



VGA CMOS Image Sensor

BF3703 Datasheet

Revision History

Revised. Date	Revision	Brief Description	Author	Proofread	Authorize
2010-8-12	A/0	Initial release	Li Yaqian	Zhou Lei	Hu Wenge

1. General Description

The BF3703 is a highly integrated VGA camera chip which includes CMOS image sensor (CIS) and image signal processing function (ISP). It is fabricated with the world's most advanced CMOS image sensor process to realize ultra-low dark noise, high sensitivity and very low power imaging system. The sensor consists of a 653 x 493 effective pixel array which has an optical format of 1/10 inch. It has integrated noise canceling CDS (Correlated Double Sampling) circuits, analog global gain and separated R/G/B gain controller, auto black level compensation and on-chip 10-bit ADC. The on-chip ISP provides a very smooth AE (Auto Exposure) and accurate AWB (Auto White Balance) control. It provides various data formats, such as Bayer RGB, RGB444, RGB555, RGB565, YCBCR 4:2:2. It has a commonly used two-wire serial interface for host to control the operation of the whole sensor.

The product is capable of operating at up to 30 frames per second at 24MHz clock in VGA mode, with complete user control over image quality and data formatting. All required image processing functions, including exposure control, white balance control, color saturation control and so on, are also programmable through the two-wire serial bus.

2. Features

- Standard optical format of 1/10 inch.
- 30 frame/sec VGA mode @ 24MHz master clock.
- Ultra-low dark noise at high temperature.
- Various output formats: YCBCR4:2:2, RGB444, RGB555, RGB565, Raw Bayer(652 x 492).
- Power supply: 2.7~3.1V for core, 1.7~3.1V for I/O.
- Horizontal /Vertical mirror.
- 50/60Hz flicker cancellation.
- Programmable I/O drive capability.
- Automatic black level control.
- Image processing function: Lens Shading Correction, Gamma Correction, Bad pixel correction, Color Interpolation, False Color Suppression, Purple Fringe Correction, Low Pass Filter, Color Space Conversion, Color Correction, Edge Enhancement, Auto exposure, Auto White Balance, Color Saturation and Contrast, and Data Format Conversion.
- 12 types of special video effect
- On-chip test pattern generation of many types including customer programmable
- Package: CSP, Bare Die

3. Applications

- Cellular Phone Cameras
- Notebook and desktop PC cameras
- PDAs
- Toys
- Digital still cameras and camcorders
- Video telephony and conferencing equipments
- Security systems
- Industrial and environmental systems

4. Technical Specifications

- Active pixel array: 653 x 493
- Pixel size: 2.25 μ m \times 2.25 μ m
- Sensitivity: 1V/lux.s
- Dark current: 3 mV/S at 40 $^{\circ}$ C
- Power consumption: 56mW @ 30fps and single 2.8V supply
- Standby current: 30uA
- S/N Ratio: 35dB
- Dynamic range: 58dB
- Operating temperature: -20~60 $^{\circ}$ C
- Stable Image temperature 0~50 $^{\circ}$ C
- Optimal lens chief ray angle: 25 $^{\circ}$

5. Functional Overview

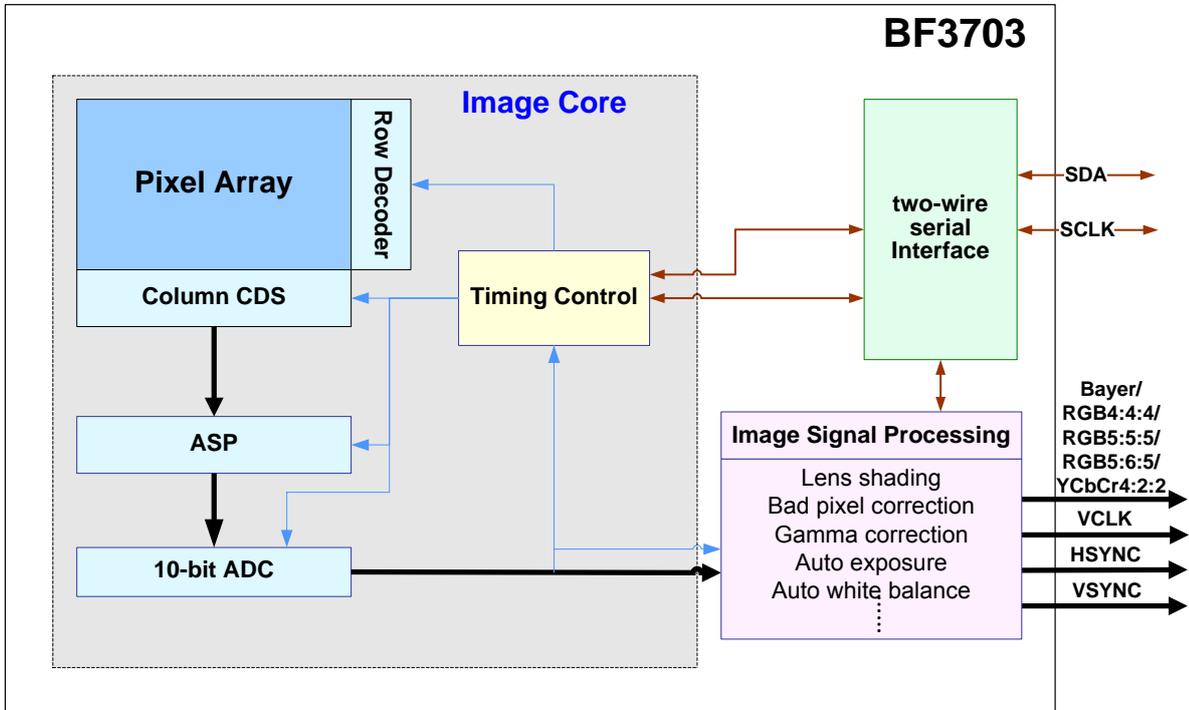


Figure 1. Block Diagram

BF3703 has an active image array of 653x493 pixels. The active pixels are read out progressively through column/row driver circuits. In order to reduce fixed pattern noise, CDS circuits are adopted. The ASP block is mainly used to control global gain and color gains to get accurate exposure and white balance under different light condition and color temperature. The analog signal is transferred to digital signal by A/D converter. The digital signals are processed in the ISP Block, including Bayer interpolation, low pass filter, color correction, gamma correction, data format conversion and so on. Users can easily control these functions via two-wire serial interface bus.

5.1 Pixel Array

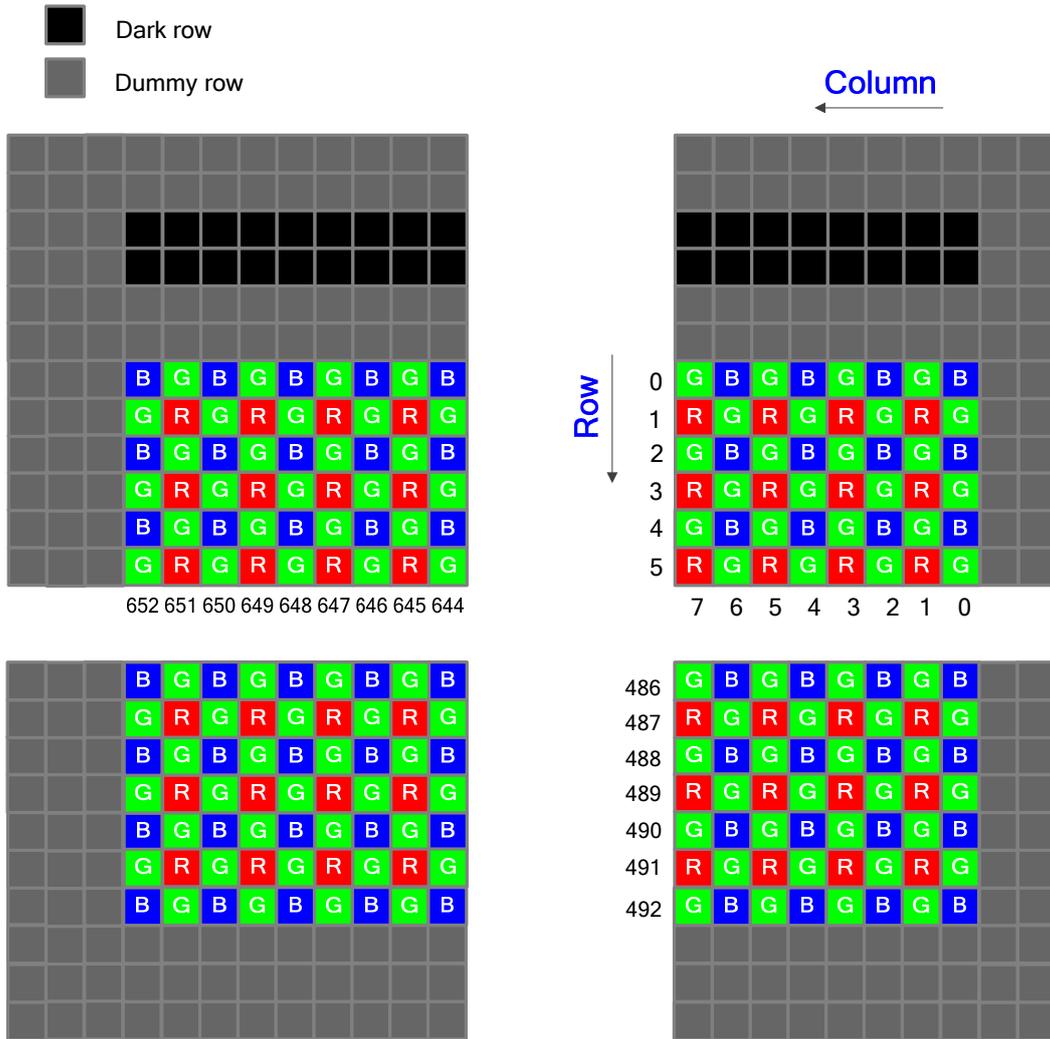


Figure 2. Sensor Array Region

The active pixel array is configured as 653 columns by 493 rows. Dummy pixels and dark rows are added outside the active pixel array.

Pixel array is covered by Bayer color filters as can be seen in the figure2. The primary color BG/GR array is arranged in line-alternating fashion. Since each pixel can have only one type of color filter on it, only one color component can be obtained by a pixel. BF3703 can provide the Raw Bayer data or YUV data through an 8-bit output data bus. If no flip in column, column is read out from 0 to 651. If flip in column, column is read out from 652 to 1. If no flip in row, row is read out from 0 to 491. If flip in row, row is read out from 492 to 1. In this way, the output pixel color order is always the same.

Pixel array output signal order is always:

BGBGBG.....

GRGRGR.....

5.2 Column CDS

BF3703 has column/row driver circuits to read out the pixel data progressively. The CDS (Correlated Double Sampling) circuit reduces temporal noise and pixel level FPN (Fixed Pattern Noise). The unique patented column buffer amplifier and ASP (Analog Signal Processing) circuit remove column level FPN caused by various sources of manufacturing process variations.

5.3 Timing controller

The timing controller controls the following functions

- Array control and frame generation
- Internal timing signal generation and distribution
- Frame rate timing
- External timing outputs (VSYNC, HREF and VCLK)

5.4 Analog Signal Processor

This block performs all analog image functions including Color gain/Global gain control and black level compensation. Each of the R, G, B color pixel signals can be multiplied by different gain factors to balance the color of the image at various light conditions.

5.5 A/D converter

The analog signals are converted to digital forms column by column and row by row, through out the whole array. BF3703 provides the 10-bit Raw Bayer data for ISP through an internal 10-bit data bus.

5.6 Automatic Black Control

The automatic black level controller calculates the data of the dark row and controls the lowest black level for output image data.

5.7 Image Signal Processor

This block performs all image processing functions including Lens Shading Correction, Gamma Correction, Bad pixel correction, Color Interpolation, False Color Suppression, Low Pass Filter, Color Space Conversion, Color Correction, Edge Enhancement, Auto exposure, Auto White Balance, Color Saturation, Contrast, and Data Format Conversion.

6. Specifications

6.1 Electrical Characteristics

6.1.1. Absolute Maximum Ratings

- Supply voltage (VDDIO): 1.7 ~ 3.1 V
- Supply voltage (VDD3A): 2.7 ~ 3.1 V
- Operating temperature: -20~60 °C
- Storage temperature: -30~80 °C
- ESD Rating, Human Body mode: 2000 V

Caution: Stresses exceeding the absolute maximum ratings may induce failure.

6.1.2. DC Parameters

Table 1. DC Operation Conditions

Symbol	Parameter	Unit	Min.	Typ.	Max.	Notes
VDDIO	I/O power supply	V	1.7	2.8	3.1	
VDD3A	Analog power supply	V	2.7	2.8	3.1	--
I_vddio	VDDIO supply current, normal operation mode	mA	--	10.0	--	1
I_vdd3a	VDD3A supply current, normal operation mode	mA	--	10.0	--	2
Vih	Input voltage logic "1"	V	0.7*VDDIO	--	--	--
Vil	Input voltage logic "0"	V	--	--	0.2*VDDIO	--
Voh	Output voltage logic "1"	V	0.9*VDDIO	--	--	--
Vol	Output voltage logic "0"	V	--	--	0.1*VDDIO	--

Note:

1. Because power consumption of I/O depends on the output load and system environment, user

should supply enough current to sensor for stable operation. It is measured when output load is floated.

2. Because current of analog circuit depends on the registers' values, it is measured at specific register's value.

6.1.3. Clock Requirement

Table 2. AC Operation Conditions

Symbol	Parameter	Unit	Min.	Typ.	Max.	Notes
MCLK	Main clock frequency	MHz	--	24	--	1
SCLK	two-wire serial interface clock frequency	KHz	--	400	--	2
Inormal	Current in YUV4:2:2 output mode	mA	--	20	--	3
Idown	Current in power down mode	uA	--	30	--	4

Note:

1. XCLK(external clock) may be divided by internal clock division logic to get MCLK for easy integration with high speed video codec system.
2. SCLK is driven by host processor. For the detail serial bus timing, refer to two-wire serial interface section
3. VDDIO=2.8V, VDD3A=2.8V(YUV4:2:2 output).
4. Hardware power down.

6.2 Electro-Optical Characteristics

Clock frequency: 24MHz.

Operating voltage: VDDIO=2.8V, VDD3A=2.8V.

Operating temperature: 25°C

Table 3. Electro-Optical Characteristics

Parameter	Unit	Min.	Typ.	Max.	Notes
Sensitivity	V/Lux·sec	--	1		1
Dark current	mV/sec	--	3	6	2
S/N ratio	dB	--	35dB	--	--
Dynamic Range	dB	--	58dB	--	--
Frame Rate	fps	--	--	30	3

Notes:

1. With color filter, measured at 50 lux green light condition at room temperature.
2. Measured at dark condition for exposure time of 1s (40 Celsius).
3. With 652×492 window size at MCLK 24MHz.

6.3 Input-Output AC Characteristics

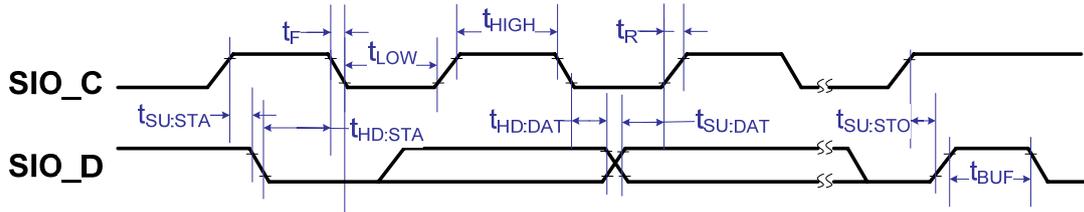


Figure 3. Two-Wire Serial Interface Timing

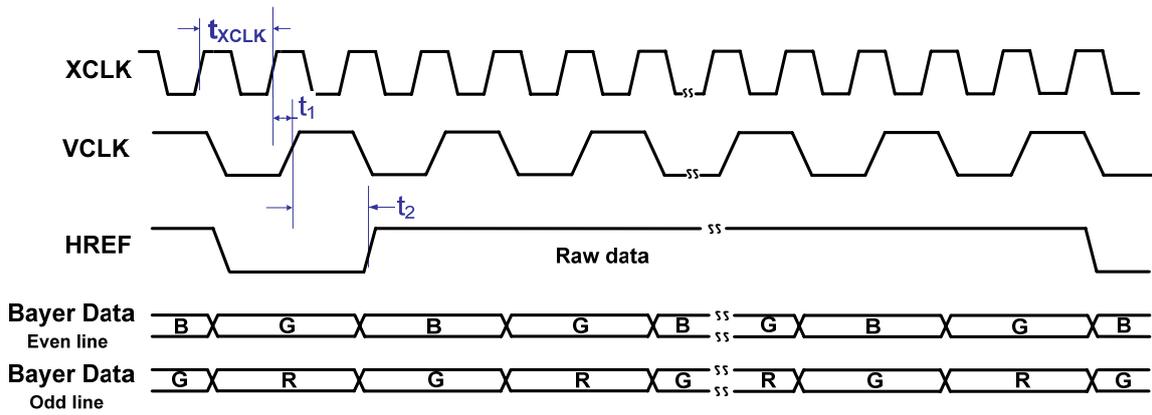


Figure 4. Horizontal Timing Raw Bayer Data

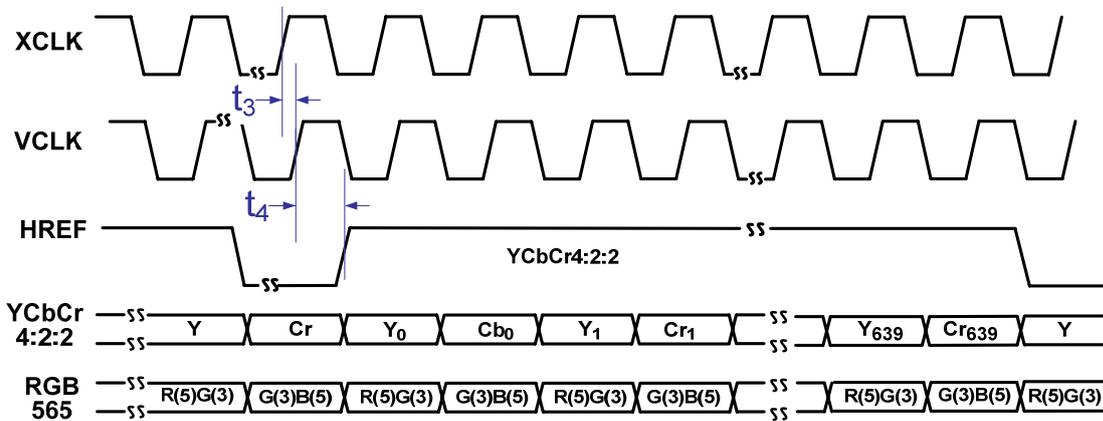


Figure 5. Horizontal Timing YUV4:2:2

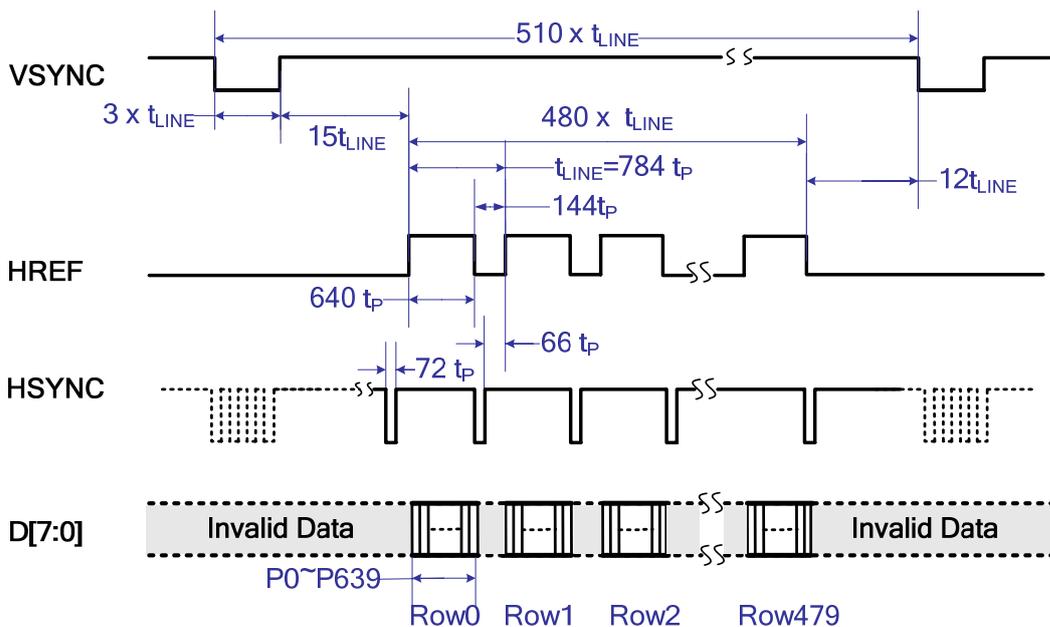


Figure 6. VGA Frame Timing

Table 4. AC Characteristics

Symbol	Descriptions	Min.	Typ.	Max.	Unit
t _P	t _P =2 x t _{MCLK}	--	83.2	--	ns
f _{MCLK}	Master Clock Frequency	--	24	--	MHz
f _{VCLK}	Video Clock Frequency for Raw data , f _v = f _{MCLK} /2 for YUV/RGB , f _v = f _{MCLK}	--	12/24	--	MHz
t _{LINE}	Line length	--	784x t _P	--	ns
t _R , t _F	two-wire serial interface rise/fall times	--	--	300	ns
t _{LOW}	Clock Low Period	1.3	--	--	us
t _{HIGH}	Clock High Period	600	--	--	ns
t _{HD:STA}	Start condition Hold Time	600	--	--	ns
t _{SU:STA}	Start condition Setup Time	600	--	--	ns
t _{HD:DAT}	Data-in Hold Time	0	--	--	ns
t _{SU:DAT}	Data-in Setup Time	100	--	--	ns
t _{SU:STO}	Stop condition Setup Time	600	--	--	ns
t ₁	XCLK rising to VCLK (RAW DATA)	--	28.8	--	ns
t ₂	VCLK rising to HREF (RAW DATA)	--	43.8	--	ns
t ₃	XCLK rising to VCLK (YUV)	--	19.2	--	ns
t ₄	VCLK rising to HREF (YUV)	--	21.6	--	ns

6.4 Color Filter Spectral Characteristics

The optical spectrum of color filters is shown below.

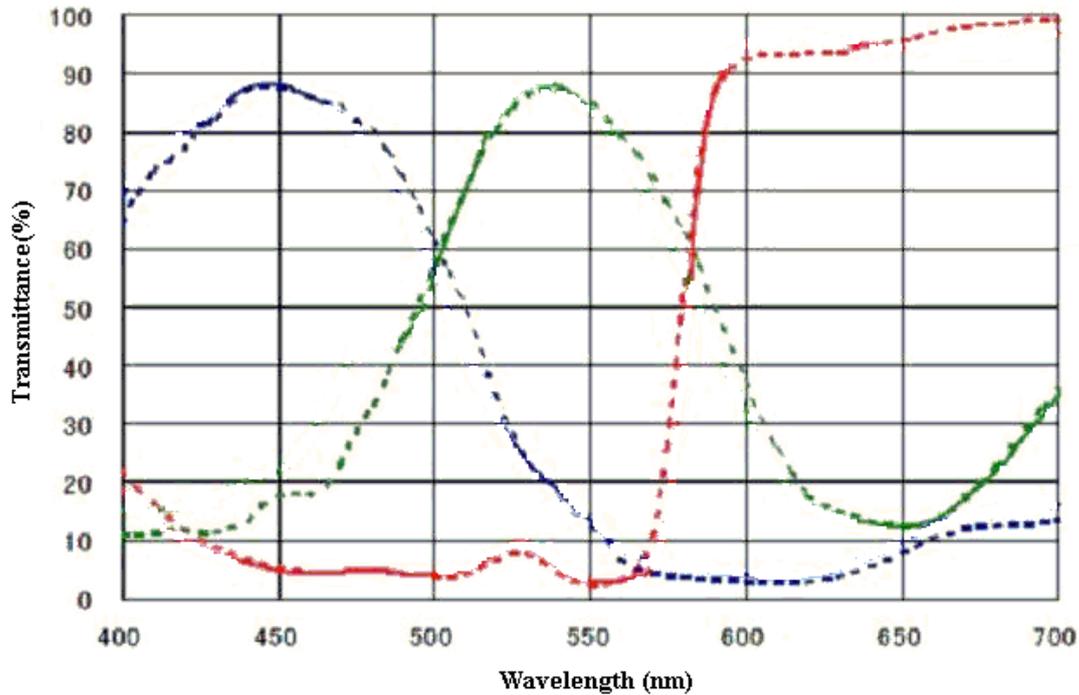


Figure 7. Spectral Characteristics

7. Two-wire serial interface & Register

7.1 Theory of Operation

The registers of BF3703 are written and read through the two-wire serial interface. BF3703 has two-wire serial interface slave. BF3703 is controlled by the two-wire serial interface clock (SCLK), which is driven by the two-wire serial interface master. Data is transferred into and out of BF3703 through the two-wire serial interface data (SDA) line. The SCL and SDA lines are pulled up to VDD by a 2kΩ off-chip resistor. Either the slave or the master device can pull the lines down. The two-wire serial interface protocol determines which device is allowed to pull the two lines down at any given time.

Note: Two-wire serial interface device address of BF3703 is 6eh.

Start bit

The start bit is defined as a HIGH to LOW transition of the data line while the clock line is HIGH.

Stop bit

The stop bit is defined as a LOW to HIGH transition of the data line while the clock line is HIGH.

Slave Address

The 8-bit address of a two-wire serial interface device consists of 7 bits of address and 1 bit of direction. A “0” in the LSB of the address indicates write mode, and “1” indicates read-mode.

Data bit transfer

One data bit is transferred during each clock pulse. The two-wire serial interface clock pulse is provided by the master. The data must be stable during the HIGH period of the two-wire serial interface clock: it can only change when the two-wire serial interface clock is LOW. Data is transferred 8 bits at a time, followed by an acknowledge bit.

Acknowledge bit

The receiver generates the acknowledge clock pulse. The transmitter (which is the master when writing, or the slave when reading) releases the data line, and receiver indicates an acknowledge bit by pulling the data line low during the acknowledge clock pulse.

No-acknowledge bit

The no-acknowledge bit is generated when the data line is not pulled down by the receiver during the acknowledge clock pulse. A no-acknowledge bit is used to terminate a read sequence.

Sequence

A typical read or write sequence begins by the master sending a start bit. After start bit, the master sends the slave device’s 8-bit address. The last bit of the address determines if the request will be a read or a write, where “0” indicates write and “1” indicates read. The slave device acknowledges its address by sending an acknowledge bit back to the master.

If the request was a write, the master then transfers the 8-bit register address to which a write should take place. The slave sends an acknowledge bit to indicate that the register address has been received. The master then transfers the data 8 bits at a time, with the slave sending an acknowledge bit after each 8 bits. The BF3703 uses 8 bit data for its internal registers, thus requiring one 8-bit transfer to write to one register. After 8 bits are transferred, the register address is automatically incremented, so that the next 8 bits are written to the next register address. The master stops writing by sending a start or stop bit.

A typical read sequence is executed as follows. First the master sends the write-mode slave address and 8-bit register address just as in the write request. The master then sends a start bit and the read-mode slave address. The master then clocks out the register data 8 bits at a time. The master

sends an acknowledge bit after each 8-bit transfer. The register address is auto-incremented after each 8 bit is transferred. The data transfer is stopped when the master sends a no-acknowledge bit.

7.2 Two-wire Serial Interface Functional Description

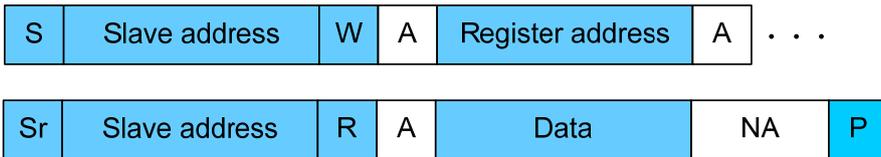
Single Write Mode Operation



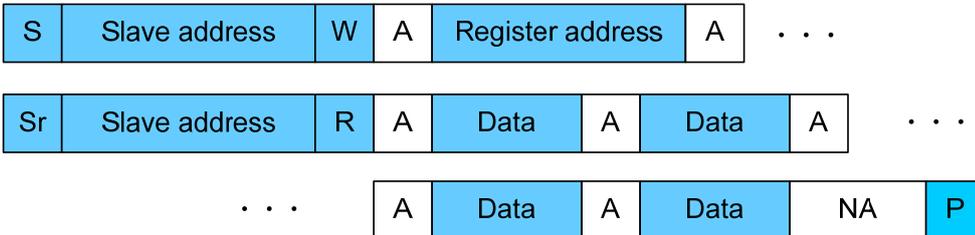
Multiple Write Mode (Register address is increased automatically)¹ operation



Single Read Mode Operation



Multiple Read Mode (Register address is increased automatically)¹ Operation



S: Start condition. **Sr:** Repeated Start (Start without preceding stop.)

Slave Address: write address = DCh = 11011100b
 read address = DDh = 11011101b

R/W: Read/Write selection. High = read, LOW = write.

A: Acknowledge bit. **NA:** No Acknowledge.

Data: 8-bit data **P:** Stop condition

Note1: Continuous writing or reading without any interrupt increases the register address automatically. If the address is increased above valid register address range, further writing does not affect the

chip operation in write mode. Data from invalid registers are undefined in read mode.

7.3 Register Summary (full list)

Table 5. BF3703 all registers

Address	Name	Width	Default value	Description
00h	<i>DBLKHE</i>	6	20h	Reserved.
01h	<i>BLUE_GAIN</i>	6	19h	Blue gain register.
02h	<i>RED_GAIN</i>	6	15h	Red gain register.
03h	<i>VHREF</i>	8	00h	VREF and HREF control. Bit[7:6]: VREF end low 2 Bits(high 8 Bit at <i>VSTOP[7:0]</i>) Bit[5:4]: VREF start low 2 Bits(high 8 Bit at <i>VSTART[7:0]</i>) Bit[3:2]: HREF end 2 LSB(high 8 MSB at register <i>HSTOP</i>) Bit[1:0]: HREF start 2 LSB(high 8 MSB at register <i>HSTART</i>)
05h	<i>LOFFN1E</i>	6	1eh	Coarse negative offset control-even column.
06h	<i>LOFFN0</i>	8	e0h	Bit[7]: Two wire serial interface switch. Bit[6]: Reserved. Bit[5:0]: Fine negative offset control col.
08h	<i>TAREG3</i>	8	00h	Reserved.
09h	<i>COM2</i>	8	10h	Common control 2. When <i>0x20[6]=0</i> , Bit[1:0]: Data & clk & hsync output drive capability. 00: 1x, 01: 2x, 10: 3x, 11: 4x. When <i>0x20[6]=1</i> , Bit[7:6]: Vclk output drive capability. 00: 1x, 01: 2x, 10: 3x, 11: 4x. Bit[5]: Spare. Bit[4]: Standby mode. 0: Disable standby mode. 1: Enable standby mode. Bit[3:2]: Hsync output drive capability. 00: 1x, 01: 2x, 10: 3x, 11: 4x. Bit[1:0]: Data output drive capability. 00: 1x, 01: 2x, 10: 3x, 11: 4x.
0ah	<i>COM5</i>	8	21h	Common control 5. Bit[7:4]: Total column number1 for gate subsample. Bit[3:0]: Column select number1 for gate subsample.
0bh	<i>COM4</i>	8	00h	Common control 4. Bit[7]: 0: Select even row, 1: Select odd row. Bit[6]: 0: Select even column, 1: Select odd column. Bit[5:4]: 0x:Output normal HSYNC/VSYNC. 10: HSYNC=0,VSYNC=0. 11: HSYNC=1,VSYNC=1. Bit[3:0]: Skip frame counter.



0ch	COM3	8	00h	<p>Common control 3.</p> <p>Bit[7]: PROCSS RAW selection, 0: Process raw from YCBCR to RGB conversion in data format, 1: Process raw from color interpolation(deniose, gamma, lsc is selectable),</p> <p>Bit[6]:Output data MSB and LSB swap,</p> <p>Bit[5:4]: PROCESS RAW sequence(when 0x0c[7]=0), 00: (LINE0:BGGB/LINE1:GRGR), 01: (LINE0:GBGB/LINE1:RGRG), 10: (LINE0:GRGR/LINE1:BGGB), 11: (LINE0:RGRG/LINE1:GBGB).</p> <p>Bit[3]: 0:no HREF when VSYNC_DAT=0, 1:Always has HREF no matter VSYNC_DAT=0 or not,</p> <p>Bit[2]: DATA ahead 1 clk(YUV MCLK, RawData PCLK) or not,</p> <p>Bit[1]: HREF ahead 1 clk(YUV MCLK, RawData PCLK) or not,</p> <p>Bit[0]: HREF ahead 0.5 clk(YUV MCLK, RawData PCLK) or not, 0x0c[1:0]: 00:HREF and data is synchronous, 01:HREF before data 0.5 clk, 10:HREF before data 1 clk, 11:HREF before data 1.5 clk.</p>
0dh	DBLKLE	6	20h	Reserved.
0eh	DBLKHO	6	20h	Reserved.
0fh	DBLKLO	6	20h	Reserved.
10h	COM6	8	21h	<p>Common control 6.</p> <p>Bit[7:4]: Total row number1 for gate subsample.</p> <p>Bit[3:0]: Row select number1 for gate subsample.</p>
11h	CLKRC	8	80h	<p>Mclk division control.</p> <p>Bit[7]: Double Clock Option. 0:Disable double clock option, Meaning the maximum MCLK can be as high as half input clock. 1:Enable double clock option, Meaning the maximum MCLK can be as high as input clock.</p> <p>Bit[6]: Use external clock directly($F(\text{internal clock})=F(\text{input clock})$).</p> <p>Bit[5:4]: Mclk divider factor 00: Divided by 1, 01: Divided by 2, 10: Digital power down, 11: Divided by4.</p> <p>Bit[3:2]: Pclk control. 0: Normal, 1: Inverse and dly 1.5ns, 2: Inverse and dly 3ns, 3: Inverse and dly 5.5ns.</p> <p>Bit[1]: Spare.</p> <p>Bit[0]: Doubler clock selection. 0: Mclk, 1: Mclk/2.</p>



12h	COM7	8	00h	<p>Common control 7.</p> <p>Bit[7]: SCCB Register Reset. 0: No change, 1: Resets all registers to default values.</p> <p>Bit[6]: Reserved.</p> <p>Bit[5]: Row subsample Selection. 0: Enable, 1: Disable.</p> <p>Bit[4]: 1/2 digital subsample Selection(only for YUV422/RGB565/RGB555/RGB444 output).</p> <p>Bit[3]: Reserved.</p> <p>Bit[2]: YUV422/RGB565/RGB555/RGB444 Selection.</p> <p>Bit[1]: Reserved.</p> <p>Bit[0]: Raw RGB Selection. {0x12[2],0x12[0]} 00: YUV422, 01: Bayer RAW, 10: RGB565/RGB555/RGB444(use with 0x3a), 11: Process RAW(use with 0x0c[7]).</p>
13h	COM8	8	07h	<p>Common control 8.</p> <p>Bit[7:4]: Reserved.</p> <p>Bit[3]: Select when to use small steps to adjust the integration time. 0: When <i>INT_TIM</i> lower than 10ms, 1: When <i>INT_TIM</i> lower than 20ms.</p> <p>Bit[2]: AGC Enable. 0:OFF , 1: ON.</p> <p>Bit[1]: AWB Enable. 0:OFF , 1: ON.</p> <p>Bit[0]: AEC Enable. 0:OFF , 1: ON.</p>
14h	LOFFN10	6	1eh	Coarse negative offset control-odd col.
15h	COM10	8	02h	<p>Common control 10.</p> <p>Bit[7]: Reserved.</p> <p>Bit[6]: 0:HREF, 1:HSYNC.</p> <p>Bit[5]: 0:VSYNC_IMAGE, 1:VSYNC_DAT.</p> <p>Bit[4]: VCLK reverse</p> <p>Bit[3]: HREF option. 0: Active high, 1: Active low.</p> <p>Bit[2]: Reserved</p> <p>Bit[1]: VSYNC option. 0: Active low, 1: Active high.</p> <p>Bit[0]: HSYNC option. 0: Active high, 1: Active low.</p>
16h	BIAS2	8	09h	Reserved.
17h	HSTART	8	00h	Output Format-Horizontal Frame(HREF column)start high 8-Bit(low 2Bits are at <i>VHREF[1:0]</i>)
18h	HSTOP	8	a0h	Output Format-Horizontal Frame(HREF column)end high 8-Bit(low 2 Bits are at <i>VHREF[3:2]</i>)
19h	VSTART	8	00h	Output Format-Vertical Frame(row)start high 8-Bit(low 2 Bits are at <i>VHREF[5:4]</i>)
1ah	VSTOP	8	78h	Output Format-Vertical Frame(row)end high 8-Bit(low 2 Bits are at <i>VHREF[7:6]</i>)
1bh	PLLCTL	8	80h	<p>PLL control.</p> <p>Bit[7]: PLL pdn Enable. 0: Enable, 1: Disable.</p> <p>Bit[6:4]: Spare.</p> <p>Bit[3:2]: Loop divide, default11 (Divided by 3). 00: Divided by 4, 01: Divided by 1, 10: Divided by 2, 11: Divided by 3.</p> <p>Bit[1:0]: Output divide, default 11 (Divided by 24). 00: Divided by 1, 01: Divided by 6, 10: Divided by 12, 11: Divided by 24.</p>
1ch	MIDH	8	7fh,RO	Reserved.
1dh	MIDL	8	a2h,RO	Reserved.



1eh	MVFP	8	00h	Mirror/Vflip Enable. Bit[7:6]:Reserved Bit[5]: Mirror. 0: Normal image, 1: Mirror image. Bit[4]: Vflip enable. 0: Normal image, 1: Vertically flip. Bit[3:0]: Reserved
1fh	DBLK_TARG	8	20h	Black control target for G. Bit[7:0]: Black control target for G. Bit[6:0]: Reserved.
20h	TDREG	8	00h	Bit[7]: Reserved. Bit[6]: Hsync&clk pad drive capability control. 0: Same drive capability, 1: Drive capability adjustment independently. (refer to register COM2) Bit[5:0]: Reserved.
21h	Reserved.			
22h	DBLK_TARR	8	20h	Black control target for R. Bit[7:0]:Black control target for R. Bit[6:0]: Reserved.
23h	GLGAINREG	7	33h	GreenGain[2:0]: Bit[6:4]: For even column (used as GreenEgain[2:0]). Bit[2:0]: For odd column (used as GreenOgain[2:0]).
24h	AE_LOCK1	8	8Ah	Y target value 1.
25h	AE_LOCK2	8	7Ah	Y target value 2.
26h	DBLK_TARB	8	20h	Black control target for B, Bit[6:0]:Black control target for B.
27h	STEP	8	04h	Bit[7:6]: Coarse adjustment range, 00: 4, 01: 8, 10: 12, 11: 16. Bit[5:0]: Step.
28h	DBLK_CNTL	8	00h	Reserved.
29h	BIAS1	8	04h	BIAS control 1. Bit[7]: Black control fine adjustment resolution control for even column. Bit[6]: Black control coarse adjustment resolution control for even column. Bit[5]: Black control fine adjustment resolution control for odd column. Bit[4]: Black control coarse adjustment resolution control for odd column. Bit[3]: Spare. Bit[2:0] ADC bias setting. 0d: Lower bias, 15d: Higher bias.
2ah	EXHCH	8	00h	Dummy Pixel Insert MSB. Bit[7:4]: Dummy Pixel Insert MSB. Bit[3:0]: Reserved.
2bh	EXHCL	8	00h	Dummy Pixel Insert LSB. Bit[7:0]: Dummy Pixel Insert LSB.
2dh	INT_TIMH	8	06h	Integration time MSB.
2eh	INT_TIML	8	66h	Integration time LSB.
2fh	DREF	8	e2h	Reserved.
30h	HSYST	8	64h	Control the rising edged of HSYNC, HSYNC rising edge low 8 Bits.
31h	HSYEN	8	14h	Control the falling edged of HSYNC, HSYNC falling edge low 8 Bits.
32h	LS_MODE	8	1fh	Bit[7:5]: Reserved, Bit[4]: Light sensor control. 0: Disable, 1: Enable. Bit[3:0]: Reserved.
33h	OFFSET_MODE	8	00h	Lens shading offset selection: Bit[7]: 0: Use black average value(from Black Control function) as offset 1: Use register OFFSET_REG as offset Bit[6:0]: Reserved.
34h	OFFSET_REG	8	38h	Lens shading offset.
35h	R_COEF	8	46h	Lens shading gain of R.



36h	Y0H_G, Y0H_B, X0H_G, X0H_B	6	05h	Bit[5]: Y0H_G. Center row coordinate HSB of G channel. Bit[4]: Y0H_B. Center row coordinate HSB of B channel. Bit[3:2]: X0H_G. Center col coordinate HSB of G channel. Bit[1:0]: X0H_B. Center col coordinate HSB of B channel.
37h	Y0L_B	8	f6h	Reserved.
38h	X0L_B	8	46h	Reserved.
39h	OFFSET2	8	80h	Gamma Offset 2: Bit[7]: 0: Positive , 1: Negative Bit[6:0]: Value.
3ah	TSLB	8	00h	Data output sequence. If YUV422 is selected. The Sequence is: Bit[1:0]: Output YUV422 Sequence 00: YUYV, 01: YVYU 10: UYVY, 11: VYUY If RGB565/RGB555/RGB444 is selected. The Sequence is: Bit[4:0]: Output RGB565/RGB555/RGB444 Sequence RGB565: 00h: R5G3H, G3LB5, 01h: B5G3H, G3LR5. 02h: B5R3H, R2LG6, 03h: R5B3H, B2LG6. 04h: G3HB5, R5G3L, 05h: G3LB5, R5G3H. 06h: G3HR5, B5G3L, 07h: G3LR5, B5G3H. 08h: G6B2H, B3LR5, 09h: G6R2H, R3LB5. RGB555: 0Ah: 1'b0R5G2H, G3LB5, 0Bh: G3LB5, 1'b0R5G2H. 0Ch: R5G3H, G2LB51'b0, 0Dh: G2LB51'b0, R5G3H. 0Eh: B5G3H, G2L1'b0, R5, 0Fh: R5G3H, G2L1'b0, B5. 10h: B51'b0G2H, G3LR5, 11h: R51'b0G2H, G3LB5. RGB444: 12h: 4'b0R4, G4B4, 13h: G4B4, 4'b0R4. 14h: 4'b0B4, G4R4, 15h: G4R4, 4'b0B4. 16h: R4G4, B44'b0, 17h: B44'b0, R4G4. 18h: B4G4, R44'b0, 19h: R44'b0, B4G4. 1Ah: B4G4, R4B4, 1Bh: R4G4, B4R4. 1Ch: R4G2H2'b0, G2LB42'b0, 1Dh: B4G2H2'b0, G2LR42'b0. 1Eh: B41'b0G3H, G1L2'b0R41'b0, 1Fh: R41'b0G3H, G1L2'b0B41'b0.
3bh	Y_AVER_TH	7	60h	Reserved.
3ch	OFFSET_TH2	7	24h	Reserved.
3dh	COM11	8	59h	Common control 11. Bit[7:4]: Total row number2 for gate sub. Bit[3:0]: Total column number2 for gate sub.
3eh	TAREG2	8	03h	Bit[7]: Tri-state option for output clock, HSYNC, VSYNC at power-down period. 0: Tri-state at this period, 1: No Tri-state at this period. Bit[6]: Tri-state option for output data OEN at power-down period. 0: Tri-state at this period, 1: No Tri-state at this period. Bit[5:0]: Reserved.
3fh	OFFSET1	8	9ah	Gamma Offset 1. Bit[7]: 0: Use black average value(from Black Control function) as offset. 1: Use register OFFSET1[6:0] as offset. Bit[6:0]: OFFSET1 value.
40h	k0	8	50h	Gamma Correction Slop Coefficient 0.
41h	k1	8	50h	Gamma Correction Slop Coefficient 1.
42h	k2	8	58h	Gamma Correction Slop Coefficient 2.
43h	k3	8	55h	Gamma Correction Slop Coefficient 3.
44h	k4	8	50h	Gamma Correction Slop Coefficient 4.
45h	k5	8	49h	Gamma Correction Slop Coefficient 5.
46h	k6	8	44h	Gamma Correction Slop Coefficient 6.



47h	k7	8	3eh	Gamma Correction Slop Coefficient 7.
48h	k8	8	38h	Gamma Correction Slop Coefficient 8.
49h	k9	8	34h	Gamma Correction Slop Coefficient 9.
4ah	SUBSAMPLE	7	60h	Bit[6:4]:Reserved Bit[3]:Window enable. 1: Window function enable, 0: Normal output(default). Bit[2]: Subsample mode. 1: Realize subsample, 0: No subsample. Bit[2:0]: 0xx: NO subsample(normal), 100:4/5sub, 101:3/5sub, 110:2/3sub, 111:1/2sub.
4bh	k10	8	30h	Gamma Correction Slop Coefficient 10.
4ch	k11	8	2dh	Gamma Correction Slop Coefficient 11.
4eh	k12	8	28h	Gamma Correction Slop Coefficient 12.
4fh	k13	8	23h	Gamma Correction Slop Coefficient 13.
50h	k14	8	20h	Gamma Correction Slop Coefficient 14.
51h	TARGET1	8	01h	Color Correction Coefficient 1.
52h	TARGET2	8	0dh	Color Correction Coefficient 2.
53h	TARGET3	8	0eh	Color Correction Coefficient 3.
54h	TARGET4	8	0ah	Color Correction Coefficient 4.
55h	BRIGHT	8	00h	Brightness control. Bit[7]: 0: Positive, 1: Negative. Bit[6:0]: Value.
56h	Y_COEF	8	40h	Y Coefficient for Contrast.
57h	TARGET5	8	42h	Color Correction Coefficient 5.
58h	TARGET6	8	4ch	Color Correction Coefficient 6.
59h	TARGET7	8	55h	Color Correction Coefficient 7.
5ah	TARGET8	8	76h	Color Correction Coefficient 8.
5bh	TARGET9	8	21h	Color Correction Coefficient 9.
5ch	TARGET	8	0eh	Bit[7]: Color Correction adjustment enable, 1: Disable, 0: Enable. Bit[6:5]: Reserved. Bit[4]: Sign of Color Correction Coefficients 9. Bit[3:0]: Reserved.
5dh	TARGET_SIGN	8	9ch	Bit[7]: Sign of Color Correction Coefficients 8. Bit[6]: Sign of Color Correction Coefficients 7. Bit[5]: Sign of Color Correction Coefficients 6. Bit[4]: Sign of Color Correction Coefficients 5. Bit[3]: Sign of Color Correction Coefficients 4. Bit[2]: Sign of Color Correction Coefficients 3. Bit[1]: Sign of Color Correction Coefficients 2. Bit[0]: Sign of Color Correction Coefficients 1.
5fh	DARK_AVERE	8	20h,RO	DARKROW_AVER FOR EVEN COLUMN
60h	GLB_GAIN_TH	8	20h	Reserved.
61h	Ma_Th_Ctr	8	e3h	Reserved.
64h	DARK_AVER0	8	20h,RO	Dark row average value for odd column.
65h	G_COEF	8	46h	Lens shading gain of G.
66h	B_COEF	8	46h	Lens shading gain of B.
67h	MANU	8	80h	Manual U value.
68h	MANV	8	80h	Manual V value.



69h	DICOM1	8	00h	<p>Dither control 1.</p> <p>Bit[7]: YBCRCR RANGE select. 0: YBCRCR 0~255, 1: Y 16~235, CBCR 16~240.</p> <p>Bit[6]: Negative image enable 0: Normal image, 1: Negative image</p> <p>Bit[5]: UV output value select. 0: Output normal value, 1: Output fixed value set in MANU and MANV.</p> <p>Bit[4]: U、V dither when YBCRCR mode/R、B dither when RGB mode: 0: Low 2 Bits, 1: Low 3Bits.</p> <p>Bit[3]: Y dither when YBCRCR mode/G dither when RGB mode: 0: Low 2 Bits, 1: Low 3Bits.</p> <p>Bit[2]: Y dither enable.</p> <p>Bit[1]: U、V dither enable.</p> <p>Bit[0]: RGB dither enable.</p>
6ah	GNGAINREG	8	81h	<p>Bit[7:3]: Reserved.</p> <p>Bit[2:0]: G channel Gain (Bit2~Bit0 is used as GreenGain[5:3]).</p>
6bh	COM9	8	02h	<p>Common control 9.</p> <p>Bit[7]: 0: Use column_gate_sub for CKGATE, 1: Use HREF for CKGATE, default=0.</p> <p>Bit[6]: Reserved.</p> <p>Bit[5:4]: Average weight select, default value=00.</p> <p>Bit[3]: 0: Normal, 1: CKGATE ahead 1 MCLK(YUV) or PCLK(rawdata).</p> <p>Bit[2]: 0: Normal, 1: CKGATE ahead 0.5 MCLK(YUV) or PCLK(rawdata).</p> <p>Bit[1]: 0: No CKGATE when HREF=0, 1: Always has CKGATE.</p> <p>Bit[0]: 0: No gate sub, 1: Gate sub enable.</p>
6ch	CLKDIV	8	10h	Reserved.
6fh	DICOM2	8	20h	Reserved.
70h	IntCtr	8	6fh	<p>Interpolation control.</p> <p>Bit[7:4]: Reserved.</p> <p>Bit[3]: Edge enhancement switch. 0: Off, 1: On.</p> <p>Bit[2]: Processed rawdata output format switch. (use with 0x0c[7]=1) 0: 648x488, 1: 652x492,</p> <p>Bit[1]: Reserved</p> <p>Bit[0]: Low pass filter switch. 0: Off, 1: On.</p>
71h	BpcCtr	8	a6h	Reserved.
72h	DenCtr	8	4fh	Reserved.
73h	EdgCtr	8	2fh	Reserved.
74h	DaECtr	8	27h	Reserved.
75h	DakCtr	8	0eh	Reserved.
76h	EffCtr	8	00h	<p>Bit[7]: Special effect output on/off 0: Off, 1: On.</p> <p>Bit[6:4]: Special effect choice 011: Sketch, 100: Cuprum relievo, 101: Blue relievo, 110: Black relievo, 111: White relievo, default: Normal relievo.</p> <p>Bit[3]: Sram on/off 0: On, 1: Off.</p> <p>Bit[2:0]: Reserved.</p>



77h	SobCtr	7	10h	Bit[7]: Reserved Bit[6]: Select the mode for G balance. 0: Less smoothing. 1: More smoothing, Bit[4]: Edge thin enable.. 1: On, 0: Off. Bit[3:0]: Reserved.
78h	SobMax	8	ddh	{Bit[7],Bit[3]}: The speed of denoise according to Gain difference 11: 1, 10:1/2, 01: 1/4, 00:0. Bit[6:4]: Reserved
79h	MacCtr	8	c8h	Reserved.
7ah	BlaCtr	8	86h	Bit[7:4]: Y_AVER threshold. Bit[3]: Denoise enable in the condition of low light. 0: Denoise mode 1. 1: Denoise mode 2. Bit[2:0]: Reserved.
7bh	GaiCtr	7	2ch	Bit[6:0]: When GLB_GAIN = GLB_GAIN_MAX , enable the denoise function in the condition of low light.
80h	AE_MODE	8	45h	AE control mode. Bit[7]: AE mode selection. 0: Use Y (from color space module). 1: Use rawdata (from gamma module), when special effect in color interpolation module is selected, 0x80[7] must set to be 1. Bit[6]: INT_TIM lower than INT_STEP_50(INT_STEP_60) or not. 0: Limit int_tim>=step(no flicker), 1: Int_tim can be less than 1*integration step(existing flicker). Bit[5:4]: Center window select. 00: ROW*12/16, COL*12/16, 01: ROW*10/16, COL*10/16, 10: ROW* 8/16, COL*8/16, 11: ROW* 6/16, COL*6/16. Bit[3:1]: Weight select. 000: 4/8*center+4/8*border, 001: 5/8*center+3/8*border, 010: 6/8*center+2/8*border, 011: 7/8*center+1/8*border, 1xx: Center 100%. Bit[0]: Banding filter value select. 0: Select {0x89[5],0x9E[7:0]} as Banding Filter Value. 1: Select {0x89[4],0x9D[7:0]} as Banding Filter Value.
81h	AE_SPEED	8	02h	Frame count value for AE speed
82h	GLB_GAIN_MIN	7	0Ah	Global Gain Minimum
83h	GLB_GAIN_MEANL	7	1Ah	Reserved.
84h	GLB_GAIN_MEANM	7	1Bh	Reserved.
85h	GLB_GAIN_MEANH	7	26h	Reserved.
86h	GLB_GAIN_MAX	7	2ch	Global Gain Maximum
87h	GLB_GAIN	7	16h	Global gain register, (the max value is limited to 0x3f)
88h	Y_AVER	8	80h,RO	The average of the current frame
89h	INT_MEAN_H	7	02h	Bit[6]: Use as INT_MIN Bit[8],INT_MIN={0x89[6],0x8b[7:0]}, Bit[5]: Use as 60HZ Banding Filter STEP's Bit[8], Bit[4]: Use as 50HZ Banding Filter STEP's Bit[8], Bit[3:0]: Reserved.
8ah	INT_MEAN_L	8	fdh	Reserved.
8bh	INT_TIM_MIN	8	06h	Min integration time[7:0], INT_MIN={0x89[6],0x8b[7:0]}, effective only when 0x80[6]=1
8ch	INT_TIM[15:8]	8	01h	Integration time MSB.
8dh	INT_TIM[7:0]	8	cbh	Integration time LSB.



8eh	INT_TIM_MAX_H	8	0bh	Integration time upper limit MSB.
8fh	INT_TIM_MAX_L	8	f5h	Integration time upper limit LSB.
90h	INT_TIM_TH	7	20h	Reserved.
91h	OFFSET_TH1	7	1ch	Reserved.
92h	DM_LNL	8	05h	Dummy line insert after active line low 8 Bits.
93h	DM_LNH	8	00h	Dummy line insert after active line high 8 Bits.
94h	INT_OPEN	6	10h	Integration time open value.
95h	INTSTEPD_SEL	8	94h	Bit[7]: IF INT_TIM < INT_STEP , it will limit the speed when AE is stable. 0: Normal, 1: Limit the speed.. Bit[6:0]: Threshold for AE speed. The value smaller, the AE speed faster. NOTE: Too small value may cause AE instability.
96h	GLB_STEPS_SEL	8	9Ah	Bit[7] : Reserved Bit[6:0]: Global gain threshold for AE speed.
97h	INT_TIM_COEF_TH	8	08h	Integration time threshold for AE speed.
98h	Y_AVER_TH	5	10h	Y frame average threshold for AE speed, The value larger, AE speed faster. Note: Too large value may cause AE instability.
9ah	GLB_GAIN_MEANL_STEPD	7	1ah	Reserved.
9bh	YOL_G	8	f6h	Reserved.
9ch	XOL_G	8	46h	Reserved.
9dh	INT_STEP_50	8	99h	50HZ Banding Filter STEP low 8 Bits, Bit[8] is in 0x89[4] (INT_MEAN_H[4]).
9eh	INT_STEP_60	8	7fh	60HZ Banding Filter STEP low 8 Bits, Bit[8] is in 0x89[5] (INT_MEAN_H[5]).
a0h	UPDATE_MODE	8	07h	Bit[7:2]: Reserved. Bit[1]: YCBCR limit enable, Bit[0]: For manual write RGAIN/BGAIN mode, 0: RGAIN/BGAIN can't be written if AWB_EN(COM8[1])=0 not strides over vsync's negedge, 1: RGAIN/BGAIN can be written no matter AWB_EN=0 strides over vsync's negedge or not.
a1h	AWB_LOCK AWB_SPEED	8	31h	Bit[7:4]:Auto White Balance Lock Boundary, Bit[3:0]:AWB Update Speed.
a2h	BLUE_GAIN_LOW_IN	6	0ah	The low limit value of blue gain.
a3h	BLUE_GAIN_HIGH_IN	6	20h	The high limit value of blue gain.
a4h	RED_GAIN_LOW_IN	6	0ch	The low limit value of red gain.
a5h	RED_GAIN_HIGH_IN	6	26h	The high limit value of red gain.
a6h	COUNT_EN	8	04h	AWB criterion: white pixels count threshold, '1' equal to 1024 pixels.
a7h	CB_TARGET	8	80h	CB frame average target value.
a8h	CR_TARGET	8	80h	CR frame average target value.
a9h	CB_LIMIT	8	1eh	AWB criterion: CB.
aaH	CR_LIMIT	8	19h	AWB criterion: CR.
abh	CBCR_LIMIT	8	1eh	AWB criterion: CBCR.
ach	Y_LOW	8	3ch	AWB criterion: Y_LOW.
adh	Y_HIGH	8	f0h	AWB criterion: Y_HIGH.
aeh	OUTDOOR_EN INT_TIM_EN	8	00h	Reserved.
afh	BGAIN_LOW_OUT	6	00h	Reserved.
b0h	SAT_CTR1	8	c0h	Saturation control: Bit[7]: Saturation mode. 0: Normal 1: Auto. Bit[6:0] Reserved.



b1h	CB_COEF	8	c6h	CB Coefficient for Color Saturation.
b2h	CR_COEF	8	cch	CR Coefficient for Color Saturation.
b3h	SAT_CTR2	8	8ch	Reserved.
b6h	MAN_R	8	80h	Define R value.
b7h	MAN_G	8	80h	Define G value.
b8h	MAN_B	8	80h	Define B value.
b9h	TEST_MODE	8	00h	Bit[7]: 0: Test pattern bypass, 1: Test pattern enable. Bit[6:5]: 00: Output color bar pattern. 01: Output gradual pattern. 10: Output manual write R/G/B. 11: Auto mode, speed is controlled by TEST_MODE [4:0] . Bit[4]: 0: Vertical pattern, 1: Horizontal pattern Bit[3:0]: Gradual gray pattern mode control
bbh	BLANK	8	00h	Reserved.
bch	Y0H_R,X0H_R	5	01h	Reserved.
bdh	Y0L_R	8	F6h	Reserved.
beh	X0L_R	8	46h	Reserved.
c5h	BGAIN_HIGH_OUT	6	16h	Reserved.
c6h	RGAIN_LOW_OUT	6	00h	Reserved.
c7h	RGAIN_HIGH_OUT	6	1fh	Reserved.
c8h	BGAIN_OUTTH	6	17h	Reserved.
c9h	RGAIN_OUTTH	6	19h	Reserved.
cah	BGAIN_INTH	6	15h	Reserved.
cbh	RGAIN_INTH	6	17h	Reserved.
cch	INT_TIM_TH	8	4dh	Reserved.
cdh	YCBCR_LIMIT	8	b4h	Reserved.
d9h	H_START_H	8	00h	When SUBSAMPLE[3] ==1'b1, in window mode, window X start[9:2].
dah	H_END_H	8	a3h	When SUBSAMPLE[3] ==1'b1, in window mode, window X end[9:2].
dbh	V_START_H	7	00h	When SUBSAMPLE[3] ==1'b1, in window mode, window Y start[8:2].
dch	V_END_H	7	7bh	When SUBSAMPLE[3] ==1'b1, in window mode, window Y end[8:2].
ddh	VH_ADD_L	8	00h	In window mode. Bit[1:0]: window X start[1:0]. Bit[3:2]: window X end[1:0]. Bit[5:4]: window Y start[1:0]. Bit[7:6]: window Y end[1:0].
e0h	PRSTF	6	06h	Reserved.
e1h	TX2_R	7	38h	Reserved.
e2h	HREF_CNTL	8	04h	Reserved.
e3h	DM_ROWL	8	09h	Dummy line insert before active line low 8 Bits.
e4h	DM_ROWH	8	00h	Dummy line insert before active line high 8 Bits.
e5h	SHRF	6	14h	Reserved.
e6h	SHSF	6	32h	Reserved.
e7h	MXSTART_R	8	74h	Reserved
e8h	H_HSYNC_EDGE	8	00h	Bit[7:4]: Control the rising edge of HSYNC. HSYNC rising edge high 4 Bits; Bit[3:0]: Control the falling edge of HSYNC. HSYNC falling edge high 4 Bits .
e9h	ISP_CK	8	72h	Reserved.
eah	ANALOG_PDN	8	50h	Reserved.
ebh	ISP_CK_CNTL	8	20h	Reserved.
eeh	P_TH	8	4ch	Reserved.
efh	SKIN_CTR	4	bh	Reserved.

f1h	BYPASS0	8	00h	Bit[7]: Data format enable, 0: Enable, 1: Disable. Bit[6]: Contrast enable, 0: Enable, 1: Disable. Bit[5]: Saturation enable , 0: Enable, 1: Disable. Bit[4]: Color space & Color correction enable, 0: Enable, 1: Disable. Bit[3]: Color Correction enable, 0: Enable, 1: Disable. Bit[2]: Color Interpolation enable, 0: Enable, 1: Disable. Bit[1]: Gamma Correction enable, 0: Enable, 1: Disable. Bit[0]: Lens Correction enable, 0: Enable, 1: Disable.
f2h	HUE_COS	8	7fh	Hue cosine coefficient range -1~0.99(0X80~0X7F) MSB is symbol
f3h	HUE_SIN	8	00h	Hue sine coefficient range -1~0.99(0X80~0X7F) MSB is symbol.
f4h	ISP_CK_NUM	8	09h	Reserved
f5h	READEN_R	5	20h	Reserved
f8h	Y_LS0	8	00h,RO	Reserved
f9h	LS_REG,Y_LS1	8	00h	Reserved
fch	PID_BME	8	37h,RO	Product ID MSB.
fdh	VER_BME	8	03h,RO	Product ID LSB.

8. Package Specifications

Mechanical Diagram

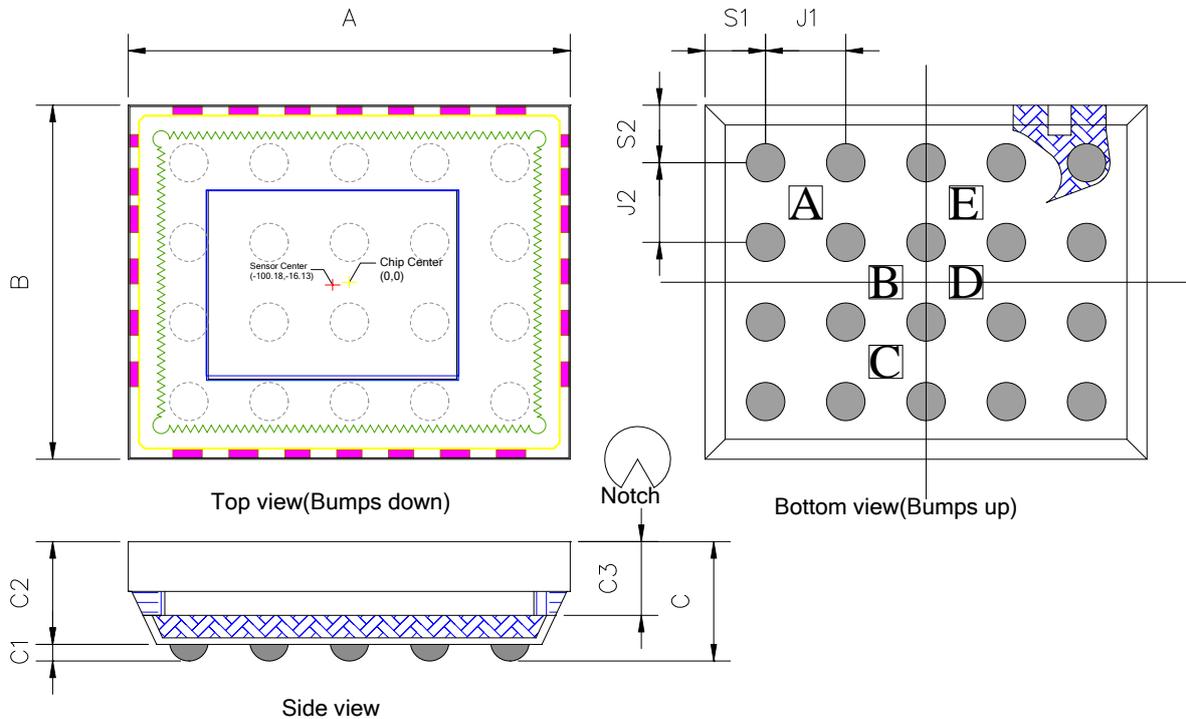


Figure 7 CSP dimension description

Table 6 CSP Dimensions

	Symbol	Nominal	Min	Max
	Unit (μm)			
Package Body Dimension X	A	2643	2618	2668
Package Body Dimension Y	B	2134	2109	2159
Package Height	C	720	660	780
Ball Height	C1	100	70	130
Package Body Thickness	C2	620	575	665
Thickness from top glass surface to wafer	C3	445	425	465
Ball Diameter	D	230	200	260
Total Ball Count	N	20		
Ball Count X axis	N1	5		
Ball Count Y axis	N2	4		
Pins Pitch X axis	J1	480		
Pins Pitch Y axis	J2	480		
Edge to Pin Center Distance along X	S1	362	332	392
Edge to Pin Center Distance along Y	S2	347	317	377

Table 7 Ball Matrix Table

	1	2	3	4	5
A	VDD3A	D6	D5	D3	VCLK
B	VSSA	D7	D4	D2	VSSD
C	SCL	HREF	RESET	D1	PWDN
D	SDA	VSYNC	XCLK	D0	VDDIO

Table 8 Pin Descriptions

Pin Number	Name	Pin Type	Function/Description
A1	VDD3A	Power	Analog power supply.
A2	D6	Output	YUV/RGB image data output port [6].
A3	D5	Output	YUV/RGB image data output port [5].
A4	D3	Output	YUV/RGB image data output port [3].
A5	VCLK	Output	Pixel clock output.
B1	VSSA	Power	Analog ground.
B2	D7	Output	YUV/RGB image data output port [7].
B3	D4	Output	YUV/RGB image data output port [4].
B4	D2	Output	YUV/RGB image data output port [2].
B5	VSSD	Power	Digital ground.
C1	SCLK	Input	SCCB serial interface clock input.
C2	HREF	Output	HREF output.
C3	RSTB	Input(1)*	Reset all registers to their default values. 0: Reset mode 1: Normal mode



C4	D1	Output	YUV/RGB image data output port [1].
C5	PDN	Input(0)**	Power Down Mode Selection. 0: Normal mode. 1: Power down mode.
D1	SDA	I/O	SCCB serial interface data I/O.
D2	VSYNC	Output	Vertical sync output.
D3	XCLK	Input	System clock input.
D4	D0	Input	YUV/RGB image data output port [0].
D5	VDDIO	Power	Power supply for I/O.

Note:

- ** Input(1) represents an internal pull-up resistor.
- ** Input(0) represents an internal pull-down resistor.

RESTRICTIONS ON PRODUCT USE

- The information contained herein is subject to change without notice.
- BYD Microelectronics Co., Ltd. (short for BME) exerts the greatest possible effort to ensure high quality and reliability. Nevertheless, semiconductor devices in general can malfunction or fail due to their inherent electrical sensitivity and vulnerability to physical stress. It is the responsibility of the buyer, when utilizing BME products, to comply with the standards of safety in making a safe design for the entire system, including redundancy, fire-prevention measures, and malfunction prevention, to prevent any accidents, fires, or community damage that may ensue. In developing your designs, please ensure that BME products are used within specified operating ranges as set forth in the most recent BME products specifications.
- The BME products listed in this document are intended for usage in general electronics applications (computer, personal equipment, office equipment, measuring equipment, industrial robotics, domestic appliances, etc.). These BME products are neither intended nor warranted for usage in equipment that requires extraordinarily high quality and/or reliability or a malfunction or failure of which may cause loss of human life or bodily injury ("Unintended Usage"). Unintended Usage include atomic energy control instruments, airplane or spaceship instruments, transportation instruments, traffic signal instruments, combustion control instruments, medical instruments, all types of safety devices, etc.. Unintended Usage of BME products listed in this document shall be made at the customer's own risk.