# **HEF4014B**

# 8-bit static shift register

Rev. 10 — 17 October 2018

**Product data sheet** 

### 1. General description

The HEF4014B is a fully synchronous edge-triggered 8-bit static shift register with eight synchronous parallel inputs (D0 to D7), a synchronous serial data input (DS), a synchronous parallel enable input (PE), a LOW-to-HIGH edge-triggered clock input (CP) and buffered parallel outputs from the last three stages (Q5 to Q7).

Operation is synchronous and the device is edge-triggered on the LOW-to-HIGH transition of CP. Each register stage is of a D-type master-slave flip-flop type. When PE is HIGH, data is loaded into the register from D0 to D7 on the LOW-to-HIGH transition of CP. When PE is LOW, data is shifted to the first position from DS, and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. The clock input's Schmitt trigger action makes it highly tolerant of slower clock rise and fall times.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

#### 2. Features and benefits

- · Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from -40 °C to +85 °C
- Complies with JEDEC standard JESD 13-B

# 3. Applications

- Parallel-to-serial converter
- Serial data queueing
- · General purpose register

# 4. Ordering information

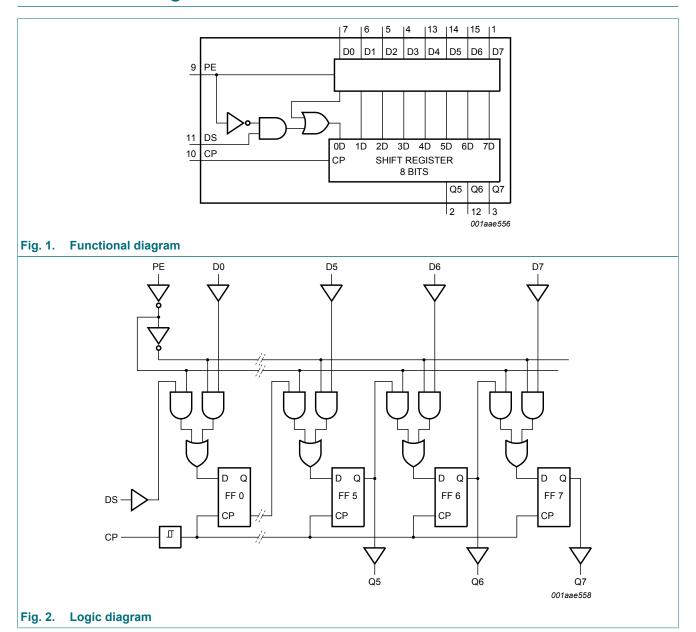
**Table 1. Ordering information** 

| Type number Package |                   |      |   |          |  |  |  |  |  |
|---------------------|-------------------|------|---|----------|--|--|--|--|--|
|                     | Temperature range | Name | Description   | Version  |  |  |  |  |  |
| HEF4014BT           | -40 °C to +85 °C  | SO16 | plastic small outline package; 16 leads;<br>body width 3.9 mm | SOT109-1 |  |  |  |  |  |



8-bit static shift register

# 5. Functional diagram

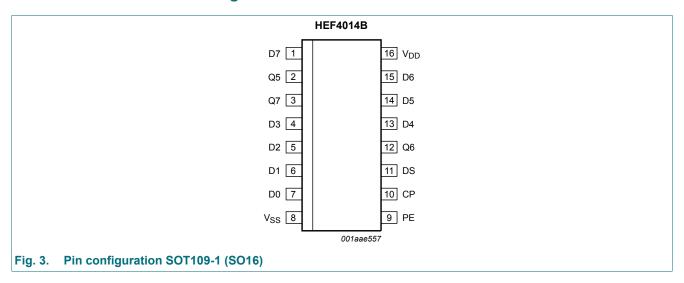


2/12

8-bit static shift register

# 6. Pinning information

### 6.1. Pinning



# 6.2. Pin description

**Table 2. Pin description** 

| Symbol          | Pin                       | Description                              |
|-----------------|---------------------------|--|
| Q5 to Q7        | 2, 12, 3                  | output                                   |
| D0 to D7        | 7, 6, 5, 4, 13, 14, 15, 1 | parallel data input                      |
| V <sub>SS</sub> | 8                         | ground supply voltage                    |
| PE              | 9                         | parallel enable input                    |
| СР              | 10                        | clock input (LOW-to-HIGH edge-triggered) |
| DS              | 11                        | serial data input                        |
| $V_{DD}$        | 16                        | supply voltage                           |

8-bit static shift register

# 7. Functional description

#### Table 3. Function table

 $H = HIGH \ voltage \ level; \ L = LOW \ voltage \ level; \ X = don't \ care; \ nD = HIGH \ or \ LOW;$ 

↑ = LOW-to-HIGH clock transition; ↓ = HIGH-to-LOW clock transition;

| Number of clock    | Inputs           |    |    | Outputs   | Outputs   |           |  |  |  |  |  |  |
|--------------------|------------------|----|----|-----------|-----------|-----------|--|--|--|--|--|--|
| transitions        | СР               | DS | PE | Q5        | Q6        | Q7        |  |  |  |  |  |  |
| Serial operation   | Serial operation |    |    |           |           |           |  |  |  |  |  |  |
| 1                  | 1                | 1D | L  | X         | X         | Х         |  |  |  |  |  |  |
| 2                  | 1                | 2D | L  | X         | X         | Х         |  |  |  |  |  |  |
| 3                  | 1                | 3D | L  | X         | X         | Х         |  |  |  |  |  |  |
| 6                  | 1                | X  | L  | 1D        | Х         | Х         |  |  |  |  |  |  |
| 7                  | 1                | X  | L  | 2D        | 1D        | Х         |  |  |  |  |  |  |
| 8                  | 1                | X  | L  | 3D        | 2D        | 1D        |  |  |  |  |  |  |
|                    | <b>\</b>         | X  | Х  | no change | no change | no change |  |  |  |  |  |  |
| Parallel operation |                  |    | ·  | ·         | ·         |           |  |  |  |  |  |  |
| 1                  | 1                | Х  | Н  | D5        | D6        | D7        |  |  |  |  |  |  |
|                    | $\downarrow$     | Х  | Х  | no change | no change | no change |  |  |  |  |  |  |

# 8. Limiting values

#### **Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol           | Parameter               | Conditions  | Min  | Max                   | Unit |
|------------------|-------------------------|---|------|-----------------------|------|
| $V_{DD}$         | supply voltage          |   | -0.5 | +18                   | V    |
| I <sub>IK</sub>  | input clamping current  | $V_1 < -0.5 \text{ V or } V_1 > V_{DD} + 0.5 \text{ V}$               | -    | ±10                   | mΑ   |
| VI               | input voltage           |   | -0.5 | V <sub>DD</sub> + 0.5 | V    |
| I <sub>OK</sub>  | output clamping current | $V_O < -0.5 \text{ V or } V_O > V_{DD} + 0.5 \text{ V}$               | -    | ±10                   | mΑ   |
| I <sub>I/O</sub> | input/output current    |   | -    | ±10                   | mΑ   |
| I <sub>DD</sub>  | supply current          |   | -    | 50                    | mΑ   |
| T <sub>stg</sub> | storage temperature     |   | -65  | +150                  | °C   |
| T <sub>amb</sub> | ambient temperature     |   | -40  | +85                   | °C   |
| P <sub>tot</sub> | total power dissipation | $T_{amb} = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}$ [1] | -    | 500                   | mW   |
| Р                | power dissipation       | per output  | -    | 100                   | mW   |

<sup>[1]</sup> For SO16 package:  $P_{tot}$  derates linearly with 8 mW/K above 70 °C.

8-bit static shift register

# 9. Recommended operating conditions

#### Table 5. Recommended operating conditions

| Symbol           | Parameter                           | Conditions             | Min | Тур | Max      | Unit |
|------------------|-------------------------------------|------------------------|-----|-----|----------|------|
| $V_{DD}$         | supply voltage                      |                        | 3   | -   | 15       | V    |
| VI               | input voltage                       |                        | 0   | -   | $V_{DD}$ | V    |
| T <sub>amb</sub> | ambient temperature                 | in free air            | -40 | -   | +85      | °C   |
| Δt/ΔV            | input transition rise and fall rate | V <sub>DD</sub> = 5 V  | -   | -   | 3.75     | μs/V |
|                  |                                     | V <sub>DD</sub> = 10 V | -   | -   | 0.5      | μs/V |
|                  |                                     | V <sub>DD</sub> = 15 V | -   | -   | 0.08     | μs/V |

### 10. Static characteristics

#### **Table 6. Static characteristics**

 $V_{SS} = 0 \ V$ ;  $V_I = V_{SS}$  or  $V_{DD}$  unless otherwise specified.

| Symbol          | Parameter                 | Conditions              | V <sub>DD</sub> | T <sub>amb</sub> = | -40 °C | T <sub>amb</sub> = | +25 °C | T <sub>amb</sub> = +85 °C |       | Unit |
|-----------------|---------------------------|-------------------------|-----------------|--------------------|--------|--------------------|--------|---------------------------|-------|------|
|                 |                           |                         |                 | Min                | Max    | Min                | Max    | Min                       | Max   |      |
| V <sub>IH</sub> | HIGH-level input voltage  | I <sub>O</sub>   < 1 μA | 5 V             | 3.5                | -      | 3.5                | -      | 3.5                       | -     | V    |
|                 |                           |                         | 10 V            | 7.0                | -      | 7.0                | -      | 7.0                       | -     | V    |
|                 |                           |                         | 15 V            | 11.0               | -      | 11.0               | -      | 11.0                      | -     | V    |
| V <sub>IL</sub> | LOW-level input voltage   | I <sub>O</sub>   < 1 μA | 5 V             | -                  | 1.5    | -                  | 1.5    | -                         | 1.5   | V    |
|                 |                           |                         | 10 V            | -                  | 3.0    | -                  | 3.0    | -                         | 3.0   | V    |
|                 |                           |                         | 15 V            | -                  | 4.0    | -                  | 4.0    | -                         | 4.0   | V    |
| V <sub>OH</sub> | HIGH-level output voltage | I <sub>O</sub>   < 1 μA | 5 V             | 4.95               | -      | 4.95               | -      | 4.95                      | -     | V    |
|                 |                           |                         | 10 V            | 9.95               | -      | 9.95               | -      | 9.95                      | -     | V    |
|                 |                           |                         | 15 V            | 14.95              | -      | 14.95              | -      | 14.95                     | -     | V    |
| V <sub>OL</sub> | LOW-level output voltage  | I <sub>O</sub>   < 1 μA | 5 V             | -                  | 0.05   | -                  | 0.05   | -                         | 0.05  | V    |
|                 |                           |                         | 10 V            | -                  | 0.05   | -                  | 0.05   | -                         | 0.05  | V    |
|                 |                           |                         | 15 V            | -                  | 0.05   | -                  | 0.05   | -                         | 0.05  | V    |
| I <sub>OH</sub> | HIGH-level output current | V <sub>O</sub> = 2.5 V  | 5 V             | -                  | -1.7   | -                  | -1.4   | -                         | -1.1  | mA   |
|                 |                           | V <sub>O</sub> = 4.6 V  | 5 V             | -                  | -0.52  | -                  | -0.44  | -                         | -0.36 | mA   |
|                 |                           | V <sub>O</sub> = 9.5 V  | 10 V            | -                  | -1.3   | -                  | -1.1   | -                         | -0.9  | mA   |
|                 |                           | V <sub>O</sub> = 13.5 V | 15 V            | -                  | -3.6   | -                  | -3.0   | -                         | -2.4  | mA   |
| I <sub>OL</sub> | LOW-level output current  | V <sub>O</sub> = 0.4 V  | 5 V             | 0.52               | -      | 0.44               | -      | 0.36                      | -     | mA   |
|                 |                           | V <sub>O</sub> = 0.5 V  | 10 V            | 1.3                | -      | 1.1                | -      | 0.9                       | -     | mA   |
|                 |                           | V <sub>O</sub> = 1.5 V  | 15 V            | 3.6                | -      | 3.0                | -      | 2.4                       | -     | mA   |
| l <sub>l</sub>  | input leakage current     |                         | 15 V            | -                  | ±0.3   | -                  | ±0.3   | -                         | ±1.0  | μA   |
| I <sub>DD</sub> | supply current            | I <sub>O</sub> = 0 A    | 5 V             | -                  | 20     | -                  | 20     | -                         | 150   | μΑ   |
|                 |                           |                         | 10 V            | -                  | 40     | -                  | 40     | -                         | 300   | μΑ   |
|                 |                           |                         | 15 V            | -                  | 80     | -                  | 80     | -                         | 600   | μΑ   |
| Cı              | input capacitance         |                         | -               | -                  | -      | -                  | 7.5    | -                         | -     | pF   |

8-bit static shift register

# 11. Dynamic characteristics

**Table 7. Dynamic characteristics** 

 $T_{amb}$  = 25 °C;  $V_{SS}$  = 0 V.

| Symbol                | Parameter             | Conditions | $V_{DD}$ | Extrapolation formula [1]           | Min | Тур | Max | Unit |
|-----------------------|-----------------------|------------|----------|-------------------------------------|-----|-----|-----|------|
| t <sub>PHL</sub>      | HIGH to LOW           | CP to Qn;  | 5 V      | 103 ns + (0.55 ns/pF)C <sub>L</sub> | -   | 130 | 260 | ns   |
|                       | propagation delay     | see Fig. 4 | 10 V     | 44 ns + (0.23 ns/pF)C <sub>L</sub>  | -   | 55  | 110 | ns   |
|                       |                       |            | 15 V     | 32 ns + (0.16 ns/pF)C <sub>L</sub>  | -   | 40  | 80  | ns   |
| t <sub>PLH</sub>      | LOW to HIGH           | CP to Qn;  | 5 V      | 88 ns + (0.55 ns/pF)C <sub>L</sub>  | -   | 115 | 230 | ns   |
|                       | propagation delay     | see Fig. 4 | 10 V     | 39 ns + (0.23 ns/pF)C <sub>L</sub>  | -   | 50  | 100 | ns   |
|                       |                       |            | 15 V     | 32 ns + (0.16 ns/pF)C <sub>L</sub>  | -   | 40  | 80  | ns   |
| t <sub>t</sub>        | transition time       | Qn output; | 5 V [2]  | 10 ns + (1.00 ns/pF)C <sub>L</sub>  | -   | 60  | 120 | ns   |
|                       |                       | see Fig. 4 | 10 V     | 9 ns + (0.42 ns/pF)C <sub>L</sub>   | -   | 30  | 60  | ns   |
|                       |                       |            | 15 V     | 6 ns + (0.28 ns/pF)C <sub>L</sub>   | -   | 20  | 40  | ns   |
| t <sub>W</sub>        | pulse width           |            | 5 V      |                                     | 70  | 35  | -   | ns   |
|                       |                       |            | 10 V     |                                     | 30  | 15  | -   | ns   |
|                       | see <u>Fig. 5</u>     | 15 V       |          | 24                                  | 12  | -   | ns  |      |
| t <sub>su</sub>       | set-up time           | PE to CP;  | 5 V      |                                     | 40  | 10  | -   | ns   |
|                       |                       | see Fig. 5 | 10 V     |                                     | 25  | 5   | -   | ns   |
|                       |                       |            | 15 V     |                                     | 15  | 0   | -   | ns   |
|                       |                       | DS to CP;  | 5 V      |                                     | +35 | -5  | -   | ns   |
|                       | see Fig. 5  Dn to CP; | see Fig. 5 | 10 V     |                                     | +25 | -5  | -   | ns   |
|                       |                       |            | 15 V     |                                     | 25  | 0   | -   | ns   |
|                       |                       |            | 5 V      |                                     | +35 | -5  | -   | ns   |
|                       |                       | see Fig. 5 | 10 V     |                                     | +25 | -5  | -   | ns   |
|                       |                       |            | 15 V     |                                     | 25  | 0   | -   | ns   |
| t <sub>h</sub>        | hold time             | PE to CP;  | 5 V      |                                     | +25 | -5  | -   | ns   |
|                       |                       | see Fig. 5 | 10 V     |                                     | 20  | 0   | -   | ns   |
|                       |                       |            | 15 V     |                                     | 15  | 0   | -   | ns   |
|                       |                       | DS to CP;  | 5 V      |                                     | 30  | 15  | -   | ns   |
|                       |                       | see Fig. 5 | 10 V     |                                     | 20  | 10  | -   | ns   |
|                       |                       |            | 15 V     |                                     | 15  | 7   | -   | ns   |
|                       |                       | Dn to CP;  | 5 V      |                                     | 30  | 15  | -   | ns   |
|                       |                       | see Fig. 5 | 10 V     |                                     | 20  | 10  | -   | ns   |
|                       |                       |            | 15 V     |                                     | 15  | 7   | -   | ns   |
| f <sub>clk(max)</sub> | maximum clock         | see Fig. 5 | 5 V      |                                     | 6   | 13  | -   | MHz  |
|                       | frequency             |            | 10 V     |                                     | 15  | 30  | -   | MHz  |
|                       |                       |            | 15 V     |                                     | 20  | 40  | -   | MHz  |

<sup>[1]</sup> The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown ( $C_L$  in pF).

6 / 12

<sup>[2]</sup>  $t_t$  is the same as  $t_{THL}$  and  $t_{TLH}$ .

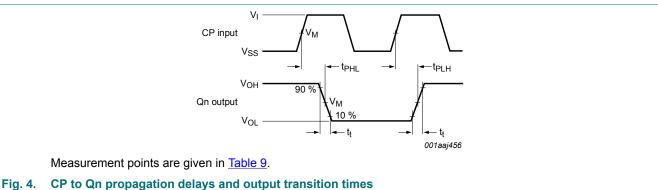
### 8-bit static shift register

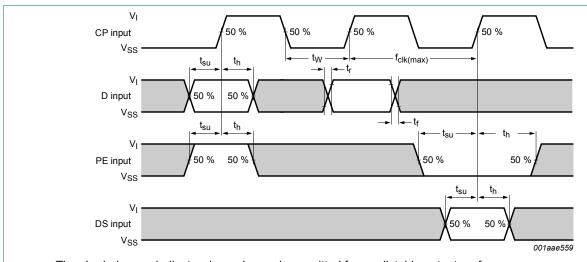
Table 8. Dynamic power dissipation P<sub>D</sub>

 $P_D$  can be calculated from the formulas shown.  $V_{SS}$  = 0 V;  $t_r$  =  $t_f$  ≤ 20 ns;  $T_{amb}$  = 25 °C.

| Symbol  | Parameter     | $V_{DD}$ | Typical formula for P <sub>D</sub> (μW)                     | Where:   |
|---------|---------------|----------|---|--|
| $P_{D}$ | dynamic power | 5 V      |   | f <sub>i</sub> = input frequency in MHz;   |
|         | dissipation   | 10 V     | FD = 4300 ^  ; T > U2 ^ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ | f <sub>o</sub> = output frequency in MHz;<br>C <sub>L</sub> = output load capacitance in pF; |
|         |               | 15 V     | D 40000 f . E/f O \ \ / 4                                   | $V_{DD}$ = supply voltage in V;<br>$\sum (C_L \times f_0)$ = sum of the outputs.             |

#### 11.1. Waveforms and test circuit





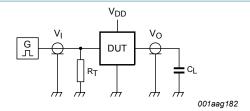
The shaded areas indicate where change is permitted for predictable output performance. Set-up and hold times are shown as positive values but may be specified as negative values. Measurement points are given in Table 9.

Minimum clock pulse width, and set-up and hold times for PE to CP, DS to CP, and D to CP Fig. 5.

Table 9. Measurement points

| Supply voltage | Input              | Output             |  |  |
|----------------|--------------------|--------------------|--|--|
| $V_{DD}$       | V <sub>M</sub>     | V <sub>M</sub>     |  |  |
| 5 V to 15 V    | 0.5V <sub>DD</sub> | 0.5V <sub>DD</sub> |  |  |

#### 8-bit static shift register



Test data is given in Table 10;

Definitions for test circuit:

DUT = Device Under Test.

 $C_L$  = load capacitance including jig and probe capacitance.

 $R_T$  = termination resistance should be equal to the output impedance  $Z_o$  of the pulse generator.

Fig. 6. Test circuit for measuring switching times

#### Table 10. Test data

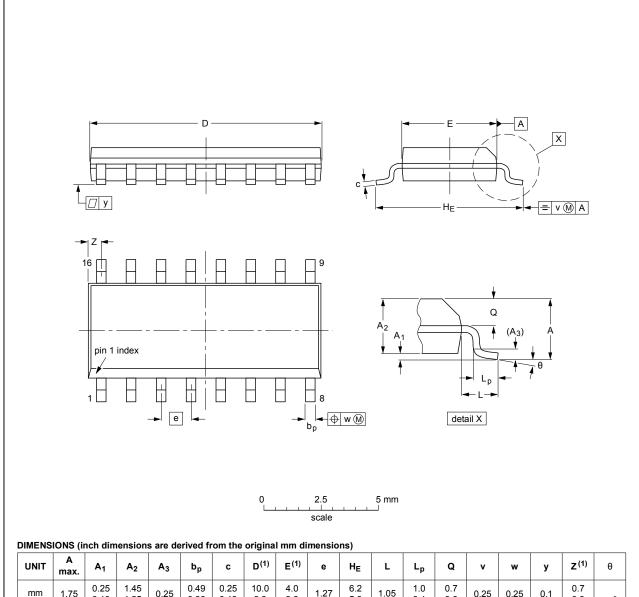
| Supply voltage | Input                              | Load                            |       |  |
|----------------|------------------------------------|---------------------------------|-------|--|
| $V_{DD}$       | V <sub>I</sub>                     | t <sub>r</sub> , t <sub>f</sub> | CL    |  |
| 5 V to 15 V    | V <sub>SS</sub> or V <sub>DD</sub> | ≤ 20 ns                         | 50 pF |  |

8-bit static shift register

# 12. Package outline

#### SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



| UNIT   | A<br>max. | <b>A</b> <sub>1</sub> | A <sub>2</sub> | A <sub>3</sub> | bp           | С                | D <sup>(1)</sup> | E <sup>(1)</sup> | е    | HE             | L     | Lp             | Q              | v    | w    | у     | Z <sup>(1)</sup> | θ  |
|--------|-----------|-----------------------|----------------|----------------|--------------|------------------|------------------|------------------|------|----------------|-------|----------------|----------------|------|------|-------|------------------|----|
| mm     | 1.75      | 0.25<br>0.10          | 1.45<br>1.25   | 0.25           | 0.49<br>0.36 | 0.25<br>0.19     | 10.0<br>9.8      | 4.0<br>3.8       | 1.27 | 6.2<br>5.8     | 1.05  | 1.0<br>0.4     | 0.7<br>0.6     | 0.25 | 0.25 | 0.1   | 0.7<br>0.3       | 8° |
| inches | 0.069     | 0.010<br>0.004        | 0.057<br>0.049 | 0.01           |              | 0.0100<br>0.0075 | 0.39<br>0.38     | 0.16<br>0.15     | 0.05 | 0.244<br>0.228 | 0.041 | 0.039<br>0.016 | 0.028<br>0.020 | 0.01 | 0.01 | 0.004 | 0.028<br>0.012   | 0° |

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

|  | OUTLINE  |        | REFER  | EUROPEAN | ISSUE DATE |            |                                 |
|--|----------|--------|--------|----------|------------|------------|---------------------------------|
|  | VERSION  | IEC    | JEDEC  | JEITA    |            | PROJECTION | ISSUE DATE                      |
|  | SOT109-1 | 076E07 | MS-012 |          |            |            | <del>99-12-27</del><br>03-02-19 |

Fig. 7. Package outline SOT109-1 (SO16)

8-bit static shift register

# 13. Revision history

### **Table 11. Revision history**

| Document ID      | Release date | Data sheet status   | Change notice | Supersedes       |  |  |
|------------------|--------------|---|---------------|------------------|--|--|
| HEF4014B v.10    | 20181017     | Product data sheet  | -             | HEF4014B v.9     |  |  |
| Modifications:   | of Nexperia  | <ul> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> </ul> |               |                  |  |  |
| HEF4014B v.9     | 20160321     | Product data sheet  | -             | HEF4014B v.8     |  |  |
| Modifications:   | Type numb    | Type number HEF4014BP (SOT38-4) removed.  |               |                  |  |  |
| HEF4014B v.8     | 20111121     | Product data sheet  | -             | HEF4014B v.7     |  |  |
| Modifications:   |              | <ul><li>Legal pages updated.</li><li>Changes in "General description" and "Features and benefits".</li></ul>  |               |                  |  |  |
| HEF4014B v.7     | 20110914     | Product data sheet  | -             | HEF4014B v.6     |  |  |
| HEF4014B v.6     | 20091102     | Product data sheet  | -             | HEF4014B v.5     |  |  |
| HEF4014B v.5     | 20090624     | Product data sheet  | -             | HEF4014B v.4     |  |  |
| HEF4014B v.4     | 20090122     | Product data sheet  | -             | HEF4014B_CNV v.3 |  |  |
| HEF4014B_CNV v.3 | 19950101     | Product specification   | -             | HEF4014B_CNV v.2 |  |  |
| HEF4014B_CNV v.2 | 19950101     | Product specification   | -             | -                |  |  |

#### 8-bit static shift register

### 14. Legal information

#### **Data sheet status**

| Document status [1][2]         | Product<br>status [3] | Definition  |
|--------------------------------|-----------------------|---|
| Objective [short] data sheet   | Development           | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification         | This document contains data from the preliminary specification.                       |
| Product [short] data sheet     | Production            | This document contains the product specification.                                     |

- Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
- The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <a href="https://www.nexperia.com">https://www.nexperia.com</a>.

#### **Definitions**

**Draft** — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. Nexperia does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local Nexperia sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

Product specification — The information and data provided in a Product data sheet shall define the specification of the product as agreed between Nexperia and its customer, unless Nexperia and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the Nexperia product is deemed to offer functions and qualities beyond those described in the Product data sheet.

#### **Disclaimers**

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, Nexperia does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. Nexperia takes no responsibility for the content in this document if provided by an information source outside of Nexperia.

In no event shall Nexperia be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, Nexperia's aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of Nexperia.

Right to make changes — Nexperia reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — Nexperia products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an Nexperia product can reasonably be expected to result in personal

injury, death or severe property or environmental damage. Nexperia and its suppliers accept no liability for inclusion and/or use of Nexperia products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Quick reference data** — The Quick reference data is an extract of the product data given in the Limiting values and Characteristics sections of this document, and as such is not complete, exhaustive or legally binding.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. Nexperia makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using Nexperia products, and Nexperia accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the Nexperia product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

Nexperia does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using Nexperia products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). Nexperia does not accept any liability in this respect.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

Terms and conditions of commercial sale — Nexperia products are sold subject to the general terms and conditions of commercial sale, as published at <a href="http://www.nexperia.com/profile/terms">http://www.nexperia.com/profile/terms</a>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. Nexperia hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of Nexperia products by sustained.

**No offer to sell or license** — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Non-automotive qualified products — Unless this data sheet expressly states that this specific Nexperia product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. Nexperia accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without Nexperia's warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond Nexperia's specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies Nexperia for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond Nexperia's standard warranty and Nexperia's product specifications.

**Translations** — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

#### **Trademarks**

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

HEF4014B

All information provided in this document is subject to legal disclaimers.

© Nexperia B.V. 2018. All rights reserved

#### 8-bit static shift register

# **Contents**

| 1. General description              | 1  |
|-------------------------------------|----|
| 2. Features and benefits            | 1  |
| 3. Applications                     | 1  |
| 4. Ordering information             | 1  |
| 5. Functional diagram               | 2  |
| 6. Pinning information              | 3  |
| 6.1. Pinning                        | 3  |
| 6.2. Pin description                | 3  |
| 7. Functional description           | 4  |
| 8. Limiting values                  | 4  |
| 9. Recommended operating conditions | 5  |
| 10. Static characteristics          | 5  |
| 11. Dynamic characteristics         | 6  |
| 11.1. Waveforms and test circuit    | 7  |
| 12. Package outline                 | 9  |
| 13. Revision history                | 10 |
| 14. Legal information               | 11 |
|                                     |    |

For more information, please visit: http://www.nexperia.com For sales office addresses, please send an email to: salesaddresses@nexperia.com Date of release: 17 October 2018

<sup>©</sup> Nexperia B.V. 2018. All rights reserved