

DATA SHEET



GPC11256C

Sound Controller with 256KB ROM

JUL. 07, 2009

Version 1.2

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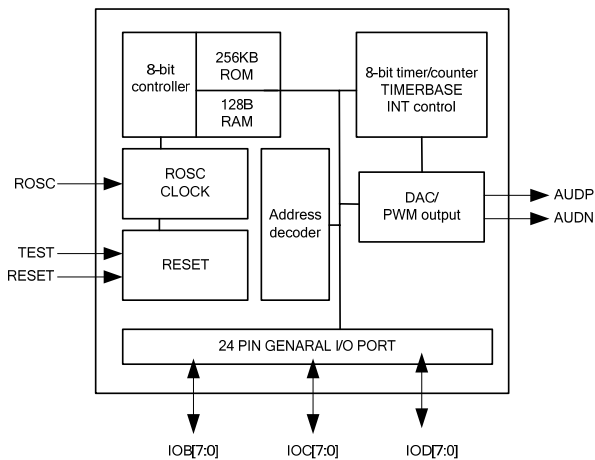
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SOUND CONTROLLER WITH 256KB ROM

1. GENERAL DESCRIPTION

The GPC11256C, a speech/wavetable synthesizer, equips an 8-bit CMOS microprocessor, and 256K-byte Working ROM, 128-byte working SRAM. Other primary features include two 8-bit Timer/Counters and can cascade to one 16-bit timer/counter, 24 Software Selectable I/Os, One 8-bit DAC and a pair of PWM output. It operates at a wide voltage range of 2.2V - 5.5V. Plus, a Clock Stop mode is built in for power savings. The unique power saving mode saves the RAM contents, but freezes the oscillator to stop executing other functions. The maximum CPU frequency can run up to 8MHz and the instruction cycle is two clock cycles (min.) ~ six clock cycles (max.). The GPC11256C loads, not only the latest technology, but also the full commitment and technical support of Generalplus.

2. BLOCK DIAGRAM



3. FEATURES

- 8-bit microprocessor
- 256K bytes ROM
- 128-byte working SRAM
- Software-based audio processing
- Wide operating voltage: 2.2V* - 5.5V @ 6.0MHz
3.6V - 5.5V @ 8.0MHz
*under the minimum operating voltage, the system clock would slow down very quickly.
- Supports ROSC only
- Standby mode (Clock Stop mode) for power savings
Max. 2.0μA @ 5.0V
- 24 general I/Os (include 4 high brightness LED driving I/O)
- Low Voltage Reset (LVR) function
- Two 8-bit timer/counters and can cascade to one 16-bit timer/counter
- Six INT sources
- Key wake -up function
- IR function
- External feedback input
- Watch dog function
- One DAC and A pair of PWM output

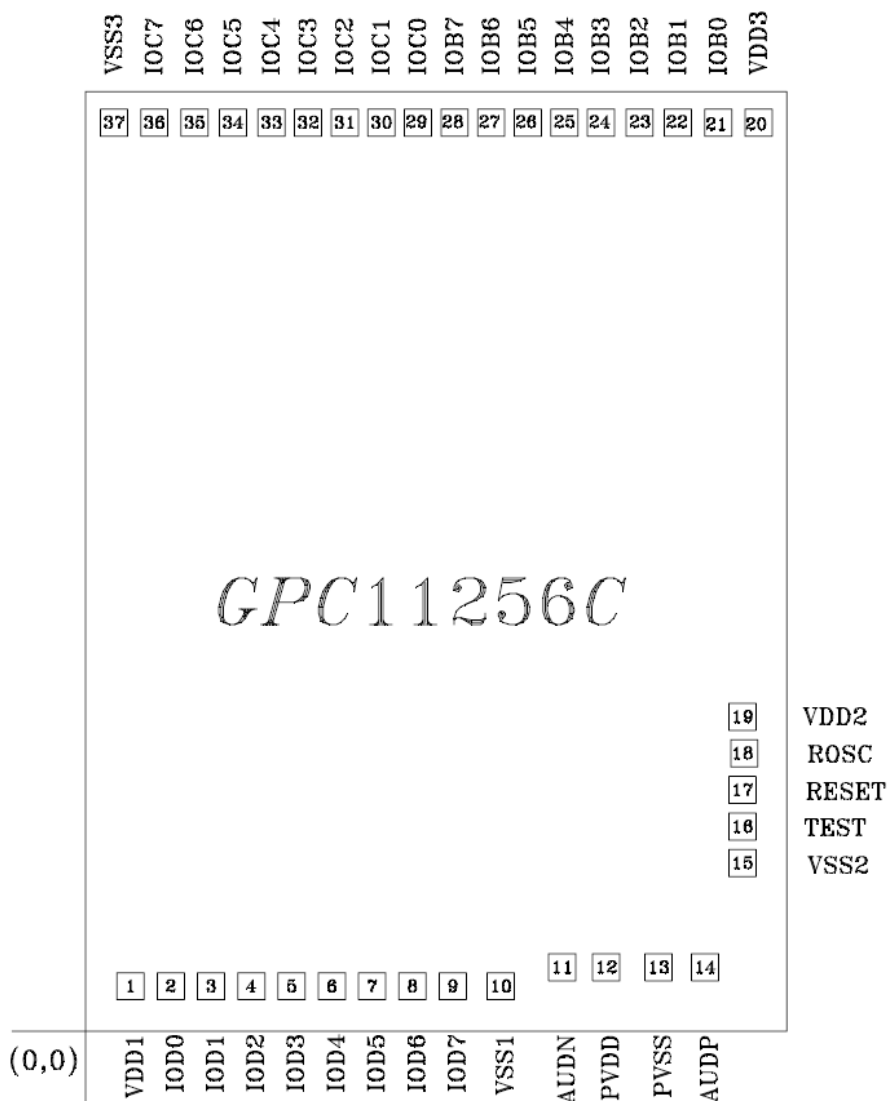
4. APPLICATION FIELD

- Intelligent education toys
Ex. Pattern to voice (animal, car, color, etc.)
Spelling (English or Chinese)
Math
- Advanced toy controller
- General speech synthesizer
- Industrial controller

5. SIGNAL DESCRIPTIONS

Mnemonic	PIN No	Type	Description
VDD1	1	I	Digital Power Pad
VSS1	10	I	Digital Ground
VDD2	19	I	Digital Power Pad
VSS2	15	I	Digital Ground
VDD3	20	I	Digital Power Pad
VSS3	37	I	Digital Ground
PVDD	12	I	PWM Power Pad
PVSS	13	I	PWM Ground
ROSC	18	I	ROSC Resistor input (Resistor must be connected to VDD)
RESET	17	I	Reset pin, active low to reset whole system
TEST	16	I	Test pin, NC
AUDP	14	O	Audio OUTPUT1
AUDN	11	O	Audio OUTPUT2
IOB0	21	I/O	Nibble-controlled programmable I/O pins In input mode, port B can be either pure or pull-low states. In output mode, port B can be buffer.
IOB1	22	I/O	
IOB2	23	I/O	
IOB3	24	I/O	
IOB4	25	I/O	
IOB5	26	I/O	
IOB6	27	I/O	
IOB7	28	I/O	
IOC0	29	I/O	Nibble-controlled programmable I/O pins In input mode, port C can be either pure or pull-low states. In output mode, port C can be buffer. IOC[3:0] can drive high brightness LED
IOC1	30	I/O	
IOC2	31	I/O	
IOC3	32	I/O	
IOC4	33	I/O	
IOC5	34	I/O	
IOC6	35	I/O	
IOC7	36	I/O	
IOD0	2	I/O	Bit-controlled programmable I/O pins In input mode, port D can be either pure or pull-low states In output mode, port D can be buffer Port D are the key wakeup I/O pins IOD4: feedback input of clock generator IOD5: feedback output of clock generator IOD6: external interrupt IOD7: IR transmitter
IOD1	3	I/O	
IOD2	4	I/O	
IOD3	5	I/O	
IOD4	6	I/O	
IOD5	7	I/O	
IOD6	8	I/O	
IOD7	9	I/O	

5.1. PAD Assignment



The IC substrate should be connected to VSS or floated

Note1: To ensure that the IC functions properly, please bond all of VDD and VSS pins.

Note2: The 0.1μF capacitor between VDD and VSS should be placed to IC as close as possible.

6. FUNCTIONAL DESCRIPTIONS

6.1. CPU

The microprocessor in GPC11256C is a high performance 8-bit processor equipped Accumulator, Program Counter, X and Y Register, Stack pointer and Processor Status Register (the same as the 6502 instruction structure). The maximum CPU speed of 8.0MHz is capable of bringing you the cleaner speech, pleasant music as well as achieving the best performance.

6.2. RAM Area

The total RAM size is 128-bytes (including Stack) starting from address \$0080 through \$00FF or mapping to \$0180 through \$01FF.

6.3. ROM Area

The GPC11256C provides a 256K-byte ROM that can be defined as the program area, audio data area, or both. To access ROM, users should program the BANK SELECT Register, choose bank, and access address to fetch data.

6.4. Map of Memory and I/Os

0x0000	IO
0x0017	
	Reserved
0x0080	SRAM
0x00FF	
	Reserved
0x0180	SRAM (Mapping)
0x01FF	
0x0200	
	Test Program
0x0600	User's Program & Data Area
0x3_FFFF	

6.5. I/O Port

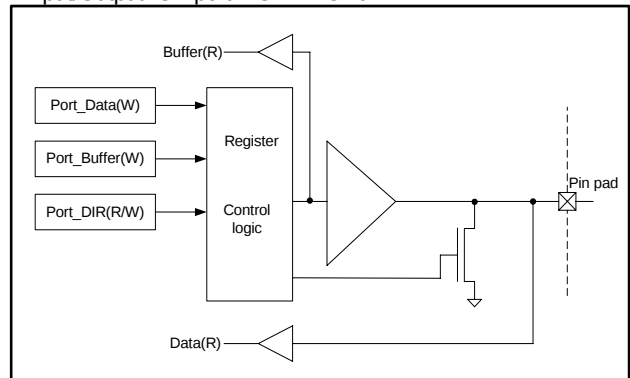
There are 24 I/Os (IOB7-0, IOC7-0 and IOD7-0) in the GPC11256C. IOB7-0 and IOC7-0 are nibble-controlled I/Os, but IOD7-0 are bit-controlled I/Os. They can be programmed as input (pure input or pull-low) or output buffer. As pull-low input IOD7-0 keep a less impedance to get good noise immunity. While pressing the key (IOD7-0 to VDD), a large impedance remained to save the DC power. IOD4, IOD5 can be programmed as a RC or crystal clock generator by adding external resistor and capacitor.

IOD6 can be programmed as an external interrupt source. IOD7 can be programmed as an IR transmitter.

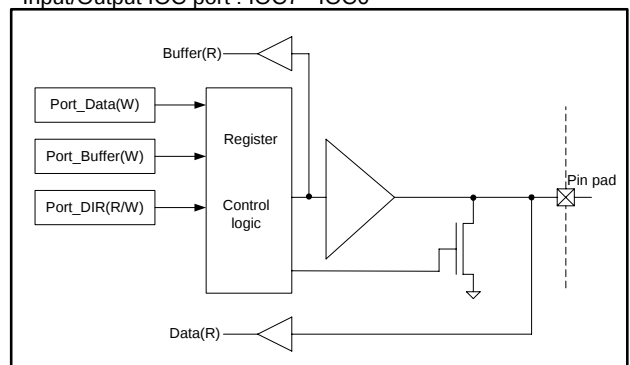
IOC[3:0] can sink high current to drive high brightness LED.

IO port configuration:

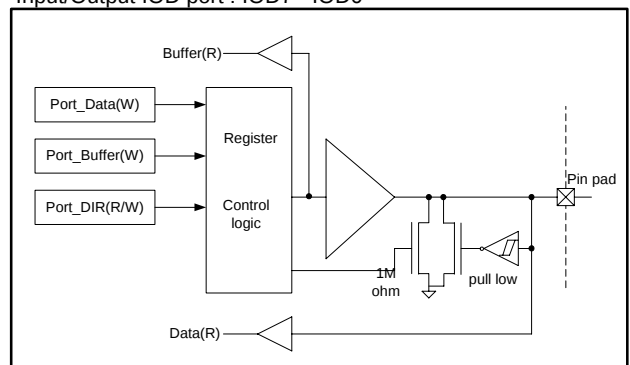
Input/Output IOB port : IOB7 - IOB0



Input/Output IOC port : IOC7 - IOC0



Input/Output IOD port : IOD7 - IOD0



6.6. Power Saving Mode

The GPC11256C includes a power saving mode (Standby mode) for those applications that require very low standby current. To enter standby mode, the Wake-Up Register must be enabled and then stop the CPU clock by writing the STOP CLOCK Register to enter standby mode. In such mode, RAM and I/Os will remain in their previous states until being awoken. Port IOD7-0 is the only wake-up source in the GPC11256C. After the GPC11256C is awoken, the internal CPU will go to the RESET State ($T_w \geq 64 \times T_1$) and continue to execute program. Wakeup Reset will not

affect RAM nor I/Os.

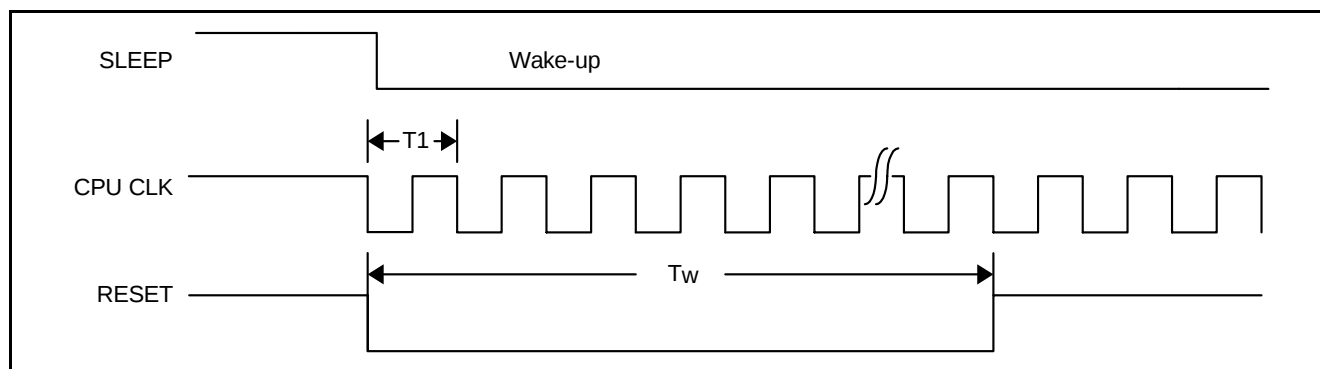


FIG. 1

$$T1 = 1 / (F_{CPU}), Tw \geq 64 \times T1$$

6.7. Timer/Counter

The GPC11256C has two 8-bit timer/counters, TMA and TMB respectively. TMA can be specified as a timer, but TMB can be used as a timer or a counter. In the timer mode, TMA and TMB are re-loaded up-counters. When timer rollovers from \$FF to \$00, the carry (overflow) signal will make the user's preset value to be loaded into timer automatically and up-count again. At the same

time, the carry signal will generate an INT signal if the corresponding bit is enabled in the INT ENABLE Register. Suppose TMB is specified as a counter, users can reset it by loading #0 into the counter. After the counter has been activated, the value in the counter can also be read at the same time. The read instruction will not affect the value of the counter nor reset it.

Clock source of Timer/Counter can be selected as follows:

Timer/Counter		Clock Source
TMA	8-BIT TIMER	CPU CLOCK (T) or T/8, T/64, TMB overflow
TMB	8-BIT TIMER	T, T/65536, EXTCLK, 0, 1

6.8. Speech and Melody

In speech synthesis, the GPC11256C can use NMI for accurate sampling frequency. The user can store the speech data in ROM and play it back with realistic sound quality. Several algorithms

are recommended for high fidelity and compression of sound: PCM, LOG PCM, ADPCM and SACMA3400.

7. ELECTRICAL SPECIFICATIONS

7.1. Absolute Maximum Ratings

Characteristics	Symbol	Ratings
DC Supply Voltage	V_+	< 7.0V
Input Voltage Range	V_{IN}	-0.5V to $V_+ + 0.5V$
Operating Temperature	T_A	0°C to +60°C
Storage Temperature	T_{STO}	-50°C to +150°C

Note: Stresses beyond those given in the Absolute Maximum Rating table may cause operational errors or damage to the device. For normal operational conditions see AC/DC Electrical Characteristics.

7.2. AC Characteristics ($T_A = 25^\circ\text{C}$)

Characteristics	Symbol	Limit			Unit	Test Condition
		Min.	Typ.	Max.		
OSC Frequency	F_{OSC2}	-	-	6.0	MHz	VDD = 2.2V - 3.6V, for 2-battery
		-	-	8.0	MHz	VDD = 3.6V - 5.5V, for 3-battery

7.3. DC Characteristics (VDD = 5.0V, $T_A = 25^\circ\text{C}$)

Characteristics	Symbol	Limit			Unit	Test Condition
		Min.	Typ.	Max.		
Operating Voltage	VDD	3.6	-	5.5	V	-
Operating Current	I_{OP}	-	5.0	-	mA	$F_{CPU} = 6.0\text{MHz}$ @ 5.0V(no load)
Standby Current	I_{STBY}	-	-	2.0	μA	VDD = 5.0V
Audio Output Current	I_{AUD}	-	5.0	-	mA	VDD = 5.0V
Input High Level	V_{IH}	3.0	-	-	V	VDD = 5.0V
Input Low Level	V_{IL}	-	-	0.8	V	VDD = 5.0V
Output Source Current (IOB,IOC, IOD)	I_{OH}	-	9	-	mA	VDD = 5.0V, $V_{OH} = 4V$
Output Sink Current (IOB,IOC[7:4], IOD)	I_{OL}	-	24	-	mA	VDD = 5.0V, $V_{OL} = 1V$
Output Sink Current (IOC[3:0])	I_{OL}	-	38	-	mA	VDD = 5.0V, $V_{OL} = 1V$
PWM Output Current	I_{OH}	-	-180	-	mA	VDD = 5.0V, $V_{OH} = 4.0V$
	I_{OL}	-	270	-	mA	VDD = 5.0V, $V_{OL} = 1.0V$
Input Resistor (IOB,IOC)	R_{IN}	-	85	-	$K\Omega$	VDD = 5.0V, $V_{IN} = VDD$
Input Resistor (IOD)	R_{IN}	-	85	-	$K\Omega$	VDD = 5.0V, $V_{IN} = 0V$
Input Resistor (IOD)	R_{IN}	-	760	-	$K\Omega$	VDD = 5.0V, $V_{IN} = VDD$

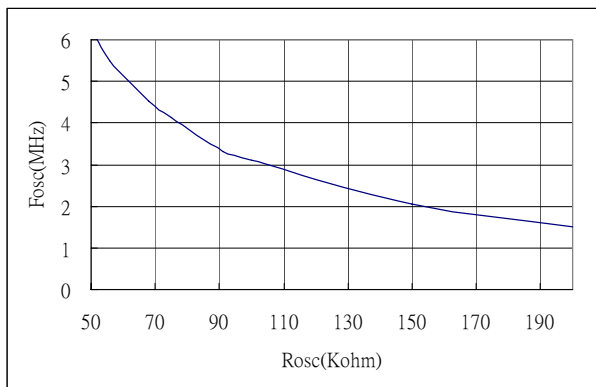
7.4. DC Characteristics (VDD = 3.0V, $T_A = 25^\circ\text{C}$)

Characteristics	Symbol	Limit			Unit	Test Condition
		Min	Typ	Max		
Operating Voltage	VDD	2.4	-	3.6	V	-
Operating Current	I_{OP}	-	1.6	-	mA	$F_{CPU} = 6.0\text{MHz}$ @ 3.0V(no load)
Standby Current	I_{STBY}	-	-	2.0	μA	VDD = 3.0V
Audio Output Current	I_{AUD}	-	2.4	-	mA	VDD = 3.0V
Input High Level	V_{IH}	2.0	-	-	V	VDD = 3.0V

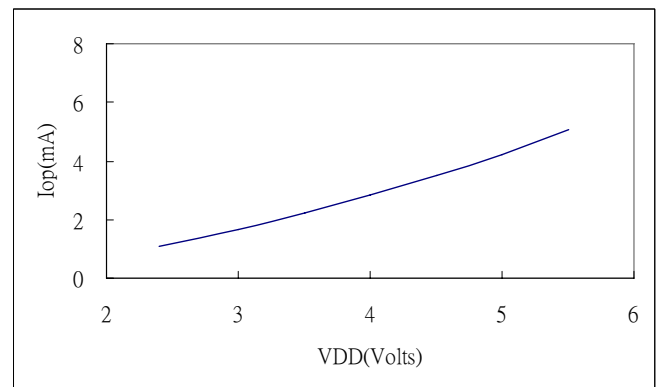
Characteristics	Symbol	Limit			Unit	Test Condition
		Min	Typ	Max		
Input Low Level	V_{IL}	-	-	0.8	V	VDD = 3.0V
Output Source Current (IOB, IOC, IOD)	I_{OH}	-	4	-	mA	VDD = 3.0V, $V_{OH} = 2.4V$
Output Sink Current (IOB, IOC[7:4], IOD)	I_{OL}	-	11	-	mA	VDD = 3.0V, $V_{OL} = 0.6V$
Output Sink Current (IOC[3:0])	I_{OL}	-	18	-	mA	VDD = 3.0V, $V_{OL} = 0.6V$
PWM Output Current	I_{OH}	-	-100	-	mA	VDD = 3.0V, $V_{OH} = 2.4V$
	I_{OL}	-	120	-	mA	VDD = 3.0V, $V_{OL} = 0.6V$
Input Resistor (IOB, IOC)	R_{IN}	-	170	-	K Ω	VDD = 3.0V, $V_{IN} = VDD$
Input Resistor (IOD)	R_{IN}	-	170	-	K Ω	VDD = 3.0V, $V_{IN} = 0V$
Input Resistor (IOD)	R_{IN}	-	1600	-	K Ω	VDD = 3.0V, $V_{IN} = VDD$

7.5. The Relationship between the R_{OSC} and the F_{CPU}

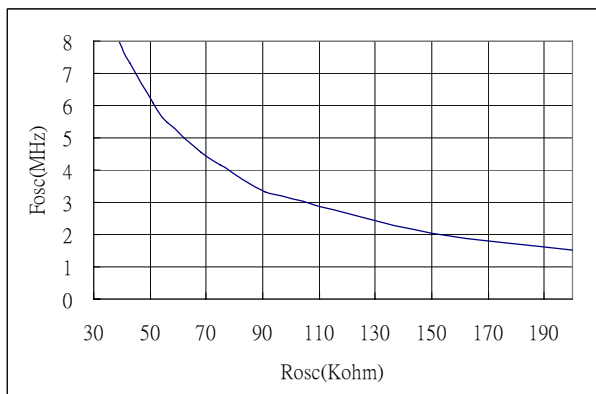
7.5.1. VDD = 3.0V, $T_A = 25^\circ C$



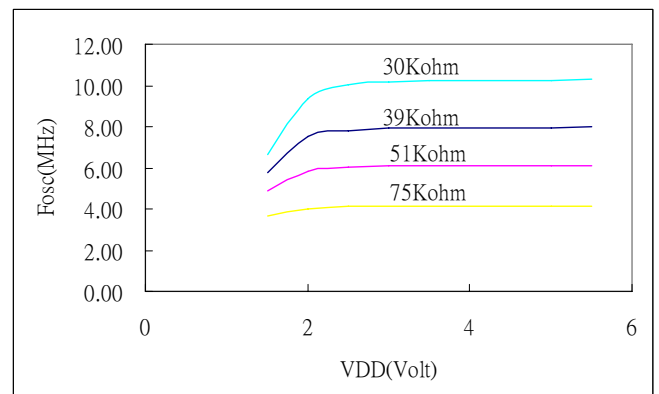
7.5.3. Operating Current vs. VDD(no load, $F_{CPU}=6MHz$)



7.5.2. VDD = 4.5V, $T_A = 25^\circ C$

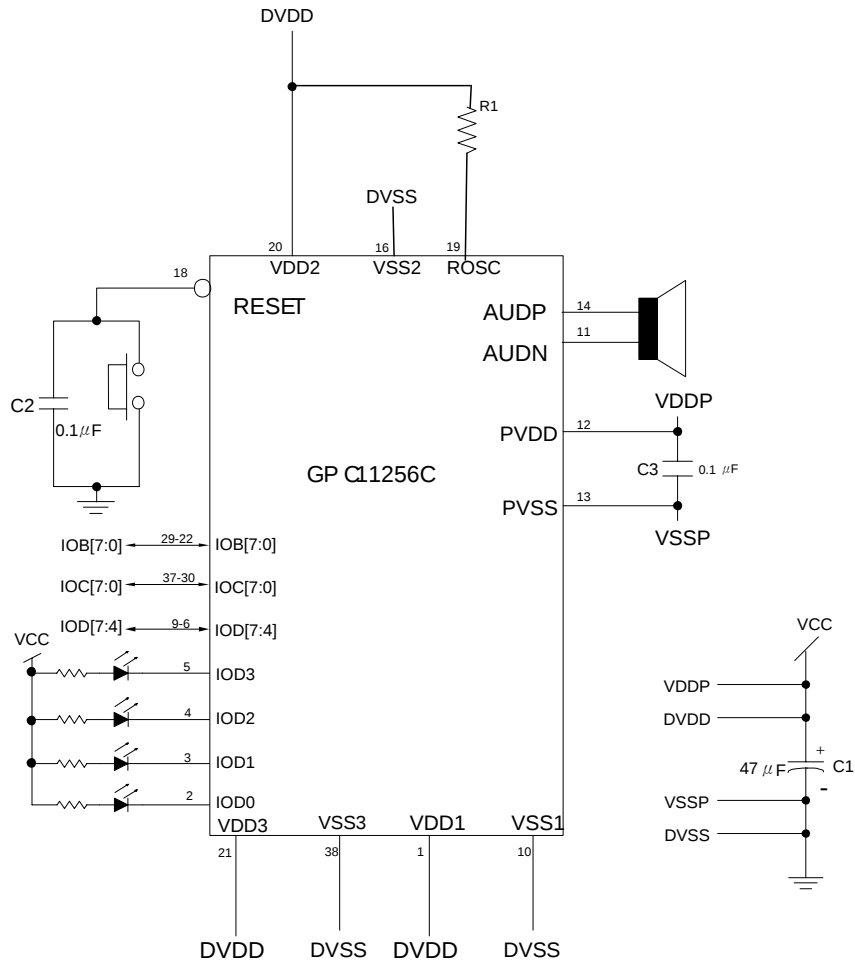


7.5.4. Frequency vs. VDD



8. APPLICATION CIRCUITS

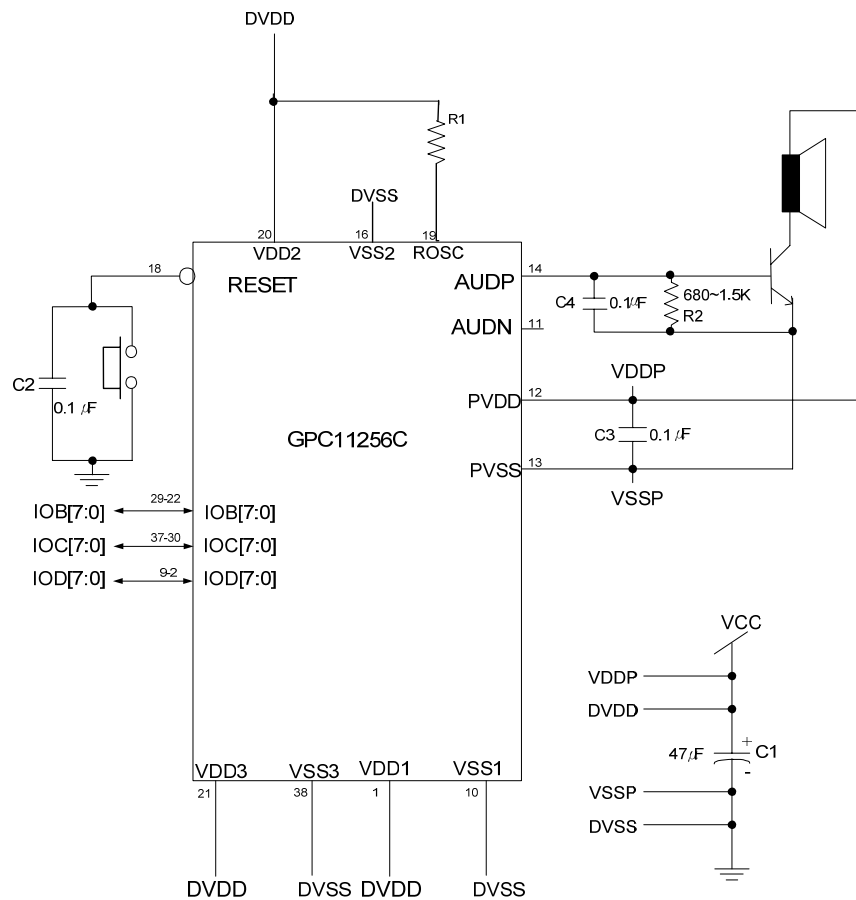
8.1. PWM Output and LED



PCB Layout Guidelines :

- 1.VDD1, VDD2, VDD3, PVDD must be connected to power input port directly, not to be the branch of each other.
- 2.VSS1, VSS2, VSS3, PVSS must be connected to ground input port directly, not to be the branch of each other.
- 3.R1 should be as close as possible to ROSC pin.
- 4.C3 should be as close as possible to PVDD/PVSS pin.
- 5.More capacitors are needed for a high loading application. Please refer to application note for more detail.

8.2. DAC Output and IR Function



PCB Layout Guidelines :

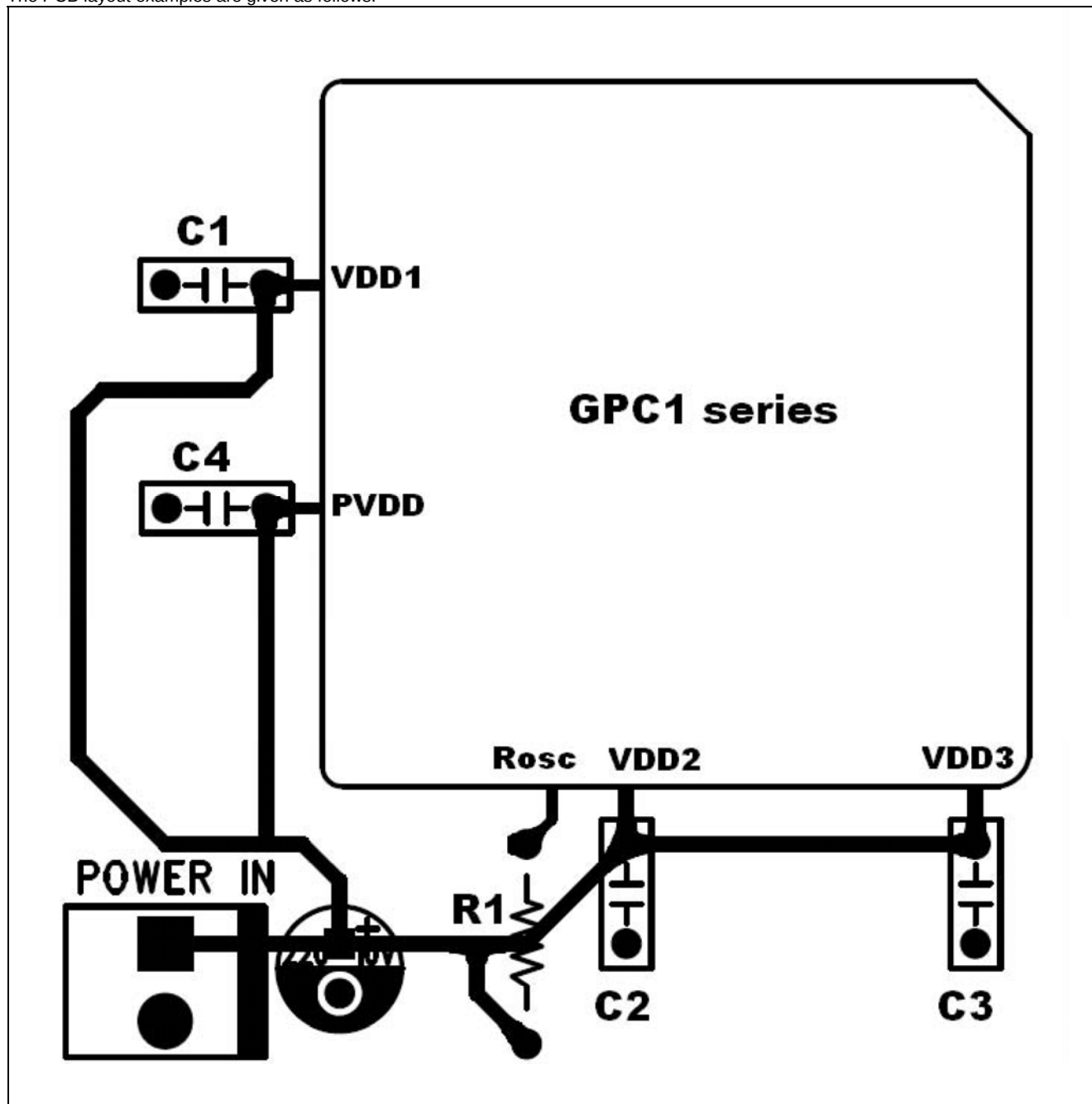
1. VDD1, VDD2, VDD3, PVDD must be connected to power input port directly, not to be the branch of each other.
2. VSS1, VSS2, VSS3, PVSS must be connected to ground input port directly, not to be the branch of each other.
3. R1 should be as close as possible to ROsc pin.
4. C3 should be as close as possible to PVDD/PVSS pin.
5. More capacitors are needed for a high loading application. Please refer to application note for more detail.

9. PCB LAYOUT GUIDE FOR HEAVY LOADING APPLICATION

To avoid the unexpected noises to end up with abnormal CPU operations, the following cares must be exercised while doing the PCB layout:

1. Bond all VDD and VSS pins out.
2. The 0.1 μ F capacitor (C1-C4) placed between VDD and VSS must be as closed as possible to IC itself.
3. The ROSC resistor R1 must be as closed as possible to IC itself.

The PCB layout examples are given as follows:



10. PACKAGE/PAD LOCATIONS

10.1. Ordering Information

Product Number	Package Type
GPC11256C - NnnV - C	Chip form

Note1: Code number is assigned for customer.

Note2: Code number (N = A - Z or 0 - 9, nn = 00 - 99); version (V = A - Z).

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12. REVISION HISTORY

Date	Revision #	Description	Page
JUL. 07, 2009	1.2	1. Modify 1. GENERAL DESCRIPTION.	3
		2. Modify 2. BLOCK DIAGRAM	3
		3. Modify 3. FEATURES.	3
		4. Delete 6.7 Low Voltage Reset.	7
		5. Modify 7.2 AC Characteristics.	8
		6. Modify section 8. APPLICATION CIRCUITS.	10, 11
MAY 21, 2008	1.1	Add section 9. PCB LAYOUT GUIDE.	12
JAN. 03, 2008	1.0	Release to 1.0.	14
APR. 04, 2007	0.3	Modify the "Low Voltage Reset" in section 6.7.	6
MAR. 16, 2007	0.2	1. Modify the "ELECTRICAL SPECIFICATIONS" in section 7.	7
		2. Modify the "APPLICATION CIRCUITS" in section 8.	9
		3. Modify the "PAD Assignment" in section 9.1.	11
JAN. 09, 2007	0.1	Original	13