Programmable 4-bit binary down counter Rev. 5 — 22 November 2011

Product data sheet

General description 1.

The HEF4526B is a synchronous programmable 4-bit binary down counter with active HIGH and active LOW clock inputs (CP0, CP1), an asynchronous parallel load input (PL), four parallel inputs (A0 to A3), a cascade feedback input (CF), four buffered parallel outputs (Q0 to Q3), a terminal count output (TC), an overriding asynchronous master reset input (MR) and a decoded TC output that can be used for divide-by-n applications. In single stage applications the TC output is connected to PL. CF allows cascade divide-by-n operation with no additional gates required.

Information on A0 to A3 is loaded into the counter while PL is HIGH, independent of all other inputs except MR, which must be LOW. When PL and CP1 are LOW, the counter advances on a LOW-to-HIGH transition of CP0. When PL is LOW and CP0 is HIGH, the counter advances on a HIGH to LOW transition of CP1. TC is HIGH when the counter is in the zero state (Q0 = Q1 = Q2 = Q3 = LOW) and CF is HIGH and PL is LOW. A HIGH on MR resets the counter (Q0 to Q3 = LOW) independent of other inputs. The clock input is highly tolerant of slower clock rise and fall times due to Schmitt trigger action.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

2. **Features and benefits**

- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +85 °C
- Complies with JEDEC standard JESD 13-B

Ordering information 3.

Table 1. **Ordering information**

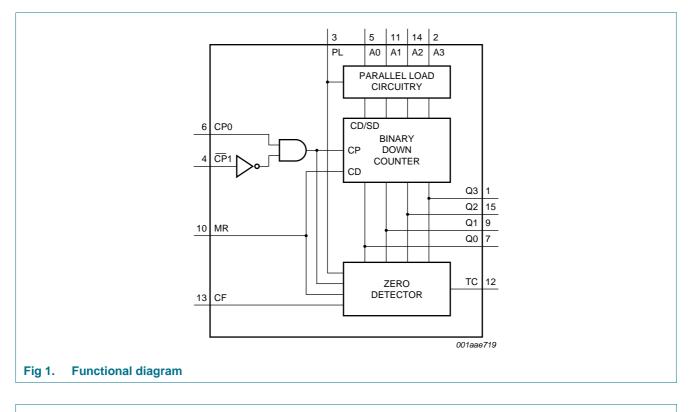
All types operate from -40 °C to +85 °C.

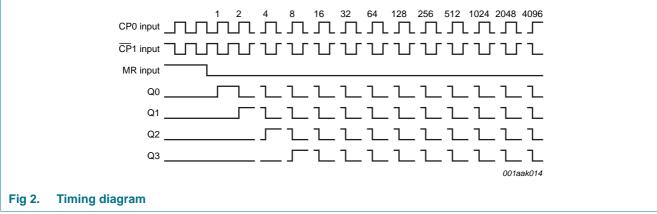
Type number	Package						
	Name	Description	Version				
HEF4526BP	DIP16	plastic dual in-line package; 16 leads (300 mil)	SOT38-4				
HEF4526BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1				



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4. Functional diagram

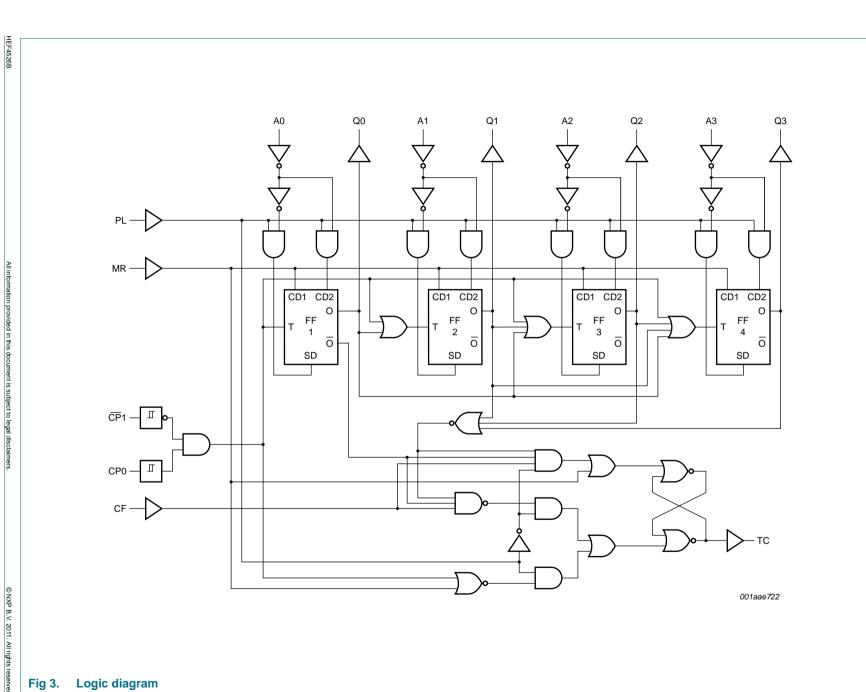




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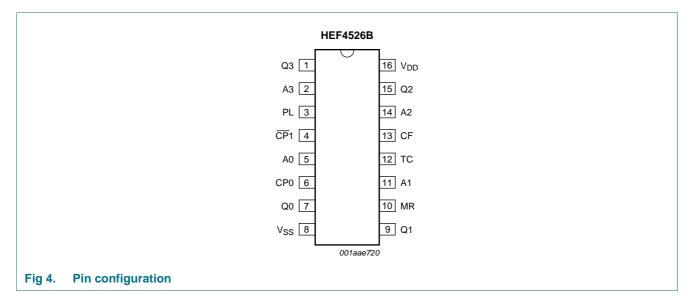
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Programmable 4-bit binary down counter **HEF4526B**

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5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2.	Pin description	
Symbol	Pin	Description
A0 to A3	5, 11, 14, 2	parallel input
PL	3	parallel load input
CP0	6	clock input (LOW-to-HIGH, triggered)
CP1	4	clock input (HIGH-to-LOW, triggered)
CF	13	cascade feedback input
MR	10	asynchronous master reset input
тс	12	terminal count output
Q0 to Q3	7, 9, 15, 1	buffered parallel output
V _{DD}	16	supply voltage
V _{SS}	8	ground (0 V)

Functional description 6.

Table 3.	Function table ^[1]			
MR	PL	CP0	CP1	Mode
Н	Х	Х	Х	reset (asynchronous)
L	Н	Х	Х	preset (asynchronous)
L	L	↑	Н	no change
L	L	L	\downarrow	no change
L	L	\downarrow	Х	no change
L	L	Х	\uparrow	no change
L	L	\uparrow	L	counter advances
L	L	Н	\downarrow	counter advances

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; \uparrow = positive-going transition; \downarrow = negative-going transition.

Table 4.Counting modeCF = HIGHPI = I OWMR = I OW

Count	Outputs							
	Q3	Q2	Q1	Q0				
15	Н	Н	Н	Н				
14	Н	Н	Н	L				
13	Н	Н	L	Н				
12	Н	Н	L	L				
11	Н	L	Н	Н				
10	Н	L	Н	L				
9	Н	L	L	Н				
8	Н	L	L	L				
7	L	Н	Н	Н				
6	L	Н	Н	L				
5	L	Н	L	Н				
4	L	Н	L	L				
3	L	L	Н	Н				
2	L	L	Н	L				
1	L	L	L	Н				
0	L	L	L	L				

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PL	A3	A2	A1	A0	Divide by	TC output pulse width
L	Х	Х	Х	Х	16	one clock period
тс	Н	Н	Н	Н	15	clock pulse HIGH
тс	Н	Н	Н	L	14	
тс	Н	Н	L	Н	13	
тс	Н	Н	L	L	12	
тс	Н	L	Н	Н	11	
тс	Н	L	Н	L	10	
тс	Н	L	L	Н	9	
тс	Н	L	L	L	8	
тс	L	Н	Н	Н	7	
тс	L	Н	Н	L	6	
тс	L	Н	L	Н	5	
тс	L	Н	L	L	4	
тс	L	L	Н	Н	3	
тс	L	L	Н	L	2	
тс	L	L	L	Н	1	
тс	L	L	L	L	no operation	

Table 5. Single stage operation Divide-by-p: MR = LOW: CE = HIGH: $\overline{CP1} = LOW$

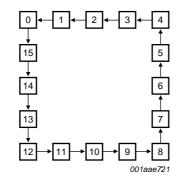


Fig 5. State diagram

7. Limiting values

Table 6. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_{\rm I}$ < –0.5 V or $V_{\rm I}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
VI	input voltage		-0.5	V _{DD} + 0.5	V
I _{OK}	output clamping current	V_{O} < –0.5 V or V_{O} > V_{DD} + 0.5 V	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I _{DD}	supply current	to any supply terminal	-	±100	mA
T _{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+85	°C
P _{tot}	total power dissipation	DIP16 package	<u>[1]</u> -	750	mW
		SO16 package	[2] _	500	mW
Р	power dissipation	per output	-	100	mW

[1] For DIP16 package: P_{tot} derates linearly with 12 mW/K above 70 $^\circ\text{C}.$

[2] For SO16 package: Ptot derates linearly with 8 mW/K above 70 °C.

8. Recommended operating conditions

Table 7. Recommended operating conditions

Parameter	Conditions	Min	Тур	Max	Unit
supply voltage		3	-	15	V
input voltage		0	-	V_{DD}	V
ambient temperature	in free air	-40	-	+85	°C
input transition rise and fall rate	$V_{CC} = 5 V$	-	-	3.75	μs/V
	V _{CC} = 10 V	-	-	0.5	μs/V
	V _{CC} = 15 V	-	-	0.08	μs/V
	supply voltage input voltage ambient temperature	supply voltageinput voltageambient temperatureinput transition rise and fall rate $V_{CC} = 5 V$ $V_{CC} = 10 V$	$\begin{tabular}{ c c c c } & & & & & & & & & & & & & & & & & & &$	supply voltage3-input voltage0-ambient temperaturein free air-40input transition rise and fall rate $V_{CC} = 5 V$ - $V_{CC} = 10 V$	supply voltage3-15input voltage0- V_{DD} ambient temperaturein free air-40-+85input transition rise and fall rate $V_{CC} = 5 V$ 3.75 $V_{CC} = 10 V$ 0.5

9. Static characteristics

Table 8. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

Symbol	Parameter	rameter Conditions V _{DD}	V _{DD}	T _{amb} =	T _{amb} = -40 °C		T _{amb} = 25 °C		T _{amb} = 85 °C	
				Min	Max	Min	Max	Min	Max	
VIH	HIGH-level input voltage	I _O < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V _{IL}	LOW-level input voltage	$ I_O < 1 \ \mu A$	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V _{OH}	HIGH-level output voltage	$ I_O < 1 \ \mu A$	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V _{OL}	LOW-level output voltage	$ I_O < 1 \ \mu A$	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
l _{OL}	LOW-level output current	$V_{O} = 0.4 V$	5 V	0.52	-	0.44	-	0.36	-	mA
		$V_{O} = 0.5 V$	10 V	1.3	-	1.1	-	0.9	-	mA
		$V_{O} = 1.5 V$	15 V	3.6	-	3.0	-	2.4	-	mA
I _{OH}	HIGH-level output current	$V_{O} = 2.5 V$	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		$V_{O} = 4.6 V$	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		$V_{O} = 9.5 V$	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V _O = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μA
I _{DD}	supply current	I _O = 0 A	5 V	-	20	-	20	-	150	μA
			10 V	-	40	-	40	-	300	μA
			15 V	-	80	-	80	-	600	μA
CI	input capacitance		-	-	-	-	7.5	-	-	рF

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10. Dynamic characteristics

Table 9. Dynamic characteristics

 $V_{SS} = 0 V$; $T_{amb} = 25 \circ C$; for test circuit see <u>Figure 7</u>; unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit
t _{PHL}	HIGH to LOW propagation delay	CP0, CP1 to Qn;	5 V	^[1] 123 ns + (0.55 ns/pF)C _L	-	150	300	ns
	propagation delay	see Figure 6	10 V	54 ns + (0.23 ns/pF)C _L	-	65	130	ns
			15 V	42 ns + (0.16 ns/pF)C _L	-	50	100	ns
		CP0, CP1 to TC;	5 V	183 ns + (0.55 ns/pF)C _L	-	210	420	ns
		see Figure 6	10 V	79 ns + (0.23 ns/pF)C _L	-	90	180	ns
			15 V	62 ns + (0.16 ns/pF)C _L	-	70	140	ns
		PL to Qn;	5 V	173 ns + (0.55 ns/pF)C _L	-	200	400	ns
		see Figure 6	10 V	69 ns + (0.23 ns/pF)C _L	-	80	160	ns
			15 V	52 ns + (0.16 ns/pF)C _L	-	60	120	ns
		MR to Qn	5 V	113 ns + (0.55 ns/pF)C _L	-	140	280	ns
			10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
t _{PLH}	LOW to HIGH	CP0, CP1 to Qn;	5 V	123 ns + (0.55 ns/pF)CL	-	150	300	ns
	propagation delay	see Figure 6	10 V	54 ns + (0.23 ns/pF)C _L	-	65	130	ns
			15 V	42 ns + (0.16 ns/pF)C _L	-	50	100	ns
		CP0, CP1 to TC; see <u>Figure 6</u>	5 V	183 ns + (0.55 ns/pF)C _L	-	210	420	ns
			10 V	79 ns + (0.23 ns/pF)C _L	-	90	180	ns
			15 V	62 ns + (0.16 ns/pF)C _L	-	70	140	ns
		PL to Qn;	5 V	153 ns + (0.55 ns/pF)C _L	-	180	360	ns
		see Figure 6	10 V	59 ns + (0.23 ns/pF)C _L	-	70	140	ns
			15 V	42 ns + (0.16 ns/pF)C _L	-	50	100	ns
tt	transition time	see Figure 6	5 V	10 ns + (1.00 ns/pF)C _L	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C _L	-	20	40	ns
t _{su}	set-up time	An to PL;	5 V		30	0	-	ns
		see Figure 6	10 V		20	0	-	ns
			15 V		15	0	-	ns
t _h	hold time	An to PL;	5 V		30	5	-	ns
		see Figure 6	10 V		20	5	-	ns
			15 V		15	5	-	ns

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Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit
t _W	pulse width	CP0 input; LOW;	5 V		80	40	-	ns
		see Figure 6	10 V		40	20	-	ns
			15 V		30	15	-	ns
		CP1 input; HIGH; see <u>Figure 6</u>	5 V		80	40	-	ns
			10 V		40	20	-	ns
			15 V		30	15	-	ns
		PL input; HIGH; see <u>Figure 6</u> MR input; LOW	5 V		100	50	-	ns
			10 V		40	20	-	ns
			15 V		32	16	-	ns
			5 V		130	65	-	ns
			10 V		50	25	-	ns
			15 V		40	20	-	ns
f _{max}	maximum frequency	PL = LOW;	5 V	[2]	6	12	-	MHz
		see Figure 6	10 V		12	25	-	MHz
			15 V		16	32	-	MHz

Table 9.Dynamic characteristics ... continued $V_{SS} = 0$ V: $T_{omb} = 25$ °C: for test circuit see Figure

 $V_{SS} = 0 \text{ V}; T_{amb} = 25 \text{ °C};$ for test circuit see Figure 7; unless otherwise specified.

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

[2] In the divide-by-n mode (PL connected to TC), the CP0 or CP1 pulse width must be greater than the maximum HIGH to LOW propagation delay for CP0 or CP1 to TC.

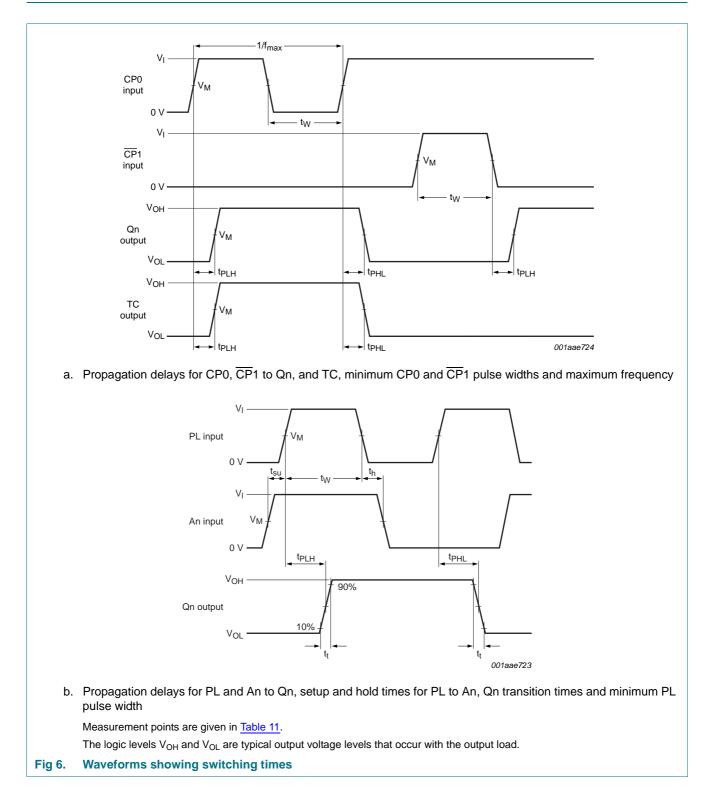
Table 10. Dynamic power dissipation P_D

P_D can be calculated from the formulas shown. $V_{SS} = 0$ V; $t_r = t_f \le 20$ ns; $T_{amb} = 25$ °C.

Symbol	Parameter	V_{DD}	Typical formula for $P_D(\mu W)$	where:		
P _D dynamic power		5 V	$P_D = 1000 \times f_i + \Sigma(f_o \times C_L) \times V_DD^2$	$f_i = input frequency in MHz,$		
	dissipation		dissipation 10 V		$P_D = 4000 \times f_i + \Sigma(f_o \times C_L) \times V_DD^2$	$f_o = output frequency in MHz,$
		15 V	$P_{D} = 10000 \times f_{i} + \Sigma(f_{o} \times C_{L}) \times V_{DD}^{2}$	C_L = output load capacitance in pF,		
				V _{DD} = supply voltage in V,		
				$\Sigma(f_o \times C_L)$ = sum of the outputs.		

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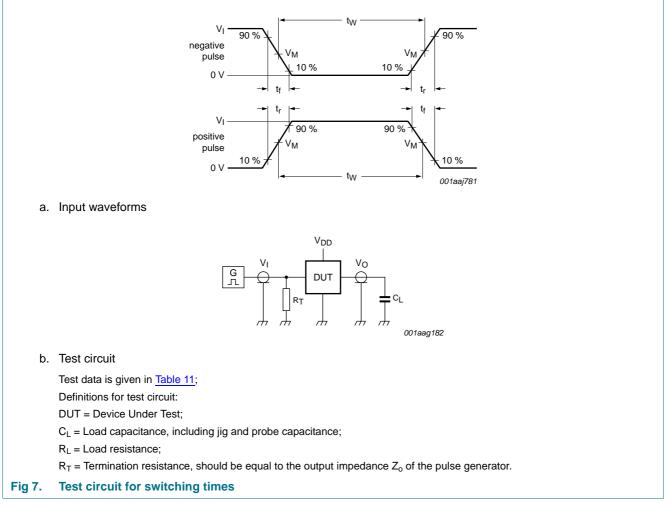
11. Waveforms



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Supply voltage	Input			Load	
	VI	V _M	t _r , t _f	CL	RL
5 V to 15 V	V _{DD}	0.5V _I	\leq 20 ns	50 pF	1 kΩ

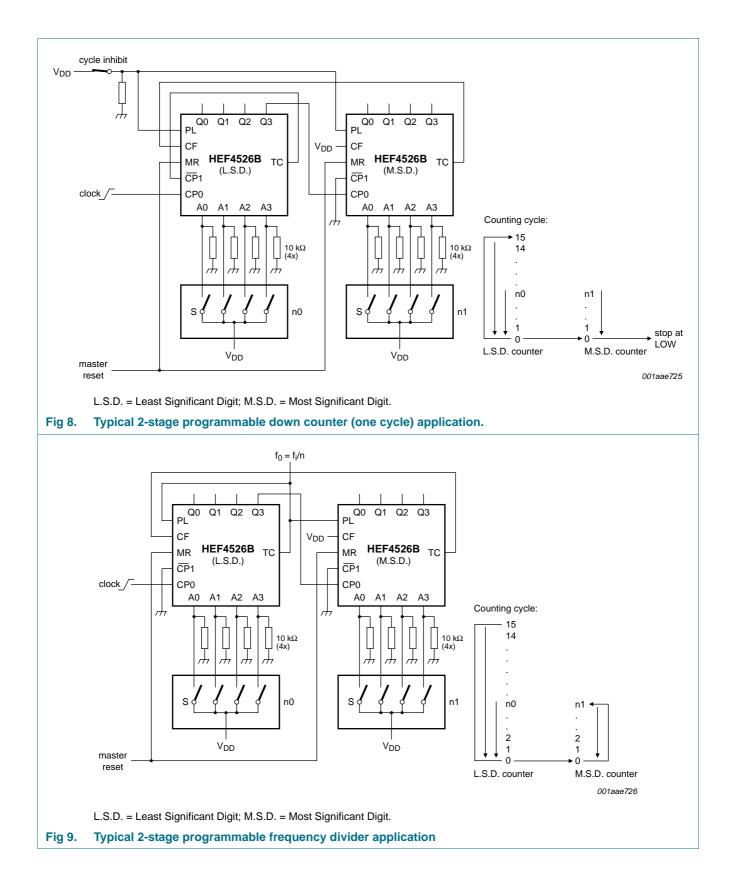
12. Application information

Some examples of HEF4526B applications are:

- Divide-by-n counter
- Programmable frequency divider

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13. Package outline

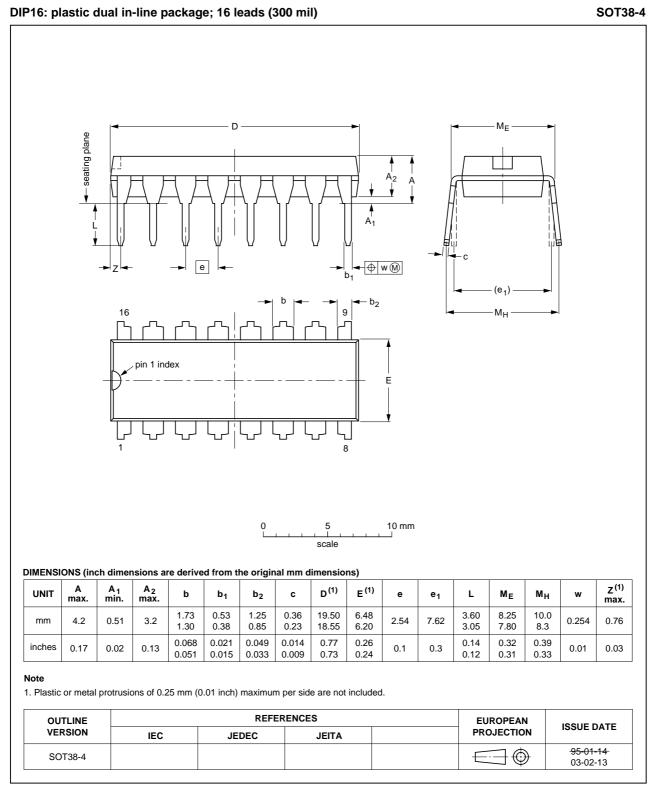


Fig 10. Package outline SOT38-4 (DIP16)

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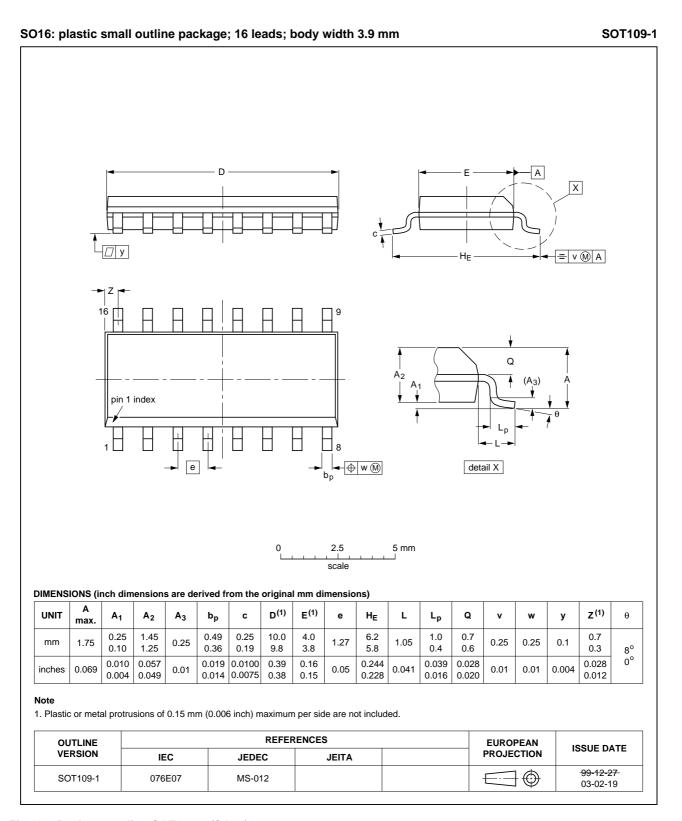


Fig 11. Package outline SOT109-1 (SO16)

14. Revision history

Table 12. Revision hi	story			
Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4526B v.5	20111122	Product data sheet	-	HEF4526B v.4
Modifications:				
	 <u>Table 8</u>: I_{OH} 	minimum values changed t	o maximum	
HEF4526B v.4	20090921	Product data sheet	-	HEF4526B_CNV v.3
HEF4526B_CNV v.3	19950101	Product specification	-	HEF4526B_CNV v.2
HEF4526B_CNV v.2	19950101	Product specification	-	-
-				

15. Legal information

15.1 Data sheet status

Document status[1][2]	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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