

## Low Power 2-Channel Central-Office xDSL Driver

Check for Samples: [LMH6678](#)

### FEATURES

- $AV_{CC1} = AV_{CC2} = +12V$ ,  $AV_{DD} = DV_{DD} = +3.3V$ ,  $T_A = 25^\circ C$ , 2/3 Power Mode, Typical Values Unless Specified.
- **Low Power Consumption**
  - Line Power  $P_{LINE} = 100\text{ mW } 580\text{ mW/Ch}$
  - No Signal  $185\text{ mW/Ch}$
  - Listen Mode  $100\text{ mW/Ch}$
  - Shutdown Mode  $3\text{ mW/Ch}$
- **Power Supply**
  - Analog ( $AV_{CC1}$ ,  $AV_{CC2}$ )  $+12V$
  - Digital ( $DV_{DD}$ ,  $AV_{DD}$ )  $+3.3V$
- **Output Voltage Swing @  $R_L = 31\Omega$** 
  - Single Ended  $11.5\text{ V}_{PP}$
  - Differential  $23\text{ V}_{PP}$
- **Multi Yone Power Ratio,  $f = 500\text{ kHz } 72\text{ dB}$**
- **Output Current  $580\text{ mA}$**
- **Thermal Shutdown Protection**
- **5mm x 4mm LLP Package**
- **Low Thermal Resistance  $36^\circ C/W$  ( $\theta_{JA}$ )**
- **Small PCB Footprint**

### APPLICATION

- Full Rate ADSL, ADSL+, ADSL++ or G. Lite Linecard
- Remote DSLAMs

### DESCRIPTION

The LMH6678 is a low power 2-channel differential output driver utilizing dual current feedback op amps with a fixed gain of  $A_V = +5.4$ .

The LMH6678 utilizes high integration with low power consumption to provide 580 mW at 19.8 dBm line output. The LMH6678 can also be put into a listen mode to maintain the termination for receive signals with 100 mW/Ch power dissipation.

The LMH6678 has two separate 2-bit power control inputs compatible with 3.3V CMOS for each channel that enable independent control of line status. When the drivers for both channels are shut off, power consumption drops to only 6 mW.

Thermal Shutdown function protects the IC from a shorted line fault or system over temperature.

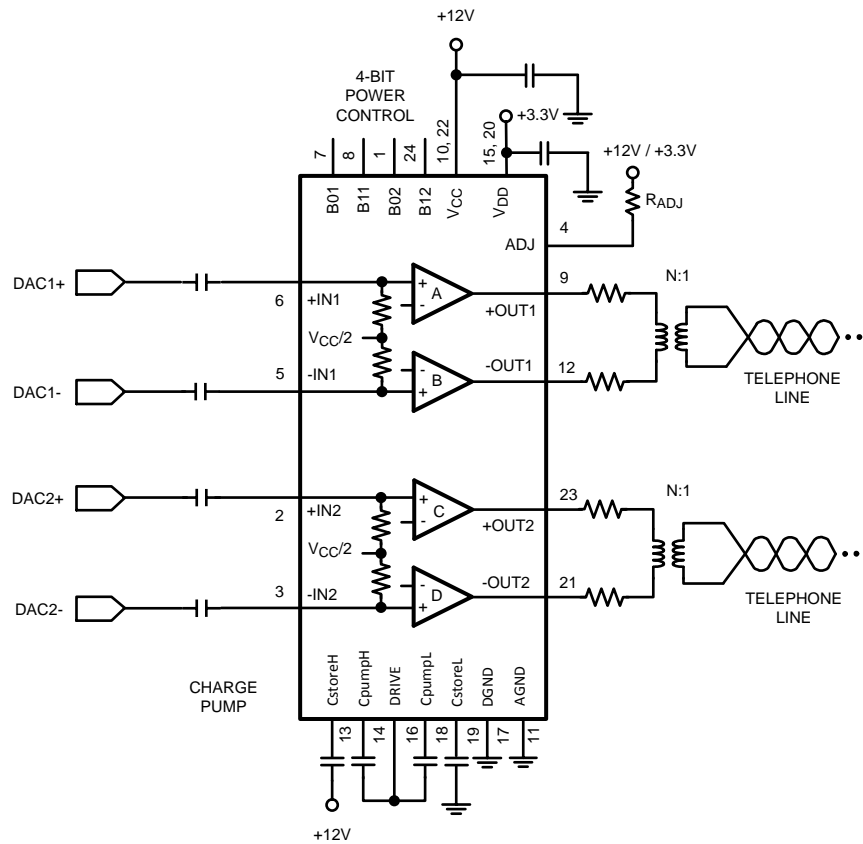
The LMH6678 is available in a 5mm x 4mm 24-lead LLP package.



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## Block Diagram



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

**Absolute Maximum Ratings<sup>(1)(2)</sup>**

ESD Tolerance	Human Body Model	2KV <sup>(3)</sup>
	Machine Model	200V <sup>(4)</sup>
V <sub>IN</sub> Differential		±3V
Supply Voltages	AV <sub>CC1</sub> – AGND or AV <sub>CC2</sub> – AGND	+13.2V
	DV <sub>DD</sub> – DGND	+3.6V
	AV <sub>DD</sub> – AGND	+3.6V
	DGND – AGND	±0.2V
	AV <sub>CC1</sub> – AV <sub>CC2</sub>	±0.2V
	AV <sub>DD</sub> – DV <sub>DD</sub>	±0.2V
Voltage at Input Pin	Analog Input	AV <sub>CC1</sub> (AV <sub>CC2</sub> ) +0.8V, AGND –0.8V
	Digital Control Input	DV <sub>DD</sub> +0.8V, DGND –0.8V
Soldering Information	Infrared or Convection (20 sec.)	235°C
Storage Temperature Range		–65°C to +150°C
Junction Temperature <sup>(5)</sup>		+150°C

- (1) Absolute maximum ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) Human body model, 1.5kΩ in series with 100pF.
- (4) Machine Model, 0Ω in series with 200 pF.
- (5) The maximum power dissipation is a function of T<sub>J(MAX)</sub>, θ<sub>JA</sub>, and T<sub>A</sub>. The maximum allowable power dissipation at any ambient temperature is P<sub>D</sub> = (T<sub>J(MAX)</sub> - T<sub>A</sub>)/θ<sub>JA</sub>. All numbers apply for packages soldered directly onto a PC board. Die attach pad is electrically connected to AGND.

**Operating Ratings<sup>(1)</sup>**

Supply Voltage	AV <sub>CC1</sub> to AGND	+12V ±10%
	AV <sub>CC2</sub> to AGND	+12V ±10%
	DV <sub>DD</sub> to DGND	+3.3V ±10%
	AV <sub>DD</sub> to AGND	+3.3V ±10%
Operating Temperature Range <sup>(2)(3)</sup>		–40°C to +85°C
Package Thermal Resistance (θ <sub>JA</sub> ) <sup>(3)</sup>		36°C/W

- (1) Absolute maximum ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
- (2) Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150° C.
- (3) The maximum power dissipation is a function of T<sub>J(MAX)</sub>, θ<sub>JA</sub>, and T<sub>A</sub>. The maximum allowable power dissipation at any ambient temperature is P<sub>D</sub> = (T<sub>J(MAX)</sub> - T<sub>A</sub>)/θ<sub>JA</sub>. All numbers apply for packages soldered directly onto a PC board. Die attach pad is electrically connected to AGND.

## Electrical Characteristics

Unless otherwise specified, all limits ensured for  $T_J = 25^\circ\text{C}$ ,  $AV_{CC1} = AV_{CC2} = +12\text{V}$ ,  $DV_{DD} = AV_{DD} = +3.3\text{V}$ . DGND = AGND = 0V, 2/3 Power Mode. See <sup>(1)</sup>.

Symbol	Parameter	Conditions	Min <sup>(2)</sup>	Typ <sup>(3)</sup>	Max <sup>(2)</sup>	Units			
<b>Dynamic Performance</b>									
$f_{CL}$	-3 dB BW	$R_L = 100\Omega$		50		MHZ			
SR	Slew Rate <sup>(4)</sup>	$V_{IN\_DIFF} = \pm 2.4\text{V}$ , $R_L = 100\Omega$		700		V/ $\mu\text{s}$			
<b>Distortion and Noise Response</b>									
HD2	2nd Harmonic Distortion	$f_c = 1\text{ MHz}$ , $V_O = 2 V_{PP}$ , $R_L = 31\Omega$		-91		dBc			
		$f_c = 200\text{ kHz}$ , $V_O = 2 V_{PP}$ , $R_L = 31\Omega$		-98					
HD3	3 <sup>rd</sup> Harmonic Distortion	$f_c = 1\text{ MHz}$ , $V_O = 2 V_{PP}$ , $R_L = 31\Omega$		-57		dBc			
		$f_c = 200\text{ kHz}$ , $V_O = 2 V_{PP}$ , $R_L = 31\Omega$		-71					
MTPR	Multi-Tone Power Ratio	$f = 500\text{ kHz}$		72		dBc			
$V_{IN}$	Differential Output Noise	100 kHz to 10 MHz		57		nV/ $\sqrt{\text{Hz}}$			
<b>Input Characteristics</b>									
$V_{IN}$	Input DC Voltage	Common Mode	6.04	6.1	6.16	V			
$R_{IN}$	Input Resistance	Differential $I_{DIFF} = 10\ \mu\text{A}$ from +IN to -IN	14.4	20	28.4	k $\Omega$			
<b>Transfer Characteristics</b>									
$A_V$	Voltage Gain	$V_{IN\_DIFF} = -1$ to 1V, No Load	+5.37	+5.40	+5.48	V/V			
PSRR	Power Supply Rejection Ratio			-108		dB			
Xt	Cross Talk	$f = 1\text{ MHz}$ , $R_L = 100\Omega$		-95					
$V_O$	Output Voltage Swing High	$V_{IN\_DIFF} = \pm 2.4\text{V}$ , No Load		11.85		V			
		$V_{IN\_DIFF} = \pm 2.4\text{V}$ , $R_L = 31\Omega$	11.68	11.75					
		$V_{IN\_DIFF} = \pm 2.4\text{V}$ , $I_{OUT} = 580\text{ mA}$	11.64	11.74					
	Output Voltage Swing Low	$V_{IN\_DIFF} = \pm 2.4\text{V}$ , No Load		0.15		V			
		$V_{IN\_DIFF} = \pm 2.4\text{V}$ , $R_L = 31\Omega$		0.25	0.36				
		$V_{IN\_DIFF} = \pm 2.4\text{V}$ , $I_{OUT} = 580\text{ mA}$		0.31	0.39				
$I_{SC}$	Output Short Circuit Current	Sourcing to Ground		+800		mA			
		Sinking to Ground		-800					
$I_{OUT}$	Output Current	$V_{IN\_DIFF} = \pm 2.4\text{V}$ Sourcing, $R_L = 20\Omega$ Sinking, $R_L = 20\Omega$		$\pm 580$		mA			
$V_{OC}$	Output Common Mode Voltage		5.89	6	6.05	V			
$V_{OS}$	Output Offset Voltage		-40	0	+40	mV			
<b>Power Supply<sup>(5)(6)</sup></b>									
$I_{CC}$	AV <sub>CC</sub> Quiescent Supply Current	B01	B11	B02	B12		mA		
	Full Power	L	L	L	L	28.6		33	36.9
	2/3 Power	H	L	H	L	18.6		22	25.4
	1/3 Power	L	H	L	H	9.2		12	14.3
	Shutdown	H	H	H	H			0.2	.95

(1) Electrical table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No specification of parametric performance is indicated in the electrical tables under conditions of internal self heating where  $T_J > T_A$ . Absolute maximum ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

(2) All limits are guaranteed by testing or statistical analysis.

(3) Typical Values represent the most likely parametric norm.

(4) Slew rate is the slowest of the rising and falling slew rates.

(5) Quiescent supply current specification apply for the condition of no input signal. See [Application Notes](#) for information on power consumption as a function of output power, power control bit settings and external resistor  $R_{ADJ}$ .

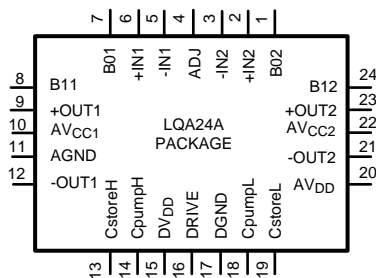
(6) "L" is  $V_{IL}$  and "H" is  $V_{IH}$ .

## Electrical Characteristics (continued)

Unless otherwise specified, all limits ensured for  $T_J = 25^\circ\text{C}$ ,  $AV_{CC1} = AV_{CC2} = +12\text{V}$ ,  $DV_{DD} = AV_{DD} = +3.3\text{V}$ .  $DGND = AGND = 0\text{V}$ , 2/3 Power Mode. See<sup>(1)</sup>.

Symbol	Parameter	Conditions				Min <sup>(2)</sup>	Typ <sup>(3)</sup>	Max <sup>(2)</sup>	Units
$I_{DV}$	$DV_{DD}$ Quiescent Supply Current	B01	B11	B02	B12				mA
	Full Power	L	L	L	L	11	16	19	
	2/3 Power	H	L	H	L	7	12	15	
	1/3 Power	L	H	L	H	3	7	10.3	
	Shutdown	H	H	H	H		0.05	.14	
$I_{AV}$	$AV_{DD}$ Quiescent Supply Current	All Power Modes				.8	1.1	1.4	mA
<b>Logic Inputs</b>									
$V_{IH}$	Input High Voltage					2.7	3.3		V
$V_{IL}$	Input Low Voltage						0	0.5	V
$I_{IH}$	Input High Current	@ $V_{IH} = 3.3\text{V}$				-0.5	0.02	+0.5	$\mu\text{A}$
$I_{IL}$	Input Low Current	@ $V_{IH} = 0\text{V}$				-0.5	0.02	+0.5	$\mu\text{A}$
<b>Charge Pump</b>									
$f_{CP}$	Charge Pump Frequency	Measure at DRIVE at Full Power				2.43	2.75		MHz
$V_{HIGH}$	Charge Pump High Average Voltage	Measure at CstoreH at Full Power					+14.6		V
$V_{LOW}$	Charge Pump Low Average Voltage	Measure at CstoreL at Full Power					-2.7V		V

## Connection Diagram



Note: Die attach pad is electrically connected to AGND

### Typical Performance Characteristics

Single-Ended Small Signal Frequency Response  
@  $R_L = 100\Omega$

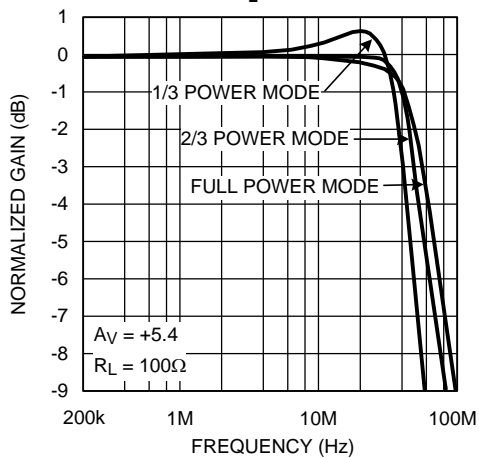


Figure 1.

Single-Ended Small Signal Frequency Response  
@  $R_L = 36\Omega$

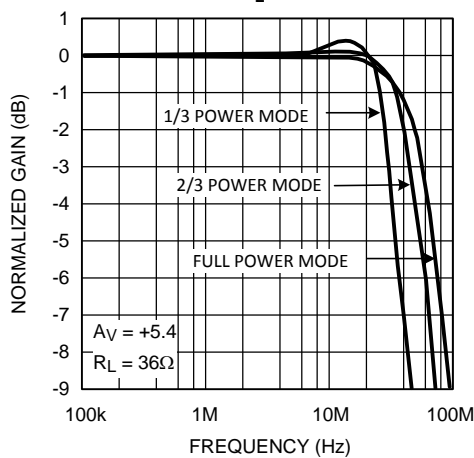


Figure 2.

Medium Signal Pulse Response  
@  $R_L = 100\Omega, 1\text{ MHz}$

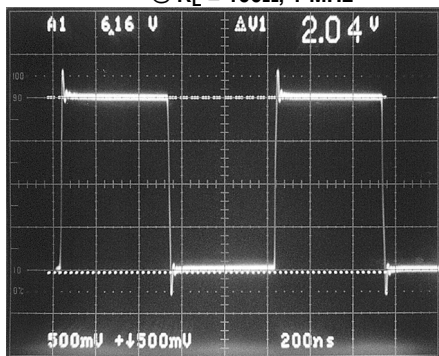


Figure 3.

Medium Signal Pulse Response  
@  $R_L = 36\Omega, 1\text{ MHz}$

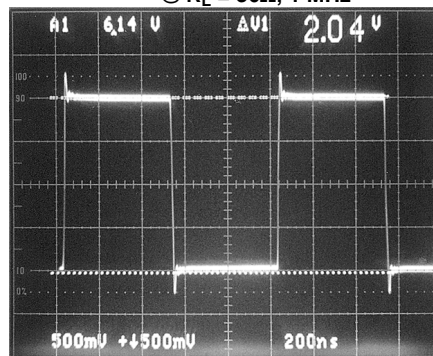


Figure 4.

Large Signal Pulse Response  
@  $R_L = 100\Omega, 1\text{ MHz}$

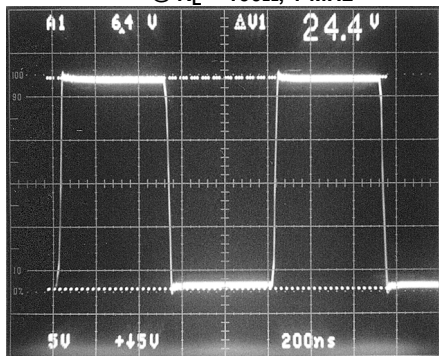


Figure 5.

Large Signal Pulse Response  
@  $R_L = 36\Omega, 1\text{ MHz}$

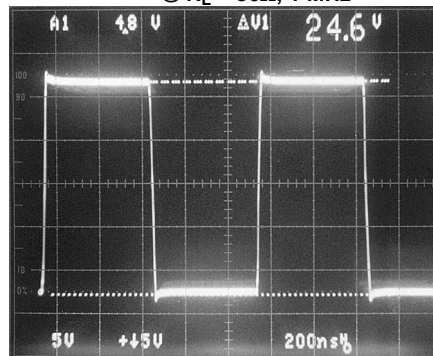


Figure 6.



**Typical Performance Characteristics (continued)**

Single-Ended Small Signal Frequency Response  
@  $Z_L = 100\Omega || 100\text{ pF}$

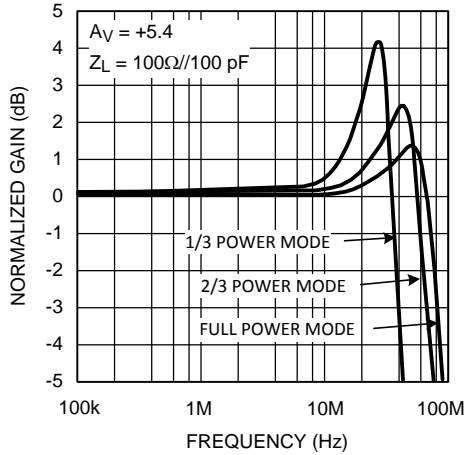


Figure 7.

Single-Ended Small Signal Frequency Response  
@  $Z_L = 36\Omega || 100\text{ pF}$

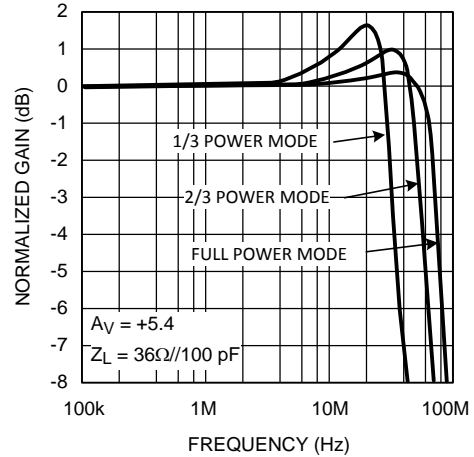


Figure 8.

Output Swing @  $Z_L = 100\Omega || 100\text{ pF}$ , 1 MHz

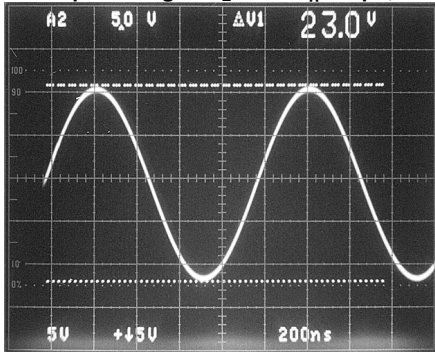


Figure 9.

Output Swing @  $Z_L = 36\Omega || 100\text{ pF}$ , 1 MHz

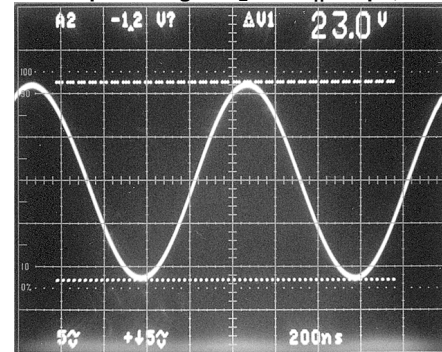


Figure 10.

Output Swing @  $Z_L = 100\Omega || 100\text{ pF}$ , 5 MHz

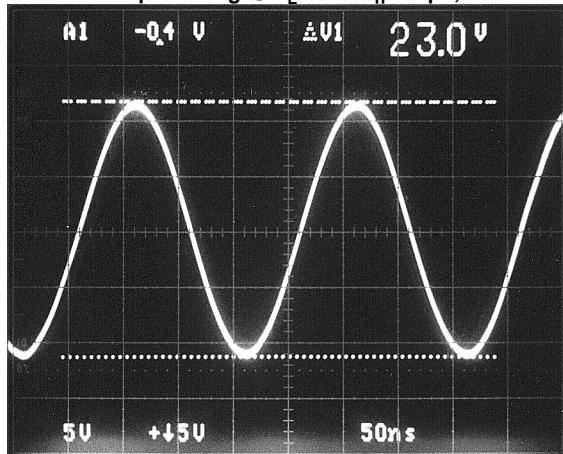


Figure 11.

Output Swing @  $Z_L = 36\Omega || 100\text{ pF}$ , 5 MHz

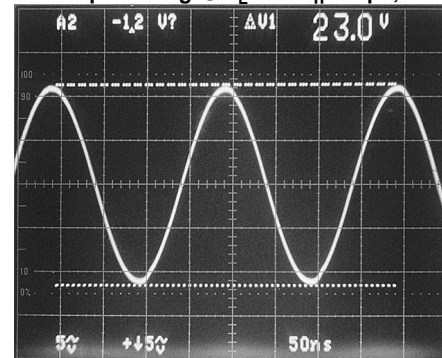


Figure 12.

**Typical Performance Characteristics (continued)**

**Differential PSRR @ Analog  $V_{CC}$**

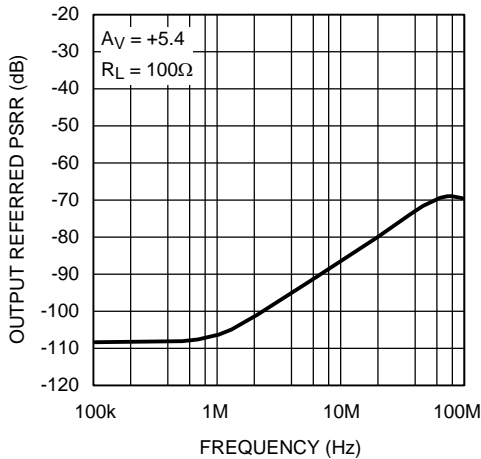


Figure 13.

**Differential Output Referred Cross Talk**

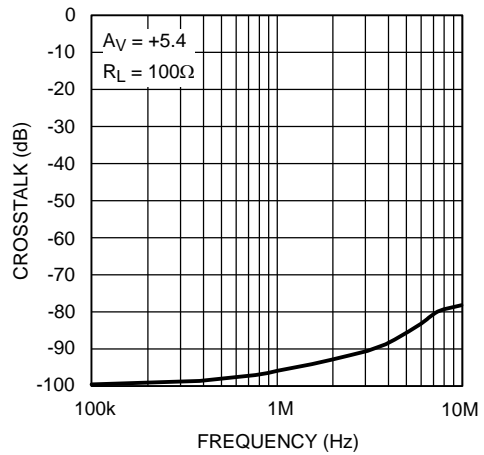


Figure 14.

**Charge Pump @ Drive Pin**

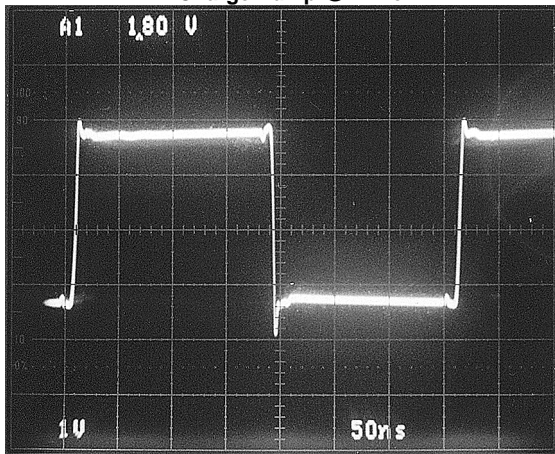


Figure 15.

**Charge Pump Leakage (Differential)**

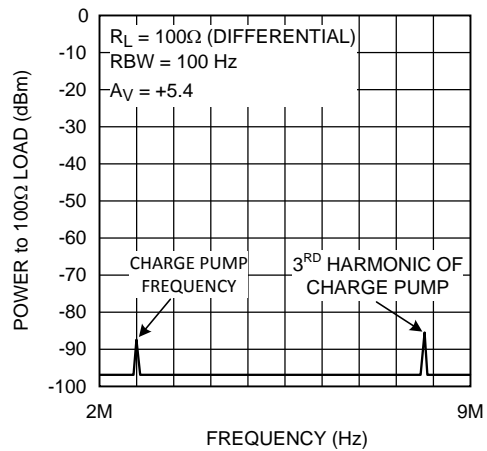


Figure 16.

**Output Voltage Noise @  $R_S = 50\Omega$**

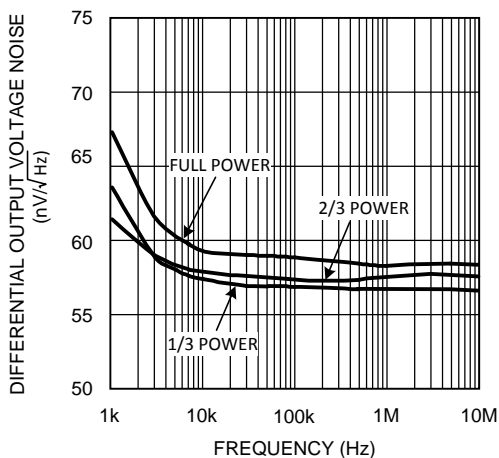


Figure 17.

**Output Voltage Swing**

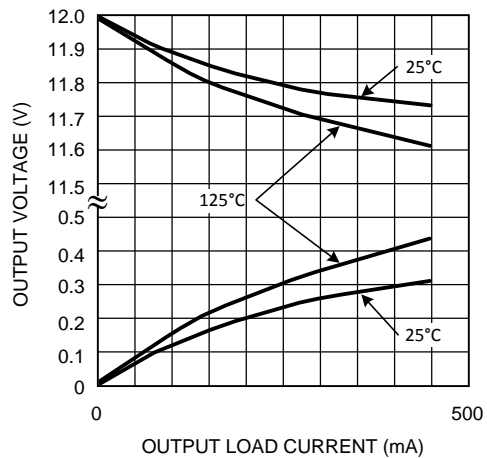


Figure 18.



Typical Performance Characteristics (continued)

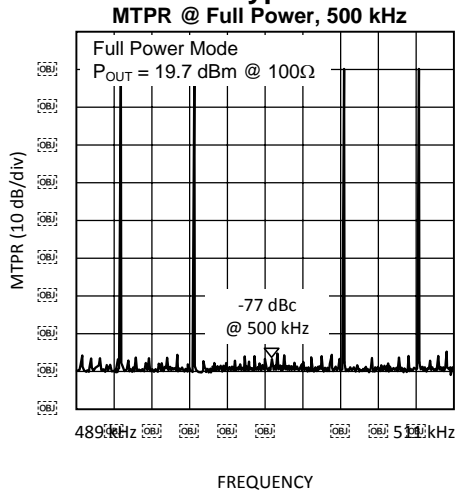


Figure 19.

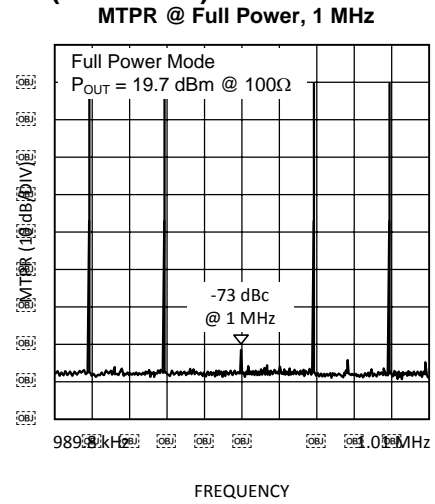


Figure 20.

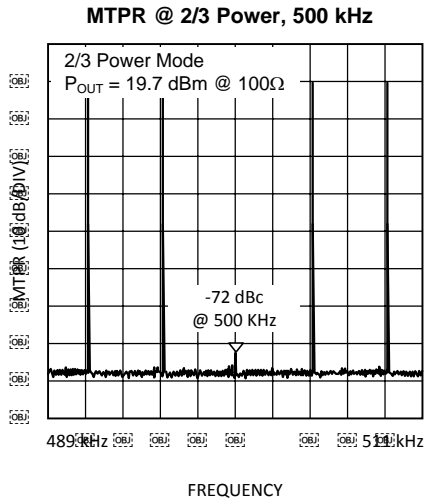


Figure 21.

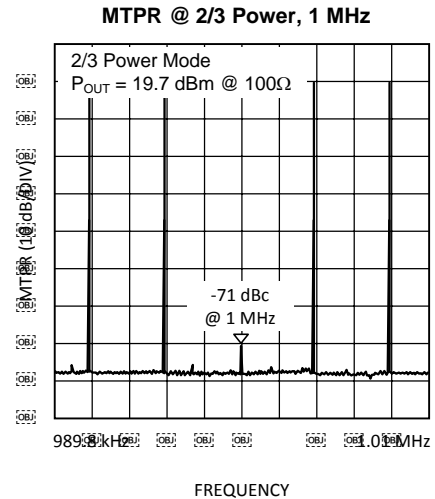


Figure 22.

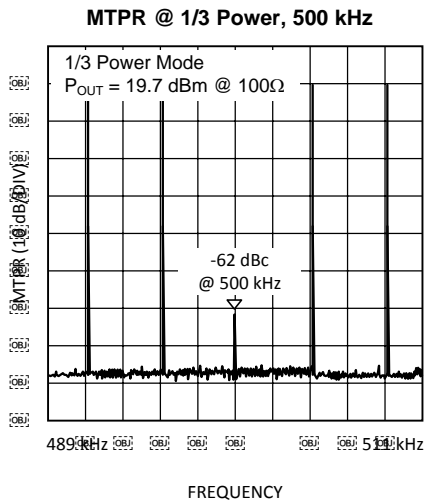


Figure 23.

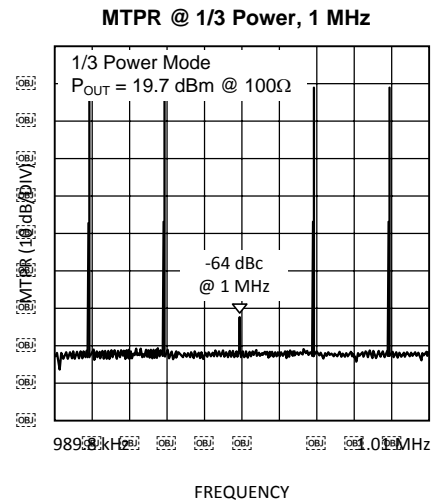


Figure 24.

**Typical Performance Characteristics (continued)**

**Detail View of Total  $I_{CC}$  vs.  $R_{ADJ}$  @  $V_{ADJ} = +12V$**

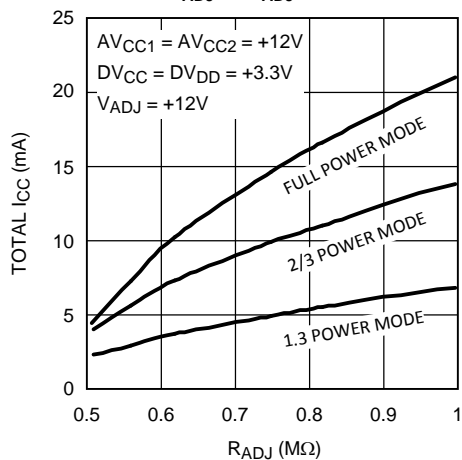


Figure 25.

**Detail View of Total  $I_{CC}$  vs.  $R_{ADJ}$  @  $V_{ADJ} = +3.3V$**

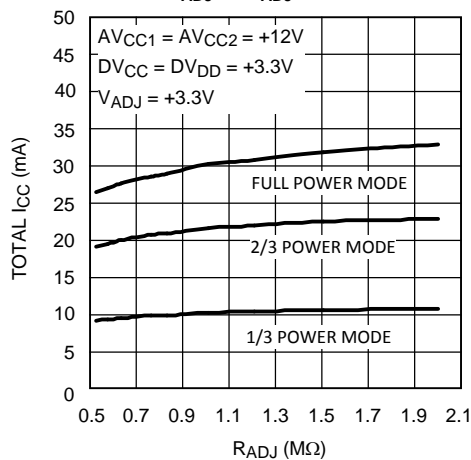


Figure 26.

**Harmonic Distortion vs. Frequency**

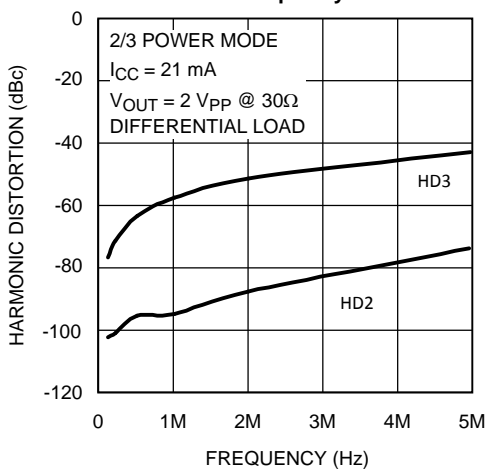


Figure 27.

**Harmonic Distortion vs. Load**

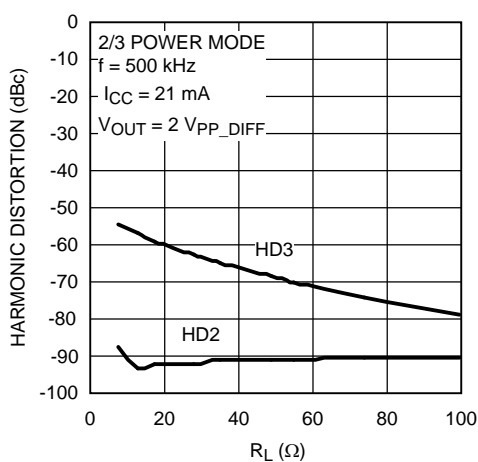


Figure 28.

**Harmonic Distortion @ I<sub>CC</sub> = 33mA, 200 kHz**

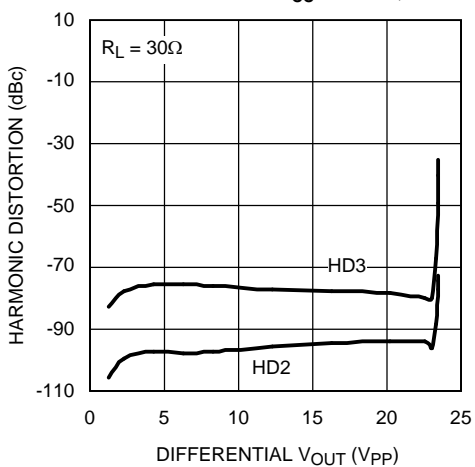


Figure 29.

**Harmonic Distortion @ I<sub>CC</sub> = 33 mA, 1 MHz**

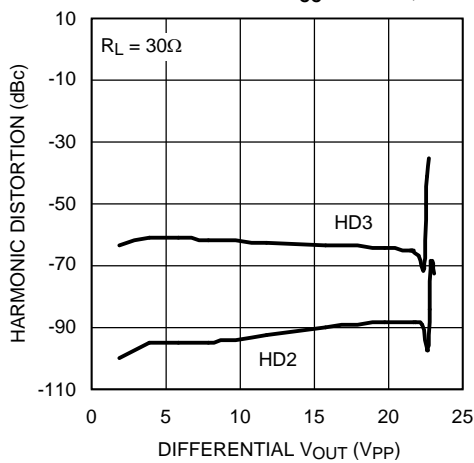


Figure 30.

Typical Performance Characteristics (continued)

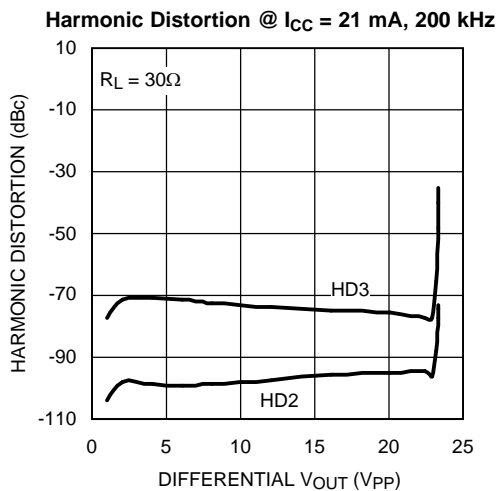


Figure 31.

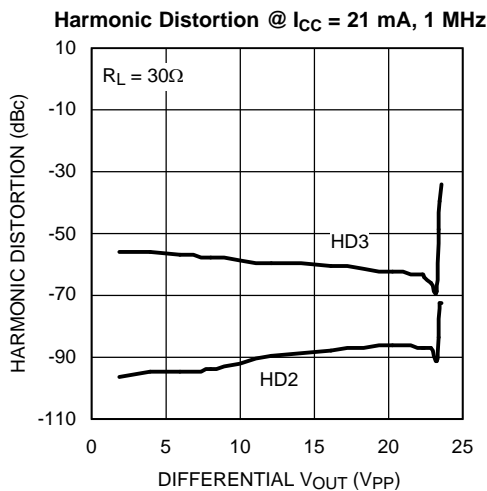


Figure 32.

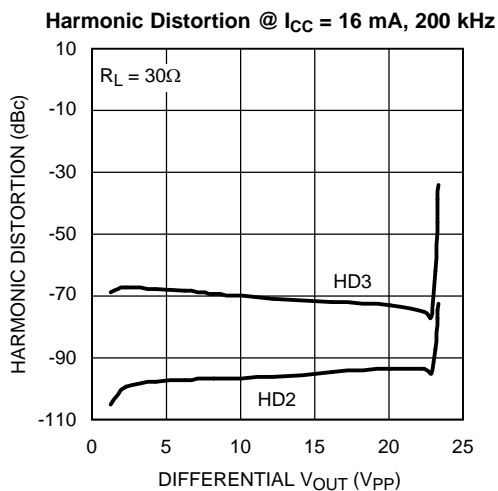


Figure 33.

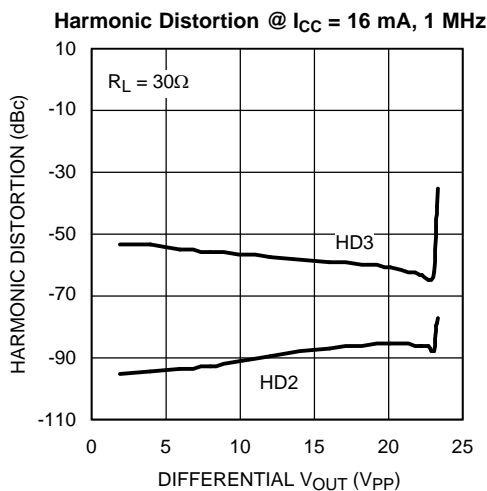


Figure 34.

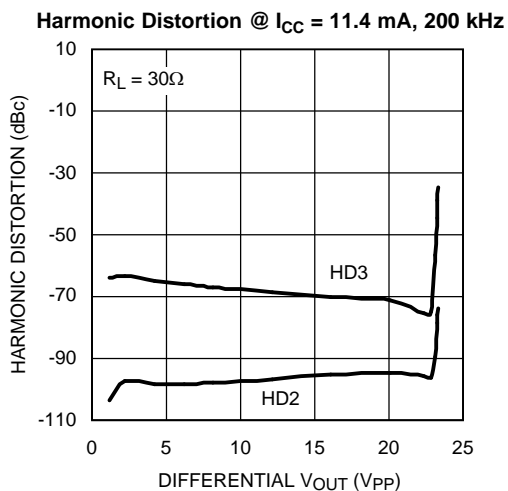


Figure 35.

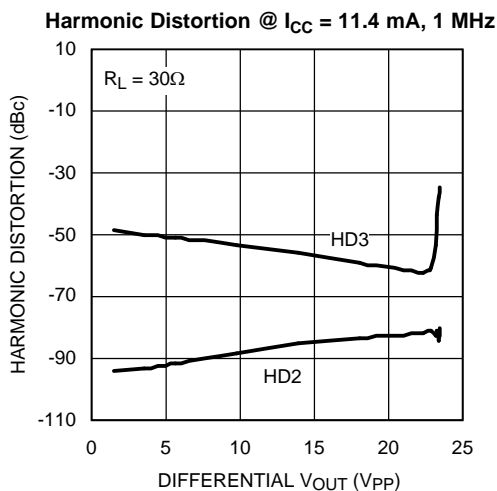


Figure 36.

## APPLICATION NOTES

### FUNCTIONAL DESCRIPTION

The LMH6678 contains two pairs of high speed/high output current operational amplifiers configured as two amplifiers differential inputs and outputs, as shown in Figure 37. Quiescent current can be set independently for each channel via two control bits as depicted in Table 1. Also, quiescent current can be continuously varied by selection of an external resistor between the ADJ pin and a supply voltage of either +12V or +3.3V.

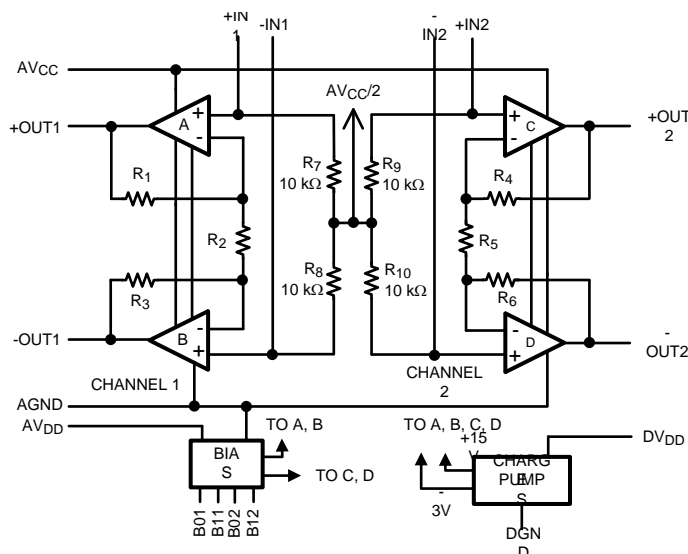


Figure 37. Functional Block Diagram

Table 1. Power Mode Logic Control

Power Mode	Channel A (B)	
	B01 (B02)	B11 (B12)
Full Power	L	L
2/3 Power	H	L
1/3 Power	L	H
Shutdown	H	H

Two supply voltages are required, +12V  $\pm$ 10% and +3.3V  $\pm$ 10%. Current for the driver amplifiers, including their output current, flows from the 12V analog  $V_{CC}$  ( $AV_{CC}$ ) supply and Analog Ground (AGND.) For proper output swing and distortion performance, both  $AV_{CC}$  pins must be connected to +12V and the exposed metal pad must be soldered to ground potential as described in the [HIGH SPEED DRIVER LAYOUT GUIDELINES](#) section. Both  $AV_{DD}$  and  $DV_{DD}$  pins must be connected to +3.3V. The internal bias circuitry is powered from  $AV_{DD}$  and AGND while the digital circuitry and charge pump are powered from  $DV_{DD}$  and DGND. This allows separate bypassing and decoupling for  $AV_{DD}$  and  $DV_{DD}$ .

All supply voltage pins need a 0.1  $\mu$ F ceramic capacitor in parallel with a 4.7  $\mu$ F capacitor as bypass capacitors. The 0.1  $\mu$ F capacitor should be as close as possible to the supply voltage pin and the larger capacitor placed next to it.

The LMH6678 delivers very low power consumption at a single +12V analog supply voltage by a combination of its circuit architecture and the on-chip dual charge pump. The output stage is an emitter-follower type, which can provide low distortion, low quiescent current and high peak output currents.

The charge pumps generate two internal dc voltages,  $V_{HIGH} = +15V$  and  $V_{LOW} = -3V$ . As shown in Figure 38,  $V_{HIGH}$  and  $V_{LOW}$  supply base currents for the output stages. This enables the drivers to swing within a  $V_{CE(sat)}$  of  $V_{CC}$  and ground, giving the LMH6678 its high swing of +11.5  $V_{PP}$  into a 31 $\Omega$  load.

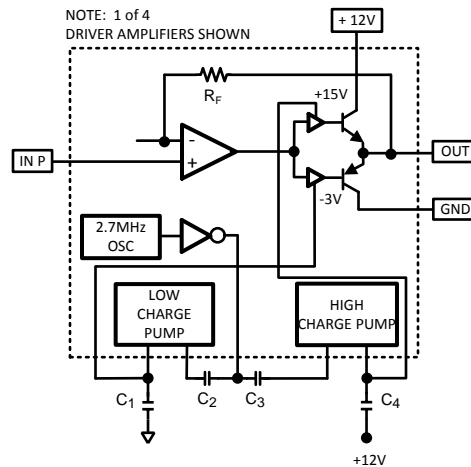


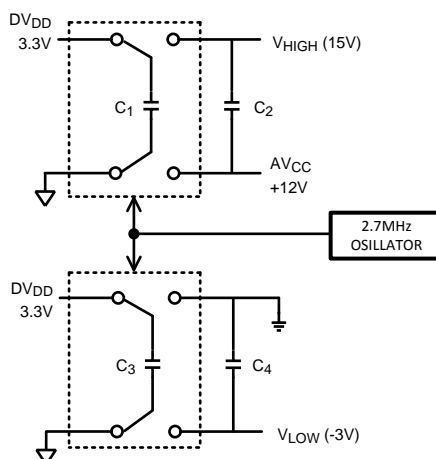
Figure 38. Internal Connections of Integrated Charge Pumps

## CHARGE PUMPS

Figure 39 is a simplified schematic of the internal charge pumps. Each pump consists of a transfer capacitor and a reservoir capacitor and switches. The states of switches are driven by an internal 2.75 MHz clock oscillator. The transfer capacitor of the high charge pump, C<sub>1</sub>, is connected across DV<sub>DD</sub> and DGND during one phase of the clock and between V<sub>HIGH</sub> and AV<sub>CC</sub> during the opposite phase. This causes its reservoir capacitor, C<sub>2</sub>, to charge up to DV<sub>DD</sub> (3.3Volts) potential less a small drop due to finite switch resistance. V<sub>HIGH</sub> therefore is pumped to nearly V<sub>CC</sub> + V<sub>DD</sub> potential or approximately +15V.

Similarly, the transfer capacitor of the low charge pump, C<sub>3</sub>, is connected across DV<sub>DD</sub> and DGND during one phase of the clock and between AGND and V<sub>LOW</sub> during the opposite phase. This causes its reservoir capacitor, C<sub>4</sub>, to charge up to V<sub>DD</sub> potential less a small drop due to finite switch resistance. V<sub>LOW</sub> therefore is pumped to nearly -V<sub>DD</sub> potential or approximately -3V.

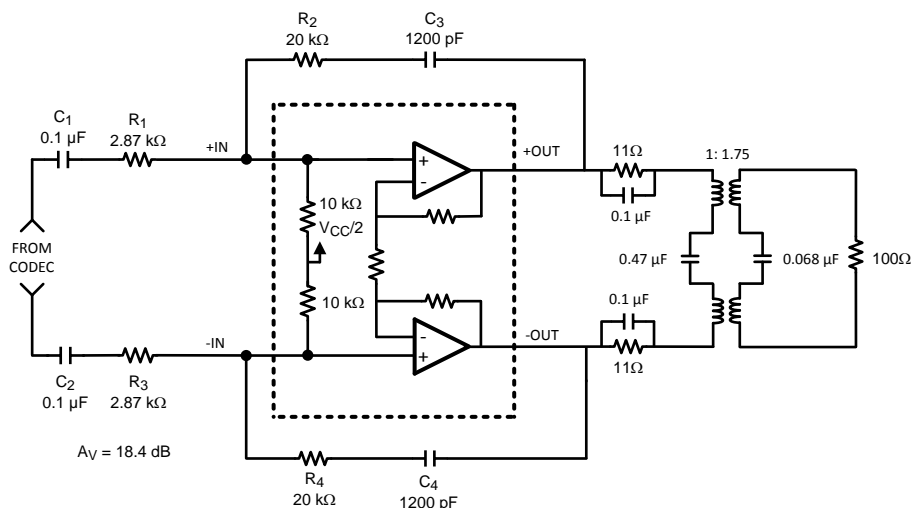
The charge pumps outputs provide both dc bias currents and the base current of the output transistors. These base currents are small compared to the dc bias currents. Typical and maximum quiescent V<sub>DD</sub> supply currents are given in the electrical characteristics. Thus, for the charge pump capacitors C<sub>1</sub>-C<sub>4</sub>, the suggested values are 0.022 μF 20% X7R type. With these values, the ripple on V<sub>HIGH</sub> and V<sub>LOW</sub> will be approximately 40 mV<sub>PP</sub>. This results in a small spurious output on the line of typically -120 dBm/Hz at 2.75 MHz. Spurs produced at harmonics of the clock frequency are at least 20 dB lower and further attenuated by the transformer. This is shown in the [Typical Performance Characteristics](#) section. Ripple and spurious outputs can be further attenuated by increasing the size of the reservoir capacitors C<sub>2</sub> and C<sub>4</sub>.



**Figure 39. Charge Pump Functional Schematic**

## MULTI-TONE POWER RATIO AND NOISE

The Multi-Tone Power Ratio of the LMH6678 is shown in the [Typical Performance Characteristics](#) section. MTPR is the best representation of non-linearity for ADSL modems. The measurement is accomplished with all ADSL bins transmitting full power except one. The delta between the peak amplitude of the transmitting carriers and energy left in the single bin defines the maximum available SNR for that bin. The test circuit is described in [Figure 40](#). Here  $R_2$ ,  $C_3$ ,  $R_4$  and  $C_4$  were added for increase gain.



**Figure 40. MTPR Measurement Test Circuit**

## R-C TERMINATION CIRCUIT AND TRANSFORMER TURNS RATIO

The LMH6678 was designed to operate in the circuit of [Figure 41](#). In this circuit, resistor  $R_1$  and  $R_2$  provide a line termination in the upstream band. At higher frequencies in the downstream band, capacitors  $C_1$  and  $C_2$  bypass  $R_1$  and  $R_2$  for higher efficiency.

To calculate the transformer turns ratio required, we assume a peak-to-rms ratio of 5.8 must be supported and the  $V_{CC}$  supply tolerance is 5%. At a 30Ω load, the driver outputs can swing to 350 mV of each rail with low distortion. This gives a peak swing of  $12(.95) - 0.7 = 10.7V$ . A typical selection for  $C_1$ ,  $C_2$ ,  $R_1$  and  $R_2$  results in approximately 0.1 dB loss and the transformer loss is typically 0.25 dB, so total voltage loss is about 0.35 dB.



For 19.8 dBm output, line rms voltage is 3.09 and peak voltage is 17.9. The optimum turns ratio is calculated at  $1.035 \times 17.9/10.7 = 1.73$ . This gives a reflected line impedance of  $100\Omega/(1.73)^2 = 33.4$  at the primary side.  $R_1$  and  $R_2$  are usually chosen to be  $33.4/2 = 16.7$  to terminate the line at lower frequencies.

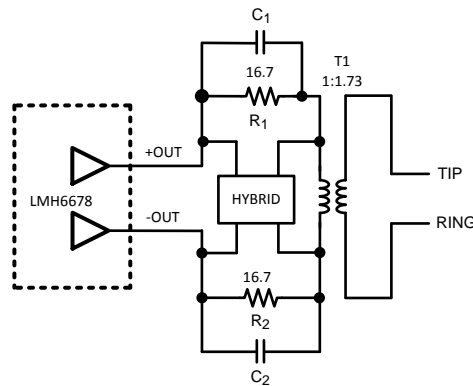


Figure 41. Typical R-C Termination

### INPUT POWER LEVEL AND GAIN

With losses included, output power from the LMH6678 should be  $19.8 \text{ dBm} + 0.35 \text{ dB} = 20.15 \text{ dBm}$  or 103.5 mW. At  $33.4\Omega$ , the rms differential output voltage is  $\sqrt{(P \times R)} = 1.86 \text{ V}_{\text{rms}}$ . The driver amplifiers have a voltage gain of  $5.4 \text{ V/V}$ , so the input level should be  $1.86/5.4 = 344 \text{ mV}_{\text{RMS}}$  to deliver 19.8 dBm to the line.

The driver input equivalent circuit is shown in Figure 37. The inputs should be capacitively coupled to maintain the input and output common-mode voltage at  $V_{\text{CC}}/2$ .

If additional gain is required, the gain can be increased with positive feedback using the circuit of Figure 42. In this case the voltage gain  $A_V$  will be

$$A_V = 5.4 * (1 - K) / (1 - 5.4 * K)$$

where

- $K = (R_1 || 10K) / (R_1 || 10K + R_2) = 10K * R_1 / (10K * R_1 + R_1 * R_2 + 10K * R_2)$
  - $R_1 = R_3$
  - $R_2 = R_4$
- (1)

It is suggested to choose  $R_1 < 3K$  so that the 15% tolerance of the input resistance will not greatly affect the gain. Furthermore, this circuit will have a differential input resistance of

$$R_{\text{IN\_DIFF}} = 2 * R_1 - 2 * R_2 / (4.4) \tag{2}$$

which may be negative in band. Usually no stability problems are seen if this  $|R_{\text{IN}}|$  is chosen larger than  $500\Omega$ . To minimize distortion caused by loading on the Codec outputs,  $|R_{\text{IN}}|$  is usually chosen to be  $1k\Omega$  or more. Additional blocking capacitors  $C_3$  and  $C_4$  must be inserted in series with  $R_2$  and  $R_4$  to prevent the circuit from latching.  $C_3$  and  $C_4$  should be chosen to be less than  $1/5$  of  $C_1$  to avoid large signal oscillation.

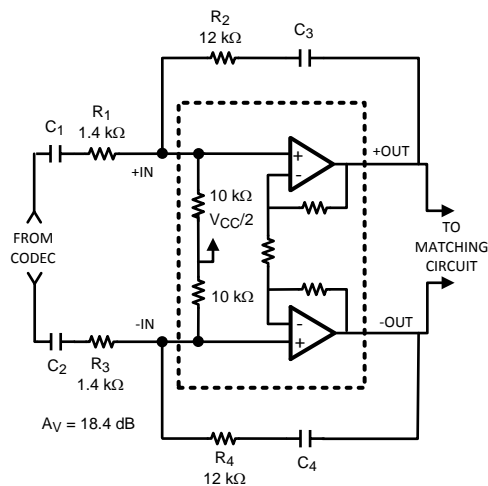


Figure 42. Increasing Gain

### ACTIVE TERMINATION CIRCUIT

The LMH6678 can be used to synthesize the output impedance by using positive feedback to increase the output resistance. In ADSL this technique is often used to lower the total power consumption of the line driver by reducing the voltage across the series termination resistors. This approach gives slightly higher power consumption but better return loss in the downstream band compared to the R-C termination of Figure 41. The equations that follow and Figure 43 describe how to implement this technique with the LMH6678.

1. Pick positive feedback factor (also called the resistance gain),  $A_Z$ .
2. Pick desired output resistance,  $R_{OUT}$ , seen by the line.
3. Calculate transformer turns ratio based on  $A_Z$ , line driver voltage swing, and transformer insertion loss (TIL).  $R_L$  is the line impedance, 100Ω for ADSL.  $N = [(V_{LINEPP} / (2 * 11.2))] * [(1 + R_{OUT} / (R_L * A_Z))] * 10^{(TIL/20)}$
4. Calculate  $R_4$  from  $R_{OUT}$ ,  $A_Z$ , and  $NR_4 = R_{OUT} / (2 * A_Z * N^2)$
5. Calculate the resistance looking into the transformer secondary (chip side).  $R_{SEC} = R_L / N^2$
6. Calculate  $K_1$ .  $K_1 = (A_Z - 1) / (5.4 * A_Z)$
7. Calculate  $K_2$ .  $K_2 = R_{SEC} / (R_{SEC} + 2 * R_4)$
8. Pick a value for  $R_2$ . Typically 3kΩ is a good value.
9. Calculate  $R_{EQ}$ .  $R_{EQ} = R_2 / (1 - 5.4 * K_2)$  (Note  $R_{EQ}$  is usually negative.)
10. Calculate  $R_{IN}$ .  $R_{IN} = [(K_1 * R_2) / (1 - K_1) * 10k] / [10k - (K_1 * R_2) / (1 - K_1)]$
11. Calculate the gain without the input voltage divider.  $A_{V1} = N * 5.4 * K_2 * [(R_{EQ} / 10k) / (R_{IN} + R_{EQ} / 10k)] / (10^{TIL/20})$
12. Calculate  $A_{VTOTAL}$  the final required gain from input to the line.  $A_{VTOTAL} = V_{LINERMS} / V_{INRMS}$
13. Calculate the voltage divider network of  $R_1$  and  $R_3$  using  $A_{V1}$ , transformer insertion loss (TIL),  $R_1 = R_{IN} * [A_{V1} / (A_{VTOTAL} * 10^{TIL/20})]$ ,  $R_3 = (2 * R_{IN}) / [1 - (A_{VTOTAL} * 10^{TIL/20}) / A_{V1}]$

The example shown in Figure 43 is designed to the following parameters:

$$V_{LINERMS} = 3.13V \quad (19.8 \text{ dBm output power})$$

$$A_Z = 4.5$$

$$R_{OUT} = 65\Omega \quad (13.5\text{dB return loss})$$

$$\text{Crest Factor} = 5.8 \text{ @ nominal 12V supply}$$

$$\text{Transformer Insertion Loss} = 0.4\text{dB}$$

$$V_{INRMS} = 350\text{mV} \quad (\text{AFE output level})$$

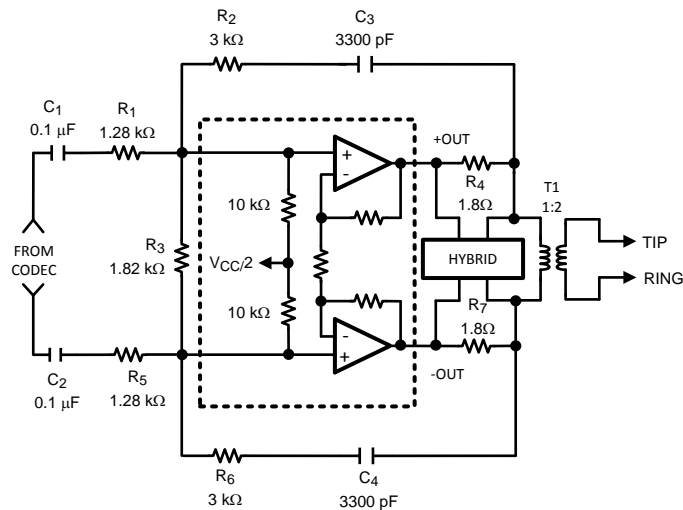


Figure 43. Active Termination Application

## POWER CONSUMPTION

Power consumption is a function of line power and dynamic bias current of the line driver. After the transformer turns ratio has been selected as described above, power consumption per channel for the typical R-C termination application can be estimated as follows:

$$I_{CC} = I_{dB} + I_{LOAD} \quad (3)$$

$$I_{dB} = 0.25 * I_q \quad (4)$$

This is because 25% of the total dc current flows in the output transistors. This term effectively vanishes when the class AB stage is drives a heavy load.

**Where**  $I_{LOAD}$  = average load current driven by output transistors  
 $I_{dB}$  = dynamic  $V_{CC}$  bias current while driving full load power  
 $I_{CC}$  = average  $V_{CC}$  current

When losses included, 103.5 mW is delivered by the driver, therefore

$$I_{RMS} = TR * \sqrt{(1035/100)} = 32.2 \text{ mA} \quad (5)$$

Since the ADSL signal is DMT and is effectively gaussian, the average value of the supply current due to driving the load is given by

$$I_{LOAD} = \text{average}|I_{RMS}| = \sqrt{(2/\pi)} * I_{RMS} = 0.8 * I_{RMS} = 44.6 \text{ mA for } TR = 1.73 \quad (6)$$

Assuming 2/3 power mode,  $I_{fixed} = 0.25 * 11 \text{ mA} = 2.75 \text{ mA}$

$$I_{CC} = 2.75 \text{ mA} + 44.6 \text{ mA} = 47.4 \text{ mA} \quad (7)$$

$$P_{CC} = I_{CC} * V_{CC} = 569 \text{ mW} \quad (8)$$

To get the  $I_{DD}$  full current, simply add 0.75 mA to the quiescent current per channel:

$$I_{DD} = 0.75 + 5.5 + 0.6 = 6.8 \text{ mA} \quad (9)$$

$$P_{DD} = V_{DD} * I_{DD} = 23 \text{ mW} \quad (10)$$

For the total power consumption per channel,

$$P_{CON} = P_{DD} + P_{CC} = 592 \text{ mW} \quad (11)$$

For power dissipation of the LMH6678, subtract the power into the load plus external losses:

$$P_{DISS} = 592 - 103 = 489 \text{ mW per channel} \quad (12)$$

$$P_{DISS} \text{ total} = 2 * 489 = 978 \text{ mW for both channels} \quad (13)$$

Proper selection of the external resistor between the ADJ pin can optimize the trade-off between power consumption and distortion. This external resistor will reduce the supply current for the 1/3, 2/3 and full bias settings for both channels. The approximately equation is

$$I_S = I_S * (1 - (V_{CC} - 0.8) / (30\mu A * R_{ADJ})) \quad (14)$$

Curves of  $V_{CC}$  and  $V_{DD}$  supply currents per channel vs.  $R_{ADJ}$  for the various power settings are shown in [Typical Performance Characteristics](#) section.

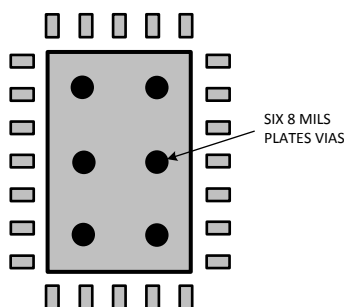
## PACKAGE AND LAYOUT CONSIDERATION

The LMH6678 uses the 24-pin Leadless Leadframe Package, a thermally enhanced, standard size IC package designed to eliminate the use of bulky heatsinks traditionally used in thermal packages. This package can be easily mounted using standard PCB surface mount assembly techniques.

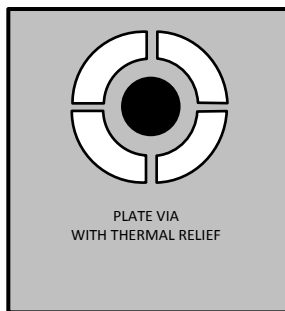
The LLP is designed so that the thermal pad is exposed on the bottom of the IC, as shown in the package drawing. This provides an extremely low thermal resistance ( $\theta_{JC}$ ) path between the die and the exterior of the package. The thermal pad on the bottom of the IC can then be soldered directly to the PCB, using the PCB as a heatsink. In addition, plated-through holes (vias) on the PCB provide a low thermal resistance heat flow path to the backside of the circuit board.

## LAND PATTERN AND ASSEMBLY GUIDELINE FOR LMH6678

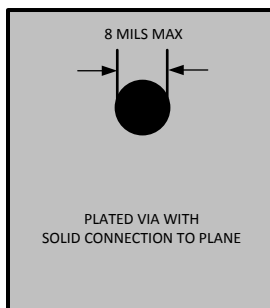
1. The thermal pad must be connected to analog ground AGND in LMH6678.
2. Prepare the PCB with a top-side land pattern, as shown in [Figure 44](#).
3. Place the recommended number of plated-through holes in the area of the thermal pad. These holes should be 8 mils max. in diameter. They are kept small so that solder wicking through the holes is not a problem during reflow. The minimum recommended number of holes for the 24-pin LLP is six, as shown in [Figure 44](#).
4. Connect all holes to the internal and bottom analog ground plane.
5. When laying out these holes to the ground plane, do not use the typical web or spoke via connection methodology, as shown in [Figure 45](#). Web connections have a high thermal resistance connection that is useful for slowing the heat transfer during soldering operations. This makes soldering the vias that have ground plane connections easier. However, in this application, low thermal resistance is desired for the most efficient heat transfer. Therefore, the holes under the thermal pad should make their connection to the internal ground plane with a complete connection around the entire circumference of the plated-through hole. Use plated via with solid connection to plane as shown in [Figure 46](#).
6. The top-side solder mask should leave the terminals of the pad connections and the thermal pad area exposed. The thermal pad area should leave the 8 mils holes exposed.
7. Apply solder paste to the exposed thermal pad area and all of the package terminals.
8. With these preparatory steps in place, the LLP is simply placed in position and run through the solder reflow operation as any standard surface-mount component. This results in a part that is properly installed.



**Figure 44. Recommended Land Pattern**



**Figure 45. Via Connection Not Recommended Under the Thermal Pad**



**Figure 46. Via Connection Recommended For Use in Thermal Pad**

## HIGH SPEED DRIVER LAYOUT GUIDELINES

The LMH6678 is a high performance differential line amplifier that requires proper layout for best performance.

- Keep power-supply leads as short as possible. This will keep inductance low and resistive losses at a minimum.
- Proper power-supply bypassing with low ESR capacitors is essential to achieve good performance. A parallel combination of small (around 0.1  $\mu\text{F}$ ) ceramic and bigger (6.8  $\mu\text{F}$ ) tantalum bypass capacitors will provide low and impedance over a wide frequency range.
- Bypass capacitor should be placed as close as possible, limited by pick and place machine requirement, to the power-supply pins of the LMH6678 (ceramic cap first and then tantalum cap).
- PCB traces conducting high currents, such as from output to load or from power-supply connector to the power-supply pins of the LMH6678 should be kept as wide and short as possible to minimize inductance and resistive loss.
- The six holes in the landing pattern for the LMH6678 are for the thermal vias that connect the thermal pad of LLP package to the internal/external ground plane on the PCB.

For detail information on the LLP package including thermal modeling considerations and prepared procedures, please see Texas Instruments.

"Applications Note 1187: Leadless Leadframe Package (LLP)" at [www.ti.com](http://www.ti.com)

## REVISION HISTORY

Changes from Revision A (April 2013) to Revision B	Page
• Changed layout of National Data Sheet to TI format .....	<a href="#">19</a>



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