

**LC864266A, 864265A****8-bit Single Chip Microcontroller****Overview**

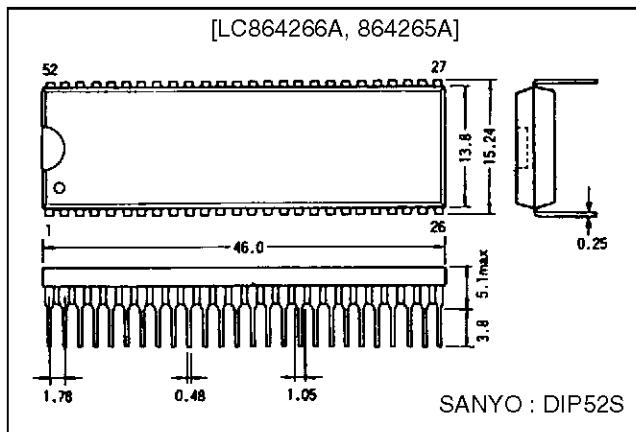
The LC864266A/65A microcontrollers are 8-bit single chip microcontrollers with the following on-chip functional blocks:

- CPU : Operable at a minimum bus cycle time of 0.5 μ s
- On-chip program ROM maximum capacity : 64 Kbytes
- On-chip look up table ROM maximum capacity : 64 Kbytes for LC864266A
32 Kbytes for LC864265A
- On-chip RAM capacity : 512 bytes
- CRT display RAM : 640 \times 9 bits
- Closed-caption TV controller and the on-screen display controller
- 16-bit timer/counter
- 4-channel \times 5-bit AD converter
- 8-bit synchronous serial-interface circuit
- Closed-caption data slicer
- 11-source 9-vectored interrupt system

All of the above functions are fabricated on a single chip.

Package Dimensions

unit : mm

3128-DIP52S**Features**

(1) Read-only program memory (ROM) :	LC864266A	65280×8 bits
	LC864265A	65280×8 bits
(2) Read-only look up table memory (ROM) :	LC864266A	65536×8 bits
	LC864265A	32768×8 bits
(3) Random access memory (RAM) :		512×8 bits
		640×9 bits (for CRT display)

SANYO Electric Co.,Ltd. Semiconductor Bussiness Headquarters
 TOKYO OFFICE Tokyo Bldg., 1-10, 1 Chome, Ueno, Taito-ku, TOKYO, 110-8534 JAPAN

(4) OSD functions

- Screen for display : 34 columns × 16 rows (standard character size)
- Display for RAM : 640 × 9 bits (6 columns for control + 34 columns for display) × 16 rows × 9 bits
- 377 kinds of user specified characters
 - Caption/Text mode : (9 × 9 dots) × 125 kinds
 - OSD mode : (12 × 18 dots) × 127 characters (127 characters can also be used in Caption/Text mode)
- Various character attributes
 - Character colors : 16 colors
 - Character background colors : 16 colors
 - Fringe / shadow colors : 16 colors
 - Full screen colors : 16 colors
 - Fringe / shadow
 - Rounding
 - Underline
 - Italic character (slanting)
- Close-character attribute data changing available
- Vertical display start line setting in row units available (Row overlapping available)
- Horizontal display start position available
- Display mode specification by row (Display mode mixable)
 - caption mode / text mode / OSD mode
- Eight kinds of character size
 - Horiz. × Vert. = (1 × 1), (1 × 2), (2 × 2), (2 × 4)
(1.5 × 1), (1.5 × 2), (3 × 2), (3 × 4)
- Shuttering and scrolling in row units available
- Horizontal character pitch selectable : 9 to 16 dots
- Polarity of R, G, B, I, BL output programmable
- Polarity of HS, VS input programmable

(5) Data slicer clock switching function

Clock source is selective from LC oscillation or ceramic resonator (or X'tal) oscillation.

(6) Bus cycle time / Instruction cycle time

The LC864132B/24B/20B/16B/12B microcontrollers are designed to read the ROM twice within one instruction cycle. It has about 1.7 times performance capability within the same instruction-cycle compared to our 4-bit microcontrollers (LC66000 series).

The bus cycle time indicates the speed to read ROM.

Bus cycle time	Instruction cycle time	System clock oscillation	Oscillation frequency	Voltage
0.49 μs	0.99 μs	Ceramic or Crystal	12.08 MHz	4.5 V to 5.5 V
7.5 μs	15.0 μs	Internal RC	800k Hz	4.5 V to 5.5 V

(7) Ports

- Input/output port : 2 ports (16 lines)
- Input/output port programmable in nibble unit : 1 port (8 lines)
(When the N-ch open drain output is selected, the data in a bit can be inputted)
- Input/output port programmable in a bit : 1 port (8 lines)
- Input port : 2 ports (8 lines)

(8) A/D converter

- 4-channel \times 5-bit AD converter (converted with program)

(9) PWM output

- 10-channel \times 7-bit PWM

(10) Timer

- Timer 0 : 16-bit timer / counter

2-bit prescaler + 8-bit built-in programmable prescaler

Mode 0 : Two 8-bit timers with a programmable prescaler

Mode 1 : 8-bit timer with a programmable prescaler + 8-bit counter

Mode 2 : 16-bit timer with a programmable prescaler

Mode 3 : 16-bit counter

The resolution of timer is 1 tCYC.

- Timer 1 : 16-bit timer / PWM

Mode 0 : Two 8-bit timers

Mode 1 : 8-bit timer + 8-bit PWM

Mode 2 : 16-bit timer

Mode 3 : Variable-bit PWM (9 to 16 bits)

In Mode 0 and Mode 1, the resolution of Timer and PWM is tCYC.

In Mode 2 and Mode 3, the resolution of Timer and PWM selectable : tCYC or 1/2tCYC by program.

(11) Remote control receiver circuit (shares with the P73/INT3/T0IN terminal)

- Noise rejection function

- Polarity switching

(12) Watchdog timer

External RC circuit is required

Interrupt or system reset is selectable

(13) Interrupts

- 11-source 9-vectorized interrupts

1. External Interrupt INT0

2. External Interrupt INT1

3. External Interrupt INT2, Timer/counter T0L (Lower 8 bits)

4. External Interrupt INT3

5. Timer/counter T0H (Upper 8 bits)

6. Timer T1H, T1L

7. Serial interface 0 (SIO0)

8. Data slicer

9. Vertical synchronous signal interrupt (VS)

- Interrupt priority control available

Three interrupt priorities are supported (low, high and the highest) and multilevel nesting is possible. Low or high priority can be assigned to the interrupts from 3 to 10 listed above. For the external interrupt INT0 and INT1, high or the highest priority can be set.

(14) Sub-routine stack level

- A maximum of 128 levels (Sets the stack inside a RAM.)

(15) Multiplication/division instruction

- 16 bits × 8 bits (7 instruction cycle times)
- 16 bits / 8 bits (7 instruction cycle times)

(16) Three oscillation circuits

- On-chip RC oscillation circuit for the system clock
- On-chip ceramic resonator oscillation circuit for the system clock
- On-chip LC oscillation circuit for the CRT synchronization

(17) Standby function

- HALT mode function

The HALT mode is used to reduce the power dissipation. In this operation mode, the program execution is stopped.
This mode can be released by the interrupt request signals or the system reset.

- HOLD mode

The HOLD mode is used to stop oscillations ; the RC (internal) and the ceramic oscillations.
This mode can be released by the following conditions.

- Pull the reset terminal (\overline{RES}) to low level.
- Feed the selected level to either P70/INT0 or P71/INT1.

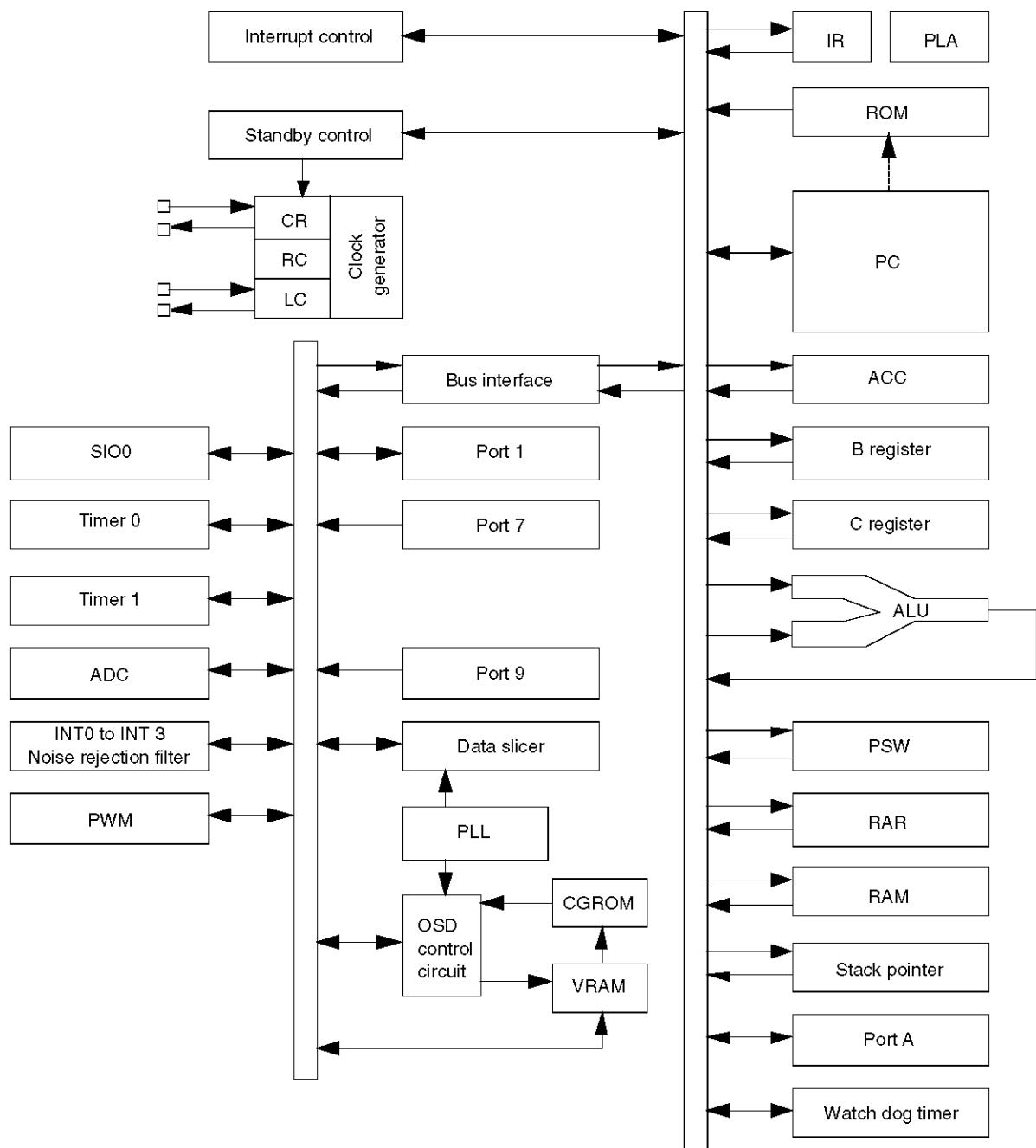
(18) Factory shipment

DIP52S

(19) Development Tools

- | | | |
|---------------------------|---|--|
| - Evaluation (EVA) chip | : | LC866098 |
| - EPROM attached a window | : | LC86E4266 |
| - Emulator | : | EVA86000 (Main) + ECB864200 (Evaluation board) + POD864100 (Pod) |

System Block Diagram



Pin Assignment

P10/SO0	1	52	PA7
P11/SI0/SB0	2	51	PA6
P12/SCK0	3	50	PA5
P13	4	49	PA4
P14	5	48	PA3
P15	6	47	PA2
P16	7	46	PA1
P17/PWM	8	45	PA0
DVSS	9	44	P73/INT3/T0IN
CF1	10	43	P72/INT2/T0IN
CF2	11	42	P71/INT1
DVDD	12	41	P70/INT0
P90/AN0	13	40	PWM9
P91/AN1	14	39	PWM8
P92/AN2	15	38	PWM7
P93/AN3	16	37	PWM6
<u>RES</u>	17	36	PWM5
LC1	18	35	PWM4
LC2	19	34	PWM3
FILT	20	33	PWM2
AVDD	21	32	PWM1
AVSS	22	31	PWM0
CVIN	23	30	BL
<u>VS</u>	24	29	B
<u>HS</u>	25	28	G
I	26	27	R

Top view

LC864266A, 864265A

Pin Description

- Port option can be specified in bit units except the pull-up resistor selection of port 0.

Pin Description Table

Pin name	Pin No.	I/O	Function description	Option																																											
DVSS	9	—	Negative power supply for digital circuit																																												
CF1	10	Input	Input terminal for ceramic resonator																																												
CF2	11	Output	Output terminal for ceramic resonator																																												
DVDD	12	—	Positive power supply for digital circuit																																												
RES	17	Input	Reset terminal																																												
LC1	18	Input	LC oscillation circuit input terminal																																												
LC2	19	Output	LC oscillation circuit output terminal																																												
FILT	20	Output	Filter terminal for PLL																																												
AVDD	21	—	Positive power supply for analog circuit																																												
AVSS	22	—	Negative power supply for analog circuit																																												
CVIN	23	Input	Video signal input terminal																																												
VS	24	Input	Vertical synchronization signal input terminal																																												
HS	25	Input	Horizontal synchronization signal input terminal																																												
I	26	Output	Image intensity output																																												
R	27	Output	Red (R) output terminal of RGB image output																																												
G	28	Output	Green (G) output terminal of RGB image output																																												
B	29	Output	Blue (B) output terminal of RGB image output																																												
BL	30	Output	Fast blanking control signal Switch TV image signal and caption/OSD image signal																																												
PWM0 to PWM9	31 to 40	Output	PWM0 to 9 output terminal 15 V withstand																																												
Port 1 P10 to P17	1 to 8	I/O	8-bit Input/output port Input/output can be specified in bit units. Other function <table border="1" style="margin-left: 10px;"><tr><td>P10</td><td>SIO0 data output</td></tr><tr><td>P11</td><td>SIO0 data input / bus input/output</td></tr><tr><td>P12</td><td>SIO0 clock input/output</td></tr><tr><td>P17</td><td>Timer 1 (PWM) output</td></tr></table>	P10	SIO0 data output	P11	SIO0 data input / bus input/output	P12	SIO0 clock input/output	P17	Timer 1 (PWM) output	Output Format CMOS/Nch-OD (in bit units)																																			
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Port 7 P70 P71 to P73	41 42 to 44	I/O Input	4-bit input port Other function <table border="1" style="margin-left: 10px;"><tr><td>P70</td><td>INT0 input/HOLD release input/ Nch-transistor output for watchdog timer</td></tr><tr><td>P71</td><td>INT1 input/HOLD release input</td></tr><tr><td>P72</td><td>INT2 input/timer 0 event input</td></tr><tr><td>P73</td><td>INT3 input (noise rejection filter attached input/ timer 0 event input)</td></tr></table> Interrupt receiver formats / vector addresses <table border="1" style="margin-left: 10px;"><thead><tr><th></th><th>Rising</th><th>Falling</th><th>Rising/falling</th><th>H level</th><th>L level</th><th>Vector</th></tr></thead><tbody><tr><td>INT0</td><td>enable</td><td>enable</td><td>disable</td><td>enable</td><td>enable</td><td>03H</td></tr><tr><td>INT1</td><td>enable</td><td>enable</td><td>disable</td><td>enable</td><td>enable</td><td>0BH</td></tr><tr><td>INT2</td><td>enable</td><td>enable</td><td>enable</td><td>disable</td><td>disable</td><td>13H</td></tr><tr><td>INT3</td><td>enable</td><td>enable</td><td>enable</td><td>disable</td><td>disable</td><td>1BH</td></tr></tbody></table>	P70	INT0 input/HOLD release input/ Nch-transistor output for watchdog timer	P71	INT1 input/HOLD release input	P72	INT2 input/timer 0 event input	P73	INT3 input (noise rejection filter attached input/ timer 0 event input)		Rising	Falling	Rising/falling	H level	L level	Vector	INT0	enable	enable	disable	enable	enable	03H	INT1	enable	enable	disable	enable	enable	0BH	INT2	enable	enable	enable	disable	disable	13H	INT3	enable	enable	enable	disable	disable	1BH	Pull-up resistor provided/ not provided (in bit units)
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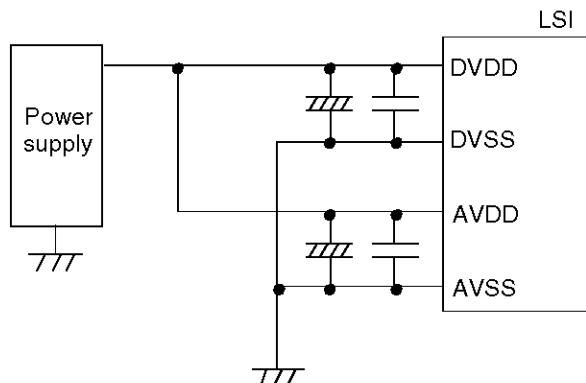
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Pin name	Pin No.	I/O	Function Description	Option
Port9			4-bit input port	
P90 to P93	13 to 16	Input	Other functions AD converter input port (4 lines)	
Port A			8-bit Input/output port	
PA0 to PA7	45 to 52	I/O	Input/output can be specified in nibble units	

- Any port option can be selected in bit units.
- Port 0 portion : Pull-up resistor is provided when CMOS output is selected.
The pull-up resistor is not provided when N-ch Open Drain is selected.
- Port 1 option : Programmable pull-up resistor is provided when any output form is selected.
- Port status during reset

Terminal	I/O	Pull-up resistor status at selecting pull-up option
Port 1	Input	Programmable pull-up resistor OFF
Port 7	Input	Fixed pull-up resistor provided

- AVDD and AVSS are the power supply terminals for built-in analog circuit, while DVDD and DVSS are for built-in digital circuit. Connect them like the following figure to reduce the mutual noise-influence.



Specifications

1. Absolute Maximum Ratings at $T_a = 25^\circ\text{C}$, $V_{SS} = 0 \text{ V}$

Parameter		Symbol	Pins	Conditions	Ratings			Unit
					V_{DD} [V]	min	typ	
Supply voltage	$V_{DD\max}$	DVDD, AVDD	DVDD = AVDD		-0.3		7.0	V
Input voltage	$V_I(1)$	• P71, 72, 73 • Port 9 • RES, HS, VS, CVIN			-0.3		$V_{DD}+0.3$	
Output voltage	$V_O(1)$	R, G, B, BL, I, FILT			-0.3		$V_{DD}+0.3$	mA
	$V_O(2)$	PWM0 to PWM9			-0.3		15	
Input/output voltage	V_{IO}	Ports A, 1, P70			-0.3		$V_{DD}+0.3$	
High-level output current	$I_{OAH}(1)$	Ports A, 1	• Pull-up MOS transistor output • At each pin		-2			mA
		Ports A, 1	• CMOS output • At each pin		-4			
		R, G, B, BL, I	• CMOS output • At each pin		-5			
	$\Sigma I_{OAH}(2)$	Port 1	The total of all pins		-10			
		Port A	The total of all pins		-10			
		R, G, B, BL, I	The total of all pins		-15			
Low-level output current	$I_{OAL}(1)$	Ports A, 1	At each pin				20	mA
		P70	At each pin				30	
		• R, G, B, BL, I • PWM0 to PWM9	At each pin				5	
	$\Sigma I_{OAL}(2)$	Port A	The total of all pins				40	
		Port 1, P70	The total of all pins				40	
		R, G, B, BL, I	The total of all pins				15	
		PWM0 to PWM9	The total of all pins				30	
Maximum power dissipation	$P_d\max$	DIP52S	$T_a = -30 \text{ to } +70^\circ\text{C}$				430	mW
Operating temperature range	T_{opr}				-30		+70	$^\circ\text{C}$
Storage temperature range	T_{stg}				-55		+125	

* DVSS and AVSS must be supplied the same voltage, V_{SS} . $V_{SS} = DVSS = AVSS$
DVDD and AVDD must be supplied the same voltage, V_{DD} . $V_{DD} = DVDD = AVDD$

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2. Recommended Operating Range at $T_a = -30^{\circ}\text{C}$ to $+70^{\circ}\text{C}$, $V_{SS} = 0 \text{ V}$

Parameter	Symbol	Pins	Conditions	Ratings			Unit
				$V_{DD} [\text{V}]$	min	typ	
Operating supply voltage range	V_{DD}	DVDD, AVDD	$0.98 \mu\text{s} \leq t_{CYC}$ $t_{CYC} \leq 1.02 \mu\text{s}$		4.5		5.5
Hold voltage	V_{HD}	DVDD, AVDD	RAMs and the registers hold data at HOLD mode.		2.0		5.5
Input high voltage	$V_{IH}(1)$	Port A (Schmitt)	Output disable	4.5 to 5.5	$0.6V_{DD}$		V_{DD}
	$V_{IH}(2)$	• Port 1 (Schmitt) • P72, 73 • HS, VS	Output disable	4.5 to 5.5	$0.75V_{DD}$		V_{DD}
	$V_{IH}(3)$	• P70 port input / interrupt • P71 • RES (Schmitt)	Output N-channel transistor OFF	4.5 to 5.5	$0.75V_{DD}$		V_{DD}
	$V_{IH}(4)$	• P70 Watchdog timer input	Output N-channel transistor OFF	4.5 to 5.5	$V_{DD}-0.5$		V_{DD}
	$V_{IH}(5)$	Port 9 port input		4.5 to 5.5	$0.7V_{DD}$		V_{DD}
Input low voltage	$V_{IL}(1)$	Port A (Schmitt)	Output disable	4.5 to 5.5	V_{SS}		$0.2V_{DD}$
	$V_{IL}(2)$	• Port 1 (Schmitt) • P72, 73 • HS, VS • Port 9	Output disable	4.5 to 5.5	V_{SS}		$0.25V_{DD}$
	$V_{IL}(3)$	• P70 port input / interrupt • P71 • RES (Schmitt)	N-channel transistor OFF	4.5 to 5.5	V_{SS}		$0.25V_{DD}$
	$V_{IL}(4)$	• P70 Watchdog timer input	N-channel transistor OFF	4.5 to 5.5	V_{SS}		$0.6V_{DD}$
	$V_{IL}(5)$	Port 9 port input		4.5 to 5.5	V_{SS}		$0.3V_{DD}$
CVIN input amplitude	V_{CVIN}	CVIN		5.0	$1V_{pp}$ -3dB	$1V_{pp}$	$1V_{pp}$ +3 dB
Operation cycle time	tCYC(1)		OSD function	4.5 to 5.5	0.97	1	1.02
	tCYC(2)		Except OSD function	4.5 to 5.5	0.97		40

* V_{pp} : Peak-to-peak voltage

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Parameter	Symbol	Pins	Conditions	Ratings			Unit	
				V _{DD} [V]	min	typ		
Oscillation frequency range (Note 1)	FmCF (1)	CF1, CF2	12 MHz (ceramic resonator oscillation) Refer to Figure 1.	4.5 to 5.5	11.76	12	12.24	MHz
	FmCF (2)		12.08 MHz (ceramic resonator oscillation) Refer to Figure 1.		11.84	12.08	12.32	
	FmLC	LC1, LC2	14.11 MHz (LC oscillation) Refer to Figure 2.	4.5 to 5.5		14.11		
	FmRC		RC oscillation	4.5 to 5.5	0.3	0.8	2.0	
Oscillation stable time period (Note 2)	tmsCF (1)	CF1, CF2	12 MHz (ceramic resonator oscillation) Refer to Figure 3.	4.5 to 5.5		0.02	0.2	ms
	tmsCF (2)		12.08 MHz (ceramic resonator oscillation) Refer to Figure 3.			0.02	0.2	

(Note 1) Refer to Table 1 and Table 2 for the oscillation constant.

(Note 2) The oscillation stable time is a period necessary for the oscillation to be stable after the power first applied, the HOLD mode released and the main-clock oscillation stop instruction released.
Refer to the Figure 3 for details.

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3. Electrical Characteristics at $T_a = -30^{\circ}\text{C}$ to $+70^{\circ}\text{C}$, $V_{SS} = 0 \text{ V}$

Parameter	Symbol	Pins	Conditions	Ratings			Unit
				V_{DD} [V]	min	typ	
Input high-level current	$I_{IH}(1)$	• Port 1 • Port A	• Output disable • Pull-up MOS transistor OFF • $V_{IN} = V_{DD}$ (including the off-leak current of the output transistor)	4.5 to 5.5			1 μA
	$I_{IH}(2)$	• Port 7 without pull-up MOS transistor • Port 9 • $\overline{\text{RES}}$ • $\overline{\text{HS,VS}}$	$V_{IN} = V_{DD}$	4.5 to 5.5			1
Input low-level current	$I_{IL}(1)$	• Port 1 • Port A	• Output disable • Pull-up MOS transistor OFF • $V_{IN} = V_{SS}$ (including the off-leak current of the output transistor)	4.5 to 5.5	-1		
	$I_{IL}(2)$	• Port 7 without pull-up MOS transistor • Port 9	$V_{IN} = V_{SS}$	4.5 to 5.5	-1		
	$I_{IL}(3)$	• $\overline{\text{RES}}$ • $\overline{\text{HS,VS}}$	$V_{IN} = V_{SS}$	4.5 to 5.5	-1		
Output high-level voltage	$V_{OH}(1)$	CMOS output of ports A, 1	$I_{OH} = -1.0 \text{ mA}$	4.5 to 5.5	$V_{DD}-1$		V
	$V_{OH}(2)$	R, G, B, BL, I	$I_{OH} = -0.1 \text{ mA}$	4.5 to 5.5	$V_{DD}-0.5$		
Output low-level voltage	$V_{OL}(1)$	Ports A, 1	$I_{OL} = 10 \text{ mA}$	4.5 to 5.5			1.5
	$V_{OL}(2)$	Ports A, 1	• $I_{OL} = 1.6 \text{ mA}$ • The total current of the ports A, 1 is not over 40 mA.	4.5 to 5.5			0.4
	$V_{OL}(3)$	• R, G, B, BL, I • PWM0 to PWM9	• $I_{OL} = 3.0 \text{ mA}$ • The current of any unmeasured pins is not over 3 mA.	4.5 to 5.5			0.4
	$V_{OL}(4)$	P70	$I_{OL} = 1 \text{ mA}$	4.5 to 5.5			0.4
Pull-up MOS transistor resistance	R_{pu}	• Ports A, 1 • Port 7	$V_{OH} = 0.9V_{DD}$	4.5 to 5.5	13	38	80 $\text{k}\Omega$
Output off-leakage current	I_{OFF}	PWM0 to PWM9	$V_{OUT} = 13.5 \text{ V}$	4.5 to 5.5			5 μA
Hysteresis voltage	V_{HIS}	• Ports A, 1 • Port 7 • $\overline{\text{RES}}$ • $\overline{\text{HS,VS}}$	Output disable	4.5 to 5.5		$0.1V_{DD}$	V

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Parameter	Symbol	Pins	Conditions	Ratings			Unit	
				V _{DD} [V]	min	typ		
Input clamp voltage	V _{CLMP}	CVIN		5.0	2.3	2.5	2.7	V
Pin capacitance	CP	All pins	<ul style="list-style-type: none"> f = 1 MHz Unmeasured input pins are set to V_{SS} level. T_a = 25°C 	4.5 to 5.5		10		pF

4. Serial Input/Output Characteristics at T_a = -30°C to +70°C , V_{SS} = 0 V

Parameter			Symbol	Pins	Conditions	Ratings			Unit
Serial clock	Input clock	Cycle	tCKCY(1)	<ul style="list-style-type: none"> SCK0 SCLK0 	Refer to Figure 5.	V _{DD} [V]	min	typ	
		Low-level pulse width	tCKL(1)			4.5 to 5.5	2		
		High-level pulse width	tCKH(1)			4.5 to 5.5	1		
	Output clock	Cycle	tCKCY(2)	<ul style="list-style-type: none"> SCK0 SCLK0 	<ul style="list-style-type: none"> Use an external pull-up resistor (1 kΩ) during open drain output Refer to Figure 5. 	4.5 to 5.5	2		
		Low-level pulse width	tCKL(2)			4.5 to 5.5		1/2tCKCY	
		High-level pulse width	tCKH(2)			4.5 to 5.5		1/2tCKCY	
	Serial input	Data set-up time	tICK	<ul style="list-style-type: none"> SI0 	<ul style="list-style-type: none"> Data set-up to SCK0 rising 	4.5 to 5.5	0.1		μs
		Data hold time	tCKI		<ul style="list-style-type: none"> Data hold from SCK0 rising Refer to Figure 5. 	4.5 to 5.5	0.1		
	Serial output	Output delay time (External serial clock)	tCKO(1)	<ul style="list-style-type: none"> SO0 	<ul style="list-style-type: none"> Use an external pull-up resistor (1 kΩ) during open drain output. 	4.5 to 5.5			μs
		Output delay time (Internal serial clock)	tCKO(2)		<ul style="list-style-type: none"> Data set-up to SCK0 falling Data hold from SCK0 falling Refer to Figure 5. 	4.5 to 5.5			

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5. Pulse Input Conditions at $T_a = -30^{\circ}\text{C}$ to $+70^{\circ}\text{C}$, $V_{SS} = 0 \text{ V}$

Parameter	Symbol	Pins	Conditions	Ratings			Unit
				$V_{DD} [\text{V}]$	min	typ	
High/low-level pulse width	tPIH(1) tPIL(1)	• INT0, INT1 • INT2/T0IN	• Interrupt acceptable • Timer/counter 0 pulse countable	4.5 to 5.5	1		tCYC
	tPIH(2) tPIL(2)	INT3/T0IN (The noise rejection clock is selected to 1/1)	• Interrupt acceptable • Timer/counter 0 pulse countable	4.5 to 5.5	2		
	tPIH(3) tPIL(3)	INT3/T0IN (The noise rejection clock is selected to 1/16)	• Interrupt acceptable • Timer/counter 0 pulse countable	4.5 to 5.5	32		
	tPIL(4)	$\overline{\text{RES}}$	Reset acceptable	4.5 to 5.5	200		μs
	tPIH(5) tPIL(5)	$\overline{\text{HS}}, \overline{\text{VS}}$	Display position controllable Each active edge of HS, VS must be more than 1tCYC. Refer to Figure 7.	4.5 to 5.5	10		tCYC
Rising/falling time	tTHL tTLH	$\overline{\text{HS}}$	Refer to Figure 7.	4.5 to 5.5		500	ns
Horizontal pull-in range	FH	$\overline{\text{HS}}$	The monitor point in Figure 10 is 1/2 V_{DD} .	4.5 to 5.5	15.23	15.73	16.23
							kHz

6. A/D Converter Characteristics at $T_a = -30^{\circ}\text{C}$ to $+70^{\circ}\text{C}$, $V_{SS} = 0 \text{ V}$

Parameter	Symbol	Pins	Conditions	Ratings			Unit
				$V_{DD} [\text{V}]$	min	typ	
Resolution	N			4.5 to 5.5		5	
Absolute precision	ET		(Note 3)	4.5 to 5.5		$\pm 1/4$	$\pm 3/4$ LSB
Conversion time	tCAD	From selecting Vref to resulting	1 bit conversion time = 2tCYC	4.5 to 5.5			1.96 μs
Reference current	I _{REF}		(Regulate the ladder resistor)	4.5 to 5.5		1.0	2.0 mA
Analog input voltage range	V _{A1N}	AN0 to AN3		4.5 to 5.5	V _{SS}		V _{DD} V
Analog port input current	I _{A1NH}		V _{A1N} = V _{DD}	4.5 to 5.5			1 μA
	I _{A1NL}		V _{A1N} = V _{SS}	4.5 to 5.5	-1		

(Note 3) Absolute precision excepts quantizing error ($\pm 1/2$ LSB).

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7. Current Drain Characteristics at $T_a = -30^{\circ}\text{C}$ to $+70^{\circ}\text{C}$, $V_{SS} = 0 \text{ V}$

Parameter	Symbol	Pins	Conditions	Ratings			Unit	
				$V_{DD} [\text{V}]$	min	typ		
Current drain during basic operation (Note 4)	$I_{DDOP}(1)$	DVDD, AVDD	<ul style="list-style-type: none"> \bullet $F_{mCF} = 12 \text{ MHz}$ Ceramic resonator oscillation \bullet $F_{mLC} = 14.11 \text{ MHz}$ LC oscillation \bullet System clock : CF oscillation \bullet Internal RC oscillation stops 	4.5 to 5.5		21	32	mA
Current drain in HALT mode (Note 4)	$I_{DDHALT}(1)$	DVDD, AVDD	<ul style="list-style-type: none"> \bullet HALT mode \bullet $F_{mCF} = 12 \text{ MHz}$ or 12.08 MHz Ceramic resonator oscillation \bullet $F_{mLC} = 0 \text{ Hz}$ (oscillation stops) \bullet System clock : CF oscillation \bullet Internal RC oscillation stops. 	4.5 to 5.5		5	10	mA
	$I_{DDHALT}(2)$	DVDD, AVDD	<ul style="list-style-type: none"> \bullet HALT mode \bullet $F_{mCF} = 0 \text{ MHz}$ (oscillation stops) \bullet $F_{mLC} = 0 \text{ Hz}$ (oscillation stops) \bullet System clock : Internal RC 	4.5 to 5.5		300	800	μA
Current drain in HOLD mode (Note 4)	I_{DDHOLD}	DVDD, AVDD	<ul style="list-style-type: none"> \bullet HOLD mode \bullet All oscillation stops. 	4.5 to 5.5		0.05	20	μA

(Note 4) The currents of the output transistors and the pull-up MOS transistors are ignored.

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Oscillation type	Manufacturer	Oscillator	C1	C2
12 MHz ceramic resonator oscillation	Murata	CSA12.0MTZ	33 pF	33 pF
		CST12.0MTW	on chip	
	Kyocera	KBR-12.0M	33 pF	33 pF
12.08 MHz ceramic resonator oscillation	Murata	CSA 12.0MTZ021	33 pF	33 pF
	Kyocera	KBR-12.08M	33 pF	33 pF

* Both C1 and C2 must use an K rank ($\pm 10\%$) and an SL characteristics.

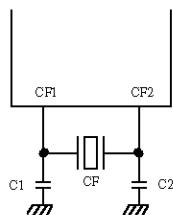
Table 1. Ceramic Resonator Oscillation Guaranteed Constant (Main-clock)

Oscillation	L	C3	C4
14.11 MHz LC oscillation	4.7 μ H	33 pF	45 pF (Trimmer)
	4.7 μ H $\pm 10\%$ (Variable)	33 pF	33 pF

* See Figure 11, 12 for LC oscillation characteristics.

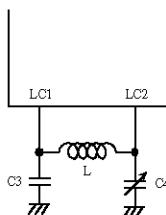
Table 2. LC Oscillation Guaranteed Constant (OSD clock)

- (Notes) • Since the circuit pattern affects the oscillation frequency, place the oscillation-related parts as close to the oscillation pins as possible with the shortest pattern length.
- If you use other oscillators than those shown above, we provide no guarantee for the characteristics.
 - Adjust the voltage of monitor point in figure 10 to $1/2 V_{DD} \pm 10\%$ by the LC oscillation constant 'L' or 'C' to lock the PLL circuit.



Main clock

Figure 1 Ceramic Resonator Oscillation



OSD clock

Figure 2 LC Resonator Oscillation 1, 2

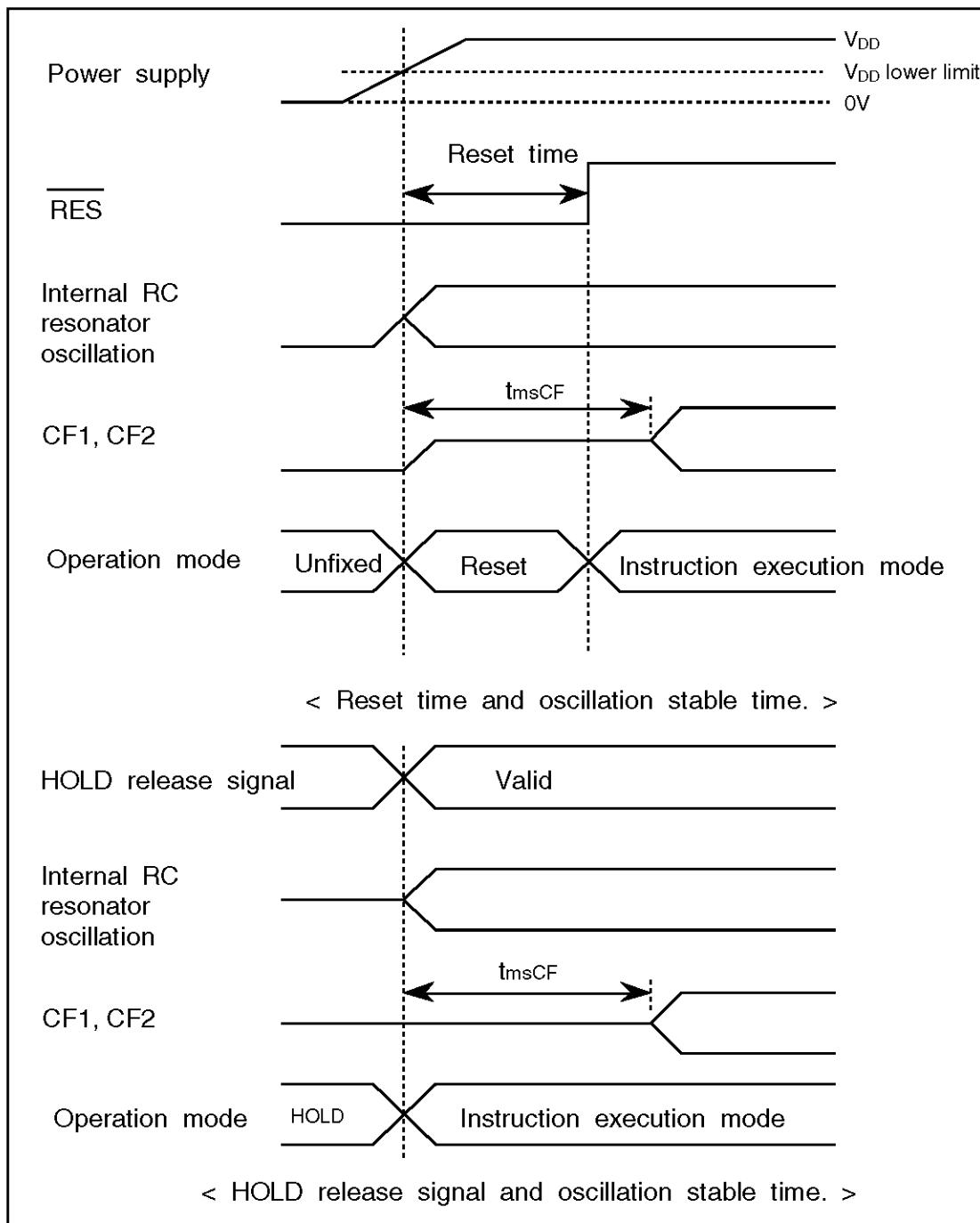


Figure 3 Oscillation Stable Time

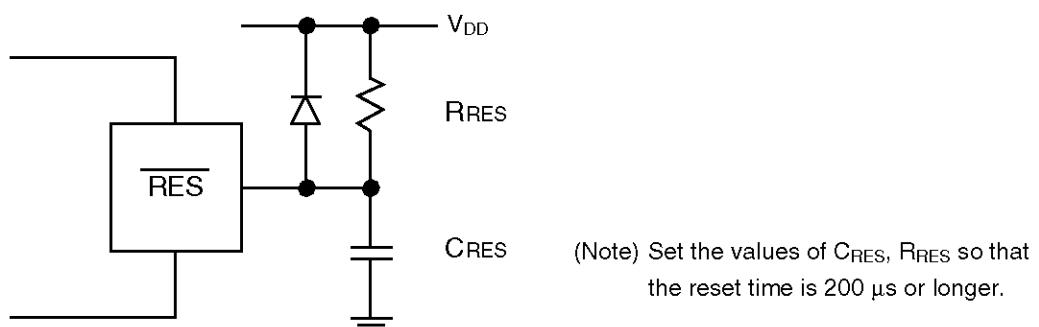


Figure 4 Reset Circuit

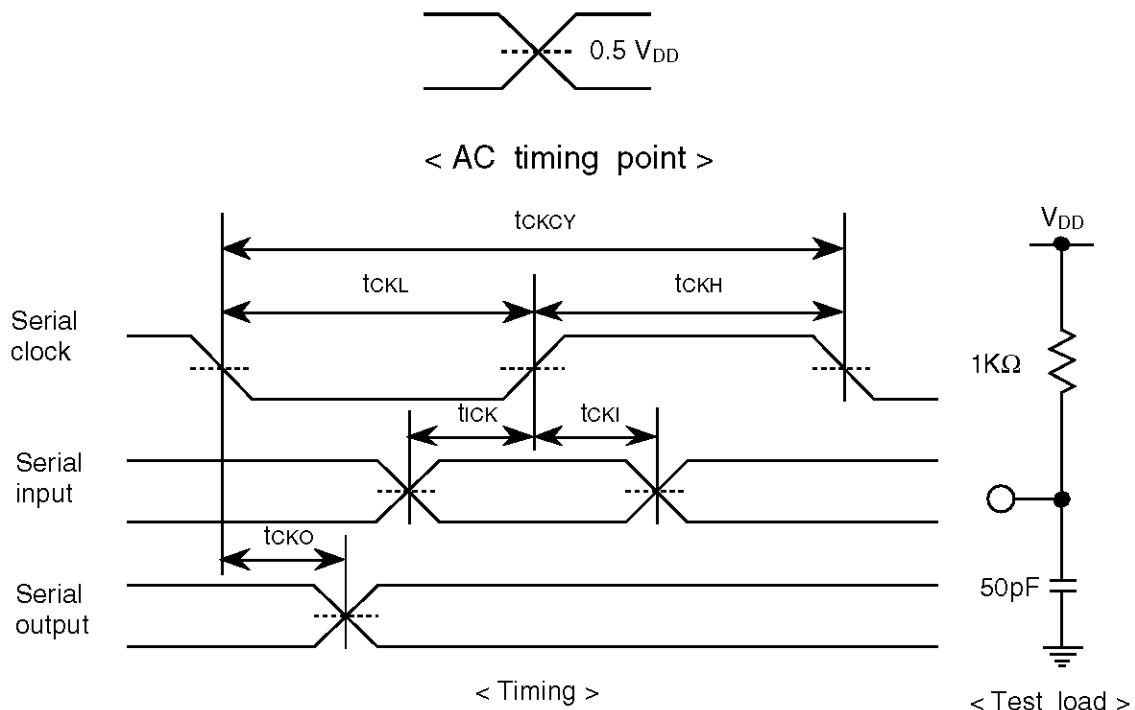


Figure 5 Serial Input/output Test Condition

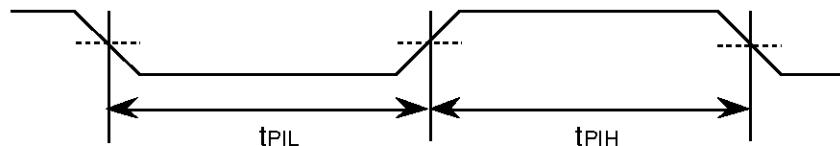


Figure 6 Pulse Input Timing Condition - 1

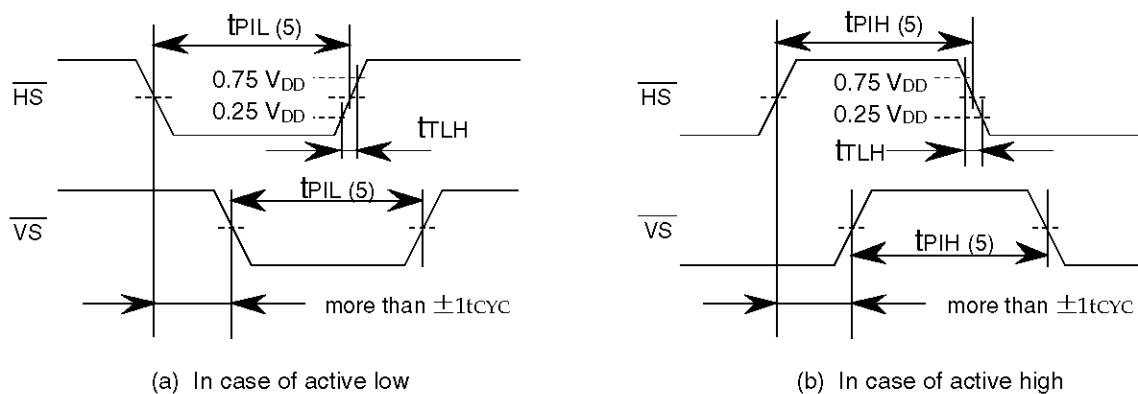


Figure 7 Pulse Input Timing Condition - 2

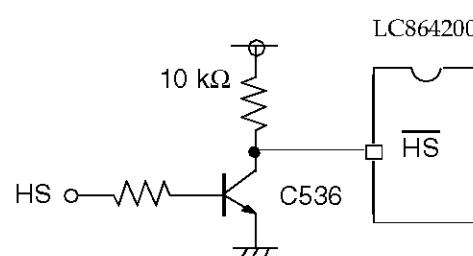


Figure 8 Recommended Interface Circuit

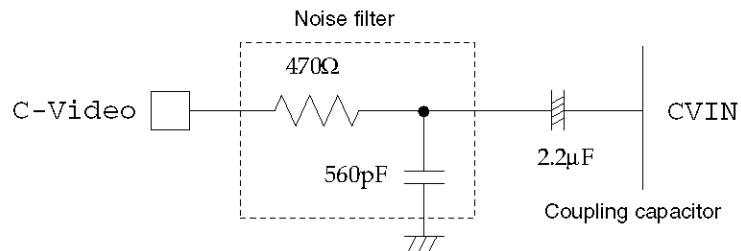


Figure 9 CVIN Recommended Circuit

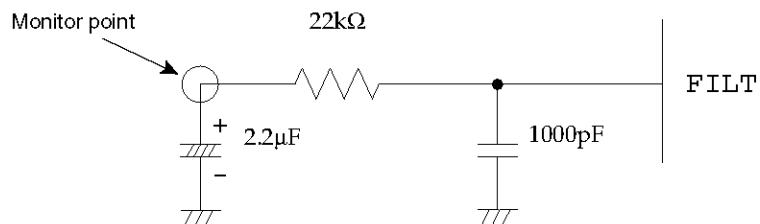


Figure 10 FILT Recommended Circuit

(Note) • Place the parts connected FILT terminal as close to the FILT as possible with the pattern length on the board.

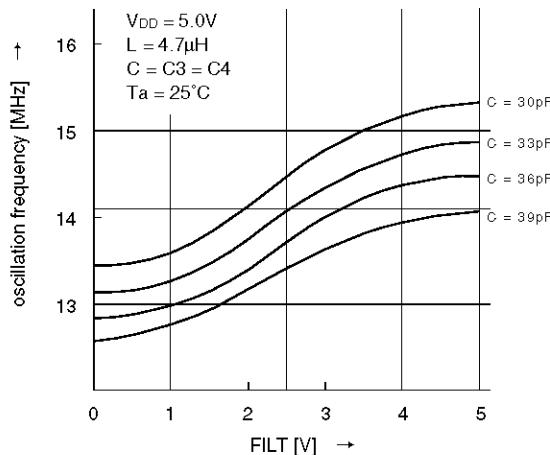


Figure 11 FILT-LC Oscillation Frequency (1)

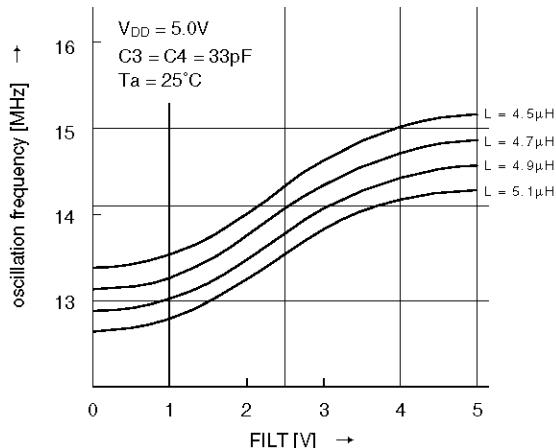


Figure 12 FILT-LC Oscillation Frequency (2)

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