LINEAR INTEGRATED CIRCUIT

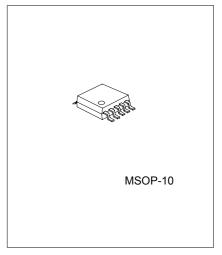
SINGLE-PHASE FULL-WAVE MOTOR DRIVER IC

DESCRIPTION

The UTC LB1962 is a Single-phase full-wave motor driver designed specially for small DC fans. For example, CPU cooling fans.

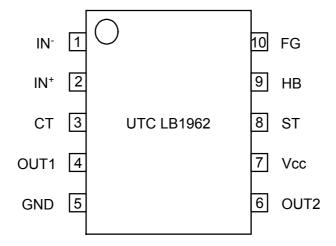
FEATURES

- * Wide operating voltage 5V or12V are both acceptable
- * Built-in Hall amplifier and Hall bias circuit.
- * Built-in lockup and thermal protection with automatic recovery circuits
- * Rotation detection output
- * start/stop pin for standby mode control.

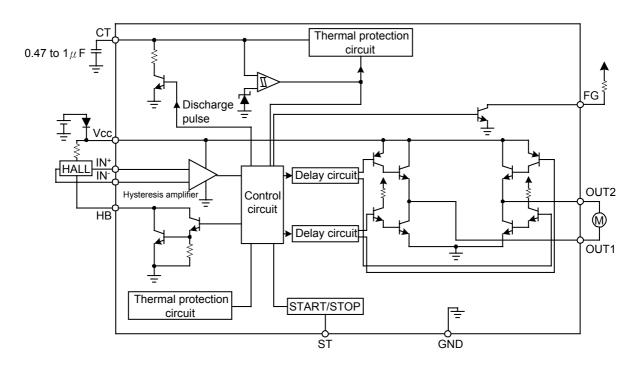


*Pb-free plating product number: LB1962L

PIN CONFIGURATION



BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

(Ta=25°C)

PARAMETER	SYMBOL	RATINGS	UNIT	
Maximum Supply voltage	V _{CC} (max)	17	V	
Maximum Output current	I _{OUT} (max)	0.5	Α	
Maximum Output withstand voltage	V _{OUT} (max)	15	V	
Maximum output withstand voltage	V _F (max)	17	V	
Maximum autout august	I _F (max)	5	mA	
Maximum output current	I _R (max)	5	mA	
HB maximum output current	I _B (max)	10	mA	
ST maximum input voltage	V _{ST} (max)	15	V	
Allowable power dissipation (With specified substrate*)	P _D	850	mW	
Operating Temperature Range	T _{OPR}	-30 ~ +85	$^{\circ}\!\mathbb{C}$	
Storage Temperature Range	T _{STG}	-40 ~ +150	$^{\circ}\mathbb{C}$	

^{*}Specified substrate: 114.3×76.2×1.5mm³ glass epoxy.

RECOMMANDED OPERATING RATINGS

(Ta=25°ℂ)

PARAMETER	SYMBOL	RATINGS	UNIT	
Power supply voltage	Vcc	3.8 ~ 16.8	V	
ST input High level voltage	ST _H	3 ~ 14	V	
ST input Low level voltage	STL	-0.3 ~ +0.4	V	
Hall input common mode voltage range	V _{ICM}	0.2 ~ Vcc-1.5	V	

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LINEAR INTEGRATED CIRCUIT

ELECTRICAL CHARACTERISTICS

(Ta=25°C, V_{CC}=5V)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		In drive mode (CT= [L] , ST= [L])		6.5	9.1	mA
Current drain	I _{CC}	In lockup protection mode (CT= [H] , ST= [L])		2.2	3.1	mA
		In standby mode (ST= [H])		110	150	μΑ
Lockup detection Capacitor charge current	I _{CT} ¹		1.9	2.8	3.7	μA
Capacitor discharge current	I_{CT}^2		0.32	0.46	0.60	μΑ
Capacitor charge/discharge current ratio	R _{CT}	R _{CD} =I _{CT} ¹ /I _{CT} ²	5.0	6.0	7.0	
CT charge voltage	V _{CT} ¹		2.55	2.75	2.95	V
CT discharge voltage	V_{CT}^2		1.6	1.8	2.0	V
Output Low level voltage	V_{OL}	I _O =200mA		0.2	0.3	V
Output High level voltage	V_{OH}	I _O =200mA	3.9	4.1		V
Hall input sensitivity	V_{HN}	Zero peak value (Including offset and hysteresis)		7	15	mV
Output pin Low voltage	V_{FG}	I _{RD} , I _{FG} =5mA		0.1	0.3	V
Output pin leakage current	I_{FGL}	V _{RD} , V _{FG} =15V			30	μΑ
HB output Low voltage	V_{HBL}	I _{HB} =5mA		1.0	1.3	V
ST pin input current	I _{ST}	V _{ST} =5V		75	100	μΑ

TRUTH TABLE

ST	IN⁻	IN ⁺	CT	OUT1	OUT2	FG	HB	Mode
Н				off	off	off	off	Standby
	Н	L	L	Н	L	Н		Deteting
	L	Н		L	Н	L	L	Rotating
L			Н	off	off		L	Lockup protection activated

LINEAR INTEGRATED CIRCUIT

DESIGN REFERENCE

(1) V_{cc} pin

Power supply pin for whole I_C.

(2) OUT1, OUT2 pins

Single-phase coil output pins.

Bipolar forward or reverse drive output determined by OUT1 or OUT2 high. Built-in regenerative circuit that regenerates kickback current between lower side NPN outputs if a diode is used for protection against reverse connection.

(3) IN⁻, IN⁺ pins

Hall signal input pins

The Hall signal is amplified into a square wave by the Hall amplifier with hysteresis characteristics of ± 3.5 mV (typ.). The Hall signal amplitude should be 70 mV or more.

(4) CT pin

This pin serves timing capacitor connecting pin between CT and GND.

The capacitor determines timing of the built-in lockup protection circuit for preventing coil burnout when motor is locked. Once normal motor rotating condition is restored, the automatic recovery circuit will reset itself.

Adjusting the capacitance alters the lockup detection time.

When a 0.47 mF capacitor is connected between CT and GND

Lockup detection time :approx. 0.5s

Lockup protection time/automatic recovery time :approx. 0.16s (output ON)

:approx. 1s (output OFF)

Connecting this pin to ground when lockup function is not used

(6) FG pin

Open-collector output pin for rotation frequency detection.

When $IN^- = High$ and $IN^+ = Low$, then FG = Low

When $IN^- = Low$ and $IN^+ = High$, then FG = High

(7) ST pin and HB pin

ST pin: When input to this pin is High, motor drive is stopped (OUT is high impedance).

HB pin: Hall bias switching pin. At ST pin High input, Hall bias is switched to reduce current drain in fan standby mode.

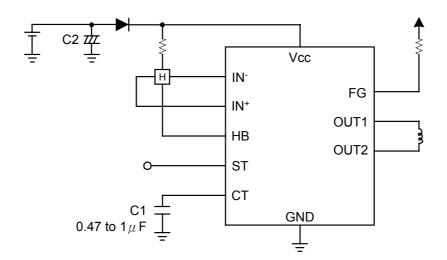
If not used, both pins should be open.

(8) Thermal protection circuit

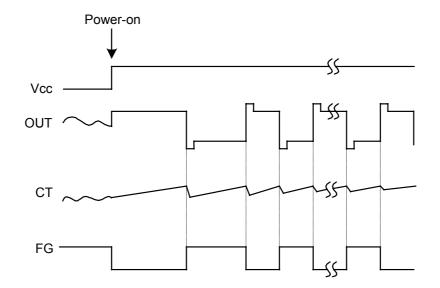
When junction temperature Tj of IC is or over about 150° , output current limiter is activated to protect against damage.



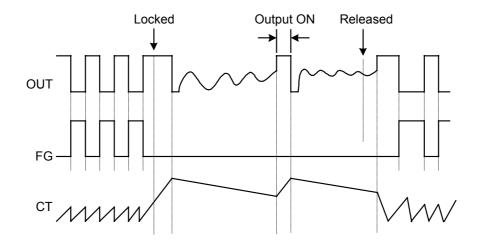
SAMPLE APPLICATION CIRCUIT



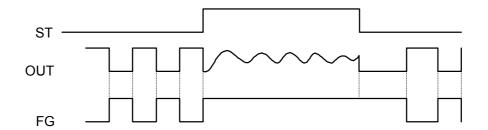
Startup



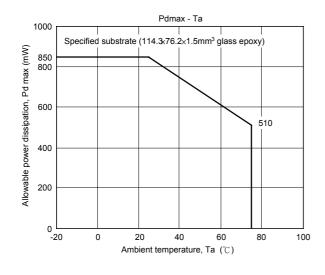
Locked-up protection and automatic recovery curves

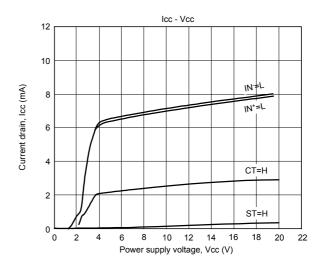


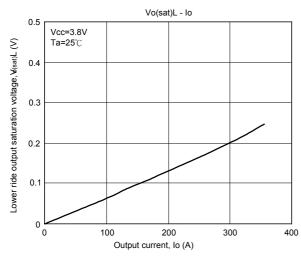
Start or stop curve

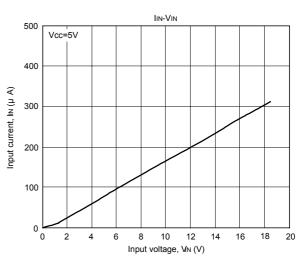


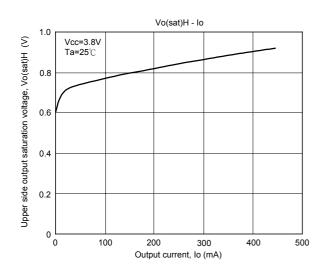
TYPICAL CHARACTERISTION

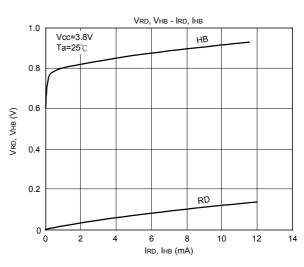












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