2.5-V Phase-lock Loop Clock Driver

HITACHI

ADE-205-335C (Z) Preliminary 4th Edition March 2000

Description

The HD74CDCV857 is a high-performance, low-skew, low-jitter, phase locked loop clock driver. It is specifically designed for use with DDR (Double Data Rate) synchronous DRAMs.

Features

- Supports 60 MHz to 200 MHz operation range
- Distributes one differential clock input pair to ten differential clock outputs pairs
- Supports spread spectrum clock requirements meeting the PC100 SDRAM registered DIMM specification
- External feedback pins (FBIN, FBIN) are used to synchronize the outputs to the clock input
- Supports 2.5V analog supply voltage (AV $_{CC}$), and 2.5 V V_{DDO}
- No external RC network required
- Sleep mode detection
- 48pin TSSOP (Thin Shrink Small Outline Package)



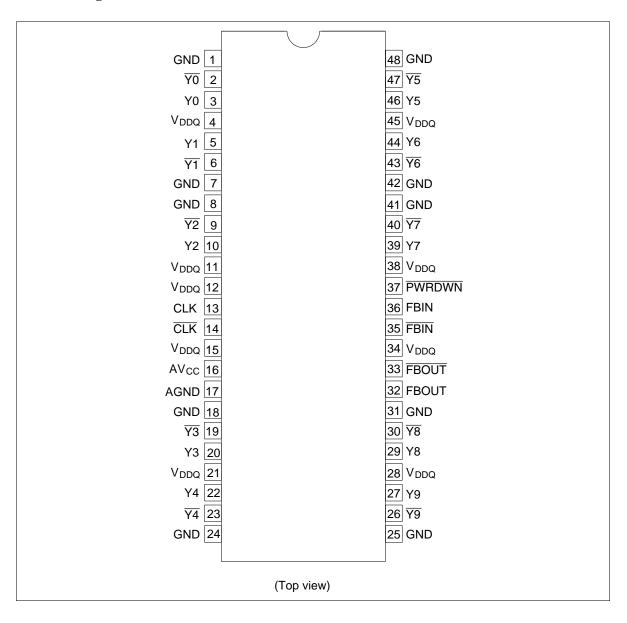
Function Table

| Inputs | | | | : | Outputs | | | | : | PLL |
|------------------|--------|-------|-------|---|---------|---|-------|-------|---|-------------------|
| AV _{cc} | PWRDWN | CLK | CLK | : | Υ | Y | FBOUT | FBOUT | | |
| GND | Н | L | Н | : | L | Н | L | Н | : | Bypassed / off *1 |
| GND | Н | Н | L | : | Н | L | Н | L | : | Bypassed / off *1 |
| X | L | L | Н | : | Z | Z | Z | Z | : | off |
| X | L | Н | L | : | Z | Z | Z | Z | : | off |
| 2.5 V | Н | L | Н | : | Н | L | Н | L | : | on |
| 2.5 V | Н | Н | L | : | Н | L | Н | L | : | on |
| 2.5 V | Χ | 0 MHz | 0 MHz | : | Z | Z | Z | Z | : | off |

H: High level
L: Low level
X: Don't care
Z: High impedance

Note: 1. Bypasse mode is used for Hitachi test mode.

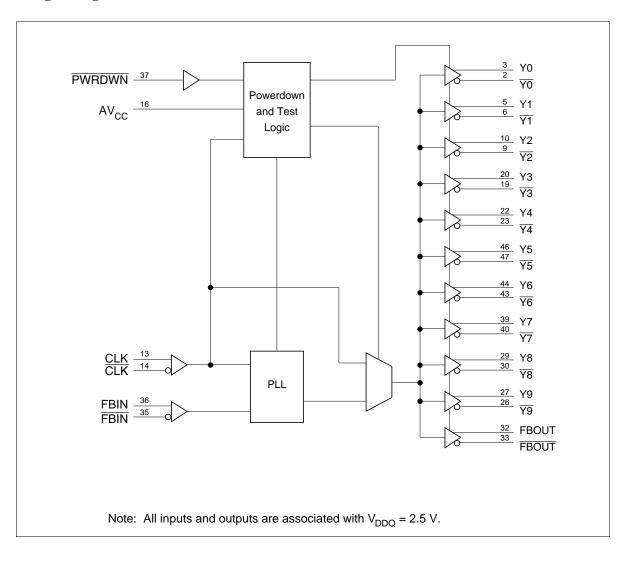
Pin Arrangement



Pin Function

| Pin name | No. | Туре | Description | | | | | |
|------------------|--|-----------------------------|--|--|--|--|--|--|
| AGND | 17 | Ground | Analog ground. AGND provides the ground reference for the analog circuitry. | | | | | |
| AV _{cc} | 16 | Power | Analog power supply. AV_{cc} provides the power reference for the analog circuitry. In addition, AV_{cc} can be used to bypass the PLL for test purposes. When AV_{cc} is strapped to ground, PLL is bypassed and CLK is buffered directly to the device outputs. This bypass mode is used for Hitachi test. | | | | | |
| CLK, CLK | 13, 14 | I Differential input | Clock input. CLK provides the clock signal to be distributed by the HD74CDCV857 clock driver. CLK is used to provide the reference signal to the integrated PLL that generates the clock output signals. CLK must have a fixed frequency and fixed phase for the PLL to obtain phase lock. Once the circuit is powered up and a valid CLK signal is applied, a stabilization time is required for the PLL to phase lock the feedback signal to its reference signal. | | | | | |
| FBIN, FBIN | 35, 36 | I Differential input | Feedback input. FBIN provides the feedback signal to the internal PLL. FBIN must be hard-wired to FBOUT to complete the PLL. The integrated PLL synchronizes CLK and FBIN so that there is nominally zero phase error between CLK and FBIN. | | | | | |
| FBOUT, FBOUT | 32, 33 | O Differential output | Feedback output. FBOUT is dedicated for external feedback. It switches at the same frequency as CLK. When externally wired to FBIN, FBOUT completes the feedback loop of the PLL. | | | | | |
| PWRDWN | 37 | I | Output bank enable. PWRDWN is the output enable for all outputs. When PWRDWN is low, VCO will stop and all outputs are disabled to a high impedance state. When PWRDWN will be returned high, PLL will re-synchroniz to CLK frequency and all outputs are enabled. | | | | | |
| GND | 1, 7, 8, 18, 24, 25, 31, 41, 42, 48 | Ground | Ground | | | | | |
| V_{DDQ} | 4, 11, 12, 15, 21, 28, 34, 38, 45 | Power | Power supply | | | | | |
| Y | 3, 5, 10, 20, 22, 27, 29, 39, 44, 46 | O Differential output | Clock outputs. These outputs provide low-skew copies of CLK. | | | | | |
| \overline{Y} | 2, 6, 9, 19, 23, 26, 30, 40, 43, 47 | O Differential output | Clock outputs. These outputs provide low-skew copies of $\overline{\text{CLK}}$. | | | | | |

Logic Diagram



Absolute Maximum Ratings

| Item | Symbol | Ratings | Unit | Conditions | |
|---|---------------------------------------|----------------------------------|------|--------------------------|--|
| Supply voltage | V_{DDQ} | -0.5 to 3.6 | V | | |
| Input voltage | V _I | -0.5 to V _{DDQ} +0 | .5 V | | |
| Output voltage *1 | V _o | -0.5 to V _{DDQ} +0.5 | V | | |
| Input clamp current | I _{IK} | -50 | mA | V ₁ < 0 | |
| Output clamp current | I _{OK} | -50 | mA | V _o < 0 | |
| Continuous output current | Io | ±50 | mA | $V_{O} = 0$ to V_{DDQ} | |
| Supply current through each $V_{\tiny DDQ}$ or GND | I _{VDDQ} or I _{GND} | ±100 | mA | | |
| Maximum power dissipation at Ta = 55°C (in still air) | | 0.7 | W | | |
| Storage temperature | T _{sta} | -65 to +150 | °C | | |

Notes:

Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

1. The input and output negative voltage ratings may be exceeded if the input and output clamp current ratings are observed.

Recommended Operating Conditions

| Item | Symbol | Min | Тур | Max | Unit | Conditions |
|--------------------------------------|------------------|---|-----|-------------------------------|-------------|------------------|
| Supply voltage | AV_CC | 2.3 | 2.5 | 2.7 | V | |
| Output supply voltage | V_{DDQ} | 2.3 | 2.5 | 2.7 | V | |
| DC input signal voltage *1 | | -0.3 | _ | V_{DDQ} +0.3 | V | All pins |
| High level input voltage | V_{IHG} | 1.7 | _ | V _{DDQ} +0.3 | V | PWRDWN input pin |
| Low level input voltage | V_{ILG} | -0.3 | _ | 0.7 | V | PWRDWN input pin |
| Differential input signal voltage *2 | V_{ID} | 0.36 | _ | V_{DDQ} +0.6 | V | |
| Differential cross point voltage *3 | $V_{IX} V_{OX}$ | $\begin{array}{c} 0.5 \times V_{\text{DDQ}} \\ -0.20 \end{array}$ | _ | $0.5 \times V_{DDQ}$ +0.20 | V | |
| Output current | I _{OH} | _ | _ | -12 | mA | |
| | I _{OL} | _ | _ | 12 | | |
| Input slew rate | SR | 1 | _ | 4 | V/ns | 20% – 80% |
| Operating temperature | T _a | 0 | _ | 70 | °C | |

Notes:

Inputs pins must be prevent from floating.

Feedback inputs (FBIN, FBIN) may float when the device is in low power mode.

- 1. DC input signal voltage specifies the allowable dc execution of differential input.
- 2. Differential cross point voltage is expected to track variations of V_{DDQ} and is the voltage at which the differential signals must be crossing. (See figure1-1)

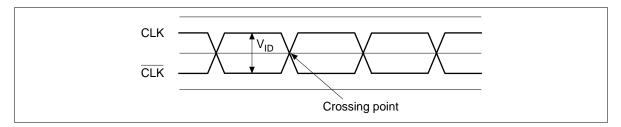


Figure 1 Differential input levels

Electrical Characteristics

| Item | Symbol | Min | Typ ^{*1} | Max | Unit | Test Conditions | | |
|--|-------------------|----------------------|-------------------|------|-------------|---|--|--|
| Input clamp CLK, CLK voltage FBIN, FBIN, G | V _{IK} | _ | _ | -1.2 | V | $I_1 = -18 \text{ mA}, V_{DDQ} = 2.3 \text{ V}$ | | |
| Output voltage | V _{OH} | V _{cc} -0.2 | _ | _ | V | $I_{OH} = -100 \mu A, V_{CC} = 2.3 \text{ to } 2.7 \text{ V}$ | | |
| | | 1.7 | _ | _ | _ | $I_{OH} = -12 \text{ mA}, V_{CC} = 2.3 \text{ V}$ | | |
| | V _{OL} | _ | _ | 0.2 | | I_{OL} = 100 μ A, V_{CC} = 2.3 to 2.7 V | | |
| | | _ | _ | 0.6 | _ | I_{OL} = 12 mA, V_{CC} = 2.3 V | | |
| Input current | I _i | _ | _ | ±10 | μΑ | $V_1 = 0 \text{ V to } 2.7 \text{ V}, V_{DDQ} = 2.7 \text{ V}$ | | |
| Input capacitance | Cı | 2.5 | _ | 3.5 | pF | CLK and $\overline{\text{CLK}}$, FBIN and $\overline{\text{FBIN}}$ | | |
| Delta input capacitance | C _{DI} | -0.25 | _ | 0.25 | pF | CLK and CLK, FBIN and FBIN | | |
| Supply current | DI _{cc} | _ | 250 | TBD | mA | | | |
| | Al _{cc} | _ | 9 | TBD | _ | | | |
| Supply current in power down mode | I _{CCpd} | _ | _ | 100 | μΑ | | | |

Note: 1. For conditions shown as Min or Max, use the appropriate value specified under recommended operating conditions.

Switching Characteristics

| Item | Symbol | Min | Тур | Max | Unit | Test Conditions | Notes |
|-----------------------------|---------------------|-------------|-----|-----|------|------------------------|-----------|
| Period jitter | t _{PER} | -75 | _ | 75 | ps | See figure 6, 9 | 7, 8 |
| Half period jitter | t _{HPER} | -100 | _ | 100 | ps | See figure 7, 9 | 8 |
| Cycle to cycle jitter | t _{cc} | - 75 | _ | 75 | ps | See figure 5, 9 | |
| Static phase error | t _{SPE} | - 50 | _ | 50 | ps | See figure 3, 9 | 4, 5 |
| Output clock skew | t _{sk} | _ | _ | 100 | ps | See figure 4, 9 | |
| Operating clock frequency | f _{CLK(O)} | 60 | _ | 200 | MHz | See figure 9 | 1, 2 |
| Application clock frequency | f _{CLK(A)} | 95 | 133 | 170 | MHz | See figure 9 | 1, 3 |
| Slew rate | t _{SL} | 1.0 | _ | 2.0 | V/ns | See figure 9 | 20% - 80% |
| PLL stabilization time | t _{STAB} | _ | _ | 0.1 | ms | See figure 9 | 6 |

Notes: 1. The PLL must be able to handle spread spectrum induced skew (the specification for this frequency modulation can be found in the latest Intel PC100 Registered DIMM specification)

- 2. Operating clock frequency indicates a range over which the PLL must be able to lock, but in which it is not required to meet the other timing parameters.
- 3. Application clock frequency indicates a range over which the PLL must meet all timing parameters.
- 4 Assumes equal wire length and loading on the clock output and feedback path.
- 5. Static phase error does not include jitter.
- 6. Stabilization time is the time required for the integrated PLL circuit to obtain phase lock of its feedback signal to its reference signal after power up.
- 7. Period jitter defines the largest variation in clock period, around anominal clock period.
- 8. Period jitter and half period jitter are independent from each other.

Differential clock outputs are directly terminated by a 120 Ω resistor. Figure 2 is typical usage conditions of outputs load.

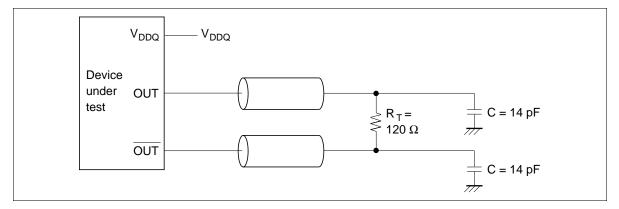


Figure 2 Differential signal using direct termination resistor

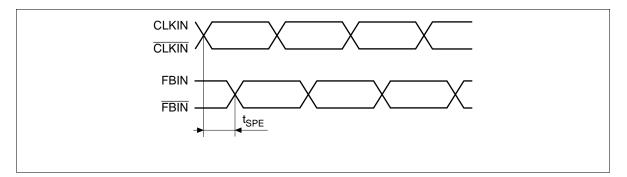


Figure 3 Static phase error

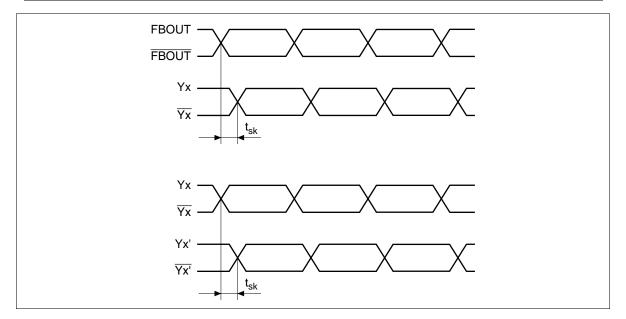


Figure 4 Output skew

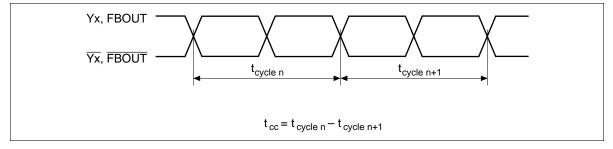


Figure 5 Cycle to cycle jitter

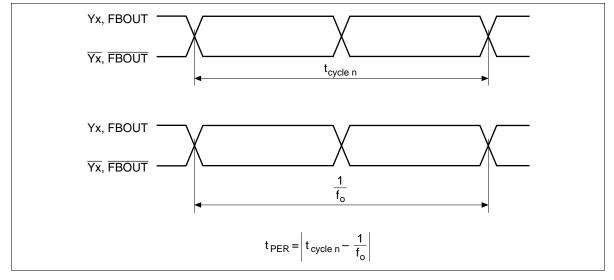


Figure 6 Period jitter

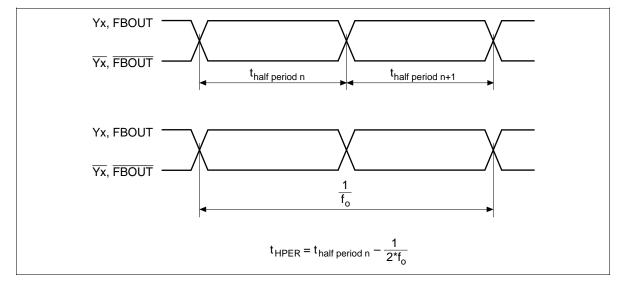


Figure 7 Half period jitter

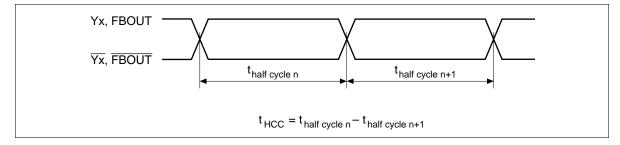


Figure 8 Half cycle to cycle jitter

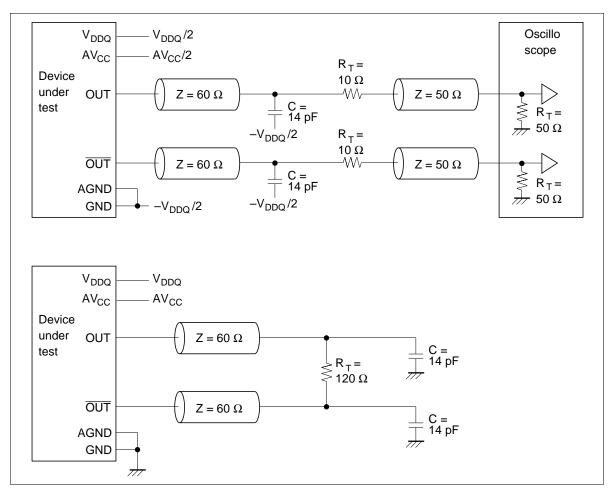
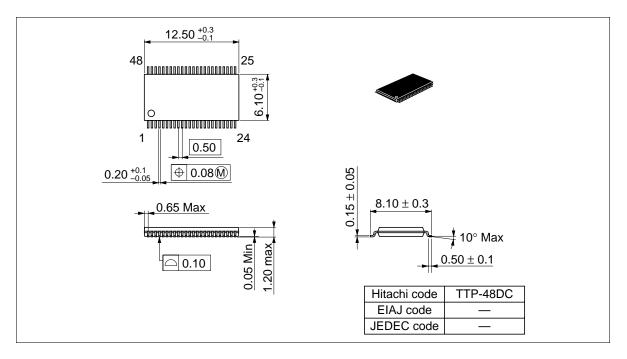


Figure 9 Output load test circuit

Package Dimensions

Unit: mm



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