

MIL-STD-1553 TRANSCEIVER

FEATURES

 MEETS ALL MIL-STD-1553A AND 1553B REQUIREMENTS

VERY LOW POWER DISSIPATION

IMPROVED FILTERING ON
 RECEIVER TO ENHANCE BIT
 ERROR RATE OF SYSTEM DataSher

±15V OR +15V AND -12V
 POWER SUPPLY VOLTAGES

• SCREENED TO MIL-STD-883

 HARRIS 15530 ENCODER/ DECODER DIRECT INTERFACE COMPATIBILITY

DESCRIPTION

The BUS-8553 Transceiver is a complete transmitter and receiver conforming fully to MIL-STD-1553A and 1553B. Features of this high reliability transceiver include: Harris 15530 type Encoder/Decoder direct interface capability, ±15V or +15V and -12V power supply voltage requirements, and an internal (factory pre-set) threshold level.

Figure 1 illustrates a block diagram of the BUS-8553 Transceiver. The receiver section accepts phase-modulated bipolar data from a MIL-STD-1553 Data Bus and produces TTL signal data at its outputs: RX Data Out and RX Data Out. These outputs represent positive and negative excursions of the input Bus signals beyond a preset threshold level. The receiver can be taken off-line (outputs disabled) by the

application of a logic "0" to the STROBE input.

The transmitter section accepts bipolar TTL signal data at its TX Data and TX Data input lines and produces a 28Vpp differential signal across a 140 Ohm load that's coupled to the TX Data and TX Data outputs via transformer. An external input, INHIBIT, takes priority over the transmitter inputs and disables the transmitter when activated with a logic "1".

The BUS-8553 Transceiver is packaged in a 24 pin DDIP, measuring 1.4 x 0.8 x 0.2 inches. Its small size, low power dissipation, and direct interface compatibility with Harris 15530 type Encoder/Decoder make it an excellent choice for any MIL-STD-1553A or 1553B Transceiver application.

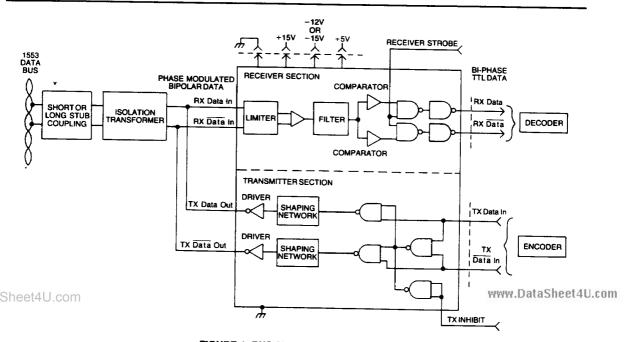


FIGURE 1. BUS-8553 BLOCK DIAGRAM

DataSheet4U.com



BUS-8553

TABLE 1. BUS-8553 SPECIFICATIONS				
PARAMETER	VALUE			
RECEIVER Input Level Internal Threshold ⁽¹⁾ CMRR Input Resistance, differential Input Capacitance, differential	40Vpp, differential, max 0.56Vpp min, 1Vpp max 40 db, min 7K Ohm, min 5pf, max			
DRIVER Output Level Rise/Fall Time	28Vpp, nominal, across 140 Ohm load 130ns, typical			
Output Noise Output Offset	10mVpp, differential, max ±90mVpp, max differential across 35Ω load			
Output Impedance (Non-Transmitting) Output Resistance, differential Output Capacitance, differential	10K Ohm, min 5pf, max			
LOGIC; TTL/CMOS Compatible Receiver Strobe Input All Logic Outputs (Receiver) Transmitter Inhibit Input Transmitter TX Data	2LSTTL loads, max 10 LSTTL loads, min 1 TTL load, max			
and TX Data inputs	2 TTL loads, max			
POWER SUPPLY REQMTS		+15V±5%	-15V±5%	
Non-Transmitting (typ/max) Transmitting, 50% duty cycle (typ/max) Transmitting, 100% duty cycle (typ/max)		30/40mA 110/130mA 200/220mA	Dotos	
THERMAL Operating Junction Temp. (2) Operating Case Temperature (2) Storage Temperature Thermal Resistance	-55°C to 160°C -55°C to 125°C -65°C to 150°C			
Junction to Case (Hottest Die) Case to Air	110°C/W 30°C/W			
POWER DISSIPATION Non-Transmitting (typ/max) Transmitting, 50% duty cycle	1.0/1.3W			
(typ/max) Transmitting, 100% duty cycle	1.7/2.0W			
(typ/max) POWER DISSIPATION	2.3/2.8W			
Transmitting, 50% duty cycle (typ/max)	0.14/0.16			
Transmitting, 100% duty cycle (typ/max)	0.28/0.31	iw		
MECHANICAL Size, 24 Pin DDIP, inches (mm) Weight	1.4×0.8×0.2 (35.6×20.3×5.1) 0.4 oz typ			

Notes:

et4U

(1) The Threshold Level, as referred to in this specification, is meant to be the maximum peak to peak voltage (measured on the Data Bus) that can be applied to the receiver without causing the output to change from the OFF state.
(2) For any transmitting duty cycle (derating not required).

DataSheet4U.com

GENERAL

Figure 1 illustrates a BUS-8553 Transceiver with connections to a MIL-STD-1553 data bus. Once transformer isolated, coupling

to a MIL-STD-1553 Data Bus can be either short stub (direct) or long stub (transformer.) Figure 2 illustrates direct and transformer coupling between the transceiver and the data bus.

TRANSMIT OPERATING MODE

The transmitter section accepts encoded TTL data and converts this data to phase-modulated bipolar form by means of a wave-shaping network and driver circuitry. These driver outputs are coupled to a MIL-STD-1553 Data Bus by means of a transformer. These output terminals can be put into a high impedance state when transmitting by enabling the INHIBIT, or by placing both inputs at the same logic level. Table 2 is the truth table for the transmitter operating mode.

The transceiver's transmitter is able to operate in a "wraparound" mode; this allows output data to be monitored by the receiver section and returned to the decoder where it can be checked for errors.

TABLE 2. TRANSMITTER OPERATING MODE				
TX Data in	TX Data In	TXINHIBIT	DRIVER OUTPUT(1)	
X ⁽²⁾	×	Н	OFF	
0	0	х	OFF	
0	1	L	ON ⁽³⁾	
1	0	L	ON	
et4U.com	1 1	×	OFF ⁽⁴⁾⁽⁵⁾	

Notes

- (1) Driver Out = TX Data Out and TXData Out
- (2) X = don't care.
- (3) ON = low impedance
- (4) OFF = high impedance.
- (5) The driver output terminals are in the high impedance mode during OFF time, independent of INHIBIT status.

RECEIVER OPERATING MODE

The receiver section accepts data from a MIL-STD-1553 Data Bus when properly coupled through a transformer in any of the two possible configurations (long or short stub), and converts it to bi-phase TTL and makes it available for decoding at the RX Data and RX Data output terminals. Applying a logic "0" to the STROBE input disables the receiver outputs, causing them both to go to a logic "0" state. When not being used, a 2K pull-up resistor should be connected between the STROBE input terminal (pin 8) and the +5V supply (pin 20).

BUS-8553 WAVEFORMS

Figure 3 illustrates the waveforms for the BUS-8553 Transceiver.

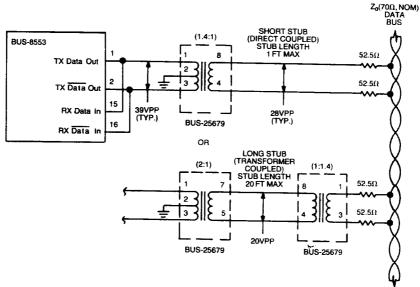
CAUTION

- (1) Complementary inputs on the TX Data and TX Data for more than 10 seconds may cause permanent damage to the BUS-8553 at high temperatures due to high power dissipation in the driver output transistors.
- (2) When transmitting, TX Data and TX/Data another eet 4U.com must be complementary waveforms of 50% duty cycle average, with no gate delays or skewing between them. It is recommended that the inputs be driven with a properly gated "D-type" flip-flop.

DataSheet4U.con



BUS-8553



DataShe

Notes:

et4U.com

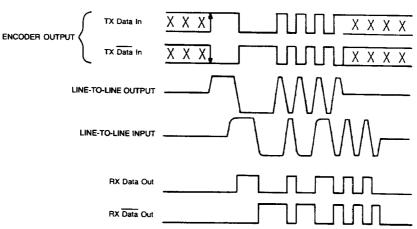
- Notes:

 (1) Only one connection can be made from the Transceiver to the MiL-STD-1553 Data Bus, either short or long stub, but not both.

 (2) Value of isolation resistors are 52.5\(\Omega\$) (0.75Z_o).

 (3) Bus must be terminated with its characteristic impedance at both ends.

FIGURE 2. TRANSCEIVER TO DATA BUS COUPLING CONNECTIONS



- Notes:
 (1) TX Data In and RX Data Out are TTL signals.
 (2) TX Data In lines must be at opposite logic levels during transmission, and at the same logic level when not transmitting.
 (3) LINE-TO-LINE output voltage is measured between TX Data and TX Data Out.
 (4) LINE-TO-LINE input voltage is measured on the Data Bus.
 (5) RX Data outputs are OFF when in the LOW state.

 DataSheet4U.con1 and inverting their signal with external inverting gates.

et4U



BUS-8553

TABLE 3. BUS-6553 PIN CONNECTIONS 24 PIN DDIP		
PIN	FUNCTION	
1	TX Data Out	
2	TX Data Out	
3	GND	
4	NC	
5	NC	
6	NC	
7	RX Data Out	
8	Strobe	
9	GND	
10	RX Data Out	
11	NC	
nm 12	NC	
13	+15VDC	
14	NC	
15	RX Data in	
16	RX Data In	
17	NC	
18	GND	
19	-12V or -15VDC	
20	+5VDC	
21	TX Inhibit	
22	TX <u>Data in</u>	
23	TX Data In	
24	NC	

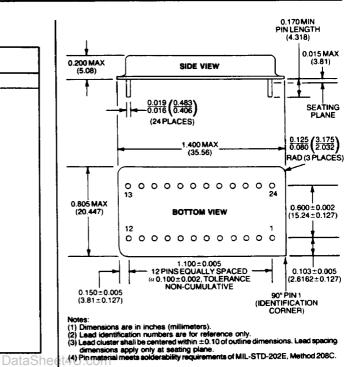


FIGURE 4. MECHANICAL OUTLINE 24 PIN DDIP

ORDERING INFORMATION

BUS-8553-<u>883B</u>

-Reliability Grade:

883B = Fully compliant with MIL-STD-883

B = Screened to MIL-STD-883 but

without QCI testing.

Blank = Standard DDC procedures.

Mating Transformer BUS-25679

www.DataSheet4U.com