

1.REVISION RECORD

DATE	VERSION	REVISION ITEMS	PAGE	DESING BY
2014-05-20	1.0	Preliminary	----	CZH
2014-06-10	2.0	Modify display mode	5	CZH

ote : The Product and specifications are subject to change without any notice.

Please ask for the latest Product Standards to guarantee the satisfaction of our product requirements.

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3. PRODUCT INFORMATION

3.1. Description

FY07024DI26A30-D is a color active matrix LCD module incorporating amorphous silicon TFT (Thin Film Transistor). It is composed of a color TFT-LCD panel, driver ICs, FPC and a backlight unit. The 7.0' display area contains 1024 (RGB) x 600 pixels

3.2. Applications

- UMPC**
- Portable DVD**
- GPS**
- MID**

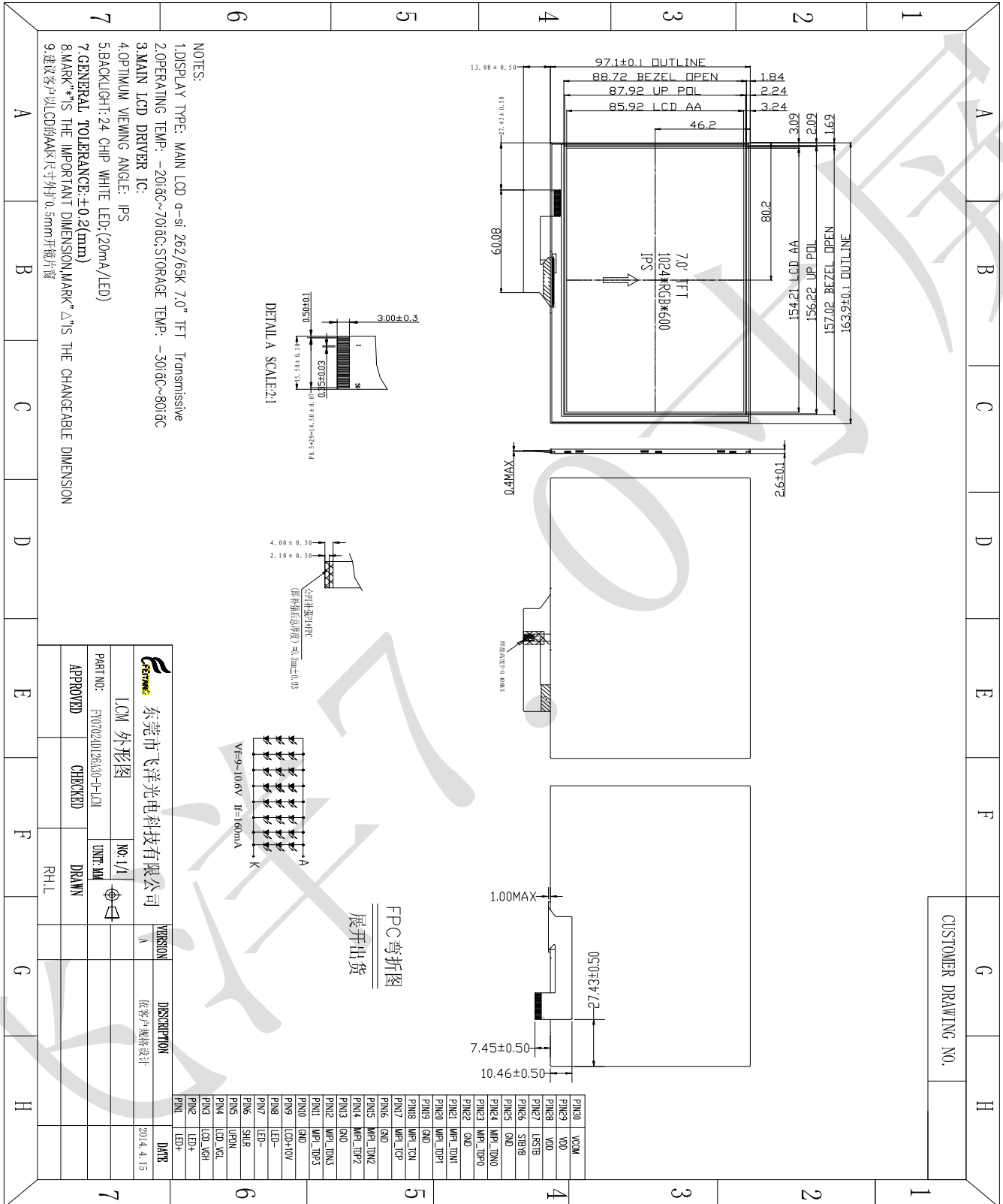
3.3. Features

- High Resolution:1024(RGB) x 600 Dots**
- adopting a high aperture ratio**
- 24 chip LED backlight**
- Dot-Inversion**

4. General Specifications

NO.	ITEM	SPECIFICATION	UNIT	REMARK
1	LCD size	7.0 (Diagonal)	inch	
2	Driver Method	a-si TFT active matrix	-	
3	Resolution	1024 × 3(RGB) × 600	dots	
4	Display mode	FFS Normally black	-	
5	Dot pitch	0.1506(H) × 0.1432(V)	mm	
6	Active area	154.21(H) × 85.92(V)	mm	
7	Panel size	163.9 (H) × 97.1(V) × 2.6(T)	mm	
8	Color Pixel	RGB vertical stripe	-	
9	Surface treatment	Glare type	-	
10	View Direction	ALL	o'clock	
11	Interface	MIPI	-	

5. Mechanical drawing



6. ABSOLUTE MAXIMUM RATINGS

The following are maximum values which, if exceeded, may cause faulty operation or damage to the unit.

Item	Symbol	Min.	Max.	Unit	Note
Digital Supply Voltage	DVDD	-0.3	3.96	V	-
Analog Supply Voltage	AVDD	-0.5	14.85	V	-
Gate On Voltage	VGH	-0.3	40	V	-
Gate Off Voltage	VGL	-20	0.3	V	-
Gate On-Gate Off Voltage	VGH-VGL	12	40	V	-
Operating Temperature	Topa	-20	70	°C	Note1
Storage Temperature	Tstg	-30	80	°C	Note1

Note1 : If users use the product out off the environmental operation range (temperature and humidity,it will have visual quality concerns.

7.ELECTRICAL CHARACTERISTICS

7.1 Typical operation conditions

ITEM	SYMBOL	MIN.	TYP.	MAX.	UNIT	NOTE
Digital supply voltage	DVDD	1.79	1.8	1.89	V	
Analog supply voltage	AVDD	9.4	9.6	9.8	V	
Gate on voltage	VGH	17	18	19	V	
Gate off voltage	VGL	-6.6	-6	-5.4	V	
Common voltage	VCOM	2.85	--	3.45	V	
Logic input voltage	VIH	0.7*DVDD	-	DVDD	V	NOTE1
	VIL	GND	-	0.3*DVDD	V	

[note1] please adjust VCOM to make the flicker lever be minimum

7.2 Current consumption

Current consumption

TEM	SYMBOL	CONDITION	MIN	TYPE	MAX	UNIT	NOTE
Gate on Power Current	IVGH	VGH =18V	--	0.7	1.5	mA	Note1
Gate off Power Current	IVGL	VGL= -6V	--	0.7	1.5	mA	Note1
Digital Power Current	IDVDD	DVDD =1.8V	--	65	70	mA	Note1
Analog Power Current	IAVDD	AVDD = 9.6V		40	50	mA	Note1
Total Power Consumption	PC		--	674	822	mW	Note1

Note1: Typ. specification: Gray-level test Pattern

Max. specification: Black test Pattern



(a) Gray-level Pattern

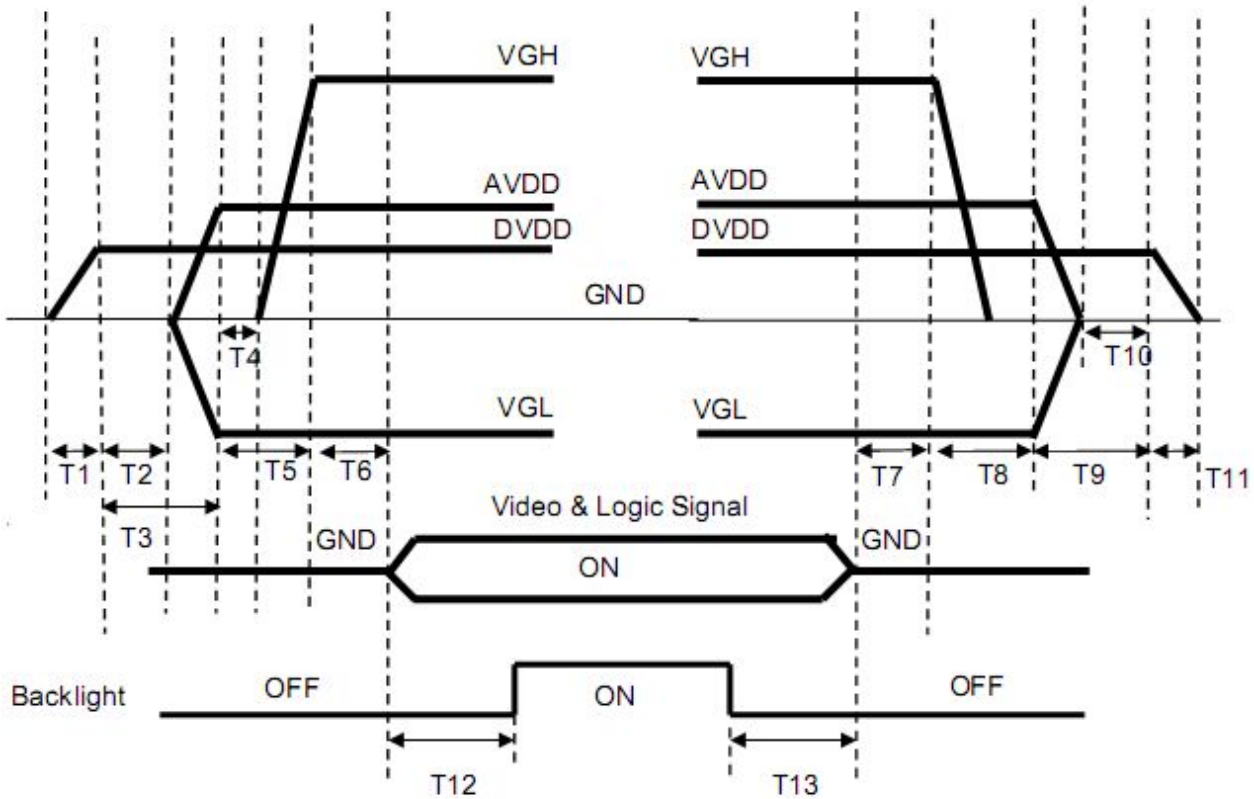


(b) Black Pattern

7.3 Power、Signal sequence

Power On : DVDD→AVDD/VGL →VGH →Video & Logic Signal→Backlight

Power Off : Backlight→Video & Logic Signal→ VGH→AVDD/VGL→DVDD



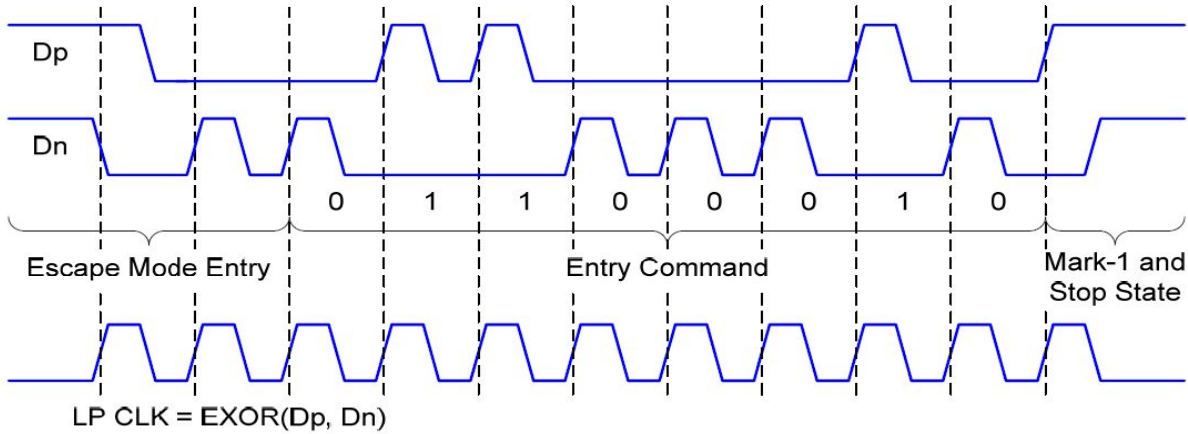
$0 < T1 \leq 10\text{ms}$
 $T2 > 0\text{ms}$
 $T3 > 20\text{ms}$
 $T4 > 0\text{ms}$
 $T5 > 10\text{ms}$
 $0 < T6 \leq 10\text{ms}$
 $T12 \geq 200\text{ms}$

$T7 > 0\text{ms}$
 $T8 > 0\text{ms}$
 $T9 > 0\text{ms}$
 $T10 > 0\text{ms}$
 $0 < T11 \leq 10\text{ms}$
 $T13 \geq 200\text{ms}$

4 MIPI AC Characteristic

7.1.1. LP Transmitter AC Specification

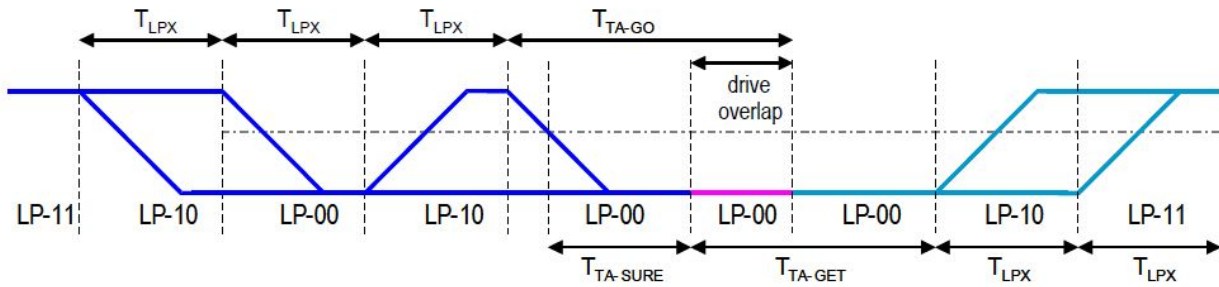
Parameter	Symbol	Min	Typ	Max	Units	Notes	
15%~85% rising time and falling time	T_{RLP} / T_{FLP}	-	-	25	ns	-	
30%~85% rising time and falling time	T_{REOT}	-	-	35	ns	-	
Pulse width of LP exclusive-OR clock	First LP EXOR clock pulse after STOP state or Last pulse before stop state	$T_{LP-PULSE-TX}$	40	-	-	ns	-
			All other pulses	20	-	-	ns
Period of the LP EXOR clock	$T_{LP-PER-TX}$	90	-	-	mV/ns	-	
Slew Rate @CLOAD =0pF	$\delta V / \delta t_{SR}$	30	-	500	mV/ns	-	
Slew Rate @CLOAD =5pF		30	-	200	mV/ns	-	
Slew Rate @CLOAD =20pF		30	-	150	mV/ns	-	
Slew Rate @CLOAD =70pF		30	-	100	mV/ns	-	
Load Capacitance	T_{RLP}	-	-	70	pF	-	



7.1.2. Turnaround Procedure

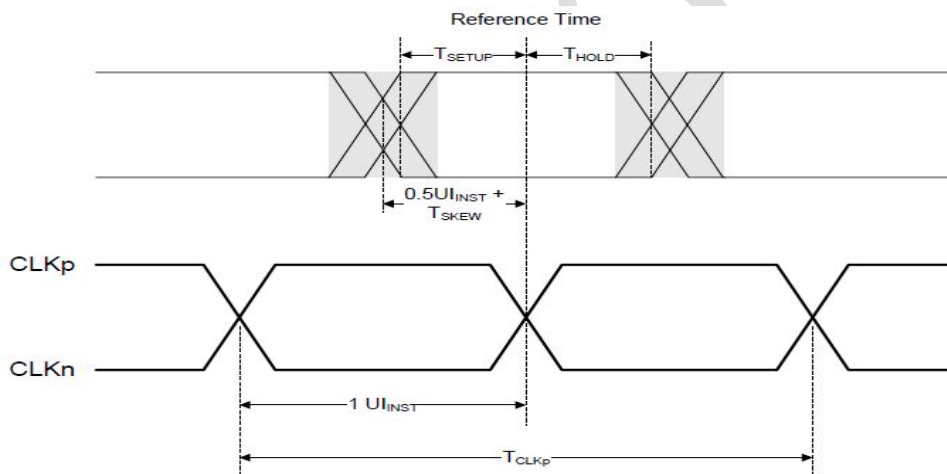
Turnaround Procedure Operation Timing Parameters

Parameter	Symbol	Min	Typ	Max	Units
Length of any Low-Power state period: Master side	T_{LPX}	50	-	75	ns
Length of any Low-Power state period: Slave side	T_{LPX}	50	55.56	58.34	ns
Ratio of T_{LPX} (Master)/ T_{LPX} (Slave) between Master and Slave side	Ratio T_{LPX}	2/3	-	3/2	
Time-out before new TX side start driving	$T_{TA-Sure}$	T_{LPX}		$2T_{LPX}$	ns
Time to drive LP-00 by new TX	T_{TA-GET}	-	$5T_{LPX}$	-	ns
Time to drive LP-00 after Turnaround Request	T_{TA-GO}	-	$4T_{LPX}$	-	ns



7.1.3. High speed transmission

Parameter	Symbol	Min	Typ	Max	Units
UI instantaneous	U_{INST}	2	-	12.5	ns
Data to Clock Skew(measured at transmitter)	$T_{SKEW(TX)}$	-0.15	-	0.15	U_{INST}
Data to Clock Setup time(measured at receiver)	$T_{SETUP(RX)}$	0.15	-	-	U_{INST}
Data to Clock Hold time(measured at receiver)	$T_{HOLD(RX)}$	0.15	-	-	U_{INST}
20%~80% rise time and fall time	T_R, T_F	150	-	-	ps
		-	-	0.3	U_{INST}

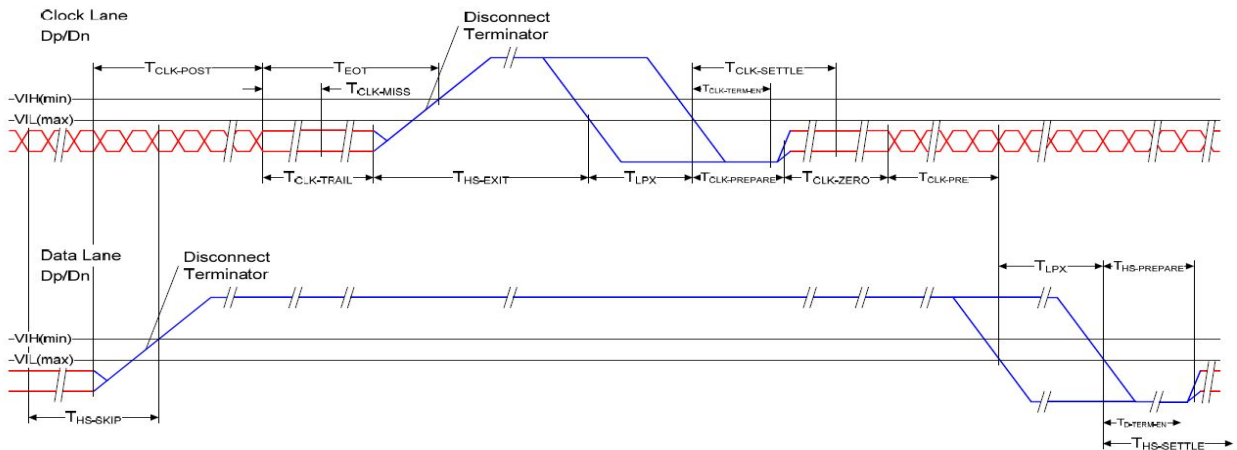


7.1.4. High Speed Clock Transmi

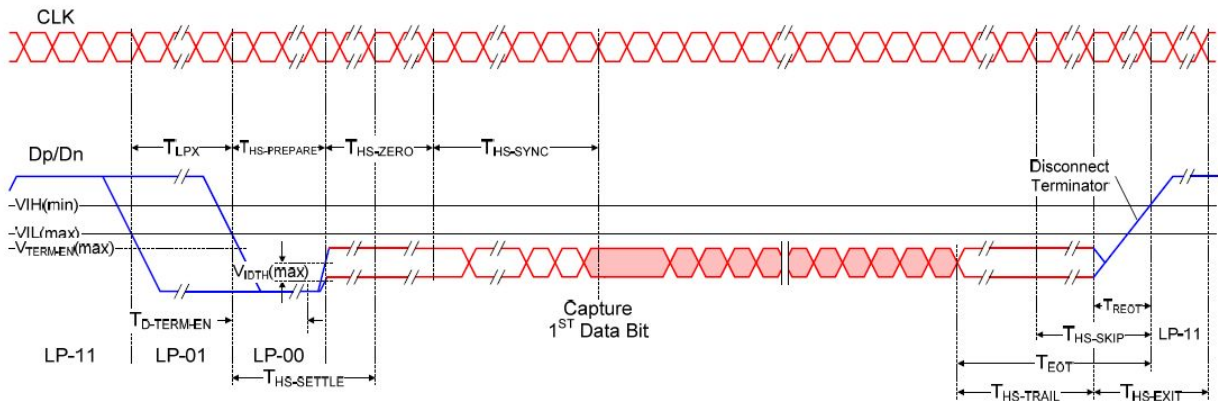
Parameter	Symbol	Min	Typ	Max	Unit
Time that the transmitter shall continue sending HS clock after the last associated Data Lane has transitioned to LP mode	$T_{CLK-POST}$	$60+52 U_I$	-	--	ns
Detection time that the clock has stopped toggling	$T_{CLK-MISS}$	-	-	60	ns
Time to drive LP-00 to prepare for HS clock	$T_{CLK-PREPA}$	38	-	95	

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transmission	RE				
Minimum lead HS-0 drive period before starting clock	TCLK-PREPA RE + TCLK-ZERO	300	-	-	ns
Time to enable Clock Lane receiver line termination measured from when Dn cross $V_{IL,MAX}$	THS-TERM-E N	-	-	38	ns
Minimum time that the HS clock must be prior to any associated data lane beginning the transmission from LP to HS mode	TCLK-PRE	8	-	-	UI
Time to drive HS differential state after last payload clock bit of a HS transmission burst	TCLK-TRAIL	60	-	-	ns



7.1.5. High Speed Data Transmission in Bursts



When Clock lane of DSI TX chip always keeps High speed mode, then Clock lane never go back to Low power mode. If Date lane of TX chip

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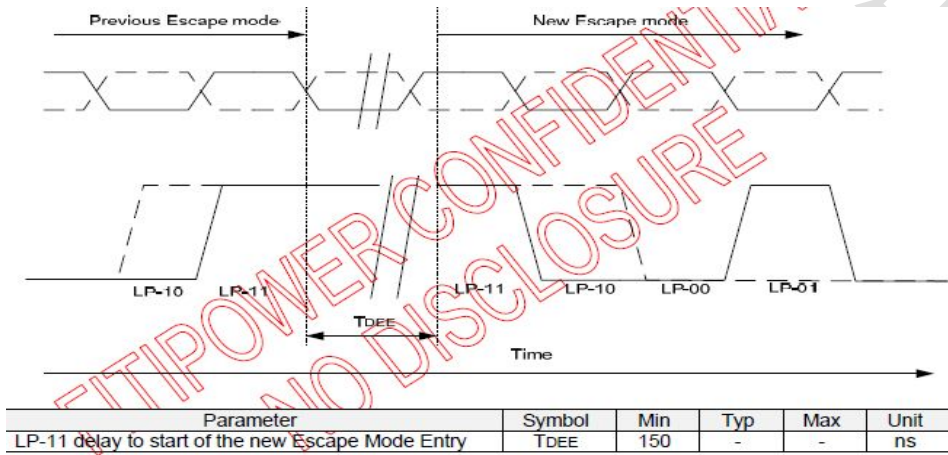
needs to transmit the next new data transmission or sequence, after the end of Low power mode or High speed mode BTA. Then TX chip needs

to keep LP-11 stop state before the next new data transmission, no matter in Low power mode or High speed mode BTA. The LP-11

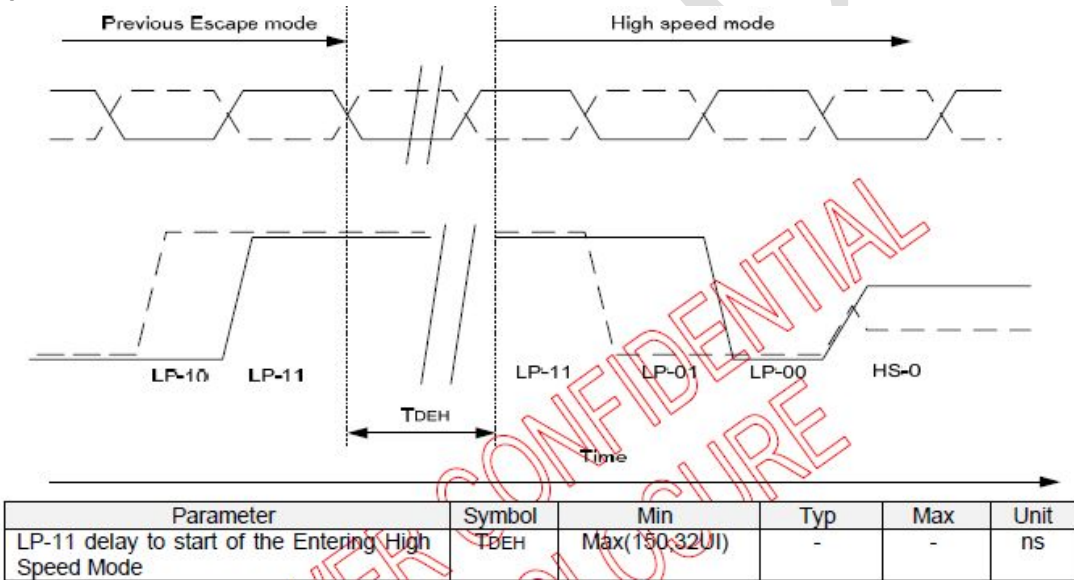
minimum timing is required for RX chip in the following 9 conditions, include of LP-LP, LP-HS, HS-LP, HS-H

TA-BTA, LP-BTA, BTA-LP, HS-BTA, and BTA-HS. This rule is suitable for short or long packet between TX and RX data transmission

(1) Timing between LP-LP command

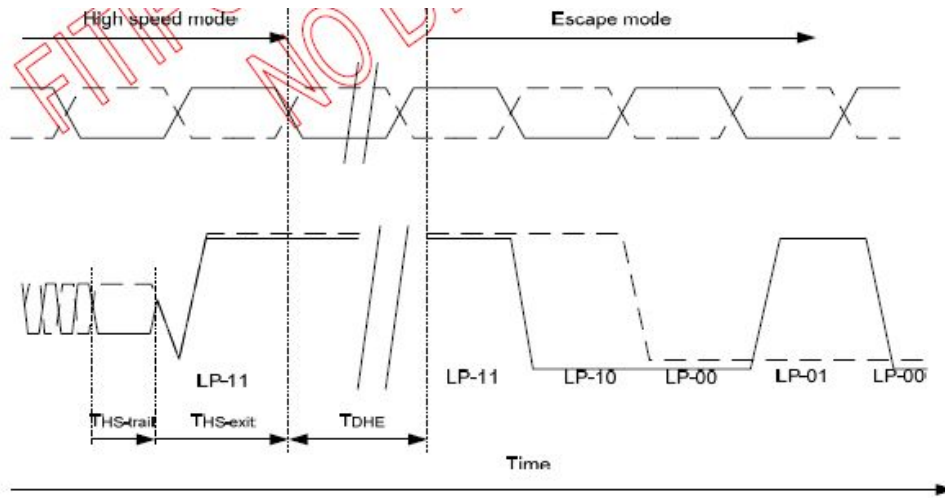


(2) Timing between LP-HS command



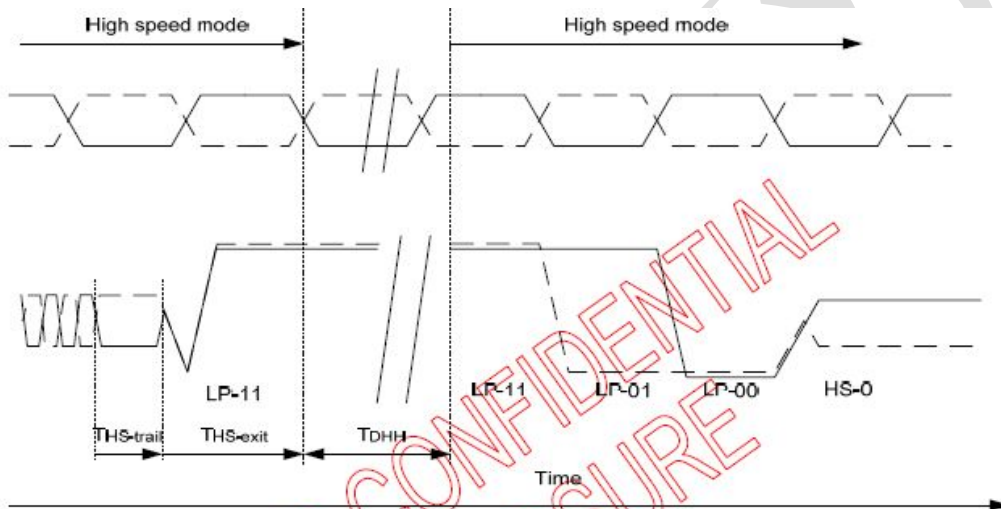
(3) Timing between HS-LP command

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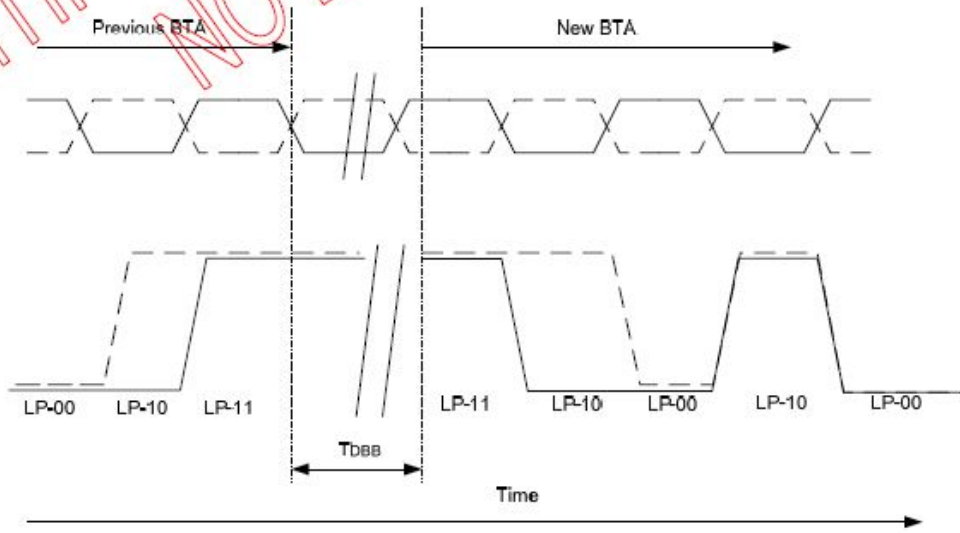
Parameter	Symbol	Min	Typ	Max	Unit
LP-11 delay to start of the Escape Mode Entry	TDHE	Max(150,32UI)	-	-	ns

(4) Timing between HS-HS command



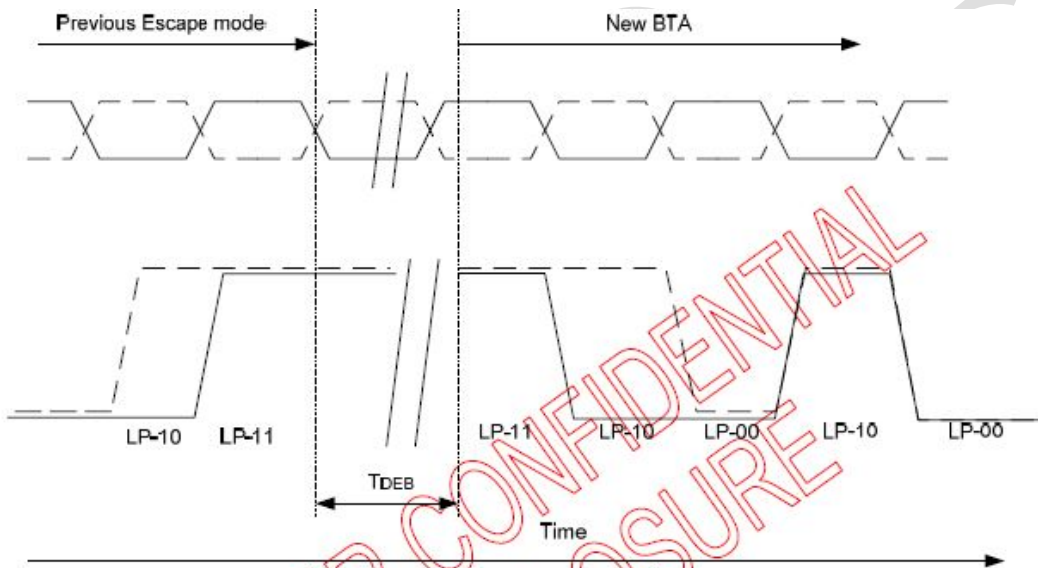
Parameter	Symbol	Min	Typ	Max	Unit
LP-11 delay to start of the Entering High Speed Mode	TDHH	Max(150,32UI)	-	-	ns

(5) Timing between BTA-BTA command



Parameter	Symbol	Min	Typ	Max	Unit
LP-11 delay to start of the new BTA	TDBB	150	-	-	ns

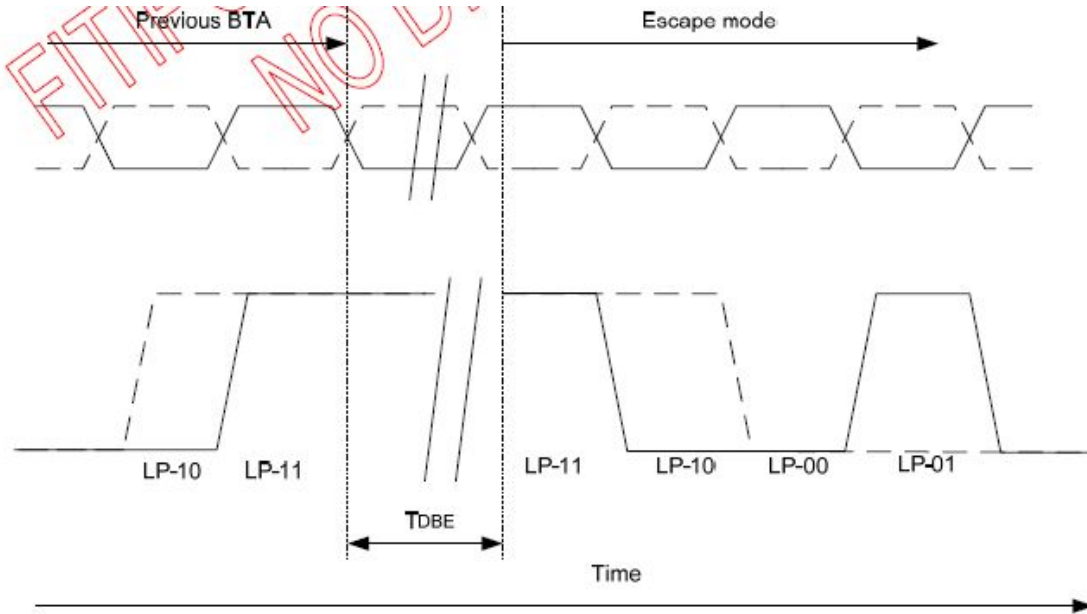
(6) Timing between LP-BTA command



Parameter	Symbol	Min	Typ	Max	Unit
LP-11 delay to start of the new BTA	TDEB	150	-	-	ns

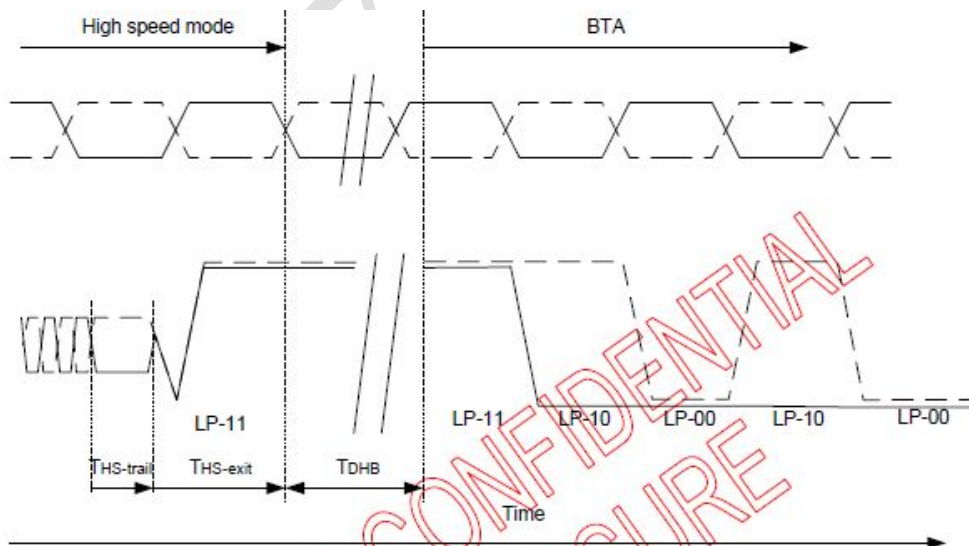
(7) Timing between BTA-LP command

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Parameter	Symbol	Min	Typ	Max	Unit
LP-11 delay to start of the Escape Mode Entry	TDBE	150	-	-	ns

(8) Timing between HS-BTA command

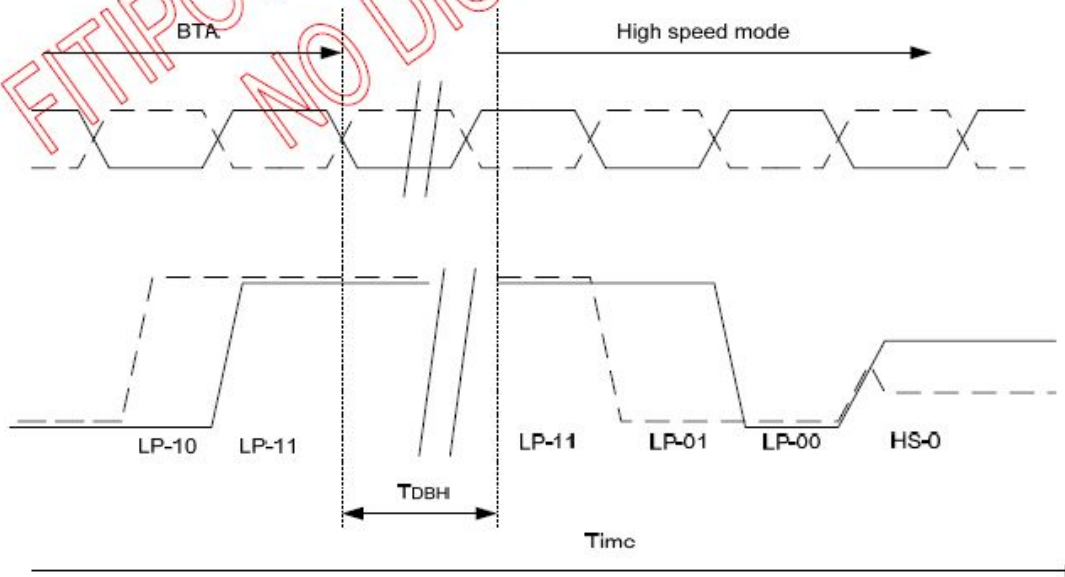


Parameter	Symbol	Min	Typ	Max	Unit
LP-11 delay to start of the BTA	TDHB	Max(150,32UI)	-	-	ns

(9) Timing between BTA-HP command

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(9) Timing between BTA-HP command



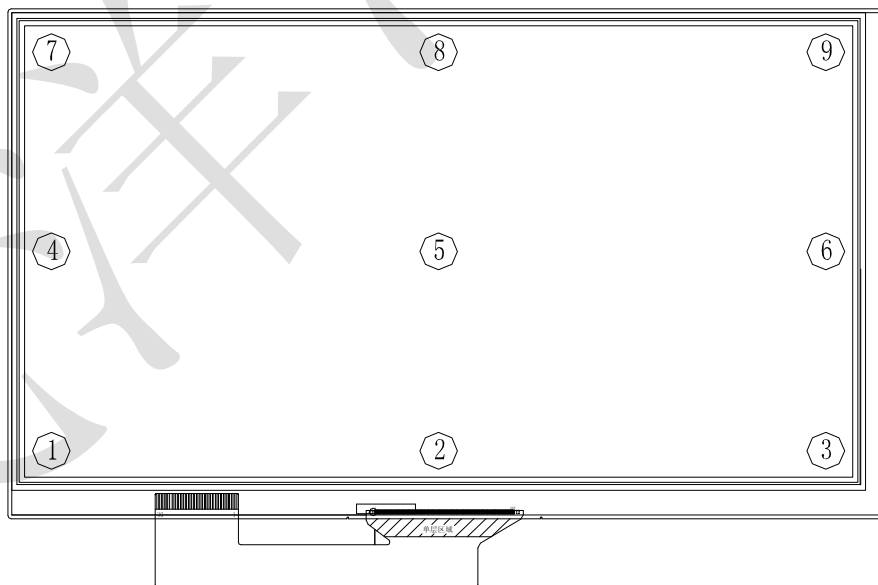
Parameter	Symbol	Min	Typ	Max	Unit
LP-11 delay to start of the Entering High Speed Mode	T _{DBH}	Max(150,32UI)	-	-	ns

. OPTICAL CHARACTERISTICS

ITEM	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT	REMARK
Transmittance	T		3.8	4.1		%	
Contrast Ratio	CR	*1)	600	800	--	--	Note 3
Response Time	Tr+ Tf	*3)	-	25	40	ms	Note 4
NTSC			45%	50%	--		
Viewing Angle	Left	ϕ	CR \geq 10	80	85		Note 5
	Right	ϕ		80	85		
	Upper	θ		80	85		
	Lower	θ		80	85		
Color Filter Chromacity with C light	White	x y	$\theta = \phi = 0^\circ$	0.27	0.290	0.31	Note 6
				0.311	0.331	0.351	
	Red	x y	$\theta = \phi = 0^\circ$	0.612	0.632	0.652	
				0.291	0.311	0.331	
	Green	x y	$\theta = \phi = 0^\circ$	0.277	0.297	0.317	
				0.516	0.536	0.556	
	Blue	x y	$\theta = \phi = 0^\circ$	0.12	0.140	0.16	
				0.134	0.154	0.174	

Note2: Definition of contrast ratio :

$$\text{Contrast Ratio (CR)} = \frac{\text{(White) Luminance of ON}}{\text{(Black) Luminance of OFF}}$$



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Note 3: Definition of Response Time.(White-Black)
 The response time is defined as the time interval between the 10% and 90% amplitudes.

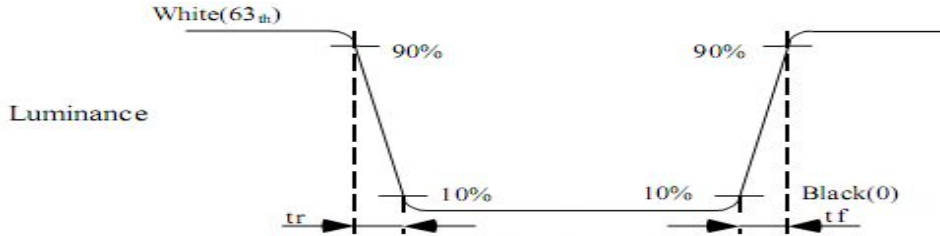


Fig. 6-2 Measuring point

Note 4: Definition of Viewing Angle(θ, ψ), refer to Fig.6 as below :

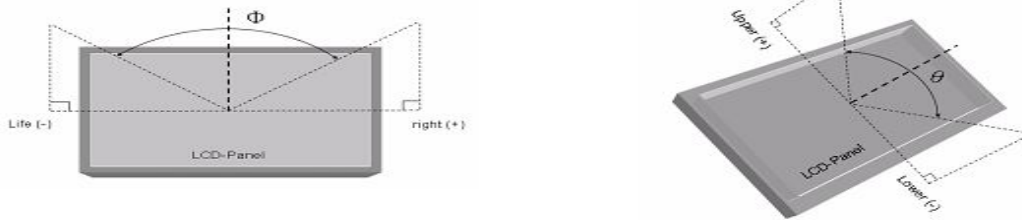


Fig.6-3 Definition of Viewing Angle

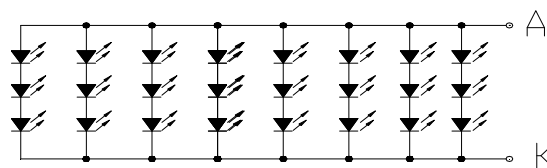
1). Backlight Driving Section

Item	Symbol	Min.	Typ.	Max.	Unit	Remark
LED Voltage	VF	9	9.8	10.6	V	Note1
LED Current	IF	-	160	-	mA	
Life Time	-	-	(25,000)	-	hr	Note2;3
Number of LED	--	24			--	

Note 1: There are 1 Groups LED

Note 2: Ta = 25_

Note 3: Brightness to be decreased to 50% of the initial value



Vf=9~10.6V If=160mA

BLU CIRCUIT DIAGRAM

0. MIPI Interface Pin Function

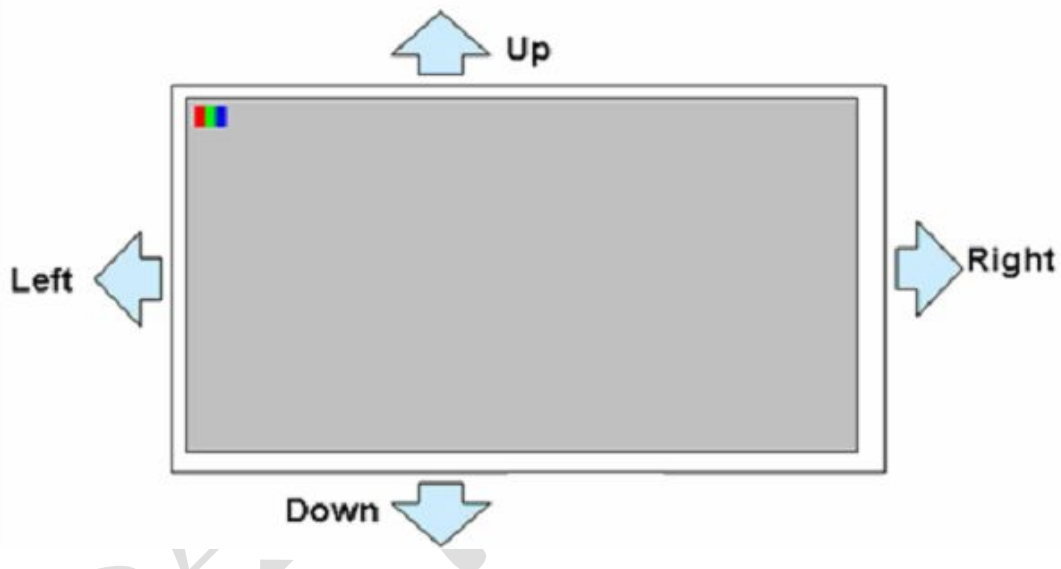
Pin No. 序号	Symbol 符号	I/O	Description 描述	When not in use 不用时
30	VCOM	I	Common voltage	-
29	DVDD	I	Digital power	-
28	DVDD	I	Digital power	-
27	RESET	I	Global reset pin. Active low to enter reset state. Suggest to connecting with an RC reset circuit for stability Normally pull high. (R=10K Ω , C=1 μ F) Standby mode, normally pull high STBYB="1", normal operation	-
26	STBYB	I	Standby mode, normally pull high STBYB="1", normal operation STBYB="0", timing control, source driver will turn off, all output are high-Z	DVDD
25	GND	P	Ground	-
24	MIPI_D0N	I	Negative MIPI differential data input	-
23	MIPI_D0P	I	Positive MIPI differential data input	-
22	GND	P	Ground	-
21	MIPI_D1N	I	Negative MIPI differential data input	-
20	MIPI_D1P	I	Positive MIPI differential data input	-
19	GND	P	Ground	-
18	MIPI_CLKN	I	Negative MIPI differential clock input	-
17	MIPI_CLKP	I	Positive MIPI differential clock input	-
16	GND	P	Ground	-
15	MIPI_D2N	I	Negative MIPI differential data input	-
14	MIPI_D2P	I	Positive MIPI differential data input	-
13	GND	P	Ground	-
12	MIPI_D3N	I	Negative MIPI differential data input	-
11	MIPI_D3P	I	Positive MIPI differential data input	-
10	GND	P	Ground	-
9	AVDD	P	Power for Analog Circuit	--
8	LED-	LEDP	LED Cathode	-
7				
6	SHLR	I	Left or Right Display Control	-

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5	UPDN	I	Up / Down Display Control	-
4	VGL	P	Negative power for TFT	-
3	VGH	P	Positive power for TFT	-
2	LED+		LED Anode	-
1				

【Note1】 SHLR : left or right setting
UPDN : up or down setting

UPDN	SHLR	FUNCTION
0	1	Normal Display
0	0	Inverse Left and Right
1	1	Inverse Up and Down
1	0	Inverse Left and Right Inverse Up and Down



11. Caution

11.1 Handling of LCM

- . **Be sure to ground the body when handling the LCM.**
- . **Don't give external shock**
- . **Don't apply excessive force on the surface.**
- . **Liquid in LCD is hazardous substance. Must not lick and swallow.**
When the liquid is attach to your hand, skin, cloth etc. Wash it out thoroughly and immediately.
- . **Don't operate it above the absolute maximum rating.**
- . **Don't disassemble the LCM**

11.2 Storage

- . **Store in an ambient temperature of 5℃ to 45℃, and in a relative humidity of 40% to 60%. Don't expose to sunlight or intensive ultraviolet rays**
- . **Storage in a clean environment, free from dust, active gas, and solvent.**
- . **Store in anti-static electricity container.**
- . **Store without any physical load.**