#### 2M x 8 11/10 EDO DRAM

#### **Features**

- 2,097,152 word by 8 bit organization
- Single 3.3V  $\pm$  0.3V or 5.0V  $\pm$  0.5V power supply
- Standard Power (SP) and Low Power (LP)
- · 2048 Refresh Cycles
  - 32 ms Refresh Rate (SP version)
  - 128 ms Refresh Rate (LP version)
- High Performance:

		-50	-60	-6R	-70	Units
t <sub>RAC</sub>	RAS Access Time	50	60	60	70	ns
t <sub>CAC</sub>	CAS Access Time	13	15	17	20	ns
t <sub>AA</sub>	Column Address Access Time	25	30	30	35	ns
t <sub>RC</sub>	Cycle Time	84	104	104	124	ns
t <sub>HPC</sub>	EDO (Hyper Page) Mode Cycle Time	20	25	25	30	ns

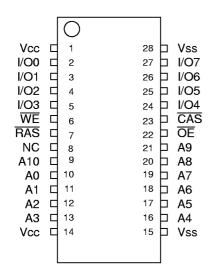
- · Low Power Dissipation
  - Active (max) 100 mA / 90 mA / 80 mA
  - Standby: TTL Inputs (max) 1.0 mA
  - Standby: CMOS Inputs (max)
    - 1.0 mA (SP version)
    - 0.2 mA (LP version)
  - Self Refresh (LP version only)
    - 200µA (3.3 Volt)
    - 300μA (5.0 Volt)
- · Extended Data Out (Hyper Page) Mode
- · Read-Modify-Write
- RAS Only and CAS before RAS Refresh
- Hidden Refresh
- Package: TSOP-II 28 (400milx725mil)

#### **Description**

The IBM0117805 is a dynamic RAM organized 2,097,152 words by 8 bits, which has a very low "sleep mode" power consumption option. These devices are fabricated in IBM's advanced 0.5µm CMOS silicon gate process technology. The circuit and process have been carefully designed to pro-

vide high performance, low power dissipation, and high reliability. The devices operate with a single  $3.3V \pm 0.3V$  or  $5.0V \pm 0.5V$  power supply. The 21 addresses required to access any bit of data are multiplexed (11 are strobed with RAS, 10 are strobed with  $\overline{CAS}$ ).

#### Pin Assignments (Top View)



#### **Pin Description**

RAS	Row Address Strobe
CAS	Column Address Strobe
WE	Read/Write Input
A0 - A10	Address Inputs
ŌĒ	Output Enable
1/00 - 1/07	Data Input/Output
V <sub>cc</sub>	Power (+3.3V or +5.0V)
V <sub>SS</sub>	Ground

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# **Ordering Information**

Part Number	SP / LP	Self Refresh	Power Supply	Speed	Package	Notes
IBM0117805T3 -50	SP	No	5.0V	50ns	400mil TSOP-II 28	1
IBM0117805T3 -60	SP	No	5.0V	60ns	400mil TSOP-II 28	1
IBM0117805T3 -6R	SP	No	5.0V	60ns	400mil TSOP-II 28	1
IBM0117805T3 -70	SP	No	5.0V	70ns	400mil TSOP-II 28	1
IBM0117805BT3 -50	SP	No	3.3V	50ns	400mil TSOP-II 28	1
IBM0117805BT3 -60	SP	No	3.3V	60ns	400mil TSOP-II 28	1
IBM0117805BT3 -6R	SP	No	3.3V	60ns	400mil TSOP-II 28	1
IBM0117805BT3 -70	SP	No	3.3V	70ns	400mil TSOP-II 28	1
IBM0117805MT3 -50	LP	Yes	5.0V	50ns	400mil TSOP-II 28	1
IBM0117805MT3 -60	LP	Yes	5.0V	60ns	400mil TSOP-II 28	1
IBM0117805MT3 -70	LP	Yes	5.0V	70ns	400mil TSOP-II 28	1
IBM0117805PT3 -50	LP	Yes	3.3V	50ns	400mil TSOP-II 28	1
IBM0117805PT3 -60	LP	Yes	3.3V	60ns	400mil TSOP-II 28	1
IBM0117805PT3 -6R	LP	Yes	3.3V	60ns	400mil TSOP-II 28	1
IBM0117805PT3 -70	LP	Data Yes	Sheet4U.com	70ns	400mil TSOP-II 28	1

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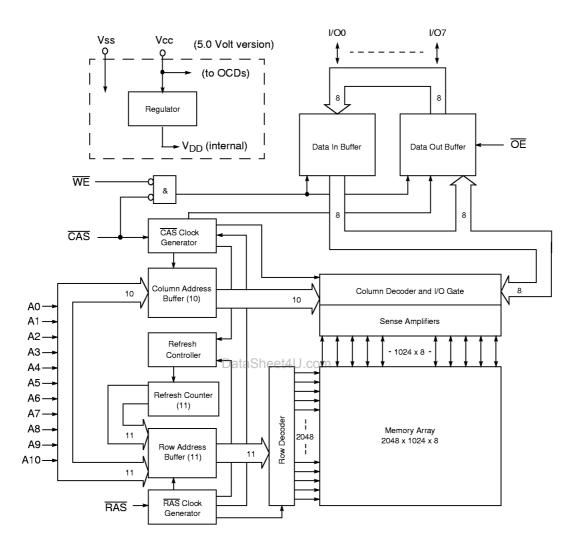
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<sup>1.</sup> SP = Standard Power version (IBM0117805 and IBM0117805B); LP = Low Power version (IBM0117805M and IBM00117805P)



## **Block Diagram**



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#### **Truth Table**

Function		RAS	CAS	WE	ŌĒ	Row Address	Col Address	1/00 - 1/07
Standby	***************************************	Н	Н→Х	Χ	Χ	X	X	High Impedance
Read		L	L	Н	L	Row	Col	Data Out
Early-Write		L	L	L	Χ	Row	Col	Data In
Delayed-Write		L	L	H→L	Н	Row	Col	Data In
Read-Modify-Write		L	L	H→L	L→H	Row	Col	Data Out, Data In
EDO (Hyper Page) Mode	1st Cycle	L	H→L	Н	L	Row	Col	Data Out
Read	2nd Cycle	L	H→L	Н	L	N/A	Col	Data Out
EDO (Hyper Page) Mode	1st Cycle	L	H→L	L	Х	Row	Col	Data In
Write	2nd Cycle	L	H→L	L	Х	N/A	Col	Data In
EDO (Hyper Page) Mode	1st Cycle	L	H→L	H→L	L→H	Row	Col	Data Out, Data In
Read-Modify-Write	2nd Cycle	L	H→L	H→L	L→H	N/A	Col	Data Out, Data In
RAS-Only Refresh		L	Н	Х	Х	Row	N/A	High Impedance
CAS-Before-RAS Refresh	***************************************	H→L	L	Н	Х	X	N/A	High Impedance
Lliddon Dofroch	Read	L→H→L	L	Н	L	Row	Col	Data Out
Hidden Refresh	Write	L→H→Ы	taShee	t4U.com	X	Row	Col	Data In
Self Refresh (LP version only)		H→L	L	L	Н	Х	Х	Χ

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#### **Absolute Maximum Ratings**

Comple el	Down stor	Rat	ting	l leite	Nietes
Symbol	Parameter	3.3 Volt Device	5.0 Volt Device	Units	Notes
V <sub>CC</sub>	Power Supply Voltage	-0.5 to +4.6	-1.0 to +7.0	٧	1
$V_{IN}$	Input Voltage	-0.5 to min (V <sub>CC</sub> +0.5, 4.6)	-0.5 to min (V <sub>CC</sub> +0.5, 7.0)	٧	1
V <sub>OUT</sub>	Output Voltage	-0.5 to min (V <sub>CC</sub> +0.5, 4.6)	-0.5 to min (V <sub>CC</sub> +0.5, 7.0)	٧	1
T <sub>OPR</sub>	Operating Temperature	0 to +70	0 to +70	°C	1
T <sub>STG</sub>	Storage Temperature	-55 to +150	-55 to +150	°C	1
P <sub>D</sub>	Power Dissipation	1.0	1.0	W	1
I <sub>OUT</sub>	Short Circuit Output Current	50	50	mA	1

Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a
stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational
sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability

#### Recommended DC Operating Conditions (T<sub>A</sub>= 0 to 70°C)

		Б	3	3.3 Volt Devic	:е	5	5.0 Volt Devic	e .		, , , , , , , , , , , , , , , , , , ,
Syi	mbol	Parameter	Min.	Тур.	Max.	Min.	Тур.	Max.	Units	Notes
	/ <sub>cc</sub>	Supply Voltage	3.0	3.3Data	Shee64U.	com <sub>4.5</sub>	5.0	5.5	٧	1
١	<b>V</b> IH	Input High Voltage	2.0	_	V <sub>CC</sub> + 0.5	2.4	_	V <sub>CC</sub> + 0.5	٧	1, 2
\	V <sub>IL</sub>	Input Low Voltage	-0.5	_	0.8	-0.5	<u> </u>	0.8	٧	1, 2

<sup>1.</sup> All voltages referenced to  $V_{\rm SS}$ .

#### **Capacitance** (T<sub>A</sub>= 25°C, V<sub>CC</sub>= $3.3V \pm 0.3V$ or V<sub>CC</sub>= $5.0V \pm 0.5V$ )

Symbol	Parameter	Min.	Max.	Units	Notes
C <sub>I1</sub>	Input Capacitance (A0 - A10)	—	5	pF	1
	Input Capacitance (RAS, CAS, WE, OE)	_	7	pF	1
Co	Output Capacitance (I/O0 - I/O7)	_	7	pF	1
Co			7	pF	

<sup>1.</sup> Input capacitance measurements made with rise time shift method with  $\overline{CAS}$  &  $\overline{RAS}$  =  $V_{IH}$  to disable output.

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V<sub>IH</sub> may overshoot to V<sub>CC</sub> + 1.2V for pulse widths of ≤ 4.0ns with 3.3 Volt, or V<sub>CC</sub> + 2.0V for pulse widths of ≤ 4.0ns (or V<sub>CC</sub> + 1.0V for ≤ 8.0ns) with 5.0 Volt. Additionally, V<sub>IL</sub> may undershoot to -2.0V for pulse widths ≤ 4.0ns with 3.3 Volt, or to -2.0V for pulse widths ≤ 4.0ns (or -1.0V for ≤ 8.0ns) with 5.0 Volt. Pulse widths measured at 50% points with amplitude measured peak to DC reference.



#### **DC Electrical Characteristics** $(T_A=0 \text{ to } +70 ^{\circ}\text{C}, V_{CC}=3.3\text{V} \pm 0.3\text{V or } V_{CC}=5.0\text{V} \pm 0.5\text{V})$

Symbol	Parameter	***************************************	Min.	Max.	Units	Notes
	Operating Current	-50	<u> </u>	100	**************************************	
I <sub>CC1</sub>	Average Power Supply Operating Current	-60 / 6R	<u> </u>	90	mA	1, 2, 3
	(RAS, CAS, Address Cycling: t <sub>RC</sub> = t <sub>RC</sub> min.)	-70	_	80		
I <sub>CC2</sub>	Standby Current (TTL) Power Supply Standby Current (RAS = CAS = V <sub>IH</sub> )		_	1	mA	
	RAS Only Refresh Current	-50	_	100		
I <sub>CC3</sub>	Average Power Supply Current, RAS Only Mode	-60 / 6R	<u> </u>	90	mA	1, 3
	$(\overline{RAS} \text{ Cycling}, \overline{CAS} = V_{IH}: t_{RC} = t_{RC} \text{ min})$	-70	—	80		
	EDO (Illunes Dece) Made Correct	-50	<u> </u>	60		4
I <sub>CC4</sub>	EDO (Hyper Page) Mode Current Average Power Supply Current	-60 / 6R	<u> </u>	50	mA	1, 2, 3
	$(RAS = V_{IL}, \overline{CAS}, Address Cycling: t_{PC} = t_{PC} min)$	-70	—	40		
	Standby Current (CMOS)	SP version	<u> </u>	1		
I <sub>CC5</sub>	Power Supply Standby Current (RAS = CAS = V <sub>CC</sub> - 0.2V)	LP version	_	0.2	mA	
		-50	<u> </u>	100		
I <sub>CC6</sub>	CAS Before RAS Refresh Current Average Power Supply Current, CAS Before RAS Mode	-60 / 6R	<u> </u>	90	mA	1, 3
	$(\overline{RAS}, \overline{CAS}, Cycling: t_{RC} = t_{RC} min)$	-70	_	80		
	Self Refresh Current, LP version only	3.3V	<u> </u>	200		
I <sub>CC7</sub>	Average Power Supply Current during Self Refresh CBR cycle with RAS $\geq$ t <sub>RASS</sub> (min); CAS held low; WE = V <sub>CC</sub> - 0.2V; Addresses and D <sub>IN</sub> = V <sub>CC</sub> - 0.2V or 0.2V.	5.0V	—	300	μА	
I <sub>I(L)</sub>	Input Leakage Current Input Leakage Current, any input $(0.0 \le V_{IN} \le (V_{CC} + 0.3V))$ , All Other Pins Not Under Test = 0V		-5	+5	μА	
I <sub>O(L)</sub>	Output Leakage Current ( $D_{OUT}$ is disabled, $0.0 \le V_{OUT} \le V_{CC}$ )		-5	+5	μА	
V <sub>OH</sub>	Output Level (TTL) Output "H" Level Voltage (I <sub>OUT</sub> = -2.0mA for 3.3V, or I <sub>OUT</sub> = -5mA for 5.0V)		2.4	V <sub>cc</sub>	٧	
V <sub>OL</sub>	Output Level (TTL) Output "L" Level Voltage (I <sub>OUT</sub> = +2.0mA for 3.3V, or I <sub>OUT</sub> = +4.2mA for 5.0V)		0.0	0.4	V	

<sup>1.</sup>  $I_{CC1}$ ,  $I_{CC3}$ ,  $I_{CC4}$  and  $I_{CC6}$  depend on cycle rate.

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<sup>2.</sup>  $I_{CC1}$  and  $I_{CC4}$  depend on output loading. Specified values are obtained with the output open.

<sup>3.</sup> Address can be changed once or less while  $\overline{RAS} = V_{IL}$ . In the case of  $I_{CC4}$ , it can be changed once or less when  $\overline{CAS} = V_{IH}$ .



#### **AC Characteristics** ( $T_A$ = 0 to +70°C, $V_{CC}$ = 3.3V $\pm$ 0.3V or $V_{CC}$ = 5.0V $\pm$ 0.5V)

- 1. An initial pause of 200µs is required after power-up followed by 8 RAS only refresh cycles before proper device operation is achieved. In case of using the internal refresh counter, a minimum of 8 CAS before RAS refresh cycles instead of 8 RAS only refresh cycles is required.
- 2. AC measurements assume t<sub>T</sub>=2ns.
- 3.  $V_{IH}(min.)$  and  $V_{IL}(max.)$  are reference levels for measuring timing of input signals. Also, transition times are measured between  $V_{IH}$  and  $V_{II}$ .
- 4. Valid column addresses are A0 through A9.

#### Read, Write, Read-Modify-Write and Refresh Cycles (Common Parameters)

Symbol	Parameter	-	-50	-	60	-	6R	-70		Units	Notes
Symbol	raidiletei	Min.	Мах.	Min.	Max.	Min.	Max.	Min.	Max.	UIIIIS	Motes
t <sub>RC</sub>	Random Read or Write Cycle Time	84	_	104	_	104	_	124	_	ns	
t <sub>RP</sub>	RAS Precharge Time	30	_	40	—	40	—	50	—	ns	
t <sub>CP</sub>	CAS Precharge Time	8	_	10	_	10	_	10	—	ns	
t <sub>RAS</sub>	RAS Pulse Width	50	10K	60	10K	60	10K	70	10K	ns	
t <sub>CAS</sub>	CAS Pulse Width	8	10K	10	10K	10	10K	12	10K	ns	
t <sub>ASR</sub>	Row Address Setup Time	0	_	0	_	0	_	0	—	ns	
t <sub>RAH</sub>	Row Address Hold Time	10	—	10	—	10	—	10	—	ns	
t <sub>ASC</sub>	Column Address Setup Time	0	_	0	_	0	_	0	—	ns	
t <sub>CAH</sub>	Column Address Hold Time	8	_	10	_	10	—	10	—	ns	
t <sub>RCD</sub>	RAS to CAS Delay Time	<sub>1</sub> 2ai	taShee	14 H4 C	om <sub>45</sub>	14	43	14	50	ns	1
t <sub>RAD</sub>	RAS to Column Address Delay Time	12	25	12	30	12	30	12	35	ns	2
t <sub>RSH</sub>	RAS Hold Time	8	_	10	—	10	_	12	_	ns	
t <sub>сsн</sub>	CAS Hold Time	38	_	45	_	45	_	50	—	ns	
t <sub>CRP</sub>	CAS to RAS Precharge Time	5	_	5	—	5	_	5	_	ns	
t <sub>OED</sub>	OE to D <sub>IN</sub> Delay Time	13	_	15	_	15	_	15	_	ns	3
t <sub>DZO</sub>	OE Delay Time from D <sub>IN</sub>	0		0		0	_	0	_	ns	4
t <sub>DZC</sub>	CAS Delay Time from D <sub>IN</sub>	0		0		0	_	0		ns	4
t <sub>T</sub>	Transition Time (Rise and Fall)	2	50	2	50	2	50	2	50	ns	5

- Operation within the t<sub>RCD</sub>(max.) limit ensures that t<sub>RAC</sub>(max.) can be met. t<sub>RCD</sub>(max.) is specified as a reference point only. If t<sub>RCD</sub> is greater than the specified t<sub>RCD</sub>(max.) limit, then access time is controlled by t<sub>CAC</sub>.
- 2. Operation within the  $t_{RAD}(max.)$  limit ensures that  $t_{RAD}(max.)$  can be met.  $t_{RAD}(max.)$  is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}(max.)$  limit, then access time is controlled by  $t_{AA}$ .
- 3. Either t<sub>CDD</sub> or t<sub>OED</sub> must be satisfied.
- 4. Either t<sub>DZC</sub> or t<sub>DZO</sub> must be satisfied.
- 5. AC measurements assume  $t_T$ =2ns.

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#### **Write Cycle**

	Parameter	-50		-60 / -6R			70	Linita	
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Units	Notes
t <sub>wcs</sub>	Write Command Set Up Time	0	_	0	_	0	_	ns	1
t <sub>wch</sub>	Write Command Hold Time	7	_	10	_	12	_	ns	
t <sub>WP</sub>	Write Command Pulse Width	7		10	_	12		ns	*****************
t <sub>RWL</sub>	Write Command to RAS Lead Time	7	_	10	_	12	_	ns	
t <sub>CWL</sub>	Write Command to CAS Lead Time	7		10	_	12		ns	
t <sub>DS</sub>	D <sub>IN</sub> Setup Time	0		0		0		ns	2
t <sub>DH</sub>	D <sub>IN</sub> Hold Time	7	_	10	_	12	_	ns	2

<sup>1.</sup> t<sub>WCS</sub>, t<sub>RWD</sub>, t<sub>CWD</sub> and t<sub>AWD</sub> are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If t<sub>WCS</sub> ≥ t<sub>WCS</sub> (min), the cycle is an early write cycle and the data pin will remain open circuit (high impedance) through the entire cycle. If t<sub>RWD</sub> ≥ t<sub>RWD</sub> (min), t<sub>CWD</sub> ≥ t<sub>CWD</sub> (min) and t<sub>AWD</sub> ≥ t<sub>AWD</sub> (min), the cycle is a Read-Modify-Write cycle and the data out will contain data read from the selected cell. If neither of the above sets of conditions are satisfied, the condition of the data out (at access time) is indeterminate.

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<sup>2.</sup> These parameters are referenced to CAS leading edge in early write cycles and to WE leading edge in Read-Modify-Write cycles.



#### **Read Cycle**

			-50		-60	-	6R	-	70		
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Units	Notes
t <sub>RAC</sub>	Access Time from RAS	<u> </u>	50	<u> </u>	60	<u> </u>	60	-	70	ns	1, 2, 3
t <sub>CAC</sub>	Access Time from CAS	-	13	_	15	_	17	_	20	ns	1, 3
t <sub>AA</sub>	Access Time from Address	_	25	_	30	_	30	_	35	ns	2, 3
t <sub>OEA</sub>	Access Time from OE	_	13	_	15	_	17	-	20	ns	3
t <sub>RCS</sub>	Read Command Setup Time	0	_	0	_	0	_	0	_	ns	
t <sub>RCH</sub>	Read Command Hold Time to CAS	0	_	0	<del></del>	0		0	_	ns	4
t <sub>RRH</sub>	Read Command Hold Time to RAS	0	_	0		0	_	0	_	ns	4
t <sub>RAL</sub>	Column Address to RAS Lead Time	25	_	30	_	30	_	35	_	ns	
t <sub>CLZ</sub>	CAS to Output in Low-Z	0	_	0		0		0	_	ns	3
t <sub>OFF</sub>	Output Buffer Turn-Off Delay	-	13	<u> </u>	15	<u> </u>	15	_	15	ns	5, 6
t <sub>CDD</sub>	CAS to D <sub>IN</sub> Delay Time	13	_	15		15		15	_	ns	7
t <sub>OEZ</sub>	Output Buffer Turn-Off Delay from OE	_	13	_	15	<u> </u>	15	_	15	ns	5
t <sub>OES</sub>	OE Setup Time Prior to CAS	5	_	5	<u> </u>	5		5	_	ns	
t <sub>ORD</sub>	OE Setup Time Prior to RAS (Hidden Refresh)	0	—	0	<b>—</b>	0	_	0	_	ns	

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- 1. Operation within the t<sub>RCD</sub>(max.) limit ensures that t<sub>RAC</sub>(max.) can be met. t<sub>RCD</sub>(max.) is specified as a reference point only. If t<sub>RCD</sub> is greater than the specified t<sub>RCD</sub>(max.) limit, then access time is controlled by t<sub>CAC</sub>.
- 2. Operation within the  $t_{RAD}$ (max.) limit ensures that  $t_{RAD}$ (max.) can be met.  $t_{RAD}$ (max.) is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}$ (max.) limit, then access time is controlled by  $t_{AA}$ .
- 3. Measured with the specified current load and 100pF at  $V_{OL} = 0.8V$  and  $V_{OH} = 2.0V$ .
- 4. Either t<sub>RCH</sub> or t<sub>RRH</sub> must be satisfied for a read cycle.
- 5. t<sub>OFF</sub> (max) and t<sub>OEZ</sub> (max) define the time at which the output achieves the open circuit condition and are not referenced to output voltage levels.
- 6. t<sub>OFF</sub> is referenced from the rising edge of RAS or CAS, which ever is last.
- 7. Either t<sub>CDD</sub> or t<sub>OED</sub> must be satisfied.

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#### **Read-Modify-Write Cycle**

C	Parameter	-50		-60		-6R		-70		Units	Notes
Symbol	Parameter	Min.	Мах.	Min.	Max.	Min.	Max.	Min.	Max.	Units	Notes
t <sub>RWC</sub>	Read-Modify-Write Cycle Time	115	_	135	_	135	_	162	_	ns	***************************************
t <sub>RWD</sub>	RAS to WE Delay Time	67	_	79	_	79		94	—	ns	1
t <sub>CWD</sub>	CAS to WE Delay Time	30	_	34	_	36	_	44		ns	1
t <sub>AWD</sub>	Column Address to WE Delay Time	42	-	49	_	49		59	_	ns	1
toeh	OE Command Hold Time	7	_	10		10		12	—	ns	

<sup>1.</sup> t<sub>WCS</sub>, t<sub>RWD</sub>, t<sub>CWD</sub> and t<sub>AWD</sub> are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If t<sub>WCS</sub> ≥ t<sub>WCS</sub> (min), the cycle is an early write cycle and the data pin will remain open circuit (high impedance) through the entire cycle. If t<sub>RWD</sub> ≥ t<sub>RWD</sub> (min), t<sub>CWD</sub> ≥ t<sub>CWD</sub> (min) and t<sub>AWD</sub> ≥ t<sub>AWD</sub> (min), the cycle is a Read-Modify-Write cycle and the data out will contain data read from the selected cell. If neither of the above sets of conditions are satisfied, the condition of the data out (at access time) is indeterminate.

## **Extended Data Out (Hyper Page) Mode Cycle**

Symbol Parameter	-50		-60 / -6R		-70		llmita	Notes	
	Min.	Max.	Min.	Мах.	Min.	Max.	Units	Notes	
t <sub>HCAS</sub>	EDO (Hyper Page) Mode CAS Pulse Width	8	10K	10	10K	12	10K	ns	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
t <sub>HPC</sub>	EDO (Hyper Page) Mode Cycle Time (Read/Write)	20	_	25	_	30	_	ns	
t <sub>HPRWC</sub>	EDO (Hyper Page) Mode Read Modify Write Cycle Time	51	— —	60	_	72	_	ns	
t <sub>DOH</sub>	Data-out Hold Time from CAS	5	_	5	_	5	<del>-</del>	ns	
t <sub>WHZ</sub>	Output buffer Turn-Off Delay from WE	0	10	0	10	0	15	ns	
t <sub>WPZ</sub>	WE Pulse Width to Output Disable at CAS High	7	_	10	_	10		ns	
t <sub>CPRH</sub>	RAS Hold Time from CAS Precharge	30	_	35	_	40	_	ns	
t <sub>CPA</sub>	Access Time from CAS Precharge	_	28	-	35	_	40	ns	1
t <sub>RASP</sub>	EDO (Hyper Page) Mode RAS Pulse Width	50	200K	60	200K	70	200K	ns	
t <sub>OEP</sub>	OE Precharge	5	_	5	_	5	_	ns	
toehc	OE High Hold Time from CAS High	5	<u> </u>	5	—	5	<u> </u>	ns	

<sup>1.</sup> Measured with the specified current load and 100pF at  $V_{OL} = 0.8V$  and  $V_{OH} = 2.0V$ .

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#### **Refresh Cycle**

	Parameter	-50		-60 / -6R		-70			
Symbol		Min.	Max.	Min.	Max.	Min.	Мах.	Units	Notes
t <sub>CSR</sub>	CAS Setup Time (CAS before RAS Refresh Cycle)	5	_	5	—	5	_	ns	
t <sub>CHR</sub>	CAS Hold Time (CAS before RAS Refresh Cycle)	10	_	10	_	10	_	ns	
t <sub>WRP</sub>	WE Setup Time (CAS before RAS Refresh Cycle)	10	<u>—</u>	10	<u>—</u>	10	_	ns	
t <sub>WRH</sub>	WE Hold Time (CAS before RAS Cycle)	10	_	10	_	10	_	ns	
t <sub>RPC</sub>	RAS Precharge to CAS Hold Time	5	_	5	_	5	_	ns	

#### Self Refresh Cycle - Low Power version only

C. makal	ol Parameter		-50		-60		-70		NI_1_
Symbol			Max.	Min.	Max.	Min.	Max.	Units	Notes
t <sub>RASS</sub>	RAS Pulse Width During Self Refresh Cycle	100	_	100	_	100	_	μs	1
t <sub>RPS</sub>	RAS Precharge Time During Self Refresh Cycle	89	_	104	_	124	_	ns	1
t <sub>chs</sub>	CAS Hold Time From RAS Rising During Self Refresh Cycle DataShe	et4 <b>59</b> .c	om <del>-</del>	-50		-50		ns	1, 2
t <sub>CHD</sub>	CAS Hold Time From RAS Falling During Self Refresh Cycle	350	_	350	_	350	_	μs	1, 2

When using Self Refresh mode, the following refresh operations must be performed to ensure proper DRAM operation:
 If row addresses are being refreshed in an EVENLY DISTRIBUTED manner over the refresh interval using CBR refresh cycles,
 then only one CBR cycle must be performed immediately after exit from Self Refresh.
 If row addresses are being refreshed in any other manner (ROR- Distributed/Burst; or CBR-Burst) over the refresh interval, then a

If row addresses are being refreshed in any other manner (ROR- Distributed/Burst; or CBR-Burst) over the refresh interval, then a full set of row refreshes must be performed immediately before entry to and immediately after exit from Self Refresh.

2. If  $t_{RASS} > t_{CHD}$  (min) then  $t_{CHD}$  applies. If  $t_{RASS} \le t_{CHD}$  (min) then  $t_{CHS}$  applies.

#### Refresh

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SYMBOL	Parameter		-50		-60 / -6R		-70			
			Min.	Max.	Min.	Max.	Min.	Max.	Units	Notes
	Refresh Period	SP version	—	32	_	32	—	32	ms	1
₹REF		LP version	_	128	_	128	—	128		
1. 2048 cycle										

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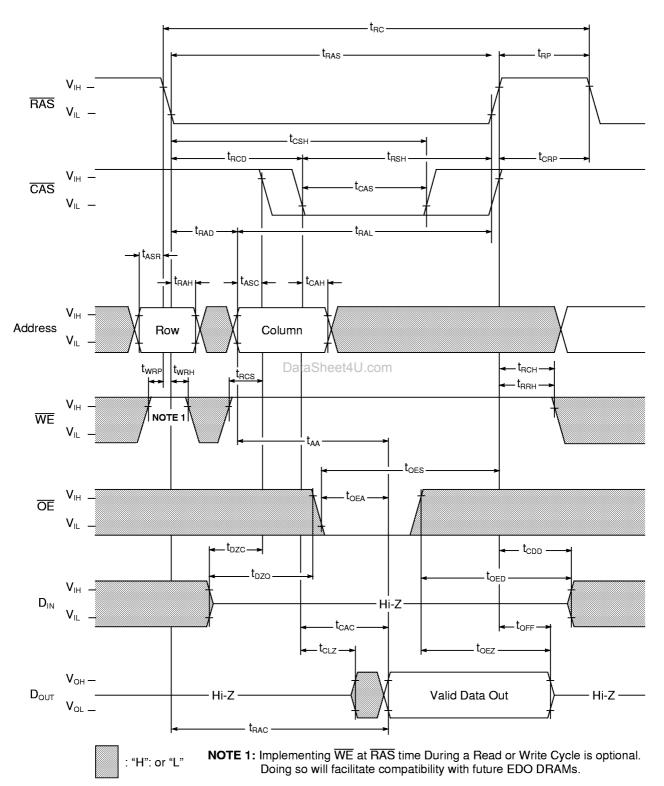
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## **Read Cycle**



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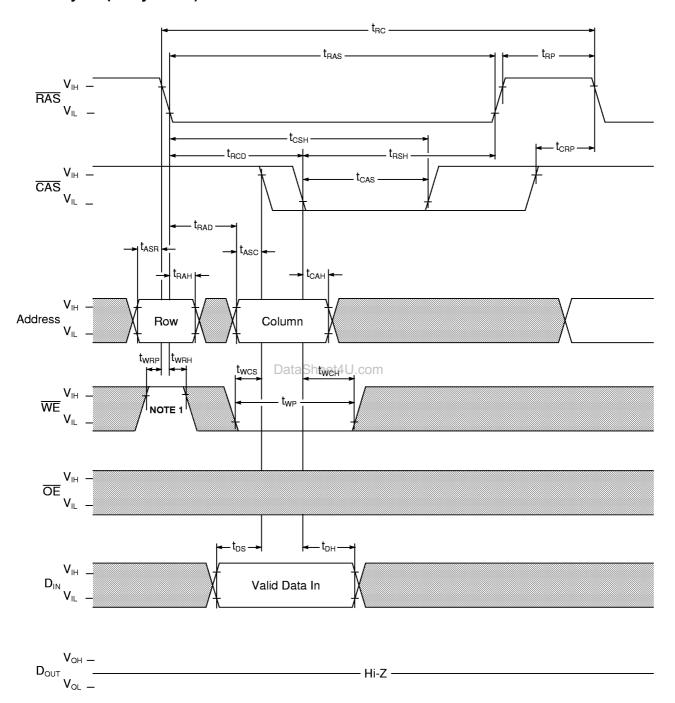
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## Write Cycle (Early Write)



: "H" or "L"

NOTE 1: Implementing WE at RAS time During a Read or Write Cycle is optional.

Doing so will facilitate compatibility with future EDO DRAMs.

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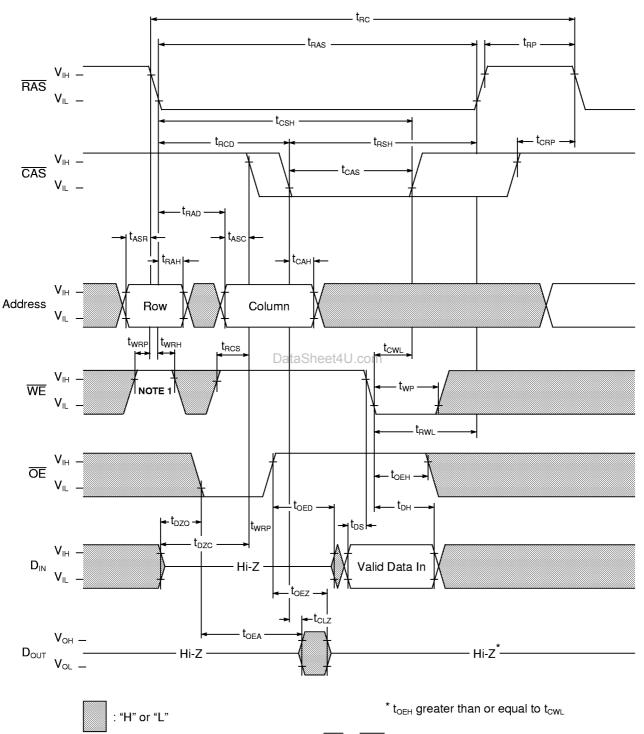
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## Write Cycle (Delayed Write)



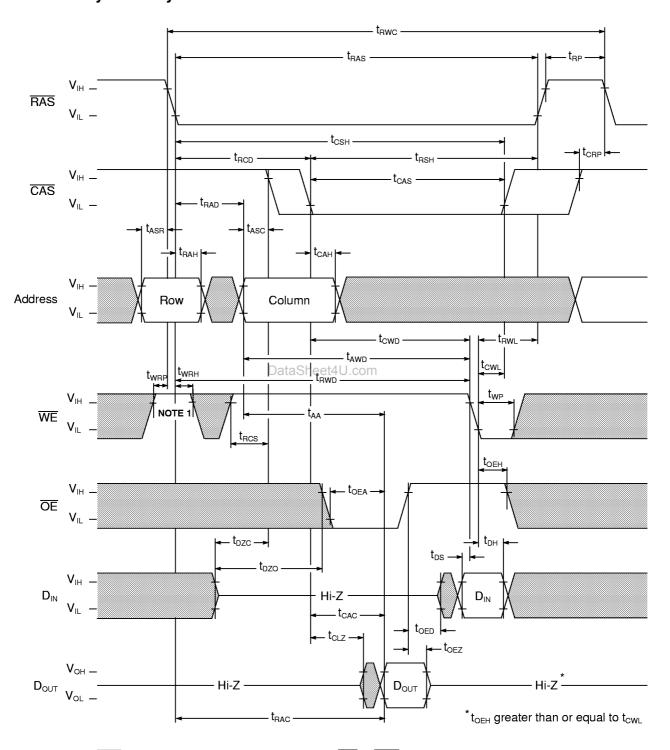
**NOTE 1:** Implementing  $\overline{\text{WE}}$  at  $\overline{\text{RAS}}$  time During a Read or Write Cycle is optional. Doing so will facilitate compatibility with future EDO DRAMs.

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#### **Read-Modify-Write Cycle**



**NOTE 1:** Implementing WE at RAS time During a Read or Write Cycle is optional. Doing so will facilitate compatibility with future EDO DRAMs.

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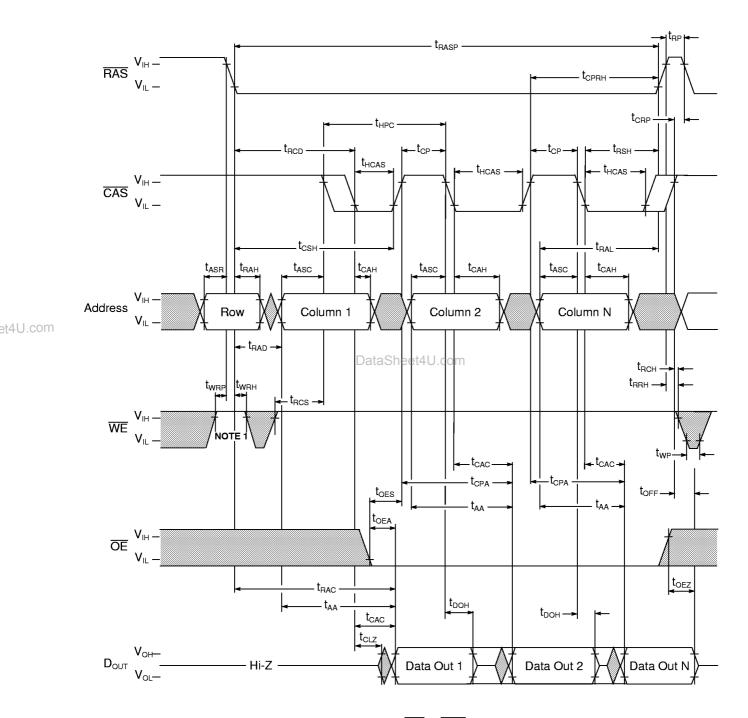
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## **EDO (Hyper Page) Mode Read Cycle**



**NOTE 1:** Implementing WE at RAS time During a Read or Write Cycle is optional. Doing so will facilitate compatibility with future EDO DRAMs.

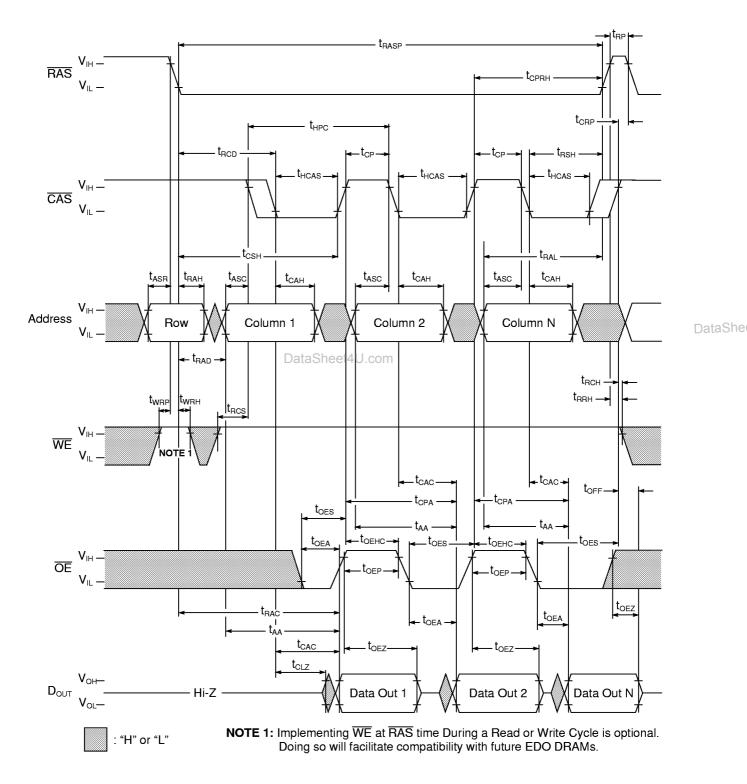
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: "H" or "L"

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# **EDO (Hyper Page) Mode Read Cycle (OE Control)**



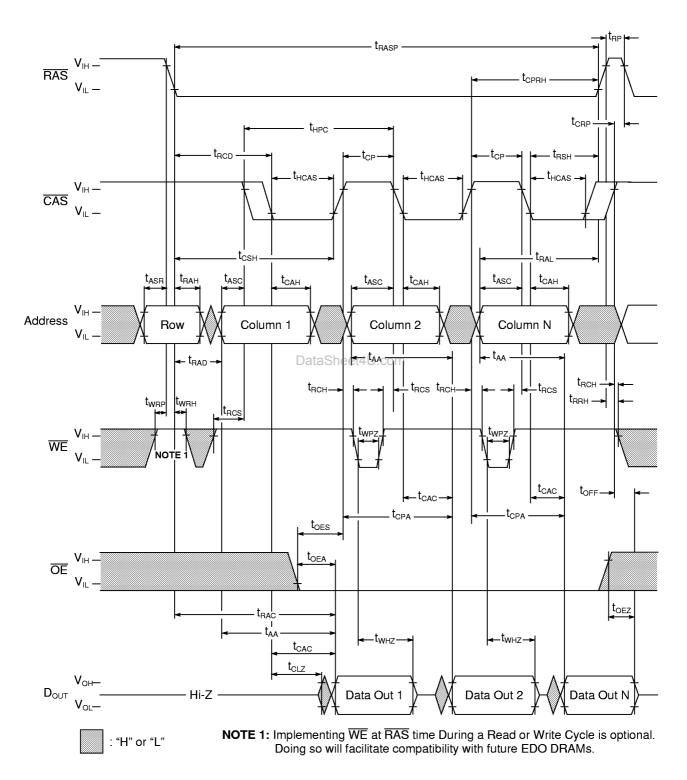
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# **EDO (Hyper Page) Mode Read Cycle (WE Control)**



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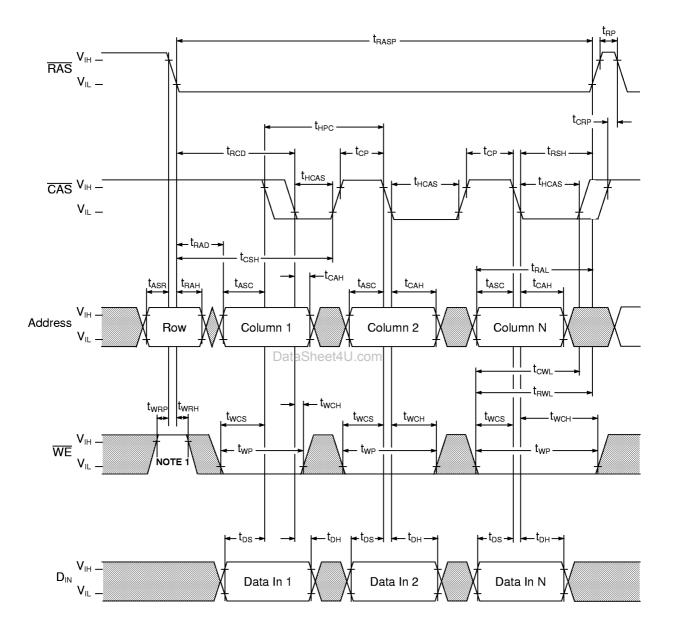
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# **EDO (Hyper Page) Mode Early Write Cycle**



: "H" or "L"

**NOTE 1:** Implementing WE at RAS time During a Read or Write Cycle is optional. Doing so will facilitate compatibility with future EDO DRAMs.

OE = Don't care

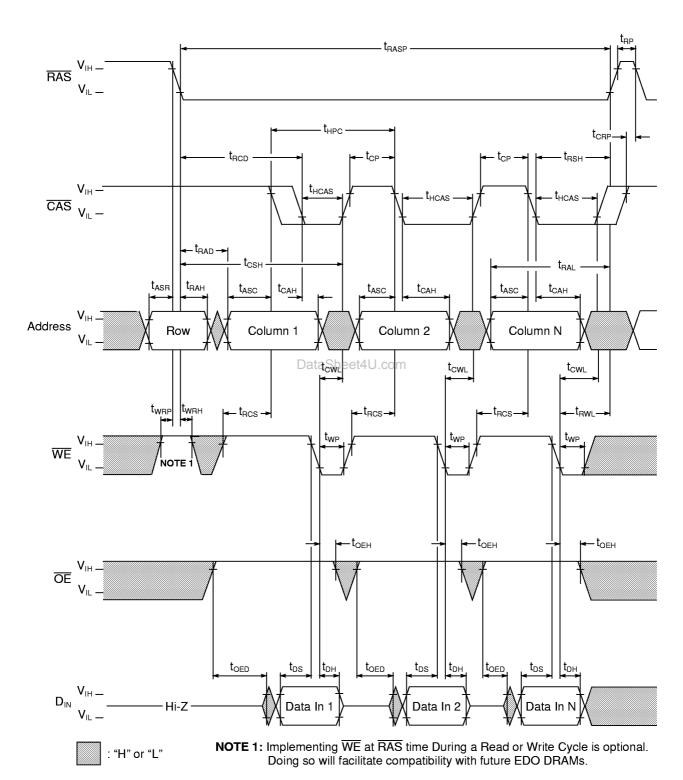
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## **EDO (Hyper Page) Mode Late Write Cycle**



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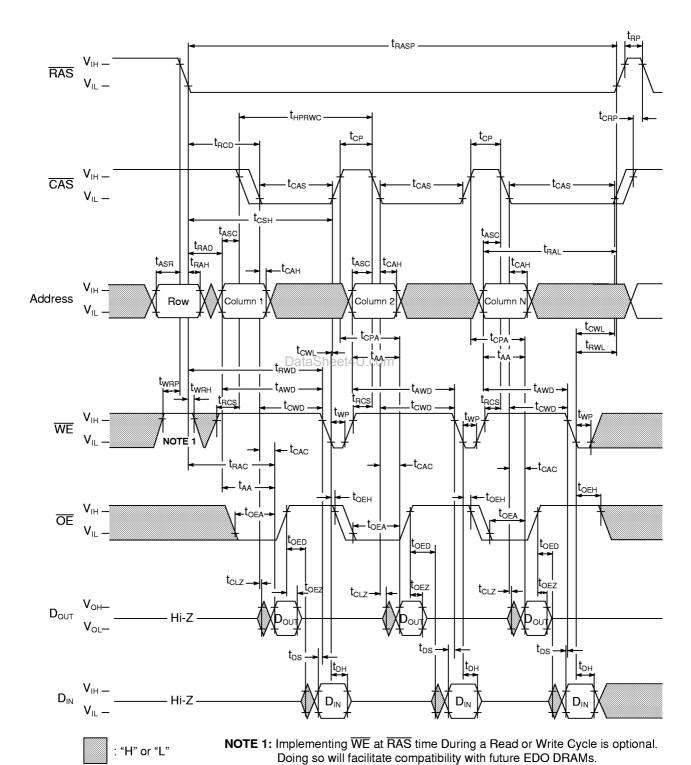
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## **EDO (Hyper Page) Mode Read Modify Write Cycle**



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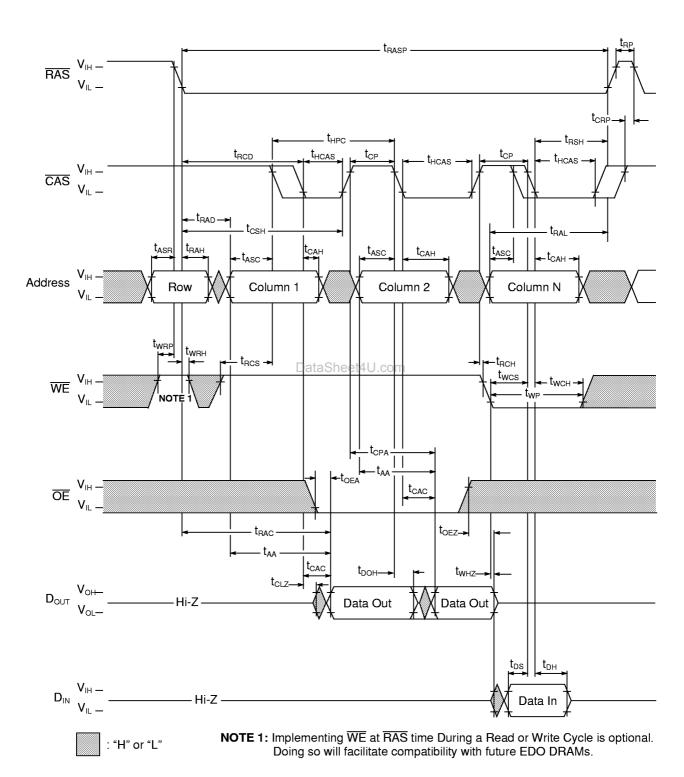
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## **EDO (Hyper Page) Mode Read and Write Cycle**



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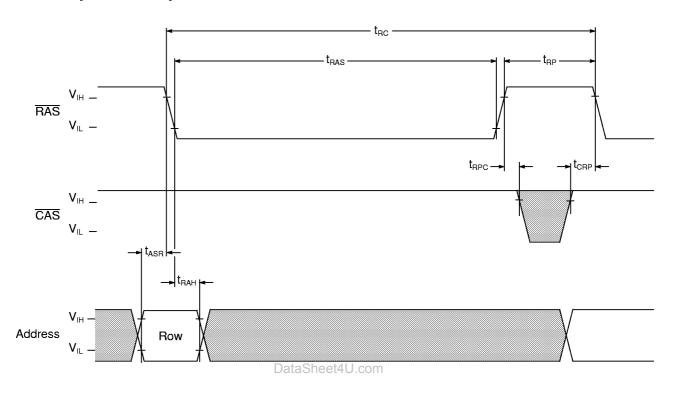
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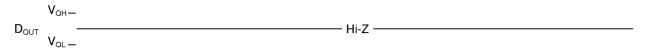
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# **RAS** Only Refresh Cycle



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: "H" or "L"

NOTE: WE, OE and DIN are "H" or "L"

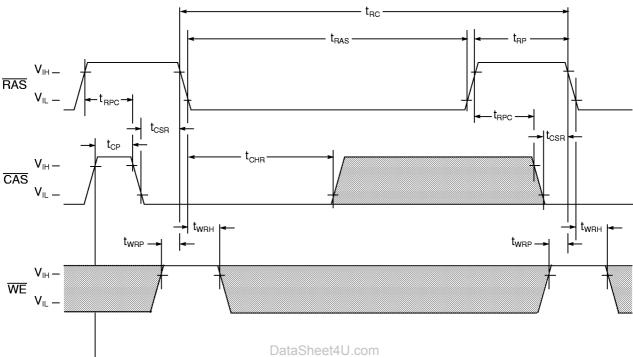
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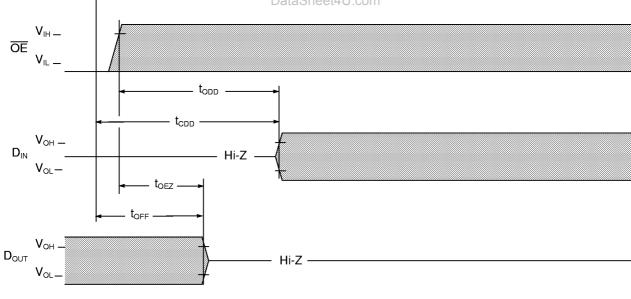


# **CAS** Before **RAS** Refresh Cycle



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NOTE: Address is "H" or "L"

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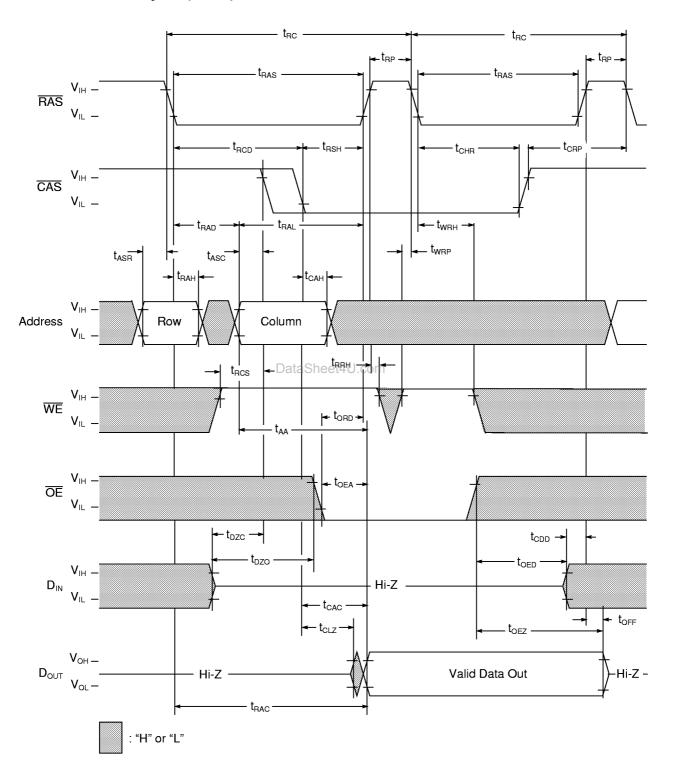
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# Hidden Refresh Cycle (Read)



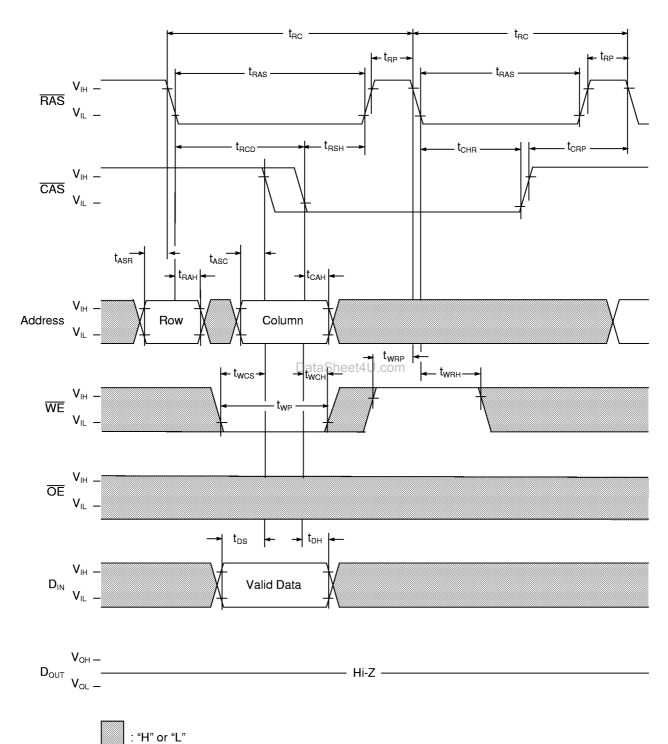
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# **Hidden Refresh Cycle (Write)**



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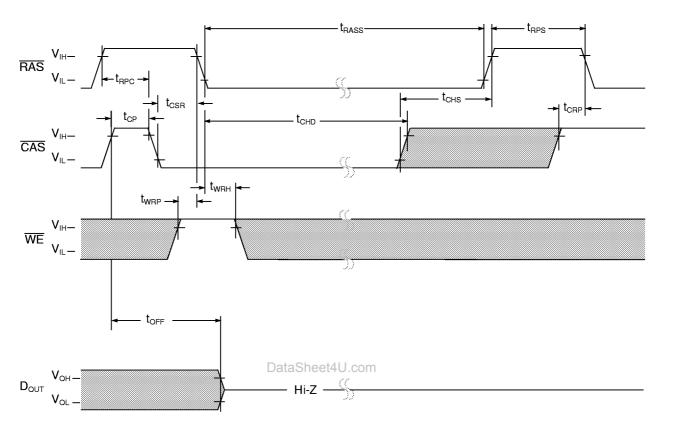
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#### Self Refresh Cycle (Sleep Mode) - Low Power version only



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# : "H" or "L"

#### NOTES:

- 1. Address and  $\overline{OE}$  are "H" or "L"
- 2. Once RAS (min) is provided and RAS remains low, the DRAM will be in Self Refresh, commonly known as "Sleep Mode."
- 3. If  $t_{RASS} > t_{CHD}$  (min) then  $t_{CHD}$  applies. If  $t_{RASS} \le t_{CHD}$  (min) then  $t_{CHS}$  applies.

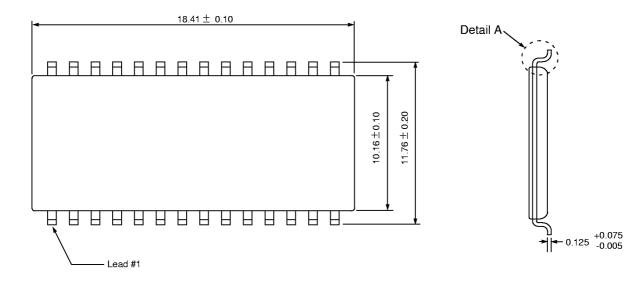
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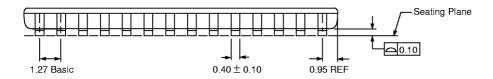
#### Package Dimensions (400 mil; 28/28 lead; Thin Small Outline Package)

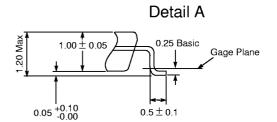


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NOTE: All dimensions are in millimeters; Package diagrams are not drawn to scale

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# **Revision Log**

Revision	Contents Of Modification
11/15/95	Initial Release
	<ol> <li>The Low Power and Standard Power Specifications were combined. ES# 43G9060 and ES# 28H4724 were combined into ES# 28H4724.</li> </ol>
	2. Added Die Rev E part numbers.
	3. A -6R speed sort was added, with the following differences over the -60 speed sort:
	- t <sub>CAC</sub> was increased from 15ns to 17ns for the -6R speed sort
	- t <sub>RCD</sub> (max) was decreased from 45ns to 43ns for the -6R speed sort.
12/10/95	<ul> <li>t<sub>CWD</sub> was increased from 34ns to 36ns for the -6R speed sort.</li> <li>t<sub>OEA</sub> was increased from 15ns to 17ns for the -6R speed sort.</li> </ul>
	4. t <sub>CHD</sub> was added to the Self Refresh Cycle with a value of 350µs for all speed sorts.
	<ol> <li>The Self Refresh timing diagram was changed to allow CAS to go high t<sub>CHD</sub> (350μs) after RAS falls entering Self Refresh.</li> </ol>
	6. The CBR timing diagram was changed to allow CAS to remain low for back-to-back CBR cycles.
	7. WE for the Hidden Refresh Write cycle in the Truth Table was changed from "L" to "H".
	1. I <sub>CC2</sub> was changed from 2mA to 1mA.
	2. I <sub>I(L)</sub> and I <sub>O(L)</sub> were altered from +/- 10uA to +/- 5uA.
	3. t <sub>RC</sub> was changed from 89ns to 84ns for the -50 speed sort.
	4. t <sub>CSH</sub> changed from 45ns to 38ns, 50ns to 45ns, and 55ns to 50ns for the -50, -60, and -70 speed sorts, respetively.
09/01/96	5. $t_T$ was initially at a max of 30ns. It has been modified to 50ns for all speed sorts.
	6. t <sub>CPA</sub> was decreased from 30ns to 28ns for the -50 speed sort.
	7. t <sub>RASP</sub> max of 125K was raised to 200K for all speed sorts.
	8. t <sub>OEP</sub> was changed from 10ns to 5ns for all speed sorts.
	9. t <sub>OEHC</sub> was also lowered from 10ns to 5ns for all speed sorts.
	10. t <sub>RP</sub> was changed from 35ns to 30ns for the -50 speed sort.

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