BTM8670

Bluetooth Module Data Sheet

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1. INTRODUCTION

The BTM8670 Bluetooth[®] module is a perfect consumer audio solution for wireless applications, such as wireless sound bars, wireless stereo speakers and headphones. It can be connected with any Bluetooth[®] devices in an operating range. It is slim and light so the designers can have better flexibilities for the product shapes.

The BTM8670 Bluetooth[®] module complies with Bluetooth[®] specification version 4.0. It supports HSP,HFP,A2DP,AVRCP,PBAP,MAP,SPP....profiles. It integrates an ultra-low-power DSP and application processor with embedded flash memory, a high-performance stereo codec, a power management subsystem, LED and LCD drivers and capacitive touch sensor inputs in a SOC IC. The dual-core architect with flash memory enables manufactures to easily differentiate the products with new features without extending development cycles. It integrates RF Baseband controller, antenna,... etc. and provide UART interface, programmable I/O, stereo speaker output, microphone input,... etc.

The detail information of BTM8670 Bluetooth[®] module is presented in this document below.



1.1 Block Diagram

Figure 1

1.2 Features

- ✓ Small overall dimension(22mm x 15mm x 2mm)
- ✓ Bluetooth Specification V4.0(Dual Mode)
- ✓ Class1, Class 2and Class 3 support
- ✓ Physical connection as SMD type
- ✓ 80MHz RISC MCU and 80MIPS Kalimba DSP
- ✓ 16Mb internal flash memory(64-bit wide,45ns);optional support for 64Mb of external SPI flash
- Stereo codec with 2 channels ADC and up to 6 microphone inputs(include bias generators and digital microphone support)
- Support for CSR's latest CVC technology for narrow-band and wideband voice connections including wind noise reduction
- ✓ Music Enhancements: SBC,MP3,AAC and AAC+, Fast stream codec,atpX,5-band EQ,3D stereo separation and so on.
- ✓ Audio Interfaces: I2S,PCM and SPDIF
- ✓ Serial Interfaces: UART, USB 2.0, I2C and SPI
- ✓ Support HSP, HFP, A2DP, AVRCP, PBAP, MAP, SPP, iAP profile
- ✓ Multipoint support for HFP connection to 2 handsets for voice
- ✓ Multipoint support for A2DP connection to 2 A2DP source for music play back
- ✓ 3 Hardware LED controllers (for RGB) and ability to drive LCD segment display directly
- ✓ Support for up to 6 capacitive touch sensor inputs
- ✓ Built-in RF combo filter, Integrated 26M Crystal.
- ✓ No radio signal interference, support for 802.11 co-existence
- **%** Some features are optional for customization on demand.

1.3 Application

- ✓ TVs
- ✓ Smart remote controllers
- ✓ Wired or wireless sound bars
- \checkmark Wired or wireless speakers and headphones
- ✓ Wearable audio with sensors(health and well-being applications)

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12. GENERAL SPECIFICATION

Bluetooth Specification	
Chip Set	CSR8670
Module ID	BTM8670
BT Standard	Bluetooth [®] V4.0 specification
RF TX Output Power	10dBm (Max)
Sensitivity	-90dBm@0.1%BER
Frequency Band	2.402GHz~2.480GHz ISM Band
Baseband Crystal OSC	26MHz
Hopping	1600hops/sec, 1MHz channel space
RF Input Impedance	50 ohms
Major Interface	 Microphone : Input (Differential) Speaker : Output (Differential) UART : Tx/Rx PIOs Antenna
Profile	HSP, HFP, A2DP, AVRCP, PBAP, MAP, SPP
Voice Processor	80MIPS Kalimba with cVc support
Power	
Supply Voltage	3.0V ~ 4.2V DC
Working Current	15mA typical, Depends on profiles
Standby Current	<1mA
Operating Environment	
Temperature	-40°C to +85°C
Humidity	10%~90% Non-Condensing
Environmental	RoHS Compliant

3. PHYSICAL CHARACTERISTIC





Pin Definition Figure 3

3.1 Pin Description

Pin#	Pin Name	Pad Type	Description	
1	CAP_SENSE_5	Analogue input	Capacitive touch sensor input	
2	CAP_SENSE_2	Analogue input	Capacitive touch sensor input	
3	CAP_SENSE_0	Analogue input	Capacitive touch sensor input	
4	GND	Ground	Digital Ground	
5	AIO_1	Bi-directional	Analogue programmable input / output line	
6	PCM_IN/PIO_17	Bi-directional with weak pull_down	Synchronous data input. Alternative function PIO[17]	
7	PCM_CLK/PIO_20	Bi-directional with weak pull_down	Synchronous data clock. Alternative function PIO[20]	
8	PCM_SYNC/PIO_19	Bi-directional with weak pull_down	Synchronous data sync. Alternative function PIO[19]	
9	PCM OUT/PIO 18	Bi-directional with weak	Synchronous data output. Alternative	
		pull_down	function PIO[18]	
10	BT_RESET	Input with strong pull-up	Reset if low. Input debouched so	
11	SPI_CLK	Input with weak pull-down	SPI Clock	
12	SPI_MOSI	Input with weak pull-down	SPI data input	
13	SPI_CSB	Input with strong pull-up	Chip select for SPI, active low	
14	SPI_MISO	Output with weak pull-down	SPI data output	
15	UART_RTS	Bi-directional with weak pull_up	UART request to send, active low. Alternative function PIO[16]	
16	SPI_CTS	Bi-directional with weak pull_down	UART clear to send, active low	
17	UART_RX	Bi-directional with strong pull up	UART data input	
18	UART_TX	Bi-directional with weak	UART data output	
19	GND	Ground	Digital Ground	
20	LED_0	Open drain	LED driver Alternative function PO[29]	
21	LED_1	Open drain	LED driver Alternative function PO[30]	

22		Open drein	LED driver Alternative function PO[31]	
22	LED_2	Open drain		
23	PIO 0	Bi-directional with weak	Programmable input/output line	
		pull_down		
24	PIO 1	Bi-directional with weak	Programmable input/output line	
	110_1	pull_down	- rogrammere inpas carpatione	
25		Bi-directional with weak	Programmable input/output line	
23	110_2	pull_down		
26	GND	Ground	Digital Ground	
27		D i directional	USB data plus with selectable internal	
21	USB_DF	DI-unecuonar	1.5kohm pull-up resistor	
28	USB_DN	Bi-directional	USB data minus	
29	VDD_USB	NC	Positive supply for USB ports	
20		Bi-directional with weak		
30	PIO_3	pull_down	Programmable input/output line	
21		Bi-directional with weak		
31	PIO_4	pull_down	Programmable input/output line	
22		Bi-directional with weak		
32	PIO_5	pull_down	Programmable input/output line	
22		Bi-directional with weak		
33	PIO_6	pull_down	Programmable input/output line	
24		Bi-directional with weak		
54	PIO_/	pull_down	Programmable input/output inte	
25	DIO 10	Bi-directional with weak	Programmable input/output line	
33	FIO_10	pull_down	riogrammable inpu/output inte	
26	\mathbf{DIO} 11	Bi-directional with weak	Programmable input/output line	
30	FIO_11	pull_down		
27	DIO 12	Bi-directional with weak	Drogrammahla input/output ling	
57	PIO_12	pull_down	Programmable inpul/output inte	
20	\mathbf{DIO} 12	Bi-directional with weak	Des grommshis innut/output line	
30	FIO_13	pull_down	Frogrammable inpu/output inte	
20	\mathbf{DIO} 14	Bi-directional with weak		
39	PIO_14	pull_down	Programmable input/output inte	
40	DIO 15	Bi-directional with weak	Programmable input/output line	
40	FIO_13	pull_down	riogrammaole mpul/output me	
A 1		NC	1.7V to 3.6V positive supply input for digital	
41 VDD_PADS		input/output ports PIO[15:4]		



http://www.buddies-tech.com

42	GND	Ground	Digital Ground	
43	PWR VBAT	Input enable Power supply	Regulator enable input.Can also be sensed as an input.Regulator enable and multifunction button. A highinput (tolerant to VBAT) enables the on-chipregulators, which can then be latched oninternally and the button used as a multifunctioinput.Battery positive terminal	
45	VBAT_SENSE	NC	Battery charger sense input	
46	VBUS	Power supply	Alternative supply via bypass regulator for 1.8V and 1.35V Switch mode power supply regulator inputs. Must be connected to the same potential as VOUT_3V3.	
47	CHG_EXT	NC	External battery charger control	
48	+1V8	Open drain output	LED driver	
49	3V3_OUT	NC	3.3V bypass linear regulator output	
50	GND	Ground	Digital Ground	
51	MIC_RN	Analogue in	Microphone input negative, right	
52	MIC_RP	Analogue in	Microphone input positive, right	
53	MIC_BIAS_B	Analogue out	Microphone bias B	
54	MIC_BIAS_A	Analogue out	Microphone bias A	
55	MIC_LN	Analogue in	Microphone input negative, left	
56	MIC_LP	Analogue in	Microphone input positive, left	
57	AGND	Ground	Analogue Ground	
58	SPKR_LN	Analogue out	Speaker output negative, left	
59	SPKR_LP	Analogue out	Speaker output positive, left	
60	SPKR_RN	Analogue out	Speaker output negative, right	
61	SPKR_RP	Analogue out	Speaker output positive, right	
62	AIO_0	Bi-directional	Analogue programmable input / output line	
63	GND	Ground	Analogue Ground	



http://www.buddies-tech.com		ech.com	BTM8670 DATASHEET
64	RF_IN	RF	Bluetooth 50ohm transmitter output/receiver input
65	GND	Ground	Analogue Ground
66	CAP_SENSE_ 1	Analogue input	Capacitive touch sensor input
67	CAP_SENSE_ 3	Analogue input	Capacitive touch sensor input
68	CAP_SENSE_ 4	Analogue input	Capacitive touch sensor input

4. PHYSICAL INTERFACE

4.1 Power Supply

The transient response of the regulator is important. If the power rails of the module are supplied from an external voltage source, the transient response of any regulator used should be 20µs or less.

4.2 Audio Interfaces

The Audio interface circuit consists of:

- Stereo/dual-mono audio codec
- Dual analogue audio inputs
- Dual analogue audio outputs
- 6 digit MEMS microphone inputs
- A configurable PCM,I2S or SPDIF interface

As below shows the functional blocks of the interface. The codec supports stereo/dual-mono playback and recording of audio signals at multiple sample rates with a 16-bit resolution. The ADC and DAC of the codec each contain 2 independent high-quality channels. Any ADC or DAC channel runs at its own independent sample rate.



Figure 4

The interface for the digital audio bus shares the same pins as the PCM codec interface described in section as below which means each of the audio buses are mutually exclusive in the usage. As below lists these alternative functions.

PCM Interface	SPDIF Interface	I ² S Interface
PCM_OUT	SPDIF_OUT	SD_OUT
PCM_IN	SPDIF_IN	SD_IN
PCM_SYNC	-	ws
PCM_CLK	-	SCK

Figure 5

4.2.1 Audio Codec Interface

The main features of the interface are:

- Stereo and mono analogue input for voice band and audio band
- Stereo and mono analogue output for voice band and audio band
- Support for stereo digital audio bus standards such as I2S
- Support for IEC-60958 standard stereo digital audio bus standards, e.g. SPDIF and AES3(also known as AES/EBU)
- Support for PCM interfaces including PCM master codec that require an external system clock



4.2.2 ADC

Figure 3 shows the CSR8670 consists of 2 high-quality ADCs:

- Each ADC has a second-order Sigma-Delta converter
- Each ADC is a separate channel with identical functionality
- There are 2 gain stages for each channel,1 of which is an analogue gain stage and the other is a digital gain stages

4.2.3 ADC Sample Rate Selection

Each ADC supports the following pre-defined sample rates, although other rates are programable, e.g. 40kHz:

- 8kHz
- 11.025 kHz
- 16kHz
- 22.050kHz
- 24kHz
- 32 kHz
- 44.1kHz
- 48 kHz

4.2.4 ADC Digital Gain

A digital gain stage inside the ADC varies from -24dB to 21.5dB,see as below, there is also a fine gain interface with 9-bit gain setting allowing gain changes in 1/32 steps. The Firmware controls the audio input gain.

Digital Gain Selection Value	ADC Digital Gain Setting (dB)	Digital Gain Selection Value	ADC Digital Gain Setting (dB)
0	0	8	-24
1	3.5	9	-20.5
2	6	10	-18
3	9.5	11	-14.5
4	12	12	-12
5	15.5	13	-8.5
6	18	14	-6
7	21.5	15	-2.5

The DAC consists of:

- 2 fourth-order Sigma-Delta converters enabling 2 separate channels that are identical functionality, as figure x shows
- 2 gain stages for each channel, 1 of which is an analogue gain stage and the other is a digital gain stage

4.2.6 DAC Sample Rate Selection

- 8kHz
- 11.025kHz
- 16kHz
- 22.050kHz
- 32kHz
- 40kHz44.1kHz
- $\bullet 44.1 \text{ kHz}$
- 96kHz

4.2.7 DAC Digital Gain

A digital gain stage inside the DAC varies from -24dB to 21.5dB,see as below, there is also a fine gain interface with 9-bit gain setting enabling gain changes in 1/32 steps. The overall gain control of the ADC is controlled by the firmware. Its setting is a combined function of the digital and analogue amplifier settings

Digital Gain Selection Value	DAC Digital Gain Setting (dB)	Digital Gain Selection Value	DAC Digital Gain Setting (dB)
0	0	8	-24
1	3.5	9	-20.5
2	6	10	-18
3	9.5	11	-14.5
4	12	12	-12
5	15.5	٦ 13	-8.5
6	18	14	-6
7	21.5	15	-2.5

4.2.8 **DAC Analogue Gain**

As below shows that the DAC analogue gain stage consists of 8 gain selection values that represent seven 3dB steps

The firmware controls the overall gain control of the DAC. Its setting is a combined function of the digital and analogue amplifier settings

Analogue G <mark>ain</mark> Selection Value	DAC Analogue Gain Setting (dB)	Analogue Gain Selection Value	DAC Analogue Gain Setting (dB)
7	0	3	-12
6	-3	2	-15
5	-6	1	-18
4	-9	0	-21

4.2.9 **IEC 60958 Interface**

The IEC 60958 interface is a digital audio interface that uses bi-phase coding to minimize the DC content of the transmitted signal and enables the receiver to decode the clock information from the transmitted signal. The IEC 60958 specification is based on the 2 industry standards:

- AES3(also known as AES/EBU)
- Sony and Philips interface specification SPDIF

The interface is compatible with IEC 60958-1, IEC 60958-3 and IEC 60958-4 The SPDIF interface signals are SPDIF-IN and SPDIF-OUT and are shared on the PCM interface pin.

4.2.10 **Microphone Input**

BTM8670contains 2 independent low-noise microphone bias generators. The microphone bias generators are recommended for biasing electro condenser microphones. A biasing circuit for microphones with a sensitivity between about -40dB to -60dB(0dB=1V/Pa)

Digital Microphone Inputs 4.2.11

The CSR8670 interfaces to 6 digital MEMS microphones. Figure x shows that 4 of the inputs have dedicated codec channels and 2 are multiplexed with the high-quality ADC channels.

4.2.12 Line input If the pre-amplifier audio input gain is set at a low gain level it acts as an audio line level amplifier. In this line input mode the input impendence varies from 6kohm to 30kohm, depending on the volume setting.

4.2.13 Audio Output Stage

The output digital circuitry converts the signal from 16-bit per sample, linear PCM of

variable sampling frequency to a 2Mbits/sec multi-bit stream, which is fed into the analogue output circuitry.

The output circuit comprises a digital to analogue converter with gain setting and output amplifier. Its class-AB output-stage is capable of driving a signal on both channels of up to 2V pk-pk-differential into a load of 16Ω . The output is available as a differential signal between SPK_R_RP and SPK_R_RN for the left channel; and between SPK_L_LP and SPK_L_LN for the right channel. The output is capable of driving a speaker directly if its impedance is at least 8Ω if only one channel is connected or an external regulator is used.

The gain of the output stage is controlled by a 3-bit programmable resistive divider, which sets the gain in steps of approximately 3dB.

The multi-bit stream from the digital circuitry is low pass filtered by a second order bi-quad filter with a pole at 20kHz. The signal is then amplified in the fully differential output stage, which has a gain bandwidth of typically 1MHz.

4.3 PCM Interface

The audio PCM interface on the BTM8670 supports:

- On-chip routing to Kalimba DSP
- Continuous transmission and reception of PCM encoded audio data over Bluetooth.
- Processor overhead reduction through hardware support for continual transmission and reception of PCM data
- A bidirectional digital audio interface that routes directly into the baseband layer of the firmware .It does not pass through the HCI protocol layer.
- Hardware on the BTM8670 for sending data to and from a SCO connection.
- Up to 3 SCO connections on the PCM interface at any one time.
- PCM interface master, generating PCM_SYNC and PCM_CLK.
- PCM interface slave, accepting externally generated PCM_SYNC and PCM_CLK.
- Various clock formats including:
 - Long Frame Sync
 - Short Frame Sync
 - GCI timing environments
- 13-bit or 16-bit linear, 8-bit u-law or A-law compander sample formats.
- Receives and transmits on any selection of 3 the first 4 slots following PCM_SYNC.

The PCM configuration options are enabled by setting the PS Key PSKEY_PCM_CONFIG32.



4.4 Digital Audio Interface(I2S)

The digital audio interface supports the industry standard formats for I2S,left-justified or right-justified. The interface shares the same pins as the PCM interface ,which means each audio bus is mutually exclusive in its usage. Table as below lists these alternative functions

PCM Interface	I ² S Interface	
PCM_OUT	SD_OUT	
PCM_IN	SD_IN	
PCM_SYNC	WS	
PCM_CLK	SCK	

4.5 **RF Interface**

The module integrates a balun filter. The user can connect a 50ohms antenna directly to the RF port.

4.6 General Purpose Analog IO

The general purpose analog IOs can be configured as ADC inputs by software. Do not connect them if not use.

4.7 General Purpose Digital IO

There are nine general purpose digital IOs defined in the module. All these GPIOs can be configured by software to realize various functions, such as button controls, LED displays or interrupt signals to host controller, etc. Do not connect them if not use.

4.8 Serial Interfaces 4.8.1 UART

This is a standard UART interface for communicating with other serial devices. The UART interface provides a simple mechanism for communicating with other serial devices using the RS232 protocol.

When the module is connected to another digital device, UART_RX and UART_TX transfer data between the two devices. The remaining two signals, UART_CTS and UART_RTS, can be used to implement RS232 hardware flow control where both are active low indicators.

Note: The serial port interface(UART)can be used for system debugging. Don't support to use command set for profile function application by UART, such as HFP/A2DP/AVRCP and so on. These profiles function application can be controlled only by PIO, such as pairing/connect/answer/play/pause/next/previous function application and so on.

4.8.2 I2C Interface

As this I2C interface is software-driven it is suited to relatively slow functions such as driving a dot matrix LCD, keyboard scanner or EEPROM. If it is not used, then PIO[7:6] are available to form a software-driven master I2C interface.

4.8.3 SPI

The synchronous serial port interface (SPI) can be used for system debugging. It can also be used for in-system programming for the flash memory within the module. SPI interface uses the SPI_MOSI, SPI_MISO, SPI_CSB and SPI_CLK pins. Testing points for the SPI interface are reserved on board in case that the firmware shall be updated during manufacture.

The module operates as a slave and thus SPI_MISO is an output of the module. SPI_MISO is not in high-impedance state when SPI_CSB is pulled high. Instead, the module outputs 0 if the processor is running and 1 if it is stopped. Thus the module should NOT be connected in a multi-slave arrangement by simple parallel connection of slave SPI_MISO lines.



Figure 6

5. ELECTRICAL CHARACTERISTICS

5.1 Absolute Maximum Ratings

Rating		Min	Max	Unit
Storage temperate	ıre	-40	105	°C
Supply Voltage				
5V(USB VBUS)	VCHG	-0.4	5.75	V
3.3V	SMPS_3V3	-0.4	3.60	V
	VDD_USB	-0.4	3.60	V
	LED[2:0]	-0.4	4.40	V
Battery	SMP VBAT	-0.4	4.40	V
		-0.4	5.75	V
		-0.4	4.40	V
	VDD_AUDIO_DRV	-0.4	1.95	V
	VDD_AUX_1V8	-0.4	1.95	V
1.8V	VDD_PADS_1	-0.4	3.60	V
	VDD_PADS_2	-0.4	3.60	V
	VDD_PADS_3	-0.4	3.60	V
	SMPS_1V8_SENSE	-0.4	1.95	V
	SMPS_1V35_SENSE	-0.4	1.45	V
1.35V	VDD_AUDIO	-0.4	1.45	V
	VREGIN_DIG	-0.4	1.95	V
Other terminal vo	ltages	VSS - 0.4	VDD + 0.4	V

Table 1

5.2 Recommended Operating Conditions

Rating		Mi	Тур	Max	Uni
Operating temperature range		-40	20	85	°C
Supply Voltage					
	VCHG	4.75 / 3.10	5.00	5.75	V
3.3V	SMPS_3V3	3.10	3.30	3.60	V
	VDD_USB	3.10	3.30	3.60	V
	LED[2:0]	1.10	3.70	4.25	V
Battery	SMP_VBAT	2.50	3.70	4.25	V
	VBAT_SENSE	0	3.70	4.25	V
	VDD_AUDIO_DRV	1.70	1.80	1.95	V
1.8V	VDD_AUX_1V8	1.70	1.80	1.95	V
	VDD_PADS_1	1.70	1.80	3.60	V
	VDD_PADS_2	1.70	1.80	3.60	V
	VDD_PADS_3	1.70	1.80	3.60	
	SMPS_1V8_SENSE	1.70	1.80	1.95.	V
	SMPS_1V35_SENSE	1.30	1.35	1.40	V
1.35V	VDD_AUDIO	1.30	1.35	1.40	V
	VREGIN_DIG	1.30	1.35 or 1.80	1.95	V

Table 2



5.3 Input/output Terminal Characteristics

5.3.1 Codec: Analogue to Digital Converter

Analogue to Digital C	Converter					
Parameter	Conditions		Mi	Тур	Max	Uni
Resolution	-		-	-	16	Bits
Input Sample Rate,	-		8	-	48	kHz
		Fsample				
	f _{in} = 1kHz	8kHz	-	93	-	dB
	$B/W = 20Hz \rightarrow F_{sample}/2$	16kHz	-	92	-	dB
SNR	(20kHz	32kHz	-	92	-	dB
	max)	44.1kHz	-	92	-	dB
	A-Weighted	48kHz	-	92	-	dB
	fin = 1kHz	F _{sample}	z - 92 -			
THD+N	$B/W = 20Hz \rightarrow F_{sample}/2$	8kHz	-	0.004	-	%
	(20kHz max)	48kHz	-	0.008	-	%
Digital gain	Digital gain resolution = 1	1/32	-24	-	21.5	dB
Analogue gain	Pre-amplifier setting = 0d 30dB Analogue setting = -3dB t steps	Pre-amplifier setting = 0dB, 9dB, 21dB or 30dB Analogue setting = -3dB to 12dB in 3dB			42	dB
Stereo separation(cros	stalk)		-	-89	-	dB

Table 3

5.3.2 Codec: Digital to Analogue Converter

Digital to Analogue	Converter						
Parameter	Conditions			Mi	Тур	Max	Uni
Resolution	-			-	-	16	Bits
Output Sample Rate, F _{sample}	-			8	-	96	kHz
	6 11 11	Fsample	Load				
	$I_{in} = I K H Z$	48kHz	100kΩ	-	96	-	dB
SNR	$B/W = 20HZ \rightarrow 20KHZ$	48kHz	32Ω	-	96	-	dB
	THD $N > 0.1\%$	48kHz	16Ω	-	96	-	dB
	$\begin{array}{c c c c c c c c c c c c c c c c c c c $						
THD+N		8kHz	100kΩ	-	0.002	-	%
	f _{in} = 1kHz B/W = 20Hz→20kHz 0dBFS input	8kHz	32Ω	-	0.002	-	%
		8kHz	16Ω	-	0.003	-	%
		48kHz	100kΩ	-	0.003	-	%
		48kHz	32Ω	-	0.003	-	%
		48kHz	16Ω	-	0.004	-	%
Digital Gain	Digital Gain Resolution	n = 1/32		-24	-	21.5	dB
Analogue Gain	Analogue Gain Resolut	tion = 3dB		-21	-	0	dB
Stereo separation(cro	osstalk)			-	-88-	-	dB

Table 4

6. RECOMMENDED TEMPERATURE REFLOW PROFILE

The soldering profile depends on various parameters necessitating a set up for each application. The data here is given only for guidance on solder reflow.

				\$	Site:					
Oven Name: WQ				K.	Process Win	dow Name: 无铅				
Setnoints (Celsius)										
Zone	1 2	3	4	5 6	7	8				
Тор	140 150	170	170 1	190 225	265	230				
Bottom Convoyor Speed (om/min	140 150): 75.0	170	170 1	190 225	265	230				
Conveyor Speed (cm/mm	j. 73.0									
250										
								-		
200								Non a		
(A)										
1 50					_					
100									Í	
l ll										
50										
Z1	Z2	Z3 100	Z4	Z\$ 150	Z6 20	Z7 00	Z8 250		300	:
					Seconds					
PWI=304%	Max R	lising Slope	Prehe	at 110-190C	Soak T	lime 150-180C	Reflow 1	Fime /220C	Peal	K Temp
2	4.0	189%	141.4	15/%	70.4	-296%	71.1	103%	254.8	9/%
4	3.9	192%	142.1	160%	69.6	-304%	71.2	112%	256.5	1309
rocess Window:										
older Paste:	SYSTEM DEFAUL	1								
Statistic Name	Low	v Limit High	Limit Units							
Max Rising Slope (Target Probect Time 110, 100C	=2.0) 0.0	3.0	Degrees	s/Second						
Soak Time 150-180C	90	110	Second	5						
Time Above Reflow - 220	C 50	70	Second	s						
Dool: Termperature	245	255	Degrees Celsius	;						

Figure 7

7. PACKAGING INFORMATION

1. BLUETOOTH[®] Module: BTM8670



2. Assembly







3. Dimension



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