

512Mb I-die Mobile SDR SDRAM

32Mb x16, 54FBGA with Lead-Free & Halogen-Free
(VDD / VDDQ = 1.8V / 1.8V)

datasheet

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Revision History

<u>Revision No.</u>	<u>History</u>	<u>Draft Date</u>	<u>Remark</u>	<u>Editor</u>
0.0	- First version for target specification.	Sep. 23, 2009	Target	J.Y.Bae
1.0	- Final datasheet.	Dec. 17, 2009	Final	J.Y.Bae
	- Revised DC characteristics.			
	1. ICC1 : 60mA -> 55mA @ 166Mhz.			
	2. ICC2NS : 1mA -> 5mA @ 166Mhz , 1mA -> 4mA @ 133Mhz.			
	3. ICC3P : 5mA -> 3mA @ 166Mhz, 133Mhz			
	4. ICC3N : 20mA ->12mA@ 166Mhz , 15mA -> 12mA @ 133Mhz.			
	5. ICC3NS : 10mA -> 8mA @ 166Mhz			
	6. ICC4 : 70mA -> 60mA @ 166Mhz, 60mA -> 55mA @ 133Mhz.			
	7. ICC5 : 80mA -> 70mA @ 166Mhz, 133Mhz.			

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8M x 16Bit x 4 Banks Mobile SDR SDRAM in 54FBGA**1.0 FEATURES**

- VDD/VDDQ = 1.8V/1.8V
- LVCMOS compatible with multiplexed address.
- Four banks operation.
- MRS cycle with address key programs.
 - CAS latency (2, 3).
 - Burst length (1, 2, 4, 8 & Full page).
 - Burst type (Sequential & Interleave).
- EMRS cycle with address key programs.
- All inputs are sampled at the positive going edge of the system clock.
- Burst read single-bit write operation.
- Special Function Support.
 - PASR (Partial Array Self Refresh).
 - Internal TCSR (Temperature Compensated Self Refresh)
 - Driver Strength (Full, 1/2, 1/4, 1/8, 3/4, 3/8, 5/8, 7/8)
- DQM for masking.
- Auto refresh.
- 64ms refresh period (8K cycle).
- Extended Temperature Operation (-25°C ~ 85°C).
- Clock Stop capability.
- 54Balls FBGA(-BXXX -Pb Free).

2.0 GENERAL DESCRIPTION

The K4M51163PI is 536,870,912 bits synchronous high data rate Dynamic RAM organized as 4 x 8,388,608 words by 16 bits, fabricated with SAM-SUNG's high performance CMOS technology. Synchronous design allows precise cycle control with the use of system clock and I/O transactions are possible on every clock cycle. Range of operating frequencies, programmable burst lengths and programmable latencies allow the same device to be useful for a variety of high bandwidth and high performance memory system applications.

3.0 ORDERING INFORMATION

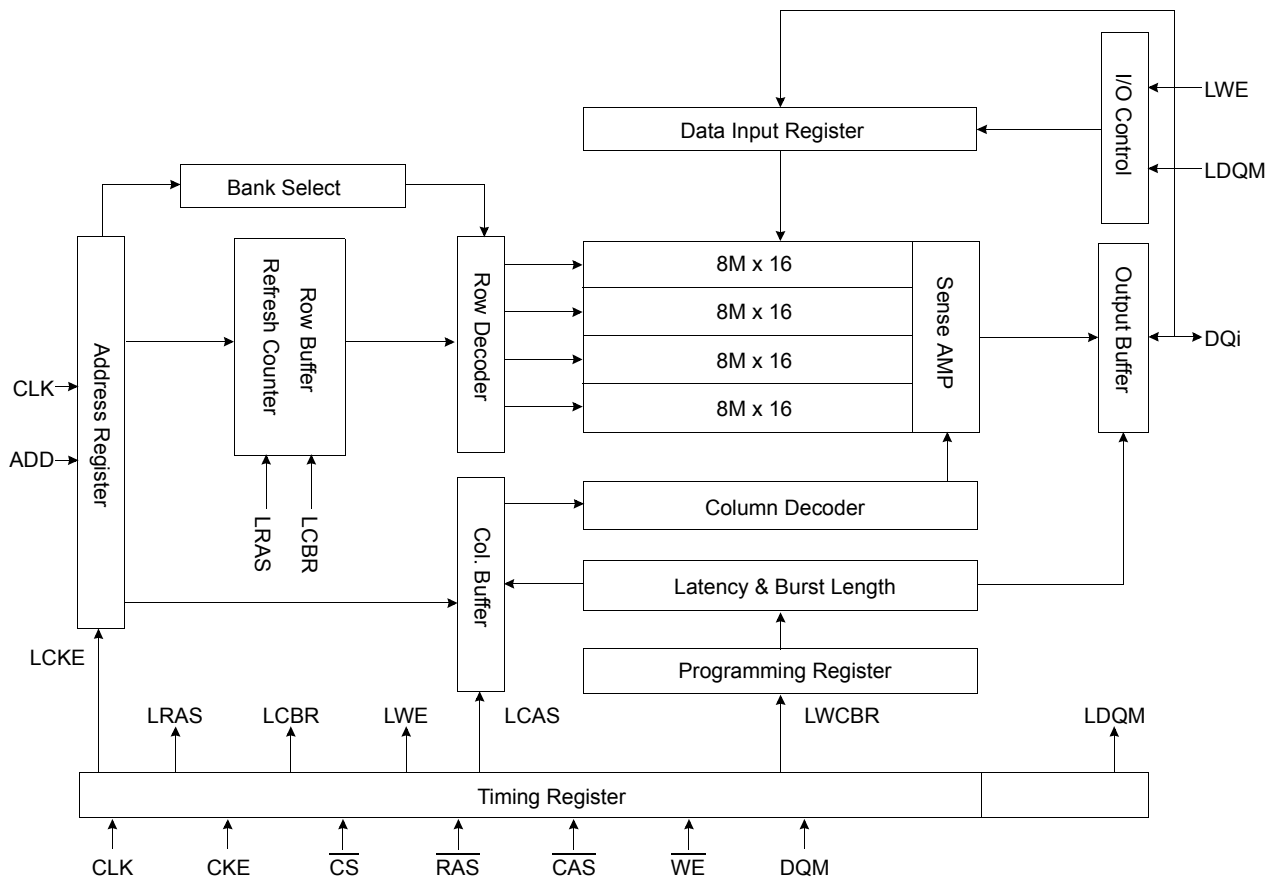
Part No.	Max Freq.	Interface	Package
K4M51163PI-BG60	166MHz(CL=3), 83MHz(CL=2)	LVCMOS	54 FBGA Halogen, Pb Free
K4M51163PI-BG75	133MHz(CL=3), 83MHz(CL=2)		

- K4M51163PI-BG60/75 : 54FBGA (Lead Free, Halogen Free)
- K4M51163PI-BG60/75 : Extended, Low, PASR & TCSR
- K4M51163PI-BG60/75 : 6.0ns @ CL3,PIB 7.5ns @ CL3

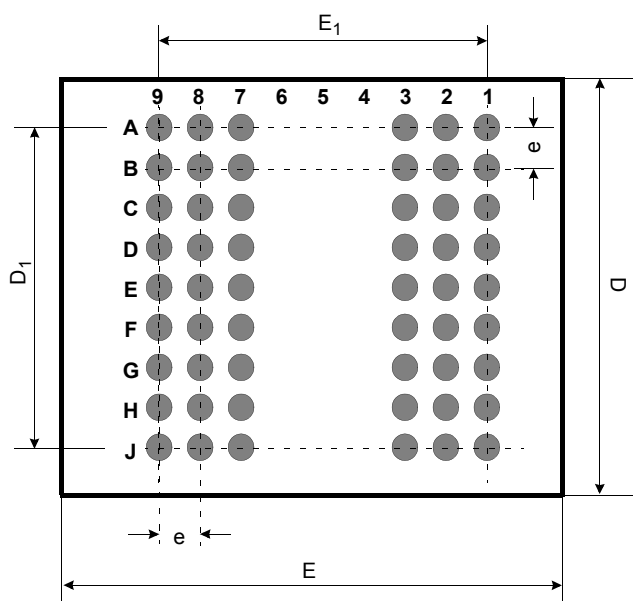
4.0 Address configuration

Organization	Bank Address	Row Address	Column Address
32M x 16	BA0,BA1	A0 - A12	A0 - A9

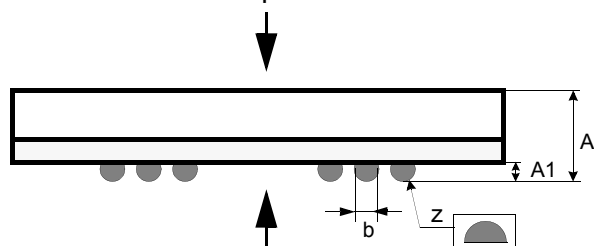
5.0 FUNCTIONAL BLOCK DIAGRAM



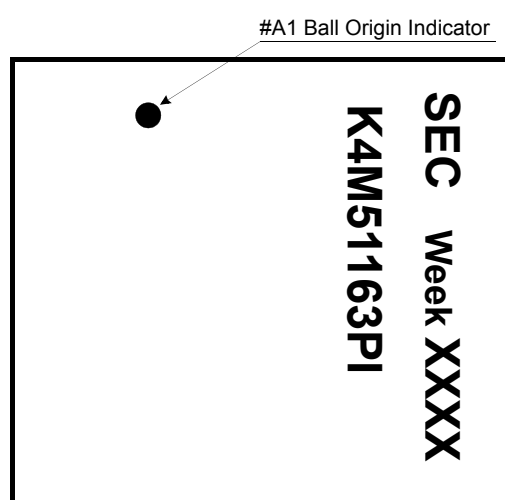
6.0 Package Dimension and Pin Configuration

< Bottom View ^{*1} >

*2: Top View



*1: Bottom View

< Top View ^{*2} >< Top View ^{*2} >

54Ball(6x9) FBGA						
	1	2	3	7	8	9
A	VSS	DQ15	VSSQ	VDDQ	DQ0	VDD
B	DQ14	DQ13	VDDQ	VSSQ	DQ2	DQ1
C	DQ12	DQ11	VSSQ	VDDQ	DQ4	DQ3
D	DQ10	DQ9	VDDQ	VSSQ	DQ6	DQ5
E	DQ8	NC	VSS	VDD	LDQM	DQ7
F	UDQM	CLK	CKE	CAS	RAS	WE
G	A12	A11	A9	BA0	BA1	CS
H	A8	A7	A6	A0	A1	A10
J	VSS	A5	A4	A3	A2	VDD

Pin Name	Pin Function
CLK	System Clock
$\overline{\text{CS}}$	Chip Select
CKE	Clock Enable
A0 ~ A12	Address
BA0 ~ BA1	Bank Select Address
$\overline{\text{RAS}}$	Row Address Strobe
$\overline{\text{CAS}}$	Column Address Strobe
$\overline{\text{WE}}$	Write Enable
L(U)DQM	Data Input/Output Mask
DQ0 ~ 15	Data Inputs/Outputs
VDD/VSS	Power Supply/Ground
VDDQ/VSSQ	Data Output Power/Ground

[Unit:mm]

Symbol	Min	Typ	Max
A	-	-	1.0
A ₁	0.25	-	-
E	7.9	8.0	8.1
E ₁	-	6.40	-
D	9.9	10.0	10.1
D ₁	-	6.40	-
e	-	0.80	-
b	0.45	0.50	0.55
z	-	-	0.10

7.0 ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Value	Unit
Voltage on any pin relative to Vss	V_{IN}, V_{OUT}	-1.0 ~ 2.6	V
Voltage on V_{DD} supply relative to Vss	V_{DD}, V_{DDQ}	-1.0 ~ 2.6	V
Storage temperature	T_{STG}	-55 ~ +150	°C
Power dissipation	P_D	1.0	W
Short circuit current	I_{OS}	50	mA

NOTE :

- 1) Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded.
- 2) Functional operation should be restricted to recommended operating condition.
- 3) Exposure to higher than recommended voltage for extended periods of time could affect device reliability.

8.0 DC OPERATING CONDITIONS

Recommended operating conditions (Voltage referenced to Vss = 0V, Tc = -25 to 85°C for Extended)

Parameter	Symbol	Min	Max	Unit	Note
Supply voltage (for device with a namal VDD of 1.8V)	V_{DD}	1.7	1.95	V	1
I/O Supply voltage	V_{DDQ}	1.7	1.95	V	1
Input logic high voltage	for Add.	$0.8 \times V_{DDQ}$	$V_{DDQ} + 0.3$	V	2
	for DQ	$0.7 \times V_{DDQ}$	$V_{DDQ} + 0.3$	V	
Input logic low voltage	for Add.	-0.3	0.3	V	3
	for DQ	-0.3	0.3	V	
Output logic high voltage	V_{OH}	$V_{DDQ} - 0.2$	-	V	$I_{OH} = -0.1mA$
Output logic low voltage	V_{OL}	-	0.2	V	$I_{OL} = 0.1mA$
Input leakage current	I_{LI}	-2	2	uA	4

NOTE :

- 1) Under all conditions, VDDQ must be less than or equal to VDD.
- 2) V_{IH} (max) = 2.2V AC. The overshoot voltage duration is $\leq 3ns$.
- 3) V_{IL} (min) = -1.0V AC. The undershoot voltage duration is $\leq 3ns$.
- 4) Any input $0V \leq V_{IN} \leq V_{DDQ}$.
Input leakage currents include Hi-Z output leakage for all bi-directional buffers with tri-state outputs.
- 5) Dout is disabled, $0V \leq V_{OUT} \leq V_{DDQ}$.

9.0 CAPACITANCE

(VDD = 1.8V, Tc = 25°C, f = 100MHz, VREF = 0.9V $\pm$ 50 mV)

Pin	Symbol	Min	Max	Unit	Note
Clock	C_{CLK}	1.5	3.5	pF	
$\overline{RAS}$, $\overline{CAS}$, $\overline{WE}$, $\overline{CS}$, CKE	C_{IN}	1.5	3.0	pF	
DQM	C_{IN}	1.5	3.0	pF	
Address	C_{ADD}	1.5	3.0	pF	
DQ0 ~ DQ31	C_{OUT}	2.0	4.5	pF	

10.0 DC CHARACTERISTICS

Recommended operating conditions (Voltage referenced to V_{SS} = 0V, T_C = -25 to 85°C for Extended)

Parameter	Symbol	Test Condition		Version		Unit	Note	
				-60	-75			
Operating Current (One Bank Active)	I _{CC1}	Burst length = 1 t _{RC} ≥ t _{RC} (min) IO = 0 mA		55	50	mA	1	
Precharge Standby Current in power-down mode	I _{CC2P}	CKE ≤ VIL(max), t _{CC} = 10ns		0.3		mA		
	I _{CC2PS}	CKE & CLK ≤ VIL(max), t _{CC} = ∞		0.3				
Precharge Standby Current in non power-down mode	I _{CC2N}	CKE ≥ VIH(min), CS ≥ VIH(min), t _{CC} = 10ns Input signals are changed one time during 20ns		10	8	mA		
	I _{CC2NS}	CKE ≥ VIH(min), CLK ≤ VIL(max), t _{CC} = ∞ Input signals are stable		5	4			
Active Standby Current in power-down mode	I _{CC3P}	CKE ≤ VIL(max), t _{CC} = 10ns		3		mA		
	I _{CC3PS}	CKE & CLK ≤ VIL(max), t _{CC} = ∞		2				
Active Standby Current in non power-down mode (One Bank Active)	I _{CC3N}	CKE ≥ VIH(min), CS ≥ VIH(min), t _{CC} = 10ns Input signals are changed one time during 20ns		12	12	mA		
	I _{CC3NS}	CKE ≥ VIH(min), CLK ≤ VIL(max), t _{CC} = ∞ Input signals are stable		8	8	mA		
Operating Current (Burst Mode)	I _{CC4}	IO = 0 mA Page burst 4Banks Activated t _{CCD} = 2CLKs		60	55	mA	1	
Refresh Current	I _{CC5}	t _{ARFC} ≥ t _{ARFC}		70		mA	2,3	
Self Refresh Current	I _{CC6}	CKE ≤ 0.2V	TCSR Range		Values			
					Typ	Max		
			Full Array	85°C	400	500	uA	4
				70°C	250			
				45°C	150	250		
				15°C	140			
			1/2 Array	85°C	300	400	uA	
				70°C	200			
				45°C	120	220		
				15°C	110			
			1/4 Array	85°C	250	350	uA	
				70°C	165			
				45°C	100	200		
				15°C	95			

NOTE :

- 1) Measured with outputs open.
- 2) Refresh period is 64ms.
- 3) ICC5 is measured in the below test condition.

Density	128Mb	256Mb	512Mb	1Gb	2Gb	Unit
t _{ARFC}	80	80	110	140	140	ns

- 4) Internal TCSR can be supported.
- 5) DPD(Deep Power Down) function is an optional feature, and it will be enabled upon request.
Please contact Samsung for more information.
- 6) Unless otherwise noted, input swing level is CMOS(VIH /VIL=VDDQ/VSSQ).

11.0 AC OPERATING TEST CONDITIONS

(VDD = 1.7 ~ 1.95 V, T_C = -25 ~ 85°C for Extended)

Parameter	Value	Unit
AC input levels (V _{ih} /V _{il})	$0.9 \times V_{DDQ} / 0.2$	V
Input timing measurement reference level	$0.5 \times V_{DDQ}$	V
Input rise and fall time	tr/tf = 1/1	ns
Output timing measurement reference level	$0.5 \times V_{DDQ}$	V
Output load condition	See Figure 2	

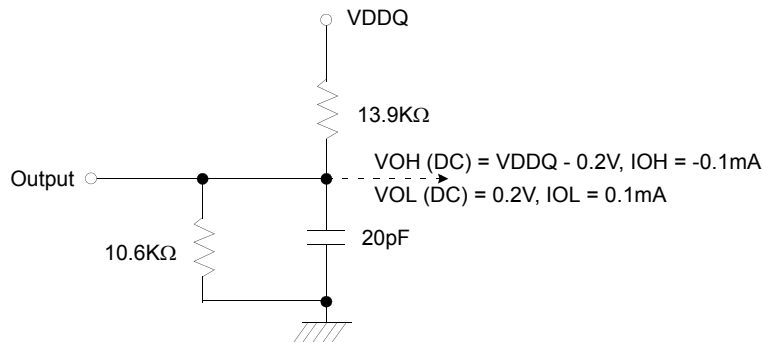


Figure 1. DC Output Load Circuit

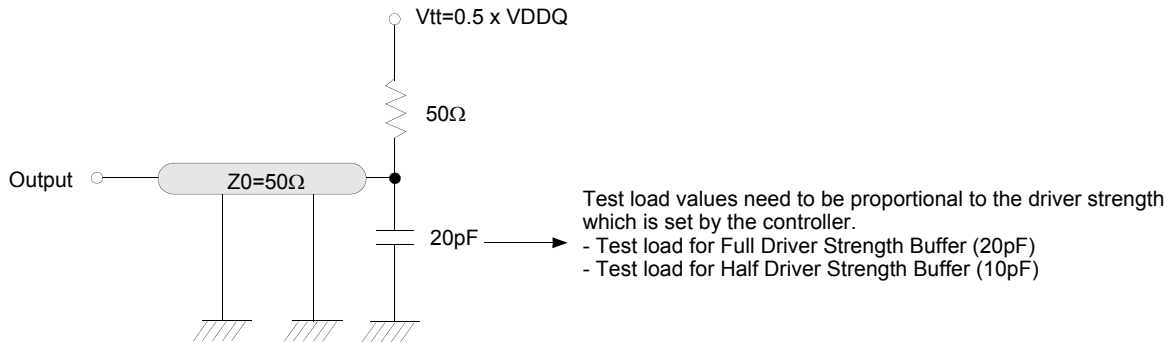


Figure 2. AC Output Load Circuit ^{1), 2)}

NOTE :

1) The circuit shown above represents the timing reference load used in defining the relevant timing parameters of the part. It is not intended to be either a precise representation of the typical system environment nor a depiction of the actual load presented by a production tester. System designers will use IBIS or other simulation tools to correlate the timing reference load to system environment. Manufacturers will correlate to their production test conditions (generally a coaxial transmission line terminated at the tester electronics). For the half strength driver with a nominal 10pF load parameters t_{AC} and t_{QH} are expected to be in their same range. However, these parameters are not subject to production test but are estimated by design / characterization. Use of IBIS or other simulation tools for system design validation is suggested.

2) Based on nominal impedance at 0.5 x VDDQ.
The impedance for Half(1/2) Driver Strength is designed 55ohm. And for other Driver Strength, it is designed proportionally.

12.0 OPERATING AC PARAMETER

(AC operating conditions unless otherwise noted)

Parameter	Symbol	Version		Unit	Note
		-60	-75		
Row active to row active delay	tRRD(min)	12	15	ns	1
RAS to CAS delay	tRCD(min)	18	22.5	ns	1
Row precharge time	tRP(min)	18	22.5	ns	1
Row active time	tRAS(min)	42	50	ns	1
	tRAS(max)	100		us	
Row cycle time	tRC(min)	60	72.5	ns	1
Last data in to row precharge	tRDL(min)	12	15	ns	2
Last data in to Active delay	tDAL(min)	tRDL + tRP		-	3
Last data in to new col. address delay	tCDL(min)	1		CLK	2
Last data in to burst stop	tBDL(min)	1		CLK	2
Auto refresh cycle time	tARFC(min)	80		ns	6
Exit self refresh to active command	tSRFX(min)	120		ns	
Col. address to col. address delay	tCCD(min)	1		CLK	4
Number of valid output data	CAS latency=3	2		ea	5
	CAS latency=2	1			

- NOTE :**
- 1) The minimum number of clock cycles is determined by dividing the minimum time required with clock cycle time and then rounding off to the next higher integer.
 - 2) Minimum delay is required to complete write.
 - 3) $t_{DAL} = (t_{RDL}/t_{CC}) + (t_{RP}/t_{CC})$
In case of below 33MHz ($t_{CC} = 30\text{ns}$) condition, SEC could support $t_{DAL} (=2 \cdot t_{CK})$
 - 4) All parts allow every cycle column address change.
 - 5) In case of row precharge interrupt, auto precharge and read burst stop.
 - 6) Maximum burst refresh cycle : 8

13.0 AC CHARACTERISTICS

(AC operating conditions unless otherwise noted)

Parameter		Symbol	-60		-75		Unit	Note
			Min	Max	Min	Max		
CLK cycle time	CAS latency=3	tCC	6.0	1000	7.5	1000	ns	1,2,3
	CAS latency=2		-		12			
CLK to valid output delay	CAS latency=3	tSAC		5.4		6	ns	1,4
	CAS latency=2			-		9		
Output data hold time	CAS latency=3	tOH	2.5		2.5		ns	4
	CAS latency=2		-		2.5			
CLK high pulse width		tCH	2.5		2.5		ns	5
CLK low pulse width		tCL	2.5		2.5		ns	5
Input setup time		tSS	2.0		2.0		ns	5
Input hold time		tSH	1		1		ns	5
CLK to output in Low-Z		tSLZ	1		1		ns	4
CLK to output in Hi-Z	CAS latency=3	tSHZ		5.4		6	ns	
	CAS latency=2			-		9		

NOTE :

- Parameters depend on programmed CAS latency.
- tCC(max) value is measured at 100ns.
- The only time that the clock Frequency is allowed to be changed is during clock stop, power-down, self-refresh modes.
- If clock rising time is longer than 1ns, $(tr/2-0.5)$ ns should be added to the parameter.
- Assumed input rise and fall time (tr & tf) = 1ns.
If tr & tf is longer than 1ns, transient time compensation should be considered,
i.e., $[(tr + tf)/2-1]$ ns should be added to the parameter.

14.0 SIMPLIFIED TRUTH TABLE

COMMAND			CKEn-1	CKEn	$\overline{CS}$	$\overline{RAS}$	$\overline{CAS}$	$\overline{WE}$	DQM	BA0,1	A10/AP	A12,11, A9 ~ A0	Note
Register	Mode Register Set		H	X	L	L	L	L	X	OP CODE			1, 2
Refresh	Auto Refresh		H	H	L	L	L	H	X	X			3
	Self Refresh	Entry		L									3
		Exit	L	H	L	H	H	H	X	X			3
					H	X	X	X					3
Bank Active & Row Addr.			H	X	L	L	H	H	X	V	Row Address		
Read & Column Address	Auto Precharge Disable		H	X	L	H	L	H	X	V	L	Column Address (A0~A9)	4
	Auto Precharge Enable										H		4, 5
Write & Column Address	Auto Precharge Disable		H	X	L	H	L	L	X	V	L	Column Address (A0~A9)	4
	Auto Precharge Enable										H		4, 5
Burst Stop			H	X	L	H	H	L	X	X			6
Precharge	Bank Selection		H	X	L	L	H	L	X	V	L	X	
	All Banks									X	H		
Clock Suspend or Active Power Down		Entry	H	L	H	X	X	X	X	X			
					L	H	H	H					
		Exit	L	H	X	X	X	X	X				
Precharge Power Down Mode		Entry	H	L	H	X	X	X	X	X			
					L	H	H	H					
		Exit	L	H	H	X	X	X	X				
					L	H	H	H					
DQM			H	X					V	X			7
No Operation Command			H	X	H	X	X	X	X	X			
					L	H	H	H					

NOTE :

- 1) OP Code : Operand Code
A0 ~ A12 & BA0 ~ BA1 : Program keys. (@MRS)
- 2) MRS can be issued only at all banks precharge state.
A new command can be issued after 2 CLK cycles of MRS.
- 3) Auto refresh functions are the same as CBR refresh of DRAM.
The automatical precharge without row precharge command is meant by "Auto".
Auto/self refresh can be issued only at all banks precharge state.
Partial self refresh can be issued only after setting partial self refresh mode of EMRS.
- 4) BA0 ~ BA1 : Bank select addresses.
- 5) During burst read or write with auto precharge, new read/write command can not be issued.
Another bank read/write command can be issued after the end of burst.
New row active of the associated bank can be issued at tRP after the end of burst.
- 6) Burst stop command is valid at every burst length.
- 7) DQM sampled at the positive going edge of CLK masks the data-in at that same CLK in write operation (Write DQM latency is 0), but in read operation, it makes the data-out Hi-Z state after 2 CLK cycles. (Read DQM latency is 2).

15.0 MODE REGISTER FIELD TABLE TO PROGRAM MODES

15.1 Register Programmed with Normal MRS

Address	BA0 ~ BA1	A12 ~ A10/AP	A9 ²⁾	A8	A7	A6	A5	A4	A3	A2	A1	A0
Function	"0" Setting for Normal MRS	RFU ¹⁾	W.B.L	Test Mode		CAS Latency			BT	Burst Length		

15.2 Normal MRS Mode

Test Mode			CAS Latency				Burst Type			Burst Length				
A8	A7	Type	A6	A5	A4	Latency	A3	Type		A2	A1	A0	BT=0	BT=1
0	0	Mode Register Set	0	0	0	Reserved	0	Sequential		0	0	0	1	1
0	1	Reserved	0	0	1	Reserved	1	Interleave		0	0	1	2	2
1	0	Reserved	0	1	0	2	Mode Select			0	1	0	4	4
1	1	Reserved	0	1	1	3	BA1	BA0	Mode	0	1	1	8	8
Write Burst Length			1	0	0	Reserved	0	0	Setting for Normal MRS	1	0	0	Reserved	Reserved
A9	Length		1	0	1	Reserved				1	0	1	Reserved	Reserved
0	Burst		1	1	0	Reserved				1	1	0	Reserved	Reserved
1	Single Bit		1	1	1	Reserved				1	1	1	Full Page ³⁾	Reserved

15.3 Register Programmed with Extended MRS

Address	BA1	BA0	A12 ~ A10/AP	A9	A8	A7	A6	A5	A4	A3	A2	A1	A0
Function	Mode Select		RFU ¹⁾			DS			RFU ¹⁾		PASR		

15.4 EMRS for PASR(Partial Array Self Ref.) & DS(Driver Strength)

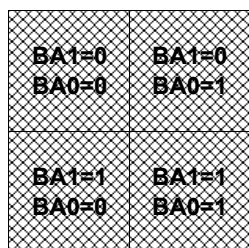
Mode Select					Driver Strength				PASR				
BA1	BA0	Mode			A7	A6	A5	Driver Strength	A2	A1	A0	# of Banks	
0	0	Normal MRS			0	0	0	Full	0	0	0	Full Array	
0	1	Reserved			0	0	1	1/2	0	0	1	1/2 Array	
1	0	EMRS			0	1	0	1/4	0	1	0	1/4 Array	
1	1	Reserved			0	1	1	1/8	0	1	1	Reserved	
					1	0	0	3/4	1	0	0	Reserved	
Reserved Address					1	0	1	3/8	1	0	1	Reserved	
A12~A10/AP		A9	A8	A4	A3	1	1	0	5/8	1	1	0	Reserved
0		0	0	0	0	1	1	1	7/8	1	1	1	Reserved

NOTE :

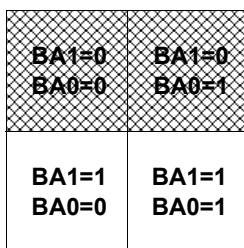
- 1) RFU(Reserved for future use) should stay "0" during MRS cycle.
 2) If A9 is high during MRS cycle, "Burst Read Single Bit Write" function will be enabled.
 3) Full Page Length x32 : 64Mb(256) , 128Mb (256), 256Mb (512), 512Mb (512)

15.4.1. Partial Array Self Refresh

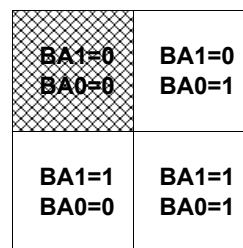
1. In order to save power consumption, Mobile SDR SDRAM has PASR option.
2. Mobile SDR SDRAM supports 3 kinds of PASR in self refresh mode : Full array, 1/2 array, 1/4 array



- Full Array



- 1/2 Array



- 1/4 Array



Partial Self Refresh Area

15.4.2. Internal Temperature Compensated Self Refresh (TCSR)

1. In order to save power consumption, this Mobile DRAM includes the internal temperature sensor and control units to control the self refresh cycle automatically according to the real device temperature.
2. TCSR ranges for IDD6 shown in the table are as an example only. Max IDD6 value for 45°C, 85°C are guaranteed. Typical values for 85 °C, 70 °C, 45 °C and 15 °C are obtained from device characterization.
3. If the EMRS for external TCSR is issued by the controller, this EMRS code for TCSR is ignored.

Temperature Range	Self Refresh Current (IDD6)						Unit
	Full Array		1/2 Array		1/4 Array		
	Typ.	Max	Typ.	Max	Typ.	Max	
85 °C	400	500	300	400	250	350	uA
70 °C	250		200		165		
45 °C	150	250	120	220	100	200	
15 °C	140		110		95		

16.0 POWER UP SEQUENCE

1. Apply power and attempt to maintain CKE at a high state and all other inputs may be undefined.
 - Apply VDD before or at the same time as VDDQ.
2. Maintain stable power, stable clock and NOP input condition for a minimum of 200us.
3. Issue precharge commands for all banks of the devices.
4. Issue 2 or more auto-refresh commands.
5. Issue a mode register set command to initialize the mode register.
6. Issue a extended mode register set command for the desired operating modes after normal MRS.

The Mode Register and Extended Mode Register do not have default values.
If they are not programmed during the initialization sequence, it may lead to unspecified operation.
All banks have to be in idle state prior to adjusting MRS and EMRS set.

17.0 BURST SEQUENCE

17.1 BURST LENGTH = 4

Initial Address		Sequential				Interleave			
A1	A0								
0	0	0	1	2	3	0	1	2	3
0	1	1	2	3	0	1	0	3	2
1	0	2	3	0	1	2	3	0	1
1	1	3	0	1	2	3	2	1	0

17.2 BURST LENGTH = 8

Initial Address			Sequential								Interleave							
A2	A1	A0																
0	0	0	0	1	2	3	4	5	6	7	0	1	2	3	4	5	6	7
0	0	1	1	2	3	4	5	6	7	0	1	0	3	2	5	4	7	6
0	1	0	2	3	4	5	6	7	0	1	2	3	0	1	6	7	4	5
0	1	1	3	4	5	6	7	0	1	2	3	2	1	0	7	6	5	4
1	0	0	4	5	6	7	0	1	2	3	4	5	6	7	0	1	2	3
1	0	1	5	6	7	0	1	2	3	4	5	4	7	6	1	0	3	2
1	1	0	6	7	0	1	2	3	4	5	6	7	4	5	2	3	0	1
1	1	1	7	0	1	2	3	4	5	6	7	6	5	4	3	2	1	0