

Description

The GM71V(S)17803B/BL is the new generation dynamic RAM organized 2,097,152 words x 8 bit. GM71V(S)17803B/BL has realized higher density, higher performance and various functions by utilizing advanced CMOS process technology. The GM71V(S)17803B/BL offers Extended Data Out (EDO) Mode as a high speed access mode. Multiplexed address inputs permit the GM71V(S)17803B/BL to be packaged in standard 400 mil 28pin plastic SOJ, and standard 400mil 28pin plastic TSOP II. The package size provides high system bit densities and is compatible with widely available automated testing and insertion equipment. System oriented features include single power supply 3.3V ± 0.3V tolerance, direct interfacing capability with high performance logic families such as Schottky TTL.

Features

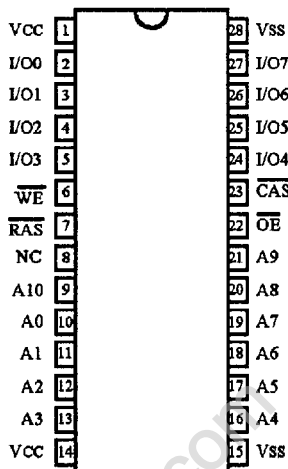
- 2,097,152 Words x 8 Bit Organization
- Extended Data Out Mode Capability
- Single Power Supply (3.3V ± 0.3V)
- Fast Access Time & Cycle Time (Unit: ns)

	t _{TRAC}	t _{CAC}	t _{RC}	t _{HPC}
GM71V(S)17803B/BL-6	60	15	104	25
GM71V(S)17803B/BL-7	70	18	124	30
GM71V(S)17803B/BL-8	80	20	144	35

- Low Power
Active : 432/396/360mW (MAX)
Standby : 3.6mW (CMOS level : MAX)
0.54mW (L-version : MAX)
- $\overline{\text{RAS}}$ Only Refresh, $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ Refresh, Hidden Refresh Capability
- All inputs and outputs TTL Compatible
- 2048 Refresh Cycles/32ms
- 2048 Refresh Cycles/128ms (L-version)
- Battery Back Up Operation (L-version)
- Self Refresh Operation (L-version)

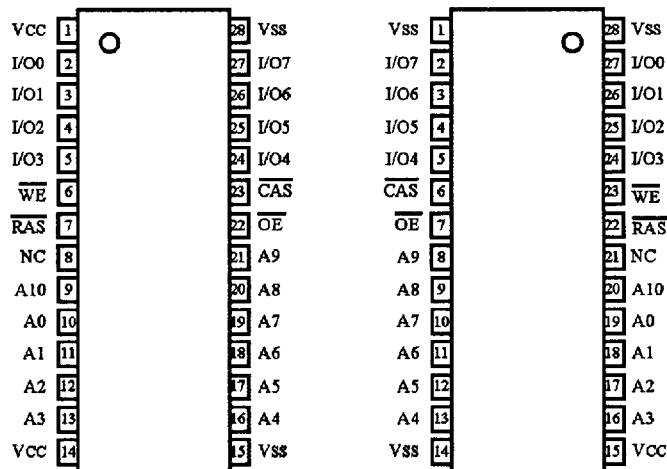
Pin Configuration

28 SOJ



(Top View)

28 TSOP II



(Normal)

(Reverse)

(Top View)

Pin Description

Pin	Function	Pin	Function
A0-A10	Address Inputs	\overline{WE}	Read/Write Enable
A0-A10	Refresh Address Inputs	\overline{OE}	Output Enable
I/O0-I/O7	Data Input / Data Output	V _{cc}	Power (+3.3V)
\overline{RAS}	Row Address Strobe	V _{ss}	Ground
\overline{CAS}	Column Address Strobe	NC	No Connection

Ordering Information

Type No.	Access Time	Package
GM71V17803BJ-6 GM71V17803BJ-7 GM71V17803BJ-8	60ns 70ns 80ns	400 Mil 28 Pin Plastic SOJ
GM71V17803BT-6 GM71V17803BT-7 GM71V17803BT-8	60ns 70ns 80ns	400 Mil 28 Pin Plastic TSOP II
GM71V17803BR-6 GM71V17803BR-7 GM71V17803BR-8	60ns 70ns 80ns	400 Mil 28 Pin Plastic TSOP II (Reverse Type)
GM71VS17803BLJ-6 GM71VS17803BLJ-7 GM71VS17803BLJ-8	60ns 70ns 80ns	400 Mil 28 Pin Plastic SOJ
GM71VS17803BLT-6 GM71VS17803BLT-7 GM71VS17803BLT-8	60ns 70ns 80ns	400 Mil 28 Pin Plastic TSOP II
GM71VS17803BLR-6 GM71VS17803BLR-7 GM71VS17803BLR-8	60ns 70ns 80ns	400 Mil 28 Pin Plastic TSOP II (Reverse Type)

Absolute Maximum Ratings*

Symbol	Parameter	Rating	Unit
T _A	Ambient Temperature under Bias	0 ~ 70	°C
T _{STG}	Storage Temperature (Plastic)	-55 ~ 125	°C
V _{IN} /V _{OUT}	Voltage on any Pin Relative to V _{SS}	-0.5 ~ V _{CC} +0.5 (≤4.6 V(MAX))	V
V _{CC}	Voltage on V _{CC} Relative to V _{SS}	-0.5 ~ +4.6	V
I _{OUT}	Short Circuit Output Current	50	mA
P _D	Power Dissipation	1.0	W

*Note: Operation at or above Absolute Maximum Ratings can adversely affect device reliability.

Recommended DC Operating Conditions (T_A = 0 ~ 70°C)

Symbol	Parameter	Min	Typ	Max	Unit
V _{CC}	Supply Voltage	3.0	3.3	3.6	V
V _{IH}	Input High Voltage	2.0	-	V _{CC} +0.3	V
V _{IL}	Input Low Voltage	-0.3	-	0.8	V

*Note: All voltage referred to V_{SS}.

DC Electrical Characteristics ($V_{CC} = 3.3V \pm 0.3V$, $T_A = 0 \sim 70^\circ C$)

Symbol	Parameter	Min	Max	Unit	Note	
V_{OH}	Output Level Output "H" Level Voltage ($I_{OUT} = -2mA$)	2.0	V_{CC}	V		
V_{OL}	Output Level Output "L" Level Voltage ($I_{OUT} = 2mA$)	0	0.4	V		
I_{CC1}	Operating Current Average Power Supply Operating Current (\overline{RAS} , \overline{CAS} Cycling: $t_{RC} = t_{RC\ min}$)	60 ns	-	120	mA	1, 2
		70 ns	-	110		
		80 ns	-	100		
I_{CC2}	Standby Current (TTL) Power Supply Standby Current (\overline{RAS} , $\overline{CAS} = V_{IH}$, $D_{OUT} = High-Z$)	-	2	mA		
I_{CC3}	\overline{RAS} Only Refresh Current Average Power Supply Current \overline{RAS} Only Refresh Mode ($t_{RC} = t_{RC\ min}$)	60 ns	-	120	mA	2
		70 ns	-	110		
		80 ns	-	100		
I_{CC4}	Extended Data Out Mode Current Average Power Supply Current EDO Page Mode ($t_{RDC} = t_{RDC\ min}$)	60 ns	-	120	mA	1, 3
		70 ns	-	110		
		80 ns	-	100		
I_{CC5}	Standby Current (CMOS) Power Supply Standby Current (\overline{RAS} , $\overline{CAS} \geq V_{CC} - 0.2V$, $D_{OUT} = High-Z$)	-	1	mA		
		-	150	μA	5	
I_{CC6}	\overline{CAS} -before- \overline{RAS} Refresh Current ($t_{RC} = t_{RC\ min}$)	60 ns	-	120	mA	
		70 ns	-	110		
		80 ns	-	100		
I_{CC7}	Battery Back Up Operating Current (Standby with CBR Refresh) ($t_{RC} = 62.5 \mu s$, $t_{RAS} \leq 0.3 \mu s$, $D_{OUT} = High-Z$)	-	400	μA	4, 5	
I_{CC8}	Standby Current $\overline{RAS} = V_{IH}$ $\overline{CAS} = V_{IL}$ $D_{OUT} = Enable$	-	5	mA	1	
I_{CC9}	Self-Refresh Mode Current (\overline{RAS} , $\overline{CAS} \leq 0.2V$, $D_{OUT} = High-Z$)	-	250	μA	5	
$I_{(L)}$	Input Leakage Current Any Input ($0V \leq V_{IN} \leq 4.6V$)	-10	10	μA		
$I_{(O)}$	Output Leakage Current (D_{OUT} is Disabled, $0V \leq V_{OUT} \leq 4.6V$)	-10	10	μA		

Note: 1. I_{CC} depends on output load condition when the device is selected. $I_{CC(max)}$ is specified at the output open condition.

2. Address can be changed once or less while $\overline{RAS} = V_{IL}$.
3. Address can be changed once or less while $\overline{CAS} = V_{IH}$.
4. $\overline{CAS} = L (\leq 0.2V)$ while $\overline{RAS} = L (\leq 0.2V)$
5. L-version

Capacitance ($V_{CC} = 3.3V \pm 0.3V$, $T_A = 25^\circ C$)

Symbol	Parameter	Min	Max	Unit	Note
C_{11}	Input Capacitance (Address)	-	5	pF	1
C_{12}	Input Capacitance (Clocks)	-	7	pF	1
C_{10}	Output Capacitance (Data-In/Out)	-	7	pF	1, 2

Note: 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.
 2. $CAS = V_{IH}$ to disable $Dout$.

AC Characteristics ($V_{CC} = 3.3V \pm 0.3V$, $T_A = 0 \sim 70^\circ C$, Notes 1, 2, 18)
Test Conditions

Input rise and fall times : 2 ns

 Input levels : $V_{IL} = 0V$, $V_{IH} = 3V$

Input timing reference levels : 0.8V, 2.0V

Output timing reference levels : 0.8V, 2.0V

 Output load : 1TTL gate + CL (100 pF)

(Including scope and jig)

Read, Write, Read-Modify-Write and Refresh Cycles (Common Parameters)

Symbol	Parameter	GM71V(S)17803 B/BL-6		GM71V(S)17803 B/BL-7		GM71V(S)17803 B/BL-8		Unit	Note
		Min	Max	Min	Max	Min	Max		
t_{RC}	Random Read or Write Cycle Time	104	-	124	-	144	-	ns	
t_{RP}	\overline{RAS} Precharge Time	40	-	50	-	60	-	ns	
t_{CP}	\overline{CAS} Precharge Time	10	-	13	-	15	-	ns	
t_{RAS}	\overline{RAS} Pulse Width	60	10,000	70	10,000	80	10,000	ns	
t_{CAS}	\overline{CAS} Pulse Width	10	10,000	13	10,000	15	10,000	ns	
t_{ASR}	Row Address Set up Time	0	-	0	-	0	-	ns	
t_{RAH}	Row Address Hold Time	10	-	10	-	10	-	ns	
t_{ASC}	Column Address Set-up Time	0	-	0	-	0	-	ns	
t_{CAH}	Column Address Hold Time	10	-	13	-	15	-	ns	
t_{RCD}	\overline{RAS} to \overline{CAS} Delay Time	20	45	20	52	20	60	ns	3
t_{RAD}	\overline{RAS} to Column Address Delay Time	15	30	15	35	15	40	ns	4
t_{RSH}	\overline{RAS} Hold Time	15	-	18	-	20	-	ns	
t_{CSH}	\overline{CAS} Hold Time	48	-	58	-	68	-	ns	
t_{CRP}	\overline{CAS} to \overline{RAS} Precharge Time	5	-	5	-	5	-	ns	
t_{ODD}	\overline{OE} to D_{IN} Delay Time	15	-	18	-	20	-	ns	5
t_{DZO}	\overline{OE} Delay Time from D_{IN}	0	-	0	-	0	-	ns	6
t_{DZC}	\overline{CAS} Delay Time from D_{IN}	0	-	0	-	0	-	ns	6
t_T	Transition Time (Rise and Fall)	2	50	2	50	2	50	ns	7
t_{REF}	Refresh Period	-	32	-	32	-	32	ms	
	Refresh Period (L-version)	-	128	-	128	-	128	ms	

Read Cycle

Symbol	Parameter	GM71V(S)17803 B/BL-6		GM71V(S)17803 B/BL-7		GM71V(S)17803 B/BL-8		Unit	Note
		Min	Max	Min	Max	Min	Max		
t _{RAC}	Access Time from \overline{RAS}	-	60	-	70	-	80	ns	8,9
t _{CAC}	Access Time from \overline{CAS}	-	15	-	18	-	20	ns	9,10,17
t _{AA}	Access Time from Address	-	30	-	35	-	40	ns	9,11,17
t _{OAC}	Access Time from \overline{OE}	-	15	-	18	-	20	ns	9
t _{RCS}	Read Command Setup Time	0	-	0	-	0	-	ns	
t _{RCH}	Read Command Hold Time to \overline{CAS}	0	-	0	-	0	-	ns	12
t _{RCHR}	Read Command Hold Time from \overline{RAS}	60	-	70	-	80	-	ns	
t _{RRH}	Read Command Hold Time to \overline{RAS}	0	-	0	-	0	-	ns	12
t _{RAL}	Column Address to \overline{RAS} Lead Time	30	-	35	-	40	-	ns	
t _{CAL}	Column Address to \overline{CAS} Lead Time	18	-	23	-	28	-	ns	
t _{CLZ}	\overline{CAS} to Output in Low-Z	0	-	0	-	0	-	ns	
t _{OH}	Output Data Hold Time	3	-	3	-	3	-	ns	
t _{OHO}	Output Data Hold Time from \overline{OE}	3	-	3	-	3	-	ns	
t _{OFF}	Output Buffer Turn-off Time	-	15	-	15	-	15	ns	13
t _{OEZ}	Output Buffer Turn-off Time to \overline{OE}	-	15	-	15	-	15	ns	13
t _{CDD}	\overline{CAS} to D _{IN} Delay Time	15	-	18	-	20	-	ns	5
t _{OHR}	Output Data Hold Time from \overline{RAS}	3	-	3	-	3	-	ns	
t _{OFR}	Output Buffer Turn-off Time to \overline{RAS}	-	15	-	15	-	15	ns	
t _{WEZ}	Output Buffer Turn-off Time to \overline{WE}	-	15	-	15	-	15	ns	
t _{WDD}	\overline{WE} to D _{IN} Delay Time	15	-	18	-	20	-	ns	
t _{RDD}	\overline{RAS} to D _{IN} Delay Time	15	-	18	-	20	-	ns	

Write Cycle

Symbol	Parameter	GM71V(S)17803 B/BL-6		GM71V(S)17803 B/BL-7		GM71V(S)17803 B/BL-8		Unit	Note
		Min	Max	Min	Max	Min	Max		
t _{WCS}	Write Command Setup Time	0	-	0	-	0	-	ns	14
t _{WCH}	Write Command Hold Time	10	-	13	-	15	-	ns	
t _{WP}	Write Command Pulse Width	10	-	10	-	10	-	ns	
t _{RWL}	Write Command to $\overline{\text{RAS}}$ Lead Time	10	-	13	-	15	-	ns	
t _{CWL}	Write Command to $\overline{\text{CAS}}$ Lead Time	10	-	13	-	15	-	ns	
t _{DS}	Data-in Setup Time	0	-	0	-	0	-	ns	15
t _{DH}	Data-in Hold Time	10	-	13	-	15	-	ns	15

Read-Modify-Write Cycle

Symbol	Parameter	GM71V(S)17803 B/BL-6		GM71V(S)17803 B/BL-7		GM71V(S)17803 B/BL-8		Unit	Note
		Min	Max	Min	Max	Min	Max		
t _{RWC}	Read-Modify-Write Cycle Time	149	-	175	-	199	-	ns	
t _{RWD}	$\overline{\text{RAS}}$ to $\overline{\text{WE}}$ Delay Time	82	-	95	-	107	-	ns	14
t _{CWD}	$\overline{\text{CAS}}$ to $\overline{\text{WE}}$ Delay Time	37	-	43	-	47	-	ns	14
t _{AWD}	Column Address to $\overline{\text{WE}}$ Delay Time	52	-	60	-	67	-	ns	14
t _{OEH}	$\overline{\text{OE}}$ Hold Time from $\overline{\text{WE}}$	15	-	18	-	20	-	ns	

Refresh Cycle

Symbol	Parameter	GM71V(S)17803 B/BL-6		GM71V(S)17803 B/BL-7		GM71V(S)17803 B/BL-8		Unit	Note
		Min	Max	Min	Max	Min	Max		
t _{CSR}	$\overline{\text{CAS}}$ Setup Time (CAS-before-RAS Refresh Cycle)	5	-	5	-	5	-	ns	
t _{CHR}	$\overline{\text{CAS}}$ Hold Time (CAS-before-RAS Refresh Cycle)	10	-	10	-	10	-	ns	
t _{WRP}	$\overline{\text{WE}}$ Setup Time (CAS-before-RAS Refresh Cycle)	0	-	0	-	0	-	ns	
t _{WRH}	$\overline{\text{WE}}$ Hold Time (CAS-before-RAS Refresh Cycle)	10	-	10	-	10	-	ns	
t _{RPC}	$\overline{\text{RAS}}$ Precharge to $\overline{\text{CAS}}$ Hold Time	0	-	0	-	0	-	ns	

EDO Mode Cycle

Symbol	Parameter	GM71V(S)17803 B/BL-6		GM71V(S)17803 B/BL-7		GM71V(S)17803 B/BL-8		Unit	Note
		Min	Max	Min	Max	Min	Max		
t _{HPC}	EDO Mode Cycle Time	25	-	30	-	35	-	ns	20
t _{RASP}	EDO Mode $\overline{\text{RAS}}$ Pulse Width	-	100,000	-	100,000	-	100,000	ns	16
t _{ACP}	Access Time from $\overline{\text{CAS}}$ Precharge	-	35	-	40	-	45	ns	9,17
t _{RHCP}	$\overline{\text{RAS}}$ Hold Time from $\overline{\text{CAS}}$ Precharge	35	-	40	-	45	-	ns	
t _{DOH}	Output Data Hold Time from $\overline{\text{CAS}}$ Low	3	-	3	-	3	-	ns	9,17
t _{COL}	$\overline{\text{CAS}}$ Hold Time Referred $\overline{\text{OE}}$	10	-	13	-	15	-	ns	
t _{COP}	$\overline{\text{CAS}}$ to $\overline{\text{OE}}$ Setup Time	5	-	5	-	5	-	ns	
t _{RCHP}	Read command hold Time from $\overline{\text{CAS}}$ precharge	35	-	40	-	45	-	ns	

EDO Mode Read-Modify-Write Cycle

Symbol	Parameter	GM71V(S)17803 B/BL-6		GM71V(S)17803 B/BL-7		GM71V(S)17803 B/BL-8		Unit	Note
		Min	Max	Min	Max	Min	Max		
t _{HPRWC}	EDO Mode Read-Modify-Write Cycle Time	79	-	90	-	99	-	ns	
t _{CPW}	$\overline{\text{WE}}$ Delay Time from $\overline{\text{CAS}}$ Precharge	54	-	62	-	69	-	ns	14

Self Refresh Mode (L-Version)

Symbol	Parameter	GM71VS17803 BL-6		GM71VS17803 BL-7		GM71VS17803 BL-8		Unit	Note
		Min	Max	Min	Max	Min	Max		
t _{RASS}	$\overline{\text{RAS}}$ Pulse Width (Self-Refresh)	100	-	100	-	100	-	us	
t _{RPS}	$\overline{\text{RAS}}$ Precharge Time (Self-Refresh)	110	-	130	-	150	-	ns	
t _{CHS}	$\overline{\text{CAS}}$ Hold Time (Self-Refresh)	-50	-	-50	-	-50	-	ns	

Notes :

1. AC measurements assume $t_r = 2 \text{ ns}$.
2. An initial pause of $200 \mu\text{s}$ is required after power followed by a minimum of eight initialization cycles (any combination of cycles containing $\overline{\text{RAS}}$ -only refresh or $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh).
3. Operation with the $t_{\text{RCD}}(\text{max})$ limit insures that $t_{\text{RAC}}(\text{max})$ can be met, $t_{\text{RCD}}(\text{max})$ is specified as a reference point only; if t_{RCD} is greater than the specified $t_{\text{RCD}}(\text{max})$ limit, then access time is controlled exclusively by t_{CAC} .
4. Operation with the $t_{\text{RAD}}(\text{max})$ limit insures that $t_{\text{RAC}}(\text{max})$ can be met, $t_{\text{RAD}}(\text{max})$ is specified as a reference point only; if t_{RAD} is greater than the specified $t_{\text{RAD}}(\text{max})$ limit, then access time is controlled exclusively by t_{AA} .
5. Either t_{ODD} or t_{CDD} must be satisfied.
6. Either t_{DZO} or t_{DZC} must be satisfied.
7. $V_{\text{IH}}(\text{min})$ and $V_{\text{IL}}(\text{max})$ are reference levels for measuring timing of input signals. Also, transition times are measured between $V_{\text{IH}}(\text{min})$ and $V_{\text{IL}}(\text{max})$.
8. Assumes that $t_{\text{RCD}} \leq t_{\text{RCD}}(\text{max})$ and $t_{\text{RAD}} \leq t_{\text{RAD}}(\text{max})$. If t_{RCD} or t_{RAD} is greater than the maximum recommended value shown in this table, t_{RAC} exceeds the value shown.
9. Measured with a load circuit equivalent to 1TTL loads and 100pF .
10. Assumes that $t_{\text{RCD}} \geq t_{\text{RCD}}(\text{max})$ and $t_{\text{RAD}} \leq t_{\text{RAD}}(\text{max})$.
11. Assumes that $t_{\text{RCD}} \leq t_{\text{RCD}}(\text{max})$ and $t_{\text{RAD}} \geq t_{\text{RAD}}(\text{max})$.
12. Either t_{RCH} or t_{RRH} must be satisfied for a read cycles.
13. $t_{\text{OFF}}(\text{max})$ and $t_{\text{OEZ}}(\text{max})$ define the time at which the outputs achieve the open circuit condition and are not referred to output voltage levels.
14. t_{WCS} , t_{RWD} , t_{CWD} , t_{AWD} and t_{CPW} are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only; if $t_{\text{WCS}} \geq t_{\text{WCS}}(\text{min})$, the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout the entire cycle; if $t_{\text{RWD}} \geq t_{\text{RWD}}(\text{min})$, $t_{\text{CWD}} \geq t_{\text{CWD}}(\text{min})$, and $t_{\text{AWD}} \geq t_{\text{AWD}}(\text{min})$, or $t_{\text{CWD}} \geq t_{\text{CWD}}(\text{min})$ $t_{\text{AWD}} \geq t_{\text{AWD}}(\text{min})$ and $t_{\text{CPW}} \geq t_{\text{CPW}}(\text{min})$, the cycle is a read-modify-write and the data output will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.
15. These parameters are referred to $\overline{\text{CAS}}$ leading edge in early write cycles and to $\overline{\text{WE}}$ leading edge in delayed write or read-modify-write cycles.
16. t_{RASP} defines $\overline{\text{RAS}}$ pulse width in EDO mode cycles.
17. Access time is determined by the longer of t_{AA} or t_{CAC} or t_{ACP} .
18. In delayed write or read-modify-write cycles, $\overline{\text{OE}}$ must disable output buffer prior to applying data to the device. After $\overline{\text{RAS}}$ is reset, if $t_{\text{OEH}} \geq t_{\text{CWL}}$, the I/O pin will remain open circuit (high impedance); if $t_{\text{OEH}} \leq t_{\text{CWL}}$, invalid data will be out at each I/O.
19. EDO Hi-Z control by $\overline{\text{OE}}$ or $\overline{\text{WE}}$. $\overline{\text{OE}}$ rising edge disables data outputs. When $\overline{\text{OE}}$ goes high during $\overline{\text{CAS}}$ high, the data will not come out until next $\overline{\text{CAS}}$ access. When $\overline{\text{WE}}$ goes low during $\overline{\text{CAS}}$ high, the data will not come out until next $\overline{\text{CAS}}$ access.
20. $t_{\text{HPC}}(\text{min})$ can be achieved during a series of EDO mode write cycles or EDO mode read cycles. If both write and read operation are mixed in a EDO mode $\overline{\text{RAS}}$ cycle (EDO mode mix cycle (1),(2)) minimum value of $\overline{\text{CAS}}$ cycle ($t_{\text{CAS}} + t_{\text{CP}} + 2t_r$) becomes greater than the specified $t_{\text{HPC}}(\text{min})$ value. The value of $\overline{\text{CAS}}$ cycle time of mixed EDO mode is shown in EDO mode mix cycle (1) and (2).

Timing Waveforms

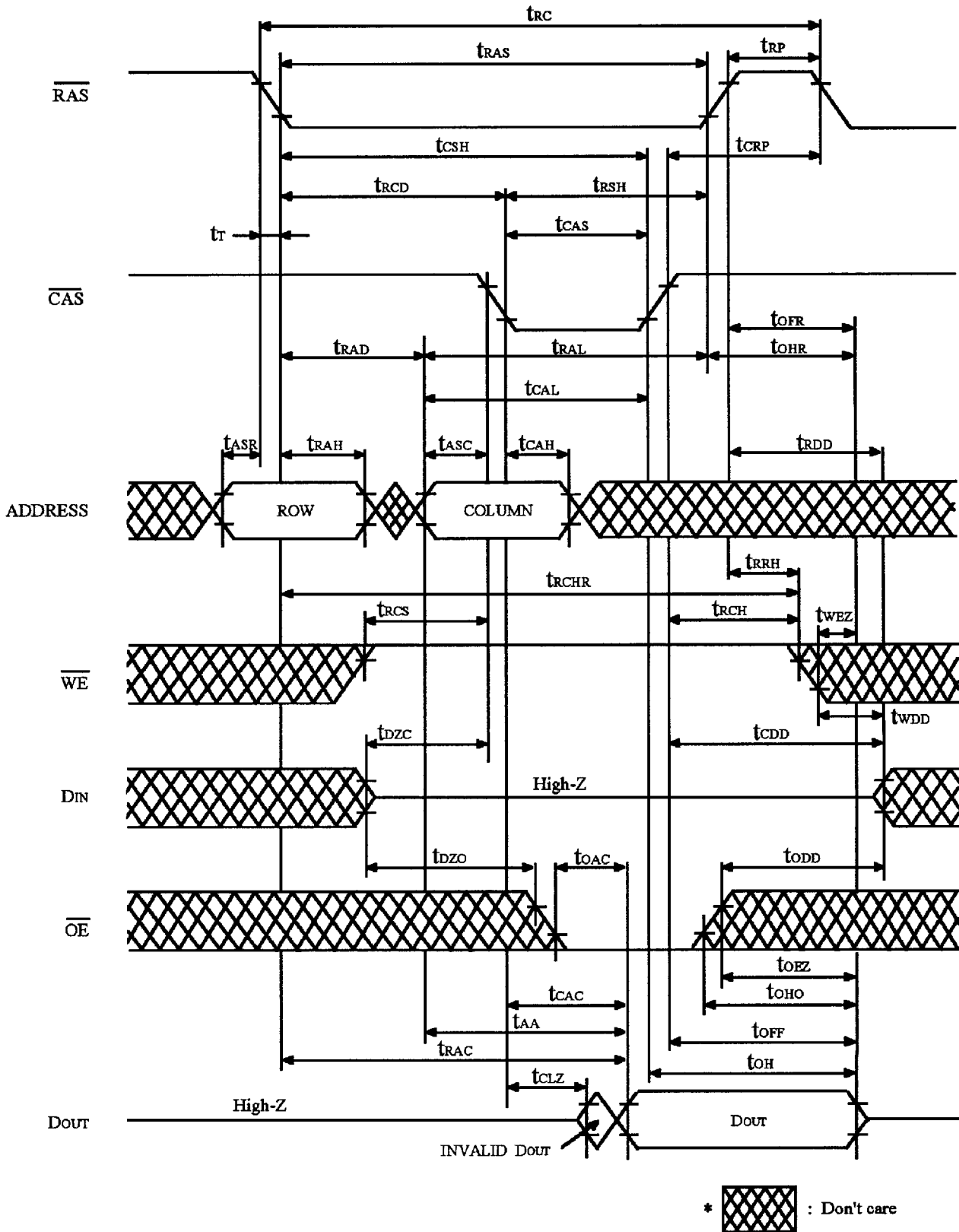
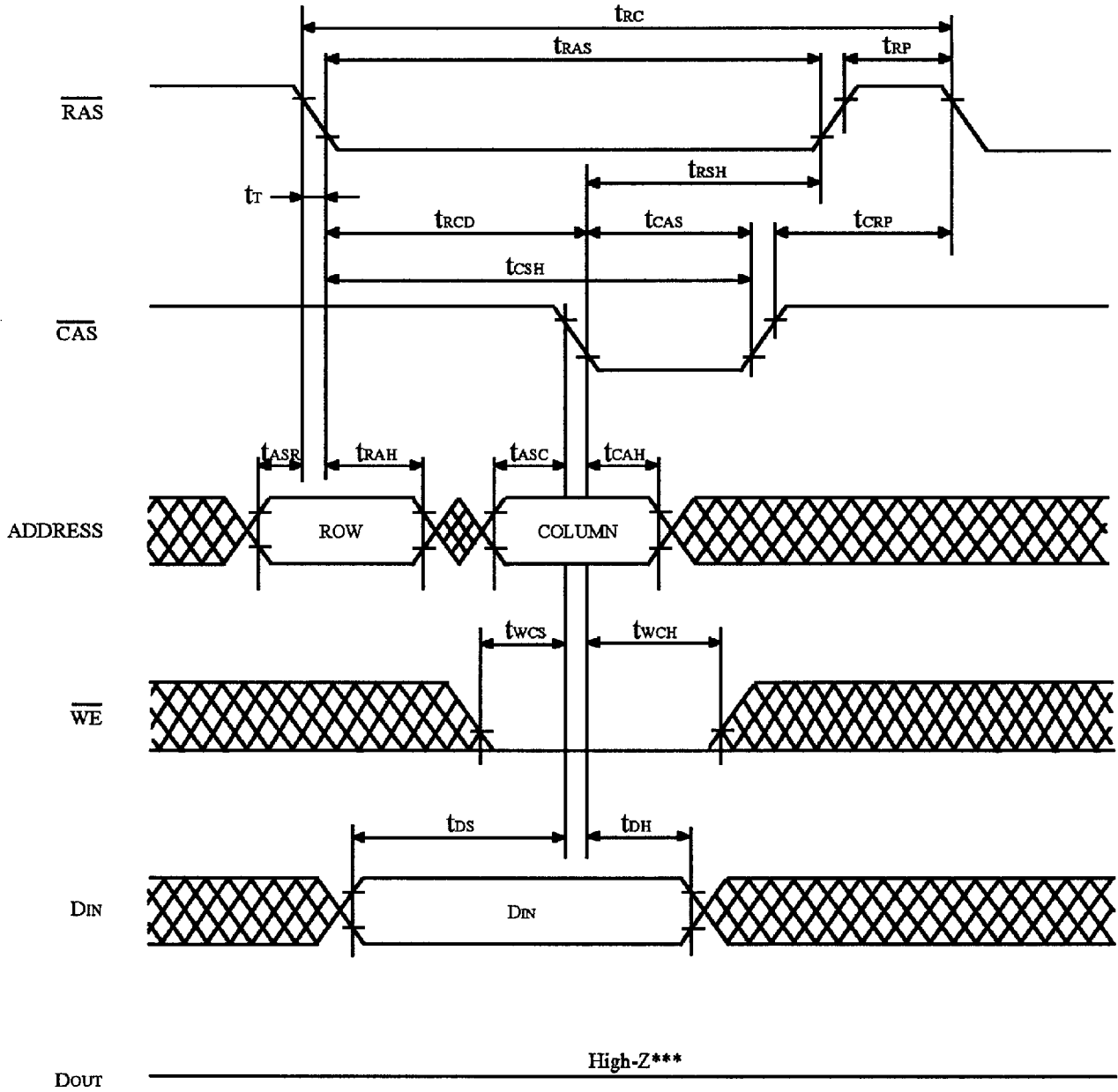


FIGURE 1. READ CYCLE




- *  : Don't care
- ** \overline{OE} : Don't care
- *** $t_{wcs} \geq t_{wcs}(\min)$

FIGURE 2. EARLY WRITE CYCLE

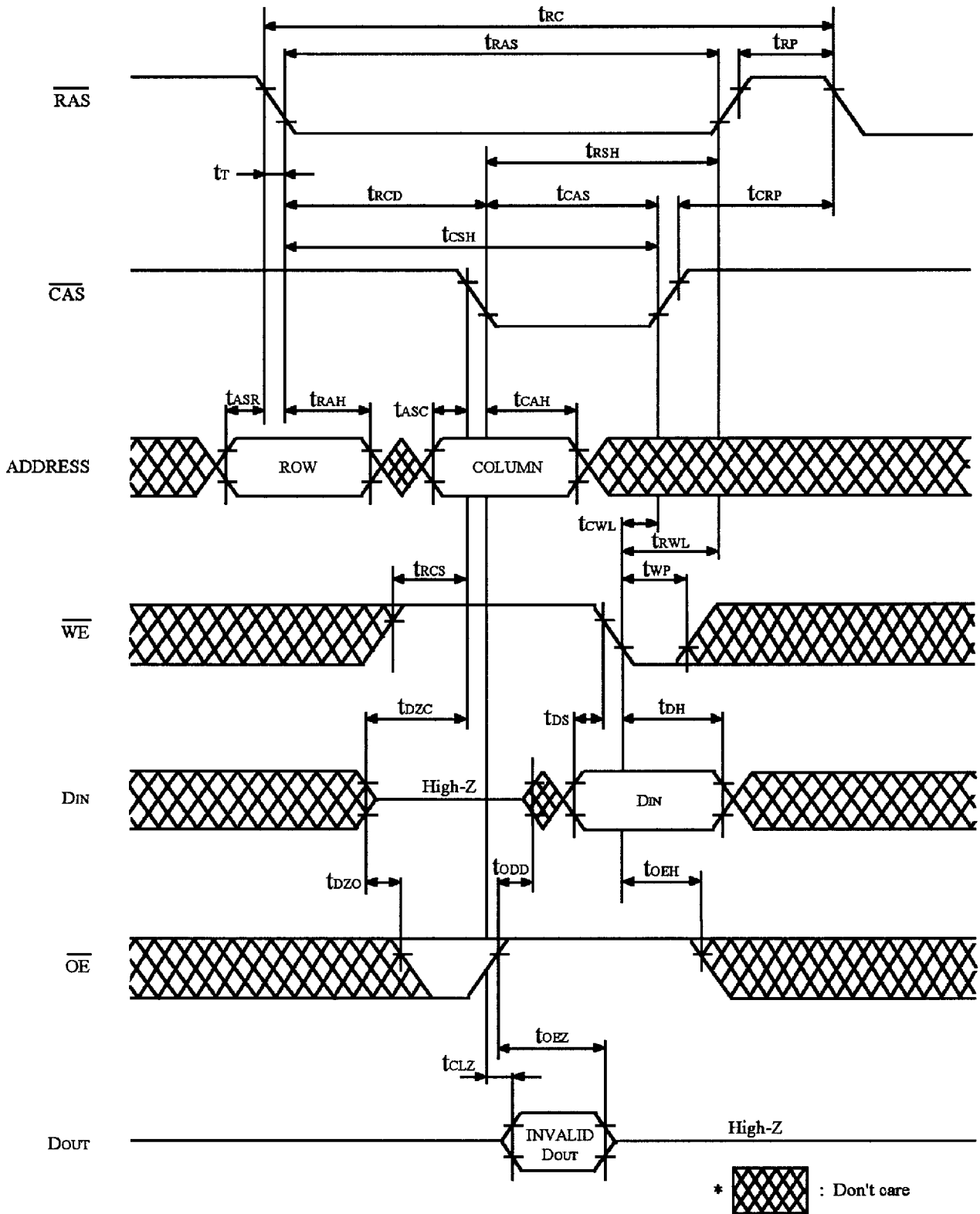


FIGURE 3. DELAYED WRITE CYCLE ^{*18}

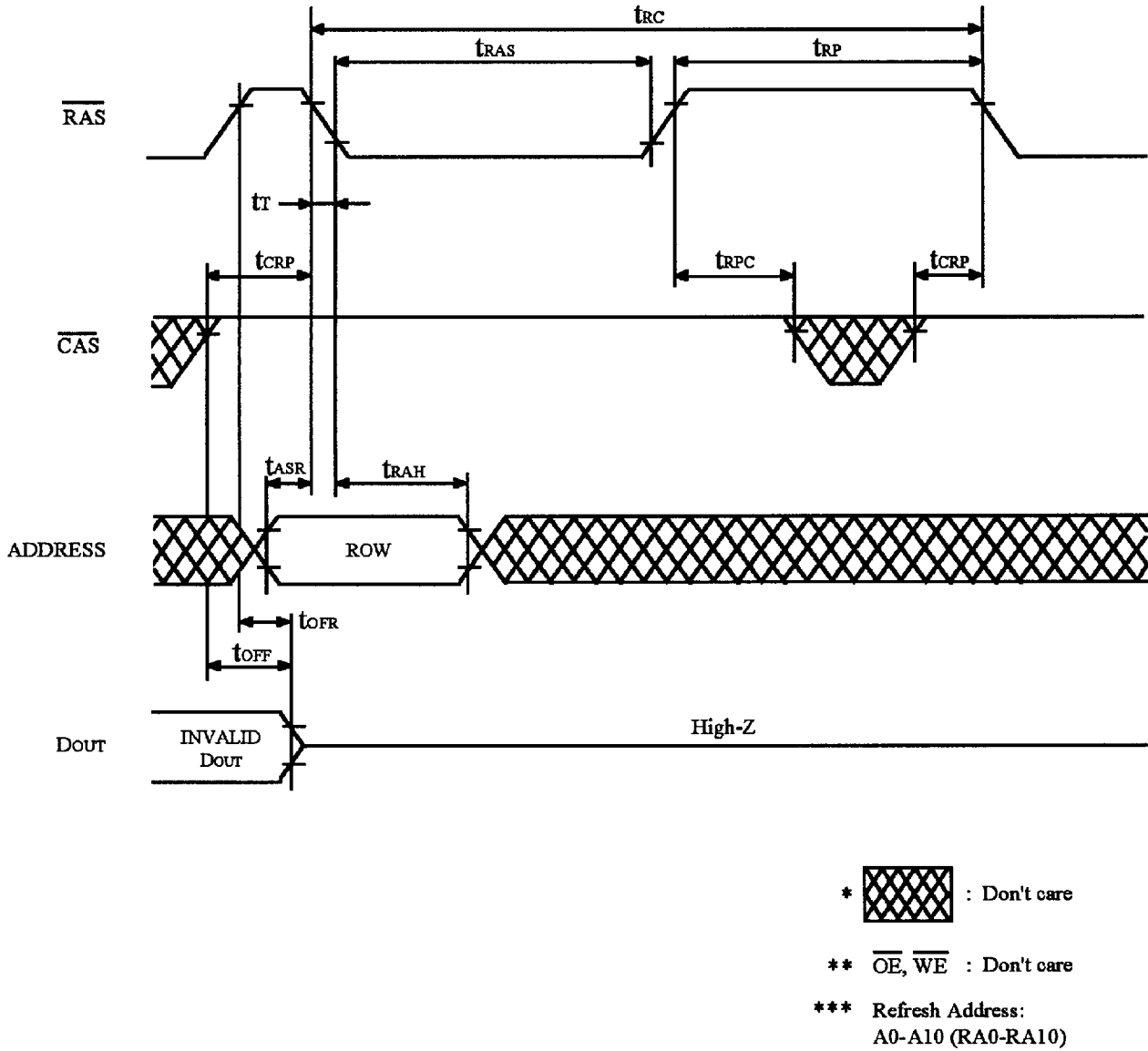
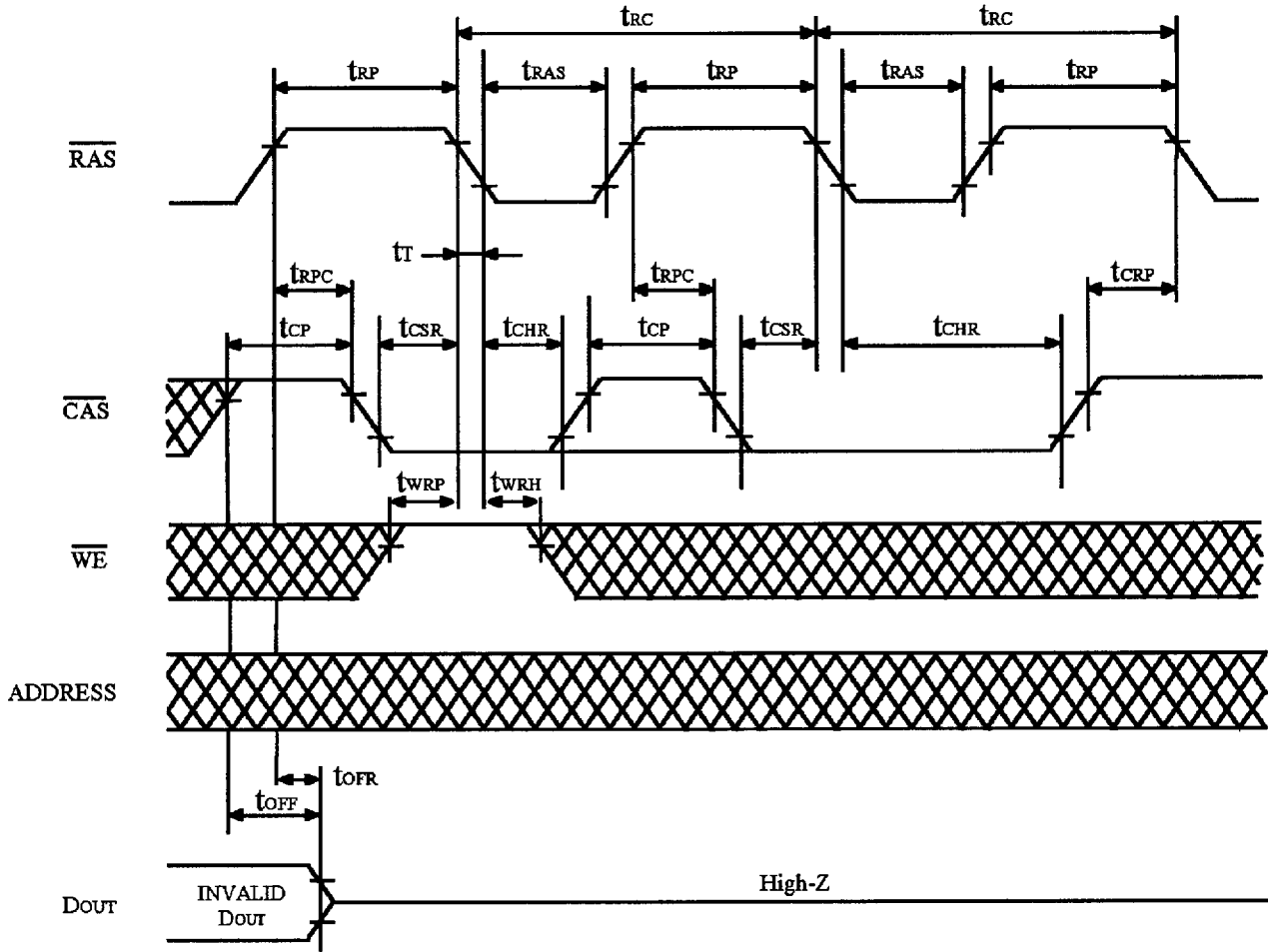



FIGURE 5. $\overline{\text{RAS}}$ ONLY REFRESH CYCLE



*  : Don't care

** \overline{OE} : Don't care

FIGURE 6. \overline{CAS} BEFORE \overline{RAS} REFRESH CYCLE

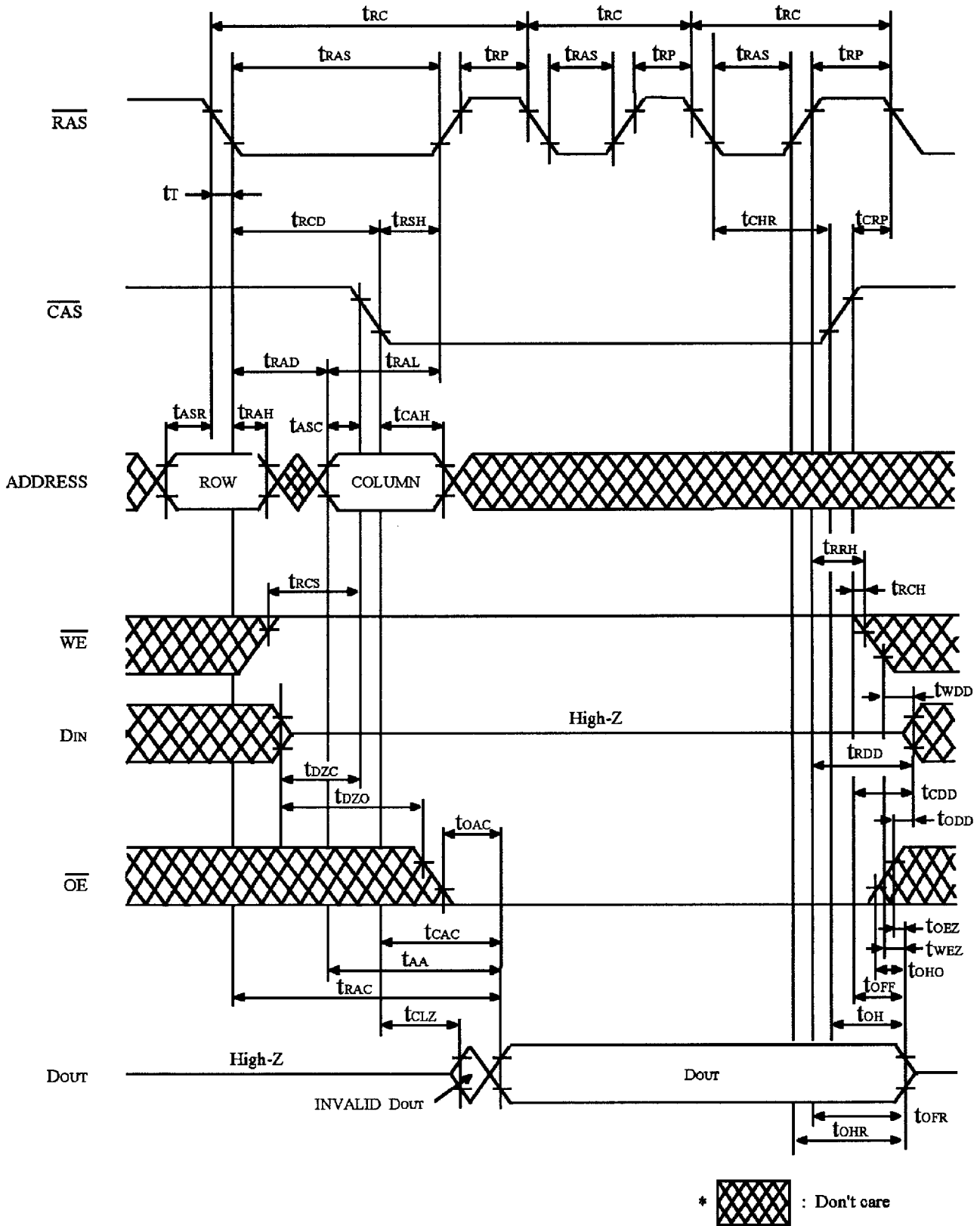
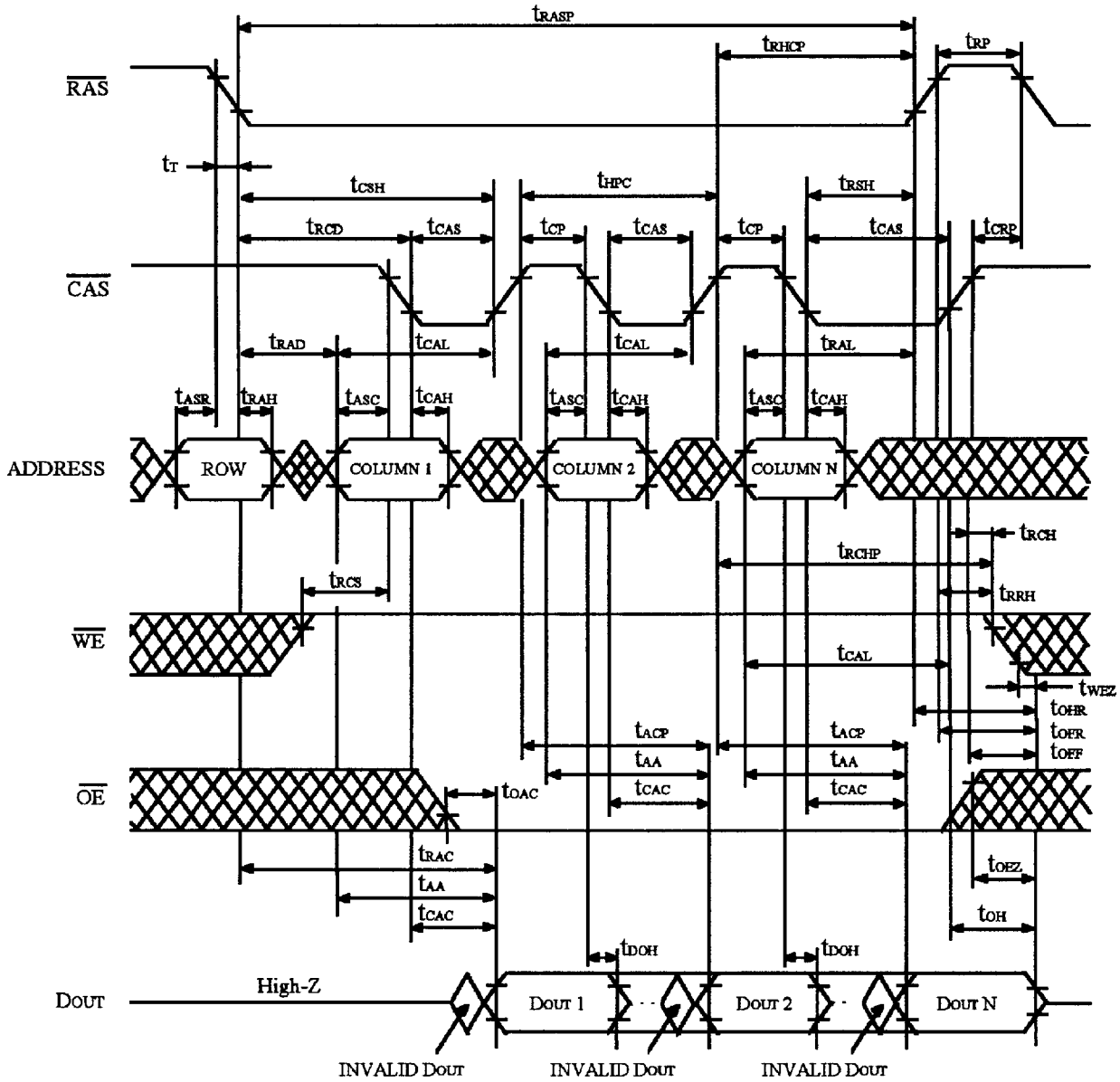


FIGURE 7. HIDDEN REFRESH CYCLE



*  : Don't care

FIGURE 8. EXTENDED DATA OUT MODE READ CYCLE

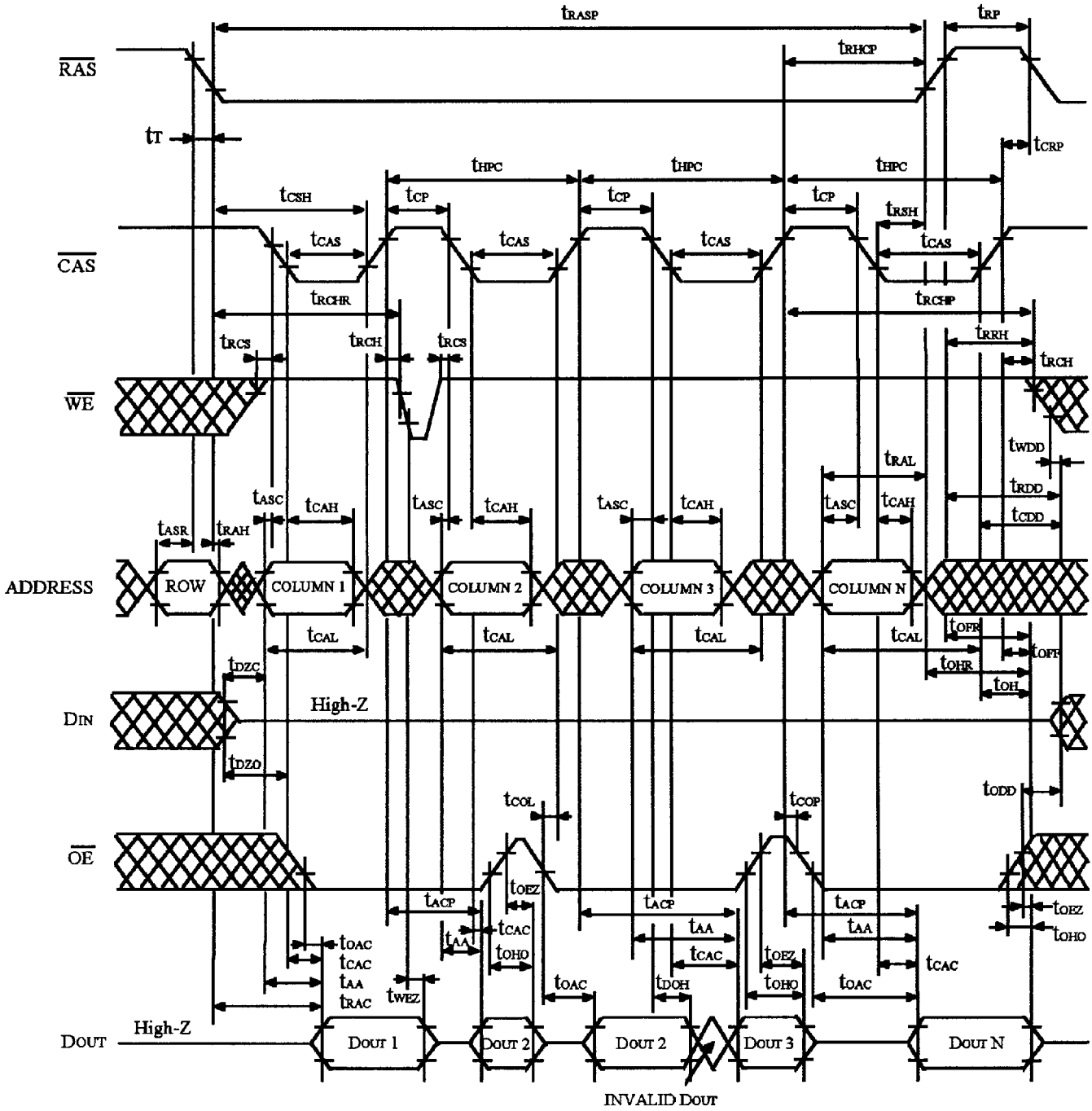


FIGURE 9. EXTENDED DATA OUT MODE READ CYCLE (\overline{OE} CONTROL) ^{*19}

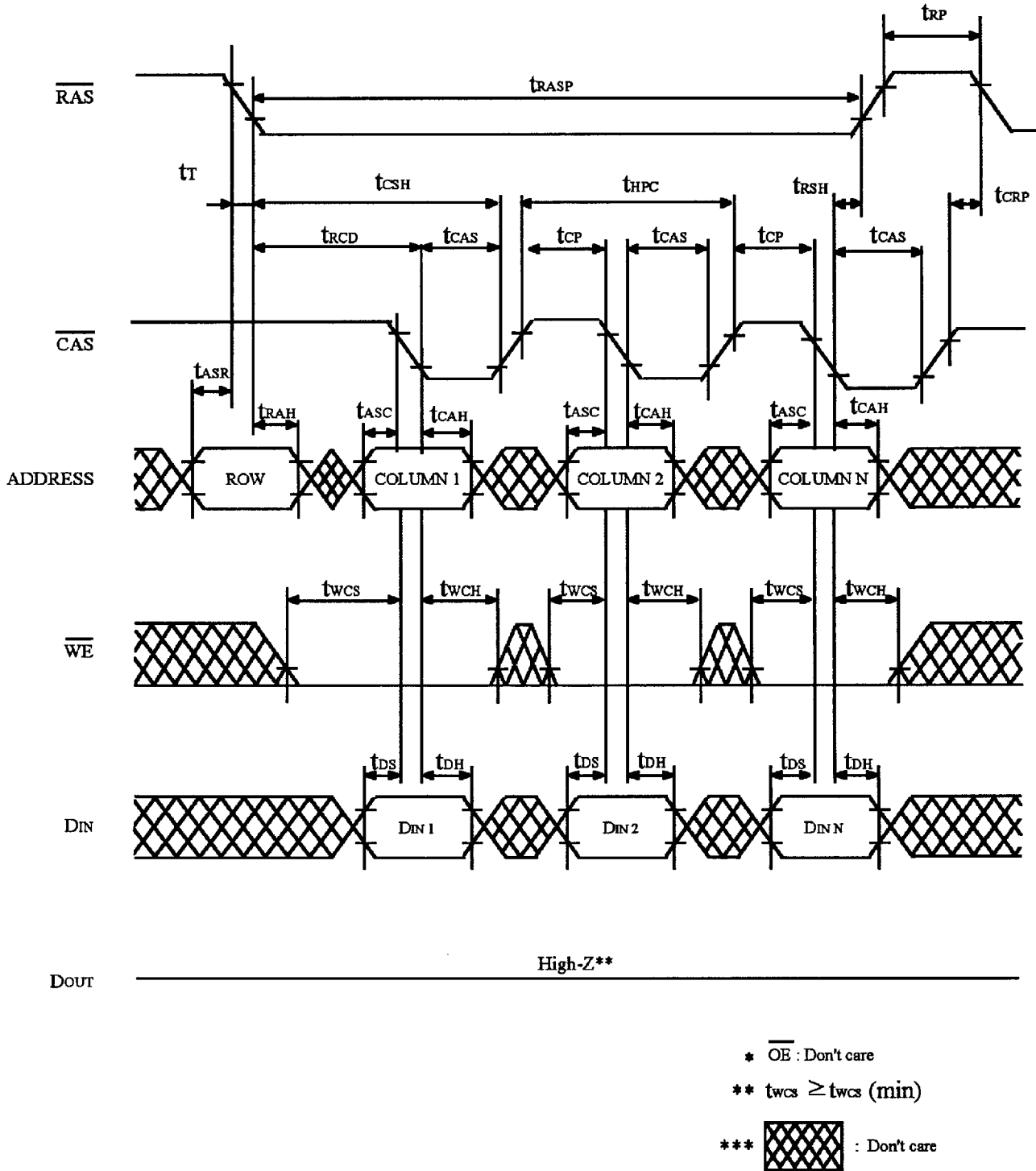


FIGURE 10. EXTENDED DATA OUT MODE EARLY WRITE CYCLE

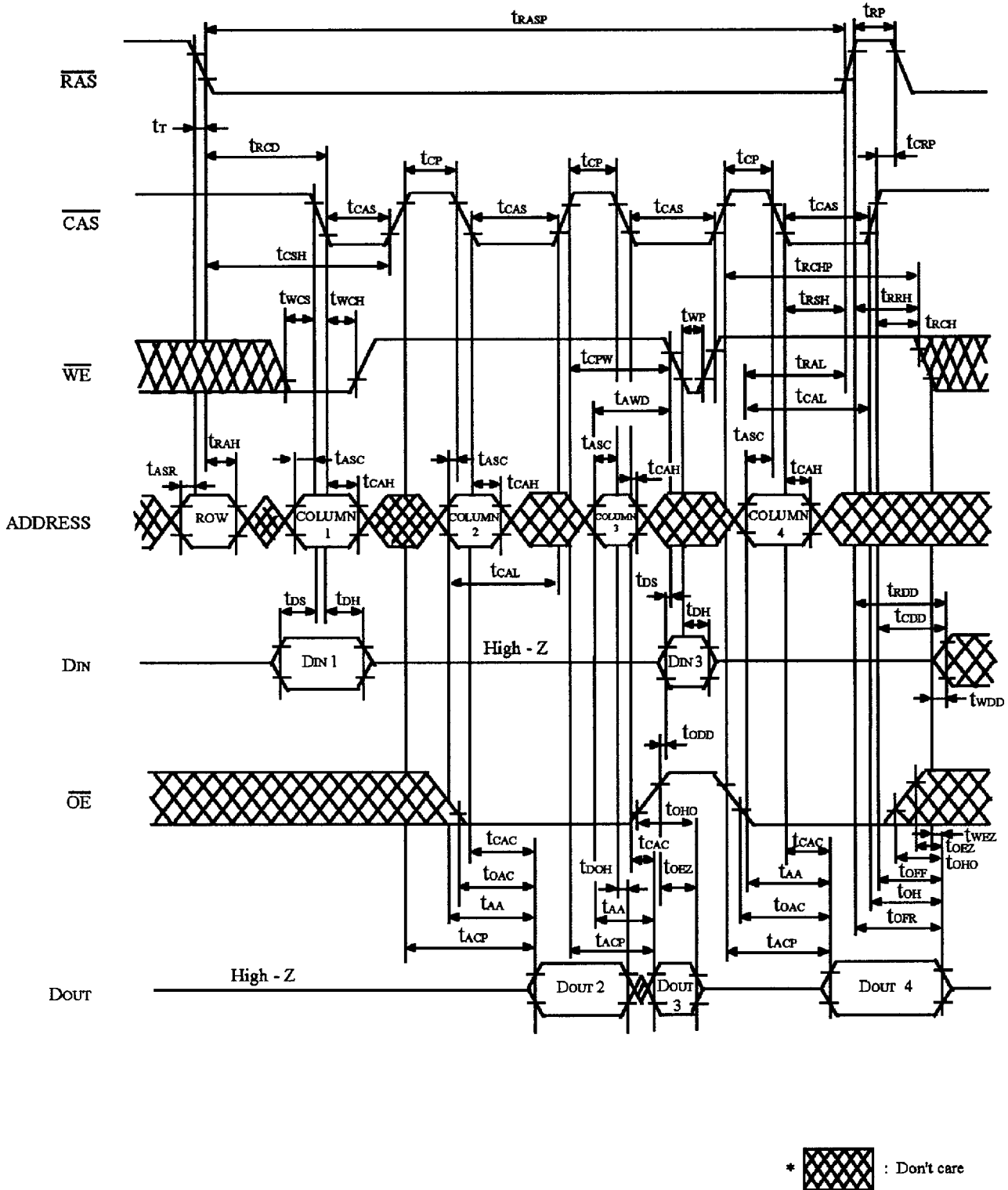
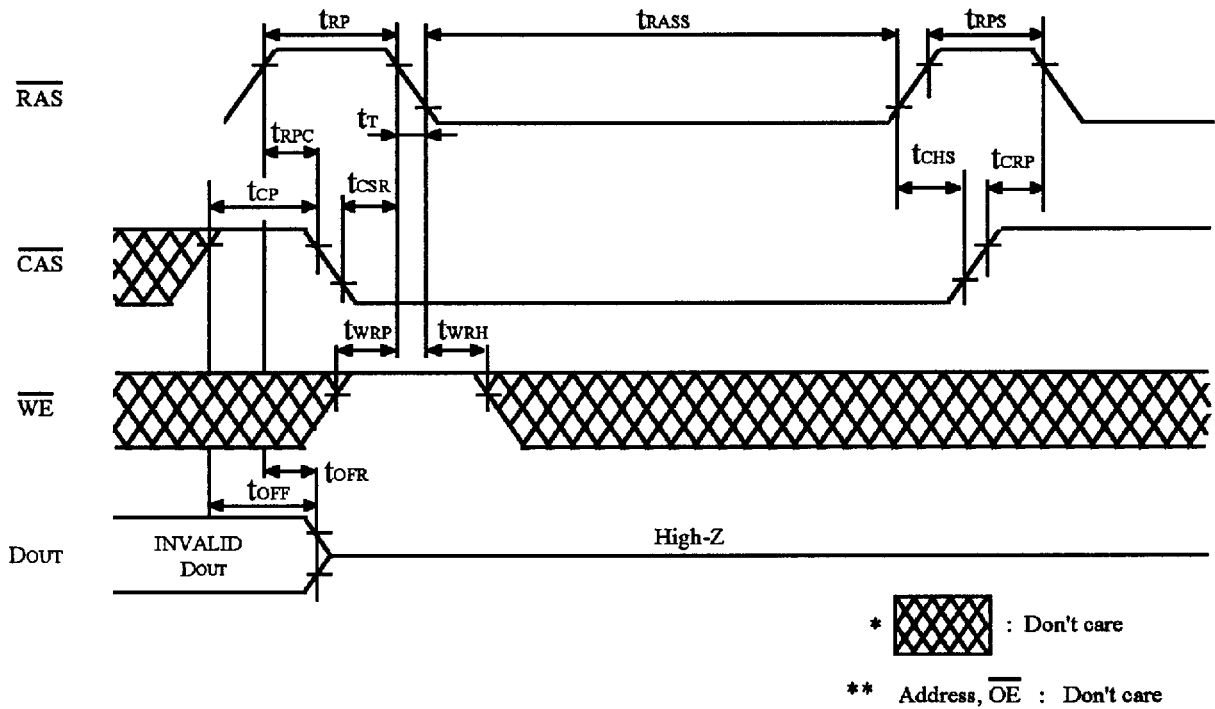


FIGURE 13. EXTENDED DATA OUT MODE MIX CYCLE (1) *20



The low self refresh current is achieved by introducing extremely long internal refresh cycle. Therefore some care needs to be taken on the refresh.

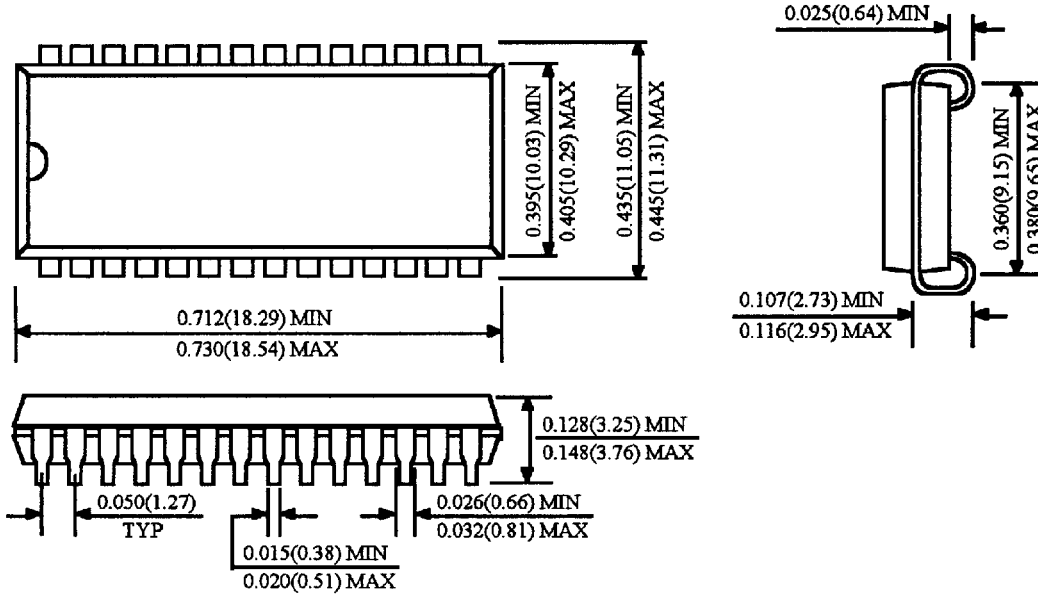
1. Please do not t_{TRASS} timing, $10\mu\text{s} \leq t_{TRASS} \leq 100\mu\text{s}$. During this period, the device is in transition state from normal operation mode to self refresh mode. If $t_{TRASS} \geq 100\mu\text{s}$, then $\overline{\text{RAS}}$ precharge time should use t_{TRPS} instead of t_{TRP} .
2. If you use $\overline{\text{RAS}}$ only refresh or CBR burst refresh mode in normal read/write cycle, 2048 cycles of distributed CBR refresh with $15.6\mu\text{s}$ interval should be executed within 32ms immediately after exiting from and before entering into the self refresh mode.
3. If you use distributed CBR refresh mode with $15.6\mu\text{s}$ interval in normal read/write cycle, CBR refresh should be executed within $15.6\mu\text{s}$ immediately after exiting from and before entering into the self refresh mode.
4. Repetitive self refresh mode without refreshing all memory is not allowed. Once you exit from self refresh mode, all memory cells need to be refreshed before re-entering the self refresh mode again.

FIGURE 15. SELF-REFRESH CYCLE

Package Dimensions

Unit: Inches (mm)

28 SOJ



28 TSOP II

