

AUTOMOTIVE CURRENT TRANSDUCER HAG 240-V/SP1



Introduction

The HAG Family is best suited for DC, AC or pulsed currents measurement in high power and low voltage automotive applications. It's contains galvanic isolation between the primary circuit (high power) and the secondary circuit (electronic circuit).

The HAG family gives you a choice of having different current measuring ranges in the same housing (from \pm 50 A up to \pm 250 A).

Features

- Open Loop transducer using the Hall effect sensor
- Low voltage application
- Unipolar + 5 V DC power supply
- Primary current measuring range from 0 A up to 240 A
- Maximum rms primary current limited by the busbar, the magnetic core or the ASIC temperature T° < + 150°C
- Operating temperature range: 40°C < T° < + 125°C
- Output voltage: full ratio-metric (in gain and offset).

Advantages

- · Good accuracy for high and low current range
- Good linearity
- Low thermal offset drift
- Low thermal gain drift
- Hermetic package.

Automotive applications

- Battery Pack Monitoring
- Hybrid Vehicles
- EV and Utility Vehicles.

Principle of HAG Family

The open loop transducers use an Hall effect integrated circuit. The magnetic flux density B, contributing to the rise of the Hall voltage, is generated by the primary current I_p to be measured. The control current I_p is supplied by a current source i.e. battery or generator (Fig. 1).

Within the linear region of the hysteresis cycle, B is proportional to:

B
$$(\mathbf{I}_{P})$$
 = constant (a) x \mathbf{I}_{P}

The Hall voltage is thus expressed by:

$$\mathbf{V}_{H} = (\mathbf{R}_{H}/\mathbf{d}) \times \mathbf{I} \times \text{constant}$$
 (a) $\times \mathbf{I}_{F}$

Except for $\mathbf{I}_{\mathrm{p}},$ all terms of this equation are constant. Therefore:

$$\mathbf{V}_{H}$$
 = constant (b) x \mathbf{I}_{P}

The measurement signal $\mathbf{V}_{_{\!H}}$ amplified to supply the user output voltage or current.



Fig. 1: Principle of the open loop transducer

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Dimensions HAG 240-V/SP1 family (in mm. 1mm = 0.0394 inch)



System Architecture

	LEM Transducer Electronic Controller Modu	lle
	Primary current Primary current Primary current Primary current Primary current Primary current Primary current Primary current Primary current Primary current Primary current Primary current Primary current Primary current Primary Current Current Primary Current Curren	+ 5V
>PA66- GF25 FR< (UL94 V0) FeSi alloy	\mathbf{R}_{L} > 10 K Ω optional resistor for signal line diagnost	tic
Brass tin platted	C _L > 100 nF EMC protection	
25 g	RC = Low pass filter EMC protection (optinal).	Pag

Magi
Pins
m

Bill of materialsPlastic caseMagnetic core



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Absolute maximum ratings (not operating)

Parameter	Symbol	Unit		Specificatio	n	Que all'élique a				
			Min	Typical	Max	Conditions				
Electrical Data										
Max primary current peak	I _{Pmax}	A			1)					
Supply continuous over voltage					8.5					
Supply over voltage	v _c −	V			14	1 min @ T _A = 25°C				
Reverse voltage			-14			1 min @ T _A = 25°C				
Output over voltage (Analog)	- V _{out}	V			8.5					
Output over voltage		v			14	1 min @ T _A = 25°C				
Continuous output current	I _{OUT}	mA	-10		10					
Output short circuit duration	T _c	min			2					
Rms voltage for AC isolation test	V _d	kV			2	50Hz, 1min				
Isolation resistance	R _{is}	MΩ	500			500 V - ISO 16750-2				
Electrostatic discharge voltage	V _{ESD}	kV			2	JESD22-A114-B				
Ambient storage temperature	T _s	°C	-40		+125					

Operating characteristics

Paramotor	Symbol	Unit		Specificatio	n	Conditions			
Farameter	Symbol		Min	Typical	Max	Conditions			
Electrical data									
Primary current	I _P	A	0		240				
Calibration current		А	0		120	@ T _A = 25°C			
Supply voltage	V _c	V	4.5	5.00	5.5				
Output voltage (Analog) 2)	V _{OUT}	V	$\boldsymbol{V}_{\text{out}} = \frac{\boldsymbol{V}_{c}}{5} \times (0.5 + \boldsymbol{G} \times \boldsymbol{I}_{P})$			@ V _c			
Sensitivity 2)	G	mV/A		16.67		@ V _c = 5 V			
Current consumption		mA		7.5	10	@ $V_{c} = 5 V$, -40°C < $T_{A} < 125$ °C			
Power up inrush current	LC C	mA			20	@ V _c < 3.5 V			
Load resistance	R	KΩ	10						
Output internal resistance	R _{OUT}	Ω			10				
Capacitive loading	С _.	nF	1		100				
Ambient operating temperature	T _A	°C	-40		125				
Output drift versus power supply	V _{OUT PS}	%		0.5					
Frequency bandwidth ³⁾	BW	Hz			80	@ -3 dB			
Output clamping voltage min	v	V	0.2	0.25	0.3	@ V _c = 5 V			
Output clamping voltage max	• sz	V	4.7	4.75	4.8	@ V _c = 5 V			
Output voltage noise peak-peak	V _{no pp}	mV			10				
Resolution		mV		2.5		@ V _c = 5 V			
Power up time		ms		25	110				
Settling time after over load		ms			25				

Notes: ¹⁾ Busbar temperature must be below 150°C ²⁾ The output voltage **V**_{OUT} is fully ratiometric. The offset and sensitivity are dependent on the supply voltage **V**_C relative to the following formula:

$$\mathbf{I}_{P} = \left(\frac{5}{V_{C}} \times V_{OUT} - 0.5\right) \times \frac{1}{G} \qquad \text{with } \mathbf{G} \text{ in (V/A)}$$

³⁾ Tested only with small signal only to avoid excessive heating of the magnetic core.

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Accuracy

Parameter	Symbol	Unit	Specification			Conditions				
			Min	Тур	Max	Conditions				
Performance Data										
Global offset current	I _o	A		± 0.3		@ T _A = 25°C				
				± 0.5		@ - 20°C < T° < 65°C				
				± 0.6		@ - 40°C < T° < 125°C				
Sensitivity error	E _G	%		± 0.8		@ T _A = 25°C				
				± 2		@ - 20°C < T° < 65°C				
				± 4		@ - 40°C < T° < 125°C				
Linearity error	٤	%		± 1		of full range, @ T _A = 25°C				

Global error table

Parameter	Symbol	Unit	Temperature T° (°C)							
			-40°C	-20°C	0°C	25°C	65°C	125°C		
Global offset error		•	± 0.90	± 0.81	± 0.72	± 0.60	± 0.76	± 1.00		
Global error at 120A		А	± 6.00	± 5.40	± 4.80	± 4.10	± 5.30	± 7.00		
Global error at 240A			± 13.00	± 11.60	± 10.10	± 8.30	± 10.60	± 14.10		





HAG 240-V/SP1 PERFORMANCES PARAMETERS DEFINITIONS

Output noise voltage:

The output voltage noise is the result of the noise floor of the Hall elements and the linear ${\rm I_c}$ amplifier gain.

Magnetic offset:

The magnetic offset is the consequence of an over-current on the primary side. It's defined after an excursion of $I_{P max}$.

Linearity:

It's the maximum positive or negative discrepancy with a reference straight line $V_{\text{out}} = f(I_{\text{P}})$.

Unit: linearity (%) expressed with full scale of I_{P max}.



Response time (delay time) t,:

The time between the primary current signal and the output signal reach at 90 % of its final values



Typical value @ T_A : The maximum of 90% of the values found in production.

Sensitivity:

The Transducer's sensitivity **G** is the slope of the straight line $V_{out} = f(I_p)$, it must establish the relation: $V_{out} = V_C/5 (G \times I_p + 0.5)$

Offset with temperature:

The error of the offset in the operating temperature Eoffset is the relative variation of the offset in the temperature considered with the initial offset at 25° C.

The offset variation \mathbf{TCV}_{OUT} in the operating temperature is the slope of Eoffset = f(T).

Sensitivity with temperature:

The error of the sensitivity in the operating temperature is the relative variation of sensitivity with the temperature considered with the initial offset at 25° C.

The sensitivity variation $\mathbf{TC}_{\epsilon G}$ in the temperature is the slope of Eoffset = f(T).

Offset voltage @ I_P = 0 A:

Is the output voltage when the primary current is null. The ideal value of V_{o} is $V_{c}/2$. So, the difference of V_{o} - $V_{c}/2$ is called the total offset voltage error can be attributed to the electrical offset. (due to the resolution of the ASIC quiescent voltage trimming), the magnetic offset, the thermal drift and the thermal hysteresis.

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