

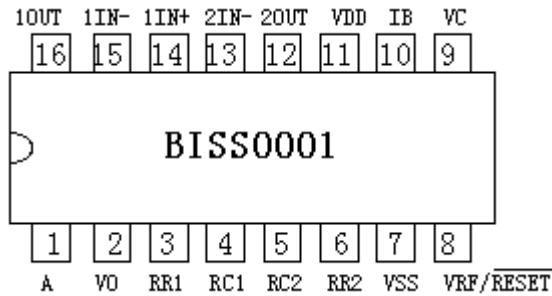
# **BISS0001**

## **Micro Power PIR Motion Detector IC**

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### **Features**

- Low power CMOS technology (ideal for battery operated PIR devices)
- CMOS high input impedance operational amplifiers
- Bi-directional level detector / Excellent noise immunity
- Built-in Power up disable & output pulse control logic
- Dual mode : retriggerable & non-retriggerable



### **Pin description**

<b>Pin Number</b>	<b>Symbol</b>	<b>Description</b>
1	<b>A</b>	Retriggerable & non-retriggerable mode select (A=1 : re-triggerable)
2	<b>VO</b>	Detector output pin (active high)
3	<b>RR1</b>	Output pulse width control (Tx) * See definition below
4	<b>RC1</b>	Output pulse width control (Tx) *
5	<b>RC2</b>	Trigger inhibit control (Ti) *
6	<b>RR2</b>	Trigger inhibit control (Ti) *
7	<b>Vss</b>	Ground
8	<b>VRF</b>	RESET & voltage reference input (Normally high. Low=reset)
9	<b>VC</b>	Trigger disable input (VC >0.2Vdd=enable; VC<0.2Vdd =disabled)
10	<b>IB</b>	Op-amp input bias current setting
11	<b>Vdd</b>	Supply voltage
12	<b>2OUT</b>	2 <sup>nd</sup> stage Op-amp output
13	<b>2IN-</b>	2 <sup>nd</sup> stage Op-amp inverting input
14	<b>1IN+</b>	1 st stage Op-amp non-inverting input
15	<b>1IN-</b>	1 st stage Op-amp inverting input
16	<b>1OUT</b>	1 st stage Op-amp output

\*

Tx = The time duration during which the output pin (Vo) remains high after triggering.

Ti = During this time period, triggering is inhibited. See timing charts for details.

**Tx**  $\approx$  24576 x R10 x C6;    **Ti**  $\approx$  24 x R9 x C7. (ref to schematic)

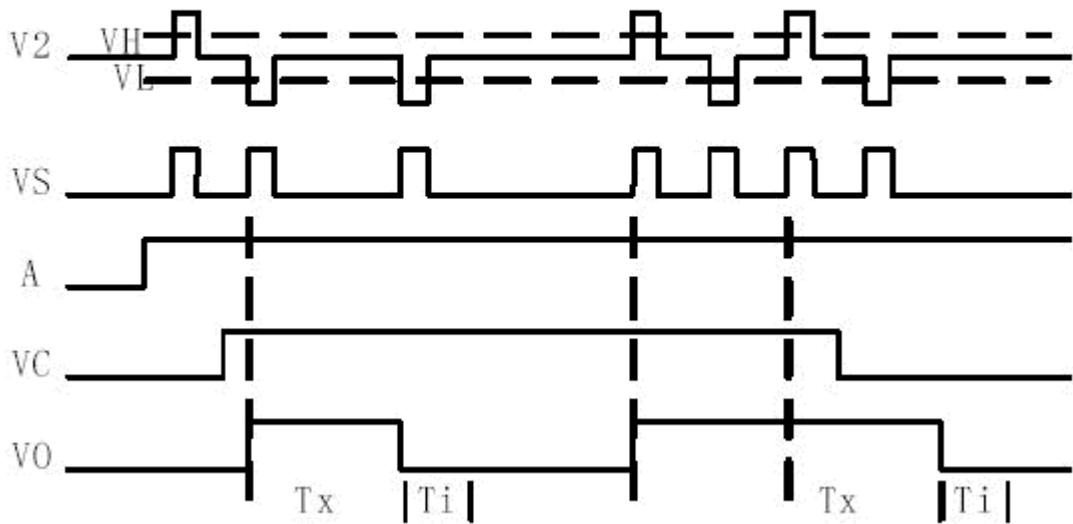
## Absolute max. ratings

Description	Condition	Range	Unit
Supply voltage	--	3 ~ 5	V
Input voltage	--	Vss-0.3~ Vdd+0.3	V
Output current	Vdd=5V	10	mA
Operating temperature	--	-20 ~ +70	°C
Storage temperature	--	-40 ~ +125	°C

## Retriggable waveform

(NOTE : VH=0.7Vdd, VL=0.3Vdd)

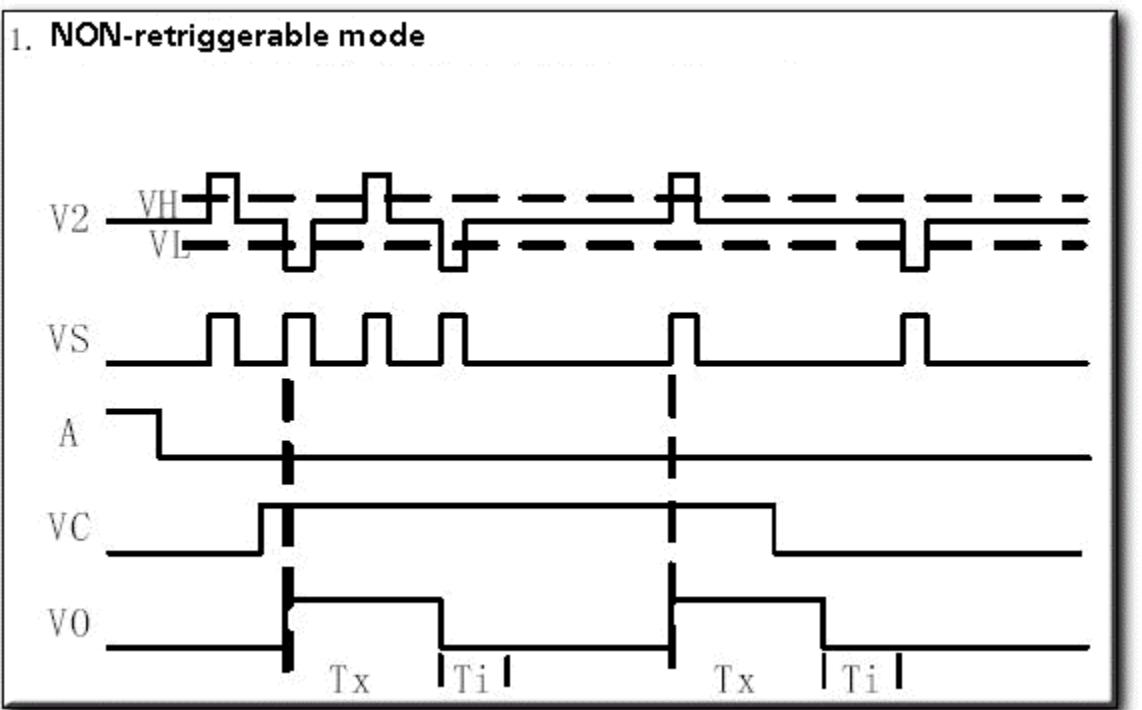
### 2. Re-triggerable mode



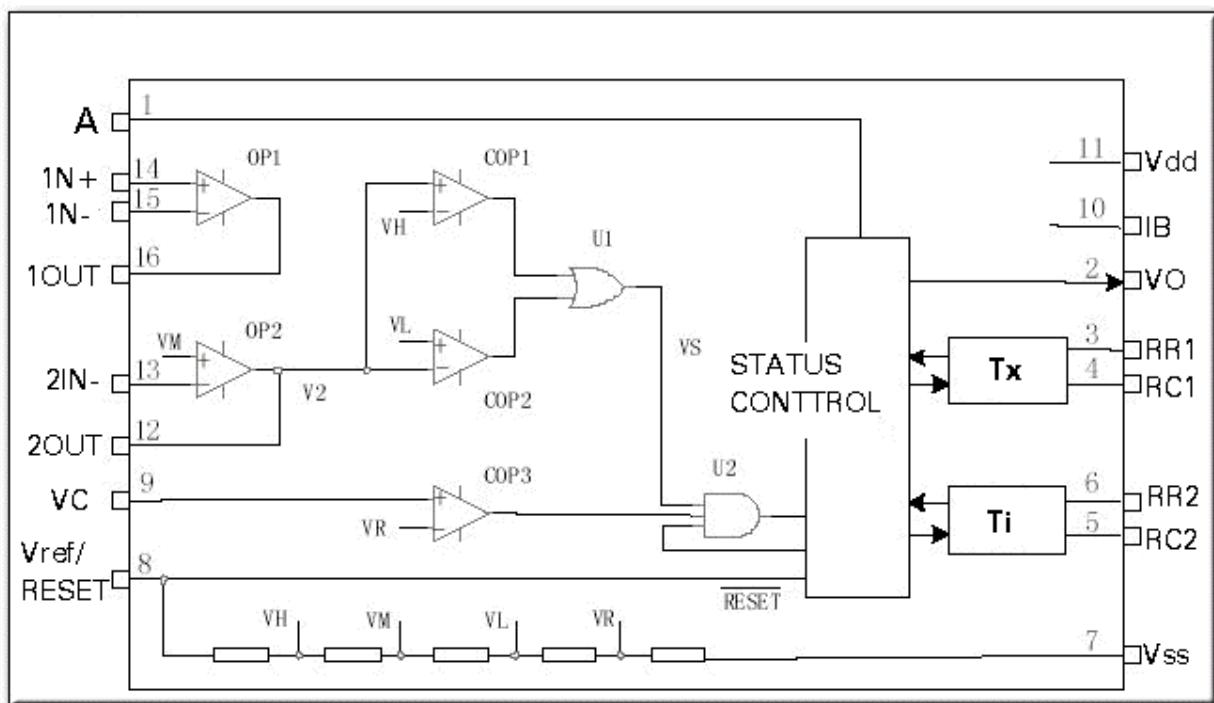
## Non-retriggerable waveform

(NOTE : VH=0.7Vdd, VL=0.3Vdd)

### 1. NON-retriggerable mode



### Internal Block Diagram

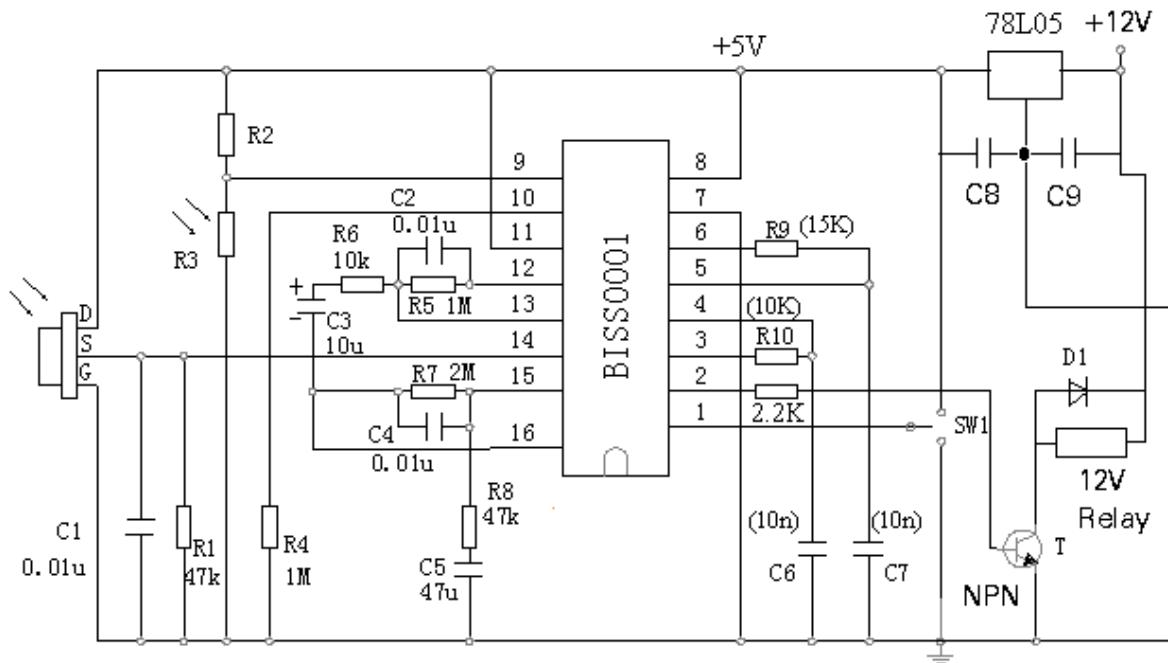


**Tx** – Output pulse width control

**Ti** - Trigger inhibit timing control

## Application Example

### -- Passive Infrared Detector for alarm system



$$T_x \approx 24576 \times \mathbf{R10} \times \mathbf{C6}; \quad T_i \approx 24 \times \mathbf{R9} \times \mathbf{C7}. \quad (\text{ref to schematic})$$

**R3** is a light dependent resistor which has low resistance under strong ambient light. This causes the detector to be operational only when the detection area is sufficiently dark.