

CY96670 series is based on Cypress's advanced F<sup>2</sup>MC-16FX architecture (16-bit with instruction pipeline for RISC-like performance). The CPU uses the same instruction set as the established F<sup>2</sup>MC-16LX family thus allowing for easy migration of F<sup>2</sup>MC-16LX Software to the new F<sup>2</sup>MC-16FX products.

F<sup>2</sup>MC-16FX product improvements compared to the previous generation include significantly improved performance - even at the same operation frequency, reduced power consumption and faster start-up time.

For high processing speed at optimized power consumption an internal PLL can be selected to supply the CPU with up to 32MHz operation frequency from an external 4MHz to 8MHz resonator. The result is a minimum instruction cycle time of 31.2ns going together with excellent EMI behavior. The emitted power is minimized by the on-chip voltage regulator that reduces the internal CPU voltage. A flexible clock tree allows selecting suitable operation frequencies for peripheral resources independent of the CPU speed.

## Features

### ■ Technology

0.18µm CMOS

### ■ CPU

- F<sup>2</sup>MC-16FX CPU
- Optimized instruction set for controller applications (bit, byte, word and long-word data types, 23 different addressing modes, barrel shift, variety of pointers)
- 8-byte instruction queue
- Signed multiply (16-bit × 16-bit) and divide (32-bit/16-bit) instructions available

### ■ System clock

- On-chip PLL clock multiplier (×1 to ×8, ×1 when PLL stop)
- 4MHz to 8MHz crystal oscillator (maximum frequency when using ceramic resonator depends on Q-factor)
- Up to 8MHz external clock for devices with fast clock input feature
- 32.768kHz subsystem quartz clock
- 100kHz/2MHz internal RC clock for quick and safe startup, clock stop detection function, watchdog
- Clock source selectable from mainclock oscillator, subclock oscillator and on-chip RC oscillator, independently for CPU and 2 clock domains of peripherals
- The subclock oscillator is enabled by the Boot ROM program controlled by a configuration marker after a Power or External reset
- Low Power Consumption - 13 operating modes (different Run, Sleep, Timer, Stop modes)

### ■ On-chip voltage regulator

Internal voltage regulator supports a wide MCU supply voltage range (Min=2.7V), offering low power consumption

### ■ Low voltage detection function

Reset is generated when supply voltage falls below programmable reference voltage

### ■ Code Security

Protects Flash Memory content from unintended read-out

### ■ DMA

Automatic transfer function independent of CPU, can be assigned freely to resources

### ■ Interrupts

- Fast Interrupt processing
- 8 programmable priority levels
- Non-Maskable Interrupt (NMI)

### ■ CAN

- Supports CAN protocol version 2.0 part A and B
- ISO16845 certified
- Bit rates up to 1Mbps
- 32 message objects
- Each message object has its own identifier mask
- Programmable FIFO mode (concatenation of message objects)
- Maskable interrupt
- Disabled Automatic Retransmission mode for Time Triggered CAN applications
- Programmable loop-back mode for self-test operation

### ■ USART

- Full duplex USARTs (SCI/LIN)
- Wide range of baud rate settings using a dedicated reload timer
- Special synchronous options for adapting to different synchronous serial protocols
- LIN functionality working either as master or slave LIN device
- Extended support for LIN-Protocol to reduce interrupt load

### ■ I<sup>2</sup>C

- Up to 400kbps
- Master and Slave functionality, 7-bit and 10-bit addressing

- A/D converter
  - SAR-type
  - 8/10-bit resolution
  - Signals interrupt on conversion end, single conversion mode, continuous conversion mode, stop conversion mode, activation by software, external trigger, reload timers and PPGs
  - Range Comparator Function
  - Scan Disable Function
  - ADC Pulse Detection Function
- Source Clock Timers
  - Three independent clock timers (23-bit RC clock timer, 23-bit Main clock timer, 17-bit Sub clock timer)
- Hardware Watchdog Timer
  - Hardware watchdog timer is active after reset
  - Window function of Watchdog Timer is used to select the lower window limit of the watchdog interval
- Reload Timers
  - 16-bit wide
  - Prescaler with  $1/2^1$ ,  $1/2^2$ ,  $1/2^3$ ,  $1/2^4$ ,  $1/2^5$ ,  $1/2^6$  of peripheral clock frequency
  - Event count function
- Free-Running Timers
  - Signals an interrupt on overflow
  - Prescaler with  $1$ ,  $1/2^1$ ,  $1/2^2$ ,  $1/2^3$ ,  $1/2^4$ ,  $1/2^5$ ,  $1/2^6$ ,  $1/2^7$ ,  $1/2^8$  of peripheral clock frequency
- Input Capture Units
  - 16-bit wide
  - Signals an interrupt upon external event
  - Rising edge, Falling edge or Both (rising & falling) edges sensitive
- Programmable Pulse Generator
  - 16-bit down counter, cycle and duty setting registers
  - Can be used as  $2 \times 8$ -bit PPG
  - Interrupt at trigger, counter borrow and/or duty match
  - PWM operation and one-shot operation
  - Internal prescaler allows  $1$ ,  $1/4$ ,  $1/16$ ,  $1/64$  of peripheral clock as counter clock or of selected Reload timer underflow as clock input
  - Can be triggered by software or reload timer
  - Can trigger ADC conversion
  - Timing point capture
- Stepping Motor Controller
  - Stepping Motor Controller with integrated high current output drivers
  - Four high current outputs for each channel
  - Two synchronized 8/10-bit PWMs per channel
  - Internal prescaling for PWM clock:  $1$ ,  $1/4$ ,  $1/5$ ,  $1/6$ ,  $1/8$ ,  $1/10$ ,  $1/12$ ,  $1/16$  of peripheral clock
  - Dedicated power supply for high current output drivers
- LCD Controller
  - LCD controller with up to  $4\text{COM} \times 24\text{SEG}$
  - Internal or external voltage generation
  - Duty cycle: Selectable from options:  $1/2$ ,  $1/3$  and  $1/4$
  - Fixed  $1/3$  bias
  - Programmable frame period
  - Clock source selectable from four options (main clock, peripheral clock, subclock or RC oscillator clock)
  - Internal divider resistors or external divider resistors
  - On-chip data memory for display
  - LCD display can be operated in Timer Mode
  - Blank display: selectable
  - All SEG, COM and V pins can be switched between general and specialized purposes
- Sound Generator
  - 8-bit PWM signal is mixed with tone frequency from 16-bit reload counter
  - PWM clock by internal prescaler:  $1$ ,  $1/2$ ,  $1/4$ ,  $1/8$  of peripheral clock
- Real Time Clock
  - Operational on main oscillation (4MHz), sub oscillation (32kHz) or RC oscillation (100kHz/2MHz)
  - Capable to correct oscillation deviation of Sub clock or RC oscillator clock (clock calibration)
  - Read/write accessible second/minute/hour registers
  - Can signal interrupts every half second/second/minute/hour/day
  - Internal clock divider and prescaler provide exact 1s clock
- External Interrupts
  - Edge or Level sensitive
  - Interrupt mask bit per channel
  - Each available CAN channel RX has an external interrupt for wake-up
  - Selected USART channels SIN have an external interrupt for wake-up
- Non Maskable Interrupt
  - Disabled after reset, can be enabled by Boot-ROM depending on ROM configuration block
  - Once enabled, can not be disabled other than by reset
  - High or Low level sensitive
  - Pin shared with external interrupt 0
- I/O Ports
  - Most of the external pins can be used as general purpose I/O
  - All push-pull outputs (except when used as I2C SDA/SCL line)
  - Bit-wise programmable as input/output or peripheral signal
  - Bit-wise programmable input enable
  - One input level per GPIO-pin (either Automotive or CMOS hysteresis)
  - Bit-wise programmable pull-up resistor

**■ Built-in On Chip Debugger (OCD)**

- One-wire debug tool interface
- Break function:
  - Hardware break: 6 points (shared with code event)
  - Software break: 4096 points
- Event function
  - Code event: 6 points (shared with hardware break)
  - Data event: 6 points
  - Event sequencer: 2 levels + reset
- Execution time measurement function
- Trace function: 42 branches
- Security function

**■ Flash Memory**

- Dual operation flash allowing reading of one Flash bank while programming or erasing the other bank
- Command sequencer for automatic execution of programming algorithm and for supporting DMA for programming of the Flash Memory
- Supports automatic programming, Embedded Algorithm
- Write/Erase/Erase-Suspend/Resume commands
- A flag indicating completion of the automatic algorithm
- Erase can be performed on each sector individually
- Sector protection
- Flash Security feature to protect the content of the Flash
- Low voltage detection during Flash erase or write

## Contents

<b>1. Product Lineup</b> .....	<b>6</b>
<b>2. Block Diagram</b> .....	<b>7</b>
<b>3. Pin Assignment</b> .....	<b>8</b>
<b>4. Pin Description</b> .....	<b>9</b>
<b>5. Pin Circuit Type</b> .....	<b>11</b>
<b>6. I/O Circuit Type</b> .....	<b>13</b>
<b>7. Memory Map</b> .....	<b>19</b>
<b>8. RAMSTART Addresses</b> .....	<b>20</b>
<b>9. User ROM Memory Map For Flash Devices</b> .....	<b>21</b>
<b>10. Serial Programming Communication Interface</b> .....	<b>22</b>
<b>11. Interrupt Vector Table</b> .....	<b>23</b>
<b>12. Handling Precautions</b> .....	<b>27</b>
12.1 Precautions for Product Design .....	27
12.2 Precautions for Package Mounting.....	28
12.3 Precautions for Use Environment.....	29
<b>13. Handling Devices</b> .....	<b>30</b>
13.1 Latch-Up Prevention.....	30
13.2 Unused Pins Handling .....	30
13.3 External Clock Usage .....	31
13.3.1 Single Phase External Clock for Main Oscillator .....	31
13.3.2 Single Phase External Clock for Sub Oscillator .....	31
13.3.3 Opposite Phase External Clock.....	31
13.4 Notes on PLL Clock Mode Operation .....	31
13.5 Power Supply Pins (Vcc/Vss).....	31
13.6 Crystal Oscillator and ceramic resonator Circuit.....	32
13.7 Turn on Sequence of Power Supply to A/D Converter and Analog Inputs.....	32
13.8 Pin Handling when not using the A/D Converter .....	32
13.9 Notes on Power-on.....	32
13.10 Stabilization of Power Supply Voltage .....	32
13.11 SMC Power Supply Pins .....	32
13.12 Serial Communication .....	32
13.13 Mode Pin (MD) .....	32
<b>14. Electrical Characteristics</b> .....	<b>33</b>
14.1 Absolute Maximum Ratings.....	33
14.2 Recommended Operating Conditions .....	35
14.3 DC Characteristics .....	36
14.3.1 Current Rating.....	36
14.3.2 Pin Characteristics .....	39
14.4 AC Characteristics.....	42
14.4.1 Main Clock Input Characteristics.....	42
14.4.2 Sub Clock Input Characteristics .....	43
14.4.3 Built-in RC Oscillation Characteristics.....	44
14.4.4 Internal Clock Timing .....	44
14.4.5 Operating Conditions of PLL .....	45
14.4.6 Reset Input.....	45
14.4.7 Power-on Reset Timing.....	46

14.4.8 USART Timing .....	47
14.4.9 External Input Timing .....	49
14.4.10 I <sup>2</sup> C Timing.....	50
14.5 A/D Converter.....	51
14.5.1 Electrical Characteristics for the A/D Converter .....	51
14.5.2 Accuracy and Setting of the A/D Converter Sampling Time .....	52
14.5.3 Definition of A/D Converter Terms .....	53
14.6 High Current Output Slew Rate .....	55
14.7 Low Voltage Detection Function Characteristics .....	56
14.8 Flash Memory Write/Erase Characteristics .....	58
<b>15. Example Characteristics .....</b>	<b>59</b>
<b>16. Ordering Information .....</b>	<b>62</b>
<b>17. Package Dimension .....</b>	<b>63</b>
<b>18. Major Changes .....</b>	<b>65</b>
<b>Document History.....</b>	<b>68</b>
<b>Sales, Solutions, and Legal Information.....</b>	<b>69</b>

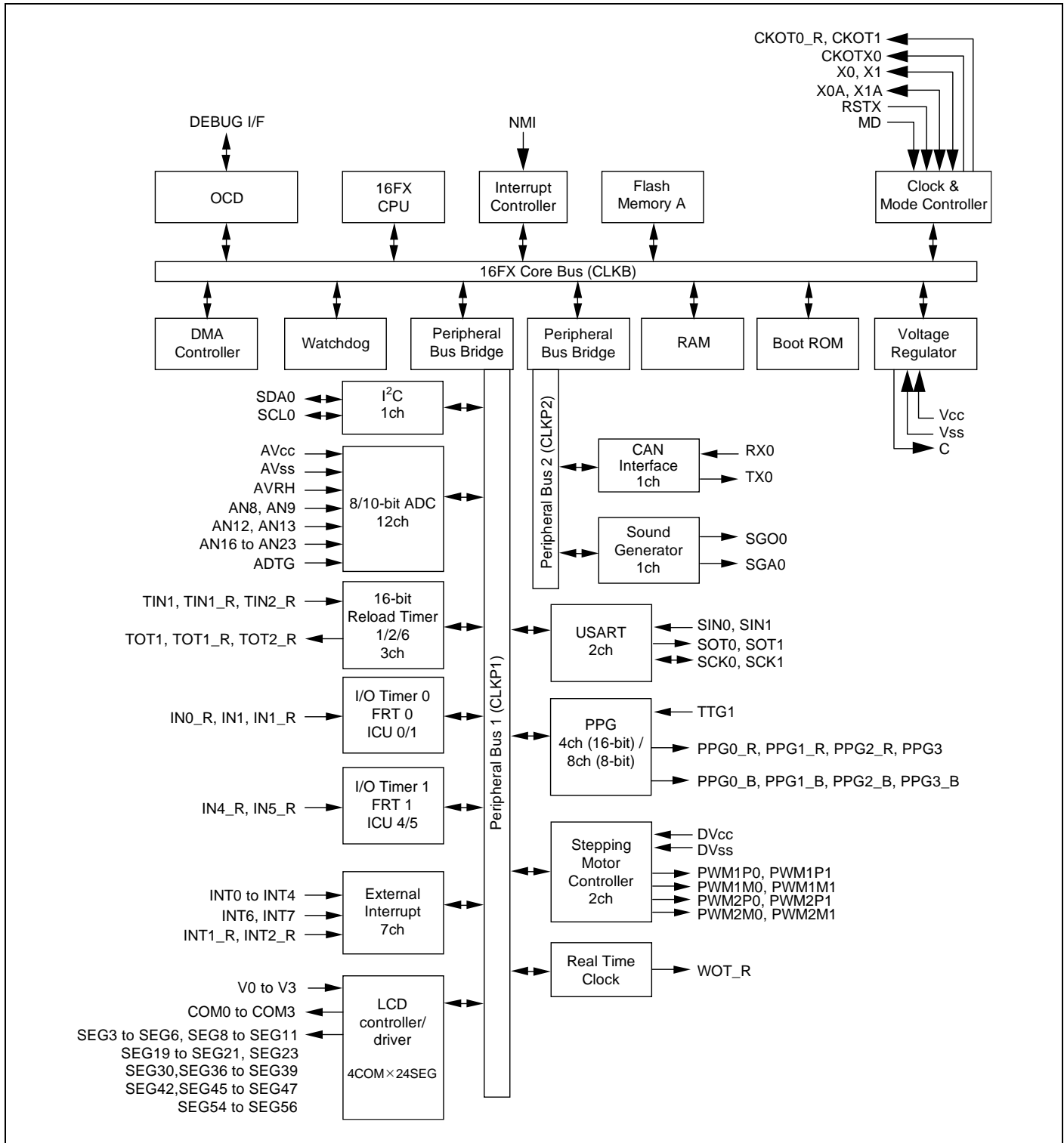
**1. Product Lineup**

Features		CY96670	Remark
Product Type		Flash Memory Product	
Subclock		Subclock can be set by software	
Dual Operation Flash Memory	RAM	-	
64.5KB + 32KB	4KB	CY96F673R, CY96F673A	Product Options R: MCU with CAN A: MCU without CAN
128.5KB + 32KB	4KB	CY96F675R, CY96F675A	
Package		LQFP-64 LQG064/LQD064	
DMA		2ch	
USART		2ch	LIN-USART 0/1
	with automatic LIN-Header transmission/reception	Yes (only 1ch)	LIN-USART 0
	with 16 byte RX- and TX-FIFO	No	
I <sup>2</sup> C		1ch	I <sup>2</sup> C 0
8/10-bit A/D Converter		12ch	AN 8/9/12/13/16 to 23
	with Data Buffer	No	
	with Range Comparator	Yes	
	with Scan Disable	Yes	
	with ADC Pulse Detection	Yes	
16-bit Reload Timer (RLT)		3ch	RLT 1/2/6
16-bit Free-Running Timer (FRT)		2ch	FRT 0/1
16-bit Input Capture Unit (ICU)		4ch (2 channels for LIN-USART)	ICU 0/1/4/5 ICU 0/1 for LIN-USART
8/16-bit Programmable Pulse Generator (PPG)		4ch (16-bit) / 8ch (8-bit)	PPG 0 to 3
	with Timing point capture	Yes	
	with Start delay	No	
	with Ramp	No	
CAN Interface		1ch	CAN 0 32 Message Buffers
Stepping Motor Controller (SMC)		2ch	SMC 0/1
External Interrupts (INT)		7ch	INT 0 to 4/6/7
Non-Maskable Interrupt (NMI)		1ch	
Sound Generator (SG)		1ch	SG 0
LCD Controller		4COM x 24SEG	COM 0 to 3 SEG 3 to 6/8 to 11/ 19 to 21/23/30/36 to 39/42/45 to 47/54 to 56
Real Time Clock (RTC)		1ch	
I/O Ports		48 (Dual clock mode) 50 (Single clock mode)	
Clock Calibration Unit (CAL)		1ch	
Clock Output Function		2ch	
Low Voltage Detection Function		Yes	Low voltage detection function can be disabled by software
Hardware Watchdog Timer		Yes	
On-chip RC-oscillator		Yes	
On-chip Debugger		Yes	

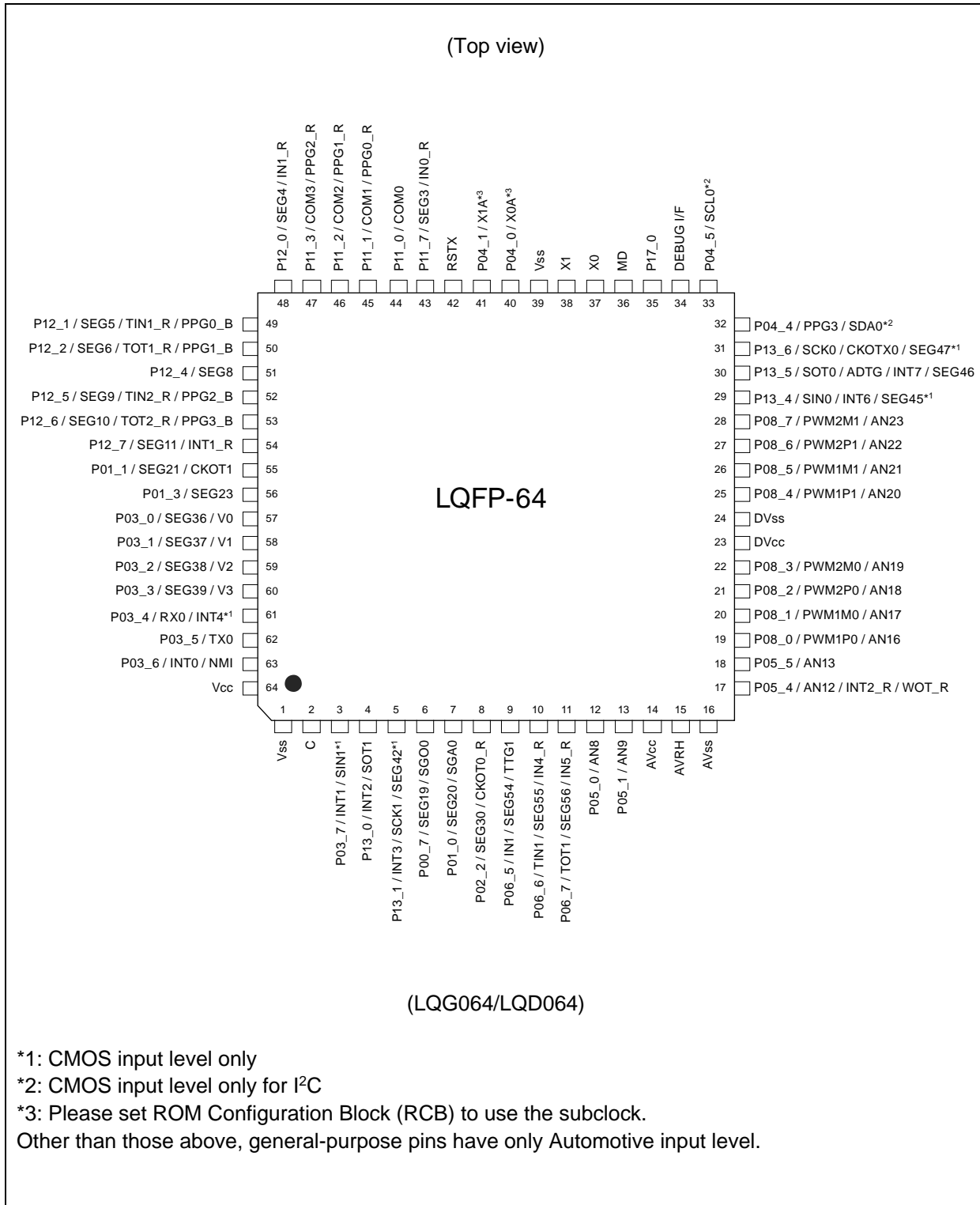
**Note:**

All signals of the peripheral function in each product cannot be allocated by limiting the pins of package. It is necessary to use the port relocate function of the general I/O port according to your function use.

## 2. Block Diagram



### 3. Pin Assignment





#### 4. Pin Description

Pin Name	Feature	Description
ADTG	ADC	A/D converter trigger input pin
ANn	ADC	A/D converter channel n input pin
AVcc	Supply	Analog circuits power supply pin
AVRH	ADC	A/D converter high reference voltage input pin
AVss	Supply	Analog circuits power supply pin
C	Voltage regulator	Internally regulated power supply stabilization capacitor pin
CKOTn	Clock Output function	Clock Output function n output pin
CKOTn_R	Clock Output function	Relocated Clock Output function n output pin
CKOTXn	Clock Output function	Clock Output function n inverted output pin
COMn	LCD	LCD Common driver pin
DEBUG I/F	OCD	On Chip Debugger input/output pin
DVcc	Supply	SMC pins power supply
DVss	Supply	SMC pins power supply
INn	ICU	Input Capture Unit n input pin
INn_R	ICU	Relocated Input Capture Unit n input pin
INTn	External Interrupt	External Interrupt n input pin
INTn_R	External Interrupt	Relocated External Interrupt n input pin
MD	Core	Input pin for specifying the operating mode
NMI	External Interrupt	Non-Maskable Interrupt input pin
Pnn_m	GPIO	General purpose I/O pin
PPGn	PPG	Programmable Pulse Generator n output pin (16bit/8bit)
PPGn_R	PPG	Relocated Programmable Pulse Generator n output pin (16bit/8bit)
PPGn_B	PPG	Programmable Pulse Generator n output pin (16bit/8bit)
PWMn	SMC	SMC PWM high current output pin
RSTX	Core	Reset input pin
RXn	CAN	CAN interface n RX input pin
SCKn	USART	USART n serial clock input/output pin
SCLn	I <sup>2</sup> C	I <sup>2</sup> C interface n clock I/O input/output pin
SDAn	I <sup>2</sup> C	I <sup>2</sup> C interface n serial data I/O input/output pin
SEGn	LCD	LCD Segment driver pin
SGAn	Sound Generator	Sound Generator amplitude output pin
SGOn	Sound Generator	Sound Generator sound/tone output pin
SINn	USART	USART n serial data input pin
SOTn	USART	USART n serial data output pin
TINn	Reload Timer	Reload Timer n event input pin
TINn_R	Reload Timer	Relocated Reload Timer n event input pin
TOTn	Reload Timer	Reload Timer n output pin
TOTn_R	Reload Timer	Relocated Reload Timer n output pin
TTGn	PPG	Programmable Pulse Generator n trigger input pin
TXn	CAN	CAN interface n TX output pin

Pin Name	Feature	Description
Vn	LCD	LCD voltage reference pin
Vcc	Supply	Power supply pin
Vss	Supply	Power supply pin
WOT_R	RTC	Relocated Real Time clock output pin
X0	Clock	Oscillator input pin
X0A	Clock	Subclock Oscillator input pin
X1	Clock	Oscillator output pin
X1A	Clock	Subclock Oscillator output pin

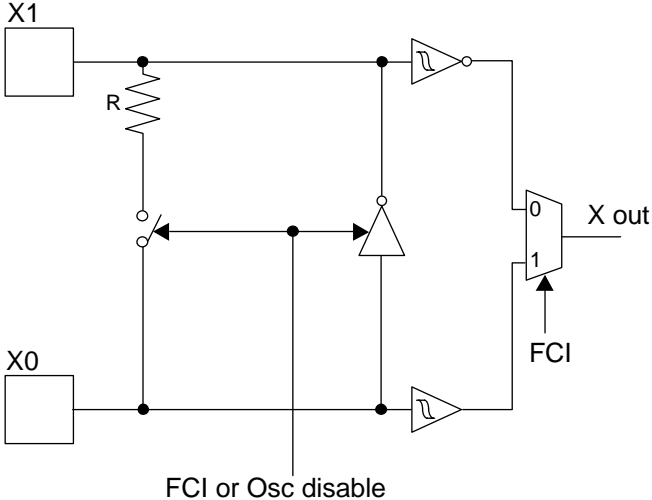
## 5. Pin Circuit Type

Pin No.	I/O Circuit Type*	Pin Name
1	Supply	Vss
2	F	C
3	M	P03_7 / INT1 / SIN1
4	H	P13_0 / INT2 / SOT1
5	P	P13_1 / INT3 / SCK1 / SEG42
6	J	P00_7 / SEG19 / SGO0
7	J	P01_0 / SEG20 / SGA0
8	J	P02_2 / SEG30 / CKOT0_R
9	J	P06_5 / IN1 / SEG54 / TTG1
10	J	P06_6 / TIN1 / SEG55 / IN4_R
11	J	P06_7 / TOT1 / SEG56 / IN5_R
12	K	P05_0 / AN8
13	K	P05_1 / AN9
14	Supply	AVcc
15	G	AVRH
16	Supply	AVss
17	K	P05_4 / AN12 / INT2_R / WOT_R
18	K	P05_5 / AN13
19	R	P08_0 / PWM1P0 / AN16
20	R	P08_1 / PWM1M0 / AN17
21	R	P08_2 / PWM2P0 / AN18
22	R	P08_3 / PWM2M0 / AN19
23	Supply	DVcc
24	Supply	DVss
25	R	P08_4 / PWM1P1 / AN20
26	R	P08_5 / PWM1M1 / AN21
27	R	P08_6 / PWM2P1 / AN22
28	R	P08_7 / PWM2M1 / AN23
29	P	P13_4 / SIN0 / INT6 / SEG45
30	J	P13_5 / SOT0 / ADTG / INT7 / SEG46
31	P	P13_6 / SCK0 / CKOTX0 / SEG47
32	N	P04_4 / PPG3 / SDA0

Pin No.	I/O Circuit Type*	Pin Name
33	N	P04_5 / SCL0
34	O	DEBUG I/F
35	H	P17_0
36	C	MD
37	A	X0
38	A	X1
39	Supply	Vss
40	B	P04_0 / X0A
41	B	P04_1 / X1A
42	C	RSTX
43	J	P11_7 / SEG3 / IN0_R
44	J	P11_0 / COM0
45	J	P11_1 / COM1 / PPG0_R
46	J	P11_2 / COM2 / PPG1_R
47	J	P11_3 / COM3 / PPG2_R
48	J	P12_0 / SEG4 / IN1_R
49	J	P12_1 / SEG5 / TIN1_R / PPG0_B
50	J	P12_2 / SEG6 / TOT1_R / PPG1_B
51	J	P12_4 / SEG8
52	J	P12_5 / SEG9 / TIN2_R / PPG2_B
53	J	P12_6 / SEG10 / TOT2_R / PPG3_B
54	J	P12_7 / SEG11 / INT1_R
55	J	P01_1 / SEG21 / CKOT1
56	J	P01_3 / SEG23
57	L	P03_0 / SEG36 / V0
58	L	P03_1 / SEG37 / V1
59	L	P03_2 / SEG38 / V2
60	L	P03_3 / SEG39 / V3
61	M	P03_4 / RX0 / INT4
62	H	P03_5 / TX0
63	H	P03_6 / INT0 / NMI
64	Supply	Vcc

\*: See "I/O CIRCUIT TYPE" for details on the I/O circuit types.

### 6. I/O Circuit Type

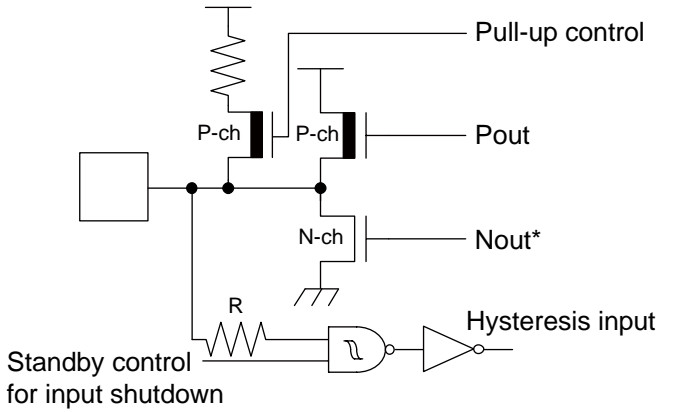
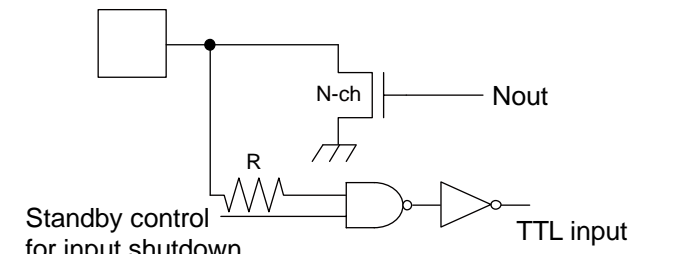
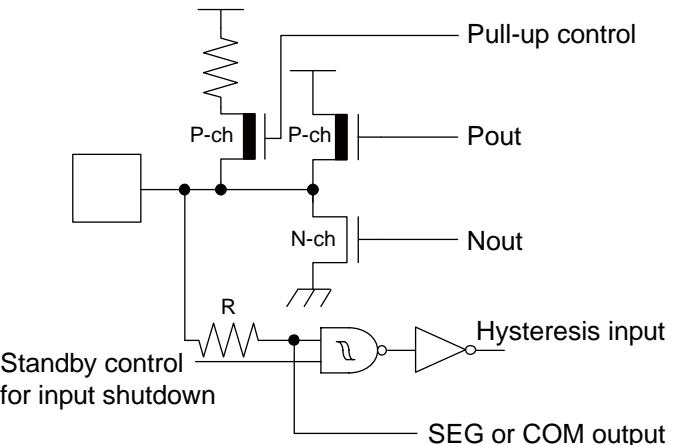
Type	Circuit	Remarks
A		<p>High-speed oscillation circuit:</p> <ul style="list-style-type: none"> <li>• Programmable between oscillation mode (external crystal or resonator connected to X0/X1 pins) and Fast external Clock Input (FCI) mode (external clock connected to X0 pin)</li> <li>• Feedback resistor = approx. 1.0MΩ</li> <li>• The amplitude: 1.8V±0.15V to operate by the internal supply voltage</li> </ul>

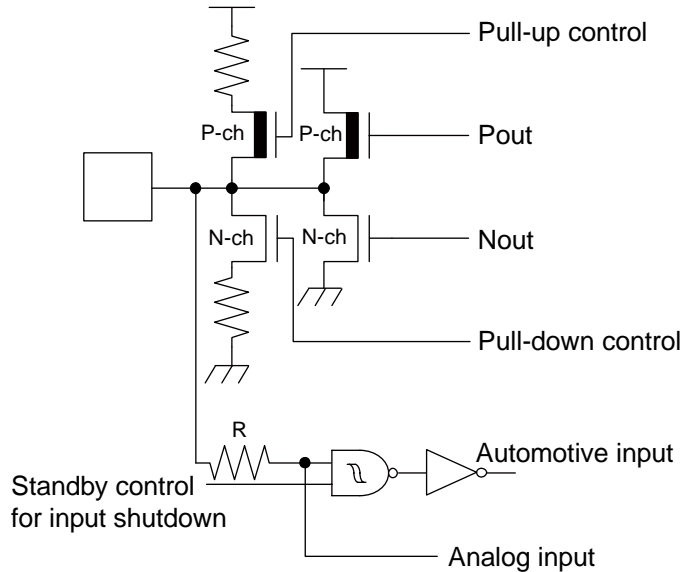
Type	Circuit	Remarks
B	<p>The diagram for Type B shows a complex input circuit. At the top, a pull-up resistor is connected to a 'Pull-up control' signal. Below it, two P-channel MOSFETs (P-ch) are shown, one labeled 'Pout'. An N-channel MOSFET (N-ch) is labeled 'Nout'. A 'Standby control for input shutdown' signal is connected to a resistor 'R' and an AND gate. The output of the AND gate is connected to an 'Automotive input' through an inverter. Below this, two input pins 'X1A' and 'X0A' are shown. Each has a pull-up resistor 'R' and is connected to a switch. The outputs of these switches are connected to a differential pair of inverters. The outputs of these inverters are connected to a multiplexer labeled 'X out'. The multiplexer has two inputs, '0' and '1', and is controlled by 'FCI'. A 'FCI or Osc disable' signal is also connected to the circuit. At the bottom, there is another pull-up control section with P-ch and N-ch MOSFETs, and an 'Automotive input' section similar to the one above.</p>	<p>Low-speed oscillation circuit shared with GPIO functionality:</p> <ul style="list-style-type: none"> <li>• Feedback resistor = approx. 5.0MΩ</li> <li>• GPIO functionality selectable (CMOS level output (<math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math>), Automotive input with input shutdown function and programmable pull-up resistor)</li> </ul>
C	<p>The diagram for Type C shows a simple input circuit. A resistor 'R' is connected to an input pin, which is then connected to a hysteresis input pin through a dashed box containing two inverters connected in a feedback loop.</p>	<p>CMOS hysteresis input pin</p>

Type	Circuit	Remarks
F		<p>Power supply input protection circuit</p>
G		<ul style="list-style-type: none"> <li>• A/D converter ref+ (AVRH) power supply input pin with protection circuit</li> <li>• Without protection circuit against V<sub>CC</sub> for pins AVRH</li> </ul>
H		<ul style="list-style-type: none"> <li>• CMOS level output (I<sub>OL</sub> = 4mA, I<sub>OH</sub> = -4mA)</li> <li>• Automotive input with input shutdown function</li> <li>• Programmable pull-up resistor</li> </ul>
J		<ul style="list-style-type: none"> <li>• CMOS level output (I<sub>OL</sub> = 4mA, I<sub>OH</sub> = -4mA)</li> <li>• Automotive input with input shutdown function</li> <li>• Programmable pull-up resistor</li> <li>• SEG or COM output</li> </ul>

Type	Circuit	Remarks
K		<ul style="list-style-type: none"> <li>• CMOS level output (<math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math>)</li> <li>• Automotive input with input shutdown function</li> <li>• Programmable pull-up resistor</li> <li>• Analog input</li> </ul>
L		<ul style="list-style-type: none"> <li>• CMOS level output (<math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math>)</li> <li>• Automotive input with input shutdown function</li> <li>• Programmable pull-up resistor</li> <li>• Vn input or SEG output</li> </ul>
M		<ul style="list-style-type: none"> <li>• CMOS level output (<math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math>)</li> <li>• CMOS hysteresis input with input shutdown function</li> <li>• Programmable pull-up resistor</li> </ul>



Type	Circuit	Remarks
N	 <p>The diagram shows a CMOS output stage. A pull-up resistor is connected to the output node. A P-channel MOSFET (P-ch) is connected to the output node and to a pull-up control input. An N-channel MOSFET (N-ch) is connected to the output node and to ground. The output node is also connected to a hysteresis input through a resistor (R). A standby control input for input shutdown is connected to the hysteresis input through another resistor (R). The output node is labeled Pout, and the N-channel MOSFET output is labeled Nout*.</p>	<ul style="list-style-type: none"> <li>• CMOS level output (<math>I_{OL} = 3\text{mA}</math>, <math>I_{OH} = -3\text{mA}</math>)</li> <li>• CMOS hysteresis input with input shutdown function</li> <li>• Programmable pull-up resistor</li> </ul> <p>*: N-channel transistor has slew rate control according to I<sup>2</sup>C spec, irrespective of usage.</p>
O	 <p>The diagram shows an open-drain output stage. An N-channel MOSFET (N-ch) is connected to the output node and to ground. The output node is also connected to a hysteresis input through a resistor (R). A standby control input for input shutdown is connected to the hysteresis input through another resistor (R). The output node is labeled Nout, and the hysteresis input is labeled TTL input.</p>	<ul style="list-style-type: none"> <li>• Open-drain I/O</li> <li>• Output 25mA, <math>V_{CC} = 2.7\text{V}</math></li> <li>• TTL input</li> </ul>
P	 <p>The diagram shows a CMOS output stage similar to Type N. A pull-up resistor is connected to the output node. A P-channel MOSFET (P-ch) is connected to the output node and to a pull-up control input. An N-channel MOSFET (N-ch) is connected to the output node and to ground. The output node is also connected to a hysteresis input through a resistor (R). A standby control input for input shutdown is connected to the hysteresis input through another resistor (R). The output node is labeled Pout, and the N-channel MOSFET output is labeled Nout. The hysteresis input is labeled Hysteresis input, and the standby control input is labeled SEG or COM output.</p>	<ul style="list-style-type: none"> <li>• CMOS level output (<math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math>)</li> <li>• CMOS hysteresis inputs with input shutdown function</li> <li>• Programmable pull-up resistor</li> <li>• SEG or COM output</li> </ul>

Type	Circuit	Remarks
R	 <p>The diagram shows an input pin circuit. A pull-up resistor is connected to the pin from the top, controlled by a 'Pull-up control' signal. A pull-down resistor is connected to the pin from the bottom, controlled by a 'Pull-down control' signal. The pin is connected to the gates of two transistors: a P-channel MOSFET (P-ch) and an N-channel MOSFET (N-ch). The P-ch MOSFET's source is connected to the pin, and its gate is controlled by 'Pout'. The N-ch MOSFET's source is connected to ground, and its gate is controlled by 'Nout'. Below the pin, there is an 'Automotive input' which is connected to an AND gate. One input of the AND gate is the 'Automotive input' signal, and the other is a 'Standby control for input shutdown' signal. The output of the AND gate is connected to an inverter, which then outputs to the 'Automotive input' pin. An 'Analog input' is also shown connected to the pin.</p>	<ul style="list-style-type: none"> <li>• CMOS level output (programmable <math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math> and <math>I_{OL} = 30\text{mA}</math>, <math>I_{OH} = -30\text{mA}</math>)</li> <li>• Automotive input with input shutdown function</li> <li>• Programmable pull-up / pull-down resistor</li> <li>• Analog input</li> </ul>

## 7. Memory Map

FF:FFFF <sub>H</sub>	USER ROM*1
DE:0000 <sub>H</sub> DD:FFFF <sub>H</sub>	Reserved
10:0000 <sub>H</sub>	Boot-ROM
0F:C000 <sub>H</sub>	Peripheral
0E:9000 <sub>H</sub>	Reserved
01:0000 <sub>H</sub>	ROM/RAM MIRROR
00:8000 <sub>H</sub>	Internal RAM bank0
RAMSTART0*2	Reserved
00:0C00 <sub>H</sub>	Peripheral
00:0380 <sub>H</sub>	GPR*3
00:0180 <sub>H</sub>	DMA
00:0100 <sub>H</sub>	Reserved
00:00F0 <sub>H</sub>	Reserved
00:0000 <sub>H</sub>	Peripheral

\*1: For details about USER ROM area, see “User ROM Memory Map For Flash Devices” on the following pages.

\*2: For RAMSTART addresses, see the table on the next page.

\*3: Unused GPR banks can be used as RAM area.

GPR: General-Purpose Register

The DMA area is only available if the device contains the corresponding resource.

The available RAM and ROM area depends on the device.

**8. RAMSTART Addresses**

Devices	Bank 0 RAM Size	RAMSTART0
CY96F673 CY96F675	4KB	00:7200 <sub>H</sub>

## 9. User ROM Memory Map For Flash Devices

CPU mode address	Flash memory mode address	CY96F673	CY96F675	
		Flash size 64.5KB + 32KB	Flash size 128.5KB + 32KB	
FF:FFFF <sub>H</sub>	3F:FFFF <sub>H</sub>	SA39 - 64KB	SA39 - 64KB	Bank A of Flash A
FF:0000 <sub>H</sub>	3F:0000 <sub>H</sub>		SA38 - 64KB	
FE:FFFF <sub>H</sub>	3E:FFFF <sub>H</sub>	Reserved	Reserved	
FE:0000 <sub>H</sub>	3E:0000 <sub>H</sub>			
FD:FFFF <sub>H</sub>				
DF:A000 <sub>H</sub>				Bank B of Flash A
DF:9FFF <sub>H</sub>	1F:9FFF <sub>H</sub>	SA4 - 8KB	SA4 - 8KB	
DF:8000 <sub>H</sub>	1F:8000 <sub>H</sub>			
DF:7FFF <sub>H</sub>	1F:7FFF <sub>H</sub>	SA3 - 8KB	SA3 - 8KB	
DF:6000 <sub>H</sub>	1F:6000 <sub>H</sub>			
DF:5FFF <sub>H</sub>	1F:5FFF <sub>H</sub>	SA2 - 8KB	SA2 - 8KB	
DF:4000 <sub>H</sub>	1F:4000 <sub>H</sub>			Bank A of Flash A
DF:3FFF <sub>H</sub>	1F:3FFF <sub>H</sub>	SA1 - 8KB	SA1 - 8KB	
DF:2000 <sub>H</sub>	1F:2000 <sub>H</sub>			
DF:1FFF <sub>H</sub>	1F:1FFF <sub>H</sub>	SAS - 512B*	SAS - 512B*	
DF:0000 <sub>H</sub>	1F:0000 <sub>H</sub>			
DE:FFFF <sub>H</sub>		Reserved	Reserved	
DE:0000 <sub>H</sub>				

\*: Physical address area of SAS-512B is from DF:0000<sub>H</sub> to DF:01FF<sub>H</sub>.

Others (from DF:0200<sub>H</sub> to DF:1FFF<sub>H</sub>) is mirror area of SAS-512B.

Sector SAS contains the ROM configuration block RCBA at CPU address DF:0000<sub>H</sub> -DF:01FF<sub>H</sub>.

SAS can not be used for E<sup>2</sup>PROM emulation.

## 10. Serial Programming Communication Interface

USART pins for Flash serial programming (MD = 0, DEBUG I/F = 0, Serial Communication mode)

CY96670		
Pin Number	USART Number	Normal Function
29	USART0	SIN0
30		SOT0
31		SCK0
3	USART1	SIN1
4		SOT1
5		SCK1

## 11. Interrupt Vector Table

Vector Number	Offset in Vector Table	Vector Name	Cleared by DMA	Index in ICR to Program	Description
0	3FC <sub>H</sub>	CALLV0	No	-	CALLV instruction
1	3F8 <sub>H</sub>	CALLV1	No	-	CALLV instruction
2	3F4 <sub>H</sub>	CALLV2	No	-	CALLV instruction
3	3F0 <sub>H</sub>	CALLV3	No	-	CALLV instruction
4	3EC <sub>H</sub>	CALLV4	No	-	CALLV instruction
5	3E8 <sub>H</sub>	CALLV5	No	-	CALLV instruction
6	3E4 <sub>H</sub>	CALLV6	No	-	CALLV instruction
7	3E0 <sub>H</sub>	CALLV7	No	-	CALLV instruction
8	3DC <sub>H</sub>	RESET	No	-	Reset vector
9	3D8 <sub>H</sub>	INT9	No	-	INT9 instruction
10	3D4 <sub>H</sub>	EXCEPTION	No	-	Undefined instruction execution
11	3D0 <sub>H</sub>	NMI	No	-	Non-Maskable Interrupt
12	3CC <sub>H</sub>	DLY	No	12	Delayed Interrupt
13	3C8 <sub>H</sub>	RC_TIMER	No	13	RC Clock Timer
14	3C4 <sub>H</sub>	MC_TIMER	No	14	Main Clock Timer
15	3C0 <sub>H</sub>	SC_TIMER	No	15	Sub Clock Timer
16	3BC <sub>H</sub>	LVDI	No	16	Low Voltage Detector
17	3B8 <sub>H</sub>	EXTINT0	Yes	17	External Interrupt 0
18	3B4 <sub>H</sub>	EXTINT1	Yes	18	External Interrupt 1
19	3B0 <sub>H</sub>	EXTINT2	Yes	19	External Interrupt 2
20	3AC <sub>H</sub>	EXTINT3	Yes	20	External Interrupt 3
21	3A8 <sub>H</sub>	EXTINT4	Yes	21	External Interrupt 4
22	3A4 <sub>H</sub>	-	-	22	Reserved
23	3A0 <sub>H</sub>	EXTINT6	Yes	23	External Interrupt 6
24	39C <sub>H</sub>	EXTINT7	Yes	24	External Interrupt 7
25	398 <sub>H</sub>	-	-	25	Reserved
26	394 <sub>H</sub>	-	-	26	Reserved
27	390 <sub>H</sub>	-	-	27	Reserved
28	38C <sub>H</sub>	-	-	28	Reserved
29	388 <sub>H</sub>	-	-	29	Reserved
30	384 <sub>H</sub>	-	-	30	Reserved
31	380 <sub>H</sub>	-	-	31	Reserved
32	37C <sub>H</sub>	-	-	32	Reserved
33	378 <sub>H</sub>	CAN0	No	33	CAN Controller 0
34	374 <sub>H</sub>	-	-	34	Reserved
35	370 <sub>H</sub>	-	-	35	Reserved
36	36C <sub>H</sub>	-	-	36	Reserved
37	368 <sub>H</sub>	-	-	37	Reserved
38	364 <sub>H</sub>	PPG0	Yes	38	Programmable Pulse Generator 0
39	360 <sub>H</sub>	PPG1	Yes	39	Programmable Pulse Generator 1

Vector Number	Offset in Vector Table	Vector Name	Cleared by DMA	Index in ICR to Program	Description
40	35C <sub>H</sub>	PPG2	Yes	40	Programmable Pulse Generator 2
41	358 <sub>H</sub>	PPG3	Yes	41	Programmable Pulse Generator 3
42	354 <sub>H</sub>	-	-	42	Reserved
43	350 <sub>H</sub>	-	-	43	Reserved
44	34C <sub>H</sub>	-	-	44	Reserved
45	348 <sub>H</sub>	-	-	45	Reserved
46	344 <sub>H</sub>	-	-	46	Reserved
47	340 <sub>H</sub>	-	-	47	Reserved
48	33C <sub>H</sub>	-	-	48	Reserved
49	338 <sub>H</sub>	-	-	49	Reserved
50	334 <sub>H</sub>	-	-	50	Reserved
51	330 <sub>H</sub>	-	-	51	Reserved
52	32C <sub>H</sub>	-	-	52	Reserved
53	328 <sub>H</sub>	-	-	53	Reserved
54	324 <sub>H</sub>	-	-	54	Reserved
55	320 <sub>H</sub>	-	-	55	Reserved
56	31C <sub>H</sub>	-	-	56	Reserved
57	318 <sub>H</sub>	-	-	57	Reserved
58	314 <sub>H</sub>	-	-	58	Reserved
59	310 <sub>H</sub>	RLT1	Yes	59	Reload Timer 1
60	30C <sub>H</sub>	RLT2	Yes	60	Reload Timer 2
61	308 <sub>H</sub>	-	-	61	Reserved
62	304 <sub>H</sub>	-	-	62	Reserved
63	300 <sub>H</sub>	-	-	63	Reserved
64	2FC <sub>H</sub>	RLT6	Yes	64	Reload Timer 6
65	2F8 <sub>H</sub>	ICU0	Yes	65	Input Capture Unit 0
66	2F4 <sub>H</sub>	ICU1	Yes	66	Input Capture Unit 1
67	2F0 <sub>H</sub>	-	-	67	Reserved
68	2EC <sub>H</sub>	-	-	68	Reserved
69	2E8 <sub>H</sub>	ICU4	Yes	69	Input Capture Unit 4
70	2E4 <sub>H</sub>	ICU5	Yes	70	Input Capture Unit 5
71	2E0 <sub>H</sub>	-	-	71	Reserved
72	2DC <sub>H</sub>	-	-	72	Reserved
73	2D8 <sub>H</sub>	-	-	73	Reserved
74	2D4 <sub>H</sub>	-	-	74	Reserved
75	2D0 <sub>H</sub>	-	-	75	Reserved
76	2CC <sub>H</sub>	-	-	76	Reserved
77	2C8 <sub>H</sub>	-	-	77	Reserved
78	2C4 <sub>H</sub>	-	-	78	Reserved
79	2C0 <sub>H</sub>	-	-	79	Reserved
80	2BC <sub>H</sub>	-	-	80	Reserved



Vector Number	Offset in Vector Table	Vector Name	Cleared by DMA	Index in ICR to Program	Description
81	2B8H	-	-	81	Reserved
82	2B4H	-	-	82	Reserved
83	2B0H	-	-	83	Reserved
84	2ACH	-	-	84	Reserved
85	2A8H	-	-	85	Reserved
86	2A4H	-	-	86	Reserved
87	2A0H	-	-	87	Reserved
88	29CH	-	-	88	Reserved
89	298H	FRT0	Yes	89	Free-Running Timer 0
90	294H	FRT1	Yes	90	Free-Running Timer 1
91	290H	-	-	91	Reserved
92	28CH	-	-	92	Reserved
93	288H	RTC0	No	93	Real Time Clock
94	284H	CAL0	No	94	Clock Calibration Unit
95	280H	SG0	No	95	Sound Generator 0
96	27CH	IIC0	Yes	96	I <sup>2</sup> C interface 0
97	278H	-	-	97	Reserved
98	274H	ADC0	Yes	98	A/D Converter 0
99	270H	-	-	99	Reserved
100	26CH	-	-	100	Reserved
101	268H	LINR0	Yes	101	LIN USART 0 RX
102	264H	LINT0	Yes	102	LIN USART 0 TX
103	260H	LINR1	Yes	103	LIN USART 1 RX
104	25CH	LINT1	Yes	104	LIN USART 1 TX
105	258H	-	-	105	Reserved
106	254H	-	-	106	Reserved
107	250H	-	-	107	Reserved
108	24CH	-	-	108	Reserved
109	248H	-	-	109	Reserved
110	244H	-	-	110	Reserved
111	240H	-	-	111	Reserved
112	23CH	-	-	112	Reserved
113	238H	-	-	113	Reserved
114	234H	-	-	114	Reserved
115	230H	-	-	115	Reserved
116	22CH	-	-	116	Reserved
117	228H	-	-	117	Reserved
118	224H	-	-	118	Reserved
119	220H	-	-	119	Reserved
120	21CH	-	-	120	Reserved

Vector Number	Offset in Vector Table	Vector Name	Cleared by DMA	Index in ICR to Program	Description
121	218H	-	-	121	Reserved
122	214H	-	-	122	Reserved
123	210H	-	-	123	Reserved
124	20CH	-	-	124	Reserved
125	208H	-	-	125	Reserved
126	204H	-	-	126	Reserved
127	200H	-	-	127	Reserved
128	1FCH	-	-	128	Reserved
129	1F8H	-	-	129	Reserved
130	1F4H	-	-	130	Reserved
131	1F0H	-	-	131	Reserved
132	1ECH	-	-	132	Reserved
133	1E8H	FLASHA	Yes	133	Flash memory A interrupt
134	1E4H	-	-	134	Reserved
135	1E0H	-	-	135	Reserved
136	1DCH	-	-	136	Reserved
137	1D8H	-	-	137	Reserved
138	1D4H	-	-	138	Reserved
139	1D0H	ADCRC0	No	139	A/D Converter 0 - Range Comparator
140	1CCH	ADCPD0	No	140	A/D Converter 0 - Pulse detection
141	1C8H	-	-	141	Reserved
142	1C4H	-	-	142	Reserved
143	1C0H	-	-	143	Reserved

## 12. Handling Precautions

Any semiconductor devices have inherently a certain rate of failure. The possibility of failure is greatly affected by the conditions in which they are used (circuit conditions, environmental conditions, etc.). This page describes precautions that must be observed to minimize the chance of failure and to obtain higher reliability from your Cypress semiconductor devices.

### 12.1 Precautions for Product Design

This section describes precautions when designing electronic equipment using semiconductor devices.

#### ■ Absolute Maximum Ratings

Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of certain established limits, called absolute maximum ratings. Do not exceed these ratings.

#### ■ Recommended Operating Conditions

Recommended operating conditions are normal operating ranges for the semiconductor device. All the device's electrical characteristics are warranted when operated within these ranges.

Always use semiconductor devices within the recommended operating conditions. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their sales representative beforehand.

#### ■ Processing and Protection of Pins

These precautions must be followed when handling the pins which connect semiconductor devices to power supply and input/output functions.

##### 1. Preventing Over-Voltage and Over-Current Conditions

Exposure to voltage or current levels in excess of maximum ratings at any pin is likely to cause deterioration within the device, and in extreme cases leads to permanent damage of the device. Try to prevent such overvoltage or over-current conditions at the design stage.

##### 2. Protection of Output Pins

Shorting of output pins to supply pins or other output pins, or connection to large capacitance can cause large current flows. Such conditions if present for extended periods of time can damage the device. Therefore, avoid this type of connection.

##### 3. Handling of Unused Input Pins

Unconnected input pins with very high impedance levels can adversely affect stability of operation. Such pins should be connected through an appropriate resistance to a power supply pin or ground pin.

#### ■ Latch-up

Semiconductor devices are constructed by the formation of P-type and N-type areas on a substrate. When subjected to abnormally high voltages, internal parasitic PNP junctions (called thyristor structures) may be formed, causing large current levels in excess of several hundred mA to flow continuously at the power supply pin. This condition is called latch-up.

**CAUTION:** The occurrence of latch-up not only causes loss of reliability in the semiconductor device, but can cause injury or damage from high heat, smoke or flame. To prevent this from happening, do the following:

1. Be sure that voltages applied to pins do not exceed the absolute maximum ratings. This should include attention to abnormal noise, surge levels, etc.
2. Be sure that abnormal current flows do not occur during the power-on sequence.

#### ■ Observance of Safety Regulations and Standards

Most countries in the world have established standards and regulations regarding safety, protection from electromagnetic interference, etc. Customers are requested to observe applicable regulations and standards in the design of products.

#### ■ Fail-Safe Design

Any semiconductor devices have inherently a certain rate of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions.

**■ Precautions Related to Usage of Devices**

Cypress semiconductor devices are intended for use in standard applications (computers, office automation and other office equipment, industrial, communications, and measurement equipment, personal or household devices, etc.).

CAUTION: Customers considering the use of our products in special applications where failure or abnormal operation may directly affect human lives or cause physical injury or property damage, or where extremely high levels of reliability are demanded (such as aerospace systems, atomic energy controls, sea floor repeaters, vehicle operating controls, medical devices for life support, etc.) are requested to consult with sales representatives before such use. The company will not be responsible for damages arising from such use without prior approval.

**12.2 Precautions for Package Mounting**

Package mounting may be either lead insertion type or surface mount type. In either case, for heat resistance during soldering, you should only mount under Cypress's recommended conditions. For detailed information about mount conditions, contact your sales representative.

**■ Lead Insertion Type**

Mounting of lead insertion type packages onto printed circuit boards may be done by two methods: direct soldering on the board, or mounting by using a socket.

Direct mounting onto boards normally involves processes for inserting leads into through-holes on the board and using the flow soldering (wave soldering) method of applying liquid solder. In this case, the soldering process usually causes leads to be subjected to thermal stress in excess of the absolute ratings for storage temperature. Mounting processes should conform to Cypress recommended mounting conditions.

If socket mounting is used, differences in surface treatment of the socket contacts and IC lead surfaces can lead to contact deterioration after long periods. For this reason it is recommended that the surface treatment of socket contacts and IC leads be verified before mounting.

**■ Surface Mount Type**

Surface mount packaging has longer and thinner leads than lead-insertion packaging, and therefore leads are more easily deformed or bent. The use of packages with higher pin counts and narrower pin pitch results in increased susceptibility to open connections caused by deformed pins, or shorting due to solder bridges.

You must use appropriate mounting techniques. Cypress recommends the solder reflow method, and has established a ranking of mounting conditions for each product. Users are advised to mount packages in accordance with Cypress ranking of recommended conditions.

**■ Lead-Free Packaging**

CAUTION: When ball grid array (BGA) packages with Sn-Ag-Cu balls are mounted using Sn-Pb eutectic soldering, junction strength may be reduced under some conditions of use.

**■ Storage of Semiconductor Devices**

Because plastic chip packages are formed from plastic resins, exposure to natural environmental conditions will cause absorption of moisture. During mounting, the application of heat to a package that has absorbed moisture can cause surfaces to peel, reducing moisture resistance and causing packages to crack. To prevent, do the following:

1. Avoid exposure to rapid temperature changes, which cause moisture to condense inside the product. Store products in locations where temperature changes are slight.
2. Use dry boxes for product storage. Products should be stored below 70% relative humidity, and at temperatures between 5°C and 30°C.  
When you open Dry Package that recommends humidity 40% to 70% relative humidity.
3. When necessary, Cypress packages semiconductor devices in highly moisture-resistant aluminum laminate bags, with a silica gel desiccant. Devices should be sealed in their aluminum laminate bags for storage.
4. Avoid storing packages where they are exposed to corrosive gases or high levels of dust.

**■ Baking**

Packages that have absorbed moisture may be de-moisturized by baking (heat drying). Follow the Cypress recommended conditions for baking.

Condition: 125°C/24 h

**■ Static Electricity**

Because semiconductor devices are particularly susceptible to damage by static electricity, you must take the following precautions:

1. Maintain relative humidity in the working environment between 40% and 70%. Use of an apparatus for ion generation may be needed to remove electricity.
2. Electrically ground all conveyors, solder vessels, soldering irons and peripheral equipment.
3. Eliminate static body electricity by the use of rings or bracelets connected to ground through high resistance (on the level of 1 M $\Omega$ ).  
Wearing of conductive clothing and shoes, use of conductive floor mats and other measures to minimize shock loads is recommended.
4. Ground all fixtures and instruments, or protect with anti-static measures.
5. Avoid the use of styrofoam or other highly static-prone materials for storage of completed board assemblies.

**12.3 Precautions for Use Environment**

Reliability of semiconductor devices depends on ambient temperature and other conditions as described above.

For reliable performance, do the following:

1. Humidity  
Prolonged use in high humidity can lead to leakage in devices as well as printed circuit boards. If high humidity levels are anticipated, consider anti-humidity processing.
2. Discharge of Static Electricity  
When high-voltage charges exist close to semiconductor devices, discharges can cause abnormal operation. In such cases, use anti-static measures or processing to prevent discharges.
3. Corrosive Gases, Dust, or Oil  
Exposure to corrosive gases or contact with dust or oil may lead to chemical reactions that will adversely affect the device. If you use devices in such conditions, consider ways to prevent such exposure or to protect the devices.
4. Radiation, Including Cosmic Radiation  
Most devices are not designed for environments involving exposure to radiation or cosmic radiation. Users should provide shielding as appropriate.
5. Smoke, Flame  
**CAUTION:** Plastic molded devices are flammable, and therefore should not be used near combustible substances. If devices begin to smoke or burn, there is danger of the release of toxic gases.

Customers considering the use of Cypress products in other special environmental conditions should consult with sales representatives.

## 13. Handling Devices

### Special Care is Required for the Following when Handling the Device:

- Latch-up prevention
- Unused pins handling
- External clock usage
- Notes on PLL clock mode operation
- Power supply pins ( $V_{CC}/V_{SS}$ )
- Crystal oscillator and ceramic resonator circuit
- Turn on sequence of power supply to A/D converter and analog inputs
- Pin handling when not using the A/D converter
- Notes on Power-on
- Stabilization of power supply voltage
- SMC power supply pins
- Serial communication
- Mode Pin (MD)

### 13.1 Latch-Up Prevention

CMOS IC chips may suffer latch-up under the following conditions:

- A voltage higher than  $V_{CC}$  or lower than  $V_{SS}$  is applied to an input or output pin.
- A voltage higher than the rated voltage is applied between  $V_{CC}$  pins and  $V_{SS}$  pins.
- The  $AV_{CC}$  power supply is applied before the  $V_{CC}$  voltage.

Latch-up may increase the power supply current dramatically, causing thermal damages to the device.

For the same reason, extra care is required to not let the analog power-supply voltage ( $AV_{CC}$ ,  $AV_{RH}$ ) exceed the digital power-supply voltage.

### 13.2 Unused Pins Handling

Unused input pins can be left open when the input is disabled (corresponding bit of Port Input Enable register  $PIER = 0$ ).

Leaving unused input pins open when the input is enabled may result in misbehavior and possible permanent damage of the device. To prevent latch-up, they must therefore be pulled up or pulled down through resistors which should be more than  $2k\Omega$ .

Unused bidirectional pins can be set either to the output state and be then left open, or to the input state with either input disabled or external pull-up/pull-down resistor as described above.

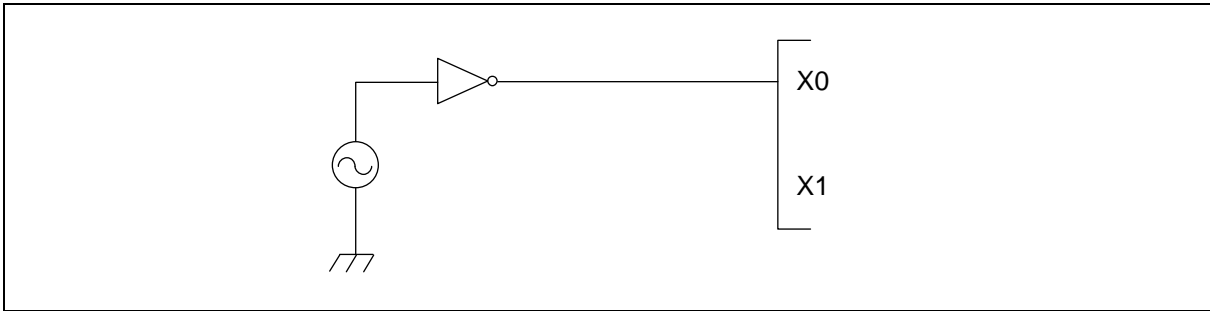
### 13.3 External Clock Usage

The permitted frequency range of an external clock depends on the oscillator type and configuration.

See AC Characteristics for detailed modes and frequency limits. Single and opposite phase external clocks must be connected as follows:

#### 13.3.1 Single Phase External Clock for Main Oscillator

When using a single phase external clock for the Main oscillator, X0 pin must be driven and X1 pin left open. And supply 1.8V power to the external clock.

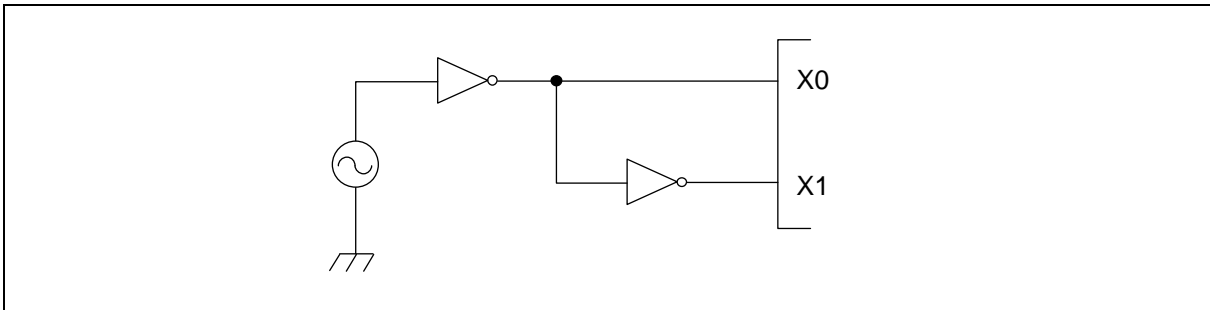


#### 13.3.2 Single Phase External Clock for Sub Oscillator

When using a single phase external clock for the Sub oscillator, "External clock mode" must be selected and X0A/P04\_0 pin must be driven. X1A/P04\_1 pin can be configured as GPIO.

#### 13.3.3 Opposite Phase External Clock

When using an opposite phase external clock, X1 (X1A) pins must be supplied with a clock signal which has the opposite phase to the X0 (X0A) pins. Supply level on X0 and X1 pins must be 1.8V.



### 13.4 Notes on PLL Clock Mode Operation

If the microcontroller is operated with PLL clock mode and no external oscillator is operating or no external clock is supplied, the microcontroller attempts to work with the free oscillating PLL. Performance of this operation, however, cannot be guaranteed.

### 13.5 Power Supply Pins (Vcc/Vss)

It is required that all V<sub>CC</sub>-level as well as all V<sub>SS</sub>-level power supply pins are at the same potential. If there is more than one V<sub>CC</sub> or V<sub>SS</sub> level, the device may operate incorrectly or be damaged even within the guaranteed operating range.

V<sub>CC</sub> and V<sub>SS</sub> pins must be connected to the device from the power supply with lowest possible impedance.

The smoothing capacitor at V<sub>CC</sub> pin must use the one of a capacity value that is larger than C<sub>s</sub>.

Besides this, as a measure against power supply noise, it is required to connect a bypass capacitor of about 0.1μF between V<sub>CC</sub> and V<sub>SS</sub> pins as close as possible to V<sub>CC</sub> and V<sub>SS</sub> pins.

### 13.6 Crystal Oscillator and ceramic resonator Circuit

Noise at X0, X1 pins or X0A, X1A pins might cause abnormal operation. It is required to provide bypass capacitors with shortest possible distance to X0, X1 pins and X0A, X1A pins, crystal oscillator (or ceramic resonator) and ground lines, and, to the utmost effort, that the lines of oscillation circuit do not cross the lines of other circuits.

It is highly recommended to provide a printed circuit board art work surrounding X0, X1 pins and X0A, X1A pins with a ground area for stabilizing the operation.

It is highly recommended to evaluate the quartz/MCU or resonator/MCU system at the quartz or resonator manufacturer, especially when using low-Q resonators at higher frequencies.

### 13.7 Turn on Sequence of Power Supply to A/D Converter and Analog Inputs

It is required to turn the A/D converter power supply ( $AV_{CC}$ ,  $AVRH$ ) and analog inputs ( $ANn$ ) on after turning the digital power supply ( $V_{CC}$ ) on.

It is also required to turn the digital power off after turning the A/D converter supply and analog inputs off. In this case,  $AVRH$  must not exceed  $AV_{CC}$ . Input voltage for ports shared with analog input ports also must not exceed  $AV_{CC}$  (turning the analog and digital power supplies simultaneously on or off is acceptable).

### 13.8 Pin Handling when not using the A/D Converter

If the A/D converter is not used, the power supply pins for A/D converter should be connected such as  $AV_{CC} = V_{CC}$ ,  $AV_{SS} = AVRH = V_{SS}$ .

### 13.9 Notes on Power-on

To prevent malfunction of the internal voltage regulator, supply voltage profile while turning the power supply on should be slower than  $50\mu s$  from 0.2V to 2.7V.

### 13.10 Stabilization of Power Supply Voltage

If the power supply voltage varies acutely even within the operation safety range of the  $V_{CC}$  power supply voltage, a malfunction may occur. The  $V_{CC}$  power supply voltage must therefore be stabilized. As stabilization guidelines, the power supply voltage must be stabilized in such a way that  $V_{CC}$  ripple fluctuations (peak to peak value) in the commercial frequencies (50Hz to 60Hz) fall within 10% of the standard  $V_{CC}$  power supply voltage and the transient fluctuation rate becomes  $0.1V/\mu s$  or less in instantaneous fluctuation for power supply switching.

### 13.11 SMC Power Supply Pins

All  $DV_{CC}/DV_{SS}$  pins must be set to the same level as the  $V_{CC}/V_{SS}$  pins.

Note that the SMC I/O pin state is undefined if  $DV_{CC}$  is powered on and  $V_{CC}$  is below 3V. To avoid this,  $V_{CC}$  must always be powered on before  $DV_{CC}$ .

$DV_{CC}/DV_{SS}$  must be applied when using SMC I/O pin as GPIO.

### 13.12 Serial Communication

There is a possibility to receive wrong data due to noise or other causes on the serial communication.

Therefore, design a printed circuit board so as to avoid noise.

Consider receiving of wrong data when designing the system. For example apply a checksum and retransmit the data if an error occurs.

### 13.13 Mode Pin (MD)

Connect the mode pin directly to  $V_{CC}$  or  $V_{SS}$  pin. To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the mode pin to  $V_{CC}$  or  $V_{SS}$  pin and provide a low-impedance connection.

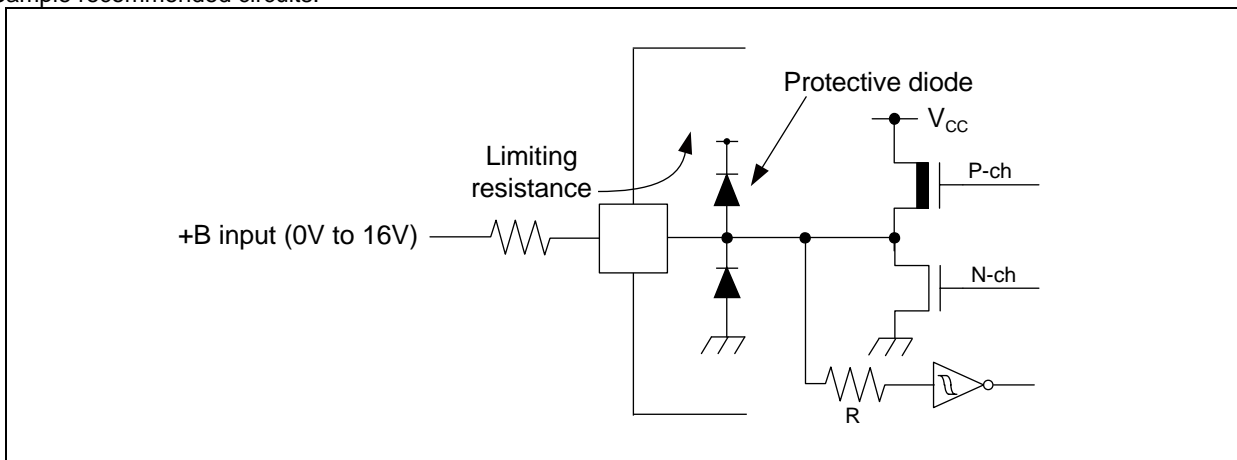


## 14. Electrical Characteristics

### 14.1 Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating		Unit	Remarks
			Min	Max		
Power supply voltage*1	V <sub>CC</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	
Analog power supply voltage*1	AV <sub>CC</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	V <sub>CC</sub> = AV <sub>CC</sub> *2
Analog reference voltage*1	AVRH	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	AV <sub>CC</sub> ≥ AVRH, AVRH ≥ AV <sub>SS</sub>
SMC Power supply*1	DV <sub>CC</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	V <sub>CC</sub> = AV <sub>CC</sub> = DV <sub>CC</sub> *2
LCD power supply voltage*1	V0 to V3	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	V0 to V3 must not exceed V <sub>CC</sub>
Input voltage*1	V <sub>I</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	V <sub>I</sub> ≤ (D)V <sub>CC</sub> + 0.3V*3
Output voltage*1	V <sub>O</sub>	-	V <sub>SS</sub> - 0.3	V <sub>SS</sub> + 6.0	V	V <sub>O</sub> ≤ (D)V <sub>CC</sub> + 0.3V*3
Maximum Clamp Current	I <sub>CLAMP</sub>	-	-4.0	+4.0	mA	Applicable to general purpose I/O pins *4
Total Maximum Clamp Current	Σ I <sub>CLAMP</sub>	-	-	16	mA	Applicable to general purpose I/O pins *4
"L" level maximum output current	I <sub>OL</sub>	-	-	15	mA	Normal port
	I <sub>OLSMC</sub>	T <sub>A</sub> = -40°C	-	52	mA	High current port
		T <sub>A</sub> = +25°C	-	39	mA	
		T <sub>A</sub> = +85°C	-	32	mA	
T <sub>A</sub> = +105°C		-	30	mA		
"L" level average output current	I <sub>OLAV</sub>	-	-	4	mA	Normal port
	I <sub>OLAVSMC</sub>	T <sub>A</sub> = -40°C	-	40	mA	High current port
		T <sub>A</sub> = +25°C	-	30	mA	
		T <sub>A</sub> = +85°C	-	25	mA	
T <sub>A</sub> = +105°C		-	23	mA		
"L" level maximum overall output current	ΣI <sub>OL</sub>	-	-	34	mA	Normal port
	ΣI <sub>OLSMC</sub>	-	-	180	mA	High current port
"L" level average overall output current	ΣI <sub>OLAV</sub>	-	-	17	mA	Normal port
	ΣI <sub>OLAVSMC</sub>	-	-	90	mA	High current port
"H" level maximum output current	I <sub>OH</sub>	-	-	-15	mA	Normal port
	I <sub>OHSMC</sub>	T <sub>A</sub> = -40°C	-	-52	mA	High current port
		T <sub>A</sub> = +25°C	-	-39	mA	
		T <sub>A</sub> = +85°C	-	-32	mA	
T <sub>A</sub> = +105°C		-	-30	mA		
"H" level average output current	I <sub>OHAV</sub>	-	-	-4	mA	Normal port
	I <sub>OHAVSMC</sub>	T <sub>A</sub> = -40°C	-	-40	mA	High current port
		T <sub>A</sub> = +25°C	-	-30	mA	
		T <sub>A</sub> = +85°C	-	-25	mA	
T <sub>A</sub> = +105°C		-	-23	mA		
"H" level maximum overall output current	ΣI <sub>OH</sub>	-	-	-34	mA	Normal port
	ΣI <sub>OHSMC</sub>	-	-	-180	mA	High current port
"H" level average overall output current	ΣI <sub>OHAV</sub>	-	-	-17	mA	Normal port
	ΣI <sub>OHAVSMC</sub>	-	-	-90	mA	High current port
Power consumption*5	P <sub>D</sub>	T <sub>A</sub> = +105°C	-	281*6	mW	
Operating ambient temperature	T <sub>A</sub>	-	-40	+105	°C	
Storage temperature	T <sub>STG</sub>	-	-55	+150	°C	

- \*1: This parameter is based on  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ .
- \*2:  $AV_{CC}$  and  $V_{CC}$  and  $DV_{CC}$  must be set to the same voltage. It is required that  $AV_{CC}$  does not exceed  $V_{CC}$ ,  $DV_{CC}$  and that the voltage at the analog inputs does not exceed  $AV_{CC}$  when the power is switched on.
- \*3:  $V_I$  and  $V_O$  should not exceed  $V_{CC} + 0.3V$ .  $V_I$  should also not exceed the specified ratings. However if the maximum current to/from an input is limited by some means with external components, the  $I_{CLAMP}$  rating supersedes the  $V_I$  rating. Input/Output voltages of high current ports depend on  $DV_{CC}$ . Input/Output voltages of standard ports depend on  $V_{CC}$ .
- \*4: Applicable to all general purpose I/O pins (Pnn\_m).
  - Use within recommended operating conditions.
  - Use at DC voltage (current).
  - The +B signal should always be applied a limiting resistance placed between the +B signal and the microcontroller.
  - The value of the limiting resistance should be set so that when the +B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
  - Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the  $V_{CC}$  pin, and this may affect other devices.
  - Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0V), the power supply is provided from the pins, so that incomplete operation may result.
  - Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the Power reset.
  - The DEBUG I/F pin has only a protective diode against  $V_{SS}$ . Hence it is only permitted to input a negative clamping current (4mA). For protection against positive input voltages, use an external clamping diode which limits the input voltage to maximum 6.0V.
  - Sample recommended circuits:



- \*5: The maximum permitted power dissipation depends on the ambient temperature, the air flow velocity and the thermal conductance of the package on the PCB.  
 The actual power dissipation depends on the customer application and can be calculated as follows:  
 $P_D = P_{IO} + P_{INT}$   
 $P_{IO} = \sum (V_{OL} \times I_{OL} + V_{OH} \times I_{OH})$  (I/O load power dissipation, sum is performed on all I/O ports)  
 $P_{INT} = V_{CC} \times (I_{CC} + I_A)$  (internal power dissipation)  
 $I_{CC}$  is the total core current consumption into  $V_{CC}$  as described in the “DC characteristics” and depends on the selected operation mode and clock frequency and the usage of functions like Flash programming.  
 $I_A$  is the analog current consumption into  $AV_{CC}$ .
- \*6: Worst case value for a package mounted on single layer PCB at specified  $T_A$  without air flow.

**WARNING**

Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

**14.2 Recommended Operating Conditions**

(V<sub>SS</sub> = AV<sub>SS</sub> = DV<sub>SS</sub> = 0V)

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Power supply voltage	V <sub>CC</sub> , AV <sub>CC</sub> , DV <sub>CC</sub>	2.7	-	5.5	V	
		2.0	-	5.5	V	Maintains RAM data in stop mode
Smoothing capacitor at C pin	C <sub>S</sub>	0.5	1.0 to 3.9	4.7	μF	1.0μF (Allowance within ± 50%) 3.9μF (Allowance within ± 20%) Please use the ceramic capacitor or the capacitor of the frequency response of this level. The smoothing capacitor at V <sub>CC</sub> must use the one of a capacity value that is larger than C <sub>S</sub> .

**WARNING**

The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges. Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure. No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

**14.3 DC Characteristics**

**14.3.1 Current Rating**

(V<sub>CC</sub> = AV<sub>CC</sub> = DV<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = AV<sub>SS</sub> = DV<sub>SS</sub> = 0V, T<sub>A</sub> = - 40°C to + 105°C)

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current in Run modes*1	I <sub>CCPLL</sub>	V <sub>CC</sub>	PLL Run mode with CLKS1/2 = CLKB = CLKP1/2 = 32MHz	-	25	-	mA	T <sub>A</sub> = +25°C
			Flash 0 wait (CLKRC and CLKSC stopped)	-	-	34	mA	T <sub>A</sub> = +105°C
	I <sub>CCMAIN</sub>		Main Run mode with CLKS1/2 = CLKB = CLKP1/2 = 4MHz	-	3.5	-	mA	T <sub>A</sub> = +25°C
			Flash 0 wait (CLKPLL, CLKSC and CLKRC stopped)	-	-	7.5	mA	T <sub>A</sub> = +105°C
	I <sub>CCRCH</sub>		RC Run mode with CLKS1/2 = CLKB = CLKP1/2 = CLKRC = 2MHz	-	1.7	-	mA	T <sub>A</sub> = +25°C
			Flash 0 wait (CLKMC, CLKPLL and CLKSC stopped)	-	-	5.5	mA	T <sub>A</sub> = +105°C
	I <sub>CCRCL</sub>		RC Run mode with CLKS1/2 = CLKB = CLKP1/2 = CLKRC = 100kHz	-	0.15	-	mA	T <sub>A</sub> = +25°C
			Flash 0 wait (CLKMC, CLKPLL and CLKSC stopped)	-	-	3.2	mA	T <sub>A</sub> = +105°C
	I <sub>CCSUB</sub>		Sub Run mode with CLKS1/2 = CLKB = CLKP1/2 = 32kHz	-	0.1	-	mA	T <sub>A</sub> = +25°C
			Flash 0 wait (CLKMC, CLKPLL and CLKRC stopped)	-	-	3	mA	T <sub>A</sub> = +105°C

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks		
				Min	Typ	Max				
Power supply current in Sleep modes <sup>1</sup>	I <sub>CCSPLL</sub>	V <sub>CC</sub>	PLL Sleep mode with CLKS1/2 = CLKP1/2 = 32MHz (CLKRC and CLKSC stopped)	-	6.5	-	mA	T <sub>A</sub> = +25°C		
				-	-	13	mA	T <sub>A</sub> = +105°C		
	I <sub>CCSMAN</sub>		Main Sleep mode with CLKS1/2 = CLKP1/2 = 4MHz, SMCR:LPMSS = 0 (CLKPLL, CLKRC and CLKSC stopped)	-	0.9	-	mA	T <sub>A</sub> = +25°C		
				-	-	4	mA	T <sub>A</sub> = +105°C		
	I <sub>CCSRCH</sub>		RC Sleep mode with CLKS1/2 = CLKP1/2 = CLKRC = 2MHz, SMCR:LPMSS = 0 (CLKMC, CLKPLL and CLKSC stopped)	-	0.5	-	mA	T <sub>A</sub> = +25°C		
				-	-	3.5	mA	T <sub>A</sub> = +105°C		
	I <sub>CCSRCL</sub>		RC Sleep mode with CLKS1/2 = CLKP1/2 = CLKRC = 100kHz (CLKMC, CLKPLL and CLKSC stopped)	-	0.06	-	mA	T <sub>A</sub> = +25°C		
				-	-	2.7	mA	T <sub>A</sub> = +105°C		
	I <sub>CCSSUB</sub>		Sub Sleep mode with CLKS1/2 = CLKP1/2 = 32kHz, (CLKMC, CLKPLL and CLKRC stopped)	-	0.04	-	mA	T <sub>A</sub> = +25°C		
				-	-	2.5	mA	T <sub>A</sub> = +105°C		
	Power supply current in Timer modes <sup>2</sup>		I <sub>CCTPLL</sub>	V <sub>CC</sub>	PLL Timer mode with CLKPLL = 32MHz (CLKRC and CLKSC stopped)	-	1800	2245	μA	T <sub>A</sub> = +25°C
						-	-	3140	μA	T <sub>A</sub> = +105°C
I <sub>CCTMAN</sub>		Main Timer mode with CLKMC = 4MHz, SMCR:LPMSS = 0 (CLKPLL, CLKRC and CLKSC stopped)	-		285	325	μA	T <sub>A</sub> = +25°C		
			-		-	1055	μA	T <sub>A</sub> = +105°C		
I <sub>CCTRCH</sub>		RC Timer mode with CLKRC = 2MHz, SMCR:LPMSS = 0 (CLKPLL, CLKMC and CLKSC stopped)	-		160	210	μA	T <sub>A</sub> = +25°C		
			-		-	970	μA	T <sub>A</sub> = +105°C		
I <sub>CCTRCL</sub>		RC Timer mode with CLKRC = 100kHz (CLKPLL, CLKMC and CLKSC stopped)	-		30	70	μA	T <sub>A</sub> = +25°C		
			-		-	820	μA	T <sub>A</sub> = +105°C		
I <sub>CCTSUB</sub>		Sub Timer mode with CLKSC = 32kHz (CLKMC, CLKPLL and CLKRC stopped)	-		25	55	μA	T <sub>A</sub> = +25°C		
			-		-	800	μA	T <sub>A</sub> = +105°C		

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current in Stop mode* <sup>3</sup>	I <sub>CCH</sub>	V <sub>CC</sub>	-	-	20	55	μA	T <sub>A</sub> = +25°C
				-	-	800	μA	T <sub>A</sub> = +105°C
Flash Power Down current	I <sub>CCFLASHPD</sub>		-	-	36	70	μA	
Power supply current for active Low Voltage detector* <sup>4</sup>	I <sub>CCLVLD</sub>		Low voltage detector enabled	-	5	-	μA	T <sub>A</sub> = +25°C
				-	-	12.5	μA	T <sub>A</sub> = +105°C
Flash Write/ Erase current* <sup>5</sup>	I <sub>CCFLASH</sub>		-	-	12.5	-	mA	T <sub>A</sub> = +25°C
				-	-	20	mA	T <sub>A</sub> = +105°C

\*1: The power supply current is measured with a 4MHz external clock connected to the Main oscillator and a 32kHz external clock connected to the Sub oscillator. See chapter "Standby mode and voltage regulator control circuit" of the Hardware Manual for further details about voltage regulator control. Current for "On Chip Debugger" part is not included. Power supply current in Run mode does not include Flash Write / Erase current.

\*2: The power supply current in Timer mode is the value when Flash is in Power-down / reset mode.

When Flash is not in Power-down / reset mode, I<sub>CCFLASHPD</sub> must be added to the Power supply current.

The power supply current is measured with a 4MHz external clock connected to the Main oscillator and a 32kHz external clock connected to the Sub oscillator. The current for "On Chip Debugger" part is not included.

\*3: The power supply current in Stop mode is the value when Flash is in Power-down / reset mode.

When Flash is not in Power-down / reset mode, I<sub>CCFLASHPD</sub> must be added to the Power supply current.

\*4: When low voltage detector is enabled, I<sub>CCLVLD</sub> must be added to Power supply current.

\*5: When Flash Write / Erase program is executed, I<sub>CCFLASH</sub> must be added to Power supply current.

**14.3.2 Pin Characteristics**
 $(V_{CC} = AV_{CC} = DV_{CC} = 2.7V \text{ to } 5.5V, V_{SS} = AV_{SS} = DV_{SS} = 0V, T_A = -40^{\circ}C \text{ to } +105^{\circ}C)$ 

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
"H" level input voltage	V <sub>IH</sub>	Port inputs Pnn_m	-	V <sub>CC</sub> × 0.7	-	V <sub>CC</sub> + 0.3	V	CMOS Hysteresis input
			-	V <sub>CC</sub> × 0.8	-	V <sub>CC</sub> + 0.3	V	AUTOMOTIVE Hysteresis input
	V <sub>IHX0S</sub>	X0	External clock in "Fast Clock Input mode"	V <sub>D</sub> × 0.8	-	V <sub>D</sub>	V	V <sub>D</sub> =1.8V±0.15V
	V <sub>IHX0AS</sub>	X0A	External clock in "Oscillation mode"	V <sub>CC</sub> × 0.8	-	V <sub>CC</sub> + 0.3	V	
	V <sub>IHR</sub>	RSTX	-	V <sub>CC</sub> × 0.8	-	V <sub>CC</sub> + 0.3	V	CMOS Hysteresis input
	V <sub>IHM</sub>	MD	-	V <sub>CC</sub> - 0.3	-	V <sub>CC</sub> + 0.3	V	CMOS Hysteresis input
	V <sub>IHD</sub>	DEBUG I/F	-	2.0	-	V <sub>CC</sub> + 0.3	V	TTL Input
"L" level input voltage	V <sub>IL</sub>	Port inputs Pnn_m	-	V <sub>SS</sub> - 0.3	-	V <sub>CC</sub> × 0.3	V	CMOS Hysteresis input
			-	V <sub>SS</sub> - 0.3	-	V <sub>CC</sub> × 0.5	V	AUTOMOTIVE Hysteresis input
	V <sub>ILX0S</sub>	X0	External clock in "Fast Clock Input mode"	V <sub>SS</sub>	-	V <sub>D</sub> × 0.2	V	V <sub>D</sub> =1.8V±0.15V
	V <sub>ILX0AS</sub>	X0A	External clock in "Oscillation mode"	V <sub>SS</sub> - 0.3	-	V <sub>CC</sub> × 0.2	V	
	V <sub>ILR</sub>	RSTX	-	V <sub>SS</sub> - 0.3	-	V <sub>CC</sub> × 0.2	V	CMOS Hysteresis input
	V <sub>ILM</sub>	MD	-	V <sub>SS</sub> - 0.3	-	V <sub>SS</sub> + 0.3	V	CMOS Hysteresis input
	V <sub>ILD</sub>	DEBUG I/F	-	V <sub>SS</sub> - 0.3	-	0.8	V	TTL Input

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks	
				Min	Typ	Max			
"H" level output voltage	V <sub>OH4</sub>	4mA type	4.5V ≤ (D)V <sub>CC</sub> ≤ 5.5V I <sub>OH</sub> = -4mA	(D)V <sub>CC</sub> - 0.5	-	(D)V <sub>CC</sub>	V		
			2.7V ≤ (D)V <sub>CC</sub> < 4.5V I <sub>OH</sub> = -1.5mA						
	V <sub>OH30</sub>	High Drive type*	4.5V ≤ DV <sub>CC</sub> ≤ 5.5V I <sub>OH</sub> = -52mA	DV <sub>CC</sub> - 0.5	-	DV <sub>CC</sub>	V		T <sub>A</sub> = -40°C
			2.7V ≤ DV <sub>CC</sub> < 4.5V I <sub>OH</sub> = -18mA						T <sub>A</sub> = +25°C
			4.5V ≤ DV <sub>CC</sub> ≤ 5.5V I <sub>OH</sub> = -39mA						T <sub>A</sub> = +85°C
			2.7V ≤ DV <sub>CC</sub> < 4.5V I <sub>OH</sub> = -16mA						T <sub>A</sub> = +105°C
			4.5V ≤ DV <sub>CC</sub> ≤ 5.5V I <sub>OH</sub> = -32mA						
			2.7V ≤ DV <sub>CC</sub> < 4.5V I <sub>OH</sub> = -14.5mA						
			4.5V ≤ DV <sub>CC</sub> ≤ 5.5V I <sub>OH</sub> = -30mA						
			2.7V ≤ DV <sub>CC</sub> < 4.5V I <sub>OH</sub> = -14mA						
	V <sub>OH3</sub>	3mA type	4.5V ≤ V <sub>CC</sub> ≤ 5.5V I <sub>OH</sub> = -3mA	V <sub>CC</sub> - 0.5	-	V <sub>CC</sub>	V		
			2.7V ≤ V <sub>CC</sub> < 4.5V I <sub>OH</sub> = -1.5mA						
	"L" level output voltage	V <sub>OL4</sub>	4mA type	4.5V ≤ (D)V <sub>CC</sub> ≤ 5.5V I <sub>OL</sub> = +4mA	-	-	0.4		V
2.7V ≤ (D)V <sub>CC</sub> < 4.5V I <sub>OL</sub> = +1.7mA									
V <sub>OL30</sub>		High Drive type*	4.5V ≤ DV <sub>CC</sub> ≤ 5.5V I <sub>OL</sub> = +52mA	-	-	0.5	V	T <sub>A</sub> = -40°C	
			2.7V ≤ DV <sub>CC</sub> < 4.5V I <sub>OL</sub> = +22mA					T <sub>A</sub> = +25°C	
			4.5V ≤ DV <sub>CC</sub> ≤ 5.5V I <sub>OL</sub> = +39mA					T <sub>A</sub> = +85°C	
			2.7V ≤ DV <sub>CC</sub> < 4.5V I <sub>OL</sub> = +18mA					T <sub>A</sub> = +105°C	
			4.5V ≤ DV <sub>CC</sub> ≤ 5.5V I <sub>OL</sub> = +32mA						
			2.7V ≤ DV <sub>CC</sub> < 4.5V I <sub>OL</sub> = +14mA						
			4.5V ≤ DV <sub>CC</sub> ≤ 5.5V I <sub>OL</sub> = +30mA						
			2.7V ≤ DV <sub>CC</sub> < 4.5V I <sub>OL</sub> = +13.5mA						
V <sub>OL3</sub>		3mA type	2.7V ≤ V <sub>CC</sub> < 5.5V I <sub>OL</sub> = +3mA	-	-	0.4	V		
V <sub>OLD</sub>		DEBUG I/F	V <sub>CC</sub> = 2.7V I <sub>OL</sub> = +25mA	0	-	0.25	V		



Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input leak current	I <sub>IL</sub>	Pnn_m	V <sub>SS</sub> < V <sub>I</sub> < V <sub>CC</sub> AV <sub>SS</sub> < V <sub>I</sub> < AV <sub>CC</sub> , AVR <sub>H</sub>	- 1	-	+ 1	μA	Single port pin except high current output I/O for SMC
		P08_m	DV <sub>SS</sub> < V <sub>I</sub> < DV <sub>CC</sub> AV <sub>SS</sub> < V <sub>I</sub> < AV <sub>CC</sub> , AVR <sub>H</sub>	- 3	-	+ 3	μA	
Total LCD leak current	Σ I <sub>ILCD</sub>	All SEG/COM pin	V <sub>CC</sub> = 5.0V	-	0.5	10	μA	Maximum leakage current of all LCD pins
Internal LCD divide resistance	R <sub>LCD</sub>	Between V3 and V2, V2 and V1, V1 and V0	V <sub>CC</sub> = 5.0V	6.25	12.5	25	kΩ	
Pull-up resistance value	R <sub>PU</sub>	Pnn_m	V <sub>CC</sub> = 5.0V ±10%	25	50	100	kΩ	
Pull-down resistance value	R <sub>DOWN</sub>	P08_m	V <sub>CC</sub> = 5.0V ±10%	25	50	100	kΩ	
Input capacitance	C <sub>IN</sub>	Other than C, V <sub>CC</sub> , V <sub>SS</sub> , DV <sub>CC</sub> , DV <sub>SS</sub> , AV <sub>CC</sub> , AV <sub>SS</sub> , AVR <sub>H</sub> , P08_m	-	-	5	15	pF	
		P08_m	-	-	15	30	pF	

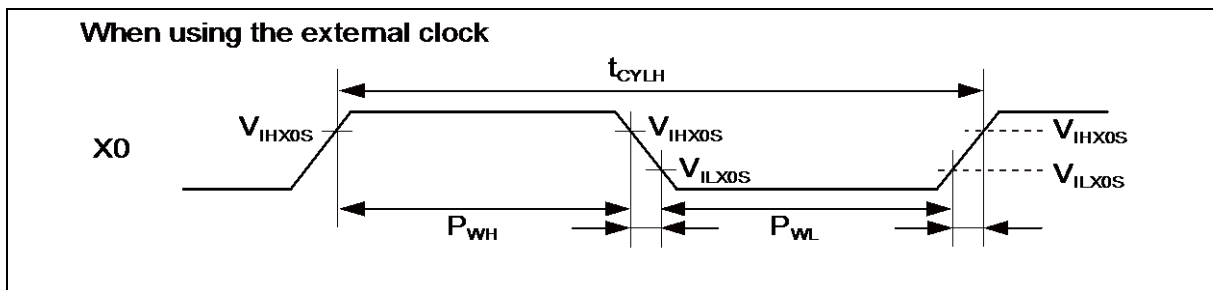
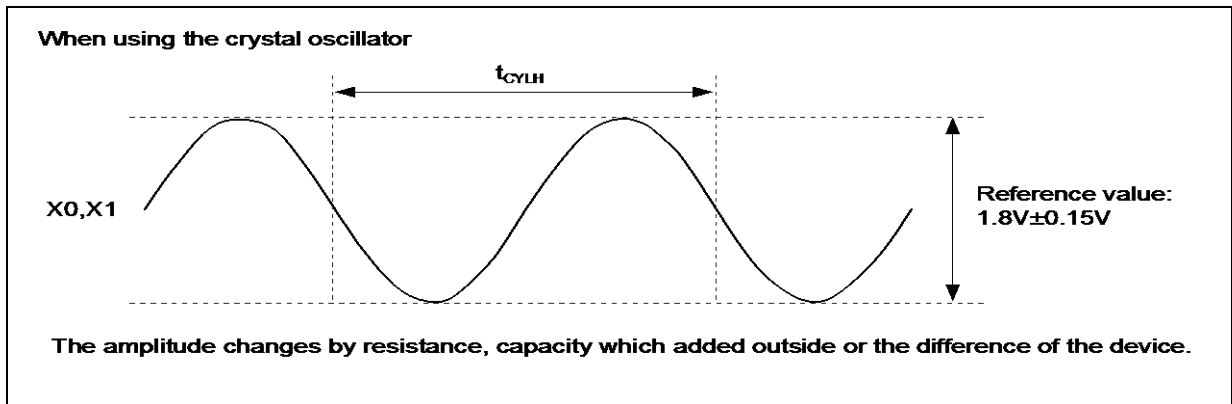
\*: In the case of driving stepping motor directly or high current outputs, set "1" to the bit in the Port High Drive Register (PHDRnn:HDx="1").

## 14.4 AC Characteristics

### 14.4.1 Main Clock Input Characteristics

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_D = 1.8V \pm 0.15V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^\circ C$  to  $+105^\circ C$ )

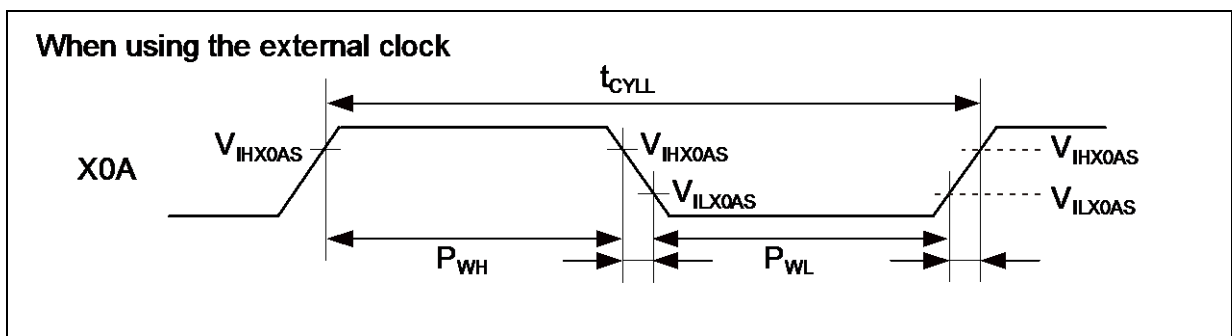
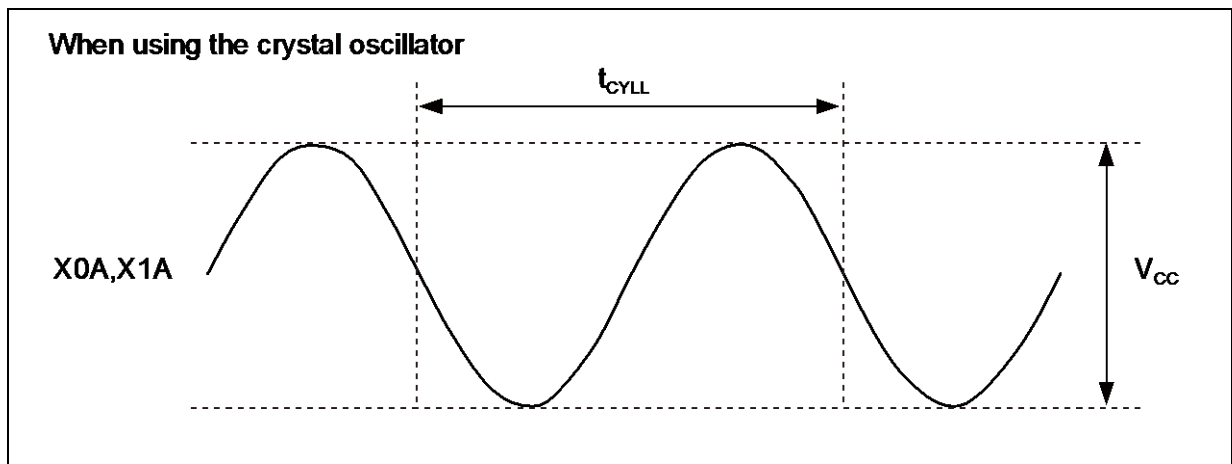
Parameter	Symbol	Pin Name	Value			Unit	Remarks
			Min	Typ	Max		
Input frequency	$f_c$	X0, X1	4	-	8	MHz	When using a crystal oscillator, PLL off
			-	-	8	MHz	When using an opposite phase external clock, PLL off
			4	-	8	MHz	When using a crystal oscillator or opposite phase external clock, PLL on
Input frequency	$f_{FCI}$	X0	-	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL off
			4	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL on
Input clock cycle	$t_{CYLH}$	-	125	-	-	ns	
Input clock pulse width	$P_{WH}, P_{WL}$	-	55	-	-	ns	



**14.4.2 Sub Clock Input Characteristics**

 ( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ )

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input frequency	$f_{CL}$	X0A, X1A	-	-	32.768	-	kHz	When using an oscillation circuit
			-	-	-	100		kHz
		X0A	-	-	-	50	kHz	When using a single phase external clock
Input clock cycle	$t_{CYLL}$	-	-	10	-	-	$\mu s$	
Input clock pulse width	-	-	$P_{WH}/t_{CYLL}$ , $P_{WL}/t_{CYLL}$	30	-	70	%	



**14.4.3 Built-in RC Oscillation Characteristics**
 $(V_{CC} = AV_{CC} = DV_{CC} = 2.7V \text{ to } 5.5V, V_{SS} = AV_{SS} = DV_{SS} = 0V, T_A = -40^{\circ}C \text{ to } +105^{\circ}C)$ 

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Clock frequency	$f_{RC}$	50	100	200	kHz	When using slow frequency of RC oscillator
		1	2	4		MHz
RC clock stabilization time	$t_{RCSTAB}$	80	160	320	$\mu s$	When using slow frequency of RC oscillator (16 RC clock cycles)
		64	128	256	$\mu s$	When using fast frequency of RC oscillator (256 RC clock cycles)

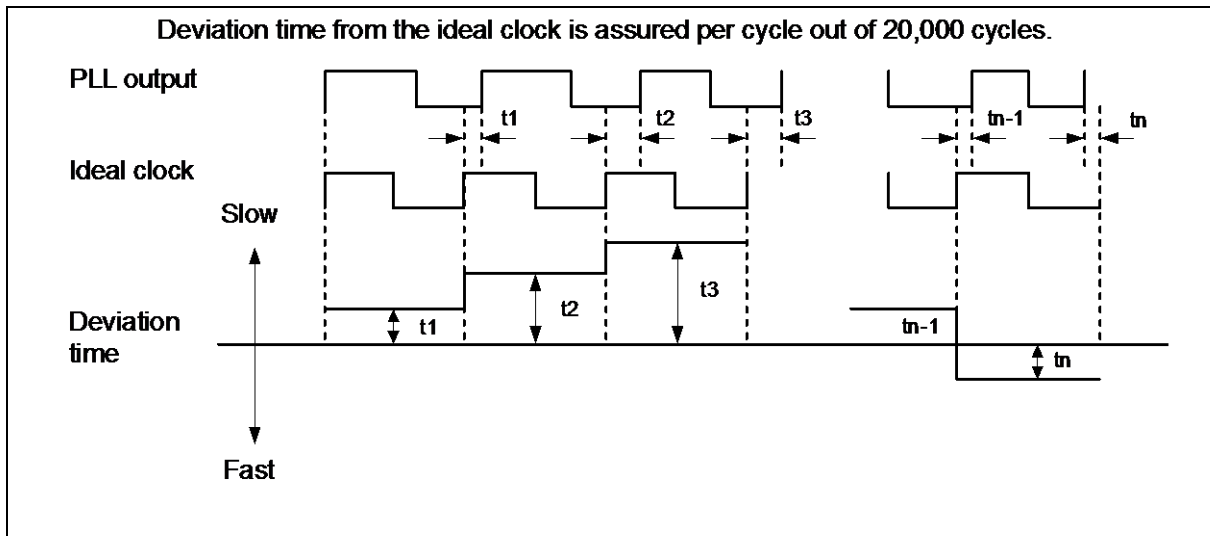
**14.4.4 Internal Clock Timing**
 $(V_{CC} = AV_{CC} = DV_{CC} = 2.7V \text{ to } 5.5V, V_{SS} = AV_{SS} = DV_{SS} = 0V, T_A = -40^{\circ}C \text{ to } +105^{\circ}C)$ 

Parameter	Symbol	Value		Unit
		Min	Max	
Internal System clock frequency (CLKS1 and CLKS2)	$f_{CLKS1}, f_{CLKS2}$	-	54	MHz
Internal CPU clock frequency (CLKB), Internal peripheral clock frequency (CLKP1)	$f_{CLKB}, f_{CLKP1}$	-	32	MHz
Internal peripheral clock frequency (CLKP2)	$f_{CLKP2}$	-	32	MHz

**14.4.5 Operating Conditions of PLL**

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ )

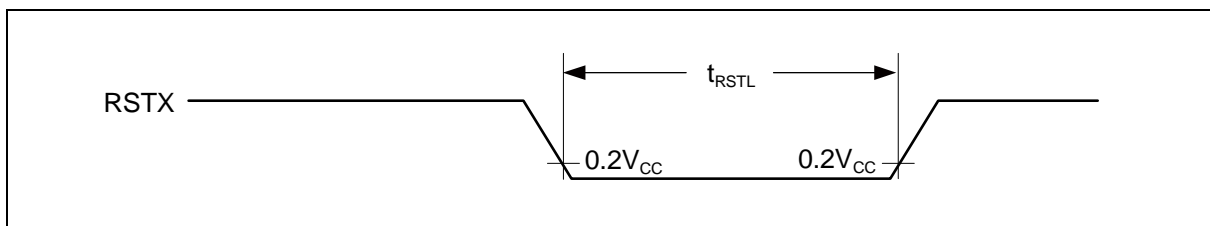
Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
PLL oscillation stabilization wait time	$t_{LOCK}$	1	-	4	ms	For CLKMC = 4MHz
PLL input clock frequency	$f_{PLL}$	4	-	8	MHz	
PLL oscillation clock frequency	$f_{CLKVCO}$	56	-	108	MHz	Permitted VCO output frequency of PLL (CLKVCO)
PLL phase jitter	$t_{PSKEW}$	-5	-	+5	ns	For CLKMC (PLL input clock) $\geq 4MHz$



**14.4.6 Reset Input**

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ )

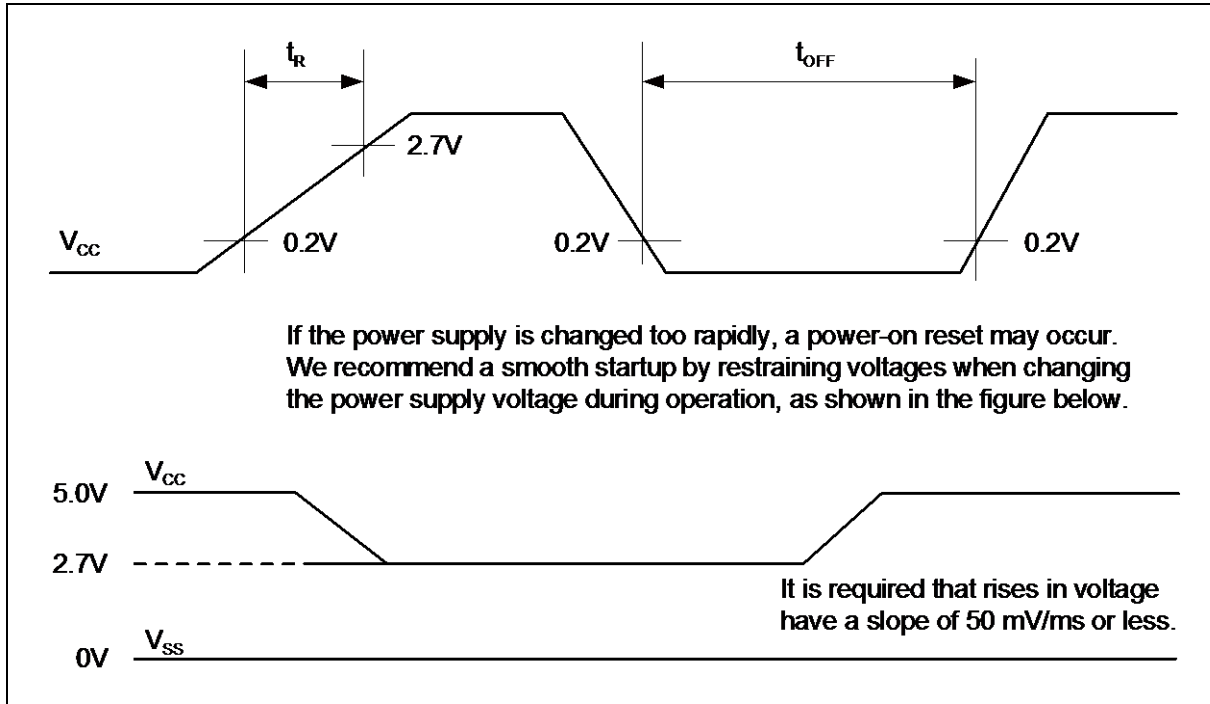
Parameter	Symbol	Pin Name	Value		Unit
			Min	Max	
Reset input time	$t_{RSTL}$	RSTX	10	-	$\mu s$
Rejection of reset input time			1	-	$\mu s$



14.4.7 Power-on Reset Timing

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ )

Parameter	Symbol	Pin Name	Value			Unit
			Min	Typ	Max	
Power on rise time	$t_R$	Vcc	0.05	-	30	ms
Power off time	$t_{OFF}$	Vcc	1	-	-	ms



14.4.8 USART Timing

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ ,  $C_L=50pF$ )

Parameter	Symbol	Pin Name	Conditions	4.5V ≤ V <sub>CC</sub> < 5.5V		2.7V ≤ V <sub>CC</sub> < 4.5V		Unit
				Min	Max	Min	Max	
Serial clock cycle time	t <sub>SCYC</sub>	SCKn	Internal shift clock mode	4t <sub>CLKP1</sub>	-	4t <sub>CLKP1</sub>	-	ns
SCK ↓ → SOT delay time	t <sub>SLOVI</sub>	SCKn, SOTn		- 20	+ 20	- 30	+ 30	ns
SOT → SCK ↑ delay time	t <sub>OVSHI</sub>	SCKn, SOTn		N×t <sub>CLKP1</sub> - 20*	-	N×t <sub>CLKP1</sub> - 30*	-	ns
SIN → SCK ↑ setup time	t <sub>IVSHI</sub>	SCKn, SINn		t <sub>CLKP1</sub> + 45	-	t <sub>CLKP1</sub> + 55	-	ns
SCK ↑ → SIN hold time	t <sub>SHIXI</sub>	SCKn, SINn		0	-	0	-	ns
Serial clock "L" pulse width	t <sub>LSLH</sub>	SCKn	External shift clock mode	t <sub>CLKP1</sub> + 10	-	t <sub>CLKP1</sub> + 10	-	ns
Serial clock "H" pulse width	t <sub>SHSL</sub>	SCKn		t <sub>CLKP1</sub> + 10	-	t <sub>CLKP1</sub> + 10	-	ns
SCK ↓ → SOT delay time	t <sub>SLOVE</sub>	SCKn, SOTn		-	2t <sub>CLKP1</sub> + 45	-	2t <sub>CLKP1</sub> + 55	ns
SIN → SCK ↑ setup time	t <sub>IVSHE</sub>	SCKn, SINn		t <sub>CLKP1</sub> /2 + 10	-	t <sub>CLKP1</sub> /2 + 10	-	ns
SCK ↑ → SIN hold time	t <sub>SHIXE</sub>	SCKn, SINn		t <sub>CLKP1</sub> + 10	-	t <sub>CLKP1</sub> + 10	-	ns
SCK fall time	t <sub>F</sub>	SCKn		-	20	-	20	ns
SCK rise time	t <sub>R</sub>	SCKn		-	20	-	20	ns

Notes:

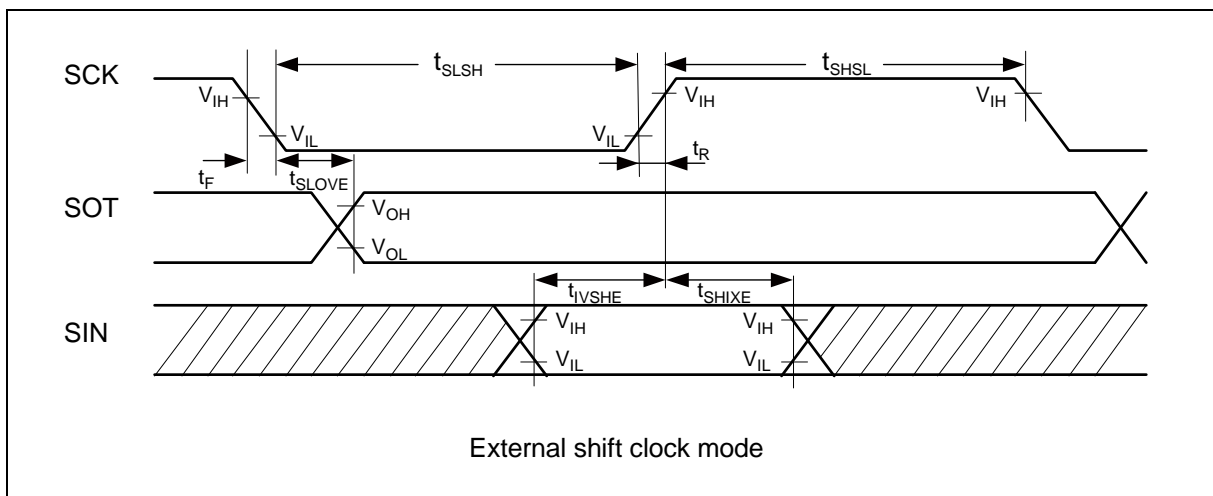
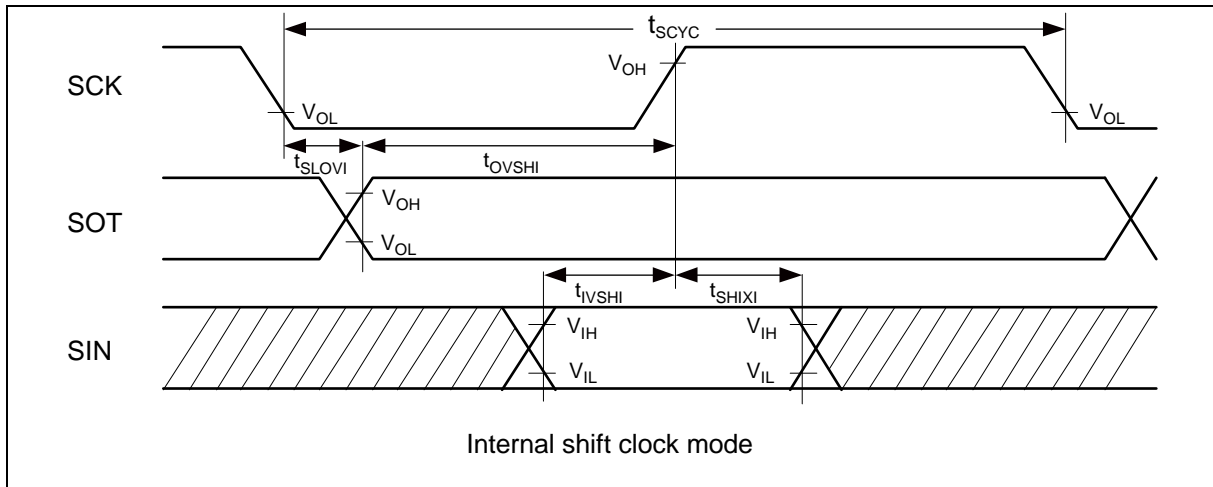
- AC characteristic in CLK synchronized mode.
- C<sub>L</sub> is the load capacity value of pins when testing.
- Depending on the used machine clock frequency, the maximum possible baud rate can be limited by some parameters. These parameters are shown in "CY96600 series HARDWARE MANUAL".
- t<sub>CLKP1</sub> indicates the peripheral clock 1 (CLKP1), Unit: ns
- These characteristics only guarantee the same relocate port number.  
For example, the combination of SCKn and SOTn\_R is not guaranteed.

\*: Parameter N depends on t<sub>SCYC</sub> and can be calculated as follows:

- If t<sub>SCYC</sub> = 2 × k × t<sub>CLKP1</sub>, then N = k, where k is an integer > 2
- If t<sub>SCYC</sub> = (2 × k + 1) × t<sub>CLKP1</sub>, then N = k + 1, where k is an integer > 1

Examples:

t <sub>scyc</sub>	N
4 × t <sub>CLKP1</sub>	2
5 × t <sub>CLKP1</sub> , 6 × t <sub>CLKP1</sub>	3
7 × t <sub>CLKP1</sub> , 8 × t <sub>CLKP1</sub>	4
...	...



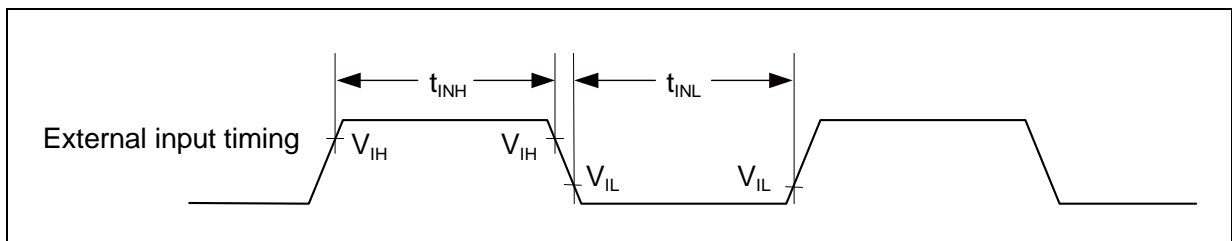


14.4.9 External Input Timing

(V<sub>CC</sub> = AV<sub>CC</sub> = DV<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = AV<sub>SS</sub> = DV<sub>SS</sub> = 0V, T<sub>A</sub> = - 40°C to + 105°C)

Parameter	Symbol	Pin Name	Value		Unit	Remarks
			Min	Max		
Input pulse width	t <sub>INH</sub> , t <sub>INL</sub>	Pnn_m	2t <sub>CLKP1</sub> + 200 (t <sub>CLKP1</sub> = 1/f <sub>CLKP1</sub> )*	-	ns	General Purpose I/O
		ADTG				A/D Converter trigger input
		TINn, TINn_R				Reload Timer
		TTGn				PPG trigger input
		INn, INn_R				Input Capture
		INTn, INTn_R	External Interrupt			
		NMI	Non-Maskable Interrupt			
			200	-	ns	

\*: t<sub>CLKP1</sub> indicates the peripheral clock1 (CLKP1) cycle time except stop when in stop mode.



14.4.10 I<sup>2</sup>C Timing

(V<sub>CC</sub> = AV<sub>CC</sub> = DV<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = AV<sub>SS</sub> = DV<sub>SS</sub> = 0V, T<sub>A</sub> = - 40°C to + 105°C)

Parameter	Symbol	Conditions	Typical Mode		High-Speed Mode <sup>*4</sup>		Unit	
			Min	Max	Min	Max		
SCL clock frequency	f <sub>SCL</sub>		0	100	0	400	kHz	
(Repeated) START condition hold time SDA ↓ → SCL ↓	t <sub>HDSTA</sub>	C <sub>L</sub> = 50pF, R = (V <sub>p</sub> /I <sub>OL</sub> ) <sup>*1</sup>	4.0	-	0.6	-	μs	
SCL clock "L" width	t <sub>LOW</sub>		4.7	-	1.3	-	μs	
SCL clock "H" width	t <sub>HIGH</sub>		4.0	-	0.6	-	μs	
(Repeated) START condition setup time SCL ↑ → SDA ↓	t <sub>SUSTA</sub>		4.7	-	0.6	-	μs	
Data hold time SCL ↓ → SDA ↓ ↑	t <sub>HDDAT</sub>		0	3.45 <sup>*2</sup>	0	0.9 <sup>*3</sup>	μs	
Data setup time SDA ↓ ↑ → SCL ↑	t <sub>SUDAT</sub>		250	-	100	-	ns	
STOP condition setup time SCL ↑ → SDA ↑	t <sub>SUSTO</sub>		4.0	-	0.6	-	μs	
Bus free time between "STOP condition" and "START condition"	t <sub>BUS</sub>		4.7	-	1.3	-	μs	
Pulse width of spikes which will be suppressed by input noise filter	t <sub>SP</sub>		-	0	(1-1.5) × t <sub>CLKP1</sub> <sup>*5</sup>	0	(1-1.5) × t <sub>CLKP1</sub> <sup>*5</sup>	ns

\*1: R and C<sub>L</sub> represent the pull-up resistance and load capacitance of the SCL and SDA lines, respectively.

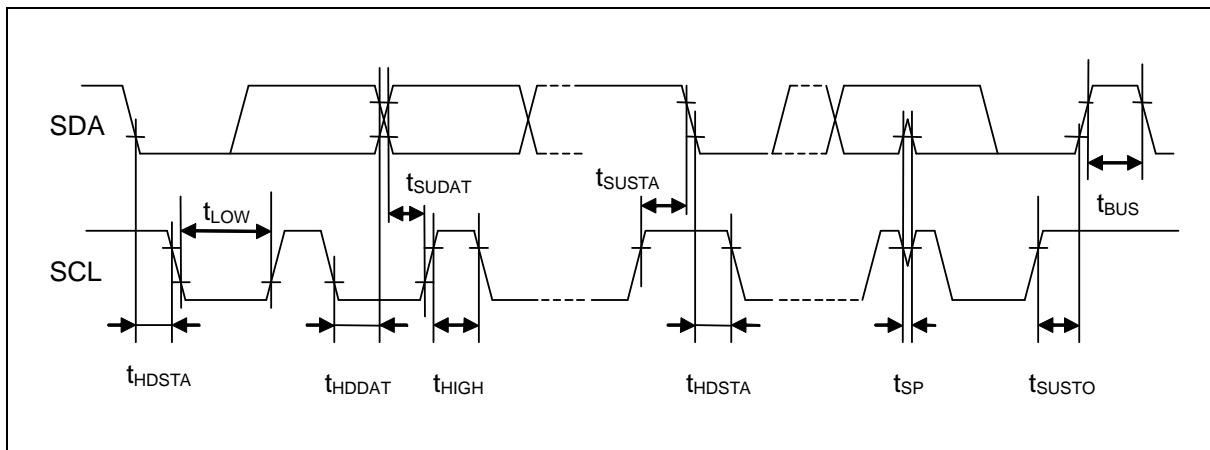
V<sub>p</sub> indicates the power supply voltage of the pull-up resistance and I<sub>OL</sub> indicates V<sub>OL</sub> guaranteed current.

\*2: The maximum t<sub>HDDAT</sub> only has to be met if the device does not extend the "L" width (t<sub>LOW</sub>) of the SCL signal.

\*3: A high-speed mode I<sup>2</sup>C bus device can be used on a standard mode I<sup>2</sup>C bus system as long as the device satisfies the requirement of "t<sub>SUDAT</sub> ≥ 250ns".

\*4: For use at over 100kHz, set the peripheral clock1 (CLKP1) to at least 6MHz.

\*5: t<sub>CLKP1</sub> indicates the peripheral clock1 (CLKP1) cycle time.



**14.5 A/D Converter**
**14.5.1 Electrical Characteristics for the A/D Converter**
*(V<sub>CC</sub> = AV<sub>CC</sub> = DV<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = AV<sub>SS</sub> = DV<sub>SS</sub> = 0V, T<sub>A</sub> = - 40°C to + 105°C)*

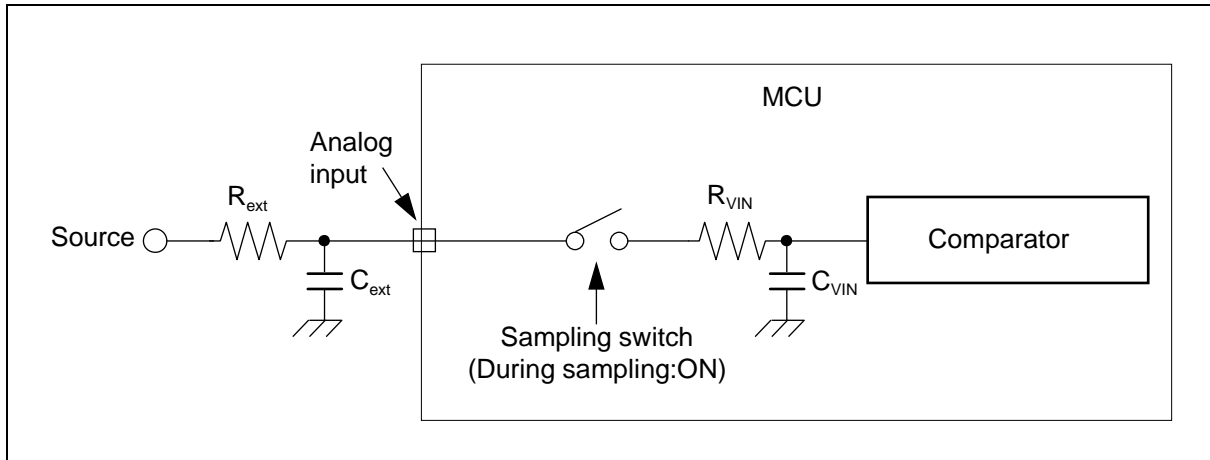
Parameter	Symbol	Pin Name	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	-	-	-	-	10	bit	
Total error	-	-	- 3.0	-	+ 3.0	LSB	
Nonlinearity error	-	-	- 2.5	-	+ 2.5	LSB	
Differential Nonlinearity error	-	-	- 1.9	-	+ 1.9	LSB	
Zero transition voltage	V <sub>OT</sub>	ANn	Typ - 20	AV <sub>SS</sub> + 0.5LSB	Typ + 20	mV	
Full scale transition voltage	V <sub>FST</sub>	ANn	Typ - 20	AVRH - 1.5LSB	Typ + 20	mV	
Compare time*	-	-	1.0	-	5.0	μs	4.5V ≤ AV <sub>CC</sub> ≤ 5.5V
			2.2	-	8.0	μs	2.7V ≤ AV <sub>CC</sub> < 4.5V
Sampling time*	-	-	0.5	-	-	μs	4.5V ≤ AV <sub>CC</sub> ≤ 5.5V
			1.2	-	-	μs	2.7V ≤ AV <sub>CC</sub> < 4.5V
Power supply current	I <sub>A</sub>	AV <sub>CC</sub>	-	2.0	3.1	mA	A/D Converter active
	I <sub>AH</sub>		-	-	3.3	μA	A/D Converter not operated
Reference power supply current (between AVRH and AV <sub>SS</sub> )	I <sub>R</sub>	AVRH	-	520	810	μA	A/D Converter active
	I <sub>RH</sub>		-	-	1.0	μA	A/D Converter not operated
Analog input capacity	C <sub>VIN</sub>	AN8, 9, 12, 13	-	-	15.5	pF	Normal outputs
		AN16 to 23	-	-	17.4	pF	High current outputs
Analog impedance	R <sub>VIN</sub>	ANn	-	-	1450	Ω	4.5V ≤ AV <sub>CC</sub> ≤ 5.5V
			-	-	2700	Ω	2.7V ≤ AV <sub>CC</sub> < 4.5V
Analog port input current (during conversion)	I <sub>AIN</sub>	AN8, 9, 12, 13	- 1.0	-	+ 1.0	μA	AV <sub>SS</sub> < V <sub>AIN</sub> < AV <sub>CC</sub> , AVRH
		AN16 to 23	- 3.0	-	+ 3.0	μA	
Analog input voltage	V <sub>AIN</sub>	ANn	AV <sub>SS</sub>	-	AVRH	V	
Reference voltage range	-	AVRH	AV <sub>CC</sub> - 0.1	-	AV <sub>CC</sub>	V	
Variation between channels	-	ANn	-	-	4.0	LSB	

\*: Time for each channel.

**14.5.2 Accuracy and Setting of the A/D Converter Sampling Time**

If the external impedance is too high or the sampling time too short, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting the A/D conversion precision.

To satisfy the A/D conversion precision, a sufficient sampling time must be selected. The required sampling time ( $T_{samp}$ ) depends on the external driving impedance  $R_{ext}$ , the board capacitance of the A/D converter input pin  $C_{ext}$  and the  $AV_{CC}$  voltage level. The following replacement model can be used for the calculation:



$R_{ext}$ : External driving impedance

$C_{ext}$ : Capacitance of PCB at A/D converter input

$C_{VIN}$ : Analog input capacity (I/O, analog switch and ADC are contained)

$R_{VIN}$ : Analog input impedance (I/O, analog switch and ADC are contained)

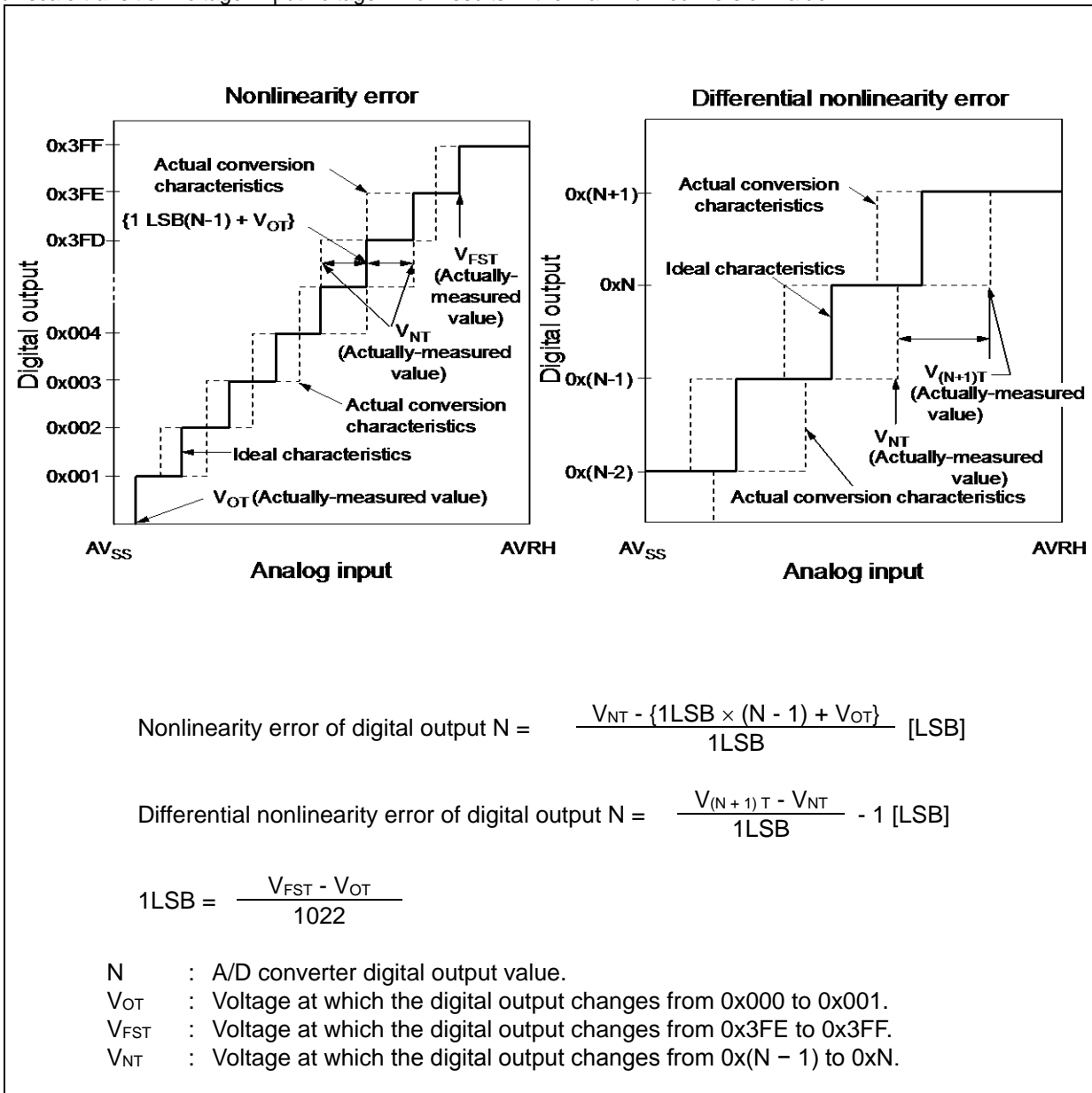
The following approximation formula for the replacement model above can be used:

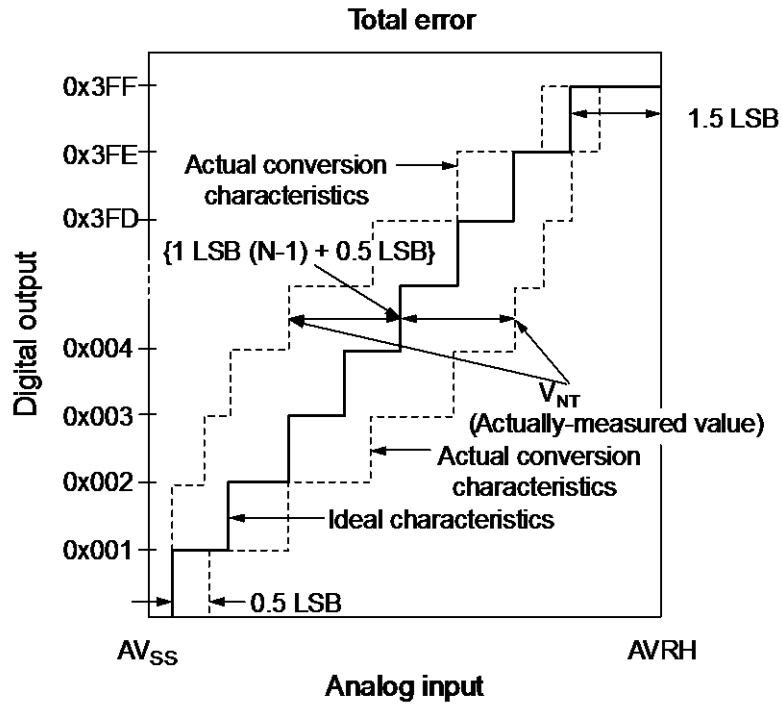
$$T_{samp} = 7.62 \times (R_{ext} \times C_{ext} + (R_{ext} + R_{VIN}) \times C_{VIN})$$

- Do not select a sampling time below the absolute minimum permitted value. (0.5 $\mu$ s for 4.5V  $\leq$   $AV_{CC}$   $\leq$  5.5V, 1.2 $\mu$ s for 2.7V  $\leq$   $AV_{CC}$  < 4.5V)
- If the sampling time cannot be sufficient, connect a capacitor of about 0.1 $\mu$ F to the analog input pin.
- A big external driving impedance also adversely affects the A/D conversion precision due to the pin input leakage current  $I_{IL}$  (static current before the sampling switch) or the analog input leakage current  $I_{AIN}$  (total leakage current of pin input and comparator during sampling). The effect of the pin input leakage current  $I_{IL}$  cannot be compensated by an external capacitor.
- The accuracy gets worse as  $|AVRH - AV_{SS}|$  becomes smaller.

14.5.3 Definition of A/D Converter Terms

- Resolution : Analog variation that is recognized by an A/D converter.
- Nonlinearity error : Deviation of the actual conversion characteristics from a straight line that connects the zero transition point (0b0000000000 ↔ 0b0000000001) to the full-scale transition point (0b1111111110 ↔ 0b1111111111).
- Differential nonlinearity error : Deviation from the ideal value of the input voltage that is required to change the output code by 1LSB.
- Total error : Difference between the actual value and the theoretical value. The total error includes zero transition error, full-scale transition error and nonlinearity error.
- Zero transition voltage : Input voltage which results in the minimum conversion value.
- Full scale transition voltage: Input voltage which results in the maximum conversion value.





$$1\text{LSB (Ideal value)} = \frac{\text{AVRH} - \text{AV}_{\text{SS}}}{1024} \text{ [V]}$$

$$\text{Total error of digital output N} = \frac{V_{\text{NT}} - \{1\text{LSB} \times (\text{N} - 1) + 0.5\text{LSB}\}}{1\text{LSB}}$$

N : A/D converter digital output value.

V<sub>NT</sub> : Voltage at which the digital output changes from 0x(N + 1) to 0xN.

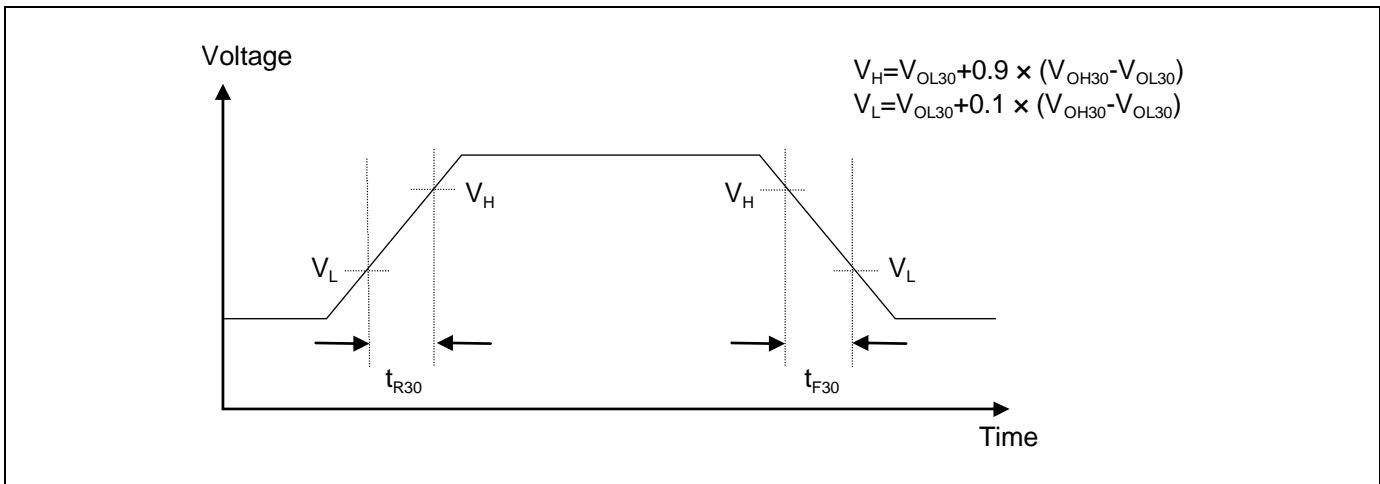
V<sub>OT</sub> (Ideal value) = AV<sub>SS</sub> + 0.5LSB[V]

V<sub>FST</sub> (Ideal value) = AV<sub>RH</sub> - 1.5LSB[V]

### 14.6 High Current Output Slew Rate

( $V_{CC} = AV_{CC} = DV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = DV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+105^{\circ}C$ )

Parameter	Symbol	Pin Name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Output rise/fall time	$t_{R30}$ , $t_{F30}$	P08_m	Outputs driving strength set to "30mA"	15	-	75	ns	$C_L=85pF$



**14.7 Low Voltage Detection Function Characteristics**

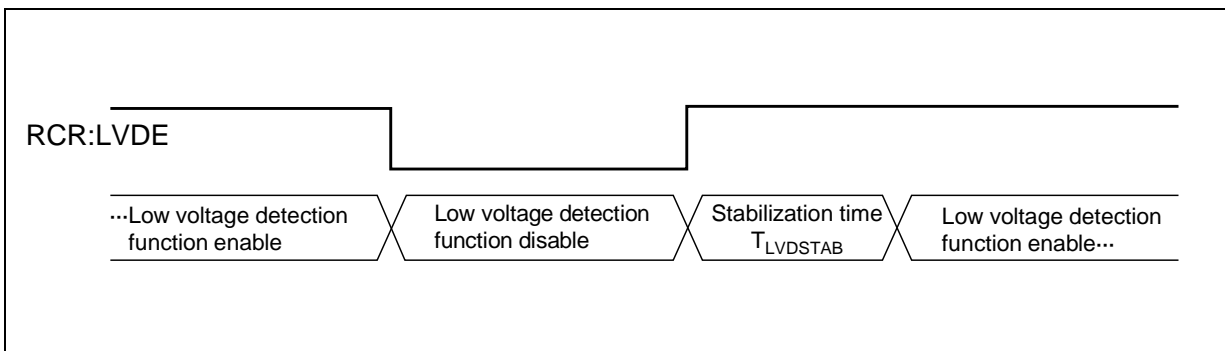
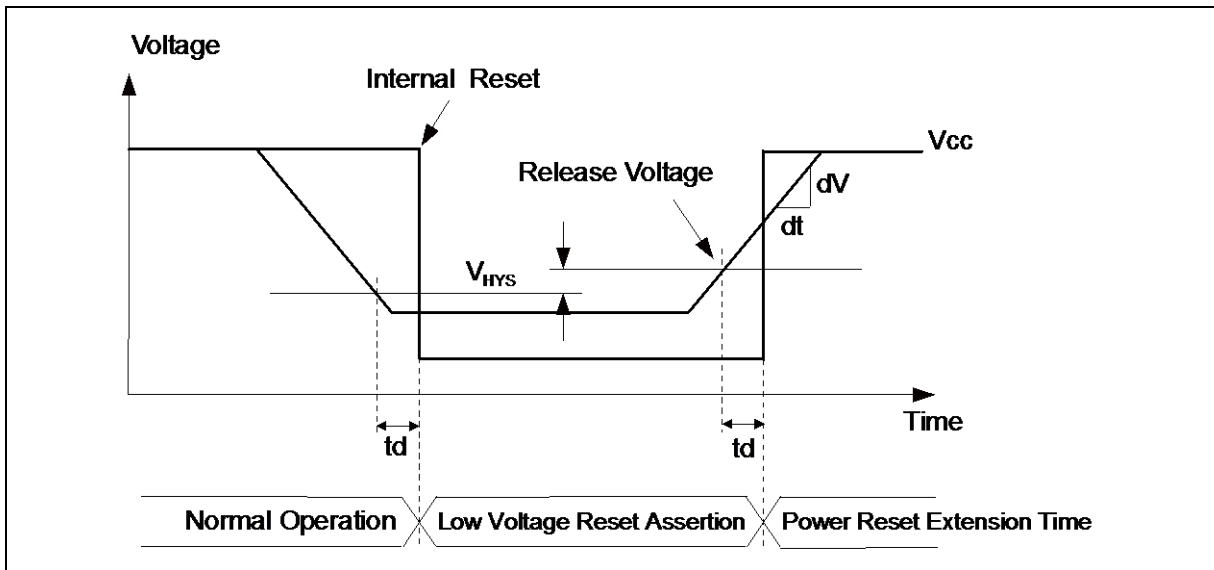
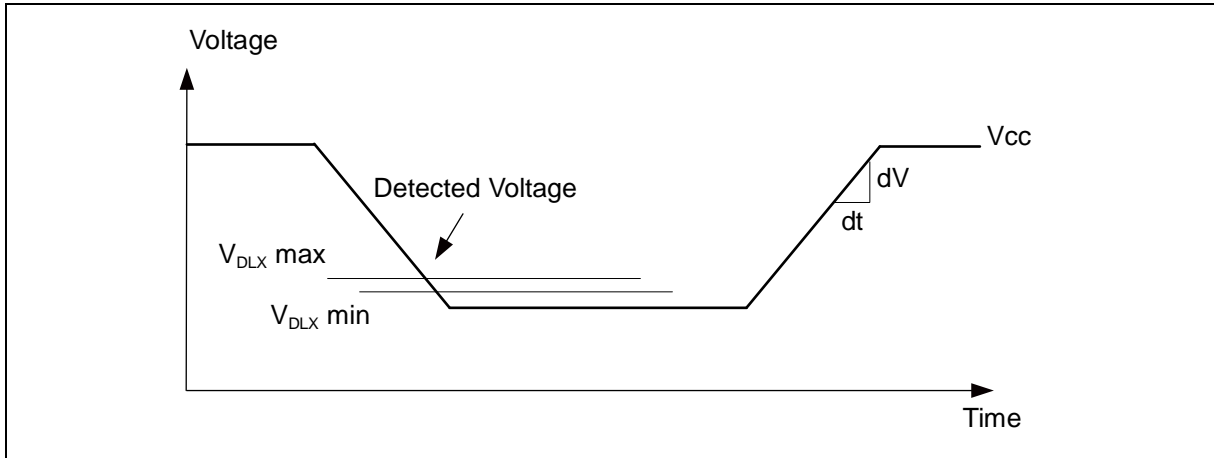
 (V<sub>CC</sub> = AV<sub>CC</sub> = DV<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = AV<sub>SS</sub> = DV<sub>SS</sub> = 0V, T<sub>A</sub> = - 40°C to + 105°C)

Parameter	Symbol	Conditions	Value			Unit
			Min	Typ	Max	
Detected voltage <sup>*1</sup>	V <sub>DL0</sub>	CILCR:LVL = 0000 <sub>B</sub>	2.70	2.90	3.10	V
	V <sub>DL1</sub>	CILCR:LVL = 0001 <sub>B</sub>	2.79	3.00	3.21	V
	V <sub>DL2</sub>	CILCR:LVL = 0010 <sub>B</sub>	2.98	3.20	3.42	V
	V <sub>DL3</sub>	CILCR:LVL = 0011 <sub>B</sub>	3.26	3.50	3.74	V
	V <sub>DL4</sub>	CILCR:LVL = 0100 <sub>B</sub>	3.45	3.70	3.95	V
	V <sub>DL5</sub>	CILCR:LVL = 0111 <sub>B</sub>	3.73	4.00	4.27	V
	V <sub>DL6</sub>	CILCR:LVL = 1001 <sub>B</sub>	3.91	4.20	4.49	V
Power supply voltage change rate <sup>*2</sup>	dV/dt	-	- 0.004	-	+ 0.004	V/μs
Hysteresis width	V <sub>HYS</sub>	CILCR:LVHYS=0	-	-	50	mV
		CILCR:LVHYS=1	80	100	120	mV
Stabilization time	T <sub>LVDSTAB</sub>	-	-	-	75	μs
Detection delay time	t <sub>d</sub>	-	-	-	30	μs

\*1: If the power supply voltage fluctuates within the time less than the detection delay time (t<sub>d</sub>), there is a possibility that the low voltage detection will occur or stop after the power supply voltage passes the detection range.

\*2: In order to perform the low voltage detection at the detection voltage (V<sub>DLX</sub>), be sure to suppress fluctuation of the power supply voltage within the limits of the change ration of power supply voltage.





**14.8 Flash Memory Write/Erase Characteristics**

 (V<sub>CC</sub> = AV<sub>CC</sub> = DV<sub>CC</sub> = 2.7V to 5.5V, V<sub>SS</sub> = AV<sub>SS</sub> = DV<sub>SS</sub> = 0V, T<sub>A</sub> = - 40°C to + 105°C)

Parameter	Conditions	Value			Unit	Remarks
		Min	Typ	Max		
Sector erase time	Large Sector	-	1.6	7.5	s	Includes write time prior to internal erase.
	Small Sector	-	0.4	2.1	s	
	Security Sector	-	0.31	1.65	s	
Word (16-bit) write time	-	-	25	400	μs	Not including system-level overhead time.
Chip erase time	-	-	5.11	25.05	s	Includes write time prior to internal erase.

**Note:**

While the Flash memory is written or erased, shutdown of the external power (V<sub>CC</sub>) is prohibited. In the application system where the external power (V<sub>CC</sub>) might be shut down while writing or erasing, be sure to turn the power off by using a low voltage detection function.

To put it concrete, change the external power in the range of change ration of power supply voltage (-0.004V/μs to +0.004V/μs) after the external power falls below the detection voltage (V<sub>DLX</sub>)<sup>\*1</sup>.

## Write/Erase cycles and data hold time

Write/Erase Cycles (Cycle)	Data Hold Time (Year)
1,000	20 <sup>*2</sup>
10,000	10 <sup>*2</sup>
100,000	5 <sup>*2</sup>

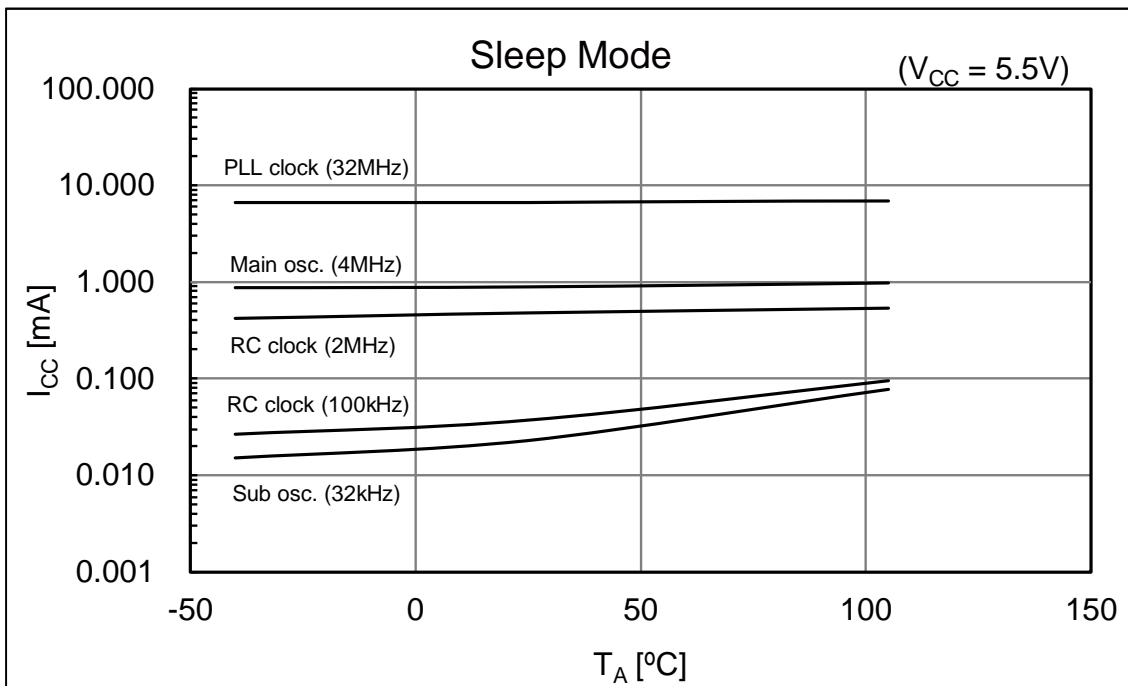
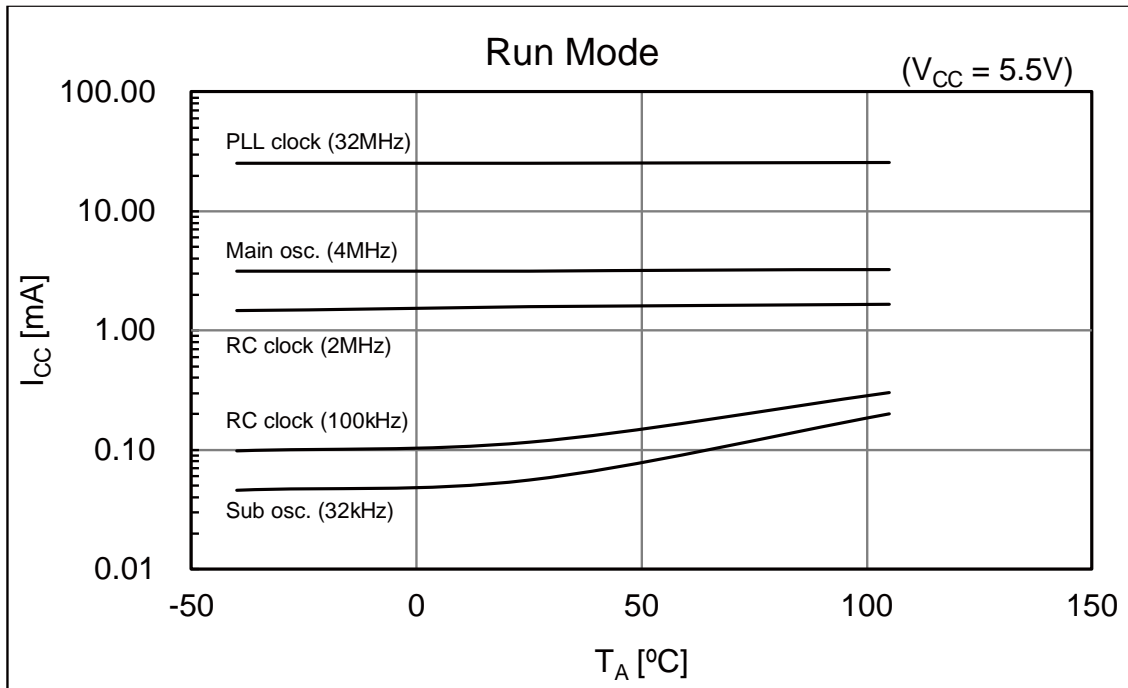
\*1: See "Low Voltage Detection Function Characteristics".

\*2: This value comes from the technology qualification (using Arrhenius equation to translate high temperature measurements into normalized value at + 85°C).

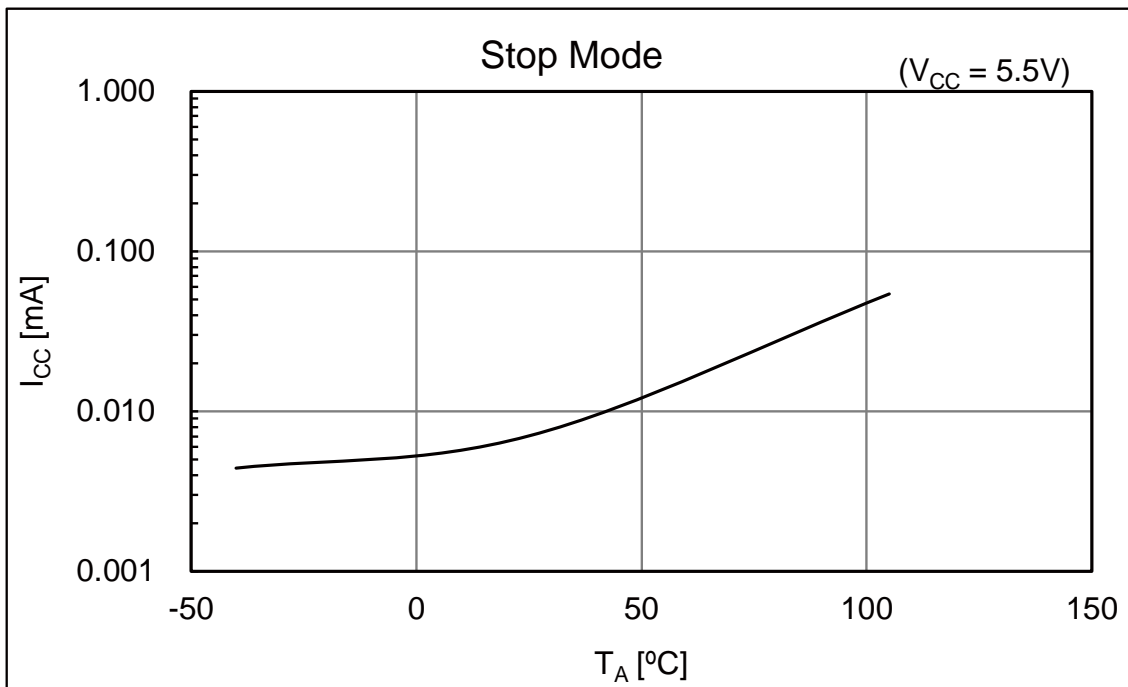
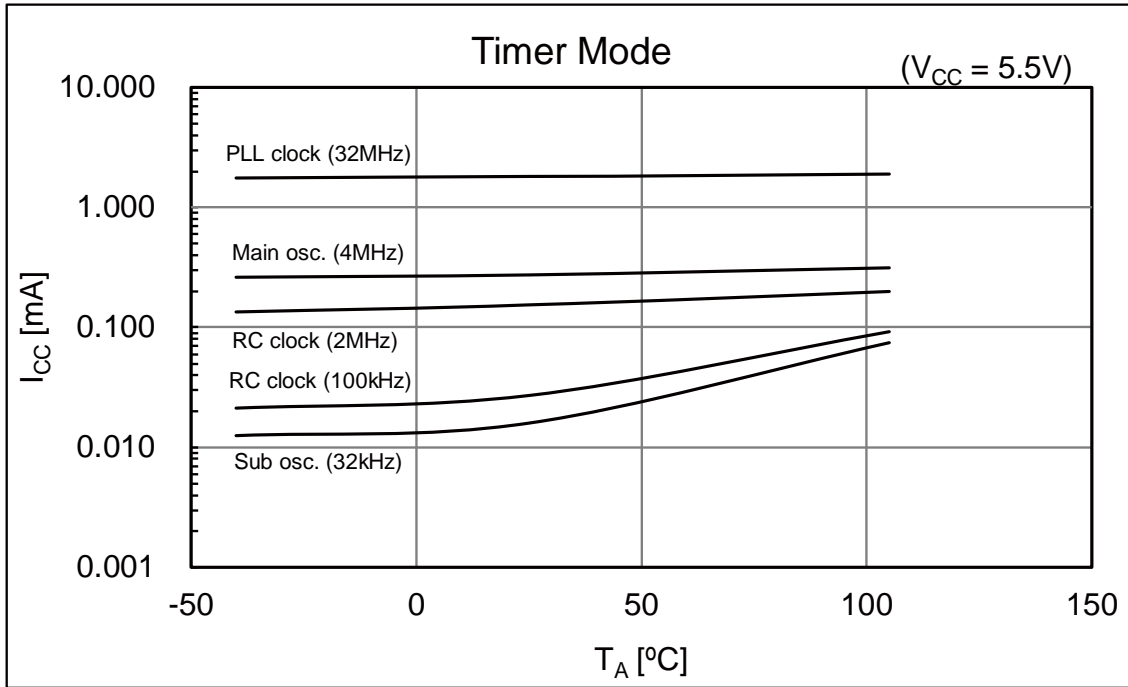
### 15. Example Characteristics

This characteristic is an actual value of the arbitrary sample. It is not the guaranteed value.

■ CY96F675



■ CY96F675



**■ Used setting**

Mode	Selected Source Clock	Clock/Regulator and FLASH Settings
Run mode	PLL	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 32MHz
	Main osc.	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 4MHz
	RC clock fast	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 2MHz
	RC clock slow	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 100kHz
	Sub osc.	CLKS1 = CLKS2 = CLKB = CLKP1 = CLKP2 = 32kHz
Sleep mode	PLL	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 32MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	Main osc.	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 4MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	RC clock fast	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 2MHz Regulator in High Power Mode, (CLKB is stopped in this mode)
	RC clock slow	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 100kHz Regulator in Low Power Mode, (CLKB is stopped in this mode)
	Sub osc.	CLKS1 = CLKS2 = CLKP1 = CLKP2 = 32kHz Regulator in Low Power Mode, (CLKB is stopped in this mode)
Timer mode	PLL	CLKMC = 4MHz, CLKPLL = 32MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	Main osc.	CLKMC = 4MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	RC clock fast	CLKMC = 2MHz (System clocks are stopped in this mode) Regulator in High Power Mode, FLASH in Power-down / reset mode
	RC clock slow	CLKMC = 100kHz (System clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode
	Sub osc.	CLKMC = 32 kHz (System clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode
Stop mode	stopped	(All clocks are stopped in this mode) Regulator in Low Power Mode, FLASH in Power-down / reset mode

## 16. Ordering Information

### MCU with CAN Controller

Part Number	Flash Memory	Package*
CY96F673RBPMC-GS-UJE1	Flash A (96.5KB)	64-pin plastic LQFP (LQG064)
CY96F673RBPMC-GS-UJE2		64-pin plastic LQFP (LQD064)
CY96F673RBPMC1-GS-UJE1		64-pin plastic LQFP (LQD064)
CY96F675RBPMC1-GS-UJE2	Flash A (160.5KB)	64-pin plastic LQFP (LQD064)

\*: For details about package, see "[PACKAGE DIMENSION](#)".

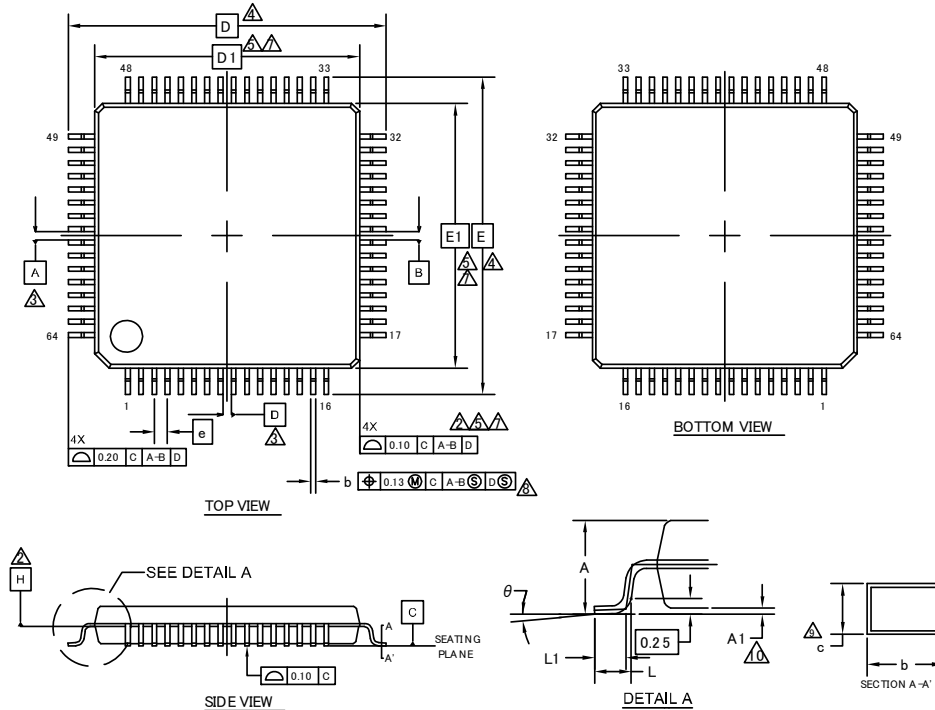
### MCU without CAN Controller

Part Number	Flash Memory	Package*
CY96F673ABPMC-GS-UJE2	Flash A (96.5KB)	64-pin plastic LQFP (LQG064)
CY96F673ABPMC1-GS-UJE1		64-pin plastic LQFP (LQD064)
CY96F673ABPMC1-GS-UJE2		64-pin plastic LQFP (LQD064)

\*: For details about package, see "[PACKAGE DIMENSION](#)".

### 17. Package Dimension

Package Type	Package Code
LQFP 64 pin	LQG064



SYMBOL	DIMENSION		
	MIN.	NOM.	MAX.
A	—	—	1.70
A1	0.00	—	0.20
b	0.27	0.32	0.37
c	0.09	—	0.20
D	14.00 BSC		
D1	12.00 BSC		
e	0.65 BSC		
E	14.00 BSC		
E1	12.00 BSC		
L	0.45	0.60	0.75
L1	0.30	0.50	0.70
$\theta$	0°	—	8°

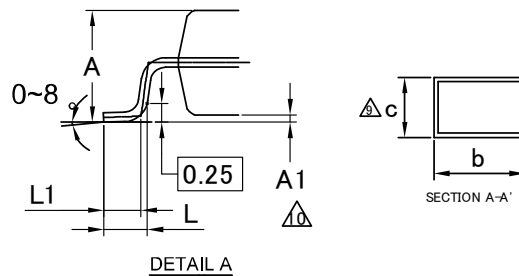
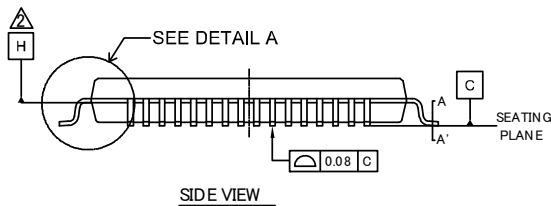
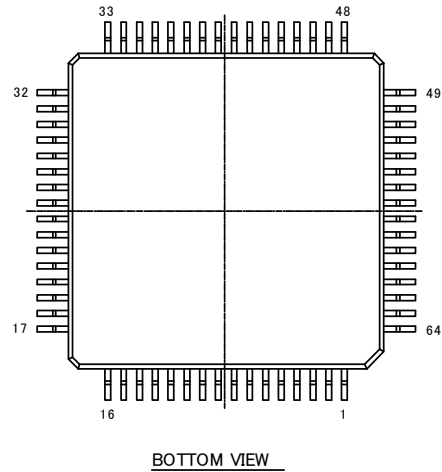
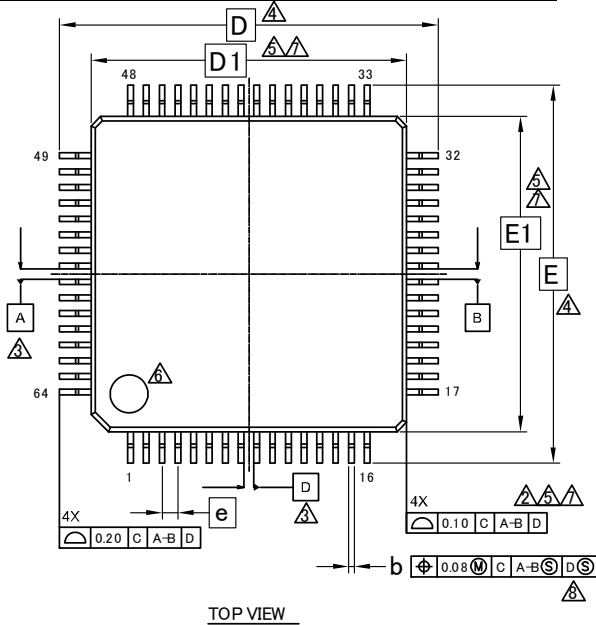
#### NOTES

- ALL DIMENSIONS ARE IN MILLIMETERS.
- DATUM PLANE H IS LOCATED AT THE BOTTOM OF THE MOLD PARTING LINE COINCIDENT WITH WHERE THE LEAD EXITS THE BODY.
- DATUMS A-B AND D TO BE DETERMINED AT DATUM PLANE H.
- TO BE DETERMINED AT SEATING PLANE C.
- DIMENSIONS D1 AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25mm PRE SIDE. DIMENSIONS D1 AND E1 INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE H.
- DETAILS OF PIN 1 IDENTIFIER ARE OPTIONAL BUT MUST BE LOCATED WITHIN THE ZONE INDICATED.
- REGARDLESS OF THE RELATIVE SIZE OF THE UPPER AND LOWER BODY SECTIONS, DIMENSIONS D1 AND E1 ARE DETERMINED AT THE LARGEST FEATURE OF THE BODY EXCLUSIVE OF MOLD FLASH AND GATE BURRS, BUT INCLUDING ANY MISMATCH BETWEEN THE UPPER AND LOWER SECTIONS OF THE MOLDER BODY.
- DIMENSION b DOES NOT INCLUDE DAMBER PROTRUSION. THE DAMBER PROTRUSION (S) SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED b MAXIMUM BY MORE THAN 0.08mm. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE LEAD FOOT.
- THESE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.10mm AND 0.25mm FROM THE LEAD TIP.
- A1 IS DEFINED AS THE DISTANCE FROM THE SEATING PLANE TO THE LOWEST POINT OF THE PACKAGE BODY.

002-13881 \*\*

PACKAGE OUTLINE, 64 LEAD LQFP  
12.0X12.0X1.7 MM LQG064 REV\*\*

Package Type	Package Code
LQFP 64 pin	LQD064



SYMBOL	DIMENSIONS		
	MIN.	NOM.	MAX.
A	—	—	1.70
A1	0.00	—	0.20
b	0.15	—	0.27
c	0.09	—	0.20
D	12.00 BSC.		
D1	10.00 BSC.		
e	0.50 BSC.		
E	12.00 BSC.		
E1	10.00 BSC.		
L	0.45	0.60	0.75
L1	0.30	0.50	0.70

### NOTES

- ALL DIMENSIONS ARE IN MILLIMETERS.
- DATUM PLANE H IS LOCATED AT THE BOTTOM OF THE MOLD PARTING LINE COINCIDENT WITH WHERE THE LEAD EXITS THE BODY.
- DATUMS A-B AND D TO BE DETERMINED AT DATUM PLANE H.
- TO BE DETERMINED AT SEATING PLANE C.
- DIMENSIONS D1 AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25mm PRE SIDE. DIMENSIONS D1 AND E1 INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE H.
- DETAILS OF PIN 1 IDENTIFIER ARE OPTIONAL BUT MUST BE LOCATED WITHIN THE ZONE INDICATED.
- REGARDLESS OF THE RELATIVE SIZE OF THE UPPER AND LOWER BODY SECTIONS, DIMENSIONS D1 AND E1 ARE DETERMINED AT THE LARGEST FEATURE OF THE BODY EXCLUSIVE OF MOLD FLASH AND GATE BURRS, BUT INCLUDING ANY MISMATCH BETWEEN THE UPPER AND LOWER SECTIONS OF THE MOLDER BODY.
- DIMENSION b DOES NOT INCLUDE DAMBER PROTRUSION. THE DAMBER PROTRUSION (S) SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED b MAXIMUM BY MORE THAN 0.08mm. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE LEAD FOOT.
- THESE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.10mm AND 0.25mm FROM THE LEAD TIP.
- A1 IS DEFINED AS THE DISTANCE FROM THE SEATING PLANE TO THE LOWEST POINT OF THE PACKAGE BODY.

002-11499 \*\*

PACKAGE OUTLINE, 64 LEAD LQFP  
10.0X10.0X1.7 MM LQD064 Rev\*\*



## 18. Major Changes

Spanion Publication Number: MB96670\_DS704-00001

Page	Section	Change Results
Revision 2.0		
4	FEATURES	<p>Changed the description of “LCD Controller” On-chip drivers for internal divider resistors or external divider resistors → Internal divider resistors or external divider resistors</p> <p>Changed the description of “External Interrupts” Interrupt mask and pending bit per channel → Interrupt mask bit per channel</p>
9	PIN DESCRIPTION	Deleted Pin name WOT
27 to 30	HANDLING PRECAUTIONS	Added a section
33	HANDLING DEVICES	<p>Changed the description in “11. SMC power supply pins” To avoid this, VCC must always be powered on before DVCC. → To avoid this, VCC must always be powered on before DVCC. DVcc/DVss must be applied when using SMC I/O pin as GPIO.</p>
35	ELECTRICAL CHARACTERISTICS 1. Absolute Maximum Ratings	<p>Changed the annotation *2 It is required that AVCC does not exceed VCC and that the voltage at the analog inputs does not exceed AVCC when the power is switched on. → It is required that AVCC does not exceed VCC, DVCC and that the voltage at the analog inputs does not exceed AVCC when the power is switched on.</p>
39	3. DC Characteristics (1) Current Rating	<p>Changed the Conditions for ICCSRCH CLKS1/2 = CLKB = CLKP1/2 = CLKRC = 2MHz, → CLKS1/2 = CLKP1/2 = CLKRC = 2MHz,</p> <p>Changed the Conditions for ICCSRCL CLKS1/2 = CLKB = CLKP1/2 = CLKRC = 100kHz → CLKS1/2 = CLKP1/2 = CLKRC = 100kHz</p> <p>Changed the Conditions for ICCTPLL PLL Timer mode with CLKP1 = 32MHz → PLL Timer mode with CLKPLL = 32MHz</p> <p>Changed the Value of “Power supply current in Timer modes” ICCTPLL Typ: 2480µA → 1800µA (TA = +25°C) Max: 2710µA → 2245µA (TA = +25°C) Max: 3955µA → 3140µA (TA = +105°C)</p> <p>Changed the Conditions for ICCTRCL RC Timer mode with CLKRC = 100kHz, SMCR:LPMSS = 0 (CLKPLL, CLKMC and CLKSC stopped) → RC Timer mode with CLKRC = 100kHz (CLKPLL, CLKMC and CLKSC stopped)</p>

Page	Section	Change Results
40	ELECTRICAL CHARACTERISTICS 3. DC Characteristics (1) Current Rating	Changed the annotation *2 Power supply for "On Chip Debugger" part is not included. Power supply current in Run mode does not include Flash Write / Erase current. → The current for "On Chip Debugger" part is not included.
		Added the description to annotation *2, *3 When Flash is not in Power-down / reset mode, I <sub>CCFLASHPD</sub> must be added to the Power supply current.
52	4. AC Characteristics (10) I <sup>2</sup> C timing	Added parameter, "Noise filter" and an annotation *5 for it
		Added t <sub>SP</sub> to the figure
54	5. A/D Converter (2) Accuracy and Setting of the A/D Converter Sampling Time	Deleted the unit "[Min]" from approximation formula of Sampling time
57	6. High Current Output Slew Rate	Changed the condition (V <sub>CC</sub> = AV <sub>CC</sub> = DV <sub>CC</sub> = 2.7V to 5.5V, VD=1.8V±0.15V, V <sub>SS</sub> = AV <sub>SS</sub> = DV <sub>SS</sub> = 0V, T <sub>A</sub> = - 40°C to + 105°C) → (V <sub>CC</sub> = AV <sub>CC</sub> = DV <sub>CC</sub> = 2.7V to 5.5V, V <sub>SS</sub> = AV <sub>SS</sub> = DV <sub>SS</sub> = 0V, T <sub>A</sub> = - 40°C to + 105°C)
60	8. Flash Memory Write/Erase Characteristics	Changed the condition (V <sub>CC</sub> = AV <sub>CC</sub> = DV <sub>CC</sub> = 2.7V to 5.5V, VD=1.8V±0.15V, V <sub>SS</sub> = AV <sub>SS</sub> = DV <sub>SS</sub> = 0V, T <sub>A</sub> = - 40°C to + 105°C) → (V <sub>CC</sub> = AV <sub>CC</sub> = DV <sub>CC</sub> = 2.7V to 5.5V, V <sub>SS</sub> = AV <sub>SS</sub> = DV <sub>SS</sub> = 0V, T <sub>A</sub> = - 40°C to + 105°C)
		Changed the Note While the Flash memory is written, shutdown of the external power (V <sub>CC</sub> ) is prohibited. In the application system where the external power (V <sub>CC</sub> ) might be shut down while writing, be sure to turn the power off by using an external voltage detector. → While the Flash memory is written or erased, shutdown of the external power (V <sub>CC</sub> ) is prohibited. In the application system where the external power (V <sub>CC</sub> ) might be shut down while writing or erasing, be sure to turn the power off by using a low voltage detection function.
Revision 2.1		
-	-	Company name and layout design change
Rev.*B		
-	Marketing Part Numbers changed from an MB prefix to a CY prefix.	
6, 8, 62, 63, 64	1. Product Lineup 3. Pin Assignment 16. Ordering Information 17. Package Dimension	Package description modified to JEDEC description. FPT-64P-M23 → LQG064 FPT-64P-M24 → LQD064

Page	Section	Change Results
62	16. Ordering Information	<p>Revised Marketing Part Numbers as follows:</p> <p>Before)</p> <p><b>MCU with CAN controller</b>            MB96F673RBPMC-GSE1            MB96F673RBPMC-GSE2            MB96F673RBPMC1-GSE1            MB96F673RBPMC1-GSE2            MB96F675RBPMC-GSE1            MB96F675RBPMC-GSE2            MB96F675RBPMC1-GSE1            MB96F675RBPMC1-GSE2</p> <p><b>MCU without CAN controller</b>            MB96F673ABPMC-GSE1            MB96F673ABPMC-GSE2            MB96F673ABPMC1-GSE1            MB96F673ABPMC1-GSE2            MB96F675ABPMC-GSE1            MB96F675ABPMC-GSE2            MB96F675ABPMC1-GSE1            MB96F675ABPMC1-GSE2</p> <p>After)</p> <p><b>MCU with CAN controller</b>            CY96F673RBPMC-GS-UJE1            CY96F673RBPMC-GS-UJE2            CY96F673RBPMC1-GS-UJE1            CY96F673RBPMC1-GS-UJE2</p> <p><b>MCU without CAN controller</b>            CY96F673ABPMC-GS-UJE2            CY96F673ABPMC1-GS-UJE1            CY96F673ABPMC1-GS-UJE2</p>

**NOTE:** Please see “Document History” about later revised information.

**Document History**

**Document Title: CY96670 Series F<sup>2</sup>MC-16FX 16-Bit Microcontroller**

**Document Number: 002-04703**

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	-	TORS	01/31/2014	Migrated to Cypress and assigned document number 002-04703. No change to document contents or format.
*A	5135634	TORS	02/18/2016	Updated to Cypress format.
*B	6002978	MIYH	12/22/2017	Revised the following items: Marketing Part Numbers changed from an MB prefix to a CY prefix. 1. Product Lineup 3. Pin Assignment 16. Ordering Information 17. Package Dimension For details, please see 18. Major Changes.

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