# HAMAMATSU

**DATA SHEET** 

# Position Sensor C7339 (For Laser Beam Alignment)



The C7339 Position Sensor is an opto-electric positionsensing unit which measures the position of a single point of light spot-focused onto the sensor head.

The use of hybrid circuitry allows for a compact, light-weight design and a divided configuration with a light, compact sensor head and a controller equipped with a light level indicator and data displays for ease of operation. The measured position is displayed digitally in terms of X- and Y-coordinate voltages on the front panel of the controller and may be simultaneously output to a recorder.

The C7339 does not possess a background-light cancellation function and is suited for use in locations where the signal light is distinct from the background such as in the detection of laser beams.

### SYSTEM CONFIGURATION EXAMPLE

## **FEATURES**

#### Quick Response

The response time of less than 20µs enables accurate measurement of the spot, even while it is moving at high speeds.

#### Stable Measurement

The position data (X-Y coordinate voltages) of a light spot is obtained without being affected by signal current fluctuations from the PSD, enabling accurate position measurement regardless of fluctuations in the light intensity.

#### Broad Spectral Response

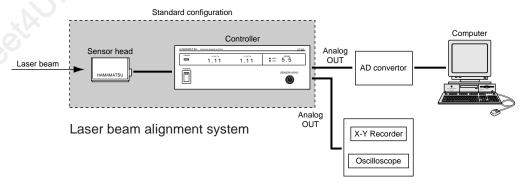
The C7339 has a broad spectral range, from 300 to 1100 nm, enabling the detection of a variety of light sources, including lasers.

#### High Resolution

The PSD employed in the sensor head is of the non-discrete type, which, contrary to a discrete-type sensor, has no insensitive area. This enables continuous measurement at a high resolution of 1/5000 (when using a recorder).

#### Light Level Indicator

The input light level is indicated in digits on the front panel of the control unit (0.00 to 10.0) so as to make it easy to adjust the lens iris and select an ND filter.



## OTHER APPLICATIONS

- Surface Flatness Measurement
- Solar Tracking Systems

# CONFIGURATION

Sensor head (C73	39-01)	1
Controller (C7339-	0X*)	1
AC cable (2m)		1
Head connecting of	able (5m)	1
Signal cables (BN0	C-BNC, 3m)	2
Fuses (1A)		3
Line voltage $*X = 3$	2	100V
;	3	117V
	4	220V
:	5	240V

## OPTIONAL

Metal interference filters Filter adapter

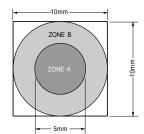


Fig.1 Useful Sensitive Area and Zones A and B

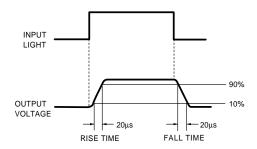


Fig.2 Rise and fall time of the output voltage when a pulsed light is applied to the center of the sensitive area.

The rise time is the period of time required for the output voltage to rise from 10% to 90% of its full level.

The fall time is the period required for the output voltage to return from 90% to 10%.

# SPECIFICATIONS

Detector	Non-discrete position-sensitive detector (Hamamatsu S1880-03)	
Useful sensitive area (Fig.1)	10 × 10mm	
Lens mount	C mount	
Output voltage: X-axis	- 5 to + 5V	
Y-axis	– 5 to + 5V	
Output impedance	500Ω ± 10%	
Response speed (Fig.2)	Within 20μs	
Recommended measurement light level	Light level ( $\Sigma$ ) = 8 (Displayed on a level indicator)	
Position detection error	Zone A (refer to figure below) ±1.0%, Zone B ±2.0%	
Error due to light intensity variations	$\pm 1\%$ (Light level ( $\Sigma$ ) = 8 $\rightarrow$ 4)	
Resolution (when using a recorder)	1/5000	
Jitter	±1.5/1000	
Drift	±0.5%/day (after the first 30 minutes)	
Operating temperature	0 to +40°C	
Storage temperature	−10 to +50°C	
Operating/storage humidity	Less than 90% (with no condensation)	
Line voltage	100/117/220/240VAC ±10%, 50/60Hz	
Power consumption	Approx. 30VA	

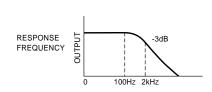


Fig.3 Response frequency of the output voltage when a spot light is moved right and left repeatedly while it is being applied to the sensitive area.

## **OPTIMUM INPUT LASER POWER**

Laser	Wavelength	Input Laser Power
He-Ne Laser	632nm	Approx. 23μW
Ar Laser	514nm	Approx. 27μW

When light with the value on the table at the left is input, "8" appears on the display indicating the volume of incident light. If strong laser light is used, an ND filter or similar means should be used to reduce the volume of laser light to the optimum volume before beginning measurement.

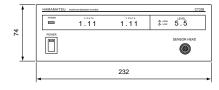
# DIMENTIONAL OUTLINE (UNIT:mm)

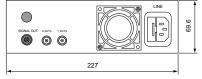
• Sensor head (Weight: Approx. 140g)





• Controller (Weight: Approx. 3.87kg)





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