

# **DDR Phase Lock Loop Zero Delay Clock Buffer**

#### **Recommended Application:**

DDR Zero Delay Clock Buffer

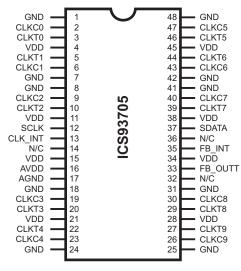
#### **Product Description/Features:**

- Low skew, low jitter PLL clock driver
- I<sup>2</sup>C for functional and output control
- Feedback pins for input to output synchronization
- · Spread Spectrum tolerant inputs
- 3.3V tolerant CLK\_INT input

### **Switching Characteristics:**

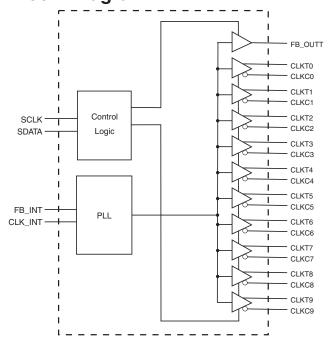
- PEAK PEAK jitter (66MHz): <120ps</li>
- PEAK PEAK jitter (>100MHz): <75ps</li>
- CYCLE CYCLE jitter (66MHz):<120ps</li>
- CYCLE CYCLE jitter (>100MHz):<65ps
- OUTPUT OUTPUT skew: <100ps
- Output Rise and Fall Time: 450ps 950ps
- DUTY CYCLE: 49% 51%

### **Pin Configuration**



48-Pin SSOP

## **Block Diagram**



## **Functionality**

II.	IPUTS		OUTP	PLL State		
AVDD	CLK_INT	CLKT	CLKC	FB_OUTT	PLL State	
2.5V (nom)	L	L	Н	L	on	
2.5V (nom)	Н	Н	L	Н	on	
2.5V (nom)	<20MHz <sup>(1)</sup>	Z	Z	Z	off	
GND	L	L	Н	L	Bypassed/off	
GND	Н	Н	L	Н	Bypassed/off	

0418D-04/28/05



# **Pin Descriptions**

PIN NUMBER	PIN NAME	TYPE	DESCRIPTION
1, 7, 8, 18, 24, 25, 31, 41, 42, 48	GND	PWR	Ground
26, 30, 40, 43, 47, 23, 19, 9, 6, 2	CLKC(9:0)	OUT	"Complementary" clocks of differential pair outputs.
27, 29, 39, 44, 46, 22, 20, 10, 5, 3	CLKT(9:0)	OUT	"True" Clock of differential pair outputs.
4, 11, 15, 21, 28, 34, 38, 45,	VDD	PWR	Power supply 2.5V
12	SCLK	IN	Clock input of I <sup>2</sup> C input, 5V tolerant input
13	CLK_INT	IN	"True" reference clock input, 3.3V tolerant input
14, 32, 36	N/C	-	Not connected
16	AVDD	PWR	Analog power supply, 2.5V
17	AGND	PWR	Analog ground.
33	FB_OUTT	OUT	"True" Feedback output, dedicated for external feedback. It switches at the same frequency as the CLK. This output must be wired to FB_INT.
35	FB_INT	IN	"True" Feedback input, provides feedback signal to the internal PLL for synchronization with CLK_INT to eliminate phase error.
37	SDATA	I/O	Data pin for I <sup>2</sup> C circuitry 5V tolerant

Byte 0: Output Control (1= enable, 0 = disable)

BIT	PIN#	PWD	DESCRIPTION
Bit 7	-	1	Reserved
Bit 6	-	1	Reserved
Bit 5	-	1	Reserved
Bit 4	-	1	Reserved
Bit 3	-	1	Reserved
Bit 2	-	1	Reserved
Bit 1	-	1	Reserved
Bit 0	-	1	Reserved

Byte 1: Output Control (1= enable, 0 = disable)

BIT	PIN#	PWD	DESCRIPTION
Bit 7	-	1	Reserved
Bit 6	-	1	Reserved
Bit 5	-	1	Reserved
Bit 4	-	1	Reserved
Bit 3	-	1	Reserved
Bit 2	-	1	Reserved
Bit 1	-	1	Reserved
Bit 0	-	1	Reserved

# RENESAS

Byte 2: Reserved (1= enable, 0 = disable)

BIT	PIN#	PWD	DESCRIPTION
Bit 7	ı	1	Reserved
Bit 6	-	1	Reserved
Bit 5	-	1	Reserved
Bit 4	-	1	Reserved
Bit 3	-	1	Reserved
Bit 2	-	1	Reserved
Bit 1	-	1	Reserved
Bit 0	-	1	Reserved

Byte 3: Reserved (1= enable, 0 = disable)

BIT	PIN#	PWD	DESCRIPTION
Bit 7	-	1	Reserved
Bit 6	-	1	Reserved
Bit 5	-	1	Reserved
Bit 4	-	1	Reserved
Bit 3	-	1	Reserved
Bit 2	-	1	Reserved
Bit 1	-	1	Reserved
Bit 0	-	1	Reserved

Byte 4: Reserved (1= enable, 0 = disable)

PIN#	PWD	DESCRIPTION				
-	1	Reserved				
-	1	Reserved				
-	1	Reserved				
-	1	Reserved				
-	1	Reserved				
-	1	Reserved				
-	1	Reserved				
-	1	Reserved				
	PIN#	PIN# PWD - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1				

Byte 5: Reserved (1= enable, 0 = disable)

BIT	PIN#	PWD	DESCRIPTION
Bit7	3,2	1	CLK0 (T&C)
Bit6	-	1	-
Bit5	10, 9	1	CLK2 (T&C)
Bit4	20, 19	1	CLK3 (T&C)
Bit3	22, 23	1	CLK4 (T&C)
Bit2	27, 26	1	CLK9 (T&C)
Bit1	-	1	Reserved
Bit0	-	1	Reserved

Byte 6: Reserved (1= enable, 0 = disable)

BIT	PIN#	PWD	DESCRIPTION
Bit7	-	0	Reserved (Note)
Bit6	- 0		Reserved (Note)
Bit5	-	0	Reserved (Note)
Bit4	29, 30	1	CLK8 (T&C)
Bit3	39, 40	1	CLK7 (T&C)
Bit2	44, 43	1	CLK6 (T&C)
Bit1	46, 47	1	CLK5 (T&C)
Bit0	-	1	Reserved

Note: Don't write into these registers (7:5), writing into these registers can cause malfunction.



### **Absolute Maximum Ratings**

Supply Voltage (VDD & AVDD).....--0.5V to 3.6V

Logic Inputs . . . . . . . . . . . . . GND -0.5 V to  $V_{DD}$  +0.5 V

Ambient Operating Temperature . . . . . . .  $0^{\circ}$ C to  $+85^{\circ}$ C Storage Temperature . . . . . . . . . .  $-65^{\circ}$ C to  $+150^{\circ}$ C

Stresses above those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These ratings are stress specifications only and functional operation of the device at these or any other conditions above those listed in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect product reliability.

### **Electrical Characteristics - Input / Supply / Common Output Parameters**

 $T_A = 0 - 70^{\circ}C$ ; Supply Voltage  $V_{DD} = 2.5 V + -0.2 V$  (unless otherwise stated)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input High Current	I <sub>IH</sub>	$V_I = V_{DD}$ or GND				μΑ
Input Low Current	I <sub>IL</sub>	$V_I = V_{DD}$ or GND				μА
Operating Cumply Current	I <sub>DD2.5</sub>	C <sub>L</sub> = 0 pF at 133 MHz		245	300	mA
Operating Supply Current	I <sub>DDPD</sub>	$C_L = 0 pF$			100	μА
Output High Current	I <sub>OH</sub>	$V_{DD} = 2.3V$ , $V_{OUT} = 1V$		-43	-18	mA
Output High Current	I <sub>OL</sub>	$V_{DD} = 2.3V, V_{OUT} = 1.2V$	26	43		mA
High Impedance Output Current	I <sub>OZ</sub>	$V_{DD} = 2.7V$ , $V_{OUT} = V_{DD}$ or GND			10	μА
Input Clamp Voltage	V <sub>IK</sub>	lin = -18 mA;				V
Lligh lovel Output Voltage	V	$V_{DD}$ = min to max, $I_{OH}$ = -1mA	2.1	2.42		V
High-level Output Voltage	$V_{OH}$	$V_{DD} = 2.3V, I_{OH} = -12mA$		1.87		V
Low lovel Output Voltage	V <sub>OL</sub>	$V_{DD}$ = min to max, $I_{OH}$ = 1mA		0.04	0.1	V
Low-level Output Voltage		$V_{DD} = 2.3V, I_{OH} = 12mA$		0.35	0.6	V
Input Capacitance <sup>1</sup>	C <sub>IN</sub>	$V_I = V_{DD}$ or GND				pF
Output Capacitance <sup>1</sup>	C <sub>OUT</sub>	$V_I = V_{DD}$ or GND		3		pF

<sup>&</sup>lt;sup>1</sup> Guaranteed by design, not 100% tested in production.



### **Recommended Operating Condition**

T<sub>A</sub> = 0 - 70°C; Supply Voltage AVDD, VDD = 2.5 V +/- 0.2V (unless otherwise stated)

7 117	3	<u>′</u>	1		,	
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Analog/core supply voltage	V <sub>DD</sub> , A <sub>VDD</sub>		2.3	2.5	2.7	\ \
loon to valtage lavel	$V_{IL}$		-		VDD/2 - 0.5V	V
Input voltage level	V <sub>IH</sub>		VDD/2 + 0.5V		-	٧
Input duty cycle	I <sub>DC</sub>		40		60	%
Input max jitter	I <sub>TCYC</sub>			-	500	ps

### **Timing Requirements**

 $T_A = 0 - 70C$ ; Supply Voltage AV<sub>DD</sub>,  $V_{DD} = 2.5 \text{ V} + /-0.2 \text{V}$  (unless otherwise stated)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Operating Clock Frequency <sup>1</sup>	freq <sub>op</sub>		66		170	MHz
Input Clock Duty Cycle <sup>1</sup>	$d_{tin}$		40		60	%
Clock Stabilization <sup>1</sup>	t <sub>STAB</sub>	from $V_{DD} = 2.5 V$ to 1% target frequency			100	μs

<sup>1.</sup> Guaranteed by design, not 100% tested in production.

### **Switching Characteristics**

 $T_A = 0 - 70C$ ; Supply Voltage  $V_{DD} = 2.5 \text{ V} + /-0.2 \text{V}$  (unless otherwise stated)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Absolute Jitter <sup>1</sup>	$t_{ m jabs}$	66 MHz			120	no
		100 / 125 / 133 / 167 MHz			75	ps
Cycle to cycle Jitter <sup>1,2</sup>	t <sub>c-c</sub>	66 MHz		50	110	no
		100 / 125 / 133 / 167 MHz		35	65	ps
Phase Error <sup>1</sup>	t <sub>pe</sub>	with input clock 0-2.5V 0.8ns rise/fall	-150	50	150	ps
Output to output Skew <sup>1</sup>	$T_{skew}$	with input clock 0-2.5V 0.8ns rise/fall		40	100	ps
Low-to-high level Propagation Delay Time, Bypass Mode <sup>1</sup>	t <sub>PLH</sub>	CLK_IN to any output, Load = 120W / 12 pF	4	4.5	6	ns
Pulse Skew <sup>1</sup>	$T_{skewp}$				100	ps
Duty Cycle (differential) <sup>1,3</sup>	$D_{C}$	no loads, 66 MHz to 167 MHz	49	50	51	%
Rise Time, Fall Time <sup>1</sup>	$t_R, t_F$	Single-ended 20 - 80 %; Load = $120\Omega / 12 \text{ pF}$	450	550	950	ps

- 1. Guaranteed by design, not 100% tested in production.
- 2. Refers to transistion on non-inverting period.
- 3. While the pulse skew is almost constant over frequency, the duty cycle error increases at higher frequencies. This is due to the formula: duty cycle =  $t_{wH}/t_C$ , where the cycle time ( $t_C$ ) decreases as the frequency increases.



### General I<sup>2</sup>C serial interface information

The information in this section assumes familiarity with  $I^2C$  programming. For more information, contact ICS for an  $I^2C$  programming application note.

### **How to Write:**

- Controller (host) sends a start bit.
- Controller (host) sends the write address D4 (H)
- ICS clock will *acknowledge*
- Controller (host) sends a dummy command code
- ICS clock will acknowledge
- Controller (host) sends a dummy byte count
- ICS clock will acknowledge
- Controller (host) starts sending first byte (Byte 0) through byte 6
- ICS clock will acknowledge each byte one at a time.
- Controller (host) sends a Stop bit

How to Write:				
Controller (Host)	ICS (Slave/Receiver)			
Start Bit				
Address				
D4 <sub>(H)</sub>				
	ACK			
Dummy Command Code				
	ACK			
Dummy Byte Count				
	ACK			
Byte 0				
	ACK			
Byte 1				
	ACK			
Byte 2				
	ACK			
Byte 3				
	ACK			
Byte 4				
	ACK			
Byte 5				
	ACK			
Byte 6				
	ACK			
Stop Bit				

### How to Read:

- Controller (host) will send start bit.
- Controller (host) sends the read address D5 (H)
- ICS clock will acknowledge
- ICS clock will send the *byte count*
- · Controller (host) acknowledges
- ICS clock sends first byte (Byte 0) through byte 6
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a stop bit

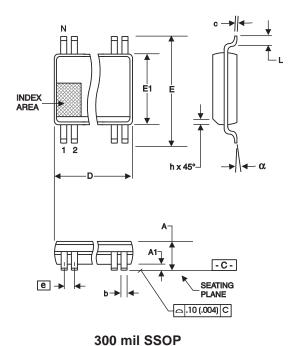
How to Read:				
Controller (Host)	ICS (Slave/Receiver)			
Start Bit				
Address				
D5 <sub>(H)</sub>				
	ACK			
	Byte Count			
ACK				
	Byte 0			
ACK				
	Byte 1			
ACK				
	Byte 2			
ACK				
	Byte 3			
ACK				
	Byte 4			
ACK				
	Byte 5			
ACK				
	Byte 6			
ACK				
Stop Bit				

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#### **Notes:**

- 1. The ICS clock generator is a slave/receiver, I<sup>2</sup>C component. It can read back the data stored in the latches for verification. **Read-Back will support Intel PIIX4 "Block-Read" protocol**.
- 2. The data transfer rate supported by this clock generator is 100K bits/sec or less (standard mode)
- 3. The input is operating at 3.3V logic levels.
- 4. The data byte format is 8 bit bytes.
- To simplify the clock generator I<sup>2</sup>C interface, the protocol is set to use only "**Block-Writes**" from the controller. The bytes must be accessed in sequential order from lowest to highest byte with the ability to stop after any complete byte has been transferred. The Command code and Byte count shown above must be sent, but the data is ignored for those two bytes. The data is loaded until a Stop sequence is issued.
- 6. At power-on, all registers are set to a default condition, as shown.





SYMBOL	In Millimeters		In Inches		
	COMMON DIMENSIONS		COMMON DIMENSIONS		
	MIN	MAX	MIN MAX		
	171114	100 (7)	171114	100 (7)	
Α	2.413	2.794	.095	.110	
A1	0.203	0.406	.008	.016	
b	0.203	0.343	.008	.0135	
С	0.127	0.254	.005	.010	
D	SEE VARIATIONS		SEE VARIATIONS		
Е	10.033	10.668	.395 .420		
E1	7.391	7.595	.291	.299	
е	0.635	BASIC	0.025 BASIC		
h	0.381	0.635	.015	.025	
L	0.508	1.016	.020	.040	
N	SEEVAF	RIATIONS	SEE VARIATIONS		
α	0°	8°	0°	8°	

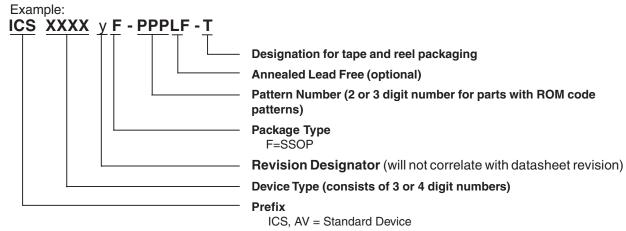
#### VARIATIONS

N	D mm.		D (inch)		
	MIN	MAX	MIN	MAX	
48	15.748	16.002	.620	.630	

JEDECMO-118 6/1/00 DOC# 10-0034 REVB

## **Ordering Information**

## ICS93705yFLF-T



0418D-04/28/05



**Revision History** 

Rev.	Issue Date	Description	Page #
D	4/28/2005	Added Lead Free Ordering Information	7

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TOYOSU FORESIA, 3-2-24 Toyosu, Koto-ku, Tokyo 135-0061, Japan www.renesas.com

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