

#### HIP4081A

80V/2.5A Peak, High Frequency Full Bridge FET Driver

FN3659 Rev.9.00 Feb12, 2020

The HIP4081A is a high frequency, medium voltage Full Bridge N-Channel FET driver IC, available in 20 lead plastic SOIC and DIP packages. The HIP4081A can drive every possible switch combination except those which would cause a shoot-through condition. The HIP4081A can switch at frequencies up to 1MHz and is well suited to driving Voice Coil Motors, high-frequency switching power amplifiers, and power supplies.

For example, the HIP4081A can drive medium voltage brush motors, and two HIP4081As can be used to drive high performance stepper motors, since the short minimum "on-time" can provide fine micro-stepping capability.

Short propagation delays of approximately 55ns maximizes control loop crossover frequencies and dead-times which can be adjusted to near zero to minimize distortion, resulting in rapid, precise control of the driven load.

A similar part, the HIP4080A, includes an on-chip input comparator to create a PWM signal from an external triangle wave and to facilitate "hysteresis mode" switching.

The Application Note for the HIP4081A is the AN9405.

### Ordering Information

PART NUMBER	TEMP RANGE (°C)	PACKAGE (RoHS Compliant)	PKG. DWG.#
HIP4081AIPZ (Note)	-40 to 85	20 Ld PDIP	E20.3
HIP4081AIBZ (Note)	-40 to 85	20 Ld SOIC (W)	M20.3
HIP4081AIBZT (Note)	-40 to 85	20 Ld SOIC (W)	M20.3

NOTE: Pb-free products employ special Pb-free material sets; molding compounds/die attach materials and 100% matte tin plate termination finish, which is compatible with both SnPb and Pb-free soldering operations. Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J Std-020B.

#### Features

- Independently Drives 4 N-Channel FET in Half Bridge or Full Bridge Configurations
- Bootstrap Supply Max Voltage to 95V<sub>DC</sub>
- Drives 1000pF Load at 1MHz in Free Air at 50°C with Rise and Fall Times of Typically 10ns
- · User-Programmable Dead Time
- On-Chip Charge-Pump and Bootstrap Upper Bias Supplies
- · DIS (Disable) Overrides Input Control
- Input Logic Thresholds Compatible with 5V to 15V Logic Levels
- · Very Low Power Consumption
- · Undervoltage Protection
- · Pb-free RoHS Compliant

#### **Applications**

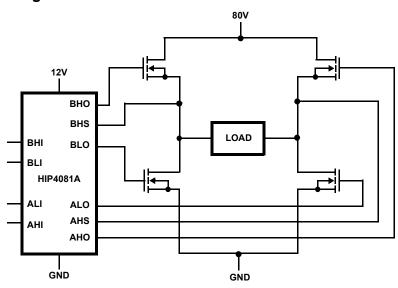
- · Medium/Large Voice Coil Motors
- · Full Bridge Power Supplies
- Switching Power Amplifiers
- High Performance Motor Controls
- · Noise Cancellation Systems
- Battery Powered Vehicles
- · Peripherals
- U.P.S.

#### **Pinout**

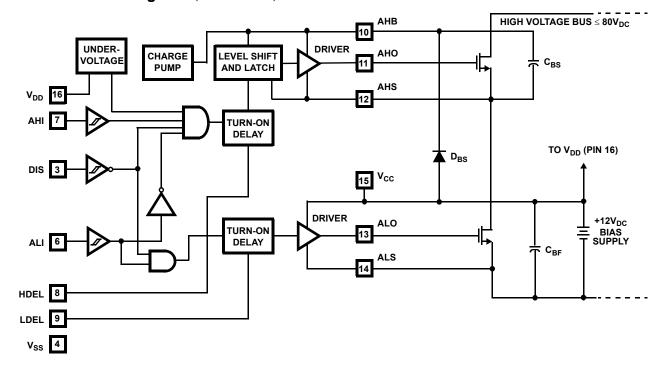
(PDIP, SOIC) **TOP VIEW** вно внв 20 **BHS** BHI 19 18 DIS BLO  $v_{\text{ss}}$ 17 BLS BLI 16  $V_{DD}$ ALI 15  $v_{cc}$ ALS 14 AHI ALO **HDEL** 13 LDEL AHS 12 AHO AHB 11

**HIP4081A** 

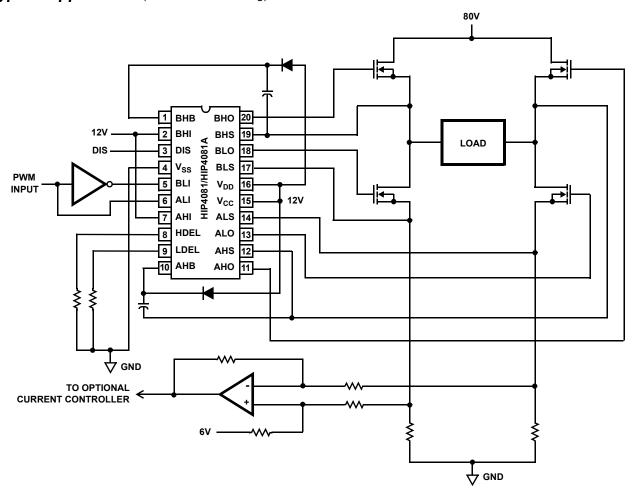
## Application Block Diagram



## Functional Block Diagram (1/2 HIP4081A)



## Typical Application (PWM Mode Switching)



#### **Absolute Maximum Ratings**

Supply Voltage, V <sub>DD</sub> and V <sub>CC</sub> 0.3V to 16V
Logic I/O Voltages0.3V to V <sub>DD</sub> +0.3V
Voltage on AHS, BHS6.0V (Transient) to 80V (25°C to 125°C)
Voltage on AHS, BHS6.0V (Transient) to 70V (-55°C to 125°C)
Voltage on ALS, BLS2.0V (Transient) to +2.0V (Transient)
Voltage on AHB, BHBV <sub>AHS, BHS</sub> -0.3V to V <sub>AHS, BHS</sub> +V <sub>DD</sub>
Voltage on ALO, BLO
Voltage on AHO, BHO V <sub>AHS, BHS</sub> -0.3V to V <sub>AHB, BHB</sub> +0.3V
Input Current, HDEL and LDEL5mA to 0mA
Phase Slew Rate
NOTE: All Voltages relative to V <sub>SS</sub> , unless otherwise specified.

#### **Thermal Information**

Thermal Resistance (Typical, Note 1)	$\theta_{JA}$ (°C/W)
SOIC Package	85
DIP Package	75
Storage Temperature Range	
Operating Max. Junction Temperature	125°C
Lead Temperature (Soldering 10s))	300°C
(For SOIC - Lead Tips Only	

#### **Operating Conditions**

Supply Voltage,  $V_{DD}$  and  $V_{CC}$  ... +9.5V to +15V Voltage on ALS, BLS ... -1.0V to +1.0V Voltage on AHB, BHB ...  $V_{AHS, BHS}$  +5V to  $V_{AHS, BHS}$  +15V Input Current, HDEL and LDEL ... -500 $\mu$ A to -50 $\mu$ A Operating Ambient Temperature Range ... -40°C to 85°C

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

#### NOTE:

1.  $\theta_{JA}$  is measured with the component mounted on an evaluation PC board in free air.

			T <sub>J</sub> = 25°C		T <sub>JS</sub> = -4 12!	0°C TO 5°C			
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	MIN	MAX	UNITS	
SUPPLY CURRENTS AND CHAR	RGE PUMPS		•			•			
V <sub>DD</sub> Quiescent Current	I <sub>DD</sub>	All inputs = 0V	8.5	10.5	14.5	7.5	14.5	mA	
V <sub>DD</sub> Operating Current	I <sub>DDO</sub>	Outputs switching f = 500kHz	9.5	12.5	15.5	8.5	15.5	mA	
V <sub>CC</sub> Quiescent Current	I <sub>CC</sub>	All Inputs = 0V, I <sub>ALO</sub> = I <sub>BLO</sub> = 0	-	0.1	10	-	20	μА	
V <sub>CC</sub> Operating Current	I <sub>cco</sub>	f = 500kHz, No Load	1	1.25	2.0	0.8	3	mA	
AHB, BHB Quiescent Current - Qpump Output Current	I <sub>AHB</sub> , I <sub>BHB</sub>	All Inputs = 0V, $I_{AHO} = I_{BHO} = 0$ $V_{DD} = V_{CC} = V_{AHB} = V_{BHB} = 10V$	-50	-30	-11	-60	-10	μА	
AHB, BHB Operating Current	I <sub>AHBO</sub> , I <sub>BHBO</sub>	f = 500kHz, No Load	0.6	1.2	1.5	0.5	1.9	mA	
AHS, BHS, AHB, BHB Leakage Current	I <sub>HLK</sub>	V <sub>BHS</sub> = V <sub>AHS</sub> = 80V, V <sub>AHB</sub> = V <sub>BHB</sub> = 93V	-	0.02	1.0	-	10	μА	
AHB-AHS, BHB-BHS Qpump Output Voltage	V <sub>AHB</sub> -V <sub>AHS</sub> V <sub>BHB</sub> -V <sub>BHS</sub>	I <sub>AHB</sub> = I <sub>AHB</sub> = 0, No Load	11.5	12.6	14.0	10.5	14.5	V	
INPUT PINS: ALI, BLI, AHI, BHI,	AND DIS								
Low Level Input Voltage	V <sub>IL</sub>	Full Operating Conditions	-	-	1.0	-	0.8	V	
High Level Input Voltage	V <sub>IH</sub>	Full Operating Conditions	2.5	-	-	2.7	-	V	
Input Voltage Hysteresis			-	35	-	-	-	mV	
Low Level Input Current	I <sub>IL</sub>	V <sub>IN</sub> = 0V, Full Operating Conditions	-130	-100	-75	-135	-65	μА	
High Level Input Current	I <sub>IH</sub>	V <sub>IN</sub> = 5V, Full Operating Conditions	-1	-	+1	-10	+10	μΑ	
TURN-ON DELAY PINS: LDEL A	TURN-ON DELAY PINS: LDEL AND HDEL								
LDEL, HDEL Voltage	V <sub>HDEL</sub> , V <sub>LDEL</sub>	I <sub>HDEL</sub> = I <sub>LDEL</sub> = -100μA	4.9	5.1	5.3	4.8	5.4	V	
GATE DRIVER OUTPUT PINS: ALO, BLO, AHO, AND BHO									
Low Level Output Voltage	V <sub>OL</sub>	I <sub>OUT</sub> = 100mA	0.7	0.85	1.0	0.5	1.1	V	
High Level Output Voltage	V <sub>CC</sub> -V <sub>OH</sub>	I <sub>OUT</sub> = -100mA	0.8	0.95	1.1	0.5	1.2	V	
Peak Pullup Current	I <sub>O</sub> +	V <sub>OUT</sub> = 0V	1.7	2.6	3.8	1.4	4.1	Α	



# **Electrical Specifications** $V_{DD} = V_{CC} = V_{AHB} = V_{BHB} = 12V$ , $V_{SS} = V_{ALS} = V_{BLS} = V_{AHS} = 0V$ , $V_{BHS} = 0V$ , $V_{BHS} = 100K$ and $V_{AHS} = 100K$ and

			T <sub>J</sub> = 25°C		T <sub>JS</sub> = -40°C TO 125°C			
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	MIN	MAX	UNITS
Peak Pulldown Current	I <sub>O</sub> -	V <sub>O UT</sub> = 12V	1.7	2.4	3.3	1.3	3.6	Α
Undervoltage, Rising Threshold	UV+		8.1	8.8	9.4	8.0	9.5	V
Undervoltage, Falling Threshold	UV-		7.6	8.3	8.9	7.5	9.0	V
Undervoltage, Hysteresis	HYS		0.25	0.4	0.65	0.2	0.7	V

## Switching Specifications $V_{DD} = V_{CC} = V_{AHB} = V_{BHB} = 12V$ , $V_{SS} = V_{ALS} = V_{BLS} = V_{AHS} = 0V$ , $V_{BHS} = 0V$ , $V_{BHS} = 10V$ , $V_{BHS} =$

			T <sub>J</sub> = 25°C			T <sub>JS</sub> = -40°C TO 125°C		
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	MIN	MAX	UNITS
Lower Turn-off Propagation Delay (ALI-ALO, BLI-BLO)	T <sub>LPHL</sub>		-	30	60	-	80	ns
Upper Turn-off Propagation Delay (AHI-AHO, BHI-BHO)	T <sub>HPHL</sub>		-	35	70	-	90	ns
Lower Turn-on Propagation Delay (ALI-ALO, BLI-BLO)	T <sub>LPLH</sub>	R <sub>HDEL</sub> = R <sub>LDEL</sub> = 10K	-	45	70	-	90	ns
Upper Turn-on Propagation Delay (AHI-AHO, BHI-BHO)	T <sub>HPLH</sub>	R <sub>HDEL</sub> = R <sub>LDEL</sub> = 10K	-	60	90	-	110	ns
Rise Time	T <sub>R</sub>		-	10	25	-	35	ns
Fall Time	T <sub>F</sub>		-	10	25	-	35	ns
Turn-on Input Pulse Width	T <sub>PWIN-ON</sub>	R <sub>HDEL</sub> = R <sub>LDEL</sub> = 10K	50	-	-	50	-	ns
Turn-off Input Pulse Width	T <sub>PWIN-OFF</sub>	R <sub>HDEL</sub> = R <sub>LDEL</sub> = 10K	40	-	-	40	-	ns
Turn-on Output Pulse Width	T <sub>PWOUT-ON</sub>	R <sub>HDEL</sub> = R <sub>LDEL</sub> = 10K	40	-	-	40	-	ns
Turn-off Output Pulse Width	T <sub>PWOUT-OFF</sub>	R <sub>HDEL</sub> = R <sub>LDEL</sub> = 10K	30	-	-	30	-	ns
Disable Turn-off Propagation Delay (DIS - Lower Outputs)	T <sub>DISLOW</sub>		-	45	75	-	95	ns
Disable Turn-off Propagation Delay (DIS - Upper Outputs)	T <sub>DISHIGH</sub>		-	55	85	-	105	ns
Disable to Lower Turn-on Propagation Delay (DIS - ALO and BLO)	T <sub>DLPLH</sub>		-	40	70	-	90	ns
Refresh Pulse Width (ALO and BLO)	T <sub>REF-PW</sub>		240	410	550	200	600	ns
Disable to Upper Enable (DIS - AHO and BHO)	T <sub>UEN</sub>		-	450	620	-	690	ns

#### **TRUTH TABLE**

INPUT				ОИТРИТ		
ALI, BLI	BLI AHI, BHI U/V DIS			ALO, BLO	АНО, ВНО	
X	Х	Х	1	0	0	
1	Х	0	0	1	0	
0	1	0	0	0	1	
0	0	0	0	0	0	
X	Х	1	Х	0	0	

NOTE: X signifies that input can be either a "1" or "0".



## Pin Descriptions

PIN NUMBER	SYMBOL	DESCRIPTION
1	ВНВ	B High-side Bootstrap supply. External bootstrap diode and capacitor are required. Connect cathode of bootstrap diode and positive side of bootstrap capacitor to this pin. Internal charge pump supplies 30µA out of this pin to maintain bootstrap supply. Internal circuitry clamps the bootstrap supply to approximately 12.8V.
2	ВНІ	B High-side Input. Logic level input that controls BHO driver (Pin 20). BLI (Pin 5) high level input overrides BHI high level input to prevent half-bridge shoot-through, see Truth Table. DIS (Pin 3) high level input overrides BHI high level input. The pin can be driven by signal levels of 0V to 15V (no greater than V <sub>DD</sub> ).
3	DIS	DISable input. Logic level input that when taken high sets all four outputs low. DIS high overrides all other inputs. When DIS is taken low the outputs are controlled by the other inputs. The pin can be driven by signal levels of 0V to 15V (no greater than $V_{DD}$ ).
4	V <sub>SS</sub>	Chip negative supply, generally will be ground.
5	BLI	B Low-side Input. Logic level input that controls BLO driver (Pin 18). If BHI (Pin 2) is driven high or not connected externally then BLI controls both BLO and BHO drivers, with dead time set by delay currents at HDEL and LDEL (Pin 8 and 9). DIS (Pin 3) high level input overrides BLI high level input. The pin can be driven by signal levels of 0V to 15V (no greater than V <sub>DD</sub> ).
6	ALI	A Low-side Input. Logic level input that controls ALO driver (Pin 13). If AHI (Pin 7) is driven high or not connected externally then ALI controls both ALO and AHO drivers, with dead time set by delay currents at HDEL and LDEL (Pin 8 and 9). DIS (Pin 3) high level input overrides ALI high level input. The pin can be driven by signal levels of 0V to 15V (no greater than V <sub>DD</sub> ).
7	AHI	A High-side Input. Logic level input that controls AHO driver (Pin 11). ALI (Pin 6) high level input overrides AHI high level input to prevent half-bridge shoot-through, see Truth Table. DIS (Pin 3) high level input overrides AHI high level input. The pin can be driven by signal levels of 0V to 15V (no greater than V <sub>DD</sub> ).
8	HDEL	High-side turn-on DELay. Connect resistor from this pin to V <sub>SS</sub> to set timing current that defines the turn-on delay of both high-side drivers. The low-side drivers turn-off with no adjustable delay, so the HDEL resistor guarantees no shoot-through by delaying the turn-on of the high-side drivers. HDEL reference voltage is approximately 5.1V.
9	LDEL	Low-side turn-on DELay. Connect resistor from this pin to V <sub>SS</sub> to set timing current that defines the turn-on delay of both low-side drivers. The high-side drivers turn-off with no adjustable delay, so the LDEL resistor guarantees no shoot-through by delaying the turn-on of the low-side drivers. LDEL reference voltage is approximately 5.1V.
10	AHB	A High-side Bootstrap supply. External bootstrap diode and capacitor are required. Connect cathode of bootstrap diode and positive side of bootstrap capacitor to this pin. Internal charge pump supplies 30µA out of this pin to maintain bootstrap supply. Internal circuitry clamps the bootstrap supply to approximately 12.8V.
11	АНО	A High-side Output. Connect to gate of A High-side power MOSFET.
12	AHS	A High-side Source connection. Connect to source of A High-side power MOSFET. Connect negative side of bootstrap capacitor to this pin.
13	ALO	A Low-side Output. Connect to gate of A Low-side power MOSFET.
14	ALS	A Low-side Source connection. Connect to source of A Low-side power MOSFET.
15	V <sub>CC</sub>	Positive supply to gate drivers. Must be same potential as V <sub>DD</sub> (Pin 16). Connect to anodes of two bootstrap diodes.
16	$V_{DD}$	Positive supply to lower gate drivers. Must be same potential as V <sub>CC</sub> (Pin 15). De-couple this pin to V <sub>SS</sub> (Pin 4).
17	BLS	B Low-side Source connection. Connect to source of B Low-side power MOSFET.
18	BLO	B Low-side Output. Connect to gate of B Low-side power MOSFET.
19	BHS	B High-side Source connection. Connect to source of B High-side power MOSFET. Connect negative side of bootstrap capacitor to this pin.
20	вно	B High-side Output. Connect to gate of B High-side power MOSFET.



## **Timing Diagrams**

X = A OR B, A AND B HALVES OF BRIDGE CONTROLLER ARE INDEPENDENT

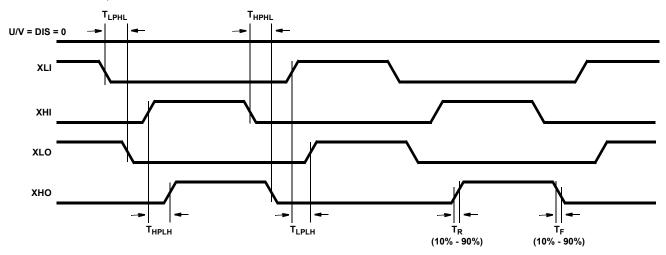


FIGURE 1. INDEPENDENT MODE

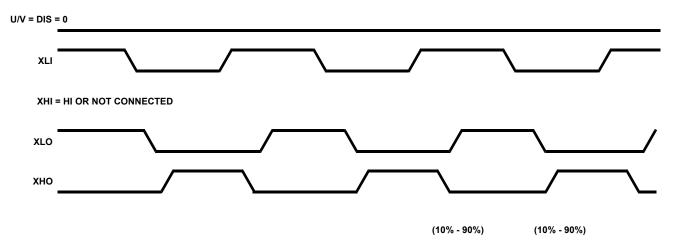


FIGURE 2. BISTATE MODE

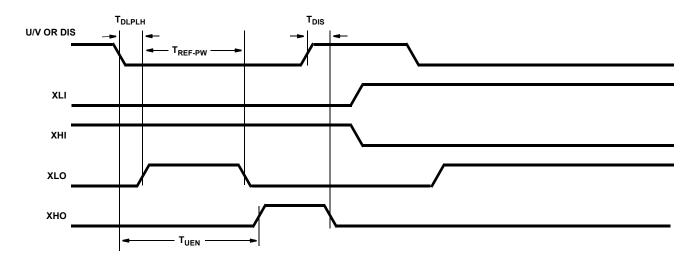


FIGURE 3. DISABLE FUNCTION

**Typical Performance Curves**  $V_{DD} = V_{CC} = V_{AHB} = V_{BHB} = 12V$ ,  $V_{SS} = V_{ALS} = V_{BLS} = V_{AHS} = 0V$ ,  $V_{BHS} = 0V$ ,  $V_{BHDEL} = 100K$  and  $V_{AHDEL} = 100K$ 

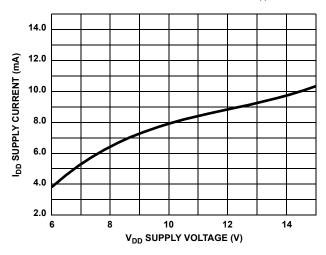


FIGURE 4. QUIESCENT  $I_{DD}$  SUPPLY CURRENT vs  $V_{DD}$  SUPPLY VOLTAGE

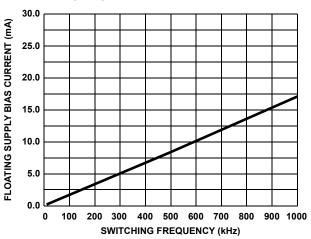


FIGURE 6. SIDE A, B FLOATING SUPPLY BIAS CURRENT vs FREQUENCY (LOAD = 1000pF)

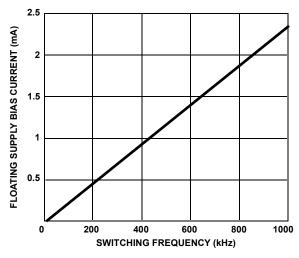


FIGURE 8.  $I_{AHB}$ ,  $I_{BHB}$ , NO-LOAD FLOATING SUPPLY BIAS CURRENT vs FREQUENCY

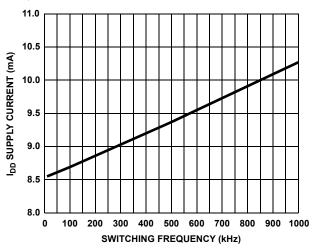


FIGURE 5.  $I_{DDO}$ , NO-LOAD  $I_{DD}$  SUPPLY CURRENT vs FREQUENCY (kHz)

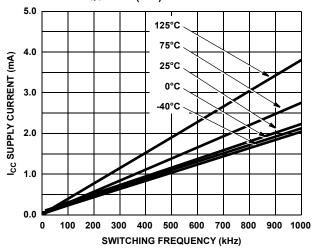


FIGURE 7.  $I_{CCO}$ , NO-LOAD  $I_{CC}$  SUPPLY CURRENT vs FREQUENCY (kHz) TEMPERATURE

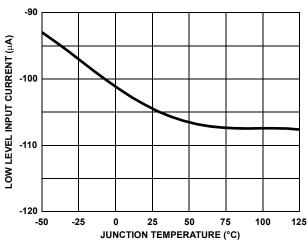


FIGURE 9. ALI, BLI, AHI, BHI LOW LEVEL INPUT CURRENT I<sub>IL</sub> vs TEMPERATURE

**Typical Performance Curves**  $V_{DD} = V_{CC} = V_{AHB} = V_{BHB} = 12V$ ,  $V_{SS} = V_{ALS} = V_{BLS} = V_{AHS} = 0V$ ,  $V_{BHS} = 0V$ ,  $V_{BHS} = 10V$ ,  $V_{BH$ 

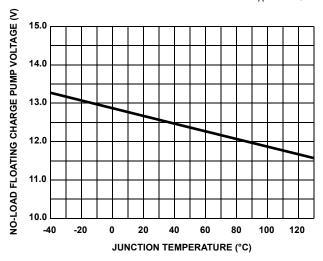


FIGURE 10. AHB - AHS, BHB - BHS NO-LOAD CHARGE PUMP VOLTAGE vs TEMPERATURE

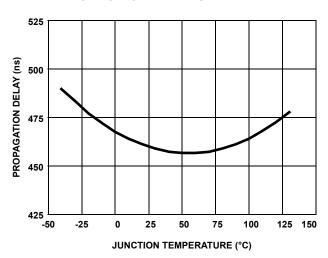


FIGURE 12. DISABLE TO UPPER ENABLE, T<sub>UEN</sub>,
PROPAGATION DELAY vs TEMPERATURE

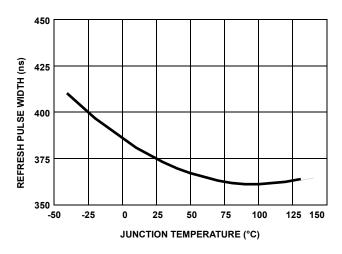


FIGURE 14.  $T_{REF,PW}$  REFRESH PULSE WIDTH vs TEMPERATURE

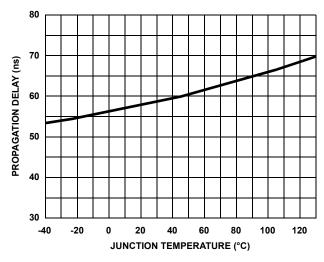


FIGURE 11. UPPER DISABLE TURN-OFF PROPAGATION DELAY T<sub>DISHIGH</sub> vs TEMPERATURE

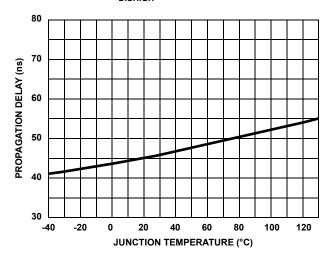


FIGURE 13. LOWER DISABLE TURN-OFF PROPAGATION DELAY  $T_{\text{DISLOW}}$  vs TEMPERATURE

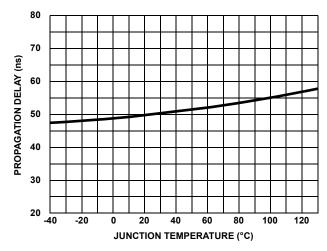


FIGURE 15. DISABLE TO LOWER ENABLE T<sub>DLPLH</sub>
PROPAGATION DELAY vs TEMPERATURE

**Typical Performance Curves**  $V_{DD} = V_{CC} = V_{AHB} = V_{BHB} = 12V, V_{SS} = V_{ALS} = V_{BLS} = V_{AHS} = 0V, R_{HDEL} = R_{LDEL} = 10K$  and  $T_A = 25^{\circ}C$ , Unless Otherwise Specified (Continued)

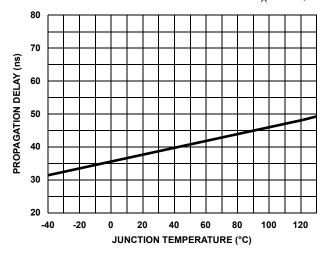


FIGURE 16. UPPER TURN-OFF PROPAGATION DELAY  $\mathsf{T}_{\mathsf{HPHL}}$  vs  $\mathsf{TEMPERATURE}$ 

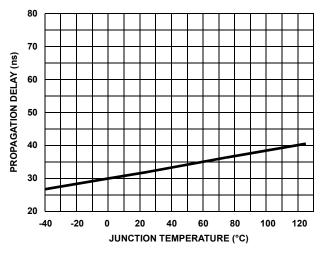


FIGURE 18. LOWER TURN-OFF PROPAGATION DELAY  $T_{LPHL}$  vs TEMPERATURE

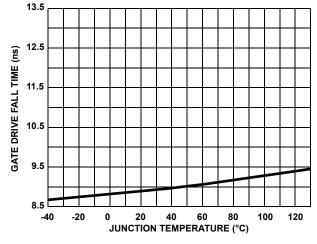


FIGURE 20. GATE DRIVE FALL TIME  $T_{\rm F}$  vs TEMPERATURE

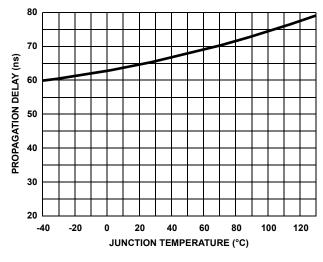


FIGURE 17. UPPER TURN-ON PROPAGATION DELAY  $T_{HPLH}$  vs TEMPERATURE

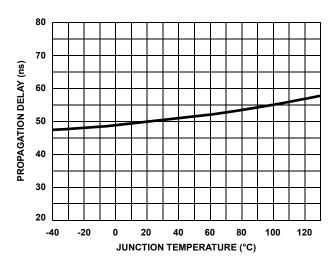


FIGURE 19. LOWER TURN-ON PROPAGATION DELAY  $T_{LPLH}$  vs  $T_{LPLH}$  vs

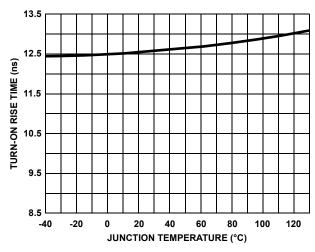


FIGURE 21. GATE DRIVE RISE TIME  $\mathrm{T}_{\mathrm{R}}$  vs TEMPERATURE

**Typical Performance Curves**  $V_{DD} = V_{CC} = V_{AHB} = V_{BHB} = 12V$ ,  $V_{SS} = V_{ALS} = V_{BLS} = V_{AHS} = 0V$ ,  $V_{BHS} = 0V$ ,  $V_{BHDEL} = 0V$ , V

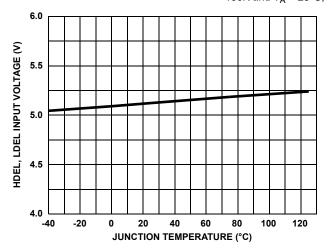


FIGURE 22.  $V_{LDEL}$ ,  $V_{HDEL}$  VOLTAGE vs TEMPERATURE

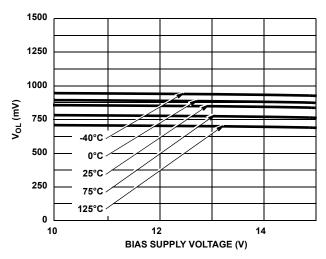


FIGURE 24. LOW LEVEL OUTPUT VOLTAGE  $V_{OL}$  vs BIAS SUPPLY AND TEMPERATURE AT 100mA

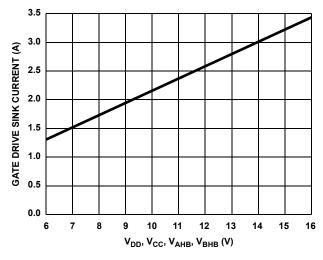


FIGURE 26. PEAK PULLUP CURRENT  $I_{O+}$  vs BIAS SUPPLY VOLTAGE

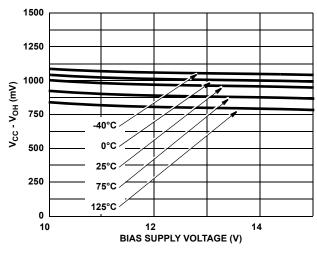


FIGURE 23. HIGH LEVEL OUTPUT VOLTAGE  $V_{CC}$  -  $V_{OH}$  vs BIAS SUPPLY AND TEMPERATURE AT 100mA

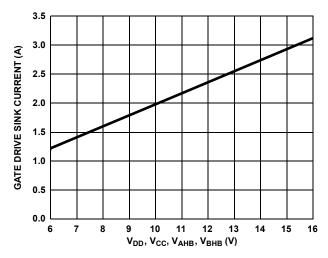


FIGURE 25. PEAK PULLDOWN CURRENT  $I_{\rm O}$  vs BIAS SUPPLY VOLTAGE

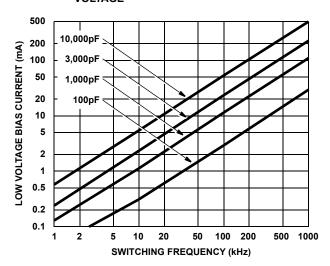


FIGURE 27. LOW VOLTAGE BIAS CURRENT I<sub>DD</sub> (LESS
QUIESCENT COMPONENT) vs FREQUENCY AND
GATE LOAD CAPACITANCE



Typical Performance Curves  $V_{DD} = V_{CC} = V_{AHB} = V_{BHB} = 12V$ ,  $V_{SS} = V_{ALS} = V_{BLS} = V_{AHS} = 0V$ ,  $V_{BHS} = 0V$ ,  $V_{BHS} = 0V$ ,  $V_{BHDEL} = 0V$ ,  $V_{BH$ 

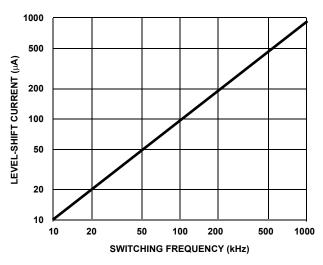
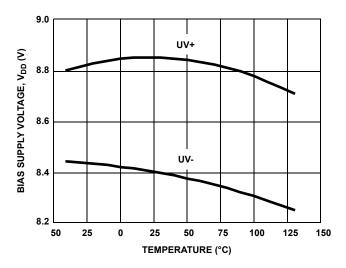


FIGURE 28. HIGH VOLTAGE LEVEL-SHIFT CURRENT VS FREQUENCY AND BUS VOLTAGE





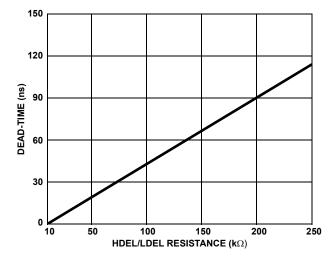


FIGURE 30. MINIMUM DEAD-TIME vs DEL RESISTANCE

CĎ4069UB

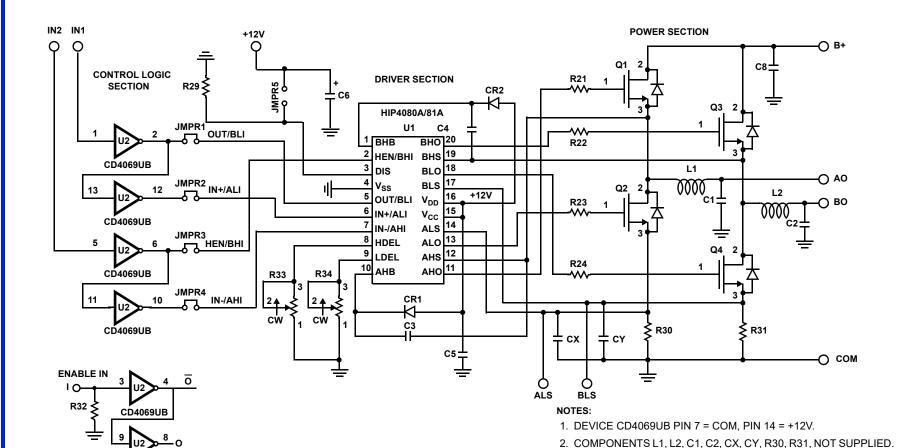


FIGURE 31. HIP4081A EVALUATION PC BOARD SCHEMATIC

REFER TO APPLICATION NOTE FOR DESCRIPTION OF INPUT

LOGIC OPERATION TO DETERMINE JUMPER LOCATIONS FOR

JMPR1 - JMPR4.

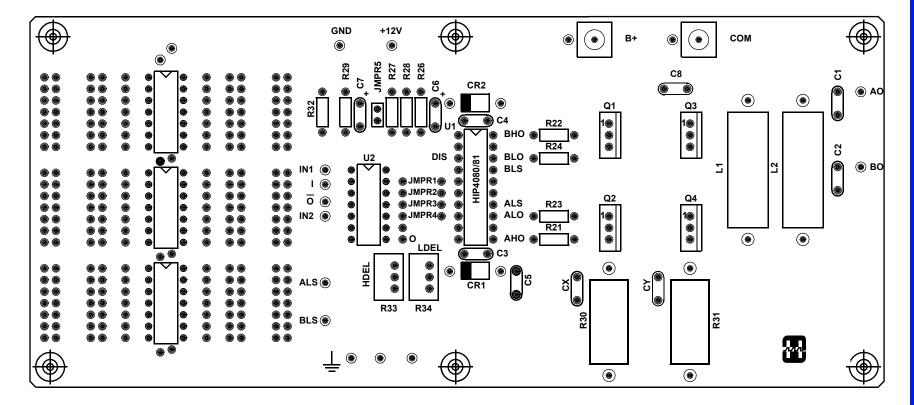


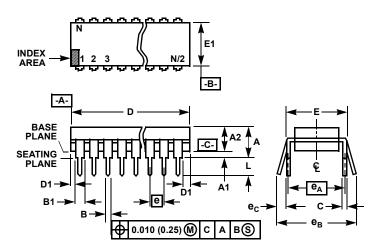
FIGURE 32. HIP4081A EVALUATION BOARD SILKSCREEN

## **Revision History**

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please go to the web to make sure that you have the latest revision.

DATE	REVISION	CHANGE
Feb 12, 2020	FN3659.9	Removed retired parts. Removed About Intersil section. Updated disclaimer.
Sep15, 2015	FN3659.8	Updated Ordering Information Table on page 1.  Added Revision History and About Intersil sections.  Updated POD M20.3 from rev 1 to rev 3. Changes since rev 1:  Top View:  Corrected "7.50 BSC" to "7.60/7.40" (no change from rev 2; error was introduced in conversion)  Changed "10.30 BSC" to "10.65/10.00" (no change from rev 2; error was introduced in conversion)  Side View:  Changed "12.80 BSC" to "13.00/12.60" (no change from rev 2; error was introduced in conversion)  Changed "2.65 max" to "2.65/2.35" (no change from rev 2; error was introduced in conversion)  Changed Note 1 from "ANSI Y14.5M-1982." to "ASME Y14.5M-1994"  Updated to new POD format by moving dimensions from table onto drawing and adding land pattern

## Dual-In-Line Plastic Packages (PDIP)



#### NOTES:

- Controlling Dimensions: INCH. In case of conflict between English and Metric dimensions, the inch dimensions control.
- 2. Dimensioning and tolerancing per ANSI Y14.5M-1982.
- Symbols are defined in the "MO Series Symbol List" in Section 2.2 of Publication No. 95.
- 4. Dimensions A, A1 and L are measured with the package seated in JEDEC seating plane gauge GS-3.
- D, D1, and E1 dimensions do not include mold flash or protrusions.
   Mold flash or protrusions shall not exceed 0.010 inch (0.25mm).
- 6. E and  $\boxed{e_A}$  are measured with the leads constrained to be perpendicular to datum  $\boxed{-C_-}$ .
- 7.  $e_B$  and  $e_C$  are measured at the lead tips with the leads unconstrained.  $e_C$  must be zero or greater.
- 8. B1 maximum dimensions do not include dambar protrusions. Dambar protrusions shall not exceed 0.010 inch (0.25mm).
- 9. N is the maximum number of terminal positions.
- 10. Corner leads (1, N, N/2 and N/2 + 1) for E8.3, E16.3, E18.3, E28.3, E42.6 will have a B1 dimension of 0.030 0.045 inch (0.76 1.14 mm).

**E20.3** (JEDEC MS-001-AD ISSUE D) 20 LEAD DUAL-IN-LINE PLASTIC PACKAGE

	INC	HES	MILLIN			
SYMBOL	MIN	MAX	MIN	MAX	NOTES	
Α	-	0.210	-	5.33	4	
A1	0.015	-	0.39	-	4	
A2	0.115	0.195	2.93	4.95	-	
В	0.014	0.022	0.356	0.558	-	
B1	0.045	0.070	1.55	1.77	8	
С	0.008	0.014	0.204	0.355	-	
D	0.980	1.060	24.89	26.9	5	
D1	0.005	-	0.13	-	5	
Е	0.300	0.325	7.62	8.25	6	
E1	0.240	0.280	6.10	7.11	5	
е	0.100	BSC	2.54 BSC		-	
e <sub>A</sub>	0.300	BSC	7.62 BSC		6	
e <sub>B</sub>	-	0.430	-	10.92	7	
L	0.115	0.150	2.93	3.81	4	
N	2	20		20		

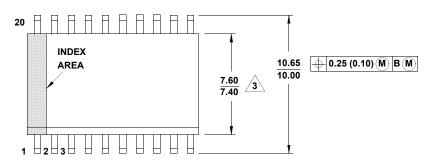
Rev. 0 12/93



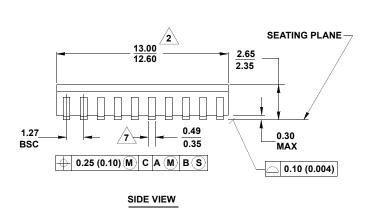
## **Package Outline Drawing**

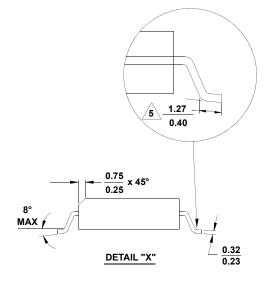
#### M20.3

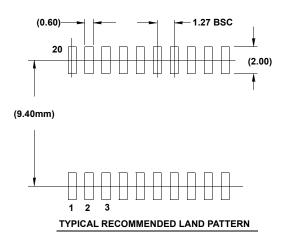
20 LEAD WIDE BODY SMALL OUTLINE PLASTIC PACKAGE (SOIC) Rev 3, 2/11



**TOP VIEW** 







#### NOTES:

- 1. Dimensioning and tolerancing per ASME Y14.5M-1994.
- 2. Dimension does not include mold flash, protrusions or gate burrs. Mold flash, protrusion and gate burrs shall not exceed 0.15mm (0.006 inch) per side.
- 3. Dimension does not include interlead lash or protrusions. Interlead flash and protrusions shall not exceed 0.25mm (0.010 inch) per side.
  - 4. The chamfer on the body is optional. If it is not present, a visual index feature must be located within the crosshatched area.
- 5. Dimension is the length of terminal for soldering to a substrate.
- 6. Terminal numbers are shown for reference only.
- 7. The lead width as measured 0.36mm (0.14 inch) or greater above the seating plane, shall not exceed a maximum value of 0.61mm (0.024 inch)
- 8. Controlling dimension: MILLIMETER.
- 9. Dimensions in ( ) for reference only.
- 10. JEDEC reference drawing number: MS-013-AC.

#### **Notice**

- Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products
  and application examples. You are fully responsible for the incorporation or any other use of the circuits, software, and information in the design of your
  product or system. Renesas Electronics disclaims any and all liability for any losses and damages incurred by you or third parties arising from the use of
  these circuits, software, or information.
- 2. Renesas Electronics hereby expressly disclaims any warranties against and liability for infringement or any other claims involving patents, copyrights, or other intellectual property rights of third parties, by or arising from the use of Renesas Electronics products or technical information described in this document, including but not limited to, the product data, drawings, charts, programs, algorithms, and application examples.
- 3. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or
- 4. You shall not alter, modify, copy, or reverse engineer any Renesas Electronics product, whether in whole or in part. Renesas Electronics disclaims any and all liability for any losses or damages incurred by you or third parties arising from such alteration, modification, copying or reverse engineering.
- 5. Renesas Electronics products are classified according to the following two quality grades: "Standard" and "High Quality". The intended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below.
  - "Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; industrial robots; etc.
  - "High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control (traffic lights); large-scale communication equipment; key financial terminal systems; safety control equipment; etc.

Unless expressly designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not intended or authorized for use in products or systems that may pose a direct threat to human life or bodily injury (artificial life support devices or systems; surgical implantations; etc.), or may cause serious property damage (space system; undersea repeaters; nuclear power control systems; aircraft control systems; military equipment; etc.). Renesas Electronics disclaims any and all liability for any damages or losses incurred by you or any third parties arising from the use of any Renesas Electronics product that is inconsistent with any Renesas Electronics data sheet, user's manual or other Renesas Electronics document.

- 6. When using Renesas Electronics products, refer to the latest product information (data sheets, user's manuals, application notes, "General Notes for Handling and Using Semiconductor Devices" in the reliability handbook, etc.), and ensure that usage conditions are within the ranges specified by Renesas Electronics with respect to maximum ratings, operating power supply voltage range, heat dissipation characteristics, installation, etc. Renesas Electronics disclaims any and all liability for any malfunctions, failure or accident arising out of the use of Renesas Electronics products outside of such specified ranges.
- 7. Although Renesas Electronics endeavors to improve the quality and reliability of Renesas Electronics products, semiconductor products have specific characteristics, such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Unless designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not subject to radiation resistance design. You are responsible for implementing safety measures to guard against the possibility of bodily injury, injury or damage caused by fire, and/or danger to the public in the event of a failure or malfunction of Renesas Electronics products, such as safety design for hardware and software, including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult and impractical, you are responsible for evaluating the safety of the final products or systems manufactured by you.
- 8. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. You are responsible for carefully and sufficiently investigating applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive, and using Renesas Electronics products in compliance with all these applicable laws and regulations. Renesas Electronics disclaims any and all liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
- 9. Renesas Electronics products and technologies shall not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations. You shall comply with any applicable export control laws and regulations promulgated and administered by the governments of any countries asserting jurisdiction over the parties or transactions.
- 10. It is the responsibility of the buyer or distributor of Renesas Electronics products, or any other party who distributes, disposes of, or otherwise sells or transfers the product to a third party, to notify such third party in advance of the contents and conditions set forth in this document.
- 11. This document shall not be reprinted, reproduced or duplicated in any form, in whole or in part, without prior written consent of Renesas Electronics.
- 12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products.
- (Note1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its directly or indirectly controlled subsidiaries.
- (Note2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.

(Rev.4.0-1 November 2017)

#### **Corporate Headquarters**

TOYOSU FORESIA, 3-2-24 Toyosu, Koto-ku, Tokyo 135-0061, Japan www.renesas.com

#### **Trademarks**

Renesas and the Renesas logo are trademarks of Renesas Electronics Corporation. All trademarks and registered trademarks are the property of their respective owners.

#### **Contact Information**

For further information on a product, technology, the most up-to-date version of a document, or your nearest sales office, please visit: www.renesas.com/contact/