



# IMU280ZA

INERTIAL MEASUREMENT SYSTEM



The ACEINNA IMU280ZA is a low cost miniature fully-calibrated inertial measurement system designed for demanding embedded applications that require a complete dynamic measurement solution in a robust low-profile package. The IMU280ZA provides a standard SPI bus for cost-effective board-to-board communications.



*Cabin Leveling*



*Antenna Stabilization*

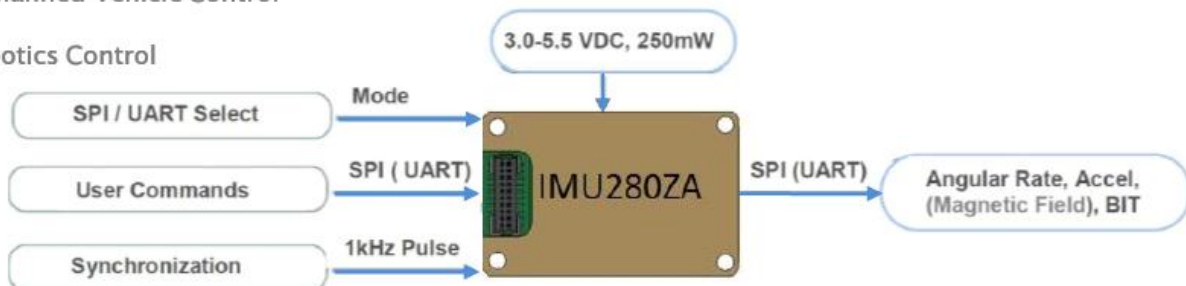
The ACEINNA IMU280ZA integrates highly-reliable MEMS 6DOF inertial sensors (optional 3-axis magnetic sensors) in a miniature factory-calibrated module to provide consistent performance through the extreme operating environments in a wide variety of dynamic control and navigation applications.

### Applications

- Cabin Leveling
- Platform Stabilization
- Unmanned Vehicle Control
- Robotics Control

### Features

- Complete 6DOF Inertial System
- Optional 3-Axis Magnetometer
- Standard and High Range Options
- SPI (or UART) Interface
- Update Rate, 1Hz to 200Hz
- 1KHz Clock Sync Input
- Miniature Package, 24 x 37 x 9.5 mm
- Lightweight < 17 g
- Low Power Consumption < 250 mW
- Wide Temp Range, -40C to +85C
- High Reliability, MTBF > 50k hours



## Performance IMU280ZA (-200,-209,-400,-409)

| Angular Rate                                  |                                |
|---|--------------------------------|
| Range: Roll, Pitch, Yaw (°/sec)               | ± 200 (± 400 High Range Model) |
| Bias Instability (°/hr) <sup>1,2</sup>        | < 20                           |
| Bias Stability Over Temp (°/sec) <sup>2</sup> | < 2.0                          |
| Resolution (°/sec)                            | < 0.02                         |
| Scale Factor Accuracy (%)                     | < 0.2                          |
| Non-Linearity (%FS)                           | < 0.2                          |
| Angle Random Walk (°/√hr) <sup>2</sup>        | < 1.5                          |
| Bandwidth (Hz)                                | 5-50 (user-configurable)       |
| Acceleration                                  |                                |
| Range: X, Y, Z (g)                            | ± 4 (± 8 High Range Model)     |
| Bias Instability (mg) <sup>1,2</sup>          | < 0.05                         |
| Bias Stability Over Temp (mg) <sup>2</sup>    | < 15                           |
| Resolution (mg)                               | < 0.5                          |
| Scale Factor Accuracy (%)                     | < 0.2                          |
| Non-Linearity (%FS)                           | < 0.2                          |
| Velocity Random Walk (m/s/√hr) <sup>2</sup>   | < 0.1                          |
| Bandwidth (Hz)                                | 5-50 (user-configurable)       |
| Magnetic Field                                |                                |
| Range: X, Y, Z (Gauss)                        | ± 4                            |
| Resolution (mGauss)                           | < 5                            |
| Noise Density (mGauss /√Hz) <sup>2</sup>      | < 1                            |
| Bandwidth (Hz)                                | 5                              |

## Specifications

| Environment                    |                                     |
|--------------------------------|-------------------------------------|
| Operating Temperature (°C)     | -40 to +85                          |
| Non-Operating Temperature (°C) | -55 to +105                         |
| Enclosure                      | Aluminum (Gold Anodized)            |
| Electrical                     |                                     |
| Input Voltage (VDC)            | 3.0 to 5.5                          |
| Power Consumption (mW)         | < 250                               |
| Digital Interface              | SPI or UART (user-configurable)     |
| Output Data Rate               | 1Hz to 200Hz (user-configurable)    |
| Input Clock Sync               | 1kHz Sync Pulse                     |
| Physical                       |                                     |
| Size (mm)                      | 24.15 x 37.7 x 9.5                  |
| Weight (gm)                    | < 17                                |
| Interface Connector            | 20-Pin (10 x 2) 1.0 mm pitch header |

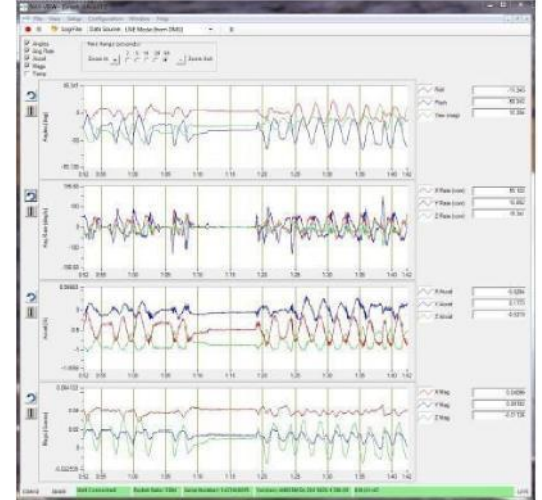
## Ordering Information

| Model                 | Description                                 |
|-----------------------|---|
| IMU280ZA-200          | 6DOF OEM Standard Range IMU                 |
| IMU280ZA-400          | 6DOF OEM High Range IMU                     |
| IMU280ZA-209          | 9DOF OEM Standard Range IMU                 |
| IMU280ZA-409          | 9DOF OEM High Range IMU                     |
| EVAL-KIT DMU280ZA-200 | 9DOF Standard Range DMU380ZA Evaluation Kit |
| EVAL-KIT DMU280ZA-400 | 9DOF High Range DMU380ZA Evaluation Kit     |

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<sup>1</sup> Allan Variance Curve, constant temperature. <sup>2</sup> 1-sigma error.

## NAV-VIEW Configuration and Display Software



NAV-VIEW provides an easy to use graphical interface to display, record, playback, and analyze all of the IMU280ZA Inertial Measurement System parameters.

NAV-VIEW can also be used to set a wide range of user-configurable fields in the IMU280ZA to optimize the system performance for highly dynamic applications.

NAV-VIEW software is available for download from ACEINNA's website at: [www.aceinna.com/support](http://www.aceinna.com/support)

## Other Components

The DMU280ZA evaluation kits include an AHR280ZA, evaluation board, and USB cable allowing direct connection to a PC for use with NAV-VIEW display and configuration software.

## Support

For more detailed information please refer to the DMU280ZA Series User's Manual available online at: [www.aceinna.com/support](http://www.aceinna.com/support)