

HT48R062/HT48C062

Cost-Effective I/O Type 8-Bit MCU

Technical Document

- Tools Information
- FAQs
- Application Note
 - HA0003E Communicating between the HT48 & HT46 Series MCUs and the HT93LC46 EEPROM
 - HA0013E HT48 & HT46 LCM Interface Design
 - HA0016E Writing and Reading to the HT24 EEPROM with the HT48 MCU Series
 - HA0018E Controlling the HT1621 LCD Controller with the HT48 MCU Series
 - HA0049E Read and Write Control of the HT1380

Features

- Operating voltage: f_{SYS}=4MHz: 2.2V~5.5V f_{SYS}=8MHz: 3.3V~5.5V
- 11 bidirectional I/O lines
- On-chip crystal and RC oscillator
- · Watchdog Timer
- 1K×14 program memory
- 32×8 data RAM
- HALT function and wake-up feature reduce power consumption

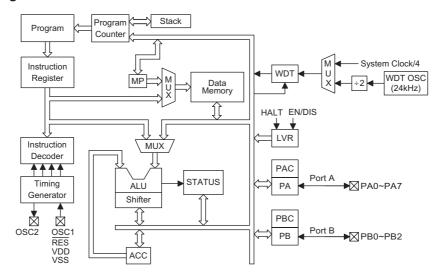
- 63 powerful instructions
- Up to 0.5μs instruction cycle with 8MHz system clock
- All instructions in 1 or 2 machine cycles
- · 14-bit table read instructions
- One-level subroutine nesting
- · Bit manipulation instructions
- Low voltage reset function
- 16-pin DIP/NSOP package

General Description

The HT48R062/HT48C062 are 8-bit high performance, RISC architecture microcontroller devices specifically designed for cost-effective multiple I/O control product applications. The mask version HT48C062 is fully pin and functionally compatible with the OTP version HT48R062 devices.

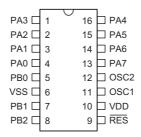
The advantages of low power consumption, I/O flexibility, oscillator options, HALT and wake-up functions, watchdog timer, as well as low cost, enhance the versatility of these devices to suit a wide range of application possibilities such as industrial control, consumer products, subsystem controllers, etc.

Block Diagram





Pin Assignment



HT48R062/HT48C062 -16 DIP-A/NSOP-A

Pin Description

Pin Name	I/O	Code Option	Description
PA0~PA7	I/O	Pull-high Wake-up	Bidirectional 8-bit input/output port. Each bit can be configured as wake-up input by options. Software instructions determine the CMOS output or Schmitt trigger input with a pull-high resistor (determined by pull-high options).
PB0~PB2	I/O	Pull-high	Bidirectional 3-bit input/output port. Software instructions determine the CMOS output or Schmitt trigger input with a pull-high resistor (determined by pull-high options).
VDD		_	Positive power supply
VSS	_	_	Negative power supply, ground
OSC2 OSC1	0	Crystal or RC	OSC1, OSC2 are connected to an RC network or a crystal (determined by code option) for the internal system clock. In the case of RC operation, OSC2 is the output terminal for 1/4 system clock (NMOS open drain output).
RES	ı	_	Schmitt trigger reset input. Active low.

Absolute Maximum Ratings

Supply Voltage	V_{SS} -0.3V to V_{SS} +6.0V	Storage Temperature	50°C to 125°C
Input Voltage	V_{SS} -0.3V to V_{DD} +0.3V	Operating Temperature	40°C to 85°C
IOL Total	150mA	IOH Total	–100mA
Total Power Dissipation	500mW		

Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.

D.C. Characteristics Ta=25°C

Symbol	Parameter		Test Conditions	Min.	Tun	Max.	l lmi4
	Parameter	V_{DD}	Conditions	wiin.	Тур.	wax.	Unit
\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	On a making at Malka ma	_	f _{SYS} =4MHz	2.2	_	5.5	V
V_{DD}	Operating Voltage		f _{SYS} =8MHz	3.3		5.5	V
	0 " 0 " (0 1 1 0 0 0)		No local 6 - 4NALI-	_	0.6	1.5	mA
I _{DD1}	Operating Current (Crystal OSC)	5V	No load, f _{SYS} =4MHz	_	2	4	mA
	Operating Current (RC OSC)		No load, f _{SYS} =4MHz	_	0.8	1.5	mA
I _{DD2}				_	2.5	4	mA

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Complete !	Damana dan		Test Conditions		_		Unit
Symbol	Parameter	V _{DD}	Conditions	Min.	Тур.	Max.	
I _{DD3}	Operating Current (Crystal OSC, RC OSC)	5V	No load, f _{SYS} =8MHz	_	4	8	mA
ı	Chandless Command (MDT Franklad)	3V	No local sustains HALT	_	_	5	μА
I _{STB1}	Standby Current (WDT Enabled)	5V	No load, system HALT	_	_	10	μА
	Other division of AMDT District (AMDT District (AMD	3V	No local content HALT	_	_	1	μΑ
I _{STB2}	Standby Current (WDT Disabled)	5V	No load, system HALT	_	_	2	μΑ
V _{IL1}	Input Low Voltage for I/O Port		_	0	_	0.3V _{DD}	V
V _{IH1}	Input High Voltage for I/O Port		_	0.7V _{DD}	_	V _{DD}	V
V _{IL2}	Input Low Voltage (RES)		_	0	_	0.4V _{DD}	V
V _{IH2}	Input High Voltage (RES)		_	0.9V _{DD}	_	V _{DD}	V
V_{LVR}	Low Voltage Reset		LVRenabled	2.7	3	3.3	V
	1/0 P	3V	V =0.4V	4	8	_	mA
l _{OL}	I/O Port Sink Current	5V	V _{OL} =0.1V _{DD}	10	20	_	mA
		3V	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	-2	-4	_	mA
I _{OH}	I/O Port Source Current	5V	-V _{OH} =0.9V _{DD}	-5	-10	_	mA
<u></u>	B. III. I. B	3V		20	60	100	kΩ
R _{PH}	Pull-high Resistance	5V	<u> </u>	10	30	50	kΩ

A.C. Characteristics

Cumbal	Parameter		Test Conditions	Min	Trees	Mari	Unit
Symbol			Conditions	Min.	Тур.	Max.	
f	Customs Clash (Countal CCC)		2.2V~5.5V	400	_	4000	kHz
f _{SYS1}	System Clock (Crystal OSC)	_	3.3V~5.5V	400	_	8000	kHz
		_	2.2V~5.5V	400	_	4000	kHz
f _{SYS2}	System Clock (RC OSC)		3.3V~5.5V	400	_	8000	kHz
	Wateh dan Oas 'Hatan Ban'a d	3V		22	45	90	μS
twdtosc	Watchdog Oscillator Period	5V	_	16	32	64	μS
t _{RES}	External Reset Low Pulse Width	_	_	1	_	_	μS
t _{SST}	System Start-up Timer Period	_	Power-up or wake-up from HALT	_	1024	_	t _{SYS}
t _{LVR}	Low Voltage Width to Reset	_	_	0.25	1	2	ms

Note: t_{SYS} =1/ f_{SYS}



Functional Description

Execution Flow

The HT48R062/HT48C062 system clock can be derived from a crystal/ceramic resonator oscillator or an RC. It is internally divided into four non-overlapping clocks. One instruction cycle consists of four system clock cycles.

Instruction fetching and execution are pipelined in such a way that a fetch takes an instruction cycle while decoding and execution takes the next instruction cycle. However, the pipelining scheme causes each instruction to effectively execute in a cycle. If an instruction changes the program counter, two cycles are required to complete the instruction.

Program Counter - PC

The 10-bit program counter (PC) controls the sequence in which the instructions stored in program ROM are executed and its contents specify a maximum of 1024 addresses.

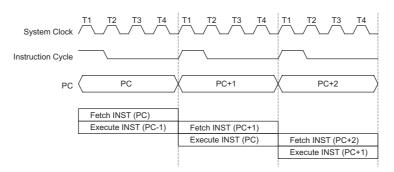
After accessing a program memory word to fetch an instruction code, the contents of the program counter are incremented by one. The program counter then points to the memory word containing the next instruction code.

When executing a jump instruction, conditional skip execution, loading PCL register, subroutine call, initial reset or return from subroutine, the PC manipulates the program transfer by loading the address corresponding to each instruction.

The conditional skip is activated by instruction. Once the condition is met, the next instruction, fetched during the current instruction execution, is discarded and a dummy cycle replaces it to get the proper instruction. Otherwise proceed with the next instruction.

The lower byte of the program counter (PCL) is a readable and writeable register (06H). Moving data into the PCL performs a short jump. The destination will be within 256 locations.

When a control transfer takes place, an additional dummy cycle is required.



Execution Flow

Mada	Program Counter									
Mode	*9	*8	*7	*6	*5	*4	*3	*2	*1	*0
Initial Reset	0	0	0	0	0	0	0	0	0	0
Skip	Program Counter+2									
Loading PCL	*9	*8	@7	@6	@5	@4	@3	@2	@1	@0
Jump, Call Branch	#9	#8	#7	#6	#5	#4	#3	#2	#1	#0
Return from Subroutine	S9	S8	S7	S6	S5	S4	S3	S2	S1	S0

Program Counter

Note: *9~*0: Program counter bits S9~S0: Stack register bits #9~#0: Instruction code bits @7~@0: PCL bits



Program Memory – ROM

The program memory is used to store the program instructions which are to be executed. It also contains data and table and is organized into 1024×14 bits, addressed by the program counter and table pointer.

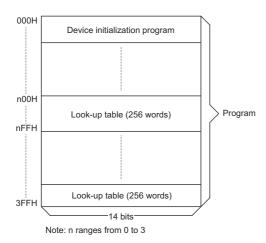
Certain locations in the program memory are reserved for special usage:

Location 000H

This area is reserved for the initialization program. After chip reset, the program always begins execution at location 000H.

Table location

Any location in the EPROM space can be used as look-up tables. The instructions "TABRDC [m]" (the current page, one page=256 words) and "TABRDL [m]" (the last page) transfer the contents of the lower-order byte to the specified data memory, and the higher-order byte to TBLH (08H). Only the destination of the lower-order byte in the table is well-defined, the other bits of the table word are transferred to the lower portion of TBLH, the remaining 2 bits are read as "0". The Table Higher-order byte register (TBLH) is read only. The table pointer (TBLP) is a read/write register (07H), where P indicates the table location. Before accessing the table, the location must be placed in TBLP. The TBLH is read only and cannot be restored. All table related instructions need 2 cycles to complete the operation. These areas may function as normal program memory depending upon the requirements.



Program Memory

Table Location Instruction(s) *8 *7 *6 *5 *4 *3 *2 *1 *0 P9 TABRDC [m] P8 @7 @6 @5 @4 @3 @2 @0 @1 TABRDL [m] 1 @7 @6 @5 @4 @3 @2 @1 @0

Table Location

Note: *9~*0: Table location bits

P9~P8: Current program counter bits

@7~@0: Table pointer bits

Stack Register - STACK

This is a special part of the memory used to save the contents of the Program Counter only. The stack is organized into one level and is neither part of the data nor part of the program space, and is neither readable nor writeable. The activated level is indexed by the stack pointer (SP) and is neither readable nor writeable. At a subroutine call the contents of the program counter are pushed onto the stack. At the end of a subroutine signaled by a return instruction (RET), the program counter is restored to its previous value from the stack. After a chip reset, the SP will point to the top of the stack.

If the stack is full and a "CALL" is subsequently executed, stack overflow occurs and the first entry will be lost (only the most recent return address is stored).

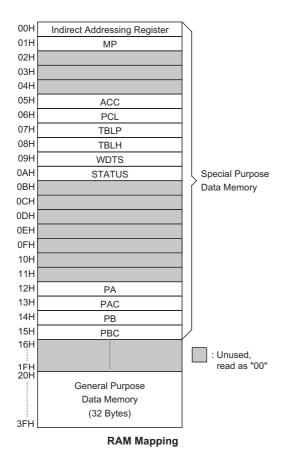
Data Memory - RAM

The data memory is designed with 44×8 bits. The data memory is divided into two functional groups: special function registers and general purpose data memory (32×8). Most of them are read/write, but some are read only.

The special function registers include the Indirect Addressing Register (00H), the Memory Pointer register (MP;01H), the Accumulator (ACC;05H) the Program Counter Lower-order byte register (PCL;06H), the Table Pointer (TBLP;07H), the table higher-order byte register (TBLH;08H), the Watchdog Timer option setting register (WDTS;09H), the STATUS register (STATUS;0AH), the I/O registers (PA;12H, PB;14H) and I/O control registers (PAC;13H, PBC;15H). The remaining space before the 20H is reserved for future expanded usage and reading these locations will return the result 00H. The general purpose data memory, addressed from 20H to 3FH, is used for data and control information under instruction command.

All data memory areas can handle arithmetic, logic, increment, decrement and rotate operations directly. Except for some dedicated bits, each bit in the data memory can be set and reset by the "SET [m].i" and "CLR [m].i" instructions, respectively. They are also indirectly accessible through memory pointer register (MP:01H).





Indirect Addressing Register

Location 00H is an indirect addressing register that is not physically implemented. Any read/write operation of [00H] accesses data memory pointed to by MP (01H). Reading location 00H itself indirectly will return the result 00H. Writing indirectly results in no operation.

The memory pointer register MP (01H) is a 7-bit register. The bit 7 of MP is undefined and reading will return the

result "1". Any writing operation to MP will only transfer the lower 7-bit data to MP.

Accumulator

The accumulator closely relates to ALU operations. It is also mapped to location 05H of the data memory and is capable of carrying out immediate data operations. Data movement between two data memory locations has to pass through the accumulator.

Arithmetic and Logic Unit - ALU

This circuit performs 8-bit arithmetic and logic operation. The ALU provides the following functions.

- Arithmetic operations (ADD, ADC, SUB, SBC, DAA)
- Logic operations (AND, OR, XOR, CPL)
- Rotation (RL, RR, RLC, RRC)
- Increment and Decrement (INC, DEC)
- Branch decision (SZ, SNZ, SIZ, SDZ)

The ALU not only saves the results of a data operation but also changes the contents of the status register.

Status Register - STATUS

This 8-bit status register (0AH) contains the zero flag (Z), carry flag (C), auxiliary carry flag (AC), overflow flag (OV), power down flag (PDF) and watchdog time-out flag (TO). It also records the status information and controls the operation sequence.

With the exception of the TO and PDF flags, bits in the status register can be altered by instructions like most other register. Any data written into the status register will not change the TO or PDF flags. In addition it should be noted that operations related to the status register may give different results from those intended. The TO and PDF flags can only be changed by the Watchdog Timer overflow, chip power-up, clearing the Watchdog Timer and executing the "HALT" instruction.

Bit No.	Label	Function
0	С	C is set if the operation results in a carry during an addition operation or if a borrow does not take place during a subtraction operation; otherwise C is cleared. C is also affected by a rotate through carry instruction.
1	AC	AC is set if the operation results in a carry out of the low nibbles in addition or no borrow from the high nibble into the low nibble in subtraction; otherwise AC is cleared.
2	Z	Z is set if the result of an arithmetic or logic operation is zero; otherwise Z is cleared.
3	OV	OV is set if the operation results in a carry into the highest-order bit but not a carry out of the highest-order bit, or vice versa; otherwise OV is cleared.
4	PDF	PDF is cleared when either a system power-up or executing the "CLR WDT" instruction. PDF is set by executing the "HALT" instruction.
5	то	TO is cleared by a system power-up or executing the "CLR WDT" or "HALT" instruction. TO is set by a WDT time-out.
6~7	_	Unused bit, read as "0"

Status (0AH) Register

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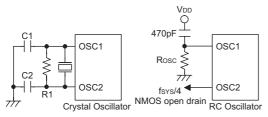


The Z, OV, AC and C flags generally reflect the status of the latest operations.

In addition, on executing the subroutine call, the status register will not be automatically pushed onto the stack. If the contents of the status are important and if the subroutine can corrupt the status register, precautions must be taken to save it properly.

Oscillator Configuration

There are two oscillator circuits implemented in the microcontroller.



System Oscillator

Both are designed for system clocks; the RC oscillator and the Crystal oscillator, which are determined by code options. No matter what oscillator type is selected, the signal provides the system clock. The HALT mode stops the system oscillator and ignores the external signal to conserve power.

If an RC oscillator is used, an external resistor between OSC1 and VSS in needed and the resistance must range from $24k\Omega$ to $1M\Omega.$ The system clock, divided by 4, is available on OSC2, which can be used to synchronize external logic. The RC oscillator provides the most cost effective solution. However, the frequency of the oscillation may vary with VDD, temperature and the chip itself due to process variations. It is, therefore, not suitable for timing sensitive operations where accurate oscillator frequency is desired.

If the Crystal oscillator is used, a crystal across OSC1 and OSC2 is needed to provide the feedback and phase shift for the oscillator. No other external components are needed. Instead of a crystal, the resonator can also be connected between OSC1 and OSC2 to get a frequency reference, but two external capacitors in OSC1 and OSC2 are required.

Watchdog Timer - WDT

The clock source of WDT is implemented by a dedicated RC oscillator (WDT oscillator) or instruction clock (sys-

tem clock divided by 4), decided by options. This timer is designed to prevent a software malfunction or sequence from jumping to an unknown location with unpredictable results. The Watchdog Timer can be disabled by an option. If the Watchdog Timer is disabled, all the executions related to the WDT result in no operation.

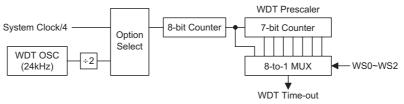
Once the internal WDT oscillator (RC oscillator with a period of 32µs at 5V normally) is selected, it is first divided by 512 (9-stage) to get the nominal time-out period of approximately 17ms at 5V. This time-out period may vary with temperatures, VDD and process variations. By invoking the WDT prescaler, longer time-out periods can be realized. Writing data to WS2, WS1, WS0 (bit 2,1,0 of the WDTS) can give different time-out periods. If WS2, WS1, and WS0 are all equal to 1, the division ratio is up to 1:128, and the maximum time-out period is 2.1s at 5V seconds. If the WDT oscillator is disabled, the WDT clock may still come from the instruction clock and operate in the same manner except that in the HALT state the WDT may stop counting and lose its protecting purpose. In this situation the logic can only be restarted by external logic. The high nibble and bit 3 of the WDTS are reserved for user's defined flags, which can be used to indicate some specified status.

If the device operates in a noisy environment, using the on-chip RC oscillator (WDT OSC) is strongly recommended, since the HALT will stop the system clock.

WS2	WS1	WS0	Division Ratio
0	0	0	1:1
0	0	1	1:2
0	1	0	1:4
0	1	1	1:8
1	0	0	1:16
1	0	1	1:32
1	1	0	1:64
1	1	1	1:128

WDTS (09H) Register

The WDT overflow under normal operation will initialize "chip reset" and set the status bit "TO". But in the HALT mode, the overflow will initialize a "warm reset", and only the Program Counter and SP are reset to zero. To clear the contents of WDT (including the WDT prescaler), three methods are adopted; external reset (a low level to RES), software instruction and a "HALT" in-



Watchdog Timer



struction. The software instruction include "CLR WDT" and the other set – "CLR WDT1" and "CLR WDT2". Of these two types of instruction, only one can be active depending on the option – "CLR WDT times selection option". If the "CLR WDT" is selected (i.e. CLRWDT times equal one), any execution of the "CLR WDT" instruction will clear the WDT. In the case that "CLR WDT1" and "CLR WDT2" are chosen (i.e. CLRWDT times equal two), these two instructions must be executed to clear the WDT; otherwise, the WDT may reset the chip as a result of time-out.

Power Down Operation - HALT

The HALT mode is initialized by the "HALT" instruction and results in the following...

- · The system oscillator turns off and the WDT stops.
- The contents of the on-chip RAM and registers remain unchanged.
- WDT prescaler are cleared.
- All I/O ports maintain their original status.
- The PDF flag is set and the TO flag is cleared.

The system can quit the HALT mode by means of an external reset or an external falling edge signal on port B. An external reset causes a device initialization. Examining the TO and PDF flags, the reason for chip reset can be determined. The PDF flag is cleared when the system powers up or execute the "CLR WDT" instruction and is set when the "HALT" instruction is executed. The TO flag is set if the WDT time-out occurs, and causes a wake-up that only resets the program counter and SP, the others keep their original status.

The Port A wake-up can be considered as a continuation of normal execution. Each bit in Port A can be independently selected to wake up the device by the code option. Awakening from an I/O port stimulus, the program will resume execution of the next instruction.

Once a wake-up event(s) occurs, it takes 1024 t_{SYS} (system clock period) to resume normal operation. In other words, a dummy cycle period will be inserted after the wake-up.

To minimize power consumption, all I/O pins should be carefully managed before entering the HALT status.

Reset

There are three ways in which a reset can occur:

- RES reset during normal operation
- RES reset during HALT
- WDT time-out reset during normal operation

Some registers remain unchanged during reset conditions. Most registers are reset to the "initial condition" when the reset conditions are met. By examining the PDF and TO flags, the program can distinguish between different "chip resets".

то	PDF	RESET Conditions
0	0	RES reset during power-up
u	u	RES reset during normal operation
0	1	RES wake-up HALT
1	u	WDT time-out during normal operation
1	1	WDT wake-up HALT

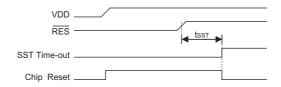
Note: "u" means unchanged.

To guarantee that the system oscillator has started and stabilized, the SST (System Start-up Timer) provides an extra-delay of 1024 system clock pulses when the system powers up or when the system awakes from a HALT state

When a system power up occurs, an SST delay is added during the reset period. But when the reset comes from the $\overline{\text{RES}}$ pin, the SST delay is disabled. Any wake-up from HALT will enable the SST delay.

The functional unit chip reset status is shown below.

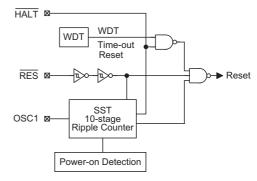
Program Counter	000H
WDT Prescaler	Clear
Input/Output ports	Input mode
Stack Pointer	Points to the top of the stack



Reset Timing Chart

VDD Q RES

Reset Circuit



Reset Configuration



The chip reset status	of the register	e je summarizad in	the following table:
The chib reset status	or the redister	s is summanzed in	the following table.

Register	Reset (Power-on)	WDT Time-out (Normal Operation)	RES Reset (Normal Operation)	RES Reset (HALT)	WDT Time-out (HALT)*
Program Counter	000H	000H	000H	000H	000H
MP	-xxx xxxx	-uuu uuuu	-uuu uuuu	-uuu uuuu	-uuu uuuu
ACC	XXXX XXXX	uuuu uuuu	uuuu uuuu	uuuu uuuu	uuuu uuuu
TBLP	XXXX XXXX	uuuu uuuu	uuuu uuuu	uuuu uuuu	uuuu uuuu
TBLH	xx xxxx	uu uuuu	uu uuuu	uu uuuu	uu uuuu
WDTS	0000 0111	0000 0111	0000 0111	0000 0111	uuuu uuuu
STATUS	00 xxxx	1u uuuu	uu uuuu	01 uuuu	11 uuuu
PA	1111 1111	1111 1111	1111 1111	1111 1111	uuuu uuuu
PAC	1111 1111	1111 1111	1111 1111	1111 1111	uuuu uuuu
РВ	111	111	111	111	uuu
PBC	111	111	111	111	uuu

Note: "*" means "warm reset"
"u" means "unchanged"

"x" means "unknown"

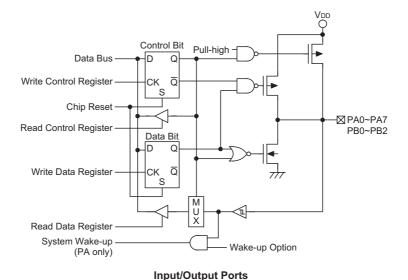
Input/Output Ports

There are up to 11 bidirectional input/output lines in the microcontroller labeled with port names PA and PB, which are mapped to the data memory of [12H] and [14H] respectively. All of these I/O ports can be used for input and output operations. For input operation, these ports are non-latching, that is, the inputs must be ready at the T2 rising edge of instruction "MOV A,[m]" (m=12H or 14H). For output operation, all the data is latched and remains unchanged until the output latch is rewritten.

Each I/O line has its own control register (PAC, PBC) to control the input/output configuration. With this control register, CMOS output or Schmitt trigger input with or

without pull-high resistor structures can be reconfigured dynamically (i.e. on-the-fly) under software control. To function as an input, the corresponding latch of the control register must write "1". The input source also depends on the control register. If the control register bit is "1", the input will read the pad state. If the control register bit is "0", the contents of the latches will move to the internal bus. The latter is possible in the "read-modify-write" instruction.

For output function, CMOS is the only configuration. These control registers are mapped to locations 13H and 15H.



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After a chip reset, these input/output lines remain at high levels or floating state (dependent on pull-high options). Each bit of these input/output latches can be set or cleared by "SET [m].i" and "CLR [m].i" (m=12H or 14H) instructions.

Some instructions first input data and then follow the output operations. For example, "SET [m].i", "CLR [m].i", "CPL [m]", "CPLA [m]" read the entire port states into the CPU, execute the defined operations (bit-operation), and then write the results back to the latches or the accumulator.

Each line of Port A has the capability of waking-up the device. The highest 5-bit of Port B are not physically implemented; on reading them a "0" is returned whereas writing then results in a no-operation. See Application note.

There are pull-high options available for PA and PB. Once the pull-high option is selected, I/O lines have pull-high resistors. Otherwise, the pull-high resistors are absent. It should be noted that a non-pull-high I/O line operating in input mode will cause a floating state.

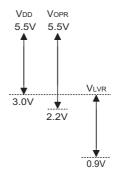
Low Voltage Reset - LVR

The microcontroller provides low voltage reset circuit in order to monitor the supply voltage of the device. If the supply voltage of the device is within the range $0.9V \sim V_{LVR}$, such as changing a battery, the LVR will automatically reset the device internally.

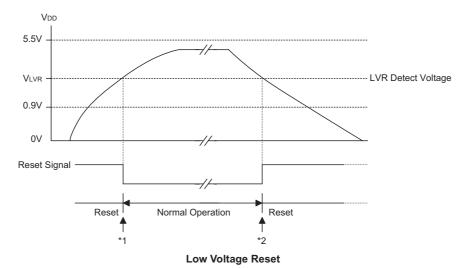
The LVR includes the following specifications:

- The low voltage (0.9V~V_{LVR}) has to remain in their original state to exceed 1ms. If the low voltage state does not exceed 1ms, the LVR will ignore it and do not perform a reset function.
- The LVR uses the "OR" function with the external RES signal to perform chip reset.

The relationship between V_{DD} and V_{LVR} is shown below.



Note: V_{OPR} is the voltage range for proper chip operation at 4MHz system clock.



Note: *1: To make sure that the system oscillator has stabilized, the SST provides an extra delay of 1024 system clock pulses before entering the normal operation.

*2: Since low voltage has to be maintained in its original state and exceed 1ms, therefore 1ms delay enters the reset mode.

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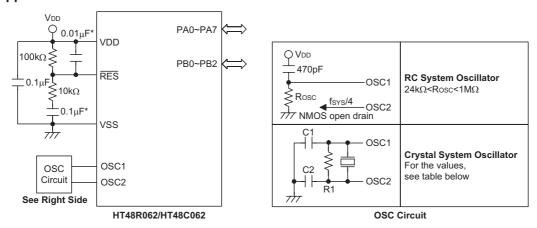


Options

The following table shows eight kinds of code option in the HT48R062/HT48C062. All the code options must be defined to ensure proper system functioning.

No.	Options			
1	WDT clock source: WDTOSC or f _{SYS} /4			
2	WDT function: enable or disable			
3	LVR function: enable or disable			
4	CLRWDT instruction(s): one or two clear WDT instruction(s)			
5	System oscillator: RC or crystal			
6	PA and PB pull-high resistors: none or pull-high			
7	PA0~PA7 wake-up: enable or disable			

Application Circuits



Note: The resistance and capacitance for reset circuit should be designed to ensure that the V_{DD} is stable and remains in a valid range of the operating voltage before bringing \overline{RES} high.

"*" Make the length of the wiring, which is connected to the $\overline{\text{RES}}$ pin as short as possible, to avoid noise interference

The following table shows the C1, C2 and R1 values corresponding to the different crystal values. (For reference only)

Crystal or Resonator	C1, C2	R1
4MHz Crystal	25pF	10kΩ
4MHz Resonator	10pF	12kΩ
3.58MHz Crystal	25pF	10kΩ
3.58MHz Resonator	25pF	10kΩ
2MHz Crystal	30pF	12kΩ
2MHz Resonator	25pF	12kΩ
1MHz Crystal	100pF	10kΩ
480kHz Resonator	300pF	9.1kΩ
455kHz Resonator	300pF	10kΩ
429kHz Resonator	300pF	10kΩ
400kHz Resonator	300pF	10kΩ

The function of the resistor R1 is to ensure that the oscillator will switch off should low voltage conditions occur. Such a low voltage, as mentioned here, is one which is less than the lowest value of the MCU operating voltage. Note however that if the LVR is enabled then R1 can be removed.



Instruction Set Summary

Mnemonic	Description	Instruction Cycle	Flag Affected
Arithmetic			
ADD A,[m] ADDM A,[m] ADD A,x ADC A,[m] ADCM A,[m] SUB A,x SUB A,[m] SUBM A,[m] SBC A,[m] SBCM A,[m] DAA [m]	Add data memory to ACC Add ACC to data memory Add immediate data to ACC Add data memory to ACC with carry Add ACC to data memory with carry Subtract immediate data from ACC Subtract data memory from ACC Subtract data memory from ACC with result in data memory Subtract data memory from ACC with carry Subtract data memory from ACC with carry Subtract data memory from ACC with carry and result in data memory Decimal adjust ACC for addition with result in data memory	1 1(1) 1 1 1(1) 1 1 1(1) 1 1(1) 1(1)	Z,C,AC,OV Z,C,AC,OV Z,C,AC,OV Z,C,AC,OV Z,C,AC,OV Z,C,AC,OV Z,C,AC,OV Z,C,AC,OV Z,C,AC,OV Z,C,AC,OV C,C,AC,OV
Logic Operation	,		
AND A,[m] OR A,[m] XOR A,[m] ANDM A,[m] ORM A,[m] XORM A,[m] AND A,x OR A,x CPL [m] CPLA [m]	AND data memory to ACC OR data memory to ACC Exclusive-OR data memory to ACC AND ACC to data memory OR ACC to data memory Exclusive-OR ACC to data memory AND immediate data to ACC OR immediate data to ACC Exclusive-OR immediate data to ACC Complement data memory Complement data memory with result in ACC	1 1 1 1(1) 1(1) 1(1) 1 1 1 1(1) 1	Z Z Z Z Z Z Z Z Z Z
Increment & D			
INCA [m] INC [m] DECA [m] DEC [m]	Increment data memory with result in ACC Increment data memory Decrement data memory with result in ACC Decrement data memory	1 1 ⁽¹⁾ 1 1 ⁽¹⁾	Z Z Z Z
Rotate			
RRA [m] RR [m] RRCA [m] RRC [m] RLA [m] RL [m] RLCA [m] RLCA [m]	Rotate data memory right with result in ACC Rotate data memory right Rotate data memory right through carry with result in ACC Rotate data memory right through carry Rotate data memory left with result in ACC Rotate data memory left Rotate data memory left through carry with result in ACC Rotate data memory left through carry	1 1(1) 1 1(1) 1 1(1) 1 1(1)	None None C C None None C
Data Move			
MOV A,[m] MOV [m],A MOV A,x	Move data memory to ACC Move ACC to data memory Move immediate data to ACC	1 1 ⁽¹⁾ 1	None None None
Bit Operation			
CLR [m].i SET [m].i	Clear bit of data memory Set bit of data memory	1 ⁽¹⁾ 1 ⁽¹⁾	None None



Mnemonic	Description	Instruction Cycle	Flag Affected
Branch			
JMP addr	Jump unconditionally	2	None
SZ [m]	Skip if data memory is zero	1 ⁽²⁾	None
SZA [m]	Skip if data memory is zero with data movement to ACC	1 ⁽²⁾	None
SZ [m].i	Skip if bit i of data memory is zero	1 ⁽²⁾	None
SNZ [m].i	Skip if bit i of data memory is not zero	1 ⁽²⁾	None
SIZ [m]	Skip if increment data memory is zero	1 ⁽³⁾	None
SDZ [m]	Skip if decrement data memory is zero	1 ⁽³⁾	None
SIZA [m]	Skip if increment data memory is zero with result in ACC	1 ⁽²⁾	None
SDZA [m]	Skip if decrement data memory is zero with result in ACC	1 ⁽²⁾	None
CALL addr	Subroutine call	2	None
RET	Return from subroutine	2	None
RET A,x	Return from subroutine and load immediate data to ACC	2	None
RETI	Return from interrupt	2	None
Table Read			
TABRDC [m]	Read ROM code (current page) to data memory and TBLH	2 ⁽¹⁾	None
TABRDL [m]	Read ROM code (last page) to data memory and TBLH	2 ⁽¹⁾	None
Miscellaneous	3		
NOP	No operation	1	None
CLR [m]	Clear data memory	1 ⁽¹⁾	None
SET [m]	Set data memory	1 ⁽¹⁾	None
CLR WDT	Clear Watchdog Timer	1	TO,PDF
CLR WDT1	Pre-clear Watchdog Timer	1	TO ⁽⁴⁾ ,PDF ⁽⁴⁾
CLR WDT2	Pre-clear Watchdog Timer	1	TO ⁽⁴⁾ ,PDF ⁽⁴⁾
SWAP [m]	Swap nibbles of data memory	1 ⁽¹⁾	None
SWAPA [m]	Swap nibbles of data memory with result in ACC	1	None
HALT	Enter Power Down Mode	1	TO,PDF

Note: x: Immediate data

m: Data memory address

A: Accumulator

i: 0~7 number of bits

addr: Program memory address

- $\sqrt{:}$ Flag is affected
- -: Flag is not affected
- ⁽¹⁾: If a loading to the PCL register occurs, the execution cycle of instructions will be delayed for one more cycle (four system clocks).
- (2): If a skipping to the next instruction occurs, the execution cycle of instructions will be delayed for one more cycle (four system clocks). Otherwise the original instruction cycle is unchanged.
- (3): (1) and (2)
- (4): The flags may be affected by the execution status. If the Watchdog Timer is cleared by executing the "CLR WDT1" or "CLR WDT2" instruction, the TO and PDF are cleared. Otherwise the TO and PDF flags remain unchanged.

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Instruction Definition

ADC A,[m] Add data memory and carry to the accumulator

Description The contents of the specified data memory, accumulator and the carry flag are added si-

multaneously, leaving the result in the accumulator.

Operation $ACC \leftarrow ACC+[m]+C$

Affected flag(s)

TO	PDF	OV	Z	AC	С
		√	√	√	√

ADCM A,[m] Add the accumulator and carry to data memory

Description The contents of the specified data memory, accumulator and the carry flag are added si-

multaneously, leaving the result in the specified data memory.

Operation $[m] \leftarrow ACC+[m]+C$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_		√	√	√	√

ADD A,[m] Add data memory to the accumulator

Description The contents of the specified data memory and the accumulator are added. The result is

stored in the accumulator.

Operation $ACC \leftarrow ACC+[m]$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_	√	√	√	√

ADD A,x Add immediate data to the accumulator

Description The contents of the accumulator and the specified data are added, leaving the result in the

accumulator.

Operation $ACC \leftarrow ACC+x$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_	√	√	√	√

ADDM A,[m] Add the accumulator to the data memory

Description The contents of the specified data memory and the accumulator are added. The result is

stored in the data memory.

Operation $[m] \leftarrow ACC+[m]$

ТО	PDF	OV	Z	AC	С
_	_	√	√	√	√





AND A,[m] Logical AND accumulator with data memory

Description Data in the accumulator and the specified data memory perform a bitwise logical_AND op-

eration. The result is stored in the accumulator.

Operation $ACC \leftarrow ACC \ "AND" \ [m]$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	_	√	_	_

AND A,x Logical AND immediate data to the accumulator

Description Data in the accumulator and the specified data perform a bitwise logical_AND operation.

The result is stored in the accumulator.

Operation $ACC \leftarrow ACC "AND" x$

Affected flag(s)

TO	PDF	OV	Z	AC	С
_	_		√	_	_

ANDM A,[m] Logical AND data memory with the accumulator

Description Data in the specified data memory and the accumulator perform a bitwise logical_AND op-

eration. The result is stored in the data memory.

Operation $[m] \leftarrow ACC "AND" [m]$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_			√	_	_

CALL addr Subroutine call

Description The instruction unconditionally calls a subroutine located at the indicated address. The

program counter increments once to obtain the address of the next instruction, and pushes this onto the stack. The indicated address is then loaded. Program execution continues

with the instruction at this address.

Operation Stack ← Program Counter+1

 $Program\ Counter \leftarrow addr$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	_	_	_	_

CLR [m] Clear data memory

Description The contents of the specified data memory are cleared to 0.

Operation $[m] \leftarrow 00H$

ТО	PDF	OV	Z	AC	С
_	_	_	_	_	_



CLR [m].i Clear bit of data memory

Description The bit i of the specified data memory is cleared to 0.

Operation $[m].i \leftarrow 0$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_		_	_	_	_

CLR WDT Clear Watchdog Timer

Description The WDT is cleared (clears the WDT). The power down bit (PDF) and time-out bit (TO) are

cleared.

Operation $WDT \leftarrow 00H$

PDF and TO \leftarrow 0

Affected flag(s)

ТО	PDF	OV	Z	AC	С
0	0	_	_		_

CLR WDT1 Preclear Watchdog Timer

Description Together with CLR WDT2, clears the WDT. PDF and TO are also cleared. Only execution

of this instruction without the other preclear instruction just sets the indicated flag which implies this instruction has been executed and the TO and PDF flags remain unchanged.

Operation WDT \leftarrow 00H*

PDF and TO \leftarrow 0*

Affected flag(s)

TO	PDF	OV	Z	AC	С
0*	0*		_		_

CLR WDT2 Preclear Watchdog Timer

Description Together with CLR WDT1, clears the WDT. PDF and TO are also cleared. Only execution

of this instruction without the other preclear instruction, sets the indicated flag which implies this instruction has been executed and the TO and PDF flags remain unchanged.

Operation WDT \leftarrow 00H*

PDF and TO ← 0*

Affected flag(s)

ТО	PDF	OV	Z	AC	С
0*	0*		_		_

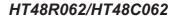
CPL [m] Complement data memory

Description Each bit of the specified data memory is logically complemented (1's complement). Bits

which previously contained a 1 are changed to 0 and vice-versa.

Operation $[m] \leftarrow \overline{[m]}$

TO	PDF	OV	Z	AC	С
_	_	_	√	_	_





CPLA [m] Complement data memory and place result in the accumulator

Description Each bit of the specified data memory is logically complemented (1's complement). Bits

which previously contained a 1 are changed to 0 and vice-versa. The complemented result is stored in the accumulator and the contents of the data memory remain unchanged.

Operation $ACC \leftarrow [\overline{m}]$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_		√		_

DAA [m] Decimal-Adjust accumulator for addition

Description The accumulator value is adjusted to the BCD (Binary Coded Decimal) code. The accumulator value is adjusted to the BCD (Binary Coded Decimal) code.

lator is divided into two nibbles. Each nibble is adjusted to the BCD code and an internal carry (AC1) will be done if the low nibble of the accumulator is greater than 9. The BCD adjustment is done by adding 6 to the original value if the original value is greater than 9 or a carry (AC or C) is set; otherwise the original value remains unchanged. The result is stored

in the data memory and only the carry flag (C) may be affected.

Operation If ACC.3~ACC.0 >9 or AC=1

then [m].3~[m].0 \leftarrow (ACC.3~ACC.0)+6, AC1= \overline{AC} else [m].3~[m].0 \leftarrow (ACC.3~ACC.0), AC1=0

and

If ACC.7~ACC.4+AC1 >9 or C=1

then [m].7~[m].4 \leftarrow ACC.7~ACC.4+6+AC1,C=1 else [m].7~[m].4 \leftarrow ACC.7~ACC.4+AC1,C=C

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	_	_	_	√

DEC [m] Decrement data memory

Description Data in the specified data memory is decremented by 1.

Operation $[m] \leftarrow [m]-1$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_		√	_	_

DECA [m] Decrement data memory and place result in the accumulator

Description Data in the specified data memory is decremented by 1, leaving the result in the accumula-

tor. The contents of the data memory remain unchanged.

Operation $ACC \leftarrow [m]{-}1$

ТО	PDF	OV	Z	AC	С
		_	√	_	_





HALT Enter Power Down Mode

Description This instruction stops program execution and turns off the system clock. The contents of

the RAM and registers are retained. The WDT and prescaler are cleared. The power down

bit (PDF) is set and the WDT time-out bit (TO) is cleared.

Operation Program Counter ← Program Counter+1

 $PDF \leftarrow 1$ $TO \leftarrow 0$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
0	1	_	_	_	_

INC [m] Increment data memory

Description Data in the specified data memory is incremented by 1

Operation $[m] \leftarrow [m]+1$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_		_	√	_	_

INCA [m] Increment data memory and place result in the accumulator

Description Data in the specified data memory is incremented by 1, leaving the result in the accumula-

tor. The contents of the data memory remain unchanged.

Operation $ACC \leftarrow [m]+1$

Affected flag(s)

TO	PDF	OV	Z	AC	С
	_	_	√	_	_

JMP addr Directly jump

Description The program counter are replaced with the directly-specified address unconditionally, and

control is passed to this destination.

Operation Program Counter ←addr

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	_	_	_	_

MOV A,[m] Move data memory to the accumulator

Description The contents of the specified data memory are copied to the accumulator.

Operation $ACC \leftarrow [m]$

ТО	PDF	OV	Z	AC	С
_	_	_	_	_	_



MOV A,x Move immediate data to the accumulator

Description The 8-bit data specified by the code is loaded into the accumulator.

Operation $ACC \leftarrow x$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_			_	_	_

MOV [m],A Move the accumulator to data memory

Description The contents of the accumulator are copied to the specified data memory (one of the data

memories).

Operation $[m] \leftarrow ACC$

Affected flag(s)

TO	PDF	OV	Z	AC	С
_	_	_	_	_	_

NOP No operation

Description No operation is performed. Execution continues with the next instruction.

Operation Program Counter ← Program Counter+1

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	_	_	_	_

OR A,[m] Logical OR accumulator with data memory

Description Data in the accumulator and the specified data memory (one of the data memories) per-

form a bitwise $logical_OR$ operation. The result is stored in the accumulator.

Operation $ACC \leftarrow ACC "OR" [m]$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	_	√	_	_

OR A,x Logical OR immediate data to the accumulator

Description Data in the accumulator and the specified data perform a bitwise logical_OR operation.

The result is stored in the accumulator.

Operation $ACC \leftarrow ACC "OR" x$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	_	√	_	_

ORM A,[m] Logical OR data memory with the accumulator

Description Data in the data memory (one of the data memories) and the accumulator perform a

bitwise logical_OR operation. The result is stored in the data memory.

Operation $[m] \leftarrow ACC "OR" [m]$

TO	PDF	OV	Z	AC	С
_	_	_	√		_



RET Return from subroutine

Description The program counter is restored from the stack. This is a 2-cycle instruction.

Operation Program Counter ← Stack

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_		_	_	_

RET A,x Return and place immediate data in the accumulator

Description The program counter is restored from the stack and the accumulator loaded with the speci-

fied 8-bit immediate data.

Operation Program Counter ← Stack

 $\mathsf{ACC} \leftarrow \mathsf{x}$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_	_	_		_

RETI Return from interrupt

Description The program counter is restored from the stack, and interrupts are enabled by setting the

EMI bit. EMI is the enable master (global) interrupt bit.

Operation Program Counter ← Stack

 $EMI \leftarrow 1$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_	_	_	_	_

RL [m] Rotate data memory left

Description The contents of the specified data memory are rotated 1 bit left with bit 7 rotated into bit 0.

 $\label{eq:continuous} \mbox{Operation} \qquad [m].(i+1) \leftarrow [m].i; [m].i: \mbox{bit } i \mbox{ of the data memory } (i=0 \mbox{\sim} 6)$

 $[m].0 \leftarrow [m].7$

Affected flag(s)

TO	PDF	OV	Z	AC	С
_	_			_	_

RLA [m] Rotate data memory left and place result in the accumulator

Description Data in the specified data memory is rotated 1 bit left with bit 7 rotated into bit 0, leaving the

rotated result in the accumulator. The contents of the data memory remain unchanged.

Operation ACC.(i+1) \leftarrow [m].i; [m].i:bit i of the data memory (i=0~6)

 $ACC.0 \leftarrow [m].7$

TO	PDF	OV	Z	AC	С
_	_	_	_	_	_



RLC [m] Rotate data memory left through carry

Description The contents of the specified data memory and the carry flag are rotated 1 bit left. Bit 7 re-

places the carry bit; the original carry flag is rotated into the bit 0 position.

Operation [m].(i+1) \leftarrow [m].i; [m].i:bit i of the data memory (i=0~6)

 $[m].0 \leftarrow C$ $C \leftarrow [m].7$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	_	_	_	√

RLCA [m] Rotate left through carry and place result in the accumulator

Description Data in the specified data memory and the carry flag are rotated 1 bit left. Bit 7 replaces the

carry bit and the original carry flag is rotated into bit 0 position. The rotated result is stored

in the accumulator but the contents of the data memory remain unchanged.

Operation $ACC.(i+1) \leftarrow [m].i; [m].i: bit \ i \ of \ the \ data \ memory \ (i=0~6)$

 $\begin{array}{c} \mathsf{ACC.0} \leftarrow \mathsf{C} \\ \mathsf{C} \leftarrow [\mathsf{m}].7 \end{array}$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_		_	_	_	√

RR [m] Rotate data memory right

Description The contents of the specified data memory are rotated 1 bit right with bit 0 rotated to bit 7.

Operation [m].i \leftarrow [m].(i+1); [m].i:bit i of the data memory (i=0~6)

 $[m].7 \leftarrow [m].0$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_	_	_	_	_

RRA [m] Rotate right and place result in the accumulator

Description Data in the specified data memory is rotated 1 bit right with bit 0 rotated into bit 7, leaving

the rotated result in the accumulator. The contents of the data memory remain unchanged.

Operation ACC.(i) \leftarrow [m].(i+1); [m].i:bit i of the data memory (i=0~6)

 $ACC.7 \leftarrow [m].0$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_		_	_	_

RRC [m] Rotate data memory right through carry

Description The contents of the specified data memory and the carry flag are together rotated 1 bit

right. Bit 0 replaces the carry bit; the original carry flag is rotated into the bit 7 position.

Operation [m].i \leftarrow [m].(i+1); [m].i:bit i of the data memory (i=0~6)

 $[m].7 \leftarrow C \\ C \leftarrow [m].0$

TO	PDF	OV	Z	AC	С
			_	_	√



RRCA [m] Rotate right through carry and place result in the accumulator

Description Data of the specified data memory and the carry flag are rotated 1 bit right. Bit 0 replaces

the carry bit and the original carry flag is rotated into the bit 7 position. The rotated result is

stored in the accumulator. The contents of the data memory remain unchanged.

Operation ACC.i \leftarrow [m].(i+1); [m].i:bit i of the data memory (i=0~6)

 $\begin{array}{c} ACC.7 \leftarrow C \\ C \leftarrow [m].0 \end{array}$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_		_	_		√

SBC A,[m] Subtract data memory and carry from the accumulator

Description The contents of the specified data memory and the complement of the carry flag are sub-

tracted from the accumulator, leaving the result in the accumulator.

Operation $ACC \leftarrow ACC+[m]+C$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	√	√	√	√

SBCM A,[m] Subtract data memory and carry from the accumulator

Description The contents of the specified data memory and the complement of the carry flag are sub-

tracted from the accumulator, leaving the result in the data memory.

Operation $[m] \leftarrow ACC + \overline{[m]} + C$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_	√	√	√	√

SDZ [m] Skip if decrement data memory is 0

Description The contents of the specified data memory are decremented by 1. If the result is 0, the next

instruction is skipped. If the result is 0, the following instruction, fetched during the current instruction execution, is discarded and a dummy cycle is replaced to get the proper instruc-

tion (2 cycles). Otherwise proceed with the next instruction (1 cycle).

 $\label{eq:Skip if ([m]-1)=0, [m] lemma of matter of the content of the content$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_	_	_	_	_

SDZA [m] Decrement data memory and place result in ACC, skip if 0

Description The contents of the specified data memory are decremented by 1. If the result is 0, the next

instruction is skipped. The result is stored in the accumulator but the data memory remains unchanged. If the result is 0, the following instruction, fetched during the current instruction execution, is discarded and a dummy cycle is replaced to get the proper instruction (2 cy-

cles). Otherwise proceed with the next instruction (1 cycle).

Operation Skip if ([m]-1)=0, ACC \leftarrow ([m]-1)

ТО	PDF	OV	Z	AC	С
_	_	_	_	_	_



SET [m] Set data memory

Description Each bit of the specified data memory is set to 1.

Operation $[m] \leftarrow FFH$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_		_	_	_

SET [m]. i Set bit of data memory

Description Bit i of the specified data memory is set to 1.

Operation [m].i \leftarrow 1

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_			_	_	_

SIZ [m] Skip if increment data memory is 0

Description The contents of the specified data memory are incremented by 1. If the result is 0, the fol-

lowing instruction, fetched during the current instruction execution, is discarded and a dummy cycle is replaced to get the proper instruction (2 cycles). Otherwise proceed with

the next instruction (1 cycle).

Operation Skip if ([m]+1)=0, $[m] \leftarrow ([m]+1)$

Affected flag(s)

TO	PDF	OV	Z	AC	С
_			_	_	_

SIZA [m] Increment data memory and place result in ACC, skip if 0

Description The contents of the specified data memory are incremented by 1. If the result is 0, the next

instruction is skipped and the result is stored in the accumulator. The data memory remains unchanged. If the result is 0, the following instruction, fetched during the current instruction execution, is discarded and a dummy cycle is replaced to get the proper

instruction (2 cycles). Otherwise proceed with the next instruction (1 cycle).

Operation Skip if ([m]+1)=0, ACC $\leftarrow ([m]+1)$

Affected flag(s)

TO	PDF	OV	Z	AC	С
_	_	_	_	_	_

SNZ [m].i Skip if bit i of the data memory is not 0

Description If bit i of the specified data memory is not 0, the next instruction is skipped. If bit i of the data

memory is not 0, the following instruction, fetched during the current instruction execution, is discarded and a dummy cycle is replaced to get the proper instruction (2 cycles). Other-

wise proceed with the next instruction (1 cycle).

Operation Skip if [m].i≠0

TO	PDF	OV	Z	AC	С
_	_	_	_	_	_





SUB A,[m] Subtract data memory from the accumulator

Description The specified data memory is subtracted from the contents of the accumulator, leaving the

result in the accumulator.

Operation $ACC \leftarrow ACC+[m]+1$

Affected flag(s)

TO	PDF	OV	Z	AC	С
_	_	√	√	√	√

SUBM A,[m] Subtract data memory from the accumulator

Description The specified data memory is subtracted from the contents of the accumulator, leaving the

result in the data memory.

Operation $[m] \leftarrow ACC + [\overline{m}] + 1$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_		$\sqrt{}$	√	√	√

SUB A,x Subtract immediate data from the accumulator

Description The immediate data specified by the code is subtracted from the contents of the accumula-

tor, leaving the result in the accumulator.

Operation $ACC \leftarrow ACC + x + 1$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_	√	√	√	√

SWAP [m] Swap nibbles within the data memory

Description The low-order and high-order nibbles of the specified data memory (1 of the data memo-

ries) are interchanged.

Operation $[m].3\sim[m].0 \leftrightarrow [m].7\sim[m].4$

Affected flag(s)

TO	PDF	OV	Z	AC	С
_	_	_	_	_	_

SWAPA [m] Swap data memory and place result in the accumulator

Description The low-order and high-order nibbles of the specified data memory are interchanged, writ-

ing the result to the accumulator. The contents of the data memory remain unchanged.

Operation $ACC.3 \text{-}ACC.0 \leftarrow [m].7 \text{-}[m].4$

 $ACC.7 \sim ACC.4 \leftarrow [m].3 \sim [m].0$

ТО	PDF	OV	Z	AC	С
_	_		_	_	_



SZ [m] Skip if data memory is 0

Description If the contents of the specified data memory are 0, the following instruction, fetched during

the current instruction execution, is discarded and a dummy cycle is replaced to get the

proper instruction (2 cycles). Otherwise proceed with the next instruction (1 cycle).

Operation Skip if [m]=0

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_	_		_	_	_

SZA [m] Move data memory to ACC, skip if 0

Description The contents of the specified data memory are copied to the accumulator. If the contents is

0, the following instruction, fetched during the current instruction execution, is discarded and a dummy cycle is replaced to get the proper instruction (2 cycles). Otherwise proceed

with the next instruction (1 cycle).

Operation Skip if [m]=0

Affected flag(s)

ТО	PDF	OV	Z	AC	С
	_	_	_	_	_

SZ [m].i Skip if bit i of the data memory is 0

Description If bit i of the specified data memory is 0, the following instruction, fetched during the current

instruction execution, is discarded and a dummy cycle is replaced to get the proper instruc-

tion (2 cycles). Otherwise proceed with the next instruction (1 cycle).

Operation Skip if [m].i=0

Affected flag(s)

TO	PDF	OV	Z	AC	С
_	_	_	_	_	_

TABRDC [m] Move the ROM code (current page) to TBLH and data memory

Description The low byte of ROM code (current page) addressed by the table pointer (TBLP) is moved

to the specified data memory and the high byte transferred to TBLH directly.

Operation $[m] \leftarrow ROM \text{ code (low byte)}$

TBLH ← ROM code (high byte)

Affected flag(s)

TO	PDF	OV	Z	AC	С
_	_	_	_	_	_

TABRDL [m] Move the ROM code (last page) to TBLH and data memory

Description The low byte of ROM code (last page) addressed by the table pointer (TBLP) is moved to

the data memory and the high byte transferred to TBLH directly.

Operation $[m] \leftarrow ROM \text{ code (low byte)}$

TBLH ← ROM code (high byte)

ТО	PDF	OV	Z	AC	С
_	_		_		_



XOR A,[m] Logical XOR accumulator with data memory

Description Data in the accumulator and the indicated data memory perform a bitwise logical Exclu-

sive_OR operation and the result is stored in the accumulator.

Operation $ACC \leftarrow ACC \text{ "XOR" [m]}$

Affected flag(s)

TO	PDF	OV	Z	AC	С
	_	_	√	_	_

XORM A,[m] Logical XOR data memory with the accumulator

Description Data in the indicated data memory and the accumulator perform a bitwise logical Exclu-

sive_OR operation. The result is stored in the data memory. The 0 flag is affected.

Operation $[m] \leftarrow ACC "XOR" [m]$

Affected flag(s)

ТО	PDF	OV	Z	AC	С
_		_	√	_	_

XOR A,x Logical XOR immediate data to the accumulator

Description Data in the accumulator and the specified data perform a bitwise logical Exclusive_OR op-

eration. The result is stored in the accumulator. The 0 flag is affected.

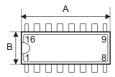
Operation $ACC \leftarrow ACC "XOR" x$

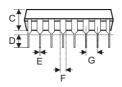
ТО	PDF	OV	Z	AC	С
	_		√	_	_



Package Information

16-pin DIP (300mil) Outline Dimensions



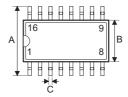


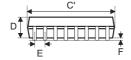


Complete all	Dimensions in mil				
Symbol	Min.	Nom.	Max.		
А	745	_	775		
В	240	_	260		
С	125	_	135		
D	125	_	145		
E	16	_	20		
F	50	_	70		
G	_	100	_		
Н	295	_	315		
I	335	_	375		
α	0°	_	15°		



16-pin NSOP (150mil) Outline Dimensions





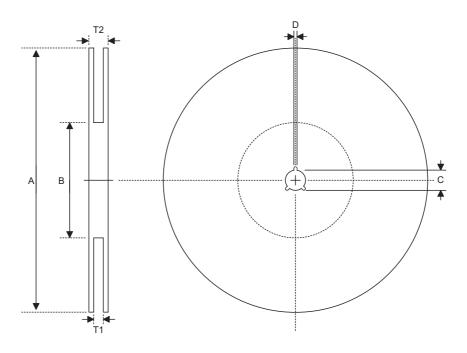


Comphal	Dimensions in mil				
Symbol	Min.	Nom.	Max.		
Α	228		244		
В	149	_	157		
С	14	_	20		
C'	386	_	394		
D	53	_	69		
E	_	50	_		
F	4	_	10		
G	22	_	28		
Н	4	_	12		
α	0°	_	10°		



Product Tape and Reel Specifications

Reel Dimensions

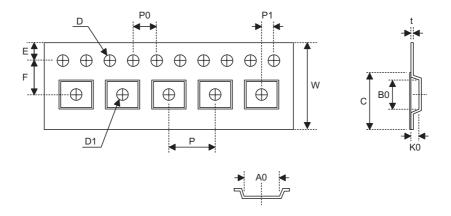


SOP 16N (150mil)

Symbol	Description	Dimensions in mm
Α	Reel Outer Diameter	330±1
В	Reel Inner Diameter	62±1.5
С	Spindle Hole Diameter	13+0.5 -0.2
D	Key Slit Width	2±0.5
T1	Space Between Flange	16.8+0.3 -0.2
T2	Reel Thickness	22.2±0.2



Carrier Tape Dimensions



SOP 16N (150mil)

Symbol	Description	Dimensions in mm
W	Carrier Tape Width	16±0.3
Р	Cavity Pitch	8±0.1
E	Perforation Position	1.75±0.1
F	Cavity to Perforation (Width Direction)	7.5±0.1
D	Perforation Diameter	1.55+0.1
D1	Cavity Hole Diameter	1.5+0.25
P0	Perforation Pitch	4±0.1
P1	Cavity to Perforation (Length Direction)	2±0.1
A0	Cavity Length	6.5±0.1
В0	Cavity Width	10.3±0.1
K0	Cavity Depth	2.1±0.1
t	Carrier Tape Thickness	0.3±0.05
С	Cover Tape Width	13.3



Holtek Semiconductor Inc. (Headquarters)

No.3, Creation Rd. II, Science Park, Hsinchu, Taiwan Tel: 886-3-563-1999

Fax: 886-3-563-1189 http://www.holtek.com.tw

Holtek Semiconductor Inc. (Taipei Sales Office) 4F-2, No. 3-2, YuanQu St., Nankang Software Park, Taipei 115, Taiwan

Tel: 886-2-2655-7070 Fax: 886-2-2655-7373

Fax: 886-2-2655-7383 (International sales hotline)

Holtek Semiconductor Inc. (Shanghai Sales Office)

7th Floor, Building 2, No.889, Yi Shan Rd., Shanghai, China 200233 Tel: 021-6485-5560 Fax: 021-6485-0313 http://www.holtek.com.cn

Holtek Semiconductor Inc. (Shenzhen Sales Office)

5/F, Unit A, Productivity Building, Cross of Science M 3rd Road and Gaoxin M 2nd Road, Science Park, Nanshan District, Shenzhen, China 518057

Tel: 0755-8616-9908, 8616-9308

Fax: 0755-8616-9533

Holtek Semiconductor Inc. (Beijing Sales Office)

Suite 1721, Jinyu Tower, A129 West Xuan Wu Men Street, Xicheng District, Beijing, China 100031 Tel: 010-6641-0030, 6641-7751, 6641-7752

Fax: 010-6641-0125

Holtek Semiconductor Inc. (Chengdu Sales Office)

709, Building 3, Champagne Plaza, No.97 Dongda Street, Chengdu, Sichuan, China 610016

Tel: 028-6653-6590 Fax: 028-6653-6591

Holmate Semiconductor, Inc. (North America Sales Office)

46729 Fremont Blvd., Fremont, CA 94538

Tel: 510-252-9880 Fax: 510-252-9885 http://www.holmate.com

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