

DC Brushless Motor Drivers for Cooling Fans **Two-Phase Half-Wave Pre Driver**

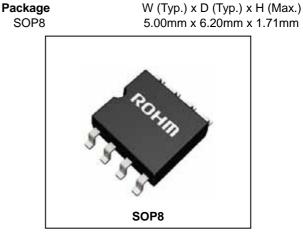
Fan Motor Driver

General description

BA6506F is two-phase half-wave fan motor pre-driver. This driver incorporates lock protection, automatic restart circuit and Rotation speed pulse signal (FG) output.

Features

- Pre-driver
- Incorporates lock protection and automatic restart circuit
- Rotation speed pulse signal (FG) output



Application

For desktop PC, server, general consumer equipment, communication equipment and industrial equipment.

Absolute maximum ratings

| Parameter | Symbol | Limit | Unit |
|---|--------|-------------------|------|
| Supply voltage | Vcc | 30 | V |
| Power dissipation | Pd | 624 ^{*1} | mW |
| Operating temperature range | Topr | -40 to +100 | °C |
| Storage temperature range | Tstg | -55 to +125 | °C |
| Output current | Iomax | 70 | mA |
| Rotation speed pulse signal (FG) output voltage | IFG | 8 | mA |
| Rotation speed pulse signal (FG) output current | VFG | 30 | V |
| Junction temperature | Tjmax | 125 | °C |

*1 Reduce by 6.24mW/°C over Ta=25°C. (On 70.0mm×70.0mm×1.6mm glass epoxy board)

Recommended operating conditions

| Parameter | Symbol | Limit | Unit |
|--------------------------------|--------|---------------|------|
| Operating supply voltage range | Vcc | 4.0 to 28.0 | V |
| Hall input voltage range | VH | 1.0 ~ Vcc-0.5 | V |

Pin configuration

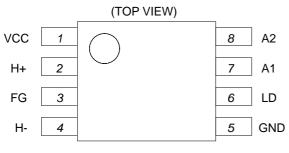


Fig.1 Pin configuration

| Pir | n descri | ption | | | |
|-----|----------|--------|--|--|--|
| | P/No. | T/Name | Function | | |
| | 1 | Vcc | Power terminal | | |
| | 2 | H+ | Hall input terminal + | | |
| | 3 | FG | Rotating speed pulse signal output terminal | | |
| | 4 | H- | Hall input terminal - | | |
| | 5 | GND | GND terminal | | |
| | 6 | LD | Lock detection and automatic restart capacitor connecting terminal | | |
| | 7 | A1 | Output terminal 1 | | |
| | 8 | A2 | Output terminal 2 | | |

Block diagram

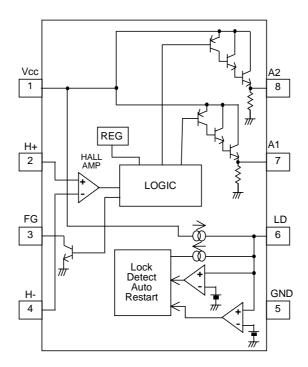


Fig.2 Block diagram

I/O truth table

| H+ | H- | A1 | A2 | FG H (Output Tr OFF) | |
|----|----|-------------------|-------------------|-------------------------|--|
| Н | L | H (Output Tr ON) | L (Output Tr OFF) | | |
| L | Н | L (Output Tr OFF) | H (Output Tr ON) | L (Output Tr ON) | |

H; High, L; Low, Hi-Z; High impedance

FG output is open-drain type.

Electrical characteristics(Unless otherwise specified Ta=25°C, Vcc=12V)

| Deveryoter | Ci una la al | Limit | | 1.1 | | |
|--|--------------|-------|------|------|------|---------------|
| Parameter | Symbol | Min. | Тур. | Max. | Unit | Conditions |
| Circuit current | lcc | - | 3.2 | 5.0 | mA | At output OFF |
| Hall input hysteresis | Vhys | ±3 | - | ±15 | mV | |
| FG output L voltage | VFG | - | - | 0.5 | V | IFG=5mA |
| FG current capacity | IFG | 8.0 | - | - | mA | VFG=2V |
| Charge current of capacitor for lock detection | ILDC | 2.0 | 3.45 | 5.25 | μA | VLD=1.5V |
| Discharge current of capacitor for lock detection | ILDD | 0.35 | 0.80 | 1.45 | μA | VLD=1.5V |
| Charge-discharge current ratio of capacitor for lock detection | rCD | 3 | 4.5 | 8 | - | rCD=ILDC/ILDD |
| Clamp voltage of capacitor for lock detection | VLDCL | 2.2 | 2.6 | 3.0 | V | |
| Comparison voltage of capacitor for lock detection | VLDCP | 0.4 | 0.6 | 0.8 | V | |
| Output H voltage | VOH | 10 | 10.5 | - | V | lo=10mA |

Typical performance curves(Reference data)

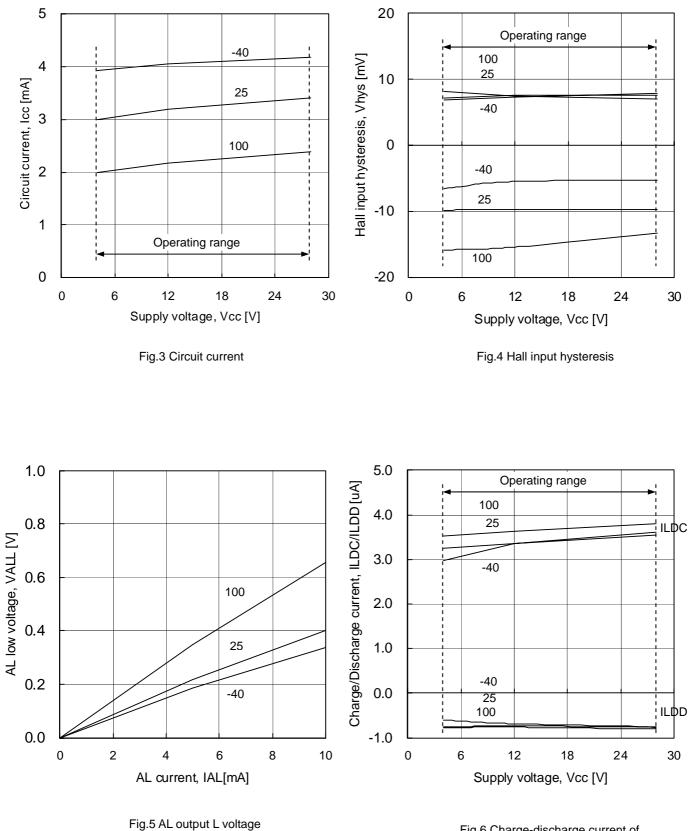


Fig.6 Charge-discharge current of capacitor for lock detection

Typical performance curves(Reference data)

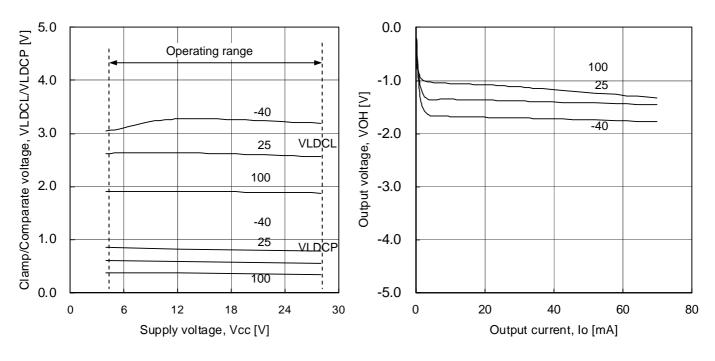


Fig.7 Clamp-comparison voltage of capacitor for lock detection Fig.8 Output H voltage

Application circuit example(Constant values are for reference)

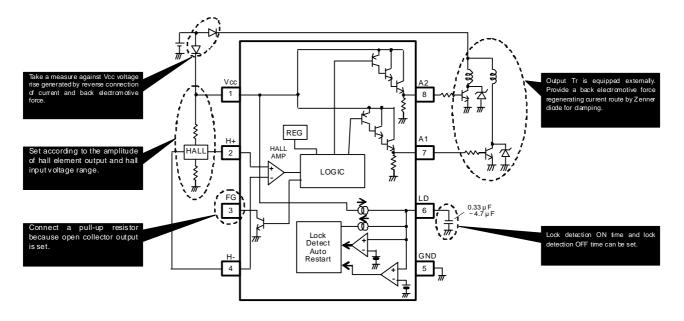


Fig.9 application circuit

Substrate design note

- a) IC power, motor outputs, and motor ground lines are made as fat as possible.
- b) IC ground (signal ground) line is common with the application ground except motor ground (i.e. hall ground etc.), and arranged near to (–) land.
- c) The bypass capacitor and/or Zenner diode are arrangement near to Vcc terminal.
- d) H+ and H– lines are arranged side by side and made from the hall element to IC as shorter as possible, because it is easy for the noise to influence the hall lines.

Description of operations

1) Lock protection and automatic restart

CR timer system

Charging and discharging time at LD terminal depends on the capacitor equipped externally on LD terminal. Charging and discharging time is determined as follows:

| TON(charging time) = | | $C \times (VLDCL-VLDCP)$ | |
|-------------------------------------|-------------------------------------|--|------|
| | | ILDC | |
| TOFF(discharging time)= | | C × (VLDCL-VLDCP) | |
| | | ILDD | |
| C VLDCL VLDCP ILDC ILDD | : LD term : LD term : LD term | y of capacitor equipped externally on LD term inal clamping voltage inal comparator voltage inal charging current inal discharging current | inal |

Timing chart of LD terminal is shown in Fig.10.

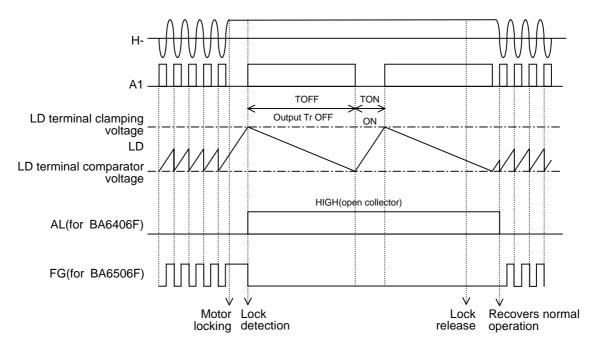


Fig.10 Lock protection (CR timer system) timing chart

Thermal derating curve

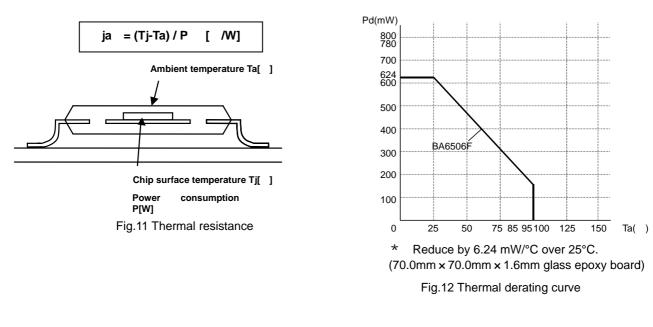
Power dissipation (total loss) indicates the power that can be consumed by IC at $Ta = 25^{\circ}C$ (normal temperature). IC is heated when it consumes power, and the temperature of IC chip becomes higher than ambient temperature. The temperature that can be accepted by IC chip depends on circuit configuration, manufacturing process, etc, and consumable power is limited. Power dissipation is determined by the temperature allowed in IC chip (maximum junction temperature) and thermal resistance of package (heat dissipation capability). The maximum junction temperature is in general equal to the maximum value in the storage temperature range.

Heat generated by consumed power of IC is radiated from the mold resin or lead frame of package. The parameter which indicates this heat dissipation capability (hardness of heat release) is called heat resistance, represented by the symbol θ_{ja} [/W]. The temperature of IC inside the package can be estimated by this heat resistance. Fig.11 shows the model of heat resistance of the package.

Heat resistance $\dot{\theta}_{ja}$, ambient temperature Ta, junction temperature Tj, and power consumption P can be calculated by the equation below:

Thermal derating curve indicates power that can be consumed by IC with reference to ambient temperature. Power that can be consumed by IC begins to attenuate at certain ambient temperature. This gradient is determined by thermal resistance θ_{ja} .

Thermal resistance θ depends on chip size, power consumption, package ambient temperature, packaging condition, wind velocity, etc., even when the same package is used. Thermal derating curve indicates a reference value measured at a specified condition. Fig.12 shows a thermal derating curve (Value when mounting FR4 glass epoxy board 70 [mm] x 70 [mm] x 1.6 [mm] (copper foil area below 3 [%]))

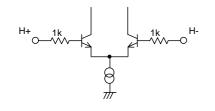


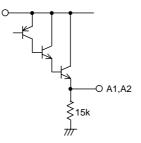
Equivalent circuit

1) Hall input terminal

2) Output terminal

3)FG signal output terminal







Safety measure

1) Reverse connection protection diode

Reverse connection of power results in IC destruction as shown in Fig 13. When reverse connection is possible, reverse connection protection diode must be added between power supply and Vcc.

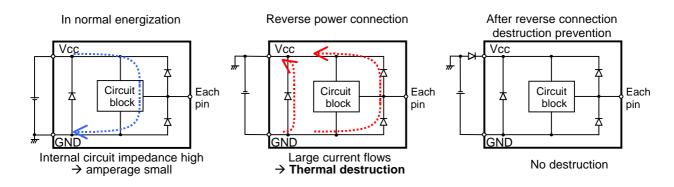


Fig.13 Current flow when power is connected reversely

2) About measures of voltage rise by back electromotive force

The voltage of output terminal rises by back electromotive force. The diode D1 of Fig.14 is necessary to divide a power supply line of motor with small signal line, so that the voltage of the output does not affect a power supply line.

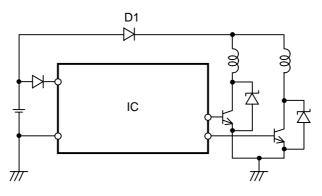


Fig.14 Separation of a power supply line

3) FG output

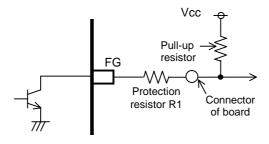


Fig.15 Protection of FG terminal

FG output is an open collector and requires pull-up resistor.

The IC can be protected by adding resistor R1. An excess of absolute maximum rating, when FG output terminal is directly connected to power supply, could damage the IC.

4) Problem of GND line PWM switching

Do not perform PWM switching of GND line because GND terminal potential cannot be kept to a minimum.

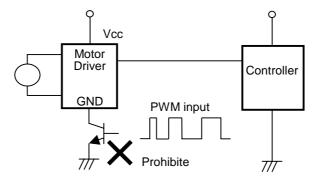


Fig.16 GND Line PWM switching prohibited

Operational Notes

1) Absolute maximum ratings

An excess in the absolute maximum rations, such as supply voltage, temperature range of operating conditions, etc., can break down the devices, thus making impossible to identify breaking mode, such as a short circuit or an open circuit. If any over rated values will expect to exceed the absolute maximum ratings, consider adding circuit protection devices, such as fuses.

2) Connecting the power supply connector backward

Connecting of the power supply in reverse polarity can damage IC. Take precautions when connecting the power supply lines. An external direction diode can be added

3) Power supply line

Back electromotive force causes regenerated current to power supply line, therefore take a measure such as placing a capacitor between power supply and GND for routing regenerated current. And fully ensure that the capacitor characteristics have no problem before determine a capacitor value. (when applying electrolytic capacitors, capacitance characteristic values are reduced at low temperatures)

4) GND potential

The potential of GND pin must be minimum potential in all operating conditions. Also ensure that all terminals except GND terminal do not fall below GND voltage including transient characteristics. However, it is possible that the motor output terminal may deflect below GND because of influence by back electromotive force of motor. Malfunction may possibly occur depending on use condition, environment, and property of individual motor. Please make fully confirmation that no problem is found on operation of IC.

5) Thermal design

Use a thermal design that allows for a sufficient margin in light of the power dissipation(Pd) in actual operating conditions

6) Inter-pin shorts and mounting errors

Use caution when positioning the IC for mounting on printed circuit boards. The IC may be damaged if there is any connection error or if pins are shorted together

7) Actions in strong electromagnetic field

Use caution when using the IC in the presence of a strong electromagnetic field as doing so may cause the IC to malfunction

8) ASO

When using the IC, set the output transistor so that it does not exceed absolute maximum rations or ASO

9) Testing on application boards

When testing the IC on an application board, connecting a capacitor to a pin with low impedance subjects the IC to stress. Always discharge capacitors after each process or step. Always turn the IC's power supply off before connecting it to or removing it from a jig or fixture during the inspection process. Ground the IC during assembly steps as an antistatic measure. Use similar precaution when transporting or storing the IC

10) GND wiring pattern

When using both small signal and large current GND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the ground potential of application so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern of any external components, either

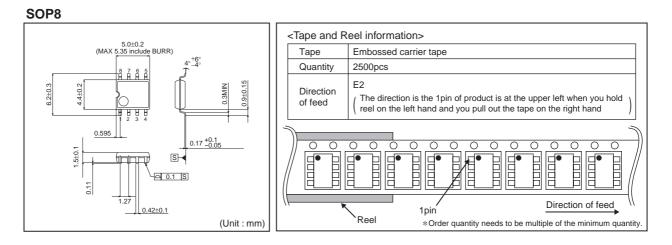
11) Capacitor between output and GND

When a large capacitor is connected between output and GND, if Vcc is shorted with 0V or GND for some cause, it is possible that the current charged in the capacitor may flow into the output resulting in destruction. Keep the capacitor between output and GND below 100uF

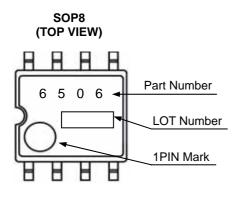
12) IC terminal input

When Vcc voltage is not applied to IC, do not apply voltage to each input terminal. When voltage above Vcc or below GND is applied to the input terminal, parasitic element is actuated due to the structure of IC. Operation of parasitic element causes mutual interference between circuits, resulting in malfunction as well as destruction in the last. Do not use in a manner where parasitic element is actuated

Physical dimension tape and reel information



Marking diagram



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