



**F2962**

Preliminary

**LINEAR INTEGRATED CIRCUIT**

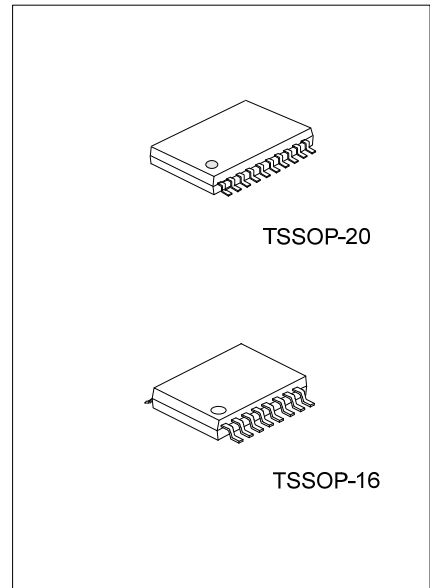
**HIGH EFFICIENT DIRECT PWM DRIVE IC**

■ **DESCRIPTION**

The UTC **F2962** is a high efficient, single phase and bipolar drive direct PWM drive motor driver IC. It is suitable for variable speed control FAN of personal computer's power supply radiation and CPU cooler with over temperature protection.

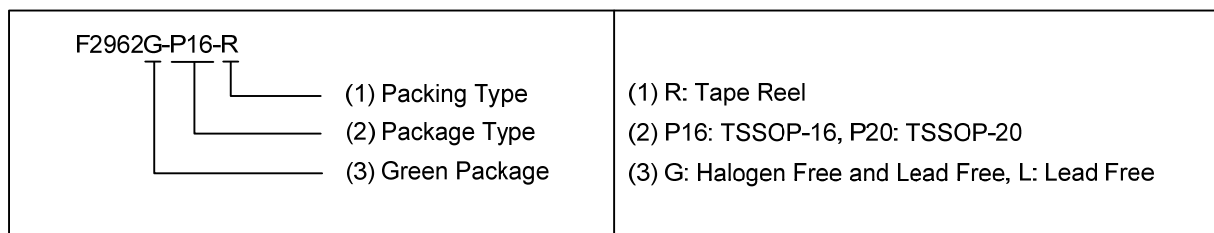
■ **FEATURES**

- \* Single phase bipolar drive(16V,2A output transistor built in.)
- \* Built in variable speed function with thermistor input signal.  
(External excitations direct PWM of upper side transistor control, low noise and low vibration.)
- \* Include re-circulation Diode and external parts are few.
- \* Include Hall bias circuit and thermal shut down circuit.
- \* Minimum speed settable.
- \* Full drive at open thermistor.
- \* Lock protect and auto restart function.
- \* FG output and RD output signal available.

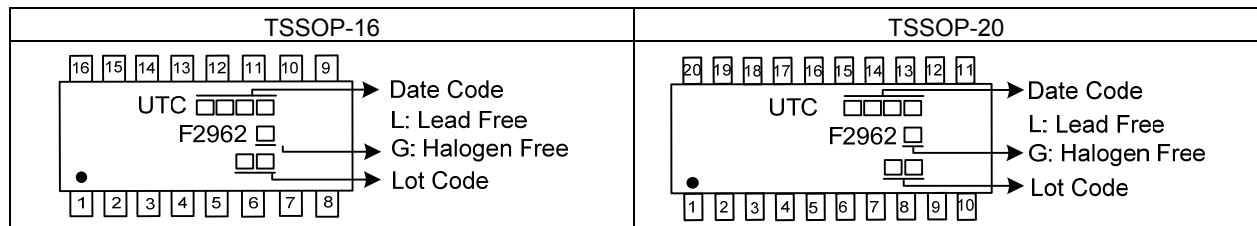


■ **ORDERING INFORMATION**

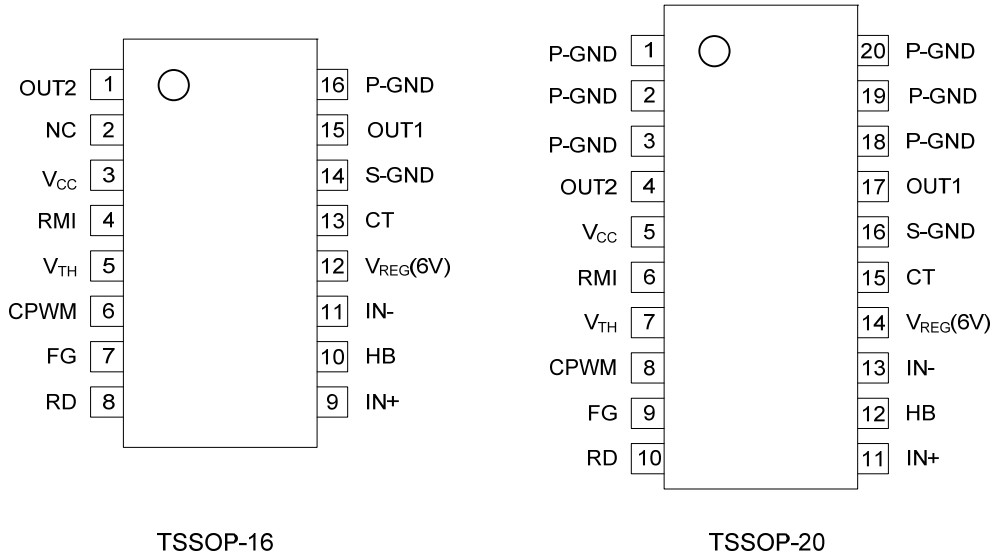
Ordering Number		Package	Packing
Lead Free	Halogen Free		
F2962L-P16-R	F2962G-P16-R	TSSOP-16	Tape Reel
F2962L-P20-R	F2962G-P20-R	TSSOP-20	Tape Reel



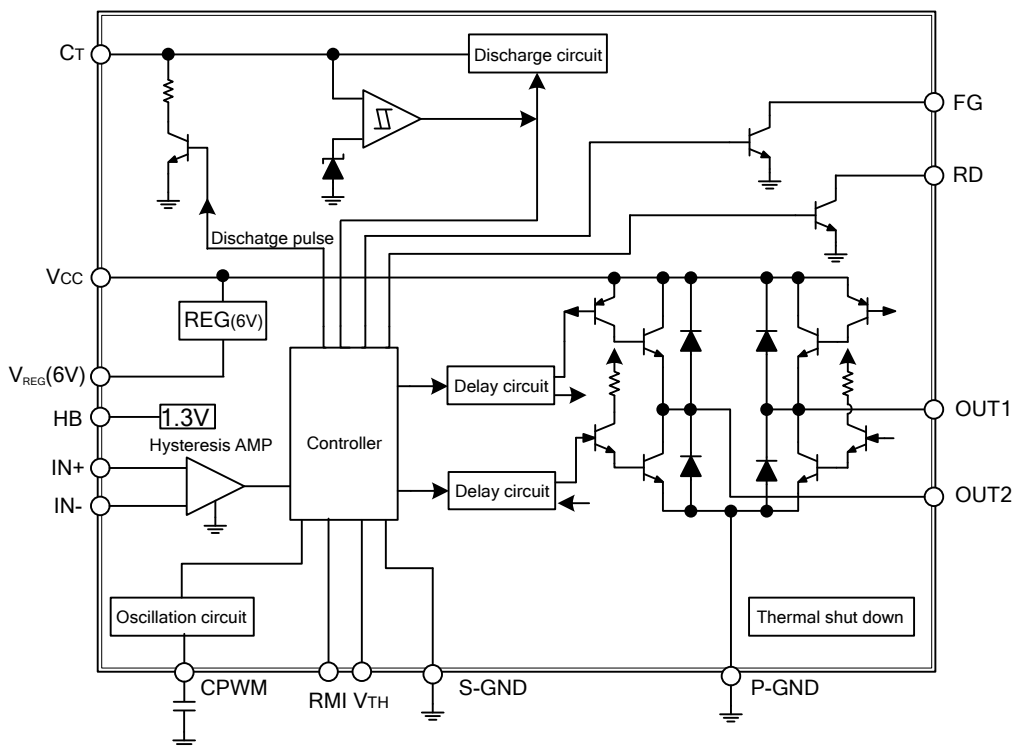
■ **MARKING**



■ PIN CONFIGURATION



■ BLOCK DIAGRAM



### ■ ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	RATINGS	UNIT	
Supply Voltage	$V_{CC}$	18	V	
Output Current	$I_{OUT}$	2	A	
Output Supply Voltage	$V_{OUT}$	18	V	
HB Output Current	$I_{HB}$	10	mA	
$V_{TH}$ Input Voltage	$V_{IH}$	6	V	
RD/FG Output Supply	$V_{RD/FG}$	18	V	
RD/FG Output Current	$I_{RD/FG}$	10	mA	
Allowable Power Dissipation (Note 2)	TSSOP-16	PD	1.1	W
	TSSOP-20		1.15	W
Junction Temperature	$T_J$	+150	°C	
Operating Temperature	$T_{OPR}$	-30 ~ +90	°C	
Storage Temperature	$T_{STG}$	-40 ~ +150	°C	

Note: 1. Absolute maximum ratings are those values beyond which the device could be permanently damaged.

Absolute maximum ratings are stress ratings only and functional device operation is not implied.

2. Mounted on a specified board (114.3mm×76.1mm×1.6mm, Glass epoxy).

### ■ RECOMMENDED OPERATING CONDITION ( $T_A=25^{\circ}\text{C}$ , unless otherwise specified)

PARAMETER	SYMBOL	RATINGS	UNIT
Supply Voltage	$V_{CC}$	4.5 ~ 16	V
V Threshold Input Voltage Range	$V_{TH}$	0 ~ 9	V
Common- mode Hall Input Voltage Range	$V_{ICM}$	0.2 ~ 3	V

### ■ ELECTRICAL CHARACTERISTICS ( $V_{CC}=12\text{V}$ , $T_A=25^{\circ}\text{C}$ , unless otherwise specified)

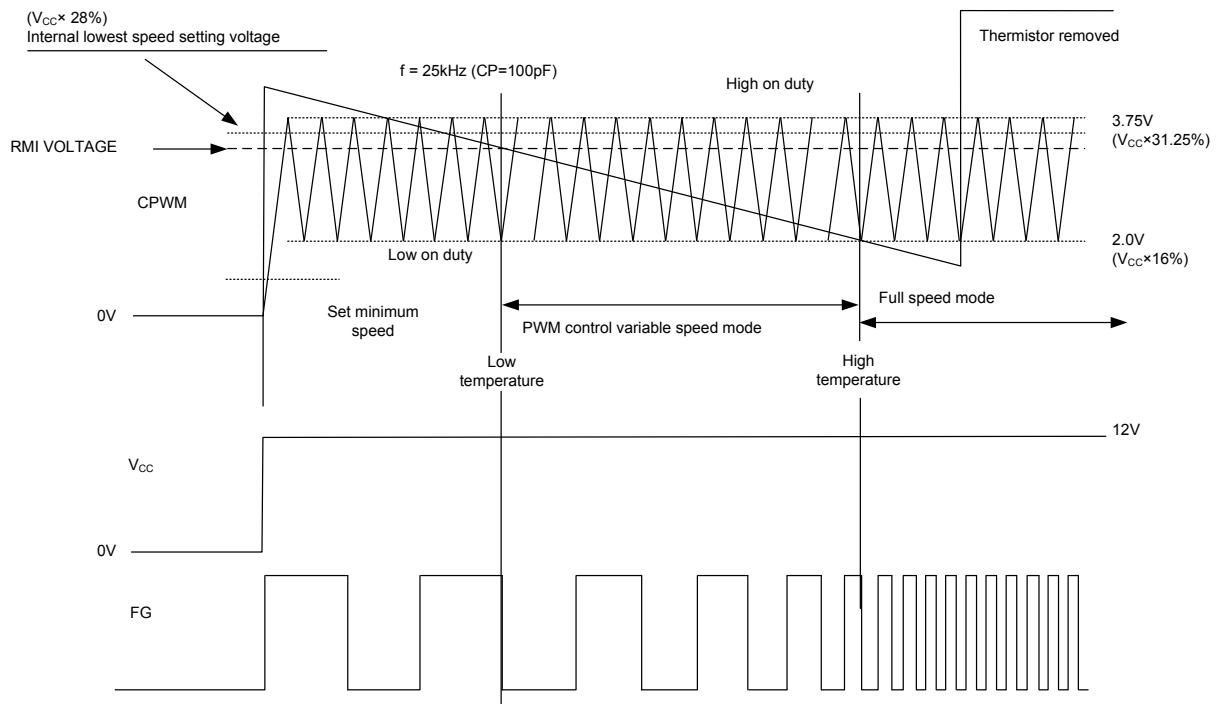
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
Operating Current Drain	$I_{CC1}$	Rotation mode	12	32	40	mA	
	$I_{CC2}$	Lock protect mode	8	11	16	mA	
6V Regulator	$V_{REG(6V)}$	$I_{REG}=5\text{mA}$	5.8	6	6.2	V	
CPWM Voltage	High	$V_{CRH}$	3.5	3.75	4.0	V	
	Low	$V_{CRL}$	1.95	2.0	2.15	V	
CPWM Oscillation Frequency	FPWM	$C=100\text{pF}$	18	25	32	KHz	
$C_T$ pin Voltage	High	$V_{CTH}$	3.4	3.6	3.75	V	
	Low	$V_{CTL}$	1.5	1.6	1.85	V	
$C_T$ Current	Charge	$I_{CT1}$	$V_{CT}=1\text{V}$	1.5	2.2	2.9	$\mu\text{A}$
	Discharge	$I_{CT2}$	$V_{CT}=4.2\text{V}$	0.1	0.2	0.3	$\mu\text{A}$
$C_T$ Charge/Discharge Current Ratio	$R_{CT}$	$R_{CD}=I_{CT1}/I_{CT2}$	8.5	10.0	11.5		
Output Saturation	Lower side	$V_{OL}$	$I_{OUT}=400\text{mA}$	0.2	0.3	V	
	upper side	$V_{OH}$	$I_{OUT}=400\text{mA}$	0.9	1.1	V	
HB Voltage	$V_{HB}$	$I_{HB}=5\text{mA}$	1.1	1.25	1.4	V	
Hall input sensitivity	$V_{HN}$	Zero to peak including offset and hysteresis		15	25	mV	
RD/FG pin Low Voltage	$V_{FG}$	$I_{FG}=5\text{mA}$		0.1	0.3	V	
RD/FG pin Leak Current	$I_{FGL}$	$V_{FG}=7\text{V}$			30	$\mu\text{A}$	

TRUTH TABLE

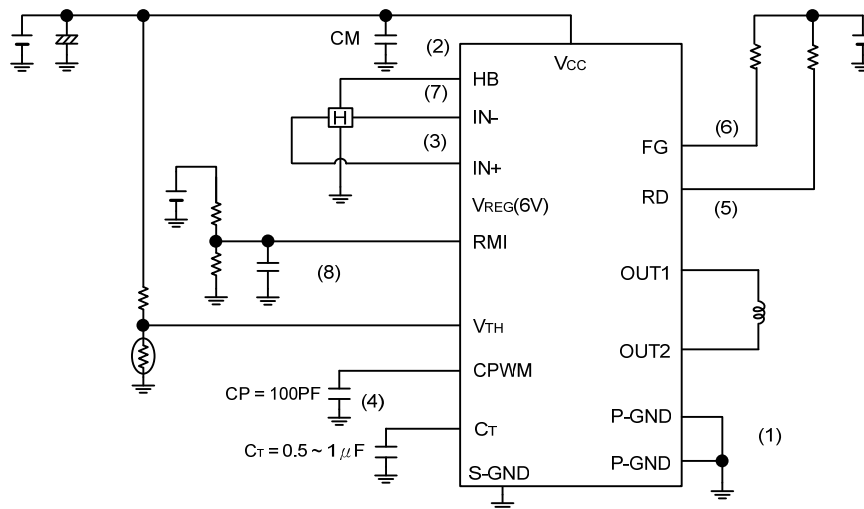
IN-	IN+	CPWM	CT	OUT1	OUT2	FG	RO	MODE
H	L	L	L	H	L	L		ROTATION(DRIVE) PWM OFF
L	H			L	H	OFF		
H	L	H	L	OFF	L	L		ROTATION(RECIRCULATION) PWM OFF
L	H			L	OFF	OFF		
H	L		H	H	OFF	L		ROCK PROTECT
L	H			OFF	H	OFF		

Note: CPWM-H = CPWM > V<sub>TH</sub>, CPWM-L = CPWM < V<sub>TH</sub>

CONTROL TIMING CHART



■ TYPICAL APPLICATION CIRCUIT



(1) **Voltage source-GND line layout**

P-GND is connected to motor supply stage and S-GND is connected to control stage. Divides each line and external parts of control stage are connect to S-GND.

(2) **Capacitor of re-circulation stability**

CM capacitor that is for PWM drive and kick back absorption to be  $0.1 \sim 1\mu\text{F}$  for restrain  $V_{CC}$  rising by kick back voltage. This IC is upper side transistor switching type then re-circulation current through lower side transistor. CM capacitor connects between  $V_{CC}(VM)$  and P-GND with shortest and wide line.

(3) **Hall input**

To be short lines for avoid noise. Hall input amplifier has 20mV hysteresis. Then we recommend the hall input level to be 60mV or over.

(4) **PWM oscillation frequency setting capacitor**

PWM basic frequency becomes 25KHz when put on  $CP=100\text{PF}$ .

(5) **RD output**

Terminal is open corrector output. Low at rotation mode and High at stop mode. Open the terminal at no use.

(6) **FG output**

Output is open corrector. FG output according to rotation speed by phase change. Open the terminal at no use.

(7) **HB pin**

1.25V voltage reference for hall element bias.

(8) **RMI pin**

The pin must be connected to  $V_{TH}$  pin if no use. Lowest speed voltage is settled 10% duty inside.

If you set full speed mode when fan will start, capacitor is required.

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