

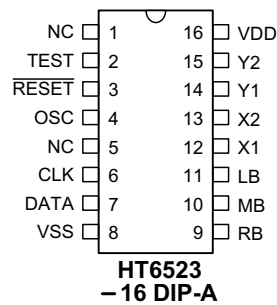
Features

- Compatible with IBM PS/2 mouse
- Integrated oscillator circuit with external resistor
- 6MHz clock frequency
- Minimal external components
- Three key-switches and four photo-coupler inputs
- Supports test mode operation
- 16-pin DIP package

General Description

The HT6523 is a PS/2 compatible mouse controller IC. Capable of driving up to 3 key-switches and 4 photo-couplers directly into a 6-pin connector line.

Pin Assignment



Pin Description

Pin No.	Pin Name	I/O	Description
1, 5	NC	—	No connection
2	TEST	I	If TEST is floating or connected to VSS, then the chip is under normal operation. If TEST is connected to VDD, it will operate under the TEST mode.
3	RESET	I	Input to reset internal LSI
4	OSC	I	OSC is connected to an external resistor then to VDD to generate a 6MHz system clock.
6	CLK	I/O	Synchronous clock signal. The mouse generates a clock signal when sending data to and receiving data from the system.
7	DATA	I/O	Bidirectional data transmission line
8	VSS	—	Negative power supply, ground
9 10 11	RB MB LB	I	In the non-active state these 3 switch inputs are pulled low. To activate they must be connected to VDD. In the TEST mode, MB, LB will indicate the condition of the X1, X2 inputs, if RB is left floating or connected to VSS. Also in the TEST mode, if RB is connected to VDD then MB and LB will indicate the condition of the Y1 and Y2 inputs.
12 13 14 15	X1 X2 Y1 Y2	I	Mouse interface input terminal. Four photo-coupler signals denote UP, DOWN, LEFT and RIGHT state.
16	VDD	—	Positive power supply

Absolute Maximum Ratings

Supply Voltage	$V_{SS}-0.3V$ to $V_{SS}+5.5V$	Storage Temperature	$-50^{\circ}C$ to $125^{\circ}C$
Input Voltage.....	$V_{SS}-0.3$ to $V_{DD}+0.3V$	Operating Temperature.....	$-25^{\circ}C$ to $70^{\circ}C$

Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.

D.C. Characteristics

Symbol	Parameter	Test Conditions		Min.	Typ.	Max.	Unit
		V_{DD}	Conditions				
V_{DD}	Operating Voltage	—	—	4.75	—	5.25	V
I_{DD}	Operating Current	5V	$f_{SYS}=6MHz$, No load	—	—	5	mA
V_{IL}	Input Low Voltage for I/O Ports	3V	—	0	—	0.9	V
		5V		0	—	1.5	
V_{IH}	Input High Voltage for I/O Ports	3V	—	2.1	—	3	V
		5V		3.5	—	5	
V_{IL1}	Input Low Voltage (\overline{RESET})	3V	—	0	—	0.7	V
		5V		0	—	1.3	
V_{IH1}	Input High Voltage (\overline{RESET})	3V	—	2.3	—	3	V
		5V		3.8	—	5	
V_{IL2}	Input Low Voltage (X1, X2, Y1, Y2)	3V	—	0	—	1	V
		5V		0	—	2	
V_{IH2}	Input High Voltage (X1, X2, Y1, Y2)	3V	—	2	—	3	V
		5V		3	—	5	
I_{OL}	I/O Ports Sink Current	3V	$V_{OL}=0.3V$	1.5	2.5	—	mA
		5V	$V_{OL}=0.5V$	4	6	—	
I_{OH}	I/O Ports Source Current	3V	$V_{OH}=2.7V$	-1	-1.5	—	mA
		5V	$V_{OH}=4.5V$	-2	-3	—	
I_{OL1}	CLK, DATA Sink Current	3V	$V_{OL}=0.3V$	8	—	—	mA
		5V	$V_{OL}=0.5V$	8	—	—	
I_{OH1}	CLK, DATA Source Current	3V	$V_{OH}=2.7V$	-1.5	-2.5	—	mA
		5V	$V_{OH}=4.5V$	-1.5	-2.5	—	
R_{PH}	Pull-high Resistance of CLK, DATA	3V	—	5	7.5	10	k Ω
		5V	—	3	4.7	6.3	
R_{PL}	Pull-low Resistance of TEST, RB, MB, LB	3V	—	10	30	50	k Ω
		5V	—	8	17	35	
R_{PL1}	Pull-low Resistance of X1, X2, Y1, Y2	3V	—	60	100	160	k Ω
		5V	—	35	60	90	

A.C. Characteristics

Symbol	Parameter	Test Conditions		Min.	Typ.	Max.	Unit
f _{SYS}	System Clock (RC OSC)	3V	R _{OSC} =120K	5.4	6	6.6	MHz
		5V	R _{OSC} =120K	5.4	6	6.6	MHz
t _{RES}	External Reset Low Pulse Width	3V	—	1	—	—	μs

Functional Description

Power-on Reset

The Mouse logic generates a power-on reset at power up after 600 millisecond \pm 20%.

Modes of Operation

- **Reset**
After power up or when receiving a reset command, CLK and DATA lines can go to a positive level. The mouse waits between 300 to 500 milliseconds and sends AA to the host, followed by a device ID of 00. After reset the mouse is set to its default values: Incremental stream mode, 1:1 scaling, report rate of 100, 6 counts per mm at 320 DPI or 4 counts per mm at 200 DPI, and then disable itself. No further action occurs until a command is sent from the host.
- **Stream**
In this mode, a data report is transmitted to the system if a switch is pressed or released, or if at least one count of movement has been detected. The maximum rate of transfer is the programmed sample rate.
- **Remote**
In this mode, data is transmitted only in response to a read data command.
- **Wrap**
In this mode, any byte of data sent by the system, except hex EC or hex FF, is returned by the mouse.

Data Transmission

During data transmission, CLK is used to clock serial data. The mouse generates a clocking signal when sending data to and receiving data from the system. The system requests the mouse receiving system data output by forcing the data line to an inactive level and allowing CLK to go to an active level.

Communication is bidirectional using the clock and data signal lines. The signal for each of these lines comes from open collector devices, allowing either the mouse or the system to force a line to an inactive level. During a non-transmission state, CLK and DATA are both held at an active level.

- **Data output**
When the mouse is ready to transmit, it checks for an inhibit signal or a host request-to-send status on CLK and DATA. If CLK is low, data is continuously updated

in the mouse and no transmissions are made. If CLK is high and DATA is low (request-to-send), the data is also updated in the mouse, the mouse inputs the host data, and no transmissions are started by the mouse until CLK and DATA are both high. If CLK and DATA are both high, the mouse proceeds to output 0 start bit, 8 data bits, parity bit, and stop bit if a transmission is required. Data is valid prior to the falling edge of CLK and beyond the rising edge of CLK. During transmission, the mouse checks for a line contention by checking for an inactive level on CLK at intervals not to exceed 100 μs. Contention occurs when the host lowers CLK to inhibit the mouse output after the mouse starts a transmission. If this occurs before the rising edge of the tenth clock (parity bit), the mouse internally stores its data packet in the mouse buffer and returns both DATA and CLK high. If there is no contention by the tenth clock, the mouse completes the transmission. Following a transmission, the host can inhibit the mouse until it services the input or until it requests to send a response if necessary.

- **Data input**
When the host is ready to send data to the mouse, it first checks to see if the mouse is transmitting data. If the mouse is transmitting, the host can override the mouse output by forcing CLK low before the tenth clock. If the mouse transmits beyond this, the host receives the data. If the mouse is not transmitting or if the host overrides the mouse output, the host forces CLK to an inactive level for a period of not less than 100 μs while preparing for output. When the system is ready to output 0 start bit (data line is low), it allows CLK to go to an active level. The mouse checks this state every 10ms.
If request-to-send is detected, the mouse clocks 11 bits. After the tenth clock, the mouse checks for a high on the DATA line and if found, the mouse forces DATA to a low level and clocks once more. This signals the host to return to the ready state when it can accept input or go to an inhibit mode until ready. If DATA is found at an inactive level following clock 10, a framing error has occurred and the mouse continues to clock until DATA is high, then clocks the line control bit and request a resend. For host commands and data transmission that requires a response, the host waits for the mouse to respond before sending its next output.

The response must be within 20ms, unless the host inhibits the mouse output or inhibits the data transmissions from the system that require a response. If the host initiates a command or data transmission and the response is invalid or has a parity error, the host retransmits the command or data. If after two retries the response is still invalid or has a parity error, the host resets the mouse.

Data Format

The following data report format is valid for the stream and remote modes and is 3 bytes long:

Byte	Bit	Description
3	7	MSB of Y Data
	6-1	Y Data
2	0	LSB of Y Data
	7	MSB of X Data
1	6-1	X Data
	0	LSB of X Data
1	7	Y Data Overflow 1=Overflow
	6	X Data Overflow 1=Overflow
	5	Y Data sign 1=Negative
	4	X Data sign 1=Negative
	3	Reserved always=1
	2	Reserved for middle Button
	1	Right Button Status 1=Pressed
0	Left Button Status 1=Pressed	

Commands

- The following table lists all the valid commands:

Hex Code	Command
FF	Reset
FE	Resend
F6	Set default
F5	Disable
F4	Enable
F3	Set sampling rate
F2	Read device type
F0	Set remote mode
EE	Set wrap mode
EC	Reset wrap mode
EB	Read data
EA	Set stream mode
E9	Status request
E8	Set resolution
E7	Set scaling 2:1
E6	Reset scaling

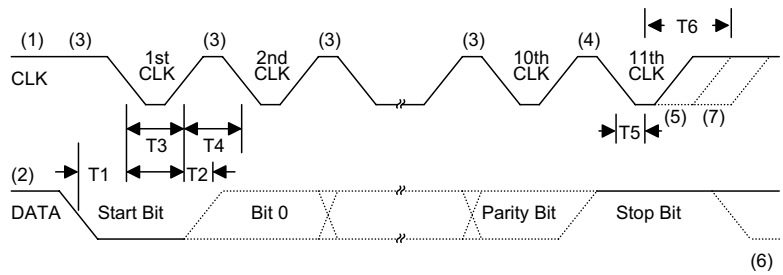
- The following describe valid commands:

Hex Code	Command	Description
FF	Reset	This command cause the mouse to enter a reset mode and do an internal self-test.
FE	Resend	The system can send this command when it detects an error in any transmission from the mouse. The Resend command could be sent following a mouse transmission and before the system enables the interface allowing the next mouse output. On receipt of Resend, the mouse retransmits the previous three bytes if the previous output was a 3-byte packet. The previous two bytes if the previous output was a 2-byte packet, and the previous one byte if the previous output was a 1-byte packet, unless the previous output from the mouse was a Resend command. In this case, the mouse will resend the previous output prior to the Resend command. If a Resend command is received by the mouse from the host immediately following a 3-byte data packet transmission from the mouse to the host while the mouse is in stream mode. The mouse should resend the 3-byte data packet prior to clearing the count accumulators.
F6	Set default	This command reinitializes all conditions to the power-on default state.
F5	Disable	This command is used in the stream mode to stop transmissions initiated from the mouse. It responds to all other commands while disabled. If the mouse is in the stream mode, it must be disabled before sending it any command that requires a response.
F4	Enable	Begin transmission, if in stream mode
F3, XX	Set sampling rate	In the stream mode, this command sets the sampling rate to the value indicated by bytes hex XX shown in the following figure: Second Byte hex XX (sample rate): hex 0A (10/sec), hex 14 (20/sec), hex 28 (40/sec), hex 3C (60/sec), hex 50 (80/sec), hex 64 (100/sec), hex C8 (200/sec)
F2	Read device type	This command always receives a response of hex 00

Hex Code	Command	Description																																	
F0	Set remote mode	This command sets the remote mode. Data values are reported only in response to a Read Data command.																																	
EE	Set wrap mode	This command sets the wrap mode. This mode remains until hex FF or hex EC is received.																																	
EC	Reset wrap mode	This command resets the wrap mode																																	
EB	Read data	This command requests that all data defined in the data packet format be transmitted. This command is executed in either remote or stream mode. The data is transmitted even if there has been no movement since the last report or the switch status is unchanged. Following a Read Data command, the accumulators are cleared after a data transmission.																																	
EA	Set stream mode	This command sets the stream mode																																	
E9	Status request	<p>When this command is issued by the system, the mouse responds with a 3-byte status report as follows:</p> <table border="1"> <thead> <tr> <th>Byte</th> <th>Bit</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>3</td> <td>0~7</td> <td>Current sampling rate</td> </tr> <tr> <td>2</td> <td>0~7</td> <td>Current resolution setting</td> </tr> <tr> <td>1</td> <td>7</td> <td>always = 0</td> </tr> <tr> <td></td> <td>6</td> <td>0 = Stream mode, 1 = Remote mode</td> </tr> <tr> <td></td> <td>5</td> <td>0 = Disabled, 1 = Enabled</td> </tr> <tr> <td></td> <td>4</td> <td>0 = Scaling 1:1, 1 = Scaling 2:1</td> </tr> <tr> <td></td> <td>3</td> <td>always = 0</td> </tr> <tr> <td></td> <td>2</td> <td>1 = Left button pressed</td> </tr> <tr> <td></td> <td>1</td> <td>Reserved for middle button</td> </tr> <tr> <td></td> <td>0</td> <td>1 = Right button pressed</td> </tr> </tbody> </table>	Byte	Bit	Description	3	0~7	Current sampling rate	2	0~7	Current resolution setting	1	7	always = 0		6	0 = Stream mode, 1 = Remote mode		5	0 = Disabled, 1 = Enabled		4	0 = Scaling 1:1, 1 = Scaling 2:1		3	always = 0		2	1 = Left button pressed		1	Reserved for middle button		0	1 = Right button pressed
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E8, XX	Set resolution	<p>The mouse provides four resolutions selected by the second byte of this command as follows:</p> <table border="1"> <thead> <tr> <th rowspan="2">Second Byte</th> <th colspan="3">Resolution (Counts per mm)</th> </tr> <tr> <th>hex XX</th> <th>200 DPI</th> <th>320 DPI</th> <th>400 DPI</th> </tr> </thead> <tbody> <tr> <td></td> <td>hex 00</td> <td>1</td> <td>1</td> <td>2</td> </tr> <tr> <td></td> <td>hex 01</td> <td>2</td> <td>3</td> <td>4</td> </tr> <tr> <td></td> <td>hex 02</td> <td>4</td> <td>6</td> <td>8</td> </tr> <tr> <td></td> <td>hex 03</td> <td>8</td> <td>12</td> <td>16</td> </tr> </tbody> </table>	Second Byte	Resolution (Counts per mm)			hex XX	200 DPI	320 DPI	400 DPI		hex 00	1	1	2		hex 01	2	3	4		hex 02	4	6	8		hex 03	8	12	16					
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	hex 01	2	3	4																															
	hex 02	4	6	8																															
	hex 03	8	12	16																															
E7	Set scaling 2:1	<p>Scaling is used to provide a course/fine tracking response. At the end of a sample interval in the stream mode, the current X and Y data values are converted to new values. The sign bits are not involved in this conversion. 2:1 scaling is only performed in stream mode. In response to a Read Data command, the mouse will transmit the current value before conversion.</p> <table border="1"> <thead> <tr> <th>Input</th> <th>Output</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> </tr> <tr> <td>1</td> <td>1</td> </tr> <tr> <td>2</td> <td>1</td> </tr> <tr> <td>3</td> <td>3</td> </tr> <tr> <td>4</td> <td>6</td> </tr> <tr> <td>5</td> <td>9</td> </tr> <tr> <td>N (≥6)</td> <td>2.0 × N</td> </tr> </tbody> </table>	Input	Output	0	0	1	1	2	1	3	3	4	6	5	9	N (≥6)	2.0 × N																	
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E6	Reset scaling	This command restores 1:1 scaling																																	

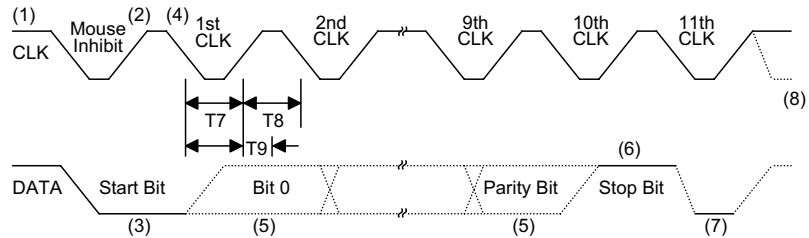
Timing Diagrams

Data Output



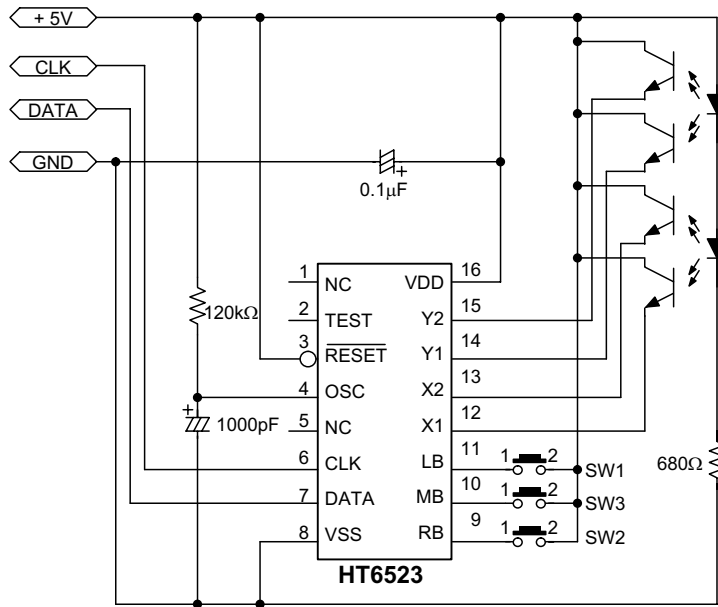
	Timing Parameter	Min/Max
T1	Data transition to the falling edge of CLK	5/25 μ s
T2	Rising edge of CLK to DATA transition	5/T4-5 μ s
T3	Duration of CLK low	30/50 μ s
T4	Duration of CLK high	30/50 μ s
T5	Minimum time to MOUSE inhibit after clock 11	> 0 μ s
T6	Maximum time to MOUSE inhibit after clock 11 to ensure MOUSE does not start another transmission	< 50 μ s

Data Input



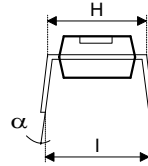
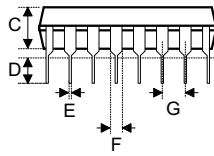
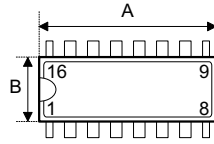
	Timing Parameter	Min/Max
T7	Duration of CLK low	30/50 μ s
T8	Duration of CLK high	30/50 μ s
T9	Time from low to high CLK transition to time when MOUSE samples DATA line	5/25 μ s

Application Circuits



Package Information

16-pin DIP (300mil) Outline Dimensions



Symbol	Dimensions in mil		
	Min.	Nom.	Max.
A	745	—	775
B	240	—	260
C	125	—	135
D	125	—	145
E	16	—	20
F	50	—	70
G	—	100	—
H	295	—	315
I	335	—	375
α	0°	—	15°

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