

# 6A Voltage Mode Synchronous Buck PWM DC-DC Converter

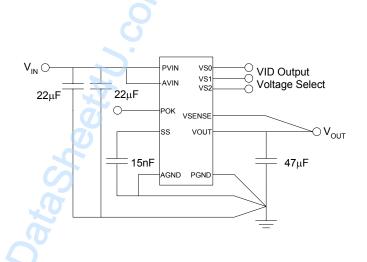
**RoHS Compliant** 

# Description

This Enpirion EN5360 is a Power System on a Chip DC-DC converter. It is specifically designed to meet the precise voltage and fast transient requirements of present and future high-performance, low-power processor, DSP, FPGA, memory boards and system level applications in a distributed power architecture. Advanced circuit techniques, ultra high switching frequency, and very advanced, high-density, integrated circuit and proprietary inductor technology deliver high-quality, ultra compact, non-isolated DC-DC conversion. Operating this converter requires only four external components that include small value input and output ceramic capacitors and a soft-start capacitor.

The Enpirion EN5360 significantly helps in system design and productivity by offering greatly simplified board design, layout and manufacturing requirements. In addition, a reduction in the number of vendors required for the complete power solution helps to enable an overall system cost savings.

# **Typical Application Circuit**



## **Features**

- Up to 20W output power (at V<sub>OUT</sub>=3.3V)
- External inductor is NOT required
- RoHS compliant, MSL3 rated to 260°C
- 5MHz operating frequency
- More than 90% efficient
- V<sub>OUT</sub> accuracy of 2% over line, load and temperature
- 1/3 the board area of discrete component solutions
- Very fast transient response
- All high speed switching signals contained inside the part
- Wide input voltage range of 2.375V to 5.5V
- Digital voltage selector with options for common output voltages from 0.8V to 3.3V
- External resistor divider and OVP option for output voltages from 0.8V to V<sub>IN</sub>-600mV
- Output enable pin and Power OK signal
- Programmable soft-start time
- Over-current protection
- Thermal shutdown, short circuit, output overvoltage and input under-voltage protection

## **Applications**

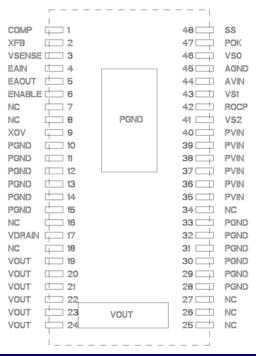
- Servers, workstations and PCs
- Broadband, networking, LAN/WAN, optical telecommunications equipment
- Point of load regulation for low-power processors, network processors, DSPs, FPGAs, and ASICs
- Low voltage, distributed power architectures with 2.5V, 3.3V or 5V rails

# Ordering Information

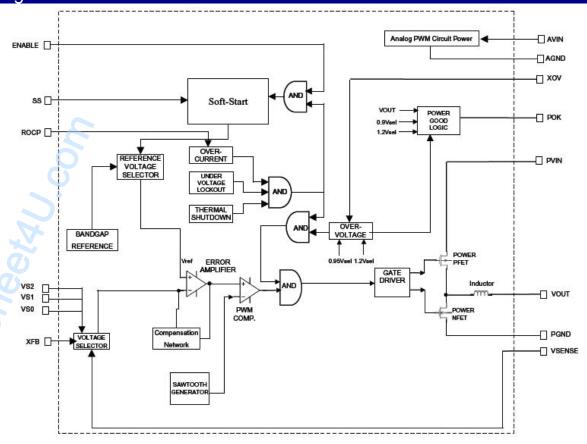
Part Number	Temp Rating (°C)	Package	
EN5360DC	0 to 70	48-pin DFN	
EN5360DC-T	0 to 70	48-pin DFN T&R	
EN5360DI	-40 to +85	48-pin DFN	
EN5360DI-T	-40 to +85	48-pin DFN T&R	
EN5360DC-E	DFN Evaluation Board		

# Pin Configuration

This diagram is a top-view of the component and represents the on-board layout requirements for the landing pads and thermal connection points. Specific dimensions for the pads are presented on page 10. Pin 1 of the device is signified by the white dot marked on the top of the device.



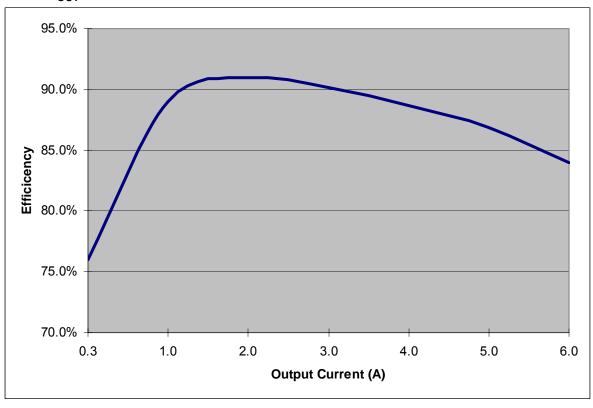
# **Block Diagram**



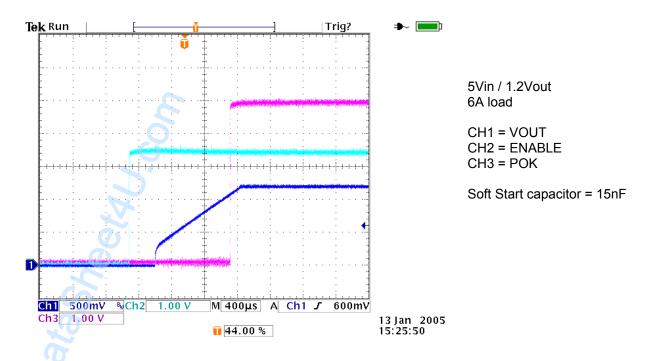


# Typical Efficiency

 $V_{IN} = 3.3V$  and  $V_{OUT} = 2.5V$ 

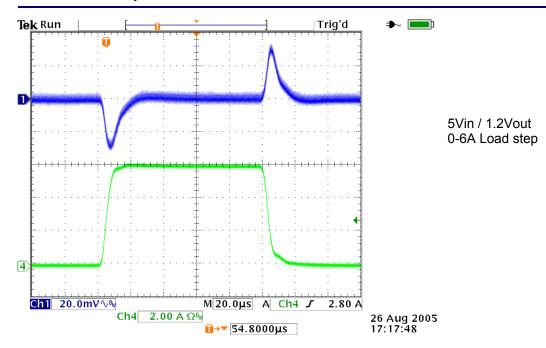


# Waveforms





#### Rev 1.01 – January 2006



## Absolute Maximum Ratings

CAUTION: Stresses in excess of the absolute maximum ratings may cause permanent damage to the device. Exposure to absolute maximum ratings for extended periods can adversely affect device reliability.

PARAMETER	SYMBOL	MIN	MAX	UNITS
Input Supply Voltage	V <sub>IN</sub>	-0.5	6.5	V
Input Voltage – Enable		-0.5	$V_{IN}$	V
Input Voltage – VS0, VS1 & VS2 (Note 1)		-0.5	2.8	V
Storage Temperature Range	T <sub>STG</sub>	-65	150	°C
Operating Junction Temperature	TJ		150	°C
MSL per JEDEC J-STD-020A Level 3			260	°C
ESD Rating (based on Human Body Model)			2000	V

#### NOTES:

1. VS0, VS1 and VS2 pins have an internal pull-up resistor, only ground potentials should be placed on them as required.

# Recommended Operating Conditions

PARAMETER	SYMBOL	MIN	MAX	UNITS
Input Supply Voltage	$V_{IN}$	2.375	5.5	V
Operating Junction Temperature	$T_J$	-40	125	°C

## Thermal Characteristics

PARAMETER	SYMBOL	<b>TYPICAL</b>	UNITS
Thermal Resistance: Junction to Ambient (0 LFM) (Note 2)	$\theta_{JA}$	22	°C/W
Thermal Resistance: Junction to Case (0 LFM)	$\theta_{JC}$	3	°C/W

#### NOTES:

2. Based on a four-layer board and proper thermal design in line with JEDEC EIJ/JESD 51 Standards.



# **Electrical Characteristics**

NOTE:  $V_{IN}$ =3.3V and over operating temperature range unless otherwise noted. Typical values are at  $T_A$  = 25°C.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNITS
Operating Input Voltage	V <sub>IN</sub>		2.375		5.5	V
Quiescent Supply Current		No switching, AVIN = 3.3V, PVIN = 3.3V, ENABLE=0V		20		mA
No-Load Operating Current	I <sub>NL</sub>	Includes PWM, gate drive and inductor ripple current.		100		mA
Switching Frequency	Fosc			5		MHz
Thermal Overload Trip Point	TJ			160		°C
V <sub>OUT</sub>		,	1	T		
Range	V <sub>OUT</sub>	Using external voltage divider	0.8			V
Accuracy	V <sub>OUT</sub>	Over line, load and temperature			2.0	%
Line Regulation	V <sub>OUT</sub>	$V_{IN} = 2.5 \text{ to } 5.0 \text{ volts}$		3		mV
Load Regulation	V <sub>OUT</sub>	I <sub>LOAD</sub> = 0 to 6A		3		mV
Temperature	V <sub>OUT</sub>	T <sub>A</sub> = 0 to 70°C		+0.25 -0.45		%
Regulation	V <sub>OUT</sub>	T <sub>A</sub> = -40 to 85°C		+0.65 -0.55		%
		100% or 100% to 0% of Rated Load)	1			
Peak Deviation	V <sub>OUT</sub>	$V_{IN} = 5V$ , 1.2V < $V_{OUT}$ < 3.3V		2	5	%
Output Voltage Ripp	ole (with 5 x 1	0μF X5R or X7R ceramic capacitors)	1	1		T
Peak-to-peak	V <sub>OUT-PP</sub>	$V_{IN}$ = 5.0V, $V_{OUT}$ = 1.2V, $I_{OUT}$ = 6A, $C_{OUT}$ = 50uF, 5 x 10µF X5R or X7R ceramic capacitors		15		mV
<b>Output Current (Not</b>	e 3)					
Max Continuous Output Current	I <sub>OUT</sub>				6	Α
Over-Current Threshold	I <sub>OCP</sub>			9		Α
Short-Circuit Current	I <sub>sc</sub>			8.5		Α
<b>Enable Operation</b>						
Disable Threshold	V <sub>DISABLE</sub>	Max voltage to ensure the converter is disabled			0.8	V
Enable Threshold	V <sub>ENABLE</sub>	Min voltage to ensure the converter is enabled	1.8			V
Power OK Operation						
POK low voltage	$V_{POK}$	$I_{POK} = 1mA$			0.4	V
Max POK Voltage	$V_{POK}$	Supply voltage applied to POK			5.5	V

NOTES:



<sup>3.</sup> Maximum output current may need to be de-rated, based on operating condition, to meet T<sub>J</sub> requirements.

Rev 1.01 – January 2006

Pin D	escriptions			
PIN	NAME	FUNCTION		
1	COMP	Output of the buffer leading to the error amplifier. Used for external modifications of the compensation network.		
2	XFB	External feedback voltage input. Option for programming the output voltage with a resistor divider on V <sub>OUT</sub> .		
3	VSENSE	Remote voltage sense input. Connect this pin to the load voltage at the point to be regulated.		
4	EAIN	Input of the error amplifier for external modifications of the compensation network.		
5	EAOUT	Output of the error amplifier for external modifications of the compensation network.		
6	ENABLE	Enable input. An input high enables operation. An input low disables operation.		
7	NC	NO CONNECT – Do not electrically connect this pin to PCB. See Note 4.		
8	NC	NO CONNECT – Do not electrically connect this pin to PCB. <b>See Note 4.</b>		
9	XOV	Over-Voltage set-point input. When using an external voltage divider and the XFB pin. When VS0, VS1 and VS2 are left OPEN or pulled high, an additional voltage divider separate from the XFB pin is required to set the OVP set-point. In this mode, the OVP function is disabled if this voltage divider is not present.		
10				
11				
12	PGND	Power ground for the power stage circuits.		
13	I GND	Tower ground for the power stage circuits.		
14				
15				
16	NC	NO CONNECT – Do not electrically connect this pin to PCB. See Note 4.		
17	VDRAIN	Test point between the power FETs and Inductor.		
18	NC	NO CONNECT – Do not electrically connect this pin to PCB. See Note 4.		
19				
20				
21	VOUT	Voltage and power output.		
22	, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Voltago ana powor output.		
23				
24				
25	2			
26	NC	NO CONNECT – Do not electrically connect this pin to PCB. <b>See Note 4.</b>		
27	O			
28				
29				
30	PGND	Power ground for the power stage circuits.		
31		1 one greate for the power stage offente.		
32				
33	9			
34	<b>ONC</b>	NO CONNECT – Do not electrically connect this pin to PCB. <b>See Note 4.</b>		
35				
36				
37	PVIN	Power voltage input for the power stage circuits.		
38	I VIIN	Towar valuage input for the power stage circuits.		
39				
40				
41	VS2	Voltage select line 2 input. See Table 1.		
42	ROCP	Over-Current trip point adjust input. Used for adjusting the OCP trip point.		
43	VS1	Voltage select line 1 input. See Table 1.		



PIN	NAME	FUNCTION	
44	AVIN	Analog voltage input for the controller circuits.	
45	AGND	Analog ground for the controller circuits.	
46	VS0	Voltage select line 0 input. See Table 1.	
47	POK	Power OK is an open drain transistor for power system state indication.	
48	SS	Soft-Start node. A capacitor is connected between this pin and AGND.	

#### NOTES:

4. This pin is used for engineering test purposes and reserved for future use. Solder, but do not electrically connect this pin to the PCB.

# Theory of Operation

#### **Synchronous Buck Converter**

The EN5360 is а synchronous, pin programmable power supply with integrated power MOSFET switches and inductor. The nominal input voltage range is 2.5-5.0V. The output can be set to common voltages by connecting appropriate combinations of 3 voltage selection pins to ground. If different voltage levels are required, provision is also made to allow external programming. The feedback control loop is voltage-mode and the part uses a low-noise PWM topology. Up to 6A of output current can be drawn from this converter. The 5MHz operating frequency enables the use of small-size output capacitors.

The power supply also has protection features such as:

- Programmable over-current protection (to protect the IC from excessive load current)
- Thermal shutdown (to protect the converter from getting too hot)
- Over-voltage protection that stops the PWM switching and turns on the lower N-MOSFET at 120% of the programmed output voltage in order to protect the load from an OV condition.
- Under-voltage lockout circuit to disable the converter output when the input voltage is less than approximately 2.2V

#### Additional features include:

 Soft-start circuit, limiting the in-rush current when the converter is powered up.  Power good circuit indicating whether the output voltage is within 90%-120% of the programmed voltage.

#### **Output Voltage Programming**

The EN5360 output voltage is programmed using one of two methods. Common output voltages are achieved by tying one or more of the three Voltage Select pins (VS0, VS1 & VS2) to ground (see Table 1). If all three are left floating, the output voltage and over voltage thresholds are determined by the voltages presented at the XFB and XOV pins respectively. These voltages should be set by way of resistor dividers between  $V_{\text{OUT}}$  to AGND with the midpoint going to XFB and XOV (See Figure 1).

It is recommended that Rb1 and Rb2 resistor values be  $\sim 2k\Omega$ . Use the following equation to set the resistor Ra1 for the desired output voltage:

$$Ra1 = \frac{(Vout - 0.8V) * Rb1}{0.8V}$$

If over-voltage protection is desired, use the following equation to set the resistor Ra2 for the desired OVP trip-point:

$$Ra2 = \frac{(OVPtrip - 0.96V) * Rb2}{0.96V}$$

By design, if both resistor dividers are the same, the OV trip-point will be 20% above the nominal output voltage.



www.DataSheet4U.com

Rev 1.01 – January 2006 **EN5360** 

Figure 1: External output voltage and OVP setting

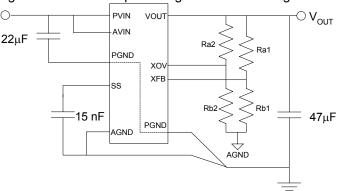


Table 1: Output Voltage Select Table

VS2*	VS1*	VS0*	Output Voltage
0	0	0	3.3V
0	0	1	2.5V
0	1	0	1.8V
0	1	1	1.5V
1	0	0	1.25V
1	0	1	1.2V
1	1	0	0.8V**
1	1	1	User Selectable

\*\* 0.8V ref only, not guaranteed performance

\*NOTE: The VS0, VS1 and VS2 pins are defaulted to a '1' with an internal pull-up resistor. Only connect these pins to AGND if a '0' is required. If a '1' is required, then leave the pin floating.

#### **Capacitor Selection**

The EN5360 needs about 40-80uF of input capacitance. Low-cost, low-ESR ceramic capacitors must be used as input capacitors for this converter and it is required that they be rated X5R or X7R. In some applications, lower value capacitors are needed in parallel with the larger, lossy capacitors in order to provide high frequency decoupling.

The EN5360 has been optimized for use with about 50µF of ceramic output capacitance. It is required that these be low-cost, low-ESR, ceramic capacitors rated X5R or X7R. (See the Enpirion application note on ripple comparison for optimum selection of number and value of these capacitors based on ripple requirements.) In order to eliminate high-frequency switching spikes on the output ripple, usually a low-value,

low-ESR ceramic capacitor is used in parallel with the larger capacitors right at the load.

#### **Enable Operation**

The ENABLE pin provides a means to shut down the power FET switching or enable normal operation. A logic low will disable the converter and cause it to shut down. A logic high will enable the converter into normal operation.

#### **Soft-Start Operation**

The SS pin in conjunction with a small capacitor between this pin and AGND provides the soft start function to limit the in-rush current during start-up. During start-up of the converter the reference voltage to the error amplifier is gradually increased to its final level by an internal current source of typically 10uA. The whole soft-start procedure is designed to take 1ms - 3ms with a 15-30nF soft start capacitor, but can be programmed by capacitor selection using the following equation:

Rise Time:  $T_R = C_{ss}^* 80k$ 

During the soft-start cycle, when the soft-start capacitor reaches 0.8V, the output has reached its programmed regulation range. Note that the soft-start current source will continue to operate and during normal operation, the soft-start capacitor will charge up to a final value of 2.5V.

#### **Power Up Sequencing**

The sequencing of AVIN, PVIN and ENABLE should meet the following requirements:

- 1. ENABLE should not be asserted before PVIN
- 2. PVIN should not be applied before AVIN.

Note that tying AVIN, PVIN and ENABLE together and brought up at the same time does meet these requirements.



www.DataSheet4U.com

Rev 1.01 – January 2006 **EN5360** 

#### **POK Operation**

The POK signal is an open drain signal from the converter indicating the output voltage is within the specified range. The POK signal will be a logic high when the output voltage is within 90% - 120% of the programmed output voltage. If the output voltage goes outside of this range, the POK signal will be a logic low until the output voltage has returned to within this range. In the event of an over-voltage condition the POK signal will go low and will remain in this condition until the output voltage has dropped to 95% of the programmed output voltage before returning to the high state (see also Over Voltage Protection)

#### **Over-Current Protection**

The cycle-by-cycle current limit function is achieved by sensing the current flowing through the sense P-MOSFET and a signal generated by a differential amplifier with a preset over-current threshold. During a particular cycle, if the over-current threshold is exceeded, the power P-MOSFET is turned off and the power N-MOSFET is turned on to protect the P-MOSFET. If the over-current condition is removed, the over-current protection circuit will enable the PWM operation. If the over-current condition persists, the converter will eventually go through a full soft-start cycle. This circuit is designed to provide high noise immunity.

It is possible to raise the over-current set-point by ~50% by connecting a 4.99k $\Omega$  resistor between ROCP and GND.

## **Over-Voltage Protection**

When the output voltage exceeds 120% of the programmed output voltage, the PWM operation stops, the lower N-MOSFET is turned on and the POK signal goes low. When the output voltage drops below 95% of the programmed output voltage, normal PWM operation resumes and POK returns to its high state.

#### **Thermal Overload Protection**

Thermal shutdown will disable operation once the Junction temperature exceeds approximately 160°C. Once the junction temperature drops by approx 25°C, the converter will re-start with a normal soft-start.

#### **Input Under-voltage Operation**

Circuitry is provided to ensure that when the input voltage is below the specified voltage range, the operation of the converter is controlled and predictable. Circuits for hysteresis, input deglitch and output leading edge blanking are included to ensure high noise immunity and prevent false tripping.

#### Compensation

The EN5360 is internally compensated through the use of a type 3 compensation network and is optimized for use with about 50µF of output capacitance and will provide excellent loop bandwidth and transient performance for most applications. (See the section on Capacitor Selection for details on recommended capacitor types.) In some cases modifications to the compensation may be required. For more information, contact Enpirion Applications Engineering support.

#### **Layout Considerations**

The EN5360 Layout Guidelines application note provides more details on specific layout recommendations for this part. The following are general layout guidelines to consider.

The CMOS chip inside the EN5360 has two grounds: AGND for the controller, and PGND for the power stage. These two grounds need to be connected outside the package at one point through a low-impedance trace. The connection should be made such that the impedance between the connection point and the AGND pad on the package is minimized. Since the internal voltage sensing circuit is based on AGND, the connection of the two grounds should also be made such that the best voltage regulation can



Rev 1.01 – January 2006 **EN5360** 

be achieved. The soft-start capacitor, the voltage programming resistors, and any other external control component should be tied to AGND.

The placement of the input decoupling capacitors and output filter capacitors relative to their respective pins is very critical. The input capacitors should be placed such that they have the lowest inductance traces to PVIN and PGND pins 28-33. The output filter capacitors should have the lowest inductance traces to VOUT and PGND pins 10-15.

There are two thermal pads underneath the device. The centrally located pad is PGND, and, depending on the number of layers of the PC board, it needs to be connected to a thermal plane in order to conduct heat away from the device. Note that if any of the thermal planes is

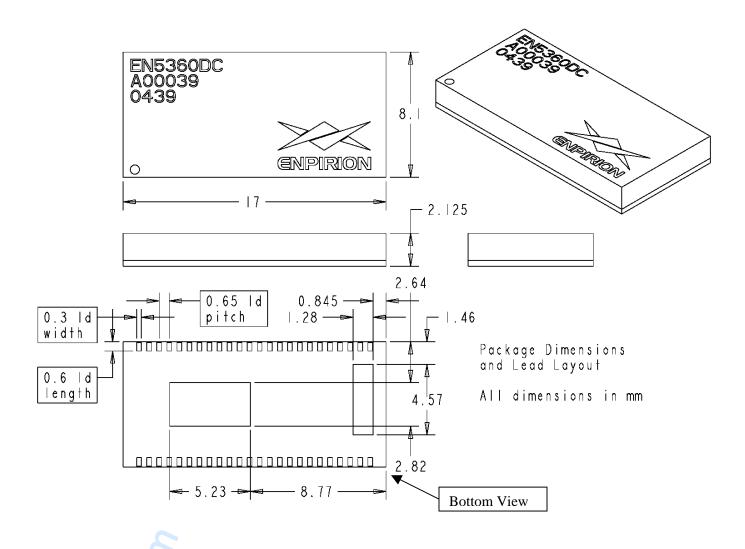
also connected to AGND, the impedance between this point and the GND connection of the load needs to be minimized in order to get the best possible load regulation. The pad in front of the  $V_{\text{OUT}}$  pins 22-24 is connected to  $V_{\text{OUT}}$ . This  $V_{\text{OUT}}$  pad should be connected to a top layer copper area as large as possible to conduct more heat away from the package. This will also help minimize the trace inductance to the output filter caps.

Pin 17 is a connected to a noisy internal node and is brought out for test purposes only. Keep all sensitive signal traces as far as possible from this pin. In order to minimize cross-talk to other parts of the board, do not run any unrelated traces from other circuits underneath the EN5360.



# Packaging Information

## **Mechanical Drawing and Nominal Dimensions**

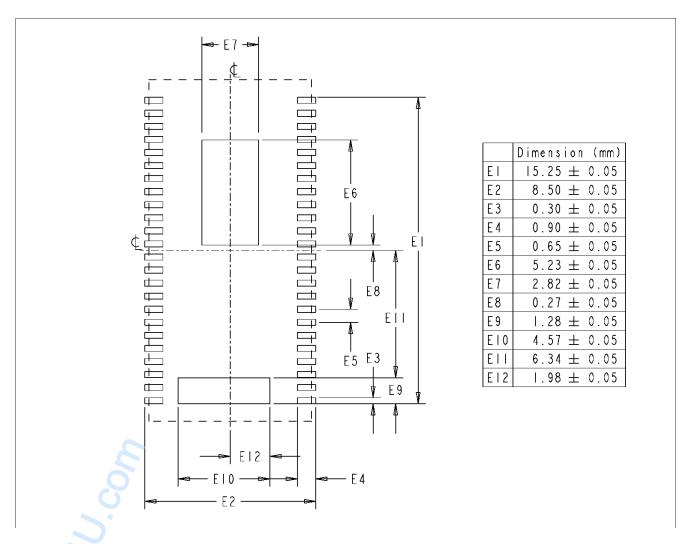


Rev 1.01 – January 2006 **EN5360** 

#### **Landing Pad Information**

The Enpirion DFN package is footprint compatible with the JEDEC standard 40-pin TSSOP package code DE that has been extended to 17mm and 48-pins. The reference document and board layout diagram appear below.

JEDEC Solid State Technology Association TSSOP (Plastic Thin Shrink Small Outline Package) standardized package code DD. This TSSOP standard package is defined in the JEDEC document MO-153, Issue F, dated 05/01, which defines 57 variations on package size, lead pitch, and lead count.



## **Contact Information**

Enpirion, Inc. 685 Route 202/206 Suite 305

Bridgewater, NJ 08807 Phone: 908-575-7550 Fax: 908-575-0775

Enpirion reserves the right to make changes in circuit design and/or specifications at any time without notice. Information furnished by Enpirion is believed to be accurate and reliable. Enpirion assumes no responsibility for its use or for infringement of patents or other third party rights, which may result from its use. Enpirion products are not authorized for use in nuclear control systems, as critical components in life support systems or equipment used in hazardous environment without the express written authority from Enpirion.

