

# 2A,30V,300KHz Step-Down Converter

### DESCRIPTION

The EUP3452A is current mode, step-down switching regulator capable of driving 2A continuous load with excellent line and load regulation. The EUP3452A can operate with an input voltage range from 4.5V to 30V and the output can be externally set from 0.8V to 12V with a resistor divider.

Fault condition protection includes cycle-by-cycle current limiting and thermal shutdown. In shutdown mode the regulator draws  $1\mu A$  of supply current. Programmable soft-start minimizes the inrush supply current and the output overshoot at initial startup.

The EUP3452A require a minimum number of external components.

## **FEATURES**

- 35V Input Surge Protection
- 2A Output Current
- 0.135Ω Internal DMOS Output Switch
- 4.5V to 30V Input Operating Range
- Output Adjustable from 0.8V to 12V
- Up to 95% Efficiency
- 1μA Shutdown Current
- Fixed 300KHz Frequency
- Thermal Shutdown and Overcurrent Protection
- Input Supply Overvoltage and Undervoltage Lockout
- Available SOP-8 Package
- RoHS Compliant and 100% Lead(Pb)-Free Halogen-Free

# **APPLICATIONS**

- PC Monitors
- Distributed Power Systems
- Networking Systems
- Portable Electronics

# **Typical Application Circuit**

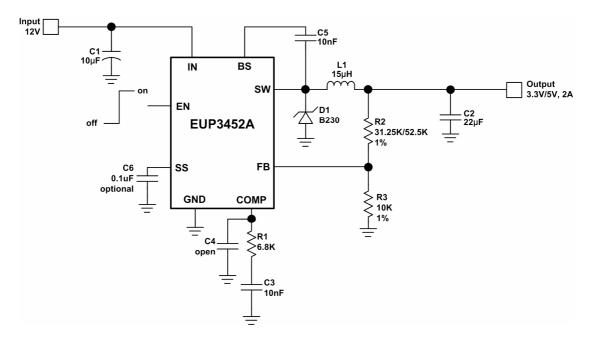


Figure 1. 12V to 3.3V/5V Application Circuit



# **Typical Application Circuit (continued)**

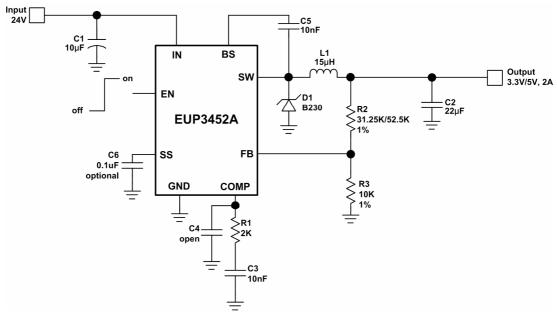


Figure 2. 24V to 3.3V/5V Application Circuit

# **Pin Configurations**

Package Type	Pin Confi	gurations
SOP-8	BS 1 IN 2 SW 3 GND 4	

# **Pin Description**

Pin Name	SOP-8	DESCRIPTION
BS	1	High-Side Gate Driver Boostrap Supply. BS provides power to the gate driver of high-side n-channel MOSFET switch. Connect a 10nF or greater capacitor from SW to BS.
IN	2	Input Supply Pin. IN supplies the power to the IC and the high side power switch. Connect IN to a 4.5V to 30V power source. Bypass IN to GND with a suitably large value capacitor to minimize input ripple to the IC. See Input Capacitor Section of the applications notes.
SW	3	Power Switcher Output. Connect the output LC filter from SW to the output.
GND	4	Ground.
FB	5	Output Feedback Input. FB senses the output voltage to regulate that voltage. Connect FB to an external resistor divider to set the output voltage. The feedback threshold is 0.8V. See Setting the Output Voltage.
COMP	6	Loop compensation pin. Connect a series RC network from COMP to GND to compensate the regulation control loop. <i>See Compensation</i> .
EN	7	Enable Input. EN is a logic input that controls the regulator on or off. Drive EN logic high to turn on the regulator, and set EN logic low to turn it off. Don't leave EN pin floating. Directly connect EN to IN (or through a resistance) for automatic startup.
SS	8	Soft-start. Connect SS to an external capacitor to program the soft-start. If unused ,leave it open, which means internal soft-start function.



# **Ordering Information**

Order Number	Package Type	Marking	Operating Temperature Range
EUP3452ADIR1	SOP-8	₩ xxxxx 3452A	-40°C to +85°C

# Lead Free Code Lead Free, Halogen Free 0: Lead Packing R: Tape & Reel Operating temperature range I: Industry Standard Package Type

D: SOP

# **Block Diagram**

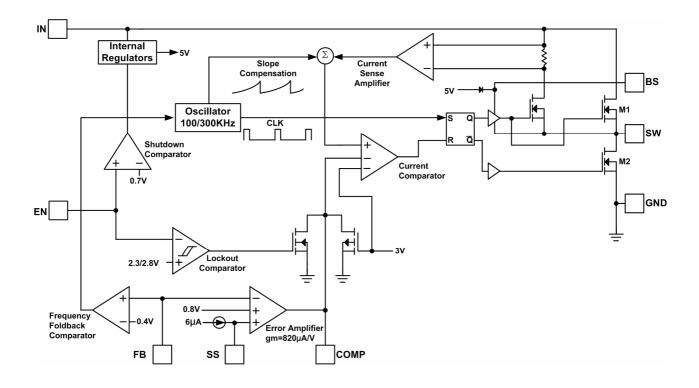


Figure 3. Functional Block Diagram



# **Absolute Maximum Ratings (1)**

•	Input Voltage (V <sub>IN</sub> )	-0.3V to 35V
•	Enable Input ( $V_{EN}$ )	-0.3V to 35V
•	Switch Voltage (V <sub>SW</sub> )	$V$ to $V_{IN}+0.3V$
•	Boot Strap Voltage (V <sub>BS</sub> )V <sub>SW</sub> -0.3 <sup>V</sup>	$V$ to $V_{SW}$ +6 $V$
•	All Other Pins	-0.3V to 6V
•	Junction Temperature	150°C
	Storage Temperature	°C to +150°C
•	Lead Temp (Soldering, 10sec)	260°C
•	Thermal Resistance <sub>JA</sub> (SOP-8)	125°C/W

# **Recommend Operating Conditions (2)**

- Note (1): Stress beyond those listed under "Absolute Maximum Ratings" may damage the device.

Note (2): The device is not guaranteed to function outside the recommended operating conditions.

# **Electrical Characteristics**

The denote specifications which apply over the full operating temperature range, otherwise specifications are

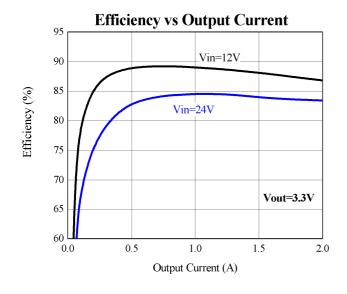
 $T_A$ =+25°C.  $V_{EN}$ =5V,  $V_{IN}$ =12V unless otherwise specified.

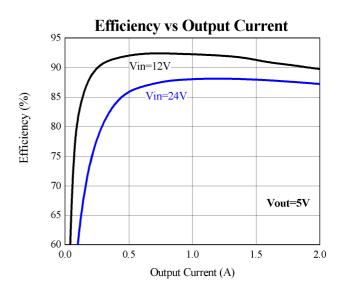
Downworton	Conditions	E	EUP3452A			
Parameter	Conditions	Min.	Typ.	Max.	Unit	
Foodback Voltage	45V/V / 20V	0.784	0.800	0.816	V	
Feedback Voltage	$4.5V \le V_{\rm IN} \le 30V$	0.776	0.800	0.824		
Shutdown Supply Current	V <sub>EN</sub> =0V		1	5	μΑ	
Operating Supply Current	$V_{FB}=1V$		0.45	0.9	mA	
Upper Switch On Resistance			0.135		Ω	
Lower Switch On Resistance			5.6		Ω	
Upper Switch Leakage	$V_{EN}=0V$ , $V_{SW}=0V$			5	μΑ	
Switch Peak Current Limit		2.8	3.6		A	
Oscillator Frequency		250	300	350	KHz	
Short Circuit Frequency	V <sub>FB</sub> =0V		100		KHz	
Maximum Duty Cycle	V <sub>FB</sub> =0.7V		90		%	
Minimum Duty Cycle	$V_{FB}=1V$			0	%	
Enable Threshold		0.62	1.1	1.52	V	
Enable Infeshold		0.36	1.1	1.76		
Enable Lockout Threshold	EN Diging	2.3	2.5	2.8	V	
Enable Lockout Threshold	EN Rising	2	2.5	3		
Enable Lockout Threshold Hysteresis			120		mV	
Input Undervoltage Lockout Threshold	In Rising	3.8	4.1	4.4	V	
Input Overvoltage Lockout Threshold	In Rising		35		V	
Input Overvoltage Lockout Threshold Hysteresis			2		V	
Soft-start Supply Current	V <sub>SS</sub> =0V		6		μΑ	
Enable Leakage Current	V <sub>EN</sub> =0V		0.1	5	μΑ	
Current Sense Transconductance Output Current to Comp Pin Voltage			6		A/V	
Error Amplifier Voltage Gain			400		V/V	
Error Amplifier Transconductance	$\Delta I_C = \pm 10 \mu A$		820		μA/V	
Thermal Shutdown			160		°C	

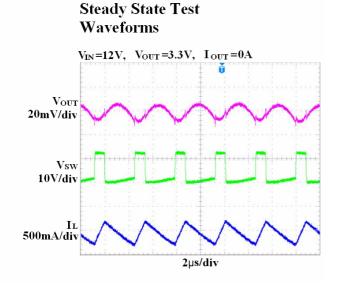


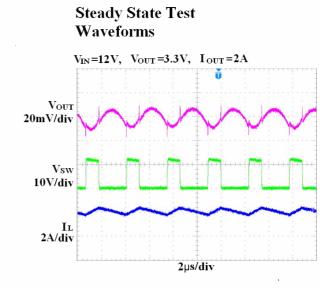
# **Typical Operating Characteristics**

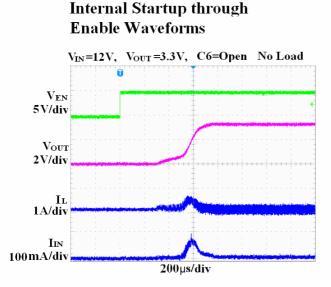
See Figure 1, C1 =  $10\mu$ F, C2= $22\mu$ F, L= $15\mu$ H,  $T_A$ =+25°C.

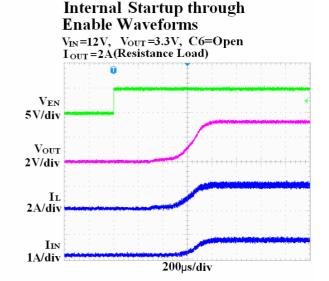










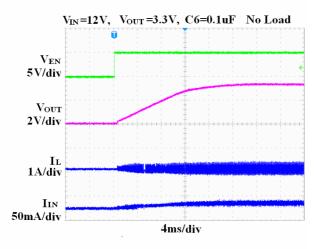


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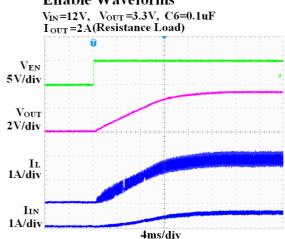
# **Typical Operating Characteristics (continued)**

See Figure 1, C1 =  $10\mu$ F, C2= $22\mu$ F, L= $15\mu$ H,  $T_A$ =+25°C.

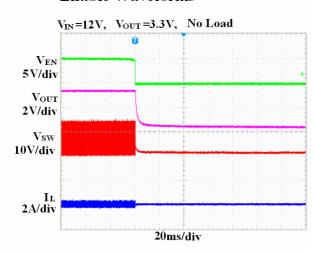
# External Startup through Enable Waveforms



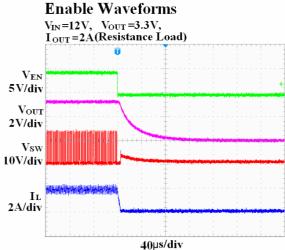
# External Startup through Enable Waveforms



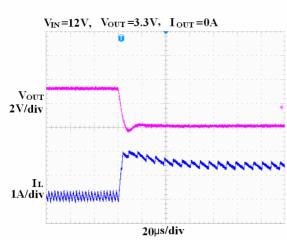
# Shutdown through Enable Waveforms



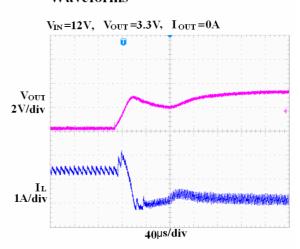
# Shutdown through



# Short Circuit Test Waveforms



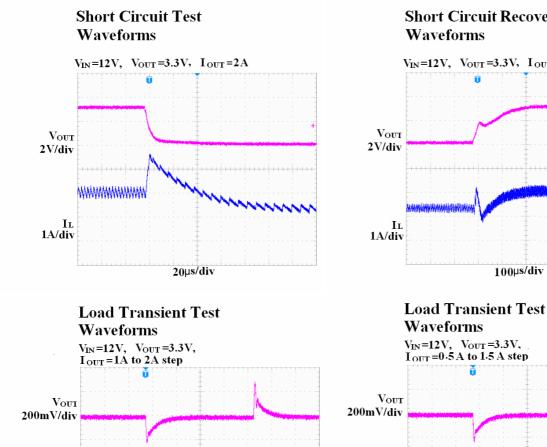
# Short Circuit Recovery Waveforms

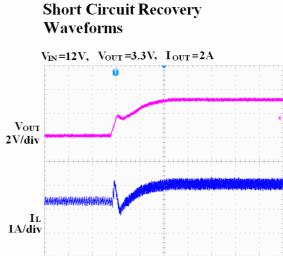




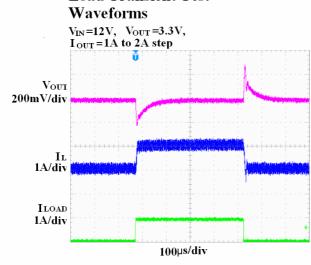
# **Typical Operating Characteristics (continued)**

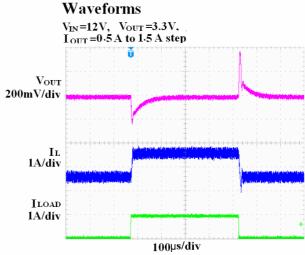
See Figure 1, C1 =  $10\mu$ F, C2= $22\mu$ F, L= $15\mu$ H,  $T_A$ =+25°C.





100µs/div





# **Functional Description**

The EUP3452A is current-mode step-down switching regulator. The device regulates an output voltage as low as 0.8V from a 4.5V to 30V input power supply. The device can provide up to 2Amp continuous current to the output. The EUP3452A uses current-mode architecture to control the regulator loop. The output voltage is measured at FB through a resistive voltage divider and amplified through the internal error amplifier. The output current of the transconductance error amplifier is presented at COMP pin where a RC network compensates the regulator loop. Slope compensation is internally added to eliminate subharmonic oscillation at high duty cycle. The slope compensation adds voltage ramp to the inductor current signal which reduces maximum inductor peak current at high duty cycles.

The device uses an internal Hside n-channel switch to step down the input voltage to the regulated output voltage. Since the Hside n-channel switch requires gate voltage greater than the input voltage, a boostrap BS capacitor is connected between SW and BS to drive the n-channel gate. The BS capacitor is internally charged while the switch is off. An internal  $5.6\Omega$  switch from SW to GND is added to insure that SW is pulled to GND when the switch is off to fully charge the BS capacitor.

# **Application Information**

# **Setting the Output Voltage**

The output voltage is set through a resistive voltage divider (see Figure 1 or 2). The voltage divider divides the output voltage down by the ratio:

$$V_{FB} = V_{OUT} * R3/(R2 + R3) = 0.8V$$

Thus the output voltage is:

$$V_{\rm OUT} = 0.8V*(R2+R3)/R3$$

Choose R3 value in the range 10k to 100k, R2 is determined by :

$$R2 = (V_{OUT} / 0.8 - 1) * R3$$

For example, for a 3.3V output voltage, R3 is  $10K\Omega$ , and R2 is  $31.25K\Omega$ .

### Inductor

The inductor is required to supply constant current to the output load while being driven by the switched input voltage. A larger value inductor results in less ripple current and lower output ripple voltage. However, the larger value inductor has a larger physical size, higher series resistance, and lower saturation current. Choose an inductor that does not saturate under the worst-case load conditions. A good rule for determining the inductance is to allow the peak-to-peak ripple current in the inductor to be approximately 30% of the maximum load current. Also, make sure that the peak inductor current (the load current plus half the peak-to-peak

inductor ripple current) is below the 3.6A minimum peak current limit.

The inductance value can be calculated by the equation:

$$L = (V_{OUT})*(V_{IN} - V_{OUT})/(V_{IN} * f * \Delta I)$$

Where  $V_{OUT}$  is the output voltage,  $V_{IN}$  is the input voltage, f is the switching frequency, and  $\Delta I$  is the peak-to-peak inductor ripple current.

# **Input Capacitor**

The input current to the step-down converter is discontinuous, and therefore an input capacitor C1 is required to supply the AC current to the step-down converter while maintaining the DC input voltage. A low ESR capacitor is required to keep the noise minimum at the IC. Ceramic capacitors are preferred, but tantalum or low-ESR electrolytic capacitors may also suffice. The input capacitor value should be greater than  $10\mu F$ , and the RMS current rating should be greater than approximately 1/2 of the DC load current. In Figure 1 or 2, all ceramic capacitors should be placed close to the EUP3452A.

# **Output Capacitor**

The output capacitor is required to maintain the DC output voltage. Low ESR capacitors are preferred to keep the output voltage ripple low. The characteristics of the output capacitor also affect the stability of the regulator control loop. In the case of ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance. The output voltage ripple is estimated to be:

$$V_{RIPPLE} \sim = 1.4 * V_{IN} * (f_{IC} / f)^2$$

Where  $V_{RIPPLE}$  is the output ripple voltage,  $V_{IN}$  is the input voltage,  $f_{LC}$  is the resonant frequency of the LC filter, f is the switching frequency.

# **Output Rectifier Diode**

The output rectifier diode supplies the current to the inductor when the high-side switch is off. A schottky diode is recommended to reduce losses due to the diode forward voltage and recovery times.

# **Loop Compensation**

The system stability is controlled through the COMP pin. COMP is the output of the internal transconductance error amplifier. A series capacitor-resistor combination sets a pole-zero combination to control the feedback loop.

The DC loop gain is:

$$\mathbf{A}_{\mathrm{VDC}} = \left(\mathbf{V}_{\mathrm{FB}} \, / \, \mathbf{V}_{\mathrm{OUT}}\right) \! * \, \mathbf{A}_{\mathrm{VEA}} \, * \, \mathbf{G}_{\mathrm{CS}} \, * \, \mathbf{R}_{\mathrm{LOAD}}$$

Where:



V<sub>FB</sub> is the feedback threshold voltage, 0.8V

V<sub>OUT</sub> is the desired output regulation voltage

 $A_{VEA}$  is the transconductance error amplifier voltage gain,  $400 \; V/V$ 

 $G_{CS}$  is the current sense gain, (roughly the output current divided by the voltage at COMP), 6A/V

 $R_{LOAD}$  is the load resistance ( $V_{OUT}$  /  $I_{OUT}$  where  $I_{OUT}$  is the output load current)

The system has 2 poles. One is due to the compensation capacitor (C3), and the other is due to the output capacitor (C2). These are:

$$f_{P1} = G_{FA} / (2\pi * A_{VFA} * C3)$$

Where P1 is the first pole, and  $G_{EA}$  is the error amplifier transconductance (820 $\mu$ A/V).

and

$$f_{P2} = 1/(2\pi * R_{LOAD} * C2)$$

The system has one zero of importance, due to the compensation capacitor (C3) and the compensation resistor (R1). The zero is:

$$f_{z_1} = 1/(2\pi * R1 * C3)$$

If a large value capacitor (C2) with relatively high equivalent-series-resistance (ESR) is used, the zero due to the capacitance and ESR of the output capacitor can be compensated by a third pole set by R1 and C4. The pole is:

$$f_{p_3} = 1/(2\pi * R1 * C4)$$

The system crossover frequency (the frequency where the loop gain drops to 1, or 0dB) is important. A good rule of thumb is to set the crossover frequency to approximately 1/10 of the switching frequency. In this case, the switching frequency is 300 KHz, therefore use a crossover frequency,  $f_C$ , of 30 KHz. Lower crossover frequency results in slower loop response and poor load transient performance. Higher crossover frequency can result in loop instability.

Table 1. External components for typical designs

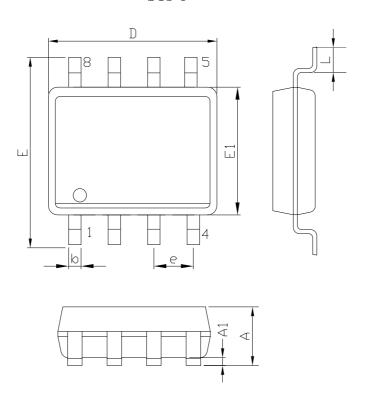
Vin(V)	Vout(V)	L1(μH)	C2(µF)	R2(KΩ)	R1(KΩ)	C3(nF)	C4(pF)
5	1.2	15	22	5	2	10	Open
5	1.8	15	22	12.5	2	10	Open
12	1.8	15	22	12.5	2	10	Open
12	3.3	15	22	31.25	6.8	10	Open
12	5	15	22	52.5	6.8	10	Open
24	3.3	15	22	31.25	2	10	Open
24	5	15	22	52.5	2	10	Open

To simplify design efforts using the EUP3452A, the typical designs for common applications are listed in Table 1.



# **Packaging Information**

SOP-8



SYMBOLS	MILLIMETERS		INCHES		
	MIN.	MAX.	MIN.	MAX.	
A	1.35	1.75	0.053	0.069	
A1	0.10	0.25	0.004	0.010	
D	4.90		0.193		
Е	5.80	6.20	0.228	0.244	
E1	3.90		0.153		
L	0.40	1.27	0.016	0.050	
b	0.31	0.51	0.012	0.020	
e	1.27		0.050		