E500 Series

The cost-effective variable speed control solution for general purpose applications.

- Up to 1 Hp at 115 VAC
- Up to 10 Hp at 240 VAC, 480 and 600 VAC
- Advanced Magnetic Flux Vector Control
- Auto-tuning
- 50°C maximum ambient temperature
- RS-485 serial communication (standard)
- Selectable cooling fan operation mode
- Built-in PID control
- Adjustable carrier frequency (0.7kHz to 14.5kHz)
- Optional keypad interface (FR-PA02-02)

- Compatible with FR-PU04 user interface
- UL & cUL listed / CE marked
- Available configuration software for Windows® 95 / 98
- Open-network communication options
 - □ DeviceNet
 - □ CC-Link
 - ☐ Profibus DP (400V and 600V only)
- Brake Transistor







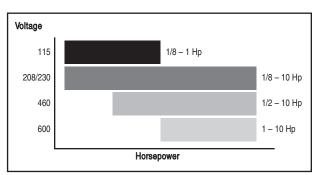


Inverter Type

FR-E520 - 0.1 K - NA

Symbol	Voltage Class
E510W	Single-phase 100V class
E520	Three-phase 200V class
E540	Three-phase 400V class
E560	Three-phase 600V class





E500 Selection

	Rating (CT & VT)		IP20 Open Chassis		Dime	nsions		
I	Нр		tput it Amps	Model Number	Height mm (in)	Width mm (in)	Depth mm (in)	Weight kg (lbs)	Stocked Item
				1-Phase 100 – 1	15 VAC Input / 3-Phase	230 VAC Output			
1	1/8	0	.8	FR-E510W-0.1K-NA	128 (5.0)	68 (2.7)	76 (3.0)	0.6 (1.4)	_
1	1/4	1	.5	FR-E510W-0.2K-NA	128 (5.0)	68 (2.7)	106 (4.2)	0.6 (1.4)	S
1	1/2	3	.0	FR-E510W-0.4K-NA	128 (5.0)	68 (2.7)	138 (5.5)	1.0 (2.2)	S
1	1.0	5	.0	FR-E510W-0.75K-NA	128 (5.0)	108 (4.3)	155 (6.1)	1.7 (3.8)	S
				200 – 240 VAC	Input / 3-Phase 200 – 2	240 VAC Output			
3-P	hase	1-P	hase	Madel Number	Height	Width	Depth	Weight	Oto also d litera
Нр	amp	Нр	amp	Model Number	mm (in)	mm (in)	mm (in)	kg (lbs)	Stocked Item
1/8	0.8	_	_	FR-E520-0.1K-NA	128 (5.0)	68 (2.7)	76 (3.0)	0.6 (1.4)	S
1/4	1.5	_	_	FR-E520-0.2K-NA	128 (5.0)	68 (2.7)	76 (3.0)	0.6 (1.4)	S
1/2	3	1/4	1.5	FR-E520-0.4K-NA	128 (5.0)	68 (2.7)	108 (4.3)	0.8 (1.8)	S
1.0	5	1/2	2.5	FR-E520-0.75K-NA	128 (5.0)	68 (2.7)	128 (5.0)	1.0 (2.2)	S
2.0	8	3/4	4	FR-E520-1.5K-NA	128 (5.0)	108 (4.3)	131 (5.2)	1.7 (3.8)	S
3.0	11	1.0	5	FR-E520-2.2K-NA	128 (5.0)	108 (4.3)	131 (5.2)	1.7 (3.8)	S
5.0	17.5	2.0	7	FR-E520-3.7K-NA	128 (5.0)	170 (6.7)	138 (5.5)	2.2 (4.9)	S
7.5	24	_	_	FR-E520-5.5K-NA	260 (10.2)	180 (7.1)	170 (6.7)	4.4 (9.7)	S
10.0	33	_	_	FR-E520-7.5K-NA	260 (10.2)	180 (7.1)	170 (6.7)	4.9 (10.8)	-
				3-Phase	380 – 480 VAC Input	Output			
1	1/2	1	.6	FR-E540-0.4K-NA	150 (5.9)	140 (5.5)	116 (4.6)	1.9 (4.2)	S
1	1.0	2	.6	FR-E540-0.75K-NA	150 (5.9)	140 (5.5)	116 (4.6)	1.9 (4.2)	S
2	2.0		4	FR-E540-1.5K-NA	150 (5.9)	140 (5.5)	136 (5.4)	2.0 (4.4)	S
3	3.0		6	FR-E540-2.2K-NA	150 (5.9)	140 (5.5)	136 (5.4)	2.1 (4.7)	S
5	5.0	9	.5	FR-E540-3.7K-NA	150 (5.9)	140 (5.5)	136 (5.4)	2.1 (4.7)	S
7	7.5		2	FR-E540-5.5K-NA	150 (5.9)	220 (8.7)	148 (5.8)	3.8 (8.4)	S
1	0.0	1	7	FR-E540-7.5K-NA	150 (5.9)	220 (8.7)	148 (5.8)	3.8 (8.4)	S
				3-Phase	575 – 600 VAC Input	Output /			
1	1.0	1	.7	FR-E560-0.75K-NA	150 (5.9)	140 (5.5)	136 (5.4)	1.8 (4.0)	S
2	2.0	2	.7	FR-E560-1.5K-NA	150 (5.9)	140 (5.5)	136 (5.4)	2.0 (4.7)	S
	3.0		.0	FR-E560-2.2K-NA	150 (5.9)	140 (5.5)	136 (5.4)	2.0 (4.7)	S
5	5.0	6	.1	FR-E560-3.7K-NA	150 (5.9)	220 (8.7)	148 (5.8)	3.8 (8.4)	S
	7.5		.0	FR-E560-5.5K-NA	150 (5.9)	220 (8.7)	148 (5.8)	3.8 (8.4)	S
1	0.0	1	2	FR-E560-7.5K-NA	150 (5.9)	220 (8.7)	148 (5.8)	3.8 (8.4)	S

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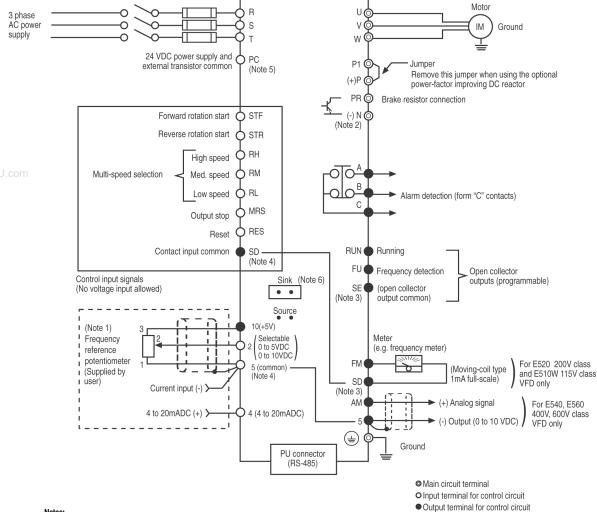
E500 General Specifications

Control Method Soft-PWM control / high carrier frequency PWM control can be selected. V / F control or general-purpose magnetic flux vector control can be selected. Output Frequency Range Frequency Control Analog Input Digital Input Dig	
Frequency Control Analog Input Digital Inpu	
Frequency Control Analog Input Digital Inpu	
Prequency Control Digital Input 0.01Hz (less than 100Hz), 0.1Hz (100Hz or more) when digital setting is made using the control panel.	
Digital Input Within 0.01% of set output frequency when setting is made from control panel. Voltage / Frequency Characteristics Base frequency set as required between 0 and 400Hz. Constant torque or variable torque pattern can be selected. 150% or more (at 1Hz), 200% or more (at 3Hz) when general-purpose magnetic flux vector control or slip compensation is selected. Torque Boost Acceleration / Deceleration Time Setting 0.01, 0.1 to 3600 sec. (accel. and decel. can be set individually), linear or S-pattern accel./decel. mode can be selected Braking Torque Regenerative DC Dynamic Brake Operation frequency (0 to 120Hz), operation time (0 to 10 s), operation voltage (0 to 30%) variable. Stall Prevention Operation Level Operation level is fixed, presence or absence can be selected. Operation level is fixed, presence or absence can be selected. Operation level is fixed, presence or absence can be selected.	
Voltage / Frequency Characteristics Base frequency set as required between 0 and 400Hz. Constant torque or variable torque pattern can be selected. 150% or more (at 1Hz), 200% or more (at 3Hz) when general-purpose magnetic flux vector control or slip compensation is selected. Torque Boost Acceleration / Deceleration Time Setting 0.01, 0.1 to 3600 sec. (accel. and decel. can be set individually), linear or S-pattern accel./decel. mode can be selected Braking Torque Regenerative 0.1K, 0.2K150% or more, 0.4K, 0.75K 00% or more, 1.5K50% or more, 2.2K, 3.7K, 5.5K, 7.5K 20% or more (*1) DC Dynamic Brake Operation frequency (0 to 120Hz), operation time (0 to 10 s), operation voltage (0 to 30%) variable. Stall Prevention Operation Level Voltage Stall Prevention Operation Level Operation level is fixed, presence or absence can be selected. Operation level is fixed, presence or absence can be selected.	
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DC Dynamic Brake Operation frequency (0 to 120Hz), operation time (0 to 10 s), operation voltage (0 to 30%) variable. Stall Prevention Operation Level Operation current level can be set (0 to 200% variable), presence or absence can be selected. Voltage Stall Prevention Operation Level Operation level is fixed, presence or absence can be selected. Fast-Response Current Limit Level Operation level is fixed, presence or absence can be selected.	
Voltage Stall Prevention Operation Level Operation level is fixed, presence or absence can be selected. Fast-Response Current Limit Level Operation level is fixed, presence or absence can be selected.	
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A. J. J. J. J. J. S. J. S. J.	
Frequency Setting Analog Input 0 to 5 VDC, 0 to 10 VDC, 4 to 20mADC.	
Signal Digital Input Entered from control panel (FR-PA02-02).	
Starting Signal Forward and reverse rotation, start signal automatic self-holding input (3-wire input) can be selected.	
Alarm Reset Used to reset alarm output provided when protective function is activated.	
Multi-Speed Selection Up to 15 speeds can be selected. (Each speed can be set between 0 and 400Hz, running speed can be	
changed during operation from the control panel.)	
Second Function Selection Used to select second functions (accel. time, decel. time, torque boost, freq., electronic overcurrent protection).	
Output Stop Instantaneous shut-off of inverter output (frequency, voltage).	
ent Input Selection Used to select input of frequency setting signal 4 to 20mADC (terminal 4).	
Signal Automatic Used to select start signal automatic self-holding input. (3-wire input)	
Self-Holding Selection External Thermal Relay Input Thermal relay contact input for use when the inverter is stopped by the external thermal relay.	Use Pr. 180 to Pr. 183 for selection.
PU Operation-External Operation Switching Used to switch between PU operation and external operation from outside the inverter.	0 P
V/F-General-Purpose Magnetic Used to switch between V/F control and general-purpose magnetic flux vector	80 t
Flux Switching from outside the inverter.	<u>-</u>
Maximum/minimum frequency setting, frequency jump operation, external thermal relay input selection,	l e
Operation Functions automatic restart operation after instantaneous power failure, forward/reverse rotation prevention, slip	s
comp., operation mode selection, off-line auto tuning function, PID control, computer link operation (RS-485).	
2 open collector output signals can be selected from inverter running, up to frequency, frequency	
Operation Status detection, overload alarm, zero current detection, output current detection, PID upper limit, PID lower limit,	
PID forward/reverse rotation, operation ready, minor fault and alarm, and 1 contact output (230 VAC 0.3A,	
Operation Status detection, overload alarm, zero current detection, output current detection, PID upper limit, PID lower limit, PID forward/reverse rotation, operation ready, minor fault and alarm, and 1 contact output (230 VAC 0.3A, 30 VDC 0.3A) can be selected. To support the support of	
FOI Meter	
Pulse train output (1440 pulses/second/full scale).	
Control Panel Operating Status Output voltage, output current, set frequency, running.	
Display Alarm Definition Alarm definition is displayed when protective function is activated. 4 alarm definitions are stored. Power application /POWER)	
Total application (Correctly)	
Overcurrent shut-off (during acceleration, deceleration, constant speed), regenerative overvoltage shut-off,	
Protective And Warning Functions undervoltage (*2), instantaneous power failure (*2), overload shut-off (electronic overcurrent protection),	
brake transistor alarm, output short circuit, stall prevention, brake resistor overheat protection, fan overheat,	
Low Letters (* A) and an artist of the control of t	
fan failure (*4), parameter error, PU disconnection, ground fault protection.	
Ambient Temperature Constant torque: -10°C to +50°C (non-freezing) 14°F to 122°F	
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Ambient Temperature Constant torque: -10°C to +50°C (non-freezing) 14°F to 122°F Ambient Humidity 90%RH or less (non-condensing) Storage Temperature (*3) -20°C to +65°C / -4°F to 149°F Atmosphere Indoors, no corrosive and flammable gases, oil mist, dust and dirt. Maximum 1000m (3300 ft.) above sea level for standard operation. After that derate by 3% for every extra	
Ambient Temperature Constant torque: -10°C to +50°C (non-freezing) 14°F to 122°F Ambient Humidity 90%RH or less (non-condensing)	

Notes:

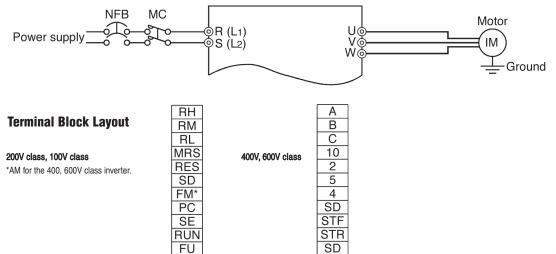
- 1. The braking torque indicated is a short-duration average torque (which varies with motor loss) when the motor alone is decelerated from 60Hz in the shortest time and is not a continuous regenerative torque. When the motor is decelerated from the frequency higher than the base frequency, the average deceleration torque will reduce. Since the inverter does not contain a brake resistor, use the optional brake resistor when regenerative energy is large. (The optional brake resistor cannot be used with 0.1K and 0.2K.) A brake unit (BU) may also be used.
- 2. When undervoltage or instantaneous power failure has occurred, alarm display or alarm output is not provided but the inverter itself is protected. Overcurrent, regenerative overvoltage or other protection may be activated at power restoration according to the operating status (load size, etc.).
- 3. Temperature applicable for a short period in transit, etc.
- $\textbf{4.} \quad \text{Not provided for the FR-E520-0.1K to 0.4K and FR-E510W-0.1K to 0.75K which are not equipped with a cooling fan.} \\$

E500 Series Terminal Connection Diagram



- Notes:
- 1. Use 0.5W, $1k\Omega$ potentiometer. For heavier duty applications, use a 2W, $1k\Omega$ potentiometer.
- 2. 0.1kW and 0.2kW rated models do not contain braking transistor.
- 3. Terminals SD and SE are electrically isolated.
- Terminals SD and 5 are not electrically isolated. Do not connect them to each other or to ground.
- To avoid damage to the VFD, do not allow a short circuit between terminals PC and SD.

Single-phase 100V power input / three-phase 200V power output



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E500 Series Options

Model Number	Description	Notes	Stocked Item
FR-PA02-02	Keypad for E500 VFD	For mounting on E500 VFD	S
FR-E5P	Keypad Panel Mounting Adapter	For use only on FR-PA02-02 and FR-CB20x	S
FR-DU04	LED Parameter Unit	Also used with A500(L).	-
FR-PU04	LCD Parameter Unit	Also used with A500(L).	S
FR-E5ND	E540, E560 DeviceNet Interface	Plug-in Option. Not for use with E520 or E510W.	S
FR-E5NP	E540, E560 Profibus DP Interface	Plug-in Option. Not for use with E520 or E510W.	S
FR-E5NC	E540, E560 CC-Link Interface	Plug-in Option. Not for use with E520 or E510W.	S
FR-E5NL	E540, E560 LonWorks Interface	Plug-in Option. Not for use with E520 or E510W.	-
FR-E520-□□KND	E520 with Built-In DeviceNet Interface	Same ratings as -NA version. Deeper by 19.6 mm than -NA.	_
FR-E520-□□KN	E520 with Built-In CC-Link Interface	Same ratings as -NA version. Deeper by 19.6 mm than -NA.	_
FR-CB201	Remote cable	1m cable	S
FR-CB203	Remote Cable	3m cable	S
FR-CB205	Remote Cable	5m cable	S
IB(NA)66866	FR-E520/E540/E510W Instruction Manual		-
IB(NA)66864	FR-E520-KN CC-Link Instruction Manual		_
SH(NA)3193	FR-A500 / E500 Technical Manual		-
IB(NA)0600003	FR-E5NC, CC-Link Instruction Manual		-
IB(NA)0600006	FR-E5ND, DeviceNet Instruction Manual		_
IB(NA)0600007	FR-E5NP, Profibus Instruction Manual		_
IB(NA)0600008	FR-E520-KND, DeviceNet Instruction Manual		-
IB(NA)0600204	FR-E560 Instruction Manual	Only available for download.	-
FR-CONFIGURATOR	Programming and Diagnostic Software		S
SC-FRPC	Serial Communication Cable		S

Note: \square \square represents drive kW rating

Dynamic Braking

All Mitsubishi Electric VFD's have some inherent braking capability. During controlled deceleration, motor regenerative losses are dissipated in the motor, wire, and VFD circuitry. The built-in DC injection braking allows for low speed braking and stopping.

When the above capabilities are inadequate for an application, it is necessary to add a power transistor brake unit and resistor unit in series across the DC bus. Motor regeneration causes the DC bus voltage to increase, and when the voltage exceeds a specified threshold, the transistor turns on to pass current through the resistor. Motor kinetic energy is converted to heat energy. VFD overcurrent and overvoltage protective circuits are active at all times, and will fault-trip the VFD if the brake size is inadequate.

Two main factors must be considered when sizing the brake, the effective duty cycle (%ED) and the short time duty rating. The effective duty cycle is increased when an external resistor is added. It is preferable to profile the effective duty cycle of the units of time. With this information, the short time duty is known and the %ED can be calculated, as shown in the below example.

%ED = Braking time / total time for complete operating cycle *100

Example: Complete cycle is:

5 sec: Acceleration time to reach set speed

60 sec: Run time at set speed

3 sec: Deceleration time to come to a complete stop

12 sec: Time period motor remains stopped

%ED = 3 / (5 + 60 + 3 + 12) * 100 = 3.6%

The tables shown assume 100% brake torque, when brake torque is represented by its percentage to the rated torque of the applied motor.

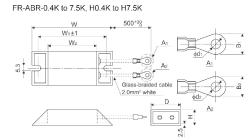
Torque (kg.m) = 974 * Power (kW) / Speed (rpm).

	Dynamic Braking Unit for 230 VAC • Braking Torque = 100%										
Braking Unit	Weight	Resistor Kit	Stocked	Weight	Resistance	Rated	Motor		Drive	Model	
Model No. (*3)	kg / lbs	Model No. (*3)	Item	kg / lbs	(Ohms)	(W)	(Hp)	E520	% ED	E510W	%ED
	FR-ABR-0.4K-UL	S	0.2 / 0.5	200	80	0.5	0.4K	10%	0.4K	10%	
		FR-ABR-0.75K-UL	S	0.4 / 0.9	100	150	1	0.75K	10%	0.75K	10%
Not Necessary	N/A	FR-ABR-2.2K-UL	S	0.5 / 1.1	60	250	3	1.5K - 2.2K	10%		
(*1)	19/73	FR-ABR-3.7K-UL	S	0.8 / 1.8	40	300	5	3.7K	10%		
		FR-ABR-5.5K-UL	S	1.3 / 2.9	25	500	7.5	5.5K	10%		
		FR-ABR-7.5K-UL	S	2.2 / 4.9	20	800	10	7.5K	10%		. DataCh

See notes next page.

E500 Dynamic Braking

_	Dynamic Braking Unit for 460-480 VAC • Braking torque = 100%								
Braking Unit Model	Weight kg /	Hesistor Kit	Stocked	Weight	Resistance	Rated	Motor		Model
	lbs	Model No. (*2)	Item	kg / lbs	(Ohms)	(W)	(Hp)	E540	% ED
	FR-ABR-H	FR-ABR-H0.4K-UL	S	0.2 / 0.5	1200	60	0.5	0.4K	10%
		FR-ABR-H0.75K-UL	S	0.2 / 0.5	700	80	1	0.75K	10%
Not		FR-ABR-H1.5K-UL	S	0.4 / 0.9	350	150	2	1.5K	10%
Necessary	N/A	FR-ABR-H2.2K-UL	S	0.5 / 1.1	250	250	3	2.2K	10%
(*1)		FR-ABR-H3.7K-UL	S	0.8 / 1.8	150	300	5	3.7K	10%
		FR-ABR-H5.5K-UL	S	1.3 / 2.9	110	500	7.5	5.5K	10%
		FR-ABR-H7.5K-UL	S	2.2 / 4.9	75	800	10	7.5K	10%



- 1. The FR-A520-0.4K to 7.5K and FR-V520 1.5K to 15K have a built-in braking transistor.
- . Optional brake resistor is only available for FR-E520-0.4K-NA and higher. DataSheet4U. Products are UL listed.

Input Radio Noise Filter

This filter is connected to the input of the drive and helps to reduce radiated noise in the radio frequencies.

Drive	Kit Model	Leakage	Dir	nensions mm	` '	
Voltage	Number	Current (mA)	L	w	D	Stocked Item
208 – 230	FR-BIF	4	58 (2.3)	44 (1.8)	42 (1.7)	S
460	FR-BIF-H	4	58 (2.3)	44 (1.8)	42 (1.7)	-

Line Noise Filter

Provides a toroid for line noise reduction.

Drive Hn	rive Hp Kit Model		Dimensions mm (in)				
Dilverip	Number	L	W	D	Item		
0.5 – 5	FR-BSF01	110 (4.33)	22.5 (0.89)	65 (2.56)	S		
0.5 – 75	FR-BLF	180 (7.07)	31.5 (1.24)	83 (3.27)	S		

DIN Rail Mounting Attachment

This attachment allows the E500 Series inverter to mount on a 35mm DIN rail.

Model Number	Drive	Stocked Item	
Woder Number	E510W	E520	Stocked item
FR-UDA01	0.1K – 0.4K	0.1K – 0.75K	S
FR-UDA02	0.75K	1.5K – 2.2K	S
FR-UDA03	_	3.7K	-

Installation Interchange AttachmentThis attachment allows the E500 Series inverter to be mounted using the installation holes from the previous series VFDs.

Model Number	Installation Model		Previous Model		Stocked Item
Model Number	E500 Series	A0x4 Series	Z024 Series	A200E Series	Stocked item
	FR-E520-0.1K-NA	FR-A024-0.1K-UL	FR-Z024-0.1K-UL	_	
FR-E5T-10	FR-E520-0.2K-NA	FR-A024-0.2K-UL	FR-Z024-0.2K-UL	_	S
111-231-10	FR-E520-0.4K-NA	FR-A024-0.4K-UL	FR-Z024-0.4K-UL	_	5
	FR-E520-0.75K-NA	FR-A024-0.75K-UL	_	_	
FR-E5T-11	FR-E520-0.75K-NA	_	FR-Z024-0.75K-UL	_	
rn-E31-11	FR-E520-1.5K-NA	FR-A024-1.5K-UL	FR-Z024-1.5K-UL	_	_
FR-E5T	FR-E520-2.2K-NA	FR-A024-2.2K-UL	FR-Z024-2.2K-UL	_	
rn-E01	FR-E520-3.7K-NA	FR-A024-3.7K-UL	FR-Z024-3.7K-UL	_	_
FR-E5T-02	FR-E520-5.5K-NA	_	_	FR-A220E-5.5K-UL	
FR-E31-02	FR-E520-7.5K-NA	_	_	FR-A220E-7.5K-UL	_
Direct Attachment	FR-E540-0.4K-NA	FR-A044-0.4K-UL	_	_	
Direct Attachinent	FR-E540-0.75K-NA	FR-A044-0.75K-UL	_	_	_
	FR-E540-1.5K-NA	FR-A044-1.5K-UL	_	_	
FR-E5T-14	FR-E540-2.2K-NA	FR-A044-2.2K-UL	_	_	-
	FR-E540-3.7K-NA	FR-A044-3.7K-UL	_	_	

E500 Installation Interchange Attachment

This attachment allows the E500 Series inverter to be mounted at a 90° angle so that the depth is reduced to 80 mm.

Madel Number	Installation Model	Previous Model		
Model Number	E500 Series	A0x4 Series	Z024 Series	Stocked Item
	FR-E520-0.4K-NA	FR-A024-0.4K-UL	FR-Z024-0.4K-UL	_
FR-E5T-L	FR-E520-0.75K-NA	FR-A024-0.75K-UL	_	_

E500 Series Watt Loss and Efficiency Data

HP-CT	240VA	C 3-Phase Input or 1-	Phase Input			480VAC 3-Phase In	put	
mr-CI	Model Number	Rated Watts	Watts Loss	Efficiency	Model Number	Rated Watts	Watts Loss	Efficiency
1/8	FR-E520-0.1K-NA	100	16	84%	_	_	_	_
et4U.com	FR-E520-0.2K-NA	200	20	90%	_	_	_	_
1/20	FR-E520-0.4K-NA	400	45	89%	FR-E540-0.4K-NA	400	45	89%
1	FR-E520-0.75K-NA	750	50	93%	FR-E540-0.75K-NA	750	50	93%
2	FR-E520-1.5K-NA	1500	85	94%	FR-E540-1.5K-NA	1500	85	94%
3	FR-E520-2.2K-NA	2200	100	95%	FR-E540-4.4K-NA	2200	100	95%
5	FR-E520-3.7K-NA	3700	160	96%	FR-E540-3.7K-NA	3700	160	96%
7.5	FR-E520-5.5K-NA	5500	310	94%	FR-E540-5.5K-NA	5500	310	94%
10	FR-E520-7.5K-NA	7500	420	94%	FR-E540-7.5K-NA	7500	420	94%

General Notes:

- The amount of heat generated by the inverter is based on one inverter connected to one motor of the same capacity.
 The amount of heat generated in the above table is the amount of heat generated when the inverter is operated at it's rated current.
 The amount of heat generated will decrease according to the motor load and usage (duty).

E540 EMC Filters

This attachment allows the VFD to be mounted onto the filter.

Model Number	Installation Mode	Stocked Item
FFR-E540-4.5A-SF1	FR-E540-0.4K – 0.75K	S
FFR-E540-15A-SF1	FR-E540-1.5K – 3.7K	-
FFR-E540-27A-SF1	FR-E540-5.5K - 7.5K	-