

Features

- Independent 6-Channel H-Bridge
- Built-in 4 constant voltage drivers, all of those drivers with brake function.
- Built-in 2 constant current drivers with brake function.
- Low on-resistance <math><1.2\Omega</math> (typ.)
- Built-in charge pump(to drive the upside NMOS of H-bridge drivers)
- Low Voltage operation
- Built-in Thermal Shutdown Function
- LQFP-48/QFN-48 Package

General Description

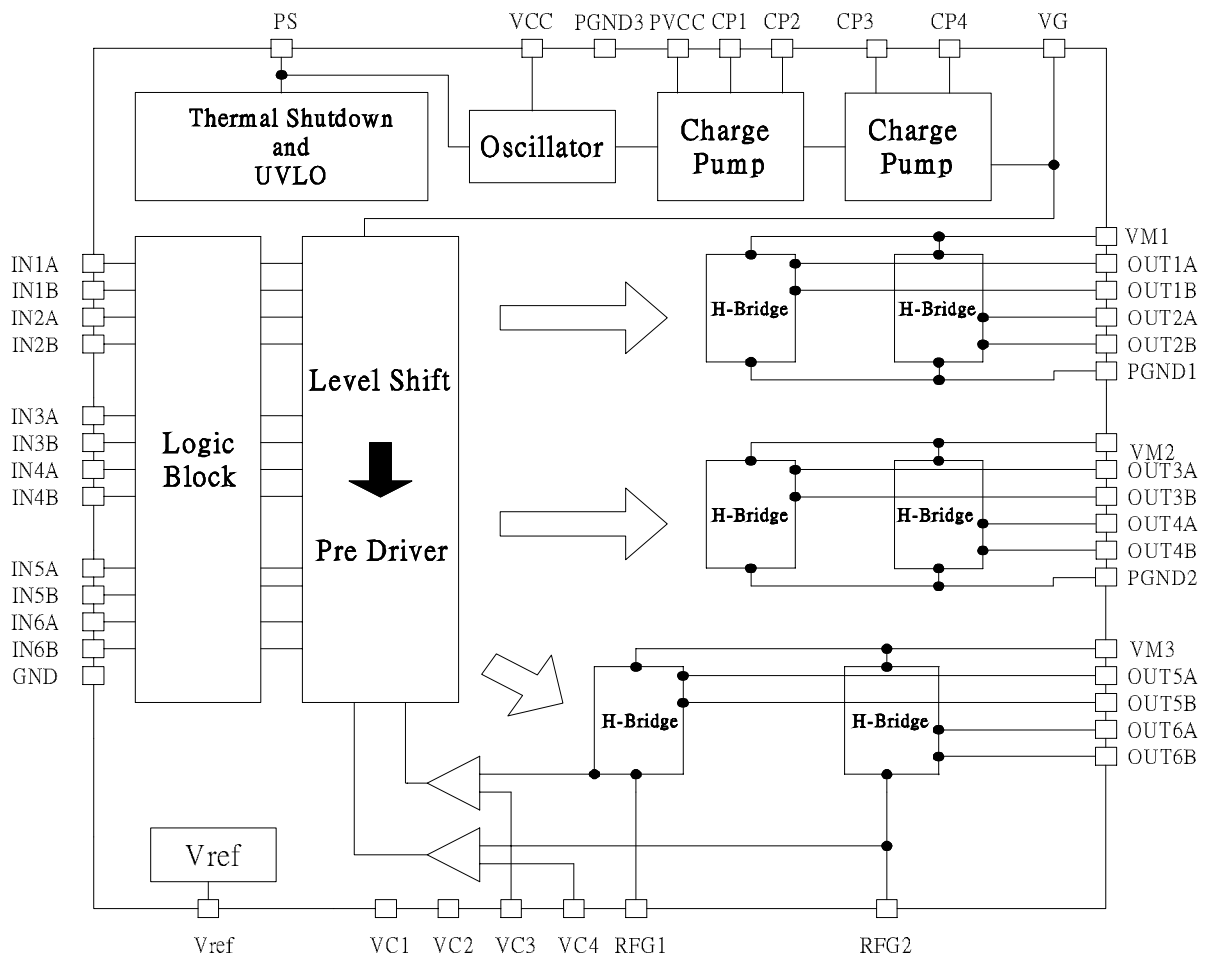
The AT5556 is a 6-channel H-bridge drivers IC for DSC motor application. It built in with 4 constant voltage drivers and 2 constant current blocks to drive auto-focus, zoom, shutter, auto-exposure motors.

Applications

- DSC motor Driver

** Protected by U.S. Patent #6,943,514*

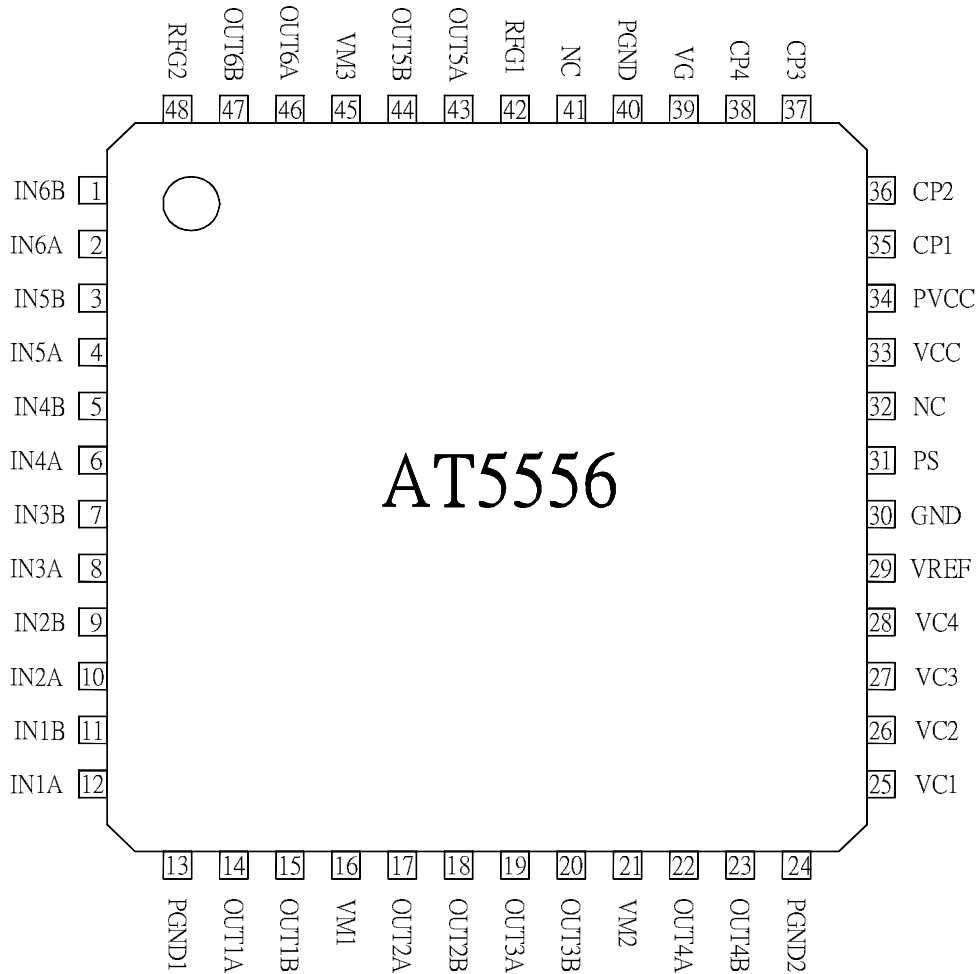
Block Diagram



Aimtron reserves the right without notice to change this circuitry and specifications.

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Pin Configuration



Ordering Information

| Part number | Package | Marking |
|-------------|-----------------|---|
| AT5556F | LQFP48 | AT5556F |
| AT5556F_PBF | LQFP48, PB-Free | AT5556F, date code with one bottom line |
| AT5556F_GRE | LQFP48, Green | AT5556F, date code with two bottom line |
| AT5556N GRE | QFN48, Green | AT5556N |

Pin Description

| Pin NO. | Symbol | I/O | Description |
|---------|--------|-----|--|
| 1 | IN6B | I | It combines IN6A to decide the state of the constant current driver6 |
| 2 | IN6A | I | It combines IN6B to decide the state of the constant current driver6 |
| 3 | IN5B | I | It combines IN5A to decide the state of the constant current driver5 |
| 4 | IN5A | I | It combines IN5B to decide the state of the constant current driver5 |
| 5 | IN4B | I | It combines IN4A to decide the state of the constant voltage driver4 |
| 6 | IN4A | I | It combines IN4B to decide the state of the constant voltage driver4 |
| 7 | IN3B | I | It combines IN3A to decide the state of the constant voltage driver3 |
| 8 | IN3A | I | It combines IN3B to decide the state of the constant voltage driver3 |
| 9 | IN2B | I | It combines IN2A to decide the state of the constant voltage driver2 |
| 10 | IN2A | I | It combines IN2B to decide the state of the constant voltage driver2 |
| 11 | IN1B | I | It combines IN1A to decide the state of the constant voltage driver1 |
| 12 | IN1A | I | It combines IN1B to decide the state of the constant voltage driver1 |
| 13 | PGND1 | P | GND1 |
| 14 | OUT1A | O | H-bridge output terminal 1A of the constant voltage driver1 |
| 15 | OUT1B | O | H-bridge output terminal 1B of the constant voltage driver1 |
| 16 | VM1 | P | Power supply for Motor1, 2 |
| 17 | OUT2A | O | H-bridge output terminal 2A of the constant voltage driver2 |
| 18 | OUT2B | O | H-bridge output terminal 2B of the constant voltage driver2 |
| 19 | OUT3A | O | H-bridge output terminal 3A of the constant voltage driver3 |
| 20 | OUT3B | O | H-bridge output terminal 3B of the constant voltage driver3 |
| 21 | VM2 | P | Power supply for Motor3, 4 |
| 22 | OUT4A | O | H-bridge output terminal 4A of the constant voltage driver4 |
| 23 | OUT4B | O | H-bridge output terminal 4B of the constant voltage driver4 |
| 24 | PGND2 | P | GND2 |
| 25 | VC1 | I | It is used to control the output voltage of constant voltage driver1~2 |
| 26 | VC2 | I | It is used to control the output voltage of constant voltage driver3~4 |
| 27 | VC3 | I | Voltage for current limit control of the constant current driver5 |
| 28 | VC4 | I | Voltage for current limit control of the constant current driver6 |
| 29 | VREF | I | Reference voltage being divided for VC1~4 to individually use |
| 30 | GND | P | GND |
| 31 | PS | I | Power save which can force all outputs to become open state |
| 32 | NC | | |
| 33 | VCC | P | Power supply |
| 34 | PVCC | P | Power supply for input voltage of charge pump |
| 35 | CP1 | I | Capacitor terminal 1 for charge pump |
| 36 | CP2 | I | Capacitor terminal 2 for charge pump |
| 37 | CP3 | I | Capacitor terminal 3 for charge pump |
| 38 | CP4 | I | Capacitor terminal 4 for charge pump |
| 39 | VG | P | Output voltage of charge pump |
| 40 | PGND | P | GND |
| 41 | NC | | |
| 42 | RFG1 | | Current detection terminal for the constant current driver5 |
| 43 | OUT5A | O | H-bridge output terminal 5A of the constant current driver5 |
| 44 | OUT5B | O | H-bridge output terminal 5B of the constant current driver5 |
| 45 | VM3 | P | Power supply for Motor5, 6 |
| 46 | OUT6A | O | H-bridge output terminal 6A of the constant current driver6 |
| 47 | OUT6B | O | H-bridge output terminal 6B of the constant current driver6 |
| 48 | RFG2 | | Current detection terminal for the constant current driver6 |

Absolute Maximum Ratings

| Item | Symbol | Ratings | Unit |
|---------------------------|--------|-------------|------|
| Supply voltage VCC | VCC | -0.5 ~ +5.5 | V |
| Supply voltage VM | VM | -0.5 ~ +5.5 | V |
| Supply voltage PVCC | PVCC | -0.5 ~ +5.5 | V |
| Charge pump voltage | VG | 12 | V |
| Control input voltage | VIN | -0.5 ~ VCC | V |
| Power dissipation | Pd | 1000 | mW |
| Operating temperature | Topr | -20 ~ +85 | ° C |
| Junction temperature | Tj | ~ +150 | ° C |
| Storage temperature range | Tstg | -55 ~ +150 | ° C |
| Maximum output current | Iout | 800 | mA |
| ESD Susceptibility *2 | HBM | 2 | KV |
| | MM | 200 | V |

1. Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.
2. Device are ESD sensitive. Handling precaution recommended. The Human Body model is a 100pF capacitor discharged through a 1.5KΩ resistor into each pin.

Recommended Operating Conditions(Ta=25°C)

| Item | Symbol | Ratings | Unit |
|---------------------------|---------|-------------|------|
| Supply voltage VCC | VCC | +2.5 ~ +5.5 | V |
| Supply voltage VM1,2,3 | VM1,2,3 | +1.9 ~ +5.5 | V |
| Charge pump voltage | VG | +7.5~ +10.0 | V |
| Control input voltage | VIN | 0 ~ VCC | V |
| H Bridge output current | Iout | -400 ~ +400 | mA |
| Logic input frequency | Fin | 0 ~ 100 | kHz |
| Capacitor for Charge pump | CCP | 0.01 ~ 0.1 | μF |

Electrical Characteristic

 (Ta=25°C, VCC=PVCC=3.0V, VM=2.5V, $R_{L1} = R_{L2} = R_{L3} = R_{L4} = 7.5\Omega$, $R_{L5} = R_{L6} = 5\Omega$)

| Parameter | Symbol | Condition | Values | | | Unit |
|---|--------|--|--------|------|------|------------|
| | | | Min. | Typ. | Max. | |
| Whole circuits | | | | | | |
| Circuit current at standby | ICCST | PS=L | - | 0 | 10 | μ A |
| Circuit current1 | ICC1 | PS=H, IN1A1B~6A6B=L | - | 1.5 | 3 | mA |
| Circuit current2 | ICC2 | PS=H, IN1A or IN1B or IN2A or IN2B=H | - | 2.65 | 4.7 | mA |
| Circuit current3 | ICC3 | PS=H, IN3A or IN3B or IN4A or IN4B=H | - | 2.65 | 4.7 | mA |
| Circuit current4 | ICC4 | PS=H, IN5A or IN5B or IN6A or IN6B=H | - | 2.65 | 4.7 | mA |
| Circuit current5 | ICC5 | PS=H, IN1A=IN2A=IN3A=IN4A=IN5A=IN6A=H or IN1B=IN2B=IN3B=IN4B=IN5B=IN6B=H | - | 4.90 | 5.5 | mA |
| Power save | | | | | | |
| H level input voltage | VPSH | | 2.0 | - | - | V |
| L level input voltage | VPSL | | - | - | 0.8 | V |
| H level input voltage | IPSH | PS=3V | - | 5 | 20 | μ A |
| L level input voltage | IPSL | PS=0V | -1 | 0 | - | μ A |
| Pull-down resistance | RIN | | - | 1.5 | - | M Ω |
| Control input | | | | | | |
| H level input voltage | VINH | | 2.0 | - | - | V |
| L level input voltage | VINL | | - | - | 0.8 | V |
| H level input voltage | IINH | VIN=3V | - | 5 | 20 | μ A |
| L level input voltage | IINL | VIN=0V | -1 | 0 | - | μ A |
| Pull-down resistance | RIN | | - | 1.5 | - | M Ω |
| Charge Pump | | | | | | |
| Charge pump voltage | VCP | PVCC=5V, VG=PVCC*2 | 9 | 10 | - | V |
| UVLO | | | | | | |
| UVLO voltage | VUVLO | | 1.8 | 2.0 | 2.2 | V |
| Vref | | | | | | |
| VREF output voltage | VREF | Iout=0 ~ 1mA | 0.88 | 0.90 | 0.92 | V |
| Constant voltage driver1,2(For AF/STP) | | | | | | |
| Output ON Resistance | RON | Io=+-200mA, Sum of on-resistance | | 1.20 | 1.50 | Ω |
| Output constant voltage | VO1 | VC1=0.3V, Rload=7.5 Ω | 1.40 | 1.50 | 1.60 | V |
| Constant voltage driver3,4(For ZOOM) | | | | | | |
| Output ON Resistance | RON | Io=+-200mA, Sum of on-resistance | | 1.20 | 1.50 | Ω |
| Output constant voltage | VO2 | VC2=0.3V, Rload=7.5 Ω | 1.40 | 1.50 | 1.60 | V |

| Constant current driver5,6 | | | | | | |
|----------------------------|-----|---|-----|------|------|--------------------|
| Output ON Resistance | RON | $I_o = \pm 300\text{mA}$, Sum of on-resistance | - | 1.00 | 1.25 | Ω |
| Output Limit voltage | VOL | $R_{FG} = 1\Omega$, $V_{C3} = V_{C4} = 0.3\text{V}$ | 287 | 300 | 313 | mV |
| Thermal Protection Circuit | | | | | | |
| Protection Temperature | TSD | | | 130 | | $^{\circ}\text{C}$ |

Input-output logic table

Driver1,2: Stepping motor constant-voltage control for AF

| Input | | | | Output | | | | Mode |
|-------|------|------|------|--------|-------|-------|-------|----------------------|
| IN1A | IN1B | IN2A | IN2B | OUT1A | OUT1B | OUT2A | OUT2B | |
| L | L | L | L | Z | Z | Z | Z | Standby |
| H | L | L | L | H | L | Z | Z | 1,2 phase excitation |
| H | L | H | L | H | L | H | L | |
| L | L | H | L | Z | Z | H | L | |
| L | H | H | L | L | H | H | L | |
| L | H | L | L | L | H | Z | Z | |
| L | H | L | H | L | H | L | H | |
| L | L | L | H | Z | Z | L | H | |
| H | L | L | H | H | L | L | H | BRAKE |
| H | H | | | H | H | | | |
| | | H | H | | | H | H | |

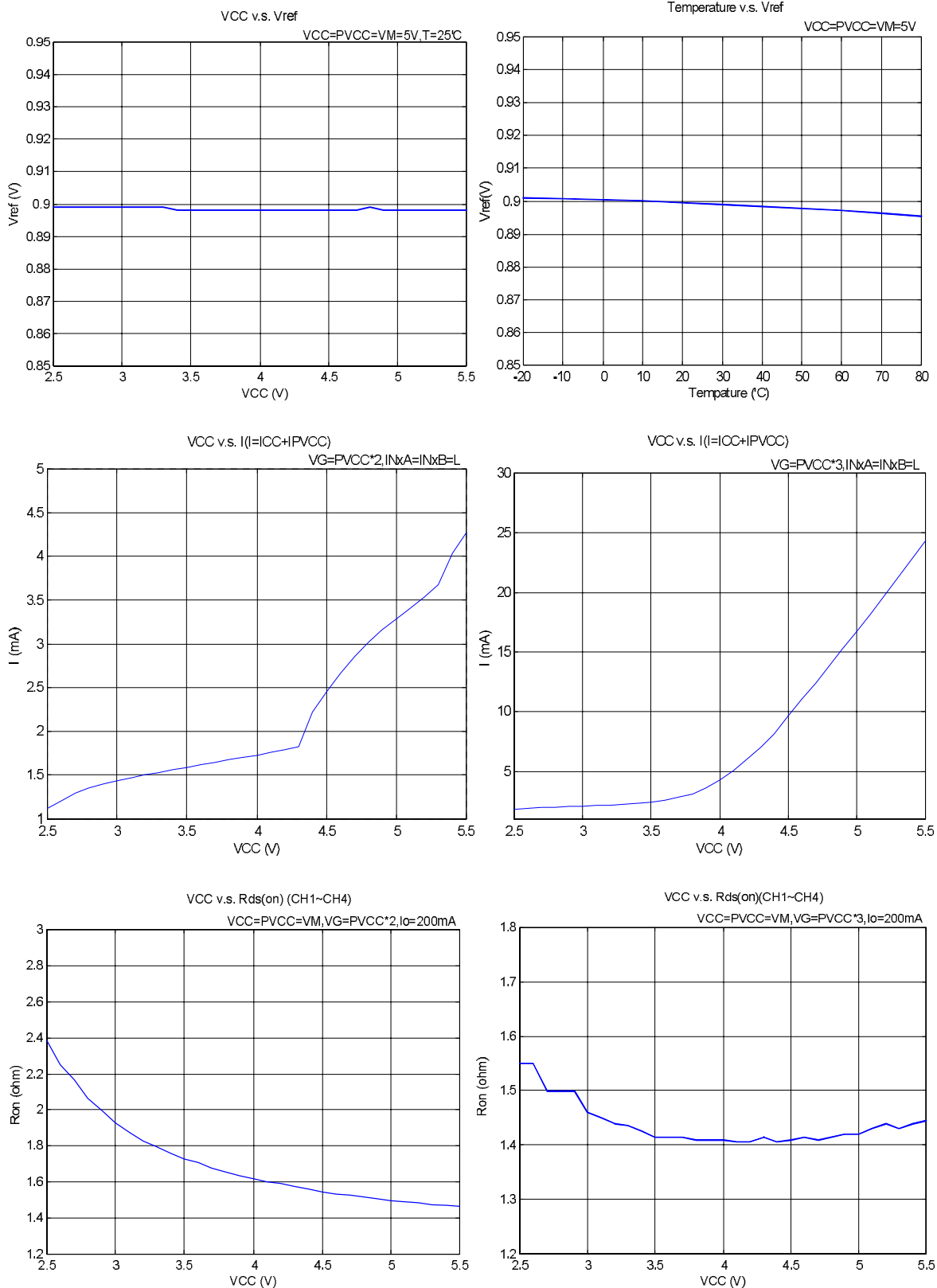
Stepping motor constant-voltage control for ZOOM or DC motor drive

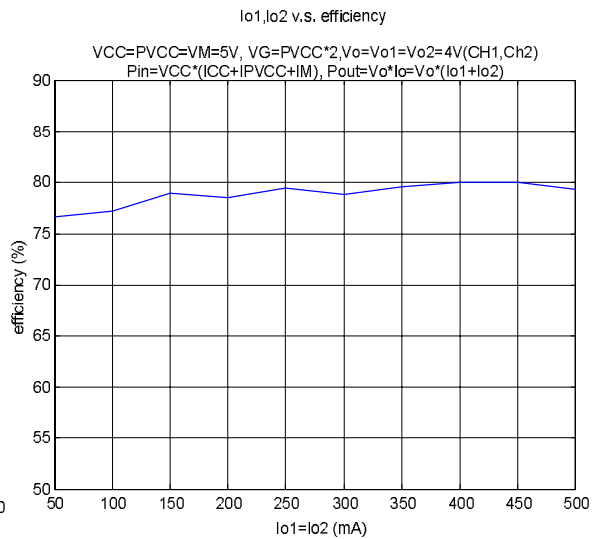
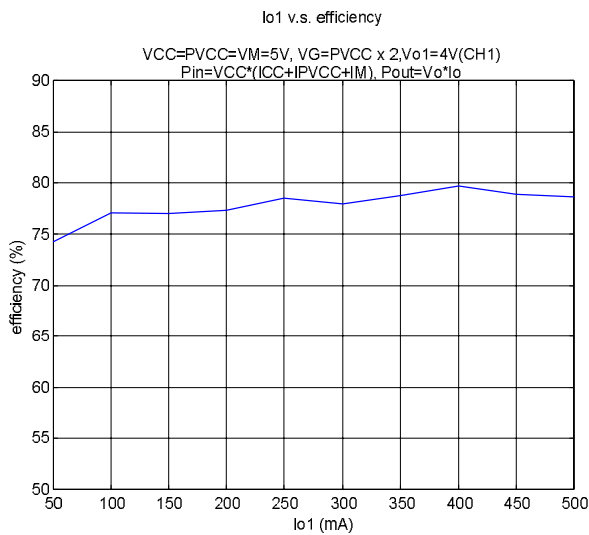
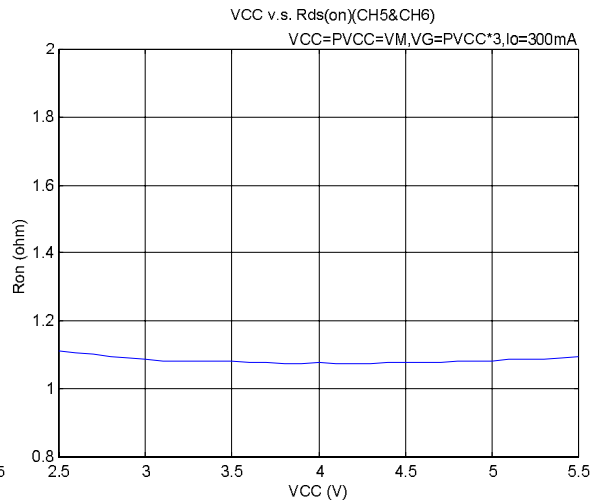
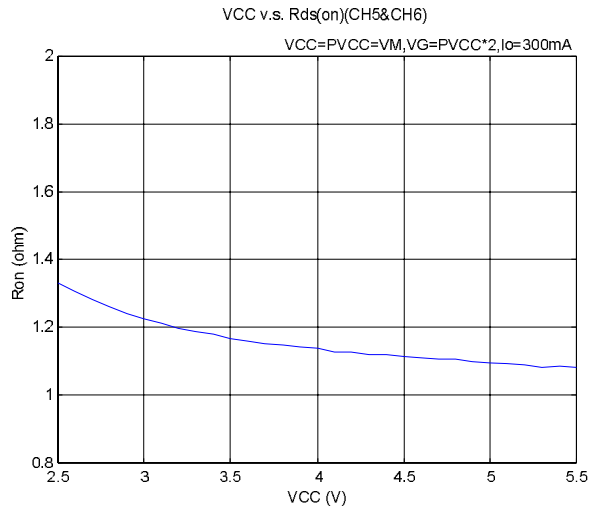
| Input | | | | Output | | | | Mode |
|-------|------|------|------|--------|-------|-------|-------|----------------------|
| IN3A | IN3B | IN4A | IN4B | OUT3A | OUT3B | OUT4A | OUT4B | |
| L | L | L | L | Z | Z | Z | Z | Standby |
| H | L | L | L | H | L | Z | Z | 1,2 phase excitation |
| H | L | H | L | H | L | H | L | |
| L | L | H | L | Z | Z | H | L | |
| L | H | H | L | L | H | H | L | |
| L | H | L | L | L | H | Z | Z | |
| L | H | L | H | L | H | L | H | |
| L | L | L | H | Z | Z | L | H | |
| H | L | L | H | H | L | L | H | BRAKE |
| H | H | | | H | H | | | |
| | | H | H | | | H | H | |

VCM constant-current control for SH/AE or stepping motor drive

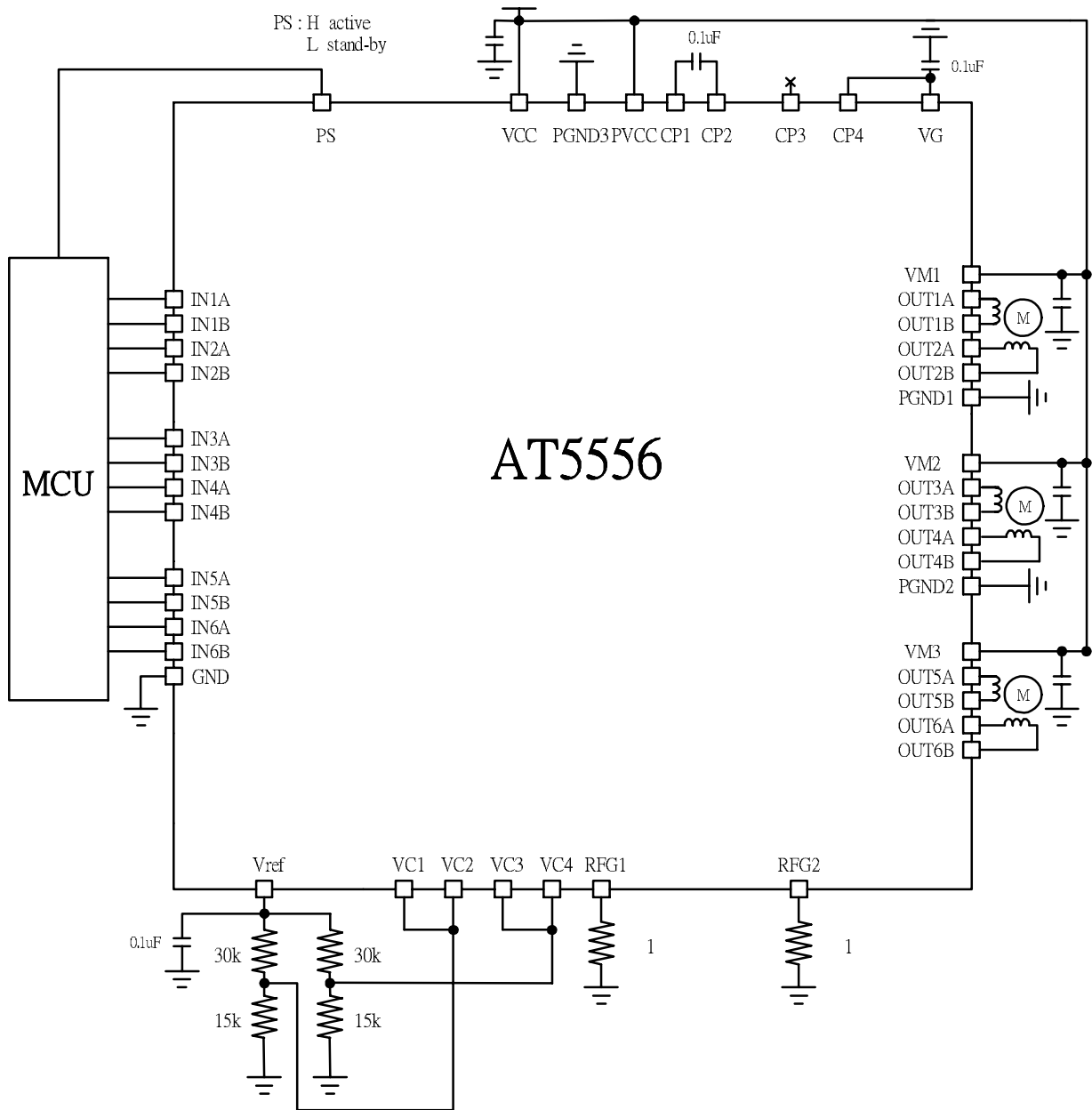
| Input | | | | Output | | | | Mode |
|-------|------|------|------|--------|-------|-------|-------|---------|
| IN5A | IN5B | IN6A | IN6B | OUT5A | OUT5B | OUT6A | OUT6B | |
| L | L | L | L | Z | Z | Z | Z | Standby |
| H | L | | | H | L | | | SH&AE |
| L | H | | | L | H | | | |
| | | H | L | | | H | L | |
| | | L | H | | | L | H | BRAKE |
| H | H | | | L | L | | | |
| | | H | H | | | L | L | |

Typical Characteristics





Application reference 1



Output voltage of charge pump(two times PVCC) : $VG = PVCC \times 2$

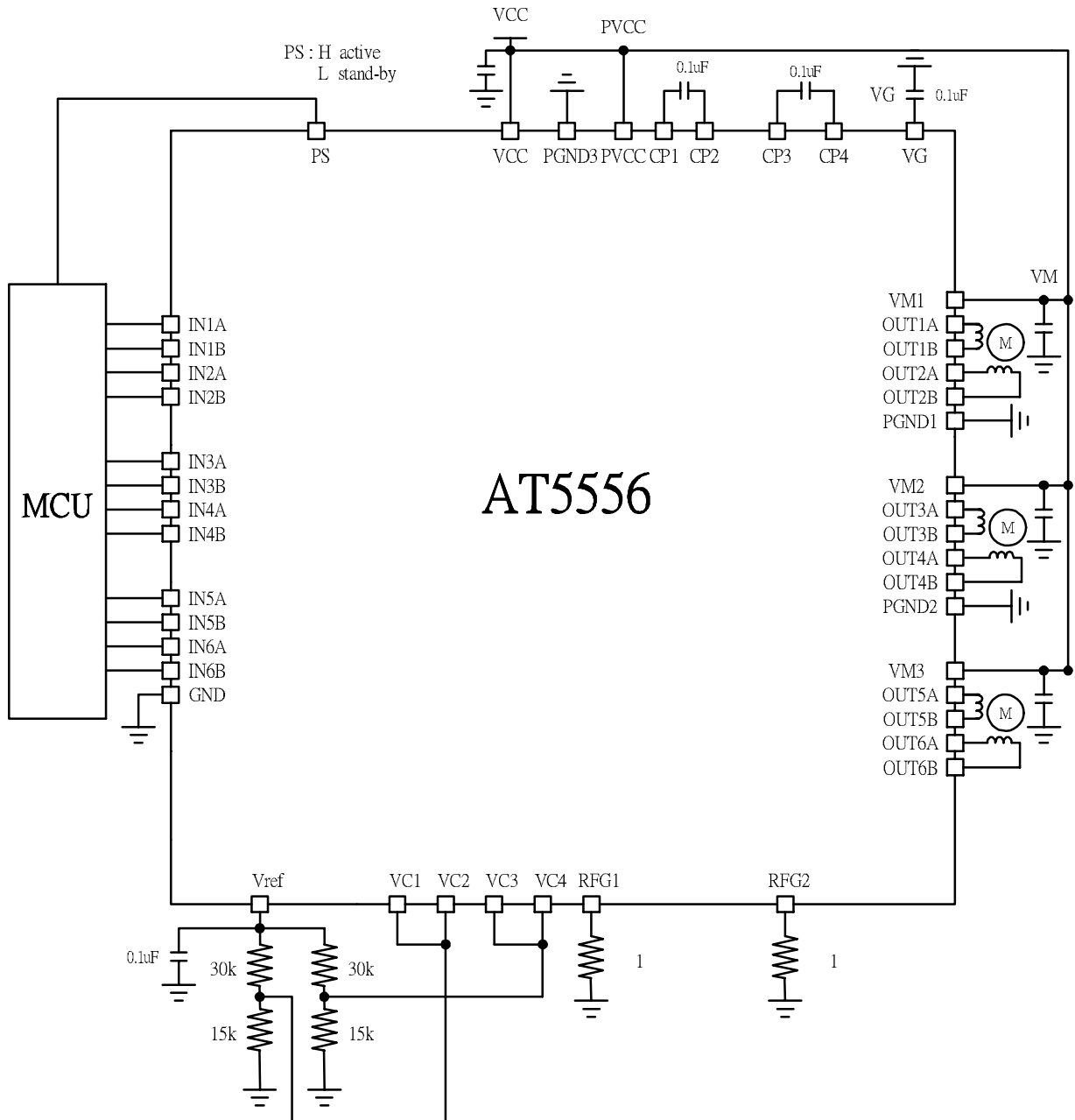
Constant voltage : CH1&CH2 $\rightarrow V_o = V_{C1} \times 5 - 0.5 \times R_{ON} \times I_o$

CH3&CH4 $\rightarrow V_o = V_{C2} \times 5 - 0.5 \times R_{ON} \times I_o$

Constant current : CH5 $\rightarrow I_o = V_{C3} / RFG1$

CH6 $\rightarrow I_o = V_{C4} / RFG2$

Application reference 2



Output voltage of charge pump(three times PVCC) : $VG = PVCC \times 3$

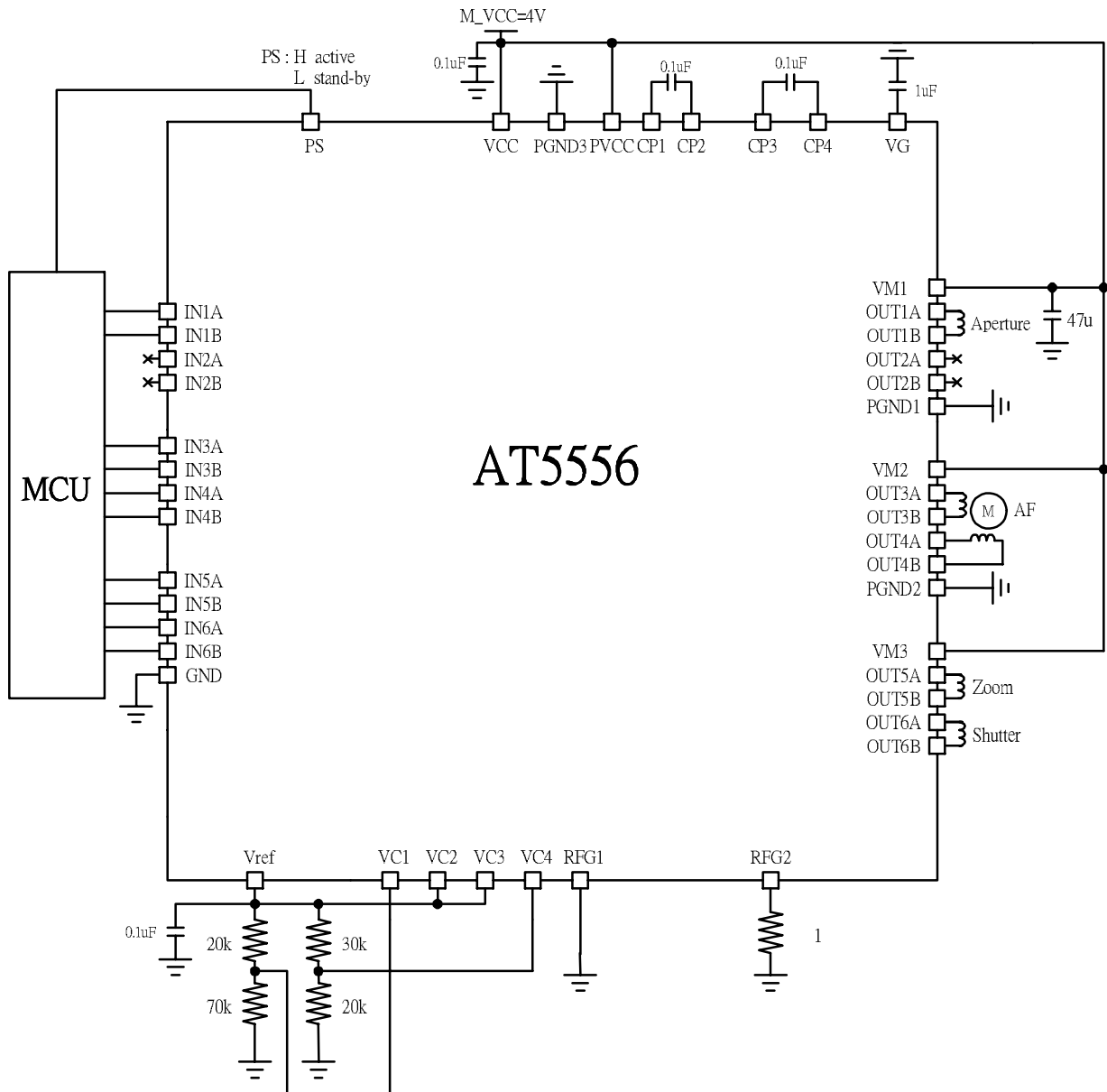
Constant voltage : CH1&CH2 $\rightarrow V_o = V_{C1} \times 5 - 0.5 \times R_{ON} \times I_o$

CH3&CH4 $\rightarrow V_o = V_{C2} \times 5 - 0.5 \times R_{ON} \times I_o$

Constant current : CH5 $\rightarrow I_o = V_{C3} / RFG1$

CH6 $\rightarrow I_o = V_{C4} / RFG2$

Application reference 3



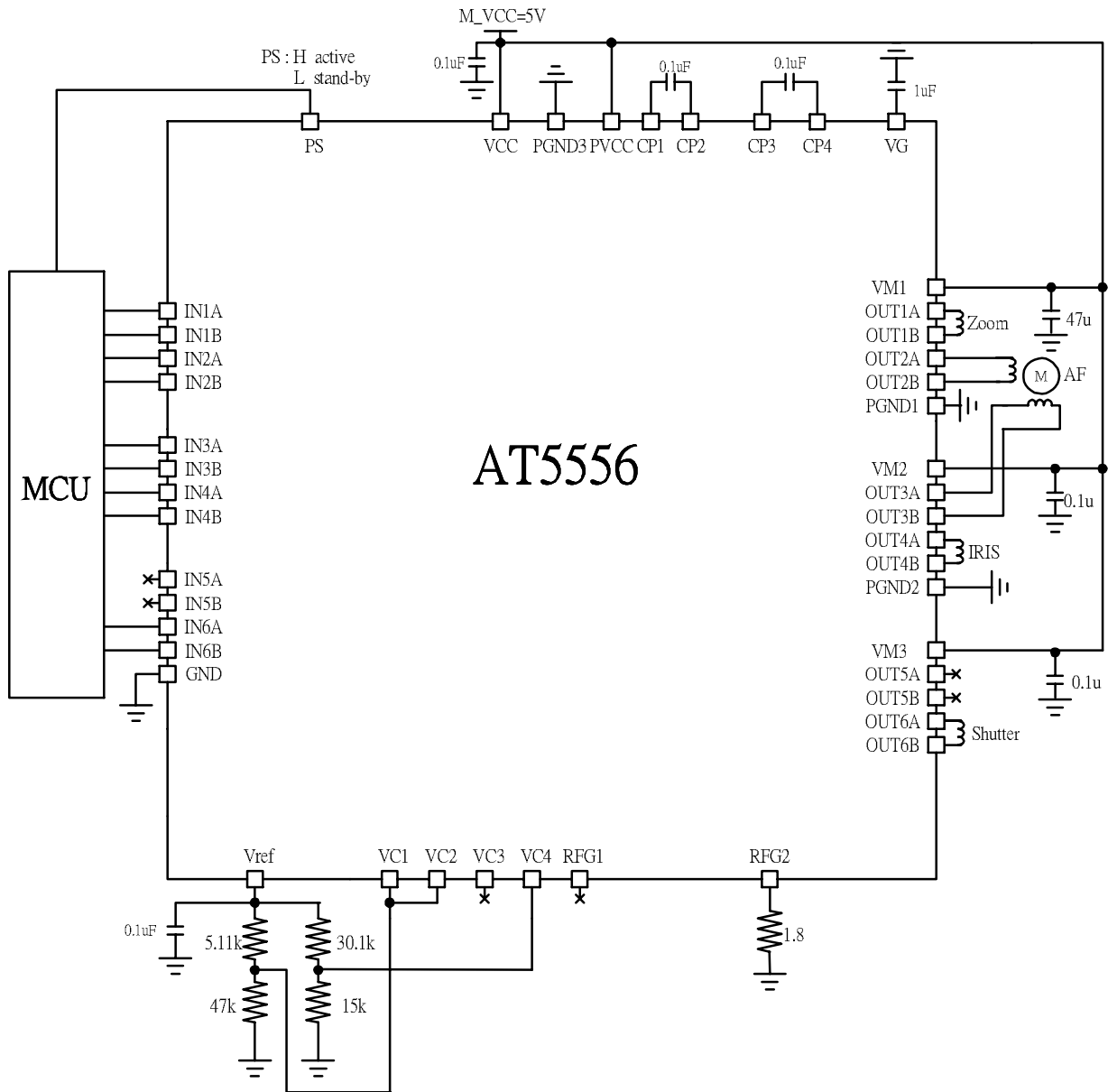
Output voltage of charge pump(three times PVCC) : $V_G = PVCC \times 3$

Constant voltage : CH1&CH2 $\rightarrow V_o = V_{C1} \times 5 - 0.5 \times R_{ON} \times I_o$

Saturation mode : CH3&CH4&CH5 $\rightarrow V_o = VM - R_{ON} \times I_o$

Constant current : CH6 $\rightarrow I_o = V_{C4} / RFG2$

Application reference 4



Output voltage of charge pump(three times PVCC) : $V_G = PVCC \times 3$

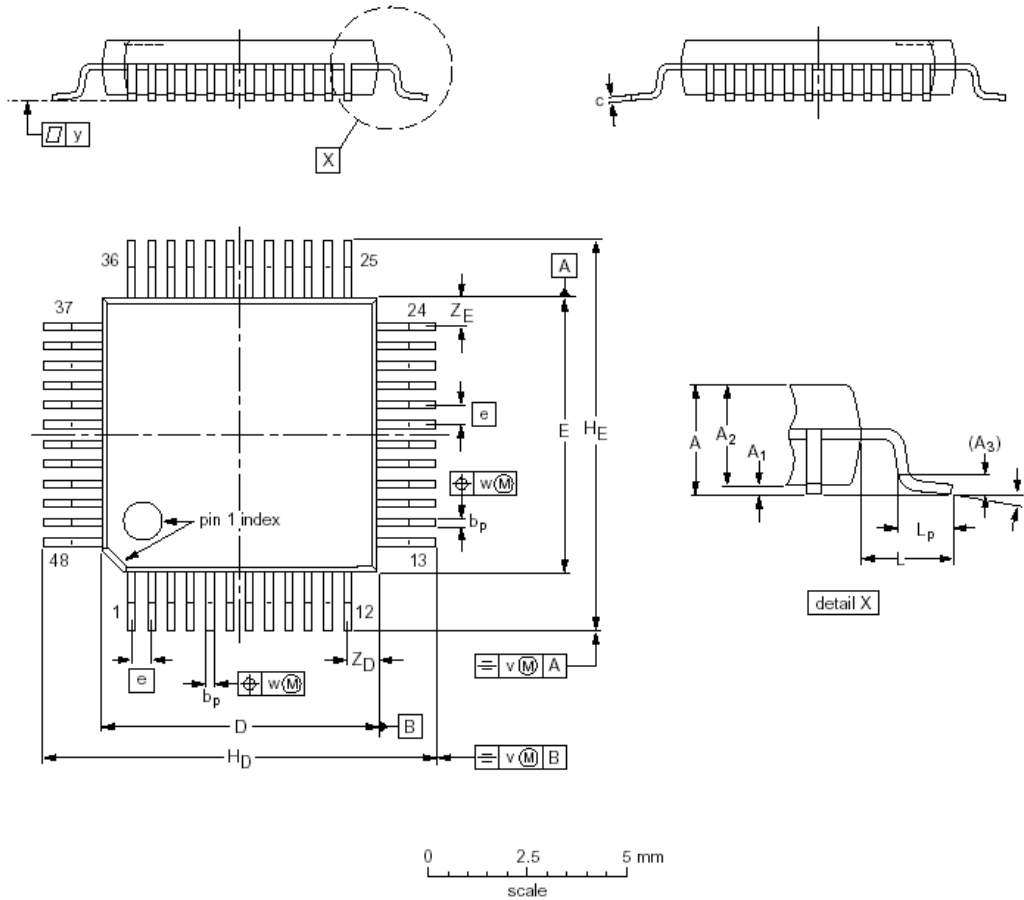
Constant voltage : CH1&CH2 $\rightarrow V_o = V_{C1} \times 5 - 0.5 \times R_{ON} \times I_o$

CH3&CH4 $\rightarrow V_o = V_{C2} \times 5 - 0.5 \times R_{ON} \times I_o$

Constant current : CH6 $\rightarrow I_o = V_{C4} / RFG2$

Package Description

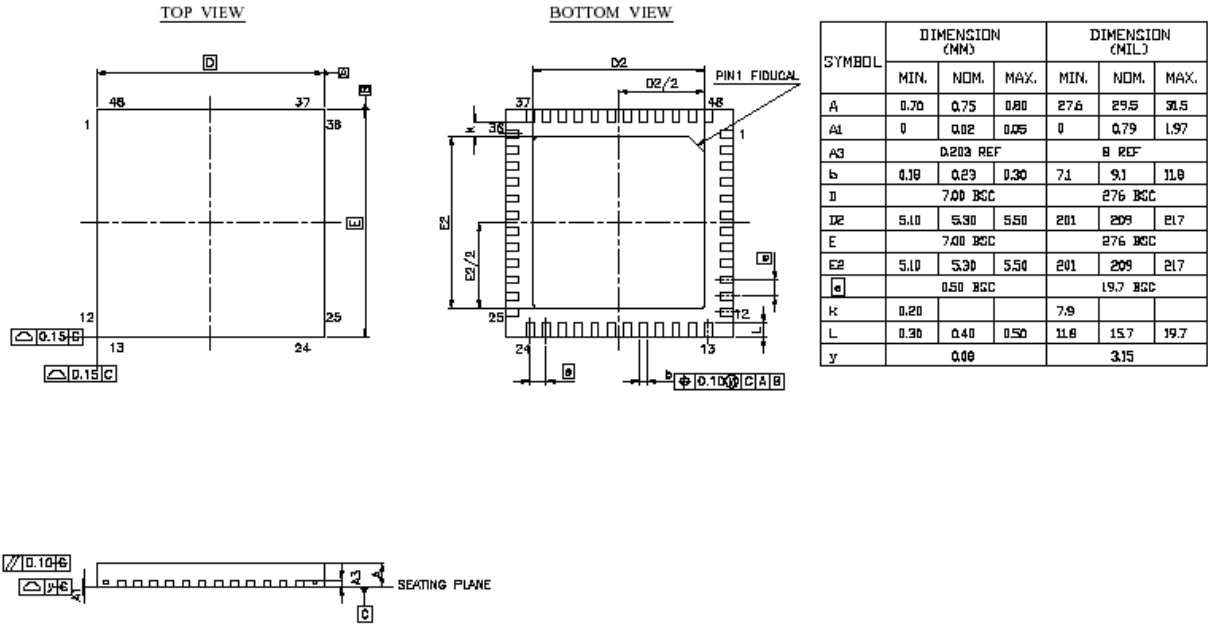
LQFP48



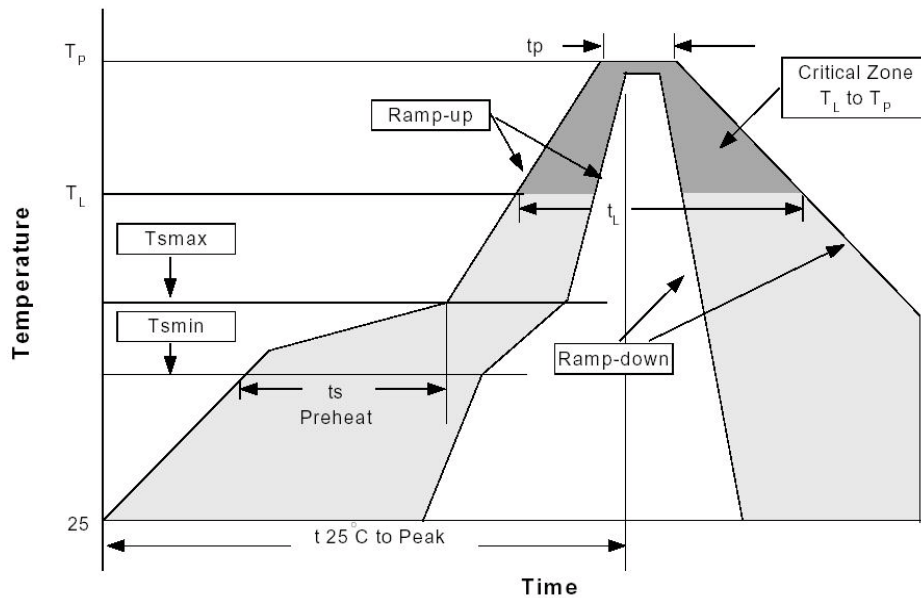
DIMENSIONS (mm are the original dimensions)

| UNIT | A max. | A ₁ | A ₂ | A ₃ | b _p | c | D ⁽¹⁾ | E ⁽¹⁾ | e | H _D | H _E | L | L _p | v | w | y | Z _D ⁽¹⁾ | Z _E ⁽¹⁾ | θ |
|------|-----------|----------------|----------------|----------------|----------------|--------------|------------------|------------------|-----|----------------|----------------|-----|----------------|-----|------|-----|-------------------------------|-------------------------------|----------|
| mm | 1.60 | 0.20 0.05 | 1.45 1.35 | 0.25 | 0.27 0.17 | 0.18 0.12 | 7.1 6.9 | 7.1 6.9 | 0.5 | 9.15 8.85 | 9.15 8.85 | 1.0 | 0.75 0.45 | 0.2 | 0.12 | 0.1 | 0.95 0.55 | 0.95 0.55 | 7° 0° |

QFN48



Reflow Profiles



| Profile Feature | Sn-Pb Eutectic Assembly | | Pb-Free Assembly | |
|---|---|---|--|---|
| | Large Body Pkg. thickness ≥2.5mm or Pkg. volume ≥350mm ³ | Small Body Pkg. thickness <2.5mm or Pkg. volume <350mm ³ | Large Body Pkg. thickness ≥2.5mm or Pkg. volume ≥350mm ³ | Small Body Pkg. thickness ≥2.5mm or Pkg. volume ≥350mm ³ |
| Average ramp-up rate (T _L to T _P) | 3°C/second max. | | 3°C/second max. | |
| Preheat -Temperature Min(T _{smin}) -Temperature Max (T _{smax}) -Time (min to max)(t _s) | 100°C 150°C 60-120 seconds | | 150°C 200°C 60-180 seconds | |
| T _{smax} to T _L -Ramp-up Rate | | | 3°C/second max. | |
| Time maintained above: -Temperature (T _L) -Time (t _L) | 183°C 60-150 seconds | | 217°C 60-150 seconds | |
| Peak Temperature(T _p) | 225+0/-5°C | 240+0/-5°C | 245+0/-5°C | 250+0/-5°C |
| Time within 5°C of actual Peak Temperature (t _p) | 10-30 seconds | 10-30 seconds | 10-30 seconds | 20-40 seconds |
| Ramp-down Rate | 6°C/second max. | | 3°C/second max. | |
| Time 25°C to Peak Temperature | 6 minutes max. | | 8 minutes max. | |

*All temperatures refer to topside of the package, measured on the package body surface.