# intersil

# DATASHEET

### ISL72027SEH

3.3V Radiation Tolerant CAN Transceiver, with Listen Mode and Split Termination Output FN8763 Rev 3.00 August 16, 2016

The Intersil <u>ISL72027SEH</u> is a 3.3V radiation tolerant CAN transceiver that is compatible with the ISO11898-2 standard for applications calling for Controller Area Network (CAN) serial communication in satellites and aerospace communications and telemetry data processing in harsh industrial environments.

The transceiver can transmit and receive at bus speeds up to 5Mbps. It can drive a 40m cable at 1Mbps per the ISO11898-2 specification. The device is designed to operate over a common-mode range of -7V to +12V with a maximum of 120 nodes. The device has three discrete selectable driver rise/fall time options, a listen mode feature and a split termination output.

Receiver (Rx) inputs feature a "full fail-safe" design, which ensures a logic high Rx output if the Rx inputs are floating, shorted, or terminated but undriven.

The ISL72027SEH is available in an 8 Ld hermetic ceramic flatpack and die form that operate across the temperature range of the -55°C to +125°C. The logic inputs are tolerant with 5V systems.

Other CAN transceivers available are the <u>ISL72026SEH</u> and <u>ISL72028SEH</u>. For a list of differences see <u>Table 1 on page 2</u>.

### **Related Literature**

- UG051, "ISL7202xSEHEVAL1Z Evaluation Board User Guide"
- TR018, "SEE Testing of the ISL72027SEH CAN Transceiver"
- TR022, "Total Dose Testing of the ISL72026SEH, ISL72027SEH and ISL72028SEH CAN Transceivers"

### **Features**

- DLA SMD <u>5962-15228</u>
- ESD Protection on all pins.....4kV HBM
- Compatible with IS011898-2
- Operating supply range ...... 3.0V to 3.6V
- Bus pin fault protection to  $\pm 20V$
- Undervoltage lockout
- Cold spare: powered down devices/nodes will not affect active devices operating in parallel
- Three selectable driver rise and fall times
- Glitch free bus  $\mathrm{I}/\mathrm{O}$  during power-up and power-down
- Full fail-safe (open, short, terminated/undriven) receiver
- Hi Z input allows for 120 nodes on the bus
- High data rates.....up to 5Mbps
- Listen mode supply current ...... 2mA (max)
- -7V to +12V common-mode input voltage range
- 5V tolerant logic inputs
- Thermal shutdown
- Acceptance tested to 75krad(Si) (LDR) wafer-by-wafer
- Radiation tolerance
  - SEL/B immune to LET 60MeV cm<sup>2</sup>/mg
  - Low dose rate (0.01rad(Si)/s) ..... 75krad(Si)

### **Applications**

- Satellites and aerospace communications
- Telemetry data processing
- High-end industrial environments
- Harsh environments

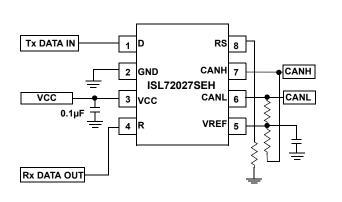


FIGURE 1. TYPICAL APPLICATION

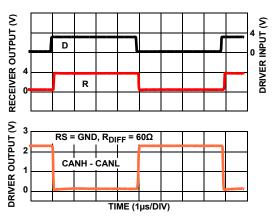


FIGURE 2. FAST DRIVER AND RECEIVER WAVEFORMS

### **Ordering Information**

ORDERING/SMD NUMBER ( <u>Note 1</u> )	PART NUMBER (Note 2)	TEMP RANGE (°C)	PACKAGE (RoHS Compliant)	PKG. DWG. #
5962L1522802VXC	ISL72027SEHVF	-55 to +125	8 Ld Ceramic Flatpack	K8.A
N/A	ISL72027SEHF/PROTO	-55 to +125	8 Ld Ceramic Flatpack	K8.A
5962L1522802V9A	ISL72027SEHVX	-55 to +125	Die	
N/A	ISL72027SEHX/SAMPLE	-55 to +125	Die	
N/A	ISL72027SEHEVAL1Z	Evaluation Board	·	

NOTES:

1. Specifications for Radiation Tolerant QML devices are controlled by the Defense Logistics Agency Land and Maritime (DLA). The SMD numbers listed in the Ordering Information must be used when ordering.

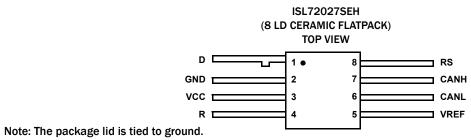
2. These Intersil Pb-free Hermetic packaged products employ 100% Au plate - e4 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations.

#### TABLE 1. ISL7202xSEH PRODUCT FAMILY FEATURE TABLE

SPEC	ISL72026SEH	ISL72027SEH	ISL72028SEH
Loopback Feature	Yes	No	No
VREF Output	No	Yes	Yes
Listen Mode	Yes	Yes	No
Shutdown Mode	No	No	Yes
VTHRLM	1150mV (Max)	1150mV (Max)	N/A
VTHFLM	525mV (Min)	525mV (Min)	N/A
VHYSLM	50mV (Min)	50mV (Min)	N/A
Supply Current, Listen Mode	2mA (Max)	2mA (Max)	N/A
Supply Current, Shutdown Mode	N/A	N/A	50µA (Max)
VREF Leakage Current	N/A	±25µA (Max)	±25µA (Max)

N/A: Not Applicable

### **Pin Configuration**



### **Pin Descriptions**

PIN NUMBER	PIN NAME	FUNCTION
1	D	CAN driver digital input. The bus states are LOW = dominant and HIGH = recessive. Internally tied HIGH.
2	GND	Ground connection.
3	VCC	System power supply input (3.0V to 3.6V). The typical voltage for the device is 3.3V.
4	R	CAN data receiver output. The bus states are LOW = dominant and HIGH = recessive.
8	RS	A resistor to GND from this pin controls the rise and fall time of the CAN output waveform. Drive RS HIGH to put into listen mode.
7	CANL	CAN bus line for low level output.
6	CANH	CAN bus line for high level output.
5	VREF	VCC/2 reference output for split mode termination.

### **Equivalent Input and Output Schematic Diagrams**

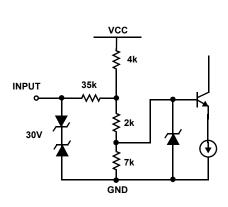


FIGURE 3. CANH AND CANL INPUTS

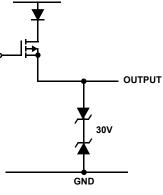


FIGURE 4. CANH OUTPUT

vcc

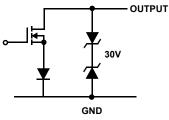


FIGURE 5. CANL OUTPUT

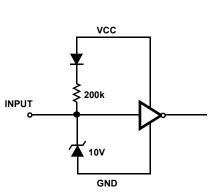


FIGURE 6. D INPUT

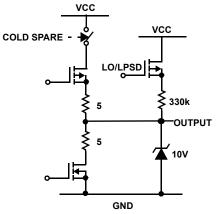


FIGURE 7. R OUTPUT

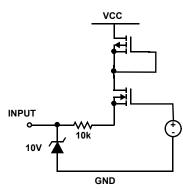
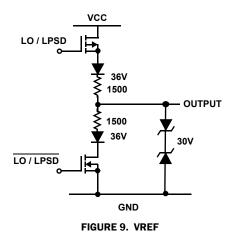


FIGURE 8. RS INPUT



#### **Absolute Maximum Ratings**

VCC to GND with/without Ion Beam	0.3V to 5.5V
CANH, CANL, VREF Under Ion Beam	±18V
CANH, CANL, VREF	±20V
I/O Voltages	
D, R, RS	0.5V to 7V
Receiver Output Current1	LOmA to 10mA
Output Short-circuit Duration	Continuous
ESD Rating:	
Human Body Model (Tested per MIL-PRF-883 3015.7)	
CANH, CANL Bus Pins	4kV
All Other Pins	4kV
Charged Device Model (Tested per JESD22-C101D)	750V
Machine Model (Tested per JESD22-A115-A)	200V

#### **Thermal Information**

Thermal Resistance (Typical)	θ <sub>JA</sub> (°C/W)	θ <b>JC</b> (°C∕W)
8 Ld FP Package (Notes 3, 4) Direct Attach .	39	7
Maximum Junction Temperature		+175°C
Storage Temperature Range	6	5°C to +150°C

#### **Recommended Operating Conditions**

Temperature Range55	°C to +125°C
V <sub>CC</sub> Supply Voltage	3V to 3.6V
Voltage on CAN I/O	7V to 12V
V <sub>IH</sub> D Logic Pin	2V to 5.5V
V <sub>IL</sub> D Logic Pin	0V to 0.8V
IOH Driver (CANH - CANL = 1.5V, V <sub>CC</sub> = 3.3V)	40mA
IOH Receiver (V <sub>OH</sub> = 2.4V)	4mA
IOL Driver (CANH - CANL = 1.5V, V <sub>CC</sub> = 3.3V)	+40mA
IOL Receiver (V <sub>OL</sub> = 0.4V)	+4mA

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

- 3. θ<sub>JA</sub> is measured with the component mounted on a high effective thermal conductivity test board (two buried 1oz copper planes) with "direct attach" features package base mounted to PCB thermal land with a 10 mil gap fill material having a k of 1W/m-K. See Tech Brief <u>TB379</u>.
- 4. For  $\theta_{\text{JC}},$  the "case temp" location is the center of the package underside.

**Electrical Specifications** Test Conditions:  $V_{CC} = 3V$  to 3.6V; Typicals are at  $T_A = +25$  °C (<u>Note 7</u>); unless otherwise specified (<u>Note 5</u>). Boldface limits apply across the operating temperature range, -55 °C to +125 °C or across a total ionizing dose of 75krad(Si) at +25 °C with exposure at a low dose rate of <10mrad(Si)/s.

PARAMETER	SYMBOL	TEST CONDITIONS		TEMP (°C)	MIN ( <u>Note 6</u> )	TYP ( <u>Note 7</u> )	MAX ( <u>Note 6</u> )	UNIT
DRIVER ELECTRICAL CHARACTI	ERISTICS							
Dominant Bus Output Voltage	V <sub>O(DOM)</sub>	D = 0V, CANH, RS = 0V, Figures 10 and <u>11</u>	$\rm 3V \le V_{CC} \le 3.6V$	Full	2.25	2.85	v <sub>cc</sub>	v
		D = 0V, CANL, RS = 0V, Figures 10 and <u>11</u>	-	Full	0.10	0.65	1.25	v
Recessive Bus Output Voltage	V <sub>O(REC)</sub>	D = 3V, CANH, RS = 0V, $60\Omega$ and no load, <u>Figures 10</u> and <u>11</u>	$3V \le V_{CC} \le 3.6V$	Full	1.80	2.30	2.70	v
		D = 3V, CANL, RS = 0V, $60\Omega$ and no load, <u>Figures 10</u> and <u>11</u>		Full	1.80	2.30	2.80	v
Dominant Output Differential	V <sub>OD(DOM)</sub>	$\textbf{D}=\textbf{0V},\textbf{RS}=\textbf{0V},\textbf{3V}\leq\textbf{V}_{\textbf{CC}}\leq\textbf{3}.$	6V, <u>Figures 10</u> and <u>11</u>	Full	1.5	2.2	3.0	V
Voltage		$\textbf{D}=\textbf{0V},\textbf{RS}=\textbf{0V},\textbf{3V}\leq\textbf{V}_{\textbf{CC}}\leq\textbf{3}.$	6V, <u>Figures 11</u> and <u>12</u>	Full	1.2	2.1	3.0	V
Recessive Output Differential	V <sub>OD(REC)</sub>	D = 3V, RS = 0V, $3V \le V_{CC} \le 3$ .	6V, <u>Figures 10</u> and <u>11</u>	Full	-120	0.2	12	mV
Voltage		D = 3V, RS = 0V, 3.0V $\leq$ V <sub>CC</sub> $\leq$	3.6V, no load	Full	-500	-34	50	mV
Logic Input High Voltage (D)	VIH	$3V \le V_{CC} \le 3.6V, Note 8$		Full	2.0	-	5.5	V
Logic Input Low Voltage (D)	V <sub>IL</sub>	3V≤ V <sub>CC</sub> ≤ 3.6V, <u>Note 8</u>		Full	0	-	0.8	V
High Level Input Current (D)	IIH	$D=2V,3V\leqV_{CC}\leq3.6V$		Full	-30	-3	30	μA
Low Level Input Current (D)	IIL	D = 0.8V, 3V $\leq$ V_{CC} $\leq$ 3.6V		Full	-30	-7	30	μA
RS Input Voltage for Listen Mode	V <sub>IN(RS)</sub>	$3V \le V_{CC} \le 3.6V$		Full	0.75xVCC	1.90	5.5	v

**Electrical Specifications** Test Conditions:  $V_{CC} = 3V$  to 3.6V; Typicals are at  $T_A = +25$  °C (<u>Note 7</u>); unless otherwise specified (<u>Note 5</u>). Boldface limits apply across the operating temperature range, -55 °C to +125 °C or across a total ionizing dose of 75krad(Si) at +25 °C with exposure at a low dose rate of <10mrad(Si)/s. (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN ( <u>Note 6</u> )	TYP ( <u>Note 7</u> )	MAX ( <u>Note 6</u> )	UNIT
Output Short-Circuit Current	losc	$V_{CANH}$ = -7V, CANL = OPEN, 3V $\leq$ $V_{CC}$ $\leq$ 3.6V, Figure 18	Full	-250	-100	-	mA
		$V_{CANH}$ = +12V, CANL = OPEN, 3V $\leq$ V_{CC} $\leq$ 3.6V, Figure 18	Full	-	0.4	1.0	mA
		$V_{CANL}$ = -7V, CANH = OPEN, 3V $\leq$ $V_{CC}$ $\leq$ 3.6V, Figure 18	Full	-1.0	-0.4	-	mA
		$V_{CANL}$ = +12V, CANH = OPEN, 3V $\leq$ $V_{CC}$ $\leq$ 3.6V, Figure 18	Full	-	100	250	mA
Thermal Shutdown Temperature	T <sub>SHDN</sub>	3V < V <sub>IN</sub> < 3.6V	-	-	163	-	°C
Thermal Shutdown Hysteresis	T <sub>HYS</sub>	3V < V <sub>IN</sub> < 3.6V	-	-	12	-	°C
RECEIVER ELECTRICAL CHARAC	TERISTICS						
Input Threshold Voltage (Rising)	V <sub>THR</sub>	RS = 0V, 10k, 50k, (recessive to dominant), Figures 14 and 15	Full	-	750	900	mV
Input Threshold Voltage (Falling)	V <sub>THF</sub>	RS = 0V, 10k, 50k, (dominant to recessive), Figures 14 and 15	Full	500	650	-	mV
Input Hysteresis	V <sub>HYS</sub>	(V <sub>THR</sub> - V <sub>THF</sub> ), RS = 0V, 10k, 50k, <u>Figures 14</u> and <u>15</u>	Full	40	90	-	mV
Listen Mode Input Threshold Voltage (Rising)	V <sub>THRLM</sub>	RS = $V_{CC}$ , (recessive to dominant), <u>Figure 14</u>	Full	-	920	1150	mV
Listen Mode Input Threshold Voltage (Falling)	V <sub>THFLM</sub>	RS = V <sub>CC</sub> , (dominant to recessive), <u>Figure 14</u>	Full	525	820	-	mV
Listen Mode Input Hysteresis	V <sub>HYSLM</sub>	(V <sub>THR</sub> - V <sub>THF</sub> ), RS = V <sub>CC</sub> , <u>Figure 14</u>	Full	50	100	-	mV
Receiver Output High Voltage	v <sub>oH</sub>	I <sub>0</sub> = -4mA	Full	2.4	VCC - 0.2	-	v
Receiver Output Low Voltage	V <sub>OL</sub>	I <sub>0</sub> = +4mA	Full	-	0.2	0.4	v
Input Current for CAN Bus	ICAN	CANH or CANL at 12V, D = 3V, other bus pin at 0V, RS = 0V	Full	-	420	500	μA
		CANH or CANL at 12V, D = 3V, V <sub>CC</sub> = 0V, other bus pin at 0V, RS = 0V	Full	-	150	250	μA
		CANH or CANL at -7V, D = 3V, other bus pin at 0V, $RS = 0V$	Full	-400	-300	-	μA
		CANH or CANL at -7V, D = 3V, $V_{CC}$ = 0V, other bus pin at 0V, RS = 0V	Full	-150	-85	-	μA
Input Capacitance (CANH or CANL)	C <sub>IN</sub>	Input to GND, D = 3V, RS = 0V	25	-	35	-	pF
Differential Input Capacitance	C <sub>IND</sub>	Input to Input, D = 3V, RS = 0V	25	-	15	-	pF
Input Resistance (CANH or CANL)	R <sub>IN</sub>	Input to GND, D = 3V, RS = 0V	Full	20	40	50	kΩ
Differential Input Resistance	R <sub>IND</sub>	Input to Input, D = 3V, RS = 0V	Full	40	80	100	kΩ
SUPPLY CURRENT							
Supply Current, Listen Mode	I <sub>CC(L)</sub>	$\text{RS = D = V}_{\text{CC}}, \ \text{3V} \leq \text{V}_{\text{CC}} \leq 3.6\text{V}$	Full	-	1	2	mA
Supply Current, Dominant	I <sub>CC(DOM)</sub>	D = RS = 0V, no load, 3V $\leq$ V_{CC} $\leq$ 3.6V	Full	-	5	7	mA
Supply Current, Recessive	I <sub>CC(REC)</sub>	D = V_{CC}, RS = 0V, no load, $3V \leq V_{CC} \leq 3.6V$	Full	-	2.6	5.0	mA
COLD SPARING BUS CURRENT							
CANH Leakage Current	I <sub>L(CANH)</sub>	$V_{CC}$ = 0.2V, CANH = -7V or 12V, CANL = float, D = V <sub>CC</sub> , RS = 0V	Full	-25	-4	25	μA
CANL Leakage Current	I <sub>L(CANL)</sub>	$V_{CC} = 0.2V$ , CANL = -7V or 12V, CANH = float, D = $V_{CC}$ , RS = 0V	Full	-25	-4	25	μA
VREF Leakage Current	I <sub>L(VREF)</sub>	V <sub>CC</sub> = 0.2V, V <sub>REF</sub> = -7V or 12V, D = V <sub>CC</sub>	Full	-25.00	0.01	25.00	μA

**Electrical Specifications** Test Conditions:  $V_{CC} = 3V$  to 3.6V; Typicals are at  $T_A = +25$  °C (<u>Note 7</u>); unless otherwise specified (<u>Note 5</u>). Boldface limits apply across the operating temperature range, -55 °C to +125 °C or across a total ionizing dose of 75krad(Si) at +25 °C with exposure at a low dose rate of <10mrad(Si)/s. (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN ( <u>Note 6</u> )	TYP ( <u>Note 7</u> )	MAX ( <mark>Note 6</mark> )	UNIT
DRIVER SWITCHING CHARACTER			( -)	······································	,	<u>, , , , , , , , , , , , , , , , , , , </u>	
Propagation Delay LOW to HIGH		RS = 0V, <u>Figure 13</u>	Full	-	75	150	ns
Propagation Delay LOW to HIGH		$RS = 10k\Omega, Figure 13$	Full	-	520	850	ns
Propagation Delay LOW to HIGH				-	850	1400	ns
Propagation Delay HIGH to LOW		RS = 0V, <u>Figure 13</u>	Full	-	80	155	ns
Propagation Delay HIGH to LOW	1 DILL	$RS = 10k\Omega, Figure 13$	Full	-	460	800	ns
Propagation Delay HIGH to LOW	TOTILE	$RS = 50k\Omega, Figure 13$	Full	-	725	1300	ns
Output Skew	tSKEW1	RS = 0V, ( t <sub>PHL</sub> - t <sub>PLH</sub>  ), <u>Figure 13</u>	Full	-	5	50	ns
Output Skew	tSKEW2	$RS = 10k\Omega, ( t_{PHL} - t_{PLH} ), Figure 13$	Full	-	60	510	ns
Output Skew	t <sub>SKEW3</sub>	$RS = 50k\Omega, ( t_{PHL} - t_{PLH} ), Figure 13$	Full	-	110	800	ns
Output Rise Time	t <sub>r1</sub>	RS = 0V, (fast speed)	Full	20	55	100	ns
Output Fall Time	t <sub>f1</sub>	Figure 13	Full	10	25	75	ns
Output Rise Time	t <sub>r2</sub>	RS = 10kΩ, (medium speed - 250Kbps) Fu		200	400	780	ns
Output Fall Time	t <sub>f2</sub>	Figure 13 Full		175	300	500	ns
Output Rise Time	t <sub>r3</sub>	RS = $50k\Omega$ , (slow speed - 125Kbps)	Full	400	700	1400	ns
Output Fall Time	t <sub>f3</sub>	Figure 13	Full	300	650	1000	ns
Total Loop Delay, Driver Input to	t(LOOP1)	RS = 0V, <u>Figure 16</u>	Full	-	115	210	ns
Receiver Output, Recessive to	()	RS = $10k\Omega$ , Figure 16	Full	-	550	875	ns
Dominant		RS = $50k\Omega$ , Figure 16	Full	-	850	1400	ns
Total Loop Delay, Driver Input to	t(LOOP2)	RS = 0V, <u>Figure 16</u>	Full	-	130	270	ns
Receiver Output, Dominant to	(2001 2)	RS = $10k\Omega$ , Figure 16	Full	-	500	825	ns
Recessive		RS = $50k\Omega$ , Figure 16	Full	-	750	1300	ns
Listen to Valid Dominant Time	t <sub>L-DOM</sub> )	Figure 17	Full	-	5	15	us
RECEIVER SWITCHING CHARACT	- /						
Propagation Delay LOW to HIGH	t <sub>PLH</sub>	Figure 14	Full	-	50	110	ns
Propagation Delay HIGH to LOW		Figure 14	Full	-	50	110	ns
Rx Skew	tSKEW1	(t <sub>PHL</sub> - t <sub>PLH</sub> ) , <u>Figure 14</u>	Full	-	2	35	ns
Rx Rise Time	t <sub>r</sub>	Figure 14	Full	-	2	-	ns
Rx Fall Time	t <sub>f</sub>	Figure 14	Full	-	2	-	ns
VREF/RS PIN CHARACTERISTICS	5	1	I	I	1		
	VREF	-5µA <iref<5µa< td=""><td>Full</td><td>0.45xV<sub>CC</sub></td><td>1.60</td><td>0.55xV<sub>CC</sub></td><td>v</td></iref<5µa<>	Full	0.45xV <sub>CC</sub>	1.60	0.55xV <sub>CC</sub>	v
VREF Pin Voltage		-50µA <iref<50µa< td=""><td>Full</td><td>0.4xV<sub>CC</sub></td><td>1.6</td><td>0.6xV<sub>CC</sub></td><td>v</td></iref<50µa<>	Full	0.4xV <sub>CC</sub>	1.6	0.6xV <sub>CC</sub>	v
	I <sub>RS(H)</sub>	RS = 0.75 x V <sub>CC</sub>	Full	-10.0	-0.2	-	μA
RS Pin Input Current	I <sub>RS(L)</sub>	V <sub>RS</sub> = 0V	Full	-450	-125	0	μA

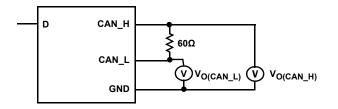
NOTES:

5. All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.

7. Typical values are at 3.3V. Parameters with a single entry in the "TYP" column apply to 3.3V. Typical values shown are not guaranteed.

8. Parameter included in functional testing.

### **Test Circuits and Waveforms**





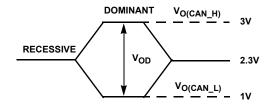
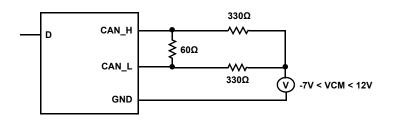
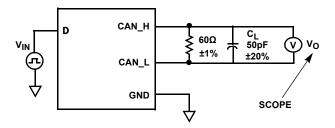


FIGURE 11. DRIVER BUS VOLTAGE DEFINITIONS







 $V_{IN}$  = 125kHz, 0V to  $V_{CC}$ , Duty Cycle 50%,  $t_r$  =  $t_f$   $\leq$  6ns,  $Z_O$  = 50 $\Omega$  CL includes fixture and instrumentation capacitance.

FIGURE 13A. DRIVER TIMING TEST CIRCUIT

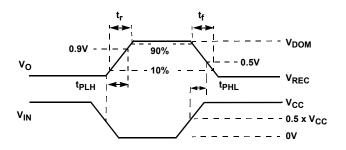
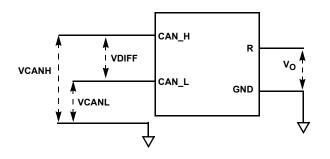


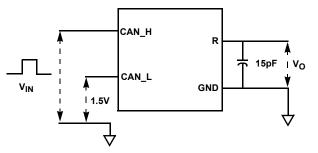
FIGURE 13B. DRIVER TIMING MEASUREMENT POINTS

FIGURE 13. DRIVER TIMING

# inter<sub>sil</sub>







 $V_{IN}$  = 125kHz, Duty Cycle 50%,  $t_r$  =  $t_f$  = 6ns,  $Z_O$  = 50 $\Omega$  CL includes test setup capacitance

FIGURE 14B. RECEIVER TEST CIRCUIT

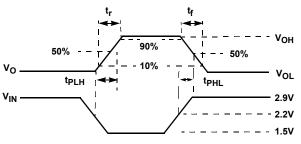


FIGURE 14A. RECEIVER VOLTAGE DEFINITIONS

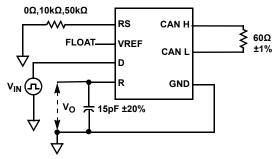
FIGURE 14C. RECEIVER TEST MEASUREMENT POINTS

FIGURE 14. RECEIVER TEST

IN	PUT	OUTPUT	MEASURED
VCANH	VCANL	R	VDIFF
-6.1V	-7V	L	900mV
12V	11.1V	L	900mV
-1V	-7V	L	6V
12V	6V	L	6V
-6.5V	-7V	н	500mV
12V	11.5V	н	500mV
-7V	-1V	н	6V

FIGURE 15. DIFFERENTIAL INPUT VOLTAGE THRESHOLD TEST





 $V_{IN}$  = 125kHz, Duty Cycle 50%, t<sub>r</sub> = t<sub>f</sub> ≤ 6ns

FIGURE 16A. TOTAL LOOP DELAY TEST CIRCUIT

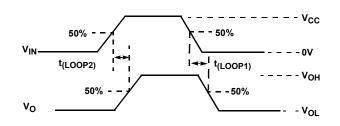
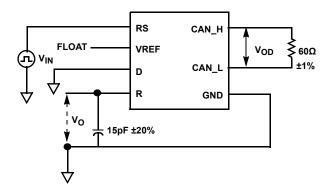


FIGURE 16B. TOTAL LOOP DELAY MEASUREMENT POINTS

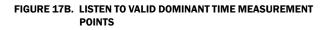


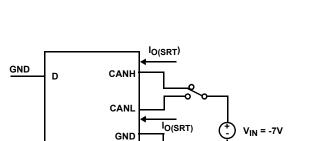


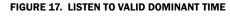
 $V_{IN}$   $V_{IN}$  V

 $V_{IN}$  = 125kHz, 0V to  $V_{CC}$ , Duty Cycle 50%,  $t_r = t_f \le 6$ ns

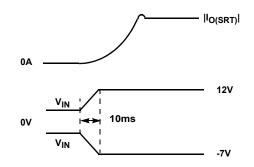
FIGURE 17A. LISTEN TO VALID DOMINANT TIME CIRCUIT







**OR 12V** 



T CIRCUIT FIGURE 18B. OUTPUT SHORT-CIRCUIT CURRENT WAVEFORMS FIGURE 18. OUTPUT SHORT-CIRCUIT

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### **Functional Description**

#### **Overview**

The Intersil ISL72027SEH is a 3.3V radiation tolerant CAN transceiver that is compatible with the ISO11898-2 standard for use in CAN (Controller Area Network) serial communication systems.

The device performs transmit and receive functions between the CAN controller and the CAN differential bus. It can transmit and receive at bus speeds of up to 5Mbps. It is designed to operate over a common-mode range of -7V to +12V with a maximum of 120 nodes. The device is capable of withstanding  $\pm 20V$  on the CANH and CANL bus pins outside of ion beam and  $\pm 16V$  under ion beam.

### **Slope Adjustment**

The output driver rise and fall time has three distinct selections that may be chosen by using a resistor from the RS pin to GND. Connecting the RS pin directly to GND results in output switching times that are the fastest, limited only by the drive capability of the output stage. RS =  $10k\Omega$  provides for a typical slew rate of  $8V/\mu s$  and RS =  $50k\Omega$  provides for a typical slew rate of  $4V/\mu s$ .

Putting a high logic level to the RS pin places the device in a low current listen mode. The protocol controller uses this mode to switch between low power listen mode and a normal transmit mode.

### **Cable Length**

The device can work per ISO11898 specification with a 40m cable and stub length of 0.3m and 60 nodes at 1Mbps. This is greater than the ISO requirement of 30 nodes. The cable type specified is a twisted pair (shielded or unshielded) with a characteristic impedance of  $120\Omega$ . Resistors equal to this are to be terminated at both ends of the cable. Stubs should be kept as short as possible to prevent reflections.

### **Cold Spare**

High reliability system designers implementing data communications have to be sensitive to the potential for single point failures. To mitigate the risk of a failure they will use redundant bus transceivers in parallel. Space systems call for high reliability in data communications that are resistant to single point failures. This is achieved by using a redundant bus transceiver in parallel. In this arrangement, both active and quiescent devices can be present simultaneously on the bus. The quiescent devices are powered down for cold spare and do not affect the communication of the other active nodes.

To achieve this, a powered down transceiver (V<sub>CC</sub> < 200mV) has a resistance between the VREF pin or the CANH pin or CANL pin and the V<sub>CC</sub> supply rail of >480k $\Omega$  (max) with a typical resistance >2M $\Omega$ . The resistance between CANH and CANL of a powered down transceiver has a typical resistance of 80k $\Omega$ .

#### **Listen Mode**

When a high level is applied to the RS pin, the device enters a low power listen mode. The driver of the transceiver is switched off to conserve power while the receiver remains active. In listen mode the transceiver draws 2mA (max) of current.

A low level on the RS pin brings the device back to normal operation.

### **Using 3.3V Devices in 5V Systems**

Looking at the differential voltage of both the 3.3V and 5V devices, the differential voltage is the same, the recessive common-mode output is the same. The dominant common-mode output voltage is slightly lower than the 5V counterparts. The receiver specs are also the same. Though the electrical parameters appear compatible, it is advised that necessary system testing be performed to verify interchangeable operation.

#### **Split Mode Termination**

The VREF pin provides a  $V_{CC}/2$  output voltage for split mode termination. The VREF pin has the same ESD protection, short-circuit protection, and common-mode operating range as the bus pins.

The split mode termination technique is shown in Figure 19.

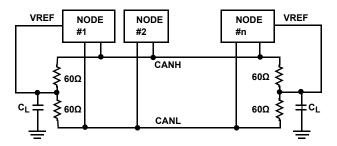
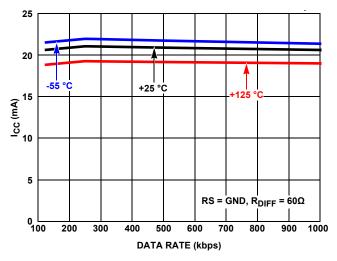


FIGURE 19. SPLIT TERMINATION

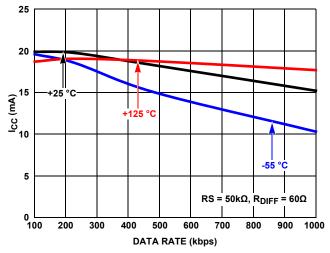
It is used to stabilize the bus voltage at  $V_{CC}/2$  and prevent it from drifting to a high common-mode voltage during periods of inactivity. The technique improves the electromagnetic compatibility of a network. The split mode termination is put at each end of the bus.

The C<sub>L</sub> capacitor between the two  $60\Omega$  resistors filters unwanted high frequency noise to ground. The resistors should have a tolerance of 1% or better and the two resistors should be carefully matched to provide the most effective EMI immunity. A typical value of C<sub>L</sub> for a high speed CAN network is 4.7nF, which generates a 3dB point at 1.1Mbps. The capacitance value used is dependent on the signaling rate of the network.

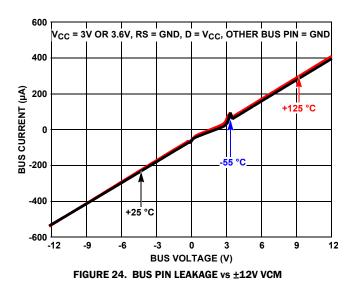
### **Typical Performance Curves** $v_{CC} = 3.3V$ , $C_L = 15pF$ , $T_A = +25°C$ ; unless otherwise specified.











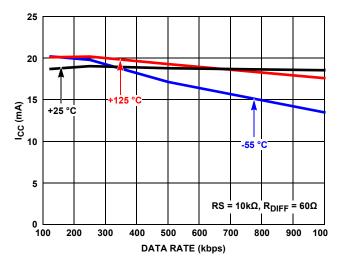
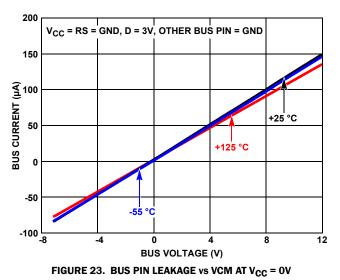
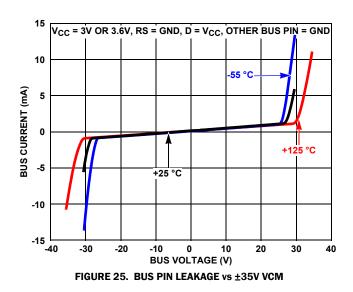
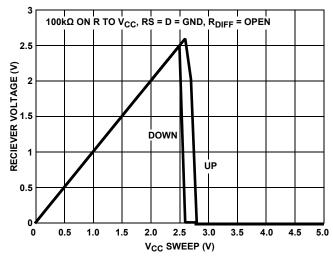


FIGURE 21. SUPPLY CURRENT vs MEDIUM DATA RATE vs TEMPERATURE





### **Typical Performance Curves** $v_{CC} = 3.3V$ , $C_L = 15pF$ , $T_A = +25$ °C; unless otherwise specified. (Continued)





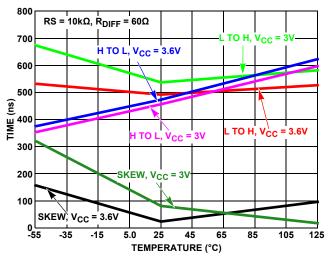


FIGURE 28. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT MEDIUM SPEED

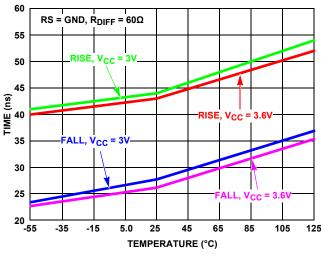


FIGURE 30. TRANSMITTER RISE AND FALL TIMES vs TEMPERATURE AT FAST SPEED

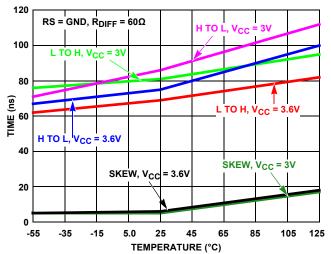


FIGURE 27. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT FAST SPEED

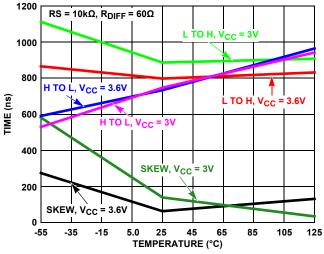
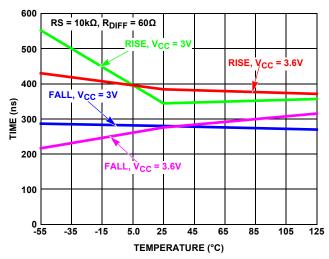
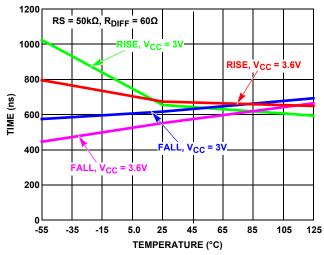


FIGURE 29. TRANSMITTER PROPAGATION DELAY AND SKEW vs TEMPERATURE AT SLOW SPEED





### Typical Performance Curves $v_{CC} = 3.3V$ , $C_L = 15pF$ , $T_A = +25$ °C; unless otherwise specified. (Continued)





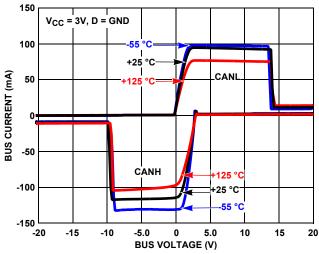
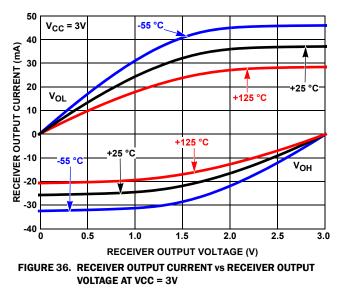


FIGURE 34. DRIVER OUTPUT CURRENT vs SHORT-CIRCUIT VOLTAGE vs TEMPERATURE



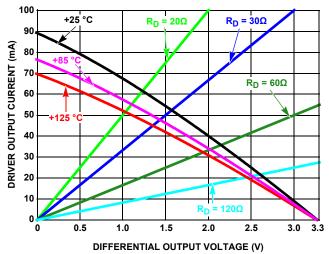


FIGURE 33. DRIVER OUTPUT CURRENT vs DIFFERENTIAL OUTPUT VOLTAGE

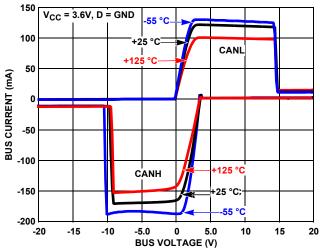
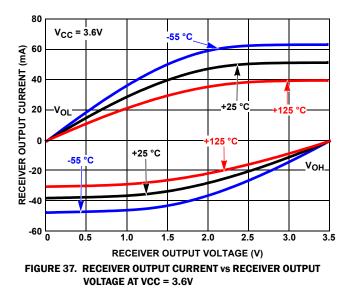
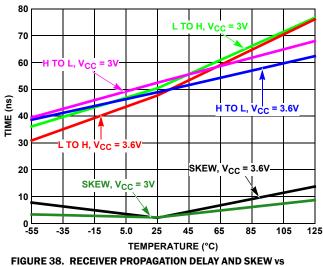


FIGURE 35. DRIVER OUTPUT CURRENT vs SHORT-CIRCUIT VOLTAGE vs TEMPERATURE

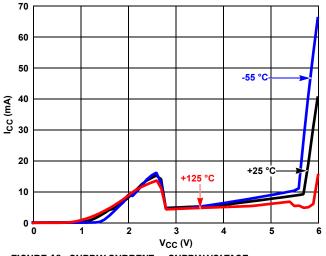


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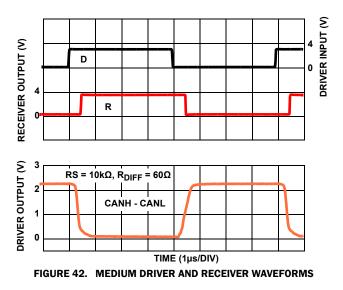
## **Typical Performance Curves** $v_{CC} = 3.3V$ , $C_L = 15pF$ , $T_A = +25$ °C; unless otherwise specified. (Continued)

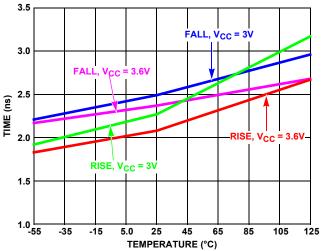




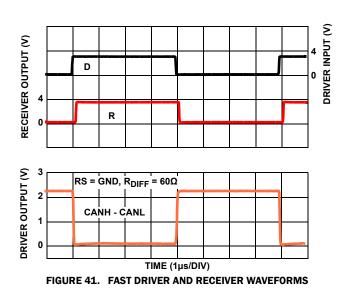












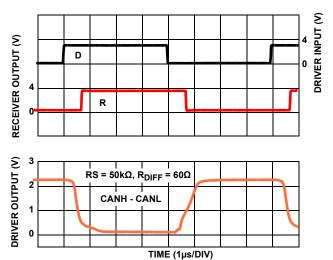


FIGURE 43. SLOW DRIVER AND RECEIVER WAVEFORMS

FN8763 Rev 3.00 August 16, 2016

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### **Die Characteristics**

#### **Die Dimensions**

 $2413\mu m x 3322\mu m$  (95 mils x 130.79 mils) Thickness:  $305\mu m \pm 25\mu m$  (12 mils  $\pm 1$  mil)

#### **Interface Materials**

#### GLASSIVATION

Type: 12kÅ Silicon Nitride on 3kÅ Oxide

#### TOP METALLIZATION

Type: 300Å TiN on 2.8µm AlCu In Bondpads, TiN has been removed.

#### **BACKSIDE FINISH**

Silicon

#### PROCESS

P6SOI

### **Assembly Related Information**

#### SUBSTRATE POTENTIAL

Floating

#### **Additional Information**

WORST CASE CURRENT DENSITY  $1.6 \times 10^{5}$ A/cm<sup>2</sup>

### TRANSISTOR COUNT

4055

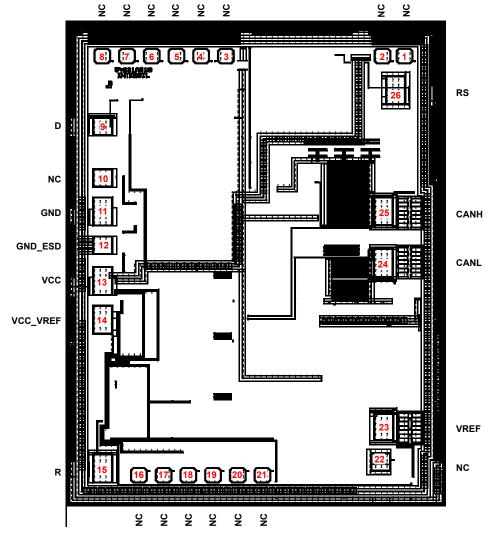
### **Weight of Packaged Device**

0.31 grams

#### **Lid Characteristics**

Finish: Gold Potential: Grounded, tied to package pin 2

### **Metalization Mask Layout**



		х	Y		
PAD NUMBER	PAD NAME	(µm)	(µm)	x	Y
1	NC	90.0	90.0	901.4	1365.6
2	NC	90.0	90.0	767.4	1365.6
3	NC	90.0	90.0	-183.23	1365.6
4	NC	90.0	90.0	-333.25	1365.6
5	NC	90.0	90.0	-483.25	1365.6
6	NC	90.0	90.0	-633.25	1365.6
7	NC	90.0	90.0	-783.25	1365.6
8	NC	90.0	90.0	-933.25	1365.6
9	D	110.0	110.0	-931.1	901.85
10	NC	110.0	110.0	-931.1	563.25
11	GND	110.0	180.0	-931.1	342.25
12	GND_ESD	110.0	110.05	-931.1	119.42
13	VCC	110.0	180.0	-931.1	-115.05
14	VCC_VREF	110.0	180.05	-931.1	-371.08
15	R	110.0	180.0	-931.1	-1350.0
16	NC	90.0	90.0	-711.1	-1394.95
17	NC	90.0	90.0	-561.1	-1394.95
18	NC	90.0	90.0	-411.1	-1394.95
19	NC	90.0	90.0	-261.1	-1394.95
20	NC	90.0	90.0	-111.1	-1394.95
21	NC	90.0	90.0	38.9	-1394.95
22	NC	110.0	110.0	756.9	-1307.3
23	VREF	110.0	180.0	775.3	-1072.3
24	CANL	110.0	180.0	772.1	2.15
25	CANH	110.0	180.05	772.1	343.33
26	RS	110.0	180.0	848.1	1140.6

### ISL72027SEH

NOTE: Origin of coordinates is the center of the die. NC - No Connect

# **Revision History** The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please go to the web to make sure that you have the latest revision.

DATE	REVISION	CHANGE
August 16, 2016	FN8763.3	"Absolute Maximum Ratings" on page 5 changed voltage value in VCC to GND With/Without Ion Beam From: -0.3V to 4.5V To: -0.3V to 5.5V.
April 29, 2016	FN8763.2	<ul> <li>Updated title.</li> <li>Updated the test condition for Output Rise Time on page 7.</li> <li>Changed maximum data rate from 1Mbps to 5Mbps in the following locations:</li> <li>Second paragraph and "Features" section on page 1.</li> <li>In "Overview" on page 11.</li> </ul>
November 9, 2015	FN8763.1	Absolute Maximum Ratings table on page 5: changed the value for "CANH, CANL, VREF Under Ion Beam" from $\pm 16V$ to $\pm 18V$ .
October 26, 2015	FN8763.0	Initial Release

### **About Intersil**

Intersil Corporation is a leading provider of innovative power management and precision analog solutions. The company's products address some of the largest markets within the industrial and infrastructure, mobile computing and high-end consumer markets.

For the most updated datasheet, application notes, related documentation and related parts, please see the respective product information page found at <u>www.intersil.com</u>.

You may report errors or suggestions for improving this datasheet by visiting www.intersil.com/ask.

Reliability reports are also available from our website at www.intersil.com/support.

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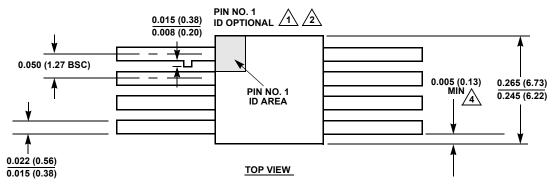
For information regarding Intersil Corporation and its products, see www.intersil.com

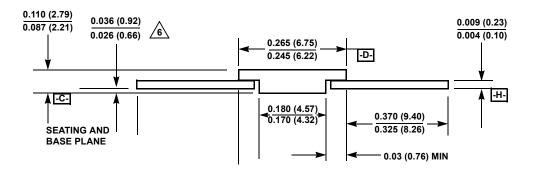


### **Package Outline Drawing**

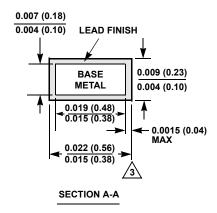
#### K8.A

8 LEAD CERAMIC METAL SEAL FLATPACK PACKAGE Rev 4, 12/14





SIDE VIEW



NOTES:

- Index area: A notch or a pin one identification mark shall be located adjacent to pin one and shall be located within the shaded area shown. The manufacturer's identification shall not be used as a pin one identification mark. Alternately, a tab may be used to identify pin one.
- $\frac{2}{2}$  If a pin one identification mark is used in addition to or instead of a tab, the limits of the tab dimension do not apply.
- The maximum limits of lead dimensions (section A-A) shall be measured at the centroid of the finished lead surfaces, when solder dip or tin plate lead finish is applied.
- 4. Measure dimension at all four corners.
- 5. For bottom-brazed lead packages, no organic or polymeric materials shall be molded to the bottom of the package to cover the leads.
- 6. Dimension shall be measured at the point of exit (beyond the meniscus) of the lead from the body. Dimension minimum shall be reduced by 0.0015 inch (0.038mm) maximum when solder dip lead finish is applied.
- 7. Dimensioning and tolerancing per ANSI Y14.5M 1982.
- 8. Controlling dimension: INCH.