Ordering number: EN 4464A

CMOS LSI

No. 4464A

LC72140, LC72140M

PLL Frequency Synthesizers

Overview

The LC72140 and LC72140M are high-performance, phase-locked loop (PLL) frequency synthesizers that operate over the VHF, MW and LW wave bands. They feature excellent frequency tracking, making them ideal as a reference frequency source for use in AM/FM radio receivers.

The LC72140 and LC72140M operate from a 5 V supply. The LC72140 is available in 24-pin DIPs, and the LC72140M, in 24-pin MFPs.

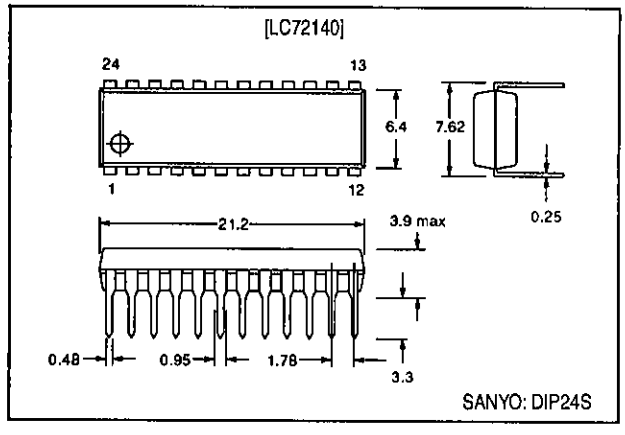
Features

- High-speed programmable dividers for
  - 10 to 160 MHz on FMIN using pulse swallower
  - 0.5 to 40.0 MHz on AMIN using pulse swallower and direct division
- General-purpose counters (used together with the SD in IF count mode)
  - HCTR for 0.4 to 25.0 MHz frequency measurement
  - LCTR for 10 to 500 kHz frequency measurement and 1 Hz to 20 kHz period measurement
- 4.5 or 7.2 MHz crystal
- Twelve selectable reference frequencies (1, 3, 5, 9, 10, 3.125, 6.25, 12.5, 25, 30, 50 and 100 kHz)
- Phase comparator
  - Insensitive band control
  - Unlock detection
  - Sub-charge pump for high-speed locking
  - Deadlock clear circuit
- C^2B input/output data interface
- Power-ON reset circuit
- Built-in MOS transistor for a low-pass filter
- Inputs/outputs (using five general-purpose input/output ports)
  - Maximum of seven inputs
  - Maximum of seven outputs (three n-channel open-drain and four CMOS outputs)
- 5 V supply
- 24-pin DIP (LC72140) and 24-pin MFP (LC72140M)

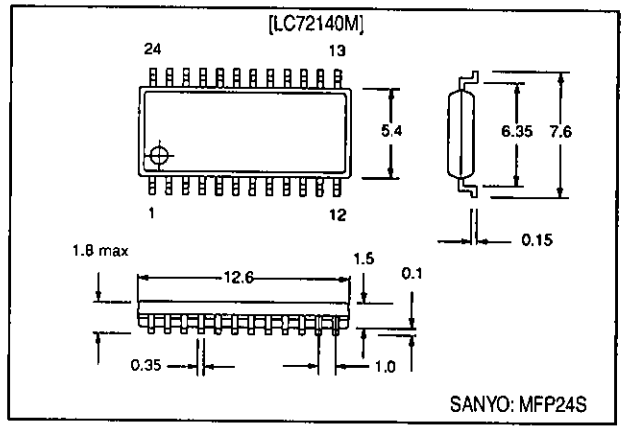
Package Dimensions

Unit: mm

3067-DIP24S



3112-MFP24S



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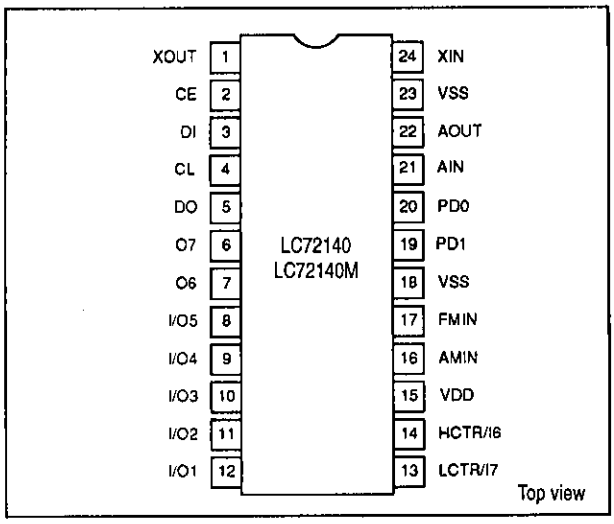
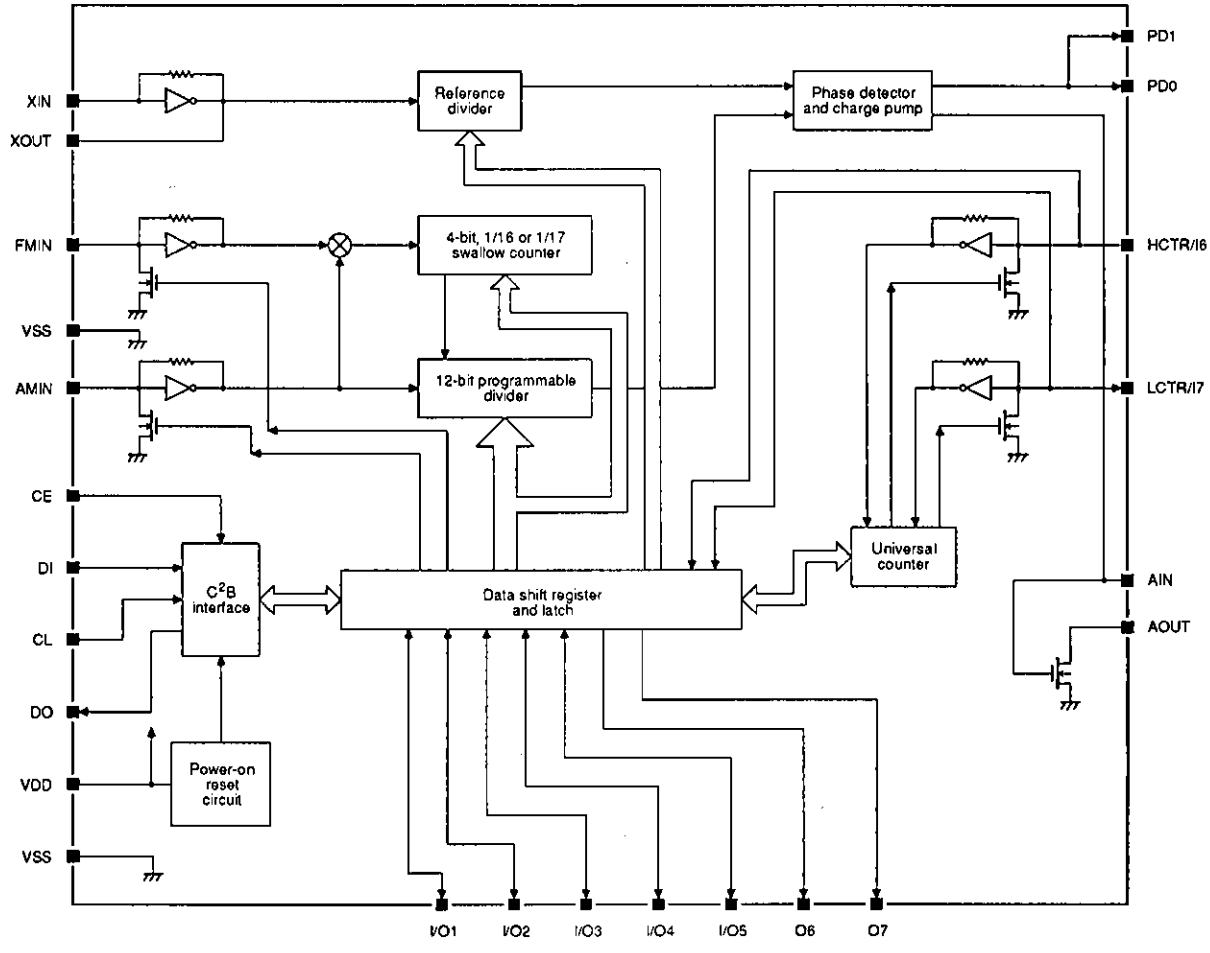
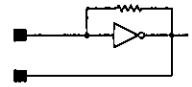
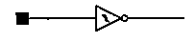
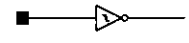
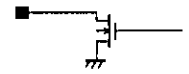
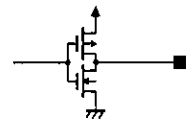
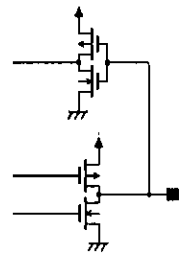
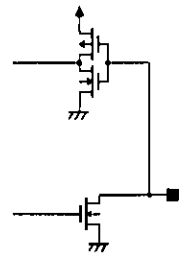
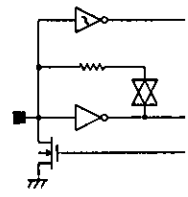
Pin Assignment

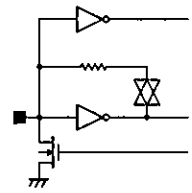
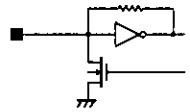
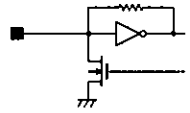
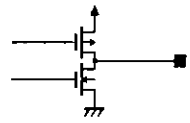
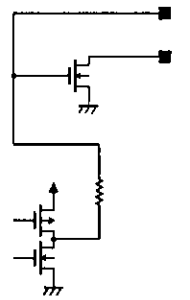


Block Diagram



Pin Functions

Number	Name	Equivalent circuit	Function
1	XOUT		4.5 or 7.2 MHz crystal oscillator output
24	XIN		4.5 or 7.2 MHz crystal oscillator input
2	CE		Chip-enable input
3	DI		Data input from microcontroller
4	CL		Clock input
5	DO		Data output to microcontroller
6	O7		OUT7 flag output
7	O6		OUT6 flag output
8	I/O5		General-purpose input/output ports 4 and 5
9	I/O4		
10	I/O3		General-purpose input/output ports 1 to 3
11	I/O2		
12	I/O1		
13	LCTR/I7		Period or frequency measurement general-purpose counter input and input port 7

Number	Name	Equivalent circuit	Function
14	HCTR/I6		Frequency measurement general-purpose counter input and input port 6
15	VDD		Supply voltage
16	AMIN		AM band local oscillator signal input
17	FMIN		FM band local oscillator signal input
19	PD1		Phase-detector charge pump outputs
20	PD0		
21	AIN		Analog low-pass filter transistor input
22	AOUT		Analog low-pass filter transistor output
18, 23	VSS		Ground

Specifications

Absolute Maximum Ratings

Parameter	Symbol	Ratings	Unit
Supply voltage range	V_{DD}	–0.3 to +7.0	V
CE, CL and DI input voltage range	V_{IN1}	–0.3 to +7.0	V
I/O1 to I/O3 input voltage range	V_{IN2}	–0.3 to +15.0	V
Input voltage range for all other pins	V_{IN3}	–0.3 to V_{DD} + 0.3	V
DO output voltage range	V_{OUT1}	–0.3 to +7.0	V
I/O1 to I/O3 and AOUT output voltage range	V_{OUT2}	–0.3 to +15.0	V

Parameter	Symbol	Ratings	Unit
Output voltage range for all other pins	V_{OUT3}	–0.3 to V_{DD} + 0.3	V
I/O4, I/O5, O6 and O7 output current range	I_{OUT1}	0 to 3.0	mA
I/O1 to I/O3, DO and AOUT output current range	I_{OUT2}	0 to 6.0	mA
Power dissipation	P_D	350 (DIP24S, $T_a \leq 85$ °C)	mW
		160 (MFP24S, $T_a \leq 85$ °C)	
Operating temperature range	Topr	–40 to +85	°C
Storage temperature range	T_{stg}	–55 to +125	°C

Allowable Operating Ranges

T_a = 25 °C, V_{SS} = 0 V

Parameter	Symbol	Ratings	Unit
Supply voltage	V_{DD}	5	V
Supply voltage range	V_{DD1}	4.5 to 5.5	V

Electrical Characteristics

T_a = –40 to +85 °C, V_{DD} = 4.5 to 5.5 V, V_{SS} = 0 V unless otherwise noted

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
Supply current	I_{DD}	f_{IN2} = 160 MHz, V_{IN2} = 100 mV, f_{XTAL} = 7.2 MHz, f_{IN4} = 25 MHz, V_{IN4} = 40 mV	–	10	15	mA
		PLL inhibited, crystal oscillator running, f_{XTAL} = 7.2 MHz	–	0.5	–	
		PLL inhibited, crystal oscillator stopped	–	–	10	µA
CL, CE, DI, I/O1 to I/O5, HCTR/I6 and LCTR/I7 LOW-level input voltage	V_{IL1}		0	–	0.8	V
LCTR/I7 LOW-level input voltage	V_{IL2}	Pulse wave, period measurement	0	–	0.8	V
CE, CL, DI and I/O1 to I/O3 HIGH-level input voltage	V_{IH1}		2.2	–	6.5	V
I/O4, I/O5, HCTR/I6 and LCTR/I7 HIGH-level input voltage	V_{IH2}		2.2	–	V_{DD}	V
LCTR/I7 HIGH-level input voltage	V_{IH3}	Pulse wave, period measurement	2.2	–	V_{DD}	V
XIN rms input amplitude	V_{IN1}		0.2	–	1.5	V
FMIN rms input amplitude	V_{IN2}	50 ≤ f < 130 MHz. See Programmable Divider section.	0.07	–	1.5	V
		10 ≤ f < 50 and 130 ≤ f ≤ 160 MHz. See Programmable Divider section.	0.10	–	1.5	

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
AMIN rms input amplitude	V_{IN3}	2 ≤ f < 25 MHz. See Programmable Divider section.	0.04	–	1.5	V
		25 ≤ f ≤ 40 MHz. See Programmable Divider section.	0.07	–	1.5	
		0.5 ≤ f < 2.5 MHz. See Programmable Divider section.	0.04	–	1.5	
		2.5 ≤ f ≤ 10 MHz. See Programmable Divider section.	0.07	–	1.5	
HCTR/I6 rms input amplitude	V_{IN4}		0.04	–	1.5	V
LCTR/I7 rms input amplitude	V_{IN5}		0.04	–	1.5	V
PD0, PD1, I/O4, I/O5, O6 and O7 LOW-level output voltage	V_{OL1}	I_O = 1 mA	–	–	1.0	V
I/O1 to I/O3 and DO LOW-level output voltage	V_{OL2}	I_O = 5 mA	–	–	1.0	V
AOUT LOW-level output voltage	V_{OL3}	I_O = 1 mA, V_{AIN} = 1.3 V	–	–	0.5	V
AIN LOW-level output voltage	V_{OL4}	I_O = 1 mA	–	0.7	1.5	V
PD0, PD1, I/O4, I/O5, O6 and O7 HIGH-level output voltage	V_{OH1}	I_O = 1 mA	V_{DD} – 1.0	–	–	V
AIN HIGH-level output voltage	V_{OH2}	I_O = 1 mA	V_{DD} – 1.5	V_{DD} – 0.7	–	V
DO output voltage	V_{OUT1}		0	–	6.5	V
I/O1 to I/O3 and AOUT output voltage	V_{OUT2}		0	–	13	V
CE, CL and DI LOW-level input current	I_{IL1}	V_{IN} = 0 V	–	–	5.0	µA
I/O1 to I/O5 LOW-level input current	I_{IL2}	V_{IN} = 0 V	–	–	5.0	µA
HCTR/I6 and LCTR/I7 LOW-level input current	I_{IL3}	V_{IN} = 0 V	–	–	5.0	µA
XIN LOW-level input current	I_{IL4}	V_{IN} = 0 V	3.5	–	11	µA
FMIN, AMIN, HCTR/I6 and LCTR/I7 LOW-level input current	I_{IL5}	V_{IN} = 0 V	6.0	–	18	µA
CE, CL and DI HIGH-level input current	I_{IH1}	V_{IN} = 6.5 V	–	–	5.0	µA
I/O1 to I/O3 HIGH-level input current	I_{IH2}	V_{IN} = 13 V	–	–	5.0	µA
I/O4, I/O5, HCTR/I6 and LCTR/I7 HIGH-level input current	I_{IH3}	V_{IN} = V_{DD}	–	–	5.0	µA
XIN HIGH-level input current	I_{IH4}	V_{IN} = V_{DD}	3.5	–	11	µA
FMIN, AMIN, HCTR/I6 and LCTR/I7 HIGH-level input current	I_{IH5}	V_{IN} = V_{DD}	6.0	–	18	µA
XIN input frequency	f_{IN1}	Sine wave, capacitive coupling	1.0	–	8.0	MHz
FMIN input frequency	f_{IN2}	Sine wave, capacitive coupling	10	–	160	MHz
AMIN input frequency	f_{IN3}	Sine wave, capacitive coupling	0.5	–	40.0	MHz

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
HCTR/I6 input frequency	f_{IN4}	Sine wave, capacitive coupling	0.4	–	25	MHz
LCTR/I7 input frequency	f_{IN5}	Sine wave, capacitive coupling	10	–	500	kHz
		Period measurement, pulse wave, DC coupling	0.001	–	20.0	
Crystal oscillator frequency	f_{XTAL}	Crystal impedance ≤ 120 Ω	4.0	–	8.0	MHz
CE, CL, DI and LCTR/I7 hysteresis width	V_H		–	$0.1V_{DD}$	–	V
XIN internal resistance	R_{I1}		–	1.0	–	MΩ
FMIN internal resistance	R_{I2}		–	500	–	kΩ
AMIN internal resistance	R_{I3}		–	500	–	kΩ
HCTR/I6 internal resistance	R_{I4}		–	500	–	kΩ
LCTR/I7 internal resistance	R_{I5}		–	500	–	kΩ
AIN sub-charge pump internal resistance	R1S		–	500	–	Ω
I/O1 to I/O3 and AOUT output leakage current	I_{OFF1}	V_O = 13 V	–	–	5.0	μA
DO output leakage current	I_{OFF2}	V_O = 6.5 V	–	–	5.0	μA
PD0, PD1 and AIN tristate LOW-level leakage current	I_{OFFL}	V_O = 0 V	–	0.01	200	nA
PD0, PD1 and AIN tristate HIGH-level leakage current	I_{OFFH}	$V_O = V_{DD}$	–	0.01	200	nA
FMIN input capacitance	C_{IN}		–	6	–	pF
DI to CL data setup time	t_{SU}		0.45	–	–	μs
DI to CL data hold time	t_{HD}		0.45	–	–	μs
CL LOW-level clock pulsewidth	t_{CL}		0.45	–	–	μs
CL HIGH-level clock pulsewidth	t_{CH}		0.45	–	–	μs
CL to CE chip enable wait time	t_{EL}		0.45	–	–	μs
CE to CL chip enable setup time	t_{ES}		0.45	–	–	μs
CL to CE chip enable hold time	t_{EH}		0.45	–	–	μs
Chip enable to data latch time	t_{LC}		–	–	0.45	μs
CL to DO data output time	t_{DC}	Depends on pull-up resistor	–	–	0.2	μs
CE to DO data output time	t_{DH}					

Functional Description

Serial Data Input

The LC72140 and LC72140M operating parameters are initialized by two 40-bit data words on the serial data input, DI, as shown in Figures 1 and 2 and Table 1.

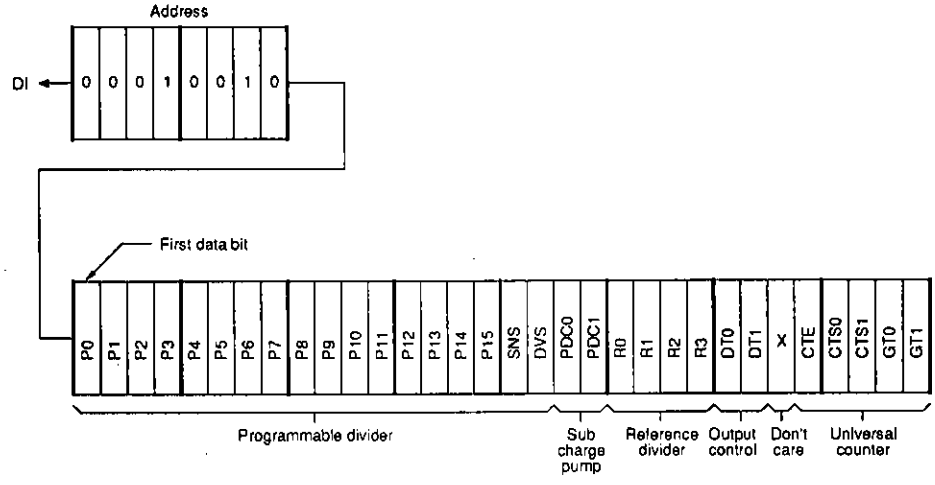


Figure 1. Input data word IN1

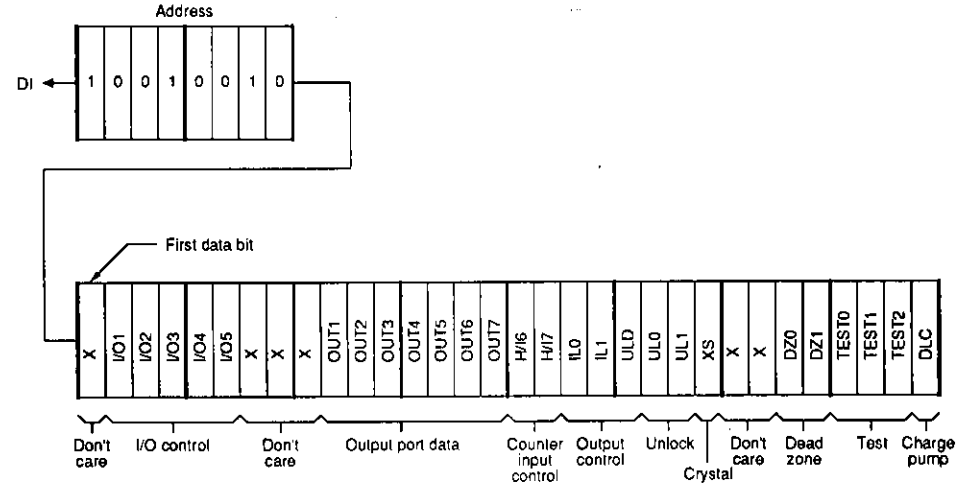


Figure 2. Input data word IN2

Table 1. Input data functions

<table>
<tr><th>Name</th><th>Function</th><th>Related bits</th></tr>
<tr><td>P0 to P15,
SNS, DVS</td><td>Programmable divider ratio
P15 is the msb. The divider ratio, frequency range and lsb are determined by the setting of the DVS and SNS flags as shown in Tables 2 and 3. P0 to P3 are ignored if P4 is the lsb.
Table 2. Divider ratio settings
<table><tr><th>DVS</th><th>SNS</th><th>lsb</th><th>Divider ratio</th></tr><tr><td>1</td><td>×</td><td>P0</td><td>272 to 65535</td></tr><tr><td>0</td><td>1</td><td>P0</td><td>272 to 65535</td></tr><tr><td>0</td><td>0</td><td>P4</td><td>4 to 4095</td></tr></table>Note
× = don't care
Table 3. Frequency range settings
<table><tr><th>DVS</th><th>SNS</th><th>Input port</th><th>Input frequency range</th></tr><tr><td>1</td><td>×</td><td>FMIN</td><td>10 to 160 MHz</td></tr><tr><td>0</td><td>1</td><td>AMIN</td><td>2 to 40 MHz</td></tr><tr><td>0</td><td>0</td><td>AMIN</td><td>0.5 to 10 MHz</td></tr></table>Note
× = don't care</td><td></td></tr>
<tr><td>PDC0, PDC1</td><td>Charge pump control
Bits PDC0 and PDC1 control the charge pump state as shown in Table 4. The sub-charge pump is connected to the gate of the lowpass filter transistor. This can be used in conjunction with PD0 and PD1 (main charge pump) to build a fast locking PLL.
Table 4. Charge pump state selection
<table><tr><th>PDC0</th><th>PDC1</th><th>Charge pump state</th></tr><tr><td>0</td><td>×</td><td>High-impedance</td></tr><tr><td>1</td><td>1</td><td>Operating (operates continuously)</td></tr><tr><td>1</td><td>0</td><td>Operating (when PLL is unlocked)</td></tr></table>Note
× = don't care</td><td>UL0, UL1, DLC</td></tr>
</table>

Table 1. Input data functions—continued

<table>
<tr><th>Name</th><th>Function</th><th>Related bits</th></tr>
<tr><td>R0 to R3</td><td>Reference frequency select
Bits R0 to R3 disable the PLL or select the reference frequency as shown in Table 5.
Table 5. Reference frequency selection
<table>
<tr><th>R_3</th><th>R_2</th><th>R_1</th><th>R_0</th><th>Reference frequency (kHz)</th></tr>
<tr><td>0</td><td>0</td><td>0</td><td>0</td><td>100</td></tr>
<tr><td>0</td><td>0</td><td>0</td><td>1</td><td>50</td></tr>
<tr><td>0</td><td>0</td><td>1</td><td>0</td><td>25</td></tr>
<tr><td>0</td><td>0</td><td>1</td><td>1</td><td>25</td></tr>
<tr><td>0</td><td>1</td><td>0</td><td>0</td><td>12.5</td></tr>
<tr><td>0</td><td>1</td><td>0</td><td>1</td><td>6.25</td></tr>
<tr><td>0</td><td>1</td><td>1</td><td>0</td><td>3.125</td></tr>
<tr><td>0</td><td>1</td><td>1</td><td>1</td><td>3.125</td></tr>
<tr><td>1</td><td>0</td><td>0</td><td>0</td><td>10</td></tr>
<tr><td>1</td><td>0</td><td>0</td><td>1</td><td>9</td></tr>
<tr><td>1</td><td>0</td><td>1</td><td>0</td><td>5</td></tr>
<tr><td>1</td><td>0</td><td>1</td><td>1</td><td>1</td></tr>
<tr><td>1</td><td>1</td><td>0</td><td>0</td><td>3</td></tr>
<tr><td>1</td><td>1</td><td>0</td><td>1</td><td>30</td></tr>
<tr><td>1</td><td>1</td><td>1</td><td>0</td><td>PLL inhibited and crystal oscillator stopped</td></tr>
<tr><td>1</td><td>1</td><td>1</td><td>1</td><td>PLL inhibited</td></tr>
</table>
When the PLL is disabled, the programmable divider is stopped, AMIN and FMIN are pulled to ground, and the charge-pump outputs become high impedance.</td><td></td></tr>
</table>

Table 1. Input data functions—continued

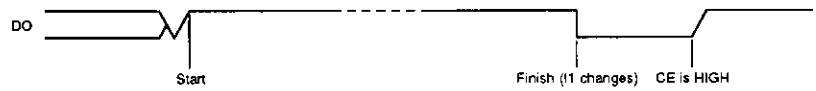
<table>
<tr><th>Name</th><th>Function</th><th>Related bits</th></tr>
<tr><td>ULD, DT0, DT1, IL0, IL1</td><td>
DO and I/O5 output control data
Bits ULD, DT0, DT1, IL0 and IL1 control the mode of outputs DO and I/O5 as shown in Tables 6 and 7.
Table 6. DO and I/O5 output flag selection
<table>
<tr><th>ULD</th><th>DT1</th><th>DT0</th><th>DO</th><th>I/O5</th></tr>
<tr><td>0</td><td>0</td><td>0</td><td>Unlock flag</td><td rowspan="4">OUT5 flag. See Note 2.</td></tr>
<tr><td>0</td><td>0</td><td>1</td><td>Open</td></tr>
<tr><td>0</td><td>1</td><td>0</td><td>End-UC flag. See note 1.</td></tr>
<tr><td>0</td><td>1</td><td>1</td><td>IN. See table 7.</td></tr>
<tr><td>1</td><td>0</td><td>0</td><td>Open</td><td rowspan="4">Unlock flag. See Note 2.</td></tr>
<tr><td>1</td><td>0</td><td>1</td><td>Open</td></tr>
<tr><td>1</td><td>1</td><td>0</td><td>End-UC flag</td></tr>
<tr><td>1</td><td>1</td><td>1</td><td>IN. See table 7.</td></tr>
</table>
Notes
1. End-UC flags that general-purpose counter operation has finished.
2. Applicable only if I/O5 is set to be an output port.


Figure 3. DO output state
Table 7. IN state selection
<table>
<tr><th>IL1</th><th>IL0</th><th>IN state</th></tr>
<tr><td>0</td><td>0</td><td>Open</td></tr>
<tr><td>0</td><td>1</td><td>I1 input</td></tr>
<tr><td>1</td><td>0</td><td>I2 input</td></tr>
<tr><td>1</td><td>1</td><td>DO goes LOW when I1 changes.</td></tr>
</table>
Notes
1. If I/O1 or I/O2 is set to be an output port, IN becomes open.
2. DO does not go LOW when the crystal oscillator has stopped.
</td><td>OUT5, I/O1, I/O2, I/O5</td></tr>
</table>

Table 1. Input data functions—continued

<table>
<tr><th>Name</th><th>Function</th><th>Related bits</th></tr>
<tr><td>CTS0, CTS1, CTE, GT0, GT1</td><td>Counter control
Bits CTS0 and CTS1 select the counter input as shown in Table 8.
Table 8. Counter input and measurement mode selection
<table>
<tr><th>Switch</th><th>CTS1</th><th>CTS0</th><th>Input</th><th>Measurement mode</th><th>Frequency range</th><th>Input rms sensitivity</th></tr>
<tr><td>S1</td><td>1</td><td>×</td><td>HCTR</td><td>Frequency</td><td>0.4 to 25.0 MHz</td><td>40 mV</td></tr>
<tr><td>S2</td><td>0</td><td>1</td><td>LCTR</td><td>Frequency</td><td>10 to 500 kHz</td><td>40 mV</td></tr>
<tr><td>S3</td><td>0</td><td>0</td><td>LCTR</td><td>Period</td><td>1 Hz to 20 kHz</td><td>(Pulse)</td></tr>
</table>
Note
× = don't care

Bit CTE starts the counter when 1, and resets the counter, when 0.
Bits GT0 and GT1 select the measurement time in frequency measurement mode or the number of periods to count in period measurement mode as shown in Table 9.
Table 9. Measurement duration selection
<table>
<tr><th rowspan="2">GT1</th><th rowspan="2">GT0</th><th colspan="2">Frequency measurement</th><th>Period measurement</th></tr>
<tr><th>Measurement duration (ms)</th><th>Wait time (ms)</th><th>Cycles</th></tr>
<tr><td>0</td><td>0</td><td>4</td><td rowspan="2">3 to 4</td><td rowspan="2">1</td></tr>
<tr><td>0</td><td>1</td><td>8</td></tr>
<tr><td>1</td><td>0</td><td>32</td><td rowspan="2">7 to 8</td><td rowspan="2">2</td></tr>
<tr><td>1</td><td>1</td><td>64</td></tr>
</table></td><td>H/I6, L/I7</td></tr>
<tr><td>I/O1 to I/O5</td><td>Input/output port control
Bits I/O1 to I/O5 set the direction of the ports. Each pin is an input when the corresponding bit is 0, and an output, when the bit is 1. All ports are set to be inputs after power-ON reset.</td><td>OUT1 to OUT5, ULD</td></tr>
<tr><td>OUT1 to OUT7</td><td>Output port data
Bits OUT1 to OUT7 set the output values of the O1 to O7 output ports. Each output is open or HIGH when the corresponding bit is 1, and LOW, when the bit is 0. A bit is ignored if the corresponding port is an input port or the unlock output.</td><td>I/O1 to I/O5, ULD</td></tr>
<tr><td>H/I6, L/I7</td><td>Counter input control
Bits H/I6 and L/I7 select the operation of the HCTR/I6 and LCTR/I7 pins. When H/I6 is 0, HCTR/I6 is an input port, and when H/I6 is 1, HCTR/I6 is the HCTR input. When L/I7 is 0, LCTR/I7 is an input port, and when L/I7 is 1, LCTR/I7 is the LCTR input.</td><td>CTS0, CTS1</td></tr>
</table>

Table 1. Input data functions—continued

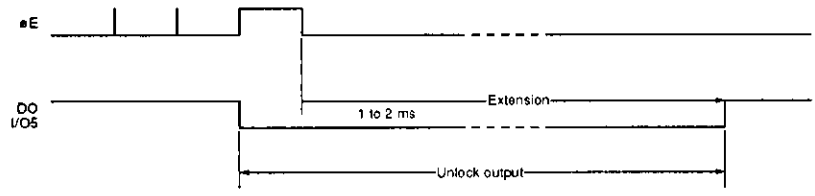
<table>
<tr><th>Name</th><th>Function</th><th>Related bits</th></tr>
<tr><td>UL0, UL1</td><td>PLL unlock detect control
Bits UL0 and UL1 select the phase error threshold and extension (ϕ_E) used to detect the PLL unlocked state as shown in Table 10 and Figure 4. When the phase error is greater than the selected error, the PLL unlock detector output goes LOW.
Table 10. Unlock detection and extension selection
<table>
<tr><th>UL1</th><th>UL0</th><th>Phase error</th><th>Detector output</th></tr>
<tr><td>0</td><td>0</td><td>Stopped</td><td>Open</td></tr>
<tr><td>0</td><td>1</td><td>0</td><td>ϕ_E output</td></tr>
<tr><td>1</td><td>0</td><td>±0.56 µs</td><td>ϕ_E with 1 to 2 ms extension</td></tr>
<tr><td>1</td><td>1</td><td>±1.11 µs</td><td>ϕ_E with 1 to 2 ms extension</td></tr>
</table>


Figure 4. Phase-error extension</td><td>ULD, DT0, DT1</td></tr>
<tr><td>XS</td><td>Crystal oscillator control
Bit XS selects the oscillator frequency. When XS is 1, the frequency is 7.2 MHz, and when XS is 0, 4.5 MHz.
4.5 MHz is selected after power-ON reset.</td><td></td></tr>
<tr><td>DZ0, DZ1</td><td>Phase comparator control
Bits DZ0 and DZ1 select the phase comparator insensitive band, or dead zone.
Table 11. Insensitive band mode selection
<table>
<tr><th>DZ1</th><th>DZ0</th><th>Insensitive band (dead zone) mode</th></tr>
<tr><td>0</td><td>0</td><td>DZA</td></tr>
<tr><td>0</td><td>1</td><td>DZB</td></tr>
<tr><td>1</td><td>0</td><td>DZC</td></tr>
<tr><td>1</td><td>1</td><td>DZD</td></tr>
</table>
DZA is selected after power-ON reset.</td><td></td></tr>
<tr><td>DLC</td><td>Charge pump control
Bit DLC controls the charge pump operation. When DLC is 1, the charge pump outputs are forced to LOW, and when DLC is 0, the charge pump operates normally.
This feature can be useful to remove the PLL from a deadlock state. The PLL can deadlock if its VCO control voltage V_{tune} becomes 0 V, halting the VCO. Setting DLC to 1 sets V_{tune} to V_{CC}, restarting the VCO.
Normal operating mode is selected after power-ON reset.</td><td></td></tr>
<tr><td>TEST0 to TEST2</td><td>Test data
Bits TEST0 to TEST2 are used for in-factory device testing. Set them all to 0. They are set to zero after a power-ON reset.</td><td></td></tr>
</table>

Serial Data Input Timing

The timing for the serial data input words is shown in Figure 5. The first eight bits are the mode select bits.

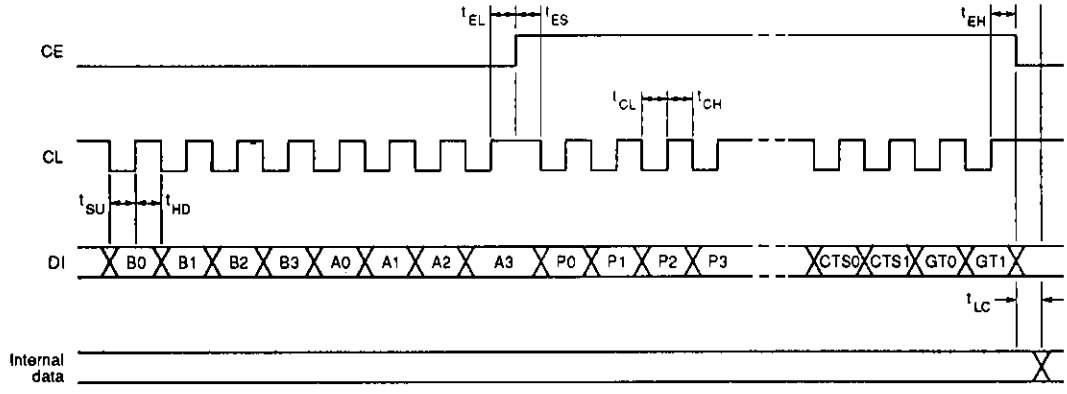


Figure 5. Input timing

Notes

1. t_{SU}, t_{HD}, t_{EL}, t_{ES}, t_{CL}, t_{CH} and $t_{EH} > 0.45$ μs
2. $t_{LC} < 0.45$ μs

Serial Data Output

The 40-bit data word output on DO has the format and functions as shown in Figure 6 and Table 12, respectively. tively.

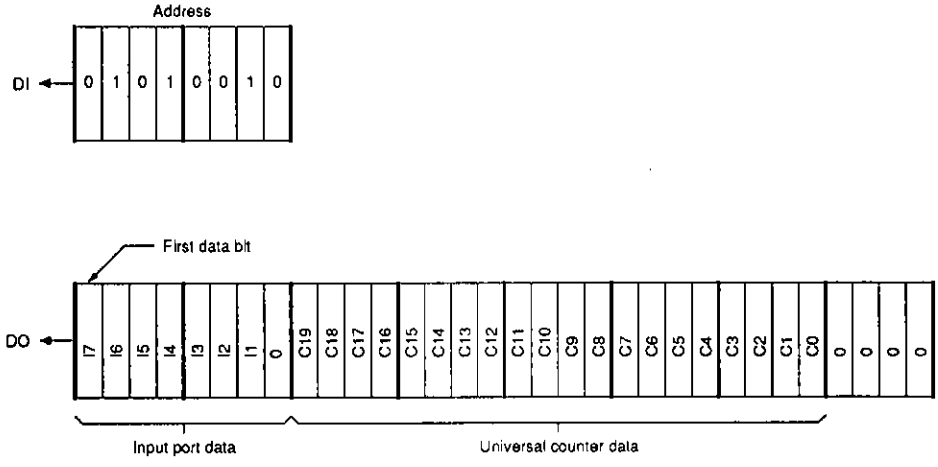


Figure 6. Output data word OUT

Table 12. Input data functions

Name	Function	Related bits
I1 to I7	Input port data Bits I1 to I7 reflect the data latched into each input port when the device changes to data output mode. I6 and I7 are zero when the corresponding port is a counter input. I1 to I5 correspond to the I/O1 to I/O5 ports, and I6 and I7, to the HCTR/I6 and LCTR/I7 inputs, respectively.	I/O1 to I/O5, H/I6, L/I7
C0 to C19	Counter contents Bits C0 to C19 are the latched contents of the 20-bit binary counter. C0 is the lsb.	CTS0, CTS1, CTE

Serial Data Output Timing

The timing for the serial data output is shown in figure 7. The first eight bits are the mode select bits.

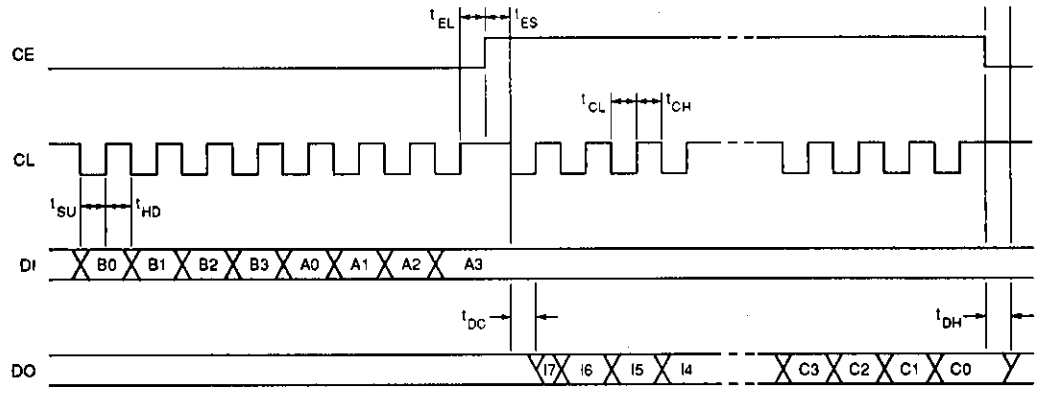


Figure 7. Output timing

Notes

1. t_{SU}, t_{HD}, t_{EL}, t_{ES}, t_{CL} and t_{CH} > 0.45 μs
2. t_{DC} and t_{DH} < 0.2 μs
3. Since DO is an open-drain output, the data transition time depends on the value of the pull-up resistor.
4. DO is normally open.

Serial Data Input/Output Mode Selection

The LC72140 and LC72140M use the C²B (computer control bus) serial data format. The first 8 bits form the address, shown in Figure 8, used to select the mode of operation as shown in Table 13.

Table 13. Serial data input/output mode selection

Input/output mode	Address								Description
	B0	B1	B2	B3	A0	A1	A2	A3	
IN1	0	0	0	1	0	0	1	0	32-bit control data input
IN2	1	0	0	1	0	0	1	0	32-bit control data input
OUT	0	1	0	1	0	0	1	0	Output data. Data is output if the clock is active.

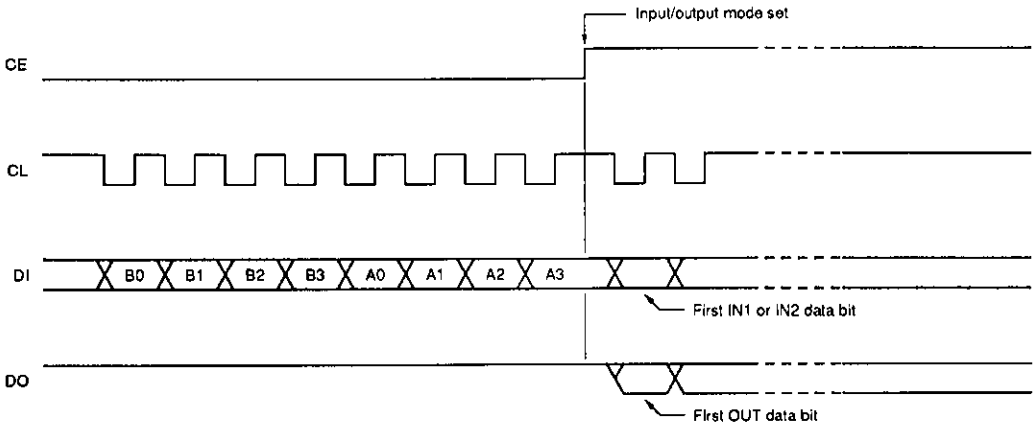


Figure 8. Mode selection address bits

Programmable Divider

The configuration of the programmable divider is shown in Figure 9. The input mode selection is shown in Table 14, and the input sensitivity, in Table 15.

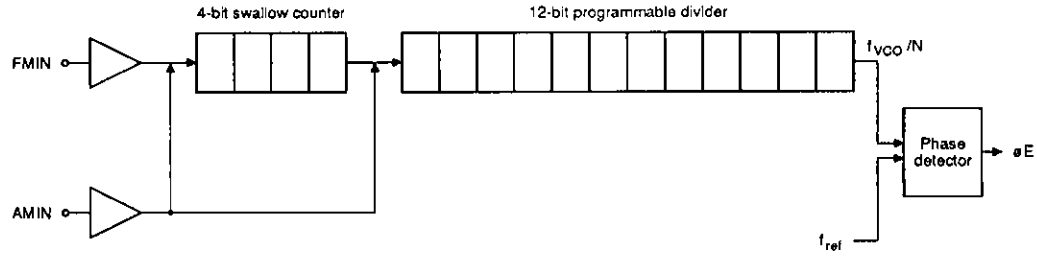


Figure 9. Programmable divider

Table 14. Programmable divider selection

DVS	SNS	1/16 and 1/17 pulse swallower	12-bit programmable divider	Input port
1	×	✓	✓	FMIN
0	1	✓	✓	AMIN
0	0	-	✓	AMIN

Note
× = don't care

Table 15. Input sensitivity

DVS	SNS	Input	Frequency (MHz)	Input rms sensitivity (mV)
1	×	FMIN	10 ≤ f < 50	100
			50 ≤ f < 130	70
			130 ≤ f < 160	100
0	1	AMIN	2 ≤ f < 25	40
			25 ≤ f < 40	70
0	0	AMIN	0.5 ≤ f < 2.5	40
			2.5 ≤ f < 10	70

Note
× = don't care

General-purpose Counter

The 20-bit general-purpose counter is used for both frequency and period measurement as shown in Figure 10. The measurement mode is selected by bits CTS0 and CTS1. The counter contents, C, in frequency measurement mode are given by

$$C = FIF \times GT$$

and in period measurement mode by

$$C = \left(\frac{1}{T}\right) \div 900\ kHz$$

The counter contents are output on DO, msb first.

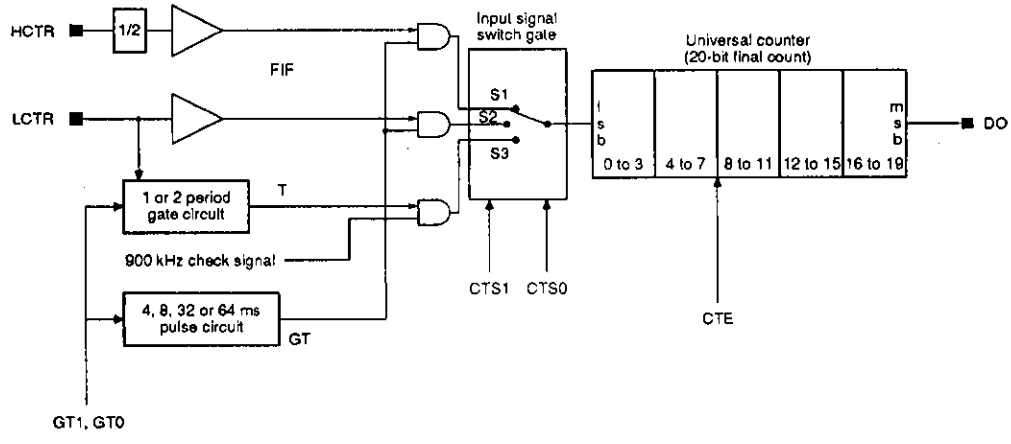


Figure 10. General-purpose counter

The LCTR signal is passed directly to the counter input. The HCTR signal is passed through a divide-by-two prescaler. The actual HCTR frequency is, therefore, two times the measured frequency. The timing for the general-purpose counter is shown in Figure 11.

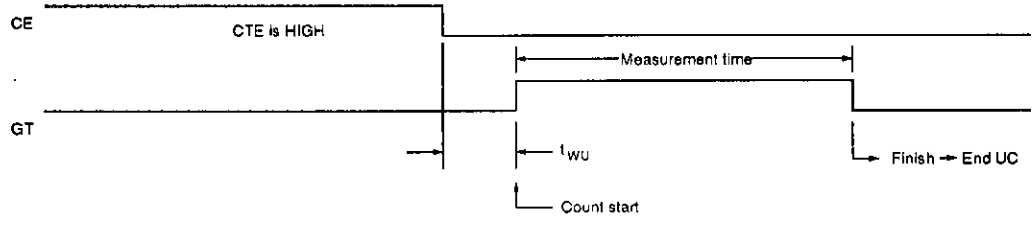


Figure 11. General-purpose counter timing

Note

t_{WU} = wait time

The counter starts when the CTE flag is set. The serial input data is latched in on the falling edge of CE. Note that the HCTR or LCTR input signal should be input within the wait time of this transition.

The period or frequency count should be read while CTE is set to 1, because the counter is reset when CTE is set to 0. Note that CTE should be set to 0 before each measurement.

In IF count mode, the IF IC's SD (station detector) signal presence is determined by the microcontroller and if an SD signal is present, the IF count buffer output turns ON and IF count becomes active. During auto-search in IF count only, there is a possibility of the count stopping even when there is no station present due to the IF count buffer output leakage.

Integrating count

When integrating the count, the count value is added to the general-purpose counter as shown in Figure 12. However, the counter can overflow. The maximum count is $2^{20} - 1$, or FFFFF in hexadecimal. DO can also be used to monitor for frequency or period measurement completion as shown in Figure 12.

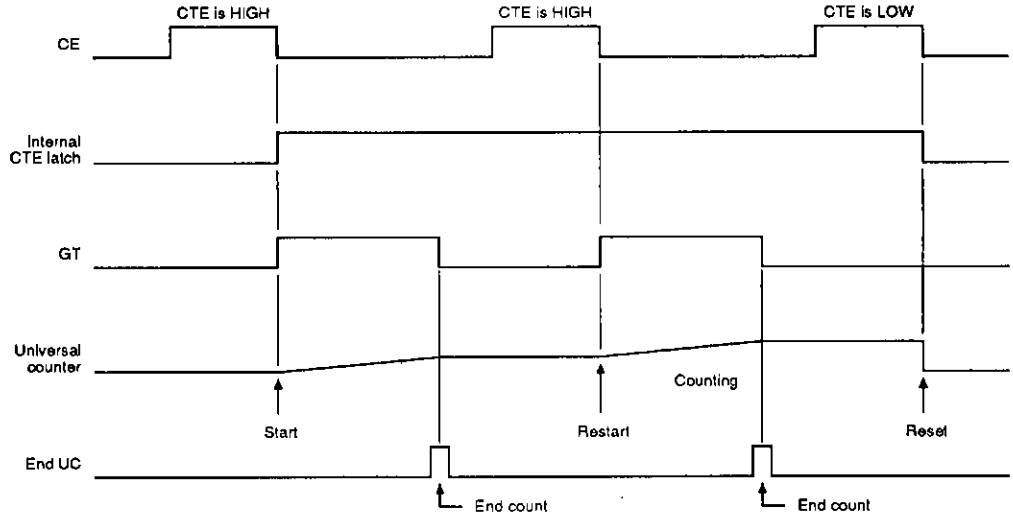


Figure 12. Integrating count timing

Charge Pump

The charge pump configuration is shown in Figure 13.

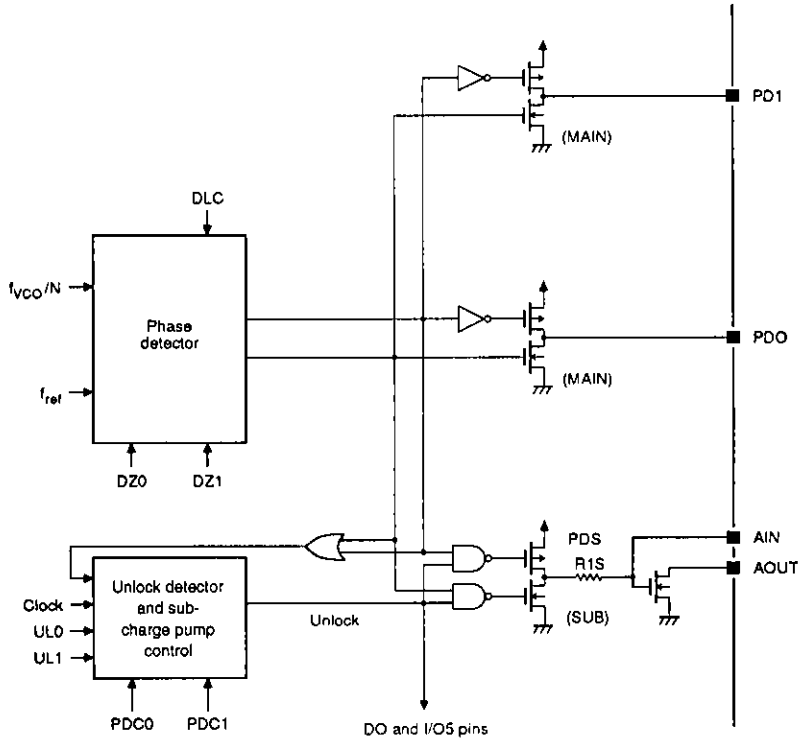


Figure 13. Charge pump

When unlock is detected following a channel change, PDS (the sub-charge pump) operates. The value of R1 changes to R1M||R1S (R1S ≅ 500 Ω), as shown in Figure 14, decreasing the low-pass filter time-constant and accelerating PLL locking.

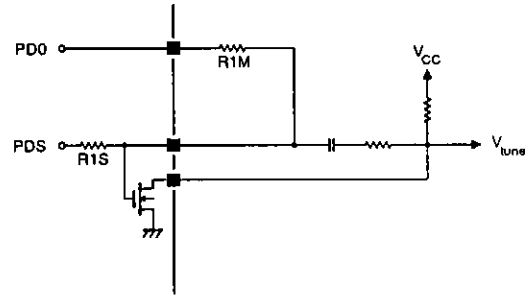


Figure 14. Charge pump connections

The local oscillator signal is divided by N. When the frequency of the divided signal is higher than the reference frequency, PD0 and PD1 are HIGH, and when lower, they are LOW. Both outputs are floating when the two signals are equal in frequency.

Pin States After Power-ON Reset

The state of the input/output ports after power-ON reset is shown in Table 16.

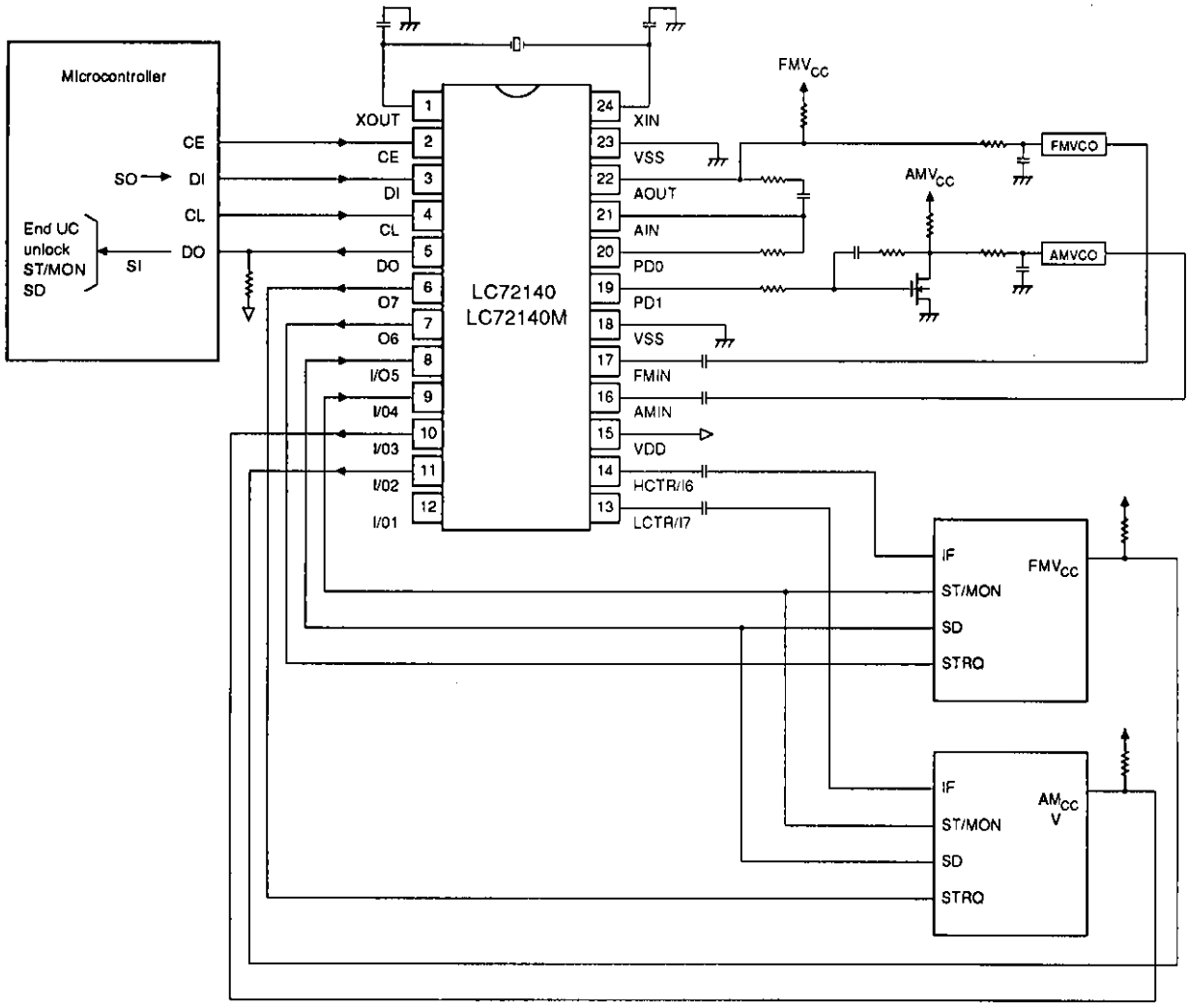
Table 16. Power-ON reset states

Pin	Reset state	Pin type
I/O1	I1	Open-drain
I/O2	I2	Open-drain
I/O3	I3	Open-drain
I/O4	I4	CMOS
I/O5	I5	CMOS
O6	O6	CMOS
O7	O7	CMOS
HCTR/I6	I6	
LCTR/I7	I7	

Notes

1. Phase comparator control
   Modes DZA and DZB do not have insensitive bands (dead zones) and, therefore, the charge pump operates continuously. Consequently, measures should be taken to ensure reference frequency sidebands do not occur.
   Modes DZC and DZD do have insensitive bands. Consequently, measures should be taken to ensure phase noise is not generated.
2. FMIN, AMIN, HCTR and LCTR
   These inputs should each be capacitively coupled using a 50 to 100 pF capacitor. Also, these capacitors should be mounted as close as possible to their respective inputs.
3. IF counting using HCTR or LCTR
   The LC72140 and LC72140M can perform IF count tuning when connected to an SD (station detector) signal from an IF IC. IF counting should start when the SD signal becomes active.
4. Using the general-purpose counter
   In IF count mode, the IF IC's SD (station detector) signal presence is determined by the microcontroller and if an SD signal is present, the IF count buffer output turns ON and IF count becomes active. During auto-search in IF count only, there is a possibility of the count stopping even when there is no station present due to the IF count buffer output leakage.

Typical Application



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