

義隆電子股份有限公司 ELAN MICROELECTRONICS CORP.

EM78P803B

8-bit MCU

2006/2/27

Version 1.3.5

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Version History

Version	Content	Release Date
1.0	1. Initial version	2004/03/29
	2. Original Spec. is oriented from EM78805C v2.0 spec	
1.1	1. Modified the LCD driving waveform of 1/3 bias	2004/05/26
	2. Add internal clock source for R to F Counter	
	3. Add option code for supporting 16-bit counter mode	
1.2	1. Modified ERIC mode function	2004/6/30
	2. Modified pad assignment	
1.3	1. Modified the configuration of PLL	2004/11/30
	2. Modified the selection of CNT2 source	
	3. Fix up the bug in R to F macro	
	4. Modified the setup of Low Battery Detect	
1.3.1	1. Modified the operating voltage range	2004/12/3
1.3.3	1. Modified the table of sub frequency divider.	2005/8/12
	2. Modified the definition of R2FHR option code.	
	3. Modified the power consumption and reset level on POVD function (in	
	product spec., not in target spec.)	
	4. Modified the definition of P803ON option code	
	5. Modified the product no. of 64-pin QFP	
	6. Modified the pad assignment	
1.3.4	1. Modified the table of pin description about P65~P67	2005/10/13
1.3.5	1. Add notice in the option code description about R to F function	2006/2/27
	2. Add more descriptions about R2FHR and 16CNT in User Application	
	Note.	



User Application Note

(Before using this chip, take a look at the following description note, it includes important messages.)

1. There are some undefined or not existent bits in the registers. For these bits, user need to take more care on them while program use them as data to execute logic or math operations. Because these bits are not relative to chip function, they never test in the factory. We use different symbols to recognize them.

"0" or "1" \rightarrow value always equal to 0 or value always equal to 1, (not existent, read only)

"-" \rightarrow value unknown, (not existent) undefined bits do not allow to use.

"x" \rightarrow (general purpose) undefined bits do not allow to use as RAM or other data read, write or read/write.

2. You will see some names for the register bits definitions. Some name will appear very frequently in the whole spec. The following describes the meaning for the register's definitions such as bit type, bit name, bit number and so on.

		KA											
		PAGE0											
		7	6	5		4	3		2	1		0]
		RAB7	RAB6	BA	B5	RAB4	-		RAB2	RAE	31	RAB0	
	┌►	R/W-0	R/W-0	R	-1	R/W-1			R	R-(0	R/W	
	Bit type read/write (default value=		=0))) (default value=1)			read only (w/o default value)		alue)	read/write (w/o default value		t value)	
	Bit name								*	, i			
Bit number				(undefined)				ined) not allowed to use					
			read	read only			read only						
Regis	ter na	me and its p	page	(defa	ult val	lue=1)				(defau	ilt val	ue=0)	

3. Family Relation

Mask	ROMless	OTP			
EM78801	EM78R803	EM78P803B			

4. Main Function Difference

	EM78P803B	EM78R803	EM78801
Туре	OTP	ROMless	Mask
ROM size	8k x 13b	16k x 13b	8k x 13b
Max. I/O	28	28	24
	3.5826MHz x	3.5826MHz x	3.5826MHz x
Main Clock	1/2, 1, 2, 4	1/2, 1, 2, 4	1/2, 1, 2, 4
	& ERIC mode	& ERIC mode	& ERIC mode
LCD	28 x 8/4	28 x 8/4	24 x 8/4
(Max. Seg.x Com.)	1/3, 1/4 Bias	1/3, 1/4 Bias	1/3, 1/4 Bias
Tone Generator	No	Yes	No
DED	No	Yes	No
R to F Counter	Yes	Yes	Yes
16 bit counter	Yes	Yes	Vac
10-bit counter	(Code Option)	(Pad Option)	1 85



5. Notice of ERIC Mode:

In ERIC mode, the RC oscillation circuit on the chip with an external resister provides the system clock. There is no 32.768kHz clock because no crystal connects to the system. The sub frequency which plays the role as the same as 32.768kHz is divided from system clock. User can setup the scale factor by CODE option when downloading the program. Furthermore, to careful to use the sub frequency clock when system working in ERIC mode. Some frequency didn't suggest might cause unpredictable condition. Please refer Sec.VII.15 for more detail

- 6. Common registers 0x20 ~ 0x3F only have three banks (banks 0,1,2). Notice that there is no bank 3 in these common registers. The bank 3 doesn't exist.
- 7. Care must be taken while programming. When R4 (bit7,bit6) = (1,1), common registers $0x10 \sim 0x1F$ cannot be read or written otherwise program maybe go to dead lock. ICE cannot reflect this problem. This is incompatible situation between mask and ICE.

8.	Notice of discrep	oancy of o	ption code on	ICE803,	EM78P803B	and EM78801
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0	Option Name	ICE803	EM78P803B	EM78801	
16CNT	Two 8bits-counters mode	J7 connects GND	16CNT = 1	COP16CNT = 0	
COP16CNT	One 16bits-counter mode	J7 connects VDD	16CNT = 0	COP16CNT = 1	
R2FHR	Slow mode	J5 connects GND	R2FHR = 1	COPR2FHR = 0	
COPHIRES	Fast mode	J5 connects VDD	R2FHR = 0	COPR2FHR = 1	



I. Main Feature

- Single power supply Operating voltage range: 2.8V ~ 5.5V(7.1652MHz) 4.5V ~ 5.5V(14.331MHz)
 - 2.2V ~ 5.5V(3.5826MHz/ERIC mode)
 - 2.2V ~ 5.5V(Sleep/Idle/Green mode)
- CPU 8-bit RISC kernel

99.9% single instruction cycle commands

Clock

32.768KHz clock source Built-in PLL to generate main clock 3.5826MHz x 0.5, 1, 2 and 4 Optional ERIC mode only with an external R

Timer and counter

Watch Dog: Programmable free running on chip watchdog timer TCC: 8-bit real time clock/counter (TCC) with 8-bit prescaler COUNTER1: 8-bit counter with 8-bit prescaler can be an interrupt source COUNTER2: 8-bit counter can be an interrupt source Two 8-bit counters can combine into one 16-bit counter when in R2F and 16-bit counter mode. Both of counters have reload function.

Memory

8k x 13bits on chip Electrical One Time Programmable Read Only Memory (OTP-ROM) 0.5k x 8bits on-chip general RAM

- 112 x 8bits common registers
- I/O

Up to 28 bi-directional tri-state I/O ports (15 independent I/O) IO with internal Pull high, wake-up and interrupt functions

Operation mode

Four modes can be selected. (Main clock is generated by internal PLL.)

Mode	CPU status	Main clock	32.768 kHz clock status			
Sleep mode	Turn off	Turn off	Turn off			
Idle mode	Turn off	Turn off	Turn on			
Green mode	Turn on	Turn off	Turn on			
Normal mode	Turn on	Turn on	Turn on			

■ Interrupt

Selective signal sources and overflow interrupt STACK: 8 levels stack for subroutine nesting 8 interrupt source, 5 external, 3 internal

Reset

Power on reset, /POVD reset (by PAD option) or external /RESET pin

R to F Counter

1 channel 16-bit counter with 2-channel sensors connected.

■ LCD

LCD operation voltage chosen by software Common driver pins: 8/4 Segment driver pins: 28 1/3 bias or 1/4 bias with output buffer 1/4 duty or 1/8 duty

PACKAGE

64-pad die (EM78P803BH) 100-pin QFP (EM78P803BQ)



64-pin QFP:

Name	/POVD	ERICen
EM78P803BAAQ	Disable (H)	Disable (L)
EM78P803BABQ	Disable (H)	Enable (H)
EM78P803BBAQ	Enable (L)	Disable (L)
EM78P803BBBQ	Enable (L)	Enable (H)

II. General Description

This is an 8-bit RISC type microprocessor with low power, high speed CMOS technology. Integrated onto a single chip are on-chip watchdog (WDT), RAM, OTP-ROM, programmable real time clock /counter, internal interrupt, power down mode, LCD driver, R to F 16-bit counter and tri-state I/O. It provides a single chip solution for versatile and general-purpose application use.

III. Application

General-purpose application such as body thermometer, hygrometer, scalars and home appliance.



IV. Pin Configuration



Fig.1 Pad assignment





Fig.1 Pad assignment (Continued)









V. Functional Block Diagram











VI. Pin Descriptions

Pin	I/O	Description	Num
Power			
VDD	POWER	Chip power VDD	1
VSS	GROUND	Chip ground GND	1
Clock for MCU	•		.1
XIN	Ι	Input pin for 32.768kHz crystal	1
XOUT	0	Output pin for 32.768kHz crystal	1
PLLC	Ι	Phase locked loop capacitor, connect a capacitor 0.01u to 0.047u	1
		to the ground.	
ERIC	I	Connect to VDD with a resister serially when in ERIC mode. This	1
		pin is shared with PLLC	
LCD driver	1		
COM0COM7	0	Common driver pins of LCD drivers	8
SEG0SEG15	0	Segment driver pins of LCD drivers	20
SEG24SEG27			
SEG16SEG19	O (PORT8)	Segment driver pins of LCD drivers	4
		Shared with P80 ~ P83	<u> </u>
SEG20SEG23	O (PORT5)	Segment driver pins of LCD drivers	4
		Shared with P54 ~ P57	
R to F Counter	т		1
IN	1	External oscillation input	1
CE	0	IN IS Shared with Poo	1
CF	0	CE is shored with D61	1
DE	0	Cr is shaled with F01 Performed resistor connection	1
KI	U	RF is shared with P62	1
CRS	0	Resistor/capacitor sensor connection	1
CIUS	Ŭ	CRS is shared with P63	1
RS	0	Resistor sensor connection	1
	_	RS is shared with P64	_
Test			1
TEST	Ι	Test pin into test mode, normal low	1
Reset	•		
/RESET	Ι	Reset input. Low enable	1
I/O			
P54 ~P57	I/O PORT5	PORT5 can be INPUT or OUTPUT port each bit	4
		And P54 ~ P57 are shared with segment signal	
P60 ~P67	I/O PORT6	PORT6 can be INPUT or OUTPUT port each bit	8
		P60 ~ P64 are shared with IN, CF, RF, CRS and RS pin of R to F	
		counter.	
P70 ~P77	I/O PORT7	PORT7 can be INPUT or OUTPUT port each bit	8
		PORT7 have internal pull high function	
R 00 R 00		$P70/INT0 \sim P73/INT3$ can be interrupt signals	<u> </u>
P80 ~ P83	I/O PORT8	PORT 8 can be INPUT or OUTPUT port each bit	4
D04 D07		And You ~ Pos are shared with segment signal.	4
P94 ~ P97	1/0 POR 19	POKI 9 can be INPUT or OUTPUT port each bit	4
DAD Ontion		ryo, ry/ nave wake-up lunction.	<u> </u>
PAD Option	т	Dower on voltage detector reset	2
/PUVD EDICor	l T	FDIC mode angle	$\frac{2}{2}$
EKICEN	1		2



When /RESET pulls to 12V, the system will be in programming mode. Then writer can program the code ROM inside the system.

No.	System Pin Name	OTP writer Pin Name	Description
4	VDD	VDD	VDD power
55	/RESET	VPP	High voltage activation pin
61	P7[7]	DINCK	Internal ssyetm clock
60	P7[6]	ACLK	External system clock
63	P7[5]	PGMB	When PGMB=0, writing action of OTP ROM activates
62	P7[4]	OEB	When OE=0, reading action of OTP ROM activates.
59	P7[3]	DATA	Serial data I/O
21	VSS	GND	Ground power



VII. Functional Descriptions

VII.1 Operational Registers

Register configuration 1:

Adda	D DACE registers	IOC F	PAGE
Addr	R PAGE legisters	IOC PAGE0	IOC PAGE1
00	INDA Indirect addressing		
01	TCCD TCC data		
02	PC Program counter		
03	STA IOC Page, Status		
04	RBSR Register bank, RSR		
05	P5IOD PORT5 I/O data, Program ROM page	P5IOC PORT5 I/O control,	
06	P6IOD PORT6 I/O data	P6IOC PORT6 I/O control	
07	P7IOD PORT7 I/O data	P7IOC PORT7 I/O control	
08	P8IOD PORT8 I/O date	P8IOC PORT8 I/O control	
09	P9IOD PORT9 I/O data	P9IOC PORT9 I/O control	
0A	MCUC CPU power saving, PLL, Main clock selection	PSW (P8 low nibble, P5) switch, LCD bias, Key scan control	LCDP LCD power saving
0B	RAMB General RAM bank	LCDA LCD RAM address	CN1D Counter 1 data
0C	RAMA General RAM address	LCDD LCD RAM data	CN2D Counter 2 data
0D	RAMD General RAM data		P7PHC PORT7 pull high
0E	WUPC Wake-up control, LCD control		CNPSC Open Drain Control, CNT1,2 CLK source, CNT1,2 prescaler, LCD mode
0F	INTF Interrupt flag	INTM Interrupt mask	R2FC R 2 F Counter Status Control ¹
10 : 1F	16 bytes Common registers		
20	Bank0~Bank2 ²		
: 3E	Common registers		
эг	(32x0 101 each Dank)		

Ps. 1. Register 20~3F has bank0~bank2 only. The bank3 doesn't exist and cannot access it.



Register Configuration 2:

Addr.	R	IOC	Register	Register bit name						Power on		
	page	page	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset val.
00	X	1 0	INDA	(Indirect ad	dress reg	gister)						
01	Х		TCCD	(TCC data	buffer)							
02	Х		PC	(Program c	ounter)							
03	Х		STA	IOCPAGE	0	0	Т	Р	Ζ	DC	С	000xxxxx
04	Х		RBSR	RB1	RB0	RSR5	RSR4	RSR3	RSR2	RSR1	RSR0	00xxxxxx
05	Х		P5IOD	P57	P56	P55	P54	PS3	PS2	PS1	PS0	xxxx0000
		0	P5IOC	IOC57	IOC56	IOC55	IOC54	0	0	0	0	11110000
		1	(non-existence)	0	0	0	0	0	0	0	0	00000000
06	Х		P6IOD	P67	P66	P65	P64	P63	P62	P61	P60	XXXXXXXX
		0	P6IOC	IOC67	IOC66	IOC65	IOC64	IOC63	IOC63	IOC61	IOC60	11111111
		1	(non-existence)	0	0	0	0	0	0	0	0	00000000
07	Х		P7IOD	P77	P76	P75	P74	P73	P72	P71	P70	XXXXXXXX
		0	P7IOC	IOC77	IOC76	IOC75	IOC74	IOC73	IOC73	IOC71	IOC70	11111111
		1	(non-existence)	0	0	0	0	0	0	0	0	00000000
08	х		P8IOD	0	0	0	0	P83	P82	P81	P80	0000xxxx
		0	P8IOC	0	0	0	0	IOC83	IOC83	IOC81	IOC80	00001111
		1	(non-existence)	0	0	0	0	0	0	0	0	00000000
09	Х		P9IOD	P97	P96	P95	P94	0	0	0	0	xxxx0000
		0	P9IOC	IOC97	IOC96	IOC95	IOC94	0	0	0	0	11110000
		1	(non-existence)	0	0	0	0	0	0	0	0	00000000
0A	Х		MCUC	IDLE	ENPLL	CLK2	CLK1	0	0	0	0	00000000
		0	PSW	BIASS	0	P8SL	P5S	BIAS3	BIAS2	BIAS1	SC	00000000
		1	LCDP	0	0	CR	0	0	0	0	0	000x0000
0B	Х		RAMB	0	0	0	0	0	0	0	CALL_1	0000x000
		0	LCDA	0	0	LCDA5	LCDA4	LCDA3	LCDA2	LCDA1	LCDA0	00000000
		1	CN1D	CN17	CN16	CN15	CN14	CN13	CN12	CN11	CN10	00000000
0C	х		RAMA	GENA7	GENA6	GENA5	GENA4	GENA3	GENA2	GENA1	GENA0	00000000
		0	LCDD	LCDD7	LCDD6	LCDD5	LCDD4	LCDD3	LCDD2	LCDD1	LCDD0	XXXXXXXX
		1	CN2D	CN27	CN26	CN25	CN24	CN23	CN22	CN21	CN20	00000000
0D	Х		RAMD	GEND7	GEND6	GEND5	GEND4	GEND3	GEND2	GEND1	GEND0	XXXXXXXX
		0	(non-existence)	0	0	0	0	0	0	0	0	00000000
		1	Р7РНС	PH7	PH6	PH5	PH4	PH3	PH2	PH1	PH0	00000000
0E	Х		WUPC	0	/WDTE	/WUP97	/WUP96	0	LCD_C2	LCD_C1	0	00000000
		0	(non-existence)	0	0	0	0	0	0	0	0	0000000
		1	CNPSC	OP77	OP76	C2S	C1S	PSC2	PSC1	PSC0	LCDM	0000000
0F	х		INTF	0	0	CNT2	CNT1	INT2/INT3	INT1	INT0	TCIF	00000000
		0	INTM	0	0	CNT2	CNT1	INT2/INT3	INT1	INT0	TCIF	0000000
		1	R2FC ¹	0	CM2	CM1	CM0	0	CNTST	0	R2FON	0000000

VII.2 Operational Register Detail Description

R0 (INDA: Indirect addressing register)

R0 is not a physically implemented register. It is useful as indirect addressing pointer. Any instruction using R0 as register actually accesses data pointed by the RAM Select Register (R4).

R1 (TCCD: TCC data buffer)

Increased by an external signal edge applied to TCC, or by the instruction cycle clock. Written and read by the program as any other register. TCC has no reload function.

R2 (PC: Program counter)

The structure is depicted in Fig.4

Generates $8k \times 13bit$ internal ROM addresses to the relative programming instruction codes.

"JMP" instruction allows the direct loading of the low 10 program counter bits.

"CALL" instruction loads the low 10 bits of the PC, PC+1, and then pushes into the stack.

"RET" ("RETL k", "RETI") instruction loads the program counter with the contents at the top of stack.

"MOV R2,A" allows the loading of an address from the A register to the PC, and the ninth and tenth bits are cleared to "0".



"ADD R2,A" allows a relative address be added to the current PC, and contents of the ninth and tenth bits are cleared to "0".

"TBL" allows a relative address be added to the current PC, and contents of the ninth and tenth bits don't change. The most significant bit (A10~A13) will be loaded with the content of bit PS0~PS3 in the status register (R5) upon the execution of a "JMP", "CALL", "ADD R2,A", or "MOV R2,A" instruction.



Fig.4 Program counter organization

The ROM size is 8k x 13bits. User don't need to use the A13 bit (PS3 in R5). Thus the PS3 and PS2 bit in R5 will not be writable and always return zero after reading.

R3 (STA: IOC Page, Status register)

7	6	5	4	3	2	1	0
PAGE	0	0	Т	Р	Z	DC	С
R/W-0	R-0	R-0	R-x	R-x	R/W-x	R/W-x	R/W-x

Bit 0 (C) : Carry flag

Bit 1 (DC) : Auxiliary carry flag

Bit 2 (Z) : Zero flag

Bit 3 (P) : Power down bit.

Set to 1 during power on or by a "WDTC" command and reset to 0 by a "SLEP" command. Bit 4 (T) : Time-out bit

Set to 1 by the "SLEP" and "WDTC" command, or during power up and reset to 0 by WDT timeout.

Event	Т	Р	Remark
WDT wake up from sleep mode	0	0	
WDT time out (not sleep mode)	0	1	
/RESET wake up from sleep	1	0	
Power up	1	1	
Low pulse on /RESET	Х	Х	x : don't care

Bit 5 ~ Bit 6 : unused

Always keep this bit to "0". Don't set it to "1" to prevent causing problem Bit 7 (PAGE) : change IOCB ~ IOCE to another Page

0/1 → PAGE0/PAGE1

R4 (RBSR: RAM bank, RAM selection for common registers R20 ~ R3F)

7	6	5	4	3	2	1	0
RB1	RB0	RSR5	RSR4	RSR3	RSR2	RSR1	RSR0
R/W-0	R/W-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x

Bit 0 ~ Bit 5 (RSR0 ~ RSR5) : Indirect addressing for common registers R20 ~ R3F



RSR bits are used to select up to 32 registers (R20 to R3F) in the indirect addressing mode.

Bit 6 ~ Bit 7 (RB0 ~ RB1) : Bank selection bits for common registers R20 ~ R3F

These selection bits are used to determine which bank is activated among the 3 banks for 32 registers (R20 to R3F). *The bank 3 doesn't exist and cannot access.*

(RB1,RB0)	Bank # for R20 ~ R3F
00	Bank 0
01	Bank 1
10	Bank 2
11	N/A

R5 (P5IOD: PORT5 I/O data, Program ROM page selection)

7	6	5	4	3	2	1	0
P57	P56	P55	P54	PS3	PS2	PS1	PS0
R/W	R/W	R/W	R/W	R-0	R/W-0	R/W-0	R/W-0

Bit 0 ~ 3 (PS0 ~ PS3) : Page selection bits

They should be set before JMP or CALL instruction. Page select bits

PS3	PS2	PS1	PS0	Program memory page (Address)
0	0	0	0	Page 0
0	0	0	1	Page 1
0	0	1	0	Page 2
0	0	1	1	Page 3
:	:	••	:	:
:	:	:	:	:
0	1	1	0	Page 6
0	1	1	1	Page 7

User can use PAGE instruction to change page and maintain program page by user. Otherwise, user can use far jump (FJMP) or far call (FCALL) instructions to program user's code. EMC's complier maintains the program page. It will change user's program by inserting instructions within program. *Bit 3 is always 0 and can't be set.*

Bit $5 \sim 7 (P54 \sim P57)$: 4-bit PORT5(4 ~ 7) I/O data register

R6 (P6IOD: PORT6 I/O data)

7	6	5	4	3	2	1	0
P67	P66	P65	P64	P63	P62	P61	P60
R/W							

Bit 0 ~ Bit 7 (P60 ~ P67) : 8-bit PORT6(0~7) I/O data register

User can use IOC register to define input or output each bit.

P60~P64 are shared with R to F Counter. When R to F Counter enables, P60~P64 must be set as input port and always return zero after reading. Only P65~P67 acts as normal.

R7 (P7IOD: PORT7 I/O data)

7	6	5	4	3	2	1	0
P77	P76	P75	P74	P73	P72	P71	P70
R/W							

Bit 0 ~ Bit 7 (P70 ~ P77) : 8-bit PORT7(0~7) I/O data register User can use IOC register to define input or output each bit.





R8 (P8IOD: PORT8 I/O data)

7	6	5	4	3	2	1	0
0	0	0	0	P83	P82	P81	P80
R-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0

Bit 0 ~ Bit 3 (P80 ~ P83) : 4-bit PORT8(0~3) I/O data register

Bit 4 ~ Bit 7 : unused

User can use IOC register to define input or output each bit.

R9 (P9IOD: PORT9 I/O data)

7	6	5	4	3	2	1	0
P97	P96	P95	P94	0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R-0	R-0	R-0	R-0

Bit 0 ~ Bit 3 : unused

Bit 4 ~ Bit 7 (P94 ~ P97) : 4-bit PORT9(4~7) I/O data register User can use IOC register to define input or output each bit.

RA (MCUC: CPU power saving, PLL, Main clock selection)

7	6	5	4	3	2	1	0
IDLE	ENPLL	CLK2	CLK1	0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R-0	R-0	R-0	R-0

Bit 0 ~ Bit 3 : unused

Bit 4 ~ 5 (CLK1 ~ CLK2) : Main clock selection bits.

User can choose the main clock by setting CLK1 and CLK2. All the clock selections are list below. When changing the main clock, insert some NOP instruction for system stability.

ENPLL	CPU's clock	(CLK2,CLK1)	MAIN clock
0	32.768kHZ	(x,x)	Х
1	1.7913MHz	(0,0)	1.7913MHz
1	14.331MHz	(0,1)	14.331MHz
1	7.1652MHz	(1,0)	7.1652MHz
1	3.5826MHz	(1,1)	3.5826MHz

When in ERIC mode, CLK1~2 will be masked. The main clock is generated by the frequency of ERIC oscillation.

Bit 6 (ENPLL) : (read/write) PLL enable/disable control

 $1/0 \rightarrow$ enable/disable

The relation between 32.768kHz and main clock can see Fig.5

When in ERIC mode, ENPLL will enforce to 0. The main clock is generated by the frequency of ERIC oscillation. The sub clock is divided from the main clock and can be scale by different factor.

Bit 7 (IDLE) : Idle mode/sleep mode selection bit

 $1/0 \rightarrow$ Idle mode/sleep mode.

This bit will decide SLEP instruction which mode to go.

These two modes can be waked up by TCC clock, Watch Dog timer (WDT), PORT96~97, Energy Detector output, PORT70~73 and run from "SLEP" next instruction.

 $P70 \sim P73$'s wakeup function is controlled by IOCF P0(1,2,3) and ENI instruction.

P70 's wakeup signal is a rising edge or falling edge defined by CONT REGISTER bit7.

Port96, Port97, Port71, Port72 and Port73 's wake-up pattern is a falling edge-triggering signal.



	1				
	SLEEP mode	IDLE mode	GREEN mode	NORMAL mode	
Wakeup signal	RA(7,6)=(0,0)	RA(7,6)=(1,0)	RA(7,6)=(x,0)	RA(7,6)=(x,1)	
	+SLEP	+ SLEP	no SLEP	no SLEP	
		Wake-up			
TCC time out	Х	+ Interrupt	Interrupt	Interrupt	
		+ Next instruction	_		
WDT time out	DECET	Wake-up	DECET	RESET	
wD1 time out	KESEI	+ Next instruction	KESE I		
Dout06.07	DECET	Wake-up			
P01190, 97	KESEI	+ Next instruction	Х	Х	
		Wake-up			
PORT70~73	RESET	+ Interrupt	Interrupt	Interrupt	
		+ Next instruction			



Fig.5 The relation between 32.768kHz and Main clock

RB (RAMB: General RAM banks)

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	CALL_1
R/W-0	R/W-0	R-0	R-0	R-x	R-0	R-0	R/W-0

Bit 0 (CALL_1) : 2 blocks of general RAM area

User can use 0.5K general RAM with RC RAM address.

Bit 1 ~ Bit 7 : unused

Always keep this bit to "0". Don't set it to "1" to prevent causing problem

RC (RAMA: General RAM address)

7	6	5	4	3	2	1	0
GENA7	GENA6	GENA5	GENA4	GENA3	GENA2	GENA1	GENA0
R/W-0							

Bit 0 ~ Bit 7 (GENA0 ~ GENA7) : General RAM address User can select general RAM address from 0 to 255.

RD (RAMD: General RAM data buffer)

7	6	5	4	3	2	1	0
GEND7	GEND6	GEND5	GEND4	GEND3	GEND2	GEND1	GEND0
R/W							

Bit 0 ~ Bit 7 (GEND0 ~ GEND7) : General RAM data register.



RE (WUPC: Wake-up control, LCD control)

7	6	5	4	3	2	1	0
0	/WDTE	/WUP97	/WUP96	0	LCD_C2	LCD_C1	0
R-0	R/W-0	R/W-0	R/W-0	R-0	R/W-0	R/W-0	R/W-0

Bit 0 : unused

Always keep this bit to "0". Don't set it to "1" to prevent causing problem Bit 1 ~ Bit 2 (LCD_C1 ~ LCD_C2) : LCD display enable or blanking. The display duty change must set the (LCD_C2,LCD_C1) to (0,0).

(LCD_C2,LCD_C1)	LCD Display Control	Duty	Bias				
(0,0)	Disable (turn off LCD) (*1) (*1)		1/4 1/4				
(0,1)	Blanking	:					
(1,1) LCD display enable :							
1. 1/8 or 1/4 duty depends on IOCE PAGE1 bit0 (LCDM)							

Bit 3 : unused

Bit 4 (/WUP96) : PORT9 bit6 wake-up control, $1/0 \rightarrow$ enable/disable Bit 5 (/WUP97) : PORT9 bit7 wake-up control, $1/0 \rightarrow$ enable/disable Bit 6 (/WDTE) : Watchdog timer enable control, $1/0 \rightarrow$ enable/disable



Fig.6 Wake up function and control signal

Bit 7 : unused

RF (INTF: Interrupt status register)

7	6	5	4	3	2	1	0
0	0	CNT2	CNT1	INT2/INT3	INT1	INT0	TCIF
R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

Bit 0 (TCIF) : TCC timer overflow interrupt flag

It will be set when TCC timer is overflow.

Bit 1 (INT0) : External INT0 pin interrupt flag

It can be used when PORT70 is set to input port.

Bit 2 (INT1) : External INT1 pin interrupt flag

It can be used when PORT71 is set to input port.

Bit 3 (INT2/INT3) : external INT2 and INT3 pin interrupt flag

It can be used when PORT72 or PORT73 is set to input port.

Bit 4 (CNT1) : 8 bit Counter1 overflow interrupt flag.

It will be set when Counter1 is overflow.

Bit 5 (CNT2) : 8 bit Counter2 overflow interrupt flag.

It will be set when Counter2 is overflow.

Bit 6 ~ Bit 7 : unused

Always keep this bit to "0". Don't set it to "1" to prevent causing problem



"1" means interrupt request and "0" means non-interrupt. INT0~INT3 interrupts are edge triggering (falling edge or rising edge) which can be set by CONT bit 7 (INT_EDGE). Also see corresponding interrupt mask in IOCF register. User can read and clear.

R10~R3F (General Purpose Register)

R10~R1F: common registers

Care must be taken while programming. When R4 (bit7,bit6) = (1,1), common registers $0x10 \sim 0x1F$ cannot be read or written otherwise program maybe go to dead lock. ICE cannot reflect this problem. This is incompatible situation between mask and ICE.

R20~R3F (Banks 0~2) : common registers

These common are bank-controlled registers with bank 0,1,2. The bank 3 doesn't exist and cannot access.

VII.3 Special Purpose Registers

A (Accumulator)

Internal data transfer, or instruction operand holding It's not an addressable register.

CONT (Control Register)

7	6	5	4	3	2	1	0
INT_EDGE	INT	TS	0	PAB	PSR2	PSR1	PSR0
R/W-1	R/W-0	R/W-1	R-0	R/W-1	R/W-1	R/W-1	R/W-1

Bit 0 ~ Bit 2 (PSR0 ~ PSR2) : TCC/WDT prescaler bits

PSR2	PSR1	PSR0	TCC rate	WDT rate
0	0	0	1:2	1:1
0	0	1	1:4	1:2
0	1	0	1:8	1:4
0	1	1	1:16	1:8
1	0	0	1:32	1:16
1	0	1	1:64	1:32
1	1	0	1:128	1:64
1	1	1	1:256	1:128

Bit 3(PAB) : Prescaler assignment bit

0/1 → TCC/WDT

Bit 4 : unused

Bit 5(TS) : TCC signal source

 $0 \rightarrow$ Instruction clock

1 **→** 16.384kHz

Instruction clock = MCU clock/2, Refer to RA Bit $4 \sim$ Bit 6 for PLL and Main clock selection. See Fig.5. In ERIC mode, the instruction clock is the half of frequency of ERIC oscillation. When TS bit sets 1, the clock is the half of sub frequency divided from the frequency of ERIC oscillation.

Bit 6 (INT) : INT enable flag

 $0 \rightarrow$ Interrupt masked by DISI or hardware interrupt

 $1 \rightarrow$ Interrupt enabled by ENI/RETI instructions

Bit 7(INT_EDGE) : interrupt edge type of P70

 $0 \rightarrow P70$'s interruption source is a rising edge signal and falling edge signal.

 $1 \rightarrow P70$'s interruption source is a falling edge signal.

CONT register is readable (CONTR) and writable (CONTW).



IOC5 (P5IOC: PORT5 I/O control)

7	6	5	4	3	2	1	0
IOC57	IOC56	IOC55	IOC54	0	0	0	0
R/W-1	R/W-1	R/W-1	R/W-1	R-0	R-0	R-0	R-0

Bit 0 ~ Bit 3 : unused

Bit 4 ~ 7 (IOC54 ~ IOC57) : PORT5(4~7) I/O direction control register

 $0 \rightarrow$ put the relative I/O pin as output

 $1 \rightarrow$ put the relative I/O pin into high impedance

IOC6 (P6IOC: PORT6 I/O control)

7	6	5	4	3	2	1	0
IOC67	IOC66	IOC65	IOC64	IOC63	IOC62	IOC61	IOC60
R/W-1							

Bit 0 ~ Bit 7 (IOC60 ~ IOC67) : PORT6(0~7) I/O direction control register

 $0 \rightarrow$ put the relative I/O pin as output

 $1 \rightarrow$ put the relative I/O pin into high impedance

P60~P64 are shared with R to F Counter. When R to F Counter enables, P60~P64 must be set as input port and always return zero after reading. Only P65~P67 acts as normal.

IOC7 (P7IOC: PORT7 I/O control)

7	6	5	4	3	2	1	0
IOC77	IOC76	IOC75	IOC74	IOC73	IOC72	IOC71	IOC70
R/W-1							

Bit 0 ~ Bit 7 (IOC70 ~ IOC77) : PORT7(0~7) I/O direction control register

 $0 \rightarrow$ put the relative I/O pin as output

 $1 \rightarrow$ put the relative I/O pin into high impedance

IOC8 (P8IOC: PORT8 I/O control)

7	6	5	4	3	2	1	0
0	0	0	0	IOC83	IOC82	IOC81	IOC80
R-0	R-0	R-0	R-0	R/W-1	R/W-1	R/W-1	R/W-1

Bit 0 ~ Bit 3 (IOC80 ~ IOC83) : PORT8(0~3) I/O direction control register

 $0 \rightarrow$ put the relative I/O pin as output

 $1 \rightarrow$ put the relative I/O pin into high impedance

Bit 4 ~ Bit 7 : unused

IOC9 (P9IOC: PORT9 I/O control)

7	6	5	4	3	2	1	0
IOC97	IOC96	IOC95	IOC94	0	0	0	0
R/W-1	R/W-1	R/W-0	R/W-0	R-0	R-0	R-0	R-0

Bit 0 ~ Bit 3 : unused

Bit 4 ~ Bit 7 (IOC94 ~ IOC97) : PORT9(4~7) I/O direction control register

 $0 \rightarrow$ put the relative I/O pin as output

 $1 \rightarrow$ put the relative I/O pin into high impedance



IOCA (PSW, LCDP)

PAGE0 (PSW: PORT8,5 switch, LCD bias, key scan)

7	6	5	4	3	2	1	0
BIASS	0	P8SL	P5S	BIAS3	BIAS2	BIAS1	SC
R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

Bit 0 (SC) : key scan function control

 $0/1 \rightarrow disable/enable$

Once you enable this bit, all of the LCD signal will have a low pulse during a common period. This pulse has 30us width. Please use the following procedure to implement the key scan function :

- 1. Set PORT7 as input port
- 2. Set IOCD PAGE1 to enable PORT7 pull high function
- 3. Enable key scan function
- 4. Once push a key. Set RA bit 6 to enable PLL (CPU will run in the normal mode)
- 5. LCD and disable key scan function
- 6. Set P5S =0 or/and P8SL=0. PORT5 or/and PORT8 sent probe signal to PORT7 and read PORT7. Get the key.
- 7. Note!! A probe signal should be delay an instruction at least to another probe signal.
- 8. Set P5S =1 or/and P8SL=1. PORT5 or/and PORT8 as LCD signal



Fig.7. Key scan circuit

Bit 1 ~ 3 (BIAS1 ~ BIAS3) : LCD bias control used to choose LCD operation voltage.

(BIAS3,BIAS2,BIAS1)	Vop (VDD 5V)	VDD=5V
(0,0,0)	0.60VDD	3V
(0,0,1)	0.66VDD	3.3V
(0,1,0)	0.74VDD	3.7V
(0,1,1)	0.82VDD	4.1V
(1,0,0)	0.87VDD	4.35V
(1,0,1)	0.93VDD	4.65V
(1,1,0)	0.96VDD	4.8V
(1,1,1)	1.00VDD	5V

Bit 4 (P5S) : PORT5 nibble switch 0/1 → normal I/O port/SEGMENT output Bit 5 (P8SL) : port8 low nibble switch



0/1 → normal I/O port P80~P83/SEGMENT output SEG16~SEG19
Bit 6 : unused
Bit 7 (BIASS) : Bias Select,
0/1 → 1/4 bias / 1/3 bias

PAGE1 (LCDP: LCD power saving)

7	6	5	4	3	2	1	0
0	0	CR	0	0	0	0	0
R-0	R-0	R/W-0	R-x	R/W-0	R/W-0	R/W-0	R/W-0

Bit 0 ~ Bit 4 : unused

Always keep this bit to "0". Don't set it to "1" to prevent causing problem

Bit 5 (CR) : LCD DC current saving

 $0/1 \rightarrow$ normal DC current drive/half DC current drive

When this bit is set to 1, the LCD driving ability will be reducing to the half than normal current drive but it can save power.

Bit $6 \sim \text{Bit } \overline{7}$: unused

IOCB (LCDA, CN1D)

PAGE0 (LCDA: LCD RAM address)

7	6	5	4	3	2	1	0
0	0	0	LCDA4	LCDA3	LCDA2	LCDA1	LCDA0
R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

Bit 0 ~ Bit 4 (LCDA0 ~ LCDA4) : LCD RAM address

The LCD display data is stored in the data RAM. The relation of data area and COM/SEG pin is as below:

COM7 ~ COM0	Segment
00H (Bit7 ~ Bit0)	SEG0
01H	SEG1
:	:
1AH	SEG26
1BH	SEG27
1CH	(empty)
:	:
1FH	(empty)

Bit $5 \sim Bit 7 = 0$: unused

PAGE1 (CN1D: Counter 1 preset)

7	6	5	4	3	2	1	0
CN17	CN16	CN15	CN14	CN13	CN12	CN11	CN10
R/W-0							

8-bit up-counter (COUNTER1) preset and read out register. (write = preset). COUNTER1 has reload function.

IOCC (LCDD, CN2D)

PAGE0 (LCDD: LCD RAM data buffer)

7	6	5	4	3	2	1	0
LCDD7	LCDD6	LCDD5	LCDD4	LCDD3	LCDD2	LCDD1	LCDD0
R/W							

Bit 0 ~ Bit 7 : LCD RAM data



For 8-COM mode, bit0 ~ bit7 are used. For 4-COM mode, only bit0 ~ bit3 are used.

PAGE1	(CN2D:	Counter 2	preset)
	1		

7	6	5	4	3	2	1	0
CN27	CN26	CN25	CN24	CN23	CN22	CN21	CN20
R/W-0							

8-bit up-counter (COUNTER2) preset and read out register. (write = preset) COUNTER2 has reload function.

IOCD (P7PHC)

PAGE0

Non-existence. Always keep this bit to "0". Don't set it to "1" to prevent causing problem

PAGE1 (P7PHC: PORT7 pull high control)

7	6	5	4	3	2	1	0
PH7	PH6	PH5	PH4	PH3	PH2	PH1	PH0
R/W-0							

Bit $0 \sim 7$ (PH0 ~ PH7) : PORT7(0~7) pull high control bits

 $0/1 \rightarrow$ Disable internal pull-high/enable internal pull-high

These control bits are used to enable the pull-high of PORT7(0 ~ 7) pins.

IOCE (CNPSC)

PAGE0

Non-existence. Always keep this bit to "0". Don't set it to "1" to prevent causing problem

PAGE1 (CNPSC: Open-drain control, Counter 1,2 clock source and prescaler, LCD mode)

7	6	5	4	3	2	1	0
OP77	OP76	C2S	C1S	PSC2	PSC1	PSC0	LCDM
R/W-0							

Bit 0 (LCDM) : LCD mode control for 8-COM, 1/8 duty or 4-COM, 1/4 duty selection

 $0 \rightarrow 8$ -COM mode selection and COM0 ~ COM7 are enabled

1 \rightarrow 4-COM mode selection and COM0 ~ COM3 are enabled

Bit 1 ~ 3 (PSC0~PSC2) : Counter1 prescaler setting

reset = (0,0,0)

(PSC2,PSC1,PSC0)	Scaler ratio
(0,0,0)	1:1
(0,0,1)	1:2
(0,1,0)	1:4
(0,1,1)	1:8
(1,0,0)	1:16
(1,0,1)	1:32
(1,1,0)	1:64
(1,1,1)	1:128

Bit 4 (C1S) : Counter1 source

 $0/1 \rightarrow 32.768$ kHz/MAIN clock if enable

In ERIC mode, the clock source will be replaced by sub frequency (0) and the frequency of ERIC oscillation (1).



Bit 5 (C2S) : Counter2 source

In the normal mode:

 $0/1 \rightarrow 32.768$ kHz/Main clock if enable, scale=1:1

In ERIC mode, the clock source will be replaced by sub frequency (0) and the frequency of ERIC oscillation (1).

In the 16-bit counter mode:

MSB of CNT1 replaces of the Main clock. Thus, the clock source changes as followed.

 $0/1 \rightarrow 32.768$ kHz/MSB of CNT1 if enable, scale=1:1

Meantime, CNT1 has no function. Please reference the section VII.13

Same as the C1S bit, in the ERIC mode, the main clock will be replaced by ERIC oscillation and the 32.768kHz will be replaced by sub frequency whatever in 16-bit counter mode or not.

Bit 6 (OP76) : P76 open-drain control

 $0/1 \rightarrow disable/enable$

Bit 7 (OP77) : P77 open-drain control

 $0/1 \rightarrow disable/enable$

IOCF (INTM, R2FC)

PAGE0 (INTM: Interrupt Mask Register)

7	6	5	4	3	2	1	0
0	0	CNT2	CNT1	INT2/INT3	INT1	INT0	TCIF
R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

Bit 0 ~ Bit 5 : interrupt enable bit

 $1/0 \rightarrow$ enable/disable interrupt

IOCF Register is readable and writable. They work with RF registers.

Bit $6 \sim Bit 7$: unused

Always keep this bit to "0". Don't set it to "1" to prevent causing problem

PAGE1 (R2FC: R to F Counter Status Control)

7	6	5	4	3	2	1	0
0	CM2	CM1	CM0	0	CNTST	0	R2FON
R-0	R/W-0	R/W-0	R/W-0	R-0	R/W-0	R-0	R/W-0

Bit 0 (R2FON) : R to F Counter Switch

 $1/0 \rightarrow$ enable/disable

When R2FON bit is enable, the two 8-bit counters will combine into one 16-bit counter. The clock source of 16-bit counter is configured by the CM0 \sim 2. The initial value of the counter can be set by write data into Counter Register.

Bit 1 : unused

Bit 2 (CNTST) : Counter Start Flag

 $1/0 \rightarrow$ enable/disable

If the flag was set, the 16-bit counter will start to go. The counter will stop and CNTST will reset when TCC overflow.

Bit 3 : unused

Bit $4 \sim 6$ (CM0 ~ 2) : Counter Mode setting.

Every mode implies different RC oscillating situation. There are only two components (one resister and one capacitor) connected in each mode. The following table lists the connection of external RC components. User should be noticed that in the mode $CM2 \sim 0$: 000, it means that user can connect the external clock into IN pad instead of RC oscillation in order to count the external source.



C	ounter Mo	de	Co	onnection of	External R	C Componer	nts
CM2	CM1	CM0	S 1	S2	S 3	S4	S5
0	0	0]	External Clo	ock Input thr	ough IN Pir	1
0	0	1	1	1	0	0	0
0	1	0	1	0	0	1	0
0	1	1	0	1	1	0	0
1	0	0	1	0	0	0	1
1	0	1	0	0	1	0	1
1	1	0	(Clock source	of counter	is 32.768kH	Z
1	1	1	Clock source of counter is half of main clock of MC				of MCU

In ERIC mode, the clock source of counter will be the sub frequency when choosing the mode "110" and the half of main frequency of ERIC oscillation when choosing the mode "111". Bit 7 : unused



Fig.8 Block Diagram of R to F Counter

Please refer Sec.VII.11 "R to F Counter" for more detail.

VII.4 TCC/WDT Prescaler

There is an 8-bit counter available as prescaler for the TCC or WDT. The prescaler is available for the TCC only or WDT only at the same time.

- An 8-bit counter is available for TCC or WDT determined by the status of the bit 3 (PAB) of the CONT register.
- See the prescaler ratio in CONT register.
- Fig.9 depicts the circuit diagram of TCC/WDT.
- Both TCC and prescaler will be cleared by instructions which write to TCC each time.
- The prescaler will be cleared by the WDTC and SLEP instructions, when assigned to WDT mode.
- The prescaler will not be cleared by SLEP instructions, when assigned to TCC mode.

In ERIC mode, the instruction clock is the half of frequency of ERIC oscillation. When TS bit sets 1, the clock is the half of sub frequency divided from the frequency of ERIC oscillation.





Fig.9 Block diagram of TCC WDT

VII.5 I/O Ports

The I/O registers, Port5 ~ Port 9, are bi-directional tri-state I/O ports. Port 7 can be pulled-high internally by software control. The I/O ports can be defined as "input" or "output" pins by the I/O control registers (IOC6 ~ IOC9) under program control. The I/O registers and I/O control registers are both readable and writable. The I/O interface circuit is shown in Fig.10.



Fig.10 Circuit of I/O port and I/O control register

VII.6 RESET and Wake-up

The RESET can be caused by

(1) External /RESET pin

(2) Power on reset or Power on voltage detector reset (/POVD reset)

(3) WDT timeout. (if enabled and in GREEN or NORMAL mode)

Note that only Power on reset, or only Power on voltage detector reset in Case(2) is enabled in the system by CODE Option bit. If /POVDs disabled, Power on reset is selected in Case (2). Refer to Fig.11.





Fig.11 Block diagram of Reset of controller

Once the RESET occurs, the following functions are performed.

- The oscillator is running, or will be started.
- The Program Counter (R2) is set to all "0".
- When power on, the upper 3 bits of R3 and the upper 2 bits of R4 are cleared.
- The Watchdog timer and prescaler are cleared.
- The Watchdog timer is disabled.
- The CONT register is set to all "1"
- The other register (bit7..bit0)

R5 = "xxxx0000"	IOC5 = "1111xxxx"	
R6 = PORT	IOC6 = "11111111"	
R7 = PORT	IOC7 = "11111111"	
R8 = PORT	IOC8 = "11111111"	
R9 = PORT	IOC9 = "11111111"	
RA = "00110000"	Page0 IOCA = "00000000"	Page1 IOCA = "00000000"
RB = "0000x000"	Page0 IOCB = "00000000"	Page1 IOCB = "00000000"
RC = "00000000"	Page0 IOCC = "xxxxxxxx"	Page1 IOCC = "00000000"
RD = "xxxxxxxx"	Page0 IOCD = "00000000"	Page1 IOCD = "00000000"
RE = "x0000000"	Page0 IOCE = "00000000"	Page1 IOCE = "00000000"
RF = "000000000"	IOCF = "00000000"	

The controller can be awakened from SLEEP mode or IDLE mode (execution of "SLEP" instruction, named as SLEEP mode or IDLE mode) by (1) TCC time out (IDLE mode only) (2) WDT time-out (if enabled) (3) external input at PORT9. The three cases will cause the controller to be wake-up and run from next instruction in IDLE mode, reset in SLEEP mode. After CPU is wake-up, user should control Watchdog in case of reset in GREEN mode or NORMAL mode. The last three should be open RE register before into SLEEP mode or IDLE mode. The first one case will set a flag in RF bit 0. And it will go to address 0x08 when TCC generates an interrupt.

VII.7 Interrupt

The EM78P803B has internal interrupts which are falling edge triggered, as follows: TCC timer overflow interrupt (internal), two 8-bit counters overflow interrupt.

If these interrupt sources change signal from high to low, then RF register will generate '1' flag to corresponding register if you enable IOCF register.



RF is the interrupt status register which records the interrupt request in flag bit. IOCF is the interrupt mask register. Global interrupt is enabled by ENI instruction and is disabled by DISI instruction. When one of the interrupts (when enabled) generated, will cause the next instruction to be fetched from address 008H. Once in the interrupt service routine the source of the interrupt can be determined by polling the flag bits in the RF register. The interrupt flag bit must be cleared in software before leaving the interrupt service routine and enabling interrupts to avoid recursive interrupts.

There are four external interrupt pins including INT0, INT1, INT2 and INT3. And four internal counters interrupt available.

External interrupt INT0, INT1, INT2, INT3 signals are from PORT7 bit0 to bit3. If IOCF is enable then these signal will cause interrupt, or these signals will be treated as general input data.

After reset, the next instruction will be fetched from address 000H and the instruction interrupt is 001H and the hardware interrupt is 008H.

TCC will go to address 0x08 in GREEN mode or NORMAL mode after time out. And it will run next instruction from "SLEP" instruction and then go to address 0x08 in IDLE mode. These two cases will set a RF flag.

VII.8 Instruction Set

Instruction set has the following features:

- (1) Every bit of any register can be set, cleared, or tested directly.
- (2) The I/O register can be regarded as general register. That is, the same instruction can operate on I/O register.

The symbol "R" represents a register designator which specifies which one of the 64 registers (including operational registers and general purpose registers) is to be utilized by the instruction. Bits 6 and 7 in R4 determine the selected register bank. "b" represents a bit field designator which selects the number of the bit, located in the register "R", affected by the operation. "k" represents an 8 or 10-bit constant or literal value.

	Instruc	tion bin	ary	Hex	Mnemonic	Operation	Status Affected
0	0000	0000	0000	0000	NOP	No Operation	None
0	0000	0000	0001	0001	DAA	DAA Decimal Adjust A	
0	0000	0000	0010	0002	CONTW	$A \rightarrow CONT$	None
0	0000	0000	0011	0003	SLEP	$0 \rightarrow WDT$, Stop oscillator	T,P
0	0000	0000	0100	0004	WDTC	$0 \rightarrow WDT$	T,P
0	0000	0000	rrrr	000r	IOW R	$A \rightarrow IOCR$	None
0	0000	0001	0000	0010	ENI	Enable Interrupt	None
0	0000	0001	0001	0011	DISI	Disable Interrupt	None
0	0000	0001	0010	0012	RET	$[Top of Stack] \rightarrow PC$	None
0	0000	0001	0011	0013	RETI	$[Top of Stack] \rightarrow PC$	None
						Enable Interrupt	
0	0000	0001	0100	0014	CONTR	$\text{CONT} \rightarrow \text{A}$	None
0	0000	0001	rrrr	001r	IOR R	$IOCR \rightarrow A$	None
0	0000	0010	0000	0020	TBL	R2+A \rightarrow R2 bits 9,10 do not clear	Z, C, DC
0	0000	01rr	rrrr	00rr	MOV R,A	$A \rightarrow R$	None
0	0000	1000	0000	0080	CLRA	$0 \rightarrow A$	Z
0	0000	11rr	rrrr	00rr	CLR R	$0 \rightarrow R$	Z
0	0001	00rr	rrrr	01rr	SUB A,R	$R-A \rightarrow A$	Z, C, DC
0	0001	01rr	rrrr	01rr	SUB R,A	$R-A \rightarrow R$	Z, C, DC
0	0001	10rr	rrrr	01rr	DECA R	$R-1 \rightarrow A$	Z
0	0001	11rr	rrrr	01rr	DEC R	$R-1 \rightarrow R$	Z
0	0010	00rr	rrrr	02rr	OR A,R	$A \lor VR \rightarrow A$	Z
0	0010	01rr	rrrr	02rr	OR R,A	$A \lor VR \rightarrow R$	Z
0	0010	10rr	rrrr	02rr	AND A,R	$A \& R \to A$	Z
0	0010	11rr	rrrr	02rr	AND R,A	$A \& R \to R$	Ζ

0	0011	00rr	rrrr	03rr	XOR A,R	$A \oplus R \to A$	Z
0	0011	01rr	rrrr	03rr	XOR R,A	$A \oplus R \to R$	Z
0	0011	10rr	rrrr	03rr	ADD A,R	$A + R \rightarrow A$	Z, C, DC
0	0011	11rr	rrrr	03rr	ADD R,A	$A + R \rightarrow R$	Z, C, DC
0	0100	00rr	rrrr	04rr	MOV A,R	$R \rightarrow A$	Z
0	0100	01rr	rrrr	04rr	MOV R,R	$R \rightarrow R$	Z
0	0100	10rr	rrrr	04rr	COMA R	$/R \rightarrow A$	Z
0	0100	11rr	rrrr	04rr	COM R	$/R \rightarrow R$	Z
0	0101	00rr	rrrr	05rr	INCA R	$R+1 \rightarrow A$	Z
0	0101	01rr	rrrr	05rr	INC R	$R+1 \rightarrow R$	Z
0	0101	10rr	rrrr	05rr	DJZA R	$R-1 \rightarrow A$, skip if zero	None
0	0101	11rr	rrrr	05rr	DJZ R	$R-1 \rightarrow R$, skip if zero	None
0	0110	00rr	rrrr	06rr	RRCA R	$R(n) \rightarrow A(n-1)$	С
						$R(0) \rightarrow C, C \rightarrow A(7)$	
0	0110	01rr	rrrr	06rr	RRC R	$R(n) \rightarrow R(n-1)$	С
						$R(0) \rightarrow C, C \rightarrow R(7)$	
0	0110	10rr	rrrr	06rr	RLCA R	$R(n) \rightarrow A(n+1)$	С
						$R(7) \rightarrow C, C \rightarrow A(0)$	
0	0110	11rr	rrrr	06rr	RLC R	$R(n) \rightarrow R(n+1)$	С
						$R(7) \rightarrow C, C \rightarrow R(0)$	
0	0111	00rr	rrrr	07rr	SWAPA R	$R(0-3) \rightarrow A(4-7)$	None
						$R(4-7) \rightarrow A(0-3)$	
0	0111	01rr	rrrr	07rr	SWAP R	$R(0-3) \leftrightarrow R(4-7)$	None
0	0111	10rr	rrrr	07rr	JZA R	$R+1 \rightarrow A$, skip if zero	None
0	0111	11rr	rrrr	07rr	JZ R	$R+1 \rightarrow R$, skip if zero	None
0	100b	bbrr	rrrr	0xxx	BC R,b	$0 \rightarrow R(b)$	None
0	101b	bbrr	rrrr	0xxx	BS R,b	$1 \rightarrow R(b)$	None
0	110b	bbrr	rrrr	0xxx	JBC R,b	if R(b)=0, skip	None
0	111b	bbrr	rrrr	0xxx	JBS R,b	if R(b)=1, skip	None
1	00kk	kkkk	kkkk	1kkk	CALL k	$PC+1 \rightarrow [SP]$	None
						$(Page, k) \rightarrow PC$	
1	01kk	kkkk	kkkk	1kkk	JMP k	$(Page, k) \rightarrow PC$	None
1	1000	kkkk	kkkk	18kk	MOV A,k	$k \rightarrow A$	None
1	1001	kkkk	kkkk	19kk	OR A,k	$A \lor k \to A$	Z
1	1010	kkkk	kkkk	1Akk	AND A,k	$A \& k \to A$	Z
1	1011	kkkk	kkkk	1Bkk	XOR A,k	$A \oplus k \to A$	Z
1	1100	kkkk	kkkk	1Ckk	RETL k	$k \rightarrow A$, [Top of Stack] $\rightarrow PC$	None
1	1101	kkkk	kkkk	1Dkk	SUB A,k	$k - A \rightarrow A$	Z, C, DC
1	1110	0000	0001	1E01	INT	$PC+1 \rightarrow [SP]$	None
						$001H \rightarrow PC$	
1	1110	1000	kkkk	1E8k	PAGE k	K->R5	None
1	1111	kkkk	kkkk	1Fkk	ADD A,k	$k+A \rightarrow A$	Z, C, DC

VII.9 System Option

VII.9.1 CODE Option Register

The IC has one CODE option register which is not part of the normal program memory. The option bits cannot be accessed during normal program execution and can be set when downloading the program code.



12	11	10	9	8	7	6	5	4	3	2	1	0
						SFDIV2	SFDIV1	SFDIV0	16CNT		R2FHR	PTB

Bit 0 (PTB) : Protection Bit

0 → enable

1 \rightarrow disable (default)

When PTB bit sets, the program code in the code ROM isn't readable. Otherwise, the program code can be read from the code ROM. The default is disable.

Bit 1 (R2FHR): Mode of R to F Oscillator

 $0 \rightarrow$ High Speed Mode

 $1 \rightarrow$ Low Speed Mode (default)

In high-speed mode, the frequency is ten times the frequency in low speed mode. Thus, be careful to choose the suitable resistor and capacitor in different mode in order to operate correctly.

Notice: This option is opposite to J5 on ICE803 and COPHIRES option in EM78801

Bit 3 (16CNT): 16-bit counter (16CNT) mode enable

 $0 \rightarrow \text{enable}$

 $1 \rightarrow$ disable (default)

When 16CNT bit cleared, the system is in the 16CNT mode. Two 8-bit counters combine into one 16-bit counter. The clock source of CNT2 changes to 32.768kHz and MSB of CNT1. Thus user can switch the clock source of CNT2 to combine two 8-bit counters into one 16-bit counter. In the 16CNT mode, all of features are as the same as in the normal mode but counters. Please refer Sec. VII.14 "Two 8-Bit Counters/One 16-Bit Counter In 16-Bit Counter Mode" for more detail.

P803ON	16CNT	R2FON	Status Of Counter 1 & 2
0	0	N/A	2 counters combine to form a 16-bit counter w/o reload function
0	1	N/A	2 counters are independent 8-bit counters w/o reload function
1	0	Х	2 counters combine to form a 16-bit counter with reload function
1	1	0	2 counters are independent 8-bit counters with reload function
1	1 1 1 2 co		2 counters combine to form a 16-bit counter with reload function

User can setup these bits no matter in ERIC mode or not.

Bit 4~6 (SFDIV2~0): Scale factor of main frequency

In ERIC mode, the sub frequency is divided from the frequency of ERIC oscillation. These three bits set up the scale factor of division. Be careful to choose the main frequency and scale factor. Because the improper sub frequency will cause some function failure. Please refer VII.15 "ERIC Mode" for more detail.

SFDIV2	SFDIV1	SFDIV0	Scale factor
0	0	0	1:2
0	0	1	1:4
0	1	0	1:8
0	1	1	1:16
1	0	0	1:32
1	0	1	1:64
1	1	0	1:128
1	1	1	1:256

Bit 2, Bit 7 ~ Bit 12 : unused

VII.9.2 PAD Option

There are two PAD options on the system, /POVD and ERICen. One pad option contains two pads. One is on the side of VSS and the other is on the side of VDD. User can choose what signal should be connect to the PAD options. Then the option pad will bind to VDD or VSS during the bonding the chip.

	ERICen	/POVD
0	Crystal mode	Power on voltage detector off
1	ERIC mode	Power on voltage detector on



ERICen : ERIC mode enable

Pull low \rightarrow Crystal mode

Pull high \rightarrow ERIC mode

If this pin pulls low, the system runs in Crystal mode. The external crystal supplies the system clock. Otherwise, the system runs in ERIC mode. The system clock is generated by RC oscillation with an external resistor. Please refer VII.15 "ERIC Mode" for more detail.

/POVD : Power on voltage detector reset enable pin

Pull low \rightarrow enable

Pull high \rightarrow disable

For VDD = 3.3V, the /POVD reset voltage

/POVD	2.2 V /POVD reset	1.6V power on reset	sleep mode current
0	yes	no	15uA
1	no	yes	1uA

Ps. When /POVD is disabled, the CPU reset is by power on reset circuit. When /POVD is enabled, the CPU reset is by /POVD reset circuit.

VII.10 LCD Driver

The EM78P803B can drive LCD directly and has 28 segments and 8 commons that can drive 28*8 dots totally. LCD block is made up of LCD driver; display RAM, segment output pins, common output pins and LCD operating power supply pins.

The outputs of commons and segments equipped with buffer. So the LCD driver has bigger driving capacity than EM78805C, which means EM78P803 can drive bigger LCD panel than EM78805C.

Duty, bias, the number of segment, the number of common and frame frequency are determined by LCD mode register. LCD control register.

The basic structure contains a timing control which uses the basic frequency 32.768KHz to generate the proper timing for different duty and display access. RE register is a command register for LCD driver, the LCD display (disable, enable, blanking) is controlled by LCD_C and the driving duty and bias is decided by LCD_M and the display data is stored in data RAM which address and data access controlled by registers RC and RD.

In ERIC mode, the PLL is off and there is no 32.768kHz clock in the system. The sub frequency is divided from main clock generated from ERIC oscillation by the scale factor listed in Sec. VII.9.1. It means that the sub frequency depends on the main clock. If user wants to use the function of LCD driver in the system, user should design a suitable system clock and scale factor after chose the LCD panel. Or, equipped with a proper LCD panel after decided what frequency the system runs on. If sub frequency is too fast or too slow, there will be some unexpected condition happened on the LCD panel.

The following table lists the recommend main frequency with proper scale factor. User can adjust the main frequency for different types of LCD panel.

Main Frequency	Scale Factor
64 kHz	2
128 kHz	4
256 kHz	8
512 kHz	16
1M Hz	32
2M Hz	64
4M Hz	128
8M Hz	256





Fig.12 LCD driver control

VII.10.1 LCD Driver Control

RE(LCD Driver Control)(initial state "0000000")

7	6	5	4	3	2	1	0
					LCD_C2	LCD_C1	

Bit 1 ~ 2 (LCD_C1,LCD_C2) : LCD display enable or blanking The display duty change must set the (LCD_C2,LCD_C1) to (0,0).

(LCD_C2,LCD_C1)	LCD Display Control	duty	bias
(0,0)	Disable(turn off I CD)	(*1)	1/4
(0,0)	Disable(turn on LCD)	(*1)	1/4
(0,1)	Blanking	:	
(1,1)	LCD display enable	:	
w1 1/0 1/4 1 · 1 1		r >	

*1. 1/8 or 1/4 duty depends on IOCE PAGE1 bit0 (LCDM)

VII.10.2 LCD display area

The LCD display data is stored in the data RAM. The relation of data area and COM/SEG pin is as below: The relation of data area and COM/SEG pin is as below:

COM7 ~ COM0	Segment
00H (Bit7 ~ Bit0)	SEG0
01H	SEG1
•	:
1AH	SEG26
1BH	SEG27
1CH	(empty)
•	:
1FH	(empty)

IOCB(LCD Display RAM address)

7	6	5	4	3	2	1	0
-	-	-	LCDA4	LCDA3	LCDA2	LCDA1	LCDA0

* Bit 0 ~ Bit 5 : select LCD Display RAM addresses up to 27.

IOCC (LCD Display data) : Bit 0 ~ Bit 7 are LCD data.



VII.10.3 LCD COM and SEG signal

COM signal : The number of COM pins varies according to the duty cycle used, as following: in 1/8 duty mode

	COM0	COM1	COM2	COM3	COM4	COM5	COM6	COM7
1/8	0	0	0	0	0	0	0	0
1/4	0	0	0	0	Х	Х	Х	Х

x : open, o : select,

SEG signal: The 28 segment signal pins are connected to the corresponding display RAM address 0 to 27. The high bit and the low bit (bit7 down to bit0) are correlated to COM7 to COM0 respectively. For 8-COM mode, COM7 to COM0 and LCD RAM IOCC PAGE0 bit0~7 are used. For 4-COM mode, COM3 to COM0 and LCD RAM only IOCC PAGE0 bit0~bit3 are used

When a bit of display RAM is 1, a select signal is sent to the corresponding segment pin, and when the bit is 0, a non-select signal is sent to the corresponding segment pin.

*COM, SEG and Select/Non-select signal is shown as following. In the figure, the VLCD is equal to VDD-VOP. It means that VLCD is higher than GND except VOP=VDD.



Fig.13 LCD waveform, 1/3 bias & 1/4 bias, 1/8 duty or 1/4 duty



VII.10.4 LCD power saving

For some application, it needs more power concerning and only small LCD dots or little LCD driving required. User can use the LCD power saving function in this application. Some bits setting will let LCD driver less current consumption. Please refer to IOCA PAGE1 bit5 (CR) for details.

VII.11 R to F Counter

R to F Counter is simply a counter which signal source is RC ring oscillation. User can use different resistor or capacitor and result different oscillation frequency. User can connect the resistive or capacitive sensor to CRS and RS pad and set the oscillation mode by switching the CM0 \sim 2 bits. Then the frequency can be obtained by counting the signal. Finally the parameter we sense can be obtained by calculating the counter value in different counting mode.

In register IOCF page1, the register file is listing in following table. When R2FON bit set, the internal two 8bits counters will combine into one 16-bit counter. The source of 16-bit counter will switch to RC oscillation. Count2 is the MSB (bit15 \sim 8) and Counter1 is the LSB (bit7 \sim 0). User can write the data into counter1 and 2 for initialization. Then CNTST bit can be set for begin to count. The 16-bit counter stops and CNTST bit resets when real time clock (TCC) overflows and generate interrupt flag. Thus the TCC must start up when starting 16-bit counter. User can set the initial value of counter1 and counter2 in order to setup the counting period of the 16-bit counter.

There is a prescaler in counter1 and TCC. There is no reload function in TCC. But user can set the prescaler to set counting period of TCC. There is prescaler in the counter1 and two counters have reload function. Thus the counting range of R2F counter is more variable.

The frequency is 1/24(RC). The frequency range of R to F Counter is several kilos Hz to several mega Hz. We don't guarantee the correct operation beyond the recommended range. Thus, it is very important to choice the suitable external resister and capacitor for R to F Counter.

7	6	5	4	3	2	1	0
	CM2	CM1	CM0		CNTST		R2FON

The usage of R to F Counter is as following:





Fig.14 The usage of R to F Counter

For example:

BS	0x3, 7	;Change to page1 of IOC register
MOV IOW	A, @0b00010001 0xF	;Turn on Counter and set the counting mode (mode 1)
MOV IOW	A, @0b00000100 0xE	;Set the prescaler of R to F Counter (1:4)
MOV IOW IOW	A, @0x00 0xB 0xC	;Set the initial of Counter
MOV CONTW	A, @0b01100000	;Set the clock source and prescaler of TCC
BC	0x3, 7	
MOV IOW	A, @0b00100001 0xF	;Set the interrupt of TCC and CNT2
CLR	0xF	
MOV	A, @0x00	



MOV	0x1, A	;Write the initial value to TCC register
MOV BS IOW	A, @0b00010101 0x3, 7 0xF	;Activate the Counter

;Then, TCC interrupt occurred, user can pick up the value in Counter and did the further calculation. But when Counter overflowed, CNT2 interrupt occurred and Counter stopped.

Every mode implies different RC oscillating situation. There are only two components (one resister and one capacitor) connected in each mode. The following table lists the connection of external RC components. User should be noticed that in the mode $CM2 \sim 0$: 000, it means that user can connect the external clock into IN pad instead of RC oscillation in order to count the external source.

Counter Mode			Connection of External RC Components				
CM2	CM1	CM0	S1	S2	S3	S4	S5
0	0	0	External Clock Input through IN Pin				
0	0	1	1	1	0	0	0
0	1	0	1	0	0	1	0
0	1	1	0	1	1	0	0
1	0	0	1	0	0	0	1
1	0	1	0	0	1	0	1
1	1	0	Clock source of counter is 32.768kHz				
1	1	1	Clock so	urce of cour	ter is half o	f main clock	c of MCU

In ERIC mode, the clock source of counter will be the sub frequency when choosing the mode "110" and the half of main frequency of ERIC oscillation when choosing the mode "111".

If user didn't need R to F counter, do not use the R2FC register as a normal register. If user used R2FC register as normal register, user cannot access data correctly and consume more power when turning on the R to F counter unintentionally.



Fig.15 The Block diagram of R to F Counter

The Fig.16 shows the curve of R to F Counter when C=100p. The curve is appropriate for the frequency formula which is mentioned before. User has to notice the variation of curve when choosing the sensor. The value of R to F counter will be different from Fig.17 because choosing the nonlinear resistive sensor.





Fig.16 Curve of R to F Counter (C=100p)

VII.12 Two 8-bit counters/One 16-bit counter in 16-bit counter mode

The Fig.17 shows the relation of two counters. The one of clock sources of Counter2 is the MSB of the Counter1. Thus if user set IOCE Page1 bit5, these two counters will combine into one 16-bit counter. The Counter1 is the LSB and the Counter2 is the MSB. When in the 16-bit counter (16CNT) mode, the interruption of CNT1 will be masked. The interruption of Counter2 acts for 16-bit counter.



Fig.17 The block diagram of the two 8-bit counters

P803ON	16CNT	R2FON	Status Of Counter 1 & 2
0	0	N/A	2 counters combine to form a 16-bit counter w/o reload function
0	1	N/A	2 counters are independent 8-bit counters w/o reload function
1	0	Х	2 counters combine to form a 16-bit counter with reload function
1	1	0	2 counters are independent 8-bit counters with reload function
1	1	1	2 counters combine to form a 16-bit counter with reload function



VII.13 ERIC Mode

The system has an optional RC mode. In this ERIC mode, user can connect PLLC to VDD with a resistor serially. Then the system will generate a clock signal internally by an internal capacitor and external resistor on PLLC pin. User can use only one resistor to replace the crystal oscillator in order to reduce PCB area and cost.

In ERIC mode, the main frequency is provided by ERIC oscillation and the sub frequency is provided by the main frequency through the scaler. User can configure the scaler with different factors in order to get the suitable match with peripheral of system (like LCD driver, R to F counter or 16-bit counter) and main frequency. For example, for low power application with LCD display, user can choose the frequency 1MHz with scale factor 32. The sub frequency will be about 32kHz. With this frequency, the LCD panel can work well.

In the other hand, user can choose a suitable sub frequency which is different from 32kHz (For example, high frequency LCD panel). Then choose the right Main frequency and set the scale factor correctly. But be careful, the sub frequency you choose cannot let the other function work well. User can refer following table to get 32kHz sub frequency.

The formula of ERIC frequency is $f=1/(R \times 5.25 \times 10^{-12})$. For example, when R=100k Ohm, main frequency is about 1.9MHz.The following table shows the suggested resistor and approximate main frequency. The scalar doesn't work when in crystal mode. In crystal mode, the sub frequency is always 32kHz. The following tables shows the suggested serial connected resistor and generated main frequency, scale factor and sub frequency.

Ext. Resistor	RC Frequency	Scale Factor	Sub. Frequency
1.5M	127k	4	31.8k
750k	254k	8	31.8k
360k	529k	16	33.1k
180k	1059k	32	33.1k
91k	2110k	64	33k
47k	4054k	128	31.7k
22k	8662k	256	33.8k

In ERIC mode, the main and sub frequency act at the same time. Thus, the operating modes of system are only normal mode and sleep mode.

The frequency of ERIC oscillator affected by operating voltage. The higher operating voltage the MCU has, the faster frequency the ERIC oscillator generates. According to our laboratory test, the following table shows the highest frequency in different operating voltage. Notice that it is our laboratory measured data. It is probably different in practical situation. And it will vary from different EM78801s. The resistance shows in the table might not be suitable for the formula of ERIC oscillation mentioned before. The formula has a bit changed because the frequency is too fast.

	Power	ERIC Oscillation	Serial Resistance
1	2.2V	6.84MHz	30.13k
2	2.6V	9.96MHz	20.29k
3	3V	11.63MHz	18.4k
4	4V	15.11MHz	13.98k
5	5V	18.12MHz	11.75k
6	5.5V	19.27MHz	11.02k





Fig.18 Frequency vs. operating voltage





Fig.19 Circuit of ERIC mode

Fig.20 Block diagram of ERIC oscillation



VIII. Absolute Operation Maximum Ratings

Rating	Symbol	Value	Unit
DC Supply Voltage	VDD	-0.3 To 6	V
Input Voltage	Vin	-0.5 to VDD +0.5	V
Operating Temperature Range	Ta	0 to 70	°C

IX. DC Electrical Characteristic

(Ta = 25°C, AVDD=VDD=5V±5%, VSS=0V)

Parameter	Symbol	Condition	Min	Тур	Max	Unit
DC Supply Voltage	VDD	Main Clock = 7.1652MHz	2.8		5.5	V
		Main Clock = 14.331MHz	4.5		5.5	V
Input Voltage	Vin		-0.5		VDD+0.5	V
Operating Temperature	Та		0		70	^o C
Input leakage current for input pins	IIL1	VIN = VDD, VSS			±1	uA
Input leakage current For bi-directional pins	IIL2	VIN = VDD, VSS			±1	uA
Input high voltage	VIH		2.5			V
Input low voltage	VIL				0.8	V
Input high threshold voltage	VIHT	/RESET, TCC	2.0			V
Input low threshold voltage	VILT	/RESET, TCC			0.8	V
Clock input high voltage	VIHX	OSCI	3.5			V
Clock input low voltage	VILX	OSCI			1.5	V
Output high voltage for (port5,6,7,8)	VOH1	IOH = -1.6mA	2.4			V
Output high voltage for PORT9	VOH2	IOH = -6mA	2.4			V
Output low voltage for (Port5, 6,7,8)	VOL1	IOH = 1.6mA			0.4	v
Output low voltage for Port9	VOL2	IOH = 6mA			0.4	V
Common voltage drop	V _{COM}	$I_0 = \pm 50 \text{ uA}$			2.9	V
Segment voltage drop	V _{SEG}	$I_0 = \pm 50 \text{ uA}$			3.8	V
Pull-high current	IPH	Pull-high active input pin at VSS	-13.2	-13.4	-13.8	uA
Power down current (SLEEP mode)	ISB1	All input and I/O pin at VDD, output pin floating, WDT disabled, POVD disable, other circuit disable		0.64	0.8	uA
Low clock current (IDLE mode) POVD disable	15D2	CLK=32.768KHz, All input and I/O pin at VDD,		35	45	μΑ
Low clock current (IDLE mode) POVD enable	1903	output pin floating, WDT disabled, LCD enable		40	60	uA
Low clock current (GREEN mode)	ISB2	CLK=32.768KHz, All input and I/O pin at VDD, output pin floating, WDT disabled, LCD enable, POVD disable		28.16	50	uA
Operating supply current (Normal mode)	ICC1	/RESET=High, CLK=3.58MHz, output pin floating, other analog circuits disabled		1.39	1.6	mA



X. AC Electrical Characteristic

Č X	,	,	,			
Parameter	Symbol	Condition	Min	Тур	Max	Unit
Input CLK duty cycle	Dclk		45	50	55	%
Instruction cycle time	Tins	32.768kHz		60		us
		3.582MHz		550		ns
Device delay hold time	Tdrh			18		ms
TCC input period	Ttcc	Note 1	(Tins+20)/N			ns
Watchdog timer period	Twdt	$Ta = 25^{\circ}C$	16-30%	18	16+30%	ms

CPU instruction timing (Ta = 25° C, AVDD=VDD=5V, VSS=0V)

Note 1: N= selected prescaler ratio.

Timing characteristic (AVDD=VDD=5V,Ta=+25°C)

Description		Symbol	Min	Тур	Max	Unit
Oscillator timing characteristic		_	_			
Crystal start up	32.768kHz	Tosc	400		1500	ms
	3.579MHz PLL			5	10	us
Timing characteristic of reset						
The minimum width of reset low pulse		Trst	3			uS
The delay between reset and program start		Tdrs		18		mS

R to F Counter AC Characteristic (Vdd=+5V,Ta=+25°C, R= 1k, C=200p)

Characteristic	Min	Тур	Max	Unit
Frequency of RC Oscillator	186	194	198	kHz



XI. Timing Diagrams

AC Test Input/Output Waveform



AC Testing: Input are driven at 2.4V for logic "1", and 0.45V for logic "0". Timing measurements are made at 2.0V for logic "1", and 0.8V for logic "0".











XII. Application Circuit



Fig.22 Power Concern in Application