



# ICM532B CIF Color CMOS Image Sensor With USB Output

# Data Sheet V1.1 November, 2002

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# ICM532B CIF Color CMOS Sensor with USB Output Data Sheet, V 1.1 November, 2002

### **Features**

- CIF format (352x288) pixels, used with 1/7" optical system.
- QVGA format (320x240) pixels, used with 1/7" optical system
- QCIF format (176x144) pixels, cropped or subsampled, up to 37.5 fps.
- Progressive readout
- Output data format: compressed 8-bit raw data
- Image processing and decompression supported with proprietary software. Image processing functions
  include color interpolation, color correction, auto white balance, auto exposure, auto anti-flickering, and
  sharpening.
- Proprietary data compression
- Input/Output interface: USB 1.1 Full Speed
- Electronic exposure control
- On-chip 9-bit ADC
- Correlated double sampling
- Dead pixel and dead column removal
- Power down/Suspend mode
- 8 User Programmable GPIO pins
- Optional 3.3V Serial EEPROM register loading during power-up (24C02/04/08/16)
- Automatic optical black compensation
- Mirror image
- Single 3.3 V power supply

### **Key Parameters**

- Number of Active Pixels: up to 352x288
- Number of Physical Pixels: 362x298
- Frame Rate: up to 30 fps (35 fps QCIF)
- Pixel Size: 6.0 μm x 6.0 μm
- Sensor Area: 2.2 mm x 1.8 mm
- Single Crystal Frequency: 6 MHz
- Exposure Time: 125  $\mu$ s (@ 25 fps, 1 line)  $\sim$  8 s (@ 12 fps)
- Sensitivity: 1.0 V/lux-sec (555 nm)
- Quantum Efficiency: 38 % (555 nm)
- Dynamic Range: 53 dB (analog), 48 dB (digital)
- Fill Factor: 36%
- S/N Ratio: 45 dB @ 75% full signal level
- Sensitive to infrared illumination source
- Digital Gain:  $1 \sim 64 \text{ x}$  @  $2^{\text{N}}$  for all pixels
- RGB Gain:  $1/256 \sim 64$  x for individual Bayer pattern pixels
- Power Supply: 3.3 V
- Power consumption: 130mW typ.
- Packages: SPLCC48



# ICM532B CIF Color CMOS Sensor with USB Output Data Sheet, V 1.1 November, 2002

### **General Description**

ICM-532B is a single-chip, CIF resolution, digital color PC camera with integrated data compression, line buffer and Full Speed USB 1.1 interface. All the image processing functions (color interpolation, color correction, auto white balance, auto exposure, auto anti-flickering, sharpening) are performed by software in the host computer. It incorporates a 352x288 sensor array operating at  $6 \sim 30$  frames per second in progressive manner. Each pixel is covered by a color filter, which forms a "Bayer pattern." Correlated double sampling is performed by the internal ADC and timing circuitry. The raw data can be adjusted with digital gain. The raw data is compressed using a proprietary compression scheme. The compression allows video out in 8-bit compressed data format through USB 1.1 with 30 frames per second video capability. For higher frame-rates, sub-sampled or cropped QCIF (176x144) modes are available that support 35 frames per second.

8 Pins are supplied that can be programmed by the driver as general purpose I/O pins, with individually selectable output enables. During power-up, the internal control registers can be loaded from an external serial EEPROM. This allows customization of Vendor ID and Product ID, as well as initialization of other device parameters.

The 48 MHz clock required for the ICM-532B is provided by an on-chip phase-lock loop that is driven by an external 6 MHz crystal oscillator. Using a PLL reduces power dissipation, electrical noise and the cost of the crystal. It also reduces the need for EMI shielding that would be required if a 48 MHz oscillator were used. The highest frequency external signal is the 12Mbps on the differential USB data pins.

### **Software Support**

- Computer & OS requirements: 750 MHz, 64M memory for 30 fps; 300 MHz, 64M memory for 12 fps. Windows 98, Windows ME, Windows 2000 Macintosh OS 9.
- Driver support
  - WDM USB driver
  - TWAIN
  - DirectShow
  - VFW extension driver
  - Proprietary DirectShow decoder
  - Installation software

### **Applications**

- PC camera
- Embedded Solutions (Notebooks, LCD monitors)

### 1. Pin Assignments

Pin#	Name	Class	Function
36	DN	B,IO	USB D- connection
37	DP	B,IO	USB D+ connection
40	XIN	A,I	6 MHz Crystal Input
39	XOUT	A,O	6 MHz Crystal Output
3,5,34	Reserved	D,O	Leave Unconnected
44	Test	D, I, N	Leave Unconnected
2	Clock_S	D, IO	Serial clock, for external serial EEPROM
1	Data_S	D, IO	Serial data, for external serial EEPROM
16	RSET	A,I	Resistor to Ground = 75 KΩ
8	RSTN	D,SI,U	Chip Reset, active low
15	RAMP	A,O	Analog Test Output
46	GPIO 0	D,IO	User Programmable I/O, Requires External Pull-up
47	GPIO 1	D,IO	User Programmable I/O, Requires External Resistor
48	GPIO 2	D,IO	User Programmable I/O, Requires External Pull-up
10	GPIO 3	D,IO	User Programmable I/O
11	GPIO 4	D,IO	User Programmable I/O
12	GPIO 5	D,IO	User Programmable I/O
13	GPIO 6	D,IO	User Programmable I/O
14	GPIO 7	D,IO	User Programmable I/O
7,27,31	VDDA	P	Sensor & PLL Analog Power
9,28,30	GNDA	P	Sensor & PLL Analog Ground
19	VDDD	P	Sensor Digital Power
17	GNDD	P	Sensor Digital Ground
4,26,33,	VDDK	P	Digital Power
38,41,43			
6,29,32,	GNDK	P	Digital Ground
35,42,45			
18	GNDS	P	Substrate Ground

Class Code: A – Analog signal, D – Digital signal, I – Input, SI – Schmitt Input, O – Output, IO – Bidirectional, P – Power or ground, U – Internal pull-up, N – Internal pull-down, B – USB Pad

### 2. Functional Description

ICM-532B is a single-chip USB digital color imaging device. It includes a 352x288 sensor array, 352 column–level ADC, and correlated double sampling circuitry. All the programmable parameters are set by writing through the USB interface which can address the register file consisting of 8-bit registers. The internal CIF image sensor is based upon the ICM-102B. The output format is USB 1.1 compatible www. Datacompressed video data using a single ISOCHRONOUS channel. Dead pixels and dead columns are

removed, to generate a high quality image.

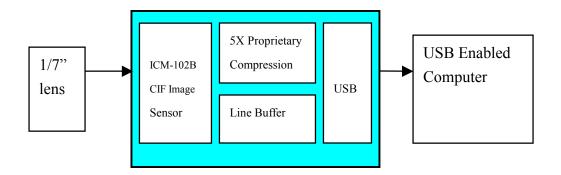


Figure 1. Block Diagram

### 2.1. Image Array

The image array consists of 352x288 pixels. Each pixel has a light sensitive photo diode and a set of control and transfer transistors. At the beginning of the cycle, a row of pixels is pre-charged to its maximum value. Then they are exposed to light for several lines worth of time and sampled by the ADC. Correlated double sampling (CDS) is performed by subtracting the reset value (sampled right before sampling the signal) from the signal value. The purpose of CDS is to eliminate the point-wise fixed pattern noise (FPN). The output of CDS is approximately proportional to the amount of received light, ranging from 0 to 255.

### 2.2. Color Filter

Each pixel is covered by a color filter. They form the Bayer Pattern as shown in Figure 2. (Row 0, Column 0) is covered by a Red filter, (Row 0, Column 1) and (Row 1, Column 0) by Green filters, and (Row 1, Column 1) by a Blue filter. Since each pixel only gets part of the frequency band, the data needs further processing (i.e., color interpolation and color correction) in order to approximate the full visible spectrum.



Figure 2. Color filter Bayer pattern

### 2.3. Exposure and Gain Control

The brightness of the scene may change by a great amount that renders the captured image either

over-exposed or under-exposed. To accommodate for different brightness, the user may change the exposure time or digital gain by adjusting the AD\_EXPOSE\_TIMEH and AD\_EXPOSE\_TIMEL. The exposure time is measured in terms of the time to read out one line of data, which is equal to 125 us (assuming the line length is 500). If the number of lines per frame is set at 320 (the default), the exposure time can vary from 1 to 319 lines. In addition, the user can adjust bit 7 to 5 of register AD\_EXPOSE\_TIMEH to digitally boost the output value by 1 to 64 times @ 2N for all pixels. Furthermore, users can adjust registers AD\_M1\_L, AD\_M1\_H, AD\_M2\_L, AD\_M2\_H, AD\_M3\_L, AD\_M3\_H, AD\_M4\_L, AD\_M4\_H, to optimize the RGB gain (from 1/256 to 64) of the 4 Bayer pattern pixels separately.

### 2.4. Output Format

During normal operation, the output format is 8-bit compressed data that ranges from 0 to 255. This data is transmitted with a USB Transceiver using Isochronous packets. The video quality is related to the size of the packets, with 1023 bytes/packet generating the highest quality image. The packets are received, decompressed, and color processed by a host PC. A typical configuration is to connect ICM-532B to a USB enabled PC. When operated at 24 fps CIF, the USB clock is 48 MHz and the Video data clock is 4MHz. When operated at 30 fp, the Video data clock is 6MHz. The line and frame timing can be adjusted through registers AD WIDTH and AD HEIGHT.

### 3. Control Registers

Registers may be configured using either the USB Command/Control Channel, or the Serial interface. The result is unpredictable if both interfaces are used simultaneously. USB access should be made using a Standard Vendor Type Device Request. For a write, if the Length field value is 0, the two bytes in the Value field are written into two registers starting at the Index field value. For all other Length field values, the data stage transfers the requested number of bytes starting from the Index field value. The data transfer Length must not be larger than 8 bytes.

The 7-bit Serial ICM-532B device address is 0x21. ICM-532B can operate in either Serial master mode or slave mode right after power up, depending on the pull-up or pull-down of the GPIO[1] pin. When GPIO[1] is pulled low during power-up, ICM-102B's Serial interface is operated as a slave device,

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during power-up, the Serial interface will first act as a master device, trying to read from an external EEPROM (24C02/04/08/16). The first word read will indicate the number of bytes to transfer from the external EEPROM. After transferring these bytes, or failing to access an external device, the ICM-532B will behave like a slave device. The external EEPROM is addressed at address 0x50, and must be 3.3v compatible.

Address	Name	Default	Description
0:00h	PART_CONTROL	0	Processing control
	_		[0] 0: normal mode
			[1] Slope adjustment enable
			[2] Exposure time control, writing a 1 will activate
			the new value set in AD EXPOSE TIME, when
			read back from it, 0 means the exposure time
			change is finished, 1 means the exposure time
			change is still in progress.
			[6:3] Reserved
			[7] Latent change, writing a 1 means the changed
			latent registers now starts taking effect, when the
			entire operation is done, the read back value of this
			bit will change from 1 to 0.
1:01h	TIMING CONTROL LOW	17	Timing control
2:02h	TIMING CONTROL HIGH	0x0011	[0] Column count enable, set to 0 when filling wave
			table, set to 1 when normal operation
			[3] Auto dark correction enable
			[4] Timing select, 0: wave table timing, 1: default
			timing
			[8] IRST select, 0: from wave table, 1: from
			IRST NUMBER register
			[11] Dead column removal mode, 0: color, 1:
			black-and-white
			[12] Out-of-array exposure pointer control, 0: point
			to row 295, 1: point to row 298 (a non-existent row)
			[13] Column stop, 0: sensor column counter stop at
			361 when exceeding real array, 1: sensor column
			counter keeps counting
7:07h	TABLE_LEN	0	Reserved
12:0Ch	AD_WIDTHL	500	[9:0] Frame width
13:0Dh	AD_WIDTHH	0x01F4	
14:0Eh	AD_HEIGHTL	400	[15:0] Frame height, should not be less than
15:0Fh	AD_HEIGHTH	0x0190	AD_ROW_BEGIN + 298
16:10h	AD_COL_BEGINL	180	[9:0] Beginning of active line in terms of column
17:11h	AD_COL_BEGINH	0x00B4	position
			[10] Mirror image enable
			[15:13] Digital gain
			0: 1
			1: 2
			2: 4
- 01- 141			3: 8
aSheet4l	J.com		4: 16
			5: 32

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			6: 64
20:14h	AD ROW BEGINL	10	[15:0] Beginning of active frame in terms of row
20:14h 21:15h	AD_ROW_BEGINH	0x000A	position
24:18h	AD HSYNC ENDL	64	[9:0] End of horizontal sync in terms of column
25:19h	AD_HSYNC_ENDH	0x0040	position
26:1Ah	AD VSYNC ENDL	3	[15:0] End of vertical sync in terms of row position
27:1Bh	AD_VSTNC_ENDE AD_VSYNC_ENDH	0x0003	[13.0] End of vertical sync in terms of fow position
28:1Ch	AD EXPOSE TIMEL	524	[15:0] Exposure time in terms of number of rows
29:1Dh	AD EXPOSE TIMEH	0x020C	[13.0] Exposure time in terms of number of rows
32:20h	AD M1 L	256	[10:0] Gain coefficient (G1), in unsigned $3.8 \sim 6.5$
33:21h	AD M1 H	0x100	format (Selected by register 52)
34:22h	AD M2 L	256	[10:0] Gain coefficient (R), in unsigned $3.8 \sim 6.5$
35:23h	AD M2 H	0x100	format (Selected by register 52)
36:24h	AD M3 L	256	[10:0] Gain coefficient (B), in unsigned $3.8 \sim 6.5$
37:25h	AD M3 H	0x100	format (Selected by register 52)
38:26h	AD M4 L	256	[10:0] Gain coefficient (G2), in unsigned $3.8 \sim 6.5$
39:27h	AD M4 H	0x100	format (Selected by register 52)
82:52h	AD INOUTSEL	0	[4:0] Output format
	_		0-7, 12-31: 8-bit raw data, with
			0: RGB gain format = 3.8
			1: RGB gain format = 4.7
			2: RGB gain format = 5.6
			3-7, 12-31: RGB gain format = 6.5
			8: control signals
			9: row address
			10: column address
			11: sensor raw data
110:6Eh	AD_DEAD0L	1023	[9:0] Dead column #0 in terms of real sensor array
111:6Fh	AD_DEAD0H	0x03FF	
112:70h	AD_DEAD1L	1023	[9:0] Dead column #1 in terms of real sensor array
113:71h	AD_DEAD1H	0x03FF	
114:72h	AD_DEAD2L	1023	[9:0] Dead column #2 in terms of real sensor array
115:73h	AD_DEAD2H	0x03FF	50 07 70 1 1 1 1/2 1
116:74h	AD_DEAD3L	1023	[9:0] Dead column #3 in terms of real sensor array
117:75h	AD_DEAD3H	0x03FF	[0.0] D. 1. 1. //A.: 4
118:76h	AD_DEAD4H	1023	[9:0] Dead column #4 in terms of real sensor array
119:77h 120:78h	AD_DEADSI	0x03FF	[0.0] Dood column #5 in terms of real concern armon
120.78h 121:79h	AD_DEAD5L AD_DEAD5H	1023 0x03FF	[9:0] Dead column #5 in terms of real sensor array
121.79h 122:7Ah	AD_DEAD3H AD_DEAD6L	1023	[9:0] Dead column #6 in terms of real sensor array
122.7An 123:7Bh	AD_DEAD6L AD_DEAD6H	0x03FF	[5.0] Dead Column #0 in terms of real sensor array
123.7Bh 124:7Ch	AD_DEAD011 AD_DEAD7L	1023	[9:0] Dead column #7 in terms of real sensor array
125:7Dh	AD_DEAD7E AD_DEAD7H	0x03FF	[9.0] Dead column #7 in terms of real sensor array
126:7Eh	AD DEAD8L	1023	[9:0] Dead column #8 in terms of real sensor array
127:7Fh	AD DEAD8H	0x03FF	[7.0] Dead column no in terms of real sensor array
128:80h	AD DEAD9L	1023	[9:0] Dead column #9 in terms of real sensor array
129:81h	AD_DEAD9H	0x03FF	[5.0] Sead cording #5 in terms of real sensor diray
130:82h	AD IDL	54048	[15:4] Device ID, can be programmed
131:83h	AD_IDH	0xD320	[10.1] Device 1D, can be programmed
144:90h	AD_DARK_DATA	0	[7:0] When auto dark correction is disabled, serve
111.5011			as the subtrahend for dark correction
www.Data49:95h141	AD SLOPE END TIMEL	341	[9:0] When auto slope adjustment is turned on, if



150:96h	AD SLOPE END TIMEH	0x0155	the slope counter exceeds this value, the ramp will
			become steeper
151:97h	AD WT BEGINL	0	Reserved
152:98h	AD_WT_BEGINH		
153:99h	AD_WT_ENDL	1020	Reserved
154:9Ah	AD_WT_ENDH	0x03FC	
155:9Bh	AD_SUB_EN_TIMEL	474	[9:0] Column position where the CDS subtraction
156:9Ch	AD_SUB_EN_TIMEH	0x01DA	pulse is applied
161:A1h	AD_WIDTHL_C	500	Reserved
162:A2h	AD_WIDTHH_C	0x01F4	
163:A3h	AD_HEIGHTL_C	400	Reserved
164:A4h	AD_HEIGHTH_C	0x0190	
165:A5h	AD_COL_BEGINL_C	100	Reserved
166:A6h	AD_COL_BEGINH_C	0x0064	
167:A7h	AD_ROW_BEGINL_C	10	Reserved
168:A8h	AD_ROW_BEGINH_C	0x000A	
169:A9h	AD_HSYNC_ENDL_C	64	Reserved
170:AAh	AD_HSYNC_ENDH_C	0x0040	
171:ABh	AD_VSYNC_ENDL_C	3	Reserved
172:ACh	AD_VSYNC_ENDH_C	0x0003	
173:ADh	AD_PART_CONTROL_C	6	Reserved
		0x06	
174:AEh	AD_WT_BEGINL_C	0	Reserved
175:AFh	AD_WT_BEGINH_C		
176:B0h	AD_WT_ENDL_C	1020	Reserved
177:B1h	AD_WT_ENDH_C	0x03FC	

\*These registers are updated at the next falling edge of VSYNC after register UPD is set. The occurrence of the update is marked in the video output by clearing bit 7 of the packet header. i.e. 80
 => 00. This bit remains set until register UPD is cleared.

### 4. GPIO

### 4.1. General Purpose I/O pins

There are 8 pins that can be programmed by the user as general purpose Input/Output pins. Three of the pins are required to have pull-up or pull-down resistors attached to select device functionality at the rising edge of NRST.

### 1. Special Purpose:

GPIO[0] Pull-up.

It is possible to configure this output as an active low power-down pin, driven by the USB controller Suspend signal. When so configured, all external power except pins 4, 33, and 43 may be removed while this pin is driven low.

www.DataShee It is also possible to configure this output as an active low power-on pin, connected to an external LED. When so configured, an external LED with 8ma current limiting resistor will be on ©2000, 2001,2002 IC Media Corporation & IC Media Technology Corp 11/21/2002

unless the device is in Suspend state.

### GPIO[1] Pull-up.

To enable external Serial EEPROM for register loads, Pull-down to disable this feature.

### GPIO[2] Pull-up.

To select crystal oscillator clock source. Required condition

### 2. General Purpose:

The other 5 GPIO pins have no Pull-up/Pull-down requirements. All of these pins default to inputs at device reset. If the pins are to remain unused, an external pull-up is recommended to prevent the inputs from floating.

To use an external switch, use a pull-up, and connect the switch between the GPIO pin and ground, and poll the selected pin in register 58. The pull-up will return a high value, and a switch event will return a low value.

### 5. Programming

### 5.1. Special considerations

There are several registers that need to be correctly programmed for device operation. If custom Vendor ID/Product ID values are required, these registers should be programmed by an external Serial EEPROM before the USB controller accesses the part<sup>1</sup>. It is recommended that the Vendor ID and Product ID registers be programmed first. This allows the correct values to be set before the USB configuration after power-up. After that, the driver can look for a specific register value to indicate the end of Serial programming. During the initialization phase, if an external EEPROM is used, care must be taken by the driver to not accesses registers while the EEPROM is transferring data. The driver software should delay an appropriate time before accessing the registers.

### Expansion RAM:

To access the internal 256Byte expansion RAM, load the RAA register with the desired address, and read or write the RAD register.

### **Device Programming:**

The maximum size of a USB data transfer is 8 bytes. Transfers larger than this will not read/write the correct data values.

### 6. Electrical Characteristics

### **6.1. DC Characteristics**

## 1. Absolute Maximum Ratings

Symbol	Parameter		Units		
Symbol	rarameter	Minimum	Typical	Maximum	Units
$V_{CCA}$	Absolute Power Supply	-0.3		3.8	V
V <sub>INA</sub>	Absolute Input Voltage	-0.3		$V_{CC} + 0.3$	V
V <sub>OUTA</sub>	Absolute Output Voltage	-0.3		$V_{CC} + 0.3$	V
$T_{STG}$	Storage Temperature	0	25	65	°C

# 2. Recommended Operating Conditions

Symbol	Danamatan		Units		
Symbol	Parameter	Minimum	Typical	Maximum	Units
V <sub>CC</sub>	Operating Power Supply	3.0	3.3	3.6	V
$V_{IN}$	Operating Input Voltage	0		$V_{CC}$	V
$T_{OPR}$	Operating Temperature	0	25	55	°C

### 3. General DC Characteristics

	Cymbol	Parameter		Rating		Units
	Symbol	rarameter	Minimum	Typical	Maximum	Units
	$I_{DD}$	Operating		40		mA
		Current @				
		$V_{CC}=3.3 \text{ V}, 25$				
		°C				
	$I_{DDS}$	Suspend			500	uA
		Current @				
		$V_{CC}=3.3 \text{ V}, 25$				
		°C				
	$ m I_{IL}$	Input Low	-1		1	μΑ
_		Current				•
	$I_{ m IH}$	Input High	-1		1	μA
_		Current				•
	$I_{OZ}$	Tri-state	-10		10	μΑ
		Leakage				•
_		Current				
	$C_{IN}$	Input		3		pF
		Capacitance				•
www.Dat	aCouret4U.co	Output		3		pF
		Capacitance				-

$C_{BID}$	Bi-directional Buffer Capacitance		3		pF
R <sub>O</sub>	USB Output Impedance	6		18	Ω
$R_{ m L}$	Input Pull-up/down Resistance		50		ΚΩ

### 4. Electrical DC Characteristics

Symbol	Parameter	Rating			Units
		Minimum	Typical	Maximum	
$V_{CC}$	Operating Power Supply	3.0	3.3	3.6	V
$V_{\mathrm{OH}}$	Output High Voltage	2.4			V
$V_{\mathrm{UL}}$	USB Output Low Voltage			0.3	V
$V_{\mathrm{UH}}$	USB Output High Voltage	2.8			V

### 6.2. Clocking

The ICM-532B clock is generated from an external low cost 6MHz crystal. The on-board PLL generates the required USB clock and the Video Clock. The nominal Video Clock rate is 8MHz. This rate can be altered by setting either the Fastclock (\*1.5) or Slowclock (/2.0) register bits.

Video Timing examples:

At 8MHz, the Video clock generates 1 pixel every 250ns, a line (500 pixels) every 125us, and 8 lines every 1ms. This produces 8 lines to be packed into 1 USB data transfer, to make a 24 fps QVGA (352 x288) transfer rate.

At 12MHz, the Video clock generates 1 pixel every 166.7ns, a line (600 pixels) every 100us, and 10 lines every 1 ms. This produces 10 lines to be packed into 1 USB data transfer, to make a 30 fps QVGA (320x240) transfer rate.

At 12MHz, the Video clock generates 1 pixel every 166.7ns, a line (500 pixels) every 83.3us, and 12 lines every 1 ms. This produces 6 lines to be packed into 1 USB data transfer, to make a 35 fps QCIF (176 x 144) transfer rate.

### 6.3. AC Characteristics

Symbol	Parameter	Rating			Units
		Minimum	Typical	Maximum	
T <sub>RISE/FALL</sub>	USB Switching Times	4	10	20	ns
$V_{CR}$	USB Cross Point	1.3		2.0	V

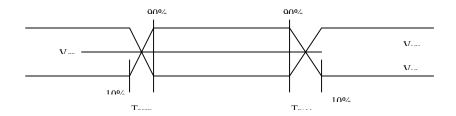


Figure 3. DP/DN Timing

### 7. Mechanical Information

ICM532B supports SPLCC (Plastic Shrunk LCC48 Packaging) packaging. Note that pin 1 should point to the top of the camera when a lens and the default driver are used.

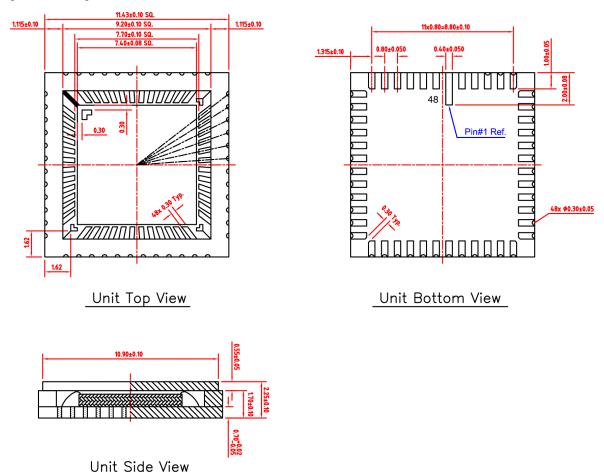


Figure 4. SPLCC48 Packaging

### 8. Board Design Information

Components:

- ICM-532B
- 6MHz Crystal
- RSET resistor
- USB connector or cable with 1.5kΩ pull-up on DP.
- 3.3v voltage regulator and associated components
- Power Supply filter capacitors

WWW.DataSheet Pull-up for SDA, SCL, GPIO0 GPIO1, and GPIO2

• If desired: Reset circuitry. A 0.1uF capacitor on RSTN is sufficient for power-on reset.

### 9. Ordering Information

Part number for different package:

Description	Part Number
Shrunk Plastic LCC48 package packaged, USB CIF resolution sensor (3.3 V)	ICM-532Bsa

### Contact Addresses:

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