

# 30V, 3.1A Monolithic Step-Down Switching Regulator in TSOT23-8

#### 1 Features

- 3.0A continuous output current capability
- 6.5V to 30Vwide operating input range with input Over Voltage Protection
- Integrated 36V,  $65m\Omega$  high side and 36V,  $45m\Omega$  low side power MOSFET switches
- Up to 95% efficiency
- Programmable Soft-Start limits the inrush current at turn-on
- Stable with Low ESR Ceramic Output Capacitors
- Fixed 300KHz Switching Frequency
- Input Under-Voltage Lockout.
- Input over-voltage protection to protect device from working in high voltage and high current condition
- Output short protection with both high side current limit and low side current limit to protect the device in hard short
- Output Over-Voltage Protection
- Over-Temperature Protection
- Small size Flip-Chip TSOT23-8 Package, best for narrow space application. More reliable and less parasitic voltage spike comparing with bonding wire package

## 2 Applications

- Set-Top-Box
- Televisions
- DVD, LCD Displays
- OLPC. Netbook
- Datacom, XDSL modems
- Distributed Power Systems
- USB car charger
- Portable charging device
- General purpose

### 3 Description

HM1483 is a monolithic 30V, 3.0A step-down switch regulator. HM1483 integrates a 36V 65m $\Omega$  high side and a 36V, 45m $\Omega$  low side MOSFETs to provide 3.0A continuous load current over a 6.5V to 36V wide operating input voltage with 30V input over voltage protection. Peak current mode control provides fast transient responses and cycle-by-cycle current limiting. Programmable soft-start prevents inrush current at power-up. Flip-chip TSOT23-8 package makes the part best fit narrow space applications

## **4 Typical Application Schematic**

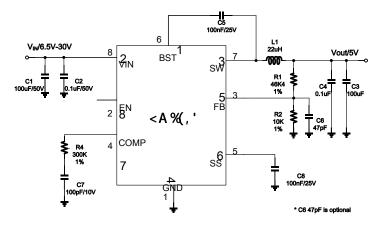


Fig. 1 Schematic

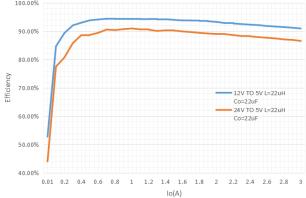
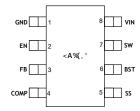


Fig. 2 Efficiency curve



## **5 Pin Configuration and Functions**

## TSOT23-8 Package (Top View)



**Pin-Functions** 

Pin		Description		
Number	Name	Description		
1	GND	Ground.		
2	EN	Enable Input. EN is a digital input that turns the regulator on or off. Drive EN high to turn on the regulator; low to turn it off. EN pin is pulled to VIN internally by a larger resistor.		
3	FB	Feedback Input. FB senses the output voltage. Connect FB with a resistor divider connected between the output and ground. FB is a sensitive node. Keep FB away from SW and BST pin. It is better to connect a 47pF capacitor between FB and GND to filter out possible coupling noise from other noisy nodes such as SW, BST and VIN.		
4	COMP	Connect compensation network to make the converter work stably.		
5	SS	This pin is used to program soft-start time, connect a cap to program soft-start time.		
6	BST	Boot-Strap pin. Connect a 0.1µF or greater capacitor between SW and BST to power the high side gate driver. A resistor can be added between the 0.1uF capacitor and BST pin to slower down high side driver speed and EMI noise.		
7	SW	Power Switching pin. Connect this pin to the switching node of inductor.		
8	VIN	Power Input. VIN supplies the power to the IC. Supply VIN with a 6.5V to 30V power source. Bypass VIN to GND with a large capacitor and at least another 0.1uF ceramic capacitor to eliminate noise on the input to the IC. Put the capacitors close to VIN and GND pins. It is better to minimize the 0.1uF ceramic capacitor, VIN pin, GND pin loop area to reduce EMI noise and voltage spike on high side power device.		

# **6 Device Marking Information**

Part Number	Order Information	Package	Package Qty	Top Marking
HM1483	HM1483	TSOT23-8	3000	83** RAABB

83\*\*: Part Number

RAABB: R: Year; AABB: Manufacturing Code

## **7Specifications**

# 7.1 Absolute Maximum Ratings<sup>(Note1)</sup>

	PARAMETER	MIN	MAX	Unit
	V <sub>IN</sub> to GND	-0.3	36	
Input Voltages	V <sub>EN</sub> to GND	-0.3	6	V
Input Voltages	V <sub>SS</sub> to GND	-0.3	6	V
	V <sub>FB</sub> to GND	-0.3	6	
	V <sub>COMP</sub> to GND	-0.3	6	
Output Voltages	$V_{BST}$ to $V_{SW}$	-0.3	6	V
	V <sub>SW</sub> to GND	-1	V <sub>IN</sub> + 0.3	



## 7.2 Handling Ratings

PARAMETER DEFINITION		MIN	MAX	UNIT
T <sub>ST</sub> Storage Temperature Range		-65	150	C
TJ	Junction Temperature		+160	C
T <sub>L</sub> Lead Temperature			+260	C
.,	HBM Human body model		2	kV
V <sub>ESD</sub>	MMMACHINE MODE		400	V

# 7.3 Recommended Operating Conditions (Note 2)

	PARAMETER	MIN	MAX	Unit	
	V <sub>IN</sub> to GND	6.5	30		
Input Voltages	EN	-0.3	5	V	
Input Voltages	SS	-0.3	5	V	
	FB	-0.3	5		
Output Voltages	V <sub>ОUТ</sub>	0.5	V <sub>IN</sub> *D <sub>max</sub>	V	
Output Current	louт	0	3.1	Α	
Temperature	Operating junction temperature range, T <sub>J</sub>	-40	+125	C	

# 7.4 Thermal Information<sup>(Note 3)</sup>

Symbol	Description	TSOT23-8	Unit
$\theta_{JA}$	Junction to ambient thermal resistance	100	°C/W
θ <sub>JC</sub>	Junction to case thermal resistance	55	C/VV

### Notes:

- Exceeding these ratings may damage the device.
   The device function is not guaranteed outside of the recommended operating conditions.
   Measured on approximately 1" square of 1 oz copper.



## **7.5 Electrical Characteristics** (Typical at Vin = 12V, T<sub>J</sub>=25°C, unless otherwise noted.)

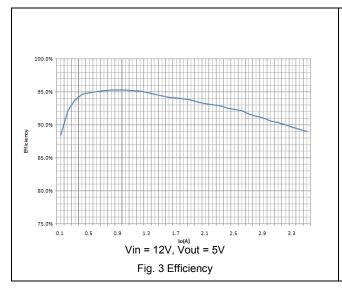
SYMBOL	PARAMETER	CONDITION	MIN	TYP	MAX	UNIT	
BUCK CONVERTER							
MOSFET							
I <sub>leak_sw</sub>	High-Side Switch Leakage Current	$V_{EN} = 0V$ , $V_{SW} = 0V$		0	10	μA	
R <sub>DS(ON)_H</sub>	High-Side Switch On-Resistance	I <sub>OUT</sub> = 1A, V <sub>OUT</sub> = 3.3V		65		mΩ	
R <sub>DS(ON)_L</sub>	Low-Side Switch On-Resistance	I <sub>OUT</sub> = 1A, V <sub>OUT</sub> = 3.3V		45		mΩ	
SUPPLY V	OLTAGE (VIN)						
V <sub>UVLO up</sub>	Minimum input voltage for startup				6.5	V	
V <sub>UVLO_down</sub>				6.0		V	
V <sub>UVLO hys</sub>				0.5		V	
I <sub>Q-NONSW</sub> CONTROL	Operating quiescent current	V <sub>FB</sub> =1.1V		1		mA	
Fosch	Buck oscillator frequency			300		kHz	
V <sub>FB</sub>	Feedback Voltage	6.5V ≤ VIN ≤ 30V		0.9		V	
V <sub>FB_OVP</sub>	Feedback Over-voltage Threshold			0.99		V	
D <sub>max</sub>	Maximum Duty Cycle <sup>(Note 4)</sup>			94		%	
Ton	Minimum On Time <sup>(Note 4)</sup>			100		ns	
PROTECTI	ON						
I <sub>ocl_hs</sub>	Upper Switch Current Limit	Minimum Duty Cycle		5.9		Α	
I <sub>ocl_ls</sub>	Lower Switch Current Limit	From Drain to Source		5.5		Α	
$V_{inovp}$	Input Over voltage protection			33		V	
Th <sub>sd</sub>	Thermal Shutdown <sup>(Note 4)</sup>			155		C	
Th <sub>sdhys</sub>	Thermal Shutdown Hysteresis <sup>(Note 4)</sup>			15		С	
V <sub>IH</sub>	EN High Voltage		1.2			V	
VIL	EN Low Voltage				1.1	V	
I <sub>EN</sub>	EN Input Current			1.5		uA	
I <sub>chg_ss</sub>	Soft-Start Charge Current			2.3		uA	
I <sub>cmp_src</sub>	Comp Source Current	V <sub>FB</sub> = 1.0 V		5.5		uA	
I <sub>cmp_snk</sub>	Comp Sink Current	V <sub>FB</sub> = 0.8 V		3.6		uA	

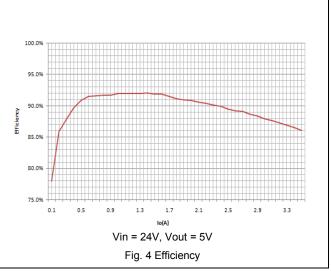
#### Note:

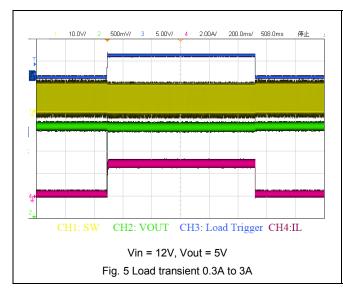
<sup>4)</sup> Guaranteed by design, not tested in production.

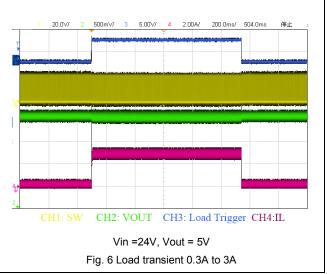


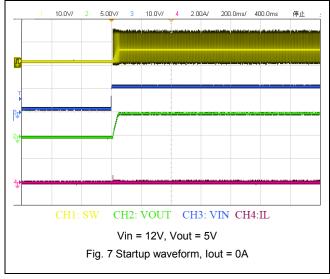
## **8 Typical Characteristics**

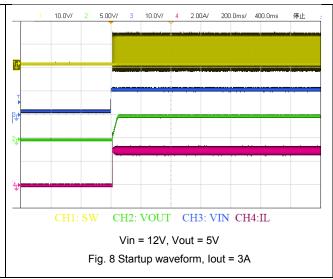




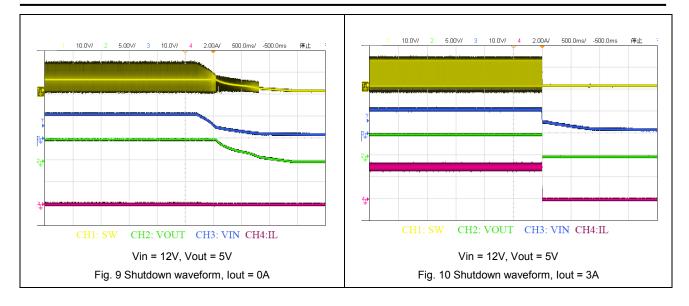


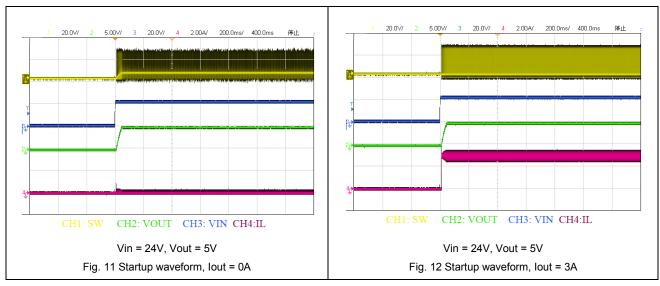


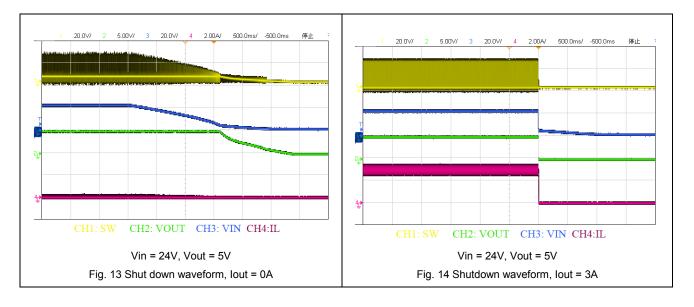




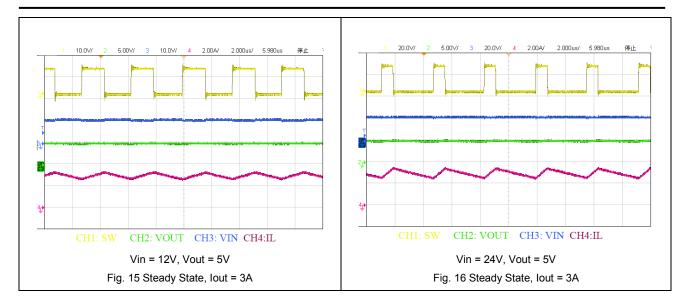


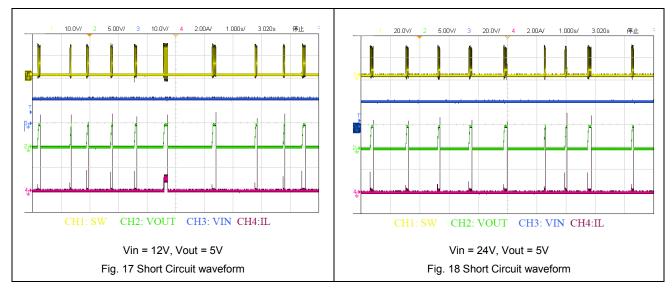














### 9 Detailed Description

#### 9.1 Overview

HM1483 is an easy to use synchronous step-down DC-DC converter that operates from 6.5V to 30V supply voltage. It is capable of delivering up to 3.1A continuous load current with high efficiency and thermal performance in a very small solution size.

HM1483 also integrates input over voltage and output over voltage protection. This feature helps customers to design a safe DC-DC converter easily.

The switching frequency is fixed at 300 kHz switching frequency to minimize inductor size and improve EMI performance. The soft-start time can be adjusted through SS pin capacitor.

#### 9.2 Functional Block Diagram

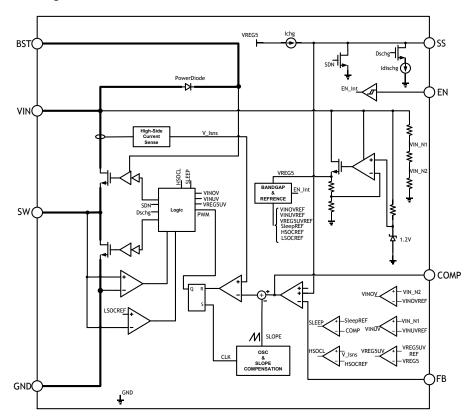


Fig.19 HM1483 Diagram

#### 9.3 Peak Current Mode Control

HM1483 employs a fixed 300kHz frequency peak current mode control. The output voltage is sensed by an external feedback resistor string on FB pin and fed to an internal error amplifier. The output of error amplifier will compare with high side current sense signal by an internal PWM comparator. When the second signal is higher than the first one, the PWM comparator will generate a turn-off signal to turn off high side switch. The output voltage of error amplifier will increase or decrease proportionally with the output load current. HM1483 has a cycle-by-cycle peak current limit feature inside to help maintain load current in a safe region.

#### 9.4 Sleep Operation for Light Load Efficiency

HM1483 has an internal feature to help improving light load efficiency. When output current is low, HM1483 will go into sleep mode.

#### 9.5 Voltage Reference

Internal circuit produces a precise ±1.5% voltage reference supported by HM1483.

#### 9.6 Setting Output Voltage

The output voltage is set with a resistor divider from the output node to the FB pin. 1% resistance accuracy of this resistor divider is preferred. The output voltage value is set as equation 1 below ( $R_1$  is the upper resistor,  $R_2$  is the lower resistor).



out ref 
$$\frac{1}{}$$
 (1)

V<sub>ref</sub> is the internal reference voltage of HM1483, which is 0.9V.

#### 9.7 Setting Enable Threshold

When the voltage at EN pin exceeds the threshold, HM1483 begins to work. When keeping EN low (below threshold), HM1483 stops working. The guiescent current of HM1483 is very low to maintain a good shut down operation for system.

HM1483 has an internal pull up resistor to make sure IC work when EN pin is float. If an application requires controlling EN pin, use open drain or open collector output logic circuit to interface with it.

When system needs a higher VIN UVLO threshold, the EN pin can be configured as shown in Figure 5 below.

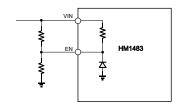


Fig.20 Adjustable VIN Under Voltage Lockout

#### 9.8 Error Amplifier

HM1483 has a trans-conductance error amplifier. It compares FB voltage with the lower one between 0.9V reference voltage and the soft-start voltage appearing at SS pin. The trans-conductance of the error amplifier is 28uA/V. The frequency compensation components are placed at COMP pin.

### 9.9 Slope Compensation

In order to avoid sub-harmonic oscillation at high duty cycle, HM1483 adds a slope compensation ramp to the sensed signal of current flowing through high side switch.

#### 9.10 Bootstrap Voltage provided by internal LDO

HM1483 has an internal LDO to provide energy consumed by high side switch. At BST pin, HM1483 needs a small ceramic capacitor like 100nF between BST and SW pin to provide gate-drive voltage for high side switch. The bootstrap capacitor is charged when high side is off. In Continuous-Current-Mode, the bootstrap capacitor will be charged when low side is on. The bootstrap capacitor voltage will be maintained at about 5.3V. When IC works under sleep mode, what value the bootstrap capacitor is charged depends on the difference of VIN and output voltage. However, when the voltage on the bootstrap capacitor is below bootstrap voltage refresh threshold, HM1483 will force low side on to charge bootstrap capacitor. Connecting an external diode from the output of regulator to the BST pin will also work and increase the efficiency of the regulator when output is high enough.

In order to improve EMI performance, a resistor can be connected between BST pin and bootstrap capacitor to slow down the turn-on speed of high side power switch.

#### 9.11 Soft-Start and Hiccup

HM1483 needs a capacitor at SS pin to support soft-start function. The soft-start time can be adjusted by setting different soft-start capacitor at this pin. There is an internal 2.3uA current to charge SS capacitor when it starts to work. The capacitor is also used to configure the short circuit hiccup rest time. After soft start ended, when  $V_{FB}$ <0.3V , HM1483 will go into hiccup mode to limit average load current. HM1483 will exit hiccup mode once the over current condition is removed.

#### 9.12 High Side Over-Current Protection

In HM1483, high-side MOSFET current is sensed. This sensed signal will compare the lower voltage between COMP pin voltage and over current threshold. High-side MOSFET will be turned off when the sensed current reaches the lower voltage. In normal operation, COMP pin voltage will be lower. If the over current threshold is lower, HM1483 enters over current protection mode.

#### 9.13 Low Side Over-Current Protection

When the low-side MOSFET is turned on, the conduction current is monitored and the SW voltage is sensed. When the difference between GND and SW is higher than an internal threshold, it means HM1483 is under over current mode. The high side switch won't be turned on until low side MOSFET's current is lower than the over current limit. When the low side MOSFET current reaches zero, it will be immediately turned off.



#### 9.14 Thermal Shutdown

The internal thermal-shutdown circuitry forces the device to stop switching if the junction temperature exceeds 155°C typically. When the junction temperature drops below 140°C, IC will start to work again.

#### 10 Application and Implementation

#### 10.1 Inductor selection

An inductor is required to supply constant current to the load while being driven by the switched input voltage. A larger value inductor will result in less current ripple and lower output voltage ripple. However, the larger value inductor will have larger physical size, higher DC resistance, and/or lower saturation current. A good rule to calculate the inductance is to allow the peak-to-peak ripple current in the inductor to be approximately 25% of the maximum load current. At the same time, it is needed to make sure that the peak inductor current is below the inductor saturation current.

The inductance value can be calculated by:

$$\frac{1}{f_s}$$
 (1-\ldots) (2)

Where  $V_{OUT}$  is the output voltage,  $V_{IN}$  is the input voltage,  $f_S$  is the switching frequency, and  $\Delta_L$  is the peak-to-peak inductor ripple current.

Choose an inductor that will not saturate under the maximum peak current. The peak inductor current can be calculated by:

$$load = \frac{1}{f_s} \left(1 - \frac{1}{f_s}\right)$$
 (3)

Where I<sub>load</sub> is the load current.

The choice of inductor material mainly depends on the price vs. size requirements and EMI constraints.

#### 10.2 Optional Schottky Diode

During the transition between the high-side switch and low-side switch, the body diode of the low-side power MOSFET conducts the inductor current. The forward voltage of this body diode is high. An optional Schottky diode may be paralleled with low side MOSFET to improve overall efficiency. Table 2 lists example Schottky diodes and their Manufacturers.

Table 2 - Diode Selection Guide

Part Number	Voltage/Current Rating	Vendor
SS25FA	50V/2A	Fairchild
B240A	40V/2A	Vishay

### 10.3 Input capacitors selection

The input current to the step-down converter is discontinuous, therefore a capacitor is required to supply the AC current to the converter. It is recommend to use low ESR capacitors to optimize the performance. Ceramic capacitor is preferred, but tantalum or low-ESR electrolytic capacitors may also meet the requirements. It is better to choose X5R or X7R dielectrics when using ceramic capacitors.

Since the input capacitor  $(C_{IN})$  absorbs the input switching current, a good ripple current rating is required for the capacitor. The RMS current in the input capacitor can be estimated by:

The worst-case condition occurs at  $V_{IN} = 2 \times V_{OUT}$ , where:

For simplification, choose the input capacitor whose RMS current rating is greater than half of the maximum load current.

When electrolytic or tantalum capacitors are used, a small, high quality ceramic capacitor, i.e.  $0.1\mu F$ , should be placed as close to the IC as possible. When ceramic capacitors are used, make sure that they have enough capacitance to maintain voltage ripple at input. The input voltage ripple caused by capacitance can be estimated by:



$$\frac{\log d}{f_{\circ}} - \left(1 - \dots\right)$$
 (6)

C<sub>IN</sub> is the input capacitance.

#### 10.4 Output capacitors selection

The output capacitor ( $C_{OUT}$ ) is required to maintain the DC output voltage. Ceramic, tantalum, or low ESR electrolytic capacitors are recommended.

Low ESR capacitors are preferred to keep the output voltage ripple low. The output voltage ripple can be estimated by:

$$\frac{}{f_s}$$
  $\left(1---\right)$   $\left(-\frac{1}{f_s}\right)$  (7)

Where L is the inductor value,  $R_{ESR}$  is the equivalent series resistance (ESR) value of the output capacitor and  $C_{OUT}$  is the output capacitance value. In the case of ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance. The output voltage ripple is mainly determined by the capacitance. For simplification, the output voltage ripple can be estimated by:

$$-\frac{}{f_s}$$
  $\left(1-\frac{}{}\right)$  (8)

In the case of tantalum or electrolytic capacitors, the ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated to:

$$\frac{}{f_s}$$
  $\left(1-\frac{}{}\right)$  (9)

The characteristics of the output capacitor also affect the stability of the regulator. PL6320is optimized for a wide range of capacitance and ESR values.

#### 10.5 External bootstrap diode

It is recommended that an external bootstrap diode could be added when the system has a 5V fixed input or the power supply generates a 5V output. This helps improve the efficiency of the regulator. The bootstrap diode can be a low cost one such as IN4148 or BAT54.

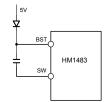


Fig.21 External Bootstrap Diode

This diode is also recommended for high duty cycle operation (when  $(V_{OUT}/V_{IN}) > 65\%$ ) and high output voltage  $(V_{OUT} > 12V)$  applications.



### 11 PCB Layout

#### 11.1 Guideline

PCB layout is a critical portion of good power supply design. The following guidelines will help users design a PCB with the best power conversion efficiency, thermal performance, and minimized EMI.

- The feedback network, resistor R<sub>1</sub> and R<sub>2</sub>, should be kept close to FB pin. V<sub>out</sub> sense path should stay away from noisy nodes, such as SW and BST signals and preferably through a layer on the other side of shielding layer.
- 2. The input bypass capacitor  $C_1$  and  $C_2$  must be placed as close as possible to the  $V_{IN}$  pin and ground. Grounding for both the input and output capacitors should consist of localized top side planes that connect to the GND pin and PAD. It is a good practice to place a ceramic cap near the  $V_{IN}$  pin to reduce the high frequency injection current.
- 3. The inductor L should be placed close to the SW pin to reduce magnetic and electrostatic noise.
- 4. The output capacitor, C<sub>OUT</sub> should be placed close to the junction of L and the diode D. The L, D, and C<sub>OUT</sub> trace should be as short as possible to reduce conducted and radiated noise and increase overall efficiency.
- 5. The ground connection for C<sub>1</sub>, C<sub>2</sub> and C<sub>3</sub>, C<sub>4</sub> should be as small as possible and connect to system ground plane at only one spot (preferably at the C<sub>OUT</sub> ground point) to minimize injecting noise into system ground plane.

#### 11.2 Example

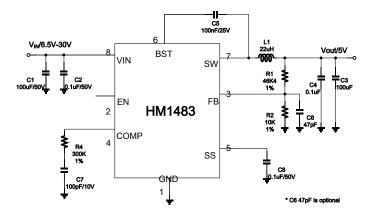


Fig.22 Schematic

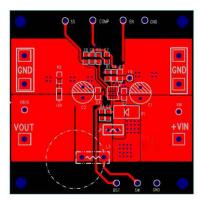


Fig. 23 Top layer layout

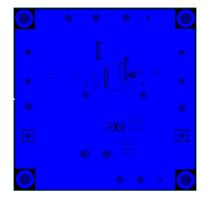
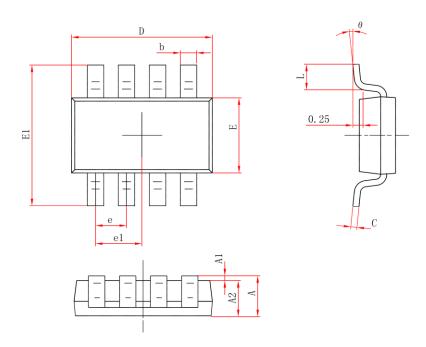


Fig. 24 Bottom layer layout



# 12 Packaging Information

## TSOT-23-8L PACKAGE OUTLINE DIMENSIONS



Symbol	Dimensions In Millimeters		Dimensions In Inches		
Symbol	Min	Max	Min	Max	
Α	0.700	0.900	0.028	0.035	
A1	0.000	0.100	0.000	0.004	
A2	0.700	0.800	0.028	0.031	
b	0.300	0.400	0.012	0.016	
С	0.080	0.200	0.003	0.008	
D	2.820	3.020	0.111	0.119	
E	1.600	1.700	0.063	0.067	
E1	2.650	2.950	0.104	0.116	
е	0.65 (E	BSC)	0.026(BSC)		
e1	0.975 (	BSC)	0.038(BSC)		
L	0.300	0.600	0.012	0.024	
θ	0°	8°	0°	8°	



# 13 Taping Orientation

