

## Synchronous Boost DC/DC Regulator KX3001

#### **Features**

- Up to 94% Efficiency
- Low voltage start-up: 0.9V
- Shut-down current: < 1µA</li>
- Input voltage: 0.9V~4.4V
- Output voltage: 2.5V~4.3V (Up to 5V with Schottky)
- Low switch on resistance R<sub>DS</sub>(ON),
   Internal switch: 0.35 Ω
- 1.4MHz fixed frequency switching
- High switch on current: 1A
- Low profile SOT-23-6 package (lead-free packaging is now available)

### **Applications**

- Digital cameras and MP3
- Palmtop computers / PDAs
- Cellular phones
- Wireless handsets and DSL modems
- PC cards
- Portable media players

### **Description**

The KX3001 is high efficiency synchronous, PWM step-up DC/DC converters optimized to provide a high efficient solution to medium power systems. The devices work under the input voltage between 0.9V and 4.4V with a 1.4MHz fixed frequency switching. These features minimize overall solution footprint by allowing the use of tiny, low profile inductors and ceramic capacitors.

The KX3001 is capable of supplying an output voltage between 2.5V and 4.3V, the internal synchronous switch is desired to provide high efficiency without Schottky.

The devices also featured providing up to 260mA from a single AA cell input or up to 600mA from a 2-cell AA with a 3V/3.3V output.

The KX3001 regulators are available in the industry standard SOT-23-6 power packages (or upon request).

### **Order Information**

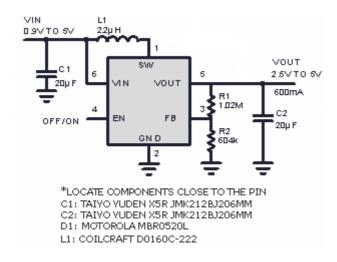
KX3001 - (1) (2) :

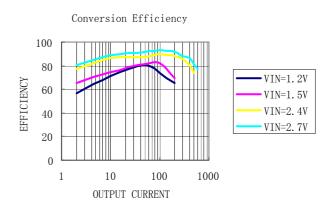
SYMBOL	DESCRIPTION		
1	Denotes Output voltage:		
	A : Adjustable Output		
2	Denotes Package Types:		
	F: SOT-23-6		

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## **Typical Application**

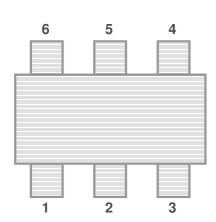




## **Absolute Maximum Ratings**

Power Dissipation	Internally limited
V <sub>IN</sub>	0.3 V $\sim$ + 6 V
V <sub>OUT</sub>	0.3 V $\sim$ + 6 V
V <sub>SW</sub>	0.3 V $\sim$ + 6 V
V <sub>EN</sub> , V <sub>OUT</sub>	0.3 V $\sim$ + 6 V
Operating Temperature Range	30℃ ~ +85℃
Lead Temperature (Soldering 10 sec.)	+ <b>300</b> ℃
Storage Temperature Range	65°C ~ + 125°C

## **Pin Assignment**



PIN NUMBER SOT-23-6	PIN NAME	FUNCTION	
1	sw	Switch Output	
2	GND	Ground	
3	FB	Feedback	
4	EN	ON/OFF Control (High Enable)	
5	V <sub>OUT</sub>	Output	
6	V <sub>IN</sub>	Input	

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### **Electrical Characteristics**

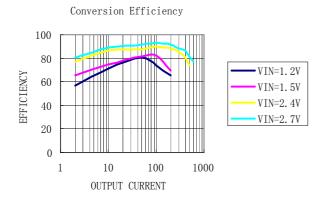
Operating Conditions: TA=25  $^{\circ}\text{C},~V_{\text{IN}}\text{=}1.2\text{V},~V_{\text{OUT}}\text{=}3.3\text{V}$  unless otherwise specified.

PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS
Output Voltage Range (Adj.)		2.5		5	V
Minimum Start-Up Voltage	I <sub>LOAD</sub> = 1mA		0.9	1.1	V
Minimum Operating Voltage	EN = V <sub>IN</sub>		0.6	0.75	V
Switching Frequency		1.1	1.4	1.7	MHz
Max Duty Cycle	V <sub>FB</sub> = 1.15V	80	87		%
Current Limit Delay to Output			40		ns
Feedback Voltage		1.165	1.212	1.241	V
Feedback Input Current	V <sub>FB</sub> = 1.22V		1		nA
NMOS Switch Leakage	V <sub>SW</sub> = 5V		0.1	5	μΑ
PMOS Switch Leakage	V <sub>SW</sub> = 0V		0.1	5	μΑ
NMOS Switch On Resistance	V <sub>OUT</sub> = 3.3V		0.35		Ω
PMOS Switch On Resistance	V <sub>OUT</sub> = 3.3V		0.45		Ω
NMOS Current Limit		700	950		mA
Quiescent Current (Active)	Measured On V <sub>OUT</sub> , Nonswitching		300	500	μA
Shutdown Current	V <sub>EN</sub> =0V, Including Switch Leakage		0.1	1	μA
En Input High		1			V
En Input Low				0.35	V
En Input Current	V <sub>EN</sub> = 5.5V		0.01	1	μΑ

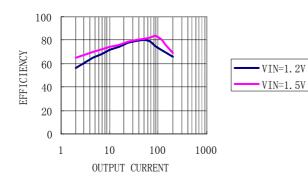


## **Typical Performance Characteristics**

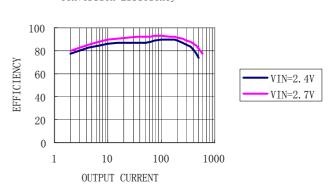
#### VOUT=3.3V



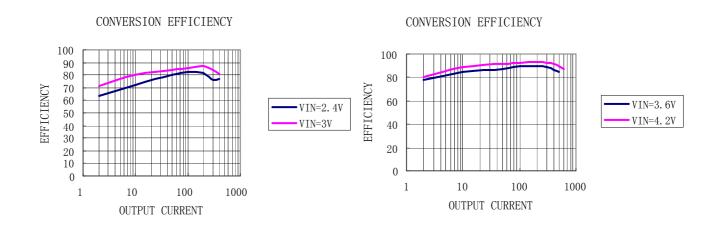




#### Conversion Efficiency



#### VOUT=5V



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### **Application Information**

**SW** (Pin 1): Switch Pin. Connect inductor between SW and  $V_{IN}$ . Keep these PCB trace lengths as short and wide as possible to reduce EMI and voltage overshoot.

**GND** (Pin 2): Signal and Power Ground. Provide a short direct PCB path between GND and the (–) side of the output capacitor(s).

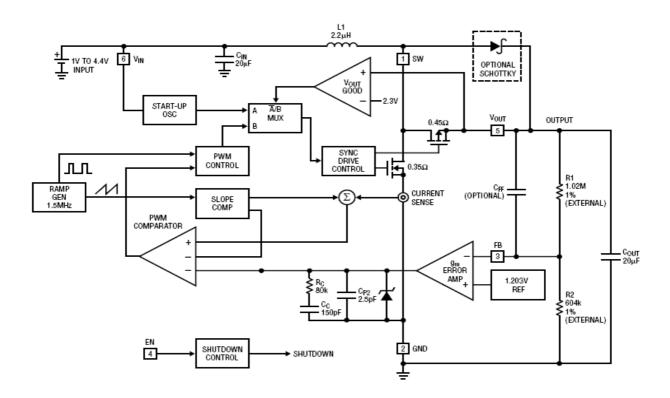
**FB** (Pin 3): Feedback Input to the  $g_m$  Error Amplifier. Connect resistor divider tap to this pin. The output voltage can be adjusted from 2.5V to 5V by:  $V_{OUT} = 1.212V \cdot [1 + (R1/R2)]$ 

**EN (Pin 4):** Logic Controlled Shutdown Input. EN = High: Normal free running operation, 1.5MHz typical operating frequency. EN = Low: Shutdown, quiescent current <1 $\mu$ A. Output capacitor can be completely discharged through the load or feedback resistors.

 $V_{\text{OUT}}$  (**Pin 5**): Output Voltage Sense Input and Drain of the Internal Synchronous Rectifier MOSFET. Bias is derived from  $V_{\text{OUT}}$ . PCB trace length from  $V_{\text{OUT}}$  to the output filter capacitor(s) should be as short and wide as possible.

 $V_{IN}$  (Pin 6): Battery Input Voltage. The device gets its start-up bias from  $V_{IN}$ . Once  $V_{OUT}$  exceeds  $V_{IN}$ , bias comes from  $V_{OUT}$ . Thus, once started, operation is completely independent from  $V_{IN}$ . Operation is only limited by the output power level and the battery's internal series resistance.

### **Functional Diagram**





#### **PCB LAYOUT GUIDELINES**

The high speed operation of the KX3001 demands careful attention to board layout. You will not get advertised performance with careless layout. Figure 2 shows the recommended component placement. A large ground pin copper area will help to lower the chip temperature. A multilayer board with a separate ground plane is ideal, but not absolutely necessary.

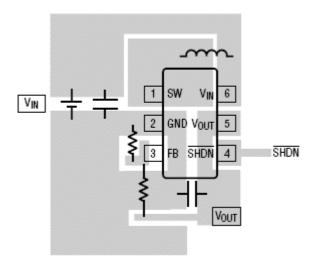


Figure 2. Recommended Component Placement for Single Layer Board

#### **INDUCTOR SELECTION**

The KX3001 can utilize small surface mount and chip inductors due to its fast 1.5MHz switching frequency. Typically, a  $2.2\mu H$  inductor is recommended for most applications. Larger values of inductance will allow greater output current capability by reducing the inductor ripple current. Increasing the inductance above  $10\mu H$  will increase size while providing little improvement in output current capability.

$$I_{OUT(MAX)} = \eta \bullet \left(I_P - \frac{V_{IN} \bullet D}{f \bullet L \bullet 2}\right) \bullet \left(1 - D\right)$$

where:

 $\eta$  = estimated efficiency

 $I_P$  = peak current limit value (0.6A)

 $V_{IN}$  = input (battery) voltage

D = steady-state duty ratio =  $(V_{OUT} - V_{IN})/V_{OUT}$ 

f = switching frequency (1.5MHz typical)

L = inductance value



The inductor current ripple is typically set for 20% to 40% of the maximum inductor current (I<sub>P</sub>). High frequency ferrite core inductor materials reduce frequency dependent power losses compared to cheaper powdered iron types, improving efficiency. The inductor should have low ESR (series resistance of the windings) to reduce the I<sup>2</sup>R power losses, and must be able to handle the peak inductor current without saturating. Molded chokes and some chip inductors usually do not have enough core to support the peak inductor currents of 850mA seen on the KX3001. To minimize radiated noise, use a toroid, pot core or shielded bobbin inductor. See Table 1 for some suggested components and suppliers.

**Table 1. Recommended Inductors** 

PART	<b>L</b> (μ <b>H</b> )	MAX DCR mΩ	MAX DC CURRENT (A)	SIZE $W \times L \times H$ $(mm^3)$	VENDOR
CDRH3D16	2.2	75	1.20	3.8 × 3.8 × 1.8	Sumida
CDH3B16	2.2	70	1.20	4.0 × 4.0 × 1.8	Ceaiya

#### **OUTPUT AND INPUT CAPACITOR SELECTION**

Low ESR (equivalent series resistance) capacitors should be used to minimize the output voltage ripple. Multilayer ceramic capacitors are an excellent choice as they have extremely low ESR and are available in small footprints. A  $4.7\mu F$  to  $20\mu F$  output capacitor is sufficient for most applications. Larger values up to  $22\mu F$  may be used to obtain extremely low output voltage ripple and improve transient response. An additional phase lead capacitor may be required with output capacitors larger than  $10\mu F$  to maintain acceptable phase margin. X5R and X7R dielectric materials are preferred for their ability to maintain capacitance over wide voltage and temperature ranges.

Low ESR input capacitors reduce input switching noise and reduce the peak current drawn from the battery. It follows that ceramic capacitors are also a good choice for input decoupling and should be located as close as possible to the device. A  $10\mu F$  input capacitor is sufficient for virtually any application. Larger values may be used without limitations. Table 2 shows a list of several ceramic capacitor manufacturers. Consult the manufacturers directly for detailed information on their entire selection of ceramic capacitors.

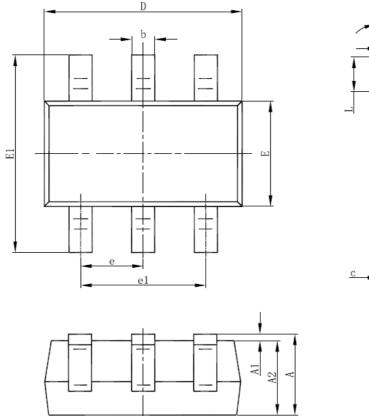
**Table 2. Capacitor Vendor Information** 

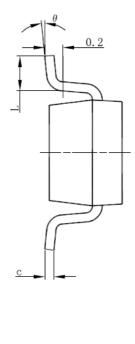
SUPPLIER	WEBSITE
AVX	www.avxcorp.com
Murata	www.murata.com
Taiyo Yuden	www.t-yuden.com



# **Packaging Information**

## **SOT-23-6 Package Outline Dimension**





Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
Α	1.050	1.250	0.041	0.049
A1	0.000	0.100	0.000	0.004
A2	1.050	1.150	0.041	0.045
b	0.300	0.500	0.012	0.020
С	0.100	0.200	0.004	0.008
D	2.820	3.020	0.111	0.119
E	1.500	1.700	0.059	0.067
E1	2.650	2.950	0.104	0.116
е	0.950(BSC )		0.037(BSC)	
e1	1.800	2.000	0.071	0.079
L	0.300	0.600	0.012	0.024
θ	0°	8°	0°	8°