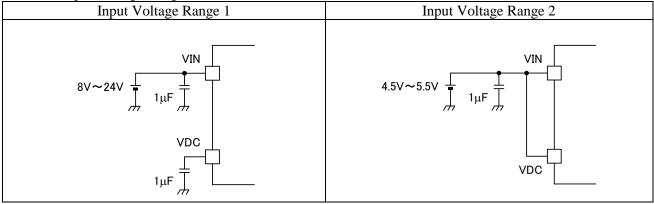
Table 10. Combination of ILED and R_{ISET}

Table 10. Combination of ILED and R _{ISET}										
ILEDRx (mA)	RISET_R ($k\Omega$)	ILEDRx (mA)								
ILEDGx (mA)	RISET_G (k Ω)	ILEDGx (mA)								
ILEDBx (mA)	RISET_B $(k\Omega)$	ILEDBx (mA)								
5.0	35.7	28.0								
6.0	34.5	29.0								
7.0	33.3	30.0								
8.0	32.3	31.0								
9.0	31.3	32.0								
10.0	30.3	33.0								
11.0	29.4	34.0								
12.0	28.6	35.0								
13.0	27.8	36.0								
14.0	27.0	37.0								
15.0	26.3	38.0								
16.0	25.6	39.0								
17.0	25.0	40.0								
18.0	24.4	41.0								
19.0	23.8	42.0								
20.0	23.3	43.0								
21.0	22.7	44.0								
22.0	22.2	45.0								
23.0	21.7	46.0								
24.0	21.3	47.0								
25.0	20.8	48.0								
26.0	20.4	49.0								
27.0	20.0	50.0								
	ILEDRx (mA) ILEDRx (mA) ILEDBx (mA) 1LEDBx (mA) 5.0 6.0 7.0 8.0 9.0 10.0 11.0 12.0 13.0 14.0 15.0 16.0 17.0 18.0 19.0 20.0 21.0 22.0 23.0 24.0 25.0 26.0	ILEDRx (mA)RISET_R ($k\Omega$)ILEDGx (mA)RISET_G ($k\Omega$)ILEDBx (mA)RISET_B ($k\Omega$)5.035.76.034.57.033.38.032.39.031.310.030.311.029.412.028.613.027.814.025.015.026.316.025.617.023.820.023.321.022.722.022.723.021.724.021.325.020.826.020.4								

10.5. Input Voltage Range (VIN)

Basically, the input voltage range is $8V \sim 24V$. It can be changed to $4.5 \sim 5.5V$ by shorting the VIN pin and the VDC1 pin when 5V power supply is used. In this case, a normal operation cannot be guaranteed with an input that is in the range of $5.5V \sim 8V$.

Table 11. Input Voltage Range



10.6. POR Operation (Power on Reset)

The internal POR circuit releases reset state after a specific period of time (t1) when a power supply more than 6V is applied to the VIN pin. Do not input a command code via the interface for specific period of time (t2) after releasing reset state for a certain stabilization of the internal oscillation frequency. The following figure shows the POR timing when power is applied. During the "t1" period, a command from the interface is not accepted. Please note, that a command accepted during the "t2" period may be interpreted incorrectly.

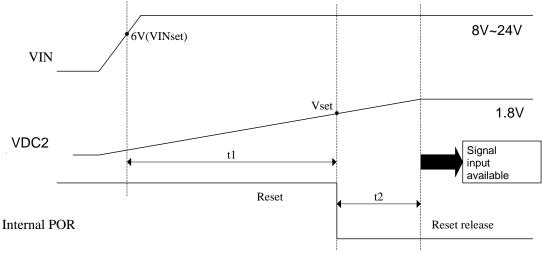


Figure 6. POR Operation (Power on Reset)

Table 12	DOD Timi	ng when Pow	or Annlind
	FOR THIE	ng when row	er Applieu

I dole	2.1 010	Thing	milen i o	mor rip	pilea
Item	min	typ	max	Unit	Condition
t1	-	-	2800	μs	VIN pin voltage > 6V, IDC1= -30mA. Bypass capacitor between the VDC pin and GND CVDC= 1.0μ F.
t2	-	-	200	μs	Stabilization time of internal power

Note 17. As shown above, the AP4203 is in normal operation after 3msec at maximum from the time the VIN voltage reaches 6V. In the case of Input Voltage Range 2, the AP4203 is in normal operation after 3mec from the time the VIN voltage reaches 4.5V.

Note 18. A recovery time of when the internal POR circuit is reset by a decreasing VIN voltage also follows the prescribed times above (t1, t2) even if it is not the power-up sequence of the AP4203.

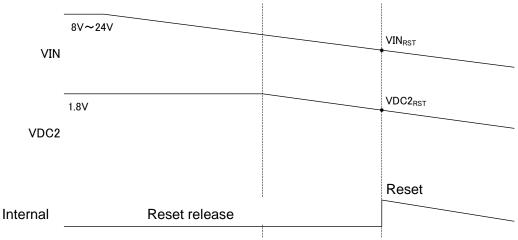


Figure 7. POR Operating Power Off

Table 13. POR Timing when VIN Decreases

Item	min	typ	max	Unit	Condition	
VINrst	-	4.0	4.2	V	VIN reset voltage	
VDC2rst	-	1.2	1.5	V	Internal 1.8V LDO reset voltage (reference value)	

Note 19. This function executes reset when the supply voltage decreases, preventing instability. However, the reset may not be executed even the supply voltage becomes below the VINrst voltage such as when VIN decreases to near 0V instantaneously. Therefore, in the actual use, it is recommended to design the application in consideration with the VIN voltage to avoid activating this function by peripheral noise or voltage fluctuations.

Note 20. The IC is designed to work normally as possible, so sometimes LED gradation data can be hold even when VIN< VIN_{RST}, and LEDs turn off all at once. (Lighting setting is holding)

Note 21. As long as the VIN voltage (IC pin voltage) is more than the maximum VINrst voltage, continuous proper operation of the AP4203 is guaranteed (by design). However if the VIN voltage is out of recommend voltage range, the communication function via input signal is not guaranteed.

10.7. Reset State

Immediately after start up the AP4203 or after reset by decreasing power supply voltage, LED gradation data in the IC is all reset (all data= "0"). Therefore, LEDs will not light unless new gradation data is input via SCI interface. The AP4203 has all turn off function (in case of SCI interface control). It can be used as reset function. Reset types and reset states are shown below.

	Types of Reset					
	VIN Input	VIN falls	VDC1 falls	VDC2 falls	LED All Off	
LED lighting status	LED All Off					
LED gradation data input		Possible				
LED gradation data hold	_	Hold	Hold	Reset	Hold	
LDO1(5V) Output		Normal				

Table 14. Types of reset and status

10.8. Protection Functions

The AP4203 has an over current (LED current) protection and a thermal protection function in order to prevent damaging the IC. The LED current is shut off when these functions are activated and recovers automatically when the fault condition is removed.

Tuble 15. Trotection Tubetion (Tin Values are Salaraneod by design)						
Protection Function	Over Current Protection	Thermal Protection				
LED Current	I = D Current ner channel > 200 m A (turn)	Junction Temperature $\geq 140^{\circ}C$				
Shut-off Condition	LED Current per channel \geq 200mA (typ.)	(typ.)				
LED Current	Objective LED line	All 15 Channels				
Shut-off points	Objective LED line	(also shut-off VDC1 output)				
Recovery Type	Timer-latch type recovery Check if the overcurrent condition still exists after 0.3 second (typ) following LED current shut-off. After checking three times, if the over current condition still exists, LED current will be shut off continuously. (Latching)	Auto-recovery				
Recovery Condition	Before Latch: Intended channel current ≥ 150 mA (typ.) After Latch: Power Reboot	Junction Temperature $\geq 120^{\circ}C$ (typ.)				

Table 15. Protection Function (All values are guaranteed by design)

Note 22. The over current protection function works when the LED is lighten by shutting off the LED current. In the case that LED channels are not set to light the LEDs, this protection will not work even if the LED pin voltage is high. This function is disabled in fixed current output mode.

- Note 23. The thermal protection function is an auxiliary function for the worst case and it is not guaranteed to work reliably. Therefore, it is recommended that application is designed in consideration with heat generation in order to prevent activation of the thermal protection.
- Note 24. When the VDC1 and VDC2 pins are shorted to GND, there is a case that thermal protection works because the internal LDO is overheated by high VIN voltage and there is a case that Power On Reset works because of the voltage at the VDC2 pin is decreased. The external current capability of the VDC1 pin is maximum 30mA.
- Note 25. V_{LED} voltage and LED current settings according to the ambient temperature (Ta) are shown below.

Output setting	IC ambient temperature	LED pin voltage	LED current	
DRSET	Ta [°C]	V _{LED} [V]	I _{LED} [mA]	
	25		I _{LEDTO} =98 [mA]	
Low (open drain)	55	—	I _{LEDTO} =81 [mA]	
	70		I _{LEDTO} =72 [mA]	
	25	5.6	I _{LEDTC} =15 [mA]	
		3.9	I _{LEDTC} =20 [mA]	
	55	4.2	$I_{LEDTC}=12 [mA]$	
High (fixed current)	55	3.1	I _{LEDTC} =15 [mA]	
High (lixed current)	70	4.2	$I_{LEDTC} = 8 [mA]$	
		3.2	I _{LEDTC} =10 [mA]	
		2.5	$I_{\text{LEDTC}}=12 \text{ [mA]}$	
		2.1	I _{LEDTC} =14 [mA]	

Table 16. V_{LED} voltage and LED current setting (Condition: $V_{IN}=12V$, $I_{DC1}=0mA$)

11. Recommended External Circuits

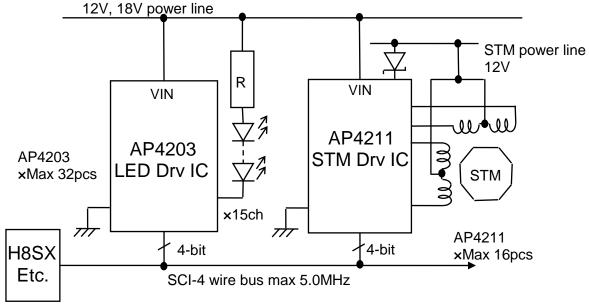
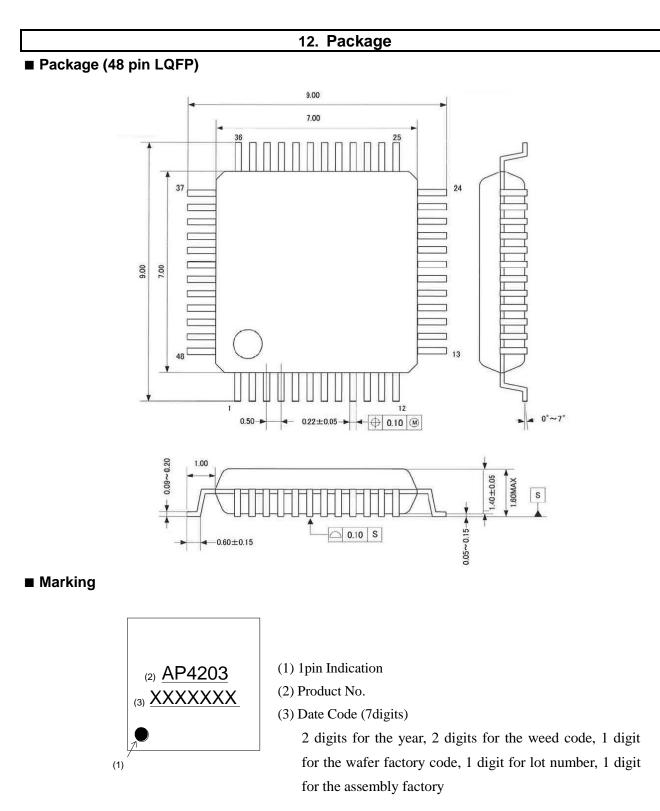


Figure 8. Recommended External Circuits

Note 26. If data on the AP4203/AP4211 application board will not be read, it is unnecessary to connect RxD of the SCI 4-wire BUS. The 4-wire BUS can be reduced to a 3-wire BUS. The RxD terminal is an output terminal, and it should be open when RxD is not used. When using the AP4203 as an open drain driver, external resistors for current setting can be removed. In this case, the ISET_R, G, B pins should also be open.



Note 27. Week code: the first Thursday of the week of the assembly year is marked to as 01, the second week is marked as 02 • • • and the 52nd week is marked as 52. (Compliance with ISO-8601) Please contact to our sales office for more detailed marking specification. (example: marking size, marking print sample and etc.)

13. Revision History			
		-	
Date (Y/M/D)	Revision	Page	Contents
15/09/15	00	-	First Edition

-IMPORTANT NOTICE

- 0. Asahi Kasei Microdevices Corporation ("AKM") reserves the right to make changes to the information contained in this document without notice. When you consider any use or application of AKM product stipulated in this document ("Product"), please make inquiries the sales office of AKM or authorized distributors as to current status of the Products.
- 1. All information included in this document are provided only to illustrate the operation and application examples of AKM Products. AKM neither makes warranties or representations with respect to the accuracy or completeness of the information contained in this document nor grants any license to any intellectual property rights or any other rights of AKM or any third party with respect to the information in this document. You are fully responsible for use of such information contained in this document in your product design or applications. AKM ASSUMES NO LIABILITY FOR ANY LOSSES INCURRED BY YOU OR THIRD PARTIES ARISING FROM THE USE OF SUCH INFORMATION IN YOUR PRODUCT DESIGN OR APPLICATIONS.
- 2. The Product is neither intended nor warranted for use in equipment or systems that require extraordinarily high levels of quality and/or reliability and/or a malfunction or failure of which may cause loss of human life, bodily injury, serious property damage or serious public impact, including but not limited to, equipment used in nuclear facilities, equipment used in the aerospace industry, medical equipment, equipment used for automobiles, trains, ships and other transportation, traffic signaling equipment, equipment used to control combustions or explosions, safety devices, elevators and escalators, devices related to electric power, and equipment used in finance-related fields. Do not use Product for the above use unless specifically agreed by AKM in writing.
- 3. Though AKM works continually to improve the Product's quality and reliability, you are responsible for complying with safety standards and for providing adequate designs and safeguards for your hardware, software and systems which minimize risk and avoid situations in which a malfunction or failure of the Product could cause loss of human life, bodily injury or damage to property, including data loss or corruption.
- 4. Do not use or otherwise make available the Product or related technology or any information contained in this document for any military purposes, including without limitation, for the design, development, use, stockpiling or manufacturing of nuclear, chemical, or biological weapons or missile technology products (mass destruction weapons). When exporting the Products or related technology or any information contained in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations. The Products and related technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations.
- 5. Please contact AKM sales representative for details as to environmental matters such as the RoHS compatibility of the Product. Please use the Product in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. AKM assumes no liability for damages or losses occurring as a result of noncompliance with applicable laws and regulations.
- 6. Resale of the Product with provisions different from the statement and/or technical features set forth in this document shall immediately void any warranty granted by AKM for the Product and shall not create or extend in any manner whatsoever, any liability of AKM.
- 7. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written consent of AKM.